

Unified Extensible Firmware Interface Specification

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Unified Extensible Firmware Interface Specification

Introduction

This *Unified Extensible Firmware Interface* (hereafter known as UEFI) *Specification 2.1* describes an interface between the operating system (OS) and the platform firmware. UEFI was preceded by the *Extensible Firmware Interface Specification 1.10* (EFI). As a result, some code and certain protocol names retain the EFI designation. Unless otherwise noted, EFI designations in this specification may be assumed to be part of UEFI.

The interface is in the form of data tables that contain platform-related information, and boot and runtime service calls that are available to the OS loader and the OS. Together, these provide a standard environment for booting an OS. This specification is designed as a pure interface specification. As such, the specification defines the set of interfaces and structures that platform firmware must implement. Similarly, the specification defines the set of interfaces and structures that the OS may use in booting. How either the firmware developer chooses to implement the required elements or the OS developer chooses to make use of those interfaces and structures is an implementation decision left for the developer.

The intent of this specification is to define a way for the OS and platform firmware to communicate only information necessary to support the OS boot process. This is accomplished through a formal and complete abstract specification of the software-visible interface presented to the OS by the platform and firmware.

Using this formal definition, a shrink-wrap OS intended to run on platforms compatible with supported processor specifications will be able to boot on a variety of system designs without further platform or OS customization. The definition will also allow for platform innovation to introduce new features and functionality that enhance platform capability without requiring new code to be written in the OS boot sequence.

Furthermore, an abstract specification opens a route to replace legacy devices and firmware code over time. New device types and associated code can provide equivalent functionality through the same defined abstract interface, again without impact on the OS boot support code.

The specification is applicable to a full range of hardware platforms from mobile systems to servers. The specification provides a core set of services along with a selection of protocol interfaces. The selection of protocol interfaces can evolve over time to be optimized for various platform market segments. At the same time, the specification allows maximum extensibility and customization abilities for OEMs to allow differentiation. In this, the purpose of UEFI is to define an evolutionary path from the traditional “PC-AT”-style boot world into a legacy-API free environment.

1.1 UEFI Driver Model Extensions

Access to boot devices is provided through a set of protocol interfaces. One purpose of the UEFI *Driver Model* is to provide a replacement for “PC-AT”-style option ROMs. It is important to point out that drivers written to the UEFI *Driver Model* are designed to access boot devices in the preboot environment. They are not designed to replace the high-performance, OS-specific drivers.

The *UEFI Driver Model* is designed to support the execution of modular pieces of code, also known as drivers, that run in the preboot environment. These drivers may manage or control hardware buses and devices on the platform, or they may provide some software-derived, platform-specific service.

The *UEFI Driver Model* also contains information required by UEFI driver writers to design and implement any combination of bus drivers and device drivers that a platform might need to boot a UEFI-compliant OS.

The *UEFI Driver Model* is designed to be generic and can be adapted to any type of bus or device. The *UEFI Specification 2.0* describes how to write PCI bus drivers, PCI device drivers, USB bus drivers, USB device drivers, and SCSI drivers. Additional details are provided that allow UEFI drivers to be stored in PCI option ROMs, while maintaining compatibility with legacy option ROM images.

One of the design goals in the *UEFI Specification 2.0* is keeping the driver images as small as possible. However, if a driver is required to support multiple processor architectures, a driver object file would also be required to be shipped for each supported processor architecture. To address this space issue, this specification also defines the *EFI Byte Code Virtual Machine*. A UEFI driver can be compiled into a single EFI Byte Code object file. UEFI 2.0-complaint firmware must contain an EFI Byte Code interpreter. This allows a single EFI Byte Code object file that supports multiple processor architectures to be shipped. Another space saving technique is the use of compression. This specification defines compression and decompression algorithms that may be used to reduce the size of UEFI Drivers, and thus reduce the overhead when UEFI Drivers are stored in ROM devices.

The information contained in the *UEFI Specification 2.0* can be used by OSVs, IHVs, OEMs, and firmware vendors to design and implement firmware conforming to this specification, drivers that produce standard protocol interfaces, and operating system loaders that can be used to boot UEFI-compliant operating systems.

1.2 Overview

The UEFI 2.0 Specification is organized as listed in [Table 1](#).

Table 1. Organization of the UEFI Specification

Section/Appendix	Description
1. Introduction	Introduces the UEFI Specification and topics related to using the specification.
2. Overview	Describes the major components of UEFI, including the boot manager, firmware core, calling conventions, protocols, and requirements.
3. Boot Manager	Describes the boot manager, which is used to load drivers and applications written to this specification.
4. EFI System Table	Describes the EFI System Table that is passed to every compliant driver and application.
5. GUID Partition Table (GPT) Format	Defines a new partitioning scheme that must be supported by firmware conforming to this specification.

6. Services — Boot Services	Contains the definitions of the fundamental services that are present in a UEFI-compliant system before an OS is booted.
7. Services — Runtime Services	Contains definitions for the fundamental services that are present in a compliant system before and after an OS is booted.
8. Protocols — EFI Loaded Image	Defines the EFI Loaded Image Protocol that describes a UEFI Image that has been loaded into memory.
9 Protocols — Device Path Protocol	Defines the device path protocol and provides the information needed to construct and manage device paths in the UEFI environment.
10. Protocols — UEFI Driver Model	Describes a generic driver model for UEFI. This includes the set of services and protocols that apply to every bus and device type, including the Driver Binding Protocol, the Platform Driver Override Protocol, the Bus Specific Driver Override Protocol, the Driver Diagnostics Protocol, the Driver Configuration Protocol, and the Component Name Protocol.
11. Protocols — Console Support	Defines the Console I/O protocols, which handle input and output of text-based information intended for the system user while executing in the boot services environment. These protocols include the Simple Input Protocol, the Simple Text Output Protocol, the Graphics Output Protocol, the Simple Pointer Protocol, and the Serial I/O Protocol.
12. Protocols—Media Access	Defines the Load File protocol, file system format and media formats for handling removable media.
13. Protocols — PCI Bus Support	Defines PCI Bus Drivers, PCI Device Drivers, and PCI Option ROM layouts. The protocols described include the PCI Root Bridge I/O Protocol and the PCI I/O Protocol.
14. Protocols — SCSI Driver Models and Bus Support	Defines the SCSI I/O Protocol and the Extended SCSI Pass Thru Protocol that is used to abstract access to a SCSI channel that is produced by a SCSI host controller.
15. Protocols —iSCSI Boot	The iSCSI protocol defines a transport for SCSI data over TCP/IP.
16. Protocols — USB Support	Defines USB Bus Drivers and USB Device Drivers. The protocols described include the USB2 Host Controller Protocol and the USB I/O Protocol.
17. Protocols — Debugger Support	An optional set of protocols that provide the services required to implement a source-level debugger for the UEFI environment. The EFI Debug Port Protocol provides services to communicate with a remote debug host. The Debug Support Protocol provides services to hook processor exceptions, save the processor context, and restore the processor context. These protocols can be used in the implementation of a debug agent on the target system that interacts with the remote debug host.
18. Protocols — Compression Algorithm Specification	Describes in detail the compression/decompression algorithm, as well as the EFI Decompress Protocol. The EFI Decompress Protocol provides a standard decompression interface for use at boot time. The EFI Decompress Protocol is used by a PCI Bus Driver to decompress UEFI drivers stored in PCI Option ROMs.

Unified Extensible Firmware Interface Specification

19. Protocols — ACPI Protocols	
20. EFI Byte Code Virtual Machine	Defines the EFI Byte Code virtual processor and its instruction set. It also defines how EBC object files are loaded into memory, and the mechanism for transitioning from native code to EBC code and back to native code. The information in this document is sufficient to implement an EFI Byte Code interpreter, an EFI Byte Code compiler, and an EFI Byte Code linker.
21. Network Protocols—SNP, PXE, and BIS	Defines the protocols that provide access to network devices while executing in the UEFI boot services environment. These protocols include the Simple Network Protocol, the PXE Base Code Protocol, and the Boot Integrity services (BIS) Protocol.
22. Network Protocols—Managed Network	Defines the EFI Managed Network Protocol, which provides raw (unformatted) asynchronous network packet I/O services and Managed Network Service Binding Protocol, which is used to locate communication devices that are supported by an MNP driver.
23. Network Protocols—ARP and DHCPv4	Defines the EFI Address Resolution Protocol (ARP) Protocol interface and the EFI DHCPv4 Protocol.
24. Network Protocols—TCPv4, IPv4 and Configuration	Defines the EFI TCPv4 (Transmission Control Protocol version 4) Protocol and the EFI IPv4 (Internet Protocol version 4) Protocol interface.
25. Network Protocols—UDPv4 and MTFTPv4	Defines the EFI UDPv4 (User Datagram Protocol version 4) Protocol that interfaces over the EFI IPv4 Protocol and defines the EFI MTFTPv4 Protocol interface that is built on the EFI UDPv4 Protocol.
26. Security—Driver Signing and Hash	Describes a means of generating a digital signature for a UEFI executable and a standard set of functions for creating a hash value for a specified variable-length input.
27. Human Interface Infrastructure Overview	
28. HII Protocols	
29. HII Configuration Processing and Browser Protocol	
A. GUID and Time Formats	Explains the GUID (Guaranteed Unique Identifier) format.
B. Console	Describes the requirements for a basic text-based console required by EFI-conformant systems to provide communication capabilities.
C. Device Path Examples	Examples of use of the data structures that define various hardware devices to the boot services.
D. Status Codes	Lists success, error, and warning codes returned by UEFI interfaces.
E. Universal Network Driver Interfaces	Defines the 32/64-bit hardware and software Universal Network Driver Interfaces (UNDIs).
F. Using the Simple Pointer Protocol	Provides the suggested usage of the Simple Pointer Protocol.
G. Using the EFI SCSI Pass Thru Protocol	Provides an example of how the SCSI Pass Thru Protocol can be used.

H. Compression Source Code	The C source code to an implementation of the Compression Algorithm.
I. Decompression Source Code	The C source code to an implementation of the EFI Decompression Algorithm.
J. EFI Byte Code Virtual Machine Opcode Lists	A summary of the opcodes in the instruction set of the EFI Byte Code Virtual Machine.
K. Alphabetic Function List	Lists all UEFI interface functions alphabetically.
L. EFI 1.10 Protocol Changes and Deprecation Lists	Lists the Protocol, GUID, and revision identifier name changes and the deprecated protocols compared to the <i>EFI Specification 1.10</i> .
M. Formats—Language Codes and Language Code Arrays	Lists the formats for language codes and language code arrays.
N. Common Platform Error Record	
O. UEFI ACPI Table	
P. Hardware Error Record Persistence Usage	
Q. References	Lists all necessary or useful specifications, web sites, and other documentation that is referenced in this UEFI specification.
R. Glossary	Briefly describes terms defined or referenced by this specification.
Index	Provides an index to the key terms and concepts in the specification.

1.3 Goals

The “PC-AT” boot environment presents significant challenges to innovation within the industry. Each new platform capability or hardware innovation requires firmware developers to craft increasingly complex solutions, and often requires OS developers to make changes to their boot code before customers can benefit from the innovation. This can be a time-consuming process requiring a significant investment of resources.

The primary goal of the UEFI specification is to define an alternative boot environment that can alleviate some of these considerations. In this goal, the specification is similar to other existing boot specifications. The main properties of this specification can be summarized by these attributes:

- ***Coherent, scalable platform environment.*** The specification defines a complete solution for the firmware to describe all platform features and surface platform capabilities to the OS during the boot process. The definitions are rich enough to cover a range of contemporary processor designs.
- ***Abstraction of the OS from the firmware.*** The specification defines interfaces to platform capabilities. Through the use of abstract interfaces, the specification allows the OS loader to be constructed with far less knowledge of the platform and firmware that underlie those interfaces. The interfaces represent a well-defined and stable boundary between the underlying platform and firmware implementation and the OS loader. Such a boundary allows the underlying firmware and the OS loader to change provided both limit their interactions to the defined interfaces.

- **Reasonable device abstraction free of legacy interfaces.** “PC-AT” BIOS interfaces require the OS loader to have specific knowledge of the workings of certain hardware devices. This specification provides OS loader developers with something different: abstract interfaces that make it possible to build code that works on a range of underlying hardware devices without having explicit knowledge of the specifics for each device in the range.
- **Abstraction of Option ROMs from the firmware.** This specification defines interfaces to platform capabilities including standard bus types such as PCI, USB, and SCSI. The list of supported bus types may grow over time, so a mechanism to extend to future bus types is included. These defined interfaces, and the ability to extend to future bus types, are components of the *UEFI Driver Model*. One purpose of the *UEFI Driver Model* is to solve a wide range of issues that are present in existing “PC-AT” option ROMs. Like OS loaders, drivers use the abstract interfaces so device drivers and bus drivers can be constructed with far less knowledge of the platform and firmware that underlie those interfaces.
- **Architecturally shareable system partition.** Initiatives to expand platform capabilities and add new devices often require software support. In many cases, when these platform innovations are activated before the OS takes control of the platform, they must be supported by code that is specific to the platform rather than to the customer’s choice of OS. The traditional approach to this problem has been to embed code in the platform during manufacturing (for example, in flash memory devices). Demand for such persistent storage is increasing at a rapid rate. This specification defines persistent store on large mass storage media types for use by platform support code extensions to supplement the traditional approach. The definition of how this works is made clear in the specification to ensure that firmware developers, OEMs, operating system vendors, and perhaps even third parties can share the space safely while adding to platform capability.

Defining a boot environment that delivers these attributes could be accomplished in many ways. Indeed, several alternatives, perhaps viable from an academic point of view, already existed at the time this specification was written. These alternatives, however, typically presented high barriers to entry given the current infrastructure capabilities surrounding supported processor platforms. This specification is intended to deliver the attributes listed above, while also recognizing the unique needs of an industry that has considerable investment in compatibility and a large installed base of systems that cannot be abandoned summarily. These needs drive the requirements for the additional attributes embodied in this specification:

- **Evolutionary, not revolutionary.** The interfaces and structures in the specification are designed to reduce the burden of an initial implementation as much as possible. While care has been taken to ensure that appropriate abstractions are maintained in the interfaces themselves, the design also ensures that reuse of BIOS code to implement the interfaces is possible with a minimum of additional coding effort. In other words, on PC-AT platforms the specification can be implemented initially as a thin interface layer over an underlying implementation based on existing code. At the same time, introduction of the abstract interfaces provides for migration away from legacy code in the future. Once the abstraction is established as the means for the firmware and OS loader to interact during boot, developers are free to replace legacy code underneath the abstract interfaces at leisure. A similar migration for hardware legacy is also possible. Since the abstractions hide the specifics of devices, it is possible to remove underlying hardware, and replace it with new hardware that provides improved functionality, reduced cost, or both. Clearly this requires that new platform firmware be written to support the device and

present it to the OS loader via the abstract interfaces. However, without the interface abstraction, removal of the legacy device might not be possible at all.

- **Compatibility by design.** The design of the system partition structures also preserves all the structures that are currently used in the “PC-AT” boot environment. Thus, it is a simple matter to construct a single system that is capable of booting a legacy OS or an EFI-aware OS from the same disk.
- **Simplifies addition of OS-neutral platform value-add.** The specification defines an open, extensible interface that lends itself to the creation of platform “drivers.” These may be analogous to OS drivers, providing support for new device types during the boot process, or they may be used to implement enhanced platform capabilities, such as fault tolerance or security. Furthermore, this ability to extend platform capability is designed into the specification from the outset. This is intended to help developers avoid many of the frustrations inherent in trying to squeeze new code into the traditional BIOS environment. As a result of the inclusion of interfaces to add new protocols, OEMs or firmware developers have an infrastructure to add capability to the platform in a modular way. Such drivers may potentially be implemented using high-level coding languages because of the calling conventions and environment defined in the specification. This in turn may help to reduce the difficulty and cost of innovation. The option of a system partition provides an alternative to nonvolatile memory storage for such extensions.
- **Built on existing investment.** Where possible, the specification avoids redefining interfaces and structures in areas where existing industry specifications provide adequate coverage. For example, the ACPI specification provides the OS with all the information necessary to discover and configure platform resources. Again, this philosophical choice for the design of the specification is intended to keep barriers to its adoption as low as possible.

1.4 Target Audience

This document is intended for the following readers:

- IHVs and OEMs who will be implementing UEFI drivers.
- OEMs who will be creating supported processor platforms intended to boot shrink-wrap operating systems.
- BIOS developers, either those who create general-purpose BIOS and other firmware products or those who modify these products for use in supported processor-based products.
- Operating system developers who will be adapting their shrink-wrap operating system products to run on supported processor-based platforms.

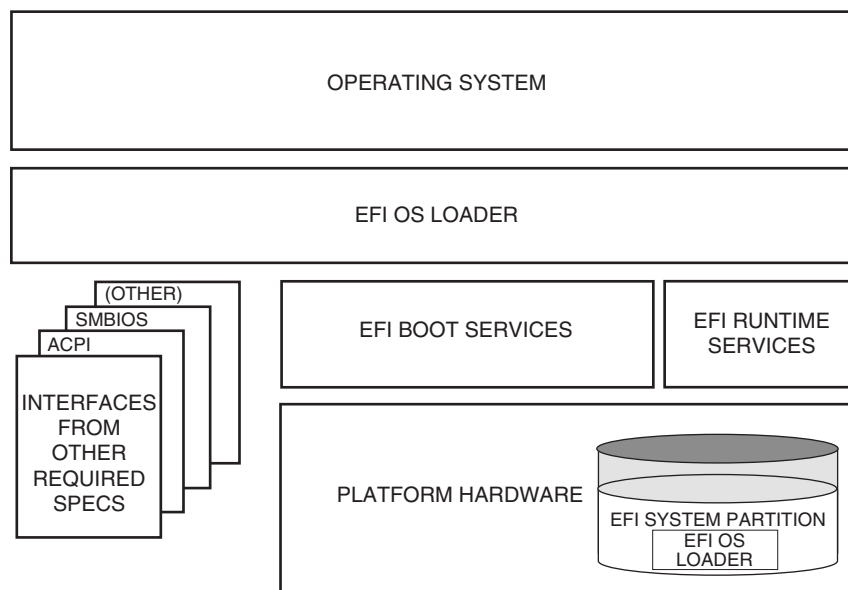
1.5 UEFI Design Overview

The design of UEFI is based on the following fundamental elements:

- **Reuse of existing table-based interfaces.** In order to preserve investment in existing infrastructure support code, both in the OS and firmware, a number of existing specifications that are commonly implemented on platforms compatible with supported processor specifications must be implemented on platforms wishing to comply with the UEFI specification. (For additional information, see [Appendix Q](#).)

- **System partition.** The System partition defines a partition and file system that are designed to allow safe sharing between multiple vendors, and for different purposes. The ability to include a separate, sharable system partition presents an opportunity to increase platform value-add without significantly growing the need for nonvolatile platform memory.
- **Boot services.** Boot services provide interfaces for devices and system functionality that can be used during boot time. Device access is abstracted through “handles” and “protocols.” This facilitates reuse of investment in existing BIOS code by keeping underlying implementation requirements out of the specification without burdening the consumer accessing the device.
- **Runtime services.** A minimal set of runtime services is presented to ensure appropriate abstraction of base platform hardware resources that may be needed by the OS during its normal operations.

Figure 1 shows the principal components of UEFI and their relationship to platform hardware and OS software.



OM13141

Figure 1. UEFI Conceptual Overview

Figure 1 illustrates the interactions of the various components of an UEFI specification-compliant system that are used to accomplish platform and OS boot.

The platform firmware is able to retrieve the OS loader image from the System Partition. The specification provides for a variety of mass storage device types including disk, CD-ROM, and DVD as well as remote boot via a network. Through the extensible protocol interfaces, it is possible to add other boot media types, although these may require OS loader modifications if they require use of protocols other than those defined in this document.

Once started, the OS loader continues to boot the complete operating system. To do so, it may use the EFI boot services and interfaces defined by this or other required specifications to survey,

comprehend, and initialize the various platform components and the OS software that manages them. EFI runtime services are also available to the OS loader during the boot phase.

1.6 UEFI Driver Model

This section describes the goals of a driver model for firmware conforming to this specification. The goal is for this driver model to provide a mechanism for implementing bus drivers and device drivers for all types of buses and devices. At the time of writing, supported bus types include PCI, USB, and so on.

As hardware architectures continue to evolve, the number and types of buses present in platforms are increasing. This trend is especially true in high-end servers. However, a more diverse set of bus types is being designed into desktop and mobile systems and even some embedded systems. This increasing complexity means that a simple method for describing and managing all the buses and devices in a platform is required in the preboot environment. The *UEFI Driver Model* provides this simple method in the form of protocols services and boot services.

1.6.1 UEFI Driver Model Goals

The *UEFI Driver Model* has the following goals:

- **Compatible** – Drivers conforming to this specification must maintain compatibility with the *EFI 1.10 Specification* and the *UEFI 2.0 Specification*. This means that the *UEFI Driver Model* takes advantage of the extensibility mechanisms in the *UEFI 2.0 Specification* to add the required functionality.
- **Simple** – Drivers that conform to this specification must be simple to implement and simple to maintain. The *UEFI Driver Model* must allow a driver writer to concentrate on the specific device for which the driver is being developed. A driver should not be concerned with platform policy or platform management issues. These considerations should be left to the system firmware.
- **Scalable** – The *UEFI Driver Model* must be able to adapt to all types of platforms. These platforms include embedded systems, mobile, and desktop systems, as well as workstations and servers.
- **Flexible** – The *UEFI Driver Model* must support the ability to enumerate all the devices, or to enumerate only those devices required to boot the required OS. The minimum device enumeration provides support for more rapid boot capability, and the full device enumeration provides the ability to perform OS installations, system maintenance, or system diagnostics on any boot device present in the system.
- **Extensible** – The *UEFI Driver Model* must be able to extend to future bus types as they are defined.
- **Portable** – Drivers written to the *UEFI Driver Model* must be portable between platforms and between supported processor architectures.
- **Interoperable** – Drivers must coexist with other drivers and system firmware and must do so without generating resource conflicts.

- **Describe complex bus hierarchies** – The *UEFI Driver Model* must be able to describe a variety of bus topologies from very simple single bus platforms to very complex platforms containing many buses of various types.
- **Small driver footprint** – The size of executables produced by the *UEFI Driver Model* must be minimized to reduce the overall platform cost. While flexibility and extensibility are goals, the additional overhead required to support these must be kept to a minimum to prevent the size of firmware components from becoming unmanageable.
- **Address legacy option rom issues** – The *UEFI Driver Model* must directly address and solve the constraints and limitations of legacy option ROMs. Specifically, it must be possible to build add-in cards that support both UEFI drivers and legacy option ROMs, where such cards can execute in both legacy BIOS systems and UEFI-conforming platforms, without modifications to the code carried on the card. The solution must provide an evolutionary path to migrate from legacy option ROMs driver to UEFI drivers.

1.6.2 Legacy Option ROM Issues

This idea of supporting a driver model came from feedback on the *UEFI Specification 2.0* that provided a clear, market-driven requirement for an alternative to the legacy option ROM (sometimes also referred to as an expansion ROM). The perception is that the advent of the *UEFI Specification 2.0* represents a chance to escape the limitations implicit in the construction and operation of legacy option ROM images by replacing them with an alternative mechanism that works within the framework of the *UEFI Specification 2.0*.

1.7 Migration Requirements

Migration requirements cover the transition period from initial implementation of this specification to a future time when all platforms and operating systems implement to this specification. During this period, two major compatibility considerations are important:

- The ability to continue booting legacy operating systems;
- The ability to implement UEFI on existing platforms by reusing as much existing firmware code to keep development resource and time requirements to a minimum.

1.7.1 Legacy Operating System Support

The UEFI specification represents the preferred means for a shrink-wrap OS and firmware to communicate during the boot process. However, choosing to make a platform that complies with this specification in no way precludes a platform from also supporting existing legacy OS binaries that have no knowledge of the UEFI specification.

The UEFI specification does not restrict a platform designer who chooses to support both the UEFI specification and a more traditional “PC-AT” boot infrastructure. If such a legacy infrastructure is to be implemented, it should be developed in accordance with existing industry practice that is defined outside the scope of this specification. The choice of legacy operating systems that are supported on any given platform is left to the manufacturer of that platform.

1.7.2 Supporting the UEFI Specification on a Legacy Platform

The UEFI specification has been carefully designed to allow for existing systems to be extended to support it with a minimum of development effort. In particular, the abstract structures and services defined in the UEFI specification can all be supported on legacy platforms.

For example, to accomplish such support on an existing and supported 32-bit-based platform that uses traditional BIOS to support operating system boot, an additional layer of firmware code would need to be provided. This extra code would be required to translate existing interfaces for services and devices into support for the abstractions defined in this specification.

1.8 Conventions Used in this Document

This document uses typographic and illustrative conventions described below.

1.8.1 Data Structure Descriptions

Supported processors are “little endian” machines. This distinction means that the low-order byte of a multibyte data item in memory is at the lowest address, while the high-order byte is at the highest address. Some supported 64-bit processors may be configured for both “little endian” and “big endian” operation. All implementations designed to conform to this specification use “little endian” operation.

In some memory layout descriptions, certain fields are marked *reserved*. Software must initialize such fields to zero and ignore them when read. On an update operation, software must preserve any reserved field.

1.8.2 Protocol Descriptions

A protocol description generally has the following format:

Protocol Name:	The formal name of the protocol interface.
Summary:	A brief description of the protocol interface.
GUID:	The 128-bit Globally Unique Identifier (GUID) for the protocol interface.
Protocol Interface Structure:	A “C-style” data structure definition containing the procedures and data fields produced by this protocol interface.
Parameters:	A brief description of each field in the protocol interface structure.
Description:	A description of the functionality provided by the interface, including any limitations and caveats of which the caller should be aware.
Related Definitions:	The type declarations and constants that are used in the protocol interface structure or any of its procedures.

1.8.3 Procedure Descriptions

A procedure description generally has the following format:

ProcedureName():	The formal name of the procedure.
Summary:	A brief description of the procedure.
Prototype:	A “C-style” procedure header defining the calling sequence.
Parameters:	A brief description of each field in the procedure prototype.
Description:	A description of the functionality provided by the interface, including any limitations and caveats of which the caller should be aware.
Related Definitions:	The type declarations and constants that are used only by this procedure.
Status Codes Returned:	A description of any codes returned by the interface. The procedure is required to implement any status codes listed in this table. Additional error codes may be returned, but they will not be tested by standard compliance tests, and any software that uses the procedure cannot depend on any of the extended error codes that an implementation may provide.

1.8.4 Instruction Descriptions

An instruction description for EBC instructions generally has the following format:

InstructionName	The formal name of the instruction.
Syntax:	A brief description of the instruction.
Description:	A description of the functionality provided by the instruction accompanied by a table that details the instruction encoding.
Operation:	Details the operations performed on operands.
Behaviors and Restrictions:	An item-by-item description of the behavior of each operand involved in the instruction and any restrictions that apply to the operands or the instruction.

1.8.5 Pseudo-Code Conventions

Pseudo code is presented to describe algorithms in a more concise form. None of the algorithms in this document are intended to be compiled directly. The code is presented at a level corresponding to the surrounding text.

In describing variables, a *list* is an unordered collection of homogeneous objects. A *queue* is an ordered list of homogeneous objects. Unless otherwise noted, the ordering is assumed to be FIFO.

Pseudo code is presented in a C-like format, using C conventions where appropriate. The coding style, particularly the indentation style, is used for readability and does not necessarily comply with an implementation of the *UEFI Specification*.

1.8.6 Typographic Conventions

This document uses the typographic and illustrative conventions described below:

Plain text	The normal text typeface is used for the vast majority of the descriptive text in a specification.
<u>Plain text (blue)</u>	Any <u>plain text</u> that is underlined and in blue indicates an active link to the cross-reference. Click on the word to follow the hyperlink.
Bold	In text, a Bold typeface identifies a processor register name. In other instances, a Bold typeface can be used as a running head within a paragraph.
<i>Italic</i>	In text, an <i>Italic</i> typeface can be used as emphasis to introduce a new term or to indicate a manual or specification name.
BOLD Monospace	Computer code, example code segments, and all prototype code segments use a BOLD Monospace typeface with a dark red color. These code listings normally appear in one or more separate paragraphs, though words or segments can also be embedded in a normal text paragraph.
<u>Bold Monospace</u>	Words in a <u>Bold Monospace</u> typeface that is underlined and in blue indicate an active hyperlink to the code definition for that function or type definition. Click on the word to follow the hyperlink.

Note: *Due to management and file size considerations, only the first occurrence of the reference on each page is an active link. Subsequent references on the same page will not be actively linked to the definition and will use the standard, nonunderlined **BOLD Monospace** typeface. Find the first instance of the name (in the underlined **BOLD Monospace** typeface) on the page and click on the word to jump to the function or type definition.*

<i>Italic Monospace</i>	In code or in text, words in <i>Italic Monospace</i> indicate placeholder names for variable information that must be supplied (i.e., arguments).
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2 Overview

UEFI allows the extension of platform firmware by loading UEFI driver and UEFI application images. When UEFI drivers and UEFI applications are loaded they have access to all UEFI-defined runtime and boot services. See [Figure 2](#).

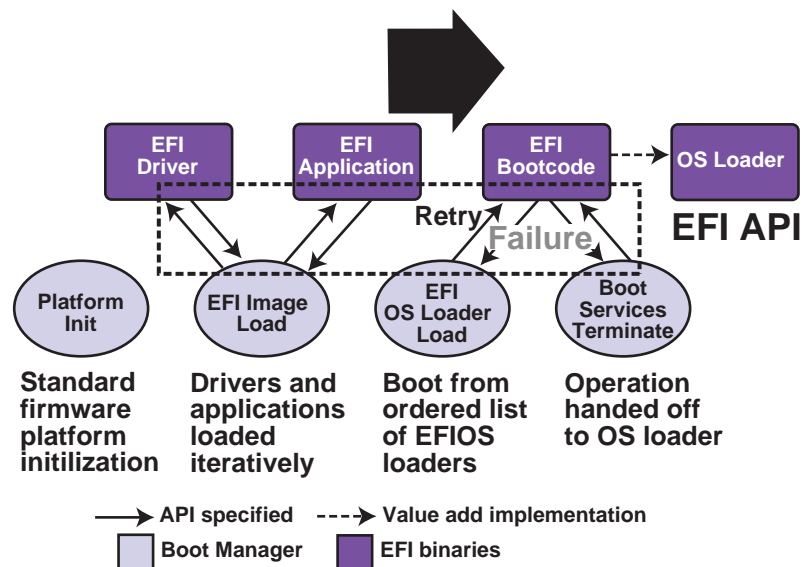


Figure 2. Booting Sequence

UEFI allows the consolidation of boot menus from the OS loader and platform firmware into a single platform firmware menu. These platform firmware menus will allow the selection of any UEFI OS loader from any partition on any boot medium that is supported by UEFI boot services. An UEFI OS loader can support multiple options that can appear on the user interface. It is also possible to include legacy boot options, such as booting from the A: or C: drive in the platform firmware boot menu.

UEFI supports booting from media that contain an UEFI OS loader or an UEFI-defined System Partition. An UEFI-defined System Partition is required by UEFI to boot from a block device. UEFI does not require any change to the first sector of a partition, so it is possible to build media that will boot on both legacy architectures and UEFI platforms.

2.1 Boot Manager

UEFI contains a boot manager that allows the loading of applications written to this specification (including OS 1st stage loader) or UEFI drivers from any file on an UEFI-defined file system or through the use of an UEFI-defined image loading service. UEFI defines NVRAM variables that are

used to point to the file to be loaded. These variables also contain application-specific data that are passed directly to the UEFI application. The variables also contain a human readable Unicode string that can be displayed in a menu to the user.

The variables defined by UEFI allow the system firmware to contain a boot menu that can point to all of the operating systems, and even multiple versions of the same operating systems. The design goal of UEFI was to have one set of boot menus that could live in platform firmware. UEFI specifies only the NVRAM variables used in selecting boot options. UEFI leaves the implementation of the menu system as value added implementation space.

UEFI greatly extends the boot flexibility of a system over the current state of the art in the PC-AT-class system. The PC-AT-class systems today are restricted to boot from the first floppy, hard drive, CD-ROM, USB keys, or network card attached to the system. Booting from a common hard drive can cause many interoperability problems between operating systems, and different versions of operating systems from the same vendor.

2.1.1 UEFI Images

UEFI Images are a class of files defined by UEFI that contain executable code. The most distinguishing feature of UEFI Images is that the first set of bytes in the UEFI Image file contains an image header that defines the encoding of the executable image.

UEFI uses a subset of the PE32+ image format with a modified header signature. The modification to the signature value in the PE32+ image is done to distinguish UEFI images from normal PE32 executables. The “+” addition to PE32 provides the 64-bit relocation fix-up extensions to standard PE32 format.

For images with the UEFI image signature, the *Subsystem* values in the PE image header are defined below. The major differences between image types are the memory type that the firmware will load the image into, and the action taken when the image’s entry point exits or returns. An application image is always unloaded when control is returned from the image’s entry point. A driver image is only unloaded if control is passed back with a UEFI error code.

```
// PE32+ Subsystem type for EFI images
#define EFI_IMAGE_SUBSYSTEM_EFI_APPLICATION      10
#define EFI_IMAGE_SUBSYSTEM_EFI_BOOT_SERVICE_DRIVER 11
#define EFI_IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER  12
```

Table 2. UEFI Image Memory Types

Subsystem Type	Code Memory Type	Data Memory Type
EFI_IMAGE_SUSBSYSTEM_EFI_APPLICATION	EfiLoaderCode	EfiLoaderData
EFI_IMAGE_SUBSYSMTE_EFI_BOOT_SERVICES_DRIVER	EfiBootServiceCode	EfiBootServicesData
EFI_IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER	EfiRuntimeServicesCode	EfiRuntimeServicesData

The *Machine* value that is found in the PE image file header is used to indicate the machine code type of the image. The machine code types for images with the UEFI image signature are defined below. A given platform must implement the image type native to that platform and the image type for EFI Byte Code (EBC). Support for other machine code types is optional to the platform.

```
// PE32+ Machine type for EFI images
#define EFI_IMAGE_MACHINE_IA32      0x014c
#define EFI_IMAGE_MACHINE_IA64     0x0200
#define EFI_IMAGE_MACHINE_EBC       0x0EBC
#define EFI_IMAGE_MACHINE_x64      0x8664
```

An UEFI image is loaded into memory through the [LoadImage\(\)](#) Boot Service. This service loads an image with a PE32+ format into memory. This PE32+ loader is required to load all sections of the PE32+ image into memory. Once the image is loaded into memory, and the appropriate fix-ups have been performed, control is transferred to a loaded image at the *AddressOfEntryPoint* reference according to the normal indirect calling conventions of applications based on supported 32-bit or supported 64-bit processors. All other linkage to and from an UEFI image is done programmatically.

2.1.2 Applications

Applications written to this specification are loaded by the Boot Manager or by other UEFI applications. To load an application the firmware allocates enough memory to hold the image, copies the sections within the application to the allocated memory, and applies the relocation fix-ups needed. Once done, the allocated memory is set to be the proper type for code and data for the image. Control is then transferred to the application's entry point. When the application returns from its entry point, or when it calls the Boot Service [Exit\(\)](#), the application is unloaded from memory and control is returned to the UEFI component that loaded the application.

When the Boot Manager loads an application, the image handle may be used to locate the “load options” for the application. The load options are stored in nonvolatile storage and are associated with the application being loaded and executed by the Boot Manager.

2.1.3 UEFI OS Loaders

An OS loader is a special type of UEFI application that normally takes over control of the system from firmware conforming to this specification. When loaded, the OS loader behaves like any other UEFI application in that it must only use memory it has allocated from the firmware and can only use UEFI services and protocols to access the devices that the firmware exposes. If the OS Loader includes any boot service style driver functions, it must use the proper UEFI interfaces to obtain access to the bus specific-resources. That is, I/O and memory-mapped device registers must be accessed through the proper bus specific I/O calls like those that an UEFI driver would perform.

If the OS loader experiences a problem and cannot load its operating system correctly, it can release all allocated resources and return control back to the firmware via the Boot Service [Exit\(\)](#) call. The [Exit\(\)](#) call allows both an error code and *ExitData* to be returned. The *ExitData* contains both a Unicode string and OS loader-specific data to be returned.

If the OS loader successfully loads its operating system, it can take control of the system by using the Boot Service [ExitBootServices\(\)](#). After successfully calling [ExitBootServices\(\)](#), all boot services in the system are terminated, including memory management, and the OS loader is responsible for the continued operation of the system.

2.1.4 UEFI Drivers

UEFI Drivers are loaded by the Boot Manager, firmware conforming to this specification, or by other UEFI applications. To load an UEFI Driver the firmware allocates enough memory to hold the image, copies the sections within the driver to the allocated memory and applies the relocation fix-ups needed. Once done, the allocated memory is set to be the proper type for code and data for the image. Control is then transferred to the driver's entry point. When the driver returns from its entry point, or when it calls the Boot Service [Exit\(\)](#), the driver is optionally unloaded from memory and control is returned to the component that loaded the driver. A driver is not unloaded from memory if it returns a status code of **EFI_SUCCESS**. If the driver's return code is an error status code, then the driver is unloaded from memory.

There are two types of UEFI Drivers. These are Boot Service Drivers and Runtime Drivers. The only difference between these two driver types is that Runtime Drivers are available after an OS Loader has taken control of the platform with the Boot Service [ExitBootServices\(\)](#).

Boot Service Drivers are terminated when [ExitBootServices\(\)](#) is called, and all the memory resources consumed by the Boot Service Drivers are released for use in the operating system environment. A runtime driver of type `EFI_IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER` gets fixed up with virtual mappings when the OS calls [SetVirtualAddressMap\(\)](#).

2.2 Firmware Core

This section provides an overview of the services defined by UEFI. These include boot services and runtime services.

2.2.1 UEFI Services

The purpose of the UEFI interfaces is to define a common boot environment abstraction for use by loaded UEFI images, which include UEFI drivers, UEFI applications, and UEFI OS loaders. The calls are defined with a full 64-bit interface, so that there is headroom for future growth. The goal of this set of abstracted platform calls is to allow the platform and OS to evolve and innovate independently of one another. Also, a standard set of primitive runtime services may be used by operating systems.

Platform interfaces defined in this section allow the use of standard Plug and Play Option ROMs as the underlying implementation methodology for the boot services. The interfaces have been designed in such a way as to map back into legacy interfaces. These interfaces have in no way been burdened with any restrictions inherent to legacy Option ROMs.

The UEFI platform interfaces are intended to provide an abstraction between the platform and the OS that is to boot on the platform. The UEFI specification also provides abstraction between diagnostics or utility programs and the platform; however, it does not attempt to implement a full diagnostic OS environment. It is envisioned that a small diagnostic OS-like environment can be easily built on top of an UEFI system. Such a diagnostic environment is not described by this specification.

Interfaces added by this specification are divided into the following categories and are detailed later in this document:

- Runtime services

- Boot services interfaces, with the following subcategories:
 - Global boot service interfaces
 - Device handle-based boot service interfaces
 - Device protocols
 - Protocol services

2.2.2 Runtime Services

This section describes UEFI runtime service functions. The primary purpose of the runtime services is to abstract minor parts of the hardware implementation of the platform from the OS. Runtime service functions are available during the boot process and also at runtime provided the OS switches into flat physical addressing mode to make the runtime call. However, if the OS loader or OS uses the Runtime Service [SetVirtualAddressMap\(\)](#) service, the OS will only be able to call runtime services in a virtual addressing mode. All runtime interfaces are non-blocking interfaces and can be called with interrupts disabled if desired.

In all cases memory used by the runtime services must be reserved and not used by the OS. runtime services memory is always available to an UEFI function and will never be directly manipulated by the OS or its components. UEFI is responsible for defining the hardware resources used by runtime services, so the OS can synchronize with those resources when runtime service calls are made, or guarantee that the OS never uses those resources.

[Table 3](#) lists the Runtime Services functions.

Table 3. UEFI Runtime Services

Name	Description
GetTime()	Returns the current time, time context, and time keeping capabilities.
SetTime()	Sets the current time and time context.
GetWakeupTime()	Returns the current wakeup alarm settings.
SetWakeupTime()	Sets the current wakeup alarm settings.
GetVariable()	Returns the value of a named variable.
GetNextVariableName()	Enumerates variable names.
SetVariable()	Sets, and if needed creates, a variable.
SetVirtualAddressMap()	Switches all runtime functions from physical to virtual addressing.
ConvertPointer()	Used to convert a pointer from physical to virtual addressing.
GetNextHighMonotonicCount()	Subsumes the platform's monotonic counter functionality.
ResetSystem()	Resets all processors and devices and reboots the system.
UpdateCapsule()	Passes capsules to the firmware with both virtual and physical mapping.

QueryCapsuleCapabilities ()	Returns if the capsule can be supported via UpdateCapsule () .
QueryVariableInfo ()	Returns information about the EFI variable store.

2.3 Calling Conventions

Unless otherwise stated, all functions defined in the UEFI specification are called through pointers in common, architecturally defined, calling conventions found in C compilers. Pointers to the various global UEFI functions are found in the **EFI_RUNTIME_SERVICES** and **EFI_BOOT_SERVICES** tables that are located via the system table. Pointers to other functions defined in this specification are located dynamically through device handles. In all cases, all pointers to UEFI functions are cast with the word **EFIAPI**. This allows the compiler for each architecture to supply the proper compiler keywords to achieve the needed calling conventions. When passing pointer arguments to Boot Services, Runtime Services, and Protocol Interfaces, the caller has the following responsibilities:

- It is the caller’s responsibility to pass pointer parameters that reference physical memory locations. If a pointer is passed that does not point to a physical memory location (i.e. a memory mapped I/O region), the results are unpredictable and the system may halt.
- It is the caller’s responsibility to pass pointer parameters with correct alignment. If an unaligned pointer is passed to a function, the results are unpredictable and the system may halt.
- It is the caller’s responsibility to not pass in a **NULL** parameter to a function unless it is explicitly allowed. If a **NULL** pointer is passed to a function, the results are unpredictable and the system may hang.
- Unless otherwise stated, a caller should not make any assumptions regarding the state of pointer parameters if the function returns with an error.
- A caller may not pass structures that are larger than native size by value and these structures must be passed by reference (via a pointer) by the caller. Passing a structure larger than native width (4 bytes on supported 32-bit processors; 8 bytes on supported 64-bit processor instructions) on the stack will produce undefined results.

Calling conventions for supported 32-bit and supported 64-bit applications are described in more detail below. Any function or protocol may return any valid return code.

All public interfaces of a UEFI module must follow the UEFI calling convention. Public interfaces include the image entry point, UEFI event handlers, and protocol member functions. The type **EFIAPI** is used to indicate conformance to the calling conventions defined in this section. Non public interfaces, such as private functions and static library calls, are not required to follow the UEFI calling conventions and may be optimized by the compiler.

2.3.1 Data Types

[Table 4](#) lists the common data types that are used in the interface definitions, and [Table 5](#) lists their modifiers. Unless otherwise specified all data types are naturally aligned. Structures are aligned on boundaries equal to the largest internal datum of the structure and internal data are implicitly padded to achieve natural alignment.

Table 4. Common UEFI Data Types

Mnemonic	Description
BOOLEAN	Logical Boolean. 1-byte value containing a 0 for FALSE or a 1 for TRUE . Other values are undefined.
INTN	Signed value of native width. (4 bytes on supported 32-bit processor instructions, 8 bytes on supported 64-bit processor instructions)
UINTN	Unsigned value of native width. (4 bytes on supported 32-bit processor instructions, 8 bytes on supported 64-bit processor instructions)
INT8	1-byte signed value.
UINT8	1-byte unsigned value.
INT16	2-byte signed value.
UINT16	2-byte unsigned value.
INT32	4-byte signed value.
UINT32	4-byte unsigned value.
INT64	8-byte signed value.
UINT64	8-byte unsigned value.
CHAR8	1-byte Character.
CHAR16	2-byte Character. Unless otherwise specified all strings are stored in the UTF-16 encoding format as defined by Unicode 2.1 and ISO/IEC 10646 standards.
VOID	Undeclared type.
EFI_GUID	128-bit buffer containing a unique identifier value. Unless otherwise specified, aligned on a 64-bit boundary.
EFI_STATUS	Status code. Type INTN.
EFI_HANDLE	A collection of related interfaces. Type VOID *.
EFI_EVENT	Handle to an event structure. Type VOID *.
EFI_LBA	Logical block address. Type UINT64.
EFI_TPL	Task priority level. Type UINTN.
EFI_MAC_ADDRESS	32-byte buffer containing a network Media Access Control address.
EFI_IPv4_ADDRESS	4-byte buffer. An IPv4 internet protocol address.
EFI_IPv6_ADDRESS	16-byte buffer. An IPv6 internet protocol address.
EFI_IP_ADDRESS	16-byte buffer aligned on a 4-byte boundary. An IPv4 or IPv6 internet protocol address.
<Enumerated Type>	Element of a standard ANSI C enum type declaration. Type INT32.
sizeof (VOID *)	4 bytes on supported 32-bit processor instructions. 8 bytes on supported 64-bit processor instructions.

Table 5. Modifiers for Common UEFI Data Types

Mnemonic	Description
IN	Datum is passed to the function.
OUT	Datum is returned from the function.

OPTIONAL	Passing the datum to the function is optional, and a NULL may be passed if the value is not supplied.
CONST	Datum is read-only.
EFIAPI	Defines the calling convention for UEFI interfaces.

2.3.2 IA-32 Platforms

All functions are called with the C language calling convention. The general-purpose registers that are volatile across function calls are **eax**, **ecx**, and **edx**. All other general-purpose registers are nonvolatile and are preserved by the target function. In addition, unless otherwise specified by the function definition, all other registers are preserved.

Firmware boot services and runtime services run in the following processor execution mode prior to the OS calling `ExitBootServices()`:

- Uniprocessor
- Protected mode
- Paging mode not enabled
- Selectors are set to be flat and are otherwise not used
- Interrupts are enabled—though no interrupt services are supported other than the UEFI boot services timer functions (All loaded device drivers are serviced synchronously by “polling.”)
- Direction flag in EFLAGS is clear
- Other general purpose flag registers are undefined
- 128 KB, or more, of available stack space

An application written to this specification may alter the processor execution mode, but the UEFI image must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

After an Operating System calls `ExitBootServices()`, firmware boot services are no longer available and it is illegal to call any boot service. After `ExitBootServices`, firmware runtime services are still available and may be called with paging enabled and virtual address pointers if `SetVirtualAddressMap()` has been called describing all virtual address ranges used by the firmware runtime service.

For an operating system to use any UEFI runtime services, it must:

- Preserve all memory in the memory map marked as runtime code and runtime data
- Call the runtime service functions, with the following conditions:
 - In protected mode
 - Paging may or may *not* be enabled, however if paging is enabled and `SetVirtualAddressMap()` has not been called, any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation. See description of [SetVirtualAddressMap\(\)](#) for details of memory map after this function has been called.
 - Direction flag in EFLAGS clear
 - 4 KB, or more, of available stack space

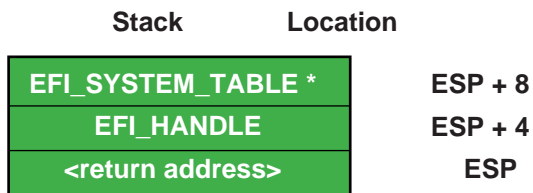
- Interrupts disabled or enabled at the discretion of the caller
- ACPI Tables loaded at boot time can be contained in memory of type **EfiACPIReclaimMemory** (recommended) or **EfiACPIMemoryNVS**. ACPI FACS must be contained in memory of type **EfiACPIMemoryNVS**.
- The system firmware must not request a virtual mapping for any memory descriptor of type **EfiACPIReclaimMemory** or **EfiACPIMemoryNVS**.
- EFI memory descriptors of type **EfiACPIReclaimMemory** and **EfiACPIMemoryNVS** must be aligned on a 4 KB boundary and must be a multiple of 4 KB in size.
- Any UEFI memory descriptor that requests a virtual mapping via the **EFI_MEMORY_DESCRIPTOR** having the **EFI_MEMORY_RUNTIME** bit set must be aligned on a 4 KB boundary and must be a multiple of 4 KB in size.
- An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.
- ACPI tables loaded at runtime must be contained in memory of type **EfiACPIMemoryNVS**. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.
- In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type **EfiRuntimeServicesData** (recommended and the system firmware must not request a virtual mapping), **EfiBootServicesdata**, **EfiACPIReclaimMemory** or **EfiACPIMemoryNVS**. Tables loaded at runtime must be contained in memory of type **EfiRuntimeServicesData** (recommended) or **EfiACPIMemoryNVS**.

Note: *Previous EFI specifications allowed ACPI tables loaded at runtime to be in the **EfiReservedMemoryType** and there was no guidance provided for other EFI Configuration Tables. **EfiReservedMemoryType** is not intended to be used by firmware. UEFI 2.0 intends to clarify the situation moving forward. Also, only OSes conforming to UEFI 2.0 are guaranteed to handle SMBIOS table in memory of type **EfiBootServicesdata**.*

2.3.2.1 Handoff State

When a 32-bit UEFI OS is loaded, the system firmware hands off control to the OS in flat 32-bit mode. All descriptors are set to their 4 GB limits so that all of memory is accessible from all segments.

[Figure 3](#) shows the stack after *AddressOfEntryPoint* in the image's PE32+ header has been called on supported 32-bit systems. All UEFI image entry points take two parameters. These are the image handle of the UEFI image, and a pointer to the EFI System Table.



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Figure 3. Stack after `AddressOfEntryPoint` Called, IA- 32

2.3.3 Intel® Itanium®-Based Platforms

UEFI executes as an extension to the SAL execution environment with the same rules as laid out by the SAL specification.

During boot services time the processor is in the following execution mode:

- Uniprocessor
- Physical mode
- 128 KB, or more, of available stack space
- 16 KB, or more, of available backing store space
- May only use the lower 32 floating point registers

An application written to this specification may alter the processor execution mode, but the UEFI image must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

After an Operating System calls `ExitBootServices()`, firmware boot services are no longer available and it is illegal to call any boot service. After `ExitBootServices`, firmware runtime services are still available. When calling runtime services, paging may or may not be enabled, however if paging is enabled and `SetVirtualAddressMap()` has not been called, any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation. See description of [SetVirtualAddressMap\(\)](#) for details of memory map after this function has been called. After `ExitBootServices()`, runtime service functions may be called with interrupts disabled or enabled at the discretion of the caller.

- ACPI Tables loaded at boot time can be contained in memory of type `EfiACPIReclaimMemory` (recommended) or `EfiACPIMemoryNVS`. ACPI FACS must be contained in memory of type `EfiACPIMemoryNVS`.
- The system firmware must not request a virtual mapping for any memory descriptor of type `EfiACPIReclaimMemory` or `EfiACPIMemoryNVS`.
- EFI memory descriptors of type `EfiACPIReclaimMemory` and `EfiACPIMemoryNVS` must be aligned on an 8 KB boundary and must be a multiple of 8 KB in size.
- Any UEFI memory descriptor that requests a virtual mapping via the `EFI_MEMORY_DESCRIPTOR` having the `EFI_MEMORY_RUNTIME` bit set must be aligned on an 8 KB boundary and must be a multiple of 8 KB in size.

- An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.
- ACPI tables loaded at runtime must be contained in memory of type **EfiACPIMemoryNVS**. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.
- In general, Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type **EfiRuntimeServicesData** (recommended and the system firmware must not request a virtual mapping), **EfiBootServicesdata**, **EfiACPIReclaimMemory** or **EfiACPIMemoryNVS**. Tables loaded at runtime must be contained in memory of type **EfiRuntimeServicesData** (recommended) or **EfiACPIMemoryNVS**.

Note: Previous EFI specifications allowed ACPI tables loaded at runtime to be in the *EfiReservedMemoryType* and there was no guidance provided for other EFI Configuration Tables. *EfiReservedMemoryType* is not intended to be used by firmware. UEFI 2.0 intends to clarify the situation moving forward. Also, only OSes conforming to UEFI 2.0 are guaranteed to handle SMBIOS table in memory of type *EfiBootServicesdata*.

Refer to the *IA-64 System Abstraction Layer Specification* (see [Appendix Q](#)) for details.

UEFI procedures are invoked using the P64 C calling conventions defined for Intel® Itanium®-based applications. Refer to the document *64 Bit Runtime Architecture and Software Conventions for IA-64* (see [Appendix Q](#)) for more information.

2.3.3.1 Handoff State

UEFI uses the standard P64 C calling conventions that are defined for Itanium-based operating systems. [Figure 4](#) shows the stack after **ImageEntryPoint** has been called on Itanium-based systems. The arguments are also stored in registers: **out0** contains **EFI_HANDLE** and **out1** contains the address of the **EFI_SYSTEM_TABLE**. The **gp** for the UEFI Image will have been loaded from the *plabel* pointed to by the *AddressOfEntryPoint* in the image’s PE32+ header. All UEFI image entry points take two parameters. These are the image handle of the image, and a pointer to the System Table.

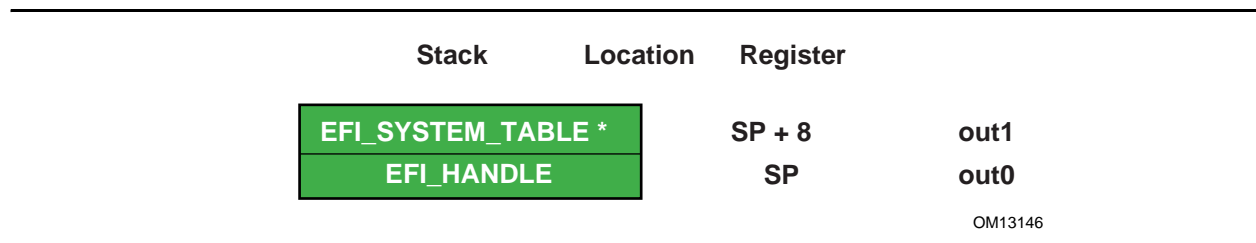


Figure 4. Stack after *AddressOfEntryPoint* Called, Itanium-based Systems

The SAL specification (see [Appendix Q](#)) defines the state of the system registers at boot handoff. The SAL specification also defines which system registers can only be used after UEFI boot services have been properly terminated.

2.3.4 x64 Platforms

All functions are called with the C language calling convention. See [Section 2.3.4.2](#) for more detail. During boot services time the processor is in the following execution mode:

- Uniprocessor
- Long mode, in 64-bit mode
- Paging mode is enabled and any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation.
- Selectors are set to be flat and are otherwise not used.
- Interrupts are enabled—though no interrupt services are supported other than the UEFI boot services timer functions (All loaded device drivers are serviced synchronously by “polling.”)
- Direction flag in EFLAGS is clear
- Other general purpose flag registers are undefined
- 128 KB, or more, of available stack space

For an operating system to use any UEFI runtime services, it must:

- Preserve all memory in the memory map marked as runtime code and runtime data
- Call the runtime service functions, with the following conditions:
- In long mode, in 64-bit mode
- Paging enabled
- All selectors set to be flat with virtual = physical address. If the OS Loader or OS used **SetVirtualAddressMap()** to relocate the runtime services in a virtual address space, then this condition does not have to be met. See description of [SetVirtualAddressMap\(\)](#) for details of memory map after this function has been called.
- Direction flag in EFLAGS clear
- 4 KB, or more, of available stack space
- Interrupts may be disabled or enabled at the discretion of the caller.
- ACPI Tables loaded at boot time can be contained in memory of type **EfiACPIReclaimMemory** (recommended) or **EfiACPIMemoryNVS**. ACPI FACS must be contained in memory of type **EfiACPIMemoryNVS**.
- The system firmware must not request a virtual mapping for any memory descriptor of type **EfiACPIReclaimMemory** or **EfiACPIMemoryNVS**.
- EFI memory descriptors of type **EfiACPIReclaimMemory** and **EfiACPIMemoryNVS** must be aligned on a 4 KB boundary and must be a multiple of 4 KB in size.

- Any UEFI memory descriptor that requests a virtual mapping via the **EFI_MEMORY_DESCRIPTOR** having the **EFI_MEMORY_RUNTIME** bit set must be aligned on a 4 KB boundary and must be a multiple of 4 KB in size.
- An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.
- ACPI tables loaded at runtime must be contained in memory of type **EfiACPIMemoryNVS**. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached..
- In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type **EfiRuntimeServicesData** (recommended and the system firmware must not request a virtual mapping), **EfiBootServicesdata**, **EfiACPIReclaimMemory** or **EfiACPIMemoryNVS**. Tables loaded at runtime must be contained in memory of type **EfiRuntimeServicesData** (recommended) or **EfiACPIMemoryNVS**.

Note: *Previous EFI specifications allowed ACPI tables loaded at runtime to be in the **EfiReservedMemoryType** and there was no guidance provided for other EFI Configuration Tables. **EfiReservedMemoryType** is not intended to be used by firmware. UEFI 2.0 intends to clarify the situation moving forward. Also, only OSes conforming to UEFI 2.0 are guaranteed to handle SMBIOS table in memory of type **EfiBootServicesdata**.*

2.3.4.1 Handoff State

Rcx – EFI_HANDLE

Rdx – EFI_SYSTEM_TABLE *

RSP - <return address>

2.3.4.2 Detailed Calling Conventions

The caller passes the first four integer arguments in registers. The integer values are passed from left to right in Rcx, Rdx, R8, and R9 registers. The caller passes arguments five and above onto the stack. All arguments must be right-justified in the register in which they are passed. This ensures the callee can process only the bits in the register that are required.

The caller passes arrays and strings via a pointer to memory allocated by the caller. The caller passes structures and unions of size 8, 16, 32, or 64 bits as if they were integers of the same size. The caller is not allowed to pass structures and unions of other than these sizes and must pass these unions and structures via a pointer.

The callee must dump the register parameters into their shadow space if required. The most common requirement is to take the address of an argument.

If the parameters are passed through `varargs` then essentially the typical parameter passing applies, including spilling the fifth and subsequent arguments onto the stack. The callee must dump the arguments that have their address taken.

Return values that fit into 64-bits are returned in the Rax register. If the return value does not fit within 64-bits, then the caller must allocate and pass a pointer for the return value as the first argument, Rcx. Subsequent arguments are then shifted one argument to the right, so for example argument one would be passed in Rdx. User-defined types to be returned must be 1,2,4,8,16,32, or 64 bits in length.

The registers Rax, Rcx Rdx R8, R9, R10, R11, and XMM0-XMM5 are volatile and are, therefore, destroyed on function calls.

The registers RBX, RBP, RDI, RSI, R12, R13, R14, R15, and XMM6-XMM15 are considered nonvolatile and must be saved and restored by a function that uses them.

Function pointers are pointers to the label of the respective function and don't require special treatment.

2.3.4.3 Enabling Paging or Alternate Translations in an Application

Boot Services define an execution environment where paging is not enabled (supported 32-bit) or where translations are enabled but mapped virtual equal physical (x64) and this section will describe how to write an application with alternate translations or with paging enabled. Some Operating Systems require the OS Loader to be able to enable OS required translations at Boot Services time.

If a UEFI application uses its own page tables, GDT or IDT, the application must ensure that the firmware executes with each supplanted data structure. There are two ways that firmware conforming to this specification can execute when the application has paging enabled.

- Explicit firmware call
- Firmware preemption of application via timer event

An application with translations enabled can restore firmware required mapping before each UEFI call. However the possibility of preemption may require the translation enabled application to disable interrupts while alternate translations are enabled. It's legal for the translation enabled application to enable interrupts if the application catches the interrupt and restores the EFI firmware environment prior to calling the UEFI interrupt ISR. After the UEFI ISR context is executed it will return to the translation enabled application context and restore any mappings required by the application.

2.4 Protocols

The protocols that a device handle supports are discovered through the [HandleProtocol \(\)](#) Boot Service or the [OpenProtocol \(\)](#) Boot Service. Each protocol has a specification that includes the following:

- The protocol's globally unique ID (GUID)
- The Protocol Interface structure
- The Protocol Services

Unless otherwise specified a protocol's interface structure is not allocated from runtime memory and the protocol member functions should not be called at runtime. If not explicitly specified a protocol member function can be called at a TPL level of less than or equal to **TPL_NOTIFY** (see [Section 6.1](#)). Unless otherwise specified a protocol's member function is not reentrant or MP safe.

Any status codes defined by the protocol member function definition are required to be implemented, Additional error codes may be returned, but they will not be tested by standard compliance tests, and any software that uses the procedure cannot depend on any of the extended error codes that an implementation may provide.

To determine if the handle supports any given protocol, the protocol's GUID is passed to **HandleProtocol ()** or **OpenProtocol ()**. If the device supports the requested protocol, a pointer to the defined Protocol Interface structure is returned. The Protocol Interface structure links the caller to the protocol-specific services to use for this device.

[Figure 5](#) shows the construction of a protocol. The UEFI driver contains functions specific to one or more protocol implementations, and registers them with the Boot Service **InstallProtocolInterface ()**. The firmware returns the Protocol Interface for the protocol that is then used to invoke the protocol specific services. The UEFI driver keeps private, device-specific context with protocol interfaces.

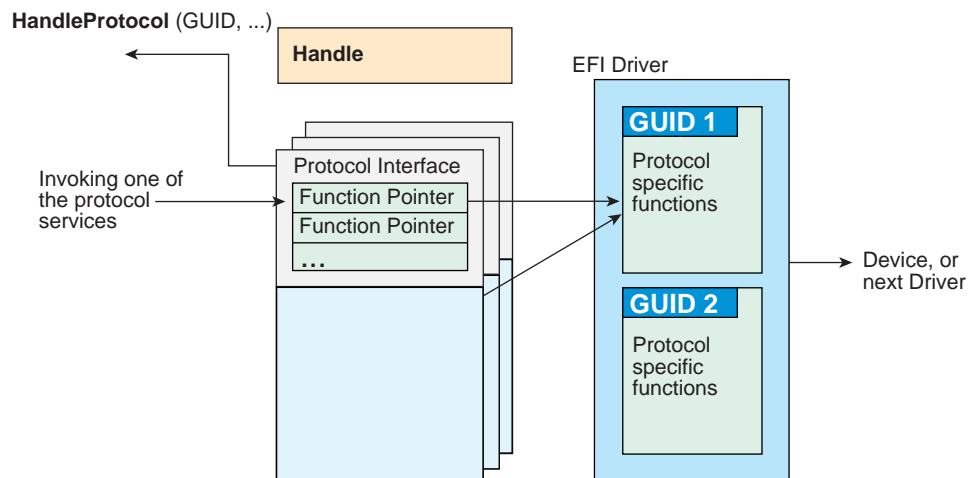


Figure 5. Construction of a Protocol

The following C code fragment illustrates the use of protocols:

```
// There is a global "EffectsDevice" structure. This
// structure contains information pertinent to the device.

// Connect to the ILLUSTRATION_PROTOCOL on the EffectsDevice,
// by calling HandleProtocol with the device's EFI device handle
// and the ILLUSTRATION_PROTOCOL GUID.

EffectsDevice.Handle = DeviceHandle;
Status = HandleProtocol (
    EffectsDevice.EFIHandle,
```


Unified Extensible Firmware Interface Specification

```

&IllustrationProtocolGuid,
    &EffectsDevice.IllustrationProtocol
);

// Use the EffectsDevice illustration protocol's "MakeEffects"
// service to make flashy and noisy effects.

Status = EffectsDevice.IllustrationProtocol->MakeEffects (
    EffectsDevice.IllustrationProtocol,
    TheFlashyAndNoisyEffect
);

```

Table 6 lists the UEFI protocols defined by this specification.

Table 6. UEFI Protocols

Protocol	Description
<u>EFI LOADED IMAGE PROTOCOL</u>	Provides information on the image.
<u>EFI DEVICE PATH PROTOCOL</u>	Provides the location of the device.
<u>EFI DRIVER BINDING PROTOCOL</u>	Provides services to determine if an UEFI driver supports a given controller, and services to start and stop a given controller.
<u>EFI PLATFORM DRIVER OVERRIDE PROTOCOL</u>	Provide a platform specific override mechanism for the selection of the best driver for a given controller.
<u>EFI BUS SPECIFIC DRIVER OVERRIDE PROTOCOL</u>	Provides a bus specific override mechanism for the selection of the best driver for a given controller.
<u>EFI DRIVER DIAGNOSTICS PROTOCOL</u>	Provides diagnostics services for the controllers that UEFI drivers are managing.
<u>EFI COMPONENT NAME2 PROTOCOL</u>	Provides human readable names for UEFI Drivers and the controllers that the drivers are managing.
<u>EFI SIMPLE TEXT INPUT PROTOCOL</u>	Protocol interfaces for devices that support simple console style text input.
<u>EFI SIMPLE TEXT OUTPUT PROTOCOL</u>	Protocol interfaces for devices that support console style text displaying.
<u>EFI SIMPLE POINTER PROTOCOL</u>	Protocol interfaces for devices such as mice and trackballs.
<u>EFI SERIAL IO PROTOCOL</u>	Protocol interfaces for devices that support serial character transfer.
<u>EFI LOAD FILE PROTOCOL</u>	Protocol interface for reading a file from an arbitrary device.
<u>EFI SIMPLE FILE SYSTEM PROTOCOL</u>	Protocol interfaces for opening disk volume containing a UEFI file system.
<u>EFI FILE PROTOCOL</u>	Provides access to supported file systems.
<u>EFI DISK IO PROTOCOL</u>	A protocol interface that layers onto any BLOCK_IO interface.
<u>EFI BLOCK IO PROTOCOL</u>	Protocol interfaces for devices that support block I/O style accesses.

<u>EFI UNICODE COLLATION PROTOCOL</u>	Protocol interfaces for Unicode string comparison operations.
<u>EFI PCI ROOT BRIDGE IO PROTOCOL</u>	Protocol interfaces to abstract memory, I/O, PCI configuration, and DMA accesses to a PCI root bridge controller.
<u>EFI PCI IO PROTOCOL</u>	Protocol interfaces to abstract memory, I/O, PCI configuration, and DMA accesses to a PCI controller on a PCI bus.
<u>EFI USB IO PROTOCOL</u>	Protocol interfaces to abstract access to a USB controller.
<u>EFI SIMPLE NETWORK PROTOCOL</u>	Provides interface for devices that support packet based transfers.
<u>EFI PXE BASE CODE PROTOCOL</u>	Protocol interfaces for devices that support network booting.
<u>EFI BIS PROTOCOL</u>	Protocol interfaces to validate boot images before they are loaded and invoked.
<u>EFI DEBUG SUPPORT PROTOCOL</u>	Protocol interfaces to save and restore processor context and hook processor exceptions.
<u>EFI DEBUG SUPPORT PROTOCOL</u>	Protocol interface that abstracts a byte stream connection between a debug host and a debug target system.
<u>EFI DECOMPRESS PROTOCOL</u>	Protocol interfaces to decompress an image that was compressed using the EFI Compression Algorithm.
DEVICE_IO	Protocol interfaces for performing device I/O.
<u>EFI EBC PROTOCOL</u>	Protocols interfaces required to support an EFI Byte Code interpreter.
<u>EFI GRAPHICS OUTPUT PROTOCOL</u>	Protocol interfaces for devices that support graphical output.
<u>EFI EXT SCSI PASS THRU PROTOCOL</u>	Protocol interfaces for a SCSI channel that allows SCSI Request Packets to be sent to SCSI devices.
<u>EFI USB2 HC PROTOCOL</u>	Protocol interfaces to abstract access to a USB Host Controller.
<u>EFI AUTHENTICATION INFO PROTOCOL</u>	Provides access for generic authentication information associated with specific device paths
<u>EFI DEVICE PATH UTILITIES PROTOCOL</u>	Aids in creating and manipulating device paths.
<u>EFI DEVICE PATH TO TEXT PROTOCOL</u>	Converts device nodes and paths to text.
<u>EFI DEVICE PATH FROM TEXT PROTOCOL</u>	Converts text to device paths and device nodes.
<u>EFI EDID DISCOVERED PROTOCOL</u>	Contains the EDID information retrieved from a video output device.
<u>EFI EDID ACTIVE PROTOCOL</u>	Contains the EDID information for an active video output device.
<u>EFI EDID OVERRIDE PROTOCOL</u>	Produced by the platform to allow the platform to provide EDID information to the producer of the Graphics Output protocol

<u>EFI ISCSI INITIATOR NAME PROTOCOL</u>	Sets and obtains the iSCSI Initiator Name.
<u>EFI TAPE IO PROTOCOL</u>	Provides services to control and access a tape drive.
<u>EFI MANAGED NETWORK PROTOCOL</u>	Used to locate communication devices that are supported by an MNP driver and create and destroy instances of the MNP child protocol driver that can use the underlying communications devices.
<u>EFI ARP SERVICE BINDING PROTOCOL</u>	Used to locate communications devices that are supported by an ARP driver and to create and destroy instances of the ARP child protocol driver.
<u>EFI ARP PROTOCOL</u>	Used to resolve local network protocol addresses into network hardware addresses.
<u>EFI DHCP4 SERVICE BINDING PROTOCOL</u>	Used to locate communication devices that are supported by an EFI DHCPv4 Protocol driver and to create and destroy EFI DHCPv4 Protocol child driver instances that can use the underlying communications devices.
<u>EFI DHCP4 PROTOCOL</u>	Used to collect configuration information for the EFI IPv4 Protocol drivers and to provide DHCPv4 server and PXE boot server discovery services.
<u>EFI TCP4 SERVICE BINDING PROTOCOL</u>	Used to locate EFI TCPv4Protocol drivers to create and destroy child of the driver to communicate with other host using TCP protocol.
<u>EFI TCP4 PROTOCOL</u>	Provides services to send and receive data stream.
<u>EFI IP4 SERVICE BINDING PROTOCOL</u>	Used to locate communication devices that are supported by an EFI IPv4 Protocol Driver and to create and destroy instances of the EFI IPv4 Protocol child protocol driver that can use the underlying communication device.
<u>EFI IP4 PROTOCOL</u>	Provides basic network IPv4 packet I/O services.
<u>EFI IP4 CONFIG PROTOCOL</u>	The EFI IPv4 Config Protocol driver performs platform- and policy-dependent configuration of the EFI IPv4 Protocol driver.
<u>EFI UDP4 SERVICE BINDING PROTOCOL</u>	Used to locate communication devices that are supported by an EFI UDPv4 Protocol driver and to create and destroy instances of the EFI UDPv4 Protocol child protocol driver that can use the underlying communication device.
<u>EFI UDP4 PROTOCOL</u>	Provides simple packet-oriented services to transmit and receive UDP packets.
<u>EFI MTFTP4 SERVICE BINDING PROTOCOL</u>	Used to locate communication devices that are supported by an EFI MTFTPv4 Protocol driver and to create and destroy instances of the EFI MTFTPv4 Protocol child protocol driver that can use the underlying communication device.
<u>EFI MTFTP4 PROTOCOL</u>	Provides basic services for client-side unicast or multicast TFTP operations.
<u>EFI HASH PROTOCOL</u>	Allows creating a hash of an arbitrary message digest using one or more hash algorithms.

EFI HASH SERVICE BINDING PROTOCOL	Used to locate hashing services support provided by a driver and create and destroy instances of the EFI Hash Protocol so that a multiple drivers can use the underlying hashing services.
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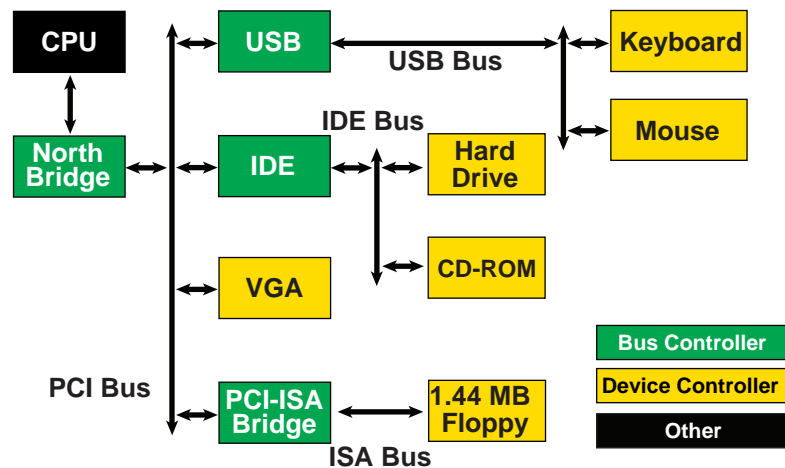
2.5 UEFI Driver Model

The UEFI *Driver Model* is intended to simplify the design and implementation of device drivers, and produce small executable image sizes. As a result, some complexity has been moved into bus drivers and in a larger part into common firmware services.

A device driver is required to produce a Driver Binding Protocol on the same image handle on which the driver was loaded. It then waits for the system firmware to connect the driver to a controller. When that occurs, the device driver is responsible for producing a protocol on the controller's device handle that abstracts the I/O operations that the controller supports. A bus driver performs these exact same tasks. In addition, a bus driver is also responsible for discovering any child controllers on the bus, and creating a device handle for each child controller found.

One assumption is that the architecture of a system can be viewed as a set of one or more processors connected to one or more core chipsets. The core chipsets are responsible for producing one or more I/O buses. The UEFI *Driver Model* does not attempt to describe the processors or the core chipsets. Instead, the UEFI *Driver Model* describes the set of I/O buses produced by the core chipsets, and any children of these I/O buses. These children can either be devices or additional I/O buses. This can be viewed as a tree of buses and devices with the core chipsets at the root of that tree.

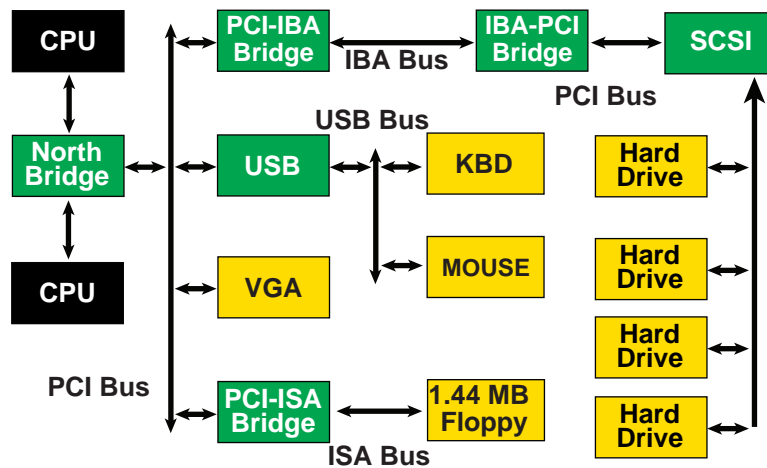
The leaf nodes in this tree structure are peripherals that perform some type of I/O. This could include keyboards, displays, disks, network, etc. The nonleaf nodes are the buses that move data between devices and buses, or between different bus types. [Figure 6](#) shows a sample desktop system with four buses and six devices.



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Figure 6. Desktop System

Figure 7 is an example of a more complex server system. The idea is to make the *UEFI Driver Model* simple and extensible so more complex systems like the one below can be described and managed in the preboot environment. This system contains six buses and eight devices.



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Figure 7. Server System

The combination of firmware services, bus drivers, and device drivers in any given platform is likely to be produced by a wide variety of vendors including OEMs, IBVs, and IHVs. These different components from different vendors are required to work together to produce a protocol for an I/O device than can be used to boot a UEFI compliant operating system. As a result, the *UEFI Driver Model* is described in great detail in order to increase the interoperability of these components.

This remainder of this section is a brief overview of the *UEFI Driver Model*. It describes the legacy option ROM issues that the *UEFI Driver Model* is designed to address, the entry point of a driver, host bus controllers, properties of device drivers, properties of bus drivers, and how the *UEFI Driver Model* can accommodate hot-plug events.

2.5.1 Legacy Option ROM Issues

Legacy option ROMs have a number of constraints and limitations that restrict innovation on the part of platform designers and adapter vendors. At the time of writing, both ISA and PCI adapters use legacy option ROMs. For the purposes of this discussion, only PCI option ROMs will be considered; legacy ISA option ROMs are not supported as part of the *UEFI Specification*.

The following is a list of the major constraints and limitations of legacy option ROMs. For each issue, the design considerations that went into the design of the *UEFI Driver Model* are also listed. Thus, the design of the *UEFI Driver Model* directly addresses the requirements for a solution to overcome the limitations implicit to PC-AT-style legacy option ROMs.

2.5.1.1 32-bit/16-Bit Real Mode Binaries

Legacy option ROMs typically contain 16-bit real mode code for an IA-32 processor. This means that the legacy option ROM on a PCI card cannot be used in platforms that do not support the

execution of IA-32 real mode binaries. Also, 16-bit real mode only allows the driver to access directly the lower 1 MB of system memory. It is possible for the driver to switch the processor into modes other than real mode in order to access resources above 1 MB, but this requires a lot of additional code, and causes interoperability issues with other option ROMs and the system BIOS. Also, option ROMs that switch the processor into to alternate execution modes are not compatible with Itanium Processors.

UEFI *Driver Model* design considerations:

- Drivers need flat memory mode with full access to system components.
- Drivers need to be written in C so they are portable between processor architectures.
- Drivers may be compiled into a virtual machine executable, allowing a single binary driver to work on machines using different processor architectures.

2.5.1.2 Fixed Resources for Working with Option ROMs

Since legacy option ROMs can only directly address the lower 1 MB of system memory, this means that the code from the legacy option ROM must exist below 1 MB. In a PC-AT platform, memory from 0x00000-0x9FFFF is system memory. Memory from 0xA0000-0xBFFFF is VGA memory, and memory from 0xF0000-0xFFFFF is reserved for the system BIOS. Also, since system BIOS has become more complex over the years, many platforms also use 0xE0000-0xEFFFF for system BIOS. This leaves 128 KB of memory from 0xC0000-0xDFFFF for legacy option ROMs. This limits how many legacy option ROMs can be run during BIOS POST.

Also, it is not easy for legacy option ROMs to allocate system memory. Their choices are to allocate memory from Extended BIOS Data Area (EBDA), allocate memory through a Post Memory Manager (PMM), or search for free memory based on a heuristic. Of these, only EBDA is standard, and the others are not used consistently between adapters, or between BIOS vendors, which adds complexity and the potential for conflicts.

UEFI *Driver Model* design considerations:

- Drivers need flat memory mode with full access to system components.
- Drivers need to be capable of being relocated so that they can be loaded anywhere in memory (PE/COFF Images)
- Drivers should allocate memory through the boot services. These are well-specified interfaces, and can be guaranteed to function as expected across a wide variety of platform implementations.

2.5.1.3 Matching Option ROMs to their Devices

It is not clear which controller may be managed by a particular legacy option ROM. Some legacy option ROMs search the entire system for controllers to manage. This can be a lengthy process depending on the size and complexity of the platform. Also, due to limitation in BIOS design, all the legacy option ROMs must be executed, and they must scan for all the peripheral devices before an operating system can be booted. This can also be a lengthy process, especially if SCSI buses must be scanned for SCSI devices. This means that legacy option ROMs are making policy decision about how the platform is being initialized, and which controllers are managed by which legacy option ROMs. This makes it very difficult for a system designer to predict how legacy option ROMs will

interact with each other. This can also cause issues with on-board controllers, because a legacy option ROM may incorrectly choose to manage the on-board controller.

UEFI *Driver Model* design considerations:

- Driver to controller matching must be deterministic
- Give OEMs more control through Platform Driver Override Protocol and Driver Configuration Protocol
- It must be possible to start only the drivers and controllers required to boot an operating system.

2.5.1.4 Ties to PC-AT System Design

Legacy option ROMs assume a PC-AT-like system architecture. Many of them include code that directly touches hardware registers. This can make them incompatible on legacy-free and headless platforms. Legacy option ROMs may also contain setup programs that assume a PC-AT-like system architecture to interact with a keyboard or video display. This makes the setup application incompatible on legacy-free and headless platforms.

UEFI *Driver Model* design considerations:

- Drivers should use well-defined protocols to interact with system hardware, system input devices, and system output devices.

2.5.1.5 Ambiguities in Specification and Workarounds Born of Experience

Many legacy option ROMs and BIOS code contain workarounds because of incompatibilities between legacy option ROMs and system BIOS. These incompatibilities exist in part because there are no clear specifications on how to write a legacy option ROM or write a system BIOS.

Also, interrupt chaining and boot device selection is very complex in legacy option ROMs. It is not always clear which device will be the boot device for the OS.

UEFI *Driver Model* design considerations:

- Drivers and firmware are written to follow this specification. Since both components have a clearly defined specification, compliance tests can be developed to prove that drivers and system firmware are compliant. This should eliminate the need to build workarounds into either drivers or system firmware (other than those that might be required to address specific hardware issues).
- Give OEMs more control through Platform Driver Override Protocol and Driver Configuration Protocol and other OEM value-add components to manage the boot device selection process.

2.5.2 Driver Initialization

The file for a driver image must be loaded from some type of media. This could include ROM, FLASH, hard drives, floppy drives, CD-ROM, or even a network connection. Once a driver image has been found, it can be loaded into system memory with the boot service [LoadImage \(\)](#). **LoadImage ()** loads a PE/COFF formatted image into system memory. A handle is created for the driver, and a Loaded Image Protocol instance is placed on that handle. A handle that contains a Loaded Image Protocol instance is called an *Image Handle*. At this point, the driver has not been started. It is just sitting in memory waiting to be started. [Figure 8](#) shows the state of an image handle for a driver after **LoadImage ()** has been called.

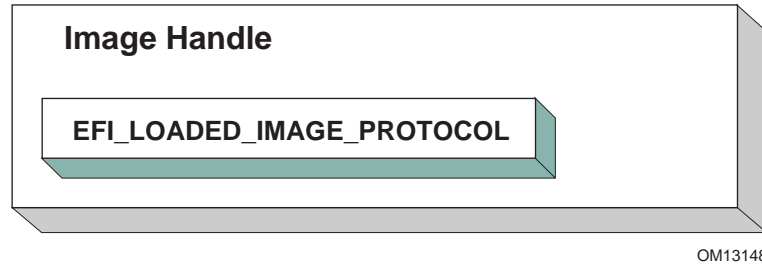


Figure 8. Image Handle

After a driver has been loaded with the boot service **LoadImage ()**, it must be started with the boot service **StartImage ()**. This is true of all types of UEFI Applications and UEFI Drivers that can be loaded and started on an UEFI-compliant system. The entry point for a driver that follows the UEFI *Driver Model* must follow some strict rules. First, it is not allowed to touch any hardware. Instead, the driver is only allowed to install protocol instances onto its own *Image Handle*. A driver that follows the UEFI *Driver Model* is *required* to install an instance of the Driver Binding Protocol onto its own *Image Handle*. It may optionally install the Driver Configuration Protocol, the Driver Diagnostics Protocol, or the Component Name Protocol. In addition, if a driver wishes to be unloadable it may optionally update the Loaded Image Protocol (see [Section 8](#)) to provide its own **Unload ()** function. Finally, if a driver needs to perform any special operations when the boot service **ExitBootServices ()** is called, it may optionally create an event with a notification function that is triggered when the boot service **ExitBootServices ()** is called. An *Image Handle* that contains a Driver Binding Protocol instance is known as a *Driver Image Handle*. [Figure 9](#) shows a possible configuration for the *Image Handle* from [Figure 8](#) after the boot service **StartImage ()** has been called.

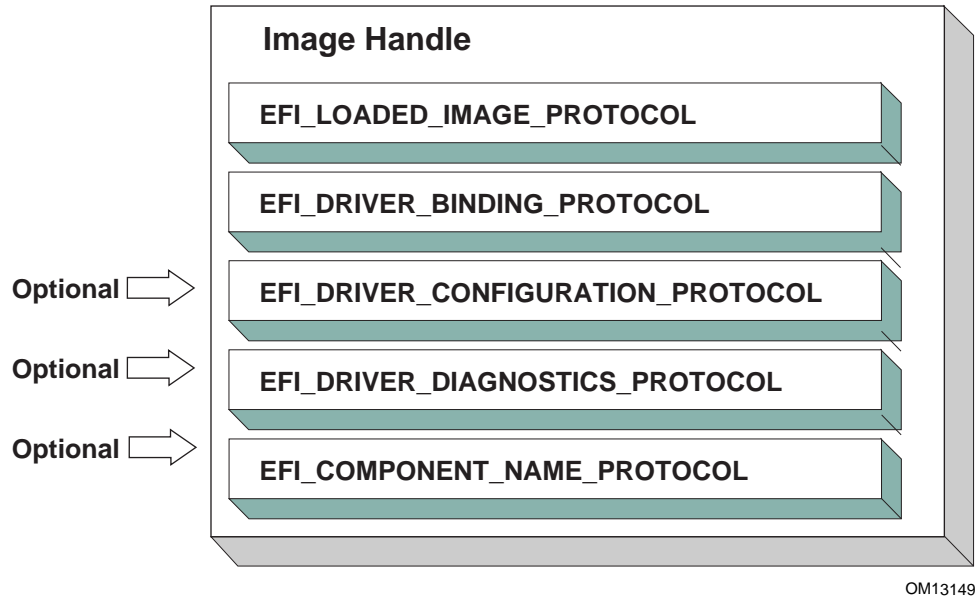
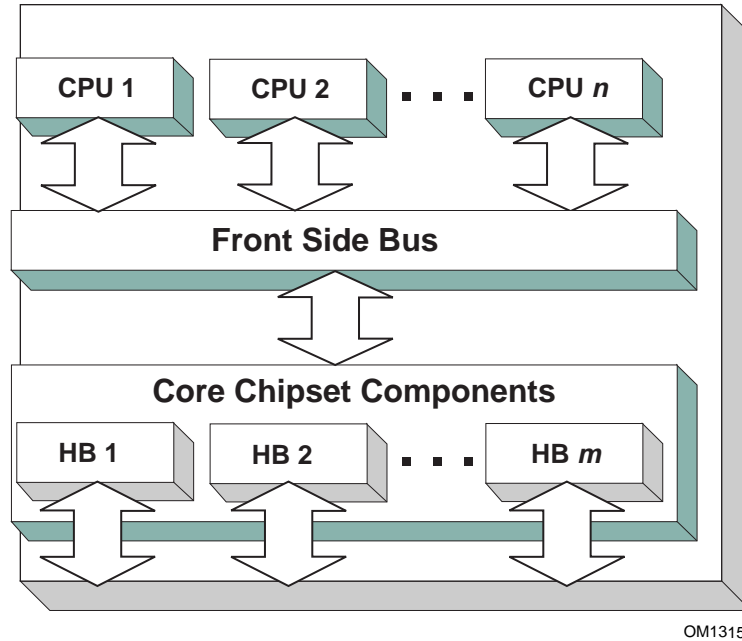


Figure 9. Driver Image Handle

2.5.3 Host Bus Controllers

Drivers are not allowed to touch any hardware in the driver’s entry point. As a result, drivers will be loaded and started, but they will all be waiting to be told to manage one or more controllers in the system. A platform component, like the Boot Manager, is responsible for managing the connection of drivers to controllers. However, before even the first connection can be made, there has to be some initial collection of controllers for the drivers to manage. This initial collection of controllers is known as the *Host Bus Controllers*. The I/O abstractions that the *Host Bus Controllers* provide are produced by firmware components that are outside the scope of the *UEFI Driver Model*. The device handles for the *Host Bus Controllers* and the I/O abstraction for each one must be produced by the core firmware on the platform, or a driver that may not follow the *UEFI Driver Model*. See the *PCI Root Bridge I/O Protocol Specification* for an example of an I/O abstraction for PCI buses.

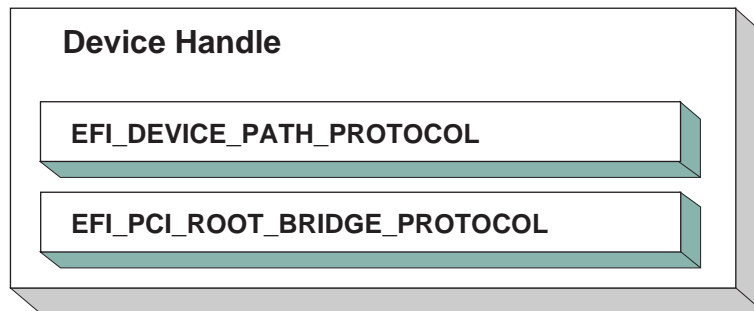
A platform can be viewed as a set of processors and a set of core chipset components that may produce one or more host buses. [Figure 10](#) shows a platform with n processors (CPUs), and a set of core chipset components that produce m host bridges.



OM13150

Figure 10. Host Bus Controllers

Each host bridge is represented in UEFI as a device handle that contains a Device Path Protocol instance, and a protocol instance that abstracts the I/O operations that the host bus can perform. For example, a PCI Host Bus Controller supports one or more PCI Root Bridges that are abstracted by the PCI Root Bridge I/O Protocol. [Figure 11](#) shows an example device handle for a PCI Root Bridge.



OM13151

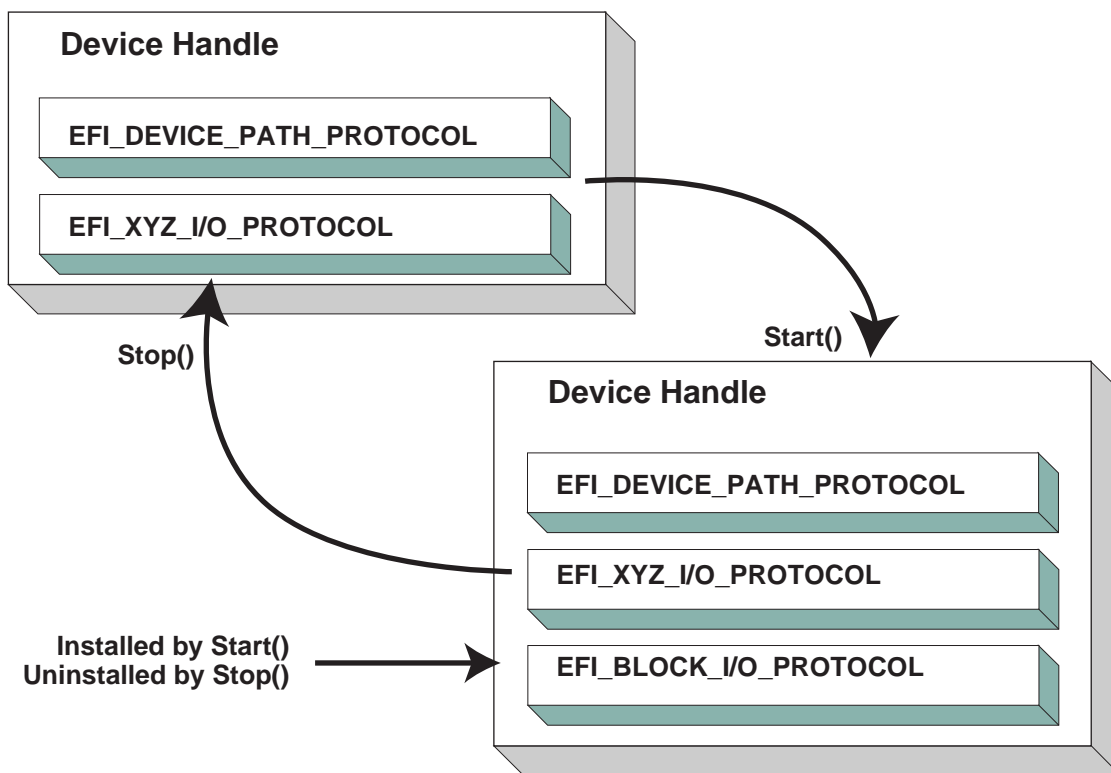
Figure 11. PCI Root Bridge Device Handle

A PCI Bus Driver could connect to this PCI Root Bridge, and create child handles for each of the PCI devices in the system. PCI Device Drivers should then be connected to these child handles, and produce I/O abstractions that may be used to boot a UEFI compliant OS. The following section describes the different types of drivers that can be implemented within the UEFI *Driver Model*. The UEFI *Driver Model* is very flexible, so all the possible types of drivers will not be discussed here.

Instead, the major types will be covered that can be used as a starting point for designing and implementing additional driver types.

2.5.4 Device Drivers

A device driver is not allowed to create any new device handles. Instead, it installs additional protocol interfaces on an existing device handle. The most common type of device driver will attach an I/O abstraction to a device handle that was created by a bus driver. This I/O abstraction may be used to boot a UEFI compliant OS. Some example I/O abstractions would include Simple Text Output, Simple Input, Block I/O, and Simple Network Protocol. [Figure 12](#) shows a device handle before and after a device driver is connected to it. In this example, the device handle is a child of the XYZ Bus, so it contains an XYZ I/O Protocol for the I/O services that the XYZ bus supports. It also contains a Device Path Protocol that was placed there by the XYZ Bus Driver. The Device Path Protocol is not required for all device handles. It is only required for device handles that represent physical devices in the system. Handles for virtual devices will not contain a Device Path Protocol.



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Figure 12. Connecting Device Drivers

The device driver that connects to the device handle in [Figure 12](#) must have installed a Driver Binding Protocol on its own image handle. The Driver Binding Protocol (see [Section 10.1](#)) contains three functions called `Supported()`, `Start()`, and `Stop()`. The `Supported()` function tests to see if the driver supports a given controller. In this example, the driver will check to see if the device handle supports the Device Path Protocol and the XYZ I/O Protocol. If a driver's

Supported() function passes, then the driver can be connected to the controller by calling the driver's **Start()** function. The **Start()** function is what actually adds the additional I/O protocols to a device handle. In this example, the Block I/O Protocol is being installed. To provide symmetry, the Driver Binding Protocol also has a **Stop()** function that forces the driver to stop managing a device handle. This will cause the device driver to uninstall any protocol interfaces that were installed in **Start()**.

The **Supported()**, **Start()**, and **Stop()** functions of the EFI Driver Binding Protocol are required to make use of the boot service [OpenProtocol\(\)](#) to get a protocol interface and the boot service [CloseProtocol\(\)](#) to release a protocol interface. **OpenProtocol()** and **CloseProtocol()** update the handle database maintained by the system firmware to track which drivers are consuming protocol interfaces. The information in the handle database can be used to retrieve information about both drivers and controllers. The new boot service [OpenProtocolInformation\(\)](#) can be used to get the list of components that are currently consuming a specific protocol interface.

2.5.5 Bus Drivers

Bus drivers and device drivers are virtually identical from the UEFI *Driver Model*'s point of view. The only difference is that a bus driver creates new device handles for the child controllers that the bus driver discovers on its bus. As a result, bus drivers are slightly more complex than device drivers, but this in turn simplifies the design and implementation of device drivers. There are two major types of bus drivers. The first creates handles for all child controllers on the first call to **Start()**. The other type allows the handles for the child controllers to be created across multiple calls to **Start()**. This second type of bus driver is very useful in supporting a rapid boot capability. It allows a few child handles or even one child handle to be created. On buses that take a long time to enumerate all of their children (e.g. SCSI), this can lead to a very large timesaving in booting a platform. [Figure 13](#) shows the tree structure of a bus controller before and after **Start()** is called. The dashed line coming into the bus controller node represents a link to the bus controller's parent controller. If the bus controller is a *Host Bus Controller*, then it will not have a parent controller. Nodes A, B, C, D, and E represent the child controllers of the bus controller.

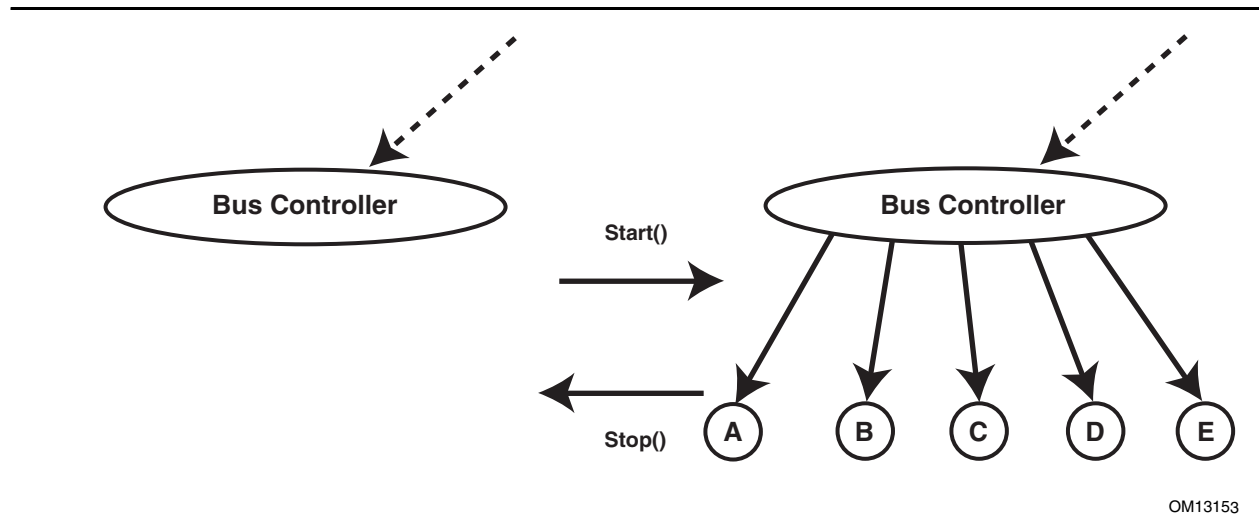


Figure 13. Connecting Bus Drivers

A bus driver that supports creating one child on each call to **Start()** might choose to create child C first, and then child E, and then the remaining children A, B, and D. The **Supported()**, **Start()**, and **Stop()** functions of the Driver Binding Protocol are flexible enough to allow this type of behavior.

A bus driver must install protocol interfaces onto every child handle that it creates. At a minimum, it must install a protocol interface that provides an I/O abstraction of the bus’s services to the child controllers. If the bus driver creates a child handle that represents a physical device, then the bus driver must also install a Device Path Protocol instance onto the child handle. A bus driver may optionally install a Bus Specific Driver Override Protocol onto each child handle. This protocol is used when drivers are connected to the child controllers. The boot service [ConnectController\(\)](#) uses architecturally defined precedence rules to choose the best set of drivers for a given controller. The Bus Specific Driver Override Protocol has higher precedence than a general driver search algorithm, and lower precedence than platform overrides. An example of a bus specific driver selection occurs with PCI. A PCI Bus Driver gives a driver stored in a PCI controller’s option ROM a higher precedence than drivers stored elsewhere in the platform. [Figure 14](#) shows an example child device handle that was created by the XYZ Bus Driver that supports a bus specific driver override mechanism.

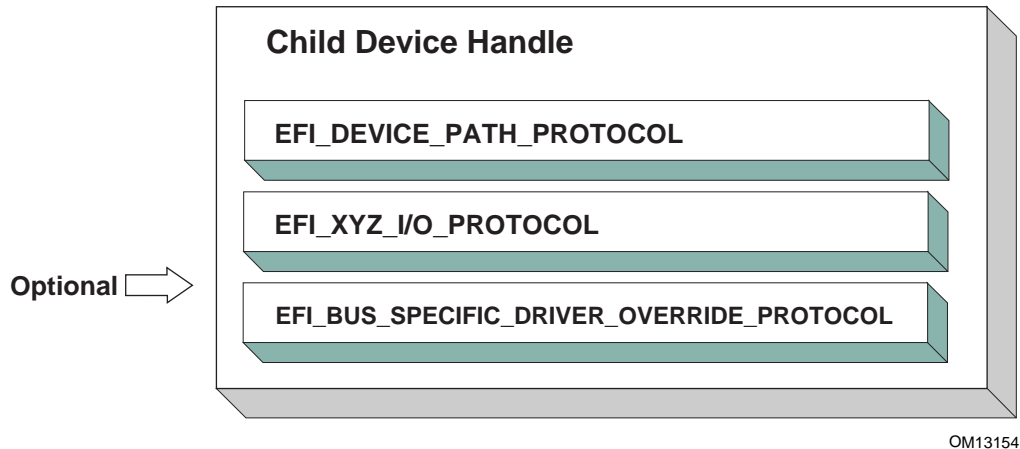


Figure 14. Child Device Handle with a Bus Specific Override

2.5.6 Platform Components

Under the *UEFI Driver Model*, the act of connecting and disconnecting drivers from controllers in a platform is under the platform firmware's control. This will typically be implemented as part of the UEFI Boot Manager, but other implementations are possible. The boot services [ConnectController \(\)](#) and [DisconnectController \(\)](#) can be used by the platform firmware to determine which controllers get started and which ones do not. If the platform wishes to perform system diagnostics or install an operating system, then it may choose to connect drivers to all possible boot devices. If a platform wishes to boot a preinstalled operating system, it may choose to only connect drivers to the devices that are required to boot the selected operating system. The *UEFI Driver Model* supports both these modes of operation through the boot services [ConnectController \(\)](#) and [DisconnectController \(\)](#). In addition, since the platform component that is in charge of booting the platform has to work with device paths for console devices and boot options, all of the services and protocols involved in the *UEFI Driver Model* are optimized with device paths in mind.

Since the platform firmware may choose to only connect the devices required to produce consoles and gain access to a boot device, the OS present device drivers cannot assume that a UEFI driver for a device has been executed. The presence of a UEFI driver in the system firmware or in an option ROM does not guarantee that the UEFI driver will be loaded, executed, or allowed to manage any devices in a platform. All OS present device drivers must be able to handle devices that have been managed by a UEFI driver and devices that have not been managed by a UEFI driver.

The platform may also choose to produce a protocol named the Platform Driver Override Protocol. This is similar to the Bus Specific Driver Override Protocol, but it has higher priority. This gives the platform firmware the highest priority when deciding which drivers are connected to which controllers. The Platform Driver Override Protocol is attached to a handle in the system. The boot service [ConnectController \(\)](#) will make use of this protocol if it is present in the system.

2.5.7 Hot-Plug Events

In the past, system firmware has not had to deal with hot-plug events in the preboot environment. However, with the advent of buses like USB, where the end user can add and remove devices at any time, it is important to make sure that it is possible to describe these types of buses in the UEFI *Driver Model*. It is up to the bus driver of a bus that supports the hot adding and removing of devices to provide support for such events. For these types of buses, some of the platform management is going to have to move into the bus drivers. For example, when a keyboard is hot added to a USB bus on a platform, the end user would expect the keyboard to be active. A USB Bus driver could detect the hot-add event and create a child handle for the keyboard device. However, because drivers are not connected to controllers unless [ConnectController \(\)](#) is called, the keyboard would not become an active input device. Making the keyboard driver active requires the USB Bus driver to call **ConnectController ()** when a hot-add event occurs. In addition, the USB Bus Driver would have to call [DisconnectController \(\)](#) when a hot-remove event occurs.

Device drivers are also affected by these hot-plug events. In the case of USB, a device can be removed without any notice. This means that the **Stop ()** functions of USB device drivers will have to deal with shutting down a driver for a device that is no longer present in the system. As a result, any outstanding I/O requests will have to be flushed without actually being able to touch the device hardware.

In general, adding support for hot-plug events greatly increases the complexity of both bus drivers and device drivers. Adding this support is up to the driver writer, so the extra complexity and size of the driver will need to be weighed against the need for the feature in the preboot environment.

2.5.8 EFI Services Binding

The UEFI *Driver Model* maps well onto hardware devices, hardware bus controllers, and simple combinations of software services that layer on top of hardware devices. However, the UEFI driver Model does not map well onto complex combinations of software services. As a result, an additional set of complementary protocols are required for more complex combinations of software services.

[Figure 15](#) contains three examples showing the different ways that software services relate to each other. In the first two cases, each service consumes one or more other services, and at most one other service consumes all of the services. Case #3 differs because two different services consume service A. The **EFI_DRIVER_BINDING_PROTOCOL** can be used to model cases #1 and #2, but it cannot be used to model case #3 because of the way that the UEFI Boot Service **OpenProtocol ()** behaves. When used with the **BY_DRIVER** open mode, **OpenProtocol ()** allows each protocol to have only at most one consumer. This feature is very useful and prevents multiple drivers from attempting to manage the same controller. However, it makes it difficult to produce sets of software services that look like case #3.

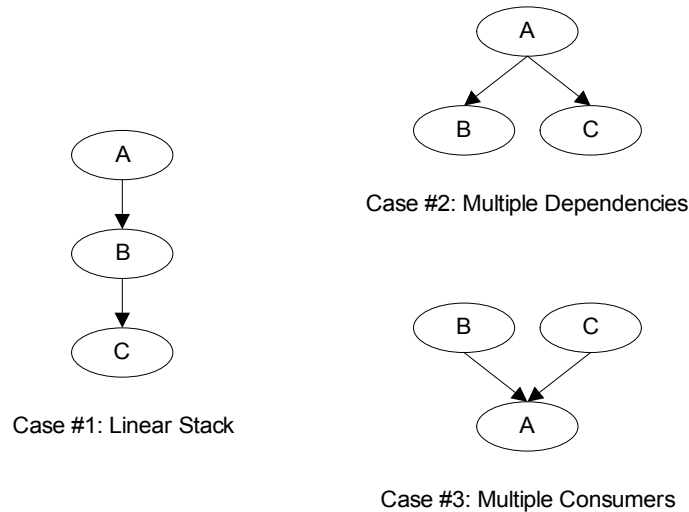


Figure 15. Software Service Relationships

The **EFI_SERVICE_BINDING_PROTOCOL** provides the mechanism that allows protocols to have more than one consumer. The **EFI_SERVICE_BINDING_PROTOCOL** is used with the **EFI_DRIVER_BINDING_PROTOCOL**. A UEFI driver that produces protocols that need to be available to more than one consumer at the same time will produce both the **EFI_DRIVER_BINDING_PROTOCOL** and the **EFI_SERVICE_BINDING_PROTOCOL**. This type of driver is a hybrid driver that will produce the **EFI_DRIVER_BINDING_PROTOCOL** in its driver entry point.

When the driver receives a request to start managing a controller, it will produce the **EFI_SERVICE_BINDING_PROTOCOL** on the handle of the controller that is being started. The **EFI_SERVICE_BINDING_PROTOCOL** is slightly different from other protocols defined in the *UEFI Specification*. It does not have a GUID associated with it. Instead, this protocol instance structure actually represents a family of protocols. Each software service driver that requires an **EFI_SERVICE_BINDING_PROTOCOL** instance will be required to generate a new GUID for its own type of **EFI_SERVICE_BINDING_PROTOCOL**. This requirement is why the various network protocols in this specification contain two GUIDs. One is the **EFI_SERVICE_BINDING_PROTOCOL** GUID for that network protocol, and the other GUID is for the protocol that contains the specific member services produced by the network driver. The mechanism defined here is not limited to network protocol drivers. It can be applied to any set of protocols that the **EFI_DRIVER_BINDING_PROTOCOL** cannot directly map because the protocols contain one or more relationships like case #3 in [Figure 15](#).

Neither the **EFI_DRIVER_BINDING_PROTOCOL** nor the combination of the **EFI_DRIVER_BINDING_PROTOCOL** and the **EFI_SERVICE_BINDING_PROTOCOL** can handle circular dependencies. There are methods to allow circular references, but they require that the circular link be present for short periods of time. When the protocols across the circular link are used, these methods also require that the protocol must be opened with an open mode of **EXCLUSIVE**, so that any attempts to deconstruct the set of protocols with a call to

DisconnectController() will fail. As soon as the driver is finished with the protocol across the circular link, the protocol should be closed.

2.6 Requirements

This document is an architectural specification. As such, care has been taken to specify architecture in ways that allow maximum flexibility in implementation. However, there are certain requirements on which elements of this specification must be implemented to ensure that operating system loaders and other code designed to run with UEFI boot services can rely upon a consistent environment.

For the purposes of describing these requirements, the specification is broken up into required and optional elements. In general, an optional element is completely defined in the section that matches the element name. For required elements however, the definition may in a few cases not be entirely self contained in the section that is named for the particular element. In implementing required elements, care should be taken to cover all the semantics defined in this specification that relate to the particular element.

2.6.1 Required Elements

[Table 7](#) lists the required elements. Any system that is designed to conform to this specification *must* provide a complete implementation of all these elements. This means that all the required service functions and protocols must be present and the implementation must deliver the full semantics defined in the specification for all combinations of calls and parameters. Implementers of applications, drivers or operating system loaders that are designed to run on a broad range of systems conforming to the UEFI specification may assume that all such systems implement all the required elements.

A system vendor may choose not to implement all the required elements, for example on specialized system configurations that do not support all the services and functionality implied by the required elements. However, since most applications, drivers and operating system loaders are written assuming all the required elements are present on a system that implements the UEFI specification; any such code is likely to require explicit customization to run on a less than complete implementation of the required elements in this specification.

Table 7. Required UEFI Implementation Elements

Element	Description
EFI SYSTEM TABLE	Provides access to UEFI Boot Services, UEFI Runtime Services, consoles, firmware vendor information, and the system configuration tables.
EFI BOOT SERVICES	All functions defined as boot services.
EFI RUNTIME SERVICES	All functions defined as runtime services.
EFI LOADED IMAGE PROTOCOL	Provides information on the image.
EFI DEVICE PATH PROTOCOL	Provides the location of the device.
EFI DECOMPRESS PROTOCOL	Protocol interfaces to decompress an image that was compressed using the EFI Compression Algorithm.

EFI DEVICE PATH UTILITIES PROTOCOL	Protocol interfaces to create and manipulate UEFI device paths and UEFI device path nodes.
EBC Interpreter	An EFI Byte Code Interpreter is required so UEFI images compiled to EFI Byte Code executables are guaranteed to function on all UEFI compliant platforms. The EBC Interpreter must also produce the EBC protocol.

2.6.2 Platform-Specific Elements

There are a number of elements that can be added or removed depending on the specific features that a platform requires. Platform firmware developers are required to implement UEFI elements based upon the features included. The following is a list of potential platform features and the elements that are required for each feature type:

1. If a platform includes console devices, the [EFI SIMPLE TEXT INPUT PROTOCOL](#), [EFI SIMPLE TEXT INPUT EX PROTOCOL](#), and [EFI SIMPLE TEXT OUTPUT PROTOCOL](#) must be implemented.
2. If a platform includes a configuration infrastructure, then the [EFI HII DATABASE PROTOCOL](#), [EFI HII STRING PROTOCOL](#), [EFI HII CONFIG ROUTING PROTOCOL](#), and [EFI HII CONFIGURATION ACCESS PROTOCOL](#) are required. If you support bitmapped fonts, you must support [EFI HII FONT PROTOCOL](#).
3. If a platform includes graphical console devices, then the [EFI GRAPHICS OUTPUT PROTOCOL](#), [EFI EDID DISCOVERED PROTOCOL](#), and [EFI EDID ACTIVE PROTOCOL](#) must be implemented. In order to support the [EFI GRAPHICS OUTPUT PROTOCOL](#), a platform must contain a driver to consume [EFI GRAPHICS OUTPUT PROTOCOL](#) and produce [EFI SIMPLE TEXT OUTPUT PROTOCOL](#) even if the [EFI GRAPHICS OUTPUT PROTOCOL](#) is produced by an external driver.
4. If a platform includes a pointer device as part of its console support, the [EFI SIMPLE POINTER PROTOCOL](#) must be implemented.
5. If a platform includes the ability to boot from a disk device, then the [EFI BLOCK IO PROTOCOL](#), the [EFI DISK IO PROTOCOL](#), the [EFI SIMPLE FILE SYSTEM PROTOCOL](#), and the [EFI UNICODE COLLATION PROTOCOL](#) are required. In addition, partition support for MBR, GPT, and El Torito must be implemented. An external driver may produce the Block I/O Protocol. All other protocols required to boot from a disk device must be carried as part of the platform.
6. If a platform includes the ability to boot from a network device, then the UNDI interface, the [EFI SIMPLE NETWORK PROTOCOL](#), and the [EFI PXE BASE CODE PROTOCOL](#) are required. If a platform includes the ability to validate a boot image received through a network device, the [EFI BIS PROTOCOL](#) is also required. An external driver may produce the UNDI interface. All other protocols required to boot from a network device must be carried by the platform.
7. If a platform supports UEFI general purpose network applications, then the [EFI MANAGED NETWORK PROTOCOL](#), [EFI MANAGED NETWORK SERVICE BINDING PROTOCOL](#), [EFI ARP PROTOCOL](#), [EFI ARP SERVICE BINDING PROTOCOL](#), [EFI DHCP4 PROTOCOL](#), [EFI DHCP4 SERVICE BINDING PROTOCOL](#), [EFI TCP4 PROTOCOL](#),

[EFI TCP4 SERVICE BINDING PROTOCOL](#),
[EFI IP4 SERVICE BINDING PROTOCOL](#), [EFI IP4 CONFIG PROTOCOL](#),
[EFI UDP4 PROTOCOL](#), [EFI UDP4 SERVICE BINDING PROTOCOL](#),
[EFI MTFTP4 PROTOCOL](#), and [EFI MTFTP4 SERVICE BINDING PROTOCOL](#) are required.

8. If a platform includes a byte-stream device such as a UART, then the [EFI SERIAL IO PROTOCOL](#) must be implemented.
9. If a platform includes PCI bus support, then the [EFI PCI ROOT BRIDGE IO PROTOCOL](#), the [EFI PCI IO PROTOCOL](#), must be implemented.
10. If a platform includes USB bus support, then the [EFI USB2 HC PROTOCOL](#) and the [EFI USB IO PROTOCOL](#) must be implemented. An external device can support USB by producing a USB Host Controller Protocol.
11. If a platform includes an I/O subsystem that utilizes SCSI command packets, then the [EFI EXT SCSI PASS THRU PROTOCOL](#) must be implemented.
12. If a platform supports booting from a block oriented SCSI peripheral, then the [EFI SCSI IO PROTOCOL](#) and [EFI BLOCK IO PROTOCOL](#) must be implemented. An external driver may produce the [EFI EXT SCSI PASS THRU PROTOCOL](#). All other protocols required to boot from a SCSI I/O subsystem must be carried by the platform.
13. If a platform supports booting from an iSCSI peripheral, then the [EFI ISCSI INITIATOR NAME PROTOCOL](#) and the [EFI AUTHENTICATION INFO PROTOCOL](#) must be implemented.
14. If a platform includes debugging capabilities, then the [EFI DEBUG SUPPORT PROTOCOL](#), the [EFI DEBUGPORT PROTOCOL](#), and the [EFI Image Info](#) Table must be implemented.
15. If a platform includes the ability to override the default driver to the controller matching algorithm provided by the UEFI Driver Model, then the [EFI PLATFORM DRIVER OVERRIDE PROTOCOL](#) must be implemented.

2.6.3 Driver-Specific Elements

There are a number of UEFI elements that can be added or removed depending on the features that a specific driver requires. Drivers can be implemented by platform firmware developers to support buses and devices in a specific platform. Drivers can also be implemented by add-in card vendors for devices that might be integrated into the platform hardware or added to a platform through an expansion slot. The following list includes possible driver features, and the UEFI elements that are required for each feature type:

1. If a driver follows the driver model of this specification, the [EFI DRIVER BINDING PROTOCOL](#) must be implemented. It is strongly recommended that all drivers that follow the driver model of this specification also implement the [EFI COMPONENT NAME2 PROTOCOL](#).
2. If a driver requires configuration information, the driver must use the [EFI HII DATABASE PROTOCOL](#). A driver should not otherwise display information to the user or request information from the user.
3. If a driver requires diagnostics, the [EFI DRIVER DIAGNOSTICS PROTOCOL](#) must be implemented. In order to support low boot times, limit diagnostics during normal boots. Time consuming diagnostics should be deferred until the [EFI_DRIVER_DIAGNOSTICS_PROTOCOL](#) is invoked.

4. If a bus supports devices that are able to provide containers for drivers (e.g. option ROMs), then the bus driver for that bus type must implement the [EFI BUS SPECIFIC DRIVER OVERRIDE PROTOCOL](#).
5. If a driver is written for a console output device, then the [EFI SIMPLE TEXT OUTPUT PROTOCOL](#) must be implemented.
6. If a driver is written for a graphical console output device, then the [EFI GRAPHICS OUTPUT PROTOCOL](#), [EFI EDID DISCOVERED PROTOCOL](#) and [EFI EDID ACTIVE PROTOCOL](#) must be implemented.
7. If a driver is written for a console input device, then the [EFI SIMPLE TEXT INPUT PROTOCOL](#) and [EFI SIMPLE TEXT INPUT EX PROTOCOL](#) must be implemented.
8. If a driver is written for a pointer device, then the [EFI SIMPLE POINTER PROTOCOL](#) must be implemented.
9. If a driver is written for a network device, then the [EFI NETWORK INTERFACE IDENTIFIER PROTOCOL](#), [EFI SIMPLE NETWORK PROTOCOL](#) or [EFI MANAGED NETWORK PROTOCOL](#) must be implemented.
10. If a driver is written for a disk device, then the [EFI BLOCK IO PROTOCOL](#) must be implemented.
11. If a driver is written for a device that is not a block oriented device but one that can provide a file system-like interface, then the [EFI SIMPLE FILE SYSTEM PROTOCOL](#) must be implemented.
12. If a driver is written for a PCI root bridge, then the [EFI PCI ROOT BRIDGE IO PROTOCOL](#) and the [EFI PCI IO PROTOCOL](#) must be implemented.
13. If a driver is written for a USB host controller, then the [EFI USB2 HC PROTOCOL](#) must be implemented.
14. If a driver is written for a SCSI controller, then the [EFI EXT SCSI PASS THRU PROTOCOL](#) must be implemented.
15. If a driver is digitally signed, it must embed the digital signature in the PE/COFF image as described in Section [“Embedded Signatures” on page 1105](#).
16. If a driver is written for a boot device that is not a block-oriented device, a file system-based device, or a console device, then the [EFI LOAD FILE PROTOCOL](#) must be implemented.

Boot Manager

The UEFI boot manager is a firmware policy engine that can be configured by modifying architecturally defined global NVRAM variables. The boot manager will attempt to load UEFI drivers and UEFI applications (including UEFI OS boot loaders) in an order defined by the global NVRAM variables. The platform firmware must use the boot order specified in the global NVRAM variables for normal boot. The platform firmware may add extra boot options or remove invalid boot options from the boot order list.

The platform firmware may also implement value added features in the boot manager if an exceptional condition is discovered in the firmware boot process. One example of a value added feature would be not loading a UEFI driver if booting failed the first time the driver was loaded. Another example would be booting to an OEM-defined diagnostic environment if a critical error was discovered in the boot process.

The boot sequence for UEFI consists of the following:

- The boot order list is read from a globally defined NVRAM variable. The boot order list defines a list of NVRAM variables that contain information about what is to be booted. Each NVRAM variable defines a Unicode name for the boot option that can be displayed to a user.
- The variable also contains a pointer to the hardware device and to a file on that hardware device that contains the UEFI image to be loaded.
- The variable might also contain paths to the OS partition and directory along with other configuration specific directories.

The NVRAM can also contain load options that are passed directly to the UEFI image. The platform firmware has no knowledge of what is contained in the load options. The load options are set by higher level software when it writes to a global NVRAM variable to set the platform firmware boot policy. This information could be used to define the location of the OS kernel if it was different than the location of the UEFI OS loader.

3.1 Firmware Boot Manager

The boot manager is a component in firmware conforming to this specification that determines which drivers and applications should be explicitly loaded and when. Once compliant firmware is initialized, it passes control to the boot manager. The boot manager is then responsible for determining what to load and any interactions with the user that may be required to make such a decision. Much of the behavior of the boot manager is left up to the firmware developer to decide, and details of boot manager implementation are outside the scope of this specification. In particular, likely implementation options might include any console interface concerning boot, integrated platform management of boot selections, possible knowledge of other internal applications or recovery drivers that may be integrated into the system through the boot manager.

3.1.1 Boot Manager Programming

Programmatic interaction with the boot manager is accomplished through globally defined variables. On initialization the boot manager reads the values which comprise all of the published load options among the UEFI environment variables. By using the [SetVariable\(\)](#) function the data that contain these environment variables can be modified.

Each load option entry resides in a *Boot####* variable or a *Driver####* variable where the *####* is replaced by a unique option number in printable hexadecimal representation using the digits 0–9, and the upper case versions of the characters A–F (0000–FFFF). The *####* must always be four digits, so small numbers must use leading zeros. The load options are then logically ordered by an array of option numbers listed in the desired order. There are two such option ordering lists. The first is *DriverOrder* that orders the *Driver####* load option variables into their load order. The second is *BootOrder* that orders the *Boot####* load options variables into their load order.

For example, to add a new boot option, a new *Boot####* variable would be added. Then the option number of the new *Boot####* variable would be added to the *BootOrder* ordered list and the *BootOrder* variable would be rewritten. To change boot option on an existing *Boot####*, only the *Boot####* variable would need to be rewritten. A similar operation would be done to add, remove, or modify the driver load list.

If the boot via *Boot####* returns with a status of **EFI_SUCCESS** the boot manager will stop processing the *BootOrder* variable and present a boot manager menu to the user. If a boot via *Boot####* returns a status other than **EFI_SUCCESS**, the boot has failed and the next *Boot####* in the *BootOrder* variable will be tried until all possibilities are exhausted.

The boot manager may perform automatic maintenance of the database variables. For example, it may remove unreferenced load option variables or any load option variables that cannot be parsed or loaded, and it may rewrite any ordered list to remove any load options that do not have corresponding load option variables. In addition, the boot manager may automatically update any ordered list to place any of its own load options where it desires. The boot manager can also, at its own discretion, provide for manual maintenance operations as well. Examples include choosing the order of any or all load options, activating or deactivating load options, etc.

3.1.2 Load Option Processing

The boot manager is required to process the Driver load option entries before the Boot load option entries. The boot manager is also required to initiate a boot of the boot option specified by the *BootNext* variable as the first boot option on the next boot, and only on the next boot. The boot manager removes the *BootNext* variable before transferring control to the *BootNext* boot option. After the *BootNext* boot option is tried, the normal *BootOrder* list is used. To prevent loops, the boot manager deletes this variable before transferring control to the preselected boot option.

The boot manager must call [LoadImage\(\)](#) which supports at least [EFI SIMPLE FILE SYSTEM PROTOCOL](#) and [EFI LOAD FILE PROTOCOL](#) for resolving load options. If [LoadImage\(\)](#) succeeds, the boot manager must enable the watchdog timer for 5 minutes by using the [SetWatchdogTimer\(\)](#) boot service prior to calling [StartImage\(\)](#). If a boot option returns control to the boot manager, the boot manager must disable the watchdog timer with an additional call to the [SetWatchdogTimer\(\)](#) boot service.

If the boot image is not loaded via [LoadImage\(\)](#) the boot manager is required to check for a default application to boot. Searching for a default application to boot happens on both removable and fixed media types. This search occurs when the device path of the boot image listed in any boot option points directly to an **EFI_SIMPLE_FILE_SYSTEM_PROTOCOL** device and does not specify the exact file to load. The file discovery method is explained in [Section 3.3](#). The default media boot case of a protocol other than **EFI_SIMPLE_FILE_SYSTEM_PROTOCOL** is handled by the [EFI_LOAD_FILE_PROTOCOL](#) for the target device path and does not need to be handled by the boot manager.

The UEFI boot manager must support booting from a short-form device path that starts with the first element being a USB WWID (see [Table 53](#)) or a USB Class (see [Table 55](#)) device path. For USB WWID, the boot manager must use the device vendor ID, device product id, and serial number, and must match any USB device in the system that contains this information. If more than one device matches the USB WWID device path, the boot manager will pick one arbitrarily. For USB Class, the boot manager must use the vendor ID, Product ID, Device Class, Device Subclass, and Device Protocol, and must match any USB device in the system that contains this information. If any of the ID, Product ID, Device Class, Device Subclass, or Device Protocol contain all F's (0xFFFF or 0xFF), this element is skipped for the purpose of matching. If more than one device matches the USB Class device path, the boot manager will pick one arbitrarily.

The boot manager must also support booting from a short-form device path that starts with the first element being a hard drive media device path (see [Table 66](#)). The boot manager must use the GUID or signature and partition number in the hard drive device path to match it to a device in the system. If the drive supports the GPT partitioning scheme the GUID in the hard drive media device path is compared with the *UniquePartitionGuid* field of the GUID Partition Entry (see [Table 14](#)). If the drive supports the PC-AT MBR scheme the signature in the hard drive media device path is compared with the *UniqueMBRSignature* in the Legacy Master Boot Record (see [Table 10](#)). If a signature match is made, then the partition number must also be matched. The hard drive device path can be appended to the matching hardware device path and normal boot behavior can then be used. If more than one device matches the hard drive device path, the boot manager will pick one arbitrarily. Thus the operating system must ensure the uniqueness of the signatures on hard drives to guarantee deterministic boot behavior.

3.1.3 Load Options

Each load option variable contains an **EFI_LOAD_OPTION** descriptor that is a byte packed buffer of variable length fields. Since some of the fields are variable length, an **EFI_LOAD_OPTION** cannot be described as a standard C data structure. Instead, the fields are listed below in the order that they appear in an **EFI_LOAD_OPTION** descriptor:

Descriptor

UINT32	<i>Attributes;</i>
UINT16	<i>FilePathListLength;</i>
CHAR16	<i>Description[];</i>
EFI_DEVICE_PATH_PROTOCOL	<i>FilePathList[];</i>
UINT8	<i>OptionalData[];</i>

Parameters

<i>Attributes</i>	The attributes for this load option entry. All unused bits must be zero and are reserved by the UEFI specification for future growth. See “Related Definitions.”
<i>FilePathListLength</i>	Length in bytes of the <i>FilePathList</i> . <i>OptionalData</i> starts at offset <code>sizeof (UINT32) + sizeof (UINT16) + StrSize (Description) + FilePathListLength</code> of the EFI_LOAD_OPTION descriptor.
<i>Description</i>	The user readable description for the load option. This field ends with a Null Unicode character.
<i>FilePathList</i>	A packed array of UEFI device paths. The first element of the array is a device path that describes the device and location of the Image for this load option. The <i>FilePathList[0]</i> is specific to the device type. Other device paths may optionally exist in the <i>FilePathList</i> , but their usage is OSV specific. Each element in the array is variable length, and ends at the device path end structure. Because the size of <i>Description</i> is arbitrary, this data structure is not guaranteed to be aligned on a natural boundary. This data structure may have to be copied to an aligned natural boundary before it is used.
<i>OptionalData</i>	The remaining bytes in the load option descriptor are a binary data buffer that is passed to the loaded image. If the field is zero bytes long, a NULL pointer is passed to the loaded image. The number of bytes in <i>OptionalData</i> can be computed by subtracting the starting offset of <i>OptionalData</i> from total size in bytes of the EFI_LOAD_OPTION .

Related Definitions

```

//*****
// Attributes
//*****
#define LOAD_OPTION_ACTIVE          0x00000001
#define LOAD_OPTION_FORCE_RECONNECT 0x00000002
#define LOAD_OPTION_GRAPHICS       0x00000004
#define LOAD_OPTION_HIDDEN          0x00000008
#define LOAD_OPTION_CATEGORY        0x00001F00

#define LOAD_OPTION_CATEGORY_BOOT   0x00000000
#define LOAD_OPTION_CATEGORY_APP    0x00000100
// All values 0x00000200-0x00001F00 are reserved

```

Description

Calling [SetVariable\(\)](#) creates a load option. The size of the load option is the same as the size of the *DataSize* argument to the [SetVariable\(\)](#) call that created the variable. When creating a new load option, all undefined attribute bits must be written as zero. When updating a load option, all undefined attribute bits must be preserved.

If a load option is marked as **LOAD_OPTION_ACTIVE**, the boot manager will attempt to boot automatically using the device path information in the load option. This provides an easy way to disable or enable load options without needing to delete and re-add them.

If any *Driver####* load option is marked as **LOAD_OPTION_FORCE_RECONNECT**, then all of the UEFI drivers in the system will be disconnected and reconnected after the last *Driver####* load option is processed. This allows a UEFI driver loaded with a *Driver####* load option to override a UEFI driver that was loaded prior to the execution of the UEFI Boot Manager.

The **LOAD_OPTION_CATEGORY** provides a hint to the boot manager to describe how it should group the *Boot####* load options. *Boot####* load options with **LOAD_OPTION_CATEGORY_BOOT** are meant to be part of the normal boot processing. *Boot####* load options with **LOAD_OPTION_CATEGORY_APP** are executables which are not part of the normal boot processing. Boot options with reserved category values will be ignored by the boot manager.

If any *Boot####* load option is marked as **LOAD_OPTION_HIDDEN**, then the load option will not appear in the menu (if any) provided by the boot manager for load option selection.

3.1.4 Boot Manager Capabilities

The boot manager can report its capabilities through the global variable *BootOptionSupport*. If the global variable is not present, then an installer or application must act as if a value of 0 was returned.

```
#define EFI_BOOT_OPTION_SUPPORT_KEY  0x00000001
#define EFI_BOOT_OPTION_SUPPORT_APP  0x00000002
#define EFI_BOOT_OPTION_SUPPORT_COUNT 0x00000300
```

If **EFI_BOOT_OPTION_SUPPORT_KEY** is set then the boot manager supports launching of *Boot####* load options using key presses. If **EFI_BOOT_OPTION_SUPPORT_APP** is set then the boot manager supports boot options with **LOAD_OPTION_CATEGORY_APP**.

The value specified in **EFI_BOOT_OPTION_SUPPORT_COUNT** describes the maximum number of key presses which the boot manager supports in the **EFI_KEY_OPTION.KeyData.InputKeyCount**. This value is only valid if **EFI_BOOT_OPTION_SUPPORT_KEY** is set. Key sequences with more keys specified are ignored.

3.1.5 Launching Boot#### Applications

The boot manager may support a separate category of *Boot####* load option for applications. The boot manager indicates that it supports this separate category by setting the **EFI_BOOT_OPTION_SUPPORT_APP** in the *BootOptionSupport* global variable.

When an application's *Boot####* option is being added to the *BootOrder*, the installer should clear **LOAD_OPTION_ACTIVE** so that the boot manager does not attempt to automatically “boot” the application. If the boot manager indicates that it supports a separate application category, as described above, the installer should set **LOAD_OPTION_CATEGORY_APP**. If not, it should set **LOAD_OPTION_CATEGORY_BOOT**.

3.1.6 Launching Boot#### Load Options Using Hot Keys

The boot manager may support launching a *Boot####* load option using a special key press. If so, the boot manager reports this capability by setting **EFI_BOOT_OPTION_SUPPORT_KEY** in the *BootOptionSupport* global variable.

A boot manager which supports key press launch reads the current key information from the console. Then, if there was a key press, it compares the key returned against zero or more *Key####* global variables. If it finds a match, it verifies that the *Boot####* load option specified is valid and, if so, attempts to launch it immediately. The #### in the *Key####* is a printable hexadecimal number ('0'-'9', 'A'-'F') with leading zeroes. The order which the *Key####* variables are checked is implementation-specific.

The boot manager may ignore *Key####* variables where the hot keys specified overlap with those used for internal boot manager functions. It is recommended that the boot manager delete these keys.

The *Key####* variables have the following format:

Prototype

```
typedef struct _EFI_KEY_OPTION {
    EFI_KEY_DATA    KeyData;
    UINT32          BootOptionCrc;
    UINT16          BootOption;
    // EFI_INPUT_KEY Keys[];
} EFI_KEY_OPTION;
```

Parameters

KeyData

Specifies options about how the key will be processed. Type **EFI_KEY_DATA** is defined in “Related Definitions” below.

BootOptionCrc

The CRC-32 which should match the CRC-32 of the entire **EFI_LOAD_OPTION** to which *BootOption* refers. If the CRC-32s do not match this value, then this key option is ignored.

BootOption

The *Boot####* option which will be invoked if this key is pressed and the boot option is active (**LOAD_OPTION_ACTIVE** is set).

Keys

The key codes to compare against those returned by the **EFI_SIMPLE_TEXT_INPUT** and **EFI_SIMPLE_TEXT_INPUT_EX** protocols. The number of key codes (0-3) is specified by the **EFI_KEY_CODE_COUNT** field in *KeyOptions*.

Related Definitions

```
typedef union {
    struct {
        UINT32 Revision : 8;
        UINT32 ShiftPressed : 1;
        UINT32 ControlPressed : 1;
        UINT32 AltPressed : 1;
        UINT32 LogoPressed : 1;
        UINT32 MenuPressed : 1;
        UINT32 SysReqPressed : 1;
        UINT32 Reserved : 16;
        UINT32 InputKeyCount : 2;
    } Options;
    UINT32 PackedValue;
} EFI_KEY_DATA;
```

Revision

Indicates the revision of the **EFI_KEY_OPTION** structure. This revision level should be 0.

ShiftPressed

Either the left or right Shift keys must be pressed (1) or must not be pressed (0).

ControlPressed

Either the left or right Control keys must be pressed (1) or must not be pressed (0).

AltPressed

Either the left or right Alt keys must be pressed (1) or must not be pressed (0).

LogoPressed

Either the left or right Logo keys must be pressed (1) or must not be pressed (0).

MenuPressed

The Menu key must be pressed (1) or must not be pressed (0).

SysReqPressed

The SysReq key must be pressed (1) or must not be pressed (0).

InputKeyCount

Specifies the actual number of entries in **EFI_KEY_OPTION.Keys**, from 0-3. If zero, then only the shift state is considered. If more than one, then the boot option will only be launched if all of the specified keys are pressed with the same shift state.

Example #1: ALT is the hot key. *KeyData.PackedValue* = **0x00000400**.

Example #2: CTRL-ALT-P-R. *KeyData.PackedValue* = **0x80000600**.

Example #3: CTRL-F1. *KeyData.PackedValue* = **0x10000200**.

3.2 Globally Defined Variables

This section defines a set of variables that have architecturally defined meanings. In addition to the defined data content, each such variable has an architecturally defined attribute that indicates when the data variable may be accessed. The variables with an attribute of NV are nonvolatile. This means that their values are persistent across resets and power cycles. The value of any environment variable that does not have this attribute will be lost when power is removed from the system and the state of firmware reserved memory is not otherwise preserved. The variables with an attribute of BS are only available before [ExitBootServices\(\)](#) is called. This means that these environment variables can only be retrieved or modified in the preboot environment. They are not visible to an operating system. Environment variables with an attribute of RT are available before and after [ExitBootServices\(\)](#) is called. Environment variables of this type can be retrieved and modified in the preboot environment, and from an operating system. All architecturally defined variables use the **EFI_GLOBAL_VARIABLE** *VendorGuid*:

```
#define EFI_GLOBAL_VARIABLE\  
{0x8BE4DF61, 0x93CA, 0x11d2, 0xAA, 0x0D, 0x00, 0xE0, 0x98, 0x03, 0x2B,  
0x8C}
```

The *AppOrder* variable contains an array of **UINT16**'s that make up an ordered list of the *Boot####* options. The first element in the array is the value for the first logical application option, the second element is the value for the second logical application option, etc. The *AppOrder* order list is used by the firmware's boot manager as the default list of installed applications.

To prevent name collisions with possible future globally defined variables, other internal firmware data variables that are not defined here must be saved with a unique *VendorGuid* other than **EFI_GLOBAL_VARIABLE**. [Table 8](#) lists the global variables.

Table 8. Global Variables

Variable Name	Attribute	Description
LangCodes	BS, RT	The language codes that the firmware supports. This value is deprecated.
Lang	NV, BS, RT	The language code that the system is configured for. This value is deprecated.
Timeout	NV, BS, RT	The firmware's boot managers timeout, in seconds, before initiating the default boot selection.
PlatformLangCodes	BS, RT	The language codes that the firmware supports.
PlatformLang	NV, BS, RT	The language code that the system is configured for.
ConIn	NV, BS, RT	The device path of the default input console.
ConOut	NV, BS, RT	The device path of the default output console.
ErrOut	NV, BS, RT	The device path of the default error output device.
ConInDev	BS, RT	The device path of all possible console input devices.
ConOutDev	BS, RT	The device path of all possible console output devices.
ErrOutDev	BS, RT	The device path of all possible error output devices.
Boot####	NV, BS, RT	A boot load option. #### is a printed hex value. No 0x or h is included in the hex value.

Variable Name	Attribute	Description
BootOrder	NV, BS, RT	The ordered boot option load list.
BootNext	NV, BS, RT	The boot option for the next boot only.
BootCurrent	BS, RT	The boot option that was selected for the current boot.
BootOptionSupport	BS,RT,RO	The types of boot options supported by the boot manager.
Driver####	NV, BS, RT	A driver load option. #### is a printed hex value.
DriverOrder	NV, BS, RT	The ordered driver load option list.
Key####	NV, BS, RT	Describes hot key relationship with a Boot#### load option.
HwErrRecSupport	NV, BS, RT	Identifies the level of hardware error record persistence support implemented by the platform. This variable is only modified by firmware and is read-only to the OS.

The *PlatformLangCodes* variable contains a null-terminated string (8-bit ASCII character) representing the language codes that the firmware can support. At initialization time the firmware computes the supported languages and creates this data variable. Since the firmware creates this value on each initialization, its contents are not stored in nonvolatile memory. This value is considered read-only. *PlatformLangCodes* is specified in Native RFC 3066 format. See [Appendix M](#). *LangCodes* is deprecated and may be provided for backwards compatibility.

The *PlatformLang* variable contains a null-terminated string (8-bit ASCII character) language code that the machine has been configured for. This value may be changed to any value supported by *PlatformLangCodes*. If this change is made in the preboot environment, then the change will take effect immediately. If this change is made at OS runtime, then the change does not take effect until the next boot. If the language code is set to an unsupported value, the firmware will choose a supported default at initialization and set *PlatformLang* to a supported value.

PlatformLang is specified in Native RFC 3066 array format. See [Appendix M](#). *Lang* is deprecated and may be provided for backwards compatibility.

Lang has been deprecated. If the platform supports this variable, it must map any changes in the *Lang* variable into *PlatformLang* in the appropriate format.

Langcodes has been deprecated. If the platform supports this variable, it must map any changes in the *Langcodes* variable into *PlatformLang* in the appropriate format.

The *Timeout* variable contains a binary **UINT16** that supplies the number of seconds that the firmware will wait before initiating the original default boot selection. A value of 0 indicates that the default boot selection is to be initiated immediately on boot. If the value is not present, or contains the value of 0xFFFF then firmware will wait for user input before booting. This means the default boot selection is not automatically started by the firmware.

The *ConIn*, *ConOut*, and *ErrOut* variables each contain an **EFI DEVICE PATH PROTOCOL** descriptor that defines the default device to use on boot. Changes to these values made in the preboot environment take effect immediately. Changes to these values at OS runtime do not take effect until the next boot. If the firmware cannot resolve the device path, it is allowed to automatically replace the values, as needed, to provide a console for the system. If the device path starts with a USB Class device path (see [Table 55](#)), then any input or output device that matches the device path must be used as a console if it is supported by the firmware.

The *ConInDev*, *ConOutDev*, and *ErrOutDev* variables each contain an **EFI_DEVICE_PATH_PROTOCOL** descriptor that defines all the possible default devices to use on boot. These variables are volatile, and are set dynamically on every boot. *ConIn*, *ConOut*, and *ErrOut* are always proper subsets of *ConInDev*, *ConOutDev*, and *ErrOutDev*.

Each *Boot####* variable contains an **EFI_LOAD_OPTION**. Each *Boot####* variable is the name “Boot” appended with a unique four digit hexadecimal number. For example, *Boot0001*, *Boot0002*, *Boot0A02*, etc.

The *BootOrder* variable contains an array of **UINT16**’s that make up an ordered list of the *Boot####* options. The first element in the array is the value for the first logical boot option, the second element is the value for the second logical boot option, etc. The *BootOrder* order list is used by the firmware’s boot manager as the default boot order.

The *BootNext* variable is a single **UINT16** that defines the *Boot####* option that is to be tried first on the next boot. After the *BootNext* boot option is tried the normal *BootOrder* list is used. To prevent loops, the boot manager deletes this variable before transferring control to the preselected boot option.

The *BootCurrent* variable is a single **UINT16** that defines the *Boot####* option that was selected on the current boot.

The *BootOptionSupport* variable is a **UINT32** that defines the types of boot options supported by the boot manager.

Each *Driver####* variable contains an **EFI_LOAD_OPTION**. Each load option variable is appended with a unique number, for example *Driver0001*, *Driver0002*, etc.

The *DriverOrder* variable contains an array of **UINT16**’s that make up an ordered list of the *Driver####* variable. The first element in the array is the value for the first logical driver load option, the second element is the value for the second logical driver load option, etc. The *DriverOrder* list is used by the firmware’s boot manager as the default load order for UEFI drivers that it should explicitly load.

The *Key####* variable associates a key press with a single boot option. Each *Key####* variable is the name "Key" appended with a unique four digit hexadecimal number. For example, *Key0001*, *Key0002*, *Key00A0*, etc.

The *HwErrRecSupport* variable contains a binary **UINT16** that supplies the level of support for Hardware Error Record Persistence (see [Section 7.2.1](#)) that is implemented by the platform. If the value is not present, then the platform implements no support for Hardware Error Record Persistence. A value of zero indicates that the platform implements no support for Hardware Error Record Persistence. A value of 1 indicates that the platform implements Hardware Error Record Persistence as defined in [Section 7.2.1](#). Firmware initializes this variable. All other values are reserved for future use.

3.3 Boot Option Variables Default Boot Behavior

The default state of globally-defined variables is firmware vendor specific. However the boot options require a standard default behavior in the exceptional case that valid boot options are not present on a platform. The default behavior must be invoked any time the *BootOrder* variable does not exist or only points to nonexistent boot options.

If no valid boot options exist, the boot manager will enumerate all removable media devices followed by all fixed media devices. The order within each group is undefined. These new default boot options are not saved to non volatile storage. The boot manager will then attempt to boot from each boot option. If the device supports the [EFI SIMPLE FILE SYSTEM PROTOCOL](#) then the removable media boot behavior (see [Section 3.4.1.1](#)) is executed. Otherwise, the firmware will attempt to boot the device via the [EFI_LOAD_FILE_PROTOCOL](#).

It is expected that this default boot will load an operating system or a maintenance utility. If this is an operating system setup program it is then responsible for setting the requisite environment variables for subsequent boots. The platform firmware may also decide to recover or set to a known set of boot options.

3.4 Boot Mechanisms

EFI can boot from a device using the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) or the [EFI_LOAD_FILE_PROTOCOL](#). A device that supports the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) must materialize a file system protocol for that device to be bootable. If a device does not wish to support a complete file system it may produce an [EFI_LOAD_FILE_PROTOCOL](#) which allows it to materialize an image directly. The Boot Manager will attempt to boot using the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) first. If that fails, then the [EFI_LOAD_FILE_PROTOCOL](#) will be used.

3.4.1 Boot via the Simple File Protocol

When booting via the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#), the *FilePath* will start with a device path that points to the device that “speaks” the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#). The next part of the *FilePath* will point to the file name, including sub directories that contain the bootable image. If the file name is a null device path, the file name must be discovered on the media using the rules defined for removable media devices with ambiguous file names (see [Section 3.4.1.1](#) below).

The format of the file system specified is contained in [Section 12.2](#). While the firmware must produce an [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) that understands the UEFI file system, any file system can be abstracted with the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) interface.

3.4.1.1 Removable Media Boot Behavior

On a removable media device it is not possible for the *FilePath* to contain a file name, including sub directories. *FilePathList[0]* is stored in non volatile memory in the platform and cannot possibly be kept in sync with a media that can change at any time. A *FilePathList[0]* for a removable media device will point to a device that supports the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) or [EFI_BLOCK_IO_PROTOCOL](#). The *FilePathList[0]* will not contain a file name or sub directories.

If *FilePathList[0]* points to a device that supports the [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#), then the system firmware will attempt to boot from a removable media *FilePathList[0]* by adding a default file name in the form `\EFI\BOOT\BOOT{machine type short-name}.EFI`. Where machine type short-name defines a

PE32+ image format architecture. Each file only contains one UEFI image type, and a system may support booting from one or more images types. [Table 9](#) lists the UEFI image types.

Table 9. UEFI Image Types

	File Name Convention	PE Executable Machine Type *
32-bit	BOOTIA32.EFI	0x14c
x64	BOOTx64.EFI	0x8664
Itanium architecture	BOOTIA64.EFI	0x200
Note: * The PE Executable machine type is contained in the machine field of the COFF file header as defined in the Microsoft Portable Executable and Common Object File Format Specification, Revision 6.0		

A media may support multiple architectures by simply having a `\EFI\BOOT\BOOT{machine type short-name}.EFI` file of each possible machine type.

If `FilePathList[0]` device does not support the **EFI_SIMPLE_FILE_SYSTEM_PROTOCOL**, but support the **EFI_BLOCK_IO_PROTOCOL** protocol, then the EFI Boot Service `ConnectController()` must be called for `FilePathList[0]` with `DriverImageHandle` and `RemainingDevicePath` set to **NULL** and the `Recursive` flag is set to **TRUE**. The firmware will then attempt to boot from any child handles produced using the algorithms outlined above.

3.4.2 Boot via LOAD_FILE PROTOCOL

When booting via the **EFI_LOAD_FILE_PROTOCOL** protocol, the `FilePath` is a device path that points to a device that “speaks” the **EFI_LOAD_FILE_PROTOCOL**. The image is loaded directly from the device that supports the **EFI_LOAD_FILE_PROTOCOL**. The remainder of the `FilePath` will contain information that is specific to the device. Firmware passes this device-specific data to the loaded image, but does not use it to load the image. If the remainder of the `FilePath` is a null device path it is the loaded image's responsibility to implement a policy to find the correct boot device.

The **EFI_LOAD_FILE_PROTOCOL** is used for devices that do not directly support file systems. Network devices commonly boot in this model where the image is materialized without the need of a file system.

3.4.2.1 Network Booting

Network booting is described by the *Preboot eXecution Environment (PXE) BIOS Support Specification* that is part of the *Wired for Management Baseline specification*. PXE specifies UDP, DHCP, and TFTP network protocols that a booting platform can use to interact with an intelligent system load server. UEFI defines special interfaces that are used to implement PXE. These interfaces are contained in the **EFI_PXE_BASE_CODE_PROTOCOL** (see [Section 21.3](#)).

3.4.2.2 Future Boot Media

Since UEFI defines an abstraction between the platform and the OS and its loader it should be possible to add new types of boot media as technology evolves. The OS loader will not necessarily have to change to support new types of boot. The implementation of the UEFI platform services

may change, but the interface will remain constant. The OS will require a driver to support the new type of boot media so that it can make the transition from UEFI boot services to OS control of the boot media.

EFI System Table

This section describes the entry point to a UEFI image and the parameters that are passed to that entry point. There are three types of UEFI images that can be loaded and executed by firmware conforming to this specification. These are UEFI Applications, OS Loaders, and drivers. There are no differences in the entry point for these three image types.

4.1 UEFI Image Entry Point

The most significant parameter that is passed to an image is a pointer to the System Table. This pointer is [EFI_IMAGE_ENTRY_POINT](#) (see definition immediately below), the main entry point for a UEFI Image. The System Table contains pointers to the active console devices, a pointer to the Boot Services Table, a pointer to the Runtime Services Table, and a pointer to the list of system configuration tables such as ACPI, SMBIOS, and the SAL System Table. This section describes the System Table in detail.

EFI_IMAGE_ENTRY_POINT

Summary

This is the main entry point for a UEFI Image. This entry point is the same for UEFI Applications, UEFI OS Loaders, and UEFI Drivers including both device drivers and bus drivers.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_IMAGE_ENTRY_POINT) (
    IN EFI_HANDLE          ImageHandle,
    IN EFI_SYSTEM_TABLE   *SystemTable
);
```

Parameters

<i>ImageHandle</i>	The firmware allocated handle for the UEFI image.
<i>SystemTable</i>	A pointer to the EFI System Table.

Description

This function is the entry point to an EFI image. An EFI image is loaded and relocated in system memory by the EFI Boot Service [LoadImage\(\)](#). An EFI image is invoked through the EFI Boot Service [StartImage\(\)](#).

The first argument is the image's image handle. The second argument is a pointer to the image's system table. The system table contains the standard output and input handles, plus pointers to the

[EFI_BOOT_SERVICES](#) and [EFI_RUNTIME_SERVICES](#) tables. The service tables contain the entry points in the firmware for accessing the core EFI system functionality. The handles in the system table are used to obtain basic access to the console. In addition, the System Table contains pointers to other standard tables that a loaded image may use if the associated pointers are initialized to nonzero values. Examples of such tables are ACPI, SMBIOS, SAL System Table, etc.

The *ImageHandle* is a firmware-allocated handle that is used to identify the image on various functions. The handle also supports one or more protocols that the image can use. All images support the [EFI_LOADED_IMAGE_PROTOCOL](#) that returns the source location of the image, the memory location of the image, the load options for the image, etc. The exact [EFI_LOADED_IMAGE_PROTOCOL](#) structure is defined in [Section 8](#).

If the image is an application written to this specification, then the application executes and either returns or calls the EFI Boot Services [Exit\(\)](#). An applications written to this specification is always unloaded from memory when it exits, and its return status is returned to the component that started the application.

If the EFI image is an EFI OS Loader, then the EFI OS Loader executes and either returns, calls the EFI Boot Service [Exit\(\)](#), or calls the EFI Boot Service [ExitBootServices\(\)](#). If the EFI OS Loader returns or calls [Exit\(\)](#), then the load of the OS has failed, and the EFI OS Loader is unloaded from memory and control is returned to the component that attempted to boot the EFI OS Loader. If [ExitBootServices\(\)](#) is called, then the OS Loader has taken control of the platform, and EFI will not regain control of the system until the platform is reset. One method of resetting the platform is through the EFI Runtime Service [ResetSystem\(\)](#).

If the image is a UEFI Driver, then the driver executes and either returns or calls the Boot Service [Exit\(\)](#). If a driver returns an error, then the driver is unloaded from memory. If the driver returns [EFI_SUCCESS](#), then it stays resident in memory. If the driver does not follow the UEFI Driver Model, then it performs any required initialization and installs its protocol services before returning. If the driver does follow the UEFI Driver Model, then the entry point is not allowed to touch any device hardware. Instead, the entry point is required to create and install the [EFI_DRIVER_BINDING_PROTOCOL](#) (see [Section 10.1](#)) on the *ImageHandle* of the UEFI driver. If this process is completed, then [EFI_SUCCESS](#) is returned. If the resources are not available to complete the driver initialization, then [EFI_OUT_OF_RESOURCES](#) is returned.

Status Codes Returned

EFI_SUCCESS	The driver was initialized.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

4.2 EFI Table Header

The data type [EFI_TABLE_HEADER](#) is the data structure that precedes all of the standard EFI table types. It includes a signature that is unique for each table type, a revision of the table that may be updated as extensions are added to the EFI table types, and a 32-bit CRC so a consumer of an EFI table type can validate the contents of the EFI table.

EFI_TABLE_HEADER

Summary

Data structure that precedes all of the standard EFI table types.

Related Definitions

```
typedef struct {
    UINT64    Signature;
    UINT32    Revision;
    UINT32    HeaderSize;
    UINT32    CRC32;
    UINT32    Reserved;
} EFI_TABLE_HEADER;
```

Parameters

<i>Signature</i>	A 64-bit signature that identifies the type of table that follows. Unique signatures have been generated for the EFI System Table, the EFI Boot Services Table, and the EFI Runtime Services Table.
<i>Revision</i>	The revision of the EFI Specification to which this table conforms. The upper 16 bits of this field contain the major revision value, and the lower 16 bits contain the minor revision value. The minor revision values are limited to the range of 00..99.
<i>HeaderSize</i>	The size, in bytes, of the entire table including the EFI_TABLE_HEADER .
<i>CRC32</i>	The 32-bit CRC for the entire table. This value is computed by setting this field to 0, and computing the 32-bit CRC for <i>HeaderSize</i> bytes.
<i>Reserved</i>	Reserved field that must be set to 0.

Note: *The capabilities found in the EFI system table, runtime table and boot services table may change over time. The first field in each of these tables is an EFI_TABLE_HEADER. This header's Revision field is incremented when new capabilities and functions are added to the functions in the table. When checking for capabilities, code should verify that Revision is greater than or equal to*

the revision level of the table at the point when the capabilities were added to the UEFI specification.

Note: *Unless otherwise specified, UEFI uses a standard CCITT32 CRC algorithm with a seed polynomial value of 0x04c11db7 for its CRC calculations.*

Note: *The size of the system table, runtime services table, and boot services table may increase over time. It is very important to always use the `HeaderSize` field of the `EFI_TABLE_HEADER` to determine the size of these tables.*

4.3 EFI System Table

UEFI uses the EFI System Table, which contains pointers to the runtime and boot services tables. The definition for this table is shown in the following code fragments. Except for the table header, all elements in the service tables are pointers to functions as defined in [Section 6](#) and [Section 7](#). Prior to a call to `ExitBootServices()`, all of the fields of the EFI System Table are valid. After an operating system has taken control of the platform with a call to `ExitBootServices()`, only the `Hdr`, `FirmwareVendor`, `FirmwareRevision`, `RuntimeServices`, `NumberOfTableEntries`, and `ConfigurationTable` fields are valid.

EFI_SYSTEM_TABLE

Summary

Contains pointers to the runtime and boot services tables.

Related Definitions

```
#define EFI_SYSTEM_TABLE_SIGNATURE      0x5453595320494249
#define EFI_2_10_SYSTEM_TABLE_REVISION ((2<<16) | (10))
#define EFI_2_00_SYSTEM_TABLE_REVISION ((2<<16) | (00))
#define EFI_1_10_SYSTEM_TABLE_REVISION ((1<<16) | (10))
#define EFI_1_02_SYSTEM_TABLE_REVISION ((1<<16) | (02))
#define EFI_SYSTEM_TABLE_REVISION      EFI_2_10_SYSTEM_TABLE_REVISION
#define EFI_SPECIFICATION_VERSION      EFI_SYSTEM_TABLE_REVISION

typedef struct {
    EFI_TABLE_HEADER      Hdr;
    CHAR16                *FirmwareVendor;
    UINT32                FirmwareRevision;
    EFI_HANDLE            ConsoleInHandle;
    EFI_SIMPLE_INPUT_PROTOCOL *ConIn;
    EFI_HANDLE            ConsoleOutHandle;
    EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *ConOut;
    EFI_HANDLE            StandardErrorHandle;
    EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *StdErr;
    EFI_RUNTIME_SERVICES  *RuntimeServices;
    EFI_BOOT_SERVICES     *BootServices;
```

```

UINTN                NumberOfTableEntries;
EFI_CONFIGURATION_TABLE *ConfigurationTable;
} EFI_SYSTEM_TABLE;

```

Parameters

<i>Hdr</i>	The table header for the EFI System Table. This header contains the EFI_SYSTEM_TABLE_SIGNATURE and EFI_SYSTEM_TABLE_REVISION values along with the size of the EFI_SYSTEM_TABLE structure and a 32-bit CRC to verify that the contents of the EFI System Table are valid.
<i>FirmwareVendor</i>	A pointer to a null terminated Unicode string that identifies the vendor that produces the system firmware for the platform.
<i>FirmwareRevision</i>	A firmware vendor specific value that identifies the revision of the system firmware for the platform.
<i>ConsoleInHandle</i>	The handle for the active console input device. This handle must support SIMPLE_INPUT_PROTOCOL and SIMPLE_INPUT_PROTOCOL_EX .
<i>ConIn</i>	A pointer to the SIMPLE_INPUT_PROTOCOL interface that is associated with <i>ConsoleInHandle</i> .
<i>ConsoleOutHandle</i>	The handle for the active console output device. This handle must support the EFI SIMPLE TEXT OUTPUT PROTOCOL .
<i>ConOut</i>	A pointer to the SIMPLE_TEXT_OUTPUT_PROTOCOL interface that is associated with <i>ConsoleOutHandle</i> .
<i>StandardErrorHandle</i>	The handle for the active standard error console device. This handle must support the SIMPLE_TEXT_OUTPUT_PROTOCOL .
<i>StdErr</i>	A pointer to the SIMPLE_TEXT_OUTPUT_PROTOCOL interface that is associated with <i>StandardErrorHandle</i> .
<i>RuntimeServices</i>	A pointer to the EFI Runtime Services Table. See Section 4.5 .
<i>BootServices</i>	A pointer to the EFI Boot Services Table. See Section 4.4 .
<i>NumberOfTableEntries</i>	The number of system configuration tables in the buffer <i>ConfigurationTable</i> .
<i>ConfigurationTable</i>	A pointer to the system configuration tables. The number of entries in the table is <i>NumberOfTableEntries</i> .

4.4 EFI Boot Services Table

UEFI uses the EFI Boot Services Table, which contains a table header and pointers to all of the boot services. The definition for this table is shown in the following code fragments. Except for the table header, all elements in the EFI Boot Services Tables are prototypes of function pointers to functions as defined in [Section 6](#). The function pointers in this table are not valid after the operating system has taken control of the platform with a call to [ExitBootServices\(\)](#).

EFI_BOOT_SERVICES

Summary

Contains a table header and pointers to all of the boot services.

Related Definitions

```

#define EFI_BOOT_SERVICES_SIGNATURE      0x56524553544f4f42
#define EFI_BOOT_SERVICES_REVISION      EFI_SPECIFICATION_VERSION

typedef struct {
    EFI_TABLE_HEADER                Hdr;

    //
    // Task Priority Services
    //
    EFI_RAISE_TPL                    RaiseTPL;           // EFI 1.0+
    EFI_RESTORE_TPL                   RestoreTPL;        // EFI 1.0+

    //
    // Memory Services
    //
    EFI_ALLOCATE_PAGES                 AllocatePages;     // EFI 1.0+
    EFI_FREE_PAGES                     FreePages;        // EFI 1.0+
    EFI_GET_MEMORY_MAP                 GetMemoryMap;     // EFI 1.0+
    EFI_ALLOCATE_POOL                   AllocatePool;    // EFI 1.0+
    EFI_FREE_POOL                       FreePool;       // EFI 1.0+

    //
    // Event & Timer Services
    //
    EFI_CREATE_EVENT                   CreateEvent;      // EFI 1.0+
    EFI_SET_TIMER                       SetTimer;        // EFI 1.0+
    EFI_WAIT_FOR_EVENT                 WaitForEvent;     // EFI 1.0+
    EFI_SIGNAL_EVENT                   SignalEvent;      // EFI 1.0+
    EFI_CLOSE_EVENT                   CloseEvent;       // EFI 1.0+
    EFI_CHECK_EVENT                    CheckEvent;       // EFI 1.0+

    //
    // Protocol Handler Services
    //
    EFI_INSTALL_PROTOCOL_INTERFACE     InstallProtocolInterface; // EFI
                                     1.0+

```



```

EFI_REINSTALL_PROTOCOL_INTERFACE ReinstallProtocolInterface; //
                                     EFI 1.0+
EFI_UNINSTALL_PROTOCOL_INTERFACE UninstallProtocolInterface; // EFI
                                     1.0+
EFI_HANDLE_PROTOCOL                HandleProtocol; // EFI 1.0+
VOID*                               Reserved; // EFI 1.0+
EFI_REGISTER_PROTOCOL_NOTIFY       RegisterProtocolNotify; // EFI
                                     1.0+
EFI_LOCATE_HANDLE                  LocateHandle; // EFI 1.0+
EFI_LOCATE_DEVICE_PATH            LocateDevicePath; // EFI 1.0+
EFI_INSTALL_CONFIGURATION_TABLE    InstallConfigurationTable; // EFI
                                     1.0+

//
// Image Services
//
EFI_IMAGE_LOAD                    LoadImage; // EFI 1.0+
EFI_IMAGE_START                   StartImage; // EFI 1.0+
EFI_EXIT                           Exit; // EFI 1.0+
EFI_IMAGE_UNLOAD                  UnloadImage; // EFI 1.0+
EFI_EXIT_BOOT_SERVICES            ExitBootServices; // EFI 1.0+

//
// Miscellaneous Services
//
EFI_GET_NEXT_MONOTONIC_COUNT       GetNextMonotonicCount; // EFI
                                     1.0+
EFI_STALL                          Stall; // EFI 1.0+
EFI_SET_WATCHDOG_TIMER            SetWatchdogTimer; // EFI 1.0+

//
// DriverSupport Services
//
EFI_CONNECT_CONTROLLER            ConnectController; // EFI 1.1
EFI_DISCONNECT_CONTROLLER        DisconnectController; // EFI 1.1+

//
// Open and Close Protocol Services
//
EFI_OPEN_PROTOCOL                 OpenProtocol; // EFI 1.1+
EFI_CLOSE_PROTOCOL               CloseProtocol; // EFI
1.1+

```

```

EFI_OPEN_PROTOCOL_INFORMATION    OpenProtocolInformation; // EFI
                                   1.1+

//
// Library Services
//
EFI_PROTOCOLS_PER_HANDLE        ProtocolsPerHandle;      // EFI
                                   1.1+
EFI_LOCATE_HANDLE_BUFFER        LocateHandleBuffer;     // EFI
                                   1.1+
EFI_LOCATE_PROTOCOL             LocateProtocol;       // EFI
                                   1.1+

EFI_INSTALL_MULTIPLE_PROTOCOL_INTERFACES InstallMultipleProtocolInt
erfaces; // EFI 1.1+
EFI_UNINSTALL_MULTIPLE_PROTOCOL_INTERFACES UninstallMultipleProtocol
Interfaces; // EFI 1.1+

//
// 32-bit CRC Services
//
EFI_CALCULATE_CRC32             CalculateCrc32;          // EFI
                                   1.1+

//
// Miscellaneous Services
//
EFI_COPY_MEM                   CopyMem;              // EFI 1.1+
EFI_SET_MEM                     SetMem;              // EFI 1.1+
EFI_CREATE_EVENT_EX             CreateEventEx;      // UEFI 2.0+
} EFI_BOOT_SERVICES;

```

Parameters

<i>Hdr</i>	The table header for the EFI Boot Services Table. This header contains the EFI_BOOT_SERVICES_SIGNATURE and EFI_BOOT_SERVICES_REVISION values along with the size of the EFI_BOOT_SERVICES structure and a 32-bit CRC to verify that the contents of the EFI Boot Services Table are valid.
<i>RaiseTPL</i>	Raises the task priority level.
<i>RestoreTPL</i>	Restores/lowers the task priority level.
<i>AllocatePages</i>	Allocates pages of a particular type.
<i>FreePages</i>	Frees allocated pages.

<i>GetMemoryMap</i>	Returns the current boot services memory map and memory map key.
<i>AllocatePool</i>	Allocates a pool of a particular type.
<i>FreePool</i>	Frees allocated pool.
<i>CreateEvent</i>	Creates a general-purpose event structure.
<i>SetTimer</i>	Sets an event to be signaled at a particular time.
<i>WaitForEvent</i>	Stops execution until an event is signaled.
<i>SignalEvent</i>	Signals an event.
<i>CloseEvent</i>	Closes and frees an event structure.
<i>CheckEvent</i>	Checks whether an event is in the signaled state.
<i>InstallProtocolInterface</i>	Installs a protocol interface on a device handle.
<i>ReinstallProtocolInterface</i>	Reinstalls a protocol interface on a device handle.
<i>UninstallProtocolInterface</i>	Removes a protocol interface from a device handle.
<i>HandleProtocol</i>	Queries a handle to determine if it supports a specified protocol.
<i>Reserved</i>	Reserved. Must be NULL .
<i>RegisterProtocolNotify</i>	Registers an event that is to be signaled whenever an interface is installed for a specified protocol.
<i>LocateHandle</i>	Returns an array of handles that support a specified protocol.
<i>LocateDevicePath</i>	Locates all devices on a device path that support a specified protocol and returns the handle to the device that is closest to the path.
<i>InstallConfigurationTable</i>	Adds, updates, or removes a configuration table from the EFI System Table.
<i>LoadImage</i>	Loads an EFI image into memory.
<i>StartImage</i>	Transfers control to a loaded image's entry point.
<i>Exit</i>	Exits the image's entry point.
<i>UnloadImage</i>	Unloads an image.
<i>ExitBootServices</i>	Terminates boot services.
<i>GetNextMonotonicCount</i>	Returns a monotonically increasing count for the platform.
<i>Stall</i>	Stalls the processor.
<i>SetWatchdogTimer</i>	Resets and sets a watchdog timer used during boot services time.
<i>ConnectController</i>	Uses a set of precedence rules to find the best set of drivers to manage a controller.
<i>DisconnectController</i>	Informs a set of drivers to stop managing a controller.

<i>OpenProtocol</i>	Adds elements to the list of agents consuming a protocol interface.
<i>CloseProtocol</i>	Removes elements from the list of agents consuming a protocol interface.
<i>OpenProtocolInformation</i>	Retrieve the list of agents that are currently consuming a protocol interface.
<i>ProtocolsPerHandle</i>	Retrieves the list of protocols installed on a handle. The return buffer is automatically allocated.
<i>LocateHandleBuffer</i>	Retrieves the list of handles from the handle database that meet the search criteria. The return buffer is automatically allocated.
<i>LocateProtocol</i>	Finds the first handle in the handle database the supports the requested protocol.
<i>InstallMultipleProtocolInterfaces</i>	Installs one or more protocol interfaces onto a handle.
<i>UninstallMultipleProtocolInterfaces</i>	Uninstalls one or more protocol interfaces from a handle.
<i>CalculateCrc32</i>	Computes and returns a 32-bit CRC for a data buffer.
<i>CopyMem</i>	Copies the contents of one buffer to another buffer.
<i>SetMem</i>	Fills a buffer with a specified value.
<i>CreateEventEx</i>	Creates an event structure as part of an event group.

4.5 EFI Runtime Services Table

UEFI uses the EFI Runtime Services Table, which contains a table header and pointers to all of the runtime services. The definition for this table is shown in the following code fragments. Except for the table header, all elements in the EFI Runtime Services Tables are prototypes of function pointers to functions as defined in [Section 7](#). Unlike the EFI Boot Services Table, this table, and the function pointers it contains are valid after the operating system has taken control of the platform with a call to [ExitBootServices\(\)](#). If a call to [SetVirtualAddressMap\(\)](#) is made by the OS, then the function pointers in this table are fixed up to point to the new virtually mapped entry points.

EFI_RUNTIME_SERVICES

Summary

Contains a table header and pointers to all of the runtime services.

Related Definitions

```
#define EFI_RUNTIME_SERVICES_SIGNATURE 0x56524553544e5552
#define EFI_RUNTIME_SERVICES_REVISION EFI_SPECIFICATION_VERSION
typedef struct {
    EFI_TABLE_HEADER Hdr;

    //
```

```

// Time Services
//
EFI_GET_TIME           GetTime;
EFI_SET_TIME           SetTime;
EFI_GET_WAKEUP_TIME    GetWakeupTime;
EFI_SET_WAKEUP_TIME    SetWakeupTime;

//
// Virtual Memory Services
//
EFI_SET_VIRTUAL_ADDRESS_MAP  SetVirtualAddressMap;
EFI_CONVERT_POINTER          ConvertPointer;

//
// Variable Services
//
EFI_GET_VARIABLE             GetVariable;
EFI_GET_NEXT_VARIABLE_NAME   GetNextVariableName;
EFI_SET_VARIABLE             SetVariable;

//
// Miscellaneous Services
//
EFI_GET_NEXT_HIGH_MONO_COUNT GetNextHighMonotonicCount;
EFI_RESET_SYSTEM             ResetSystem;

//
// UEFI 2.0 Capsule Services
//
EFI_UPDATE_CAPSULE           UpdateCapsule;
EFI_QUERY_CAPSULE_CAPABILITIES QueryCapsuleCapabilities;

//
// Miscellaneous UEFI 2.0 Service
//
EFI_QUERY_VARIABLE_INFO      QueryVariableInfo;
} EFI_RUNTIME_SERVICES;

```

Parameters

Hdr

The table header for the EFI Runtime Services Table. This header contains the **EFI_RUNTIME_SERVICES_SIGNATURE** and **EFI_RUNTIME_SERVICES_REVISION** values along with the size of the **EFI_RUNTIME_SERVICES** structure and a 32-bit CRC to verify that the contents of the EFI Runtime Services Table are valid.

<i>GetTime</i>	Returns the current time and date, and the time-keeping capabilities of the platform.
<i>SetTime</i>	Sets the current local time and date information.
<i>GetWakeuptime</i>	Returns the current wakeup alarm clock setting.
<i>SetWakeuptime</i>	Sets the system wakeup alarm clock time.
<i>SetVirtualAddressMap</i>	Used by an OS loader to convert from physical addressing to virtual addressing.
<i>ConvertPointer</i>	Used by EFI components to convert internal pointers when switching to virtual addressing.
<i>GetVariable</i>	Returns the value of a variable.
<i>GetNextVariableName</i>	Enumerates the current variable names.
<i>SetVariable</i>	Sets the value of a variable.
<i>GetNextHighMonotonicCount</i>	Returns the next high 32 bits of the platform's monotonic counter.
<i>ResetSystem</i>	Resets the entire platform.
<i>UpdateCapsule</i>	Passes capsules to the firmware with both virtual and physical mapping.
<i>QueryCapsuleCapabilities</i>	Returns if the capsule can be supported via UpdateCapsule () .
<i>QueryVariableInfo</i>	Returns information about the EFI variable store.

4.6 EFI Configuration Table

The EFI Configuration Table is the *ConfigurationTable* field in the EFI System Table. This table contains a set of GUID/pointer pairs. Each element of this table is described by the **EFI_CONFIGURATION_TABLE** structure below. The number of types of configuration tables is expected to grow over time. This is why a GUID is used to identify the configuration table type. The EFI Configuration Table may contain at most once instance of each table type.

EFI_CONFIGURATION_TABLE

Summary

Contains a set of GUID/pointer pairs comprised of the *ConfigurationTable* field in the EFI System Table.

Related Definitions

```
typedef struct{
    EFI_GUID           VendorGuid;
    VOID              *VendorTable;
} EFI_CONFIGURATION_TABLE;
```

Parameters

The following list shows the GUIDs for tables defined in some of the industry standards. These industry standards define tables accessed as UEFI Configuration Tables on UEFI-based systems. This list is not exhaustive and does not show GUIDS for all possible UEFI Configuration tables.

<i>VendorGuid</i>	The 128-bit GUID value that uniquely identifies the system configuration table.
<i>VendorTable</i>	A pointer to the table associated with <i>VendorGuid</i> . Whether this pointer is a physical address or a virtual address during runtime is determined by the <i>VendorGuid</i> . The <i>VendorGuid</i> associated with a given <i>VendorTable</i> pointer defines whether or not a particular address gets fixed up when a call to SetVirtualAddressMap() is made.

```
//
// All of these VendorTable entries will be referenced as physical
// addresses and will not be fixed up when transitioning from preboot to
//runtime phase.
//

#define EFI_ACPI_20_TABLE_GUID \
    {0x8868e871, 0xe4f1, 0x11d3, 0xbc, 0x22, 0x0, 0x80, 0xc7, 0x3c, 0x88, 0x81}

#define ACPI_TABLE_GUID \
    {0xeb9d2d30, 0x2d88, 0x11d3, 0x9a, 0x16, 0x0, 0x90, 0x27, 0x3f, 0xc1, 0x4d}

#define SAL_SYSTEM_TABLE_GUID \
    {0xeb9d2d32, 0x2d88, 0x11d3, 0x9a, 0x16, 0x0, 0x90, 0x27, 0x3f, 0xc1, 0x4d}

#define SMBIOS_TABLE_GUID \
    {0xeb9d2d31, 0x2d88, 0x11d3, 0x9a, 0x16, 0x0, 0x90, 0x27, 0x3f, 0xc1, 0x4d}

#define MPS_TABLE_GUID \
    {0xeb9d2d2f, 0x2d88, 0x11d3, 0x9a, 0x16, 0x0, 0x90, 0x27, 0x3f, 0xc1, 0x4d}
//
// ACPI 2.0 or newer tables should use EFI_ACPI_TABLE_GUID
//
#define EFI_ACPI_TABLE_GUID \
    {0x8868e871, 0xe4f1, 0x11d3, 0xbc, 0x22, 0x0, 0x80, 0xc7, 0x3c, 0x88, 0x81}
#define ACPI_10_TABLE_GUID \
    {0xeb9d2d30, 0x2d88, 0x11d3, 0x9a, 0x16, 0x0, 0x90, 0x27, 0x3f, 0xc1, 0x4d}
```

4.7 Image Entry Point Examples

The examples in the following sections show how the various table examples are presented in the UEFI environment.

4.7.1 Image Entry Point Examples

The following example shows the image entry point for a UEFI Application. This application makes use of the EFI System Table, the EFI Boot Services Table, and the EFI Runtime Services Table.

```

EFI_SYSTEM_TABLE                *gST;
EFI_BOOT_SERVICES_TABLE        *gBS;
EFI_RUNTIME_SERVICES_TABLE     *gRT;

EfiApplicationEntryPoint(
    IN EFI_HANDLE                ImageHandle,
    IN EFI_SYSTEM_TABLE         *SystemTable
)
{
    EFI_STATUS  Status;
    EFI_TIME    *Time;

    gST = SystemTable;
    gBS = gST->BootServices;
    gRT = gST->RuntimeServices;

    //
    // Use EFI System Table to print "Hello World" to the active console output
    // device.
    //
    Status = gST->ConOut->OutputString (gST->ConOut, L"Hello World\n\r");
    if (EFI_ERROR (Status)) {
        return Status;
    }

    //
    // Use EFI Boot Services Table to allocate a buffer to store the current time
    // and date.
    //
    Status = gBS->AllocatePool (
        EfiBootServicesData,
        sizeof (EFI_TIME),
        (VOID **) &Time
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }

    //
    // Use the EFI Runtime Services Table to get the current time and date.
    //
    Status = gRT->GetTime (Time, NULL)
    if (EFI_ERROR (Status)) {
        return Status;
    }

    return Status;
}

```

The following example shows the UEFI image entry point for a driver that does not follow the UEFI *Driver Model*. Since this driver returns **EFI_SUCCESS**, it will stay resident in memory after it exits.


```

EFI_SYSTEM_TABLE                *gST;
EFI_BOOT_SERVICES_TABLE         *gBS;
EFI_RUNTIME_SERVICES_TABLE      *gRT;

EfiDriverEntryPoint(
    IN EFI_HANDLE                ImageHandle,
    IN EFI_SYSTEM_TABLE         *SystemTable
)
{
    gST = SystemTable;
    gBS = gST->BootServices;
    gRT = gST->RuntimeServices;

    //
    // Implement driver initialization here.
    //

    return EFI_SUCCESS;
}

```

The following example shows the UEFI image entry point for a driver that also does not follow the UEFI *Driver Model*. Since this driver returns **EFI_DEVICE_ERROR**, it will not stay resident in memory after it exits.

```

EFI_SYSTEM_TABLE                *gST;
EFI_BOOT_SERVICES_TABLE         *gBS;
EFI_RUNTIME_SERVICES_TABLE      *gRT;

EfiDriverEntryPoint(
    IN EFI_HANDLE                ImageHandle,
    IN EFI_SYSTEM_TABLE         *SystemTable
)
{
    gST = SystemTable;
    gBS = gST->BootServices;
    gRT = gST->RuntimeServices;

    //
    // Implement driver initialization here.
    //

    return EFI_DEVICE_ERROR;
}

```

4.7.2 UEFI Driver Model Example

The following is an UEFI *Driver Model* example that shows the driver initialization routine for the ABC device controller that is on the XYZ bus. The **EFI_DRIVER_BINDING_PROTOCOL** and the function prototypes for [AbcSupported\(\)](#), [AbcStart\(\)](#), and [AbcStop\(\)](#) are defined in [Section 10.1](#). This function saves the driver's image handle and a pointer to the EFI boot services table in global variables, so the other functions in the same driver can have access to these values. It then creates an instance of the **EFI_DRIVER_BINDING_PROTOCOL** and installs it onto the driver's image handle.

```

extern EFI_GUID                  gEfiDriverBindingProtocolGuid;

```

```

EFI_BOOT_SERVICES_TABLE      *gBS;
static EFI_DRIVER_BINDING_PROTOCOL  mAbcDriverBinding = {
    AbcSupported,
    AbcStart,
    AbcStop,
    1,
    NULL,
    NULL
};

AbcEntryPoint(
    IN EFI_HANDLE      ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
)
{
    EFI_STATUS  Status;

    gBS = SystemTable->BootServices;

    mAbcDriverBinding->ImageHandle      = ImageHandle;
    mAbcDriverBinding->DriverBindingHandle = ImageHandle;

    Status = gBS->InstallMultipleProtocolInterfaces(
        &mAbcDriverBinding->DriverBindingHandle,
        &gEfiDriverBindingProtocolGuid, &mAbcDriverBinding,
        NULL
    );

    return Status;
}

```

4.7.3 UEFI Driver Model Example (Unloadable)

The following is the same UEFI *Driver Model* example as above, except it also includes the code required to allow the driver to be unloaded through the boot service [Unload\(\)](#). Any protocols installed or memory allocated in **AbcEntryPoint()** must be uninstalled or freed in the **AbcUnload()**.

```

extern EFI_GUID      gEfiLoadedImageProtocolGuid;
extern EFI_GUID      gEfiDriverBindingProtocolGuid;
EFI_BOOT_SERVICES_TABLE      *gBS;
static EFI_DRIVER_BINDING_PROTOCOL  mAbcDriverBinding = {
    AbcSupported,
    AbcStart,
    AbcStop,
    1,
    NULL,
    NULL
};

EFI_STATUS
AbcUnload (
    IN EFI_HANDLE  ImageHandle
);

AbcEntryPoint(
    IN EFI_HANDLE      ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
)

```

```

{
  EFI_STATUS          Status;
  EFI_LOADED_IMAGE_PROTOCOL *LoadedImage;

  gBS = SystemTable->BootServices;

  Status = gBS->OpenProtocol (
    ImageHandle,
    &gEfiLoadedImageProtocolGuid,
    &LoadedImage,
    ImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
  );
  if (EFI_ERROR (Status)) {
    return Status;
  }
  LoadedImage->Unload = AbcUnload;

  mAbcDriverBinding->ImageHandle          = ImageHandle;
  mAbcDriverBinding->DriverBindingHandle = ImageHandle;

  Status = gBS->InstallMultipleProtocolInterfaces(
    &mAbcDriverBinding->DriverBindingHandle,
    &gEfiDriverBindingProtocolGuid, &mAbcDriverBinding,
    NULL
  );

  return Status;
}

EFI_STATUS
AbcUnload (
  IN EFI_HANDLE ImageHandle
)
{
  EFI_STATUS Status;

  Status = gBS->UninstallMultipleProtocolInterfaces (
    ImageHandle,
    &gEfiDriverBindingProtocolGuid, &mAbcDriverBinding,
    NULL
  );

  return Status;
}

```

4.7.4 EFI Driver Model Example (Multiple Instances)

The following is the same as the first *UEFI Driver Model* example, except it produces three [EFI DRIVER BINDING PROTOCOL](#) instances. The first one is installed onto the driver's image handle. The other two are installed onto newly created handles.

```

extern EFI_GUID          gEfiDriverBindingProtocolGuid;
EFI_BOOT_SERVICES_TABLE *gBS;

static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBindingA = {
  AbcSupportedA,
  AbcStartA,

```

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```
    AbcStopA,
    1,
    NULL,
    NULL
};

static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBindingB = {
    AbcSupportedB,
    AbcStartB,
    AbcStopB,
    1,
    NULL,
    NULL
};

static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBindingC = {
    AbcSupportedC,
    AbcStartC,
    AbcStopC,
    1,
    NULL,
    NULL
};

AbcEntryPoint(
    IN EFI_HANDLE          ImageHandle,
    IN EFI_SYSTEM_TABLE   *SystemTable
)
{
    EFI_STATUS  Status;

    gBS = SystemTable->BootServices;

    //
    // Install mAbcDriverBindingA onto ImageHandle
    //
    mAbcDriverBindingA->ImageHandle          = ImageHandle;
    mAbcDriverBindingA->DriverBindingHandle = ImageHandle;

    Status = gBS->InstallMultipleProtocolInterfaces(
        &mAbcDriverBindingA->DriverBindingHandle,
        &gEfiDriverBindingProtocolGuid, &mAbcDriverBindingA,
        NULL
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }

    //
    // Install mAbcDriverBindingB onto a newly created handle
    //
    mAbcDriverBindingB->ImageHandle          = ImageHandle;
    mAbcDriverBindingB->DriverBindingHandle = NULL;

    Status = gBS->InstallMultipleProtocolInterfaces(
        &mAbcDriverBindingB->DriverBindingHandle,
        &gEfiDriverBindingProtocolGuid, &mAbcDriverBindingB,
        NULL
    );
    if (EFI_ERROR (Status)) {
```

```
    return Status;
}

//
// Install mAbcDriverBindingC onto a newly created handle
//
mAbcDriverBindingC->ImageHandle      = ImageHandle;
mAbcDriverBindingC->DriverBindingHandle = NULL;

Status = gBS->InstallMultipleProtocolInterfaces(
    &mAbcDriverBindingC->DriverBindingHandle,
    &gEfiDriverBindingProtocolGuid, &mAbcDriverBindingC,
    NULL
);

return Status;
}
```


GUID Partition Table (GPT) Format

5.1 EFI Partition Formats

This specification defines a new partitioning scheme that must be supported by firmware which conforms to it. The following list outlines the advantages of using the GUID Partition Table over the legacy MBR partition table:

- Logical Block Addressing is 64 bits.
- Supports many partitions.
- Uses a primary and backup table for redundancy.
- Uses version number and size fields for future expansion.
- Uses CRC32 fields for improved data integrity.
- Defines a GUID for uniquely identifying each partition.
- Uses a GUID and attributes to define partition content type.
- Each partition contains a 36 Unicode character human readable name.

5.2 LBA 0 Format

LBA 0 (i.e. the first block) of the hard disk contains either a legacy Master Boot Record (MBR) (see [Section 5.2.1](#)) or a protective MBR (see [Section 5.2.2](#)).

5.2.1 Legacy Master Boot Record (MBR)

A legacy master boot record may be located at LBA 0 (i.e. the first block) of the hard disk if it is not using the GPT partition scheme. The boot code on the MBR is not executed by EFI firmware. The MBR may optionally contain a UniqueMBRSignature located as defined in [Table 10](#). The UniqueMBRSignature must be maintained by operating systems, and is never maintained by EFI firmware. The UniqueMBRSignature is only 4 bytes in length, so it is not a GUID. UEFI does not specify the algorithm that is used to generate UniqueMBRSignature. The uniqueness of UniqueMBRSignature is defined as all disks in a given system having a unique value in this field.

Table 10. Legacy Master Boot Record

Mnemonic	Byte Offset	Byte Length	Description
<i>BootCode</i>	0	440	Code used on a legacy system to select a partition record and load the first block (sector) of the partition pointed to by the partition record. This code is not executed on UEFI systems.

<i>UniqueMBRSignature</i>	440	4	Unique Disk Signature, this is an optional feature and not on all hard drives. This value is always written by the OS and is never written by EFI firmware.
<i>Unknown</i>	444	2	Unknown
<i>PartitionRecord</i>	446	16*4	Array of four legacy MBR partition records (see Table 11).
<i>Signature</i>	510	2	Must be 0xaa55 (i.e., byte 510 contains 0x55 and byte 511 contains 0xaa).
<i>Reserved</i>	512	BlockSize - 512	The rest of the logical block, if any, is reserved.

The MBR contains four partition records that define the beginning and ending LBA addresses that a partition consumes on a hard disk. The partition record contains a legacy Cylinder Head Sector (CHS) address that is not used in UEFI. UEFI utilizes the *StartingLBA* entry to define the starting LBA of the partition on the disk. The size of the partition is defined by the *SizeInLBA* field.

The boot indicator field is not used by EFI firmware. The operating system indicator value of 0xEF defines a partition that contains a UEFI file system. The other values of the system indicator are not defined by this specification. If an MBR partition has an operating system indicator value of 0xEF, then the firmware must add the EFI System Partition GUID to the handle for the MBR partition using [InstallProtocolInterface\(\)](#). This will allow drivers and applications, including OS loaders, to easily search for handles that represent EFI System Partitions.

Table 11. Legacy Master Boot Record Partition Record

Mnemonic	Byte Offset	Byte Length	Description
<i>BootIndicator</i>	0	1	Not used by EFI firmware . 0x80 indicates that this is the bootable legacy partition.
<i>StartingCHS</i>	1	3	Start of partition in CHS address format, not used by EFI firmware.
<i>OSType</i>	4	1	Type of partition. 0xEF defines an EFI system partition. 0xEE is used by a protective MBR (Table 12) to define a fake partition covering the entire disk. Other values are used by legacy operating systems, and are allocated independently of the UEFI specification.
<i>Ending CHS</i>	1	3	End of partition in CHS address format, not used by EFI firmware.
<i>Starting LBA</i>	8	4	Starting LBA of the partition on the disk. Used by EFI firmware to define the start of the partition.
<i>SizeInLBA</i>	12	4	Size of the partition in LBA units of logical blocks.. Used by EFI firmware to determine the size of the partition.

The following test must be performed to determine if a legacy MBR is valid:

- The Signature must be 0xaa55.

- A partition record that contains an *OSType* value of zero or a *SizeInLBA* value of zero may be ignored.

Otherwise:

- The partition defined by each MBR partition record must physically reside on the disk.
- Each partition must not overlap with other partitions.

5.2.2 Protective Master Boot Record

On all GUID Partition Table disks a Protective MBR (PMBR) in LBA 0 (that is, the first block) precedes the GUID Partition Table Header to maintain compatibility with existing tools that do not understand GPT partition structures. The Protective MBR has the same format as a legacy MBR (see [Section 5.2.1](#)) and contains one partition entry with an *OSType* set to 0xEE reserving the entire space used on the disk by the GPT partitions, including all headers as shown in [Table 12](#). If the GPT partition is larger than a partition that can be represented by a legacy MBR, values of all *Fs* must be used to signify that all space that can be possibly reserved by the MBR is being reserved.

Table 12. Protective MBR Partition Record

Mnemonic	Byte Offset	Byte Length	Description
<i>BootIndicator</i>	0	1	Must be set to zero to indicate nonbootable partition.
<i>StartingCHS</i>	1	3	Must be 0x000200, corresponding to the <i>StartingLBA</i> .
<i>OSType</i>	4	1	Must be 0xEE.
<i>EndingCHS</i>	1	3	Set to the CHS address of the last logical block on the disk. Must be set to 0xFFFFFFFF if it is not possible to represent the value in these fields.
<i>StartingLBA</i>	8	4	Must be 0x00000001.
<i>SizeInLBA</i>	12	4	Size of the disk minus one. Set to 0xFFFFFFFF if the size of the disk is too large to be represented in this field.

5.3 GUID Partition Table (GPT) Format

This specification defines a new GUID Partition Table (GPT) partitioning scheme that must be supported by EFI firmware.

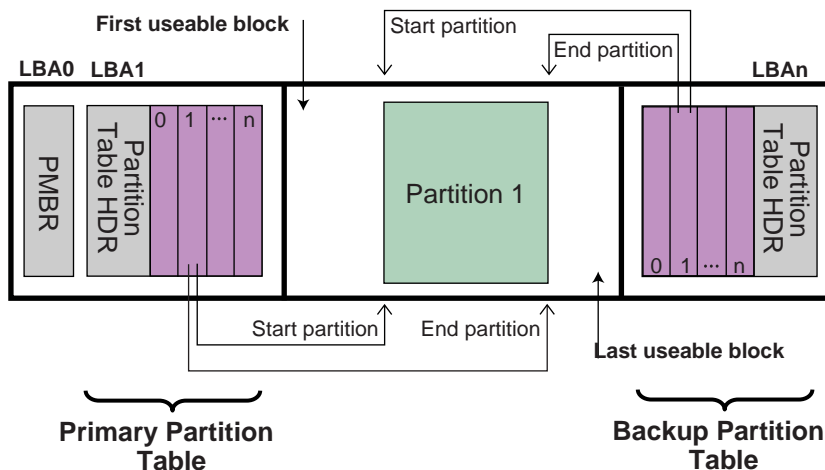
5.3.1 GUID Format overview

The GPT partitioning scheme is depicted in [Figure 16](#). The GUID Partition Table Header (see [Section 5.3.2](#)) starts with a signature and a revision number that specifies the format of the data bytes in the partition header. The GUID Partition Table Header contains a header size field that is used in calculating the CRC32 that confirms the integrity of the GUID Partition Table Header. While the GUID Partition Table Header's size may increase in the future it cannot span more than one block on the device.

LBA 0 (i.e., the first logical block) contains a protective MBR (see [Section 5.2.2](#)).

Two GUID Partition Table Header structures are stored on the device: the primary and the backup. The primary GUID Partition Table Header must be located in LBA 1 (i.e., the second logical block), and the backup GUID Partition Table Header must be located in the last LBA of the logical device. Within the GUID Partition Table Header the *MyLBA* field contains the logical block address of the GUID Partition Table Header itself, and the *AlternateLBA* field contains the logical block address of the other GUID Partition Table Header. For example, the primary GUID Partition Table Header’s *MyLBA* value would be 1 and its *AlternateLBA* would be the value for the last block of the logical device. The backup GUID Partition Table Header’s fields would be reversed.

The GUID Partition Table Header defines the range of logical block addresses that are usable by Partition Entries. This range is defined to be inclusive of *FirstUsableLBA* through *LastUsableLBA* on the logical device. All data stored on the volume must be stored between the *FirstUsableLBA* through *LastUsableLBA*, and only the data structures defined by UEFI to manage partitions may reside outside of the usable space. The value of *DiskGUID* is a GUID that uniquely identifies the entire GUID Partition Table Header and all its associated storage. This value can be used to uniquely identify the disk. The start of the GUID Partition Entry array is located at the logical block address *PartitionEntryLBA*. The size of a GUID Partition Entry element is defined in the *SizeOfPartitionEntry* field. There is a 32-bit CRC of the GUID Partition Entry array that is stored in the GUID Partition Table Header in *PartitionEntryArrayCRC32* field. The size of the GUID Partition Entry array is *SizeOfPartitionEntry* multiplied by *NumberOfPartitionEntries*. When a GUID Partition Entry is updated, the *PartitionEntryArrayCRC32* must be updated. When the *PartitionEntryArrayCRC32* is updated, the GUID Partition Table Header CRC must also be updated, since the *PartitionEntryArrayCRC32* is stored in the GUID Partition Table Header.



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Figure 16. GUID Partition Table (GPT) Scheme

The primary GUID Partition Entry array must be located after the primary GUID Partition Table Header and end before the *FirstUsableLBA*. The backup GUID Partition Entry array must be located after the *LastUsableLBA* and end before the backup GUID Partition Table Header.

Therefore the primary and backup GUID Partition Entry arrays are stored in separate locations on the disk. GUID Partition Entries define a partition that is contained in a range that is within the usable space declared by the GUID Partition Table Header. Zero or more GUID Partition Entries may be in use in the GUID Partition Entry array. Each defined partition must not overlap with any other defined partition. If all the fields of a GUID Partition Entry are zero, the entry is not in use. A minimum of 16,384 bytes of space must be reserved for the GUID Partition Entry array.

If the block size is 512, the *FirstUsableLBA* will be greater than or equal to 34 (allowing 1 block for the PMBR, 1 block for the Partition Table Header, and 32 blocks for the GUID Partition Table Entry array); if the logical block size is 4096, the *FirstUseableLBA* will be greater than or equal to 6 (allowing 1 block for the PMBR, 1 block for the Partition Table Header, and 4 blocks for the GUID Partition Table Entry array).

Historically, the logical block size and physical block size have often both been 512 bytes long. However, other block sizes may be used by a device, and larger block sizes may become more prevalent over time.

The device may present a logical block size that is not 512 bytes long. In ATA, this is called the Long Logical Sector feature set; an ATA device reports support for this feature set in IDENTIFY DEVICE data word 106 bit 12 and reports the number of words (i.e., 2 bytes) per logical sector in IDENTIFY DEVICE data words 117-118. A SCSI device reports its logical block size in the READ CAPACITY parameter data Block Length In Bytes field.

The device may present a logical block size that is smaller than the physical block size (e.g., present a logical block size of 512 bytes but implement a physical block size of 4,096 bytes). In ATA, this is called the Long Physical Sector feature set; an ATA device reports support for this feature set in IDENTIFY DEVICE data word 106 bit 13 and reports the Physical Sector Size/Logical Sector Size ratio in IDENTIFY DEVICE data word 106 bits 3-0 (as of ATA/ATAPI-7, this field can report 1, 2, 4, or 8 logical sectors per physical sector).

GPT partitions should not start at a boundary that is not aligned to the physical block size of the device, or performance may be impacted. For example, if the logical block size is 512 and the physical block size is 4,096, a GPT partition should not start at an LBA that is not a multiple of 8. GPT partitions may start at larger boundaries. To avoid the need to determine the physical block size, software may align GPT partitions at significantly larger boundaries. For example, it may use LBAs that are multiples of 256 to support physical block sizes up to 131,072 bytes.

5.3.2 GPT Partition Table Header

Table 13. GUID Partition Table Header

Mnemonic	Byte Offset	Byte Length	Description
<i>Signature</i>	0	8	Identifies EFI-compatible partition table header. This value must contain the string "EFI PART," 0x5452415020494645.
<i>Revision</i>	8	4	The revision number for this header. This revision value is not related to the UEFI Specification version. This header is version 1.0, so the correct value is 0x00010000.

Mnemonic	Byte Offset	Byte Length	Description
<i>HeaderSize</i>	12	4	Size in bytes of the GUID Partition Table Header. The <i>HeaderSize</i> must be greater than 92 and must be less than or equal to the logical block size.
<i>HeaderCRC32</i>	16	4	CRC32 checksum for the GUID Partition Table Header structure. This value is computed by setting this field to 0, and computing the 32-bit CRC for <i>HeaderSize</i> bytes.
<i>Reserved</i>	20	4	Must be zero.
<i>MyLBA</i>	24	8	The LBA that contains this data structure.
<i>AlternateLBA</i>	32	8	LBA address of the alternate GUID Partition Table Header.
<i>FirstUsableLBA</i>	40	8	The first usable logical block that may be used by a partition described by a GUID Partition Entry.
<i>LastUsableLBA</i>	48	8	The last usable logical block that may be used by a partition described by a GUID Partition Entry.
<i>DiskGUID</i>	56	16	GUID that can be used to uniquely identify the disk.
<i>PartitionEntryLBA</i>	72	8	The starting LBA of the GUID Partition Entry array.
<i>NumberOfPartitionEntries</i>	80	4	The number of Partition Entries in the GUID Partition Entry array.
<i>SizeOfPartitionEntry</i>	84	4	The size, in bytes, of each the GUID Partition Entry structures in the GUID Partition Entry array. Must be a multiple of 8.
<i>PartitionEntryArrayCRC32</i>	88	4	The CRC32 of the GUID Partition Entry array. Starts at <i>PartitionEntryLBA</i> and is computed over a byte length of $\text{NumberOfPartitionEntries} * \text{SizeOfPartitionEntry}$.
<i>Reserved</i>	92	BlockSize – 92	The rest of the block is reserved by UEFI and must be zero.

The following test must be performed to determine if a GUID Partition Table is valid:

- Check the GUID Partition Table Signature
- Check the GUID Partition Table CRC
- Check that the *MyLBA* entry points to the LBA that contains the GUID Partition Table

- Check the CRC of the GUID Partition Entry Array

If the GUID Partition Table is the primary table, stored at LBA 1:

- Check the *AlternateLBA* to see if it is a valid GUID Partition Table

If the primary GUID Partition Table is corrupt, software must check the last LBA of the device to see if it has a valid GUID Partition Table Header and point to a valid GUID Partition Entry Array. If it points to a valid GUID Partition Entry Array, then software should restore the primary GUID Partition Table if allowed by platform policy settings (e.g. a platform may require a user to provide confirmation before restoring the table, or may allow the table to be restored automatically). Software must report whenever it restores a GUID Partition Table.

Software should ask a user for confirmation before restoring the primary GUID Partition Table and must report whenever it does modify the media to restore a GUID Partition Table. If a GPT formatted disk is reformatted to the legacy MBR format by legacy software, the last logical block might not be overwritten and might still contain a stale GUID Partition Table. If GPT-cognizant software then accesses the disk and honors the stale GUID Partition Table, it will misinterpret the contents of the disk. Software may detect this scenario if the legacy MBR contains valid partitions rather than a protective MBR (see [Section 5.2.1](#)).

Any software that updates the primary GUID Partition Table must also update the backup GUID Partition Table. Software may update the GUID Partition Table Header and GUID Partition Entry array in any order, since all the CRCs are stored in the GUID Partition Table Header. Software must update the backup GUID Partition Table before the primary GUID Partition Table, so if the size of device has changed (e.g. volume expansion) and the update is interrupted, the backup GUID Partition Table is in the proper location on the disk

If the primary GUID Partition Table is invalid, the backup GUID Partition Table is used instead and it is located on the last logical block on the disk. If the backup GUID Partition Table is valid it must be used to restore the primary GUID Partition Table. If the primary GUID Partition Table is valid and the backup GUID Partition Table is invalid software must restore the backup GUID Partition Table. If both the primary and backup GUID Partition Tables are corrupted this block device is defined as not having a valid GUID Partition Header.

Both the primary and backup GUID Partition Tables must be valid before an attempt is made to grow the size of a physical volume. This is due to the GUID Partition Table recovery scheme depending on locating the backup GUID Partition Table at the end of the physical device. A volume may grow in size when disks are added to a RAID device. As soon as the volume size is increased the backup GUID Partition Table must be moved to the end of the volume and the primary and backup GUID Partition Table Headers must be updated to reflect the new volume size.

5.3.3 GUID Partition Entry Array

Table 14. GUID Partition Entry

Mnemonic	Byte Offset	Byte Length	Description
<i>PartitionTypeGUID</i>	0	16	Unique ID that defines the purpose and type of this Partition. A value of zero defines that this partition entry is not being used.

<i>UniquePartitionGUID</i>	16	16	GUID that is unique for every partition entry. Every partition ever created will have a unique GUID. This GUID must be assigned when the GUID Partition Entry is created. The GUID Partition Entry is created when ever the <i>NumberOfPartitionEntries</i> in the GUID Partition Table Header is increased to include a larger range of addresses.
<i>StartingLBA</i>	32	8	Starting LBA of the partition defined by this entry.
<i>EndingLBA</i>	40	8	Ending LBA of the partition defined by this entry.
<i>Attributes</i>	48	8	Attribute bits, all bits reserved by UEFI (see Table 15).
<i>Partition Name</i>	56	72	Unicode string.
<i>Reserved</i>	128	SizeOfPartitionEntry - 72	The rest of the GUID partition entry, if any, is reserved by UEFI and must be zero.

The *SizeOfPartitionEntry* variable in the GUID Partition Table Header defines the size of each GUID Partition Entry. Each partition entry contains a Unique Partition GUID variable that uniquely identifies every partition that will ever be created. Any time a new partition entry is created a new GUID must be generated for that partition, and every partition is guaranteed to have a unique GUID. The partition is defined as all the logical blocks inclusive of the *StartingLBA* and *EndingLBA*.

The *PartitionTypeGUID* field identifies the contents of the partition. This GUID is similar to the OSType field in the legacy MBR. Each file system must publish its unique GUID. The *Attributes* field can be used by utilities to make broad inferences about the usage of a partition and is defined in [Table 15](#). The *PartitionName* field contains a 36-character Unicode string containing a human readable string that can be used to represent what information is stored on the partition. This allows third party utilities to give human readable names to partitions.

The firmware must add the *PartitionTypeGuid* to the handle of every active GPT partition using [InstallProtocolInterface \(\)](#). This will allow drivers and applications, including OS loaders, to easily search for handles that represent EFI System Partitions or vendor specific partition types.

Software that makes copies of GPT-formatted disks and partitions must generate new Disk GUID values in the GUID Partition Table Headers and new Unique Partition GUID values in each GUID Partition Entry. If GPT-cognizant software encounters two disks or partitions with identical GUIDs, results will be indeterminate.

Table 15. Defined GUID Partition Entry - Partition Type GUIDs

Description	GUID Value
Unused Entry	00000000-0000-0000-0000-000000000000
EFI System Partition	C12A7328-F81F-11d2-BA4B-00A0C93EC93B
Partition containing a legacy MBR	024DEE41-33E7-11d3-9D69-0008C781F39F

OS vendors need to generate their own GUIDs to identify their partition types.

Table 16. Defined GUID Partition Entry - Attributes

Bits	Description
Bit 0	Required for the platform to function. The system cannot function normally if this partition is removed. This partition should be considered as part of the hardware of the system, and if it is removed the system may not boot. It may contain diagnostics, recovery tools, or other code or data that is critical to the functioning of a system independent of any OS.
Bits 1-47	Undefined and must be zero. Reserved for expansion by future versions of the UEFI specification.
Bits 48-63	Reserved for GUID specific use. The use of these bits will vary depending on the <i>PartitionTypeGUID</i> . Only the owner of the <i>PartitionTypeGUID</i> is allowed to modify these bits. They must be preserved if Bits 0–47 are modified.

Services — Boot Services

This section discusses the fundamental boot services that are present in a compliant system. The services are defined by interface functions that may be used by code running in the UEFI environment. Such code may include protocols that manage device access or extend platform capability, as well as applications running in the preboot environment, and OS loaders.

Two types of services apply in an compliant system:

Boot Services	Functions that are available <i>before</i> a successful call to ExitBootServices() . These functions are described in this section.
Runtime Services	Functions that are available <i>before and after</i> any call to ExitBootServices() . These functions are described in Section 7 .

During boot, system resources are owned by the firmware and are controlled through boot services interface functions. These functions can be characterized as “global” or “handle-based.” The term “global” simply means that a function accesses system services and is available on all platforms (since all platforms support all system services). The term “handle-based” means that the function accesses a specific device or device functionality and may not be available on some platforms (since some devices are not available on some platforms). Protocols are created dynamically. This section discusses the “global” functions and runtime functions; subsequent sections discuss the “handle-based.”

UEFI applications (including OS loaders) must use boot services functions to access devices and allocate memory. On entry, an Image is provided a pointer to a system table which contains the Boot Services dispatch table and the default handles for accessing the console. All boot services functionality is available until an OS loader loads enough of its own environment to take control of the system’s continued operation and then terminates boot services with a call to [ExitBootServices\(\)](#).

In principle, the [ExitBootServices\(\)](#) call is intended for use by the operating system to indicate that its loader is ready to assume control of the platform and all platform resource management. Thus boot services are available up to this point to assist the OS loader in preparing to boot the operating system. Once the OS loader takes control of the system and completes the operating system boot process, only runtime services may be called. Code other than the OS loader, however, may or may not choose to call [ExitBootServices\(\)](#). This choice may in part depend upon whether or not such code is designed to make continued use of boot services or the boot services environment.

The rest of this section discusses individual functions. Global boot services functions fall into these categories:

- Event, Timer, and Task Priority Services ([Section 6.1](#))
- Memory Allocation Services ([Section 6.2](#))
- Protocol Handler Services ([Section 6.3](#))

- Image Services ([Section 6.4](#))
- Miscellaneous Services ([Section 6.5](#))

6.1 Event, Timer, and Task Priority Services

The functions that make up the Event, Timer, and Task Priority Services are used during preboot to create, close, signal, and wait for events; to set timers; and to raise and restore task priority levels. See [Table 17](#).

Table 17. Event, Timer, and Task Priority Functions

Name	Type	Description
CreateEvent	Boot	Creates a general-purpose event structure.
CreateEventEx	Boot	Creates an event structure as part of an event group
CloseEvent	Boot	Closes and frees an event structure.
SignalEvent	Boot	Signals an event.
WaitForEvent	Boot	Stops execution until an event is signaled.
CheckEvent	Boot	Checks whether an event is in the signaled state.
SetTimer	Boot	Sets an event to be signaled at a particular time.
RaiseTPL	Boot	Raises the task priority level.
RestoreTPL	Boot	Restores/lowers the task priority level.

Execution in the boot services environment occurs at different task priority levels, or TPLs. The boot services environment exposes only three of these levels to UEFI applications and drivers:

- [TPL_APPLICATION](#), the lowest priority level
- [TPL_CALLBACK](#), an intermediate priority level
- [TPL_NOTIFY](#), the highest priority level

Tasks that execute at a higher priority level may interrupt tasks that execute at a lower priority level. For example, tasks that run at the **TPL_NOTIFY** level may interrupt tasks that run at the **TPL_APPLICATION** or **TPL_CALLBACK** level. While **TPL_NOTIFY** is the highest level exposed to the boot services applications, the firmware may have higher task priority items it deals with. For example, the firmware may have to deal with tasks of higher priority like timer ticks and internal devices. Consequently, there is a fourth TPL, [TPL_HIGH_LEVEL](#), designed for use exclusively by the firmware.

The intended usage of the priority levels is shown in [Table 18](#) from the lowest level (**TPL_APPLICATION**) to the highest level (**TPL_HIGH_LEVEL**). As the level increases, the duration of the code and the amount of blocking allowed decrease. Execution generally occurs at the **TPL_APPLICATION** level. Execution occurs at other levels as a direct result of the triggering of an event notification function (this is typically caused by the signaling of an event). During timer interrupts, firmware signals timer events when an event’s “trigger time” has expired. This allows event notification functions to interrupt lower priority code to check devices (for example). The notification function can signal other events as required. After all pending event notification functions execute, execution continues at the **TPL_APPLICATION** level.

Table 18. TPL Usage

Task Priority Level	Usage
TPL_APPLICATION	This is the lowest priority level. It is the level of execution which occurs when no event notifications are pending and which interacts with the user. User I/O (and blocking on User I/O) can be performed at this level. The boot manager executes at this level and passes control to other UEFI applications at this level.
TPL_CALLBACK	Interrupts code executing below TPL_CALLBACK level . Long term operations (such as file system operations and disk I/O) can occur at this level.
TPL_NOTIFY	Interrupts code executing below TPL_NOTIFY level . Blocking is not allowed at this level. Code executes to completion and returns. If code requires more processing, it needs to signal an event to wait to obtain control again at whatever level it requires. This level is typically used to process low level IO to or from a device.
(Firmware Interrupts)	This level is internal to the firmware . It is the level at which internal interrupts occur. Code running at this level interrupts code running at the TPL_NOTIFY level (or lower levels). If the interrupt requires extended time to complete, firmware signals another event (or events) to perform the longer term operations so that other interrupts can occur.
TPL_HIGH_LEVEL	Interrupts code executing below TPL_HIGH_LEVEL . This is the highest priority level. It is not interruptible (interrupts are disabled) and is used sparingly by firmware to synchronize operations that need to be accessible from any priority level. For example, it must be possible to signal events while executing at any priority level. Therefore, firmware manipulates the internal event structure while at this priority level.

Executing code can temporarily raise its priority level by calling the [RaiseTPL\(\)](#) function. Doing this masks event notifications from code running at equal or lower priority levels until the [RestoreTPL\(\)](#) function is called to reduce the priority to a level below that of the pending event notifications. There are restrictions on the TPL levels at which many UEFI service functions and protocol interface functions can execute. [Table 19](#) summarizes the restrictions.

Table 19. TPL Restrictions

Name	Restrictions	Task Priority Level
Protocol Interface Functions	<=	TPL_NOTIFY
Block I/O Protocol	<=	TPL_CALLBACK
CheckEvent()	<	TPL_HIGH_LEVEL
CloseEvent()	<	TPL_HIGH_LEVEL
CreateEvent()	<	TPL_HIGH_LEVEL
Disk I/O Protocol	<=	TPL_CALLBACK
Event Notification Levels	> <=	TPL_APPLICATION TPL_HIGH_LEVEL

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Name	Restrictions	Task Priority Level
Exit()	<=	TPL_CALLBACK
ExitBootServices()	=	TPL_APPLICATION
LoadImage()	<	TPL_CALLBACK
Memory Allocation Services	<=	TPL_NOTIFY
PXE Base Code Protocol	<=	TPL_CALLBACK
Serial I/O Protocol	<=	TPL_CALLBACK
SetTimer()	<	TPL_HIGH_LEVEL
SignalEvent()	<=	TPL_HIGH_LEVEL
Simple File System Protocol	<=	TPL_CALLBACK
Simple Input Protocol	<=	TPL_APPLICATION
Simple Network Protocol	<=	TPL_CALLBACK
Simple Text Output Protocol	<=	TPL_NOTIFY
StartImage()	<	TPL_CALLBACK
Time Services	<=	TPL_CALLBACK
UnloadImage()	<=	TPL_CALLBACK
Variable Services	<=	TPL_CALLBACK
WaitForEvent()	=	TPL_APPLICATION
ACPI Table Protocol	<	TPL_NOTIFY
Authentication Info	<=	TPL_NOTIFY
Device Path Utilities	<=	TPL_NOTIFY
Device Path From Text	<=	TPL_NOTIFY
EDID Discovered	<=	TPL_NOTIFY
EDID Active	<=	TPL_NOTIFY
Graphics Output EDID Override	<=	TPL_NOTIFY
iSCSI Initiator Name	<=	TPL_NOTIFY
Tape IO	<=	TPL_NOTIFY
Managed Network Service Binding	<=	TPL_CALLBACK
ARP Service Binding	<=	TPL_CALLBACK
ARP	<=	TPL_CALLBACK
DHCP4 Service Binding	<=	TPL_CALLBACK
DHCP4	<=	TPL_CALLBACK
TCP4 Service Binding	<=	TPL_CALLBACK
TCP4	<=	TPL_CALLBACK
IP4 Service Binding	<=	TPL_CALLBACK
IP4	<=	TPL_CALLBACK
IP4 Config	<=	TPL_CALLBACK
UDP4 Service Binding	<=	TPL_CALLBACK

Name	Restrictions	Task Priority Level
UDP4	<=	TPL_CALLBACK
MTFTP4 Service Binding	<=	TPL_CALLBACK
MTFTP4	<=	TPL_CALLBACK

CreateEvent()

Summary

Creates an event.

Prototype

```
typedef
EFI_STATUS
CreateEvent (
    IN UINT32                Type,
    IN EFI_TPL               NotifyTpl,
    IN EFI_EVENT_NOTIFY     NotifyFunction, OPTIONAL
    IN VOID                  *NotifyContext, OPTIONAL
    OUT EFI_EVENT           *Event
);
```

Parameters

<i>Type</i>	The type of event to create and its mode and attributes. The #define statements in “Related Definitions” can be used to specify an event’s mode and attributes.
<i>NotifyTpl</i>	The task priority level of event notifications, if needed. See RaiseTPL() .
<i>NotifyFunction</i>	Pointer to the event’s notification function, if any. See “Related Definitions.”
<i>NotifyContext</i>	Pointer to the notification function’s context; corresponds to parameter <i>Context</i> in the notification function.
<i>Event</i>	Pointer to the newly created event if the call succeeds; undefined otherwise.

Related Definitions

```

//*****
// EFI_EVENT
//*****
typedef VOID*EFI_EVENT

//*****
// Event Types //*****
// These types can be "ORed" together as needed - for example,
// EVT_TIMER might be "ORed" with EVT_NOTIFY_WAIT or
// EVT_NOTIFY_SIGNAL.
#define EVT_TIMER                0x80000000
#define EVT_RUNTIME              0x40000000

#define EVT_NOTIFY_WAIT0x00000100
#define EVT_NOTIFY_SIGNAL0x00000200
```

```
#define EVT_SIGNAL_EXIT_BOOT_SERVICES 0x00000201
#define EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE 0x60000202
```

EVT_TIMER The event is a timer event and may be passed to [SetTimer\(\)](#). Note that timers only function during boot services time.

EVT_RUNTIME The event is allocated from runtime memory. If an event is to be signaled after the call to [ExitBootServices\(\)](#), the event's data structure and notification function need to be allocated from runtime memory. For more information, see [SetVirtualAddressMap\(\)](#).

EVT_NOTIFY_WAIT If an event of this type is not already in the signaled state, then the event's *NotificationFunction* will be queued at the event's *NotifyTpl* whenever the event is being waited on via [WaitForEvent\(\)](#) or [CheckEvent\(\)](#).

EVT_NOTIFY_SIGNAL The event's *NotifyFunction* is queued whenever the event is signaled.

EVT_SIGNAL_EXIT_BOOT_SERVICES This event is to be notified by the system when [ExitBootServices\(\)](#) is invoked. This event is of type **EVT_NOTIFY_SIGNAL** and should not be combined with any other event types. The notification function for this event is not allowed to use the Memory Allocation Services, or call any functions that use the Memory Allocation Services and should only call functions that are known not to use Memory Allocation Services, because these services modify the current memory map.

EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE The event is to be notified by the system when [SetVirtualAddressMap\(\)](#) is performed. This event type is a composite of **EVT_NOTIFY_SIGNAL**, **EVT_RUNTIME**, and **EVT_RUNTIME_CONTEXT** and should not be combined with any other event types.

```
/**
//*****
// EFI_EVENT_NOTIFY
//*****
typedef
VOID
(EFI_API *EFI_EVENT_NOTIFY) (
    IN EFI_EVENT Event,
    IN VOID *Context
);
```

Event Event whose notification function is being invoked.

Context Pointer to the notification function's context, which is implementation-dependent. *Context* corresponds to *NotifyContext* in [CreateEventEx\(\)](#).

Description

The **CreateEvent()** function creates a new event of type *Type* and returns it in the location referenced by *Event*. The event’s notification function, context, and task priority level are specified by *NotifyFunction*, *NotifyContext*, and *NotifyTpl*, respectively.

Events exist in one of two states, “waiting” or “signaled.” When an event is created, firmware puts it in the “waiting” state. When the event is signaled, firmware changes its state to “signaled” and, if **EVT_NOTIFY_SIGNAL** is specified, places a call to its notification function in a FIFO queue. There is a queue for each of the “basic” task priority levels defined in [Section 6.1](#) (**TPL_CALLBACK**, and **TPL_NOTIFY**). The functions in these queues are invoked in FIFO order, starting with the highest priority level queue and proceeding to the lowest priority queue that is unmasked by the current TPL. If the current TPL is equal to or greater than the queued notification, it will wait until the TPL is lowered via [RestoreTPL\(\)](#).

In a general sense, there are two “types” of events, synchronous and asynchronous. Asynchronous events are closely related to timers and are used to support periodic or timed interruption of program execution. This capability is typically used with device drivers. For example, a network device driver that needs to poll for the presence of new packets could create an event whose type includes **EVT_TIMER** and then call the [SetTimer\(\)](#) function. When the timer expires, the firmware signals the event.

Synchronous events have no particular relationship to timers. Instead, they are used to ensure that certain activities occur following a call to a specific interface function. One example of this is the cleanup that needs to be performed in response to a call to the [ExitBootServices\(\)](#) function. **ExitBootServices()** can clean up the firmware since it understands firmware internals, but it cannot clean up on behalf of drivers that have been loaded into the system. The drivers have to do that themselves by creating an event whose type is **EVT_SIGNAL_EXIT_BOOT_SERVICES** and whose notification function is a function within the driver itself. Then, when **ExitBootServices()** has finished its cleanup, it signals each event of type **EVT_SIGNAL_EXIT_BOOT_SERVICES**.

Another example of the use of synchronous events occurs when an event of type **EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE** is used in conjunction with the [SetVirtualAddressMap\(\)](#).

The **EVT_NOTIFY_WAIT** and **EVT_NOTIFY_SIGNAL** flags are exclusive. If neither flag is specified, the caller does not require any notification concerning the event and the *NotifyTpl*, *NotifyFunction*, and *NotifyContext* parameters are ignored. If **EVT_NOTIFY_WAIT** is specified and the event is not in the signaled state, then the **EVT_NOTIFY_WAIT** notify function is queued whenever a consumer of the event is waiting for the event (via [WaitForEvent\(\)](#) or [CheckEvent\(\)](#)). If the **EVT_NOTIFY_SIGNAL** flag is specified then the event’s notify function is queued whenever the event is signaled.

Note: Because its internal structure is unknown to the caller, *Event* cannot be modified by the caller. The only way to manipulate it is to use the published event interfaces.

Status Codes Returned

EFI_SUCCESS	The event structure was created.
EFI_INVALID_PARAMETER	One of the parameters has an invalid value.

EFI_INVALID_PARAMETER	<i>Event</i> is NULL .
EFI_INVALID_PARAMETER	<i>Type</i> has an unsupported bit set.
EFI_INVALID_PARAMETER	<i>Type</i> has both EVT_NOTIFY_SIGNAL and EVT_NOTIFY_WAIT set.
EFI_INVALID_PARAMETER	<i>Type</i> has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and <i>NotifyFunction</i> is NULL .
EFI_INVALID_PARAMETER	Type has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and <i>NotifyTpl</i> is not a supported TPL level.
EFI_OUT_OF_RESOURCES	The event could not be allocated.

CreateEventEx()

Summary

Creates an event in a group.

Prototype

```
typedef
EFI_STATUS
CreateEventEx (
    IN UINT32                Type,
    IN EFI_TPL               NotifyTpl,
    IN EFI_EVENT_NOTIFY     NotifyFunction OPTIONAL,
    IN CONST VOID           *NotifyContext OPTIONAL,
    IN CONST EFI_GUID       *EventGroup    OPTIONAL,
    OUT EFI_EVENT           *Event
);
```

Parameters

<i>Type</i>	The type of event to create and its mode and attributes.
<i>NotifyTpl</i>	The task priority level of event notifications, if needed. See RaiseTPL() .
<i>NotifyFunction</i>	Pointer to the event's notification function, if any.
<i>NotifyContext</i>	Pointer to the notification function's context; corresponds to parameter <i>Context</i> in the notification function.
<i>EventGroup</i>	Pointer to the unique identifier of the group to which this event belongs. If this is NULL , then the function behaves as if the parameters were passed to CreateEvent .
<i>Event</i>	Pointer to the newly created event if the call succeeds; undefined otherwise.

Description

The **CreateEventEx** function creates a new event of type *Type* and returns it in the specified location indicated by *Event*. The event's notification function, context and task priority are specified by *NotifyFunction*, *NotifyContext*, and *NotifyTpl*, respectively. The event will be added to the group of events identified by *EventGroup*.

If no group is specified by *EventGroup*, then this function behaves as if the same parameters had been passed to **CreateEvent**.

Event groups are collections of events identified by a shared `EFI_GUID` where, when one member event is signaled, all other events are signaled and their individual notification actions are taken (as described in **CreateEvent**). All events are guaranteed to be signaled before the first notification action is taken. All notification functions will be executed in the order specified by their *NotifyTpl*.

A single event can only be part of a single event group. An event may be removed from an event group by using **CloseEvent**.

The *Type* of an event uses the same values as defined in **CreateEvent** except that **EVT_SIGNAL_EXIT_BOOT_SERVICES** and **EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE** are not valid.

If *Type* has **EVT_NOTIFY_SIGNAL** or **EVT_NOTIFY_WAIT**, then *NotifyFunction* must be non- **NULL** and *NotifyTpl* must be a valid task priority level. Otherwise these parameters are ignored.

More than one event of type **EVT_TIMER** may be part of a single event group. However, there is no mechanism for determining which of the timers was signaled.

Configuration Table Groups

The GUID for a configuration table also defines a corresponding event group GUID with the same value. If the data represented by a configuration table is changed, **InstallConfigurationTable()** should be called. When **InstallConfigurationTable()** is called, the corresponding event is signaled. When this event is signaled, any components that cache information from the configuration table can optionally update their cached state.

For example, **EFI_ACPI_TABLE_GUID** defines a configuration table for ACPI data. When ACPI data is changed, **InstallConfigurationTable()** is called. During the execution of **InstallConfigurationTable()**, a corresponding event group with **EFI_ACPI_TABLE_GUID** is signaled, allowing an application to invalidate any cached ACPI data.

Pre-Defined Event Groups

This section describes the pre-defined event groups used by the UEFI specification.

EFI_EVENT_GROUP_EXIT_BOOT_SERVICES

This event group is notified by the system when **ExitBootServices()** is invoked. The notification function for this event is not allowed to use the Memory Allocation Services, or call any functions that use the Memory Allocation Services, because these services modify the current memory map. This is functionally equivalent to the **EVT_SIGNAL_EXIT_BOOT_SERVICES** flag for the *Type* argument of **CreateEvent**.

EFI_EVENT_GROUP_VIRTUAL_ADDRESS_CHANGE

This event group is notified by the system when **SetVirtualAddressMap()** is invoked. This is functionally equivalent to the **EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE** flag for the *Type* argument of **CreateEvent**.

EFI_EVENT_GROUP_MEMORY_MAP_CHANGE

This event group is notified by the system when the memory map has changed. The notification function for this event should not use Memory Allocation Services to avoid reentrancy complications.

EFI_EVENT_GROUP_READY_TO_BOOT

This event group is notified by the system when the Boot Manager is about to load and execute a boot option.

Related Definitions

EFI_EVENT is defined in **CreateEvent**.

EVT_SIGNAL_EXIT_BOOT_SERVICES and **EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE** are defined in **CreateEvent**.

```
#define EFI_EVENT_GROUP_EXIT_BOOT_SERVICES \
    {0x27abf055, 0xb1b8, 0x4c26, 0x80, 0x48, 0x74, 0x8f, 0x37, \
    0xba, 0xa2, 0xdf}}
```

```
#define EFI_EVENT_GROUP_VIRTUAL_ADDRESS_CHANGE \
    {0x13fa7698, 0xc831, 0x49c7, 0x87, 0xea, 0x8f, 0x43, 0xfc, \
    0xc2, 0x51, 0x96}
```

```
#define EFI_EVENT_GROUP_MEMORY_MAP_CHANGE \
    {0x78bee926, 0x692f, 0x48fd, 0x9e, 0xdb, 0x1, 0x42, 0x2e, 0xf0, \
    0xd7, 0xab}
```

```
#define EFI_EVENT_GROUP_READY_TO_BOOT \
    {0x7ce88fb3, 0x4bd7, 0x4679, 0x87, 0xa8, 0xa8, 0xd8, 0xde, 0xe5, \
    0xd, 0x2b}
```

Status Codes Returned

EFI_SUCCESS	The event structure was created.
EFI_INVALID_PARAMETER	One of the parameters has an invalid value.
EFI_INVALID_PARAMETER	<i>Event</i> is NULL .
EFI_INVALID_PARAMETER	<i>Type</i> has an unsupported bit set.
EFI_INVALID_PARAMETER	<i>Type</i> has both EVT_NOTIFY_SIGNAL and EVT_NOTIFY_WAIT set.
EFI_INVALID_PARAMETER	<i>Type</i> has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and <i>NotifyFunction</i> is NULL .
EFI_INVALID_PARAMETER	<i>Type</i> has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and <i>NotifyTpl</i> is not a supported TPL level.
EFI_OUT_OF_RESOURCES	The event could not be allocated.

CloseEvent()

Summary

Closes an event.

Prototype

```
typedef
EFI_STATUS
CloseEvent (
    IN EFI_EVENT Event
);
```

Parameters

Event

The event to close. Type **EFI_EVENT** is defined in the [CreateEvent\(\)](#) function description.

Description

The **CloseEvent()** function removes the caller's reference to the event, removes it from any event group to which it belongs, and closes it. Once the event is closed, the event is no longer valid and may not be used on any subsequent function calls.

Status Codes Returned

EFI_SUCCESS	The event has been closed.
-------------	----------------------------

SignalEvent()

Summary

Signals an event.

Prototype

```
typedef
EFI_STATUS
SignalEvent (
    IN EFI_EVENT Event
);
```

Parameters

Event

The event to signal. Type **EFI_EVENT** is defined in the [CheckEvent\(\)](#) function description.

Description

The supplied *Event* is placed in the signaled state. If *Event* is already in the signaled state, then **EFI_SUCCESS** is returned. If *Event* is of type **EVT_NOTIFY_SIGNAL**, then the event's notification function is scheduled to be invoked at the event's notification task priority level. **SignalEvent()** may be invoked from any task priority level.

If the supplied *Event* is a part of an event group, then all of the events in the event group are also signaled and their notification functions are scheduled.

When signaling an event group, it is possible to create an event in the group, signal it and then close the event to remove it from the group. For example:

```
EFI_EVENT Event;
EFI_GUID gMyEventGroupGuid = EFI_MY_EVENT_GROUP_GUID;
gBS->CreateEventEx (
    0,
    0,
    NULL,
    NULL,
    &gMyEventGroupGuid,
    &Event
);

gBS->SignalEvent (Event);
gBS->CloseEvent (Event);
```

Status Codes Returned

EFI_SUCCESS	The event was signaled.
-------------	-------------------------

WaitForEvent()

Summary

Stops execution until an event is signaled.

Prototype

```
typedef
EFI_STATUS
WaitForEvent (
    IN UINTN      NumberOfEvents,
    IN EFI_EVENT  *Event,
    OUT UINTN     *Index
);
```

Parameters

<i>NumberOfEvents</i>	The number of events in the <i>Event</i> array.
<i>Event</i>	An array of EFI_EVENT . Type EFI_EVENT is defined in the CreateEvent() function description.
<i>Index</i>	Pointer to the index of the event which satisfied the wait condition.

Description

This function must be called at priority level **TPL_APPLICATION**. If an attempt is made to call it at any other priority level, **EFI_UNSUPPORTED** is returned.

The list of events in the *Event* array are evaluated in order from first to last, and this evaluation is repeated until an event is signaled or an error is detected. The following checks are performed on each event in the *Event* array.

- If an event is of type **EVT_NOTIFY_SIGNAL**, then **EFI_INVALID_PARAMETER** is returned and *Index* indicates the event that caused the failure.
- If an event is in the signaled state, the signaled state is cleared and **EFI_SUCCESS** is returned, and *Index* indicates the event that was signaled.
- If an event is not in the signaled state but does have a notification function, the notification function is queued at the event's notification task priority level. If the execution of the event's notification function causes the event to be signaled, then the signaled state is cleared, **EFI_SUCCESS** is returned, and *Index* indicates the event that was signaled.

To wait for a specified time, a timer event must be included in the *Event* array.

To check if an event is signaled without waiting, an already signaled event can be used as the last event in the list being checked, or the **CheckEvent()** interface may be used.

Status Codes Returned

EFI_SUCCESS	The event indicated by <i>Index</i> was signaled.
EFI_INVALID_PARAMETER	<i>NumberOfEvents</i> is 0.

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EFI_INVALID_PARAMETER	The event indicated by <i>Index</i> is of type EVT_NOTIFY_SIGNAL .
EFI_UNSUPPORTED	The current TPL is not <u>TPL_APPLICATION</u> .

CheckEvent()

Summary

Checks whether an event is in the signaled state.

Prototype

```
typedef
EFI_STATUS
CheckEvent (
    IN EFI_EVENT Event
);
```

Parameters

Event The event to check. Type **EFI_EVENT** is defined in the [CreateEvent\(\)](#) function description.

Description

The **CheckEvent()** function checks to see whether *Event* is in the signaled state. If *Event* is of type **EVT_NOTIFY_SIGNAL**, then **EFI_INVALID_PARAMETER** is returned. Otherwise, there are three possibilities:

- If *Event* is in the signaled state, it is cleared and **EFI_SUCCESS** is returned.
- If *Event* is not in the signaled state and has no notification function, **EFI_NOT_READY** is returned.
- If *Event* is not in the signaled state but does have a notification function, the notification function is queued at the event's notification task priority level. If the execution of the notification function causes *Event* to be signaled, then the signaled state is cleared and **EFI_SUCCESS** is returned; if the *Event* is not signaled, then **EFI_NOT_READY** is returned.

Status Codes Returned

EFI_SUCCESS	The event is in the signaled state.
EFI_NOT_READY	The event is not in the signaled state.
EFI_INVALID_PARAMETER	<i>Event</i> is of type EVT_NOTIFY_SIGNAL.

SetTimer()

Summary

Sets the type of timer and the trigger time for a timer event.

Prototype

```
typedef
EFI_STATUS
SetTimer (
    IN EFI_EVENT      Event,
    IN EFI_TIMER_DELAY Type,
    IN UINT64         TriggerTime
);
```

Parameters

<i>Event</i>	The timer event that is to be signaled at the specified time. Type EFI_EVENT is defined in the CreateEvent() function description.
<i>Type</i>	The type of time that is specified in <i>TriggerTime</i> . See the timer delay types in “Related Definitions.”
<i>TriggerTime</i>	The number of 100ns units until the timer expires. A <i>TriggerTime</i> of 0 is legal. If <i>Type</i> is TimerRelative and <i>TriggerTime</i> is 0, then the timer event will be signaled on the next timer tick. If <i>Type</i> is TimerPeriodic and <i>TriggerTime</i> is 0, then the timer event will be signaled on every timer tick.

Related Definitions

```

/*****
//EFI_TIMER_DELAY
/*****
typedef enum {
    TimerCancel,
    TimerPeriodic,
    TimerRelative
} EFI_TIMER_DELAY;
```

TimerCancel	The event’s timer setting is to be cancelled and no timer trigger is to be set. <i>TriggerTime</i> is ignored when canceling a timer.
TimerPeriodic	The event is to be signaled periodically at <i>TriggerTime</i> intervals from the current time. This is the only timer trigger <i>Type</i> for which the event timer does not need to be reset for each notification. All other timer trigger types are “one shot.”
TimerRelative	The event is to be signaled in <i>TriggerTime</i> 100ns units.

Description

The **SetTimer()** function cancels any previous time trigger setting for the event, and sets the new trigger time for the event. This function can only be used on events of type **EVT_TIMER**.

Status Codes Returned

EFI_SUCCESS	The event has been set to be signaled at the requested time.
EFI_INVALID_PARAMETER	<i>Event</i> or <i>Type</i> is not valid.

Note: *If `NewTpl` is below the current TPL level, then the system behavior is indeterminate. Additionally, only `TPL_APPLICATION`, `TPL_CALLBACK`, `TPL_NOTIFY`, and `TPL_HIGH_LEVEL` may be used. All other values are reserved for use by the firmware; using them will result in unpredictable behavior. Good coding practice dictates that all code should execute at its lowest possible TPL level, and the use of TPL levels above `TPL_APPLICATION` must be minimized. Executing at TPL levels above `TPL_APPLICATION` for extended periods of time may also result in unpredictable behavior.*

Status Codes Returned

Unlike other UEFI interface functions, `RaiseTPL()` does not return a status code. Instead, it returns the previous task priority level, which is to be restored later with a matching call to `RestoreTPL()`.

RestoreTPL()

Summary

Restores a task’s priority level to its previous value.

Prototype

```
typedef
VOID
RestoreTPL (
    IN EFI_TPL OldTpl
)
```

Parameters

OldTpl

The previous task priority level to restore (the value from a previous, matching call to [RaiseTPL\(\)](#)). Type **EFI_TPL** is defined in the [RaiseTPL\(\)](#) function description.

Description

The **RestoreTPL()** function restores a task’s priority level to its previous value. Calls to **RestoreTPL()** are matched with calls to **RaiseTPL()**.

Note: *If **OldTpl** is above the current TPL level, then the system behavior is indeterminate. Additionally, only **TPL APPLICATION**, **TPL CALLBACK**, **TPL NOTIFY**, and **TPL HIGH LEVEL** may be used. All other values are reserved for use by the firmware; using them will result in unpredictable behavior. Good coding practice dictates that all code should execute at its lowest possible TPL level, and the use of TPL levels above **TPL APPLICATION** must be minimized. Executing at TPL levels above **TPL APPLICATION** for extended periods of time may also result in unpredictable behavior.*

Status Codes Returned

None.

6.2 Memory Allocation Services

The functions that make up Memory Allocation Services are used during preboot to allocate and free memory, and to obtain the system’s memory map. See [Table 20](#).

Table 20. Memory Allocation Functions

Name	Type	Description
AllocatePages	Boot	Allocates pages of a particular type.
FreePages	Boot	Frees allocated pages.
GetMemoryMap	Boot	Returns the current boot services memory map and memory map key.
AllocatePool	Boot	Allocates a pool of a particular type.

Name	Type	Description
FreePool	Boot	Frees allocated pool.

The way in which these functions are used is directly related to an important feature of UEFI memory design. This feature, which stipulates that EFI firmware owns the system’s memory map during preboot, has three major consequences:

- During preboot, all components (including executing EFI images) must cooperate with the firmware by allocating and freeing memory from the system with the functions [AllocatePages \(\)](#), [AllocatePool \(\)](#), [FreePages \(\)](#), and [FreePool \(\)](#). The firmware dynamically maintains the memory map as these functions are called.
- During preboot, an executing EFI Image must only use the memory it has allocated.
- Before an executing EFI image exits and returns control to the firmware, it must free all resources it has explicitly allocated. This includes all memory pages, pool allocations, open file handles, etc. Memory allocated by the firmware to load an image is freed by the firmware when the image is unloaded.

When memory is allocated, it is “typed” according to the values in **EFI_MEMORY_TYPE** (see the description for [AllocatePages \(\)](#)). Some of the types have a different usage *before* [ExitBootServices \(\)](#) is called than they do *afterwards*. [Table 21](#) lists each type and its usage before the call; [Table 22](#) lists each type and its usage after the call. The system firmware must follow the processor-specific rules outlined in [Section 2.3.2](#) and [Section 2.3.4](#) in the layout of the EFI memory map to enable the OS to make the required virtual mappings.

Table 21. Memory Type Usage before [ExitBootServices \(\)](#)

Mnemonic	Description
EfiReservedMemoryType	Not used.
EfiLoaderCode	The code portions of a loaded application. (Note that UEFI OS loaders are UEFI applications.)
EfiLoaderData	The data portions of a loaded application and the default data allocation type used by an application to allocate pool memory.
EfiBootServicesCode	The code portions of a loaded Boot Services Driver.
EfiBootServicesData	The data portions of a loaded Boot Services Driver, and the default data allocation type used by a Boot Services Driver to allocate pool memory.
EfiRuntimeServicesCode	The code portions of a loaded Runtime Services Driver.
EfiRuntimeServicesData	The data portions of a loaded Runtime Services Driver and the default data allocation type used by a Runtime Services Driver to allocate pool memory.
EfiConventionalMemory	Free (unallocated) memory.
EfiUnusableMemory	Memory in which errors have been detected.
EfiACPIReclaimMemory	Memory that holds the ACPI tables.
EfiACPIMemoryNVS	Address space reserved for use by the firmware.
EfiMemoryMappedIO	Used by system firmware to request that a memory-mapped IO region be mapped by the OS to a virtual address so it can be accessed by EFI runtime services.

EfiMemoryMappedIOPortSpace	System memory-mapped IO region that is used to translate memory cycles to IO cycles by the processor.
EfiPalCode	Address space reserved by the firmware for code that is part of the processor.

Note: *There is only one region of type `EfiMemoryMappedIoPortSpace` defined in the architecture for Itanium-based platforms. As a result, there should be one and only one region of type `EfiMemoryMappedIoPortSpace` in the EFI memory map of an Itanium-based platform.*

Table 22. Memory Type Usage after `ExitBootServices ()`

Mnemonic	Description
EfiReservedMemoryType	Not used.
EfiLoaderCode	The Loader and/or OS may use this memory as they see fit. Note: the OS loader that called <code>ExitBootServices ()</code> is utilizing one or more <code>EfiLoaderCode</code> ranges.
EfiLoaderData	The Loader and/or OS may use this memory as they see fit. Note: the OS loader that called <code>ExitBootServices ()</code> is utilizing one or more <code>EfiLoaderData</code> ranges.
EfiBootServicesCode	Memory available for general use.
EfiBootServicesData	Memory available for general use.
EfiRuntimeServicesCode	The memory in this range is to be preserved by the loader and OS in the working and ACPI S1–S3 states.
EfiRuntimeServicesData	The memory in this range is to be preserved by the loader and OS in the working and ACPI S1–S3 states.
EfiConventionalMemory	Memory available for general use.
EfiUnusableMemory	Memory that contains errors and is not to be used.
EfiACPIReclaimMemory	This memory is to be preserved by the loader and OS until ACPI is enabled. Once ACPI is enabled, the memory in this range is available for general use.
EfiACPIMemoryNVS	This memory is to be preserved by the loader and OS in the working and ACPI S1–S3 states.
EfiMemoryMappedIO	This memory is not used by the OS. All system memory-mapped IO information should come from ACPI tables.
EfiMemoryMappedIOPortSpace	This memory is not used by the OS. All system memory-mapped IO port space information should come from ACPI tables.
EfiPalCode	This memory is to be preserved by the loader and OS in the working and ACPI S1–S3 states. This memory may also have other attributes that are defined by the processor implementation.

Note: *An image that calls `ExitBootServices ()` first calls `GetMemoryMap ()` to obtain the current memory map. Following the `ExitBootServices ()` call, the image implicitly owns all unused memory in the map. This includes memory types `EfiLoaderCode`, `EfiLoaderData`, `EfiBootServicesCode`, `EfiBootServicesData`, and `EfiConventionalMemory`. An EFI-compatible loader and operating system must preserve the memory marked as `EfiRuntimeServicesCode` and `EfiRuntimeServicesData`.*

AllocatePages()

Summary

Allocates memory pages from the system.

Prototype

```
typedef
EFI_STATUS
AllocatePages (
    IN EFI_ALLOCATE_TYPE          Type,
    IN EFI_MEMORY_TYPE           MemoryType,
    IN UINTN                      Pages,
    IN OUT EFI_PHYSICAL_ADDRESS *Memory
);
```

Parameters

<i>Type</i>	The type of allocation to perform. See “Related Definitions.”
<i>MemoryType</i>	The type of memory to allocate. The type EFI_MEMORY_TYPE is defined in “Related Definitions” below. These memory types are also described in more detail in Table 21 and Table 22 . Normal allocations (that is, allocations by any UEFI application) are of type EfiLoaderData . <i>MemoryType</i> values in the range 0x80000000..0xFFFFFFFF are reserved for use by UEFI OS loaders that are provided by operating system vendors. The only illegal memory type values are those in the range EfiMaxMemoryType ..0x7FFFFFFF.
<i>Pages</i>	The number of contiguous 4 KB pages to allocate.
<i>Memory</i>	Pointer to a physical address. On input, the way in which the address is used depends on the value of <i>Type</i> . See “Description” for more information. On output the address is set to the base of the page range that was allocated. See “Related Definitions.”

Related Definitions

```
/**
//*****
//EFI_ALLOCATE_TYPE
//*****
// These types are discussed in the "Description" section below.
typedef enum {
    AllocateAnyPages,
    AllocateMaxAddress,
    AllocateAddress,
    MaxAllocateType
} EFI_ALLOCATE_TYPE;
```

```

//*****
//EFI_MEMORY_TYPE
//*****
// These type values are discussed in Table 21 and Table 22.
typedef enum {
    EfiReservedMemoryType,
    EfiLoaderCode,
    EfiLoaderData,
    EfiBootServicesCode,
    EfiBootServicesData,
    EfiRuntimeServicesCode,
    EfiRuntimeServicesData,
    EfiConventionalMemory,
    EfiUnusableMemory,
    EfiACPIReclaimMemory,
    EfiACPIMemoryNVS,
    EfiMemoryMappedIO,
    EfiMemoryMappedIOPortSpace,
    EfiPalCode,
    EfiMaxMemoryType
} EFI_MEMORY_TYPE;

//*****
//EFI_PHYSICAL_ADDRESS
//*****
typedef UINT64EFI_PHYSICAL_ADDRESS;

```

Description

The **AllocatePages ()** function allocates the requested number of pages and returns a pointer to the base address of the page range in the location referenced by *Memory*. The function scans the memory map to locate free pages. When it finds a physically contiguous block of pages that is large enough and also satisfies the allocation requirements of *Type*, it changes the memory map to indicate that the pages are now of type *MemoryType*.

In general, UEFI OS loaders and applications should allocate memory (and pool) of type **EfiLoaderData**. Boot service drivers must allocate memory (and pool) of type **EfiBootServicesData**. Runtime drivers should allocate memory (and pool) of type **EfiRuntimeServicesData** (although such allocation can only be made during boot services time).

Allocation requests of *Type* **AllocateAnyPages** allocate any available range of pages that satisfies the request. On input, the address pointed to by *Memory* is ignored.

Allocation requests of *Type* **AllocateMaxAddress** allocate any available range of pages whose uppermost address is less than or equal to the address pointed to by *Memory* on input.

Allocation requests of *Type* **AllocateAddress** allocate pages at the address pointed to by *Memory* on input.

Status Codes Returned

EFI_SUCCESS	The requested pages were allocated.
EFI_OUT_OF_RESOURCES	The pages could not be allocated.
EFI_INVALID_PARAMETER	<i>Type</i> is not AllocateAnyPages or AllocateMaxAddress or AllocateAddress .
EFI_INVALID_PARAMETER	<i>MemoryType</i> is in the range EfiMaxMemoryType ..0x7FFFFFFF.
EFI_NOT_FOUND	The requested pages could not be found.

FreePages()

Summary

Frees memory pages.

Prototype

```
typedef
EFI_STATUS
FreePages (
    IN EFI_PHYSICAL_ADDRESS    Memory,
    IN UINTN                   Pages
);
```

Parameters

Memory

The base physical address of the pages to be freed. Type **EFI_PHYSICAL_ADDRESS** is defined in the [AllocatePages \(\)](#) function description.

Pages

The number of contiguous 4 KB pages to free.

Description

The **FreePages ()** function returns memory allocated by **AllocatePages ()** to the firmware.

Status Codes Returned

EFI_SUCCESS	The requested memory pages were freed.
EFI_NOT_FOUND	The requested memory pages were not allocated with AllocatePages () .
EFI_INVALID_PARAMETER	<i>Memory</i> is not a page-aligned address or <i>Pages</i> is invalid.

GetMemoryMap()

Summary

Returns the current memory map.

Prototype

```
typedef
EFI_STATUS
GetMemoryMap (
    IN OUT UINTN                *MemoryMapSize,
    IN OUT EFI_MEMORY_DESCRIPTOR *MemoryMap,
    OUT UINTN                   *MapKey,
    OUT UINTN                   *DescriptorSize,
    OUT UINT32                  *DescriptorVersion
);
```

Parameters

<i>MemoryMapSize</i>	A pointer to the size, in bytes, of the <i>MemoryMap</i> buffer. On input, this is the size of the buffer allocated by the caller. On output, it is the size of the buffer returned by the firmware if the buffer was large enough, or the size of the buffer needed to contain the map if the buffer was too small.
<i>MemoryMap</i>	A pointer to the buffer in which firmware places the current memory map. The map is an array of EFI_MEMORY_DESCRIPTOR s. See “Related Definitions.”
<i>MapKey</i>	A pointer to the location in which firmware returns the key for the current memory map.
<i>DescriptorSize</i>	A pointer to the location in which firmware returns the size, in bytes, of an individual EFI_MEMORY_DESCRIPTOR .
<i>DescriptorVersion</i>	A pointer to the location in which firmware returns the version number associated with the EFI_MEMORY_DESCRIPTOR . See “Related Definitions.”

Related Definitions

```

//*****
//EFI_MEMORY_DESCRIPTOR
//*****
typedef struct {
    UINT32                Type;
    EFI_PHYSICAL_ADDRESS  PhysicalStart;
    EFI_VIRTUAL_ADDRESS   VirtualStart;
    UINT64                NumberOfPages;
    UINT64                Attribute;
};
```

```

} EFI_MEMORY_DESCRIPTOR;
    Type                Type of the memory region. Type EFI_MEMORY_TYPE is
                        defined in the AllocatePages \(\) function description.
    PhysicalStart      Physical address of the first byte in the memory region. Physical
                        start must be aligned on a 4 KB boundary. Type
                        EFI_PHYSICAL_ADDRESS is defined in the
                        AllocatePages \(\) function description.
    VirtualStart       Virtual address of the first byte in the memory region. Virtual
                        start must be aligned on a 4 KB boundary. Type
                        EFI_VIRTUAL_ADDRESS is defined in “Related Definitions.”
    NumberOfPages      Number of 4 KB pages in the memory region.
    Attribute          Attributes of the memory region that describe the bit mask of
                        capabilities for that memory region, and not necessarily the
                        current settings for that memory region. See the following
                        “Memory Attribute Definitions.”

```

```

//*****
// Memory Attribute Definitions
//*****
// These types can be "ORed" together as needed.
#define EFI_MEMORY_UC           0x0000000000000001
#define EFI_MEMORY_WC           0x0000000000000002
#define EFI_MEMORY_WT           0x0000000000000004
#define EFI_MEMORY_WB           0x0000000000000008
#define EFI_MEMORY_UCE          0x0000000000000010
#define EFI_MEMORY_WP           0x0000000000000100
#define EFI_MEMORY_RP           0x0000000000000200
#define EFI_MEMORY_XP           0x0000000000000400
#define EFI_MEMORY_RUNTIME      0x8000000000000000

```

EFI_MEMORY_UC Memory cacheability attribute: The memory region supports being configured as not cacheable.

EFI_MEMORY_WC Memory cacheability attribute: The memory region supports being configured as write combining.

EFI_MEMORY_WT Memory cacheability attribute: The memory region supports being configured as cacheable with a “write through” policy. Writes that hit in the cache will also be written to main memory.

EFI_MEMORY_WB Memory cacheability attribute: The memory region supports being configured as cacheable with a “write back” policy. Reads and writes that hit in the cache do not propagate to main memory. Dirty data is written back to main memory when a new cache line is allocated.

EFI_MEMORY_UCE Memory cacheability attribute: The memory region supports being configured as not cacheable, exported, and supports the “fetch and add” semaphore mechanism.

EFI_MEMORY_WP	Physical memory protection attribute: The memory region supports being configured as write-protected by system hardware.
EFI_MEMORY_RP	Physical memory protection attribute: The memory region supports being configured as read-protected by system hardware.
EFI_MEMORY_XP	Physical memory protection attribute: The memory region supports being configured so it is protected by system hardware from executing code.
EFI_MEMORY_RUNTIME	Runtime memory attribute: The memory region needs to be given a virtual mapping by the operating system when SetVirtualAddressMap() is called (described in Section 7.4).


```

//*****
//EFI_VIRTUAL_ADDRESS
//*****
typedef UINT64     EFI_VIRTUAL_ADDRESS;

//*****
// Memory Descriptor Version Number
//*****
#define EFI_MEMORY_DESCRIPTOR_VERSION  1

```

Description

The [GetMemoryMap\(\)](#) function returns a copy of the current memory map. The map is an array of memory descriptors, each of which describes a contiguous block of memory. The map describes all of memory, no matter how it is being used. That is, it includes blocks allocated by [AllocatePages\(\)](#) and [AllocatePool\(\)](#), as well as blocks that the firmware is using for its own purposes. The memory map is only used to describe memory that is present in the system. Memory descriptors are never used to describe holes in the system memory map.

Until [ExitBootServices\(\)](#) is called, the memory map is owned by the firmware and the currently executing EFI Image should only use memory pages it has explicitly allocated.

If the *MemoryMap* buffer is too small, the **EFI_BUFFER_TOO_SMALL** error code is returned and the *MemoryMapSize* value contains the size of the buffer needed to contain the current memory map. The actual size of the buffer allocated for the consequent call to [GetMemoryMap\(\)](#) should be bigger than the value returned in *MemoryMapSize*, since allocation of the new buffer may potentially increase memory map size.

On success a *MapKey* is returned that identifies the current memory map. The firmware's key is changed every time something in the memory map changes. In order to successfully invoke [ExitBootServices\(\)](#) the caller must provide the current memory map key.

The [GetMemoryMap\(\)](#) function also returns the size and revision number of the **EFI_MEMORY_DESCRIPTOR**. The *DescriptorSize* represents the size in bytes of an **EFI_MEMORY_DESCRIPTOR** array element returned in *MemoryMap*. The size is returned to allow for future expansion of the **EFI_MEMORY_DESCRIPTOR** in response to hardware innovation. The structure of the **EFI_MEMORY_DESCRIPTOR** may be extended in the future but it

will remain backwards compatible with the current definition. Thus OS software must use the *DescriptorSize* to find the start of each **EFI_MEMORY_DESCRIPTOR** in the *MemoryMap* array.

Status Codes Returned

EFI_SUCCESS	The memory map was returned in the <i>MemoryMap</i> buffer.
EFI_BUFFER_TOO_SMALL	The <i>MemoryMap</i> buffer was too small. The current buffer size needed to hold the memory map is returned in <i>MemoryMapSize</i> .
EFI_INVALID_PARAMETER	<i>MemoryMapSize</i> is NULL .
EFI_INVALID_PARAMETER	The <i>MemoryMap</i> buffer is not too small and <i>MemoryMap</i> is NULL .

AllocatePool()

Summary

Allocates pool memory.

Prototype

```
typedef
EFI_STATUS
AllocatePool (
    IN EFI_MEMORY_TYPE PoolType,
    IN UINTN           Size,
    OUT VOID           **Buffer
);
```

Parameters

PoolType

The type of pool to allocate. Type **EFI_MEMORY_TYPE** is defined in the [AllocatePages \(\)](#) function description. *PoolType* values in the range 0x80000000..0xFFFFFFFF are reserved for use by UEFI OS loaders that are provided by operating system vendors. The only illegal memory type values are those in the range **EfiMaxMemoryType**..0x7FFFFFFF.

Size

The number of bytes to allocate from the pool.

Buffer

A pointer to a pointer to the allocated buffer if the call succeeds; undefined otherwise.

Description

The **AllocatePool ()** function allocates a memory region of *Size* bytes from memory of type *PoolType* and returns the address of the allocated memory in the location referenced by *Buffer*. This function allocates pages from **EfiConventionalMemory** as needed to grow the requested pool type. All allocations are eight-byte aligned.

The allocated pool memory is returned to the available pool with the [FreePool \(\)](#) function.

Status Codes Returned

EFI_SUCCESS	The requested number of bytes was allocated.
EFI_OUT_OF_RESOURCES	The pool requested could not be allocated.
EFI_INVALID_PARAMETER	<i>PoolType</i> was invalid.

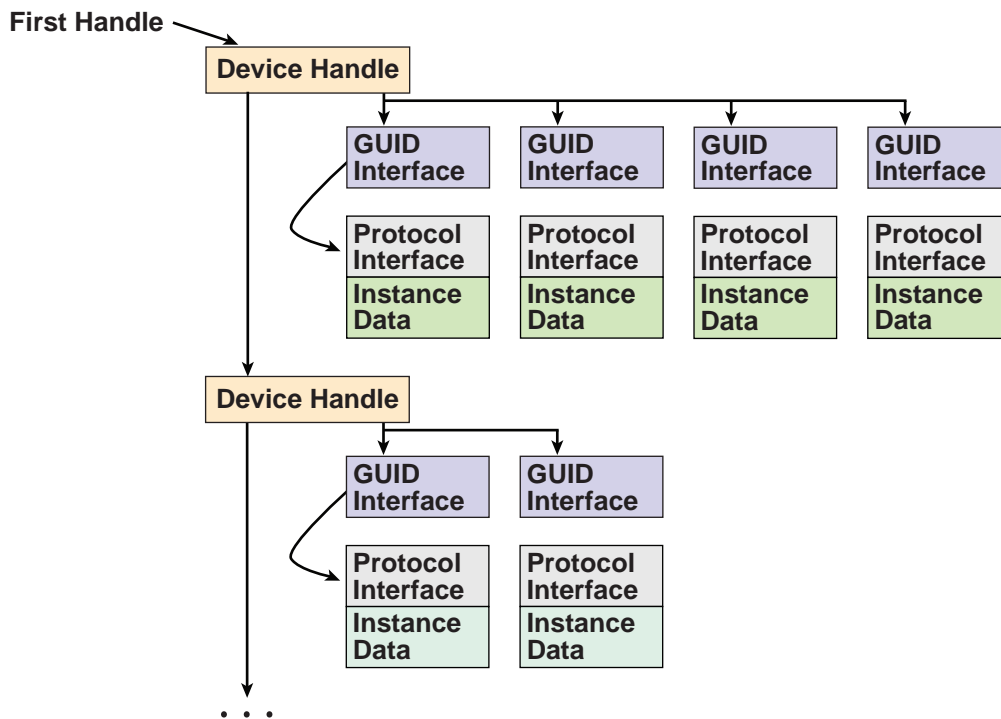
HandleProtocol	Boot	Queries a handle to determine if it supports a specified protocol.
LocateDevicePath	Boot	Locates all devices on a device path that support a specified protocol and returns the handle to the device that is closest to the path.
OpenProtocol	Boot	Adds elements to the list of agents consuming a protocol interface.
CloseProtocol	Boot	Removes elements from the list of agents consuming a protocol interface.
OpenProtocolInformation	Boot	Retrieve the list of agents that are currently consuming a protocol interface.
ConnectController	Boot	Uses a set of precedence rules to find the best set of drivers to manage a controller.
DisconnectController	Boot	Informs a set of drivers to stop managing a controller.
ProtocolsPerHandle	Boot	Retrieves the list of protocols installed on a handle. The return buffer is automatically allocated.
LocateHandleBuffer	Boot	Retrieves the list of handles from the handle database that meet the search criteria. The return buffer is automatically allocated.
LocateProtocol	Boot	Finds the first handle in the handle database the supports the requested protocol.
InstallMultipleProtocolInterfaces	Boot	Installs one or more protocol interfaces onto a handle.
UninstallMultipleProtocolInterfaces	Boot	Uninstalls one or more protocol interfaces from a handle.

The Protocol Handler boot services have been modified to take advantage of the information that is now being tracked with the [OpenProtocol \(\)](#) and [CloseProtocol \(\)](#) boot services. Since the usage of protocol interfaces is being tracked with these new boot services, it is now possible to safely uninstall and reinstall protocol interfaces that are being consumed by UEFI drivers.

As depicted in [Figure 17](#), the firmware is responsible for maintaining a “data base” that shows which protocols are attached to each device handle. (The figure depicts the “data base” as a linked list, but the choice of data structure is implementation-dependent.) The “data base” is built dynamically by calling the [InstallProtocolInterface \(\)](#) function. Protocols can only be installed by UEFI drivers or the firmware itself. In the figure, a device handle (**EFI_HANDLE**) refers to a list of one or more registered protocol interfaces for that handle. The first handle in the system has four attached protocols, and the second handle has two attached protocols. Each attached protocol is represented as a GUID/Interface pointer pair. The GUID is the name of the protocol, and Interface points to a protocol instance. This data structure will typically contain a list of interface functions, and some amount of instance data.

Access to devices is initiated by calling the [HandleProtocol \(\)](#) function, which determines whether a handle supports a given protocol. If it does, a pointer to the matching Protocol Interface structure is returned.

When a protocol is added to the system, it may either be added to an existing device handle or it may be added to create a new device handle. [Figure 17](#) shows that protocol handlers are listed for each device handle and that each protocol handler is logically a UEFI driver.



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Figure 17. Device Handle to Protocol Handler Mapping

The ability to add new protocol interfaces as new handles or to layer them on existing interfaces provides great flexibility. Layering makes it possible to add a new protocol that builds on a device’s basic protocols. An example of this might be to layer on a [EFI SIMPLE TEXT OUTPUT PROTOCOL](#) support that would build on the handle’s underlying [EFI SERIAL IO PROTOCOL](#).

The ability to add new handles can be used to generate new devices as they are found, or even to generate abstract devices. An example of this might be to add a multiplexing device that replaces *ConsoleOut* with a virtual device that multiplexes the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) protocol onto multiple underlying device handles.

6.3.1 Driver Model Boot Services

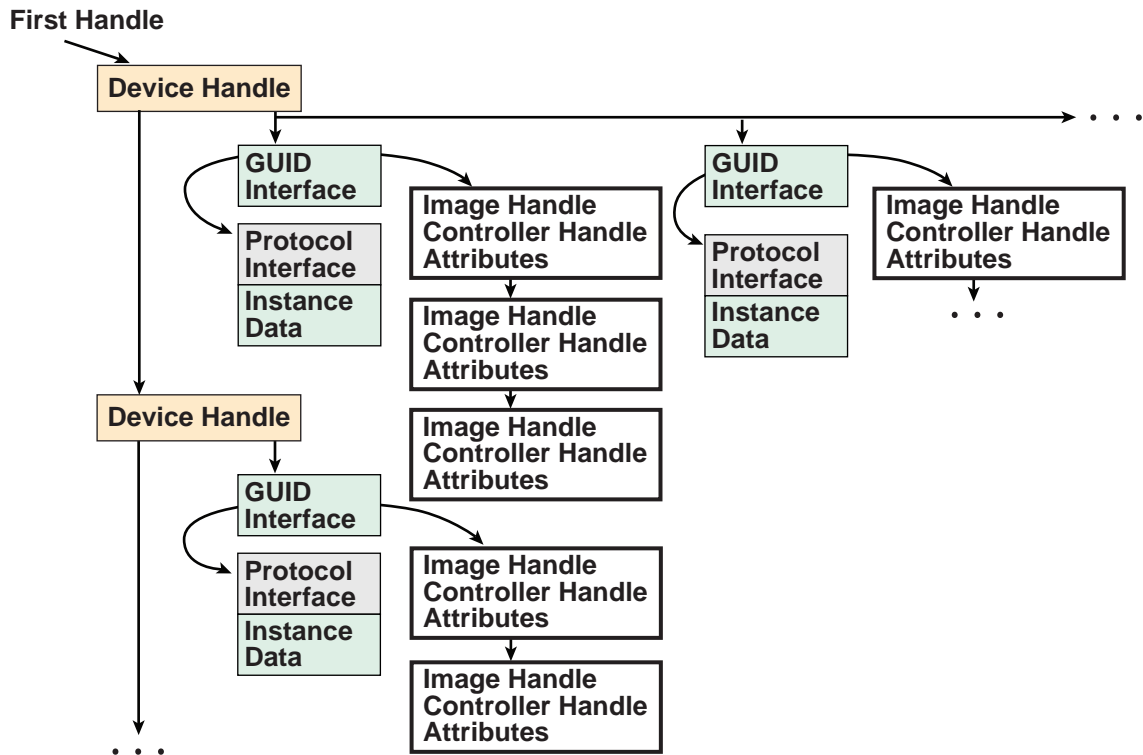
This section provides a detailed description of the new UEFI boot services that are required by the UEFI *Driver Model*. These boot services are being added to reduce the size and complexity of the bus drivers and device drivers. This, in turn, will reduce the amount of ROM space required by drivers that are programmed into ROMs on adapters or into system FLASH, and reduce the development and testing time required by driver writers.

These new services fall into two categories. The first group is used to track the usage of protocol interfaces by different agents in the system. Protocol interfaces are stored in a handle database. The handle database consists of a list of handles, and on each handle there is a list of one or more protocol interfaces. The boot services [InstallProtocolInterface\(\)](#),

[UninstallProtocolInterface\(\)](#), and [ReinstallProtocolInterface\(\)](#) are used to add, remove, and replace protocol interfaces in the handle database. The boot service [HandleProtocol\(\)](#) is used to look up a protocol interface in the handle database. However, agents that call [HandleProtocol\(\)](#) are not tracked, so it is not safe to call [UninstallProtocolInterface\(\)](#) or [ReinstallProtocolInterface\(\)](#) because an agent may be using the protocol interface that is being removed or replaced.

The solution is to track the usage of protocol interfaces in the handle database itself. To accomplish this, each protocol interface includes a list of agents that are consuming the protocol interface.

[Figure 18](#) shows an example handle database with these new agent lists. An agent consists of an image handle, a controller handle, and some attributes. The image handle identifies the driver or application that is consuming the protocol interface. The controller handle identifies the controller that is consuming the protocol interface. Since a driver may manage more than one controller, the combination of a driver's image handle and a controller's controller handle uniquely identifies the agent that is consuming the protocol interface. The attributes show how the protocol interface is being used.



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Figure 18. Handle Database

In order to maintain these agent lists in the handle database, some new boot services are required. These are [OpenProtocol\(\)](#), [CloseProtocol\(\)](#), and [OpenProtocolInformation\(\)](#). [OpenProtocol\(\)](#) adds elements to the list of agents consuming a protocol interface. [CloseProtocol\(\)](#) removes elements from the list of agents consuming a protocol interface, and

[OpenProtocolInformation\(\)](#) retrieves the entire list of agents that are currently using a protocol interface.

The second group of boot services is used to deterministically connect and disconnect drivers to controllers. The boot services in this group are [ConnectController\(\)](#) and [DisconnectController\(\)](#). These services take advantage of the new features of the handle database along with the new protocols described in this document to manage the drivers and controllers present in the system. **ConnectController()** uses a set of strict precedence rules to find the best set of drivers for a controller. This provides a deterministic matching of drivers to controllers with extensibility mechanisms for OEMs, IBVs, and IHVs.

DisconnectController() allows drivers to be disconnected from controllers in a controlled manner, and by using the new features of the handle database it is possible to fail a disconnect request because a protocol interface cannot be released at the time of the disconnect request.

The third group of boot services is designed to help simplify the implementation of drivers, and produce drivers with smaller executable footprints. The [LocateHandleBuffer\(\)](#) is a new version of [LocateHandle\(\)](#) that allocates the required buffer for the caller. This eliminates two calls to **LocateHandle()** and a call to [AllocatePool\(\)](#) from the caller's code.

[LocateProtocol\(\)](#) searches the handle database for the first protocol instance that matches the search criteria. The [InstallMultipleProtocolInterfaces\(\)](#) and [UninstallMultipleProtocolInterfaces\(\)](#) are very useful to driver writers. These boot services allow one or more protocol interfaces to be added or removed from a handle. In addition, **InstallMultipleProtocolInterfaces()** guarantees that a duplicate device path is never added to the handle database. This is very useful to bus drivers that can create one child handle at a time, because it guarantees that the bus driver will not inadvertently create two instances of the same child handle.

InstallProtocolInterface()

Summary

Installs a protocol interface on a device handle. If the handle does not exist, it is created and added to the list of handles in the system. `InstallMultipleProtocolInterfaces()` performs more error checking than `InstallProtocolInterface()`, so it is recommended that `InstallMultipleProtocolInterfaces()` be used in place of `InstallProtocolInterface()`.

Prototype

```
typedef
EFI_STATUS
InstallProtocolInterface (
    IN OUT EFI_HANDLE    *Handle,
    IN EFI_GUID          *Protocol,
    IN EFI_INTERFACE_TYPE InterfaceType,
    IN VOID              *Interface
);
```

Parameters

<i>Handle</i>	A pointer to the EFI_HANDLE on which the interface is to be installed. If <i>*Handle</i> is NULL on input, a new handle is created and returned on output. If <i>*Handle</i> is not NULL on input, the protocol is added to the handle, and the handle is returned unmodified. The type EFI_HANDLE is defined in “Related Definitions.” If <i>*Handle</i> is not a valid handle, then EFI_INVALID_PARAMETER is returned.
<i>Protocol</i>	The numeric ID of the protocol interface. The type EFI_GUID is defined in “Related Definitions.” It is the caller’s responsibility to pass in a valid GUID. See “Wired For Management Baseline” for a description of valid GUID values.
<i>InterfaceType</i>	Indicates whether <i>Interface</i> is supplied in native form. This value indicates the original execution environment of the request. See “Related Definitions.”
<i>Interface</i>	A pointer to the protocol interface. The <i>Interface</i> must adhere to the structure defined by <i>Protocol</i> . NULL can be used if a structure is not associated with <i>Protocol</i> .

Related Definitions

```
/**
//*****
//EFI_HANDLE
//*****
typedef VOID*EFI_HANDLE;
```

```

//*****
//EFI_GUID
//*****
typedef struct {
    UINT32  Data1;
    UINT16  Data2;
    UINT16  Data3;
    UINT8   Data4[8];
} EFI_GUID;

//*****
//EFI_INTERFACE_TYPE
//*****
typedef enum {
    EFI_NATIVE_INTERFACE
} EFI_INTERFACE_TYPE;

```

Description

The **InstallProtocolInterface()** function installs a protocol interface (a GUID/Protocol Interface structure pair) on a device handle. The same GUID cannot be installed more than once onto the same handle. If installation of a duplicate GUID on a handle is attempted, an **EFI_INVALID_PARAMETER** will result.

Installing a protocol interface allows other components to locate the *Handle*, and the interfaces installed on it.

When a protocol interface is installed, the firmware calls all notification functions that have registered to wait for the installation of *Protocol*. For more information, see the [RegisterProtocolNotify\(\)](#) function description.

Status Codes Returned

EFI_SUCCESS	The protocol interface was installed.
EFI_OUT_OF_RESOURCES	Space for a new handle could not be allocated.
EFI_INVALID_PARAMETER	<i>Handle</i> is NULL .
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .
EFI_INVALID_PARAMETER	<i>InterfaceType</i> is not EFI_NATIVE_INTERFACE .
EFI_INVALID_PARAMETER	<i>Protocol</i> is already installed on the handle specified by <i>Handle</i> .

UninstallProtocolInterface()

Summary

Removes a protocol interface from a device handle. It is recommended that **UninstallMultipleProtocolInterfaces()** be used in place of **UninstallProtocolInterface()**.

Prototype

```
typedef
EFI_STATUS
UninstallProtocolInterface (
    IN EFI_HANDLE  Handle,
    IN EFI_GUID    *Protocol,
    IN VOID        *Interface
);
```

Parameters

<i>Handle</i>	The handle on which the interface was installed. If <i>Handle</i> is not a valid handle, then EFI_INVALID_PARAMETER is returned. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.
<i>Protocol</i>	The numeric ID of the interface. It is the caller's responsibility to pass in a valid GUID. See "Wired For Management Baseline" for a description of valid GUID values. Type EFI_GUID is defined in the InstallProtocolInterface() function description.
<i>Interface</i>	A pointer to the interface. NULL can be used if a structure is not associated with <i>Protocol</i> .

Description

The **UninstallProtocolInterface()** function removes a protocol interface from the handle on which it was previously installed. The *Protocol* and *Interface* values define the protocol interface to remove from the handle.

The caller is responsible for ensuring that there are no references to a protocol interface that has been removed. In some cases, outstanding reference information is not available in the protocol, so the protocol, once added, cannot be removed. Examples include Console I/O, Block I/O, Disk I/O, and (in general) handles to device protocols.

If the last protocol interface is removed from a handle, the handle is freed and is no longer valid.

EFI 1.10 Extension

The extension to this service directly addresses the limitations described in the section above. There may be some drivers that are currently consuming the protocol interface that needs to be uninstalled, so it may be dangerous to just blindly remove a protocol interface from the system. Since the usage of protocol interfaces is now being tracked for components that use the [OpenProtocol\(\)](#) and [CloseProtocol\(\)](#) boot services, a safe version of this function can be implemented. Before the

protocol interface is removed, an attempt is made to force all the drivers that are consuming the protocol interface to stop consuming that protocol interface. This is done by calling the boot service [DisconnectController\(\)](#) for the driver that currently have the protocol interface open with an attribute of **EFI_OPEN_PROTOCOL_BY_DRIVER** or **EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE**.

If the disconnect succeeds, then those agents will have called the boot service [CloseProtocol\(\)](#) to release the protocol interface. Lastly, all of the agents that have the protocol interface open with an attribute of **EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL**, **EFI_OPEN_PROTOCOL_GET_PROTOCOL**, or **EFI_OPEN_PROTOCOL_TEST_PROTOCOL** are closed. If there are any agents remaining that still have the protocol interface open, the protocol interface is not removed from the handle and **EFI_ACCESS_DENIED** is returned. In addition, all of the drivers that were disconnected with the boot service [DisconnectController\(\)](#) earlier, are reconnected with the boot service [ConnectController\(\)](#). If there are no agents remaining that are consuming the protocol interface, then the protocol interface is removed from the handle as described above.

Status Codes Returned

EFI_SUCCESS	The interface was removed.
EFI_NOT_FOUND	The interface was not found.
EFI_ACCESS_DENIED	The interface was not removed because the interface is still being used by a driver.
EFI_INVALID_PARAMETER	<i>Handle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .

ReinstallProtocolInterface()

Summary

Reinstalls a protocol interface on a device handle.

Prototype

```
typedef
EFI_STATUS
ReinstallProtocolInterface (
    IN EFI_HANDLE  Handle,
    IN EFI_GUID    *Protocol,
    IN VOID        *OldInterface,
    IN VOID        *NewInterface
);
```

Parameters

<i>Handle</i>	Handle on which the interface is to be reinstalled. If <i>Handle</i> is not a valid handle, then EFI_INVALID_PARAMETER is returned. Type EFI_HANDLE is defined in the InstallProtocolInterface () function description.
<i>Protocol</i>	The numeric ID of the interface. It is the caller's responsibility to pass in a valid GUID. See "Wired For Management Baseline" for a description of valid GUID values. Type EFI_GUID is defined in the InstallProtocolInterface () function description.
<i>OldInterface</i>	A pointer to the old interface. NULL can be used if a structure is not associated with <i>Protocol</i> .
<i>NewInterface</i>	A pointer to the new interface. NULL can be used if a structure is not associated with <i>Protocol</i> .

Description

The **ReinstallProtocolInterface ()** function reinstalls a protocol interface on a device handle. The *OldInterface* for *Protocol* is replaced by the *NewInterface*. *NewInterface* may be the same as *OldInterface*. If it is, the registered protocol notifies occur for the handle without replacing the interface on the handle.

As with **InstallProtocolInterface ()**, any process that has registered to wait for the installation of the interface is notified.

The caller is responsible for ensuring that there are no references to the *OldInterface* that is being removed.

EFI 1.10 Extension

The extension to this service directly addresses the limitations described in the section above. There may be some number of drivers currently consuming the protocol interface that is being reinstalled. In this case, it may be dangerous to replace a protocol interface in the system. It could result in an

unstable state, because a driver may attempt to use the old protocol interface after a new one has been reinstalled. Since the usage of protocol interfaces is now being tracked for components that use the [OpenProtocol \(\)](#) and [CloseProtocol \(\)](#) boot services, a safe version of this function can be implemented.

When this function is called, a call is first made to the boot service [InstallProtocolInterface \(\)](#). This will guarantee that all of the agents are currently consuming the protocol interface *OldInterface* will stop using *OldInterface*. If [UninstallProtocolInterface \(\)](#) returns **EFI_ACCESS_DENIED**, then this function returns **EFI_ACCESS_DENIED**, *OldInterface* remains on *Handle*, and the protocol notifies are not processed because *NewInterface* was never installed.

If [UninstallProtocolInterface \(\)](#) succeeds, then a call is made to the boot service [InstallProtocolInterface \(\)](#) to put the *NewInterface* onto *Handle*.

Finally, the boot service [ConnectController \(\)](#) is called so all agents that were forced to release *OldInterface* with [UninstallProtocolInterface \(\)](#) can now consume the protocol interface *NewInterface* that was installed with [InstallProtocolInterface \(\)](#). After *OldInterface* has been replaced with *NewInterface*, any process that has registered to wait for the installation of the interface is notified.

Status Codes Returned

EFI_SUCCESS	The protocol interface was reinstalled.
EFI_NOT_FOUND	The <i>OldInterface</i> on the handle was not found.
EFI_ACCESS_DENIED	The protocol interface could not be reinstalled, because <i>OldInterface</i> is still being used by a driver that will not release it.
EFI_INVALID_PARAMETER	<i>Handle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .

RegisterProtocolNotify()

Summary

Creates an event that is to be signaled whenever an interface is installed for a specified protocol.

Prototype

```
typedef
EFI_STATUS
RegisterProtocolNotify (
    IN EFI_GUID    *Protocol,
    IN EFI_EVENT   Event,
    OUT VOID       **Registration
);
```

Parameters

<i>Protocol</i>	The numeric ID of the protocol for which the event is to be registered. Type EFI_GUID is defined in the InstallProtocolInterface() function description.
<i>Event</i>	Event that is to be signaled whenever a protocol interface is registered for <i>Protocol</i> . The type EFI_EVENT is defined in the CreateEvent() function description. The same EFI_EVENT may be used for multiple protocol notify registrations.
<i>Registration</i>	A pointer to a memory location to receive the registration value. This value must be saved and used by the notification function of <i>Event</i> to retrieve the list of handles that have added a protocol interface of type <i>Protocol</i> .

Description

The **RegisterProtocolNotify()** function creates an event that is to be signaled whenever a protocol interface is installed for *Protocol* by **InstallProtocolInterface()** or [ReinstallProtocolInterface\(\)](#).

Once **Event** has been signaled, the [LocateHandle\(\)](#) function can be called to identify the newly installed, or reinstalled, handles that support *Protocol*. The **Registration** parameter in [RegisterProtocolNotify\(\)](#) corresponds to the **SearchKey** parameter in [LocateHandle\(\)](#). Note that the same handle may be returned multiple times if the handle reinstalls the target protocol ID multiple times. This is typical for removable media devices, because when such a device reappears, it will reinstall the Block I/O protocol to indicate that the device needs to be checked again. In response, layered Disk I/O and Simple File System protocols may then reinstall their protocols to indicate that they can be re-checked, and so forth.

Status Codes Returned

EFI_SUCCESS	The notification event has been registered.
-------------	---

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EFI_OUT_OF_RESOURCES	Space for the notification event could not be allocated.
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .
EFI_INVALID_PARAMETER	<i>Event</i> is NULL .
EFI_INVALID_PARAMETER	<i>Registration</i> is NULL .

LocateHandle()

Summary

Returns an array of handles that support a specified protocol.

Prototype

```
typedef
EFI_STATUS
LocateHandle (
    IN EFI_LOCATE_SEARCH_TYPE    SearchType,
    IN EFI_GUID                  *Protocol OPTIONAL,
    IN VOID                      *SearchKey OPTIONAL,
    IN OUT UINTN                 *BufferSize,
    OUT EFI_HANDLE                *Buffer
);
```

Parameters

<i>SearchType</i>	Specifies which handle(s) are to be returned. Type EFI_LOCATE_SEARCH_TYPE is defined in “Related Definitions.”
<i>Protocol</i>	Specifies the protocol to search by. This parameter is only valid if <i>SearchType</i> is ByProtocol . Type EFI_GUID is defined in the InstallProtocolInterface() function description.
<i>SearchKey</i>	Specifies the search key. This parameter is ignored if <i>SearchType</i> is AllHandles or ByProtocol . If <i>SearchType</i> is ByRegisterNotify , the parameter must be the <i>Registration</i> value returned by function RegisterProtocolNotify() .
<i>BufferSize</i>	On input, the size in bytes of <i>Buffer</i> . On output, the size in bytes of the array returned in <i>Buffer</i> (if the buffer was large enough) or the size, in bytes, of the buffer needed to obtain the array (if the buffer was not large enough).
<i>Buffer</i>	The buffer in which the array is returned. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.

Related Definitions

```
/**
//*****
// EFI_LOCATE_SEARCH_TYPE
//*****
typedef enum {
    AllHandles,
    ByRegisterNotify,
    ByProtocol
};
```

```
} EFI_LOCATE_SEARCH_TYPE;
```

- AllHandles** *Protocol* and *SearchKey* are ignored and the function returns an array of every handle in the system.
- ByRegisterNotify** *SearchKey* supplies the *Registration* value returned by [RegisterProtocolNotify\(\)](#). The function returns the next handle that is new for the registration. Only one handle is returned at a time, starting with the first, and the caller must loop until no more handles are returned. *Protocol* is ignored for this search type.
- ByProtocol** All handles that support *Protocol* are returned. *SearchKey* is ignored for this search type.

Description

The **LocateHandle()** function returns an array of handles that match the *SearchType* request. If the input value of *BufferSize* is too small, the function returns **EFI_BUFFER_TOO_SMALL** and updates *BufferSize* to the size of the buffer needed to obtain the array.

Status Codes Returned

EFI_SUCCESS	The array of handles was returned.
EFI_NOT_FOUND	No handles match the search.
EFI_BUFFER_TOO_SMALL	The <i>BufferSize</i> is too small for the result. <i>BufferSize</i> has been updated with the size needed to complete the request.
EFI_INVALID_PARAMETER	<i>SearchType</i> is not a member of EFI_LOCATE_SEARCH_TYPE .
EFI_INVALID_PARAMETER	<i>SearchType</i> is ByRegisterNotify and <i>SearchKey</i> is NULL .
EFI_INVALID_PARAMETER	<i>SearchType</i> is ByProtocol and <i>Protocol</i> is NULL .
EFI_INVALID_PARAMETER	One or more matches are found and <i>BufferSize</i> is NULL .
EFI_INVALID_PARAMETER	<i>BufferSize</i> is large enough for the result and <i>Buffer</i> is NULL .

HandleProtocol()

Summary

Queries a handle to determine if it supports a specified protocol.

Prototype

```
typedef
EFI_STATUS
HandleProtocol (
    IN EFI_HANDLE  Handle,
    IN EFI_GUID    *Protocol,
    OUT VOID       **Interface
);
```

Parameters

<i>Handle</i>	The handle being queried. If <i>Handle</i> is not a valid EFI_HANDLE , then EFI_INVALID_PARAMETER is returned. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.
<i>Protocol</i>	The published unique identifier of the protocol. It is the caller's responsibility to pass in a valid GUID. See "Wired For Management Baseline" for a description of valid GUID values. Type EFI_GUID is defined in the InstallProtocolInterface() function description.
<i>Interface</i>	Supplies the address where a pointer to the corresponding Protocol Interface is returned. NULL will be returned in <i>*Interface</i> if a structure is not associated with <i>Protocol</i> .

Description

The **HandleProtocol()** function queries **Handle** to determine if it supports *Protocol*. If it does, then on return *Interface* points to a pointer to the corresponding Protocol Interface. *Interface* can then be passed to any protocol service to identify the context of the request.

EFI 1.10 Extension

The **HandleProtocol()** function is still available for use by old EFI applications and drivers. However, all new applications and drivers should use [OpenProtocol\(\)](#) in place of **HandleProtocol()**. The following code fragment shows a possible implementation of **HandleProtocol()** using **OpenProtocol()**. The variable **EfiCoreImageHandle** is the image handle of the EFI core.

```
EFI_STATUS
HandleProtocol (
    IN EFI_HANDLE  Handle,
    IN EFI_GUID    *Protocol,
    OUT VOID       **Interface
```

```

    )
  {
    return OpenProtocol (
      Handle,
      Protocol,
      Interface,
      EfiCoreImageHandle,
      NULL,
      EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL
    );
  }

```

Status Codes Returned

EFI_SUCCESS	The interface information for the specified protocol was returned.
EFI_UNSUPPORTED	The device does not support the specified protocol.
EFI_INVALID_PARAMETER	<i>Handle</i> is not a valid EFI_HANDLE ..
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .
EFI_INVALID_PARAMETER	<i>Interface</i> is NULL .

LocateDevicePath()

Summary

Locates the handle to a device on the device path that supports the specified protocol.

Prototype

```
typedef
EFI_STATUS
LocateDevicePath (
    IN EFI_GUID                      *Protocol,
    IN OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath,
    OUT EFI_HANDLE                   *Device
);
```

Parameters

Protocol

The protocol to search for. Type **EFI_GUID** is defined in the [InstallProtocolInterface\(\)](#) function description.

DevicePath

On input, a pointer to a pointer to the device path. On output, the device path pointer is modified to point to the remaining part of the device path—that is, when the function finds the closest handle, it splits the device path into two parts, stripping off the front part, and returning the remaining portion.

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Device

A pointer to the returned device handle. Type **EFI_HANDLE** is defined in the [InstallProtocolInterface\(\)](#) function description.

Description

The **LocateDevicePath()** function locates all devices on *DevicePath* that support *Protocol* and returns the handle to the device that is closest to *DevicePath*. *DevicePath* is advanced over the device path nodes that were matched.

This function is useful for locating the proper instance of a protocol interface to use from a logical parent device driver. For example, a target device driver may issue the request with its own device path and locate the interfaces to perform I/O on its bus. It can also be used with a device path that contains a file path to strip off the file system portion of the device path, leaving the file path and handle to the file system driver needed to access the file.

If the handle for *DevicePath* supports the protocol (a direct match), the resulting device path is advanced to the device path terminator node.

Status Codes Returned

EFI_SUCCESS	The resulting handle was returned.
EFI_NOT_FOUND	No handles matched the search.

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EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL
EFI_INVALID_PARAMETER	<i>DevicePath</i> is NULL .
EFI_INVALID_PARAMETER	A handle matched the search and <i>Device</i> is NULL .

OpenProtocol()

Summary

Queries a handle to determine if it supports a specified protocol. If the protocol is supported by the handle, it opens the protocol on behalf of the calling agent. This is an extended version of the EFI boot service [HandleProtocol\(\)](#).

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_OPEN_PROTOCOL) (
    IN  EFI_HANDLE      Handle,
    IN  EFI_GUID        *Protocol,
    OUT VOID            **Interface      OPTIONAL,
    IN  EFI_HANDLE      AgentHandle,
    IN  EFI_HANDLE      ControllerHandle,
    IN  UINT32           Attributes
);
```

Parameters

<i>Handle</i>	The handle for the protocol interface that is being opened.
<i>Protocol</i>	The published unique identifier of the protocol. It is the caller's responsibility to pass in a valid GUID. See "Wired For Management Baseline" for a description of valid GUID values.
<i>Interface</i>	Supplies the address where a pointer to the corresponding Protocol Interface is returned. NULL will be returned in <i>*Interface</i> if a structure is not associated with <i>Protocol</i> . This parameter is optional, and will be ignored if <i>Attributes</i> is EFI_OPEN_PROTOCOL_TEST_PROTOCOL .
<i>AgentHandle</i>	The handle of the agent that is opening the protocol interface specified by <i>Protocol</i> and <i>Interface</i> . For agents that follow the <i>UEFI Driver Model</i> , this parameter is the handle that contains the EFI_DRIVER_BINDING_PROTOCOL instance that is produced by the <i>UEFI driver</i> that is opening the protocol interface. For <i>UEFI applications</i> , this is the image handle of the <i>UEFI application</i> that is opening the protocol interface. For applications that use HandleProtocol() to open a protocol interface, this parameter is the image handle of the <i>EFI firmware</i> .
<i>ControllerHandle</i>	If the agent that is opening a protocol is a driver that follows the <i>UEFI Driver Model</i> , then this parameter is the controller handle that requires the protocol interface. If the agent does not follow the <i>UEFI Driver Model</i> , then this parameter is optional and may be NULL .
<i>Attributes</i>	The open mode of the protocol interface specified by <i>Handle</i> and <i>Protocol</i> . See "Related Definitions" for the list of legal attributes.

Description

This function opens a protocol interface on the handle specified by *Handle* for the protocol specified by *Protocol*. The first three parameters are the same as [HandleProtocol\(\)](#). The only difference is that the agent that is opening a protocol interface is tracked in an EFI's internal handle database. The tracking is used by the *UEFI Driver Model*, and also used to determine if it is safe to uninstall or reinstall a protocol interface.

The agent that is opening the protocol interface is specified by *AgentHandle*, *ControllerHandle*, and *Attributes*. If the protocol interface can be opened, then *AgentHandle*, *ControllerHandle*, and *Attributes* are added to the list of agents that are consuming the protocol interface specified by *Handle* and *Protocol*. In addition, the protocol interface is returned in *Interface*, and **EFI_SUCCESS** is returned. If *Attributes* is **TEST_PROTOCOL**, then *Interface* is optional, and can be **NULL**.

There are a number of reasons that this function call can return an error. If an error is returned, then *AgentHandle*, *ControllerHandle*, and *Attributes* are not added to the list of agents consuming the protocol interface specified by *Handle* and *Protocol*, and *Interface* is returned unmodified. The following is the list of conditions that must be checked before this function can return **EFI_SUCCESS**.

If *Protocol* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *Interface* is **NULL** and *Attributes* is not **TEST_PROTOCOL**, then **EFI_INVALID_PARAMETER** is returned.

If *Handle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned.

If *Handle* does not support *Protocol*, then **EFI_UNSUPPORTED** is returned.

If *Attributes* is not a legal value, then **EFI_INVALID_PARAMETER** is returned. The legal values are listed in “Related Definitions.”

If *Attributes* is **BY_CHILD_CONTROLLER**, **BY_DRIVER**, **EXCLUSIVE**, or **BY_DRIVER|EXCLUSIVE**, and *AgentHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned.

If *Attributes* is **BY_CHILD_CONTROLLER**, **BY_DRIVER**, or **BY_DRIVER|EXCLUSIVE**, and *ControllerHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned.

If *Attributes* is **BY_CHILD_CONTROLLER** and *Handle* is identical to *ControllerHandle*, then **EFI_INVALID_PARAMETER** is returned.

If *Attributes* is **BY_DRIVER**, **BY_DRIVER|EXCLUSIVE**, or **EXCLUSIVE**, and there are any items on the open list of the protocol interface with an attribute of **EXCLUSIVE** or **BY_DRIVER|EXCLUSIVE**, then **EFI_ACCESS_DENIED** is returned.

If *Attributes* is **BY_DRIVER**, and there are any items on the open list of the protocol interface with an attribute of **BY_DRIVER**, and *AgentHandle* is the same agent handle in the open list item, then **EFI_ALREADY_STARTED** is returned.

If *Attributes* is **BY_DRIVER**, and there are any items on the open list of the protocol interface with an attribute of **BY_DRIVER**, and *AgentHandle* is different than the agent handle in the open list item, then **EFI_ACCESS_DENIED** is returned.

If *Attributes* is **BY_DRIVER|EXCLUSIVE**, and there are any items on the open list of the protocol interface with an attribute of **BY_DRIVER|EXCLUSIVE**, and *AgentHandle* is the same agent handle in the open list item, then **EFI_ALREADY_STARTED** is returned.

If *Attributes* is **BY_DRIVER|EXCLUSIVE**, and there are any items on the open list of the protocol interface with an attribute of **BY_DRIVER|EXCLUSIVE**, and *AgentHandle* is different than the agent handle in the open list item, then **EFI_ACCESS_DENIED** is returned.

If *Attributes* is **BY_DRIVER|EXCLUSIVE** or **EXCLUSIVE**, and there is an item on the open list of the protocol interface with an attribute of **BY_DRIVER**, then the boot service [DisconnectController\(\)](#) is called for the driver on the open list. If there is an item in the open list of the protocol interface with an attribute of **BY_DRIVER** remaining after the [DisconnectController\(\)](#) call has been made, **EFI_ACCESS_DENIED** is returned.

Related Definitions

```
#define EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL    0x00000001
#define EFI_OPEN_PROTOCOL_GET_PROTOCOL         0x00000002
#define EFI_OPEN_PROTOCOL_TEST_PROTOCOL        0x00000004
#define EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER  0x00000008
#define EFI_OPEN_PROTOCOL_BY_DRIVER           0x00000010
#define EFI_OPEN_PROTOCOL_EXCLUSIVE           0x00000020
```

The following is the list of legal values for the *Attributes* parameter, and how each value is used.

- BY_HANDLE_PROTOCOL** Used in the implementation of [HandleProtocol\(\)](#). Since [OpenProtocol\(\)](#) performs the same function as [HandleProtocol\(\)](#) with additional functionality, [HandleProtocol\(\)](#) can simply call [OpenProtocol\(\)](#) with this *Attributes* value.
- GET_PROTOCOL** Used by a driver to get a protocol interface from a handle. Care must be taken when using this open mode because the driver that opens a protocol interface in this manner will not be informed if the protocol interface is uninstalled or reinstalled. The caller is also not required to close the protocol interface with [CloseProtocol\(\)](#).
- TEST_PROTOCOL** Used by a driver to test for the existence of a protocol interface on a handle. *Interface* is optional for this attribute value, so it is ignored, and the caller should only use the return status code. The caller is also not required to close the protocol interface with [CloseProtocol\(\)](#).
- BY_CHILD_CONTROLLER** Used by bus drivers to show that a protocol interface is being used by one of the child controllers of a bus. This information is used by the boot service [ConnectController\(\)](#) to recursively connect all child controllers and by the boot service [DisconnectController\(\)](#) to get the list of child controllers that a bus driver created.

- BY_DRIVER** Used by a driver to gain access to a protocol interface. When this mode is used, the driver's **Stop()** function will be called by **DisconnectController()** if the protocol interface is reinstalled or uninstalled. Once a protocol interface is opened by a driver with this attribute, no other drivers will be allowed to open the same protocol interface with the **BY_DRIVER** attribute.
- BY_DRIVER|EXCLUSIVE** Used by a driver to gain exclusive access to a protocol interface. If any other drivers have the protocol interface opened with an attribute of **BY_DRIVER**, then an attempt will be made to remove them with **DisconnectController()**.
- EXCLUSIVE** Used by applications to gain exclusive access to a protocol interface. If any drivers have the protocol interface opened with an attribute of **BY_DRIVER**, then an attempt will be made to remove them by calling the driver's **Stop()** function.

Status Codes Returned

EFI_SUCCESS	An item was added to the open list for the protocol interface, and the protocol interface was returned in <i>Interface</i> .
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .
EFI_INVALID_PARAMETER	<i>Interface</i> is NULL , and <i>Attributes</i> is not TEST_PROTOCOL .
EFI_INVALID_PARAMETER	<i>Handle</i> is not a valid EFI_HANDLE .
EFI_UNSUPPORTED	<i>Handle</i> does not support <i>Protocol</i> .
EFI_INVALID_PARAMETER	<i>Attributes</i> is not a legal value.
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_CHILD_CONTROLLER and <i>AgentHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_DRIVER and <i>AgentHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_DRIVER EXCLUSIVE and <i>AgentHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is EXCLUSIVE and <i>AgentHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_CHILD_CONTROLLER and <i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_DRIVER and <i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_DRIVER EXCLUSIVE and <i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Attributes</i> is BY_CHILD_CONTROLLER and <i>Handle</i> is identical to <i>ControllerHandle</i> .

EFI_ACCESS_DENIED	<i>Attributes</i> is BY_DRIVER and there is an item on the open list with an attribute of BY_DRIVER EXCLUSIVE or EXCLUSIVE .
EFI_ACCESS_DENIED	<i>Attributes</i> is BY_DRIVER EXCLUSIVE and there is an item on the open list with an attribute of EXCLUSIVE .
EFI_ACCESS_DENIED	<i>Attributes</i> is EXCLUSIVE and there is an item on the open list with an attribute of BY_DRIVER EXCLUSIVE or EXCLUSIVE .
EFI_ALREADY_STARTED	<i>Attributes</i> is BY_DRIVER and there is an item on the open list with an attribute of BY_DRIVER whose agent handle is the same as <i>AgentHandle</i> .
EFI_ACCESS_DENIED	<i>Attributes</i> is BY_DRIVER and there is an item on the open list with an attribute of BY_DRIVER whose agent handle is different than <i>AgentHandle</i> .
EFI_ALREADY_STARTED	<i>Attributes</i> is BY_DRIVER EXCLUSIVE and there is an item on the open list with an attribute of BY_DRIVER EXCLUSIVE whose agent handle is the same as <i>AgentHandle</i> .
EFI_ACCESS_DENIED	<i>Attributes</i> is BY_DRIVER EXCLUSIVE and there is an item on the open list with an attribute of BY_DRIVER EXCLUSIVE whose agent handle is different than <i>AgentHandle</i> .
EFI_ACCESS_DENIED	<i>Attributes</i> is BY_DRIVER EXCLUSIVE or EXCLUSIVE and there are items in the open list with an attribute of BY_DRIVER that could not be removed when DisconnectController() was called for that open item.

Examples

```

EFI_BOOT_SERVICES_TABLE    *gBS;
EFI_HANDLE                 ImageHandle;
EFI_DRIVER_BINDING_PROTOCOL *This;
IN EFI_HANDLE              ControllerHandle,
extern EFI_GUID            gEfiXyzIoProtocol;
EFI_XYZ_IO_PROTOCOL        *XyzIo;
EFI_STATUS                 Status;

//
// EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL example
//   Retrieves the XYZ I/O Protocol instance from ControllerHandle
//   The application that is opening the protocol is identified by ImageHandle
//   Possible return status codes:
//     EFI_SUCCESS           : The protocol was opened and returned in XyzIo
//     EFI_UNSUPPORTED      : The protocol is not present on ControllerHandle
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    &XyzIo,
    ImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL
);

```

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```
//
// EFI_OPEN_PROTOCOL_GET_PROTOCOL example
// Retrieves the XYZ I/O Protocol instance from ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
// Possible return status codes:
//   EFI_SUCCESS      : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED  : The protocol is not present on ControllerHandle
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    &XyzIo,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);

//
// EFI_OPEN_PROTOCOL_TEST_PROTOCOL example
// Tests to see if the XYZ I/O Protocol is present on ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
//   EFI_SUCCESS      : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED  : The protocol is not present on ControllerHandle
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    NULL,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_TEST_PROTOCOL
);

//
// EFI_OPEN_PROTOCOL_BY_DRIVER example
// Opens the XYZ I/O Protocol on ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
// Possible return status codes:
//   EFI_SUCCESS      : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED  : The protocol is not present on ControllerHandle
//   EFI_ALREADY_STARTED : The protocol is already opened by the driver
//   EFI_ACCESS_DENIED : The protocol is managed by a different driver
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    &XyzIo,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_BY_DRIVER
);
```

```

//
// EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE example
// Opens the XYZ I/O Protocol on ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
// Possible return status codes:
//   EFI_SUCCESS      : The protocol was opened and returned in XyzIo. If /
//                     a different driver had the XYZ I/O Protocol opened
//                     BY_DRIVER, then that driver was disconnected to
//                     allow this driver to open the XYZ I/O Protocol.
//   EFI_UNSUPPORTED  : The protocol is not present on ControllerHandle
//   EFI_ALREADY_STARTED : The protocol is already opened by the driver
//   EFI_ACCESS_DENIED  : The protocol is managed by a different driver that /
//                       already has the protocol opened with an EXCLUSIVE //
attribute.
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    &XyzIo,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE
);

```

CloseProtocol()

Summary

Closes a protocol on a handle that was opened using [OpenProtocol\(\)](#).

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_CLOSE_PROTOCOL) (
    IN EFI_HANDLE          Handle,
    IN EFI_GUID            *Protocol,
    IN EFI_HANDLE          AgentHandle,
    IN EFI_HANDLE          ControllerHandle
);
```

Parameters

<i>Handle</i>	The handle for the protocol interface that was previously opened with OpenProtocol() , and is now being closed.
<i>Protocol</i>	The published unique identifier of the protocol. It is the caller's responsibility to pass in a valid GUID. See "Wired For Management Baseline" for a description of valid GUID values.
<i>AgentHandle</i>	The handle of the agent that is closing the protocol interface. For agents that follow the <i>UEFI Driver Model</i> , this parameter is the handle that contains the EFI_DRIVER_BINDING_PROTOCOL instance that is produced by the <i>UEFI driver</i> that is opening the protocol interface. For <i>UEFI applications</i> , this is the image handle of the <i>UEFI application</i> . For applications that used HandleProtocol() to open the protocol interface, this will be the image handle of the <i>EFI firmware</i> .
<i>ControllerHandle</i>	If the agent that opened a protocol is a driver that follows the <i>UEFI Driver Model</i> , then this parameter is the controller handle that required the protocol interface. If the agent does not follow the <i>UEFI Driver Model</i> , then this parameter is optional and may be NULL .

Description

This function updates the handle database to show that the protocol instance specified by *Handle* and *Protocol* is no longer required by the agent and controller specified *AgentHandle* and *ControllerHandle*.

If *Handle* or *AgentHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. If *ControllerHandle* is not **NULL**, and *ControllerHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. If *Protocol* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If the interface specified by *Protocol* is not supported by the handle specified by *Handle*, then **EFI_NOT_FOUND** is returned.

If the interface specified by *Protocol* is supported by the handle specified by *Handle*, then a check is made to see if the protocol instance specified by *Protocol* and *Handle* was opened by *AgentHandle* and *ControllerHandle* with `OpenProtocol()`. If the protocol instance was not opened by *AgentHandle* and *ControllerHandle*, then **EFI_NOT_FOUND** is returned. If the protocol instance was opened by *AgentHandle* and *ControllerHandle*, then all of those references are removed from the handle database, and **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The protocol instance was closed.
EFI_INVALID_PARAMETER	<i>Handle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>AgentHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not NULL and <i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Protocol</i> is NULL .
EFI_NOT_FOUND	<i>Handle</i> does not support the protocol specified by <i>Protocol</i> .
EFI_NOT_FOUND	The protocol interface specified by <i>Handle</i> and <i>Protocol</i> is not currently open by <i>AgentHandle</i> and <i>ControllerHandle</i> .

Examples

```

EFI_BOOT_SERVICES_TABLE    *gBS;
EFI_HANDLE                 ImageHandle;
EFI_DRIVER_BINDING_PROTOCOL *This;
IN EFI_HANDLE              ControllerHandle,
extern EFI_GUID            gEfiXyzIoProtocol;
EFI_STATUS                 Status;

//
// Close the XYZ I/O Protocol that was opened on behalf of ControllerHandle
//
Status = gBS->CloseProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    This->DriverBindingHandle,
    ControllerHandle
);

//
// Close the XYZ I/O Protocol that was opened with BY_HANDLE_PROTOCOL
//
Status = gBS->CloseProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    ImageHandle,
    NULL
);

```

OpenProtocolInformation()

Summary

Retrieves the list of agents that currently have a protocol interface opened.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_OPEN_PROTOCOL_INFORMATION) (
    IN EFI_HANDLE                Handle,
    IN EFI_GUID                  *Protocol,
    OUT EFI_OPEN_PROTOCOL_INFORMATION_ENTRY **EntryBuffer,
    OUT UINTN                    *EntryCount
);
```

Parameters

<i>Handle</i>	The handle for the protocol interface that is being queried.
<i>Protocol</i>	The published unique identifier of the protocol. It is the caller's responsibility to pass in a valid GUID. See "Wired For Management Baseline" for a description of valid GUID values.
<i>EntryBuffer</i>	A pointer to a buffer of open protocol information in the form of EFI_OPEN_PROTOCOL_INFORMATION_ENTRY structures. See "Related Definitions" for the declaration of this type. The buffer is allocated by this service, and it is the caller's responsibility to free this buffer when the caller no longer requires the buffer's contents.
<i>EntryCount</i>	A pointer to the number of entries in <i>EntryBuffer</i> .

Related Definitions

```
typedef struct {
    EFI_HANDLE                AgentHandle;
    EFI_HANDLE                ControllerHandle;
    UINT32                    Attributes;
    UINT32                    OpenCount;
} EFI_OPEN_PROTOCOL_INFORMATION_ENTRY;
```

Description

This function allocates and returns a buffer of **EFI_OPEN_PROTOCOL_INFORMATION_ENTRY** structures. The buffer is returned in *EntryBuffer*, and the number of entries is returned in *EntryCount*.

If the interface specified by *Protocol* is not supported by the handle specified by *Handle*, then **EFI_NOT_FOUND** is returned.

If the interface specified by *Protocol* is supported by the handle specified by *Handle*, then *EntryBuffer* is allocated with the boot service [AllocatePool\(\)](#), and *EntryCount* is set to the number of entries in *EntryBuffer*. Each entry of *EntryBuffer* is filled in with the image handle, controller handle, and attributes that were passed to [OpenProtocol\(\)](#) when the protocol interface was opened. The field **OpenCount** shows the number of times that the protocol interface has been opened by the agent specified by **ImageHandle**, **ControllerHandle**, and **Attributes**. After the contents of *EntryBuffer* have been filled in, **EFI_SUCCESS** is returned. It is the caller's responsibility to call [FreePool\(\)](#) on *EntryBuffer* when the caller no longer required the contents of *EntryBuffer*.

If there are not enough resources available to allocate *EntryBuffer*, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The open protocol information was returned in <i>EntryBuffer</i> , and the number of entries was returned <i>EntryCount</i> .
EFI_NOT_FOUND	<i>Handle</i> does not support the protocol specified by <i>Protocol</i> .
EFI_OUT_OF_RESOURCES	There are not enough resources available to allocate <i>EntryBuffer</i> .

Examples

See example in the [LocateHandleBuffer\(\)](#) function description for an example on how [LocateHandleBuffer\(\)](#), [ProtocolsPerHandle\(\)](#), [OpenProtocol\(\)](#), and [OpenProtocolInformation\(\)](#) can be used to traverse the entire handle database.

ConnectController()

Summary

Connects one or more drivers to a controller.

Prototype

```
typedef
EFI_STATUS
ConnectController (
    IN EFI_HANDLE           ControllerHandle,
    IN EFI_HANDLE           *DriverImageHandle    OPTIONAL,
    IN EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath  OPTIONAL,
    IN BOOLEAN              Recursive
);
```

Parameters

- ControllerHandle* The handle of the controller to which driver(s) are to be connected.
- DriverImageHandle* A pointer to an ordered list handles that support the **EFI_DRIVER_BINDING_PROTOCOL**. The list is terminated by a **NULL** handle value. These handles are candidates for the Driver Binding Protocol(s) that will manage the controller specified by *ControllerHandle*. This is an optional parameter that may be **NULL**. This parameter is typically used to debug new drivers.
- RemainingDevicePath* A pointer to the device path that specifies a child of the controller specified by *ControllerHandle*. This is an optional parameter that may be **NULL**. If it is **NULL**, then handles for all the children of *ControllerHandle* will be created. This parameter is passed unchanged to the [Supported\(\)](#) and [Start\(\)](#) services of the **EFI_DRIVER_BINDING_PROTOCOL** attached to *ControllerHandle*.
- Recursive* If **TRUE**, then **ConnectController()** is called recursively until the entire tree of controllers below the controller specified by *ControllerHandle* have been created. If **FALSE**, then the tree of controllers is only expanded one level.

Description

This function connects one or more drivers to the controller specified by *ControllerHandle*. If *ControllerHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. If there are no **EFI_DRIVER_BINDING_PROTOCOL** instances present in the system, then return **EFI_NOT_FOUND**. If there are not enough resources available to complete this function, then **EFI_OUT_OF_RESOURCES** is returned.

If *Recursive* is **FALSE**, then this function returns after all drivers have been connected to *ControllerHandle*. If *Recursive* is **TRUE**, then **ConnectController()** is called recursively on all of the child controllers of *ControllerHandle*. The child controllers can be identified by searching the handle database for all the controllers that have opened *ControllerHandle* with an attribute of **EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER**.

This function uses four precedence rules when deciding the order that drivers are tested against controllers. These four rules from highest precedence to lowest precedence are as follows:

1. **Context Override** : *DriverImageHandle* is an ordered list of handles that support the **EFI_DRIVER_BINDING_PROTOCOL**. The highest priority image handle is the first element of the list, and the lowest priority image handle is the last element of the list. The list is terminated with a **NULL** image handle.
2. **Platform Driver Override** : If an **EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL** instance is present in the system, then the **GetDriver()** service of this protocol is used to retrieve an ordered list of image handles for *ControllerHandle*. The first image handle returned from **GetDriver()** has the highest precedence, and the last image handle returned from **GetDriver()** has the lowest precedence. The ordered list is terminated when **GetDriver()** returns **EFI_NOT_FOUND**. It is legal for no image handles to be returned by **GetDriver()**. There can be at most a single instance in the system of the **EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL**. If there is more than one, then the system behavior is not deterministic.
3. **Bus Specific Driver Override** : If there is an instance of the **EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL** attached to *ControllerHandle*, then the **GetDriver()** service of this protocol is used to retrieve an ordered list of image handles for *ControllerHandle*. The first image handle returned from **GetDriver()** has the highest precedence, and the last image handle returned from **GetDriver()** has the lowest precedence. The ordered list is terminated when **GetDriver()** returns **EFI_NOT_FOUND**. It is legal for no image handles to be returned by **GetDriver()**.
4. **Driver Binding Search** : The list of available driver image handles can be found by using the boot service **LocateHandle()** with a *SearchType* of *ByProtocol* for the GUID of the **EFI_DRIVER_BINDING_PROTOCOL**. From this list, the image handles found in rules (1), (2), and (3) above are removed. The remaining image handles are sorted from highest to lowest based on the *Version* field of the **EFI_DRIVER_BINDING_PROTOCOL** instance associated with each image handle.

Each of the four groups of image handles listed above is tested against *ControllerHandle* in order by using the **EFI_DRIVER_BINDING_PROTOCOL** service **Supported()**. *RemainingDevicePath* is passed into **Supported()** unmodified. The first image handle whose **Supported()** service returns **EFI_SUCCESS** is marked so the image handle will not be tried again during this call to **ConnectController()**. Then, the **Start()** service of the **EFI_DRIVER_BINDING_PROTOCOL** is called for *ControllerHandle*. Once again, *RemainingDevicePath* is passed in unmodified. Every time **Supported()** returns **EFI_SUCCESS**, the search for drivers restarts with the highest precedence image handle. This process is repeated until no image handles pass the **Supported()** check.

If at least one image handle returned **EFI_SUCCESS** from its **Start()** service, then **EFI_SUCCESS** is returned.

If no image handles returned **EFI_SUCCESS** from their [Start\(\)](#) service then **EFI_NOT_FOUND** is returned unless *RemainingDevicePath* is not **NULL**, and *RemainingDevicePath* is an End Node. In this special case, **EFI_SUCCESS** is returned because it is not an error to fail to start a child controller that is specified by an End Device Path Node.

Status Codes Returned

EFI_SUCCESS	One or more drivers were connected to <i>ControllerHandle</i> .
EFI_SUCCESS	No drivers were connected to <i>ControllerHandle</i> , but <i>RemainingDevicePath</i> is not NULL , and it is an End Device Path Node.
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_NOT_FOUND	There are no EFI_DRIVER_BINDING_PROTOCOL instances present in the system.
EFI_NOT_FOUND	No drivers were connected to <i>ControllerHandle</i> .

Examples

```
//
// Connect All Handles Example
// The following example recursively connects all controllers in a platform.
//

EFI_STATUS                Status;
EFI_BOOT_SERVICES_TABLE  *gBS;
UINTN                    HandleCount;
EFI_HANDLE                *HandleBuffer;
UINTN                    HandleIndex;

//
// Retrieve the list of all handles from the handle database
//
Status = gBS->LocateHandleBuffer (
    AllHandles,
    NULL,
    NULL,
    &HandleCount,
    &HandleBuffer
);
if (!EFI_ERROR (Status)) {
    for (HandleIndex = 0; HandleIndex < HandleCount; HandleIndex++) {
        Status = gBS->ConnectController (
            HandleBuffer[HandleIndex],
            NULL,
            NULL,
            TRUE
        );
    }
    gBS->FreePool (HandleBuffer);
}

//
// Connect Device Path Example
// The following example walks the device path nodes of a device path, and
// connects only the drivers required to force a handle with that device path
```

```

// to be present in the handle database. This algorithm guarantees that
// only the minimum number of devices and drivers are initialized.
//

EFI_STATUS          Status;
EFI_DEVICE_PATH_PROTOCOL *DevicePath;
EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath;
EFI_HANDLE          Handle;

do {
    //
    // Find the handle that best matches the Device Path. If it is only a
    // partial match the remaining part of the device path is returned in
    // RemainingDevicePath.
    //
    RemainingDevicePath = DevicePath;
    Status = gBS->LocateDevicePath (
        &gEfiDevicePathProtocolGuid,
        &RemainingDevicePath,
        &Handle
    );
    if (EFI_ERROR(Status)) {
        return EFI_NOT_FOUND;
    }

    //
    // Connect all drivers that apply to Handle and RemainingDevicePath
    // If no drivers are connected Handle, then return EFI_NOT_FOUND
    // The Recursive flag is FALSE so only one level will be expanded.
    //
    Status = gBS->ConnectController (
        Handle,
        NULL,
        RemainingDevicePath,
        FALSE
    );
    if (EFI_ERROR(Status)) {
        return EFI_NOT_FOUND;
    }
} while (!IsDevicePathEnd (RemainingDevicePath));

//
// A handle with DevicePath exists in the handle database
//
return EFI_SUCCESS;

```

DisconnectController()

Summary

Disconnects one or more drivers from a controller.

Prototype

```
typedef
EFI_STATUS
DisconnectController (
    IN EFI_HANDLE  ControllerHandle,
    IN EFI_HANDLE  DriverImageHandle  OPTIONAL,
    IN EFI_HANDLE  ChildHandle        OPTIONAL
);
```

Parameters

<i>ControllerHandle</i>	The handle of the controller from which driver(s) are to be disconnected.
<i>DriverImageHandle</i>	The driver to disconnect from <i>ControllerHandle</i> . If <i>DriverImageHandle</i> is NULL , then all the drivers currently managing <i>ControllerHandle</i> are disconnected from <i>ControllerHandle</i> .
<i>ChildHandle</i>	The handle of the child to destroy. If <i>ChildHandle</i> is NULL , then all the children of <i>ControllerHandle</i> are destroyed before the drivers are disconnected from <i>ControllerHandle</i> .

Description

This function disconnects one or more drivers from the controller specified by *ControllerHandle*. If *DriverImageHandle* is **NULL**, then all of the drivers currently managing *ControllerHandle* are disconnected from *ControllerHandle*. If *DriverImageHandle* is not **NULL**, then only the driver specified by *DriverImageHandle* is disconnected from *ControllerHandle*. If *ChildHandle* is **NULL**, then all of the children of *ControllerHandle* are destroyed before the drivers are disconnected from *ControllerHandle*. If *ChildHandle* is not **NULL**, then only the child controller specified by *ChildHandle* is destroyed. If *ChildHandle* is the only child of *ControllerHandle*, then the driver specified by *DriverImageHandle* will be disconnected from *ControllerHandle*. A driver is disconnected from a controller by calling the **Stop()** service of the **EFI_DRIVER_BINDING_PROTOCOL**. The **EFI_DRIVER_BINDING_PROTOCOL** is on the driver image handle, and the handle of the controller is passed into the **Stop()** service. The list of drivers managing a controller, and the list of children for a specific controller can be retrieved from the handle database with the boot service [OpenProtocolInformation\(\)](#). If all the required drivers are disconnected from *ControllerHandle*, then **EFI_SUCCESS** is returned.

If *ControllerHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. If no drivers are managing *ControllerHandle*, then **EFI_SUCCESS** is returned. If *DriverImageHandle* is not **NULL**, and *DriverImageHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. If *DriverImageHandle* is not **NULL**, and

DriverImageHandle is not currently managing *ControllerHandle*, then **EFI_SUCCESS** is returned. If *ChildHandle* is not **NULL**, and *ChildHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. If there are not enough resources available to disconnect drivers from *ControllerHandle*, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	One or more drivers were disconnected from the controller.
EFI_SUCCESS	On entry, no drivers are managing <i>ControllerHandle</i> .
EFI_SUCCESS	<i>DriverImageHandle</i> is not NULL , and on entry <i>DriverImageHandle</i> is not managing <i>ControllerHandle</i> .
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>DriverImageHandle</i> is not NULL , and it is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>ChildHandle</i> is not NULL , and it is not a valid EFI_HANDLE .
EFI_OUT_OF_RESOURCES	There are not enough resources available to disconnect any drivers from <i>ControllerHandle</i> .
EFI_DEVICE_ERROR	The controller could not be disconnected because of a device error.
EFI_INVALID_PARAMETER	<i>DriverImageHandle</i> does not support the EFI_DRIVER_BINDING_PROTOCOL .

Examples

```
//
// Disconnect All Handles Example
// The following example recursively disconnects all drivers from all
// controllers in a platform.
//

EFI_STATUS          Status;
EFI_BOOT_SERVICES_TABLE *gBS;
UINTN               HandleCount;
EFI_HANDLE          *HandleBuffer;
UINTN               HandleIndex;

//
// Retrieve the list of all handles from the handle database
//
Status = gBS->LocateHandleBuffer (
    AllHandles,
    NULL,
    NULL,
    &HandleCount,
    &HandleBuffer
);
if (!EFI_ERROR (Status)) {
    for (HandleIndex = 0; HandleIndex < HandleCount; HandleIndex++) {
        Status = gBS->DisconnectController (
            HandleBuffer[HandleIndex],
            NULL,
            NULL
        );
    }
}
```

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```
        );  
    }  
    gBS->FreePool(HandleBuffer);
```

ProtocolsPerHandle()

Summary

Retrieves the list of protocol interface GUIDs that are installed on a handle in a buffer allocated from pool.

Prototype

```
typedef
EFI_STATUS
ProtocolsPerHandle (
    IN EFI_HANDLE Handle,
    OUT EFI_GUID ***ProtocolBuffer,
    OUT UINTN *ProtocolBufferCount
);
```

Parameters

<i>Handle</i>	The handle from which to retrieve the list of protocol interface GUIDs.
<i>ProtocolBuffer</i>	A pointer to the list of protocol interface GUID pointers that are installed on <i>Handle</i> . This buffer is allocated with a call to the Boot Service AllocatePool() . It is the caller's responsibility to call the Boot Service FreePool() when the caller no longer requires the contents of <i>ProtocolBuffer</i> .
<i>ProtocolBufferCount</i>	A pointer to the number of GUID pointers present in <i>ProtocolBuffer</i> .

Description

The **ProtocolsPerHandle()** function retrieves the list of protocol interface GUIDs that are installed on *Handle*. The list is returned in *ProtocolBuffer*, and the number of GUID pointers in *ProtocolBuffer* is returned in *ProtocolBufferCount*.

If *Handle* is **NULL** or *Handle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned.

If *ProtocolBuffer* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *ProtocolBufferCount* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If there are not enough resources available to allocate *ProtocolBuffer*, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The list of protocol interface GUIDs installed on <i>Handle</i> was returned in <i>ProtocolBuffer</i> . The number of protocol interface GUIDs was returned in <i>ProtocolBufferCount</i> .
EFI_INVALID_PARAMETER	<i>Handle</i> is NULL .
EFI_INVALID_PARAMETER	<i>Handle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>ProtocolBuffer</i> is NULL .
EFI_INVALID_PARAMETER	<i>ProtocolBufferCount</i> is NULL .
EFI_OUT_OF_RESOURCES	There is not enough pool memory to store the results.

Examples

See example in the [LocateHandleBuffer\(\)](#) function description for an example on how [LocateHandleBuffer\(\)](#), [ProtocolsPerHandle\(\)](#), [OpenProtocol\(\)](#), and [OpenProtocolInformation\(\)](#) can be used to traverse the entire handle database.

LocateHandleBuffer()

Summary

Returns an array of handles that support the requested protocol in a buffer allocated from pool.

Prototype

```
typedef
EFI_STATUS
LocateHandleBuffer (
    IN EFI_LOCATE_SEARCH_TYPE SearchType,
    IN EFI_GUID                *Protocol OPTIONAL,
    IN VOID                    *SearchKey OPTIONAL,
    IN OUT UINTN               *NoHandles,
    OUT EFI_HANDLE             **Buffer
);
```

Parameters

<i>SearchType</i>	Specifies which handle(s) are to be returned.
<i>Protocol</i>	Provides the protocol to search by. This parameter is only valid for a <i>SearchType</i> of ByProtocol .
<i>SearchKey</i>	Supplies the search key depending on the <i>SearchType</i> .
<i>NoHandles</i>	The number of handles returned in <i>Buffer</i> .
<i>Buffer</i>	A pointer to the buffer to return the requested array of handles that support <i>Protocol</i> . This buffer is allocated with a call to the Boot Service AllocatePool() . It is the caller's responsibility to call the Boot Service FreePool() when the caller no longer requires the contents of <i>Buffer</i> .

Description

The **LocateHandleBuffer()** function returns one or more handles that match the *SearchType* request. *Buffer* is allocated from pool, and the number of entries in *Buffer* is returned in *NoHandles*. Each *SearchType* is described below:

AllHandles	<i>Protocol</i> and <i>SearchKey</i> are ignored and the function returns an array of every handle in the system.
ByRegisterNotify	<i>SearchKey</i> supplies the Registration returned by RegisterProtocolNotify() . The function returns the next handle that is new for the Registration. Only one handle is returned at a time, and the caller must loop until no more handles are returned. <i>Protocol</i> is ignored for this search type.
ByProtocol	All handles that support <i>Protocol</i> are returned. <i>SearchKey</i> is ignored for this search type.

If *NoHandles* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *Buffer* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If there are no handles in the handle database that match the search criteria, then **EFI_NOT_FOUND** is returned.

If there are not enough resources available to allocate *Buffer*, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The array of handles was returned in <i>Buffer</i> , and the number of handles in <i>Buffer</i> was returned in <i>NoHandles</i> .
EFI_INVALID_PARAMETER	<i>NoHandles</i> is NULL
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL
EFI_NOT_FOUND	No handles match the search.
EFI_OUT_OF_RESOURCES	There is not enough pool memory to store the matching results.

Examples

```

//
// The following example traverses the entire handle database. First all of
// the handles in the handle database are retrieved by using
// LocateHandleBuffer(). Then it uses ProtocolsPerHandle() to retrieve the
// list of protocol GUIDs attached to each handle. Then it uses OpenProtocol()
// to get the protocol instance associated with each protocol GUID on the
// handle. Finally, it uses OpenProtocolInformation() to retrieve the list of
// agents that have opened the protocol on the handle. The caller of these
// functions must make sure that they free the return buffers with FreePool()
// when they are done.
//

EFI_STATUS Status;
EFI_BOOT_SERVICES_TABLE *gBS;
EFI_HANDLE ImageHandle;
UINTN HandleCount;
EFI_HANDLE *HandleBuffer;
UINTN HandleIndex;
EFI_GUID **ProtocolGuidArray;
UINTN ArrayCount;
UINTN ProtocolIndex;
EFI_OPEN_PROTOCOL_INFORMATION_ENTRY *OpenInfo;
UINTN OpenInfoCount;
UINTN OpenInfoIndex;

//
// Retrieve the list of all handles from the handle database
//
Status = gBS->LocateHandleBuffer (
    AllHandles,
    NULL,
    NULL,
    &HandleCount,
    &HandleBuffer
);
if (!EFI_ERROR (Status)) {
    for (HandleIndex = 0; HandleIndex < HandleCount; HandleIndex++) {
        //
        // Retrieve the list of all the protocols on each handle
    }
}

```

```

//
Status = gBS->ProtocolsPerHandle (
    HandleBuffer[HandleIndex],
    &ProtocolGuidArray,
    &ArrayCount
);
if (!EFI_ERROR (Status)) {
    for (ProtocolIndex = 0; ProtocolIndex < ArrayCount; ProtocolIndex++) {
        //
        // Retrieve the protocol instance for each protocol
        //
        Status = gBS->OpenProtocol (
            HandleBuffer[HandleIndex],
            ProtocolGuidArray[ProtocolIndex],
            &Instance,
            ImageHandle,
            NULL,
            EFI_OPEN_PROTOCOL_GET_PROTOCOL
        );

        //
        // Retrieve the list of agents that have opened each protocol
        //
        Status = gBS->OpenProtocolInformation (
            HandleBuffer[HandleIndex],
            ProtocolGuidArray[ProtocolIndex],
            &OpenInfo,
            &OpenInfoCount
        );
        if (!EFI_ERROR (Status)) {
            for (OpenInfoIndex=0;OpenInfoIndex<OpenInfoCount;OpenInfoIndex++) {
                //
                // HandleBuffer[HandleIndex] is the handle
                // ProtocolGuidArray[ProtocolIndex] is the protocol GUID
                // Instance is the protocol instance for the protocol
                // OpenInfo[OpenInfoIndex] is an agent that has opened a protocol
                //
            }
            if (OpenInfo != NULL) {
                gBS->FreePool (OpenInfo);
            }
        }
    }
    if (ProtocolGuidArray != NULL) {
        gBS->FreePool (ProtocolGuidArray);
    }
}
if (HandleBuffer != NULL) {
    gBS->FreePool (HandleBuffer);
}
}

```

LocateProtocol()

Summary

Returns the first protocol instance that matches the given protocol.

Prototype

```
typedef
EFI_STATUS
LocateProtocol (
    IN EFI_GUID    *Protocol,
    IN VOID        *Registration    OPTIONAL,
    OUT VOID       **Interface
);
```

Parameters

<i>Protocol</i>	Provides the protocol to search for.
<i>Registration</i>	Optional registration key returned from RegisterProtocolNotify() . If <i>Registration</i> is NULL , then it is ignored.
<i>Interface</i>	On return, a pointer to the first interface that matches <i>Protocol</i> and <i>Registration</i> .

Description

The **LocateProtocol()** function finds the first device handle that support *Protocol*, and returns a pointer to the protocol interface from that handle in *Interface*. If no protocol instances are found, then *Interface* is set to **NULL**.

If *Interface* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *Registration* is **NULL**, and there are no handles in the handle database that support *Protocol*, then **EFI_NOT_FOUND** is returned.

If *Registration* is not **NULL**, and there are no new handles for *Registration*, then **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	A protocol instance matching <i>Protocol</i> was found and returned in <i>Interface</i> .
EFI_INVALID_PARAMETER	<i>Interface</i> is NULL .
EFI_NOT_FOUND	No protocol instances were found that match <i>Protocol</i> and <i>Registration</i> .

InstallMultipleProtocolInterfaces()

Summary

Installs one or more protocol interfaces into the boot services environment.

Prototype

```
typedef
EFI_STATUS
InstallMultipleProtocolInterfaces (
    IN OUT EFI_HANDLE  *Handle,
    ...
);
```

Parameters

Handle The handle to install the new protocol interfaces on, or **NULL** if a new handle is to be allocated.

...A variable argument list containing pairs of protocol GUIDs and protocol interfaces.

Description

This function installs a set of protocol interfaces into the boot services environment. It removes arguments from the variable argument list in pairs. The first item is always a pointer to the protocol's GUID, and the second item is always a pointer to the protocol's interface. These pairs are used to call the boot service [InstallProtocolInterface\(\)](#) to add a protocol interface to *Handle*. If *Handle* is **NULL** on entry, then a new handle will be allocated. The pairs of arguments are removed in order from the variable argument list until a **NULL** protocol GUID value is found. If any errors are generated while the protocol interfaces are being installed, then all the protocols installed prior to the error will be uninstalled with the boot service [UninstallProtocolInterface\(\)](#) before the error is returned. The same GUID cannot be installed more than once onto the same handle.

It is illegal to have two handles in the handle database with identical device paths. This service performs a test to guarantee a duplicate device path is not inadvertently installed on two different handles. Before any protocol interfaces are installed onto *Handle*, the list of GUID/pointer pair parameters are searched to see if a Device Path Protocol instance is being installed. If a Device Path Protocol instance is going to be installed onto *Handle*, then a check is made to see if a handle is already present in the handle database with an identical Device Path Protocol instance. If an identical Device Path Protocol instance is already present in the handle database, then no protocols are installed onto *Handle*, and **EFI_ALREADY_STARTED** is returned.

Status Codes Returned

EFI_SUCCESS	All the protocol interfaces were installed.
EFI_ALREADY_STARTED	A Device Path Protocol instance was passed in that is already present in the handle database.
EFI_OUT_OF_RESOURCES	There was not enough memory in pool to install all the protocols.

UninstallMultipleProtocolInterfaces()

Summary

Removes one or more protocol interfaces into the boot services environment.

Prototype

```
typedef
EFI_STATUS
UninstallMultipleProtocolInterfaces (
    IN EFI_HANDLE  Handle,
    ...
);
```

Parameters

Handle The handle to remove the protocol interfaces from.

...A variable argument list containing pairs of protocol GUIDs and protocol interfaces.

Description

This function removes a set of protocol interfaces from the boot services environment. It removes arguments from the variable argument list in pairs. The first item is always a pointer to the protocol’s GUID, and the second item is always a pointer to the protocol’s interface. These pairs are used to call the boot service [UninstallProtocolInterface\(\)](#) to remove a protocol interface from *Handle*. The pairs of arguments are removed in order from the variable argument list until a **NULL** protocol GUID value is found. If all of the protocols are uninstalled from *Handle*, then **EFI_SUCCESS** is returned. If any errors are generated while the protocol interfaces are being uninstalled, then the protocols uninstalled prior to the error will be reinstalled with the boot service [InstallProtocolInterface\(\)](#) and the status code **EFI_INVALID_PARAMETER** is returned.

Status Codes Returned

EFI_SUCCESS	All the protocol interfaces were removed.
EFI_INVALID_PARAMETER	One of the protocol interfaces was not previously installed on <i>Handle</i> .

6.4 Image Services

Three types of images can be loaded: applications written to this specification, EFI Boot Services Drivers, and EFI Runtime Services Drivers. An OS Loader is a type of application. The most significant difference between these image types is the type of memory into which they are loaded by the firmware’s loader. [Table 24](#) summarizes the differences between images.

Table 24. Image Type Differences Summary

	UEFI Application	EFI Boot Services Driver	EFI Runtime Services Driver
Description	<p>A transient application that is loaded during boot services time. Applications written to this specification are either unloaded when they complete, or they take responsibility for the continued operation of the system via ExitBootServices(). The applications are loaded in sequential order by the boot manager, but one application may dynamically load another.</p>	<p>A program that is loaded into boot services memory and stays resident until boot services terminates.</p>	<p>A program that is loaded into runtime services memory and stays resident during runtime. The memory required for a Runtime Services Driver must be performed in a single memory allocation, and marked as EfiRuntimeServicesData. (Note that the memory only stays resident when booting an EFI-compatible operating system. Legacy operating systems will reuse the memory.)</p>
Loaded into memory type	EfiLoaderCode , EfiLoaderData	EfiBootServicesCode , EfiBootServicesData	EfiRuntimeServicesCode, EfiRuntimeServicesData
Default pool allocations from memory type	EfiLoaderData	EfiBootServicesData	EfiRuntimeServicesData
Exit behavior	When an application exits, firmware frees the memory used to hold its image.	When a boot services driver exits with an error code, firmware frees the memory used to hold its image. When a boot services driver's entry point completes with EFI_SUCCESS , the image is retained in memory.	When a runtime services driver exits with an error code, firmware frees the memory used to hold its image. When a runtime services driver's entry point completes with EFI_SUCCESS , the image is retained in memory.
Notes	This type of image would not install any protocol interfaces or handles.	This type of image would typically use InstallProtocolInterface() .	A runtime driver can only allocate runtime memory during boot services time. Due to the complexity of performing a virtual relocation for a runtime image, this driver type is discouraged unless it is absolutely required.

Most images are loaded by the boot manager. When an application or driver is installed, the installation procedure registers itself with the boot manager for loading. However, in some cases an application or driver may want to programmatically load and start another EFI image. This can be done with the [LoadImage \(\)](#) and [StartImage \(\)](#) interfaces. Drivers may only load applications during the driver's initialization entry point. [Table 25](#) lists the functions that make up Image Services.

Table 25. Image Functions

Name	Type	Description
LoadImage	Boot	Loads an EFI image into memory.
StartImage	Boot	Transfers control to a loaded image's entry point.
UnloadImage	Boot	Unloads an image.
EFI_IMAGE_ENTRY_POINT	Boot	Prototype of an EFI Image's entry point.
Exit	Boot	Exits the image's entry point.
ExitBootServices	Boot	Terminates boot services.

The Image boot services have been modified to take advantage of the information that is now being tracked with the [OpenProtocol \(\)](#) and [CloseProtocol \(\)](#) boot services. Since the usage of protocol interfaces is being tracked with these new boot services, it is now possible to automatically close protocol interfaces when an application or a driver is unloaded or exited.

LoadImage()

Summary

Loads an EFI image into memory.

Prototype

```
typedef
EFI_STATUS
LoadImage (
    IN BOOLEAN                BootPolicy,
    IN EFI_HANDLE             ParentImageHandle,
    IN EFI_DEVICE_PATH_PROTOCOL *FilePath,
    IN VOID                   *SourceBuffer OPTIONAL,
    IN UINTN                  SourceSize,
    OUT EFI_HANDLE            *ImageHandle
);
```

Parameters

<i>BootPolicy</i>	If TRUE , indicates that the request originates from the boot manager, and that the boot manager is attempting to load <i>FilePath</i> as a boot selection. Ignored if <i>SourceBuffer</i> is not NULL .
<i>ParentImageHandle</i>	The caller's image handle. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description. This field is used to initialize the <i>ParentHandle</i> field of the EFI LOADED IMAGE PROTOCOL for the image that is being loaded.
<i>FilePath</i>	The <i>DeviceHandle</i> specific file path from which the image is loaded. EFI_DEVICE_PATH_PROTOCOL is defined in Section 9.2 .
<i>SourceBuffer</i>	If not NULL , a pointer to the memory location containing a copy of the image to be loaded.
<i>SourceSize</i>	The size in bytes of <i>SourceBuffer</i> . Ignored if <i>SourceBuffer</i> is NULL .
<i>ImageHandle</i>	Pointer to the returned image handle that is created when the image is successfully loaded. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.

Related Definitions

```
#define EFI_HII_PACKAGE_LIST_PROTOCOL_GUID \
{ 0x6alee763, 0xd47a, 0x43b4, \
{ 0xaa, 0xbe, 0xef, 0x1d, 0xe2, 0xab, 0x56, 0xfc } };
```

```
typedef EFI_HII_PACKAGE_LIST_HEADER
*EFI_HII_PACKAGE_LIST_PROTOCOL;
```

Description

The **LoadImage()** function loads an EFI image into memory and returns a handle to the image. The image is loaded in one of two ways. If *SourceBuffer* is not **NULL**, the function is a memory-to-memory load in which *SourceBuffer* points to the image to be loaded and *SourceSize* indicates the image’s size in bytes. In this case, the caller has copied the image into *SourceBuffer* and can free the buffer once loading is complete.

If *SourceBuffer* is **NULL**, the function is a file copy operation that uses the [EFI SIMPLE FILE SYSTEM PROTOCOL](#) and then the [EFI FILE PROTOCOL](#) instance associated with the handle that most closely matches *FilePath* will be used. See the boot service description for more information on how the closest handle is located. In the case of [EFI SIMPLE FILE SYSTEM PROTOCOL](#), the path name from the File Path Media Device Path node(s) of *FilePath* are used. In the case of [EFI SIMPLE FILE SYSTEM PROTOCOL](#), the remaining device path nodes of *FilePath* and the *BootPolicy* flag is passed to the [EFI LOAD FILE PROTOCOL.LoadFile\(\)](#) function; the default image responsible for booting is loaded when the *FilePath* only indicates the device. For more information see the discussion of the Load File Protocol in [Section 12.1](#).

Once the image is loaded, firmware creates and returns an **EFI_HANDLE** that identifies the image and supports [EFI LOADED IMAGE PROTOCOL](#). The caller may fill in the image’s “load options” data, or add additional protocol support to the handle before passing control to the newly loaded image by calling [StartImage\(\)](#). Also, once the image is loaded, the caller either starts it by calling **StartImage()** or unloads it by calling [UnloadImage\(\)](#).

Once the image is loaded, **LoadImage()** installs [EFI_HII_PACKAGE_LIST_PROTOCOL](#) on the handle if the image contains a custom PE/COFF resource with the type 'HII'. The protocol's interface pointer points to the HII package list which is contained in the resource's data. The format of this is in [Section 27.3.1](#).

Status Codes Returned

EFI_SUCCESS	Image was loaded into memory correctly.
EFI_NOT_FOUND	Both <i>SourceBuffer</i> and <i>FilePath</i> are NULL .
EFI_INVALID_PARAMETER	One of the parameters has an invalid value.
EFI_INVALID_PARAMETER	<i>ImageHandle</i> is NULL .
EFI_INVALID_PARAMETER	<i>ParentImageHandle</i> is NULL .
EFI_INVALID_PARAMETER	<i>ParentImageHandle</i> is not a valid EFI_HANDLE .
EFI_UNSUPPORTED	The image type is not supported.
EFI_OUT_OF_RESOURCES	Image was not loaded due to insufficient resources.
EFI_LOAD_ERROR	Image was not loaded because the image format was corrupt or not understood.
EFI_DEVICE_ERROR	Image was not loaded because the device returned a read error.

StartImage()

Summary

Transfers control to a loaded image's entry point.

Prototype

```
typedef
EFI_STATUS
StartImage (
    IN EFI_HANDLE      ImageHandle,
    OUT UINTN          *ExitDataSize,
    OUT CHAR16         **ExitData OPTIONAL
);
```

Parameters

<i>ImageHandle</i>	Handle of image to be started. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.
<i>ExitDataSize</i>	Pointer to the size, in bytes, of <i>ExitData</i> . If <i>ExitData</i> is NULL, then this parameter is ignored and the contents of <i>ExitDataSize</i> are not modified.
<i>ExitData</i>	Pointer to a pointer to a data buffer that includes a Null-terminated Unicode string, optionally followed by additional binary data. The string is a description that the caller may use to further indicate the reason for the image's exit.

Description

The **StartImage()** function transfers control to the entry point of an image that was loaded by [LoadImage\(\)](#). The image may only be started one time.

Control returns from **StartImage()** when the loaded image's **EFI_IMAGE_ENTRY_POINT** returns or when the loaded image calls [Exit\(\)](#). When that call is made, the *ExitData* buffer and *ExitDataSize* from **Exit()** are passed back through the *ExitData* buffer and *ExitDataSize* in this function. The caller of this function is responsible for returning the *ExitData* buffer to the pool by calling [FreePool\(\)](#) when the buffer is no longer needed. Using **Exit()** is similar to returning from the image's **EFI_IMAGE_ENTRY_POINT** except that **Exit()** may also return additional *ExitData*. **Exit()** function description defines clean up procedure performed by the firmware once loaded image returns control.

EFI 1.10 Extension

To maintain compatibility with UEFI drivers that are written to the *EFI 1.02 Specification*, **StartImage()** must monitor the handle database before and after each image is started. If any handles are created or modified when an image is started, then [ConnectController\(\)](#) must be called with the *Recursive* parameter set to **TRUE** for each of the newly created or modified handles before **StartImage()** returns.

Status Codes Returned

EFI_INVALID_PARAMETER	<i>ImageHandle</i> is either an invalid image handle or the image has already been initialized with StartImage
Exit code from image	Exit code from image.

UnloadImage()

Summary

Unloads an image.

Prototype

```
typedef
EFI_STATUS
UnloadImage (
    IN EFI_HANDLE ImageHandle
);
```

Parameters

ImageHandle Handle that identifies the image to be unloaded.

Description

The **UnloadImage ()** function unloads a previously loaded image.

There are three possible scenarios. If the image has not been started, the function unloads the image and returns **EFI_SUCCESS**.

If the image has been started and has an **Unload ()** entry point, control is passed to that entry point. If the image's unload function returns **EFI_SUCCESS**, the image is unloaded; otherwise, the error returned by the image's unload function is returned to the caller. The image unload function is responsible for freeing all allocated memory and ensuring that there are no references to any freed memory, or to the image itself, before returning **EFI_SUCCESS**.

If the image has been started and does not have an **Unload ()** entry point, the function returns **EFI_UNSUPPORTED**.

EFI 1.10 Extension

All of the protocols that were opened by *ImageHandle* using the boot service [OpenProtocol \(\)](#) are automatically closed with the boot service [CloseProtocol \(\)](#). If all of the open protocols are closed, then **EFI_SUCCESS** is returned. If any call to **CloseProtocol ()** fails, then the error code from **CloseProtocol ()** is returned.

Status Codes Returned

EFI_SUCCESS	The image has been unloaded.
EFI_UNSUPPORTED	The image has been started, and does not support unload.
EFI_INVALID_PARAMETER	<i>ImageHandle</i> is not a valid image handle.
Exit code from Unload handler	Exit code from the image's unload function.

EFI_IMAGE_ENTRY_POINT

Summary

This is the declaration of an EFI image entry point. This can be the entry point to an application written to this specification, an EFI boot service driver, or an EFI runtime driver.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_IMAGE_ENTRY_POINT) (
    IN EFI_HANDLE          ImageHandle,
    IN EFI_SYSTEM_TABLE   *SystemTable
);
```

Parameters

<i>ImageHandle</i>	Handle that identifies the loaded image. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.
<i>SystemTable</i>	System Table for this image. Type EFI_SYSTEM_TABLE is defined in Section 4 .

Description

An image's entry point is of type **EFI_IMAGE_ENTRY_POINT**. After firmware loads an image into memory, control is passed to the image's entry point. The entry point is responsible for initializing the image. The image's *ImageHandle* is passed to the image. The *ImageHandle* provides the image with all the binding and data information it needs. This information is available through protocol interfaces. However, to access the protocol interfaces on *ImageHandle* requires access to boot services functions. Therefore, [LoadImage\(\)](#) passes to the **EFI_IMAGE_ENTRY_POINT** a *SystemTable* that is inherited from the current scope of [LoadImage\(\)](#).

All image handles support the [EFI LOADED IMAGE PROTOCOL](#). This protocol can be used to obtain information about the loaded image's state—for example, the device from which the image was loaded and the image's load options. In addition, the *ImageHandle* may support other protocols provided by the parent image.

If the image supports dynamic unloading, it must supply an unload function in the **EFI_LOADED_IMAGE_PROTOCOL** structure before returning control from its entry point.

In general, an image returns control from its initialization entry point by calling [Exit\(\)](#) or by returning control from its entry point. If the image returns control from its entry point, the firmware passes control to **Exit()** using the return code as the *ExitStatus* parameter to **Exit()**. See **Exit()** below for entry point exit conditions.

Exit()

Summary

Terminates a loaded EFI image and returns control to boot services.

Prototype

```
typedef
EFI_STATUS
Exit (
    IN EFI_HANDLE    ImageHandle,
    IN EFI_STATUS    ExitStatus,
    IN UINTN         ExitDataSize,
    IN CHAR16        *ExitData    OPTIONAL
);
```

Parameters

<i>ImageHandle</i>	Handle that identifies the image. This parameter is passed to the image on entry.
<i>ExitStatus</i>	The image's exit code.
<i>ExitDataSize</i>	The size, in bytes, of <i>ExitData</i> . Ignored if <i>ExitStatus</i> is EFI_SUCCESS .
<i>ExitData</i>	Pointer to a data buffer that includes a Null-terminated Unicode string, optionally followed by additional binary data. The string is a description that the caller may use to further indicate the reason for the image's exit. <i>ExitData</i> is only valid if <i>ExitStatus</i> is something other than EFI_SUCCESS . The <i>ExitData</i> buffer must be allocated by calling AllocatePool() .

Description

The **Exit()** function terminates the image referenced by *ImageHandle* and returns control to boot services. This function may not be called if the image has already returned from its entry point ([EFI_IMAGE_ENTRY_POINT](#)) or if it has loaded any child images that have not exited (all child images must exit before this image can exit).

Using **Exit()** is similar to returning from the image's **EFI_IMAGE_ENTRY_POINT** except that **Exit()** may also return additional *ExitData*.

When an application exits a compliant system, firmware frees the memory used to hold the image. The firmware also frees its references to the *ImageHandle* and the handle itself. Before exiting, the application is responsible for freeing any resources it allocated. This includes memory (pages and/or pool), open file system handles, and so forth. The only exception to this rule is the *ExitData* buffer, which must be freed by the caller of [StartImage\(\)](#). (If the buffer is needed, firmware must allocate it by calling [AllocatePool\(\)](#) and must return a pointer to it to the caller of **StartImage()**.)

When an EFI boot service driver or runtime service driver exits, firmware frees the image only if the *ExitStatus* is an error code; otherwise the image stays resident in memory. The driver must not return an error code if it has installed any protocol handlers or other active callbacks into the system that have not (or cannot) be cleaned up. If the driver exits with an error code, it is responsible for freeing all resources before exiting. This includes any allocated memory (pages and/or pool), open file system handles, and so forth.

It is valid to call **Exit()** or **UnloadImage()** for an image that was loaded by **LoadImage()** before calling **StartImage()**. This will free the image from memory without having started it.

EFI 1.10 Extension

If *ImageHandle* is a UEFI application, then all of the protocols that were opened by *ImageHandle* using the boot service **OpenProtocol()** are automatically closed with the boot service **CloseProtocol()**. If *ImageHandle* is an EFI boot services driver or runtime service driver, and *ExitStatus* is an error code, then all of the protocols that were opened by *ImageHandle* using the boot service **OpenProtocol()** are automatically closed with the boot service **CloseProtocol()**. If *ImageHandle* is an EFI boot services driver or runtime service driver, and *ExitStatus* is not an error code, then no protocols are automatically closed by this service.

Status Codes Returned

(Does not return.)	Image exit. Control is returned to the StartImage() call that invoked the image specified by <i>ImageHandle</i> .
EFI_SUCCESS	The image specified by <i>ImageHandle</i> was unloaded. This condition only occurs for images that have been loaded with LoadImage() but have not been started with StartImage() .
EFI_INVALID_PARAMETER	The image specified by <i>ImageHandle</i> has been loaded and started with LoadImage() and StartImage() , but the image is not the currently executing image.

ExitBootServices()

Summary

Terminates all boot services.

Prototype

```
typedef
EFI_STATUS
ExitBootServices (
    IN EFI_HANDLE      ImageHandle,
    IN UINTN           MapKey
);
```

Parameters

<i>ImageHandle</i>	Handle that identifies the exiting image. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.
<i>MapKey</i>	Key to the latest memory map.

Description

The **ExitBootServices()** function is called by the currently executing EFI OS loader image to terminate all boot services. On success, the loader becomes responsible for the continued operation of the system. All events of type **EVT_SIGNAL_EXIT_BOOT_SERVICES** must be signaled before **ExitBootServices()** returns.

An EFI OS loader must ensure that it has the system's current memory map at the time it calls **ExitBootServices()**. This is done by passing in the current memory map's *MapKey* value as returned by [GetMemoryMap\(\)](#). Care must be taken to ensure that the memory map does not change between these two calls. It is suggested that **GetMemoryMap()** be called immediately before calling **ExitBootServices()**. If *MapKey* value is incorrect, **ExitBootServices()** returns **EFI_INVALID_PARAMETER** and **GetMemoryMap()** with **ExitBootServices()** must be called again. Firmware implementation may choose to do a partial shutdown of the boot services during the first call to **ExitBootServices()**. EFI OS loader should not make calls to any boot service function other than **GetMemoryMap()** after the first call to **ExitBootServices()**.

On success, the EFI OS loader owns all available memory in the system. In addition, the loader can treat all memory in the map marked as **EfiBootServicesCode** and **EfiBootServicesData** as available free memory. No further calls to boot service functions or EFI device-handle-based protocols may be used, and the boot services watchdog timer is disabled. On success, several fields of the EFI System Table should be set to **NULL**. These include *ConsoleInHandle*, *ConIn*, *ConsoleOutHandle*, *ConOut*, *StandardErrorHandle*, *StdErr*, and *BootServicesTable*. In addition, since fields of the EFI System Table are being modified, the 32-bit CRC for the EFI System Table must be recomputed.

Status Codes Returned

EFI_SUCCESS	Boot services have been terminated.
EFI_INVALID_PARAMETER	<i>MapKey</i> is incorrect.

6.5 Miscellaneous Boot Services

This section contains the remaining function definitions for boot services not defined elsewhere but which are required to complete the definition of the EFI environment. [Table 26](#) lists the Miscellaneous Boot Services Functions.

Table 26. Miscellaneous Boot Services Functions

Name	Type	Description
SetWatchDogTimer	Boot	Resets and sets a watchdog timer used during boot services time.
Stall	Boot	Stalls the processor.
CopyMem	Boot	Copies the contents of one buffer to another buffer.
SetMem	Boot	Fills a buffer with a specified value.
GetNextMonotonicCount	Boot	Returns a monotonically increasing count for the platform.
InstallConfigurationTable	Boot	Adds, updates, or removes a configuration table from the EFI System Table.
CalculateCrc32	Boot	Computes and returns a 32-bit CRC for a data buffer.

The [CalculateCrc32 \(\)](#) service was added because there are several places in EFI that 32-bit CRCs are used. These include the EFI System Table, the EFI Boot Services Table, the EFI Runtime Services Table, and the GUID Partition Table (GPT) structures. The **CalculateCrc32 ()** service allows new 32-bit CRCs to be computed, and existing 32-bit CRCs to be validated.

SetWatchdogTimer()

Summary

Sets the system's watchdog timer.

Prototype

```

typedef
EFI_STATUS
SetWatchdog      Timer (
    IN UINTN      Timeout,
    IN UINT64     WatchdogCode,
    IN UINTN      DataSize,
    IN CHAR16     *WatchdogData    OPTIONAL
);
    
```

Parameters

<i>Timeout</i>	The number of seconds to set the watchdog timer to. A value of zero disables the timer.
<i>WatchdogCode</i>	The numeric code to log on a watchdog timer timeout event. The firmware reserves codes 0x0000 to 0xFFFF. Loaders and operating systems may use other timeout codes.
<i>DataSize</i>	The size, in bytes, of <i>WatchdogData</i> .
<i>WatchdogData</i>	A data buffer that includes a Null-terminated Unicode string, optionally followed by additional binary data. The string is a description that the call may use to further indicate the reason to be logged with a watchdog event.

Description

The **SetWatchdogTimer()** function sets the system's watchdog timer.

If the watchdog timer expires, the event is logged by the firmware. The system may then either reset with the Runtime Service [ResetSystem\(\)](#), or perform a platform specific action that must eventually cause the platform to be reset. The watchdog timer is armed before the firmware's boot manager invokes an EFI boot option. The watchdog must be set to a period of 5 minutes. The EFI Image may reset or disable the watchdog timer as needed. If control is returned to the firmware's boot manager, the watchdog timer must be disabled.

The watchdog timer is only used during boot services. On successful completion of [ExitBootServices\(\)](#) the watchdog timer is disabled.

The accuracy of the watchdog timer is +/- 1 second from the requested *Timeout*.

Status Codes Returned

EFI_SUCCESS	The timeout has been set.
EFI_INVALID_PARAMETER	The supplied <i>WatchdogCode</i> is invalid.

EFI_UNSUPPORTED	The system does not have a watchdog timer.
EFI_DEVICE_ERROR	The watch dog timer could not be programmed due to a hardware error.

Stall()

Summary

Induces a fine-grained stall.

Prototype

```
typedef
EFI_STATUS
Stall (
    IN UINTN Microseconds
)
```

Parameters

Microseconds The number of microseconds to stall execution.

Description

The **Stall()** function stalls execution on the processor for at least the requested number of microseconds. Execution of the processor is *not* yielded for the duration of the stall.

Status Codes Returned

EFI_SUCCESS	Execution was stalled at least the requested number of <i>Microseconds</i> .
-------------	--

CopyMem()

Summary

The **CopyMem()** function copies the contents of one buffer to another buffer.

Prototype

```
typedef
VOID
CopyMem (
    IN VOID      *Destination,
    IN VOID      *Source,
    IN UINTN     Length
);
```

Parameters

<i>Destination</i>	Pointer to the destination buffer of the memory copy.
<i>Source</i>	Pointer to the source buffer of the memory copy.
<i>Length</i>	Number of bytes to copy from <i>Source</i> to <i>Destination</i> .

Description

The **CopyMem()** function copies *Length* bytes from the buffer *Source* to the buffer *Destination*.

The implementation of **CopyMem()** must be reentrant, and it must handle overlapping *Source* and *Destination* buffers. This means that the implementation of **CopyMem()** must choose the correct direction of the copy operation based on the type of overlap that exists between the *Source* and *Destination* buffers. If either the *Source* buffer or the *Destination* buffer crosses the top of the processor's address space, then the result of the copy operation is unpredictable.

The contents of the *Destination* buffer on exit from this service must match the contents of the *Source* buffer on entry to this service. Due to potential overlaps, the contents of the *Source* buffer may be modified by this service. The following rules can be used to guarantee the correct behavior:

1. If *Destination* and *Source* are identical, then no operation should be performed.
2. If $Destination > Source$ and $Destination < (Source + Length)$, then the data should be copied from the *Source* buffer to the *Destination* buffer starting from the end of the buffers and working toward the beginning of the buffers.
3. Otherwise, the data should be copied from the *Source* buffer to the *Destination* buffer starting from the beginning of the buffers and working toward the end of the buffers.

Status Codes Returned

None.

SetMem()

Summary

The **SetMem()** function fills a buffer with a specified value.

Prototype

```
typedef
VOID
SetMem (
    IN VOID      *Buffer,
    IN UINTN     Size,
    IN UINT8     Value
);
```

Parameters

<i>Buffer</i>	Pointer to the buffer to fill.
<i>Size</i>	Number of bytes in <i>Buffer</i> to fill.
<i>Value</i>	Value to fill <i>Buffer</i> with.

Description

This function fills *Size* bytes of *Buffer* with *Value*. The implementation of **SetMem()** must be reentrant. If *Buffer* crosses the top of the processor's address space, the result of the **SetMem()** operation is unpredictable.

Status Codes Returned

None.

InstallConfigurationTable()

Summary

Adds, updates, or removes a configuration table entry from the EFI System Table.

Prototype

```
typedef
EFI_STATUS
InstallConfigurationTable (
    IN EFI_GUID    *Guid,
    IN VOID        *Table
);
```

Parameters

<i>Guid</i>	A pointer to the GUID for the entry to add, update, or remove.
<i>Table</i>	A pointer to the configuration table for the entry to add, update, or remove. May be NULL .

Description

The **InstallConfigurationTable()** function is used to maintain the list of configuration tables that are stored in the EFI System Table. The list is stored as an array of (GUID, Pointer) pairs. The list must be allocated from pool memory with *PoolType* set to **EfiRuntimeServicesData**.

If *Guid* is not a valid GUID, **EFI_INVALID_PARAMETER** is returned. If *Guid* is valid, there are four possibilities:

- If *Guid* is not present in the System Table, and *Table* is not **NULL**, then the (*Guid*, *Table*) pair is added to the System Table. See Note below.
- If *Guid* is not present in the System Table, and *Table* is **NULL**, then **EFI_NOT_FOUND** is returned.
- If *Guid* is present in the System Table, and *Table* is not **NULL**, then the (*Guid*, *Table*) pair is updated with the new *Table* value.
- If *Guid* is present in the System Table, and *Table* is **NULL**, then the entry associated with *Guid* is removed from the System Table.

If an add, modify, or remove operation is completed, then **EFI_SUCCESS** is returned.

Note: If there is not enough memory to perform an add operation, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The (<i>Guid</i> , <i>Table</i>) pair was added, updated, or removed.
EFI_INVALID_PARAMETER	<i>Guid</i> is not valid.
EFI_NOT_FOUND	An attempt was made to delete a nonexistent entry.

EFI_OUT_OF_RESOURCES	There is not enough memory available to complete the operation.
----------------------	---

CalculateCrc32()

Summary

Computes and returns a 32-bit CRC for a data buffer.

Prototype

```
typedef
EFI_STATUS
CalculateCrc32 (
    IN VOID      *Data,
    IN UINTN     DataSize,
    OUT UINT32   *Crc32
);
```

Parameters

<i>Data</i>	A pointer to the buffer on which the 32-bit CRC is to be computed.
<i>DataSize</i>	The number of bytes in the buffer <i>Data</i> .
<i>Crc32</i>	The 32-bit CRC that was computed for the data buffer specified by <i>Data</i> and <i>DataSize</i> .

Description

This function computes the 32-bit CRC for the data buffer specified by *Data* and *DataSize*. If the 32-bit CRC is computed, then it is returned in *Crc32* and **EFI_SUCCESS** is returned.

If *Data* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *Crc32* is **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *DataSize* is 0, then **EFI_INVALID_PARAMETER** is returned.

Status Codes Returned

EFI_SUCCESS	The 32-bit CRC was computed for the data buffer and returned in <i>Crc32</i> .
EFI_INVALID_PARAMETER	<i>Data</i> is NULL .
EFI_INVALID_PARAMETER	<i>Crc32</i> is NULL .
EFI_INVALID_PARAMETER	<i>DataSize</i> is 0.

Services — Runtime Services

This section discusses the fundamental services that are present in a compliant system. The services are defined by interface functions that may be used by code running in the EFI environment. Such code may include protocols that manage device access or extend platform capability, as well as applications running in the preboot environment and EFI OS loaders.

Two types of services are described here:

- **Boot Services.** Functions that are available *before* a successful call to [ExitBootServices\(\)](#). These functions are described in [Section 6](#).
- **Runtime Services.** Functions that are available *before and after* any call to [ExitBootServices\(\)](#). These functions are described in this section.

During boot, system resources are owned by the firmware and are controlled through boot services interface functions. These functions can be characterized as “global” or “handle-based.” The term “global” simply means that a function accesses system services and is available on all platforms (since all platforms support all system services). The term “handle-based” means that the function accesses a specific device or device functionality and may not be available on some platforms (since some devices are not available on some platforms). Protocols are created dynamically. This section discusses the “global” functions and runtime functions; subsequent sections discuss the “handle-based.”

Applications written to this specification (including OS loaders) must use boot services functions to access devices and allocate memory. On entry, an image is provided a pointer to a system table which contains the Boot Services dispatch table and the default handles for accessing the console. All boot services functionality is available until an EFI OS loader loads enough of its own environment to take control of the system’s continued operation and then terminates boot services with a call to [ExitBootServices\(\)](#).

In principle, the [ExitBootServices\(\)](#) call is intended for use by the operating system to indicate that its loader is ready to assume control of the platform and all platform resource management. Thus boot services are available up to this point to assist the OS loader in preparing to boot the operating system. Once the OS loader takes control of the system and completes the operating system boot process, only runtime services may be called. Code other than the OS loader, however, may or may not choose to call [ExitBootServices\(\)](#). This choice may in part depend upon whether or not such code is designed to make continued use of EFI boot services or the boot services environment.

The rest of this section discusses individual functions. Runtime Services fall into these categories:

- Runtime Rules and Restrictions ([Section 7.1](#))
- Variable Services ([Section 7.2](#))
- Time Services ([Section 7.3](#))
- Virtual Memory Services ([Section 7.4](#))
- Miscellaneous Services ([Section 7.5](#))

7.1 Runtime Services Rules and Restrictions

All of the Runtime Services may be called with interrupts enabled if desired. The Runtime Service functions will internally disable interrupts when it is required to protect access to hardware resources. The interrupt enable control bit will be returned to its entry state after the access to the critical hardware resources is complete.

All callers of Runtime Services are restricted from calling the same or certain other Runtime Service functions prior to the completion and return of a previous Runtime Service call. These restrictions apply to:

- Runtime Services that have been interrupted
- Runtime Services that are active on another processor.

Callers are prohibited from using certain other services from another processor or on the same processor following an interrupt as specified in [Table 27](#). For this table ‘Busy’ is defined as the state when a Runtime Service has been entered and has not returned to the caller.

The consequence of a caller violating these restrictions is undefined except for certain special cases described below.

Table 27. Rules for Reentry Into Runtime Services

If previous call is busy in	Forbidden to call
Any	SetVirtualAddressMap()
ConvertPointer()	ConvertPointer()
SetVariable(), UpdateCapsule(), SetTime() SetWakeupTime(), GetNextHighMonotonicCount()	ResetSystem()
GetVariable() GetNextVariableName() SetVariable() QueryVariableInfo() UpdateCapsule() QueryCapsuleCapabilities() GetNextHighMonotonicCount()	GetVariable(), GetNextVariableName(), SetVariable(), QueryVariableInfo(), UpdateCapsule(), QueryCapsuleCapabilities(), GetNextHighMonotonicCount()
GetTime() SetTime() GetWakeupTime() SetWakeupTime()	GetTime() SetTime() GetWakeupTime() SetWakeupTime()

7.1.1 Exception for Machine Check, INIT, and NMI.

Certain asynchronous events (e.g., NMI on IA-32 and x64 systems, Machine Check and INIT on Itanium systems) can not be masked and may occur with any setting of interrupt enabled. These events also may require OS level handler's involvement that may involve the invocation of some of the runtime services (see below).

If SetVirtualAddressMap() has been called, all calls to runtime services after Machine Check, INIT, or NMI, must be made using the virtual address map set by that call.

A Machine Check may have interrupted a runtime service (see below). If the OS determines that the Machine Check is recoverable, the OS level handler must follow the normal restrictions in [Table 27](#).

If the OS determines that the Machine Check is non-recoverable, the OS level handler may ignore the normal restrictions and may invoke the runtime services described in [Table 28](#) even in the case where a previous call was busy. The system firmware will honor the new runtime service call(s) and the operation of the previous interrupted call is not guaranteed. Any interrupted runtime functions will not be restarted.

The INIT and NMI events follow the same restrictions.

Note: *On Itanium systems, the OS Machine Check Handler must not call SystemReset(). If a reset is required, the OS Machine Check Handler may request SAL to reset upon return to SAL_CHECK.*

The platform implementations are required to clear any runtime services in progress in order to enable the OS handler to invoke these runtime services even in the case where a previous call was busy. In this case, the proper operation of the original interrupted call is not guaranteed.

Table 28. Functions that may be called after Machine Check ,INIT and NMI

Function	Called after Machine Check, INIT and NMI
GetTime()	Yes, even if previously busy.
GetVariable()	Yes, even if previously busy
GetNextVariableName()	Yes, even if previously busy
QueryVariableInfo()	Yes, even if previously busy
SetVariable()	Yes, even if previously busy
UpdateCapsule()	Yes, even if previously busy
QueryCapsuleCapabilities()	Yes, even if previously busy
ResetSystem()	Yes, even if previously busy

7.2 Variable Services

Variables are defined as key/value pairs that consist of identifying information plus attributes (the key) and arbitrary data (the value). Variables are intended for use as a means to store data that is passed between the EFI environment implemented in the platform and EFI OS loaders and other applications that run in the EFI environment.

Although the implementation of variable storage is not defined in this specification, variables must be persistent in most cases. This implies that the EFI implementation on a platform must arrange it so that variables passed in for storage are retained and available for use each time the system boots, at least until they are explicitly deleted or overwritten. Provision of this type of nonvolatile storage may be very limited on some platforms, so variables should be used sparingly in cases where other means of communicating information cannot be used.

[Table 29](#) lists the variable services functions described in this section:

Table 29. Variable Services Functions

Name	Type	Description
GetVariable	Runtime	Returns the value of a variable.
GetNextVariableName	Runtime	Enumerates the current variable names.
SetVariable	Runtime	Sets the value of a variable.
QueryVariableInfo()	Runtime	Returns information about the EFI variables

GetVariable()

Summary

Returns the value of a variable.

Prototype

```
typedef
EFI_STATUS
GetVariable (
    IN CHAR16           *VariableName,
    IN EFI_GUID        *VendorGuid,
    OUT UINT32         *Attributes OPTIONAL,
    IN OUT UINTN       *DataSize,
    OUT VOID           *Data
);
```

Parameters

<i>VariableName</i>	A Null-terminated Unicode string that is the name of the vendor's variable.
<i>VendorGuid</i>	A unique identifier for the vendor. Type EFI_GUID is defined in the InstallProtocolInterface() function description.
<i>Attributes</i>	If not NULL , a pointer to the memory location to return the attributes bitmask for the variable. See "Related Definitions."
<i>DataSize</i>	On input, the size in bytes of the return <i>Data</i> buffer. On output the size of data returned in <i>Data</i> .
<i>Data</i>	The buffer to return the contents of the variable.

Related Definitions

```

/*****
// Variable Attributes
/*****
#define EFI_VARIABLE_NON_VOLATILE           0x00000001
#define EFI_VARIABLE_BOOTSERVICE_ACCESS  0x00000002
#define EFI_VARIABLE_RUNTIME_ACCESS       0x00000004
#define EFI_VARIABLE_HARDWARE_ERROR_RECORD 0x00000008
//This attribute is identified by the mnemonic 'HR' elsewhere in
this specification.
#define EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS 0x00000010
```

Description

Each vendor may create and manage its own variables without the risk of name conflicts by using a unique *VendorGuid*. When a variable is set its *Attributes* are supplied to indicate how the data variable should be stored and maintained by the system. The attributes affect when the variable may be accessed and volatility of the data. Any attempts to access a variable that does not have the attribute set for runtime access will yield the **EFI_NOT_FOUND** error.

If the *Data* buffer is too small to hold the contents of the variable, the error **EFI_BUFFER_TOO_SMALL** is returned and *DataSize* is set to the required buffer size to obtain the data.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NOT_FOUND	The variable was not found.
EFI_BUFFER_TOO_SMALL	The <i>DataSize</i> is too small for the result. <i>DataSize</i> has been updated with the size needed to complete the request.
EFI_INVALID_PARAMETER	<i>VariableName</i> is NULL .
EFI_INVALID_PARAMETER	<i>VendorGuid</i> is NULL .
EFI_INVALID_PARAMETER	<i>DataSize</i> is NULL .
EFI_INVALID_PARAMETER	The <i>DataSize</i> is not too small and <i>Data</i> is NULL .
EFI_DEVICE_ERROR	The variable could not be retrieved due to a hardware error.
EFI_SECURITY_VIOLATION	The variable could not be retrieved due to an authentication failure.

GetNextVariableName()

Summary

Enumerates the current variable names.

Prototype

```
typedef
EFI_STATUS
GetNextVariableName (
    IN OUT UINTN      *VariableNameSize,
    IN OUT CHAR16     *VariableName,
    IN OUT EFI_GUID   *VendorGuid
);
```

Parameters

<i>VariableNameSize</i>	The size of the <i>VariableName</i> buffer.
<i>VariableName</i>	On input, supplies the last <i>VariableName</i> that was returned by GetNextVariableName() . On output, returns the Null-terminated Unicode string of the current variable.
<i>VendorGuid</i>	On input, supplies the last <i>VendorGuid</i> that was returned by GetNextVariableName() . On output, returns the <i>VendorGuid</i> of the current variable. Type EFI_GUID is defined in the InstallProtocolInterface() function description.

Description

GetNextVariableName() is called multiple times to retrieve the *VariableName* and *VendorGuid* of all variables currently available in the system. On each call to **GetNextVariableName()** the previous results are passed into the interface, and on output the interface returns the next variable name data. When the entire variable list has been returned, the error **EFI_NOT_FOUND** is returned.

Note that if **EFI_BUFFER_TOO_SMALL** is returned, the *VariableName* buffer was too small for the next variable. When such an error occurs, the *VariableNameSize* is updated to reflect the size of buffer needed. In all cases when calling **GetNextVariableName()** the *VariableNameSize* must not exceed the actual buffer size that was allocated for *VariableName*.

To start the search, a Null-terminated string is passed in *VariableName*; that is, *VariableName* is a pointer to a Null Unicode character. This is always done on the initial call to **GetNextVariableName()**. When *VariableName* is a pointer to a Null Unicode character, *VendorGuid* is ignored. **GetNextVariableName()** cannot be used as a filter to return variable names with a specific GUID. Instead, the entire list of variables must be retrieved, and the caller may act as a filter if it chooses. Calls to [SetVariable\(\)](#) between calls to **GetNextVariableName()** may produce unpredictable results. Passing in a *VariableName*

parameter that is neither a Null-terminated string nor a value that was returned on the previous call to [GetNextVariableName\(\)](#) may also produce unpredictable results.

Once [ExitBootServices\(\)](#) is performed, variables that are only visible during boot services will no longer be returned. To obtain the data contents or attribute for a variable returned by [GetNextVariableName\(\)](#), the [GetVariable\(\)](#) interface is used.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NOT_FOUND	The next variable was not found.
EFI_BUFFER_TOO_SMALL	The <i>VariableNameSize</i> is too small for the result. <i>VariableNameSize</i> has been updated with the size needed to complete the request.
EFI_INVALID_PARAMETER	<i>VariableNameSize</i> is NULL .
EFI_INVALID_PARAMETER	<i>VariableName</i> is NULL .
EFI_INVALID_PARAMETER	<i>VendorGuid</i> is NULL .
EFI_DEVICE_ERROR	The variable name could not be retrieved due to a hardware error.

SetVariable()

Summary

Sets the value of a variable.

Prototype

```
typedef
EFI_STATUS
SetVariable (
    IN CHAR16      *VariableName,
    IN EFI_GUID    *VendorGuid,
    IN UINT32      Attributes,
    IN UINTN       DataSize,
    IN VOID        *Data
);
```

Parameters

<i>VariableName</i>	A Null-terminated Unicode string that is the name of the vendor's variable. Each <i>VariableName</i> is unique for each <i>VendorGuid</i> . <i>VariableName</i> must contain 1 or more Unicode characters. If <i>VariableName</i> is an empty Unicode string, then EFI_INVALID_PARAMETER is returned.
<i>VendorGuid</i>	A unique identifier for the vendor. Type EFI_GUID is defined in the InstallProtocolInterface() function description.
<i>Attributes</i>	Attributes bitmask to set for the variable. Refer to the GetVariable() function description.
<i>DataSize</i>	The size in bytes of the <i>Data</i> buffer. A size of zero causes the variable to be deleted.
<i>Data</i>	The contents for the variable.

Related Definitions

```

//*****
// Variable Attributes
//*****

//
// EFI_VARIABLE_AUTHENTICATION descriptor
//
// This provides the authentication method descriptor template
//
typedef struct {
    UINT64                               MonotonicCount;
    WIN_CERTIFICATE_UEFI_GUID            AuthInfo;
} EFI_VARIABLE_AUTHENTICATION;

```

MonotonicCount

Included in the signature of AuthInfo. Used to ensure freshness/no replay. Incremented during each "Write" access.

AuthInfo

Provides the authorization for the variable access. It is a signature across the variable data and the Monotonic Count value. Caller uses Private key that is associated with a public key that has been provisioned via the key exchange.

Description

Variables are stored by the firmware and may maintain their values across power cycles. Each vendor may create and manage its own variables without the risk of name conflicts by using a unique *VendorGuid*.

Each variable has *Attributes* that define how the firmware stores and maintains the data value. If the **EFI_VARIABLE_NON_VOLATILE** attribute is *not* set, the firmware stores the variable in normal memory and it is not maintained across a power cycle. Such variables are used to pass information from one component to another. An example of this is the firmware's language code support variable. It is created at firmware initialization time for access by EFI components that may need the information, but does not need to be backed up to nonvolatile storage.

EFI_VARIABLE_NON_VOLATILE variables are stored in fixed hardware that has a limited storage capacity; sometimes a severely limited capacity. Software should only use a nonvolatile variable when absolutely necessary. In addition, if software uses a nonvolatile variable it should use a variable that is only accessible at boot services time if possible.

A variable must contain one or more bytes of *Data*. Using **SetVariable()** with a *DataSize* of zero causes the entire variable to be deleted. The space consumed by the deleted variable may not be available until the next power cycle.

The Attributes have the following usage rules:

- Storage attributes are only applied to a variable when creating the variable. If a preexisting variable is rewritten with different attributes, the result is indeterminate and may vary between implementations. The correct method of changing the attributes of a variable is to delete the variable and recreate it with different attributes. There is one exception to this rule. If a preexisting variable is rewritten with no access attributes specified, the variable will be deleted.
- Setting a data variable with no access attributes, or zero *DataSize* specified, causes it to be deleted.
- Runtime access to a data variable implies boot service access. Attributes that have **EFI_VARIABLE_RUNTIME_ACCESS** set must also have **EFI_VARIABLE_BOOTSERVICE_ACCESS** set. The caller is responsible for following this rule.
- Once [ExitBootServices\(\)](#) is performed, data variables that did not have **EFI_VARIABLE_RUNTIME_ACCESS** set are no longer visible to [GetVariable\(\)](#).
- Once [ExitBootServices\(\)](#) is performed, only variables that have **EFI_VARIABLE_RUNTIME_ACCESS** and **EFI_VARIABLE_NON_VOLATILE** set can be set with [SetVariable\(\)](#). Variables that have runtime access but that are not nonvolatile are read-only data variables once [ExitBootServices\(\)](#) is performed.

The only rules the firmware must implement when saving a nonvolatile variable is that it has actually been saved to nonvolatile storage before returning **EFI_SUCCESS**, and that a partial save is not performed. If power fails during a call to [SetVariable\(\)](#) the variable may contain its previous value, or its new value. In addition there is no read, write, or delete security protection.

AuthInfo is a **WIN_CERTIFICATE** using the *wCertificateType* **WIN_CERTIFICATE_UEFI_GUID** and the *CertType* **EFI_CERT_TYPE_RSA2048_SHA256**.

If the **EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS** is set, then the *Data* buffer should begin with an authentication descriptor prior to the data payload and *DataSize* should reflect the the data and descriptor size. The caller shall digest the Monotonic Count value and the associated data for the variable update using the SHA-256 1-way hash algorithm. The ensuing the 32-byte digest will be signed using the private key associated w/ the public/private 2048-bit RSA key-pair. The **WIN_CERTIFICATE** shall be used to describe the signature of the Variable data **Data*. In addition, the signature will also include the *MonotonicCount* value to guard against replay attacks.

From the **WIN_CERTIFICATE**, the *HashType* will be **EFI_SHA256_HASH** and the **ANYSIZE_ARRAY** of *Signature* will be 256. RSASSA-PSS padding will be used during the signature block [see RSA].

The **WIN_CERTIFICATE_PKCS1_15** could have been used but was not for the following reason: There are possibly various different principals to create authenticated variables, so the public key corresponding to a given principal is added to the **EFI_CERT_BLOCK_RSA_2048_SHA256** within the **WIN_CERTIFICATE**. This does not lend cryptographic value so much as it provides something akin to a handle for the platform firmware to use during its verification operation (see security model picture).

The *MonotonicCount* value must be strictly greater for each successive variable update operation. This allows for ensuring freshness of the update operation and defense against replay

attacks (i.e., if someone had the value of a former *AuthInfo*, they could not re-invoke that same update session).

The updated data values for authenticated updates can be found in [Figure 19](#).

The flow for both the caller and the associated firmware can be found in [Figure 20](#).

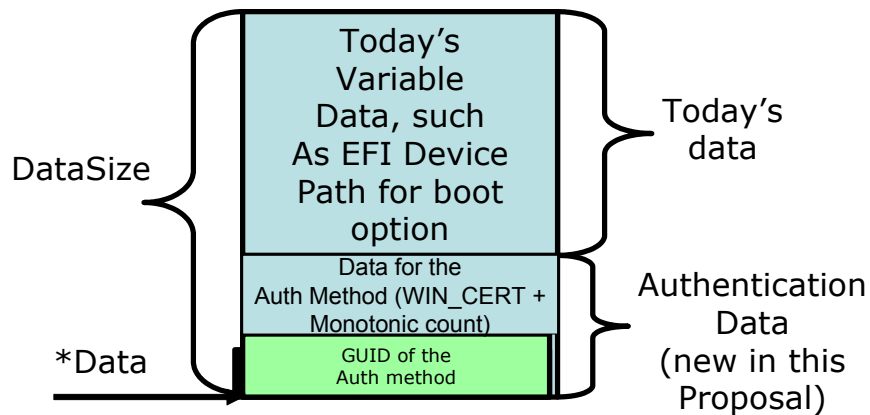


Figure 19. Authentication Method

Signature is computed across the "Data" field of the EFI Variable write call. A flow-chart of this new behavior is shown in [Figure 20](#) below:

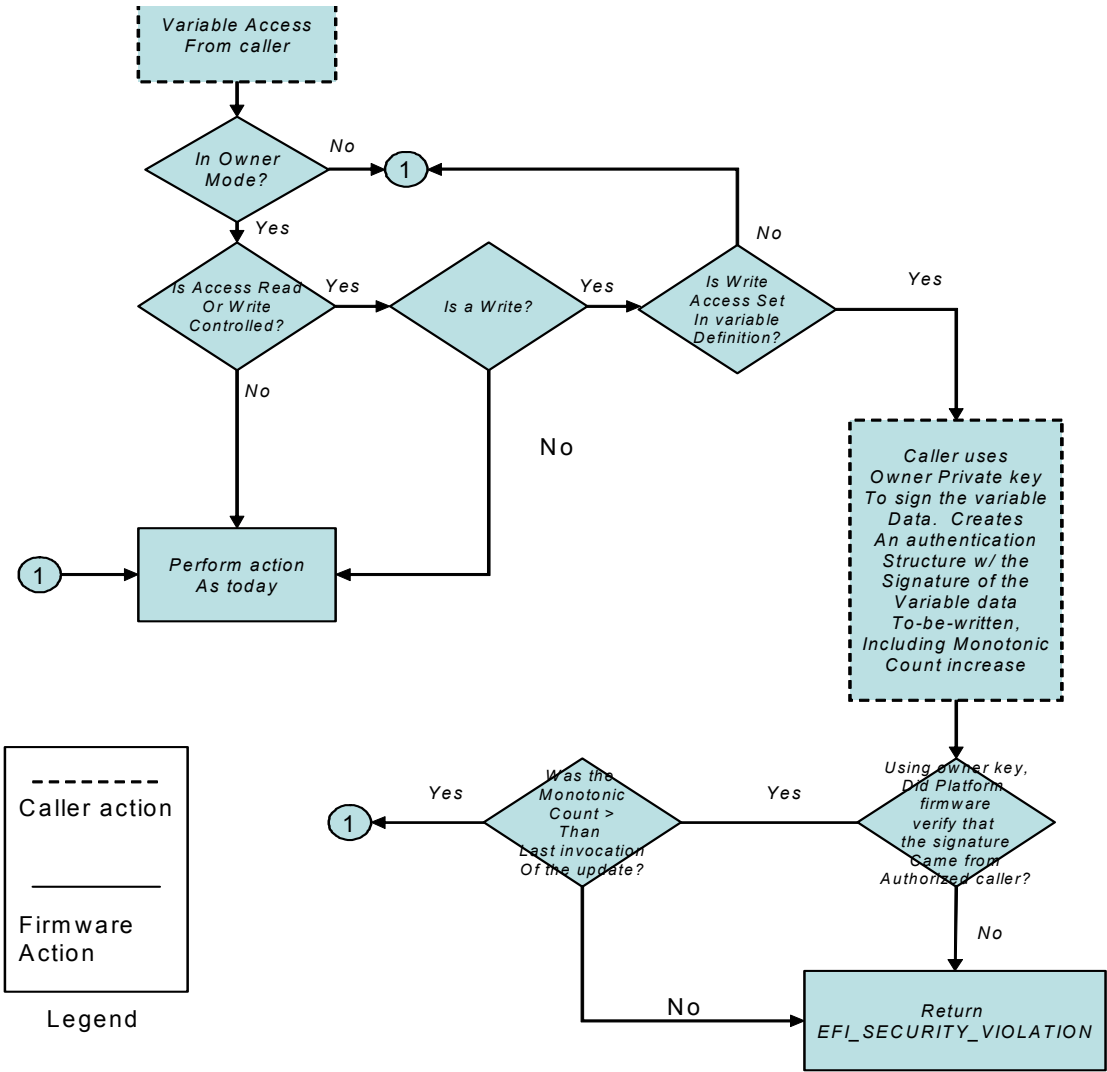


Figure 20. Flow of the Authenticated Write Access

Status Codes Returned

EFI_SUCCESS	The firmware has successfully stored the variable and its data as defined by the Attributes.
EFI_INVALID_PARAMETER	An invalid combination of attribute bits was supplied, or the <i>DataSize</i> exceeds the maximum allowed.
EFI_INVALID_PARAMETER	<i>VariableName</i> is an empty Unicode string.
EFI_OUT_OF_RESOURCES	Not enough storage is available to hold the variable and its data.
EFI_DEVICE_ERROR	The variable could not be saved due to a hardware failure.
EFI_WRITE_PROTECTED	The variable in question is read-only.
EFI_WRITE_PROTECTED	The variable in question cannot be deleted.
EFI_SECURITY_VIOLATION	The variable could not be retrieved due to an authentication failure.
EFI_NOT_FOUND	The variable trying to be updated or deleted was not found.

QueryVariableInfo()

Summary

Returns information about the EFI variables.

Prototype

```
typedef
EFI_STATUS
QueryVariableInfo (
    IN UINT32           Attributes,
    OUT UINT64          *MaximumVariableStorageSize,
    OUT UINT64          *RemainingVariableStorageSize,
    OUT UINT64          *MaximumVariableSize
);
```

Attributes Attributes bitmask to specify the type of variables on which to return information. Refer to the **GetVariable()** function description.

MaximumVariableStorageSize On output the maximum size of the storage space available for the EFI variables associated with the attributes specified.

RemainingVariableStorageSize Returns the remaining size of the storage space available for EFI variables associated with the attributes specified.

MaximumVariableSize Returns the maximum size of an individual EFI variable associated with the attributes specified.

Description

The **QueryVariableInfo()** function allows a caller to obtain the information about the maximum size of the storage space available for the EFI variables, the remaining size of the storage space available for the EFI variables and the maximum size of each individual EFI variable, associated with the attributes specified.

The *MaximumVariableSize* value will reflect the overhead associated with the saving of a single EFI variable with the exception of the overhead associated with the length of the string name of the EFI variable.

The returned *MaximumVariableStorageSize*, *RemainingVariableStorageSize*, *MaximumVariableSize* information may change immediately after the call based on other runtime activities including asynchronous error events. Also, these values associated with different attributes are not additive in nature.

After the system has transitioned into runtime (after `ExitBootServices()` is called), an implementation may not be able to accurately return information about the Boot Services variable store. In such cases, **EFI_INVALID_PARAMETER** should be returned.

Status Codes Returned

EFI_SUCCESS	Valid answer returned.
EFI_INVALID_PARAMETER	An invalid combination of attribute bits was supplied
EFI_UNSUPPORTED	The attribute is not supported on this platform, and the <i>MaximumVariableStorageSize</i> , <i>RemainingVariableStorageSize</i> , <i>MaximumVariableSize</i> are undefined.

7.2.1 Hardware Error Record Persistence

This section defines how Hardware Error Record Persistence is to be implemented. By implementing support for Hardware Error Record Persistence, the platform enables the OS to utilize the EFI Variable Services to save hardware error records so they are persistent and remain available across OS sessions until they are explicitly cleared or overwritten by their creator.

7.2.1.1 Hardware Error Record Non-Volatile Store

A platform which implements support hardware error record persistence is required to guarantee some amount of NVR is available to the OS for saving hardware error records. The platform communicates the amount of space allocated for error records via the QueryVariableInfo routine as described in [Appendix P](#).

7.2.1.2 Hardware Error Record Variables

This section defines a set of Hardware Error Record variables that have architecturally defined meanings. In addition to the defined data content, each such variable has an architecturally defined attribute that indicates when the data variable may be accessed. The variables with an attribute of HR are stored in the portion of NVR allocated for error records. NV, BS and RT have the meanings defined in section 3.2. All hardware error record variables use the EFI_HARDWARE_ERROR_VARIABLE VendorGuid:

```
#define EFI_HARDWARE_ERROR_VARIABLE\
{0x414E6BDD, 0xE47B, 0x47cc, {0xB2, 0x44, 0xBB, 0x61, 0x02, 0x0C, 0xF5, 0x16}}
```

Table 30. Hardware Error Record Persistence Variables

Variable Name	Attribute	Description
HwErrRec####	NV, BS, RT, HR	A hardware error record. #### is a printed hex value. No 0x or h is included in the hex value

The HwErrRec#### variable contains a hardware error record. Each HwErrRec#### variable is the name "HwErrRec" appended with a unique 4-digit decimal number. For example, HwErrRec0001, HwErrRec0002, HwErrRecF31A, etc. The HR attribute indicates that this variable is to be stored in the portion of NVR allocated for error records.

7.2.1.3 Common Platform Error Record Format

Error record variables persisted using this interface are encoded in the Common Platform Error Record format, which is described in appendix N of the UEFI 2.1 specification. Because error

records persisted using this interface conform to this standardized format, the error information may be used by entities other than the OS.

7.3 Time Services

This section contains function definitions for time-related functions that are typically needed by operating systems at runtime to access underlying hardware that manages time information and services. The purpose of these interfaces is to provide operating system writers with an abstraction for hardware time devices, thereby relieving the need to access legacy hardware devices directly. There is also a stalling function for use in the preboot environment. [Table 31](#) lists the time services functions described in this section:

Table 31. Time Services Functions

Name	Type	Description
GetTime	Runtime	Returns the current time and date, and the time-keeping capabilities of the platform.
SetTime	Runtime	Sets the current local time and date information.
GetWakeupTime	Runtime	Returns the current wakeup alarm clock setting.
SetWakeupTime	Runtime	Sets the system wakeup alarm clock time.

GetTime()

Summary

Returns the current time and date information, and the time-keeping capabilities of the hardware platform.

Prototype

```
typedef
EFI_STATUS
GetTime (
    OUT EFI_TIME           *Time,
    OUT EFI_TIME_CAPABILITIES *Capabilities OPTIONAL
);
```

Parameters

<i>Time</i>	A pointer to storage to receive a snapshot of the current time. Type EFI_TIME is defined in “Related Definitions.”
<i>Capabilities</i>	An optional pointer to a buffer to receive the real time clock device’s capabilities. Type EFI_TIME_CAPABILITIES is defined in “Related Definitions.”

Related Definitions

```

/*****
//EFI_TIME
/*****
// This represents the current time information
typedef struct {
    UINT16    Year;           // 1998 - 20XX
    UINT8     Month;         // 1 - 12
    UINT8     Day;           // 1 - 31
    UINT8     Hour;          // 0 - 23
    UINT8     Minute;        // 0 - 59
    UINT8     Second;        // 0 - 59
    UINT8     Pad1;
    UINT32    Nanosecond;    // 0 - 999,999,999
    INT16     TimeZone;      // -1440 to 1440 or 2047
    UINT8     Daylight;
    UINT8     Pad2;
} EFI_TIME;

/*****
```

```

// Bit Definitions for EFI_TIME.Daylight. See below.
//*****
#define EFI_TIME_ADJUST_DAYLIGHT    0x01
#define EFI_TIME_IN_DAYLIGHT       0x02

//*****
// Value Definition for EFI_TIME.TimeZone. See below.
//*****
#define EFI_UNSPECIFIED_TIMEZONE    0x07FF

```

Year, Month, Day The current local date.

Hour, Minute, Second, Nanosecond

The current local time. Nanoseconds report the current fraction of a second in the device. The format of the time is *hh:mm:ss.nnnnnnnnn*. A battery backed real time clock device maintains the date and time.

TimeZone The time's offset in minutes from GMT. If the value is **EFI_UNSPECIFIED_TIMEZONE**, then the time is interpreted as a local time.

Daylight A bitmask containing the daylight savings time information for the time.

The **EFI_TIME_ADJUST_DAYLIGHT** bit indicates if the time is affected by daylight savings time or not. This value does not indicate that the time has been adjusted for daylight savings time. It indicates only that it should be adjusted when the **EFI_TIME** enters daylight savings time.

If **EFI_TIME_IN_DAYLIGHT** is set, the time has been adjusted for daylight savings time.

All other bits must be zero.

```

//*****
// EFI_TIME_CAPABILITIES
//*****
// This provides the capabilities of the
// real time clock device as exposed through the EFI interfaces.
typedef struct {
    UINT32    Resolution;
    UINT32    Accuracy;
    BOOLEAN   SetsToZero;
} EFI_TIME_CAPABILITIES;

```

Resolution Provides the reporting resolution of the real-time clock device in counts per second. For a normal PC-AT CMOS RTC device, this value would be 1 Hz, or 1, to indicate that the device only reports the time to the resolution of 1 second.

- Accuracy* Provides the timekeeping accuracy of the real-time clock in an error rate of 1E-6 parts per million. For a clock with an accuracy of 50 parts per million, the value in this field would be 50,000,000.
- SetsToZero* A **TRUE** indicates that a time set operation clears the device's time below the *Resolution* reporting level. A **FALSE** indicates that the state below the *Resolution* level of the device is not cleared when the time is set. Normal PC-AT CMOS RTC devices set this value to **FALSE**.

Description

The **GetTime()** function returns a time that was valid sometime during the call to the function. While the returned **EFI_TIME** structure contains *TimeZone* and *Daylight* savings time information, the actual clock does not maintain these values. The current time zone and daylight saving time information returned by **GetTime()** are the values that were last set via [SetTime\(\)](#). The **GetTime()** function should take approximately the same amount of time to read the time each time it is called. All reported device capabilities are to be rounded up.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling **GetTime()**.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_INVALID_PARAMETER	<i>Time</i> is NULL .
EFI_DEVICE_ERROR	The time could not be retrieved due to a hardware error.

SetTime()

Summary

Sets the current local time and date information.

Prototype

```
typedef
EFI_STATUS
SetTime (
    IN EFI_TIME    *Time
);
```

Parameters

Time

A pointer to the current time. Type **EFI_TIME** is defined in the [GetTime\(\)](#) function description. Full error checking is performed on the different fields of the **EFI_TIME** structure (refer to the **EFI_TIME** definition in the [GetTime\(\)](#) function description for full details), and **EFI_INVALID_PARAMETER** is returned if any field is out of range.

Description

The **SetTime()** function sets the real time clock device to the supplied time, and records the current time zone and daylight savings time information. The **SetTime()** function is not allowed to loop based on the current time. For example, if the device does not support a hardware reset for the sub-resolution time, the code is *not* to implement the feature by waiting for the time to wrap.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling **SetTime()**.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_INVALID_PARAMETER	A time field is out of range.
EFI_DEVICE_ERROR	The time could not be set due to a hardware error.

GetWakeupTime()

Summary

Returns the current wakeup alarm clock setting.

Prototype

```
typedef
EFI_STATUS
GetWakeupTime (
    OUT BOOLEAN    *Enabled,
    OUT BOOLEAN    *Pending,
    OUT EFI_TIME   *Time
);
```

Parameters

<i>Enabled</i>	Indicates if the alarm is currently enabled or disabled.
<i>Pending</i>	Indicates if the alarm signal is pending and requires acknowledgement.
<i>Time</i>	The current alarm setting. Type EFI_TIME is defined in the GetTime() function description.

Description

The alarm clock time may be rounded from the set alarm clock time to be within the resolution of the alarm clock device. The resolution of the alarm clock device is defined to be one second.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling **GetWakeupTime()**.

Status Codes Returned

EFI_SUCCESS	The alarm settings were returned.
EFI_INVALID_PARAMETER	<i>Enabled</i> is NULL .
EFI_INVALID_PARAMETER	<i>Pending</i> is NULL .
EFI_INVALID_PARAMETER	<i>Time</i> is NULL .
EFI_DEVICE_ERROR	The wakeup time could not be retrieved due to a hardware error.
EFI_UNSUPPORTED	A wakeup timer is not supported on this platform.

SetWakeupTime()

Summary

Sets the system wakeup alarm clock time.

Prototype

```
typedef
EFI_STATUS
SetWakeupTime (
    IN BOOLEAN    Enable,
    IN EFI_TIME   *Time           OPTIONAL
);
```

Parameters

Enable

Enable or disable the wakeup alarm.

Time

If *Enable* is **TRUE**, the time to set the wakeup alarm for. Type **EFI_TIME** is defined in the [GetTime\(\)](#) function description. If *Enable* is **FALSE**, then this parameter is optional, and may be **NULL**.

Description

Setting a system wakeup alarm causes the system to wake up or power on at the set time. When the alarm fires, the alarm signal is latched until it is acknowledged by calling **SetWakeupTime()** to disable the alarm. If the alarm fires before the system is put into a sleeping or off state, since the alarm signal is latched the system will immediately wake up. If the alarm fires while the system is off and there is insufficient power to power on the system, the system is powered on when power is restored.

For an ACPI-aware operating system, this function only handles programming the wakeup alarm for the desired wakeup time. The operating system still controls the wakeup event as it normally would through the ACPI Power Management register set.

The resolution for the wakeup alarm is defined to be 1 second.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling **SetWakeupTime()**.

Status Codes Returned

EFI_SUCCESS	If <i>Enable</i> is TRUE , then the wakeup alarm was enabled. If <i>Enable</i> is FALSE , then the wakeup alarm was disabled.
EFI_INVALID_PARAMETER	A time field is out of range.
EFI_DEVICE_ERROR	The wakeup time could not be set due to a hardware error.
EFI_UNSUPPORTED	A wakeup timer is not supported on this platform.

7.4 Virtual Memory Services

This section contains function definitions for the virtual memory support that may be optionally used by an operating system at runtime. If an operating system chooses to make EFI runtime service calls in a virtual addressing mode instead of the flat physical mode, then the operating system must use the services in this section to switch the EFI runtime services from flat physical addressing to virtual addressing. [Table 32](#) lists the virtual memory service functions described in this section. The system firmware must follow the processor-specific rules outlined in [Section 2.3.2](#) through [Section 2.3.4](#) in the layout of the EFI memory map to enable the OS to make the required virtual mappings.

Table 32. Virtual Memory Functions

Name	Type	Description
SetVirtualAddressMap	Runtime	Used by an OS loader to convert from physical addressing to virtual addressing.
ConvertPointer	Runtime	Used by EFI components to convert internal pointers when switching to virtual addressing.

SetVirtualAddressMap()

Summary

Changes the runtime addressing mode of EFI firmware from physical to virtual.

Prototype

```
typedef
EFI_STATUS
SetVirtualAddressMap (
    IN UINTN           MemoryMapSize,
    IN UINTN           DescriptorSize,
    IN UINT32          DescriptorVersion,
    IN EFI_MEMORY_DESCRIPTOR *VirtualMap
);
```

Parameters

<i>MemoryMapSize</i>	The size in bytes of <i>VirtualMap</i> .
<i>DescriptorSize</i>	The size in bytes of an entry in the <i>VirtualMap</i> .
<i>DescriptorVersion</i>	The version of the structure entries in <i>VirtualMap</i> .
<i>VirtualMap</i>	An array of memory descriptors which contain new virtual address mapping information for all runtime ranges. Type EFI_MEMORY_DESCRIPTOR is defined in the GetMemoryMap() function description.

Description

The **SetVirtualAddressMap()** function is used by the OS loader. The function can only be called at runtime, and is called by the owner of the system's memory map. I.e., the component which called [ExitBootServices\(\)](#). All events of type **EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE** must be signaled before **SetVirtualAddressMap()** returns.

This call changes the addresses of the runtime components of the EFI firmware to the new virtual addresses supplied in the *VirtualMap*. The supplied *VirtualMap* must provide a new virtual address for every entry in the memory map at **ExitBootServices()** that is marked as being needed for runtime usage. All of the virtual address fields in the *VirtualMap* must be aligned on 4 KB boundaries.

The call to **SetVirtualAddressMap()** must be done with the physical mappings. On successful return from this function, the system must then make any future calls with the newly assigned virtual mappings. All address space mappings must be done in accordance to the cacheability flags as specified in the original address map.

When this function is called, all events that were registered to be signaled on an address map change are notified. Each component that is notified must update any internal pointers for their new addresses. This can be done with the [ConvertPointer\(\)](#) function. Once all events have been notified, the EFI firmware reapplies image “fix-up” information to virtually relocate all runtime

images to their new addresses. In addition, all of the fields of the EFI Runtime Services Table except *SetVirtualAddressMap* and *ConvertPointer* must be converted from physical pointers to virtual pointers using the **ConvertPointer()** service. The **SetVirtualAddressMap()** and **ConvertPointer()** services are only callable in physical mode, so they do not need to be converted from physical pointers to virtual pointers. Several fields of the EFI System Table must be converted from physical pointers to virtual pointers using the **ConvertPointer()** service. These fields include *FirmwareVendor*, *RuntimeServices*, and *ConfigurationTable*. Because contents of both the EFI Runtime Services Table and the EFI System Table are modified by this service, the 32-bit CRC for the EFI Runtime Services Table and the EFI System Table must be recomputed.

A virtual address map may only be applied one time. Once the runtime system is in virtual mode, calls to this function return **EFI_UNSUPPORTED**.

Status Codes Returned

EFI_SUCCESS	The virtual address map has been applied.
EFI_UNSUPPORTED	EFI firmware is not at runtime, or the EFI firmware is already in virtual address mapped mode.
EFI_INVALID_PARAMETER	<i>DescriptorSize</i> or <i>DescriptorVersion</i> is invalid.
EFI_NO_MAPPING	A virtual address was not supplied for a range in the memory map that requires a mapping.
EFI_NOT_FOUND	A virtual address was supplied for an address that is not found in the memory map.

ConvertPointer()

Summary

Determines the new virtual address that is to be used on subsequent memory accesses.

Prototype

```
typedef
EFI_STATUS
ConvertPointer (
    IN UINTN   DebugDisposition,
    IN VOID    **Address
);
```

Parameters

<i>DebugDisposition</i>	Supplies type information for the pointer being converted. See “Related Definitions.”
<i>Address</i>	A pointer to a pointer that is to be fixed to be the value needed for the new virtual address mappings being applied.

Related Definitions

```

//*****
// EFI_OPTIONAL_PTR
//*****
#define EFI_OPTIONAL_PTR          0x00000001
```

Description

The **ConvertPointer()** function is used by an EFI component during the [SetVirtualAddressMap\(\)](#) operation. **ConvertPointer()** must be called using physical address pointers during the execution of **SetVirtualAddressMap()**.

The **ConvertPointer()** function updates the current pointer pointed to by *Address* to be the proper value for the new address map. Only runtime components need to perform this operation. The [CreateEvent\(\)](#) function is used to create an event that is to be notified when the address map is changing. All pointers the component has allocated or assigned must be updated.

If the **EFI_OPTIONAL_PTR** flag is specified, the pointer being converted is allowed to be **NULL**.

Once all components have been notified of the address map change, firmware fixes any compiled in pointers that are embedded in any runtime image.

Status Codes Returned

EFI_SUCCESS	The pointer pointed to by <i>Address</i> was modified.
EFI_NOT_FOUND	The pointer pointed to by <i>Address</i> was not found to be part of the current memory map. This is normally fatal.
EFI_INVALID_PARAMETER	<i>Address</i> is NULL .
EFI_INVALID_PARAMETER	* <i>Address</i> is NULL and <i>DebugDisposition</i> does not have the EFI_OPTIONAL_PTR bit set.

7.5 Miscellaneous Runtime Services

This section contains the remaining function definitions for runtime services not defined elsewhere but which are required to complete the definition of the EFI environment. [Table 33](#) lists the Miscellaneous Runtime Services.

Table 33. Miscellaneous Runtime Services

Name	Type	Description
GetNextHighMonotonicCount	Runtime	Returns the next high 32 bits of the platform's monotonic counter.
ResetSystem	Runtime	Resets the entire platform.
UpdateCapsule	Runtime	Pass capsules to the firmware. The firmware may process the capsules immediately or return a value to be passed into ResetSystem() that will cause the capsule to be processed by the firmware as part of the reset process.
QueryCapsuleCapabilities	Runtime	Returns if the capsule can be supported via UpdateCapsule()

7.5.1 Reset System

This section describes the reset system runtime service and its associated data structures.

ResetSystem()

Summary

Resets the entire platform.

Prototype

```
typedef
VOID
ResetSystem (
    IN EFI_RESET_TYPE  ResetType,
    IN EFI_STATUS      ResetStatus,
    IN UINTN           DataSize,
    IN VOID             *ResetData OPTIONAL
);
```

Parameters

<i>ResetType</i>	The type of reset to perform. Type EFI_RESET_TYPE is defined in “Related Definitions” below.
<i>ResetStatus</i>	The status code for the reset. If the system reset is part of a normal operation, the status code would be EFI_SUCCESS . If the system reset is due to some type of failure the most appropriate EFI Status code would be used.
<i>DataSize</i>	The size, in bytes, of <i>ResetData</i> .
<i>ResetData</i>	For a <i>ResetType</i> of EfiResetCold , EfiResetWarm , or EfiResetShutdown the data buffer starts with a Null-terminated Unicode string, optionally followed by additional binary data. The string is a description that the caller may use to further indicate the reason for the system reset. <i>ResetData</i> is only valid if <i>ResetStatus</i> is something other than EFI_SUCCESS . This pointer must be a physical address. For a <i>ResetType</i> of EfiRestUpdate the data buffer also starts with a Null-terminated string that is followed by a physical VOID * to an EFI_CAPSULE_HEADER .

Related Definitions

```
/**
//*****
// EFI_RESET_TYPE
//*****
typedef enum {
    EfiResetCold,
    EfiResetWarm,
    EfiResetShutdown
} EFI_RESET_TYPE;
```

Description

The **ResetSystem()** function resets the entire platform, including all processors and devices, and reboots the system.

Calling this interface with *ResetType* of **EfiResetCold** causes a system-wide reset. This sets all circuitry within the system to its initial state. This type of reset is asynchronous to system operation and operates without regard to cycle boundaries. **EfiResetCold** is tantamount to a system power cycle.

Calling this interface with *ResetType* of **EfiResetWarm** causes a system-wide initialization. The processors are set to their initial state, and pending cycles are not corrupted. If the system does not support this reset type, then an **EfiResetCold** must be performed.

Calling this interface with *ResetType* of **EfiResetShutdown** causes the system to enter a power state equivalent to the ACPI G2/S5 or G3 states. If the system does not support this reset type, then when the system is rebooted, it should exhibit the **EfiResetCold** attributes. If the ACPI S5 state is supported on the system, then this reset type should not be used.

The platform may optionally log the parameters from any non-normal reset that occurs.

The **ResetSystem()** function does not return.

7.5.2 Get Next High Monotonic Count

This section describes the `GetNextHighMonotonicCount` runtime service and its associated data structures.

GetNextHighMonotonicCount()

Summary

Returns the next high 32 bits of the platform's monotonic counter.

Prototype

```
typedef
EFI_STATUS
GetNextHighMonotonicCount (
    OUT UINT32    *HighCount
);
```

Parameters

HighCount Pointer to returned value.

Description

The **GetNextHighMonotonicCount()** function returns the next high 32 bits of the platform's monotonic counter.

The platform's monotonic counter is comprised of two 32-bit quantities: the high 32 bits and the low 32 bits. During boot service time the low 32-bit value is volatile: it is reset to zero on every system reset and is increased by 1 on every call to **GetNextMonotonicCount()**. The high 32-bit value is nonvolatile and is increased by 1 whenever the system resets or whenever the low 32-bit count (returned by **GetNextMonotonicCount()**) overflows.

The [GetNextMonotonicCount\(\)](#) function is only available at boot services time. If the operating system wishes to extend the platform monotonic counter to runtime, it may do so by utilizing **GetNextHighMonotonicCount()**. To do this, before calling [ExitBootServices\(\)](#) the operating system would call **GetNextMonotonicCount()** to obtain the current platform monotonic count. The operating system would then provide an interface that returns the next count by:

- Adding 1 to the last count.
- Before the lower 32 bits of the count overflows, call **GetNextHighMonotonicCount()**. This will increase the high 32 bits of the platform's nonvolatile portion of the monotonic count by 1.

This function may only be called at Runtime.

Status Codes Returned

EFI_SUCCESS	The next high monotonic count was returned.
EFI_DEVICE_ERROR	The device is not functioning properly.
EFI_INVALID_PARAMETER	<i>HighCount</i> is NULL .

7.5.3 Update Capsule

This runtime function allows a caller to pass information to the firmware. Update Capsule is commonly used to update the firmware FLASH or for an operating system to have information persist across a system reset.

UpdateCapsule()

Summary

Passes capsules to the firmware with both virtual and physical mapping. Depending on the intended consumption, the firmware may process the capsule immediately. If the payload should persist across a system reset, the reset value returned from *EFI_QueryCapsuleCapabilities* must be passed into [ResetSystem\(\)](#) and will cause the capsule to be processed by the firmware as part of the reset process.

Prototype

```
typedef
EFI_STATUS
UpdateCapsule (
    IN EFI_CAPSULE_HEADER    **CapsuleHeaderArray,
    IN UINTN                  CapsuleCount,
    IN EFI_PHYSICAL_ADDRESS   ScatterGatherList OPTIONAL
);
```

Parameters

- CapsuleHeaderArray* Virtual pointer to an array of virtual pointers to the capsules being passed into update capsule. Each capsules is assumed to stored in contiguous virtual memory. The capsules in the *CapsuleHeaderArray* must be the same capsules as the *ScatterGatherList*. The *CapsuleHeaderArray* must have the capsules in the same order as the *ScatterGatherList*.
- CapsuleCount* Number of pointers to **EFI_CAPSULE_HEADER** in *CapsuleHeaderArray*.
- ScatterGatherList* Physical pointer to a set of **EFI_CAPSULE_BLOCK_DESCRIPTOR** that describes the location in physical memory of a set of capsules. See Related Definitions for an explanation of how more than one capsule is passed via this interface. The capsules in the *ScatterGatherList* must be in the same order as the *CapsuleHeaderArray*. This parameter is only referenced if the capsules are defined to persist across system reset.

Related Definitions

```
typedef struct (
    UINT64    Length;
    union {
        EFI_PHYSICAL_ADDRESS    DataBlock;
        EFI_PHYSICAL_ADDRESS    ContinuationPointer;
    }
) EFI_CAPSULE_BLOCK_DESCRIPTOR;
```

Length Length in bytes of the data pointed to by *DataBlock/ContinuationPointer*.

DataBlock Physical address of the data block. This member of the union is used if *Length* is not equal to zero.

ContinuationPointer Physical address of another block of **EFI_CAPSULE_BLOCK_DESCRIPTOR** structures. This member of the union is used if *Length* is equal to zero. If *ContinuationPointer* is zero this entry represents the end of the list.

This data structure defines the *ScatterGatherList* list the OS passes to the firmware. *ScatterGatherList* represents an array of structures and is terminated with a structure member whose *Length* is 0 and *DataBlock* physical address is 0. If *Length* is 0 and *DataBlock* physical address is not 0, the specified physical address is known as a “continuation pointer” and it points to a further list of **EFI_CAPSULE_BLOCK_DESCRIPTOR** structures. A continuation pointer is used to allow the scatter gather list to be contained in physical memory that is not contiguous. It also is used to allow more than a single capsule to be passed at one time.

```
typedef struct {
    EFI_GUID    CapsuleGuid;
    UINT32     HeaderSize;
    UINT32     Flags;
    UINT32     CapsuleImageSize;
} EFI_CAPSULE_HEADER;
```

CapsuleGuid A GUID that defines the contents of a capsule.

HeaderSize The size of the capsule header. This may be larger than the size of the **EFI_CAPSULE_HEADER** since *CapsuleGuid* may imply extended header entries.

Flags Bit-mapped list describing the capsule attributes. The Flag values of 0x0000 – 0xFFFF are defined by *CapsuleGuid*. Flag values of 0x10000 – 0xFFFF0000 are defined by this specification

CapsuleImageSize Size in bytes of the capsule.

```
#define CAPSULE_FLAGS_PERSIST_ACROSS_RESET    0x00010000
#define CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE  0x00020000
```

Description

The **UpdateCapsule ()** function allows the operating system to pass information to firmware. The **UpdateCapsule ()** function supports passing capsules in operating system virtual memory back to firmware. Each capsule is contained in a contiguous virtual memory range in the operating system, but both a virtual and physical mapping for the capsules are passed to the firmware.

If a capsule has the `CAPSULE_FLAGS_PERSIST_ACROSS_RESET` *Flag* set in its header, the firmware will process the capsules after system reset. The caller must ensure to reset the system using the required reset value obtained from `QueryCapsuleCapabilities`. If this flag is not set, the firmware will process the capsules immediately.

A capsule which has the `CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE` *Flag* must have `CAPSULE_FLAGS_PERSIST_ACROSS_RESET` set in its header as well. Firmware that processes a capsule that has the `CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE` *Flag* set in its header will coalesce the contents of the capsule from the `ScatterGatherList` into a contiguous buffer and must then place a pointer to this coalesced capsule in the EFI System Table after the system has been reset. Agents searching for this capsule will look in the `EFI_CONFIGURATION_TABLE` and search for the capsule’s GUID and associated pointer to retrieve the data after the reset.

Table 34. Flag Firmware Behavior

Flags	Firmware Behavior
None	Firmware attempts to immediately processes or launch the capsule. If capsule is not recognized, can expect an error.
<code>CAPSULE_FLAGS_PERSIST_ACROSS_RESET</code>	Firmware will attempt to process or launch the capsule across a reset. If capsule is not recognized, can expect an error. If the processing requires a reset which is unsupported by the platform, expect an error.
<code>CAPSULE_FLAGS_PERSIST_ACROSS_RESET + CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE</code>	Firmware will coalesce the capsule from the <code>ScatterGatherList</code> into a contiguous buffer and place a pointer to the coalesced capsule in the EFI System Table. Platform recognition of the capsule type is not required. If the action requires a reset which is unsupported by the platform, expect an error.

The EFI System Table entry must use the GUID from the `CapsuleGuid` field of the `EFI_CAPSULE_HEADER`. The EFI System Table entry must point to an array of capsules that contain the same `CapsuleGuid` value. The array must be prefixed by a `UINT32` that represents the size of the array of capsules.

The set of capsules is pointed to by `ScatterGatherList` and `CapsuleHeaderArray` so the firmware will know both the physical and virtual addresses of the operating system allocated buffers. The scatter-gather list supports the situation where the virtual address range of a capsule is contiguous, but the physical addresses are not.

If any of the capsules that are passed into this function encounter an error, the entire set of capsules will not be processed and the error encountered will be returned to the caller.

Status Codes Returned

EFI_SUCCESS	Valid capsule was passed. Valid capsule was passed. If CAPSULE_FLAGS_PERSIST_ACROSS_RESET is not set, the capsule has been successfully processed by the firmware.
EFI_INVALID_PARAMETER	<i>CapsuleSize</i> is NULL .
EFI_DEVICE_ERROR	The capsule update was started, but failed due to a device error.
EFI_UNSUPPORTED	The capsule type is not supported on this platform.
EFI_OUT_OF_RESOURCES	There were insufficient resources to process the capsule.

7.5.3.1 Capsule Definition

A capsule is simply a contiguous set of data that starts with an **EFI_CAPSULE_HEADER**. The *CapsuleGuid* field in the header defines the format of the capsule.

The capsule contents are designed to be communicated from an OS-present environment to the system firmware. To allow capsules to persist across system reset, a level of indirection is required for the description of a capsule, since the OS primarily uses virtual memory and the firmware at boot time uses physical memory. This level of abstraction is accomplished via the

EFI_CAPSULE_BLOCK_DESCRIPTOR. The **EFI_CAPSULE_BLOCK_DESCRIPTOR** allows the OS to allocate contiguous virtual address space and describe this address space to the firmware as a discontinuous set of physical address ranges. The firmware is passed both physical and virtual addresses and pointers to describe the capsule so the firmware can process the capsule immediately or defer processing of the capsule until after a system reset.

In most instruction sets and OS architecture, allocation of physical memory is possible only on a “page” granularity (which can range for 4 KB to at least 1 MB). The **EFI_CAPSULE_BLOCK_DESCRIPTOR** must have the following properties to ensure the safe and well defined transition of the data:

- Each new capsule must start on a new page of memory.
- All pages except for the last must be completely filled by the capsule.
 - It is legal to pad the header to make it consume an entire page of data to enable the passing of page aligned data structures via a capsule. The last page must have at least one byte of capsule in it.
- Pages must be naturally aligned
- Pages may not overlap on another
- Firmware may never make an assumption about the page sizes the operating system is using.

Multiple capsules can be concatenated together and passed via a single call to **UpdateCapsule()**. The physical address description of capsules are concatenated by converting the terminating **EFI_CAPSULE_BLOCK_DESCRIPTOR** entry of the 1st capsule into a continuation pointer by making it point to the **EFI_CAPSULE_BLOCK_DESCRIPTOR** that represents the start of the 2nd capsule. There is only a single terminating **EFI_CAPSULE_BLOCK_DESCRIPTOR** entry and it is at the end of the last capsule in the chain.

The following algorithm must be used to find multiple capsules in a single scatter gather list:

- Look at the capsule header to determine the size of the capsule

- The first Capsule header is always pointed to by the first **EFI_CAPSULE_BLOCK_DESCRIPTOR** entry
- Walk the **EFI_CAPSULE_BLOCK_DESCRIPTOR** list keeping a running count of the size each entry represents.
- If the **EFI_CAPSULE_BLOCK_DESCRIPTOR** entry is a continuation pointer and the running current capsule size count is greater than or equal to the size of the current capsule this is the start of the next capsule.
- Make the new capsules the current capsule and repeat the algorithm.

Figure 21 shows a Scatter-Gather list of **EFI_CAPSULE_BLOCK_DESCRIPTOR** structures that describes two capsules. The left side of the figure shows OS view of the capsules as two separate contiguous virtual memory buffers. The center of the figure shows the layout of the data in system memory. The right hand side of the figure shows the *ScatterGatherList* list passed into the firmware. Since there are two capsules two independent **EFI_CAPSULE_BLOCK_DESCRIPTOR** lists exist that were joined together via a continuation pointer in the first list.

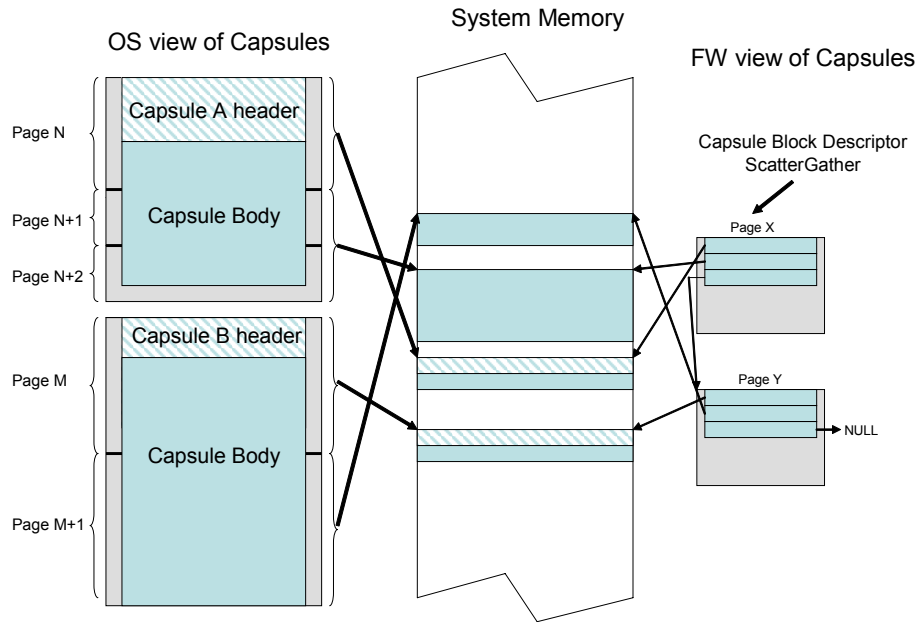


Figure 21. Scatter-Gather List of **EFI_CAPSULE_BLOCK_DESCRIPTOR** Structures

QueryCapsuleCapabilities()

Summary

Returns if the capsule can be supported via **UpdateCapsule()**.

Prototype

```
typedef
EFI_STATUS
QueryCapsuleCapabilities (
    IN EFI_CAPSULE_HEADER  **CapsuleHeaderArray,
    IN UINTN                CapsuleCount,
    OUT UINT64              *MaximumCapsuleSize,
    OUT EFI_RESET_TYPE     *ResetType
);
```

CapsuleHeaderArray Virtual pointer to an array of virtual pointers to the capsules being passed into update capsule. The capsules are assumed to stored in contiguous virtual memory.

CapsuleCount Number of pointers to **EFI_CAPSULE_HEADER** in *CapsuleHeaderArray*.

MaximumCapsuleSize On output the maximum size in bytes that **UpdateCapsule()** can support as an argument to **UpdateCapsule()** via *CapsuleHeaderArray* and *ScatterGatherList*. Undefined on input.

ResetType Returns the type of reset required for the capsule update. Undefined on input.

Description

The **QueryCapsuleCapabilities()** function allows a caller to test to see if a capsule or capsules can be updated via **UpdateCapsule()**. The Flags values in the capsule header and size of the entire capsule is checked.

If the caller needs to query for generic capsule capability a fake **EFI_CAPSULE_HEADER** can be constructed where *CapsuleImageSize* is equal to *HeaderSize* that is equal to sizeof (**EFI_CAPSULE_HEADER**). To determine reset requirements, **CAPSULE_FLAGS_PERSIST_ACROSS_RESET** should be set in the *Flags* field of the **EFI_CAPSULE_HEADER**.

Status Codes Returned

EFI_SUCCESS	Valid answer returned.
EFI_INVALID_PARAMETER	<i>MaximumCapsuleSize</i> is NULL .
EFI_UNSUPPORTED	The capsule type is not supported on this platform, and <i>MaximumCapsuleSize</i> and <i>ResetType</i> are undefined.
EFI_OUT_OF_RESOURCES	There were insufficient resources to process the query request.

Protocols — EFI Loaded Image

This section defines **EFI_LOADED_IMAGE_PROTOCOL**. This protocol describes an Image that has been loaded into memory. This description includes the source from which the image was loaded, the current location of the image in memory, the type of memory allocated for the image, and the parameters passed to the image when it was invoked.

EFI_LOADED_IMAGE_PROTOCOL

Summary

Can be used on any image handle to obtain information about the loaded image.

GUID

```
#define EFI_LOADED_IMAGE_PROTOCOL_GUID\
    {0x5B1B31A1, 0x9562, 0x11d2, 0x8E, 0x3F, 0x00, 0xA0, 0xC9, 0x69,
     0x72, 0x3B}
```

Revision Number

```
#define EFI_LOADED_IMAGE_PROTOCOL_REVISION 0x1000
```

Protocol Interface Structure

```
typedef struct {
    UINT32          Revision;
    EFI_HANDLE      ParentHandle;
    EFI_SYSTEM_TABLE *SystemTable;

    // Source location of the image
    EFI_HANDLE      DeviceHandle;
    EFI_DEVICE_PATH_PROTOCOL *FilePath;
    VOID           *Reserved;

    // Image's load options
    UINT32          LoadOptionsSize;
    VOID           *LoadOptions;

    // Location where image was loaded
    VOID           *ImageBase;
    UINT64          ImageSize;
    EFI_MEMORY_TYPE ImageCodeType;
    EFI_MEMORY_TYPE ImageDataType;
```

```

    EFI_IMAGE_UNLOAD          Unload;
} EFI_LOADED_IMAGE_PROTOCOL;

```

Parameters

<i>Revision</i>	Defines the revision of the EFI_LOADED_IMAGE_PROTOCOL structure. All future revisions will be backward compatible to the current revision.
<i>ParentHandle</i>	Parent image's image handle. NULL if the image is loaded directly from the firmware's boot manager. Type EFI_HANDLE is defined in Section 6 .
<i>SystemTable</i>	The image's EFI system table pointer. Type EFI_SYSTEM_TABLE is defined in Section 4 .
<i>DeviceHandle</i>	The device handle that the EFI Image was loaded from. Type EFI_HANDLE is defined in Section 6 .
<i>FilePath</i>	A pointer to the file path portion specific to <i>DeviceHandle</i> that the EFI Image was loaded from. EFI_DEVICE_PATH_PROTOCOL is defined in Section 9.2 .
<i>Reserved</i>	Reserved. DO NOT USE.
<i>LoadOptionsSize</i>	The size in bytes of <i>LoadOptions</i> .
<i>LoadOptions</i>	A pointer to the image's binary load options.
<i>ImageBase</i>	The base address at which the image was loaded.
<i>ImageSize</i>	The size in bytes of the loaded image.
<i>ImageCodeType</i>	The memory type that the code sections were loaded as. Type EFI_MEMORY_TYPE is defined in Section 6 .
<i>ImageDataType</i>	The memory type that the data sections were loaded as. Type EFI_MEMORY_TYPE is defined in Section 6 .
<i>Unload</i>	Function that unloads the image. See Unload() .

Description

Each loaded image has an image handle that supports **EFI_LOADED_IMAGE_PROTOCOL**. When an image is started, it is passed the image handle for itself. The image can use the handle to obtain its relevant image data stored in the **EFI_LOADED_IMAGE_PROTOCOL** structure, such as its load options.

EFI_LOADED_IMAGE_PROTOCOL.Unload()

Summary

Unloads an image from memory.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_IMAGE_UNLOAD) (
    IN EFI_HANDLE    ImageHandle,
);
```

Parameters

ImageHandle

The handle to the image to unload. Type [EFI_HANDLE](#) is defined in [Section 6.3.1](#).

Description

The **Unload()** function unloads an image from memory if *ImageHandle* is valid.

Status Codes Returned

EFI_SUCCESS	The image was unloaded.
EFI_INVALID_PARAMETER	The <i>ImageHandle</i> was not valid.

Protocols — Device Path Protocol

This section contains the definition of the device path protocol and the information needed to construct and manage device paths in the UEFI environment. A device path is constructed and used by the firmware to convey the location of important devices, such as the boot device and console, consistent with the software-visible topology of the system.

9.1 Device Path Overview

A *Device Path* is used to define the programmatic path to a device. The primary purpose of a Device Path is to allow an application, such as an OS loader, to determine the physical device that the interfaces are abstracting.

A collection of device paths is usually referred to as a name space. ACPI, for example, is rooted around a name space that is written in ASL (ACPI Source Language). Given that EFI does not replace ACPI and defers to ACPI when ever possible, it would seem logical to utilize the ACPI name space in EFI. However, the ACPI name space was designed for usage at operating system runtime and does not fit well in platform firmware or OS loaders. Given this, EFI defines its own name space, called a *Device Path*.

A Device Path is designed to make maximum leverage of the ACPI name space. One of the key structures in the Device Path defines the linkage back to the ACPI name space. The Device Path also is used to fill in the gaps where ACPI defers to buses with standard enumeration algorithms. The Device Path is able to relate information about which device is being used on buses with standard enumeration mechanisms. The Device Path is also used to define the location on a medium where a file should be, or where it was loaded from. A special case of the Device Path can also be used to support the optional booting of legacy operating systems from legacy media.

The Device Path was designed so that the OS loader and the operating system could tell which devices the platform firmware was using as boot devices. This allows the operating system to maintain a view of the system that is consistent with the platform firmware. An example of this is a “headless” system that is using a network connection as the boot device and console. In such a case, the firmware will convey to the operating system the network adapter and network protocol information being used as the console and boot device in the device path for these devices.

9.2 EFI Device Path Protocol

This section provides a detailed description of **EFI_DEVICE_PATH_PROTOCOL**.

EFI_DEVICE_PATH_PROTOCOL

Summary

Can be used on any device handle to obtain generic path/location information concerning the physical device or logical device. If the handle does not logically map to a physical device, the

handle may not necessarily support the device path protocol. The device path describes the location of the device the handle is for. The size of the Device Path can be determined from the structures that make up the Device Path.

GUID

```
#define EFI_DEVICE_PATH_PROTOCOL_GUID \
{0x09576e91,0x6d3f,0x11d2,0x8e,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}
```

Protocol Interface Structure

```
/**
 *
 */
// EFI_DEVICE_PATH_PROTOCOL
/**
 *
 */
typedef struct _EFI_DEVICE_PATH_PROTOCOL {
    UINT8  Type;
    UINT8  SubType;
    UINT8  Length[2];
} EFI_DEVICE_PATH_PROTOCOL;
```

Description

The executing EFI Image may use the device path to match its own device drivers to the particular device. Note that the executing UEFI OS loader and UEFI application images must access all physical devices via Boot Services device handles until [ExitBootServices\(\)](#) is successfully called. A UEFI driver may access only a physical device for which it provides functionality.

9.3 Device Path Nodes

There are six major types of Device Path nodes:

- **Hardware Device Path.** This Device Path defines how a device is attached to the resource domain of a system, where resource domain is simply the shared memory, memory mapped I/O, and I/O space of the system.
- **ACPI Device Path.** This Device Path is used to describe devices whose enumeration is not described in an industry-standard fashion. These devices must be described using ACPI AML in the ACPI name space; this Device Path is a linkage to the ACPI name space.
- **Messaging Device Path.** This Device Path is used to describe the connection of devices outside the resource domain of the system. This Device Path can describe physical messaging information such as a SCSI ID, or abstract information such as networking protocol IP addresses.
- **Media Device Path.** This Device Path is used to describe the portion of a medium that is being abstracted by a boot service. For example, a Media Device Path could define which partition on a hard drive was being used.
- **BIOS Boot Specification Device Path.** This Device Path is used to point to boot legacy operating systems; it is based on the BIOS Boot Specification Version 1.01. Refer to [Appendix Q](#) for details on obtaining this specification.

- End of Hardware Device Path. Depending on the Sub-Type, this Device Path node is used to indicate the end of the Device Path instance or Device Path structure.

9.3.1 Generic Device Path Structures

A Device Path is a variable-length binary structure that is made up of variable-length generic Device Path nodes. [Table 35](#) defines the structure of a variable-length generic Device Path node and the lengths of its components. The table defines the type and sub-type values corresponding to the Device Paths described in [Section 9.3](#); all other type and sub-type values are *Reserved*.

Table 35. Generic Device Path Node Structure

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 0x01 – Hardware Device Path Type 0x02 – ACPI Device Path Type 0x03 – Messaging Device Path Type 0x04 – Media Device Path Type 0x05 – BIOS Boot Specification Device Path Type 0x7F – End of Hardware Device Path
Sub-Type	1	1	Sub-Type – Varies by Type. (See Table 36 .)
Length	2	2	Length of this structure in bytes. Length is 4 + <i>n</i> bytes.
Specific Device Path Data	4	<i>n</i>	Specific Device Path data. Type and Sub-Type define type of data. Size of data is included in Length.

A Device Path is a series of generic Device Path nodes. The first Device Path node starts at byte offset zero of the Device Path. The next Device Path node starts at the end of the previous Device Path node. Therefore all nodes are byte-packed data structures that may appear on any byte boundary. All code references to device path notes must assume all fields are unaligned. Since every Device Path node contains a length field in a known place, it is possible to traverse Device Path nodes that are of an unknown type. There is no limit to the number, type, or sequence of nodes in a Device Path.

A Device Path is terminated by an End of Hardware Device Path node. This type of node has two sub-types (see [Table 36](#)):

- *End This Instance of a Device Path* (sub-type 0x01). This type of node terminates one Device Path instance and denotes the start of another. This is only required when an environment variable represents multiple devices. An example of this would be the **ConsoleOut** environment variable that consists of both a VGA console and serial output console. This variable would describe a console output stream that is sent to both VGA and serial concurrently and thus has a Device Path that contains two complete Device Paths.
- *End Entire Device Path* (sub-type 0xFF). This type of node terminates an entire Device Path. Software searches for this sub-type to find the end of a Device Path. All Device Paths must end with this sub-type.

Table 36. Device Path End Structure

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 0x7F – End of Hardware Device Path
Sub-Type	1	1	Sub-Type 0xFF – End Entire Device Path, or Sub-Type 0x01 – End This Instance of a Device Path and start a new Device Path
Length	2	2	Length of this structure in bytes. Length is 4 bytes.

9.3.2 Hardware Device Path

This Device Path defines how a device is attached to the resource domain of a system, where resource domain is simply the shared memory, memory mapped I/O, and I/O space of the system. It is possible to have multiple levels of Hardware Device Path such as a PCCARD device that was attached to a PCCARD PCI controller.

9.3.2.1 PCI Device Path

The Device Path for PCI defines the path to the PCI configuration space address for a PCI device. There is one PCI Device Path entry for each device and function number that defines the path from the root PCI bus to the device. Because the PCI bus number of a device may potentially change, a flat encoding of single PCI Device Path entry cannot be used. An example of this is when a PCI device is behind a bridge, and one of the following events occurs:

- OS performs a Plug and Play configuration of the PCI bus.
- A hot plug of a PCI device is performed.
- The system configuration changes between reboots.

The PCI Device Path entry must be preceded by an ACPI Device Path entry that uniquely identifies the PCI root bus. The programming of root PCI bridges is not defined by any PCI specification and this is why an ACPI Device Path entry is required.

Table 37. PCI Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 1 – Hardware Device Path
Sub-Type	1	1	Sub-Type 1 – PCI
Length	2	2	Length of this structure is 6 bytes
Function	4	1	PCI Function Number
Device	5	1	PCI Device Number

9.3.2.2 PCCARD Device Path

Table 38. PCCARD Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 1 – Hardware Device Path
Sub-Type	1	1	Sub-Type 2 – PCCARD
Length	2	2	Length of this structure in bytes. Length is 5 bytes.
Function Number	4	1	Function Number (0 = First Function)

9.3.2.3 Memory Mapped Device Path

Table 39. Memory Mapped Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 1 – Hardware Device Path.
Sub-Type	1	1	Sub-Type 3 – Memory Mapped.
Length	2	2	Length of this structure in bytes. Length is 24 bytes.
Memory Type	4	4	EFI_MEMORY_TYPE . Type EFI_MEMORY_TYPE is defined in the AllocatePages () function description.
Start Address	8	8	Starting Memory Address.
End Address	16	8	Ending Memory Address.

9.3.2.4 Vendor Device Path

The Vendor Device Path allows the creation of vendor-defined Device Paths. A vendor must allocate a Vendor GUID for a Device Path. The Vendor GUID can then be used to define the contents on the *n* bytes that follow in the Vendor Device Path node.

Table 40. Vendor-Defined Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 1 – Hardware Device Path.
Sub-Type	1	1	Sub-Type 4 – Vendor.
Length	2	2	Length of this structure in bytes. Length is 20 + <i>n</i> bytes.
Vendor_GUID	4	16	Vendor-assigned GUID that defines the data that follows.
Vendor Defined Data	20	<i>n</i>	Vendor-defined variable size data.

9.3.2.5 Controller Device Path

Table 41. Controller Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 1 – Hardware Device Path.
Sub-Type	1	1	Sub-Type 5 – Controller.
Length	2	2	Length of this structure in bytes. Length is 8 bytes.
Controller Number	4	4	Controller number.

9.3.3 ACPI Device Path

This Device Path contains ACPI Device IDs that represent a device's Plug and Play Hardware ID and its corresponding unique persistent ID. The ACPI IDs are stored in the `_HID`, `_CID`, and `_UID` device identification objects that are associated with a device. The ACPI Device Path contains values that must match exactly the ACPI name space that is provided by the platform firmware to the operating system. Refer to the ACPI specification for a complete description of the `_HID`, `_CID`, and `_UID` device identification objects.

The `_HID` and `_CID` values are optional device identification objects that appear in the ACPI name space. If only `_HID` is present, the `_HID` must be used to describe any device that will be enumerated by the ACPI driver. The `_CID`, if present, contains information that is important for the OS to attach generic driver (e.g., PCI Bus Driver), while the `_HID` contains information important for the OS to attach device-specific driver. The ACPI bus driver only enumerates a device when no standard bus enumerator exists for a device.

The `_UID` object provides the OS with a serial number-style ID for a device that does not change across reboots. The object is optional, but is required when a system contains two devices that report the same `_HID`. The `_UID` only needs to be unique among all device objects with the same `_HID` value. If no `_UID` exists in the ACPI name space for a `_HID` the value of zero must be stored in the `_UID` field of the ACPI Device Path.

The ACPI Device Path is only used to describe devices that are not defined by a Hardware Device Path. An `_HID` (along with `_CID` if present) is required to represent a PCI root bridge, since the PCI specification does not define the programming model for a PCI root bridge. There are two subtypes of the ACPI Device Path: a simple subtype that only includes the `_HID` and `_UID` fields, and an extended subtype that includes the `_HID`, `_CID`, and `_UID` fields.

The ACPI Device Path node only supports numeric 32-bit values for the `_HID` and `_UID` values. The Expanded ACPI Device Path node supports both numeric and string values for the `_HID`, `_UID`, and `_CID` values. As a result, the ACPI Device Path node is smaller and should be used if possible to reduce the size of device paths that may potentially be stored in nonvolatile storage. If a string value is required for the `_HID` field, or a string value is required for the `_UID` field, or a `_CID` field is required, then the Expanded ACPI Device Path node must be used. If a string field of the Expanded ACPI Device Path node is present, then the corresponding numeric field is ignored.

The `_HID` and `_CID` fields in the ACPI Device Path node and Expanded ACPI Device Path node are stored as a 32-bit compressed EISA-type IDs. The following macro can be used to compute these EISA-type IDs from a Plug and Play Hardware ID. The Plug and Play Hardware IDs used to

compute the `_HID` and `_CID` fields in the EFI device path nodes must match the Plug and Play Hardware IDs used to build the matching entries in the ACPI tables. The compressed EISA-type IDs produced by this macro differ from the compressed EISA-type IDs stored in ACPI tables. As a result, the compressed EISA-type IDs from the ACPI Device Path nodes cannot be directly compared to the compressed EISA-type IDs from the ACPI table.

```
#define EFI_PNP_ID(ID) (UINT32)((ID) << 16) | 0x41D0)
#define EISA_PNP_ID(ID) EFI_PNP_ID(ID)
```

Table 42. ACPI Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 2 – ACPI Device Path.
Sub-Type	1	1	Sub-Type 1 ACPI Device Path.
Length	2	2	Length of this structure in bytes. Length is 12 bytes.
_HID	4	4	Device's PnP hardware ID stored in a numeric 32-bit compressed EISA-type ID. This value must match the corresponding <code>_HID</code> in the ACPI name space.
_UID	8	4	Unique ID that is required by ACPI if two devices have the same <code>_HID</code> . This value must also match the corresponding <code>_UID/_HID</code> pair in the ACPI name space. Only the 32-bit numeric value type of <code>_UID</code> is supported; thus strings must not be used for the <code>_UID</code> in the ACPI name space.

Table 43. Expanded ACPI Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 2 – ACPI Device Path.
Sub-Type	1	1	Sub-Type 2 Expanded ACPI Device Path.
Length	2	2	Length of this structure in bytes. Minimum length is 19 bytes. The actual size will depend on the size of the <code>_HIDSTR</code> , <code>_UIDSTR</code> , and <code>_CIDSTR</code> fields.
_HID	4	4	Device's PnP hardware ID stored in a numeric 32-bit compressed EISA-type ID. This value must match the corresponding <code>_HID</code> in the ACPI name space.
_UID	8	4	Unique ID that is required by ACPI if two devices have the same <code>_HID</code> . This value must also match the corresponding <code>_UID/_HID</code> pair in the ACPI name space.
_CID	12	4	Device's compatible PnP hardware ID stored in a numeric 32-bit compressed EISA-type ID. This value must match at least one of the compatible device IDs returned by the corresponding <code>_CID</code> in the ACPI name space.

Mnemonic	Byte Offset	Byte Length	Description
_HIDSTR	16	>=1	Device's PnP hardware ID stored as a null-terminated ASCII string. This value must match the corresponding _HID in the ACPI name space. If the length of this string not including the null-terminator is 0, then the _HID field is used. If the length of this null-terminated string is greater than 0, then this field supersedes the _HID field.
_UIDSTR	Varies	>=1	Unique ID that is required by ACPI if two devices have the same _HID. This value must also match the corresponding _UID/_HID pair in the ACPI name space. This value is stored as a null-terminated ASCII string. If the length of this string not including the null-terminator is 0, then the _UID field is used. If the length of this null-terminated string is greater than 0, then this field supersedes the _UID field. The Byte Offset of this field can be computed by adding 16 to the size of the _HIDSTR field.
_CIDSTR	Varies	>=1	Device's compatible PnP hardware ID stored as a null-terminated ASCII string. This value must match at least one of the compatible device IDs returned by the corresponding _CID in the ACPI name space. If the length of this string not including the null-terminator is 0, then the _CID field is used. If the length of this null-terminated string is greater than 0, then this field supersedes the _CID field. The Byte Offset of this field can be computed by adding 16 to the sum of the sizes of the _HIDSTR and _UIDSTR fields.

9.3.4 ACPI _ADR Device Path

The _ADR device path is used to contain video output device attributes to support the Graphics Output Protocol. The device path can contain multiple _ADR entries if multiple video output devices are displaying the same output.

Table 44. ACPI _ADR Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 2 – ACPI Device Path
Sub-Type	1	1	Sub-Type3 _ADR Device Path
Length	2	2	Length of this structure in bytes. Minimum length is 8.
_ADR	4	4	_ADR value. For video output devices the value of this field comes from Table B-2 ACPI 3.0 specification. At least one _ADR value is required
Additional _ADR	8	N	This device path may optionally contain more than one _ADR entry.

9.3.5 Messaging Device Path

This Device Path is used to describe the connection of devices outside the resource domain of the system. This Device Path can describe physical messaging information like SCSI ID, or abstract information like networking protocol IP addresses.

9.3.5.1 ATAPI Device Path

Table 45. ATAPI Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 1 – ATAPI
Length	2	2	Length of this structure in bytes. Length is 8 bytes.
PrimarySecondary	4	1	Set to zero for primary or one for secondary
SlaveMaster	5	1	Set to zero for master or one for slave mode
Logical Unit Number	6	2	Logical Unit Number

9.3.5.2 SCSI Device Path

Table 46. SCSI Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 2 – SCSI
Length	2	2	Length of this structure in bytes. Length is 8 bytes.
Target ID	4	2	Target ID on the SCSI bus (PUN)
Logical Unit Number	6	2	Logical Unit Number (LUN)

9.3.5.3 Fibre Channel Device Path

Table 47. Fibre Channel Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 3 – Fibre Channel
Length	2	2	Length of this structure in bytes. Length is 24 bytes.
Reserved	4	4	Reserved
World Wide Number	8	8	Fibre Channel World Wide Number
Logical Unit Number	16	8	Fibre Channel Logical Unit Number

9.3.5.4 1394 Device Path

Table 48. 1394 Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 4 – 1394
Length	2	2	Length of this structure in bytes. Length is 16 bytes.
Reserved	4	4	Reserved
GUID ¹	8	8	1394 Global Unique ID (GUID) ¹

Note: ¹ The usage of the term GUID is per the 1394 specification. This is not the same as the **EFI_GUID** type defined in the EFI Specification.

9.3.5.5 USB Device Paths

Table 49. USB Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 5 – USB
Length	2	2	Length of this structure in bytes. Length is 6 bytes.
USB Parent Port Number	4	1	USB Parent Port Number
Interface	5	1	USB Interface Number

9.3.5.6 SATA Device Path

Table 50. SATA Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 18 – SATA
Length	2	2	Length of this structure in bytes. Length is 10 bytes.
HBA Port Number	4	2	The HBA port number that facilitates the connection to the device or a port multiplier. The value 0xFFFF is reserved.
Port Multiplier Port Number	6	2	The Port multiplier port number that facilitates the connection to the device. Set to 0x if device is directly connected to the HBA.
Logical Unit Number	8	2	Logical Unit Number.

9.3.5.6.1 USB Device Path Example

[Table 51](#) shows an example device path for a USB controller on a desktop platform. This USB Controller is connected to the port 0 of the root hub, and its interface number is 0. The USB Host Controller is a PCI device whose PCI device number 0x1F and PCI function 0x02. So, the whole device path for this USB Controller consists an ACPI Device Path Node, a PCI Device Path Node, a USB Device Path Node and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is: `PciRoot(0)/PCI(31,2)/USB(0,0)`.

Table 51. USB Device Path Examples

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID</code> PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x1F	PCI Function
0x11	0x01	0x02	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x13	0x01	0x05	Sub type – USB
0x14	0x02	0x06	Length – 0x06 bytes
0x16	0x01	0x00	Parent Hub Port Number
0x17	0x01	0x00	Controller Interface Number
0x18	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x19	0x01	0xFF	Sub type – End of Entire Device Path
0x1A	0x02	0x04	Length – 0x04 bytes

Another example is a USB Controller (interface number 0) that is connected to port 3 of a USB Hub Controller (interface number 0), and this USB Hub Controller is connected to the port 1 of the root hub. The shorthand notation for this device path is:

`PciRoot(0)/PCI(31,2)/USB(1,0)/USB(3,0)`.

[Table 51](#) shows the device path for this USB Controller.

Table 52. Another USB Device Path Example

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path

Byte Offset	Byte Length	Data	Description
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x1F	PCI Function
0x11	0x01	0x02	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x13	0x01	0x05	Sub type – USB
0x14	0x02	0x06	Length – 0x06 bytes
0x16	0x01	0x01	Parent Hub Port Number
0x17	0x01	0x00	Controller Interface Number
0x18	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x19	0x01	0x05	Sub type – USB
0x1A	0x02	0x06	Length – 0x06 bytes
0x1C	0x01	0x03	Parent Hub Port Number
0x1D	0x01	0x00	Controller Interface Number
0x1E	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x1F	0x01	0xFF	Sub type – End of Entire Device Path
0x20	0x02	0x04	Length – 0x04 bytes

9.3.5.7 USB Device Paths (WWID)

This device path describes a USB device using its serial number.

Specifications, such as the USB Mass Storage class, bulk-only transport subclass, require that some portion of the suffix of the device’s serial number be unique with respect to the vendor and product id for the device. So, in order to avoid confusion and overlap of WWID’s, the interface’s class, subclass, and protocol are included.

Table 53. USB WWID Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 - Messaging Device Path
Sub-Type	1	1	Sub-Type 16– USB WWID
Length	2	2	Length of this structure in bytes. Length is 10+
• Interface Number	4	2	USB interface number
• Device Vendor Id	6	2	USB vendor id of the device

Mnemonic	Byte Offset	Byte Length	Description
• Device Product Id	8	2	USB product id of the device
• Serial Number	10	n	Last 64-or-fewer UTF-16 characters of the USB serial number. The length of the string is determined by the <i>Length</i> field less the offset of the <i>Serial Number</i> field (10)

Devices that do not have a serial number string must use with the USB Device Path (type 5) as described in [Section 9.3.5.5](#).

Including the interface as part of this node allows distinction for multi-interface devices, e.g., an HID interface and a Mass Storage interface on the same device, or two Mass Storage interfaces.

[Section 3.1.2](#) defines special rules for processing the USB WWID Device Path. These special rules enable a device location to change and still have the system boot from the device.

9.3.5.8 Device Logical Unit

For some classes of devices, such as USB Mass Storage, it is necessary to specify the Logical Unit Number (LUN), since a single device may have multiple logical units. In order to boot from one of these logical units of the device, the Device Logical Unit device node is appended to the device path. The EFI path node subtype is defined, as in [Table 54](#).

Table 54. Device Logical Unit

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 - Messaging Device Path
Sub-Type	1	1	Sub-Type 17 – Device Logical unit
Length	2	2	Length of this structure in bytes. Length is 5
LUN	4	1	Logical Unit Number for the interface

[Section 3.1.2](#) defines special rules for processing the USB Class Device Path. These special rules enable a device location to change and still have the system recognize the device.

[Section 3.2](#) defines how the *ConIn*, *ConOut*, and *ErrOut* variables are processed and contains special rules for processing the USB Class device path. These special rules allow all USB keyboards to be specified as valid input devices.

9.3.5.9 USB Device Path (Class)

Table 55. USB Class Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 - Messaging Device Path.
Sub-Type	1	1	Sub-Type 15 - USB Class.
Length	2	2	Length of this structure in bytes. Length is 11 bytes.

Mnemonic	Byte Offset	Byte Length	Description
Vendor ID	4	2	Vendor ID assigned by USB-IF. A value of 0xFFFF will match any Vendor ID.
Product ID	6	2	Product ID assigned by USB-IF. A value of 0xFFFF will match any Product ID.
Device Class	8	1	The class code assigned by the USB-IF. A value of 0xFF will match any class code.
Device Subclass	9	1	The subclass code assigned by the USB-IF. A value of 0xFF will match any subclass code.
Device Protocol	10	1	The protocol code assigned by the USB-IF. A value of 0xFF will match any protocol code.

9.3.5.10 I₂O Device Path

Table 56. I₂O Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 6 – I2O Random Block Storage Class
Length	2	2	Length of this structure in bytes. Length is 8 bytes.
TID	4	4	Target ID (TID) for a device

9.3.5.11 MAC Address Device Path

Table 57. MAC Address Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 11 – MAC Address for a network interface
Length	2	2	Length of this structure in bytes. Length is 37 bytes.
MAC Address	4	32	The MAC address for a network interface padded with 0s
IfType	36	1	Network interface type(i.e. 802.3, FDDI). See RFC 1700

9.3.5.12 IPv4 Device Path

Table 58. IPv4 Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 12 – IPv4
Length	2	2	Length of this structure in bytes. Length is 19 bytes.

Local IP Address	4	4	The local IPv4 address
Remote IP Address	8	4	The remote IPv4 address
Local Port	12	2	The local port number
Remote Port	14	2	The remote port number
Protocol	16	2	The network protocol(i.e. UDP, TCP). See RFC 1700
StaticIPAddress	18	1	0x00 - The Source IP Address was assigned though DHCP 0x01 - The Source IP Address is statically bound

9.3.5.13 IPv6 Device Path

Table 59. IPv6 Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 13 – IPv6
Length	2	2	Length of this structure in bytes. Length is 43 bytes.
Local IP Address	4	16	The local IPv6 address
Remote IP Address	20	16	The remote IPv6 address
Local Port	36	2	The local port number
Remote Port	38	2	The remote port number
Protocol	40	2	The network protocol (i.e. UDP, TCP). See RFC 1700
StaticIPAddress	42	1	0x00 - The Source IP Address was assigned though DHCP 0x01 - The Source IP Address is statically bound

9.3.5.14 InfiniBand Device Path

Table 60. InfiniBand Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 9 – InfiniBand
Length	2	2	Length of this structure in bytes. Length is 48 bytes.
Resource Flags	4	4	Flags to help identify/manage InfiniBand device path elements: <ul style="list-style-type: none"> • Bit 0 – IOC/Service (0b = IOC, 1b = Service) • Bit 1 – Extend Boot Environment • Bit 2 – Console Protocol • Bit 3 – Storage Protocol • Bit 4 – Network Protocol All other bits are reserved.
PORT GID	8	16	128-bit Global Identifier for remote fabric port

IOC GUID/Service ID	24	8	64-bit unique identifier to remote IOC or server process. Interpretation of field specified by Resource Flags (bit 0)
Target Port ID	32	8	64-bit persistent ID of remote IOC port
Device ID	40	8	64-bit persistent ID of remote device
Note: The usage of the terms GUID and GID is per the InfiniBand Specification. The term GUID is not the same as the EFI_GUID type defined in this EFI Specification.			

9.3.5.15 UART Device Path

Table 61. UART Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 14 – UART
Length	2	2	Length of this structure in bytes. Length is 19 bytes.
Reserved	4	4	Reserved
Baud Rate	8	8	The baud rate setting for the UART style device. A value of 0 means that the device's default baud rate will be used.
Data Bits	16	1	The number of data bits for the UART style device. A value of 0 means that the device's default number of data bits will be used.
Parity	17	1	The parity setting for the UART style device. Parity 0x00 - Default Parity Parity 0x01 - No Parity Parity 0x02 - Even Parity Parity 0x03 - Odd Parity Parity 0x04 - Mark Parity Parity 0x05 - Space Parity
Stop Bits	18	1	The number of stop bits for the UART style device. Stop Bits 0x00 - Default Stop Bits Stop Bits 0x01 - 1 Stop Bit Stop Bits 0x02 - 1.5 Stop Bits Stop Bits 0x03 - 2 Stop Bits

9.3.5.16 Vendor-Defined Messaging Device Path

Table 62. Vendor-Defined Messaging Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 10 – Vendor
Length	2	2	Length of this structure in bytes. Length is 20 + <i>n</i> bytes.
Vendor GUID	4	16	Vendor-assigned GUID that defines the data that follows
Vendor Defined Data	20	<i>n</i>	Vendor-defined variable size data

The following GUIDs are used with a Vendor-Defined Messaging Device Path to describe the transport protocol for use with PC-ANSI, VT-100, VT-100+, and VT-UTF8 terminals. Device paths can be constructed with this node as the last node in the device path. The rest of the device path describes the physical device that is being used to transmit and receive data. The PC-ANSI, VT-100, VT-100+, and VT-UTF8 GUIDs define the format of the data that is being sent through the physical device. Additional GUIDs can be generated to describe additional transport protocols.

```
#define EFI_PC_ANSI_GUID \
    { 0xe0c14753, 0xf9be, 0x11d2, 0x9a, 0x0c, 0x00, 0x90, 0x27, 0x3f, 0xc1, 0x4d }

#define EFI_VT_100_GUID \
    { 0xdfa66065, 0xb419, 0x11d3, 0x9a, 0x2d, 0x00, 0x90, 0x27, 0x3f, 0xc1, 0x4d }

#define EFI_VT_100_PLUS_GUID \
    { 0x7baec70b, 0x57e0, 0x4c76, 0x8e, 0x87, 0x2f, 0x9e, 0x28, 0x08, 0x83, 0x43 }

#define EFI_VT_UTF8_GUID \
    { 0xad15a0d6, 0x8bec, 0x4acf, 0xa0, 0x73, 0xd0, 0x1d, 0xe7, 0x7e, 0x2d, 0x88 }
```

9.3.5.17 UART Flow Control Messaging Path

The UART messaging device path defined in the EFI 1.02 specification does not contain a provision for flow control. Therefore, a new device path node is needed to declare flow control characteristics. It is a vendor-defined messaging node which may be appended to the UART node in a device path. It has the following definition:

```
#define DEVICE_PATH_MESSAGING_UART_FLOW_CONTROL \
    { 0X37499A9D, 0X542F, 0X4C89, 0XA0, 0X26, 0X35, 0XDA, 0X14, 0X20, 0X94, 0XE4 }
```

Table 63. UART Flow Control Messaging Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 10 – Vendor
Length	2	2	Length of this structure in bytes. Length is 24 bytes.
Vendor GUID	4	16	DEVICE_PATH_MESSAGING_UART_FLOW_CONTROL
Flow_Control_Map	20	4	Bitmap of supported flow control types. <ul style="list-style-type: none"> • Bit 0 set indicates hardware flow control. • Bit 1 set indicates Xon/Xoff flow control. • All other bits are reserved and are clear.

A debugport driver that implements Xon/Xoff flow control would produce a device path similar to the following:

```
PciRoot(0)/Pci(0x1f,0)/ACPI(PNP0501,0)/UART(115200,N,8,1)/UartFlowCtrl(2)/
DebugPort()
```

Note: *If no bits are set in the Flow_Control_Map, this indicates there is no flow control and is equivalent to leaving the flow control node out of the device path completely.*

9.3.5.18 Serial Attached SCSI (SAS) Device Path

This section defines the device node for Serial Attached SCSI (SAS) devices.

Table 64. Messaging Device Path Structure

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type -3 Messaging
Sub Type	1	1	10 (Vendor)
Length	2	2	Length of this Structure.
Vendor GUID	4	16	d487ddb4-008b-11d9-afdc-001083ffca4d
Reserved	20	4	Reserved for future use.
SAS Address	24	8	SAS Address for Serial Attached SCSI Target.
Logical Unit Number	32	8	SAS Logical Unit Number.
SAS/SATA device and Topology Info	40	2	More Information about the device and its interconnect
Relative Target Port	42	2	Relative Target Port (RTP)

Summary

The device node represented by the structure in [Table 64](#) (above) shall be appended after the Hardware Device Path node in the device path.

There are two cases for boot devices connected with SAS HBA's. Each of the cases is described below with an example of the expected Device Path for these.

- SAS Device anywhere in an SAS domain accessed through SSP Protocol.
PciRoot(0)/PCI(1,0)/Sas(0x21000004CF13F6BD, 0)
 The first 64-bit number represents the SAS address of the target SAS device.
 The second number is the boot LUN of the target SAS device.
 The third number is the Relative Target Port (RTP)
- SATA Device connected directly to a HBA port.
PciRoot(0)/PCI(1,0)/Sas(0x21000004CF13F6BD)
 The first number represents either a real SAS address reserved by the HBA for above connections, or a fake but unique SAS address generated by the HBA to represent the SATA device.

9.3.5.18.1 Device and Topology Information

First Byte (At offset 40 into the structure):

Bits 0:3:

Value 0x0 -> No Additional Information about device topology.

Value 0x1 -> More Information about device topology valid in this byte.

Value 0x2 -> More Information about device topology valid in this and next 1 byte.

Values 0x3 thru 0xF -> Reserved.

Bits 4:5: Device Type (Valid only if the More Information field above is non-zero)

Value 0x0 -> SAS Internal Device

Value 0x1 -> SATA Internal Device

Value 0x2 -> SAS External Device

Value 0x3 -> SATA External Device

Bits 6:7: Topology / Interconnect (Valid only if the More Information field above is non-zero)

Value 0x0 -> Direct Connect (Connected directly with the HBA Port/Phy)

Value 0x1 -> Expander Connect (Connected thru/via one or more Expanders)

Value 0x2 and 0x3 > Reserved

9.3.5.18.2 Device and Topology Information

Second Byte (At offset 41 into the structure). Valid only if bits 0-3 of More Information in Byte 36 have a value of 2:

Bits 0-7: Internal Drive/Bay Id (Only applicable if Internal Drive is indicated in Device Type)

Value 0x0 thru 0xFF -> Drive 1 thru Drive 256

9.3.5.18.3 Relative Target Port

At offset 42 into the structure:

This two-byte field shall contain the “Relative Target Port” of the target SAS port. Relative Target Port can be obtained by performing an INQUIRY command to VPD page 0x83 in the target. Implementation of RTP is mandatory for SAS targets as defined in Section 10.2.10 of sas1r07 specification (or later).

Note: *If a LUN is seen thru multiple RTPs in a given target, then the UEFI driver shall create separate device path instances for both paths. RTP in the device path shall distinguish these two device path instantiations.*

Note: *Changing the values of the SAS/SATA device topology information or the RTP fields of the device path will make UEFI think this is a different device.*

9.3.5.18.4 Examples Of Correct Device Path Display Format

Case 1: When Additional Information is not Valid or Not Present (Bits 0:3 of Byte 40 have a value of 0)

PciRoot(0)/PCI(1,0)/SAS(0x21000004CF13F6BD, 0)

Case 2: When Additional Information is Valid and present (Bits 0:3 of Byte 40 have a value of 1 or 2)

- If Bits 4-5 of Byte 40 (Device and Topology information) indicate an SAS device (Internal or External) i.e., has values 0x0 or 0x2, then the following format shall be used.

PciRoot(0)/PCI(1,0)/SAS(0x21000004CF13F6BD, 0, SAS)

- If Bits 4-5 of Byte 40 (Device and Topology information) indicate a SATA device (Internal or External) i.e., has a value of 0x1 or 0x3, then the following format shall be used.

ACPI (PnP)/PCI(1,0)/SAS(0x21000004CF13F6BD, SATA)

9.3.5.19 iSCSI Device Path

Table 65. iSCSI Device Path Node (Base Information)

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path
Sub-Type	1	1	Sub-Type 19 – (iSCSI)
Length	2	2	Length of this structure in bytes. Length is (22 + n) bytes
Protocol	4	2	Network Protocol (0 = TCP, 1+ = reserved)
Options	6	2	iSCSI Login Options
Reserved	8	2	Reserved for future use
Target Portal group tag	10	2	iSCSI Target Portal group tag the initiator intends to establish a session with.
Logical Unit Number	12	8	SCSI Logical Unit Number
iSCSI Target Name	20	n	iSCSI NodeTarget Name. The length of the name is determined by subtracting the offset of this field from <i>Length</i> .

9.3.5.19.1 iSCSI Login Options

The iSCSI Device Node Options describe the iSCSI login options for the key values:

Bits 0:1:

- 0 = No Header Digest
- 2 = Header Digest Using CRC32C

Bits 2-3:

- 0 = No Data Digest
- 2 = Data Digest Using CRC32C

Bits 4:9:

Reserved for future use

Bits 10-11:

- 0 = AuthMethod_CHAP
- 2 = AuthMethod_None

Bit 12:

- 0 = CHAP_BI

1 = CHAP_UNI

For each specific login key, none, some or all of the defined values may be configured. If none of the options are defined for a specific key, the iSCSI driver shall propose “None” as the value. If more than one option is configured for a specific key, all the configured values will be proposed (ordering of the values is implementation dependent).

- Portal Group Tag: defines the iSCSI portal group the initiator intends to establish Session with.
- Logical Unit Number: defines the 64 bit SCSI LUN.
- iSCSI Target Name Length: defines the length in bytes of the iSCSI Target Name
- iSCSI Target Name: defines the iSCSI Target Name for the iSCSI Node. The size of the iSCSI Target Name can be up to a maximum of 223 bytes.

9.3.5.19.2 Device Path Examples

Some examples for the Device Path for the case the boot device connected to iSCSI bootable controller:

- With IPv4 configuration:

```
PciRoot(0)/PCI(2,0)/MAC(...)/IPv4(...)/iSCSI(iSCSITargetName,
PortalGroupTag, LUN)
```

- With IPv6 configuration:

```
ACPI(PnP)/PCI(2,0)/MAC(...)/IPv6(...)/iSCSI(iSCSITargetName, PortalGroupTag,
LUN)
```

9.3.6 Media Device Path

This Device Path is used to describe the portion of the medium that is being abstracted by a boot service. An example of Media Device Path would be defining which partition on a hard drive was being used.

9.3.6.1 Hard Drive

The Hard Drive Media Device Path is used to represent a partition on a hard drive. Each partition has at least Hard Drive Device Path node, each describing an entry in a partition table. EFI supports MBR and GPT partitioning formats. Partitions are numbered according to their entry in their respective partition table, starting with 1. Partitions are addressed in EFI starting at LBA zero. A partition number of zero can be used to represent the raw hard drive or a raw extended partition.

The partition format is stored in the Device Path to allow new partition formats to be supported in the future. The Hard Drive Device Path also contains a Disk Signature and a Disk Signature Type. The disk signature is maintained by the OS and only used by EFI to partition Device Path nodes. The disk signature enables the OS to find disks even after they have been physically moved in a system.

[2Section 3.1.2](#) defines special rules for processing the Hard Drive Media Device Path. These special rules enable a disk’s location to change and still have the system boot from the disk.

Table 66. Hard Drive Media Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path
Sub-Type	1	1	Sub-Type 1 – Hard Drive
Length	2	2	Length of this structure in bytes. Length is 42 bytes.
Partition Number	4	4	Describes the entry in a partition table, starting with entry 1. Partition number zero represents the entire device. Valid partition numbers for a MBR partition are [1, 4]. Valid partition numbers for a GPT partition are [1, NumberOfPartitionEntries].
Partition Start	8	8	Starting LBA of the partition on the hard drive
Partition Size	16	8	Size of the partition in units of Logical Blocks
Partition Signature	24	16	Signature unique to this partition
Partition Format	40	1	Partition Format: (Unused values reserved) 0x01 – PC-AT compatible legacy MBR (see Section 5.2.1). Partition Start and Partition Size come from <code>PartitionStartingLBA</code> and <code>PartitionSizeInLBA</code> for the partition. 0x02 – GUID Partition Table (see Section 5.3.2).
Signature Type	41	1	Type of Disk Signature: (Unused values reserved) 0x00 – No Disk Signature. 0x01 – 32-bit signature from address 0x1b8 of the type 0x01 MBR. 0x02 – GUID signature.

9.3.6.2 CD-ROM Media Device Path

The CD-ROM Media Device Path is used to define a system partition that exists on a CD-ROM. The CD-ROM is assumed to contain an ISO-9660 file system and follow the CD-ROM “El Torito” format. The Boot Entry number from the Boot Catalog is how the “El Torito” specification defines the existence of bootable entities on a CD-ROM. In EFI the bootable entity is an EFI System Partition that is pointed to by the Boot Entry.

Table 67. CD-ROM Media Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path.
Sub-Type	1	1	Sub-Type 2 – CD-ROM “El Torito” Format.
Length	2	2	Length of this structure in bytes. Length is 24 bytes.
Boot Entry	4	4	Boot Entry number from the Boot Catalog. The Initial/Default entry is defined as zero.
Partition Start	8	8	Starting RBA of the partition on the medium. CD-ROMs use Relative logical Block Addressing.
Partition Size	16	8	Size of the partition in units of Blocks, also called Sectors.

9.3.6.3 Vendor-Defined Media Device Path

Table 68. Vendor-Defined Media Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path.
Sub-Type	1	1	Sub-Type 3 – Vendor.
Length	2	2	Length of this structure in bytes. Length is 20 + <i>n</i> bytes.
Vendor GUID	4	16	Vendor-assigned GUID that defines the data that follows.
Vendor Defined Data	20	<i>n</i>	Vendor-defined variable size data.

9.3.6.4 File Path Media Device Path

Table 69. File Path Media Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path.
Sub-Type	1	1	Sub-Type 4 – File Path.
Length	2	2	Length of this structure in bytes. Length is 4 + <i>n</i> bytes.
Path Name	4	<i>n</i>	Unicode Path string including directory and file names. The length of this string <i>n</i> can be determined by subtracting 4 from the Length entry. A device path may contain one or more of these nodes. The complete path to a file can be found by concatenating all the File Path Media Device Path nodes. This is typically used to describe the directory path in one node, and the filename in another node.

9.3.6.5 Media Protocol Device Path

The Media Protocol Device Path is used to denote the protocol that is being used in a device path at the location of the path specified. Many protocols are inherent to the style of device path.

Table 70. Media Protocol Media Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path.
Sub-Type	1	1	Sub-Type 5 – Media Protocol.
Length	2	2	Length of this structure in bytes. Length is 20 bytes.
Protocol GUID	4	16	The ID of the protocol.

Note: Sub-Type 6 is reserved for future use.

9.3.6.6 PIWG Firmware Volume

This type is used by systems implementing the UEFI PI Specification 1.0 to describe a firmware volume. The exact format and usage are defined in that specification.

Table 71. PIWG Firmware Volume Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path.
Sub-Type	1	1	Sub-Type 6 – PIWG Firmware Volume.
Length	2	2	Length of this structure in bytes. Length is 4 + <i>n</i> bytes.
...	4	<i>n</i>	Contents are defined in the UEFI PI Specification.

9.3.6.7 PIWG Firmware File

This type is used by systems implementing the UEFI PI Specification 1.0 to describe a firmware file. The exact format and usage are defined in that specification.

Table 72. PIWG Firmware Volume Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 4 – Media Device Path.
Sub-Type	1	1	Sub-Type 7 – PIWG Firmware File.
Length	2	2	Length of this structure in bytes. Length is 4 + <i>n</i> bytes.
...	4	<i>n</i>	Contents are defined in the UEFI PI Specification.

9.3.7 BIOS Boot Specification Device Path

This Device Path is used to describe the booting of non-EFI-aware operating systems. This Device Path is based on the IPL and BCV table entry data structures defined in Appendix A of the *BIOS Boot Specification*. The BIOS Boot Specification Device Path defines a complete Device Path and is not used with other Device Path entries. This Device Path is only needed to enable platform firmware to select a legacy non-EFI OS as a boot option.

Table 73. BIOS Boot Specification Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 5 – BIOS Boot Specification Device Path.
Sub-Type	1	1	Sub-Type 1 – BIOS Boot Specification Version 1.01.
Length	2	2	Length of this structure in bytes. Length is 8 + <i>n</i> bytes.
Device Type	4	2	Device Type as defined by the BIOS Boot Specification.
Status Flag	6	2	Status Flags as defined by the BIOS Boot Specification

Mnemonic	Byte Offset	Byte Length	Description
Description String	8	n	ASCII string that describes the boot device to a user. The length of this string <i>n</i> can be determined by subtracting 8 from the Length entry.

Example BIOS Boot Specification Device Types include:

- 00h = Reserved
- 01h = Floppy
- 02h = Hard Disk
- 03h = CD-ROM
- 04h = PCMCIA
- 05h = USB
- 06h = Embedded network
- 07h..7Fh = Reserved
- 80h = BEV device
- 81h..FEh = Reserved
- FFh = Unknown

9.4 Device Path Generation Rules

9.4.1 Housekeeping Rules

The Device Path is a set of Device Path nodes. The Device Path must be terminated by an End of Device Path node with a sub-type of End the Entire Device Path. A NULL Device Path consists of a single End Device Path Node. A Device Path that contains a NULL pointer and no Device Path structures is illegal.

All Device Path nodes start with the generic Device Path structure. Unknown Device Path types can be skipped when parsing the Device Path since the length field can be used to find the next Device Path structure in the stream. Any future additions to the Device Path structure types will always start with the current standard header. The size of a Device Path can be determined by traversing the generic Device Path structures in each header and adding up the total size of the Device Path. This size will include the four bytes of the End of Device Path structure.

Multiple hardware devices may be pointed to by a single Device Path. Each hardware device will contain a complete Device Path that is terminated by the Device Path End Structure. The Device Path End Structures that do not end the Device Path contain a sub-type of End This Instance of the Device Path. The last Device Path End Structure contains a sub-type of End Entire Device Path.

9.4.2 Rules with ACPI _HID and _UID

As described in the ACPI specification, ACPI supports several different kinds of device identification objects, including _HID, _CID and _UID. The _UID device identification objects are

optional in ACPI and only required if more than one `_HID` exists with the same ID. The ACPI Device Path structure must contain a zero in the `_UID` field if the ACPI name space does not implement `_UID`. The `_UID` field is a unique serial number that persists across reboots.

If a device in the ACPI name space has a `_HID` and is described by a `_CRS` (Current Resource Setting) then it should be described by an ACPI Device Path structure. A `_CRS` implies that a device is not mapped by any other standard. A `_CRS` is used by ACPI to make a nonstandard device into a Plug and Play device. The configuration methods in the ACPI name space allow the ACPI driver to configure the device in a standard fashion. The presence of a `_CID` determines whether the ACPI Device Path node or the Expanded ACPI Device Path node should be used.

[Table 74](#) maps ACPI `_CRS` devices to EFI Device Path.

Table 74. ACPI `_CRS` to EFI Device Path Mapping

ACPI <code>_CRS</code> Item	EFI Device Path
PCI Root Bus	ACPI Device Path: <code>_HID PNP0A03, _UID</code>
Floppy	ACPI Device Path: <code>_HID PNP0604, _UID drive select encoding 0-3</code>
Keyboard	ACPI Device Path: <code>_HID PNP0301, _UID 0</code>
Serial Port	ACPI Device Path: <code>_HID PNP0501, _UID Serial Port COM number 0-3</code>
Parallel Port	ACPI Device Path: <code>_HID PNP0401, _UID LPT number 0-3</code>

Support of root PCI bridges requires special rules in the EFI Device Path. A root PCI bridge is a PCI device usually contained in a chipset that consumes a proprietary bus and produces a PCI bus. In typical desktop and mobile systems there is only one root PCI bridge. On larger server systems there are typically multiple root PCI bridges. The operation of root PCI bridges is not defined in any current PCI specification. A root PCI bridge should not be confused with a PCI to PCI bridge that both consumes and produces a PCI bus. The operation and configuration of PCI to PCI bridges is fully specified in current PCI specifications.

Root PCI bridges will use the plug and play ID of `PNP0A03`, This will be stored in the ACPI Device Path `_HID` field, or in the Expanded ACPI Device Path `_CID` field to match the ACPI name space. The `_UID` in the ACPI Device Path structure must match the `_UID` in the ACPI name space.

9.4.3 Rules with ACPI `_ADR`

If a device in the ACPI name space can be completely described by a `_ADR` object then it will map to an EFI ACPI, Hardware, or Message Device Path structure. A `_ADR` method implies a bus with a standard enumeration algorithm. If the ACPI device has a `_ADR` and a `_CRS` method, then it should also have a `_HID` method and follow the rules for using `_HID`.

[Table 75](#) relates the ACPI `_ADR` bus definition to the EFI Device Path:

Table 75. ACPI `_ADR` to EFI Device Path Mapping

ACPI <code>_ADR</code> Bus	EFI Device Path
EISA	Not supported
Floppy Bus	ACPI Device Path: <code>_HID PNP0604, _UID drive select encoding 0-3</code>
IDE Controller	ATAPI Message Device Path: <code>Maser/Slave : LUN</code>

ACPI_ADR Bus	EFI Device Path
IDE Channel	ATAPI Message Device Path: Maser/Slave : LUN
PCI	PCI Hardware Device Path
PCMCIA	Not Supported
PC CARD	PC CARD Hardware Device Path
SMBus	Not Supported
SATA bus	SATA Messaging Device Path

9.4.4 Hardware vs. Messaging Device Path Rules

Hardware Device Paths are used to define paths on buses that have a standard enumeration algorithm and that relate directly to the coherency domain of the system. The coherency domain is defined as a global set of resources that is visible to at least one processor in the system. In a typical system this would include the processor memory space, IO space, and PCI configuration space.

Messaging Device Paths are used to define paths on buses that have a standard enumeration algorithm, but are not part of the global coherency domain of the system. SCSI and Fibre Channel are examples of this kind of bus. The Messaging Device Path can also be used to describe virtual connections over network-style devices. An example would be the TCPI/IP address of an internet connection.

Thus Hardware Device Path is used if the bus produces resources that show up in the coherency resource domain of the system. A Message Device Path is used if the bus consumes resources from the coherency domain and produces resources out side the coherency domain of the system.

9.4.5 Media Device Path Rules

The Media Device Path is used to define the location of information on a medium. Hard Drives are subdivided into partitions by the MBR and a Media Device Path is used to define which partition is being used. A CD-ROM has boot partitions that are defined by the “El Torito” specification, and the Media Device Path is used to point to these partitions.

An [EFI BLOCK IO PROTOCOL](#) is produced for both raw devices and partitions on devices. This allows the [EFI SIMPLE FILE SYSTEM PROTOCOL](#) protocol to not have to understand media formats. The [EFI_BLOCK_IO_PROTOCOL](#) for a partition contains the same Device Path as the parent [EFI_BLOCK_IO_PROTOCOL](#) for the raw device with the addition of a Media Device Path that defines which partition is being abstracted.

The Media Device Path is also used to define the location of a file in a file system. This Device Path is used to load files and to represent what file an image was loaded from.

9.4.6 Other Rules

The BIOS Boot Specification Device Path is not a typical Device Path. A Device Path containing the BIOS Boot Specification Device Path should only contain the required End Device Path structure and no other Device Path structures. The BIOS Boot Specification Device Path is only used to allow the EFI boot menus to boot a legacy operating system from legacy media.

The EFI Device Path can be extended in a compatible fashion by assigning your own vendor GUID to a Hardware, Messaging, or Media Device Path. This extension is guaranteed to never conflict with future extensions of this specification.

The EFI specification reserves all undefined Device Path types and subtypes. Extension is only permitted using a Vendor GUID Device Path entry.

9.5 Device Path Utilities Protocol

This section describes the `EFI_DEVICE_PATH_UTILITIES_PROTOCOL`, which aids in creating and manipulating device paths.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL

Summary

Creates and manipulates device paths and device nodes.

GUID

```
// {0379BE4E-D706-437d-B037-EDB82FB772A4}
#define EFI_DEVICE_PATH_UTILITIES_PROTOCOL_GUID \
    {0x379be4e, 0xd706, 0x437d, 0xb0, 0x37, 0xed, 0xb8, 0x2f, 0xb7, \
     0x72, 0xa4 }
```

Protocol Interface Structure

```
typedef struct _EFI_DEVICE_PATH_UTILITIES_PROTOCOL {
    EFI_DEVICE_PATH_UTILS_GET_DEVICE_PATH_SIZE
    GetDevicePathSize;
    EFI_DEVICE_PATH_UTILS_DUP_DEVICE_PATH DuplicateDevicePath;
    EFI_DEVICE_PATH_UTILS_APPEND_PATH AppendDevicePath;
    EFI_DEVICE_PATH_UTILS_APPEND_NODE AppendDeviceNode;
    EFI_DEVICE_PATH_UTILS_APPEND_INSTANCE
    AppendDevicePathInstance;
    EFI_DEVICE_PATH_UTILS_GET_NEXT_INSTANCE
    GetNextDevicePathInstance;
    EFI_DEVICE_PATH_UTILS_IS_MULTI_INSTANCE
    IsDevicePathMultiInstance;
    EFI_DEVICE_PATH_UTILS_CREATE_NODE CreateDeviceNode;
} EFI_DEVICE_PATH_UTILITIES_PROTOCOL;
```

Parameters

GetDevicePathSize Returns the size of the specified device path, in bytes.

DuplicateDevicePath Duplicates a device path structure.

AppendDeviceNode Appends the device node to the specified device path.

AppendDevicePath Appends the device path to the specified device path.

- AppendDevicePathInstance* Appends a device path instance to another device path.
- GetNextDevicePathInstance* Retrieves the next device path instance from a device path data structure.
- IsDevicePathMultiInstance* Returns TRUE if this is a multi-instance device path.
- CreateDeviceNode* Allocates memory for a device node with the specified type and sub-type.

Description

The **EFI_DEVICE_PATH_UTILITIES_PROTOCOL** provides common utilities for creating a manipulating device paths and device nodes.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.GetDevicePathSize()

Summary

Returns the size of the device path, in bytes.

Prototype

```
typedef
UINTN
(EFIAPI *EFI_DEVICE_PATH_UTILS_GET_DEVICE_PATH_SIZE) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath
);
```

Parameters

DevicePath Points to the start of the EFI device path.

Description

This function returns the size of the specified device path, in bytes, including the end-of-path tag. If *DevicePath* is **NULL** then zero is returned.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.DuplicateDevicePath()

Summary

Create a duplicate of the specified path.

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFIAPI *EFI_DEVICE_PATH_UTILS_DUP_DEVICE_PATH) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL  *DevicePath,
)
```

Parameters

DevicePath Points to the source device path.

Description

This function creates a duplicate of the specified device path. The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated. If *DevicePath* is **NULL** then **NULL** will be returned and no memory will be allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the duplicate device path or NULL if there was insufficient memory.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.AppendDevicePath()

Summary

Create a new path by appending the second device path to the first.

Prototype

```

typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_UTILS_APPEND_PATH) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL *Src1,
    IN CONST EFI_DEVICE_PATH_PROTOCOL *Src2
);

```

Parameters

<i>Src1</i>	Points to the first device path.
<i>Src2</i>	Points to the second device path.

Description

This function creates a new device path by appending a copy of the second device path to a copy of the first device path in a newly allocated buffer. Only the end-of-device-path device node from the second device path is retained. If *Src1* is **NULL** and *Src2* is non-**NULL**, then a duplicate of *Src2* is returned. If *Src1* is non-**NULL** and *Src2* is **NULL**, then a duplicate of *Src1* is returned. If *Src1* and *Src2* are both **NULL**, then a copy of an end-of-device-path is returned.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the newly created device path or **NULL** if memory could not be allocated.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.AppendDeviceNode()

Summary

Creates a new path by appending the device node to the device path.

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_UTILS_APPEND_NODE) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath,
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DeviceNode
);
```

Parameters

<i>DevicePath</i>	Points to the device path.
<i>DeviceNode</i>	Points to the device node.

Description

This function creates a new device path by appending a copy of the specified device node to a copy of the specified device path in an allocated buffer. The end-of-device-path device node is moved after the end of the appended device node. If *DeviceNode* is **NULL** then a copy of *DevicePath* is returned. If *DevicePath* is **NULL** then a copy of *DeviceNode*, followed by an end-of-device path device node is returned. If both *DeviceNode* and *DevicePath* are **NULL** then a copy of an end-of-device-path device node is returned.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the allocated device path, or **NULL** if there was insufficient memory.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.AppendDevicePathInstance()

Summary

Creates a new path by appending the specified device path instance to the specified device path.

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_UTILS_APPEND_INSTANCE) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath,
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePathInstance
);
```

Parameters

DevicePath Points to the device path. If NULL, then ignored.
DevicePathInstance Points to the device path instance

Description

This function creates a new device path by appending a copy of the specified device path instance to a copy of the specified device path in an allocated buffer. The end-of-device-path device node is moved after the end of the appended device node and a new end-of-device-path-instance node is inserted between. If *DevicePath* is NULL, then a copy of *DevicePathInstance* is returned instead.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the newly created device path or NULL if *DevicePathInstance* is NULL or there was insufficient memory.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.GetNextDevicePathInstance()

Summary

Creates a copy of the current device path instance and returns a pointer to the next device path instance.

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_UTILS_GET_NEXT_INSTANCE) (
    IN OUT EFI_DEVICE_PATH_PROTOCOL **DevicePathInstance,
    OUT UINTN                               *DevicePathInstanceSize OPTIONAL
);
```

Parameters

DevicePathInstance On input, this holds the pointer to the current device path instance. On output, this holds the pointer to the next device path instance or NULL if there are no more device path instances in the device path.

DevicePathInstanceSize On output, this holds the size of the device path instance, in bytes or zero, if *DevicePathInstance* is **NULL**. If **NULL**, then the instance size is not output.

Description

This function creates a copy of the current device path instance. It also updates *DevicePathInstance* to point to the next device path instance in the device path (or NULL if no more) and updates *DevicePathInstanceSize* to hold the size of the device path instance copy.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the copy of the current device path instance or NULL if *DevicePathInstance* was NULL on entry or there was insufficient memory.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.CreateDeviceNode()**Summary**

Creates a device node

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_UTILS_CREATE_NODE) (
    IN UINT8  NodeType,
    IN UINT8  NodeSubType,
    IN UINT16 NodeLength
);
```

Parameters

<i>NodeType</i>	NodeType is the device node type (EFI_DEVICE_PATH.Type) for the new device node.
<i>NodeSubType</i>	NodeSubType is the device node sub-type (EFI_DEVICE_PATH.SubType) for the new device node.
<i>NodeLength</i>	NodeLength is the length of the device node (EFI_DEVICE_PATH.Length) for the new device node.

Description

This function creates a new device node in a newly allocated buffer.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the created device node or NULL if *NodeLength* is less than the size of the header or there was insufficient memory.

EFI_DEVICE_PATH_UTILITIES_PROTOCOL.IsDevicePathMultiInstance()

Summary

Returns whether a device path is multi-instance.

Prototype

```
typedef
BOOLEAN
(EFI_API *EFI_DEVICE_PATH_UTILS_IS_MULTI_INSTANCE) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath
);
```

Parameters

DevicePath Points to the device path. If **NULL**, then ignored.

Description

This function returns whether the specified device path has multiple path instances.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns TRUE if the device path has more than one instance or FALSE if it is empty or contains only a single instance.

9.6 EFI Device Path Display Format Overview

This section describes the recommended conversion between an EFI Device Path Protocol and Unicode text. It also describes standard protocols for implementing these. The goals are:

- Standardized display format. This allows documentation and test tools to understand output coming from drivers provided by multiple vendors.
- Increase Readability. Device paths need to be read by people, so the format should be in a form which can be deciphered, maintaining as much as possible the industry standard means of presenting data. In this case, there are two forms, a display-only form and a parse-able form.
- Round-trip conversion from text to binary form and back to text without loss, if desired.
- Ease of command-line parsing. Since device paths can appear on the command-lines of UEFI applications executed from a shell, the conversion format should not prohibit basic command-line processing, either by the application or by a shell.

This specification is designed to be inserted as Sections 8.5 and 8.6 of the UEFI 2.0 specification, immediately following Device Path Generation Rules.

9.6.1 Design Discussion

The following subsections describe the design considerations for conversion to and from the EFI Device Path Protocol binary format and its corresponding text form.

9.6.1.1 Standardized Display Format

Before the UEFI 2.0, there was no standardized format for the conversion from the EFI Device Path protocol and text. Some de-facto standards arose, either as part of the standard implementation or in descriptive text in the EFI Device Driver Writer's Guide, although they didn't agree. The standardized format attempts to maintain at least the spirit of these earlier ideas.

9.6.1.2 Readability

Since these are conversions to text and, in many cases, users have to read and understand the text form of the EFI Device Path, it makes sense to make them as readable as reasonably possible.

Several strategies are used to accomplish this:

- Creating simplified forms for well-known device paths. For example, a PCI root Bridge can be represented as Acpi(PNP0A03,0), but makes more sense as PciRoot(0). When converting from text to binary form, either form is accepted, but when converting from binary form to text, the latter is preferred.
- Omitting the conversion of fields which have empty or default values. By doing this, the average display length is greatly shortened, which improves readability.

9.6.1.3 Round-Trip Conversion

The conversions specified here guarantee at least that conversion to and from the binary representation of the EFI Device Path will be semantically identical.

$$\text{Text}_1 \Leftrightarrow \text{Binary}_1 \Leftrightarrow \text{Text}_2 \Leftrightarrow \text{Binary}_2$$

Figure 22. Text to Binary Conversion

In [Figure 22](#), the process described in this section is applied to Text1, converting it to Binary1. Subsequently, Binary1 is converted to Text2. Finally, the Text2 is converted to Binary2. In these cases, Binary1 and Binary2 will always be identical. Text1 and Text2 may or may not be identical. This is the result of the fact that the text representation has, in some cases, more than one way of representing the same EFI Device Path node.

$$\text{Binary}_1 \Leftrightarrow \text{Text}_1 \Leftrightarrow \text{Binary}_2 \Leftrightarrow \text{Text}_2$$

Figure 23. Binary to Text Conversion

In [Figure 23](#) the process described in this section is applied to Binary1, converting it to Text1. Subsequently, Text1 is converted to Binary2. Finally, Binary2 is converted to Text2. In these cases, Binary1 and Binary2 will always be identical and Text1 and Text2 will always be identical.

Another consideration in round-trip conversion is potential ambiguity in parsing. This happens when the text representation could be converted into more than type of device node, thus requiring

information beyond that contained in the text representation in order to determine the correct conversion to apply. In the case of EFI Device Paths, this causes problems primarily with literal strings in the device path, such as those found in file names, volumes or directories.

For example, the file name `Acpi(PNP0A03,0)` might be a legal FAT32 file name. However, in parsing this, it is not clear whether it refers to an Acpi device node or a file name. Thus, it is ambiguous. In order to prevent ambiguity, certain characters may only be used for device node keywords and may not be used in file names or directories.

9.6.1.4 Command-Line Parsing

Applications written to this specification need to accept the text representation of EFI device paths as command-line parameters, possibly in the context of a command-prompt or shell. In order to do this, the text representation must follow simple guidelines concerning its format.

Command-line parsing generally involves three separate concepts: substitution, redirection and division.

In substitution, the invoker of the application modifies the actual contents of the command-line before it is passed to the application. For example:

```
copy *.xyz
```

In redirection, the invoker of the application gleans from the command line parameters which it uses to, for example, redirect or pipe input or output. For example:

```
echo This text is copied to a file >abc
dir | more
```

Finally, in division, the invoker or the application startup code divides the command-line up into individual arguments. The following line, for example, has (at least) three arguments, divided by whitespace.

```
copy /b file1.info file2.info
```

9.6.1.5 Text Representation Basics

This section describes the basic rules for the text representation of device nodes and device paths. The formal grammar describing appears later.

The text representation of a device path (or text device path) consists of one or more text device nodes, each preceded by a `'/'` or `'\'` character. The behavior of a device path where the first node is not preceded by one of these characters is undefined. Some implementations may treat it as a relative path from a current working directory.

Spaces are not allowed at any point within the device path except when quoted with double quotes (`"`). The `'|'` (bar), `'<'` (less than) and `'>'` (greater than) characters are likewise reserved for use by the shell.

device-path := *device-node*
 /*device-node*
 device-path device-node
 /*device-path device-node*

Figure 24. Device Path Text Representation

There are two types of text device nodes : file-name/directory or canonical. Canonical text device nodes are prefixed by an option name consisting of only alphanumerical characters, followed by a parenthesis, followed by option-specific parameters separated by a ‘,’ (comma). File names and directories have no prefixes.

device-node := standard-*device-node* | *file-name/directory*
standard-device-node := *option-name(option-parameters)*
file-name/directory := any character except ‘/’ ‘\’ ‘|’ ‘>’ ‘<’

Figure 25. Text Device Node Names

The canonical device node can have zero or more option parameters between the parentheses. Multiple option parameters are separated by a comma. The meaning of the option parameters depends primarily on the option name, then the parameter-identifier (if present) and then the order of appearance in the parameter list. The parameter identifier allows the text representation to only contain the non-default option parameter value, even if it would normally appear fourth in the list of option parameters. Missing parameters do not require the comma unless needed as a placeholder to correctly increment the parameter count for a subsequent parameter.

Consider

Acpi(HWP0002, PNP0A03)

Which could also be written:

Acpi(HWP0002,CID=PNP0A03)

Since CID is an optional parameter.

option-name := alphanumerical characters string
option-parameters :=*option-parameter*
option-parameters,option-parameter
option-parameter :=parameter-value
parameter-identifier=parameter-value

Figure 26. Device Node Option Names

9.6.1.6 Text Device Node Reference

In each of the following table rows, a specific device node type and sub-type are given, along with the most general form of the text representation. Any parameters for the device node are listed in italics. In each case, the type is listed and along with it what is required or optional, and any default value, if applicable.

On subsequent lines, alternate representations are listed. In general, these alternate representations are simplified by the assumption that one or more of the parameters is set to a specific value.

Parameter Types

This section describes the various types of option parameter values.

Table 76. EFI Device Path Option Parameter Values

GUID	An EFI GUID in standard format xxxxxxxx-xxxx-xxxx-xxxx-xxxxxxxxxxxx, where each x is a hexadecimal digit.
Keyword	In some cases, one of a series of keywords must be listed.
Integer	Unless otherwise specified, this indicates an unsigned integer in the range of 0 to 232-1. The value is decimal, unless preceded by "0x" or "0X"
EISAID	A seven character text identifier in the format used by the ACPI specification. The first three characters must be alphabetic, either upper or lower case. The second four characters are hexadecimal digits, either numeric, upper case or lower case. Optionally, it can be the number 0.
String	Series of alphabetic, numeric and punctuation characters not including a right parenthesis ')', bar ' ' less-than '<' or greater than '>' character.
HexDump	Series of bytes, represented by two hexadecimal characters per byte. Unless otherwise indicated, the size is only limited by the length of the device node.
IP Address	Series of four integer values (each between 0-255), separated by a '.' Optionally, followed by a ':' and an integer value between 0-65555. If the ':' is not present, then the port value is zero.
IPv6	Series of four character hexadecimal values, separated by the ':' character. If '::' appears, it fills in zero or more missing 16-bit values before the any remaining hexadecimal characters with zeroes.

Table 77. Device Node Table

Device Node Type/SubType/ Other	Description
	<p>Path (<i>type, subtype, data</i>) The <i>type</i> is an integer from 0-255. The <i>sub-type</i> is an integer from 0-255. The <i>data</i> is a hex dump.</p>
Type: 1 (Hardware Device Path)	<p>HardwarePath(<i>subtype, data</i>) The <i>subtype</i> is an integer from 0-255. The <i>data</i> is a hex dump.</p>
Type: 1 (Hardware Device Path) SubType: 1 (PCI)	<p>Pci(<i>Device, Function</i>) The <i>Device</i> is an integer from 0-31 and is required. The <i>Function</i> is an integer from 0-7 and is required.</p>
Type: 1 (Hardware Device Path) SubType: 2 (PcPcard)	<p>PcCard(<i>Function</i>) The <i>Function</i> is an integer from 0-255 and is required.</p>
Type: 1 (Hardware Device Path) SubType: 3 (Memory Mapped)	<p>MemoryMapped(<i>EfiMemoryType, StartingAddress, EndingAddress</i>) The <i>EfiMemoryType</i> is a 32-bit integer and is required. The <i>StartingAddress</i> and <i>EndingAddress</i> are both 64-bit integers and are both required.</p>
Type: 1 (Hardware Device Path) SubType: 4 (Vendor)	<p>VenHw(<i>Guid, Data</i>) The <i>Guid</i> is a GUID and is required. The <i>Data</i> is a Hex Dump and is optional. The default value is zero bytes.</p>
Type: 1 (Hardware Device Path) SubType: 5 (Controller)	<p>Ctrl(<i>Controller</i>) The <i>Controller</i> is an integer and is required.</p>
Type 2	<p>AcpiPath (<i>subtype, data</i>) The <i>subtype</i> is an integer from 0-255. The <i>data</i> is a hex dump.</p>
Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path)	<p>Acpi(<i>HID, UID</i>) The <i>HID</i> parameter is an EISAID and is required. The <i>UID</i> parameter is an integer and is optional. The default value is zero.</p>
Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0A03	<p>PciRoot(<i>UID</i>) The <i>UID</i> parameter is an integer. It is optional but required for display. The default value is zero.</p>

Device Node Type/SubType/Other	Description
Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0604	Floppy(<i>UID</i>) The <i>UID</i> parameter is an integer. It is optional for input but required for display. The default value is zero.
Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0301	Keyboard(<i>UID</i>) The <i>UID</i> parameter is an integer. It is optional for input but required for display. The default value is 0.
Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0501	Serial(<i>UID</i>) The <i>UID</i> parameter is an integer. It is optional for input but required for display. The default value is 0.
Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0401	ParallelPort(<i>UID</i>) The <i>UID</i> parameter is an integer. It is optional for input but required for display. The default value is 0.
Type: 2 (ACPI Device Path) SubType: 2 (ACPI Expanded Device Path)	AcpiEx(<i>HID,CID,UID,HIDSTR,CIDSTR,UIDSTR</i>) AcpiEx(<i>HID HIDSTR,UID UIDSTR,CID CIDSTR</i>) (Display Only) The <i>HID</i> parameter is an EISAID. The default value is 0. Either <i>HID</i> or <i>HIDSTR</i> must be present. The <i>CID</i> parameter is an EISAID. The default value is 0. Either <i>CID</i> must be 0 or <i>CIDSTR</i> must be empty. The <i>UID</i> parameter is an integer. The default value is 0. Either <i>UID</i> must be 0 or <i>UIDSTR</i> must be empty. The <i>HIDSTR</i> is a string. The default value is the empty string. Either <i>HID</i> or <i>HIDSTR</i> must be present. The <i>CIDSTR</i> is a string. The default value is an empty string. Either <i>CID</i> must be 0 or <i>CIDSTR</i> must be empty. The <i>UIDSTR</i> is a string. The default value is an empty string. Either <i>UID</i> must be 0 or <i>UIDSTR</i> must be empty.
Type: 2 (ACPI Device Path) SubType: 2 (ACPI Expanded Device Path) HIDSTR=empty CIDSTR=empty UID = 0	AcpiExp(<i>HID,CID,UIDSTR</i>) The <i>HID</i> parameter is an EISAID. It is required. The <i>CID</i> parameter is an EISAID. It is optional and has a default value of 0. The <i>UIDSTR</i> parameter is a string. It is optional and defaults to an empty string.
Type: 3 MessagingPath	HardwarePath(<i>subtype, data</i>) The <i>subtype</i> is an integer from 0-255. The <i>data</i> is a hex dump.

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Type: 3 (Messaging Device Path) SubType: 1 (ATAPI)	<p>Ata(<i>Controller, Drive, LUN</i>) Ata(<i>LUN</i>) (Display only)</p> <p>The <i>Controller</i> is either an integer with a value of 0 or 1 or else the keyword Primary (0) or Secondary (1). It is required. The <i>Drive</i> is either an integer with the value of 0 or 1 or else the keyword Master (0) or Slave (1). It is required. The <i>LUN</i> is a 16-bit integer. It is required.</p>
Type: 3 (Messaging Device Path) SubType: 2 (SCSI)	<p>Scsi(<i>PUN, LUN</i>)</p> <p>The <i>PUN</i> is an integer between 0 and 65535 and is required. The <i>LUN</i> is an integer between 0 and 65535 and is required.</p>
Type: 3 (Messaging Device Path) SubType: 3 (Fibre Channel)	<p>Fibre(<i>WWN, LUN</i>)</p> <p>The <i>WWN</i> is a 64-bit unsigned integer and is required. The <i>LUN</i> is a 64-bit unsigned integer and is required.</p>
Type: 3 (Messaging Device Path) SubType: 4 (1394)	<p>I1394(<i>GUID</i>)</p> <p>The <i>GUID</i> is a GUID and is required.</p>
Type: 3 (Messaging Device Path) SubType: 5 (USB)	<p>USB(<i>Port, Interface</i>)</p> <p>The <i>Port</i> is an integer between 0 and 255 and is required. The <i>Interface</i> is an integer between 0 and 255 and is required.</p>
Type: 3 (Messaging Device Path) SubType: 6 (I ₂ O)	<p>I2O(<i>TID</i>)</p> <p>The <i>TID</i> is an integer and is required.</p>
Type: 3 (Messaging Device Path) SubType: 9 (Infiniband)	<p>Infiniband(<i>Flags, Guid, ServiceId, TargetId, DeviceId</i>)</p> <p><i>Flags</i> is an integer. <i>Guid</i> is a guid. <i>ServiceId, TargetId</i> and <i>DeviceId</i> are 64-bit unsigned integers. All fields are required.</p>
Type: 3 (Messaging Device Path) SubType: 10 (Vendor)	<p>VenMsg(<i>Guid, Data</i>)</p> <p>The <i>Guid</i> is a GUID and is required. The <i>Data</i> is a Hex Dump and is option. The default value is zero bytes.</p>
Type: 3 (Messaging Device Path) SubType: 10 (Vendor) GUID=EFI_PC_ANSI_GUID	<p>VenPcAnsi()</p>
Type: 3 (Messaging Device Path) SubType: 10 (Vendor) GUID=EFI_VT_100_GIUD	<p>VenVt100()</p>
Type: 3 (Messaging Device Path) SubType: 10 (Vendor) GUID=EFI_VT_100_PLUS_GUID	<p>VenVt100Plus()</p>

Device Node Type/SubType/Other	Description
Type: 3 (Messaging Device Path) SubType: 10 (Vendor) GUID=EFI_VT_UTF8_GUID	VenUtf8()
Type: 3 (Messaging Device Path) SubType: 10 (Vendor) GUID=DEVICE_PATH_MESSAGING_UART_FLOW_CONTROL	UartFlowCtrl(Value) The <i>Value</i> is either an integer with the value 0, 1 or 2 or the keywords XonXoff (2) or Hardware (1) or None (0).
Type: 3 (Messaging Device Path) SubType: 10 (Serial Attached SCSI) Vendor GUID: d487ddb4-008b-11d9-afdc-001083ffc4d	SAS (<i>Address, LUN, RTP, SASSATA, Location, Connect, DriveBay, Reserved</i>) The <i>Address</i> is a 64-bit unsigned integer representing the SAS Address and is required. The <i>LUN</i> is a 64-bit unsigned integer representing the Logical Unit Number and is optional. The default value is 0. The <i>RTP</i> is a 16-bit unsigned integer representing the Relative Target Port and is optional. The default value is 0. The <i>SASSATA</i> is a keyword SAS or SATA or NoTopology or an unsigned 16-bit integer and is optional. The default is NoTopology . If NoTopology or an integer are specified, then <i>Location</i> , <i>Connect</i> and <i>DriveBay</i> are prohibited. If SAS or SATA is specified, then <i>Location</i> and <i>Connect</i> are required, but <i>DriveBay</i> is optional. If an integer is specified, then the topology information is filled with the integer value. The <i>Location</i> is an integer between 0 and 1 or else the keyword Internal (0) or External (1) and is optional. If <i>SASSATA</i> is an integer or NoTopology , it is prohibited. The default value is 0. The <i>Connect</i> is an integer between 0 and 3 or else the keyword Direct (0) or Expanded (1) and is optional. If <i>SASSATA</i> is an integer or NoTopology , it is prohibited. The default value is 0. The <i>DriveBay</i> is an integer between 1 and 256 and is optional unless <i>SASSATA</i> is an integer or NoTopology , in which case it is prohibited. The <i>Reserved</i> field is an integer and is optional. The default value is 0.
Type: 3 (Messaging Device Path) SubType: 10 (Vendor) GUID=EFI_DEBUGPORT_PROTOCOL_GUID	DebugPort()
Type: 3 (Messaging Device Path) SubType: 11 (MAC Address)	MAC (<i>MacAddr, IfType</i>) The <i>MacAddr</i> is a Hex Dump and is required. If <i>IfType</i> is 0 or 1, then the <i>MacAddr</i> must be exactly six bytes. The <i>IfType</i> is an integer from 0-255 and is optional. The default is zero.

Device Node Type/SubType/ Other	Description
Type: 3 (Messaging Device Path) SubType: 12 (IPv4)	<p>IPv4(<i>Remotep, Protocol, Type, Locallp</i>) IPv4(<i>Remotep</i>) (Display Only)</p> <p>The <i>Remotep</i> is an IP Address and is required. The <i>Protocol</i> is a keyword, either UDP (0) or TCP (1). The default value is UDP. The <i>Type</i> is a keyword, either Static (1) or DHCP (0). It is optional. The default value is DHCP. The <i>Locallp</i> is an IP Address and is optional. The default value is all zeroes.</p>
Type: 3 (Messaging Device Path) SubType: 13 (IPv6)	<p>IPv6(<i>Remotep, Protocol, Type, Locallp</i>) IPv6(<i>Remotep</i>) (Display Only)</p> <p>The <i>Remotep</i> is an IPv6 Address and is required. The <i>Protocol</i> is a keyword, either UDP (0) or TCP (1). The default value is UDP. The <i>Type</i> is a keyword, either Static (1) or DHCP (0). It is optional. The default value is DHCP. The <i>Locallp</i> is an IPv6 Address and is optional. The default value is all zeroes.</p>
Type: 3 (Messaging Device Path) SubType: 14 (UART)	<p>Uart(<i>Baud, DataBits, Parity, StopBits</i>)</p> <p>The <i>Baud</i> is a 64-bit integer and is optional. The default value is 115200. The <i>DataBits</i> is an integer from 0 to 255 and is optional. The default value is 8. The <i>Parity</i> is either an integer from 0-255 or else a keyword and should be D (0), N (1), E (2), O (3), M (4) or S (5). It is optional. The default value is 0. The <i>StopBits</i> is a either an integer from 0-255 or else a keyword and should be D (0), 1 (1), 1.5 (2), 2 (3). It is optional. The default value is 0.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class)	<p>UsbClass(<i>VID,PID,Class,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>Class</i> is an integer between 0 and 255 and is optional. The default value is 0xFF. The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF. The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>

Device Node Type/SubType/ Other	Description
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 1	<p>UsbAudio(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 2	<p>UsbCDCControl(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an optional integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an optional integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an optional integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an optional integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 3	<p>UsbHID(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 6	<p>UsbImage(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>

Device Node Type/SubType/ Other	Description
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 7	<p>UsbPrinter(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 8	<p>UsbMassStorage(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 9	<p>UsbHub(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 10	<p>UsbCDCData(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>

Device Node Type/SubType/ Other	Description
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 11	<p>UsbSmartCard(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 14	<p>UsbVideo(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 220	<p>UsbDiagnostic(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 224	<p>UsbWireless(<i>VID,PID,SubClass,Protocol</i>)</p> <p>The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</p> <p>The <i>SubClass</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p> <p>The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.</p>

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Device Node Type/SubType/ Other	Description
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 254 SubClass: 1	UsbDeviceFirmwareUpdate (<i>VID,PID,Protocol</i>) The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 254 SubClass: 2	UsblrdaBridge (<i>VID,PID,Protocol</i>) The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.
Type: 3 (Messaging Device Path) SubType: 15 (USB Class) Class 254 SubClass: 3	UsbTestAndMeasurement (<i>VID,PID,Protocol</i>) The <i>VID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>PID</i> is an integer between 0 and 65535 and is optional. The default value is 0xFFFF. The <i>Protocol</i> is an integer between 0 and 255 and is optional. The default value is 0xFF.
Type: 3 (Messaging Device Path) SubType: 16 (USB WWID Class)	UsbWwid (<i>VID,PID,InterfaceNumber,"WWID"</i>) The <i>VID</i> is an integer between 0 and 65535 and is required. The <i>PID</i> is an integer between 0 and 65535 and is required. The <i>InterfaceNumber</i> is an integer between 0 and 255 and is required. The <i>WWID</i> is a string and is required.
Type: 3 (Messaging Device Path) SubType: 17 (Logical Unit Class)	Unit (<i>LUN</i>) The <i>LUN</i> is an integer and is required.
Type: 3 (Messaging Device Path) SubType: 18 (SATA)	Sata (<i>HPN, PMPN, LUN</i>) The <i>HPN</i> is an integer between 0 and 65534 and is required. The <i>PMPN</i> is an integer between 0 and 65535 and is optional. If not provided, the default is 0x0000, which implies no port multiplier. The <i>LUN</i> is a 16-bit integer. It is required. Note that LUN is applicable to ATAPI devices only, and most ATAPI devices assume LUN=0

Device Node Type/SubType/ Other	Description
Type: 3 (Messaging Device Path) SubType: 19 (iSCSI)	<p>iSCSI (<i>TargetName, PortalGroup, LUN, HeaderDigest, DataDigest, Authentication, Protocol</i>)</p> <p>The <i>TargetName</i> is a string and is required. The <i>PortalGroup</i> is an unsigned 16-bit integer and is required. The <i>LUN</i> is an unsigned 16-bit integer and is required. The <i>HeaderDigest</i> is a keyword None or CRC32C is optional. The default is None. The <i>DataDigest</i> is a keyword None or CRC32C is optional. The default is None. The <i>Authentication</i> is a keyword None or CHAP_BI or CHAP_UNI. The default is None.</p>
Type: 4	<p>MediaPath (<i>subtype, data</i>)</p> <p>The <i>subtype</i> is an integer from 0-255 and is required. The <i>data</i> is a hex dump.</p>
Type: 4 (Media Device Path) SubType: 1 (Hard Drive)	<p>HD(<i>Partition, Type, Signature, Start, Size</i>) HD(<i>Partition, Type, Signature</i>) (Display Only)</p> <p>The <i>Partition</i> is an integer representing the partition number. It is optional and the default is 0. If <i>Partition</i> is 0, then <i>Start</i> and <i>Size</i> are prohibited. The <i>Type</i> is an integer between 0-255 or else the keyword MBR (1) or GPT (2). The type is optional and the default is 2. The <i>Signature</i> is an integer if <i>Type</i> is 1 or else GUID if <i>Type</i> is 2. The signature is required. The <i>Start</i> is a 64-bit unsigned integer. It is prohibited if <i>Partition</i> is 0. Otherwise it is required. The <i>Size</i> is a 64-bit unsigned integer. It is prohibited if <i>Partition</i> is 0. Otherwise it is required.</p>
Type: 4 (Media Device Path) SubType: 2 (CD-ROM)	<p>CDROM(<i>Entry, Start, Size</i>) CDROM(<i>Entry</i>) (Display Only)</p> <p>The <i>Entry</i> is an integer representing the Boot Entry from the Boot Catalog. It is optional and the default is 0. The <i>Start</i> is a 64-bit integer and is required. The <i>Size</i> is a 64-bit integer and is required.</p>
Type: 4 (Media Device Path) SubType: 3 (Vendor)	<p>VenMedia(<i>GUID, Data</i>)</p> <p>The <i>Guid</i> is a GUID and is required. The <i>Data</i> is a Hex Dump and is option. The default value is zero bytes.</p>
Type: 4 (Media Device Path) SubType: 4 (File Path)	<p>String</p> <p>The <i>String</i> is the file path and is a string.</p>

Device Node Type/SubType/Other	Description
Type: 4 (Media Device Path) SubType: 5 (Media Protocol)	Media (<i>Guid</i>) The <i>Guid</i> is a GUID and is required.
Type: 5	BbsPath (<i>subtype, data</i>) The <i>subtype</i> is an integer from 0-255. The <i>data</i> is a hex dump.
Type: 5 – BIOS Boot Specification Device Path SubType: 1 (BBS 1.01)	BBS (<i>Type,Id,Flags</i>) BBS (<i>Type, Id</i>) (Display Only) The <i>Type</i> is an integer from 0-65535 or else one of the following keywords: Floppy (1), HD (2), CDROM (3), PCMCIA (4), USB (5), Network (6). It is required. The <i>Id</i> is a string and is required. The <i>Flags</i> are an integer and are optional. The default value is 0.

9.6.2 Device Path to Text Protocol

EFI_DEVICE_PATH_TO_TEXT_PROTOCOL

Summary

Convert device nodes and paths to text

GUID

```
#define EFI_DEVICE_PATH_TO_TEXT_PROTOCOL_GUID \
{0x8b843e20, 0x8132, 0x4852, 0x90, 0xcc, 0x55, 0x1a, 0x4e, 0x4a, \
0x7f, 0x1c}
```

Protocol Interface Structure

```
typedef struct _EFI_DEVICE_PATH_TO_TEXT_PROTOCOL {
    EFI_DEVICE_PATH_TO_TEXT_NODE ConvertDeviceNodeToText;
    EFI_DEVICE_PATH_TO_TEXT_PATH ConvertDevicePathToText;
} EFI_DEVICE_PATH_TO_TEXT_PROTOCOL;
```

Parameters

ConvertDeviceNodeToText Converts a device node to text.

ConvertDevicePathToText Converts a device path to text.

Description

The **EFI_DEVICE_PATH_TO_TEXT_PROTOCOL** provides common utility functions for converting device nodes and device paths to a text representation.

EFI_DEVICE_PATH_TO_TEXT_PROTOCOL.ConvertDeviceNodeToText()

Summary

Convert a device node to its text representation.

Prototype

```
typedef
CHAR16*
(EFI_API *EFI_DEVICE_PATH_TO_TEXT_NODE) (
    IN CONST EFI_DEVICE_PATH* DeviceNode,
    IN BOOLEAN DisplayOnly,
    IN BOOLEAN AllowShortcuts
);
```

Parameters

<i>DeviceNode</i>	Points to the device node to be converted.
<i>DisplayOnly</i>	If <i>DisplayOnly</i> is TRUE , then the shorter text representation of the display node is used, where applicable. If <i>DisplayOnly</i> is FALSE , then the longer text representation of the display node is used.
<i>AllowShortcuts</i>	If <i>AllowShortcuts</i> is TRUE , then the shortcut forms of text representation for a device node can be used, where applicable.

Description

The ConvertDeviceNodeToText function converts a device node to its text representation and copies it into a newly allocated buffer.

The *DisplayOnly* parameter controls whether the longer (parseable) or shorter (display-only) form of the conversion is used.

The *AllowShortcuts* is **FALSE**, then the shortcut forms of text representation for a device node cannot be used. A shortcut form is one which uses information other than the type or subtype.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns the pointer to the allocated text representation of the device node data or else NULL if *DeviceNode* was NULL or there was insufficient memory.

EFI_DEVICE_PATH_TO_TEXT_PROTOCOL.ConvertDevicePathToText ()

Summary

Convert a device path to its text representation.

Prototype

```
typedef
CHAR16*
(EFIAPI *EFI_DEVICE_PATH_TO_TEXT_PATH) (
    IN CONST EFI_DEVICE_PATH* DevicePath,
    IN BOOLEAN DisplayOnly,
    IN BOOLEAN AllowShortcuts
);
```

Parameters

<i>DeviceNode</i>	Points to the device path to be converted.
<i>DisplayOnly</i>	If DisplayOnly is TRUE, then the shorter text representation of the display node is used, where applicable. If DisplayOnly is FALSE, then the longer text representation of the display node is used.
<i>AllowShortcuts</i>	The AllowShortcuts is FALSE, then the shortcut forms of text representation for a device node cannot be used.

Description

This function converts a device path into its text representation and copies it into an allocated buffer.

The *DisplayOnly* parameter controls whether the longer (parseable) or shorter (display-only) form of the conversion is used.

The *AllowShortcuts* is **FALSE**, then the shortcut forms of text representation for a device node cannot be used. A shortcut form is one which uses information other than the type or subtype.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Status Codes Returned

This function returns a pointer to the allocated text representation of the device node or NULL if *DevicePath* was NULL or there was insufficient memory.

9.6.3 Device Path from Text Protocol

EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL

Summary

Convert text to device paths and device nodes.

GUID

```
#define EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL_GUID \
{0x5c99a21,0xc70f,0x4ad2,0x8a,0x5f,0x35,0xdf,0x33,0x43,
 0xf5, 0x1e}
```

Protocol Interface Structure

```
typedef struct _EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL {
    EFI_DEVICE_PATH_FROM_TEXT_NODE ConvertTextToDeviceNode;
    EFI_DEVICE_PATH_FROM_TEXT_PATH ConvertTextToDevicePath;
} EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL;
```

Parameters

ConvertTextToDeviceNode Converts text to a device node.

ConvertTextToDevicePath Converts text to a device path.

Description

The **EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL** provides common utilities for converting text to device paths and device nodes.

EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL.ConvertTextToDeviceNode()

Summary

Convert text to the binary representation of a device node.

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_FROM_TEXT_NODE) (
    IN CONST CHAR16* TextDeviceNode,
    );
```

Parameters

TextDeviceNode *TextDeviceNode* points to the text representation of a device node. Conversion starts with the first character and continues until the first non-device node character.

Description

This function converts text to its binary device node representation and copies it into an allocated buffer.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the EFI device node or NULL if *TextDeviceNode* is NULL or there was insufficient memory.

EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL.ConvertTextToDevicePath()

Summary

Convert a text to its binary device path representation.

Prototype

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFI_API *EFI_DEVICE_PATH_FROM_TEXT_PATH) (
    IN CONST CHAR16* TextDevicePath,
    );
```

Parameters

TextDevicePath *TextDevicePath* points to the text representation of a device path. Conversion starts with the first character and continues until the first non-device path character.

Description

This function converts text to its binary device path representation and copies it into an allocated buffer.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in [Section 9.2](#).

Returns

This function returns a pointer to the allocated device path or NULL if *TextDevicePath* is NULL or there was insufficient memory.

Protocols — UEFI Driver Model

EFI drivers that follow the *UEFI Driver Model* are not allowed to search for controllers to manage. When a specific controller is needed, the EFI boot service [ConnectController\(\)](#) is used along with the [EFI_DRIVER_BINDING_PROTOCOL](#) services to identify the best drivers for a controller. Once [ConnectController\(\)](#) has identified the best drivers for a controller, the start service in the [EFI_DRIVER_BINDING_PROTOCOL](#) is used by [ConnectController\(\)](#) to start each driver on the controller. Once a controller is no longer needed, it can be released with the EFI boot service [DisconnectController\(\)](#). [DisconnectController\(\)](#) calls the stop service in each [EFI_DRIVER_BINDING_PROTOCOL](#) to stop the controller.

The driver initialization routine of an UEFI driver is not allowed to touch any device hardware. Instead, it just installs an instance of the [EFI_DRIVER_BINDING_PROTOCOL](#) on the *ImageHandle* of the UEFI driver. The test to determine if a driver supports a given controller must be performed in as little time as possible without causing any side effects on any of the controllers it is testing. As a result, most of the controller initialization code is present in the start and stop services of the [EFI_DRIVER_BINDING_PROTOCOL](#).

10.1 EFI Driver Binding Protocol

This section provides a detailed description of the [EFI_DRIVER_BINDING_PROTOCOL](#). This protocol is produced by every driver that follows the *UEFI Driver Model*, and it is the central component that allows drivers and controllers to be managed. It provides a service to test if a specific controller is supported by a driver, a service to start managing a controller, and a service to stop managing a controller. These services apply equally to drivers for both bus controllers and device controllers.

EFI_DRIVER_BINDING_PROTOCOL

Summary

Provides the services required to determine if a driver supports a given controller. If a controller is supported, then it also provides routines to start and stop the controller.

GUID

```
#define EFI_DRIVER_BINDING_PROTOCOL_GUID \
    {0x18A031AB, 0xB443, 0x4D1A, 0xA5, 0xC0, 0x0C, 0x09, 0x26, 0x1E, \
     0x9F, 0x71}
```

Protocol Interface Structure

```
typedef struct _EFI_DRIVER_BINDING_PROTOCOL {
    EFI_DRIVER_BINDING_PROTOCOL_SUPPORTED    Supported;
    EFI_DRIVER_BINDING_PROTOCOL_START       Start;
```

```

EFI_DRIVER_BINDING_PROTOCOL_STOP      Stop;
UINT32                                Version;
EFI_HANDLE                            ImageHandle;
EFI_HANDLE                            DriverBindingHandle;
} EFI_DRIVER_BINDING_PROTOCOL;

```

Parameters

<i>Supported</i>	Tests to see if this driver supports a given controller. This service is called by the EFI boot service ConnectController() . In order to make drivers as small as possible, there are a few calling restrictions for this service. ConnectController() must follow these calling restrictions. If any other agent wishes to call Supported() it must also follow these calling restrictions. See the Supported() function description.
<i>Start</i>	Starts a controller using this driver. This service is called by the EFI boot service ConnectController() . In order to make drivers as small as possible, there are a few calling restrictions for this service. ConnectController() must follow these calling restrictions. If any other agent wishes to call Start() it must also follow these calling restrictions. See the Start() function description.
<i>Stop</i>	Stops a controller using this driver. This service is called by the EFI boot service DisconnectController() . In order to make drivers as small as possible, there are a few calling restrictions for this service. DisconnectController() must follow these calling restrictions. If any other agent wishes to call Stop() it must also follow these calling restrictions. See the Stop() function description.
<i>Version</i>	The version number of the UEFI driver that produced the EFI_DRIVER_BINDING_PROTOCOL . This field is used by the EFI boot service ConnectController() to determine the order that driver's Supported() service will be used when a controller needs to be started. EFI Driver Binding Protocol instances with higher <i>Version</i> values will be used before ones with lower <i>Version</i> values. The <i>Version</i> values of <i>0x0-0x0f</i> and <i>0xffffffff0-0xffffffff</i> are reserved for platform/OEM specific drivers. The <i>Version</i> values of <i>0x10-0xfffffef</i> are reserved for IHV-developed drivers.
<i>ImageHandle</i>	The image handle of the UEFI driver that produced this instance of the EFI_DRIVER_BINDING_PROTOCOL .
<i>DriverBindingHandle</i>	The handle on which this instance of the EFI_DRIVER_BINDING_PROTOCOL is installed. In most cases, this is the same handle as <i>ImageHandle</i> . However, for UEFI drivers that produce more than one instance of the EFI_DRIVER_BINDING_PROTOCOL , this value may not be the same as <i>ImageHandle</i> .

Description

The **EFI_DRIVER_BINDING_PROTOCOL** provides a service to determine if a driver supports a given controller. If a controller is supported, then it also provides services to start and stop the controller. All UEFI drivers are required to be reentrant so they can manage one or more controllers. This requires that drivers not use global variables to store device context. Instead, they must allocate a separate context structure per controller that the driver is managing. Bus drivers must support starting and stopping the same bus multiple times, and they must also support starting and stopping all of their children, or just a subset of their children.

EFI_DRIVER_BINDING_PROTOCOL.Supported()

Summary

Tests to see if this driver supports a given controller. If a child device is provided, it further tests to see if this driver supports creating a handle for the specified child device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DRIVER_BINDING_PROTOCOL_SUPPORTED) (
    IN EFI_DRIVER_BINDING_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI DRIVER BINDING PROTOCOL instance.
<i>ControllerHandle</i>	The handle of the controller to test. This handle must support a protocol interface that supplies an I/O abstraction to the driver. Sometimes just the presence of this I/O abstraction is enough for the driver to determine if it supports <i>ControllerHandle</i> . Sometimes, the driver may use the services of the I/O abstraction to determine if this driver supports <i>ControllerHandle</i> .
<i>RemainingDevicePath</i>	A pointer to the remaining portion of a device path. This parameter is ignored by device drivers, and is optional for bus drivers. For bus drivers, if this parameter is not NULL , then the bus driver must determine if the bus controller specified by <i>ControllerHandle</i> and the child controller specified by <i>RemainingDevicePath</i> are both supported by this bus driver.

Description

This function checks to see if the driver specified by *This* supports the device specified by *ControllerHandle*. Drivers will typically use the device path attached to *ControllerHandle* and/or the services from the bus I/O abstraction attached to *ControllerHandle* to determine if the driver supports *ControllerHandle*. This function may be called many times during platform initialization. In order to reduce boot times, the tests performed by this function must be very small, and take as little time as possible to execute. This function must not change the state of any hardware devices, and this function must be aware that the device specified by *ControllerHandle* may already be managed by the same driver or a different driver. This function must match its calls to [AllocatePages \(\)](#) with [FreePages \(\)](#), [AllocatePool \(\)](#) with [FreePool \(\)](#), and [OpenProtocol \(\)](#) with [CloseProtocol \(\)](#). Since *ControllerHandle* may have been previously started by the same driver, if a protocol is already in the opened state, then it must not be closed with **CloseProtocol ()**. This is required to guarantee the state of *ControllerHandle* is not modified by this function.

If any of the protocol interfaces on the device specified by *ControllerHandle* that are required by the driver specified by *This* are already open for exclusive access by a different driver or application, then **EFI_ACCESS_DENIED** is returned.

If any of the protocol interfaces on the device specified by *ControllerHandle* that are required by the driver specified by *This* are already opened by the same driver, then **EFI_ALREADY_STARTED** is returned. However, if the driver specified by *This* is a bus driver that is able to create one child handle at a time, then it is not an error, and the bus driver should continue with its test of *ControllerHandle*. This allows a bus driver to create one child handle on the first call to [Supported\(\)](#) and [Start\(\)](#), and create additional child handles on additional calls to [Supported\(\)](#) and [Start\(\)](#).

If *ControllerHandle* is not supported by *This*, then **EFI_UNSUPPORTED** is returned.

If *This* is a bus driver that creates child handles with an [EFI_DEVICE_PATH_PROTOCOL](#), then *ControllerHandle* must support the **EFI_DEVICE_PATH_PROTOCOL**. If it does not, then **EFI_UNSUPPORTED** is returned.

If *ControllerHandle* is supported by *This*, and *This* is a device driver, then **EFI_SUCCESS** is returned.

If *ControllerHandle* is supported by *This*, and *This* is a bus driver, and *RemainingDevicePath* is **NULL**, then **EFI_SUCCESS** is returned.

If *ControllerHandle* is supported by *This*, and *This* is a bus driver, and *RemainingDevicePath* is not **NULL**, then *RemainingDevicePath* must be analyzed. If the first node of **RemainingDevicePath** is an EFI Device Path node that the bus driver recognizes and supports, then **EFI_SUCCESS** is returned. Otherwise, **EFI_UNSUPPORTED** is returned.

The [Supported\(\)](#) function is designed to be invoked from the EFI boot service [ConnectController\(\)](#). As a result, much of the error checking on the parameters to [Supported\(\)](#) has been moved into this common boot service. It is legal to call [Supported\(\)](#) from other locations, but the following calling restrictions must be followed or the system behavior will not be deterministic.

ControllerHandle must be a valid **EFI_HANDLE**. If *RemainingDevicePath* is not **NULL**, then it must be a pointer to a naturally aligned **EFI_DEVICE_PATH_PROTOCOL** that contains at least one device path node other than the end node.

Status Codes Returned

EFI_SUCCESS	The device specified by <i>ControllerHandle</i> and <i>RemainingDevicePath</i> is supported by the driver specified by <i>This</i> .
EFI_ALREADY_STARTED	The device specified by <i>ControllerHandle</i> and <i>RemainingDevicePath</i> is already being managed by the driver specified by <i>This</i> .
EFI_ACCESS_DENIED	The device specified by <i>ControllerHandle</i> and <i>RemainingDevicePath</i> is already being managed by a different driver or an application that requires exclusive access.
EFI_UNSUPPORTED	The device specified by <i>ControllerHandle</i> and <i>RemainingDevicePath</i> is not supported by the driver specified by <i>This</i> .

Examples

```
extern EFI_GUID          gEfiDriverBindingProtocolGuid;
EFI_HANDLE              DriverImageHandle;
EFI_HANDLE              ControllerHandle;
EFI_DRIVER_BINDING_PROTOCOL *DriverBinding;
EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath;

//
// Use the DriverImageHandle to get the Driver Binding Protocol instance
//
Status = gBS->OpenProtocol (
    DriverImageHandle,
    &gEfiDriverBindingProtocolGuid,
    &DriverBinding,
    DriverImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return Status;
}

//
// EXAMPLE #1
//
// Use the Driver Binding Protocol instance to test to see if the
// driver specified by DriverImageHandle supports the controller
// specified by ControllerHandle
//
Status = DriverBinding->Supported (
    DriverBinding,
    ControllerHandle,
    NULL
);

return Status;

//
// EXAMPLE #2
```



```
//
// The RemainingDevicePath parameter can be used to initialize only
// the minimum devices required to boot. For example, maybe we only
// want to initialize 1 hard disk on a SCSI channel. If DriverImageHandle
// is a SCSI Bus Driver, and ControllerHandle is a SCSI Controller, and
// we only want to create a child handle for PUN=3 and LUN=0, then the
// RemainingDevicePath would be SCSI(3,0)/END. The following example
// would return EFI_SUCCESS if the SCSI driver supports creating the
// child handle for PUN=3, LUN=0. Otherwise it would return an error.
//
Status = DriverBinding->Supported (
    DriverBinding,
    ControllerHandle,
    RemainingDevicePath
);

return Status;
```

Pseudo Code

Listed below are the algorithms for the [Supported\(\)](#) function for three different types of drivers. How the [Start\(\)](#) function of a driver is implemented can affect how the [Supported\(\)](#) function is implemented. All of the services in the [EFI DRIVER BINDING PROTOCOL](#) need to work together to make sure that all resources opened or allocated in [Supported\(\)](#) and [Start\(\)](#) are released in [Stop\(\)](#).

The first algorithm is a simple device driver that does not create any additional handles. It only attaches one or more protocols to an existing handle. The second is a bus driver that always creates all of its child handles on the first call to [Start\(\)](#). The third is a more advanced bus driver that can either create one child handles at a time on successive calls to [Start\(\)](#), or it can create all of its child handles or all of the remaining child handles in a single call to [Start\(\)](#).

Device Driver:

1. Ignore the parameter *RemainingDevicePath*.
2. Open all required protocols with [OpenProtocol\(\)](#). A standard driver should use an *Attribute* of [EFI_OPEN_PROTOCOL_BY_DRIVER](#). If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an *Attribute* of [EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE](#).
3. If any of the calls to [OpenProtocol\(\)](#) in (2) returned an error, then close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return the status code from the call to [OpenProtocol\(\)](#) that returned an error.
4. Use the protocol instances opened in (2) to test to see if this driver supports the controller. Sometimes, just the presence of the protocols is enough of a test. Other times, the services of the protocols opened in (2) are used to further check the identity of the controller. If any of these tests fails, then close all the protocols opened in (2) with [CloseProtocol\(\)](#) and return [EFI_UNSUPPORTED](#).
5. Close all protocols opened in (2) with [CloseProtocol\(\)](#).
6. Return [EFI_SUCCESS](#).

Bus Driver that creates all of its child handles on the first call to Start():

1. Check the contents of the first Device Path Node of *RemainingDevicePath* to make sure it is a legal Device Path Node for this bus driver's children. If it is not, then return [EFI_UNSUPPORTED](#).

2. Open all required protocols with [OpenProtocol\(\)](#). A standard driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER**. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE**.
3. If any of the calls to [OpenProtocol\(\)](#) in (2) returned an error, then close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return the status code from the call to [OpenProtocol\(\)](#) that returned an error.
4. Use the protocol instances opened in (2) to test to see if this driver supports the controller. Sometimes, just the presence of the protocols is enough of a test. Other times, the services of the protocols opened in (2) are used to further check the identity of the controller. If any of these tests fails, then close all the protocols opened in (2) with [CloseProtocol\(\)](#) and return **EFI_UNSUPPORTED**.
5. Close all protocols opened in (2) with [CloseProtocol\(\)](#).
6. Return **EFI_SUCCESS**.

Bus Driver that is able to create all or one of its child handles on each call to Start():

1. Check the contents of the first Device Path Node of *RemainingDevicePath* to make sure it is a legal Device Path Node for this bus driver's children. If it is not, then return **EFI_UNSUPPORTED**.
2. Open all required protocols with [OpenProtocol\(\)](#). A standard driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER**. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE**.
3. If any of the calls to [OpenProtocol\(\)](#) in (2) failed with an error other than **EFI_ALREADY_STARTED**, then close all of the protocols opened in (2) that did not return **EFI_ALREADY_STARTED** with [CloseProtocol\(\)](#), and return the status code from the [OpenProtocol\(\)](#) call that returned an error.
4. Use the protocol instances opened in (2) to test to see if this driver supports the controller. Sometimes, just the presence of the protocols is enough of a test. Other times, the services of the protocols opened in (2) are used to further check the identity of the controller. If any of these tests fails, then close all the protocols opened in (2) that did not return **EFI_ALREADY_STARTED** with [CloseProtocol\(\)](#) and return **EFI_UNSUPPORTED**.
5. Close all protocols opened in (2) that did not return **EFI_ALREADY_STARTED** with [CloseProtocol\(\)](#).
6. Return **EFI_SUCCESS**.

Listed below is sample code of the [Supported\(\)](#) function of device driver for a device on the XYZ bus. The XYZ bus is abstracted with the **EFI_XYZ_IO_PROTOCOL**. Just the presence of the **EFI_XYZ_IO_PROTOCOL** on *ControllerHandle* is enough to determine if this driver supports *ControllerHandle*. The **gBS** variable is initialized in this driver's entry point. See [Section 4](#).

```
extern EFI_GUID          gEfiXyzIoProtocol;
EFI_BOOT_SERVICES_TABLE *gBS;

EFI_STATUS
AbcSupported (
```

```

IN EFI_DRIVER_BINDING_PROTOCOL *This,
IN EFI_HANDLE                  ControllerHandle,
IN EFI_DEVICE_PATH_PROTOCOL    *RemainingDevicePath  OPTIONAL
)

{
  EFI_STATUS      Status;
  EFI_XYZ_IO_PROTOCOL *XYZIo;

  Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXYZIoProtocol,
    &XYZIo,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_BY_DRIVER
  );
  if (EFI_ERROR (Status)) {
    return Status;
  }

  gBS->CloseProtocol (
    ControllerHandle,
    &gEfiXYZIoProtocol,
    This->DriverBindingHandle,
    ControllerHandle
  );

  return EFI_SUCCESS;
}

```

EFI_DRIVER_BINDING_PROTOCOL.Start()

Summary

Starts a device controller or a bus controller. The **Start()** and **Stop()** services of the [EFI DRIVER BINDING PROTOCOL](#) mirror each other.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DRIVER_BINDING_PROTOCOL_START) (
    IN  EFI_DRIVER_BINDING_PROTOCOL  *This,
    IN  EFI_HANDLE                    ControllerHandle,
    IN  EFI_DEVICE_PATH_PROTOCOL     *RemainingDevicePath  OPTIONAL
);
```

Parameters

This A pointer to the **EFI_DRIVER_BINDING_PROTOCOL** instance.

ControllerHandle The handle of the controller to start. This handle must support a protocol interface that supplies an I/O abstraction to the driver.

RemainingDevicePath A pointer to the remaining portion of a device path. This parameter is ignored by device drivers, and is optional for bus drivers. For a bus driver, if this parameter is **NULL**, then handles for all the children of *Controller* are created by this driver. If this parameter is not **NULL**, then only the handle for the child device specified by the first Device Path Node of *RemainingDevicePath* is created by this driver.

Description

This function starts the device specified by *Controller* with the driver specified by *This*. Whatever resources are allocated in **Start()** must be freed in **Stop()**. For example, every [AllocatePool\(\)](#), [AllocatePages\(\)](#), [OpenProtocol\(\)](#), and [InstallProtocolInterface\(\)](#) in **Start()** must be matched with a [FreePool\(\)](#), [FreePages\(\)](#), [CloseProtocol\(\)](#), and [UninstallProtocolInterface\(\)](#) in **Stop()**.

If *Controller* is started, then **EFI_SUCCESS** is returned. If *Controller* cannot be started due to a device error, then **EFI_DEVICE_ERROR** is returned. If there are not enough resources to start the device or bus specified by *Controller*, then **EFI_OUT_OF_RESOURCES** is returned.

If the driver specified by *This* is a device driver, then *RemainingDevicePath* is ignored.

If the driver specified by *This* is a bus driver, and *RemainingDevicePath* is **NULL**, then all of the children of *Controller* are discovered and enumerated, and a device handle is created for each child.

If the driver specified by *This* is a bus driver that is capable of creating one child handle at a time and *RemainingDevicePath* is not **NULL**, then an attempt is made to create the device handle for the child device specified by *RemainingDevicePath*. Depending on the bus type, all of the

child devices may need to be discovered and enumerated, but at most only the device handle for the one child specified by *RemainingDevicePath* shall be created.

The **Start()** function is designed to be invoked from the EFI boot service **ConnectController()**. As a result, much of the error checking on the parameters to **Start()** has been moved into this common boot service. It is legal to call **Start()** from other locations, but the following calling restrictions must be followed or the system behavior will not be deterministic.

- *ControllerHandle* must be a valid **EFI_HANDLE**.
- If *RemainingDevicePath* is not **NULL**, then it must be a pointer to a naturally aligned **EFI_DEVICE_PATH_PROTOCOL** that contains at least one device path node other than the end node.
- Prior to calling **Start()**, the **Supported()** function for the driver specified by *This* must have been called with the same calling parameters, and **Supported()** must have returned **EFI_SUCCESS**.

Status Codes Returned

EFI_SUCCESS	The device was started.
EFI_DEVICE_ERROR	The device could not be started due to a device error.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

Examples

```
extern EFI_GUID          gEfiDriverBindingProtocolGuid;
EFI_HANDLE              DriverImageHandle;
EFI_HANDLE              ControllerHandle;
EFI_DRIVER_BINDING_PROTOCOL *DriverBinding;
EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath;

//
// Use the DriverImageHandle to get the Driver Binding Protocol instance
//
Status = gBS->OpenProtocol (
    DriverImageHandle,
    &gEfiDriverBindingProtocolGuid,
    &DriverBinding,
    DriverImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return Status;
}

//
// EXAMPLE #1
//
// Use the Driver Binding Protocol instance to test to see if the
// driver specified by DriverImageHandle supports the controller
// specified by ControllerHandle
//
Status = DriverBinding->Supported (
```

```

        DriverBinding,
        ControllerHandle,
        NULL
    );
    if (!EFI_ERROR (Status)) {
        Status = DriverBinding->Start (
            DriverBinding,
            ControllerHandle,
            NULL
        );
    }

    return Status;

//
// EXAMPLE #2
//
// The RemainingDevicePath parameter can be used to initialize only
// the minimum devices required to boot. For example, maybe we only
// want to initialize 1 hard disk on a SCSI channel. If DriverImageHandle
// is a SCSI Bus Driver, and ControllerHandle is a SCSI Controller, and
// we only want to create a child handle for PUN=3 and LUN=0, then the
// RemainingDevicePath would be SCSI(3,0)/END. The following example
// would return EFI_SUCCESS if the SCSI driver supports creating the
// child handle for PUN=3, LUN=0. Otherwise it would return an error.
//
    Status = DriverBinding->Supported (
        DriverBinding,
        ControllerHandle,
        RemainingDevicePath
    );
    if (!EFI_ERROR (Status)) {
        Status = DriverBinding->Start (
            DriverBinding,
            ControllerHandle,
            RemainingDevicePath
        );
    }

    return Status;

```

Pseudo Code

Listed below are the algorithms for the [Start\(\)](#) function for three different types of drivers. How the [Start\(\)](#) function of a driver is implemented can affect how the [Supported\(\)](#) function is implemented. All of the services in the [EFI DRIVER BINDING PROTOCOL](#) need to work together to make sure that all resources opened or allocated in [Supported\(\)](#) and [Start\(\)](#) are released in [Stop\(\)](#).

The first algorithm is a simple device driver that does not create any additional handles. It only attaches one or more protocols to an existing handle. The second is a simple bus driver that always creates all of its child handles on the first call to [Start\(\)](#). It does not attach any additional protocols to the handle for the bus controller. The third is a more advanced bus driver that can either create one child handles at a time on successive calls to [Start\(\)](#), or it can create all of its child handles or all of the remaining child handles in a single call to [Start\(\)](#). Once again, it does not attach any additional protocols to the handle for the bus controller.

Device Driver:

1. Ignore the parameter *RemainingDevicePath*.
2. Open all required protocols with [OpenProtocol\(\)](#). A standard driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER**. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE**. It must use the same *Attribute* value that was used in [Supported\(\)](#).
3. If any of the calls to [OpenProtocol\(\)](#) in (2) returned an error, then close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return the status code from the call to [OpenProtocol\(\)](#) that returned an error.
4. Initialize the device specified by *ControllerHandle*. If an error occurs, close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return **EFI_DEVICE_ERROR**.
5. Allocate and initialize all of the data structures that this driver requires to manage the device specified by *ControllerHandle*. This would include space for public protocols and space for any additional private data structures that are related to *ControllerHandle*. If an error occurs allocating the resources, then close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return **EFI_OUT_OF_RESOURCES**.
6. Install all the new protocol interfaces onto *ControllerHandle* using [InstallMultipleProtocolInterfaces\(\)](#). If an error occurs, close all of the protocols opened in (1) with [CloseProtocol\(\)](#), and return the error from [InstallMultipleProtocolInterfaces\(\)](#).
7. Return **EFI_SUCCESS**.

Bus Driver that creates all of its child handles on the first call to Start():

1. Ignore the parameter *RemainingDevicePath*.
2. Open all required protocols with [OpenProtocol\(\)](#). A standard driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER**. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE**. It must use the same *Attribute* value that was used in [Supported\(\)](#).
3. If any of the calls to [OpenProtocol\(\)](#) in (2) returned an error, then close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return the status code from the call to [OpenProtocol\(\)](#) that returned an error.
4. Initialize the device specified by *ControllerHandle*. If an error occurs, close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return **EFI_DEVICE_ERROR**.
5. Discover all the child devices of the bus controller specified by *ControllerHandle*.
6. If the bus requires it, allocate resources to all the child devices of the bus controller specified by *ControllerHandle*.
7. FOR each child C of *ControllerHandle*:
 - a Allocate and initialize all of the data structures that this driver requires to manage the child device C. This would include space for public protocols and space for any additional private data structures that are related to the child device C. If an error occurs allocating the resources, then close all of the protocols opened in (2) with [CloseProtocol\(\)](#), and return **EFI_OUT_OF_RESOURCES**.

- b If the bus driver creates device paths for the child devices, then create a device path for the child C based upon the device path attached to *ControllerHandle*.
 - c Initialize the child device C. If an error occurs, close all of the protocols opened in (2) with **CloseProtocol()**, and return **EFI_DEVICE_ERROR**.
 - d Create a new handle for C, and install the protocol interfaces for child device C using **InstallMultipleProtocolInterfaces()**. This may include the **EFI_DEVICE_PATH_PROTOCOL**.
 - e Call **OpenProtocol()** on behalf of the child C with an *Attribute* of **EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER**.
8. END FOR
9. If the bus driver also produces protocols on *ControllerHandle*, then install all the new protocol interfaces onto *ControllerHandle* using **InstallMultipleProtocolInterfaces()**. If an error occurs, close all of the protocols opened in (2) with **CloseProtocol()**, and return the error from **InstallMultipleProtocolInterfaces()**.
10. Return **EFI_SUCCESS**.

Bus Driver that is able to create all or one of its child handles on each call to Start():

1. Open all required protocols with **OpenProtocol()**. A standard driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER**. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an *Attribute* of **EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE**. It must use the same *Attribute* value that was used in **Supported()**.
2. If any of the calls to **OpenProtocol()** in (1) returned an error, then close all of the protocols opened in (1) with **CloseProtocol()**, and return the status code from the call to **OpenProtocol()** that returned an error.
3. Initialize the device specified by *ControllerHandle*. If an error occurs, close all of the protocols opened in (1) with **CloseProtocol()**, and return **EFI_DEVICE_ERROR**.
4. IF *RemainingDevicePath* is not **NULL**, THEN
 - a C is the child device specified by *RemainingDevicePath*.
 - b Allocate and initialize all of the data structures that this driver requires to manage the child device C. This would include space for public protocols and space for any additional private data structures that are related to the child device C. If an error occurs allocating the resources, then close all of the protocols opened in (1) with **CloseProtocol()**, and return **EFI_OUT_OF_RESOURCES**.
 - c If the bus driver creates device paths for the child devices, then create a device path for the child C based upon the device path attached to *ControllerHandle*.
 - d Initialize the child device C.
 - e Create a new handle for C, and install the protocol interfaces for child device C using **InstallMultipleProtocolInterfaces()**. This may include the **EFI_DEVICE_PATH_PROTOCOL**.
 - f Call **OpenProtocol()** on behalf of the child C with an *Attribute* of **EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER**.

ELSE

- a Discover all the child devices of the bus controller specified by *ControllerHandle*.
- b If the bus requires it, allocate resources to all the child devices of the bus controller specified by *ControllerHandle*.
- c FOR each child C of *ControllerHandle*

Allocate and initialize all of the data structures that this driver requires to manage the child device C. This would include space for public protocols and space for any additional private data structures that are related to the child device C. If an error occurs allocating the resources, then close all of the protocols opened in (1) with **CloseProtocol()**, and return **EFI_OUT_OF_RESOURCES**.

If the bus driver creates device paths for the child devices, then create a device path for the child C based upon the device path attached to *ControllerHandle*.

Initialize the child device C.

Create a new handle for C, and install the protocol interfaces for child device C using **InstallMultipleProtocolInterfaces()**. This may include the **EFI_DEVICE_PATH_PROTOCOL**.

Call **OpenProtocol()** on behalf of the child C with an *Attribute* of **EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER**.

- d END FOR

5. END IF

- 6. If the bus driver also produces protocols on *ControllerHandle*, then install all the new protocol interfaces onto *ControllerHandle* using **InstallMultipleProtocolInterfaces()**. If an error occurs, close all of the protocols opened in (2) with **CloseProtocol()**, and return the error from **InstallMultipleProtocolInterfaces()**.

7. Return **EFI_SUCCESS**.

Listed below is sample code of the **Start()** function of a device driver for a device on the XYZ bus. The XYZ bus is abstracted with the **EFI_XYZ_IO_PROTOCOL**. This driver does allow the **EFI_XYZ_IO_PROTOCOL** to be shared with other drivers, and just the presence of the **EFI_XYZ_IO_PROTOCOL** on *ControllerHandle* is enough to determine if this driver supports *ControllerHandle*. This driver installs the **EFI_ABC_IO_PROTOCOL** on *ControllerHandle*. The **gBS** variable is initialized in this driver's entry point as shown in the UEFI Driver Model examples in [Section 1.6](#).

```
extern EFI_GUID          gEfiXyzIoProtocol;
extern EFI_GUID          gEfiAbcIoProtocol;
EFI_BOOT_SERVICES_TABLE *gBS;

EFI_STATUS
AbcStart (
    IN EFI_DRIVER_BINDING_PROTOCOL *This,
    IN EFI_HANDLE                  ControllerHandle,
    IN EFI_DEVICE_PATH_PROTOCOL    *RemainingDevicePath OPTIONAL
)
{
    EFI_STATUS          Status;
    EFI_XYZ_IO_PROTOCOL *XyzIo;
}
```

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```
EFI_ABC_DEVICE      AbcDevice;

//
// Open the Xyz I/O Protocol that this driver consumes
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiXyzIoProtocol,
    &XyzIo,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_BY_DRIVER
);
if (EFI_ERROR (Status)) {
    return Status;
}

//
// Allocate and zero a private data structure for the Abc device.
//
Status = gBS->AllocatePool (
    EfiBootServicesData,
    sizeof (EFI_ABC_DEVICE),
    &AbcDevice
);
if (EFI_ERROR (Status)) {
    goto ErrorExit;
}
ZeroMem (AbcDevice, sizeof (EFI_ABC_DEVICE));

//
// Initialize the contents of the private data structure for the Abc device.
// This includes the XyzIo protocol instance and other private data fields
// and the EFI_ABC_IO_PROTOCOL instance that will be installed.
//
AbcDevice->Signature      = EFI_ABC_DEVICE_SIGNATURE;
AbcDevice->XyzIo          = XyzIo;

AbcDevice->PrivateData1   = PrivateValue1;
AbcDevice->PrivateData2   = PrivateValue2;
. . .
AbcDevice->PrivateDataN   = PrivateValueN;

AbcDevice->AbcIo.Revision = EFI_ABC_IO_PROTOCOL_REVISION;
AbcDevice->AbcIo.Func1    = AbcIoFunc1;
AbcDevice->AbcIo.Func2    = AbcIoFunc2;
. . .
AbcDevice->AbcIo.FuncN    = AbcIoFuncN;

AbcDevice->AbcIo.Data1    = Value1;
AbcDevice->AbcIo.Data2    = Value2;
. . .
AbcDevice->AbcIo.DataN    = ValueN;

//
// Install protocol interfaces for the ABC I/O device.
//
Status = gBS->InstallMultipleProtocolInterfaces (
    &ControllerHandle,
    &gEfiAbcIoProtocolGuid, &AbcDevice->AbcIo,
```

```
        NULL
    );
    if (EFI_ERROR (Status)) {
        goto ErrorExit;
    }

    return EFI_SUCCESS;

ErrorExit:
    //
    // When there is an error, the private data structures need to be freed and
    // the protocols that were opened need to be closed.
    //
    if (AbcDevice != NULL) {
        gBS->FreePool (AbcDevice);
    }
    gBS->CloseProtocol (
        ControllerHandle,
        &gEfiXYZIoProtocolGuid,
        This->DriverBindingHandle,
        ControllerHandle
    );
    return Status;
}
```

EFI_DRIVER_BINDING_PROTOCOL.Stop()

Summary

Stops a device controller or a bus controller. The [Start\(\)](#) and **Stop()** services of the [EFI DRIVER BINDING PROTOCOL](#) mirror each other.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DRIVER_BINDING_PROTOCOL_STOP) (
    IN  EFI_DRIVER_BINDING_PROTOCOL  *This,
    IN  EFI_HANDLE                   ControllerHandle,
    IN  UINTN                        NumberOfChildren,
    IN  EFI_HANDLE                   *ChildHandleBuffer  OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_DRIVER_BINDING_PROTOCOL instance. Type EFI_DRIVER_BINDING_PROTOCOL is defined in Section 10.1 .
<i>ControllerHandle</i>	A handle to the device being stopped. The handle must support a bus specific I/O protocol for the driver to use to stop the device.
<i>NumberOfChildren</i>	The number of child device handles in <i>ChildHandleBuffer</i> .
<i>ChildHandleBuffer</i>	An array of child handles to be freed. May be NULL if <i>NumberOfChildren</i> is 0.

Description

This function performs different operations depending on the parameter *NumberOfChildren*. If *NumberOfChildren* is not zero, then the driver specified by *This* is a bus driver, and it is being requested to free one or more of its child handles specified by *NumberOfChildren* and *ChildHandleBuffer*. If all of the child handles are freed, then **EFI_SUCCESS** is returned. If *NumberOfChildren* is zero, then the driver specified by *This* is either a device driver or a bus driver, and it is being requested to stop the controller specified by *ControllerHandle*. If *ControllerHandle* is stopped, then **EFI_SUCCESS** is returned. In either case, this function is required to undo what was performed in **Start()**. Whatever resources are allocated in **Start()** must be freed in **Stop()**. For example, every [AllocatePool\(\)](#), [AllocatePages\(\)](#), [OpenProtocol\(\)](#), and [InstallProtocolInterface\(\)](#) in **Start()** must be matched with a [FreePool\(\)](#), [FreePages\(\)](#), [CloseProtocol\(\)](#), and [UninstallProtocolInterface\(\)](#) in **Stop()**.

If *ControllerHandle* cannot be stopped, then **EFI_DEVICE_ERROR** is returned. If, for some reason, there are not enough resources to stop *ControllerHandle*, then **EFI_OUT_OF_RESOURCES** is returned.

The **Stop()** function is designed to be invoked from the EFI boot service [DisconnectController\(\)](#). As a result, much of the error checking on the parameters to **Stop()** has been moved into this common boot service. It is legal to call **Stop()** from other

locations, but the following calling restrictions must be followed or the system behavior will not be deterministic.

- *ControllerHandle* must be a valid **EFI_HANDLE** that was used on a previous call to this same driver's [Start\(\)](#) function.
- The first *NumberOfChildren* handles of *ChildHandleBuffer* must all be a valid **EFI_HANDLE**. In addition, all of these handles must have been created in this driver's **Start()** function, and the **Start()** function must have called [OpenProtocol\(\)](#) on *ControllerHandle* with an *Attribute* of **EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER**.

Status Codes Returned

EFI_SUCCESS	The device was stopped.
EFI_DEVICE_ERROR	The device could not be stopped due to a device error.

Examples

```
extern EFI_GUID          gEfiDriverBindingProtocolGuid;
EFI_HANDLE              DriverImageHandle;
EFI_HANDLE              ControllerHandle;
EFI_HANDLE              ChildHandle;
EFI_DRIVER_BINDING_PROTOCOL *DriverBinding;

//
// Use the DriverImageHandle to get the Driver Binding Protocol instance
//
Status = gBS->OpenProtocol (
    DriverImageHandle,
    &gEfiDriverBindingProtocolGuid,
    &DriverBinding,
    DriverImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return Status;
}

//
// Use the Driver Binding Protocol instance to free the child
// specified by ChildHandle. Then, use the Driver Binding
// Protocol to stop ControllerHandle.
//
Status = DriverBinding->Stop (
    DriverBinding,
    ControllerHandle,
    1,
    &ChildHandle
);

Status = DriverBinding->Stop (
    DriverBinding,
    ControllerHandle,
    0,
    NULL
);
```

);

Pseudo Code

Device Driver:

1. Uninstall all the protocols that were installed onto *ControllerHandle* in [Start\(\)](#).
2. Close all the protocols that were opened on behalf of *ControllerHandle* in [Start\(\)](#).
3. Free all the structures that were allocated on behalf of *ControllerHandle* in [Start\(\)](#).
4. Return **EFI_SUCCESS**.

Bus Driver that creates all of its child handles on the first call to Start():

Bus Driver that is able to create all or one of its child handles on each call to Start():

1. IF *NumberOfChildren* is zero THEN:
 - a Uninstall all the protocols that were installed onto *ControllerHandle* in [Start\(\)](#).
 - b Close all the protocols that were opened on behalf of *ControllerHandle* in [Start\(\)](#).
 - c Free all the structures that were allocated on behalf of *ControllerHandle* in [Start\(\)](#).
2. ELSE
 - a FOR each child C in *ChildHandleBuffer*
 - Uninstall all the protocols that were installed onto C in [Start\(\)](#).
 - Close all the protocols that were opened on behalf of C in [Start\(\)](#).
 - Free all the structures that were allocated on behalf of C in [Start\(\)](#).
 - b END FOR
3. END IF
4. Return **EFI_SUCCESS**.

Listed below is sample code of the [Stop\(\)](#) function of a device driver for a device on the XYZ bus. The XYZ bus is abstracted with the **EFI_XYZ_IO_PROTOCOL**. This driver does allow the **EFI_XYZ_IO_PROTOCOL** to be shared with other drivers, and just the presence of the **EFI_XYZ_IO_PROTOCOL** on *ControllerHandle* is enough to determine if this driver supports *ControllerHandle*. This driver installs the **EFI_ABC_IO_PROTOCOL** on *ControllerHandle* in [Start\(\)](#). The **gBS** variable is initialized in this driver's entry point. See [Section 4](#).

```
extern EFI_GUID          gEfiXyzIoProtocol;
extern EFI_GUID          gEfiAbcIoProtocol;
EFI_BOOT_SERVICES_TABLE *gBS;

EFI_STATUS
AbcStop (
    IN EFI_DRIVER_BINDING_PROTOCOL *This,
    IN EFI_HANDLE                  ControllerHandle,
    IN UINTN                       NumberOfChildren,
    IN EFI_HANDLE                  *ChildHandleBuffer OPTIONAL
)
{
    EFI_STATUS          Status;
    EFI_ABC_IO          AbcIo;
    EFI_ABC_DEVICE      AbcDevice;
```

```

//
// Get our context back
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiAbcIoProtocolGuid,
    &AbcIo,
    This->DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return EFI_UNSUPPORTED;
}

//
// Use Containment Record Macro to get AbcDevice structure from
// a pointer to the AbcIo structure within the AbcDevice structure.
//
AbcDevice = ABC_IO_PRIVATE_DATA_FROM_THIS (AbcIo);

//
// Uninstall the protocol installed in Start()
//
Status = gBS->UninstallMultipleProtocolInterfaces (
    ControllerHandle,
    &gEfiAbcIoProtocolGuid, &AbcDevice->AbcIo,
    NULL
);
if (!EFI_ERROR (Status)) {

    //
    // Close the protocol opened in Start()
    //
    Status = gBS->CloseProtocol (
        ControllerHandle,
        &gEfiXyzIoProtocolGuid,
        This->DriverBindingHandle,
        ControllerHandle
    );

    //
    // Free the structure allocated in Start().
    //
    gBS->FreePool (AbcDevice);
}

return Status;
}

```

10.2 EFI Platform Driver Override Protocol

This section provides a detailed description of the **EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL**. This protocol can override the default algorithm for matching drivers to controllers.

EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL

Summary

This protocol matches one or more drivers to a controller. A platform driver produces this protocol, and it is installed on a separate handle. This protocol is used by the [ConnectController\(\)](#) boot service to select the best driver for a controller. All of the drivers returned by this protocol have a higher precedence than drivers found from an EFI Bus Specific Driver Override Protocol or drivers found from the general UEFI driver Binding search algorithm. If more than one driver is returned by this protocol, then the drivers are returned in order from highest precedence to lowest precedence.

GUID

```
#define EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL_GUID \
    {0x6b30c738, 0xa391, 0x11d4, 0x9a, 0x3b, 0x00, 0x90, 0x27, 0x3f, \
     0xc1, 0x4d}
```

Protocol Interface Structure

```
typedef struct _EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL {
    EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER           GetDriver;
    EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER_PATH      GetDriverPath;
    EFI_PLATFORM_DRIVER_OVERRIDE_DRIVER_LOADED        DriverLoaded;
} EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL;
```

Parameters

GetDriver	Retrieves the image handle of a platform override driver for a controller in the system. See the GetDriver() function description.
GetDriverPath	Retrieves the device path of a platform override driver for a controller in the system. See the GetDriverPath() function description.
DriverLoaded	This function is used after a driver has been loaded using a device path returned by GetDriverPath() . This function associates a device path to an image handle, so the image handle can be returned the next time that GetDriver() is called for the same controller. See the DriverLoaded() function description.

Description

The [EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL](#) is used by the EFI boot service [ConnectController\(\)](#) to determine if there is a platform specific driver override for a controller that is about to be started. The bus drivers in a platform will use a bus defined matching algorithm for matching drivers to controllers. This protocol allows the platform to override the bus driver's default driver matching algorithm. This protocol can be used to specify the drivers for on-board devices whose drivers may be in a system ROM not directly associated with the on-board controller, or it can even be used to manage the matching of drivers and controllers in add-in cards. This can be very useful if there are two adapters that are identical except for the revision of the driver

in the adapter's ROM. This protocol, along with a platform configuration utility, could specify which of the two drivers to use for each of the adapters.

The drivers that this protocol returns can be either in the form of an image handle or a device path. [ConnectController\(\)](#) can only use image handles, so **ConnectController()** is required to use the [GetDriver\(\)](#) service. A different component, such as the Boot Manager, will have to use the [GetDriverPath\(\)](#) service to retrieve the list of drivers that need to be loaded from I/O devices. Once a driver has been loaded and started, this same component can use the [DriverLoaded\(\)](#) service to associate the device path of a driver with the image handle of the loaded driver. Once this association has been established, the image handle can then be returned by the **GetDriver()** service the next time it is called by **ConnectController()**.

EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriver()

Summary

Retrieves the image handle of the platform override driver for a controller in the system.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER) (
    IN      EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL  *This,
    IN      EFI_HANDLE                             ControllerHandle,
    IN OUT  EFI_HANDLE                             *DriverImageHandle
);
```

Parameters

- This* A pointer to the [EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL](#) instance.
- ControllerHandle* The device handle of the controller to check if a driver override exists.
- DriverImageHandle* On input, a pointer to the previous driver image handle returned by **GetDriver()**. On output, a pointer to the next driver image handle. Passing in a **NULL**, will return the first driver image handle for **ControllerHandle**.

Description

This function is used to retrieve a driver image handle that is selected in a platform specific manner. The first driver image handle is retrieved by passing in a *DriverImageHandle* value of **NULL**. This will cause the first driver image handle to be returned in *DriverImageHandle*. On each successive call, the previous value of *DriverImageHandle* must be passed in. If a call to this function returns a valid driver image handle, then **EFI_SUCCESS** is returned. This process is repeated until **EFI_NOT_FOUND** is returned. If a *DriverImageHandle* is passed in that was not returned on a prior call to this function, then **EFI_INVALID_PARAMETER** is returned. If *ControllerHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. The first driver image handle has the highest precedence, and the last driver image handle has the lowest precedence. This ordered list of driver image handles is used by the boot service [ConnectController\(\)](#) to search for the best driver for a controller.

Status Codes Returned

EFI_SUCCESS	The driver override for <i>ControllerHandle</i> was returned in <i>DriverImageHandle</i> .
EFI_NOT_FOUND	A driver override for <i>ControllerHandle</i> was not found.
EFI_INVALID_PARAMETER	The handle specified by <i>ControllerHandle</i> is not a valid handle.

<p>EFI_INVALID_PARAMETER</p>	<p><i>DriverImageHandle</i> is not a handle that was returned on a previous call to GetDriver().</p>
------------------------------	---

EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriverPath()

Summary

Retrieves the device path of the platform override driver for a controller in the system.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER_PATH) (
    IN      EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL  *This,
    IN      EFI_HANDLE                             ControllerHandle,
    IN OUT  EFI_DEVICE_PATH_PROTOCOL              **DriverImagePath
);
```

Parameters

<i>This</i>	A pointer to the EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL instance.
<i>ControllerHandle</i>	The device handle of the controller to check if a driver override exists.
<i>DriverImagePath</i>	On input, a pointer to the previous driver device path returned by GetDriverPath() . On output, a pointer to the next driver device path. Passing in a pointer to NULL , will return the first driver device path for ControllerHandle .

Description

This function is used to retrieve a driver device path that is selected in a platform specific manner. The first driver device path is retrieved by passing in a *DriverImagePath* value that is a pointer to **NULL**. This will cause the first driver device path to be returned in *DriverImagePath*. On each successive call, the previous value of *DriverImagePath* must be passed in. If a call to this function returns a valid driver device path, then **EFI_SUCCESS** is returned. This process is repeated until **EFI_NOT_FOUND** is returned. If a *DriverImagePath* is passed in that was not returned on a prior call to this function, then **EFI_INVALID_PARAMETER** is returned. If *ControllerHandle* is not a valid **EFI_HANDLE**, then **EFI_INVALID_PARAMETER** is returned. The first driver device path has the highest precedence, and the last driver device path has the lowest precedence. This ordered list of driver device paths is used by a platform specific component, such as the EFI Boot Manager, to load and start the platform override drivers by using the EFI boot services [LoadImage\(\)](#) and [StartImage\(\)](#). Each time one of these drivers is loaded and started, the [DriverLoaded\(\)](#) service is called.

Status Codes Returned

EFI_SUCCESS	The driver override for <i>ControllerHandle</i> was returned in <i>DriverImagePath</i> .
EFI_UNSUPPORTED	The operation is not supported.
EFI_NOT_FOUND	A driver override for <i>ControllerHandle</i> was not found.

EFI_INVALID_PARAMETER	The handle specified by <i>ControllerHandle</i> is not a valid handle.
EFI_INVALID_PARAMETER	<i>DriverImagePath</i> is not a device path that was returned on a previous call to GetDriverPath() .

EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.DriverLoaded()

Summary

Used to associate a driver image handle with a device path that was returned on a prior call to the [GetDriverPath\(\)](#) service. This driver image handle will then be available through the [GetDriver\(\)](#) service.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_DRIVER_OVERRIDE_DRIVER_LOADED) (
    IN EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN EFI_DEVICE_PATH_PROTOCOL *DriverImagePath,
    IN EFI_HANDLE DriverImageHandle
);
```

Parameters

<i>This</i>	A pointer to the EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL instance.
<i>ControllerHandle</i>	The device handle of a controller. This must match the controller handle that was used in a prior call to GetDriver() to retrieve DriverImagePath .
<i>DriverImagePath</i>	A pointer to the driver device path that was returned in a prior call to GetDriverPath() .
<i>DriverImageHandle</i>	The driver image handle that was returned by LoadImage() when the driver specified by DriverImagePath was loaded into memory.

Description

This function associates the image handle specified by [DriverImageHandle](#) with the device path of a driver specified by [DriverImagePath](#). [DriverImagePath](#) must be a value that was returned on a prior call to [GetDriverPath\(\)](#) for the controller specified by [ControllerHandle](#). Once this association has been established, then the service [GetDriver\(\)](#) must return [DriverImageHandle](#) as one of the override drivers for the controller specified by [ControllerHandle](#).

If the association between the image handle specified by [DriverImageHandle](#) and the device path specified by [DriverImagePath](#) is established for the controller specified by [ControllerHandle](#), then [EFI_SUCCESS](#) is returned. If [ControllerHandle](#) is not a valid [EFI_HANDLE](#), or [DriverImagePath](#) is not a valid device path, or [DriverImageHandle](#) is not a valid [EFI_HANDLE](#), then [EFI_INVALID_PARAMETER](#) is returned. If [DriverImagePath](#) is not a device path that was returned on a prior call to [GetDriverPath\(\)](#) for the controller specified by [ControllerHandle](#), then [EFI_NOT_FOUND](#) is returned.

Status Codes Returned

EFI_SUCCESS	The association between <i>DriverImagePath</i> and <i>DriverImageHandle</i> was established for the controller specified by <i>ControllerHandle</i> .
EFI_UNSUPPORTED	The operation is not supported.
EFI_NOT_FOUND	<i>DriverImagePath</i> is not a device path that was returned on a prior call to GetDriverPath() for the controller specified by <i>ControllerHandle</i> .
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid device handle.
EFI_INVALID_PARAMETER	<i>DriverImagePath</i> is not a valid device path.
EFI_INVALID_PARAMETER	<i>DriverImageHandle</i> is not a valid image handle.

10.3 EFI Bus Specific Driver Override Protocol

This section provides a detailed description of the **EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL**. Bus drivers that have a bus specific algorithm for matching drivers to controllers are required to produce this protocol for each controller. For example, a PCI Bus Driver will produce an instance of this protocol for every PCI controller that has a PCI option ROM that contains one or more UEFI drivers. The protocol instance is attached to the handle of the PCI controller.

EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL

Summary

This protocol matches one or more drivers to a controller. This protocol is produced by a bus driver, and it is installed on the child handles of buses that require a bus specific algorithm for matching drivers to controllers. This protocol is used by the [ConnectController\(\)](#) boot service to select the best driver for a controller. All of the drivers returned by this protocol have a higher precedence than drivers found in the general EFI Driver Binding search algorithm, but a lower precedence than those drivers returned by the EFI Platform Driver Override Protocol. If more than one driver image handle is returned by this protocol, then the drivers image handles are returned in order from highest precedence to lowest precedence.

GUID

```
#define EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL_GUID \
    {0x3bc1b285, 0x8a15, 0x4a82, 0xaa, 0xbf, 0x4d, 0x7d, 0x13, 0xfb,
     0x32, 0x65}
```

Protocol Interface Structure

```
typedef struct _EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL {
    EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_GET_DRIVER GetDriver;
} EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL;
```

Parameters

GetDriver Uses a bus specific algorithm to retrieve a driver image handle for a controller. See the [GetDriver\(\)](#) function description.

Description

The `EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL` provides a mechanism for bus drivers to override the default driver selection performed by the `ConnectController()` boot service. This protocol is attached to the handle of a child device after the child handle is created by the bus driver. The service in this protocol can return a bus specific override driver to `ConnectController()`. `ConnectController()` must call this service until all of the bus specific override drivers have been retrieved. `ConnectController()` uses this information along with the EFI Platform Driver Override Protocol and all of the EFI Driver Binding protocol instances to select the best drivers for a controller. Since a controller can be managed by more than one driver, this protocol can return more than one bus specific override driver.

EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL.GetDriver()

Summary

Uses a bus specific algorithm to retrieve a driver image handle for a controller.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_GET_DRIVER) (
    IN      EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL *This,
    IN OUT EFI_HANDLE                                *DriverImageHandle
);
```

Parameters

<i>This</i>	A pointer to the EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL instance.
<i>DriverImageHandle</i>	On input, a pointer to the previous driver image handle returned by GetDriver() . On output, a pointer to the next driver image handle. Passing in a NULL , will return the first driver image handle.

Description

This function is used to retrieve a driver image handle that is selected in a bus specific manner. The first driver image handle is retrieved by passing in a *DriverImageHandle* value of **NULL**. This will cause the first driver image handle to be returned in *DriverImageHandle*. On each successive call, the previous value of *DriverImageHandle* must be passed in. If a call to this function returns a valid driver image handle, then **EFI_SUCCESS** is returned. This process is repeated until **EFI_NOT_FOUND** is returned. If a *DriverImageHandle* is passed in that was not returned on a prior call to this function, then **EFI_INVALID_PARAMETER** is returned. The first driver image handle has the highest precedence, and the last driver image handle has the lowest precedence. This ordered list of driver image handles is used by the boot service [ConnectController\(\)](#) to search for the best driver for a controller.

Status Codes Returned

EFI_SUCCESS	A bus specific override driver is returned in <i>DriverImageHandle</i> .
EFI_NOT_FOUND	The end of the list of override drivers was reached. A bus specific override driver is not returned in <i>DriverImageHandle</i> .
EFI_INVALID_PARAMETER	<i>DriverImageHandle</i> is not a handle that was returned on a previous call to GetDriver() .

10.4 EFI Driver Diagnostics Protocol

This section provides a detailed description of the **EFI_DRIVER_DIAGNOSTICS_PROTOCOL**. This is a protocol that allows a UEFI driver to perform diagnostics on a controller that the driver is managing.

EFI_DRIVER_DIAGNOSTICS_PROTOCOL

Summary

Used to perform diagnostics on a controller that a UEFI driver is managing.

GUID

```
#define EFI_DRIVER_DIAGNOSTICS_PROTOCOL_GUID \
    {0x4d330321, 0x025f, 0x4aac, 0x90, 0xd8, 0x5e, 0xd9, 0x00, 0x17, \
     0x3b, 0x63}
```

Protocol Interface Structure

```
typedef struct _EFI_DRIVER_DIAGNOSTICS_PROTOCOL {
    EFI_DRIVER_DIAGNOSTICS_RUN_DIAGNOSTICS RunDiagnostics;
    CHAR8 *SupportedLanguages;
} EFI_DRIVER_DIAGNOSTICS_PROTOCOL;
```

Parameters

RunDiagnostics Runs diagnostics on a controller. See the [RunDiagnostics\(\)](#) function description.

SupportedLanguages A Null-terminated ASCII string that contains one or more supported language codes. This is the list of language codes that this protocol supports. The number of languages supported by a driver is up to the driver writer. *SupportedLanguages* is specified in RFC 3066 format. See [Appendix M](#) for the format of language codes and language code arrays.

Description

The **EFI_DRIVER_DIAGNOSTICS_PROTOCOL** is used by a platform management utility to allow the user to run driver specific diagnostics on a controller. This protocol is optionally attached to the image handle of driver in the driver's entry point. The platform management utility can collect

all the **EFI_DRIVER_DIAGNOSTICS_PROTOCOL** instances present in the system, and present the user with a menu of the controllers that have diagnostic capabilities. This platform management utility is invoked through a platform component such as the EFI Boot Manager.

EFI_DRIVER_DIAGNOSTICS_PROTOCOL.RunDiagnostics()

Summary

Runs diagnostics on a controller.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_DRIVER_DIAGNOSTICS_RUN_DIAGNOSTICS) (
    IN  EFI_DRIVER_DIAGNOSTICS_PROTOCOL  *This,
    IN  EFI_HANDLE                       ControllerHandle,
    IN  EFI_HANDLE                       ChildHandle  OPTIONAL,
    IN  EFI_DRIVER_DIAGNOSTIC_TYPE       DiagnosticType,
    IN  CHAR8                             *Language,
    OUT EFI_GUID                          **ErrorType,
    OUT UINTN                             *BufferSize,
    OUT CHAR16                            **Buffer
);

```

Parameters

<i>This</i>	A pointer to the EFI DRIVER DIAGNOSTICS PROTOCOL instance.
<i>ControllerHandle</i>	The handle of the controller to run diagnostics on.
<i>ChildHandle</i>	The handle of the child controller to run diagnostics on. This is an optional parameter that may be NULL . It will be NULL for device drivers. It will also be NULL for a bus drivers that attempt to run diagnostics on the bus controller. It will not be NULL for a bus driver that attempts to run diagnostics on one of its child controllers.
<i>DiagnosticType</i>	Indicates type of diagnostics to perform on the controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> . See “Related Definitions” for the list of supported types.
<i>Language</i>	A pointer to a Null-terminated ASCII string array indicating the language. This is the language in which the optional error message should be returned in <i>Buffer</i> , and it must match one of the languages specified in SupportedLanguages. The number of languages supported by a driver is up to the driver writer. <i>Language</i> is specified in RFC 3066 language code format. See Appendix M for the format of language codes.
<i>ErrorType</i>	A GUID that defines the format of the data returned in <i>Buffer</i> .
<i>BufferSize</i>	The size, in bytes, of the data returned in <i>Buffer</i> .
<i>Buffer</i>	A buffer that contains a Null-terminated Unicode string plus some additional data whose format is defined by <i>ErrorType</i> . <i>Buffer</i> is allocated by this function with AllocatePool() , and it is the caller’s responsibility to free it with a call to FreePool() .

Description

This function runs diagnostics on the controller specified by *ControllerHandle* and *ChildHandle*. *DiagnosticType* specifies the type of diagnostics to perform on the controller specified by *ControllerHandle* and *ChildHandle*. If the driver specified by *This* does not support the language specified by *Language*, then **EFI_UNSUPPORTED** is returned. If the controller specified by *ControllerHandle* and *ChildHandle* is not supported by the driver specified by *This*, then **EFI_UNSUPPORTED** is returned. If the diagnostics type specified by *DiagnosticType* is not supported by this driver, then **EFI_UNSUPPORTED** is returned. If there are not enough resources available to complete the diagnostic, then **EFI_OUT_OF_RESOURCES** is returned. If the controller specified by *ControllerHandle* and *ChildHandle* passes the diagnostic, then **EFI_SUCCESS** is returned. Otherwise, **EFI_DEVICE_ERROR** is returned.

If the language specified by *Language* is supported by this driver, then status information is returned in *ErrorType*, *BufferSize*, and *Buffer*. *Buffer* contains a Null-terminated Unicode string followed by additional data whose format is defined by *ErrorType*. *BufferSize* is the size of *Buffer* is bytes, and it is the caller's responsibility to call **FreePool()** on *Buffer* when the caller is done with the return data. If there are not enough resources available to return the status information, then **EFI_OUT_OF_RESOURCES** is returned.

Related Definitions

```

//*****
// EFI_DRIVER_DIAGNOSTIC_TYPE
//*****
typedef enum {
    EfiDriverDiagnosticTypeStandard           = 0,
    EfiDriverDiagnosticTypeExtended          = 1,
    EfiDriverDiagnosticTypeManufacturing     = 2,
    EfiDriverDiagnosticTypeMaximum
} EFI_DRIVER_DIAGNOSTIC_TYPE;

```

EfiDriverDiagnosticTypeStandard

Performs standard diagnostics on the controller. This diagnostic type is required to be supported by all implementations of this protocol.

EfiDriverDiagnosticTypeExtended

This is an optional diagnostic type that performs diagnostics on the controller that may take an extended amount of time to execute.

EfiDriverDiagnosticTypeManufacturing

This is an optional diagnostic type that performs diagnostics on the controller that are suitable for a manufacturing and test environment.

Status Codes Returned

EFI_SUCCESS	The controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> passed the diagnostic.
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	The driver specified by <i>This</i> is not a device driver, and <i>ChildHandle</i> is not NULL , and <i>ChildHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Language</i> is NULL .
EFI_INVALID_PARAMETER	<i>ErrorType</i> is NULL .
EFI_INVALID_PARAMETER	<i>BufferSize</i> is NULL .
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_UNSUPPORTED	The driver specified by <i>This</i> does not support running diagnostics for the controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> .
EFI_UNSUPPORTED	The driver specified by <i>This</i> does not support the type of diagnostic specified by <i>DiagnosticType</i> .
EFI_UNSUPPORTED	The driver specified by <i>This</i> does not support the language specified by <i>Language</i> .
EFI_OUT_OF_RESOURCES	There are not enough resources available to complete the diagnostics.
EFI_OUT_OF_RESOURCES	There are not enough resources available to return the status information in <i>ErrorType</i> , <i>BufferSize</i> , and <i>Buffer</i> .
EFI_DEVICE_ERROR	The controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> did not pass the diagnostic.

10.5 EFI Component Name Protocol

This section provides a detailed description of the **EFI_COMPONENT_NAME2_PROTOCOL**. This is a protocol that allows an driver to provide a user readable name of a UEFI Driver, and a user readable name for each of the controllers that the driver is managing. This protocol is used by platform management utilities that wish to display names of components. These names may include the names of expansion slots, external connectors, embedded devices, and add-in devices.

EFI_COMPONENT_NAME2_PROTOCOL

Summary

Used to retrieve user readable names of drivers and controllers managed by UEFI Drivers.

GUID

```
#define EFI_COMPONENT_NAME2_PROTOCOL_GUID \
    {0x6a7a5cff, 0xe8d9, 0x4f70, 0xba, 0xda, 0x75, 0xab, 0x30, \
     0x25, 0xce, 0x14}
```

Protocol Interface Structure

```
typedef struct _EFI_COMPONENT_NAME2_PROTOCOL {
    EFI_COMPONENT_NAME_GET_DRIVER_NAME      GetDriverName;
    EFI_COMPONENT_NAME_GET_CONTROLLER_NAME  GetControllerName;
    CHAR8                                     *SupportedLanguages;
} EFI_COMPONENT_NAME2_PROTOCOL;
```

Parameters

<i>GetDriverName</i>	Retrieves a Unicode string that is the user readable name of the driver. See the GetDriverName () function description.
<i>GetControllerName</i>	Retrieves a Unicode string that is the user readable name of a controller that is being managed by a driver. See the GetControllerName () function description.
<i>SupportedLanguages</i>	A Null-terminated ASCII string array that contains one or more supported language codes. This is the list of language codes that this protocol supports. The number of languages supported by a driver is up to the driver writer. <i>SupportedLanguages</i> is specified in RFC 3066 format. See Appendix M for the format of language codes and language code arrays.

Description

The **EFI_COMPONENT_NAME2_PROTOCOL** is used retrieve a driver's user readable name and the names of all the controllers that a driver is managing from the driver's point of view. Each of these names is returned as a Null-terminated Unicode string. The caller is required to specify the language in which the Unicode string is returned, and this language must be present in the list of languages that this protocol supports specified by *SupportedLanguages*.

EFI_COMPONENT_NAME2_PROTOCOL.GetDriverName()

Summary

Retrieves a Unicode string that is the user readable name of the driver.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_COMPONENT_NAME_GET_DRIVER_NAME) (
    IN  EFI_COMPONENT_NAME2_PROTOCOL *This,
    IN  CHAR8                        *Language,
    OUT CHAR16                       **DriverName
);
```

Parameters

- This* A pointer to the [EFI_COMPONENT_NAME2_PROTOCOL](#) instance.
- Language* A pointer to a Null-terminated ASCII string array indicating the language. This is the language of the driver name that the caller is requesting, and it must match one of the languages specified in SupportedLanguages. The number of languages supported by a driver is up to the driver writer. *Language* is specified in RFC 3066 language code format. See [Appendix M](#) for the format of language codes.
- DriverName* A pointer to the Unicode string to return. This Unicode string is the name of the driver specified by *This* in the language specified by *Language*.

Description

This function retrieves the user readable name of a driver in the form of a Unicode string. If the driver specified by *This* has a user readable name in the language specified by *Language*, then a pointer to the driver name is returned in *DriverName*, and **EFI_SUCCESS** is returned. If the driver specified by *This* does not support the language specified by *Language*, then **EFI_UNSUPPORTED** is returned.

Status Codes Returned

EFI_SUCCESS	The Unicode string for the user readable name in the language specified by <i>Language</i> for the driver specified by <i>This</i> was returned in <i>DriverName</i> .
EFI_INVALID_PARAMETER	<i>Language</i> is NULL .
EFI_INVALID_PARAMETER	<i>DriverName</i> is NULL .
EFI_UNSUPPORTED	The driver specified by <i>This</i> does not support the language specified by <i>Language</i> .

EFI_COMPONENT_NAME2_PROTOCOL.GetControllerName()

Summary

Retrieves a Unicode string that is the user readable name of the controller that is being managed by a driver.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_COMPONENT_NAME_GET_CONTROLLER_NAME) (
    IN  EFI_COMPONENT_NAME2_PROTOCOL  *This,
    IN  EFI_HANDLE                    ControllerHandle,
    IN  EFI_HANDLE                    ChildHandle          OPTIONAL,
    IN  CHAR8                          *Language,
    OUT CHAR16                         **ControllerName
);
```

Parameters

<i>This</i>	A pointer to the EFI_COMPONENT_NAME2_PROTOCOL instance.
<i>ControllerHandle</i>	The handle of a controller that the driver specified by <i>This</i> is managing. This handle specifies the controller whose name is to be returned.
<i>ChildHandle</i>	The handle of the child controller to retrieve the name of. This is an optional parameter that may be NULL . It will be NULL for device drivers. It will also be NULL for bus drivers that attempt to retrieve the name of the bus controller. It will not be NULL for a bus driver that attempts to retrieve the name of a child controller.
<i>Language</i>	A pointer to a Null-terminated ASCII string array indicating the language. This is the language of the controller name that the caller is requesting, and it must match one of the languages specified in SupportedLanguages. The number of languages supported by a driver is up to the driver writer. <i>Language</i> is specified in RFC 3066 language code format. See Appendix M for the format of language codes.
<i>ControllerName</i>	A pointer to the Unicode string to return. This Unicode string is the name of the controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> in the language specified by <i>Language</i> from the point of view of the driver specified by <i>This</i> .

Description

This function retrieves the user readable name of the controller specified by *ControllerHandle* and *ChildHandle* in the form of a Unicode string. If the driver specified by *This* has a user readable name in the language specified by *Language*, then a pointer to the controller name is returned in *ControllerName*, and **EFI_SUCCESS** is returned.

If the driver specified by *This* is not currently managing the controller specified by *ControllerHandle* and *ChildHandle*, then **EFI_UNSUPPORTED** is returned.

If the driver specified by *This* does not support the language specified by *Language*, then **EFI_UNSUPPORTED** is returned.

Status Codes Returned

EFI_SUCCESS	The Unicode string for the user readable name specified by <i>This</i> , <i>ControllerHandle</i> , <i>ChildHandle</i> , and <i>Language</i> was returned in <i>ControllerName</i> .
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	The driver specified by <i>This</i> is not a device driver, and <i>ChildHandle</i> is not NULL , and <i>ChildHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Language</i> is NULL .
EFI_INVALID_PARAMETER	<i>ControllerName</i> is NULL .
EFI_UNSUPPORTED	The driver specified by <i>This</i> is a device driver and <i>ChildHandle</i> is not NULL .
EFI_UNSUPPORTED	The driver specified by <i>This</i> is not currently managing the controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> .
EFI_UNSUPPORTED	The driver specified by <i>This</i> does not support the language specified by <i>Language</i> .

10.6 EFI Service Binding Protocol

This section provides a detailed description of the **EFI_SERVICE_BINDING_PROTOCOL**. This protocol may be produced only by drivers that follow the UEFI Driver Model. Use this protocol with the [EFI DRIVER BINDING PROTOCOL](#) to produce a set of protocols related to a device. The **EFI_DRIVER_BINDING_PROTOCOL** supports simple layering of protocols on a device, but it does not support more complex relationships such as trees or graphs. The **EFI_SERVICE_BINDING_PROTOCOL** provides a member function to create a child handle with a new protocol installed on it, and another member function to destroy a previously created child handle. These member functions apply equally to all drivers.

EFI_SERVICE_BINDING_PROTOCOL

Summary

Provides services that are required to create and destroy child handles that support a given set of protocols.

GUID

This protocol does not have its own GUID. Instead, drivers for other protocols will define a GUID that shares the same protocol interface as the **EFI_SERVICE_BINDING_PROTOCOL**. The protocols defined in this document that have this property include the following:

- **EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL**
- **EFI_ARP_SERVICE_BINDING_PROTOCOL**
- **EFI_EAP_SERVICE_BINDING_PROTOCOL**
- **EFI_IP4_SERVICE_BINDING_PROTOCOL**
- **EFI_TCP4_SERVICE_BINDING_PROTOCOL**
- **EFI_UDP4_SERVICE_BINDING_PROTOCOL**
- **EFI_MTFTP4_SERVICE_BINDING_PROTOCOL**
- **EFI_DHCP4_SERVICE_BINDING_PROTOCOL**

Protocol Interface Structure

```
typedef struct _EFI_SERVICE_BINDING_PROTOCOL {
    EFI_SERVICE_BINDING_CREATE_CHILD    CreateChild;
    EFI_SERVICE_BINDING_DESTROY_CHILD  DestroyChild;
} EFI_SERVICE_BINDING_PROTOCOL;
```

Parameters

<i>CreateChild</i>	Creates a child handle and installs a protocol. See the CreateChild() function description.
<i>DestroyChild</i>	Destroys a child handle with a protocol installed on it. See the DestroyChild() function description.

Description

The **EFI_SERVICE_BINDING_PROTOCOL** provides member functions to create and destroy child handles. A driver is responsible for adding protocols to the child handle in **CreateChild()** and removing protocols in **DestroyChild()**. It is also required that the **CreateChild()** function opens the parent protocol BY_CHILD_CONTROLLER to establish the parent-child relationship, and closes the protocol in **DestroyChild()**. The pseudo code for **CreateChild()** and **DestroyChild()** is provided to specify the required behavior, not to specify the required implementation. Each consumer of a software protocol is responsible for calling **CreateChild()** when it requires the protocol and calling **DestroyChild()** when it is finished with that protocol.

EFI_SERVICE_BINDING_PROTOCOL.CreateChild()

Summary

Creates a child handle and installs a protocol.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERVICE_BINDING_CREATE_CHILD) (
    IN EFI_SERVICE_BINDING_PROTOCOL      *This,
    IN OUT EFI_HANDLE                    *ChildHandle
);
```

Parameters

<i>This</i>	Pointer to the EFI_SERVICE_BINDING_PROTOCOL instance.
<i>ChildHandle</i>	Pointer to the handle of the child to create. If it is a pointer to NULL , then a new handle is created. If it is a pointer to an existing UEFI handle, then the protocol is added to the existing UEFI handle.

Description

The **CreateChild()** function installs a protocol on *ChildHandle*. If *ChildHandle* is a pointer to **NULL**, then a new handle is created and returned in *ChildHandle*. If *ChildHandle* is not a pointer to **NULL**, then the protocol installs on the existing *ChildHandle*.

Status Codes Returned

EFI_SUCCESS	The protocol was added to <i>ChildHandle</i> .
EFI_INVALID_PARAMETER	<i>ChildHandle</i> is NULL .
EFI_OUT_OF_RESOURCES	There are not enough resources available to create the child.
Other	The child handle was not created.

Examples

The following example shows how a consumer of the EFI ARP Protocol would use the **CreateChild()** function of the **EFI_SERVICE_BINDING_PROTOCOL** to create a child handle with the EFI ARP Protocol installed on that handle.

```

EFI_HANDLE          ControllerHandle;
EFI_HANDLE          DriverBindingHandle;
EFI_HANDLE          ChildHandle;
EFI_ ARP_SERVICE_BINDING_PROTOCOL  *ArpSb;
EFI_ ARP_PROTOCOL   *Arp;

//
// Get the ArpServiceBinding Protocol
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiArpServiceBindingProtocolGuid,
    (VOID **) &ArpSb,
    DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return Status;
}
//
// Initialize a ChildHandle
//
ChildHandle = NULL;
//
// Create a ChildHandle with the Arp Protocol
//
Status = ArpSb->CreateChild (ArpSb, &ChildHandle);
if (EFI_ERROR (Status)) {
    goto ErrorExit;
}

//
// Retrieve the Arp Protocol from ChildHandle
//
Status = gBS->OpenProtocol (
    ChildHandle,
    &gEfiArpProtocolGuid,
    (VOID **) &Arp,
    DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_BY_DRIVER
);
if (EFI_ERROR (Status)) {
    goto ErrorExit;
}

```

Pseudo Code

The following is the general algorithm for implementing the `CreateChild()` function:

1. Allocate and initialize any data structures that are required to produce the requested protocol on a child handle. If the allocation fails, then return `EFI_OUT_OF_RESOURCES`.
2. Install the requested protocol onto `ChildHandle`. If `ChildHandle` is a pointer to `NULL`, then the requested protocol installs onto a new handle.
3. Open the parent protocol `BY_CHILD_CONTROLLER` to establish the parent-child relationship. If the parent protocol cannot be opened, then destroy the `ChildHandle` created in step 2, free the data structures allocated in step 1, and return an error.
4. Increment the number of children created by `CreateChild()`.
5. Return `EFI_SUCCESS`.

Listed below is sample code of the `CreateChild()` function of the EFI ARP Protocol driver.

This driver looks up its private context data structure from the instance of the

`EFI_SERVICE_BINDING_PROTOCOL` produced on the handle for the network controller. After retrieving the private context data structure, the driver can use its contents to build the private context data structure for the child being created. The EFI ARP Protocol driver then installs the `EFI_ARP_PROTOCOL` onto `ChildHandle`.

```

EFI_STATUS
EFIAPI
ArpServiceBindingCreateChild (
    IN EFI_SERVICE_BINDING_PROTOCOL *This,
    IN EFI_HANDLE                   *ChildHandle
)
{
    EFI_STATUS      Status;
    ARP_PRIVATE_DATA *Private;
    ARP_PRIVATE_DATA *PrivateChild;

    //
    // Retrieve the Private Context Data Structure
    //
    Private = ARP_PRIVATE_DATA_FROM_SERVICE_BINDING_THIS (This);

    //
    // Create a new child
    //
    PrivateChild = EfiLibAllocatePool (sizeof (ARP_PRIVATE_DATA));
    if (PrivateChild == NULL) {
        return EFI_OUT_OF_RESOURCES;
    }
}

```

```

//
// Copy Private Context Data Structure
//
gBS->CopyMem (PrivateChild, Private, sizeof (ARP_PRIVATE_DATA));

//
// Install Arp onto ChildHandle
//
Status = gBS->InstallMultipleProtocolInterfaces (
    ChildHandle,
    &gEfiArpProtocolGuid, &PrivateChild->Arp,
    NULL
);
if (EFI_ERROR (Status)) {
    gBS->FreePool (PrivateChild);
    return Status;
}

Status = gBS->OpenProtocol (
    Private->ChildHandle,
    &gEfiManagedNetworkProtocolGuid,
    (VOID **)&PrivateChild->ManagedNetwork,
    gArpDriverBinding.DriverBindingHandle,
    *ChildHandle,
    EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER
);
if (EFI_ERROR (Status)) {
    ArpSB->DestroyChild (This, ChildHandle);
    return Status;
}

//
// Increase number of children created
//
Private->NumberCreated++;

return EFI_SUCCESS;
}

```

EFI_SERVICE_BINDING_PROTOCOL.DestroyChild()

Summary

Destroys a child handle with a protocol installed on it.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERVICE_BINDING_DESTROY_CHILD) (
    IN EFI_SERVICE_BINDING_PROTOCOL *This,
    IN EFI_HANDLE ChildHandle
);
```

Parameters

This Pointer to the **EFI_SERVICE_BINDING_PROTOCOL** instance.

ChildHandle Handle of the child to destroy.

Description

The **DestroyChild()** function does the opposite of **CreateChild()**. It removes a protocol that was installed by **CreateChild()** from *ChildHandle*. If the removed protocol is the last protocol on *ChildHandle*, then *ChildHandle* is destroyed.

Status Codes Returned

EFI_SUCCESS	The protocol was removed from <i>ChildHandle</i> .
EFI_UNSUPPORTED	<i>ChildHandle</i> does not support the protocol that is being removed.
EFI_INVALID_PARAMETER	<i>ChildHandle</i> is not a valid UEFI handle.
EFI_ACCESS_DENIED	The protocol could not be removed from the <i>ChildHandle</i> because its services are being used.
Other	The child handle was not destroyed.

Examples

The following example shows how a consumer of the EFI ARP Protocol would use the **DestroyChild()** function of the **EFI_SERVICE_BINDING_PROTOCOL** to destroy a child handle with the EFI ARP Protocol installed on that handle.

```
EFI_HANDLE ControllerHandle;
EFI_HANDLE DriverBindingHandle;
EFI_HANDLE ChildHandle;
EFI_arp_service_binding_protocol *Arp;
```



```

//
// Get the Arp Service Binding Protocol
//
Status = gBS->OpenProtocol (
    ControllerHandle,
    &gEfiArpServiceBindingProtocolGuid,
    (VOID **)&ArpSb,
    DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return Status;
}

//
// Destroy the ChildHandle with the Arp Protocol
//
Status = ArpSb->DestroyChild (ArpSb, ChildHandle);
if (EFI_ERROR (Status)) {
    return Status;
}

```

Pseudo Code

The following is the general algorithm for implementing the **DestroyChild()** function:

1. Retrieve the protocol from *ChildHandle*. If this retrieval fails, then return **EFI_SUCCESS** because the child has already been destroyed.
2. If this call is a recursive call to destroy the same child, then return **EFI_SUCCESS**.
3. Close the parent protocol with **CloseProtocol()**.
4. Set a flag to detect a recursive call to destroy the same child.
5. Remove the protocol from *ChildHandle*. If this removal fails, then reopen the parent protocol and clear the flag to detect a recursive call to destroy the same child.
6. Free any data structures that allocated in **CreateChild()**.
7. Decrement the number of children that created with **CreateChild()**.
8. Return **EFI_SUCCESS**.

Listed below is sample code of the **DestroyChild()** function of the EFI ARP Protocol driver. This driver looks up its private context data structure from the instance of the **EFI_SERVICE_BINDING_PROTOCOL** produced on the handle for the network controller. The driver attempts to retrieve the **EFI_arp_protocol** from *ChildHandle*. If that fails, then **EFI_SUCCESS** is returned. The **EFI_arp_protocol** is then used to retrieve the private context data structure for the child. The private context data stores the flag that detects if **DestroyChild()** is being called recursively. If a recursion is detected, then **EFI_SUCCESS** is returned. Otherwise, the **EFI_arp_protocol** is removed from *ChildHandle*, the number of children are decremented, and **EFI_SUCCESS** is returned.

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```
EFI_STATUS
EFIAPI
ArpServiceBindingDestroyChild (
    IN EFI_SERVICE_BINDING_PROTOCOL *This,
    IN EFI_HANDLE                    ChildHandle
)
{
    EFI_STATUS          Status;
    EFI_ARP_PROTOCOL    *Arp;
    ARP_PRIVATE_DATA    *Private;
    ARP_PRIVATE_DATA    *PrivateChild;

    //
    // Retrieve the Private Context Data Structure
    //
    Private = ARP_PRIVATE_DATA_FROM_SERVICE_BINDING_THIS (This);

    //
    // Retrieve Arp Protocol from ChildHandle
    //
    Status = gBS->OpenProtocol (
        ChildHandle,
        &gEfiArpProtocolGuid,
        (VOID **) &Arp,
        gArpDriverBinding.DriverBindingHandle,
        ChildHandle,
        EFI_OPEN_PROTOCOL_GET_PROTOCOL
    );
    if (EFI_ERROR (Status)) {
        return EFI_SUCCESS;
    }

    //
    // Retrieve Private Context Data Structure
    //
    PrivateChild = ARP_PRIVATE_DATA_FROM_ARP_THIS (Arp);
    if (PrivateChild->Destroy) {
        return EFI_SUCCESS;
    }
}
```

```

//
// Close the ManagedNetwork Protocol
//
gBS->CloseProtocol (
    Private->ChildHandle,
    &gEfiManagedNetworkProtocolGuid,
    gArpDriverBinding.DriverBindingHandle,
    ChildHandle
);

PrivateChild->Destroy = TRUE;

//
// Uninstall Arp from ChildHandle
//
Status = gBS->UninstallMultipleProtocolInterfaces (
    ChildHandle,
    &gEfiArpProtocolGuid, &PrivateChild->Arp,
    NULL
);
if (EFI_ERROR (Status)) {
    //
    // Uninstall failed, so reopen the parent Arp Protocol and
    // return an error
    //
    PrivateChild->Destroy = FALSE;
    gBS->OpenProtocol (
        Private->ChildHandle,
        &gEfiManagedNetworkProtocolGuid,
        (VOID **)&PrivateChild->ManagedNetwork,
        gArpDriverBinding.DriverBindingHandle,
        ChildHandle,
        EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER
    );
    return Status;
}

//
// Free Private Context Data Structure
//
gBS->FreePool (PrivateChild);

```

```

//
// Decrease number of children created
//
Private->NumberCreated--;

return EFI_SUCCESS;

```

10.7 EFI Platform to Driver Configuration Protocol

This section provides a detailed description of the **EFI_PLATFORM_TO_DRIVER_CONFIGURARION_PROTOCOL**. This is a protocol that is optionally produced by the platform and optionally consumed by a UEFI Driver in its **Start()** function. This protocol allows the driver to receive configuration information as part of being started.

The **EFI_DRIVER_CONFIGUARITON_PROTOCOL** also supports configuring a UEFI driver, but it requires the driver to be started prior to configuration. The **EFI_PLATFORM_TO_DRIVER_CONFIGUARION_PROTOCOL** enables a driver to be configured as part of its **Start()** process.

EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL

Summary

Used to retrieve configuration information for a device that a UEFI driver is about to start.

GUID

```

#define EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL_GUID \
    { 0x642cd590, 0x8059, 0x4c0a, { 0xa9, 0x58, 0xc5, 0xec, 0x7,
    0xd2, 0x3c, 0x4b } }

```

Protocol Interface Structure

```

typedef struct _EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL {
    EFI_PLATFORM_TO_DRIVER_CONFIGURATION_QUERY    Query;
    EFI_PLATFORM_TO_DRIVER_CONFIGURATION_RESPONSE Response;
} EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL;

```

Parameters

Query

Called by the UEFI Driver **Start()** function to get configuration information from the platform.

Response

Called by the UEFI Driver **Start()** function to let the platform know how UEFI driver processed the data return from *Query*.

Description

The **EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL** is used by the UEFI driver to query the platform for configuration information. The UEFI driver calls **Query()** multiple times to get configuration information from the platform. For every call to *Query()* there must be a

matching call to [Response\(\)](#) so the UEFI driver can inform the platform how it used the information passed in from *Query()*.

It's legal for a UEFI driver to use *Response()* to inform the platform it does not understand the data returned via *Query()* and thus no action was taken.

EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Query()

Summary

Allows the UEFI driver to query the platform for configuration information needed to complete the drivers `Start()` operation.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_TO_DRIVER_CONFIGURATION_QUERY) (
    IN  EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL *This,
    IN  EFI_HANDLE                                     ControllerHandle,
    IN  EFI_HANDLE                                     ChildHandle OPTIONAL,
    IN  OUT UINTN                                     *Instance,
    IN  OUT EFI_GUID                                  **ParameterTypeGuid,
    IN  OUT VOID                                       **ParameterBlock,
    IN  OUT UINTN                                     *ParameterBlockSize
);
```

Parameters

<i>This</i>	A pointer to the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL instance.
<i>ControllerHandle</i>	The handle the platform will return configuration information about.
<i>ChildHandle</i>	The handle of the child controller to return information on. This is an optional parameter that may be NULL . It will be NULL for device drivers, and for bus drivers that attempt to get options for the bus controller. It will not be NULL for a bus driver that attempts to get options for one of its child controllers.
<i>Instance</i>	Pointer to the Instance value. On output the instance associated with the parameter data return. On input zero means return the first query data or pass in a valid instance number returned from a previous call to <i>Query</i> .
<i>ParameterTypeGuid</i>	An EFI_GUID that defines the contents of <i>ParameterBlock</i> . UEFI drivers must use the <i>ParameterTypeGuid</i> to determine how to parser the <i>ParameterBlock</i> .
<i>ParameterBlock</i>	The platform returns a pointer to the <i>ParameterBlock</i> structure which contains details about the configuration parameters specific to the <i>ParameterTypeGuid</i> . This structure is defined based on the protocol and may be different for different protocols. UEFI driver decodes this structure and its contents based on <i>ProtocolGuid</i> . <i>ParameterBlock</i> is allocated by the platform and the platform is responsible for freeing the <i>ParameterBlock</i> after Response is called.

ParameterBlockSize The platform returns the size of the *ParameterBlock* in bytes.

Description

The UEFI driver must call *Query* early in the **Start()** function before any time consuming operations are performed. If *ChildHandle* is **NULL** the driver is requesting information from the platform about the *ControllerHandle* that is being started. Information returned from *Query* may lead to the drivers **Start()** function failing.

If the UEFI driver is a bus driver and producing a *ChildHandle* the driver must call *Query* after the child handle has been created and an **EFI_DEVICE_PATH_PROTOCOL** has been placed on that handle, but before any time consuming operation is performed. If information return by *Query* may lead the driver to decide to not create the *ChildHandle*. The driver must then cleanup and remove the *ChildHandle* from the system.

The UEFI driver repeatedly calls *Query*, processes the information returned by the platform, and calls *Response* passing in the arguments returned from *Query*. The Instance value passed into *Response* must be the same value returned from the corresponding call to *Query*. The UEFI driver must continuously call *Query* and *Response* until **EFI_NOT_FOUND** is returned by *Query*.

The only value of *Instance* that has meaning to the UEFI driver is zero. An *Instance* value of zero means return the first *ParameterBlock* in the set of unprocessed parameter blocks. If a *ParameterBlock* has been processed via a *Query* and corresponding *Response* call it must not be returned again via a *Query* call until the driver is restarted.

Status Codes Returned

EFI_SUCCESS	The platform return parameter information for <i>ControllerHandle</i> .
EFI_NOT_FOUND	No more unread <i>Instance</i> exists.
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Instance</i> is NULL .
EFI_DEVICE_ERROR	A device error occurred while attempting to return parameter block information for the controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> .
EFI_OUT_RESOURCES	There are not enough resources available to set the configuration options for the controller specified by <i>ControllerHandle</i> and <i>ChildHandle</i> .

EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Response()

Summary

Tell the platform what actions were taken by the driver after processing the data returned from *Query*.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_TO_DRIVER_CONFIGURATION_RESPONSE) (
    IN  EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL  *This,
    IN  EFI_HANDLE                                     ControllerHandle,
    IN  EFI_HANDLE                                     ChildHandle  OPTIONAL,
    IN  UINTN                                          *Instance,
    IN  EFI_GUID                                       *ParameterTypeGuid,
    IN  VOID                                           *ParameterBlock,
    IN  UINTN                                          ParameterBlockSize ,
    IN  EFI_PLATFORM_CONFIGURATION_ACTION
    ConfigurationAction
);
```

Parameters

<i>This</i>	A pointer to the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL instance.
<i>ControllerHandle</i>	The handle the driver is returning configuration information about.
<i>ChildHandle</i>	The handle of the child controller to return information on. This is an optional parameter that may be NULL . It will be NULL for device drivers, and for bus drivers that attempt to get options for the bus controller. It will not be NULL for a bus driver that attempts to get options for one of its child controllers.
<i>Instance</i>	Instance data returned from Query() .
<i>ParameterTypeGuid</i>	<i>ParameterTypeGuid</i> returned from <i>Query</i> .
<i>ParameterBlock</i>	<i>ParameterBlock</i> returned from <i>Query</i> .
<i>ParameterBlockSize</i>	The <i>ParameterBlock</i> size returned from <i>Query</i> .
<i>ConfigurationAction</i>	The driver tells the platform what action is required for <i>ParameterBlock</i> to take effect. See "Related Definitions" for a list of actions.

Description

The UEFI driver repeatedly calls *Query*, processes the information returned by the platform, and calls *Response* passing in the arguments returned from *Query*. The UEFI driver must continuously call *Query* until **EFI_NOT_FOUND** is returned. For every call to *Query* that returns

EFI_SUCCESS a corresponding call to *Response* is required passing in the same *ContollerHandle*, *ChildHandle*, *Instance*, *ParameterTypeGuid*, *ParameterBlock*, and *ParameterBlockSize*. The UEFI driver may update values in *ParameterBlock* based on rules defined by *ParameterTypeGuid*.

The platform is responsible for freeing *ParameterBlock* and the UEFI driver must not try to free it.

Related Definitions

```
typedef enum {
    EfiPlatformConfigurationActionNone           = 0,
    EfiPlatformConfigurationActionStopController = 1,
    EfiPlatformConfigurationActionRestartController = 2,
    EfiPlatformConfigurationActionRestartPlatform = 3,
    EfiPlatformConfigurationActionNvramFailed     = 4,
    EfiPlatformConfigurationActionMaximum
} EFI_PLATFORM_CONFIGURATION_ACTION;
```

EfiPlatformConfigurationActionNone

The controller specified by *ControllerHandle* is still in a usable state, it's configuration has been updated via parsing the *ParameterBlock*. If required by the parameter block and the module supports an NVRAM store the configuration information from *ParameterBlock* was successfully saved to the NVRAM. No actions are required before this controller can be used again with the updated configuration settings

EfiPlatformConfigurationStopController

The driver has detected that the controller specified by *ControllerHandle* is not in a usable state, and it needs to be stopped. The calling agent can use the [DisconnectController\(\)](#) service to perform this operation, and it should be performed as soon as possible.

EfiPlatformConfigurationRestartController

This controller specified by *ControllerHandle* needs to be stopped and restarted before it can be used again. The calling agent can use the [DisconnectController\(\)](#) and [ConnectController\(\)](#) services to perform this operation. The restart operation can be delayed until all of the configuration options have been set.

EfiPlatformConfigurationRestartPlatform

A configuration change has been made that requires the platform to be restarted before the controller specified by *ControllerHandle* can be used again. The calling agent can use the [ResetSystem\(\)](#) services to perform this operation. The restart operation can be delayed until all of the configuration options have been set.

EfiPlatformConfigurationActionNvramFailed

The controller specified by *ControllerHandle* is still in a usable

state; its configuration has been updated via parsing the *ParameterBlock*. The driver tried to update the driver's private NVRAM store with information from *ParameterBlock* and failed. No actions are required before this controller can be used again with the updated configuration settings, but these configuration settings are not guaranteed to persist after *ControllerHandle* is stopped.

Status Codes Returned

EFI_SUCCESS	The platform return parameter information for <i>ControllerHandle</i> .
EFI_NOT_FOUND	<i>Instance</i> was not found.
EFI_INVALID_PARAMETER	<i>ControllerHandle</i> is not a valid EFI_HANDLE .
EFI_INVALID_PARAMETER	<i>Instance</i> is zero.

10.7.0.1 DMTF SM CLP ParameterTypeGuid

The following parameter protocol *ParameterTypeGuid* provides the support for parameters communicated through the DMTF SM CLP Specification 1.0 Final Standard to be used to configure the UEFI driver.

In this section the producer of the **EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL** is platform firmware and the consumer is the UEFI driver.

Note: if future versions of the DMTF SM CLP Specification require changes to the parameter block definition, newer *ParameterTypeGuid* will be used.

GUID

```
#define EFI_PLATFORM_TO_DRIVER_CONFIGURATION_CLP_GUID \
    {0x345ecc0e, 0xcb6, 0x4b75, 0xbb, 0x57, 0x1b, 0x12, 0x9c, \
    0x47, 0x33, 0x3e}
```

Parameter Block

```
typedef {
    CHAR8      *CLPCommand;
    UINT32     CLPCommandLength;
    CHAR8      *CLPReturnString;
    UINT32     CLPReturnStringLength;
    UINT8      CLPCmdStatus;
    UINT8      CLPErrorValue;
    UINT16     CLPMsgCode;
} EFI_CONFIGURE_CLP_PARAMETER_BLK;
```

Structure Member Definitions

CLPCommand A pointer to the DMTF SM CLP command line null-terminated string that the driver is required to parse and process when this

function is called. See the DMTF SM CLP Specification 1.0 Final Standard for details on the format and syntax of the CLP command line string.

CLPCommand buffer is allocated by the producer of the **EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL**.

<i>CLPCommandLength</i>	The length of the CLP Command in bytes.
<i>CLPReturnString</i>	A pointer to the CLP return status string that the driver is required to provide to the calling agent. The calling agent may parse and/or pass this for processing and user feedback. The SM CLP Command Response string buffer is filled in by the UEFI driver in the “keyword=value” format described in the <i>SM CLP Specification</i> (see section 3.1.10, “Output Data”), unless otherwise requested via the SM CLP –output option in the Command Line string buffer. UEFI driver’s support for this default “keyword=value” output format is required if the UEFI driver supports this protocol, while support for other SM CLP output formats is optional (the UEFI Driver should return an EFI_UNSUPPORTED if the SM CLP –output option requested by the caller is not supported by the UEFI Driver). <i>CLPReturnString</i> buffer is allocated by the consumer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL and undefined prior to the call to <i>Response()</i> .
<i>CLPReturnStringLength</i>	The length of the CLP return status string in bytes.
<i>CLPReturnStatus</i>	SM CLP Command Status (see <i>DMTF SM CLP Specification 1.0</i> Final Standard - Table 4)
<i>CLPErrorValue</i>	SM CLP Processing Error Value (see <i>DMTF SM CLP Specification 1.0</i> Final Standard - Table 6). This field is filled in by the consumer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL and undefined prior to the call to Response() .
<i>CLPMessageCode</i>	Bit 15: OEM Message Code Flag 0 = Message Code is an SM CLP Probable Cause Value. (see SM CLP Specification Table 11) 1 = Message Code is OEM Specific Bits 14-0: Message Code This field is filled in by the consumer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL and undefined prior to the call to Response() .

10.8 EFI Driver Supported EFI Version Protocol

EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL

Summary

Provides information about the version of the EFI specification that a driver is following. This protocol is required for EFI drivers that are on PCI and other plug in cards.

GUID

```
#define EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL_GUID \
  { 0x5c198761, 0x16a8, 0x4e69,           \
    { 0x97, 0x2c, 0x89, 0xd6, 0x79, 0x54, 0xf8, 0x1d } }
```

Protocol Interface Structure

```
typedef struct _EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL {
  UINT32      Length;
  UINT32      FirmwareVersion;
} EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL;
```

Parameters

<i>Length</i>	The size, in bytes, of the entire structure. Future versions of this specification may grow the size of the structure.
<i>FirmwareVersion</i>	The version of the EFI specification that this driver conforms to. EFI_2_10_SYSTEM_TABLE_REVISION for this version of this specification.

Description

The **EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL** provides a mechanism for an EFI driver to publish the version of the EFI specification it conforms to. This protocol must be placed on the drivers image handle when the driver's entry point is called.

Protocols — Console Support

This section explores console support protocols, including Simple Text Input, Simple Text Output, Simple Pointer, Serial IO, and Graphics Output protocols.

11.1 Console I/O Protocol

This section defines the Console I/O protocol. This protocol is used to handle input and output of text-based information intended for the system user during the operation of code in the boot services environment. Also included here are the definitions of three console devices: one for input and one each for normal output and errors.

These interfaces are specified by function call definitions to allow maximum flexibility in implementation. For example, there is no requirement for compliant systems to have a keyboard or screen directly connected to the system. Implementations may choose to direct information passed using these interfaces in arbitrary ways provided that the semantics of the functions are preserved (in other words, provided that the information is passed to and from the system user).

11.1.1 Overview

The UEFI console is built out of the [EFI SIMPLE TEXT INPUT PROTOCOL](#) and the [EFI SIMPLE TEXT OUTPUT PROTOCOL](#). These two protocols implement a basic text-based console that allows platform firmware, applications written to this specification, and UEFI OS loaders to present information to and receive input from a system administrator. The UEFI console consists of 16-bit Unicode characters, a simple set of input control characters (Scan Codes), and a set of output-oriented programmatic interfaces that give functionality equivalent to an intelligent terminal. The console does not support pointing devices on input or bitmaps on output.

This specification requires that the [SIMPLE_TEXT_INPUT_PROTOCOL](#) support the same languages as the corresponding [SIMPLE_TEXT_OUTPUT_PROTOCOL](#). The [SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is recommended to support at least the printable Basic Latin Unicode character set to enable standard terminal emulation software to be used with an EFI console. The Basic Latin Unicode character set implements a superset of ASCII that has been extended to 16-bit characters. Any number of other Unicode character sets may be optionally supported.

11.1.2 ConsoleIn Definition

The [SIMPLE_TEXT_INPUT_PROTOCOL](#) defines an input stream that contains Unicode characters and required EFI scan codes. Only the control characters defined in [Table 78](#) have meaning in the Unicode input or output streams. The control characters are defined to be characters U+0000 through U+001F. The input stream does not support any software flow control.

Table 78. Supported Unicode Control Characters

Mnemonic	Unicode	Description
Null	U+0000	Null character ignored when received.
BS	U+0008	Backspace. Moves cursor left one column. If the cursor is at the left margin, no action is taken.
TAB	U+0x0009	Tab.
LF	U+000A	Linefeed. Moves cursor to the next line.
CR	U+000D	Carriage Return. Moves cursor to left margin of the current line.

The input stream supports Scan Codes in addition to Unicode characters. If the Scan Code is set to 0x00 then the Unicode character is valid and should be used. If the Scan Code is set to a non-0x00 value it represents a special key as defined by [Table 79](#).

Table 79. EFI Scan Codes for `EFI_SIMPLE_TEXT_INPUT_PROTOCOL`

EFI Scan Code	Description
0x00	Null scan code.
0x01	Move cursor up 1 row.
0x02	Move cursor down 1 row.
0x03	Move cursor right 1 column.
0x04	Move cursor left 1 column.
0x05	Home.
0x06	End.
0x07	Insert.
0x08	Delete.
0x09	Page Up.
0x0a	Page Down.
0x0b	Function 1.
0x0c	Function 2.
0x0d	Function 3.
0x0e	Function 4.
0x0f	Function 5.
0x10	Function 6.
0x11	Function 7.
0x12	Function 8.
0x13	Function 9.
0x14	Function 10.
0x17	Escape.

11.2 Simple Text Input Ex Protocol

The Simple Text Input Ex protocol defines an extension to the Simple Text Input protocol which enables various new capabilities describes in this section.

EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL

Summary

This protocol is used to obtain input from the *ConsoleIn* device. The EFI specification requires that the **EFI_SIMPLE_TEXT_INPUT_PROTOCOL** supports the same languages as the corresponding **EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL**.

GUID

```
#define EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL_GUID \
{0xdd9e7534, 0x7762, 0x4698, 0x8c, 0x14, 0xf5, 0x85, \
 0x17, 0xa6, 0x25, 0xaa}
```

Protocol Interface Structure

```
typedef struct _EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL{
    EFI_INPUT_RESET_EX                Reset;
    EFI_INPUT_READ_KEY_EX              ReadKeyStrokeEx;
    EFI_EVENT                           WaitForKeyEx;
    EFI_SET_STATE                       SetState;
    EFI_REGISTER_KEYSTROKE_NOTIFY      RegisterKeyNotify;
    EFI_UNREGISTER_KEYSTROKE_NOTIFY    UnregisterKeyNotify;
} EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL;
```

Parameters

<i>Reset</i>	Reset the <i>ConsoleIn</i> device. See Reset() .
<i>ReadKeyStrokeEx</i>	Returns the next input character. See <i>ReadKeyStrokeEx()</i> .
<i>WaitForKeyEx</i>	Event to use with <i>WaitForEvent()</i> to wait for a key to be available.
<i>SetState</i>	Set the EFI_KEY_TOGGLE_STATE state settings for the input device.
<i>RegisterKeyNotify</i>	Register a notification function to be called when a given key sequence is hit.
<i>UnregisterKeyNotify</i>	Removes a specific notification function..

Description

The **EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL** is used on the *ConsoleIn* device. It is an extension to the Simple Text Input protocol which allows a variety of extended shift state information to be returned.

EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.Reset()

Summary

Resets the input device hardware.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_INPUT_RESET_EX) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);
```

Parameters

This A pointer to the **EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX** instance. Type **EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX** is defined in this section.

ExtendedVerification Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

The **Reset()** function resets the input device hardware.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the *ExtendedVerification* flag is **TRUE** the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Status Codes Returned

EFI_SUCCESS	The device was reset.
EFI_DEVICE_ERROR	The device is not functioning correctly and could not be reset.

EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.ReadKeyStrokeEx()

Summary

Reads the next keystroke from the input device.

```

Prototype
typedef
EFI_STATUS
(EFIAPI *EFI_INPUT_READ_KEY_EX) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL    *This,
    OUT EFI_KEY_DATA                        *KeyData
);
    
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX instance. Type EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX is defined in this section.
<i>KeyData</i>	A pointer to a buffer that is filled in with the keystroke state data for the key that was pressed. Type EFI_KEY_DATA is defined in "Related Definitions" below.

Related Definitions

```

//*****
// EFI_KEY_DATA
//*****
typedef struct {
    EFI_INPUT_KEY        Key;
    EFI_KEY_STATE        KeyState;
} EFI_KEY_DATA
    
```

<i>Key</i>	The EFI scan code and Unicode value returned from the input device..
<i>KeyState</i>	The current state of various toggled attributes as well as input modifier values.

```

//*****
// EFI_KEY_STATE
//*****
//
// Any Shift or Toggle State that is valid should have
// high order bit set.
//
typedef struct EFI_KEY_STATE {
UINT32                KeyShiftState;
EFI_KEY_TOGGLE_STATE  KeyToggleState;
} EFI_KEY_STATE;

```

KeyShiftState Reflects the currently pressed shift modifiers for the input device. The returned value is valid only if the high order bit has been set.

KeyToggleState Reflects the current internal state of various toggled attributes. The returned value is valid only if the high order bit has been set.

```

#define SHIFT_STATE_VALID      0x80000000
#define RIGHT_SHIFT_PRESSED   0x00000001
#define LEFT_SHIFT_PRESSED    0x00000002
#define RIGHT_CONTROL_PRESSED 0x00000004
#define LEFT_CONTROL_PRESSED  0x00000008
#define RIGHT_ALT_PRESSED     0x00000010
#define LEFT_ALT_PRESSED      0x00000020
#define RIGHT_LOGO_PRESSED    0x00000040
#define LEFT_LOGO_PRESSED     0x00000080
#define MENU_KEY_PRESSED      0x00000100
#define SYS_REQ_PRESSED       0x00000200

//*****
// EFI_KEY_TOGGLE_STATE
//*****
typedef UINT8           EFI_KEY_TOGGLE_STATE;

#define TOGGLE_STATE_VALID    0x80
#define SCROLL_LOCK_ACTIVE    0x01
#define NUM_LOCK_ACTIVE       0x02
#define CAPS_LOCK_ACTIVE      0x04

```

Description

The **ReadKeyStrokeEx()** function reads the next keystroke from the input device. If there is no pending keystroke the function returns **EFI_NOT_READY**. If there is a pending keystroke, then *KeyData.Key.ScanCode* is the EFI scan code defined in [Table 79](#). The *KeyData.Key.UnicodeChar* is the actual printable character or is zero if the key does not represent a printable character (control key, function key, etc.). The *KeyData.KeyState* is the modifier shift state for the character reflected in *KeyData.Key.UnicodeChar* or

KeyData.Key.ScanCode. This function mirrors the behavior of **ReadKeyStrokeEx** (in the Simple Input Protocol in that a keystroke will only be returned when *KeyData.Key* has data within it.

When interpreting the data from this function, it should be noted that if a class of printable characters that are normally adjusted by shift modifiers (e.g. Shift Key + "f" key) would be presented solely as a *KeyData.Key.UnicodeChar* without the associated shift state. So in the previous example of a Shift Key + "f" key being pressed, the only pertinent data returned would be *KeyData.Key.UnicodeChar* with the value of "F". This of course would not typically be the case for non-printable characters such as the pressing of the Right Shift Key + F10 key since the corresponding returned data would be reflected both in the *KeyData.KeyState.KeyShiftState* and *KeyData.Key.ScanCode* values.

UEFI drivers which implement the **EFI_SIMPLE_TEXT_INPUT_EX** protocol are required to return *KeyData.Key* and *KeyData.KeyState* values. These drivers must always return the most current state of *KeyData.KeyState.KeyShiftState* and *KeyData.KeyState.KeyToggleState*. It should also be noted that certain input devices may not be able to produce shift or toggle state information, and in those cases the high order bit in the respective Toggle and Shift state fields should not be active.

Status Codes Returned

EFI_SUCCESS	The keystroke information was returned.
EFI_NOT_READY	There was no keystroke data available.
EFI_DEVICE_ERROR	The keystroke information was not returned due to hardware errors.

EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.SetState()

Summary

Set certain state for the input device.

Prototype

```
typedef
    EFI_STATUS
    (EFIAPI *EFI_SET_STATE) (
        IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL    *This,
        IN EFI_KEY_TOGGLE_STATE                 *KeyToggleState
    );
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX instance. Type EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX is defined in this section.
<i>KeyToggleState</i>	Pointer to the EFI_KEY_TOGGLE_STATE to set the state for the input device. Type EFI_KEY_TOGGLE_STATE is defined in in "Related Definitions" for EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.ReadKeyStrokeEx() , above.

The SetState() function allows the input device hardware to have state settings adjusted.

Status Codes Returned

EFI_SUCCESS	The device state was set appropriately.
EFI_DEVICE_ERROR	The device is not functioning correctly and could not have the setting adjusted.
EFI_UNSUPPORTED	The device does not support the ability to have its state set.

EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.RegisterKeyNotify()

Summary

Register a notification function for a particular keystroke for the input device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_REGISTER_KEYSTROKE_NOTIFY) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL    *This,
    IN EFI_KEY_DATA                          *KeyData,
    IN EFI_KEY_NOTIFY_FUNCTION              KeyNotificationFunction,
    OUT EFI_HANDLE                           *NotifyHandle
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX instance. Type EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX is defined in this section.
<i>KeyData</i>	A pointer to a buffer that is filled in with the keystroke information for the key that was pressed.
<i>KeyNotificationFunction</i>	Points to the function to be called when the key sequence is typed specified by KeyData. See EFI_KEY_NOTIFY_FUNCTION below.
<i>NotifyHandle</i>	Points to the unique handle assigned to the registered notification..

Description

The **RegisterKeystrokeNotify()** function registers a function which will be called when a specified keystroke will occur. The keystroke being specified can be for any combination of *KeyData.Key* and *KeyData.KeyState* information.

Related Definitions

```
/** *****  
// EFI_KEY_NOTIFY  
/** *****  
typedef  
EFI_STATUS  
(EFI_API *EFI_KEY_NOTIFY_FUNCTION) (  
    IN EFI_KEY_DATA                *KeyData  
);
```

Status Codes Returned

EFI_SUCCESS	The device state was set appropriately.
EFI_OUT_OF_RESOURCES	Unable to allocate necessary data structures.

EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.UnregisterKeyNotify()

Summary

Set certain state for the input device.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_UNREGISTER_KEYSTROKE_NOTIFY) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This,
    IN EFI_HANDLE NotificationHandle
);
```

Parameters

This A pointer to the **EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX** instance. Type **EFI_SIMPLE_TEXT_INPUT_PROTOCOL_EX** is defined in this section.

NotificationHandle The handle of the notification function being unregistered.

Description

The **UnregisterKeystrokeNotify()** function removes the notification which was previously registered.

Status Codes Returned

EFI_SUCCESS	The device state was set appropriately.
EFI_INVALID_PARAMETER	The NotificationHandle is invalid.

11.3 Simple Text Input Protocol

The Simple Text Input protocol defines the minimum input required to support the *ConsoleIn* device.

EFI_SIMPLE_TEXT_INPUT_PROTOCOL

Summary

This protocol is used to obtain input from the *ConsoleIn* device. The EFI specification requires that the **EFI_SIMPLE_TEXT_INPUT_PROTOCOL** supports the same languages as the corresponding [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#).

GUID

```
#define EFI_SIMPLE_TEXT_INPUT_PROTOCOL_GUID \
{0x387477c1,0x69c7,0x11d2,0x8e,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}
```

Protocol Interface Structure

```
typedef struct _EFI_SIMPLE_TEXT_INPUT_PROTOCOL {
    EFI_INPUT_RESET      Reset;
    EFI_INPUT_READ_KEY   ReadKeyStroke;
    EFI_EVENT            WaitForKey;
} EFI_SIMPLE_TEXT_INPUT_PROTOCOL;
```

Parameters

<i>Reset</i>	Reset the <i>ConsoleIn</i> device. See Reset() .
<i>ReadKeyStroke</i>	Returns the next input character. See ReadKeyStroke() .
<i>WaitForKey</i>	Event to use with WaitForEvent() to wait for a key to be available.

Description

The **EFI_SIMPLE_TEXT_INPUT_PROTOCOL** is used on the *ConsoleIn* device. It is the minimum required protocol for *ConsoleIn*.

EFI_SIMPLE_TEXT_INPUT_PROTOCOL.Reset()

Summary

Resets the input device hardware.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_INPUT_RESET) (
    IN EFI_SIMPLE_TEXT_INPUT_PROTOCOL    *This,
    IN BOOLEAN                          ExtendedVerification
);
```

Parameters

This A pointer to the [EFI_SIMPLE_TEXT_INPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_INPUT_PROTOCOL](#) is defined in [Section 11.3](#)

ExtendedVerification Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

The **Reset()** function resets the input device hardware.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the *ExtendedVerification* flag is **TRUE** the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Status Codes Returned

EFI_SUCCESS	The device was reset.
EFI_DEVICE_ERROR	The device is not functioning correctly and could not be reset.

EFI_SIMPLE_TEXT_INPUT_PROTOCOL.ReadKeyStroke()

Summary

Reads the next keystroke from the input device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_INPUT_READ_KEY) (
    IN EFI_SIMPLE_TEXT_INPUT_PROTOCOL *This,
    OUT EFI_INPUT_KEY *Key
);
```

Parameters

- This* A pointer to the [EFI SIMPLE TEXT INPUT PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_INPUT_PROTOCOL](#) is defined in [Section 11.3](#).
- Key* A pointer to a buffer that is filled in with the keystroke information for the key that was pressed. Type [EFI_INPUT_KEY](#) is defined in “Related Definitions” below.

```
Related Definitions
//*****
// EFI_INPUT_KEY
//*****
typedef struct {
    UINT16 ScanCode;
    CHAR16 UnicodeChar;
} EFI_INPUT_KEY;
```

Description

The **ReadKeyStroke()** function reads the next keystroke from the input device. If there is no pending keystroke the function returns **EFI_NOT_READY**. If there is a pending keystroke, then *ScanCode* is the EFI scan code defined in [Table 79](#). The *UnicodeChar* is the actual printable character or is zero if the key does not represent a printable character (control key, function key, etc.).

Status Codes Returned

EFI_SUCCESS	The keystroke information was returned.
EFI_NOT_READY	There was no keystroke data available.
EFI_DEVICE_ERROR	The keystroke information was not returned due to hardware errors.

11.3.1 ConsoleOut or StandardError

The **EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL** must implement the same Unicode code pages as the **SIMPLE_TEXT_INPUT_PROTOCOL**. The protocol must also support the Unicode control

characters defined in [Table 78](#). The `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` supports special manipulation of the screen by programmatic methods and therefore does not support the EFI scan codes defined in [Table 79](#).

11.4 Simple Text Output Protocol

The Simple Text Output protocol defines the minimum requirements for a text-based *ConsoleOut* device. The EFI specification requires that the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL` support the same languages as the corresponding `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL`.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL

Summary

This protocol is used to control text-based output devices.

GUID

```
#define EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL_GUID \
{0x387477c2,0x69c7,0x11d2,0x8e,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}
```

Protocol Interface Structure

```
typedef struct _EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL {
    EFI_TEXT_RESET           Reset;
    EFI_TEXT_STRING         OutputString;
    EFI_TEXT_TEST_STRING    TestString;
    EFI_TEXT_QUERY_MODE     QueryMode;
    EFI_TEXT_SET_MODE       SetMode;
    EFI_TEXT_SET_ATTRIBUTE  SetAttribute;
    EFI_TEXT_CLEAR_SCREEN   ClearScreen;
    EFI_TEXT_SET_CURSOR_POSITION SetCursorPosition;
    EFI_TEXT_ENABLE_CURSOR  EnableCursor;
    SIMPLE_TEXT_OUTPUT_MODE *Mode;
} EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL;
```

Parameters

<i>Reset</i>	Reset the <i>ConsoleOut</i> device. See Reset() .
<i>OutputString</i>	Displays the Unicode string on the device at the current cursor location. See OutputString() .
<i>TestString</i>	Tests to see if the <i>ConsoleOut</i> device supports this Unicode string. See TestString() .
<i>QueryMode</i>	Queries information concerning the output device's supported text mode. See QueryMode() .
<i>SetMode</i>	Sets the current mode of the output device. See SetMode() .
<i>SetAttribute</i>	Sets the foreground and background color of the text that is output. See SetAttribute() .

<i>ClearScreen</i>	Clears the screen with the currently set background color. See ClearScreen() .
<i>SetCursorPosition</i>	Sets the current cursor position. See SetCursorPosition() .
<i>EnableCursor</i>	Turns the visibility of the cursor on/off. See EnableCursor() .
<i>Mode</i>	Pointer to SIMPLE_TEXT_OUTPUT_MODE data. Type SIMPLE_TEXT_OUTPUT_MODE is defined in “Related Definitions” below.

The following data values in the **SIMPLE_TEXT_OUTPUT_MODE** interface are read-only and are changed by using the appropriate interface functions:

<i>MaxMode</i>	The number of modes supported by QueryMode() and SetMode() .
<i>Mode</i>	The text mode of the output device(s).
<i>Attribute</i>	The current character output attribute.
<i>CursorColumn</i>	The cursor’s column.
<i>CursorRow</i>	The cursor’s row.
<i>CursorVisible</i>	The cursor is currently visible or not.

Related Definitions

```

//*****
// SIMPLE_TEXT_OUTPUT_MODE
//*****
typedef struct {
    INT32                MaxMode;
    // current settings
    INT32                Mode;
    INT32                Attribute;
    INT32                CursorColumn;
    INT32                CursorRow;
    BOOLEAN              CursorVisible;
} SIMPLE_TEXT_OUTPUT_MODE;

```

Description

The **SIMPLE_TEXT_OUTPUT** protocol is used to control text-based output devices. It is the minimum required protocol for any handle supplied as the *ConsoleOut* or *StandardError* device. In addition, the minimum supported text mode of such devices is at least 80 x 25 characters. A video device that only supports graphics mode is required to emulate text mode functionality. Output strings themselves are not allowed to contain any control codes other than those defined in [Table 78](#). Positional cursor placement is done only via the [SetCursorPosition\(\)](#) function. It is highly recommended that text output to the *StandardError* device be limited to sequential

string outputs. (That is, it is not recommended to use [ClearScreen\(\)](#) or [SetCursorPosition\(\)](#) on output messages to *StandardError*.)

If the output device is not in a valid text mode at the time of the [HandleProtocol\(\)](#) call, the device is to indicate that its *CurrentMode* is -1. On connecting to the output device the caller is required to verify the mode of the output device, and if it is not acceptable to set it to something it can use.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.Reset()

Summary

Resets the text output device hardware.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_RESET) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

ExtendedVerification Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

The **Reset()** function resets the text output device hardware. The cursor position is set to (0, 0), and the screen is cleared to the default background color for the output device.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the *ExtendedVerification* flag is **TRUE** the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Status Codes Returned

EFI_SUCCESS	The text output device was reset.
EFI_DEVICE_ERROR	The text output device is not functioning correctly and could not be reset.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.OutputString()

Summary

Writes a Unicode string to the output device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_STRING) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN CHAR16                          *String
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

String

The Null-terminated Unicode string to be displayed on the output device(s). All output devices must also support the Unicode drawing characters defined in “Related Definitions.”

Related Definitions

```

//*****
// UNICODE DRAWING CHARACTERS
//*****

#define BOXDRAW_HORIZONTAL          0x2500
#define BOXDRAW_VERTICAL           0x2502
#define BOXDRAW_DOWN_RIGHT        0x250c
#define BOXDRAW_DOWN_LEFT         0x2510
#define BOXDRAW_UP_RIGHT          0x2514
#define BOXDRAW_UP_LEFT           0x2518
#define BOXDRAW_VERTICAL_RIGHT     0x251c
#define BOXDRAW_VERTICAL_LEFT     0x2524
#define BOXDRAW_DOWN_HORIZONTAL   0x252c
#define BOXDRAW_UP_HORIZONTAL     0x2534
#define BOXDRAW_VERTICAL_HORIZONTAL 0x253c

#define BOXDRAW_DOUBLE_HORIZONTAL  0x2550
#define BOXDRAW_DOUBLE_VERTICAL    0x2551
#define BOXDRAW_DOWN_RIGHT_DOUBLE  0x2552
#define BOXDRAW_DOWN_DOUBLE_RIGHT  0x2553
#define BOXDRAW_DOUBLE_DOWN_RIGHT  0x2554

```

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```
#define BOXDRAW_DOWN_LEFT_DOUBLE          0x2555
#define BOXDRAW_DOWN_DOUBLE_LEFT         0x2556
#define BOXDRAW_DOUBLE_DOWN_LEFT        0x2557

#define BOXDRAW_UP_RIGHT_DOUBLE          0x2558
#define BOXDRAW_UP_DOUBLE_RIGHT         0x2559
#define BOXDRAW_DOUBLE_UP_RIGHT        0x255a

#define BOXDRAW_UP_LEFT_DOUBLE          0x255b
#define BOXDRAW_UP_DOUBLE_LEFT         0x255c
#define BOXDRAW_DOUBLE_UP_LEFT        0x255d

#define BOXDRAW_VERTICAL_RIGHT_DOUBLE   0x255e
#define BOXDRAW_VERTICAL_DOUBLE_RIGHT  0x255f
#define BOXDRAW_DOUBLE_VERTICAL_RIGHT  0x2560

#define BOXDRAW_VERTICAL_LEFT_DOUBLE    0x2561
#define BOXDRAW_VERTICAL_DOUBLE_LEFT    0x2562
#define BOXDRAW_DOUBLE_VERTICAL_LEFT    0x2563

#define BOXDRAW_DOWN_HORIZONTAL_DOUBLE  0x2564
#define BOXDRAW_DOWN_DOUBLE_HORIZONTAL  0x2565
#define BOXDRAW_DOUBLE_DOWN_HORIZONTAL  0x2566

#define BOXDRAW_UP_HORIZONTAL_DOUBLE    0x2567
#define BOXDRAW_UP_DOUBLE_HORIZONTAL    0x2568
#define BOXDRAW_DOUBLE_UP_HORIZONTAL    0x2569

#define BOXDRAW_VERTICAL_HORIZONTAL_DOUBLE 0x256a
#define BOXDRAW_VERTICAL_DOUBLE_HORIZONTAL 0x256b
#define BOXDRAW_DOUBLE_VERTICAL_HORIZONTAL 0x256c

//*****
// EFI Required Block Elements Code Chart
//*****

#define BLOCKELEMENT_FULL_BLOCK          0x2588
#define BLOCKELEMENT_LIGHT_SHADE        0x2591

//*****
// EFI Required Geometric Shapes Code Chart
//*****
```



```
#define GEOMETRICSHAPE_UP_TRIANGLE          0x25b2
#define GEOMETRICSHAPE_RIGHT_TRIANGLE      0x25ba
#define GEOMETRICSHAPE_DOWN_TRIANGLE       0x25bc
#define GEOMETRICSHAPE_LEFT_TRIANGLE       0x25c4

//*****
// EFI Required Arrow shapes
//*****

#define ARROW_UP                            0x2191
#define ARROW_DOWN                          0x2193
```

Description

The [OutputString\(\)](#) function writes a Unicode string to the output device. This is the most basic output mechanism on an output device. The *String* is displayed at the current cursor location on the output device(s) and the cursor is advanced according to the rules listed in [Table 80](#).

Table 80. EFI Cursor Location/Advance Rules

Mnemonic	Unicode	Description
Null	U+0000	Ignore the character, and do not move the cursor.
BS	U+0008	If the cursor is not at the left edge of the display, then move the cursor left one column.
LF	U+000A	If the cursor is at the bottom of the display, then scroll the display one row, and do not update the cursor position. Otherwise, move the cursor down one row.
CR	U+000D	Move the cursor to the beginning of the current row.
Other	U+XXXX	Print the character at the current cursor position and move the cursor right one column. If this moves the cursor past the right edge of the display, then the line should wrap to the beginning of the next line. This is equivalent to inserting a CR and an LF. Note that if the cursor is at the bottom of the display, and the line wraps, then the display will be scrolled one line.

Note: *If desired, the system's NVRAM environment variables may be used at install time to determine the configured locale of the system or the installation procedure can query the user for the proper language support. This is then used to either install the proper EFI image/loader or to configure the installed image's strings to use the proper text for the selected locale.*

Status Codes Returned

EFI_SUCCESS	The string was output to the device.
EFI_DEVICE_ERROR	The device reported an error while attempting to output the text.
EFI_UNSUPPORTED	The output device's mode is not currently in a defined text mode.
EFI_WARN_UNKNOWN_GLYPH	This warning code indicates that some of the characters in the Unicode string could not be rendered and were skipped.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.TestString()

Summary

Verifies that all characters in a Unicode string can be output to the target device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_TEST_STRING) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN CHAR16                          *String
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

String

The Null-terminated Unicode string to be examined for the output device(s).

Description

The **TestString()** function verifies that all characters in a Unicode string can be output to the target device.

This function provides a way to know if the desired character set is present for rendering on the output device(s). This allows the installation procedure (or EFI image) to at least select a letter set that the output devices are capable of displaying. Since the output device(s) may be changed between boots, if the loader cannot adapt to such changes it is recommended that the loader call [OutputString\(\)](#) with the text it has and ignore any “unsupported” error codes. The device(s) that are capable of displaying the Unicode letter set will do so.

Status Codes Returned

EFI_SUCCESS	The device(s) are capable of rendering the output string.
EFI_UNSUPPORTED	Some of the characters in the Unicode string cannot be rendered by one or more of the output devices mapped by the EFI handle.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.QueryMode()

Summary

Returns information for an available text mode that the output device(s) supports.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_TEXT_QUERY_MODE) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN UINTN ModeNumber,
    OUT UINTN *Columns,
    OUT UINTN *Rows
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” of Section 11.4 .
<i>ModeNumber</i>	The mode number to return information on.
<i>Columns, Rows</i>	Returns the geometry of the text output device for the request <i>ModeNumber</i> .

Description

The **QueryMode()** function returns information for an available text mode that the output device(s) supports.

It is required that all output devices support at least 80x25 text mode. This mode is defined to be mode 0. If the output devices support 80x50, that is defined to be mode 1. All other text dimensions supported by the device will follow as modes 2 and above. If an output device supports modes 2 and above, but does not support 80x50, then querying for mode 1 will return **EFI_UNSUPPORTED**.

Status Codes Returned

EFI_SUCCESS	The requested mode information was returned.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.
EFI_UNSUPPORTED	The mode number was not valid.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetMode()

Summary

Sets the output device(s) to a specified mode.

Prototype

```
typedef
EFI_STATUS
(* EFI_API EFI_TEXT_SET_MODE) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN UINTN ModeNumber
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type <code>EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL</code> is defined in the “Related Definitions” of Section 11.4 .
<i>ModeNumber</i>	The text mode to set.

Description

The `SetMode()` function sets the output device(s) to the requested mode. On success the device is in the geometry for the requested mode, and the device has been cleared to the current background color with the cursor at (0,0).

Status Codes Returned

EFI_SUCCESS	The requested text mode was set.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.
EFI_UNSUPPORTED	The mode number was not valid.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetAttribute()

Summary

Sets the background and foreground colors for the [OutputString\(\)](#) and [ClearScreen\(\)](#) functions.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_SET_ATTRIBUTE) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL  *This,
    IN UINTN                             Attribute
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

Attribute

The attribute to set. Bits 0..3 are the foreground color, and bits 4..6 are the background color. All other bits are reserved. See “Related Definitions” below.

Related Definitions

```

//*****
// Attributes
//*****
#define EFI_BLACK                0x00
#define EFI_BLUE                 0x01
#define EFI_GREEN                0x02
#define EFI_CYAN                 0x03
#define EFI_RED                  0x04
#define EFI_MAGENTA              0x05
#define EFI_BROWN                0x06
#define EFI_LIGHTGRAY            0x07
#define EFI_BRIGHT               0x08
#define EFI_DARKGRAY             0x08
#define EFI_LIGHTBLUE            0x09
#define EFI_LIGHTGREEN           0x0A
#define EFI_LIGHTCYAN            0x0B
#define EFI_LIGHTRED              0x0C
#define EFI_LIGHTMAGENTA         0x0D
#define EFI_YELLOW                0x0E
#define EFI_WHITE                 0x0F

```

```

#define EFI_BACKGROUND_BLACK      0x00
#define EFI_BACKGROUND_BLUE      0x10
#define EFI_BACKGROUND_GREEN     0x20
#define EFI_BACKGROUND_CYAN     0x30
#define EFI_BACKGROUND_RED       0x40
#define EFI_BACKGROUND_MAGENTA   0x50
#define EFI_BACKGROUND_BROWN    0x60
#define EFI_BACKGROUND_LIGHTGRAY 0x70

#define EFI_TEXT_ATTR(foreground,background) \
    ((foreground) | ((background) << 4))

```

Description

The **SetAttribute()** function sets the background and foreground colors for the [OutputString\(\)](#) and [ClearScreen\(\)](#) functions.

The color mask can be set even when the device is in an invalid text mode.

Devices supporting a different number of text colors are required to emulate the above colors to the best of the device's capabilities.

Status Codes Returned

EFI_SUCCESS	The requested attributes were set.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.ClearScreen()

Summary

Clears the output device(s) display to the currently selected background color.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_TEXT_CLEAR_SCREEN) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL    *This
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

Description

The **ClearScreen()** function clears the output device(s) display to the currently selected background color. The cursor position is set to (0, 0).

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.
EFI_UNSUPPORTED	The output device is not in a valid text mode.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetCursorPosition()

Summary

Sets the current coordinates of the cursor position.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_SET_CURSOR_POSITION) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN UINTN                            Column,
    IN UINTN                            Row
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

Column, Row

The position to set the cursor to. Must greater than or equal to zero and less than the number of columns and rows returned by [QueryMode \(\)](#).

Description

The [SetCursorPosition \(\)](#) function sets the current coordinates of the cursor position. The upper left corner of the screen is defined as coordinate (0, 0).

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.
EFI_UNSUPPORTED	The output device is not in a valid text mode, or the cursor position is invalid for the current mode.

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.EnableCursor()

Summary

Makes the cursor visible or invisible.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_TEXT_ENABLE_CURSOR) (
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN BOOLEAN Visible
);
```

Parameters

This

A pointer to the [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) instance. Type [EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL](#) is defined in the “Related Definitions” of [Section 11.4](#).

Visible

If **TRUE**, the cursor is set to be visible. If **FALSE**, the cursor is set to be invisible.

Description

The **EnableCursor()** function makes the cursor visible or invisible.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_DEVICE_ERROR	The device had an error and could not complete the request or the device does not support changing the cursor mode.
EFI_UNSUPPORTED	The output device does not support visibility control of the cursor.

11.5 Simple Pointer Protocol

This section defines the Simple Pointer Protocol and a detailed description of the [EFI_SIMPLE_POINTER_PROTOCOL](#). The intent of this section is to specify a simple method for accessing pointer devices. This would include devices such as mice and trackballs.

The [EFI_SIMPLE_POINTER_PROTOCOL](#) allows information about a pointer device to be retrieved. This would include the status of buttons and the motion of the pointer device since the last time it was accessed. This protocol is attached the device handle of a pointer device, and can be used for input from the user in the preboot environment.

EFI_SIMPLE_POINTER_PROTOCOL

Summary

Provides services that allow information about a pointer device to be retrieved.

GUID

```
#define EFI_SIMPLE_POINTER_PROTOCOL_GUID \
    {0x31878c87, 0xb75, 0x11d5, 0x9a, 0x4f, 0x0, 0x90, 0x27, 0x3f, 0xc1, \
    0x4d}
```

Protocol Interface Structure

```
typedef struct _EFI_SIMPLE_POINTER_PROTOCOL {
    EFI_SIMPLE_POINTER_RESET      Reset;
    EFI_SIMPLE_POINTER_GET_STATE  GetState;
    EFI_EVENT                     WaitForInput;
    EFI_SIMPLE_INPUT_MODE        *Mode;
} EFI_SIMPLE_POINTER_PROTOCOL;
```

Parameters

<i>Reset</i>	Resets the pointer device. See the Reset() function description.
<i>GetState</i>	Retrieves the current state of the pointer device. See the GetState() function description.
<i>WaitForInput</i>	Event to use with WaitForEvent() to wait for input from the pointer device.
<i>Mode</i>	Pointer to EFI_SIMPLE_POINTER_MODE data. The type EFI_SIMPLE_POINTER_MODE is defined in “Related Definitions” below.

Related Definitions

```
/**
 *
 */
// *****
// EFI_SIMPLE_POINTER_MODE
// *****
typedef struct {
    UINT64      ResolutionX;
    UINT64      ResolutionY;
    UINT64      ResolutionZ;
    BOOLEAN     LeftButton;
    BOOLEAN     RightButton;
} EFI_SIMPLE_POINTER_MODE;
```

The following data values in the [EFI_SIMPLE_POINTER_MODE](#) interface are read-only and are changed by using the appropriate interface functions:

<i>ResolutionX</i>	The resolution of the pointer device on the x-axis in counts/mm. If 0, then the pointer device does not support an x-axis.
<i>ResolutionY</i>	The resolution of the pointer device on the y-axis in counts/mm. If 0, then the pointer device does not support a y-axis.
<i>ResolutionZ</i>	The resolution of the pointer device on the z-axis in counts/mm. If 0, then the pointer device does not support a z-axis.

<i>LeftButton</i>	TRUE if a left button is present on the pointer device. Otherwise FALSE .
<i>RightButton</i>	TRUE if a right button is present on the pointer device. Otherwise FALSE .

Description

The **EFI_SIMPLE_POINTER_PROTOCOL** provides a set of services for a pointer device that can be used as an input device from an application written to this specification. The services include the ability to reset the pointer device, retrieve the state of the pointer device, and retrieve the capabilities of the pointer device.

EFI_SIMPLE_POINTER_PROTOCOL.Reset()

Summary

Resets the pointer device hardware.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_POINTER_RESET) (
    IN EFI_SIMPLE_POINTER_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);
```

Parameters

This A pointer to the **EFI_SIMPLE_POINTER_PROTOCOL** instance. Type **EFI_SIMPLE_POINTER_PROTOCOL** is defined in [Section 11.5](#).

ExtendedVerification Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

This **Reset()** function resets the pointer device hardware.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the *ExtendedVerification* flag is **TRUE** the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Status Codes Returned

EFI_SUCCESS	The device was reset.
EFI_DEVICE_ERROR	The device is not functioning correctly and could not be reset.

EFI_SIMPLE_POINTER_PROTOCOL.GetState()

Summary

Retrieves the current state of a pointer device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_POINTER_GET_STATE)
    IN EFI_SIMPLE_POINTER_PROTOCOL    *This,
    IN OUT EFI_SIMPLE_POINTER_STATE  *State
    );
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_POINTER_PROTOCOL instance. Type EFI_SIMPLE_POINTER_PROTOCOL is defined in Section 11.5 .
<i>State</i>	A pointer to the state information on the pointer device. Type EFI_SIMPLE_POINTER_STATE is defined in “Related Definitions” below.

Related Definitions

```

//*****
// EFI_SIMPLE_POINTER_STATE
//*****
typedef struct {
    INT32          RelativeMovementX;
    INT32          RelativeMovementY;
    INT32          RelativeMovementZ;
    BOOLEAN       LeftButton;
    BOOLEAN       RightButton;
} EFI_SIMPLE_POINTER_STATE;
```

RelativeMovementX The signed distance in counts that the pointer device has been moved along the x-axis. The actual distance moved is *RelativeMovementX/ResolutionX* millimeters. If the *ResolutionX* field of the [EFI_SIMPLE_POINTER_MODE](#) structure is 0, then this pointer device does not support an x-axis, and this field must be ignored.

RelativeMovementY The signed distance in counts that the pointer device has been moved along the y-axis. The actual distance moved is *RelativeMovementY/ResolutionY* millimeters. If the *ResolutionY* field of the [EFI_SIMPLE_POINTER_MODE](#) structure is 0, then this pointer device does not support a y-axis, and this field must be ignored.

- RelativeMovementZ* The signed distance in counts that the pointer device has been moved along the z-axis. The actual distance moved is *RelativeMovementZ / ResolutionZ* millimeters. If the *ResolutionZ* field of the **EFI_SIMPLE_POINTER_MODE** structure is 0, then this pointer device does not support a z-axis, and this field must be ignored.
- LeftButton* If **TRUE**, then the left button of the pointer device is being pressed. If **FALSE**, then the left button of the pointer device is not being pressed. If the *LeftButton* field of the **EFI_SIMPLE_POINTER_MODE** structure is **FALSE**, then this field is not valid, and must be ignored.
- RightButton* If **TRUE**, then the right button of the pointer device is being pressed. If **FALSE**, then the right button of the pointer device is not being pressed. If the *RightButton* field of the **EFI_SIMPLE_POINTER_MODE** structure is **FALSE**, then this field is not valid, and must be ignored.

Description

The **GetState()** function retrieves the current state of a pointer device. This includes information on the buttons associated with the pointer device and the distance that each of the axes associated with the pointer device has been moved. If the state of the pointer device has not changed since the last call to **GetState()**, then **EFI_NOT_READY** is returned. If the state of the pointer device has changed since the last call to **GetState()**, then the state information is placed in *State*, and **EFI_SUCCESS** is returned. If a device error occurs while attempting to retrieve the state information, then **EFI_DEVICE_ERROR** is returned.

Status Codes Returned

EFI_SUCCESS	The state of the pointer device was returned in <i>State</i> .
EFI_NOT_READY	The state of the pointer device has not changed since the last call to GetState() .
EFI_DEVICE_ERROR	A device error occurred while attempting to retrieve the pointer device's current state.

11.6 EFI Simple Pointer Device Paths

An **EFI_SIMPLE_POINTER_PROTOCOL** must be installed on a handle for its services to be available to drivers and applications written to this specification. In addition to the **EFI_SIMPLE_POINTER_PROTOCOL**, an **EFI_DEVICE_PATH_PROTOCOL** must also be installed on the same handle. See [Section 9.2](#) for a detailed description of the **EFI_DEVICE_PATH_PROTOCOL**.

A device path describes the location of a hardware component in a system from the processor's point of view. This includes the list of busses that lie between the processor and the pointer controller. The *UEFI Specification* takes advantage of the *ACPI Specification* to name system components. The following set of examples shows sample device paths for a PS/2* mouse, a serial mouse, and a USB mouse.

[Table 81](#) shows an example device path for a PS/2 mouse that is located behind a PCI to ISA bridge that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node for the PCI Root Bridge, a PCI Device Path Node for the PCI to ISA bridge, an ACPI Device Path Node for the PS/2 mouse, and a Device Path End Structure. The `_HID` and `_UID` of the first ACPI Device Path Node must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03, 0) / PCI (7, 0) / ACPI (PNP0F03, 0)

Table 81. PS/2 Mouse Device Path

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID</code> PNP0A03 – 0x41D0 represents a compressed string 'PNP' and is in the low order bytes.
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x00	PCI Function
0x11	0x01	0x07	PCI Device
0x12	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x13	0x01	0x01	Sub type – ACPI Device Path
0x14	0x02	0x0C	Length – 0x0C bytes
0x16	0x04	0x41D0, 0x0F03	<code>_HID</code> PNP0F03 – 0x41D0 represents a compressed string 'PNP' and is in the low order bytes.
0x1A	0x04	0x0000	<code>_UID</code>
0x1E	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x1F	0x01	0xFF	Sub type – End of Entire Device Path
0x20	0x02	0x04	Length – 0x04 bytes

[Table 82](#) shows an example device path for a serial mouse that is located on COM 1 behind a PCI to ISA bridge that is located at PCI device number 0x07 and PCI function 0x00. The PCI to ISA bridge is directly attached to a PCI root bridge, and the communications parameters for COM 1 are 1200 baud, no parity, 8 data bits, and 1 stop bit. This device path consists of an ACPI Device Path Node for the PCI Root Bridge, a PCI Device Path Node for the PCI to ISA bridge, an ACPI Device Path Node for COM 1, a UART Device Path Node for the communications parameters, an ACPI Device Path Node for the serial mouse, and a Device Path End Structure. The `_HID` and `_UID` of the first ACPI Device Path Node must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

**ACPI (PNP0A03, 0) / PCI (7, 0) / ACPI (PNP0501, 0) / UART (1200, N, 8, 1) /
ACPI (PNP0F01, 0)**

Table 82. Serial Mouse Device Path

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x00	PCI Function
0x11	0x01	0x07	PCI Device
0x12	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x13	0x01	0x01	Sub type – ACPI Device Path
0x14	0x02	0x0C	Length – 0x0C bytes
0x16	0x04	0x41D0, 0x0501	_HID PNP0501 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x1A	0x04	0x0000	_UID
0x1E	0x01	0x03	Generic Device Path Header – Messaging Device Path
0x1F	0x01	0x0E	Sub type – UART Device Path
0x20	0x02	0x13	Length – 0x13 bytes
0x22	0x04	0x00	Reserved
0x26	0x08	1200	Baud Rate
0x2E	0x01	0x08	Data Bits
0x2F	0x01	0x01	Parity
0x30	0x01	0x01	Stop Bits
0x31	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x32	0x01	0x01	Sub type – ACPI Device Path
0x33	0x02	0x0C	Length – 0x0C bytes
0x35	0x04	0x41D0, 0x0F01	_HID PNP0F01 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x39	0x04	0x0000	_UID
0x3D	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x3E	0x01	0xFF	Sub type – End of Entire Device Path
0x3F	0x02	0x04	Length – 0x04 bytes

[Table 83](#) shows an example device path for a USB mouse that is behind a PCI to USB host controller that is located at PCI device number 0x07 and PCI function 0x02. The PCI to USB host controller is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node for the PCI Root Bridge, a PCI Device Path Node for the PCI to USB controller, a USB Device Path Node, and a Device Path End Structure. The `_HID` and `_UID` of the first ACPI Device Path Node must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03 , 0) / PCI (7 , 2) / USB (0 , 0)

Table 83. USB Mouse Device Path

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID</code> PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x02	PCI Function
0x11	0x01	0x07	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Messaging Device Path
0x13	0x01	0x05	Sub type – USB
0x14	0x02	0x06	Length – 0x06 bytes
0x16	0x01	0x00	USB Port Number
0x17	0x01	0x00	USB Endpoint Number
0x18	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x19	0x01	0xFF	Sub type – End of Entire Device Path
0x1A	0x02	0x04	Length – 0x04 bytes

11.7 Absolute Pointer Protocol

This section defines the Absolute Pointer Protocol and a detailed description of the **EFI_ABSOLUTE_POINTER_PROTOCOL**. The intent of this section is to specify a simple method for accessing absolute pointer devices. This would include devices like touch screens, and digitizers. The **EFI_ABSOLUTE_POINTER_PROTOCOL** allows information about a pointer device to be retrieved. This would include the status of buttons and the coordinates of the pointer device on the last time it was activated. This protocol is attached to the device handle of an absolute pointer device, and can be used for input from the user in the preboot environment.

Supported devices may return 1, 2, or 3 axis of information. The Z axis may optionally be used to return pressure data measurements derived from user pen force.

All supported devices must support a touch-active status. Supported devices may optionally support a second input button, for example a pen side-button.

EFI_ABSOLUTE_POINTER_PROTOCOL

Summary

Provides services that allow information about a absolute pointer device to be retrieved.

GUID

```
#define EFI_ABSOLUTE_POINTER_PROTOCOL_GUID \
{0x8D59D32B, 0xC655, 0x4AE9, 0x9B, 0x15, 0xF2, 0x59, 0x04, 0x99, 0x2A,
0x43};
```

Protocol Interface Structure

```
typedef struct _EFI_ABSOLUTE_POINTER_PROTOCOL {
    EFI_ABSOLUTE_POINTER_RESET      Reset;
    EFI_ABSOLUTE_POINTER_GET_STATE  GetState;
    EFI_EVENT                        WaitForInput;
    EFI_ABSOLUTE_POINTER_MODE       *Mode;
} EFI_ABSOLUTE_POINTER_PROTOCOL;
```

Parameters

<i>Reset</i>	Resets the pointer device. See the Reset() function description.
<i>GetState</i>	Retrieves the current state of the pointer device. See the GetState() function description.
<i>WaitForInput</i>	Event to use with WaitForEvent() to wait for input from the pointer device.
<i>*Mode</i>	Pointer to EFI_ABSOLUTE_POINTER_MODE data. The type EFI_ABSOLUTE_POINTER_MODE is defined in "Related Definitions" below.

Related Definitions

```
/**
//*****
// EFI_ABSOLUTE_POINTER_MODE
//*****
typedef struct {
    UINT64 AbsoluteMinX;
    UINT64 AbsoluteMinY;
    UINT64 AbsoluteMinZ;
    UINT64 AbsoluteMaxX;
    UINT64 AbsoluteMaxY;
    UINT64 AbsoluteMaxZ;
}
```

```

    UINT32 Attributes;
} EFI_ABSOLUTE_POINTER_MODE;

```

The following data values in the **EFI_ABSOLUTE_POINTER_MODE** interface are read-only and are changed by using the appropriate interface functions:

<i>AbsoluteMinX</i>	The Absolute Minimum of the device on the x-axis
<i>AbsoluteMinY</i>	The Absolute Minimum of the device on the y -axis.
<i>AbsoluteMinZ</i>	The Absolute Minimum of the device on the z-axis.
<i>AbsoluteMaxX</i>	The Absolute Maximum of the device on the x-axis. If 0, and the AbsoluteMinX is 0, then the pointer device does not support a x-axis.
<i>AbsoluteMaxY</i>	The Absolute Maximum of the device on the y -axis. If 0,, and the AbsoluteMinX is 0, then the pointer device does not support a y-axis.
<i>AbsoluteMaxZ</i>	The Absolute Maximum of the device on the z-axis. If 0 , and the AbsoluteMinX is 0, then the pointer device does not support a z-axis.
<i>Attributes</i>	The following bits are set as needed (or'd together) to indicate the capabilities of the device supported. The remaining bits are undefined and should be returned as 0.

```

#define EFI_ABSP_SupportsAltActive      0x00000001
#define EFI_ABSP_SupportsPressureAsZ   0x00000002

```

EFI_ABSP_SupportsAltActive	If set, indicates this device supports an alternate button input.
EFI_ABSP_SupportsPressureAsZ	If set, indicates this device returns pressure data in parameter CurrentZ.

The driver is not permitted to return all zeros for all three pairs of Min and Max as this would indicate no axis supported.

Description

The **EFI_ABSOLUTE_POINTER_PROTOCOL** provides a set of services for a pointer device that can be used as an input device from an application written to this specification. The services include the ability to reset the pointer device, retrieve the state of the pointer device, and retrieve the capabilities of the pointer device. In addition certain data items describing the device are provided.

EFI_ABSOLUTE_POINTER_PROTOCOL.Reset()

Summary

Resets the pointer device hardware.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_ABSOLUTE_POINTER_RESET) (
    IN EFI_ABSOLUTE_POINTER_PROTOCOL  *This,
    IN BOOLEAN                        ExtendedVerification
);
```

Parameters

This A pointer to the **EFI_ABSOLUTE_POINTER_PROTOCOL** instance. Type **EFI_ABSOLUTE_POINTER_PROTOCOL** is defined in this section.

ExtendedVerification Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

This Reset() function resets the pointer device hardware. As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Codes Returned

EFI_SUCCESS	The device was reset.
EFI_DEVICE_ERROR	The device is not functioning correctly and could not be reset.

EFI_ABSOLUTE_POINTER_PROTOCOL.GetState()

Summary

Retrieves the current state of a pointer device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_ABSOLUTE_POINTER_GET_STATE)
IN EFI_ABSOLUTE_POINTER_PROTOCOL    *This,
IN OUT EFI_ABSOLUTE_POINTER_STATE  *State
);
```

Parameters

<i>This</i>	A pointer to the EFI_ABSOLUTE_POINTER_PROTOCOL instance. Type EFI_ABSOLUTE_POINTER_PROTOCOL is defined in Section 11.7 .
<i>State</i>	A pointer to the state information on the pointer device. Type EFI_ABSOLUTE_POINTER_STATE is defined in "Related Definitions" below.

Related Definitions

```

//*****
// EFI_ABSOLUTE_POINTER_STATE
//*****
typedef struct {
    UINT64 CurrentX;
    UINT64 CurrentY;
    UINT64 CurrentZ;
    UINT32 ActiveButtons;
} EFI_ABSOLUTE_POINTER_STATE;
```

<i>CurrentX</i>	The unsigned position of the activation on the x axis If the AbsoluteMinX and the AbsoluteMaxX fields of the EFI_ABSOLUTE_POINTER_MODE structure are both 0, then this pointer device does not support an x-axis, and this field must be ignored.
<i>CurrentY</i>	The unsigned position of the activation on the y axis If the AbsoluteMinY and the AbsoluteMaxY fields of the EFI_ABSOLUTE_POINTER_MODE structure are both 0, then this pointer device does not support an y-axis, and this field must be ignored.
<i>CurrentZ</i>	The unsigned position of the activation on the z axis, or the pressure measurement. If the AbsoluteMinZ and the AbsoluteMaxZ fields of the EFI_ABSOLUTE_POINTER_MODE structure are

both 0, then this pointer device does not support an z-axis, and this field must be ignored.

ActiveButtons

Bits are set to 1 in this structure item to indicate that device buttons are active.

Related Definitions

```
//*****
//definitions of bits within ActiveButtons
//*****
#define EFI_Absp_TouchActive    0x00000001
#define EFI_ABS_AltActive      0x00000002
```

EFI_Absp_TouchActive This bit is set if the touch sensor is active

EFI_ABS_AltActive This bit is set if the alt sensor, such as pen-side button, is active.

Description

The GetState() function retrieves the current state of a pointer device. This includes information on the active state associated with the pointer device and the current position of the axes associated with the pointer device. If the state of the pointer device has not changed since the last call to **GetState()**, then **EFI_NOT_READY** is returned. If the state of the pointer device has changed since the last call to **GetState()**, then the state information is placed in State, and **EFI_SUCCESS** is returned. If a device error occurs while attempting to retrieve the state information, then **EFI_DEVICE_ERROR** is returned.

Status Codes Returned

EFI_SUCCESS	The state of the pointer device was returned in <i>State</i> .
EFI_NOT_READY	The state of the pointer device has not changed since the last call to GetState() .
EFI_DEVICE_ERROR	A device error occurred while attempting to retrieve the pointer device's current state.

11.8 Serial I/O Protocol

This section defines the Serial I/O protocol. This protocol is used to abstract byte stream devices.

EFI_SERIAL_IO_PROTOCOL

Summary

This protocol is used to communicate with any type of character-based I/O device.

GUID

```
#define EFI_SERIAL_IO_PROTOCOL_GUID \
{0xBB25CF6F,0xF1D4,0x11D2,0x9A,0x0C,0x00,0x90,0x27,0x3F,0xC1,
0xFD}
```

Revision Number

```
#define EFI_SERIAL_IO_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```
typedef struct {
    UINT32                Revision;
    EFI_SERIAL_RESET      Reset;
    EFI_SERIAL_SET_ATTRIBUTES SetAttributes;
    EFI_SERIAL_SET_CONTROL_BITS SetControl;
    EFI_SERIAL_GET_CONTROL_BITS GetControl;
    EFI_SERIAL_WRITE      Write;
    EFI_SERIAL_READ       Read;
    SERIAL_IO_MODE        *Mode;
} EFI_SERIAL_IO_PROTOCOL;
```

Parameters

<i>Revision</i>	The revision to which the EFI_SERIAL_IO_PROTOCOL adheres. All future revisions must be backwards compatible. If a future version is not backwards compatible, it is not the same GUID.
<i>Reset</i>	Resets the hardware device.
<i>SetAttributes</i>	Sets communication parameters for a serial device. These include the baud rate, receive FIFO depth, transmit/receive time out, parity, data bits, and stop bit attributes.
<i>SetControl</i>	Sets the control bits on a serial device. These include Request to Send and Data Terminal Ready.
<i>GetControl</i>	Reads the status of the control bits on a serial device. These include Clear to Send, Data Set Ready, Ring Indicator, and Carrier Detect.
<i>Write</i>	Sends a buffer of characters to a serial device.
<i>Read</i>	Receives a buffer of characters from a serial device.
<i>Mode</i>	Pointer to SERIAL_IO_MODE data. Type SERIAL_IO_MODE is defined in “Related Definitions” below.

Related Definitions

```
/**
// SERIAL_IO_MODE
**/
```

```
typedef struct {
    UINT32          ControlMask;

    // current Attributes
    UINT32          Timeout;
    UINT64          BaudRate;
    UINT32          ReceiveFifoDepth;
    UINT32          DataBits;
    UINT32          Parity;
    UINT32          StopBits;
} SERIAL_IO_MODE;
```

The data values in the **SERIAL_IO_MODE** are read-only and are updated by the code that produces the **EFI_SERIAL_IO_PROTOCOL** functions:

<i>ControlMask</i>	A mask of the Control bits that the device supports. The device must always support the Input Buffer Empty control bit.
<i>Timeout</i>	If applicable, the number of microseconds to wait before timing out a Read or Write operation.
<i>BaudRate</i>	If applicable, the current baud rate setting of the device; otherwise, baud rate has the value of zero to indicate that device runs at the device's designed speed.
<i>ReceiveFifoDepth</i>	The number of characters the device will buffer on input.
<i>DataBits</i>	The number of data bits in each character.
<i>Parity</i>	If applicable, this is the EFI_PARITY_TYPE that is computed or checked as each character is transmitted or received. If the device does not support parity the value is the default parity value.
<i>StopBits</i>	If applicable, the EFI_STOP_BITS_TYPE number of stop bits per character. If the device does not support stop bits the value is the default stop bit value.

```

/*****
// EFI_PARITY_TYPE
*****/
typedef enum {
    DefaultParity,
    NoParity,
    EvenParity,
    OddParity,
    MarkParity,
    SpaceParity
} EFI_PARITY_TYPE;
```



```

//*****
// EFI_STOP_BITS_TYPE
//*****
typedef enum {
    DefaultStopBits,
    OneStopBit,      // 1 stop bit
    OneFiveStopBits, // 1.5 stop bits
    TwoStopBits      // 2 stop bits
} EFI_STOP_BITS_TYPE;

```

Description

The Serial I/O protocol is used to communicate with UART-style serial devices. These can be standard UART serial ports in PC-AT systems, serial ports attached to a USB interface, or potentially any character-based I/O device.

The Serial I/O protocol can control byte I/O style devices from a generic device, to a device with features such as a UART. As such many of the serial I/O features are optional to allow for the case of devices that do not have UART controls. Each of these options is called out in the specific serial I/O functions.

The default attributes for all UART-style serial device interfaces are: 115,200 baud, a 1 byte receive FIFO, a 1,000,000 microsecond timeout per character, no parity, 8 data bits, and 1 stop bit. Flow control is the responsibility of the software that uses the protocol. Hardware flow control can be implemented through the use of the [GetControl\(\)](#) and [SetControl\(\)](#) functions (described below) to monitor and assert the flow control signals. The XON/XOFF flow control algorithm can be implemented in software by inserting XON and XOFF characters into the serial data stream as required.

Special care must be taken if a significant amount of data is going to be read from a serial device. Since UEFI drivers are polled mode drivers, characters received on a serial device might be missed. It is the responsibility of the software that uses the protocol to check for new data often enough to guarantee that no characters will be missed. The required polling frequency depends on the baud rate of the connection and the depth of the receive FIFO.

EFI_SERIAL_IO_PROTOCOL.Reset()

Summary

Resets the serial device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERIAL_RESET) (
    IN EFI_SERIAL_IO_PROTOCOL *This
);
```

Parameters

This

A pointer to the `EFI_SERIAL_IO_PROTOCOL` instance.
Type `EFI_SERIAL_IO_PROTOCOL` is defined in [Section 11.8](#).

Description

The `Reset()` function resets the hardware of a serial device.

Status Codes Returned

EFI_SUCCESS	The serial device was reset.
EFI_DEVICE_ERROR	The serial device could not be reset.

EFI_SERIAL_IO_PROTOCOL.SetAttributes()

Summary

Sets the baud rate, receive FIFO depth, transmit/receive time out, parity, data bits, and stop bits on a serial device.

```

EFI_STATUS
(EFI_API *EFI_SERIAL_SET_ATTRIBUTES) (
    IN EFI_SERIAL_IO_PROTOCOL  *This,
    IN UINT64                   BaudRate,
    IN UINT32                   ReceiveFifoDepth,
    IN UINT32                   Timeout
    IN EFI_PARITY_TYPE          Parity,
    IN UINT8                    DataBits,
    IN EFI_STOP_BITS_TYPE       StopBits
);
    
```

Parameters

<i>This</i>	A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Section 11.8 .
<i>BaudRate</i>	The requested baud rate. A <i>BaudRate</i> value of 0 will use the device's default interface speed.
<i>ReceiveFifoDepth</i>	The requested depth of the FIFO on the receive side of the serial interface. A <i>ReceiveFifoDepth</i> value of 0 will use the device's default FIFO depth.
<i>Timeout</i>	The requested time out for a single character in microseconds. This timeout applies to both the transmit and receive side of the interface. A <i>Timeout</i> value of 0 will use the device's default time out value.
<i>Parity</i>	The type of parity to use on this serial device. A <i>Parity</i> value of DefaultParity will use the device's default parity value. Type EFI_PARITY_TYPE is defined in "Related Definitions" in Section 11.8 .
<i>DataBits</i>	The number of data bits to use on this serial device. A <i>DataBits</i> value of 0 will use the device's default data bit setting.
<i>StopBits</i>	The number of stop bits to use on this serial device. A <i>StopBits</i> value of DefaultStopBits will use the device's default number of stop bits. Type EFI_STOP_BITS_TYPE is defined in "Related Definitions" in Section 11.8 .

Description

The **SetAttributes()** function sets the baud rate, receive-FIFO depth, transmit/receive time out, parity, data bits, and stop bits on a serial device.

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The controller for a serial device is programmed with the specified attributes. If the *Parity*, *DataBits*, or *StopBits* values are not valid, then an error will be returned. If the specified *BaudRate* is below the minimum baud rate supported by the serial device, an error will be returned. The nearest baud rate supported by the serial device will be selected without exceeding the *BaudRate* parameter. If the specified *ReceiveFifoDepth* is below the smallest FIFO size supported by the serial device, an error will be returned. The nearest FIFO size supported by the serial device will be selected without exceeding the *ReceiveFifoDepth* parameter.

Status Codes Returned

EFI_SUCCESS	The new attributes were set on the serial device.
EFI_INVALID_PARAMETER	One or more of the attributes has an unsupported value.
EFI_DEVICE_ERROR	The serial device is not functioning correctly.

EFI_SERIAL_IO_PROTOCOL.SetControl()

Summary

Sets the control bits on a serial device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERIAL_SET_CONTROL_BITS) (
    IN EFI_SERIAL_IO_PROTOCOL  *This,
    IN UINT32                    Control
);
```

Parameters

<i>This</i>	A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Section 11.8 .
<i>Control</i>	Sets the bits of <i>Control</i> that are settable. See “Related Definitions” below.

Related Definitions

```

//*****
// CONTROL BITS
//*****

#define EFI_SERIAL_CLEAR_TO_SEND           0x0010
#define EFI_SERIAL_DATA_SET_READY         0x0020
#define EFI_SERIAL_RING_INDICATE         0x0040
#define EFI_SERIAL_CARRIER_DETECT       0x0080
#define EFI_SERIAL_REQUEST_TO_SEND       0x0002
#define EFI_SERIAL_DATA_TERMINAL_READY   0x0001
#define EFI_SERIAL_INPUT_BUFFER_EMPTY     0x0100
#define EFI_SERIAL_OUTPUT_BUFFER_EMPTY    0x0200
#define EFI_SERIAL_HARDWARE_LOOPBACK_ENABLE 0x1000
#define EFI_SERIAL_SOFTWARE_LOOPBACK_ENABLE 0x2000
#define EFI_SERIAL_HARDWARE_FLOW_CONTROL_ENABLE 0x4000

```

Description

The **SetControl()** function is used to assert or deassert the control signals on a serial device. The following signals are set according their bit settings:

- Request to Send
- Data Terminal Ready

Only the **REQUEST_TO_SEND**, **DATA_TERMINAL_READY**, **HARDWARE_LOOPBACK_ENABLE**, **SOFTWARE_LOOPBACK_ENABLE**, and **HARDWARE_FLOW_CONTROL_ENABLE** bits can be set with **SetControl ()** . All the bits can be read with [GetControl \(\)](#) .

Status Codes Returned

EFI_SUCCESS	The new control bits were set on the serial device.
EFI_UNSUPPORTED	The serial device does not support this operation.
EFI_DEVICE_ERROR	The serial device is not functioning correctly.

EFI_SERIAL_IO_PROTOCOL.GetControl()

Summary

Retrieves the status of the control bits on a serial device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERIAL_GET_CONTROL_BITS) (
    IN EFI_SERIAL_IO_PROTOCOL  *This,
    OUT UINT32                  *Control
);
```

Parameters

This A pointer to the **EFI_SERIAL_IO_PROTOCOL** instance. Type **EFI_SERIAL_IO_PROTOCOL** is defined in [Section 11.8](#).

Control A pointer to return the current control signals from the serial device. See “Related Definitions” below.

Related Definitions

```

//*****
// CONTROL BITS
//*****

#define EFI_SERIAL_CLEAR_TO_SEND           0x0010
#define EFI_SERIAL_DATA_SET_READY         0x0020
#define EFI_SERIAL_RING_INDICATE          0x0040
#define EFI_SERIAL_CARRIER_DETECT        0x0080
#define EFI_SERIAL_REQUEST_TO_SEND        0x0002
#define EFI_SERIAL_DATA_TERMINAL_READY    0x0001
#define EFI_SERIAL_INPUT_BUFFER_EMPTY     0x0100
#define EFI_SERIAL_OUTPUT_BUFFER_EMPTY    0x0200
#define EFI_SERIAL_HARDWARE_LOOPBACK_ENABLE 0x1000
#define EFI_SERIAL_SOFTWARE_LOOPBACK_ENABLE 0x2000
#define EFI_SERIAL_HARDWARE_FLOW_CONTROL_ENABLE 0x4000

```

Description

The **GetControl ()** function retrieves the status of the control bits on a serial device.

Status Codes Returned

EFI_SUCCESS	The control bits were read from the serial device.
EFI_DEVICE_ERROR	The serial device is not functioning correctly.

EFI_SERIAL_IO_PROTOCOL.Write()

Summary

Writes data to a serial device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERIAL_WRITE) (
    IN EFI_SERIAL_IO_PROTOCOL  *This,
    IN OUT UINTN                *BufferSize,
    IN VOID                    *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Section 11.8 .
<i>BufferSize</i>	On input, the size of the <i>Buffer</i> . On output, the amount of data actually written.
<i>Buffer</i>	The buffer of data to write.

Description

The **Write()** function writes the specified number of bytes to a serial device. If a time out error occurs while data is being sent to the serial port, transmission of this buffer will terminate, and **EFI_TIMEOUT** will be returned. In all cases the number of bytes actually written to the serial device is returned in *BufferSize*.

Status Codes Returned

EFI_SUCCESS	The data was written.
EFI_DEVICE_ERROR	The device reported an error.
EFI_TIMEOUT	The data write was stopped due to a timeout.

EFI_SERIAL_IO_PROTOCOL.Read()

Summary

Reads data from a serial device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SERIAL_READ) (
    IN EFI_SERIAL_IO_PROTOCOL *This,
    IN OUT UINTN               *BufferSize,
    OUT VOID                   *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Section 11.8 .
<i>BufferSize</i>	On input, the size of the <i>Buffer</i> . On output, the amount of data returned in <i>Buffer</i> .
<i>Buffer</i>	The buffer to return the data into.

Description

The **Read()** function reads a specified number of bytes from a serial device. If a time out error or an overrun error is detected while data is being read from the serial device, then no more characters will be read, and an error will be returned. In all cases the number of bytes actually read is returned in *BufferSize*.

Status Codes Returned

EFI_SUCCESS	The data was read.
EFI_DEVICE_ERROR	The serial device reported an error.
EFI_TIMEOUT	The operation was stopped due to a timeout or overrun.

11.9 Graphics Output Protocol

The goal of this section is to replace the functionality that currently exists with VGA hardware and its corresponding video BIOS. The Graphics Output Protocol is a software abstraction and its goal is to support any foreseeable graphics hardware and not require VGA hardware, while at the same time also lending itself to implementation on the current generation of VGA hardware.

Graphics output is important in the pre-boot space to support modern firmware features. These features include the display of logos, the localization of output to any language, and setup and configuration screens.

Graphics output may also be required as part of the startup of an operating system. There are potentially times in modern operating systems prior to the loading of a high performance OS

graphics driver where access to graphics output device is required. The Graphics Output Protocol supports this capability by providing the EFI OS loader access to a hardware frame buffer and enough information to allow the OS to draw directly to the graphics output device.

The [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) supports three member functions to support the limited graphics needs of the pre-boot environment. These member functions allow the caller to draw to a virtualized frame buffer, retrieve the supported video modes, and to set a video mode. These simple primitives are sufficient to support the general needs of pre-OS firmware code.

The [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) also exports enough information about the current mode for operating system startup software to access the linear frame buffer directly.

The interface structure for the Graphics Output protocol is defined in this section. A unique Graphics Output protocol must represent each video frame buffer in the system that is driven out to one or more video output devices.

11.9.1 Blt Buffer

The basic graphics operation in the [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) is the Block Transfer or Blt. The Blt operation allows data to be read or written to the video adapter's video memory. The Blt operation abstracts the video adapters hardware implementation by introducing the concept of a software Blt buffer.

The frame buffer abstracts the video display as an array of pixels. Each pixels location on the video display is defined by its X and Y coordinates. The X coordinate represents a scan line. A scan line is a horizontal line of pixels on the display. The Y coordinate represents a vertical line on the display. The upper left hand corner of the video display is defined as (0, 0) where the notation (X, Y) represents the X and Y coordinate of the pixel. The lower right corner of the video display is represented by (Width - 1, Height - 1).

The software Blt buffer is structured as an array of pixels. Pixel (0, 0) is the first element of the software Blt buffer. The Blt buffer can be thought of as a set of scan lines. It is possible to convert a pixel location on the video display to the Blt buffer using the following algorithm: Blt buffer array index = Y * Width + X.

Each software Blt buffer entry represents a pixel that is comprised of a 32-bit quantity. Byte zero of the Blt buffer entry represents the Red component of the pixel. Byte one of the Blt buffer entry represents the Green component of the pixel. Byte two of the Blt buffer entry represents the Blue component of the pixel. Byte three of the Blt buffer entry is reserved and must be zero. The byte values for the red, green, and blue components represent the color intensity. This color intensity value range from a minimum intensity of 0 to maximum intensity of 255.

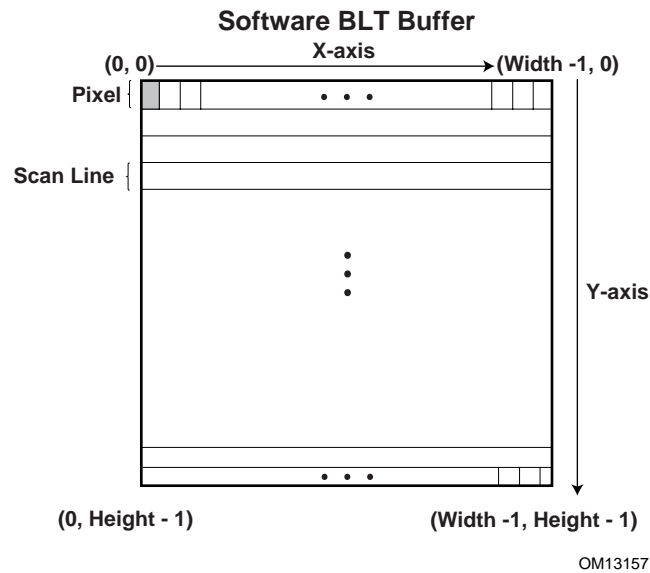


Figure 27. Software BLT Buffer

EFI_GRAPHICS_OUTPUT_PROTOCOL

Summary

Provides a basic abstraction to set video modes and copy pixels to and from the graphics controller's frame buffer. The linear address of the hardware frame buffer is also exposed so software can write directly to the video hardware.

GUID

```
#define EFI_GRAPHICS_OUTPUT_PROTOCOL_GUID \
    {0x9042a9de, 0x23dc, 0x4a38, 0x96, 0xfb, 0x7a, 0xde, 0xd0, 0x80, \
     0x51, 0x6a}
```

Protocol Interface Structure

```
typedef struct EFI_GRAPHICS_OUTPUT_PROTOCOL {
    EFI_GRAPHICS_OUTPUT_PROTOCOL_QUERY_MODE QueryMode;
    EFI_GRAPHICS_OUTPUT_PROTOCOL_SET_MODE SetMode;
    EFI_GRAPHICS_OUTPUT_PROTOCOL_BLT Blt;
    EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE *Mode;
} EFI_GRAPHICS_OUTPUT_PROTOCOL;
```

Parameters

QueryMode

Returns information for an available graphics mode that the graphics device and the set of active video output devices supports.

<i>SetMode</i>	Set the video device into the specified mode and clears the visible portions of the output display to black.
<i>Blt</i>	Software abstraction to draw on the video device's frame buffer.
<i>Mode</i>	Pointer to EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE data. Type EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE is defined in "Related Definitions" below.

Related Definitions

```
typedef struct {
    UINT32      RedMask;
    UINT32      GreenMask;
    UINT32      BlueMask;
    UINT32      ReservedMask;
} EFI_PIXEL_BITMASK;
```

If a bit is set in *RedMask*, *GreenMask*, or *BlueMask* then those bits of the pixel represent the corresponding color. Bits in *RedMask*, *GreenMask*, *BlueMask*, and *ReservedMask* must not overlap bit positions. The values for the red, green, and blue components in the bit mask represent the color intensity. The color intensities must increase as the color values for a each color mask increase with a minimum intensity of all bits in a color mask clear to a maximum intensity of all bits in a color mask set.

```
typedef enum {
    PixelRedGreenBlueReserved8BitPerColor,
    PixelBlueGreenRedReserved8BitPerColor,
    PixelBitMask,
    PixelBltOnly,
    PixelFormatMax
} EFI_GRAPHICS_PIXEL_FORMAT;
```

PixelRedGreenBlueReserved8BitPerColor

A pixel is 32-bits and byte zero represents red, byte one represents green, byte two represents blue, and byte three is reserved. This is the definition for the physical frame buffer. The byte values for the red, green, and blue components represent the color intensity. This color intensity value range from a minimum intensity of 0 to maximum intensity of 255.

PixelBlueGreenRedReserved8BitPerColor

A pixel is 32-bits and byte zero represents blue, byte one represents green, byte two represents red, and byte three is reserved. This is the definition for the physical frame buffer. The byte values for the red, green, and blue components represent the color intensity. This color intensity value range from a minimum intensity of 0 to maximum intensity of 255.

PixelBitMask

The pixel definition of the physical frame buffer is defined by **EFI_PIXEL_BITMASK**.

PixelBltOnly

This mode does not support a physical frame buffer.

PixelFormatMax Valid **EFI_GRAPHICS_PIXEL_FORMAT** enum values are less than this value.

```
typedef struct {
    UINT32          Version;
    UINT32          HorizontalResolution;
    UINT32          VerticalResolution;
    EFI_GRAPHICS_PIXEL_FORMAT PixelFormat;
    EFI_PIXEL_BITMASK PixelInformation;
    UINT32          PixelsPerScanLine;
} EFI_GRAPHICS_OUTPUT_MODE_INFORMATION;
```

Version The version of this data structure. A value of zero represents the **EFI_GRAPHICS_OUTPUT_MODE_INFORMATION** structure as defined in this specification. Future version of this specification may extend this data structure in a backwards compatible way and increase the value of *Version*.

HorizontalResolution The size of video screen in pixels in the X dimension.

VerticalResolution The size of video screen in pixels in the Y dimension.

PixelFormat Enumeration that defines the physical format of the pixel. A value of *PixelFormatOnly* implies that a linear frame buffer is not available for this mode.

PixelInformation This bit-mask is only valid if *PixelFormat* is set to *PixelFormatBitMask*. A bit being set defines what bits are used for what purpose such as Red, Green, Blue, or Reserved.

PixelsPerScanLine Defines the number of pixel elements per scan line. Not all pixel elements may be visible. *PixelFormat* defines the format of the individual pixel.

```
typedef struct {
    UINT32          MaxMode;
    UINT32          Mode;
    EFI_GRAPHICS_OUTPUT_MODE_INFORMATION *Info;
    UINTN          SizeOfInfo;
    EFI_PHYSICAL_ADDRESS FrameBufferBase;
    UINTN          FrameBufferSize;
} EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE;
```

The **EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE** is read-only and values are only changed by using the appropriate interface functions:

MaxMode The number of modes supported by **QueryMode ()** and **SetMode ()**.

Mode Current Mode of the graphics device. Valid mode numbers are 0 to *MaxMode* -1.

Info Pointer to read-only **EFI_GRAPHICS_OUTPUT_MODE_INFORMATION** data.

<i>SizeOfInfo</i>	Size of <i>Info</i> structure in bytes. Future versions of this specification may increase the size of the EFI_GRAPHICS_OUTPUT_MODE_INFORMATION data.
<i>FrameBufferBase</i>	Base address of graphics linear frame buffer. <i>Info</i> contains information required to allow software to draw directly to the frame buffer without using Blt() . Offset zero in <i>FrameBufferBase</i> represents the upper left pixel of the display.
<i>FrameBufferSize</i>	Size of the frame buffer represented by <i>FrameBufferBase</i> in bytes.

Description

The **EFI_GRAPHICS_OUTPUT_PROTOCOL** provides a software abstraction to allow pixels to be drawn directly to the frame buffer. The **EFI_GRAPHICS_OUTPUT_PROTOCOL** is designed to be lightweight and to support the basic needs of graphics output prior to Operating System boot.

EFI_GRAPHICS_OUTPUT_PROTOCOL.QueryMode()

Summary

Returns information for an available graphics mode that the graphics device and the set of active video output devices supports.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_GRAPHICS_OUTPUT_PROTOCOL_QUERY_MODE) (
    IN EFI_GRAPHICS_OUTPUT_PROTOCOL          *This,
    IN UINT32                                ModeNumber,
    OUT UINTN                                 *SizeOfInfo
    OUT EFI_GRAPHICS_OUTPUT_MODE_INFORMATION **Info
);
```

Parameters

<i>This</i>	The EFI_GRAPHICS_OUTPUT_PROTOCOL instance. Type EFI_GRAPHICS_OUTPUT_PROTOCOL is defined in this section.
<i>ModeNumber</i>	The mode number to return information on. The current mode and valid modes are read-only values in the <i>Mode</i> structure of the EFI_GRAPHICS_OUTPUT_PROTOCOL .
<i>SizeOfInfo</i>	A pointer to the size, in bytes, of the <i>Info</i> buffer.
<i>Info</i>	A pointer to a callee allocated buffer that returns information about <i>ModeNumber</i> .

Description

The **QueryMode()** function returns information for an available graphics mode that the graphics device and the set of active video output devices supports. If *ModeNumber* is not between 0 and *MaxMode* - 1, then **EFI_INVALID_PARAMETER** is returned. *MaxMode* is available from the *Mode* structure of the [EFI_GRAPHICS_OUTPUT_PROTOCOL](#).

The size of the *Info* structure should never be assumed and the value of *SizeOfInfo* is the only valid way to know the size of *Info*.

If the [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) is installed on the handle that represents a single video output device, then the set of modes returned by this service is the subset of modes supported by both the graphics controller and the video output device.

If the [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) is installed on the handle that represents a combination of video output devices, then the set of modes returned by this service is the subset of modes supported by the graphics controller and the all of the video output devices represented by the handle.

Status Codes Returned

EFI_SUCCESS	Valid mode information was returned.
EFI_DEVICE_ERROR	A hardware error occurred trying to retrieve the video mode.
EFI_INVALID_PARAMETER	<i>ModeNumber</i> is not valid.

EFI_GRAPHICS_OUTPUT_PROTOCOL.SetMode()

Summary

Set the video device into the specified mode and clears the visible portions of the output display to black.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_GRAPHICS_OUTPUT_PROTOCOL_SET_MODE) (
    IN EFI_GRAPHICS_OUTPUT_PROTOCOL *This,
    IN UINT32                        ModeNumber
);
```

Parameters

This

The [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) instance. Type [EFI_GRAPHICS_OUTPUT_PROTOCOL](#) is defined in this section.

ModeNumber

Abstraction that defines the current video mode. The current mode and valid modes are read-only values in the *Mode* structure of the [EFI_GRAPHICS_OUTPUT_PROTOCOL](#).

Description

This **SetMode ()** function sets the graphics device and the set of active video output devices to the video mode specified by *ModeNumber*. If *ModeNumber* is not supported **EFI_UNSUPPORTED** is returned.

If a device error occurs while attempting to set the video mode, then **EFI_DEVICE_ERROR** is returned. Otherwise, the graphics device is set to the requested geometry, the set of active output devices are set to the requested geometry, the visible portion of the hardware frame buffer is cleared to black, and **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The graphics mode specified by <i>ModeNumber</i> was selected.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.
EFI_UNSUPPORTED	<i>ModeNumber</i> is not supported by this device.

EFI_GRAPHICS_OUTPUT_PROTOCOL.Blt()

Summary

Blt a rectangle of pixels on the graphics screen. Blt stands for BLock Transfer.

Prototype

```
typedef struct {
    UINT8    Blue;
    UINT8    Green;
    UINT8    Red;
    UINT8    Reserved;
} EFI_GRAPHICS_OUTPUT_BLT_PIXEL;

typedef enum {
    EfiBltVideoFill,
    EfiBltVideoToBltBuffer,
    EfiBltBufferToVideo,
    EfiBltVideoToVideo,
    EfiGraphicsOutputBltOperationMax
} EFI_GRAPHICS_OUTPUT_BLT_OPERATION;

typedef
EFI_STATUS
(EFIAPI *EFI_GRAPHICS_OUTPUT_PROTOCOL_BLT) (
    IN EFI_GRAPHICS_OUTPUT_PROTOCOL          *This,
    IN OUT EFI_GRAPHICS_OUTPUT_BLT_PIXEL    *BltBuffer,    OPTIONAL
    IN  EFI_GRAPHICS_OUTPUT_BLT_OPERATION    BltOperation,
    IN  UINTN                                SourceX,
    IN  UINTN                                SourceY,
    IN  UINTN                                DestinationX,
    IN  UINTN                                DestinationY,
    IN  UINTN                                Width,
    IN  UINTN                                Height,
    IN  UINTN                                Delta           OPTIONAL
);
```

Parameters

<i>This</i>	The EFI_GRAPHICS_OUTPUT_PROTOCOL instance.
<i>BltBuffer</i>	The data to transfer to the graphics screen. Size is at least $Width * Height * \text{sizeof}(EFI_GRAPHICS_OUTPUT_BLT_PIXEL)$.
<i>BltOperation</i>	The operation to perform when copying <i>BltBuffer</i> on to the graphics screen.

<i>SourceX</i>	The X coordinate of the source for the <i>BltOperation</i> . The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.
<i>SourceY</i>	The Y coordinate of the source for the <i>BltOperation</i> . The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.
<i>DestinationX</i>	The X coordinate of the destination for the <i>BltOperation</i> . The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.
<i>DestinationY</i>	The Y coordinate of the destination for the <i>BltOperation</i> . The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.
<i>Width</i>	The width of a rectangle in the blt rectangle in pixels. Each pixel is represented by an EFI_GRAPHICS_OUTPUT_PIXEL element.
<i>Height</i>	The height of a rectangle in the blt rectangle in pixels. Each pixel is represented by an EFI_GRAPHICS_OUTPUT_PIXEL element.
<i>Delta</i>	Not used for <i>EfiBltVideoFill</i> or the <i>EfiBltVideoToVideo</i> operation. If a <i>Delta</i> of zero is used, the entire <i>BltBuffer</i> is being operated on. If a subrectangle of the <i>BltBuffer</i> is being used then <i>Delta</i> represents the number of bytes in a row of the <i>BltBuffer</i> .

Description

The **Blt()** function is used to draw the *BltBuffer* rectangle onto the video screen.

The *BltBuffer* represents a rectangle of *Height* by *Width* pixels that will be drawn on the graphics screen using the operation specified by *BltOperation*. The *Delta* value can be used to enable the *BltOperation* to be performed on a sub-rectangle of the *BltBuffer*.

[Table 84](#) describes the *BltOperations* that are supported on rectangles. Rectangles have coordinates (left, upper) (right, bottom):

Table 84. Blt Operation Table

Blt Operation	Operation
EfiBltVideoFill	Write data from the <i>BltBuffer</i> pixel (0,0) directly to every pixel of the video display rectangle (<i>DestinationX</i> , <i>DestinationY</i>) (<i>DestinationX</i> + <i>Width</i> , <i>DestinationY</i> + <i>Height</i>). Only one pixel will be used from the <i>BltBuffer</i> . <i>Delta</i> is NOT used.
EfiBltVideoToBltBuffer	Read data from the video display rectangle (<i>SourceX</i> , <i>SourceY</i>) (<i>SourceX</i> + <i>Width</i> , <i>SourceY</i> + <i>Height</i>) and place it in the <i>BltBuffer</i> rectangle (<i>DestinationX</i> , <i>DestinationY</i>) (<i>DestinationX</i> + <i>Width</i> , <i>DestinationY</i> + <i>Height</i>). If <i>DestinationX</i> or <i>DestinationY</i> is not zero then <i>Delta</i> must be set to the length in bytes of a row in the <i>BltBuffer</i> .

EfiBltBufferToVideo	Write data from the <i>BltBuffer</i> rectangle (<i>SourceX</i> , <i>SourceY</i>) (<i>SourceX</i> + <i>Width</i> , <i>SourceY</i> + <i>Height</i>) directly to the video display rectangle (<i>DestinationX</i> , <i>DestinationY</i>) (<i>DestinationX</i> + <i>Width</i> , <i>DestinationY</i> + <i>Height</i>). If <i>SourceX</i> or <i>SourceY</i> is not zero then <i>Delta</i> must be set to the length in bytes of a row in the <i>BltBuffer</i> .
EfiBltVideoToVideo	Copy from the video display rectangle (<i>SourceX</i> , <i>SourceY</i>) (<i>SourceX</i> + <i>Width</i> , <i>SourceY</i> + <i>Height</i>) to the video display rectangle (<i>X</i> , <i>Y</i>) (<i>X</i> + <i>Width</i> , <i>Y</i> + <i>Height</i>). The <i>BltBuffer</i> and <i>Delta</i> are not used in this mode. There is no limitation on the overlapping of the source and destination rectangles.

Status Codes Returned

EFI_SUCCESS	<i>BltBuffer</i> was drawn to the graphics screen.
EFI_INVALID_PARAMETER	<i>BltOperation</i> is not valid.
EFI_DEVICE_ERROR	The device had an error and could not complete the request.

EFI_EDID_DISCOVERED_PROTOCOL

Summary

This protocol contains the EDID information retrieved from a video output device.

GUID

```
#define EFI_EDID_DISCOVERED_PROTOCOL_GUID \
    {0x1c0c34f6, 0xd380, 0x41fa, 0xa0, 0x49, 0x8a, 0xd0, 0x6c, 0x1a, \
     0x66, 0xaa}
```

Protocol Interface Structure

```
typedef struct {
    UINT32    SizeOfEdid;
    UINT8     *Edid;
} EFI_EDID_DISCOVERED_PROTOCOL;
```

Parameter

SizeOfEdid The size, in bytes, of the *Edid* buffer. 0 if no EDID information is available from the video output device. Otherwise, it must be a minimum of 128 bytes.

Edid A pointer to a read-only array of bytes that contains the EDID information for a video output device. This pointer is **NULL** if no EDID information is available from the video output device. The minimum size of a valid *Edid* buffer is 128 bytes. EDID information is defined in the E-DID EEPROM specification published by VESA (www.vesa.org).

Description

EFI_EDID_DISCOVERED_PROTOCOL represents the EDID information that is returned from a video output device. If the video output device does not contain any EDID information, then the *SizeOfEdid* field must set to zero and the *Edid* field must be set to **NULL**. The **EFI_EDID_DISCOVERED_PROTOCOL** must be placed on every child handle that represents a possible video output device. The **EFI_EDID_DISCOVERED_PROTOCOL** is never placed on child handles that represent combinations of two or more video output devices.

EFI_EDID_ACTIVE_PROTOCOL

Summary

This protocol contains the EDID information for an active video output device. This is either the EDID information retrieved from the **EFI_EDID_OVERRIDE_PROTOCOL** if an override is available, or an identical copy of the EDID information from the **EFI_EDID_DISCOVERED_PROTOCOL** if no overrides are available.

GUID

```
#define EFI_EDID_ACTIVE_PROTOCOL_GUID \
    {0xbd8c1056, 0x9f36, 0x44ec, 0x92, 0xa8, 0xa6, 0x33, 0x7f, 0x81, \
     0x79, 0x86}
```

Protocol Interface Structure

```
typedef struct {
    UINT32    SizeOfEdid;
    UINT8     *Edid;
} EFI_EDID_ACTIVE_PROTOCOL;
```

Parameter

<i>SizeOfEdid</i>	The size, in bytes, of the <i>Edid</i> buffer. 0 if no EDID information is available from the video output device. Otherwise, it must be a minimum of 128 bytes.
<i>Edid</i>	A pointer to a read-only array of bytes that contains the EDID information for an active video output device. This pointer is NULL if no EDID information is available for the video output device. The minimum size of a valid <i>Edid</i> buffer is 128 bytes. EDID information is defined in the E-DID EEPROM specification published by VESA (www.vesa.org).

Description

When the set of active video output devices attached to a frame buffer are selected, the **EFI_EDID_ACTIVE_PROTOCOL** must be installed onto the handles that represent the each of those active video output devices. If the **EFI_EDID_OVERRIDE_PROTOCOL** has override EDID information for an active video output device, then the EDID information specified by **GetEdid()**

is used for the `EFI_EDID_ACTIVE_PROTOCOL`. Otherwise, the EDID information from the `EFI_EDID_DISCOVERED_PROTOCOL` is used for the `EFI_EDID_ACTIVE_PROTOCOL`. Since all EDID information is read-only, it is legal for the pointer associated with the `EFI_EDID_ACTIVE_PROTOCOL` to be the same as the pointer associated with the `EFI_EDID_DISCOVERED_PROTOCOL` when no overrides are present.

EFI_EDID_OVERRIDE_PROTOCOL

Summary

This protocol is produced by the platform to allow the platform to provide EDID information to the producer of the Graphics Output protocol.

GUID

```
#define EFI_EDID_OVERRIDE_PROTOCOL_GUID \
    {0x48ecb431, 0xfb72, 0x45c0, 0xa9, 0x22, 0xf4, 0x58, 0xfe, 0x4, 0xb, \
     0xd5}
```

Protocol Interface Structure

```
typedef struct _EFI_EDID_OVERRIDE_PROTOCOL {
    EFI_EDID_OVERRIDE_PROTOCOL_GET_EDID  GetEdid;
} EFI_EDID_OVERRIDE_PROTOCOL;
```

Parameter

GetEdid Returns EDID values and attributes that the Video BIOS must use

Description

This protocol is produced by the platform to allow the platform to provide EDID information to the producer of the Graphics Output protocol.

EFI_EDID_OVERRIDE_PROTOCOL.GetEdid()

Summary

Returns policy information and potentially a replacement EDID for the specified video output device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_EDID_OVERRIDE_PROTOCOL_GET_EDID) (
    IN      EFI_EDID_OVERRIDE_PROTOCOL  *This,
    IN      EFI_HANDLE                  *ChildHandle,
    OUT     UINT32                       *Attributes,
    IN OUT  UINTN                       *EdidSize,
    IN OUT  UINT8                       **Edid
);
```

Parameters

<i>This</i>	The EFI EDID OVERRIDE PROTOCOL instance. Type EFI_EDID_OVERRIDE_PROTOCOL is defined in Section 11.10 .
<i>ChildHandle</i>	A child handle that represents a possible video output device.
<i>Attributes</i>	A pointer to the attributes associated with <i>ChildHandle</i> video output device.
<i>EdidSize</i>	A pointer to the size, in bytes, of the <i>Edid</i> buffer.
<i>Edid</i>	A pointer to the callee allocated buffer that contains the EDID information associated with <i>ChildHandle</i> . If <i>EdidSize</i> is 0, then a pointer to NULL is returned.

Related Definitions

```
#define EFI_EDID_OVERRIDE_DONT_OVERRIDE    0x01
#define EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG 0x02
```

Table 85. Attributes Definition Table

Attribute Bit	EdidSize	Operation
0x0	!= 0	Use returned over ride EDID in all cases
0x0	0	No over rides or policy
EFI_EDID_OVERRIDE_DONT_OVERRIDE	!= 0	Only use returned over ride EDID if the display device does not have an EDID. If the display device has an EDID use that value.
EFI_EDID_OVERRIDE_DONT_OVERRIDE	0	No over rides or policy.

EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG	!= 0	Enable hot plug and used returned override EDID in all cases. This means a Graphics Output protocol must be produced even if the display device is not present.
EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG	0	Enable hot plug. This means a Graphics Output protocol must be produced even if the display device is not present.
EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG & EFI_EDID_OVERRIDE_DONT_OVERRIDE	!= 0	Enable hot plug. Only use returned override EDID if the display device does not have an EDID. This means a Graphics Output protocol must be produced even if the display device is not present.
EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG & EFI_EDID_OVERRIDE_DONT_OVERRIDE	0	Enable hot plug. This means a Graphics Output protocol must be produced even if the display device is not present.

Description

This protocol is optionally provided by the platform to override or provide EDID information and/or output device display properties to the producer of the Graphics Output protocol. If *ChildHandle* does not represent a video output device, or there are no override for the video output device specified by *ChildHandle*, then **EFI_UNSUPPORTED** is returned. Otherwise, the *Attributes*, *EdidSize*, and *Edid* parameters are returned along with a status of **EFI_SUCCESS**. [Table 85](#) defines the behavior for the combinations of the *Attribute* and *EdidSize* parameters when **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	Valid over rides returned for <i>ChildHandle</i> .
EFI_UNSUPPORTED	<i>ChildHandle</i> has no over rides.

11.10 Rules for PCI/AGP Devices

A UEFI driver that produces the Graphics Output Protocol must follow the UEFI driver model, produce an **EFI DRIVER BINDING PROTOCOL**, and follow the rules on implementing the **Supported()**, **Start()**, and **Stop()**. The **Start()** function must not update the video output device in any way that is visible to the user. The **Start()** function must create child handle for each physical video output device and each supported combination of video output devices. The driver must retrieve the EDID information from each physical video output device and produce a **EFI EDID DISCOVERED PROTOCOL** on the child handle that corresponds each physical video output device. The following summary describes the common initialization steps for a driver that produces the **EFI_GRAPHICS_OUTPUT_PROTOCOL**. This summary assumes the graphics controller supports a single frame buffer. If a graphics device supports multiple frame buffers, then handles for the frame buffers must be created first, and then the handles for the video output devices can be created as children of the frame buffer handles.

Summary of Initialization Steps:

- System calls [Start\(\)](#).
- If *RemainingDevicePath* is **NULL**, then a default set of active video output devices are selected by the driver. If the first node of *RemainingDevicePath* is not an `ACPI_ADR` node or the first two nodes of *RemainingDevicePath* are not a Controller node followed by an `ACPI_ADR` node, then **Start()** returns **EFI_UNSUPPORTED**.
- **Start()** function creates a *ChildHandle* for each physical video output device and installs the **EFI_DEVICE_PATH_PROTOCOL** onto the created *ChildHandle*. The **EFI_DEVICE_PATH_PROTOCOL** is constructed by appending an `ACPI_ADR` device path node describing the physical video output device to the end of the device path installed on the *ControllerHandle* passed into **Start()**.
- **Start()** function retrieves EDID information for each physical video output device and installs the **EFI_EDID_DISCOVERED_PROTOCOL** onto the *ChildHandle* for each physical video output device. If no EDID data is available from the video output device, then *SizeOfEdid* is set to zero, and *Edid* is set to **NULL**.
- **Start()** function create a *ChildHandle* for each valid combination of two or more video output devices, and installs the **EFI_DEVICE_PATH_PROTOCOL** onto the created *ChildHandle*. The **EFI_DEVICE_PATH_PROTOCOL** is constructed by appending an `ACPI_ADR` device path node describing the combination of video output devices to the end of the device path installed on the *ControllerHandle* passed into **Start()**. The `ACPI_ADR` entry can represent complex topologies of devices and it is possible to have more than one `ACPI_ADR` entry in a single device path node. Support of complex video output device topologies is an optional feature.
- **Start()** function evaluates the *RemainingDevicePath* to select the set of active video output devices. If *RemainingDevicePath* is **NULL**, then **Start()** selects a default set of video output devices. If *RemainingDevicePath* is not **NULL**, and `ACPI_ADR` device path node of *RemainingDevicePath* does not match any of the created *ChildHandles*, then **Start()** must destroy all its *ChildHandles* and return **EFI_UNSUPPORTED**. Otherwise, **Start()** selects the set of active video output devices specified by the `ACPI_ADR` device path node in *RemainingDevicePath*.
- **Start()** retrieves the *ChildHandle* associated with each active video output device. Only *ChildHandles* that represent a physical video output device are considered. **Start()** calls the **EFI_EDID_OVERRIDE_PROTOCOL.GetEdid()** service passing in *ChildHandle*. Depending on the return values from **GetEdid()**, either the override EDID information or the EDID information from the **EFI_EDID_DISCOVERED_PROTOCOL** on *ChildHandle* is selected. See **GetEdid()** for a detailed description of this decision. The selected EDID information is used to produce the **EFI_EDID_ACTIVE_PROTOCOL**, and that protocol is installed onto *ChildHandle*.
- **Start()** retrieves the one *ChildHandle* that represents the entire set of active video output devices. If this set is a single video output device, then this *ChildHandle* will be the same as the one used in the previous step. If this set is a combination of video output devices, then this will not be one of the *ChildHandles* used in the previous two steps. The **EFI_GRAPHICS_OUTPUT_PROTOCOL** is installed onto this *ChildHandle*.
- The **QueryMode()** service of the **EFI_GRAPHICS_OUTPUT_PROTOCOL** returns the set of modes that both the graphics controller and the set of active video output devices all support. If

a different set of active video output device is selected, then a different set of modes will likely be produced by **QueryMode ()** .

- **Start ()** function optionally initializes video frame buffer hardware. The EFI driver has the option of delaying this operation until **SetMode ()** is called.
- The EFI Driver must provide **EFI_COMPONENT_NAME_PROTOCOL** **GetControllerName ()** support for *ControllerHandle* and all the *ChildHandles* created by this driver. The name returned for *ControllerHandle* must return the name of the graphics device. The name returned for each of the *ChildHandles* allow the user to pick output display settings and should be constructed with this in mind.
- The EFI Driver's **Stop ()** function must cleanly undo what the **Start ()** function created.
-
- An **EFI_GRAPHICS_OUTPUT_PROTOCOL** must be implemented for every video frame buffer that exists on a video adapter. In most cases there will be a single **EFI_GRAPHICS_OUTPUT_PROTOCOL** placed on one of the a children of the *ControllerHandle* passed into the **EFI_DRIVER_BINDING.Start ()** function.

If a single PCI device/function contains multiple frame buffers the **EFI_GRAPHICS_OUTPUT_PROTOCOL** must create child handles of the PCI handle that inherit its PCI device path and appends a controller device path node. [cross reference 8.3.2.5 EFI 1.10 Controller Device Path]. The handles for the video output devices are children of the handles that represent the frame buffers..

A video device can support an arbitrary number of geometries, but it must support one or more of the following modes to conform to this specification:

Onboard graphics device

- A mode required in a platform design guide
- Native mode of the display

Plug in graphics device

- A mode required in a platform design guide
- 800 x 600 with 32-bit color depth or 640 x 480 with 32-bit color depth and a pixel format described by **PixelRedGreenBlueReserved8BitPerColor** or **PixelBlueGreenRedReserved8BitPerColor**.

A plug in graphics device that contains a ROM must have an EBC version of the EFI driver that produces the **EFI_GRAPHICS_OUTPUT_PROTOCOL**.

If graphics output device supports both landscape and portrait mode displays it must return a different mode via **QueryMode ()** . For example landscape mode could be 800 horizontal and 600 vertical while the equivalent portrait mode would be 600 horizontal and 800 vertical.

Protocols - Media Access

12.1 Load File Protocol

This section defines the Load File protocol. This protocol is designed to allow code running in the boot services environment to find and load other modules of code.

EFI_LOAD_FILE_PROTOCOL

Summary

Is used to obtain files from arbitrary devices.

GUID

```
#define EFI_LOAD_FILE_PROTOCOL_GUID \
{0x56EC3091,0x954C,0x11d2,0x8E,0x3F,0x00,0xA0,0xC9,0x69,0x72,
0x3B}
```

Protocol Interface Structure

```
typedef struct {
    EFI_LOAD_FILE           LoadFile;
} EFI_LOAD_FILE_PROTOCOL;
```

Parameters

LoadFile Causes the driver to load the requested file. See the [LoadFile\(\)](#) function description.

Description

The **EFI_LOAD_FILE_PROTOCOL** is a simple protocol used to obtain files from arbitrary devices.

When the firmware is attempting to load a file, it first attempts to use the device's Simple File System protocol to read the file. If the file system protocol is found, the firmware implements the policy of interpreting the File Path value of the file being loaded. If the device does not support the file system protocol, the firmware then attempts to read the file via the **EFI_LOAD_FILE_PROTOCOL** and the **LoadFile()** function. In this case the **LoadFile()** function implements the policy of interpreting the File Path value.

EFI_LOAD_FILE_PROTOCOL.LoadFile()

Summary

Causes the driver to load a specified file.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_LOAD_FILE) (
    IN EFI_LOAD_FILE_PROTOCOL    *This,
    IN EFI_DEVICE_PATH_PROTOCOL  *FilePath,
    IN BOOLEAN                   BootPolicy,
    IN OUT UINTN                 *BufferSize,
    IN VOID                      *Buffer    OPTIONAL
);
```

Parameters

<i>This</i>	Indicates a pointer to the calling context. Type EFI_LOAD_FILE_PROTOCOL is defined in Section 12.1 .
<i>FilePath</i>	The device specific path of the file to load. Type EFI_DEVICE_PATH_PROTOCOL is defined in Section 9.2 .
<i>BootPolicy</i>	If TRUE , indicates that the request originates from the boot manager, and that the boot manager is attempting to load <i>FilePath</i> as a boot selection. If FALSE , then <i>FilePath</i> must match an exact file to be loaded.
<i>BufferSize</i>	On input the size of <i>Buffer</i> in bytes. On output with a return code of EFI_SUCCESS , the amount of data transferred to <i>Buffer</i> . On output with a return code of EFI_BUFFER_TOO_SMALL , the size of <i>Buffer</i> required to retrieve the requested file.
<i>Buffer</i>	The memory buffer to transfer the file to. If <i>Buffer</i> is NULL , then no the size of the requested file is returned in <i>BufferSize</i> .

Description

The **LoadFile()** function interprets the device-specific *FilePath* parameter, returns the entire file into *Buffer*, and sets *BufferSize* to the amount of data returned. If *Buffer* is **NULL**, then the size of the file is returned in *BufferSize*. If *Buffer* is not **NULL**, and *BufferSize* is not large enough to hold the entire file, then **EFI_BUFFER_TOO_SMALL** is returned, and *BufferSize* is updated to indicate the size of the buffer needed to obtain the file. In this case, no data is returned in *Buffer*.

If *BootPolicy* is **FALSE** the *FilePath* must match an exact file to be loaded. If no such file exists, **EFI_NOT_FOUND** is returned. If *BootPolicy* is **FALSE**, and an attempt is being made to perform a network boot through the PXE Base Code protocol, **EFI_UNSUPPORTED** is returned.

If *BootPolicy* is **TRUE** the firmware’s boot manager is attempting to load an EFI image that is a boot selection. In this case, *FilePath* contains the file path value in the boot selection option. Normally the firmware would implement the policy on how to handle an inexact boot file path; however, since in this case the firmware cannot interpret the file path, the **LoadFile ()** function is responsible for implementing the policy. For example, in the case of a network boot through the PXE Base Code protocol, *FilePath* merely points to the root of the device, and the firmware interprets this as wanting to boot from the first valid loader. The following is a list of events that **LoadFile ()** will implement for a PXE boot:

- Perform DHCP.
- Optionally prompt the user with a menu of boot selections.
- Discover the boot server and the boot file.
- Download the boot file into *Buffer* and update *BufferSize* with the size of the boot file.

Status Codes Returned

EFI_SUCCESS	The file was loaded.
EFI_UNSUPPORTED	The device does not support the provided <i>BootPolicy</i> .
EFI_INVALID_PARAMETER	<i>FilePath</i> is not a valid device path, or <i>BufferSize</i> is NULL .
EFI_NO_MEDIA	No medium was present to load the file.
EFI_DEVICE_ERROR	The file was not loaded due to a device error.
EFI_NO_RESPONSE	The remote system did not respond.
EFI_NOT_FOUND	The file was not found.
EFI_ABORTED	The file load process was manually cancelled.
EFI_BUFFER_TOO_SMALL	The <i>BufferSize</i> is too small to read the current directory entry. <i>BufferSize</i> has been updated with the size needed to complete the request.

12.2 File System Format

The file system supported by the Extensible Firmware Interface is based on the FAT file system. EFI defines a specific version of FAT that is explicitly documented and testable. Conformance to the EFI specification and its associate reference documents is the only definition of FAT that needs to be implemented to support EFI. To differentiate the EFI file system from pure FAT, a new partition file system type has been defined.

EFI encompasses the use of FAT32 for a system partition, and FAT12 or FAT16 for removable media. The FAT32 system partition is identified by an OSType value other than that used to identify previous versions of FAT. This unique partition type distinguishes an EFI defined file system from a normal FAT file system. The file system supported by EFI includes support for long file names.

The definition of the EFI file system will be maintained by specification and will not evolve over time to deal with errata or variant interpretations in OS file system drivers or file system utilities. Future enhancements and compatibility enhancements to FAT will not be automatically included in EFI file systems. The EFI file system is a target that is fixed by the EFI specification, and other specifications explicitly referenced by the EFI specification.

For more information about the EFI file system and file image format, visit the web site from which this document was obtained.

12.2.1 System Partition

A System Partition is a partition in the conventional sense of a partition on a legacy system. For a hard disk, a partition is a contiguous grouping of sectors on the disk where the starting sector and size are defined by the Master Boot Record (MBR), which resides on LBA 0 (i.e., the first sector of the hard disk) (see [Section 5.2](#)), or the GUID Partition Table (GPT), which resides on logical block 1 (the second sector of the hard disk) (see [Section 5.3.1](#)). For a diskette (floppy) drive, a partition is defined to be the entire media. A System Partition can reside on any media that is supported by EFI Boot Services.

A System Partition supports backward compatibility with legacy systems by reserving the first block (sector) of the partition for compatibility code. On legacy systems, the first block (sector) of a partition is loaded into memory and execution is transferred to this code. EFI firmware does not execute the code in the MBR. The EFI firmware contains knowledge about the partition structure of various devices, and can understand legacy MBR, GPT, and “El Torito.”

The System Partition contains directories, data files, and UEFI Images. UEFI Images can contain a OS Loader, an driver to extend platform firmware capability, or an application that provides a transient service to the system. Applications written to this specification could include things such as a utility to create partitions or extended diagnostics. A System Partition can also support data files, such as error logs, that can be defined and used by various OS or system firmware software components.

12.2.1.1 File System Format

The first block (sector) of a partition contains a data structure called the BIOS Parameter Block (BPB) that defines the type and location of FAT file system on the drive. The BPB contains a data structure that defines the size of the media, the size of reserved space, the number of FAT tables, and the location and size of the root directory (not used in FAT32). The first block (sector) also contains code that will be executed as part of the boot process on a legacy system. This code in the first block (sector) usually contains code that can read a file from the root directory into memory and transfer control to it. Since EFI firmware contains a file system driver, EFI firmware can load any file from the file system with out needing to execute any code from the media.

The EFI firmware must support the FAT32, FAT16, and FAT12 variants of the EFI file system. What variant of EFI FAT to use is defined by the size of the media. The rules defining the relationship between media size and FAT variants is defined in the specification for the EFI file system.

12.2.1.2 File Names

FAT stores file names in two formats. The original FAT format limited file names to eight characters with three extension characters. This type of file name is called an 8.3, pronounced eight dot three, file name. FAT was extended to include support for long file names (LFN).

FAT 8.3 file names are always stored as uppercase ASCII characters. LFN can either be stored as ASCII or Unicode and are stored case sensitive. The string that was used to open or create the file is stored directly into LFN. FAT defines that all files in a directory must have a unique name, and

unique is defined as a case insensitive match. The following are examples of names that are considered to be the same and cannot exist in a single directory:

- “ThisIsAnExampleDirectory.Dir”
- “thisisanexamppledirectory.dir”
- THISISANEXAMPLEDIRECTORY.DIR
- ThisIsAnExampleDirectory.DIR

12.2.1.3 Directory Structure

An EFI system partition that is present on a hard disk must contain an EFI defined directory in the root directory. This directory is named **EFI**. All OS loaders and applications will be stored in subdirectories below **EFI**. Applications that are loaded by other applications or drivers are not required to be stored in any specific location in the EFI system partition. The choice of the subdirectory name is up to the vendor, but all vendors must pick names that do not collide with any other vendor’s subdirectory name. This applies to system manufacturers, operating system vendors, BIOS vendors, and third party tool vendors, or any other vendor that wishes to install files on an EFI system partition. There must also only be one executable EFI image for each supported processor architecture in each vendor subdirectory. This guarantees that there is only one image that can be loaded from a vendor subdirectory by the EFI Boot Manager. If more than one executable EFI image is present, then the boot behavior for the system will not be deterministic. There may also be an optional vendor subdirectory called **BOOT**.

This directory contains EFI images that aide in recovery if the boot selections for the software installed on the EFI system partition are ever lost. Any additional UEFI-compliant executables must be in subdirectories below the vendor subdirectory. The following is a sample directory structure for an EFI system partition present on a hard disk.

```

\EFI
  \<OS Vendor 1 Directory>
    <OS Loader Image>
  \<OS Vendor 2 Directory>
    <OS Loader Image>
  . . .
  \<OS Vendor N Directory>
    <OS Loader Image>
  \<OEM Directory>
    <OEM Application Image>
  \<BIOS Vendor Directory>
    <BIOS Vendor Application Image>
  \<Third Party Tool Vendor Directory>
    <Third Party Tool Vendor Application Image>
  \BOOT
    BOOT{machine type short name}.EFI

```

For removable media devices there must be only one UEFI-compliant system partition, and that partition must contain an UEFI-defined directory in the root directory. The directory will be named **EFI**. All OS loaders and applications will be stored in a subdirectory below **EFI** called **BOOT**.

There must only be one executable EFI image for each supported processor architecture in the **BOOT** directory. For removable media to be bootable under EFI, it must be built in accordance with the rules laid out in [Section 3.4.1.1](#). This guarantees that there is only one image that can be automatically loaded from a removable media device by the EFI Boot Manager. Any additional EFI executables must be in directories other than **BOOT**. The following is a sample directory structure for an EFI system partition present on a removable media device.

```

\EFI
\BOOT
    BOOT{machine type short name}.EFI
    
```

12.2.2 Partition Discovery

This specification requires the firmware to be able to parse the legacy master boot record(MBR) (see [Section 5.2.1](#)), GUID Partition Table (GPT)(see [Section 5.3.2](#)), and El Torito (see [Section 12.2.2.1](#)) logical device volumes. The EFI firmware produces a logical [EFI BLOCK IO PROTOCOL](#) device for each GPT Partition Entry, El Torito logical device volume, and if no GPT Partition Table is present any partitions found in the legacy MBR partition tables. LBA zero of the [EFI_BLOCK_IO_PROTOCOL](#) device will correspond to the first logical block of the partition. See [Figure 28](#).

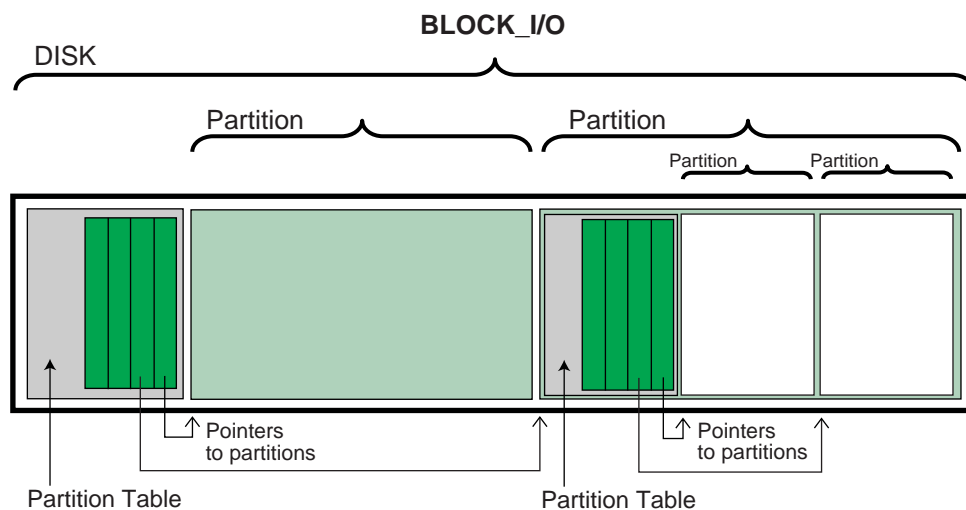


Figure 28. Nesting of Legacy MBR Partition Records

The following is the order in which a block device must be scanned to determine if it contains partitions. When a check for a valid partitioning scheme succeeds, the search terminates.

1. Check for GUID Partition Table Headers.
2. Follow ISO-9660 specification to search for ISO-9660 volume structures on the magic LBA.
3. Check for an “El Torito” volume extension and follow the “El Torito” CD-ROM specification.
4. If none of the above, check LBA 0 for a legacy MBR partition table.
5. No partition found on device.

EFI supports the nesting of legacy MBR partitions, by allowing any legacy MBR partition to contain more legacy MBR partitions. This is accomplished by supporting the same partition discovery algorithm on every logical block device. It should be noted that the GUID Partition Table does not allow nesting of GUID Partition Table Headers. Nesting is not needed since a GUID Partition Table Header can support an arbitrary number of partitions (the addressability limits of a 64-bit LBA are the limiting factor).

12.2.2.1 ISO-9660 and El Torito

ISO-9660 is the industry standard low level format used on CD-ROM and DVD-ROM. The CD-ROM format is completely described by the “El Torito” Bootable CD-ROM Format Specification Version 1.0. To boot from a CD-ROM or DVD-ROM in the boot services environment, an EFI System partition is stored in a “no emulation” mode as defined by the “El Torito” specification. A Platform ID of 0xEF indicates an EFI System Partition. The Platform ID is in either the Section Header Entry or the Validation Entry of the Booting Catalog as defined by the “El Torito” specification. EFI differs from “El Torito” “no emulation” mode in that it does not load the “no emulation” image into memory and jump to it. EFI interprets the “no emulation” image as an EFI system partition. EFI interprets the Sector Count in the Initial/Default Entry or the Section Header Entry to be the size of the EFI system partition. If the value of Sector Count is set to 0 or 1, EFI will assume the system partition consumes the space from the beginning of the “no emulation” image to the end of the CD-ROM.

DVD-ROM images formatted as required by the UDF 2.0 specification (*OSTA Universal Disk Format Specification*, Revision 2.0) can be booted by EFI. EFI supports booting from an ISO-9660 file system that conforms to the “El Torito” *Bootable CD-ROM Format Specification* on a DVD-ROM. A DVD-ROM that contains an ISO-9660 file system is defined as a “UDF Bridge” disk. Booting from CD-ROM and DVD-ROM is accomplished using the same methods.

Since the EFI file system definition does not use the same Initial/Default entry as a legacy CD-ROM it is possible to boot personal computers using an EFI CD-ROM or DVD-ROM. The inclusion of boot code for personal computers is optional and not required by EFI.

12.2.3 Media Formats

This section describes how booting from different types of removable media is handled. In general the rules are consistent regardless of a media’s physical type and whether it is removable or not.

12.2.3.1 Removable Media

Removable media may contain a standard FAT12, FAT16, or FAT32 file system. Legacy 1.44 MB floppy devices typically support a FAT12 file system.

Booting from a removable media device can be accomplished the same way as any other boot. The boot file path provided to the boot manager can consist of a UEFI application image to load, or can merely be the path to a removable media device. In the first case, the path clearly indicates the image that is to be loaded. In the later case, the boot manager implements the policy to load the default application image from the device.

For removable media to be bootable under EFI, it must be built in accordance with the rules laid out in [Section 3.4.1.1](#)

12.2.3.2 Diskette

EFI bootable diskettes follow the standard formatting conventions used on personal computers. The diskette contains only a single partition that complies to the EFI file system type. For diskettes to be bootable under EFI, it must be built in accordance with the rules laid out in [Section 3.4.1.1](#).

Since the EFI file system definition does not use the code in the first block of the diskette, it is possible to boot personal computers using a diskette that is also formatted as an EFI bootable removable media device. The inclusion of boot code for personal computers is optional and not required by EFI.

Diskettes include the legacy 3.5-inch diskette drives as well as the newer larger capacity removable media drives such as an Iomega* Zip*, Fujitsu MO, or MKE LS-120/SuperDisk*.

12.2.3.3 Hard Drive

Hard drives may contain multiple partitions as defined in [Section 12.2.2](#) on partition discovery. Any partition on the hard drive may contain a file system that the EFI firmware recognizes. Images that are to be booted must be stored under the EFI subdirectory as defined in [Section 12.2.1](#) and [Section 12.2.2](#).

EFI code does not assume a fixed block size.

Since EFI firmware does not execute the MBR code and does not depend on the *BootIndicator* field in the legacy MBR partition records, the hard disk can still boot and function normally.

12.2.3.4 CD-ROM and DVD-ROM

A CD-ROM or DVD-ROM may contain multiple partitions as defined [Section 12.2.1](#) and [Section 12.2.2](#) and in the “El Torito” specification.

EFI code does not assume a fixed block size.

Since the EFI file system definition does not use the same Initial/Default entry as a legacy CD-ROM, it is possible to boot personal computers using an EFI CD-ROM or DVD-ROM. The inclusion of boot code for personal computers is optional and not required by EFI.

12.2.3.5 Network

To boot from a network device, the Boot Manager uses the Load File Protocol to perform a [LoadFile \(\)](#) on the network device. This uses the PXE Base Code Protocol to perform DHCP and Discovery. This may result in a list of possible boot servers along with the boot files available on each server. The Load File Protocol for a network boot may then optionally produce a menu of these selections for the user to choose from. If this menu is presented, it will always have a timeout, so the Load File Protocol can automatically boot the default boot selection. If there is only one possible boot file, then the Load File Protocol can automatically attempt to load the one boot file.

The Load File Protocol will download the boot file using the MTFTP service in the PXE Base Code Protocol. The downloaded image must be an EFI image that the platform supports.

12.3 Simple File System Protocol

This section defines the Simple File System protocol. This protocol allows code running in the EFI boot services environment to obtain file based access to a device.

[EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) is used to open a device volume and return an [EFI_FILE_PROTOCOL](#) that provides interfaces to access files on a device volume.

EFI_SIMPLE_FILE_SYSTEM_PROTOCOL

Summary

Provides a minimal interface for file-type access to a device.

GUID

```
#define EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_GUID \
{0x0964e5b22,0x6459,0x11d2,0x8e,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}
```

Revision Number

```
#define EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```
typedef struct _EFI_SIMPLE_FILE_SYSTEM_PROTOCOL {
    UINT64 Revision;
    EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_OPEN_VOLUME OpenVolume;
} EFI_SIMPLE_FILE_SYSTEM_PROTOCOL;
```

Parameters

<i>Revision</i>	The version of the EFI_FILE_PROTOCOL . The version specified by this specification is 0x00010000. All future revisions must be backwards compatible. If a future version is not backwards compatible, it is not the same GUID.
<i>OpenVolume</i>	Opens the volume for file I/O access. See the OpenVolume() function description.

Description

The [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) provides a minimal interface for file-type access to a device. This protocol is only supported on some devices.

Devices that support the Simple File System protocol return an [EFI_FILE_PROTOCOL](#). The only function of this interface is to open a handle to the root directory of the file system on the volume. Once opened, all accesses to the volume are performed through the volume's file handles, using the [EFI_FILE_PROTOCOL](#) protocol. The volume is closed by closing all the open file handles.

The firmware automatically creates handles for any block device that supports the following file system formats:

- FAT12
- FAT16
- FAT32

EFI_SIMPLE_FILE_SYSTEM_PROTOCOL.OpenVolume()

Summary

Opens the root directory on a volume.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_OPEN_VOLUME) (
    IN EFI_FILE_PROTOCOL    *This,
    OUT EFI_FILE_PROTOCOL    **Root
);

```

Parameters

This

A pointer to the volume to open the root directory of. See the type [EFI_SIMPLE_FILE_SYSTEM_PROTOCOL](#) description.

Root

A pointer to the location to return the opened file handle for the root directory. See the type [EFI_FILE_PROTOCOL](#) description.

Description

The **OpenVolume()** function opens a volume, and returns a file handle to the volume's root directory. This handle is used to perform all other file I/O operations. The volume remains open until all the file handles to it are closed.

If the medium is changed while there are open file handles to the volume, all file handles to the volume will return **EFI_MEDIA_CHANGED**. To access the files on the new medium, the volume must be reopened with **OpenVolume()**. If the new medium is a different file system than the one supplied in the **EFI_HANDLE**'s **DevicePath** for the **EFI_SIMPLE_SYSTEM_PROTOCOL**, **OpenVolume()** will return **EFI_UNSUPPORTED**.

Status Codes Returned

EFI_SUCCESS	The file volume was opened.
EFI_UNSUPPORTED	The volume does not support the requested file system type.
EFI_NO_MEDIA	The device has no medium.
EFI_DEVICE_ERROR	The device reported an error.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.
EFI_ACCESS_DENIED	The service denied access to the file.
EFI_OUT_OF_RESOURCES	The file volume was not opened.
EFI_MEDIA_CHANGED	The device has a different medium in it or the medium is no longer supported. Any existing file handles for this volume are no longer valid. To access the files on the new medium, the volume must be reopened with OpenVolume () .

12.4 EFI File Protocol

The protocol and functions described in this section support access to EFI-supported file systems.

EFI_FILE_PROTOCOL

Summary

Provides file based access to supported file systems.

Revision Number

```
#define EFI_FILE_PROTOCOL_REVISION    0x00010000
```

Protocol Interface Structure

```
typedef struct _EFI_FILE_PROTOCOL {
    UINT64                Revision;
    EFI_FILE_OPEN         Open;
    EFI_FILE_CLOSE        Close;
    EFI_FILE_DELETE       Delete;
    EFI_FILE_READ         Read;
    EFI_FILE_WRITE        Write;
    EFI_FILE_GET_POSITION GetPosition;
    EFI_FILE_SET_POSITION SetPosition;
    EFI_FILE_GET_INFO     GetInfo;
    EFI_FILE_SET_INFO     SetInfo;
    EFI_FILE_FLUSH        Flush;
} EFI_FILE_PROTOCOL;
```

Parameters

<i>Revision</i>	The version of the EFI_FILE_PROTOCOL interface. The version specified by this specification is 0x00010000. Future versions are required to be backward compatible to version 1.0.
<i>Open</i>	Opens or creates a new file. See the Open() function description.
<i>Close</i>	Closes the current file handle. See the Close() function description.
<i>Delete</i>	Deletes a file. See the Delete() function description.
<i>Read</i>	Reads bytes from a file. See the Read() function description.
<i>Write</i>	Writes bytes to a file. See the Write() function description.
<i>GetPosition</i>	Returns the current file position. See the GetPosition() function description.
<i>SetPosition</i>	Sets the current file position. See the SetPosition() function description.
<i>GetInfo</i>	Gets the requested file or volume information. See the GetInfo() function description.
<i>SetInfo</i>	Sets the requested file information. See the SetInfo() function description.
<i>Flush</i>	Flushes all modified data associated with the file to the device. See the Flush() function description.

Description

The **EFI_FILE_PROTOCOL** provides file IO access to supported file systems.

An **EFI_FILE_PROTOCOL** provides access to a file's or directory's contents, and is also a reference to a location in the directory tree of the file system in which the file resides. With any given file handle, other files may be opened relative to this file's location, yielding new file handles.

On requesting the file system protocol on a device, the caller gets the **EFI_FILE_PROTOCOL** to the volume. This interface is used to open the root directory of the file system when needed. The caller must [Close\(\)](#) the file handle to the root directory, and any other opened file handles before exiting. While there are open files on the device, usage of underlying device protocol(s) that the file system is abstracting must be avoided. For example, when a file system that is layered on a [EFI_DISK_IO_PROTOCOL](#)/[EFI_BLOCK_IO_PROTOCOL](#), direct block access to the device for the blocks that comprise the file system must be avoided while there are open file handles to the same device.

A file system driver may cache data relating to an open file. A **Flush()** function is provided that flushes all dirty data in the file system, relative to the requested file, to the physical medium. If the underlying device may cache data, the file system must inform the device to flush as well.

EFI_FILE_PROTOCOL.Open()

Summary

Opens a new file relative to the source file's location.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_OPEN) (
    IN EFI_FILE_PROTOCOL    *This,
    OUT EFI_FILE_PROTOCOL  **NewHandle,
    IN CHAR16               *FileName,
    IN UINT64               OpenMode,
    IN UINT64               Attributes
);
```

Parameters

<i>This</i>	A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to the source location. This would typically be an open handle to a directory. See the type EFI_FILE_PROTOCOL description.
<i>NewHandle</i>	A pointer to the location to return the opened handle for the new file. See the type EFI_FILE_PROTOCOL description.
<i>FileName</i>	The Null-terminated string of the name of the file to be opened. The file name may contain the following path modifiers: “\”, “.”, and “..”.
<i>OpenMode</i>	The mode to open the file. The only valid combinations that the file may be opened with are: Read, Read/Write, or Create/Read/Write. See “Related Definitions” below.
<i>Attributes</i>	Only valid for EFI_FILE_MODE_CREATE , in which case these are the attribute bits for the newly created file. See “Related Definitions” below.

Related Definitions

```

//*****
// Open Modes
//*****
#define EFI_FILE_MODE_READ          0x0000000000000001
#define EFI_FILE_MODE_WRITE        0x0000000000000002
#define EFI_FILE_MODE_CREATE       0x8000000000000000

//*****
// File Attributes
//*****
#define EFI_FILE_READ_ONLY          0x0000000000000001
#define EFI_FILE_HIDDEN             0x0000000000000002
```

```
#define EFI_FILE_SYSTEM           0x0000000000000004
#define EFI_FILE_RESERVED       0x0000000000000008
#define EFI_FILE_DIRECTORY     0x0000000000000010
#define EFI_FILE_ARCHIVE       0x0000000000000020
#define EFI_FILE_VALID_ATTR    0x0000000000000037
```

Description

The **Open ()** function opens the file or directory referred to by *FileName* relative to the location of *This* and returns a *NewHandle*. The *FileName* may include the following path modifiers:

- “\” If the filename starts with a “\” the relative location is the root directory that *This* resides on; otherwise “\” separates name components. Each name component is opened in turn, and the handle to the last file opened is returned.
- “.” Opens the current location.
- “..” Opens the parent directory for the current location. If the location is the root directory the request will return an error, as there is no parent directory for the root directory.

If **EFI_FILE_MODE_CREATE** is set, then the file is created in the directory. If the final location of *FileName* does not refer to a directory, then the operation fails. If the file does not exist in the directory, then a new file is created. If the file already exists in the directory, then the existing file is opened.

If the medium of the device changes, all accesses (including the File handle) will result in **EFI_MEDIA_CHANGED**. To access the new medium, the volume must be reopened.

Status Codes Returned

EFI_SUCCESS	The file was opened.
EFI_NOT_FOUND	The specified file could not be found on the device.
EFI_NO_MEDIA	The device has no medium.
EFI_MEDIA_CHANGED	The device has a different medium in it or the medium is no longer supported.
EFI_DEVICE_ERROR	The device reported an error.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.
EFI_WRITE_PROTECTED	An attempt was made to create a file, or open a file for write when the media is write-protected.
EFI_ACCESS_DENIED	The service denied access to the file.
EFI_OUT_OF_RESOURCES	Not enough resources were available to open the file.
EFI_VOLUME_FULL	The volume is full.

EFI_FILE_PROTOCOL.Close()

Summary

Closes a specified file handle.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_CLOSE) (
    IN EFI_FILE_PROTOCOL  *This
);
```

Parameters

This

A pointer to the [EFI_FILE_PROTOCOL](#) instance that is the file handle to close. See the type [EFI_FILE_PROTOCOL](#) description.

Description

The **Close()** function closes a specified file handle. All “dirty” cached file data is flushed to the device, and the file is closed. *In all cases the handle is closed.*

Status Codes Returned

EFI_SUCCESS	The file was closed.
-------------	----------------------

EFI_FILE_PROTOCOL.Delete()

Summary

Closes and deletes a file.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_DELETE) (
    IN EFI_FILE_PROTOCOL  *This
);
```

Parameters

This

A pointer to the [EFI_FILE_PROTOCOL](#) instance that is the handle to the file to delete. See the type [EFI_FILE_PROTOCOL](#) description.

Description

The **Delete()** function closes and deletes a file. *In all cases the file handle is closed.* If the file cannot be deleted, the warning code **EFI_WARN_DELETE_FAILURE** is returned, but the handle is still closed.

Status Codes Returned

EFI_SUCCESS	The file was closed and deleted, and the handle was closed.
EFI_WARN_DELETE_FAILURE	The handle was closed, but the file was not deleted.

EFI_FILE_PROTOCOL.Read()

Summary

Reads data from a file.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_READ) (
    IN EFI_FILE_PROTOCOL *This,
    IN OUT UINTN         *BufferSize,
    OUT VOID             *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to read data from. See the type EFI_FILE_PROTOCOL description.
<i>BufferSize</i>	On input, the size of the <i>Buffer</i> . On output, the amount of data returned in <i>Buffer</i> . In both cases, the size is measured in bytes.
<i>Buffer</i>	The buffer into which the data is read.

Description

The **Read()** function reads data from a file.

If *This* is not a directory, the function reads the requested number of bytes from the file at the file's current position and returns them in *Buffer*. If the read goes beyond the end of the file, the read length is truncated to the end of the file. The file's current position is increased by the number of bytes returned.

If *This* is a directory, the function reads the directory entry at the file's current position and returns the entry in *Buffer*. If the *Buffer* is not large enough to hold the current directory entry, then **EFI_BUFFER_TOO_SMALL** is returned and the current file position is *not* updated. *BufferSize* is set to be the size of the buffer needed to read the entry. On success, the current position is updated to the next directory entry. If there are no more directory entries, the read returns a zero-length buffer. [EFI_FILE_INFO](#) is the structure returned as the directory entry.

Status Codes Returned

EFI_SUCCESS	The data was read.
EFI_NO_MEDIA	The device has no medium.
EFI_DEVICE_ERROR	The device reported an error.
EFI_DEVICE_ERROR	An attempt was made to read from a deleted file.
EFI_DEVICE_ERROR	On entry, the current file position is beyond the end of the file.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.

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EFI_BUFFER_TOO_SMALL	The <i>BufferSize</i> is too small to read the current directory entry. <i>BufferSize</i> has been updated with the size needed to complete the request.
----------------------	--

EFI_FILE_PROTOCOL.Write()

Summary

Writes data to a file.

```

EFI_STATUS
(EFI_API *EFI_FILE_WRITE) (
    IN EFI_FILE_PROTOCOL  *This,
    IN OUT UINTN          *BufferSize,
    IN VOID                *Buffer
);
    
```

Parameters

<i>This</i>	A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to write data to. See the type EFI_FILE_PROTOCOL description.
<i>BufferSize</i>	On input, the size of the <i>Buffer</i> . On output, the amount of data actually written. In both cases, the size is measured in bytes.
<i>Buffer</i>	The buffer of data to write.

Description

The **Write()** function writes the specified number of bytes to the file at the current file position. The current file position is advanced the actual number of bytes written, which is returned in *BufferSize*. Partial writes only occur when there has been a data error during the write attempt (such as “file space full”). The file is automatically grown to hold the data if required.

Direct writes to opened directories are not supported.

Status Codes Returned

EFI_SUCCESS	The data was written.
EFI_UNSUPPORTED	Writes to open directory files are not supported.
EFI_NO_MEDIA	The device has no medium.
EFI_DEVICE_ERROR	The device reported an error.
EFI_DEVICE_ERROR	An attempt was made to write to a deleted file.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.
EFI_WRITE_PROTECTED	The file or medium is write-protected.
EFI_ACCESS_DENIED	The file was opened read only.
EFI_VOLUME_FULL	The volume is full.

EFI_FILE_PROTOCOL.SetPosition()

Summary

Sets a file's current position.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_SET_POSITION) (
    IN EFI_FILE_PROTOCOL *This,
    IN UINT64             Position
);
```

Parameters

<i>This</i>	A pointer to the EFI_FILE_PROTOCOL instance that is the handle to set the requested position on. See the type EFI_FILE_PROTOCOL description.
<i>Position</i>	The byte position from the start of the file to set.

Description

The **SetPosition()** function sets the current file position for the handle to the position supplied. With the exception of seeking to position 0xFFFFFFFFFFFFFFFF, only absolute positioning is supported, and seeking past the end of the file is allowed (a subsequent write would grow the file). Seeking to position 0xFFFFFFFFFFFFFFFF causes the current position to be set to the end of the file.

If *This* is a directory, the only position that may be set is zero. This has the effect of starting the read process of the directory entries over.

Status Codes Returned

EFI_SUCCESS	The position was set.
EFI_UNSUPPORTED	The seek request for nonzero is not valid on open directories.
EFI_DEVICE_ERROR	An attempt was made to set the position of a deleted file.

EFI_FILE_PROTOCOL.GetPosition()

Summary

Returns a file's current position.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_GET_POSITION) (
    IN EFI_FILE_PROTOCOL  *This,
    OUT UINT64             *Position
);
```

Parameters

This

A pointer to the [EFI_FILE_PROTOCOL](#) instance that is the file handle to get the current position on. See the type [EFI_FILE_PROTOCOL](#) description.

Position

The address to return the file's current position value.

Description

The **GetPosition()** function returns the current file position for the file handle. For directories, the current file position has no meaning outside of the file system driver and as such the operation is not supported. An error is returned if *This* is a directory.

Status Codes Returned

EFI_SUCCESS	The position was returned.
EFI_UNSUPPORTED	The request is not valid on open directories.
EFI_DEVICE_ERROR	An attempt was made to get the position from a deleted file.

EFI_FILE_PROTOCOL.GetInfo()

Summary

Returns information about a file.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_GET_INFO) (
    IN EFI_FILE_PROTOCOL *This,
    IN EFI_GUID           *InformationType,
    IN OUT UINTN          *BufferSize,
    OUT VOID              *Buffer
);
```

Parameters

- This* A pointer to the [EFI_FILE_PROTOCOL](#) instance that is the file handle the requested information is for. See the type [EFI_FILE_PROTOCOL](#) description.
- InformationType* The type identifier for the information being requested. Type [EFI_GUID](#) is defined in [Section 6.3.1](#). See the [EFI_FILE_INFO](#) and [EFI_FILE_SYSTEM_INFO](#) descriptions for the related GUID definitions.
- BufferSize* On input, the size of *Buffer*. On output, the amount of data returned in *Buffer*. In both cases, the size is measured in bytes.
- Buffer* A pointer to the data buffer to return. The buffer's type is indicated by *InformationType*.

Description

The **GetInfo()** function returns information of type *InformationType* for the requested file. If the file does not support the requested information type, then **EFI_UNSUPPORTED** is returned. If the buffer is not large enough to fit the requested structure, **EFI_BUFFER_TOO_SMALL** is returned and the *BufferSize* is set to the size of buffer that is required to make the request.

The information types defined by this specification are required information types that all file systems must support.

Status Codes Returned

EFI_SUCCESS	The information was set.
EFI_UNSUPPORTED	The <i>InformationType</i> is not known.
EFI_NO_MEDIA	The device has no medium.
EFI_DEVICE_ERROR	The device reported an error.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.

EFI_BUFFER_TOO_SMALL	The <i>BufferSize</i> is too small to read the current directory entry. <i>BufferSize</i> has been updated with the size needed to complete the request.
----------------------	--

EFI_FILE_PROTOCOL.SetInfo()

Summary

Sets information about a file.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_SET_INFO) (
    IN EFI_FILE_PROTOCOL *This,
    IN EFI_GUID           *InformationType,
    IN UINTN              BufferSize,
    IN VOID               *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_FILE_PROTOCOL instance that is the file handle the information is for. See the type EFI_FILE_PROTOCOL description.
<i>InformationType</i>	The type identifier for the information being set. Type EFI_GUID is defined in Section 6.3.1 . See the EFI_FILE_INFO and EFI_FILE_SYSTEM_INFO descriptions in this section for the related GUID definitions.
<i>BufferSize</i>	The size, in bytes, of <i>Buffer</i> .
<i>Buffer</i>	A pointer to the data buffer to write. The buffer's type is indicated by <i>InformationType</i> .

Description

The **SetInfo()** function sets information of type *InformationType* on the requested file. Because a read-only file can be opened only in read-only mode, an *InformationType* of [EFI_FILE_INFO_ID](#) can be used with a read-only file because this method is the only one that can be used to convert a read-only file to a read-write file. In this circumstance, only the *Attribute* field of the [EFI_FILE_INFO](#) structure may be modified. One or more calls to **SetInfo()** to change the *Attribute* field are permitted before it is closed. The file attributes will be valid the next time the file is opened with **Open()**.

An *InformationType* of [EFI_FILE_SYSTEM_INFO_ID](#) or [EFI_FILE_SYSTEM_VOLUME_LABEL_ID](#) may not be used on read-only media.

Status Codes Returned

EFI_SUCCESS	The information was set.
EFI_UNSUPPORTED	The <i>InformationType</i> is not known.
EFI_NO_MEDIA	The device has no medium.
EFI_DEVICE_ERROR	The device reported an error.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.

EFI_WRITE_PROTECTED	<i>InformationType</i> is EFI_FILE_INFO_ID and the media is read-only.
EFI_WRITE_PROTECTED	<i>InformationType</i> is EFI_FILE_PROTOCOL_SYSTEM_INFO_ID and the media is read only.
EFI_WRITE_PROTECTED	<i>InformationType</i> is EFI_FILE_SYSTEM_VOLUME_LABEL_ID and the media is read-only.
EFI_ACCESS_DENIED	An attempt is made to change the name of a file to a file that is already present.
EFI_ACCESS_DENIED	An attempt is being made to change the EFI_FILE_DIRECTORY Attribute .
EFI_ACCESS_DENIED	An attempt is being made to change the size of a directory.
EFI_ACCESS_DENIED	<i>InformationType</i> is EFI_FILE_INFO_ID and the file was opened read-only and an attempt is being made to modify a field other than <i>Attribute</i> .
EFI_VOLUME_FULL	The volume is full.
EFI_BAD_BUFFER_SIZE	<i>BufferSize</i> is smaller than the size of the type indicated by <i>InformationType</i> .

EFI_FILE_PROTOCOL.Flush()

Summary

Flushes all modified data associated with a file to a device.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_FILE_FLUSH) (
    IN EFI_FILE_PROTOCOL  *This
);
```

Parameters

This A pointer to the [EFI_FILE_PROTOCOL](#) instance that is the file handle to flush. See the type [EFI_FILE_PROTOCOL](#) description.

Description

The **Flush()** function flushes all modified data associated with a file to a device.

Status Codes Returned

EFI_SUCCESS	The data was flushed.
EFI_NO_MEDIA	The device has no medium.
EFI_DEVICE_ERROR	The device reported an error.
EFI_VOLUME_CORRUPTED	The file system structures are corrupted.
EFI_WRITE_PROTECTED	The file or medium is write-protected.
EFI_ACCESS_DENIED	The file was opened read-only.
EFI_VOLUME_FULL	The volume is full.

EFI_FILE_INFO

Summary

Provides a GUID and a data structure that can be used with [EFI_FILE_PROTOCOL.SetInfo\(\)](#) and [EFI_FILE_PROTOCOL.GetInfo\(\)](#) to set or get generic file information.

GUID

```
#define EFI_FILE_INFO_ID \
{0x09576e92, 0x6d3f, 0x11d2, 0x8e39, 0x00, 0xa0, 0xc9, 0x69, 0x72, 0x3b}
```

Related Definitions

```
typedef struct {
    UINT64      Size;
    UINT64      FileSize;
```

```

    UINT64      PhysicalSize;
    EFI_TIME    CreateTime;
    EFI_TIME    LastAccessTime;
    EFI_TIME    ModificationTime;
    UINT64      Attribute;
    CHAR16      FileName[];
} EFI_FILE_INFO;

//*****
// File Attribute Bits
//*****

#define EFI_FILE_READ_ONLY      0x0000000000000001
#define EFI_FILE_HIDDEN        0x0000000000000002
#define EFI_FILE_SYSTEM        0x0000000000000004
#define EFI_FILE_RESERVED      0x0000000000000008
#define EFI_FILE_DIRECTORY     0x0000000000000010
#define EFI_FILE_ARCHIVE       0x0000000000000020
#define EFI_FILE_VALID_ATTR    0x0000000000000037

```

Parameters

<i>Size</i>	Size of the EFI_FILE_INFO structure, including the Null-terminated Unicode <i>FileName</i> string.
<i>FileSize</i>	The size of the file in bytes.
<i>PhysicalSize</i>	The amount of physical space the file consumes on the file system volume.
<i>CreateTime</i>	The time the file was created.
<i>LastAccessTime</i>	The time when the file was last accessed.
<i>ModificationTime</i>	The time when the file's contents were last modified.
<i>Attribute</i>	The attribute bits for the file. See "Related Definitions" above.
<i>FileName</i>	The Null-terminated Unicode name of the file.

Description

The **EFI_FILE_INFO** data structure supports [GetInfo\(\)](#) and [SetInfo\(\)](#) requests. In the case of **SetInfo()**, the following additional rules apply:

- On directories, the file size is determined by the contents of the directory and cannot be changed by setting *FileSize*. On directories, *FileSize* is ignored during a **SetInfo()**.
- The *PhysicalSize* is determined by the *FileSize* and cannot be changed. This value is ignored during a **SetInfo()** request.
- The **EFI_FILE_DIRECTORY** attribute bit cannot be changed. It must match the file's actual type.
- A value of zero in *CreateTime*, *LastAccess*, or *ModificationTime* causes the fields to be ignored (and not updated).

EFI_FILE_SYSTEM_INFO

Summary

Provides a GUID and a data structure that can be used with [EFI_FILE_PROTOCOL.GetInfo\(\)](#) to get information about the system volume, and [EFI_FILE_PROTOCOL.SetInfo\(\)](#) to set the system volume's volume label.

GUID

```
#define EFI_FILE_SYSTEM_INFO_ID \
{0x09576e93, 0x6d3f, 0x11d2, 0x8e39, 0x00, 0xa0, 0xc9, 0x69, 0x72, \
0x3b}
```

Related Definitions

```
typedef struct {
    UINT64      Size;
    BOOLEAN     ReadOnly;
    UINT64      VolumeSize;
    UINT64      FreeSpace;
    UINT32      BlockSize;
    CHAR16      VolumeLabel[];
} EFI_FILE_SYSTEM_INFO;
```

Parameters

<i>Size</i>	Size of the EFI_FILE_SYSTEM_INFO structure, including the Null-terminated Unicode <i>VolumeLabel</i> string.
<i>ReadOnly</i>	TRUE if the volume only supports read access.
<i>VolumeSize</i>	The number of bytes managed by the file system.
<i>FreeSpace</i>	The number of available bytes for use by the file system.
<i>BlockSize</i>	The nominal block size by which files are typically grown.
<i>VolumeLabel</i>	The Null-terminated string that is the volume's label.

Description

The **EFI_FILE_SYSTEM_INFO** data structure is an information structure that can be obtained on the root directory file handle. The root directory file handle is the file handle first obtained on the initial call to the [HandleProtocol\(\)](#) function to open the file system interface. All of the fields are read-only except for *VolumeLabel*. The system volume's *VolumeLabel* can be created or modified by calling **EFI_FILE_PROTOCOL.SetInfo()** with an updated *VolumeLabel* field.

EFI_FILE_SYSTEM_VOLUME_LABEL

Summary

Provides a GUID and a data structure that can be used with [EFI_FILE_PROTOCOL.GetInfo\(\)](#) or [EFI_FILE_PROTOCOL.SetInfo\(\)](#) to get or set information about the system's volume label.

GUID

```
#define EFI_FILE_SYSTEM_VOLUME_LABEL_ID \
  {0xDB47D7D3, 0xFE81, 0x11d3, 0x9A35, 0x00, 0x90, 0x27, 0x3F, 0xC1, 0x4D}
```

Related Definitions

```
typedef struct {
  CHAR16  VolumeLabel[];
} EFI_FILE_SYSTEM_VOLUME_LABEL;
```

Parameters

VolumeLabel The Null-terminated string that is the volume's label.

Description

The **EFI_FILE_SYSTEM_VOLUME_LABEL** data structure is an information structure that can be obtained on the root directory file handle. The root directory file handle is the file handle first obtained on the initial call to the [HandleProtocol\(\)](#) function to open the file system interface. The system volume's *VolumeLabel* can be created or modified by calling **EFI_FILE_PROTOCOL.SetInfo()** with an updated *VolumeLabel* field.

12.5 Tape Boot Support

12.5.1 Tape I/O Support

This section defines the Tape I/O Protocol and standard tape header format. These enable the support of booting from tape on UEFI systems.. This protocol is used to abstract the tape drive operations to support applications written to this specification.

Mission-critical server systems provide reliability and availability. Traditional RISC servers have long supported native tape boot to perform system recovery tasks. Industry standard servers have not traditionally provided native tape boot support. Some workarounds have been provided, e.g., One-button Disaster Recovery (which makes a tape drive appear as a CD device after a special start-up sequence; Dual Media support where one boots from CD but recovers from tape; Hard Drive used for back-up; DVD±RW for backup.

These alternatives have not satisfied customers. They want to migrate native tape boot support to industry standard servers because most of them do not staff the technical expertise to perform the human intervention involved, or, they do not perceive the media as reliable or having enough capacity.

As a result, high-profile customers base their purchases on the promise of the native tape boot support.

After considering the existing Disk IO Protocol, GPT Disk and File System IO Protocol supporting the hard disk boot, it was decided that the best approach to support the tape boot is to define a new Tape IO protocol and a standard tape header format to enable tape-based OS bootloaders to be run using the EFI Load File Protocol.

12.5.2 Tape I/O Protocol

This section defines the Tape I/O Protocol and its functions. This protocol is used to abstract the tape drive operations to support applications written to this specification.

EFI_TAPE_IO_PROTOCOL

Summary

The EFI_TAPE_IO protocol provides services to control and access a tape device.

GUID

```
#define EFI_TAPE_IO_PROTOCOL_GUID \
  {0x1e93e633, 0xd65a, 0x459e, 0xab, 0x84, 0x93, 0xd9, 0xec, 0x26, \
   0x6d, 0x18}
```

Protocol Interface Structure

```
typedef struct _EFI_TAPE_IO_PROTOCOL {
    EFI_TAPE_READ      TapeRead;
    EFI_TAPE_WRITE     TapeWrite;
    EFI_TAPE_REWIND    TapeRewind;
    EFI_TAPE_SPACE     TapeSpace;
    EFI_TAPE_WRITEFM   TapeWriteFM;
    EFI_TAPE_RESET     TapeReset;
} EFI_TAPE_IO_PROTOCOL;
```

Parameters

<i>TapeRead</i>	Read a block of data from the tape. See the TapeRead() description.
<i>TapeWrite</i>	Write a block of data to the tape. See the TapeWrite() description.
<i>TapeRewind</i>	Rewind the tape. See the TapeRewind() description.
<i>TapeSpace</i>	Position the tape. See the TapeSpace() description.
<i>TapeWriteFM</i>	Write filemarks to the tape. See the TapeWriteFM() description.
<i>TapeReset</i>	Reset the tape device or its parent bus. See the TapeReset() description.

Description

The **EFI_TAPE_IO_PROTOCOL** provides basic sequential operations for tape devices. These include read, write, rewind, space, write filemarks and reset functions. Per this specification, a boot application uses the services of this protocol to load the bootloader image from tape.

No provision is made for controlling or determining media density or compression settings. The protocol relies on devices to behave normally and select settings appropriate for the media loaded.

No support is included for tape partition support, setmarks or other tapemarks such as End of Data. Boot tapes are expected to use normal variable or fixed block size formatting and filemarks.

EFI_TAPE_IO_PROTOCOL.TapeRead()

Summary

Reads from the tape.

Prototype

```

Typedef EFI_STATUS
(EFIAPI *EFI_TAPE_READ) (
    IN EFI_TAPE_IO_PROTOCOL      *This,
    IN OUT UINTN                *BufferSize,
    OUT VOID                      *Buffer
);

```

Parameters

<i>This</i>	A pointer to the EFI_TAPE_IO_PROTOCOL instance.
<i>BufferSize</i>	Size of the buffer in bytes pointed to by <i>Buffer</i> .
<i>Buffer</i>	Pointer to the buffer for data to be read into.

Description

This function will read up to *BufferSize* bytes from media into the buffer pointed to by *Buffer* using an implementation-specific timeout. *BufferSize* will be updated with the number of bytes transferred.

Each read operation for a device that operates in variable block size mode reads one media data block. Unread bytes which do not fit in the buffer will be skipped by the next read operation. The number of bytes transferred will be limited by the actual media block size. Best practice is for the buffer size to match the media data block size. When a filemark is encountered in variable block size mode the read operation will indicate that 0 bytes were transferred and the function will return an **EFI_END_OF_FILE** error condition.

In fixed block mode the buffer is expected to be a multiple of the data block size. Each read operation for a device that operates in fixed block size mode may read multiple media data blocks. The number of bytes transferred will be limited to an integral number of complete media data blocks. *BufferSize* should be evenly divisible by the device's fixed block size. When a filemark is encountered in fixed block size mode the read operation will indicate that the number of bytes transferred is less than the number of blocks that would fit in the provided buffer (possibly 0 bytes transferred) and the function will return an **EFI_END_OF_FILE** error condition.

Two consecutive filemarks are normally used to indicate the end of the last file on the media.

The value specified for *BufferSize* should correspond to the actual block size used on the media. If necessary, the value for *BufferSize* may be larger than the actual media block size.

Specifying a *BufferSize* of 0 is valid but requests the function to provide read-related status information instead of actual media data transfer. No data will be attempted to be read from the device however this operation is classified as an access for status handling. The status code returned may be used to determine if a filemark has been encountered by the last read request with a non-zero size, and to determine if media is loaded and the device is ready for reading. A **NULL** value for *Buffer* is valid when *BufferSize* is zero.

Status Codes Returned

EFI_SUCCESS	Data was successfully transferred from the media.
EFI_END_OF_FILE	A filemark was encountered which limited the data transferred by the read operation or the head is positioned just after a filemark.
EFI_NO_MEDIA	No media is loaded in the device.
EFI_MEDIA_CHANGED	The media in the device was changed since the last access. The transfer was aborted since the current position of the media may be incorrect.
EFI_DEVICE_ERROR	A device error occurred while attempting to transfer data from the media.
EFI_INVALID_PARAMETER	A NULL <i>Buffer</i> was specified with a non-zero <i>BufferSize</i> or the device is operating in fixed block size mode and the <i>BufferSize</i> was not a multiple of device's fixed block size
EFI_NOT_READY	The transfer failed since the device was not ready (e.g. not online). The transfer may be retried at a later time.
EFI_UNSUPPORTED	The device does not support this type of transfer.
EFI_TIMEOUT	The transfer failed to complete within the timeout specified.

EFI_TAPE_IO_PROTOCOL.TapeWrite()

Summary

Write to the tape.

Prototype

```

Typedef EFI_STATUS
(EFIAPI *EFI_TAPE_WRITE) (
    IN EFI_TAPE_IO_PROTOCOL *This,
    IN UINTN *BufferSize,
    IN VOID *Buffer
);
    
```

Parameters

This A pointer to the **EFI_TAPE_IO_PROTOCOL** instance.

BufferSize Size of the buffer in bytes pointed to by *Buffer*.

Buffer Pointer to the buffer for data to be written from.

Description

This function will write *BufferSize* bytes from the buffer pointed to by *Buffer* to media using an implementation-specific timeout.

Each write operation for a device that operates in variable block size mode writes one media data block of *BufferSize* bytes.

Each write operation for a device that operates in fixed block size mode writes one or more media data blocks of the device's fixed block size. *BufferSize* must be evenly divisible by the device's fixed block size.

Although sequential devices in variable block size mode support a wide variety of block sizes, many issues may be avoided in I/O software, adapters, hardware and firmware if common block sizes are used such as: 32768, 16384, 8192, 4096, 2048, 1024, 512, and 80.

BufferSize will be updated with the number of bytes transferred.

When a write operation occurs beyond the logical end of media an **EFI_END_OF_MEDIA** error condition will occur. Normally data will be successfully written and *BufferSize* will be updated with the number of bytes transferred. Additional write operations will continue to fail in the same manner. Excessive writing beyond the logical end of media should be avoided since the physical end of media may be reached.

Specifying a *BufferSize* of 0 is valid but requests the function to provide write-related status information instead of actual media data transfer. No data will be attempted to be written to the device however this operation is classified as an access for status handling. The status code returned may be used to determine if media is loaded, writable and if the logical end of media point has been reached. A **NULL** value for *Buffer* is valid when *BufferSize* is zero.

Status Codes Returned

EFI_SUCCESS	Data was successfully transferred to the media.
-------------	---

EFI_END_OF_MEDIA	The logical end of media has been reached. Data may have been successfully transferred to the media.
EFI_NO_MEDIA	No media is loaded in the device.
EFI_MEDIA_CHANGED	The media in the device was changed since the last access. The transfer was aborted since the current position of the media may be incorrect.
EFI_WRITE_PROTECTED	The media in the device is write-protected. The transfer was aborted since a write cannot be completed.
EFI_DEVICE_ERROR	A device error occurred while attempting to transfer data from the media.
EFI_INVALID_PARAMETER	A NULL Buffer was specified with a non-zero <i>BufferSize</i> or the device is operating in fixed block size mode and <i>BufferSize</i> was not a multiple of device's fixed block size.
EFI_NOT_READY	The transfer failed since the device was not ready (e.g. not online). The transfer may be retried at a later time.
EFI_UNSUPPORTED	The device does not support this type of transfer.
EFI_TIMEOUT	The transfer failed to complete within the timeout specified.

EFI_TAPE_IO_PROTOCOL.TapeRewind()

Summary

Rewinds the tape.

Prototype

```

Typedef EFI_STATUS
(EFIAPI *EFI_TAPE_REWIND) (
    IN EFI_TAPE_IO_PROTOCOL    *This,
);

```

Parameters

This A pointer to the **EFI_TAPE_IO_PROTOCOL** instance.

Description

This function will rewind the media using an implementation-specific timeout. The function will check if the media was changed since the last access and reinstall the **EFI_TAPE_IO_PROTOCOL** interface for the device handle if needed.

Status Codes Returned

EFI_SUCCESS	The media was successfully repositioned.
EFI_NO_MEDIA	No media is loaded in the device.
EFI_DEVICE_ERROR	A device error occurred while attempting to reposition the media.
EFI_NOT_READY	Repositioning the media failed since the device was not ready (e.g. not online). The transfer may be retried at a later time.
EFI_UNSUPPORTED	The device does not support this type of media repositioning.
EFI_TIMEOUT	Repositioning of the media did not complete within the timeout specified.

EFI_TAPE_IO_PROTOCOL.TapeSpace()

Summary

Positions the tape.

Prototype

```

Typedef EFI_STATUS
(EFIAPI *EFI_TAPE_SPACE) (
    IN EFI_TAPE_IO_PROTOCOL    *This,
    INTN                       Direction,
    UINTN                      Type
);
    
```

Parameters

<i>This</i>	A pointer to the EFI_TAPE_IO_PROTOCOL instance.
<i>Direction</i>	Direction and number of data blocks or filemarks to space over on media.
<i>Type</i>	Type of mark to space over on media.

Description

This function will position the media using an implementation-specific timeout.

A positive *Direction* value will indicate the number of data blocks or filemarks to forward space the media. A negative *Direction* value will indicate the number of data blocks or filemarks to reverse space the media.

The following *Type* marks are mandatory:

Type of Tape Mark	MarkType
BLOCK	0
FILEMARK	1

Space operations position the media past the data block or filemark. Forward space operations leave media positioned with the tape device head after the data block or filemark. Reverse space operations leave the media positioned with the tape device head before the data block or filemark.

If beginning of media is reached before a reverse space operation passes the requested number of data blocks or filemarks an **EFI_END_OF_MEDIA** error condition will occur. If end of recorded data or end of physical media is reached before a forward space operation passes the requested number of data blocks or filemarks an **EFI_END_OF_MEDIA** error condition will occur. An **EFI_END_OF_MEDIA** error condition will not occur due to spacing over data blocks or filemarks past the logical end of media point used to indicate when write operations should be limited.

Status Codes Returned

EFI_SUCCESS	The media was successfully repositioned.
-------------	--

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EFI_END_OF_MEDIA	Beginning or end of media was reached before the indicated number of data blocks or filemarks were found.
EFI_NO_MEDIA	No media is loaded in the device.
EFI_MEDIA_CHANGED	The media in the device was changed since the last access. Repositioning the media was aborted since the current position of the media may be incorrect.
EFI_DEVICE_ERROR	A device error occurred while attempting to reposition the media.
EFI_NOT_READY	Repositioning the media failed since the device was not ready (e.g. not online). The transfer may be retried at a later time.
EFI_UNSUPPORTED	The device does not support this type of media repositioning.
EFI_TIMEOUT	Repositioning of the media did not complete within the timeout specified.

EFI_TAPE_IO_PROTOCOL.TapeWriteFM()

Summary

Writes filemarks to the media.

Prototype

```

Typedef EFI_STATUS
(EFIAPI *EFI_TAPE_WRITEFM) (
    IN EFI_TAPE_IO_PROTOCOL  *This,
    IN UINTN                  Count
);
    
```

Parameters

This A pointer to the **EFI_TAPE_IO_PROTOCOL** instance.

Count Number of filemarks to write to the media.

Description

This function will write filemarks to the tape using an implementation-specific timeout. Writing filemarks beyond logical end of tape does not result in an error condition unless physical end of media is reached.

Status Codes Returned

EFI_SUCCESS	Data was successfully transferred from the media.
EFI_NO_MEDIA	No media is loaded in the device.
EFI_MEDIA_CHANGED	The media in the device was changed since the last access. The transfer was aborted since the current position of the media may be incorrect.
EFI_DEVICE_ERROR	A device error occurred while attempting to transfer data from the media.
EFI_NOT_READY	The transfer failed since the device was not ready (e.g. not online). The transfer may be retried at a later time.
EFI_UNSUPPORTED	The device does not support this type of transfer.
EFI_TIMEOUT	The transfer failed to complete within the timeout specified.

EFI_TAPE_IO_PROTOCOL.TapeReset()

Summary

Resets the tape device.

Prototype

```

Typedef EFI_STATUS
(EFI_API *EFI_TAPE_RESET) (
    IN EFI_TAPE_IO_PROTOCOL       *This,
    IN BOOLEAN                   ExtendedVerification
);
  
```

Parameters

This A pointer to the **EFI_TAPE_IO_PROTOCOL** instance.

ExtendedVerification Indicates whether the parent bus should also be reset.

Description

This function will reset the tape device. If *ExtendedVerification* is set to true, the function will reset the parent bus (e.g., SCSI bus). The function will check if the media was changed since the last access and reinstall the **EFI_TAPE_IO_PROTOCOL** interface for the device handle if needed. Note media needs to be loaded and device online for the reset, otherwise, **EFI_DEVICE_ERROR** is returned.

Status Codes Returned

EFI_SUCCESS	The bus and/or device were successfully reset.
EFI_NO_MEDIA	No media is loaded in the device.
EFI_DEVICE_ERROR	A device error occurred while attempting to reset the bus and/or device.
EFI_NOT_READY	The reset failed since the device and/or bus was not ready. The reset may be retried at a later time.
EFI_UNSUPPORTED	The device does not support this type of reset.
EFI_TIMEOUT	The reset did not complete within the timeout allowed.

12.5.3 Tape Header Format

The boot tape will contain a Boot Tape Header to indicate it is a valid boot tape. The Boot Tape Header must be located within the first 20 blocks on the tape. The Boot Tape Header must begin on a block boundary and be contained completely within a block. The Boot Tape Header will have the following format:

Table 86. Tape Header Formats

Bytes (Dec)	Value	Purpose
0-7	0x544f4f4220494645	Signature ('EFI BOOT' in ASCII)

Bytes (Dec)	Value	Purpose
8-11	1	Revision
12-15	1024	Tape Header Size in bytes
16-19	calculated	Tape Header CRC
20-35	{ 0x8befa29a, 0x3511, 0x4cf7, { 0xa2, 0xeb, 0x5f, 0xe3, 0x7c, 0x3b, 0xf5, 0x5b } }	EFI Boot Tape GUID (same for all EFI Boot Tapes, like EFI Disk GUID)
36-51	User Defined	EFI Boot Tape Type GUID (bootloader / OS specific, like EFI Partition Type GUID)
52-67	User Defined	EFI Boot Tape Unique GUID (unique for every EFI Boot Tape)
68-71	e.g. 2	File Number of EFI Bootloader relative to the Boot Tape Header (first file immediately after the Boot Tape Header is file number 1, ANSI labels are counted)
72-75	e.g. 0x400	EFI Bootloader Block Size in bytes
76-79	e.g. 0x20000	EFI Bootloader Total Size in bytes
80-119	e.g. HPUX 11.23	OS Version (ASCII)
120-159	e.g. Ignite-UX C.6.2.241	Application Version (ASCII)
160-169	e.g. 1993-02-28	EFI Boot Tape creation date (UTC) (yyyy-mm-dd ASCII)
170-179	e.g. 13:24:55	EFI Boot Tape creation time (UTC) (hh:mm:ss in ASCII)
180-435	e.g. testsys1 (alt e.g. testsys1.xyzcorp.com)	Computer System Name (UTF-8, ref: RFC 2044)
436-555	e.g. Primary Disaster Recovery	Boot Tape Title / Comment (UTF-8, ref: RFC 2044)
556-1023	reserved	

All numeric values will be specified in binary format. Note that all values are specified in Little Endian byte ordering.

The Boot Tape Header can also be represented as the following data structure:

```

struct tape_header {
    UINT64      Signature;
    UINT32      Revision;
    UINT32      BootDescSize;
    UINT32      BootDescCRC;
    EFI_GUID    TapeGUID;
    EFI_GUID    TapeType;
    EFI_GUID    TapeUnique;
    UINT32      BLLocation;
    UINT32      BLBlocksize;
    UINT32      BLFilesize;
    CHAR8       OSVersion[40];
    CHAR8       AppVersion[40];
    CHAR8       CreationDate[10];
    CHAR8       CreationTime[10];
    CHAR8       SystemName[256];    // UTF-8
    CHAR8       TapeTitle[120];    // UTF-8
    CHAR8       pad[468];          // pad to 1024
};

```

12.6 Disk I/O Protocol

This section defines the Disk I/O protocol. This protocol is used to abstract the block accesses of the Block I/O protocol to a more general offset-length protocol. The firmware is responsible for adding this protocol to any Block I/O interface that appears in the system that does not already have a Disk I/O protocol. File systems and other disk access code utilize the Disk I/O protocol.

EFI_DISK_IO_PROTOCOL

Summary

This protocol is used to abstract Block I/O interfaces.

GUID

```

#define EFI_DISK_IO_PROTOCOL_GUID \
{0xCE345171,0xBA0B,0x11d2,0x8e,0x4F,0x00,0xa0,0xc9,0x69,0x72,0x3b}

```

Revision Number

```

#define EFI_DISK_IO_PROTOCOL_REVISION 0x00010000

```

Protocol Interface Structure

```

typedef struct _EFI_DISK_IO_PROTOCOL {
    UINT64      Revision;
    EFI_DISK_READ  ReadDisk;
    EFI_DISK_WRITE WriteDisk;
};

```

```
} EFI_DISK_IO_PROTOCOL;
```

Parameters

<i>Revision</i>	The revision to which the disk I/O interface adheres. All future revisions must be backwards compatible. If a future version is not backwards compatible, it is not the same GUID.
<i>ReadDisk</i>	Reads data from the disk. See the ReadDisk() function description.
<i>WriteDisk</i>	Writes data to the disk. See the WriteDisk() function description.

Description

The **EFI_DISK_IO_PROTOCOL** is used to control block I/O interfaces.

The disk I/O functions allow I/O operations that need not be on the underlying device's block boundaries or alignment requirements. This is done by copying the data to/from internal buffers as needed to provide the proper requests to the block I/O device. Outstanding write buffer data is flushed by using the [FlushBlocks\(\)](#) function of the [EFI_BLOCK_IO_PROTOCOL](#) on the device handle.

The firmware automatically adds an **EFI_DISK_IO_PROTOCOL** interface to any **EFI_BLOCK_IO_PROTOCOL** interface that is produced. It also adds file system, or logical block I/O, interfaces to any [EFI_DISK_IO_PROTOCOL](#) interface that contains any recognized file system or logical block I/O devices. The firmware must automatically support the following required formats:

- The EFI FAT12, FAT16, and FAT32 file system type.
- The legacy master boot record partition block. (The presence of this on any block I/O device is optional, but if it is present the firmware is responsible for allocating a logical device for each partition).
- The extended partition record partition block.
- The El Torito logical block devices.

EFI_DISK_IO_PROTOCOL.ReadDisk()

Summary

Reads a specified number of bytes from a device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DISK_READ) (
    IN EFI_DISK_IO_PROTOCOL *This,
    IN UINT32                MediaId,
    IN UINT64                Offset,
    IN UINTN                 BufferSize,
    OUT VOID                 *Buffer
);
```

Parameters

<i>This</i>	Indicates a pointer to the calling context. Type EFI_DISK_IO_PROTOCOL is defined in the EFI_DISK_IO_PROTOCOL description.
<i>MediaId</i>	ID of the medium to be read.
<i>Offset</i>	The starting byte offset on the logical block I/O device to read from.
<i>BufferSize</i>	The size in bytes of <i>Buffer</i> . The number of bytes to read from the device.
<i>Buffer</i>	A pointer to the destination buffer for the data. The caller is responsible for either having implicit or explicit ownership of the buffer.

Description

The **ReadDisk()** function reads the number of bytes specified by *BufferSize* from the device. All the bytes are read, or an error is returned. If there is no medium in the device, the function returns **EFI_NO_MEDIA**. If the *MediaId* is not the ID of the medium currently in the device, the function returns **EFI_MEDIA_CHANGED**.

Status Codes Returned

EFI_SUCCESS	The data was read correctly from the device.
EFI_DEVICE_ERROR	The device reported an error while performing the read operation.
EFI_NO_MEDIA	There is no medium in the device.
EFI_MEDIA_CHANGED	The <i>MediaId</i> is not for the current medium.
EFI_INVALID_PARAMETER	The read request contains device addresses that are not valid for the device.

EFI_DISK_IO_PROTOCOL.WriteDisk()

Summary

Writes a specified number of bytes to a device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DISK_WRITE) (
    IN EFI_DISK_IO_PROTOCOL *This,
    IN UINT32                MediaId,
    IN UINT64                Offset,
    IN UINTN                 BufferSize,
    IN VOID                  *Buffer
);
```

Parameters

<i>This</i>	Indicates a pointer to the calling context. Type EFI_DISK_IO_PROTOCOL is defined in the EFI_DISK_IO_PROTOCOL protocol description.
<i>MediaId</i>	ID of the medium to be written.
<i>Offset</i>	The starting byte offset on the logical block I/O device to write.
<i>BufferSize</i>	The size in bytes of <i>Buffer</i> . The number of bytes to write to the device.
<i>Buffer</i>	A pointer to the buffer containing the data to be written.

Description

The **WriteDisk()** function writes the number of bytes specified by *BufferSize* to the device. All bytes are written, or an error is returned. If there is no medium in the device, the function returns **EFI_NO_MEDIA**. If the *MediaId* is not the ID of the medium currently in the device, the function returns **EFI_MEDIA_CHANGED**.

Status Codes Returned

EFI_SUCCESS	The data was written correctly to the device.
EFI_WRITE_PROTECTED	The device cannot be written to.
EFI_NO_MEDIA	There is no medium in the device.
EFI_MEDIA_CHANGED	The <i>MediaId</i> is not for the current medium.
EFI_DEVICE_ERROR	The device reported an error while performing the write operation.
EFI_INVALID_PARAMETER	The write request contains device addresses that are not valid for the device.

12.7 Block I/O Protocol

This section defines the Block I/O protocol. This protocol is used to abstract mass storage devices to allow code running in the EFI boot services environment to access them without specific knowledge of the type of device or controller that manages the device. Functions are defined to read and write data at a block level from mass storage devices as well as to manage such devices in the EFI boot services environment.

EFI_BLOCK_IO_PROTOCOL

Summary

This protocol provides control over block devices.

GUID

```
#define EFI_BLOCK_IO_PROTOCOL_GUID \
{0x964e5b21,0x6459,0x11d2,0x8e,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}
```

Revision Number

```
#define EFI_BLOCK_IO_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```
typedef struct _EFI_BLOCK_IO_PROTOCOL {
    UINT64                Revision;
    EFI_BLOCK_IO_MEDIA    *Media;
    EFI_BLOCK_RESET       Reset;
    EFI_BLOCK_READ        ReadBlocks;
    EFI_BLOCK_WRITE       WriteBlocks;
    EFI_BLOCK_FLUSH       FlushBlocks;
} EFI_BLOCK_IO_PROTOCOL;
```

Parameters

<i>Revision</i>	The revision to which the block IO interface adheres. All future revisions must be backwards compatible. If a future version is not back wards compatible it is not the same GUID.
<i>Media</i>	A pointer to the EFI_BLOCK_IO_MEDIA data for this device. Type EFI_BLOCK_IO_MEDIA is defined in “Related Definitions” below.
<i>Reset</i>	Resets the block device hardware. See the Reset() function description.
<i>ReadBlocks</i>	Reads the requested number of blocks from the device. See the ReadBlocks() function description.
<i>WriteBlocks</i>	Writes the requested number of blocks to the device. See the WriteBlocks() function description.

FlushBlocks

Flushes and cache blocks. This function is optional and only needs to be supported on block devices that cache writes. See the [FlushBlocks \(\)](#) function description.

Related Definitions

```

//*****
// EFI_BLOCK_IO_MEDIA
//*****

typedef struct {
    UINT32           MediaId;
    BOOLEAN          RemovableMedia;
    BOOLEAN          MediaPresent;
    BOOLEAN          LogicalPartition;
    BOOLEAN          ReadOnly;
    BOOLEAN          WriteCaching;
    UINT32           BlockSize;
    UINT32           IoAlign;
    EFI_LBA          LastBlock;
} EFI_BLOCK_IO_MEDIA;

//*****
// EFI_LBA
//*****

typedef UINT64      EFI_LBA;

```

The following data values in **EFI_BLOCK_IO_MEDIA** are read-only and are updated by the code that produces the **EFI_BLOCK_IO_PROTOCOL** functions:

<i>MediaId</i>	The current media ID. If the media changes, this value is changed.
<i>RemovableMedia</i>	TRUE if the media is removable; otherwise, FALSE .
<i>MediaPresent</i>	TRUE if there is a media currently present in the device; otherwise, FALSE . This field shows the media present status as of the most recent ReadBlocks () or WriteBlocks () call.
<i>LogicalPartition</i>	TRUE if the EFI_BLOCK_IO_PROTOCOL was produced to abstract partition structures on the disk. FALSE if the BLOCK_IO protocol was produced to abstract the logical blocks on a hardware device.
<i>ReadOnly</i>	TRUE if the media is marked read-only otherwise, FALSE . This field shows the read-only status as of the most recent WriteBlocks () call.
<i>WriteCaching</i>	TRUE if the WriteBlocks () function caches write data.
<i>BlockSize</i>	The intrinsic block size of the device. If the media changes, then this field is updated.

<i>IoAlign</i>	Supplies the alignment requirement for any buffer used in a data transfer. <i>IoAlign</i> values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, <i>IoAlign</i> must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by <i>IoAlign</i> with no remainder.
<i>LastBlock</i>	The last logical block address on the device. If the media changes, then this field is updated.

Description

The *LogicalPartition* is **TRUE** if the device handle is for a partition. For media that have only one partition, the value will always be **TRUE**. For media that have multiple partitions, this value is **FALSE** for the handle that accesses the entire device. The firmware is responsible for adding device handles for each partition on such media.

The firmware is responsible for adding an [EFI DISK IO PROTOCOL](#) interface to every [EFI BLOCK IO PROTOCOL](#) interface in the system. The **EFI_DISK_IO_PROTOCOL** interface allows byte-level access to devices.

EFI_BLOCK_IO_PROTOCOL.Reset()

Summary

Resets the block device hardware.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BLOCK_RESET) (
    IN EFI_BLOCK_IO_PROTOCOL  *This,
    IN BOOLEAN                 ExtendedVerification
);
```

Parameters

This

Indicates a pointer to the calling context. Type **EFI_BLOCK_IO_PROTOCOL** is defined in the [EFI_BLOCK_IO_PROTOCOL](#) description.

ExtendedVerification

Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

The **Reset()** function resets the block device hardware.

As part of the initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the *ExtendedVerification* flag is **TRUE** the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Status Codes Returned

EFI_SUCCESS	The block device was reset.
EFI_DEVICE_ERROR	The block device is not functioning correctly and could not be reset.

EFI_BLOCK_IO_PROTOCOL.ReadBlocks()

Summary

Reads the requested number of blocks from the device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BLOCK_READ) (
    IN EFI_BLOCK_IO_PROTOCOL *This,
    IN UINT32 MediaId,
    IN EFI_LBA LBA,
    IN UINTN BufferSize,
    OUT VOID *Buffer
);
```

Parameters

<i>This</i>	Indicates a pointer to the calling context. Type EFI_BLOCK_IO_PROTOCOL is defined in the EFI_BLOCK_IO_PROTOCOL description.
<i>MediaId</i>	The media ID that the read request is for.
<i>LBA</i>	The starting logical block address to read from on the device. Type EFI_LBA is defined in the EFI_BLOCK_IO_PROTOCOL description.
<i>BufferSize</i>	The size of the <i>Buffer</i> in bytes. This must be a multiple of the intrinsic block size of the device.
<i>Buffer</i>	A pointer to the destination buffer for the data. The caller is responsible for either having implicit or explicit ownership of the buffer.

Description

The **ReadBlocks ()** function reads the requested number of blocks from the device. All the blocks are read, or an error is returned.

If there is no media in the device, the function returns **EFI_NO_MEDIA**. If the *MediaId* is not the ID for the current media in the device, the function returns **EFI_MEDIA_CHANGED**.

Status Codes Returned

EFI_SUCCESS	The data was read correctly from the device.
EFI_DEVICE_ERROR	The device reported an error while attempting to perform the read operation.
EFI_NO_MEDIA	There is no media in the device.
EFI_MEDIA_CHANGED	The <i>MediaId</i> is not for the current media.

EFI_BAD_BUFFER_SIZE	The <i>BufferSize</i> parameter is not a multiple of the intrinsic block size of the device.
EFI_INVALID_PARAMETER	The read request contains LBAs that are not valid, or the buffer is not on proper alignment.

EFI_BLOCK_IO_PROTOCOL.WriteBlocks()

Summary

Writes a specified number of blocks to the device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BLOCK_WRITE) (
    IN EFI_BLOCK_IO_PROTOCOL  *This,
    IN UINT32                  MediaId,
    IN EFI_LBA                 LBA,
    IN UINTN                   BufferSize,
    IN VOID                    *Buffer
);
```

Parameters

<i>This</i>	Indicates a pointer to the calling context. Type is defined in the EFI_BLOCK_IO_PROTOCOL description.
<i>MediaId</i>	The media ID that the write request is for.
<i>LBA</i>	The starting logical block address to be written. The caller is responsible for writing to only legitimate locations. Type EFI_LBA is defined in the EFI_BLOCK_IO_PROTOCOL description.
<i>BufferSize</i>	The size in bytes of <i>Buffer</i> . This must be a multiple of the intrinsic block size of the device.
<i>Buffer</i>	A pointer to the source buffer for the data.

Description

The **WriteBlocks()** function writes the requested number of blocks to the device. All blocks are written, or an error is returned.

If there is no media in the device, the function returns **EFI_NO_MEDIA**. If the *MediaId* is not the ID for the current media in the device, the function returns **EFI_MEDIA_CHANGED**.

Status Codes Returned

EFI_SUCCESS	The data were written correctly to the device.
EFI_WRITE_PROTECTED	The device cannot be written to.
EFI_NO_MEDIA	There is no media in the device.
EFI_MEDIA_CHANGED	The <i>MediaId</i> is not for the current media.
EFI_DEVICE_ERROR	The device reported an error while attempting to perform the write operation.
EFI_BAD_BUFFER_SIZE	The <i>BufferSize</i> parameter is not a multiple of the intrinsic block size of the device.

EFI_INVALID_PARAMETER	The write request contains LBAs that are not valid, or the buffer is not on proper alignment.
-----------------------	---

EFI_BLOCK_IO_PROTOCOL.FlushBlocks()

Summary

Flushes all modified data to a physical block device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BLOCK_FLUSH) (
    IN EFI_BLOCK_IO_PROTOCOL    *This
);
```

Parameters

This Indicates a pointer to the calling context. Type **EFI_BLOCK_IO_PROTOCOL** is defined in the [EFI_BLOCK_IO_PROTOCOL](#) protocol description.

Description

The **FlushBlocks ()** function flushes all modified data to the physical block device. All data written to the device prior to the flush must be physically written before returning **EFI_SUCCESS** from this function. This would include any cached data the driver may have cached, and cached data the device may have cached. A flush may cause a read request following the flush to force a device access.

Status Codes Returned

EFI_SUCCESS	All outstanding data were written correctly to the device.
EFI_DEVICE_ERROR	The device reported an error while attempting to write data.
EFI_NO_MEDIA	There is no media in the device.

12.8 Unicode Collation Protocol

This section defines the Unicode Collation protocol. This protocol is used to allow code running in the boot services environment to perform lexical comparison functions on Unicode strings for given languages.

EFI_UNICODE_COLLATION_PROTOCOL

Summary

Is used to perform case-insensitive comparisons of Unicode strings.

GUID

```
#define EFI_UNICODE_COLLATION_PROTOCOL_GUID \
{0x1d85cd7f,0xf43d,0x11d2,0x9a,0x0c,0x00,0x90,0x27,0x3f,0xc1,0x4d}
```

Protocol Interface Structure

```
typedef struct {
    EFI_UNICODE_COLLATION_STRICOLL           StriColl;
    EFI_UNICODE_COLLATION_METAIMATCH        MetaiMatch;
    EFI_UNICODE_COLLATION_STRLWR            StrLwr;
    EFI_UNICODE_COLLATION_STRUPR           StrUpr;
    EFI_UNICODE_COLLATION_FATTOSTR          FatToStr;
    EFI_UNICODE_COLLATION_STRTOFAT          StrToFat;
    CHAR8                                     *SupportedLanguages;
} EFI_UNICODE_COLLATION_PROTOCOL;
```

Parameters

<i>StriColl</i>	Performs a case-insensitive comparison of two Null-terminated Unicode strings. See the StriColl() function description.
<i>MetaiMatch</i>	Performs a case-insensitive comparison between a Null-terminated Unicode pattern string and a Null-terminated Unicode string. The pattern string can use the ‘?’ wildcard to match any character, and the ‘*’ wildcard to match any substring. See the MetaiMatch() function description.
<i>StrLwr</i>	Converts all the Unicode characters in a Null-terminated Unicode string to lowercase Unicode characters. See the StrLwr() function description.
<i>StrUpr</i>	Converts all the Unicode characters in a Null-terminated Unicode string to uppercase Unicode characters. See the StrUpr() function description.
<i>FatToStr</i>	Converts an 8.3 FAT file name using an OEM character set to a Null-terminated Unicode string. See the FatToStr() function description.
<i>StrToFat</i>	Converts a Null-terminated Unicode string to legal characters in a FAT filename using an OEM character set. See the StrToFat() function description.
<i>SupportedLanguages</i>	A Null-terminated ASCII string array that contains one or more language codes. This array is specified in RFC 3066 format. See Appendix M for the format of language codes and language code arrays.

Description

The **EFI_UNICODE_COLLATION_PROTOCOL** is used to perform case-insensitive comparisons of Unicode strings.

One or more of the **EFI_UNICODE_COLLATION_PROTOCOL** instances may be present at one time. Each protocol instance can support one or more language codes. The language codes that are

supported in the **EFI_UNICODE_COLLATION_PROTOCOL** is declared in *SupportedLanguages*.

The *SupportedLanguages* is a Null-terminated ASCII string array that contains one or more supported language codes. This is the list of language codes that this protocol supports. See [Appendix M](#) for the format of language codes and language code arrays.

The main motivation for this protocol is to help support file names in a file system driver. When a file is opened, a file name needs to be compared to the file names on the disk. In some cases, this comparison needs to be performed in a case-insensitive manner. In addition, this protocol can be used to sort files from a directory or to perform a case-insensitive file search.

EFI_UNICODE_COLLATION_PROTOCOL.StriColl()

Summary

Performs a case-insensitive comparison of two Null-terminated Unicode strings.

Prototype

```
typedef
INTN
(EFIAPI *EFI_UNICODE_COLLATION_STRICOLL) (
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,
    IN CHAR16 *s1,
    IN CHAR16 *s2
);
```

Parameters

<i>This</i>	A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined in Section 12.8 .
<i>s1</i>	A pointer to a Null-terminated Unicode string.
<i>s2</i>	A pointer to a Null-terminated Unicode string.

Description

The **StriColl()** function performs a case-insensitive comparison of two Null-terminated Unicode strings.

This function performs a case-insensitive comparison between the Unicode string *s1* and the Unicode string *s2* using the rules for the language codes that this protocol instance supports. If *s1* is equivalent to *s2*, then 0 is returned. If *s1* is lexically less than *s2*, then a negative number will be returned. If *s1* is lexically greater than *s2*, then a positive number will be returned. This function allows Unicode strings to be compared and sorted.

Status Codes Returned

0	s1 is equivalent to s2.
> 0	s1 is lexically greater than s2.
< 0	s1 is lexically less than s2.

EFI_UNICODE_COLLATION_PROTOCOL.MetaiMatch()

Summary

Performs a case-insensitive comparison of a Null-terminated Unicode pattern string and a Null-terminated Unicode string.

Prototype

```
typedef
BOOLEAN
(EFI_API *EFI_UNICODE_COLLATION_METAIMATCH) (
    IN EFI_UNICODE_COLLATION_PROTOCOL  *This,
    IN CHAR16                          *String,
    IN CHAR16                          *Pattern
);
```

Parameters

<i>This</i>	A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined in Section 12.8 .
<i>String</i>	A pointer to a Null-terminated Unicode string.
<i>Pattern</i>	A pointer to a Null-terminated Unicode pattern string.

Description

The **MetaiMatch()** function performs a case-insensitive comparison of a Null-terminated Unicode pattern string and a Null-terminated Unicode string.

This function checks to see if the pattern of characters described by *Pattern* are found in *String*. The pattern check is a case-insensitive comparison using the rules for the language codes that this protocol instance supports. If the pattern match succeeds, then **TRUE** is returned.

Otherwise **FALSE** is returned. The following syntax can be used to build the string *Pattern*:

*	Match 0 or more characters.
?	Match any one character.
[<char1><char2>...<charN>]	Match any character in the set.
[<char1>-<char2>]	Match any character between <char1> and <char2>.
<char>	Match the character <char>.

Following is an example pattern for English:

*.FW	Matches all strings that end in “.FW” or “.fw” or “.Fw” or “.fW.”
[a-z]	Match any letter in the alphabet.
[!@#\$\$%^&* ()]	Match any one of these symbols.
z	Match the character “z” or “Z.”
D?.*	Match the character “D” or “d” followed by any character followed by a “.” followed by any string.

Status Codes Returned

TRUE	Pattern was found in <i>String</i> .
FALSE	Pattern was not found in <i>String</i> .

EFI_UNICODE_COLLATION_PROTOCOL.StrLwr()**Summary**

Converts all the Unicode characters in a Null-terminated Unicode string to lowercase Unicode characters.

Prototype

```
typedef
VOID
(EFIAPI *EFI_UNICODE_COLLATION_STRLWR) (
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,
    IN OUT CHAR16                      *String
);
```

Parameters

<i>This</i>	A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined in Section 12.8 .
<i>String</i>	A pointer to a Null-terminated Unicode string.

Description

This function walks through all the Unicode characters in *String*, and converts each one to its lowercase equivalent if it has one. The converted string is returned in *String*.

EFI_UNICODE_COLLATION_PROTOCOL.StrUpr()

Summary

Converts all the Unicode characters in a Null-terminated Unicode string to uppercase Unicode characters.

Prototype

```
typedef
VOID
(EFIAPI *EFI_UNICODE_COLLATION_STRUPR) (
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,
    IN OUT CHAR16                      *String
);
```

Parameters

<i>This</i>	A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined in Section 12.8 .
<i>String</i>	A pointer to a Null-terminated Unicode string.

Description

This functions walks through all the Unicode characters in *String*, and converts each one to its uppercase equivalent if it has one. The converted string is returned in *String*.

EFI_UNICODE_COLLATION_PROTOCOL.FatToStr()**Summary**

Converts an 8.3 FAT file name in an OEM character set to a Null-terminated Unicode string.

Prototype

```
typedef
VOID
(EFIAPI *EFI_UNICODE_COLLATION_FATTOSTR) (
    IN EFI_UNICODE_COLLATION_PROTOCOL  *This,
    IN UINTN                            FatSize,
    IN CHAR8                             *Fat,
    OUT CHAR16                           *String
);
```

Parameters

<i>This</i>	A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined in Section 12.8 .
<i>FatSize</i>	The size of the string <i>Fat</i> in bytes.
<i>Fat</i>	A pointer to a Null-terminated string that contains an 8.3 file name using an OEM character set.
<i>String</i>	A pointer to a Null-terminated Unicode string. The string must be allocated in advance to hold <i>FatSize</i> Unicode characters.

Description

This function converts the string specified by *Fat* with length *FatSize* to the Null-terminated Unicode string specified by *String*. The characters in *Fat* are from an OEM character set.

EFI_UNICODE_COLLATION_PROTOCOL.StrToFat()

Summary

Converts a Null-terminated Unicode string to legal characters in a FAT filename using an OEM character set.

Prototype

```
typedef
BOOLEAN
(EFI_API *EFI_UNICODE_COLLATION_STRTOFAT) (
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,
    IN CHAR16 *String,
    IN UINTN FatSize,
    OUT CHAR8 *Fat
);
```

Parameters

<i>This</i>	A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined in Section 12.8 .
<i>String</i>	A pointer to a Null-terminated Unicode string.
<i>FatSize</i>	The size of the string <i>Fat</i> in bytes.
<i>Fat</i>	A pointer to a string that contains the converted version of <i>String</i> using legal FAT characters from an OEM character set.

Description

This function converts the Unicode characters from *String* into legal FAT characters in an OEM character set and stores them in the string *Fat*. This conversion continues until either *FatSize* bytes are stored in *Fat*, or the end of *String* is reached. The Unicode characters ‘.’ (period) and ‘ ’ (space) are ignored for this conversion. Unicode characters that map to an illegal FAT character are substituted with an ‘_’. If no valid mapping from a Unicode character to an OEM character is available, then it is also substituted with an ‘_’. If any of the Unicode character conversions are substituted with a ‘_’, then **TRUE** is returned. Otherwise **FALSE** is returned.

Status Codes Returned

TRUE	One or more conversions failed and were substituted with ‘_’.
FALSE	None of the conversions failed.

Protocols - PCI Bus Support

13.1 PCI Root Bridge I/O Support

[Section 13.1](#) and [Section 13.2](#) describe the PCI Root Bridge I/O Protocol. This protocol provides an I/O abstraction for a PCI Root Bridge that is produced by a PCI Host Bus Controller. A PCI Host Bus Controller is a hardware component that allows access to a group of PCI devices that share a common pool of PCI I/O and PCI Memory resources. This protocol is used by a PCI Bus Driver to perform PCI Memory, PCI I/O, and PCI Configuration cycles on a PCI Bus. It also provides services to perform different types of bus mastering DMA on a PCI bus. PCI device drivers will not directly use this protocol. Instead, they will use the I/O abstraction produced by the PCI Bus Driver. Only drivers that require direct access to the entire PCI bus should use this protocol. In particular, this chapter defines functions for managing PCI buses, although other bus types may be supported in a similar fashion as extensions to this specification.

All the services described in this chapter that generate PCI transactions follow the ordering rules defined in the *PCI Specification*. If the processor is performing a combination of PCI transactions and system memory transactions, then there is no guarantee that the system memory transactions will be strongly ordered with respect to the PCI transactions. If strong ordering is required, then processor-specific mechanisms may be required to guarantee strong ordering. Some 64-bit systems may require the use of memory fences to guarantee ordering.

13.1.1 PCI Root Bridge I/O Overview

The interfaces provided in the [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#) are for performing basic operations to memory, I/O, and PCI configuration space. The system provides abstracted access to basic system resources to allow a driver to have a programmatic method to access these basic system resources.

The [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#) allows for future innovation of the platform. It abstracts device-specific code from the system memory map. This allows system designers to make changes to the system memory map without impacting platform independent code that is consuming basic system resources.

A platform can be viewed as a set of processors and a set of core chipset components that may produce one or more host buses. [Figure 29](#) shows a platform with n processors (*CPUs* in the figure), and a set of core chipset components that produce m host bridges.

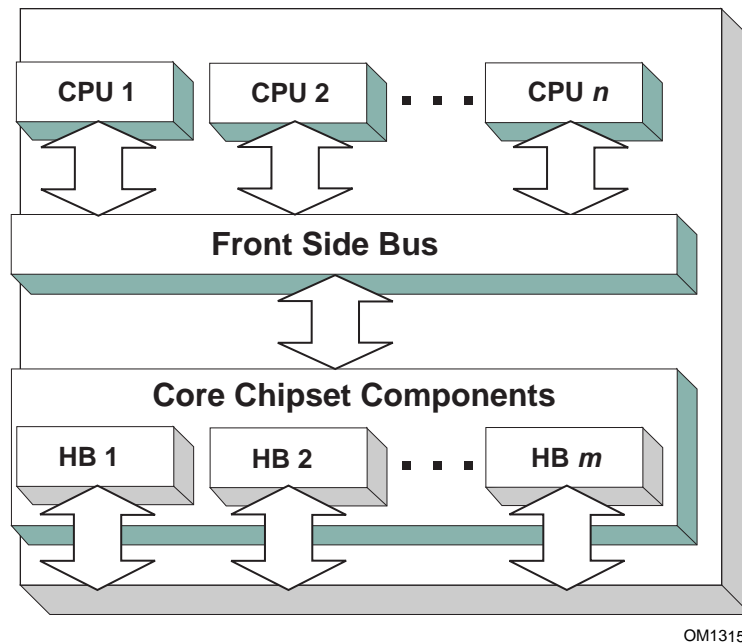
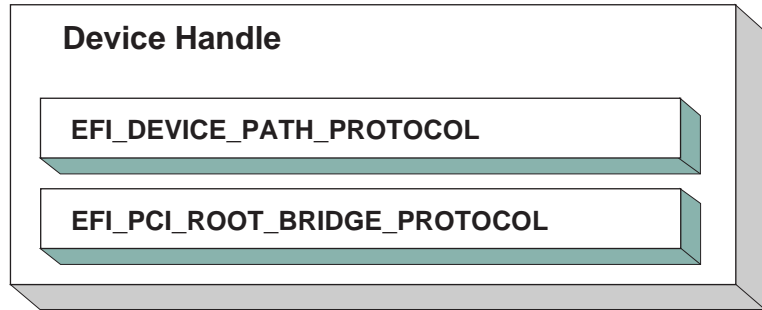


Figure 29. Host Bus Controllers

Simple systems with one PCI Host Bus Controller will contain a single instance of the [EFI PCI ROOT BRIDGE IO PROTOCOL](#). More complex system may contain multiple instances of this protocol. It is important to note that there is no relationship between the number of chipset components in a platform and the number of [EFI PCI ROOT BRIDGE IO PROTOCOL](#) instances. This protocol abstracts access to a PCI Root Bridge from a software point of view, and it is attached to a device handle that represents a PCI Root Bridge. A PCI Root Bridge is a chipset component(s) that produces a physical PCI Bus. It is also the parent to a set of PCI devices that share common PCI I/O, PCI Memory, and PCI Prefetchable Memory regions. A PCI Host Bus Controller is composed of one or more PCI Root Bridges.

A PCI Host Bridge and PCI Root Bridge are different than a PCI Segment. A PCI Segment is a collection of up to 256 PCI busses that share the same PCI Configuration Space. Depending on the chipset, a single [EFI PCI ROOT BRIDGE IO PROTOCOL](#) may abstract a portion of a PCI Segment, or an entire PCI Segment. A PCI Host Bridge may produce one or more PCI Root Bridges. When a PCI Host Bridge produces multiple PCI Root Bridges, it is possible to have more than one PCI Segment.

PCI Root Bridge I/O Protocol instances are either produced by the system firmware or by a UEFI driver. When a PCI Root Bridge I/O Protocol is produced, it is placed on a device handle along with an EFI Device Path Protocol instance. [Figure 30](#) shows a sample device handle for a PCI Root Bridge Controller that includes an instance of the [EFI DEVICE PATH PROTOCOL](#) and the [EFI PCI ROOT BRIDGE IO PROTOCOL](#). [Section 13.2](#) describes the PCI Root Bridge I/O Protocol in detail, and [Section 13.2.1](#) describes how to build device paths for PCI Root Bridges. The [EFI PCI ROOT BRIDGE IO PROTOCOL](#) does not abstract access to the chipset-specific registers that are used to manage a PCI Root Bridge. This functionality is hidden within the system firmware or the driver that produces the handles that represent the PCI Root Bridges.



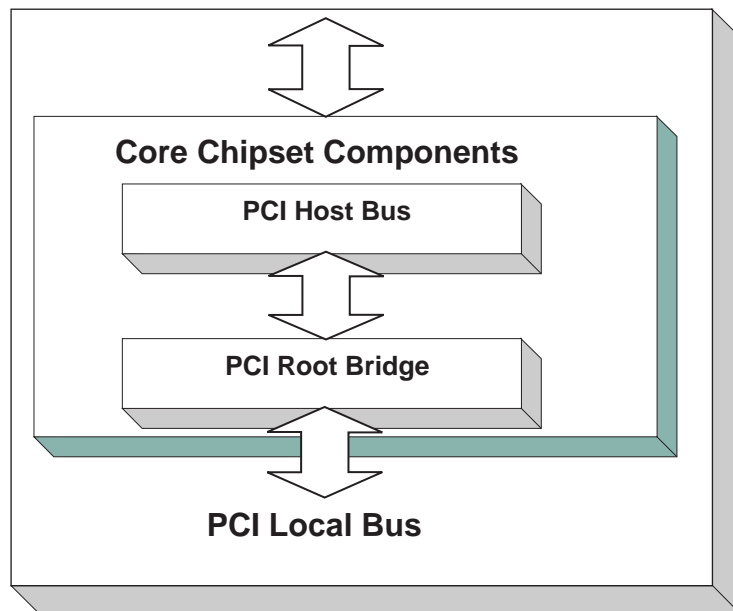
OM13151

Figure 30. Device Handle for a PCI Root Bridge Controller

13.1.1.1 Sample PCI Architectures

The PCI Root Bridge I/O Protocol is designed to provide a software abstraction for a wide variety of PCI architectures including the ones described in this section. This section is not intended to be an exhaustive list of the PCI architectures that the PCI Root Bridge I/O Protocol can support. Instead, it is intended to show the flexibility of this protocol to adapt to current and future platform designs.

[Figure 31](#) shows an example of a PCI Host Bus with one PCI Root Bridge. This PCI Root Bridge produces one PCI Local Bus that can contain PCI Devices on the motherboard and/or PCI slots. This would be typical of a desktop system. A higher end desktop system might contain a second PCI Root Bridge for AGP devices. The firmware for this platform would produce one instance of the PCI Root Bridge I/O Protocol.



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Figure 31. Desktop System with One PCI Root Bridge

[Figure 32](#) shows an example of a larger server with one PCI Host Bus and four PCI Root Bridges. The PCI devices attached to the PCI Root Bridges are all part of the same coherency domain. This means they share a common PCI I/O Space, a common PCI Memory Space, and a common PCI Prefetchable Memory Space. Each PCI Root Bridge produces one PCI Local Bus that can contain PCI Devices on the motherboard or PCI slots. The firmware for this platform would produce four instances of the PCI Root Bridge I/O Protocol.

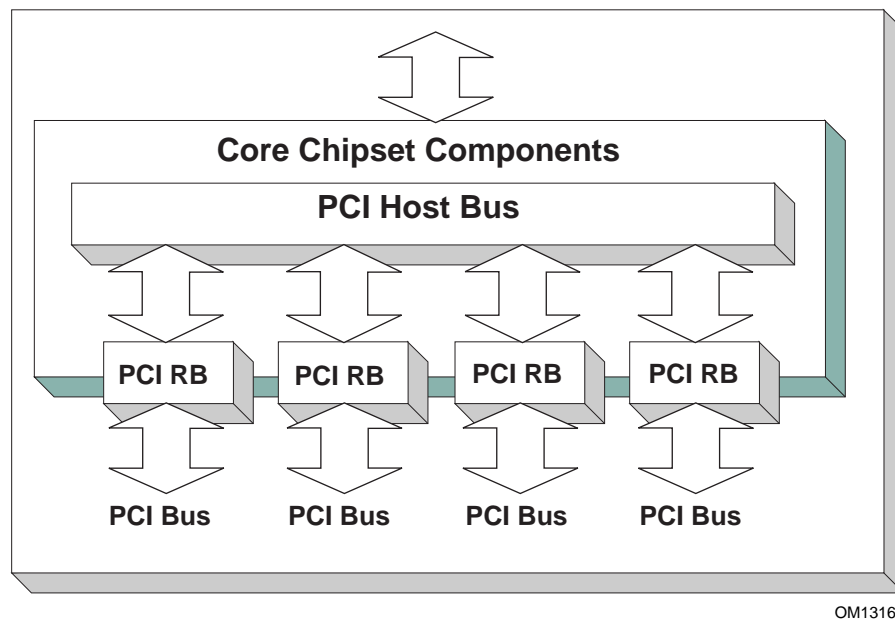
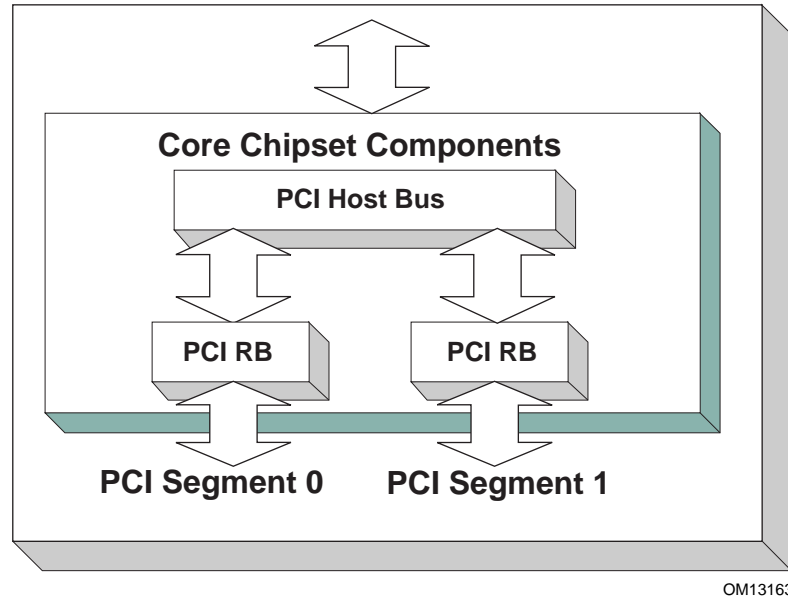


Figure 32. Server System with Four PCI Root Bridges

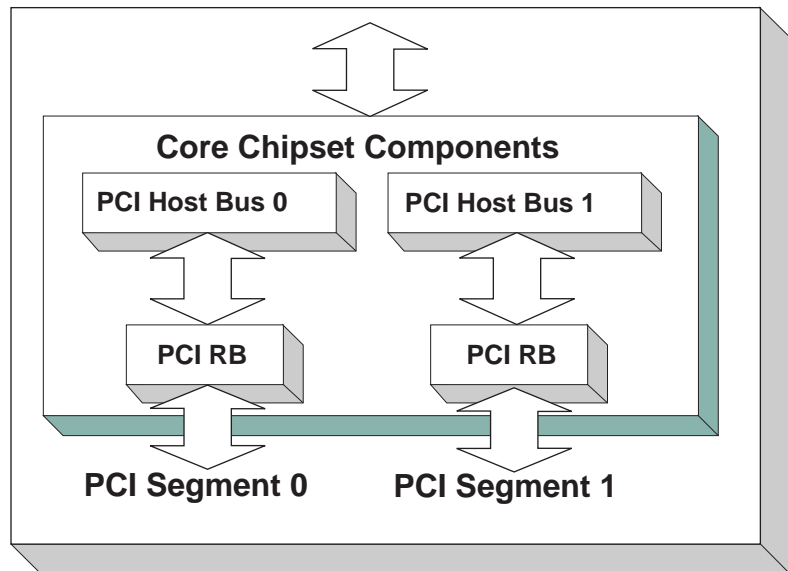
[Figure 33](#) shows an example of a server with one PCI Host Bus and two PCI Root Bridges. Each of these PCI Root Bridges is a different PCI Segment which allows the system to have up to 512 PCI Buses. A single PCI Segment is limited to 256 PCI Buses. These two segments do not share the same PCI Configuration Space, but they do share the same PCI I/O, PCI Memory, and PCI Prefetchable Memory Space. This is why it can be described by a single PCI Host Bus. The firmware for this platform would produce two instances of the PCI Root Bridge I/O Protocol.



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Figure 33. Server System with Two PCI Segments

[Figure 34](#) shows a server system with two PCI Host Buses and one PCI Root Bridge per PCI Host Bus. This system supports up to 512 PCI Buses, but the PCI I/O, PCI Memory Space, and PCI Prefetchable Memory Space are not shared between the two PCI Root Bridges. The firmware for this platform would produce two instances of the PCI Root Bridge I/O Protocol.



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Figure 34. Server System with Two PCI Host Buses

13.2 PCI Root Bridge I/O Protocol

This section provides detailed information on the PCI Root Bridge I/O Protocol and its functions.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL

Summary

Provides the basic Memory, I/O, PCI configuration, and DMA interfaces that are used to abstract accesses to PCI controllers behind a PCI Root Bridge Controller.

GUID

```
#define EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_GUID \
  {0x2F707EBB, 0x4A1A, 0x11d4, 0x9A, 0x38, 0x00, 0x90, 0x27, 0x3F, \
  0xC1, 0x4D}
```

Protocol Interface Structure

```
typedef struct _EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL {
  EFI_HANDLE ParentHandle;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM PollMem;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM PollIo;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS Mem;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS Io;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS Pci;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_COPY_MEM CopyMem;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_MAP Map;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_UNMAP Unmap;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ALLOCATE_BUFFER AllocateBuffer;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FREE_BUFFER FreeBuffer;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FLUSH Flush;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_GET_ATTRIBUTES GetAttributes;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_SET_ATTRIBUTES SetAttributes;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_CONFIGURATION Configuration;
  UINT32 SegmentNumber;
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL;
```

Parameters

<i>ParentHandle</i>	The EFI_HANDLE of the PCI Host Bridge of which this PCI Root Bridge is a member.
<i>PollMem</i>	Polls an address in memory mapped I/O space until an exit condition is met, or a timeout occurs. See the PollMem() function description.
<i>PollIo</i>	Polls an address in I/O space until an exit condition is met, or a timeout occurs. See the PollIo() function description.

<i>Mem.Read</i>	Allows reads from memory mapped I/O space. See the Mem.Read() function description.
<i>Mem.Write</i>	Allows writes to memory mapped I/O space. See the Mem.Write() function description.
<i>Io.Read</i>	Allows reads from I/O space. See the Io.Read() function description.
<i>Io.Write</i>	Allows writes to I/O space. See the Io.Write() function description.
<i>Pci.Read</i>	Allows reads from PCI configuration space. See the Pci.Read() function description.
<i>Pci.Write</i>	Allows writes to PCI configuration space. See the Pci.Write() function description.
<i>CopyMem</i>	Allows one region of PCI root bridge memory space to be copied to another region of PCI root bridge memory space. See the CopyMem() function description.
<i>Map</i>	Provides the PCI controller-specific addresses needed to access system memory for DMA. See the Map() function description.
<i>Unmap</i>	Releases any resources allocated by Map() . See the Unmap() function description.
<i>AllocateBuffer</i>	Allocates pages that are suitable for a common buffer mapping. See the AllocateBuffer() function description.
<i>FreeBuffer</i>	Free pages that were allocated with AllocateBuffer() . See the FreeBuffer() function description.
<i>Flush</i>	Flushes all PCI posted write transactions to system memory. See the Flush() function description.
<i>GetAttributes</i>	Gets the attributes that a PCI root bridge supports setting with SetAttributes() , and the attributes that a PCI root bridge is currently using. See the GetAttributes() function description.
<i>SetAttributes</i>	Sets attributes for a resource range on a PCI root bridge. See the SetAttributes() function description.
<i>Configuration</i>	Gets the current resource settings for this PCI root bridge. See the Configuration() function description.
<i>SegmentNumber</i>	The segment number that this PCI root bridge resides.

Related Definitions

```

//*****
// EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH
//*****
typedef enum {
    EfiPciWidthUint8,
    EfiPciWidthUint16,
    EfiPciWidthUint32,
    EfiPciWidthUint64,
    EfiPciWidthFifoUint8,

```

```

    EfiPciWidthFifoUint16,
    EfiPciWidthFifoUint32,
    EfiPciWidthFifoUint64,
    EfiPciWidthFillUint8,
    EfiPciWidthFillUint16,
    EfiPciWidthFillUint32,
    EfiPciWidthFillUint64,
    EfiPciWidthMaximum
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH;

//*****
// EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM
//*****
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM) (
    IN struct EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN UINT64 Address,
    IN UINT64 Mask,
    IN UINT64 Value,
    IN UINT64 Delay,
    OUT UINT64 *Result
);

//*****
// EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM
//*****
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN UINT64 Address,
    IN UINTN Count,
    IN OUT VOID *Buffer
);

//*****
// EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS
//*****
typedef struct {
    EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM Read;
    EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM Write;
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS;

```

```

//*****
// EFI PCI Root Bridge I/O Protocol Attribute bits
//*****
#define EFI_PCI_ATTRIBUTE_ISA_MOTHERBOARD_IO    0x0001
#define EFI_PCI_ATTRIBUTE_ISA_IO                0x0002
#define EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO       0x0004
#define EFI_PCI_ATTRIBUTE_VGA_MEMORY           0x0008
#define EFI_PCI_ATTRIBUTE_VGA_IO               0x0010
#define EFI_PCI_ATTRIBUTE_IDE_PRIMARY_IO       0x0020
#define EFI_PCI_ATTRIBUTE_IDE_SECONDARY_IO     0x0040
#define EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE 0x0080
#define EFI_PCI_ATTRIBUTE_MEMORY_CACHED       0x0800
#define EFI_PCI_ATTRIBUTE_MEMORY_DISABLE      0x1000
#define EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE  0x8000
#define EFI_PCI_ATTRIBUTE_ISA_IO_16           0x10000
#define EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16   0x20000
#define EFI_PCI_ATTRIBUTE_VGA_IO_16           0x40000

```

EFI_PCI_ATTRIBUTE_ISA_IO_16
 If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices onto a PCI root bridge. This bit may not be combined with **EFI_PCI_ATTRIBUTE_ISA_IO**.

EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16
 If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers onto a PCI root bridge. This bit may not be combined with **EFI_PCI_ATTRIBUTE_VGA_IO** or **EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO**.

EFI_PCI_ATTRIBUTE_VGA_IO_16
 If this bit is set, then the PCI I/O cycles in the ranges 0x3B0–0x3BB and 0x3C0–0x3DF are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller onto a PCI root bridge. This bit may not be combined with **EFI_PCI_ATTRIBUTE_VGA_IO** or **EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO**. Because **EFI_PCI_ATTRIBUTE_VGA_IO_16** also includes the I/O range described by **EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16**, the **EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16** bit is ignored if **EFI_PCI_ATTRIBUTE_VGA_IO_16** is set.

EFI_PCI_ATTRIBUTE_ISA_MOTHERBOARD_IO
 If this bit is set, then the PCI I/O cycles between 0x00000000 and

0x000000FF are forwarded onto a PCI root bridge. This bit is used to forward I/O cycles for ISA motherboard devices onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_ISA_IO

If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded onto a PCI root bridge using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO

If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded onto a PCI root bridge using a 10 bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_VGA_MEMORY

If this bit is set, then the PCI memory cycles between 0xA0000 and 0xBFFFF are forwarded onto a PCI root bridge. This bit is used to forward memory cycles for a VGA frame buffer onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_VGA_IO

If this bit is set, then the PCI I/O cycles in the ranges 0x3B0-0x3BB and 0x3C0-0x3DF are forwarded onto a PCI root bridge using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and the address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller onto a PCI root bridge. Since

EFI_PCI_ATTRIBUTE_ENABLE_VGA_IO also includes the I/O range described by

EFI_PCI_ATTRIBUTE_ENABLE_VGA_PALETTE_IO, the **EFI_PCI_ATTRIBUTE_ENABLE_VGA_PALETTE_IO** bit is ignored if **EFI_PCI_ATTRIBUTE_ENABLE_VGA_IO** is set.

EFI_PCI_ATTRIBUTE_IDE_PRIMARY_IO

If this bit is set, then the PCI I/O cycles in the ranges 0x1F0-0x1F7 and 0x3F6-0x3F7 are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Primary IDE controller onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_IDE_SECONDARY_IO

If this bit is set, then the PCI I/O cycles in the ranges 0x170-0x177 and 0x376-0x377 are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Secondary IDE controller onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE

If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is

accessed in a write combining mode. By default, PCI memory ranges are not accessed in a write combining mode.

EFI_PCI_ATTRIBUTE_MEMORY_CACHED

If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a cached mode. By default, PCI memory ranges are accessed noncached.

EFI_PCI_ATTRIBUTE_MEMORY_DISABLE

If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is disabled, and can no longer be accessed. By default, all PCI memory ranges are enabled.

EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE

This bit may only be used in the *Attributes* parameter to [AllocateBuffer\(\)](#). If this bit is set, then the PCI controller that is requesting a buffer through **AllocateBuffer()** is capable of producing PCI Dual Address Cycles, so it is able to access a 64-bit address space. If this bit is not set, then the PCI controller that is requesting a buffer through **AllocateBuffer()** is not capable of producing PCI Dual Address Cycles, so it is only able to access a 32-bit address space.

```
//*****
// EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION
//*****
typedef enum {
    EfiPciOperationBusMasterRead,
    EfiPciOperationBusMasterWrite,
    EfiPciOperationBusMasterCommonBuffer,
    EfiPciOperationBusMasterRead64,
    EfiPciOperationBusMasterWrite64,
    EfiPciOperationBusMasterCommonBuffer64,
    EfiPciOperationMaximum
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION;
```

EfiPciOperationBusMasterRead

A read operation from system memory by a bus master that is not capable of producing PCI dual address cycles.

EfiPciOperationBusMasterWrite

A write operation to system memory by a bus master that is not capable of producing PCI dual address cycles.

EfiPciOperationBusMasterCommonBuffer

Provides both read and write access to system memory by both the processor and a bus master that is not capable of producing PCI dual address cycles. The buffer is coherent from both the processor's and the bus master's point of view.

EfiPciOperationBusMasterRead64

A read operation from system memory by a bus master that is capable of producing PCI dual address cycles.

EfiPciOperationBusMasterWrite64

A write operation to system memory by a bus master that is capable of producing PCI dual address cycles.

EfiPciOperationBusMasterCommonBuffer64

Provides both read and write access to system memory by both the processor and a bus master that is capable of producing PCI dual address cycles. The buffer is coherent from both the processor's and the bus master's point of view.

Description

The **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** provides the basic Memory, I/O, PCI configuration, and DMA interfaces that are used to abstract accesses to PCI controllers. There is one **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** instance for each PCI root bridge in a system. Embedded systems, desktops, and workstations will typically only have one PCI root bridge. High-end servers may have multiple PCI root bridges. A device driver that wishes to manage a PCI bus in a system will have to retrieve the **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** instance that is associated with the PCI bus to be managed. A device handle for a PCI Root Bridge will minimally contain an [EFI_DEVICE_PATH_PROTOCOL](#) instance and an **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** instance. The PCI bus driver can look at the [EFI_DEVICE_PATH_PROTOCOL](#) instances to determine which **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** instance to use.

Bus mastering PCI controllers can use the DMA services for DMA operations. There are three basic types of bus mastering DMA that is supported by this protocol. These are DMA reads by a bus master, DMA writes by a bus master, and common buffer DMA. The DMA read and write operations may need to be broken into smaller chunks. The caller of [Map \(\)](#) must pay attention to the number of bytes that were mapped, and if required, loop until the entire buffer has been transferred. The following is a list of the different bus mastering DMA operations that are supported, and the sequence of **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** APIs that are used for each DMA operation type. See "Related Definitions" above for the definition of the different DMA operation types.

DMA Bus Master Read Operation

- Call [Map \(\)](#) for **EfiPciOperationBusMasterRead** or **EfiPciOperationBusMasterRead64**.
- Program the DMA Bus Master with the *DeviceAddress* returned by **Map ()**.
- Start the DMA Bus Master.
- Wait for DMA Bus Master to complete the read operation.
- Call [Unmap \(\)](#).

DMA Bus Master Write Operation

- Call **Map ()** for **EfiPciOperationBusMasterWrite** or **EfiPciOperationBusMasterRead64**.

- Program the DMA Bus Master with the *DeviceAddress* returned by [Map \(\)](#).
- Start the DMA Bus Master.
- Wait for DMA Bus Master to complete the write operation.
- Perform a PCI controller specific read transaction to flush all PCI write buffers (See *PCI Specification* Section 3.2.5.2) .
- Call [Flush \(\)](#) .
- Call [Unmap \(\)](#) .

DMA Bus Master Common Buffer Operation

- Call [AllocateBuffer \(\)](#) to allocate a common buffer.
- Call [Map \(\)](#) for **EfiPciOperationBusMasterCommonBuffer** or **EfiPciOperationBusMasterCommonBuffer64**.
- Program the DMA Bus Master with the *DeviceAddress* returned by [Map \(\)](#) .
- The common buffer can now be accessed equally by the processor and the DMA bus master.
- Call [Unmap \(\)](#) .
- Call [FreeBuffer \(\)](#) .

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.PollMem()

Summary

Reads from the memory space of a PCI Root Bridge. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM) (
    IN  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH  Width,
    IN  UINT64                               Address,
    IN  UINT64                               Mask,
    IN  UINT64                               Value,
    IN  UINT64                               Delay,
    OUT UINT64                               *Result
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI ROOT BRIDGE IO PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH is defined in Section 13.2 .
<i>Address</i>	The base address of the memory operations. The caller is responsible for aligning <i>Address</i> if required.
<i>Mask</i>	Mask used for the polling criteria. Bytes above <i>Width</i> in <i>Mask</i> are ignored. The bits in the bytes below <i>Width</i> which are zero in <i>Mask</i> are ignored when polling the memory address.
<i>Value</i>	The comparison value used for the polling exit criteria.
<i>Delay</i>	The number of 100 ns units to poll. Note that timer available may be of poorer granularity.
<i>Result</i>	Pointer to the last value read from the memory location.

Description

This function provides a standard way to poll a PCI memory location. A PCI memory read operation is performed at the PCI memory address specified by *Address* for the width specified by *Width*. The result of this PCI memory read operation is stored in *Result*. This PCI memory read operation is repeated until either a timeout of *Delay* 100 ns units has expired, or $(Result \& Mask)$ is equal to *Value*.

This function will always perform at least one PCI memory read access no matter how small *Delay* may be. If *Delay* is zero, then *Result* will be returned with a status of **EFI_SUCCESS** even if *Result* does not match the exit criteria. If *Delay* expires, then **EFI_TIMEOUT** is returned.

If *Width* is not **EfiPciWidthUint8**, **EfiPciWidthUint16**, **EfiPciWidthUint32**, or **EfiPciWidthUint64**, then **EFI_INVALID_PARAMETER** is returned.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI Root Bridge on a platform might require. For example on some platforms, width requests of **EfiPciWidthUint64** are not supported.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. However, if the memory mapped I/O region being accessed by this function has the **EFI_PCI_ATTRIBUTE_MEMORY_CACHED** attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

EFI_SUCCESS	The last data returned from the access matched the poll exit criteria.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Result</i> is NULL .
EFI_TIMEOUT	<i>Delay</i> expired before a match occurred.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.PollIo()

Summary

Reads from the I/O space of a PCI Root Bridge. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM) (
    IN  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN  UINT64                               Address,
    IN  UINT64                               Mask,
    IN  UINT64                               Value,
    IN  UINT64                               Delay,
    OUT UINT64                               *Result
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI ROOT BRIDGE IO PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Width</i>	Signifies the width of the I/O operations. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH is defined in Section 13.2 .
<i>Address</i>	The base address of the I/O operations. The caller is responsible for aligning <i>Address</i> if required.
<i>Mask</i>	Mask used for the polling criteria. Bytes above <i>Width</i> in <i>Mask</i> are ignored. The bits in the bytes below <i>Width</i> which are zero in <i>Mask</i> are ignored when polling the I/O address.
<i>Value</i>	The comparison value used for the polling exit criteria.
<i>Delay</i>	The number of 100 ns units to poll. Note that timer available may be of poorer granularity.
<i>Result</i>	Pointer to the last value read from the memory location.

Description

This function provides a standard way to poll a PCI I/O location. A PCI I/O read operation is performed at the PCI I/O address specified by *Address* for the width specified by *Width*. The result of this PCI I/O read operation is stored in *Result*. This PCI I/O read operation is repeated until either a timeout of *Delay* 100 ns units has expired, or $(Result \& Mask)$ is equal to *Value*.

This function will always perform at least one I/O access no matter how small *Delay* may be. If *Delay* is zero, then *Result* will be returned with a status of **EFI_SUCCESS** even if *Result* does not match the exit criteria. If *Delay* expires, then **EFI_TIMEOUT** is returned.

If *Width* is not **EfiPciWidthUint8**, **EfiPciWidthUint16**, **EfiPciWidthUint32**, or **EfiPciWidthUint64**, then **EFI_INVALID_PARAMETER** is returned.

The I/O operations are carried out exactly as requested. The caller is responsible satisfying any alignment and I/O width restrictions that the PCI Root Bridge on a platform might require. For example on some platforms, width requests of **EfiPciWidthUint64** do not work.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

EFI_SUCCESS	The last data returned from the access matched the poll exit criteria.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Result</i> is NULL .
EFI_TIMEOUT	<i>Delay</i> expired before a match occurred.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Mem.Read() EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Mem.Write()

Summary

Enables a PCI driver to access PCI controller registers in the PCI root bridge memory space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN      UINT64                               Address,
    IN      UINTN                                Count,
    IN OUT VOID                               *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Width</i>	Signifies the width of the memory operation. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH is defined in Section 13.2 .
<i>Address</i>	The base address of the memory operation. The caller is responsible for aligning the <i>Address</i> if required.
<i>Count</i>	The number of memory operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>Address</i> .
<i>Buffer</i>	For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The **Mem.Read()**, and **Mem.Write()** functions enable a driver to access PCI controller registers in the PCI root bridge memory space.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI Root Bridge on a platform might require. For example on some platforms, width requests of **EfiPciWidthUint64** do not work.

If *Width* is **EfiPciWidthUint8**, **EfiPciWidthUint16**, **EfiPciWidthUint32**, or **EfiPciWidthUint64**, then both *Address* and *Buffer* are incremented for each of the *Count* operations performed.

If *Width* is **EfiPciWidthFifoUint8**, **EfiPciWidthFifoUint16**, **EfiPciWidthFifoUint32**, or **EfiPciWidthFifoUint64**, then only *Buffer* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times on the same *Address*.

If *Width* is **EfiPciWidthFillUint8**, **EfiPciWidthFillUint16**, **EfiPciWidthFillUint32**, or **EfiPciWidthFillUint64**, then only *Address* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times from the first element of *Buffer*.

All the PCI read transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the *PCI Specification*. However, if the memory-mapped I/O region being accessed by this function has the **EFI_PCI_ATTRIBUTE_MEMORY_CACHED** attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

EFI_SUCCESS	The data was read from or written to the PCI root bridge.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid for this PCI root bridge.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Io.Read() EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Io.Write()

Summary

Enables a PCI driver to access PCI controller registers in the PCI root bridge I/O space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN      UINT64                               Address,
    IN      UINTN                                Count,
    IN OUT VOID                               *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH is defined in Section 13.2 .
<i>Address</i>	The base address of the I/O operation. The caller is responsible for aligning the <i>Address</i> if required.
<i>Count</i>	The number of I/O operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>Address</i> .
<i>Buffer</i>	For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The `Io.Read()`, and `Io.Write()` functions enable a driver to access PCI controller registers in the PCI root bridge I/O space.

The I/O operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and I/O width restrictions that a PCI root bridge on a platform might require. For example on some platforms, width requests of `EfiPciWidthUint64` do not work.

If *Width* is `EfiPciWidthUint8`, `EfiPciWidthUint16`, `EfiPciWidthUint32`, or `EfiPciWidthUint64`, then both *Address* and *Buffer* are incremented for each of the *Count* operations performed.

If *Width* is `EfiPciWidthFifoUint8`, `EfiPciWidthFifoUint16`, `EfiPciWidthFifoUint32`, or `EfiPciWidthFifoUint64`, then only *Buffer* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times on the same *Address*.

If *Width* is **EfiPciWidthFillUint8**, **EfiPciWidthFillUint16**, **EfiPciWidthFillUint32**, or **EfiPciWidthFillUint64**, then only *Address* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times from the first element of *Buffer*.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

EFI_SUCCESS	The data was read from or written to the PCI root bridge.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid for this PCI root bridge.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Pci.Read() EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Pci.Write()

Summary

Enables a PCI driver to access PCI controller registers in a PCI root bridge's configuration space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN      UINT64                               Address,
    IN      UINTN                                Count,
    IN OUT VOID                               *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH is defined in Section 13.2 .
<i>Address</i>	The address within the PCI configuration space for the PCI controller. See Table 87 for the format of <i>Address</i> .
<i>Count</i>	The number of PCI configuration operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>Address</i> .
<i>Buffer</i>	For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The **Pci.Read()** and **Pci.Write()** functions enable a driver to access PCI configuration registers for a PCI controller.

The PCI Configuration operations are carried out exactly as requested. The caller is responsible for any alignment and PCI configuration width issues that a PCI Root Bridge on a platform might require. For example on some platforms, width requests of **EfiPciWidthUint64** do not work.

If *Width* is **EfiPciWidthUint8**, **EfiPciWidthUint16**, **EfiPciWidthUint32**, or **EfiPciWidthUint64**, then both *Address* and *Buffer* are incremented for each of the *Count* operations performed.

If *Width* is **EfiPciWidthFifoUint8**, **EfiPciWidthFifoUint16**, **EfiPciWidthFifoUint32**, or **EfiPciWidthFifoUint64**, then only *Buffer* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times on the same *Address*.

If *Width* is **EfiPciWidthFillUint8**, **EfiPciWidthFillUint16**, **EfiPciWidthFillUint32**, or **EfiPciWidthFillUint64**, then only *Address* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times from the first element of *Buffer*.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Table 87. PCI Configuration Address

Mnemonic	Byte Offset	Byte Length	Description
Register	0	1	The register number on the PCI Function.
Function	1	1	The PCI Function number on the PCI Device.
Device	2	1	The PCI Device number on the PCI Bus.
Bus	3	1	The PCI Bus number.
ExtendedRegister	4	4	The register number on the PCI Function. If this field is zero, then the Register field is used for the register number. If this field is nonzero, then the Register field is ignored, and the ExtendedRegister field is used for the register number.

Status Codes Returned

EFI_SUCCESS	The data was read from or written to the PCI root bridge.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid for this PCI root bridge.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.CopyMem()

Summary

Enables a PCI driver to copy one region of PCI root bridge memory space to another region of PCI root bridge memory space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_COPY_MEM) (
    IN     EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN     EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN     UINT64                               DestAddress,
    IN     UINT64                               SrcAddress,
    IN     UINTN                               Count
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instance. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH is defined in Section 13.2 .
<i>DestAddress</i>	The destination address of the memory operation. The caller is responsible for aligning the <i>DestAddress</i> if required.
<i>SrcAddress</i>	The source address of the memory operation. The caller is responsible for aligning the <i>SrcAddress</i> if required.
<i>Count</i>	The number of memory operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>DestAddress</i> and <i>SrcAddress</i> .

Description

The **CopyMem()** function enables a PCI driver to copy one region of PCI root bridge memory space to another region of PCI root bridge memory space. This is especially useful for video scroll operation on a memory mapped video buffer.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI root bridge on a platform might require. For example on some platforms, width requests of **EfiPciWidthUint64** do not work.

If *Width* is **EfiPciWidthUint8**, **EfiPciWidthUint16**, **EfiPciWidthUint32**, or **EfiPciWidthUint64**, then *Count* read/write transactions are performed to move the contents of the *SrcAddress* buffer to the *DestAddress* buffer. The implementation must be reentrant, and it must handle overlapping *SrcAddress* and *DestAddress* buffers. This means that the implementation of **CopyMem()** must choose the correct direction of the copy operation based on the type of overlap that exists between the *SrcAddress* and *DestAddress* buffers. If either the

SrcAddress buffer or the *DestAddress* buffer crosses the top of the processor's address space, then the result of the copy operation is unpredictable.

The contents of the *DestAddress* buffer on exit from this service must match the contents of the *SrcAddress* buffer on entry to this service. Due to potential overlaps, the contents of the *SrcAddress* buffer may be modified by this service. The following rules can be used to guarantee the correct behavior:

- If $DestAddress > SrcAddress$ and $DestAddress < (SrcAddress + Width \text{ size} * Count)$, then the data should be copied from the *SrcAddress* buffer to the *DestAddress* buffer starting from the end of buffers and working toward the beginning of the buffers.
- Otherwise, the data should be copied from the *SrcAddress* buffer to the *DestAddress* buffer starting from the beginning of the buffers and working toward the end of the buffers.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the *PCI Specification*. However, if the memory-mapped I/O region being accessed by this function has the

EFI_PCI_ATTRIBUTE_MEMORY_CACHED attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

EFI_SUCCESS	The data was copied from one memory region to another memory region.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid for this PCI root bridge.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map()

Summary

Provides the PCI controller-specific addresses required to access system memory from a DMA bus master.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_MAP) (
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL      *This,
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION Operation,
    IN      VOID                                  *HostAddress,
    IN OUT  UINTN                                *NumberOfBytes,
    OUT     EFI_PHYSICAL_ADDRESS                 *DeviceAddress,
    OUT     VOID                                  **Mapping
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI ROOT BRIDGE IO PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Operation</i>	Indicates if the bus master is going to read or write to system memory. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION is defined in Section 13.2 .
<i>HostAddress</i>	The system memory address to map to the PCI controller.
<i>NumberOfBytes</i>	On input the number of bytes to map. On output the number of bytes that were mapped.
<i>DeviceAddress</i>	The resulting map address for the bus master PCI controller to use to access the system memory's <i>HostAddress</i> . Type EFI_PHYSICAL_ADDRESS is defined in Section 6.2 , AllocatePages () . This address cannot be used by the processor to access the contents of the buffer specified by <i>HostAddress</i> .
<i>Mapping</i>	The value to pass to Unmap () when the bus master DMA operation is complete.

Description

The **Map ()** function provides the PCI controller specific addresses needed to access system memory. This function is used to map system memory for PCI bus master DMA accesses.

All PCI bus master accesses must be performed through their mapped addresses and such mappings must be freed with [Unmap \(\)](#) when complete. If the bus master access is a single read or single write data transfer, then **EfiPciOperationBusMasterRead**,

EfiPciOperationBusMasterRead64, **EfiPciOperationBusMasterWrite**, or **EfiPciOperationBusMasterWrite64** is used and the range is unmapped to complete the operation. If performing an **EfiPciOperationBusMasterRead** or **EfiPciOperationBusMasterRead64** operation, all the data must be present in system memory before **Map ()** is performed. Similarly, if performing an **EfiPciOperation-BusMasterWrite** or **EfiPciOperationBusMasterWrite64** the data cannot be properly accessed in system memory until **Unmap ()** is performed.

Bus master operations that require both read and write access or require multiple host device interactions within the same mapped region must use **EfiPciOperation-BusMasterCommonBuffer** or **EfiPciOperationBusMasterCommonBuffer64**. However, only memory allocated via the [AllocateBuffer \(\)](#) interface can be mapped for this type of operation.

In all mapping requests the resulting *NumberOfBytes* actually mapped may be less than the requested amount. In this case, the DMA operation will have to be broken up into smaller chunks. The **Map ()** function will map as much of the DMA operation as it can at one time. The caller may have to loop on **Map ()** and **Unmap ()** in order to complete a large DMA transfer.

Status Codes Returned

EFI_SUCCESS	The range was mapped for the returned <i>NumberOfBytes</i> .
EFI_INVALID_PARAMETER	<i>Operation</i> is invalid.
EFI_INVALID_PARAMETER	HostAddress is NULL .
EFI_INVALID_PARAMETER	NumberOfBytes is NULL .
EFI_INVALID_PARAMETER	DeviceAddress is NULL .
EFI_INVALID_PARAMETER	<i>Mapping</i> is NULL .
EFI_UNSUPPORTED	The <i>HostAddress</i> cannot be mapped as a common buffer.
EFI_DEVICE_ERROR	The system hardware could not map the requested address.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Unmap()

Summary

Completes the [Map \(\)](#) operation and releases any corresponding resources.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_UNMAP) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    IN VOID *Mapping
);
```

Parameters

This A pointer to the [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#). Type [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#) is defined in [Section 13.2](#).

Mapping The mapping value returned from [Map \(\)](#).

Description

The [Unmap \(\)](#) function completes the [Map \(\)](#) operation and releases any corresponding resources. If the operation was an [EfiPciOperationBusMasterWrite](#) or [EfiPciOperationBusMasterWrite64](#), the data is committed to the target system memory. Any resources used for the mapping are freed.

Status Codes Returned

EFI_SUCCESS	The range was unmapped.
EFI_INVALID_PARAMETER	<i>Mapping</i> is not a value that was returned by Map () .
EFI_DEVICE_ERROR	The data was not committed to the target system memory.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.AllocateBuffer()

Summary

Allocates pages that are suitable for an **EfiPciOperationBusMasterCommonBuffer** or **EfiPciOperationBusMasterCommonBuffer64** mapping.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ALLOCATE_BUFFER) (
    IN      EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL  *This,
    IN      EFI_ALLOCATE_TYPE                Type,
    IN      EFI_MEMORY_TYPE                  MemoryType,
    IN      UINTN                            Pages,
    OUT     VOID                             **HostAddress,
    IN      UINT64                            Attributes
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2.1 .
<i>Type</i>	This parameter is not used and must be ignored.
<i>MemoryType</i>	The type of memory to allocate, EfiBootServicesData or EfiRuntimeServicesData . Type EFI_MEMORY_TYPE is defined in Section 6.2, AllocatePages() .
<i>Pages</i>	The number of pages to allocate.
<i>HostAddress</i>	A pointer to store the base system memory address of the allocated range.
<i>Attributes</i>	The requested bit mask of attributes for the allocated range. Only the attributes EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE , EFI_PCI_ATTRIBUTE_MEMORY_CACHED , and EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE may be used with this function. If any other bits are set, then EFI_UNSUPPORTED is returned. This function may choose to ignore this bit mask. The EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE , and EFI_PCI_ATTRIBUTE_MEMORY_CACHED attributes provide a hint to the implementation that may improve the performance of the calling driver. The implementation may choose any default for the memory attributes including write combining, cached, both, or neither as long as the allocated buffer can be seen equally by both the processor and the PCI bus master.

Description

The **AllocateBuffer ()** function allocates pages that are suitable for an **EfiPciOperationBusMasterCommonBuffer** or **EfiPciOperationBusMasterCommonBuffer64** mapping. This means that the buffer allocated by this function must support simultaneous access by both the processor and a PCI Bus Master. The device address that the PCI Bus Master uses to access the buffer can be retrieved with a call to **Map ()**.

If the **EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE** bit of *Attributes* is set, then when the buffer allocated by this function is mapped with a call to **Map ()**, the device address that is returned by **Map ()** must be within the 64-bit device address space of the PCI Bus Master.

If the **EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE** bit of *Attributes* is clear, then when the buffer allocated by this function is mapped with a call to **Map ()**, the device address that is returned by **Map ()** must be within the 32-bit device address space of the PCI Bus Master.

If the memory allocation specified by *MemoryType* and *Pages* cannot be satisfied, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The requested memory pages were allocated.
EFI_INVALID_PARAMETER	<i>MemoryType</i> is invalid.
EFI_INVALID_PARAMETER	HostAddress is NULL .
EFI_UNSUPPORTED	<i>Attributes</i> is unsupported. The only legal attribute bits are MEMORY_WRITE_COMBINE , MEMORY_CACHED , and DUAL_ADDRESS_CYCLE .
EFI_OUT_OF_RESOURCES	The memory pages could not be allocated.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.FreeBuffer()

Summary

Frees memory that was allocated with [AllocateBuffer\(\)](#).

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FREE_BUFFER) (
    IN  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL  *This,
    IN  UINTN                             Pages,
    IN  VOID                             *HostAddress
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI ROOT BRIDGE IO PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Pages</i>	The number of pages to free.
<i>HostAddress</i>	The base system memory address of the allocated range.

Description

The **FreeBuffer()** function frees memory that was allocated with **AllocateBuffer()**.

Status Codes Returned

EFI_SUCCESS	The requested memory pages were freed.
EFI_INVALID_PARAMETER	The memory range specified by <i>HostAddress</i> and <i>Pages</i> was not allocated with AllocateBuffer() .

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Flush()

Summary

Flushes all PCI posted write transactions from a PCI host bridge to system memory.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FLUSH) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This
);
```

Parameters

This A pointer to the [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#). Type [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#) is defined in [Section 13.2.1](#).

Description

The **Flush()** function flushes any PCI posted write transactions from a PCI host bridge to system memory. Posted write transactions are generated by PCI bus masters when they perform write transactions to target addresses in system memory.

This function does not flush posted write transactions from any PCI bridges. A PCI controller specific action must be taken to guarantee that the posted write transactions have been flushed from the PCI controller and from all the PCI bridges into the PCI host bridge. This is typically done with a PCI read transaction from the PCI controller prior to calling **Flush()**.

If the PCI controller specific action required to flush the PCI posted write transactions has been performed, and this function returns **EFI_SUCCESS**, then the PCI bus master's view and the processor's view of system memory are guaranteed to be coherent. If the PCI posted write transactions cannot be flushed from the PCI host bridge, then the PCI bus master and processor are not guaranteed to have a coherent view of system memory, and **EFI_DEVICE_ERROR** is returned.

Status Codes Returned

EFI_SUCCESS	The PCI posted write transactions were flushed from the PCI host bridge to system memory.
EFI_DEVICE_ERROR	The PCI posted write transactions were not flushed from the PCI host bridge due to a hardware error.

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.GetAttributes()

Summary

Gets the attributes that a PCI root bridge supports setting with [SetAttributes\(\)](#), and the attributes that a PCI root bridge is currently using.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_GET_ATTRIBUTES) (
    IN  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL  *This,
    OUT UINT64                          *Supports    OPTIONAL,
    OUT UINT64                          *Attributes  OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Supports</i>	A pointer to the mask of attributes that this PCI root bridge supports setting with SetAttributes() . The available attributes are listed in Section 13.2 . This is an optional parameter that may be NULL .
<i>Attributes</i>	A pointer to the mask of attributes that this PCI root bridge is currently using. The available attributes are listed in Section 13.2 . This is an optional parameter that may be NULL .

Description

The [GetAttributes\(\)](#) function returns the mask of attributes that this PCI root bridge supports and the mask of attributes that the PCI root bridge is currently using. If *Supports* is not **NULL**, then *Supports* is set to the mask of attributes that the PCI root bridge supports. If *Attributes* is not **NULL**, then *Attributes* is set to the mask of attributes that the PCI root bridge is currently using. If both *Supports* and *Attributes* are **NULL**, then **EFI_INVALID_PARAMETER** is returned. Otherwise, **EFI_SUCCESS** is returned.

If a bit is set in *Supports*, then the PCI root bridge supports this attribute type, and a call can be made to [SetAttributes\(\)](#) using that attribute type. If a bit is set in *Attributes*, then the PCI root bridge is currently using that attribute type. Since a PCI host bus may be composed of more than one PCI root bridge, different *Attributes* values may be returned by different PCI root bridges.

Status Codes Returned

EFI_SUCCESS	If <i>Supports</i> is not NULL , then the attributes that the PCI root bridge supports is returned in <i>Supports</i> . If <i>Attributes</i> is not NULL , then the attributes that the PCI root bridge is currently using is returned in <i>Attributes</i> .
EFI_INVALID_PARAMETER	Both <i>Supports</i> and <i>Attributes</i> are NULL .

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.SetAttributes()

Summary

Sets attributes for a resource range on a PCI root bridge.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_SET_ATTRIBUTES) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL  *This,
    IN UINT64                            Attributes,
    IN OUT UINT64                        *ResourceBase    OPTIONAL,
    IN OUT UINT64                        *ResourceLength  OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL . Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section 13.2 .
<i>Attributes</i>	The mask of attributes to set. If the attribute bit MEMORY_WRITE_COMBINE , MEMORY_CACHED , or MEMORY_DISABLE is set, then the resource range is specified by <i>ResourceBase</i> and <i>ResourceLength</i> . If MEMORY_WRITE_COMBINE , MEMORY_CACHED , and MEMORY_DISABLE are not set, then <i>ResourceBase</i> and <i>ResourceLength</i> are ignored, and may be NULL . The available attributes are listed in Section 13.2 .
<i>ResourceBase</i>	A pointer to the base address of the resource range to be modified by the attributes specified by <i>Attributes</i> . On return, <i>*ResourceBase</i> will be set the actual base address of the resource range. Not all resources can be set to a byte boundary, so the actual base address may differ from the one passed in by the caller. This parameter is only used if the MEMORY_WRITE_COMBINE bit, the MEMORY_CACHED bit, or the MEMORY_DISABLE bit of <i>Attributes</i> is set. Otherwise, it is ignored, and may be NULL .
<i>ResourceLength</i>	A pointer to the length of the resource range to be modified by the attributes specified by <i>Attributes</i> . On return, <i>*ResourceLength</i> will be set the actual length of the resource range. Not all resources can be set to a byte boundary, so the actual length may differ from the one passed in by the caller. This parameter is only used if the MEMORY_WRITE_COMBINE bit, the MEMORY_CACHED bit, or the MEMORY_DISABLE bit of <i>Attributes</i> is set. Otherwise, it is ignored, and may be NULL .

Description

The **SetAttributes ()** function sets the attributes specified in *Attributes* for the PCI root bridge on the resource range specified by *ResourceBase* and *ResourceLength*. Since the granularity of setting these attributes may vary from resource type to resource type, and from platform to platform, the actual resource range and the one passed in by the caller may differ. As a result, this function may set the attributes specified by *Attributes* on a larger resource range than the caller requested. The actual range is returned in *ResourceBase* and *ResourceLength*. The caller is responsible for verifying that the actual range for which the attributes were set is acceptable.

If the attributes are set on the PCI root bridge, then the actual resource range is returned in *ResourceBase* and *ResourceLength*, and **EFI_SUCCESS** is returned.

If the attributes specified by *Attributes* are not supported by the PCI root bridge, then **EFI_UNSUPPORTED** is returned. The set of supported attributes for a PCI root bridge can be found by calling [GetAttributes \(\)](#).

If either *ResourceBase* or *ResourceLength* are **NULL**, and a resource range is required for the attributes specified in *Attributes*, then **EFI_INVALID_PARAMETER** is returned.

If more than one resource range is required for the set of attributes specified by *Attributes*, then **EFI_INVALID_PARAMETER** is returned.

If there are not enough resources available to set the attributes, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The set of attributes specified by <i>Attributes</i> for the resource range specified by <i>ResourceBase</i> and <i>ResourceLength</i> were set on the PCI root bridge, and the actual resource range is returned in <i>ResourceBase</i> and <i>ResourceLength</i> .
EFI_UNSUPPORTED	A bit is set in <i>Attributes</i> that is not supported by the PCI Root Bridge. The supported attribute bits are reported by GetAttributes () .
EFI_INVALID_PARAMETER	More than one attribute bit is set in <i>Attributes</i> that requires a resource range.
EFI_INVALID_PARAMETER	A resource range is required, and <i>ResourceBase</i> is NULL .
EFI_INVALID_PARAMETER	A resource range is required, and <i>ResourceLength</i> is NULL .
EFI_OUT_OF_RESOURCES	There are not enough resources to set the attributes on the resource range specified by <i>BaseAddress</i> and <i>Length</i> .

EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Configuration()

Summary

Retrieves the current resource settings of this PCI root bridge in the form of a set of ACPI 2.0 resource descriptors.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_CONFIGURATION) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    OUT VOID **Resources
);
```

Parameters

This

A pointer to the [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#). Type [EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL](#) is defined in [Section 13.2](#).

Resources

A pointer to the ACPI 2.0 resource descriptors that describe the current configuration of this PCI root bridge. The storage for the ACPI 2.0 resource descriptors is allocated by this function. The caller must treat the return buffer as read-only data, and the buffer must not be freed by the caller. See “Related Definitions” for the ACPI 2.0 resource descriptors that may be used.

Related Definitions

There are only two resource descriptor types from the *ACPI Specification* that may be used to describe the current resources allocated to a PCI root bridge. These are the QWORD Address Space Descriptor (ACPI 2.0 Section 6.4.3.5.1), and the End Tag (ACPI 2.0 Section 6.4.2.8). The QWORD Address Space Descriptor can describe memory, I/O, and bus number ranges for dynamic or fixed resources. The configuration of a PCI root bridge is described with one or more QWORD Address Space Descriptors followed by an End Tag. [Table 23](#) and [Table 89](#) contains these two descriptor types. Please see the *ACPI Specification* for details on the field values.

Table 88. ACPI 2.0 QWORD Address Space Descriptor

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x8A	QWORD Address Space Descriptor
0x01	0x02	0x2B	Length of this descriptor in bytes not including the first two fields
0x03	0x01		Resource Type 0 – Memory Range 1 – I/O Range 2 – Bus Number Range
0x04	0x01		General Flags
0x05	0x01		Type Specific Flags

0x06	0x08		Address Space Granularity
0x0E	0x08		Address Range Minimum
0x16	0x08		Address Range Maximum
0x1E	0x08		Address Translation Offset
0x26	0x08		Address Length

Table 89. ACPI 2.0 End Tag

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x79	End Tag
0x01	0x01	0x00	Checksum. If 0, then checksum is assumed to be valid.

Description

The **Configuration()** function retrieves a set of ACPI 2.0 resource descriptors that contains the current configuration of this PCI root bridge. If the current configuration can be retrieved, then it is returned in *Resources* and **EFI_SUCCESS** is returned. See “Related Definitions” below for the resource descriptor types that are supported by this function. If the current configuration cannot be retrieved, then **EFI_UNSUPPORTED** is returned.

Status Codes Returned

EFI_SUCCESS	The current configuration of this PCI root bridge was returned in <i>Resources</i> .
EFI_UNSUPPORTED	The current configuration of this PCI root bridge could not be retrieved.

13.2.1 PCI Root Bridge Device Paths

An [EFI PCI ROOT BRIDGE IO PROTOCOL](#) must be installed on a handle for its services to be available to drivers. In addition to the **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL**, an [EFI_DEVICE_PATH_PROTOCOL](#) must also be installed on the same handle. See [Section 9](#) for a detailed description of **EFI_DEVICE_PATH_PROTOCOL**.

Typically, an ACPI Device Path Node is used to describe a PCI Root Bridge. Depending on the bus hierarchy in the system, additional device path nodes may precede this ACPI Device Path Node. A desktop system will typically contain only one PCI Root Bridge, so there would be one handle with a **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** and an **EFI_DEVICE_PATH_PROTOCOL**. A server system may contain multiple PCI Root Bridges, so it would contain a handle for each PCI Root Bridge present, and on each of those handles would be an **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL** and an **EFI_DEVICE_PATH_PROTOCOL**. In all cases, the contents of the ACPI Device Path Nodes for PCI Root Bridges must match the information present in the ACPI tables for that system.

[Table 90](#) shows an example device path for a PCI Root Bridge in a desktop system. Today, a desktop system typically contains one PCI Root Bridge. This device path consists of an ACPI Device Path Node, and a Device Path End Structure. The **_HID** and **_UID** must match the ACPI

table description of the PCI Root Bridge. For a system with only one PCI Root Bridge, the `_UID` value is usually 0x0000. The shorthand notation for this device path is **ACPI (PNP0A03, 0)**.

Table 90. PCI Root Bridge Device Path for a Desktop System

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID PNP0A03</code> – 0x41D0 represents a compressed string 'PNP' and is in the low order bytes
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x0D	0x01	0xFF	Sub type – End of Entire Device Path
0x0E	0x02	0x04	Length – 0x04 bytes

[Table 91](#) through [Table 94](#) show example device paths for the PCI Root Bridges in a server system with four PCI Root Bridges. Each of these device paths consists of an ACPI Device Path Node, and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridges. The only difference between each of these device paths is the `_UID` field. The shorthand notation for these four device paths is **ACPI (PNP0A03, 0)**, **ACPI (PNP0A03, 1)**, **ACPI (PNP0A03, 2)**, and **ACPI (PNP0A03, 3)**.

Table 91. PCI Root Bridge Device Path for Bridge #0 in a Server System

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID PNP0A03</code> – 0x41D0 represents a compressed string 'PNP' and is in the low order bytes
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x0D	0x01	0xFF	Sub type – End of Entire Device Path
0x0E	0x02	0x04	Length – 0x04 bytes

Table 92. PCI Root Bridge Device Path for Bridge #1 in a Server System

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes

0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0001	_UID
0x0C	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x0D	0x01	0xFF	Sub type – End of Entire Device Path
0x0E	0x02	0x04	Length – 0x04 bytes

Table 93. PCI Root Bridge Device Path for Bridge #2 in a Server System

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0002	_UID
0x0C	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x0D	0x01	0xFF	Sub type – End of Entire Device Path
0x0E	0x02	0x04	Length – 0x04 bytes

Table 94. PCI Root Bridge Device Path for Bridge #3 in a Server System

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0003	_UID
0x0C	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x0D	0x01	0xFF	Sub type – End of Entire Device Path
0x0E	0x02	0x04	Length – 0x04 bytes

[Table 95](#) shows an example device path for a PCI Root Bridge using an Expanded ACPI Device Path. This device path consists of an Expanded ACPI Device Path Node, and a Device Path End Structure. The _UID and _CID fields must match the ACPI table description of the PCI Root Bridge. For a system with only one PCI Root Bridge, the _UID value is usually 0x0000. The shorthand notation for this device path is **ACPI (12345678, 0, PNP0A03)**.

Table 95. PCI Root Bridge Device Path Using Expanded ACPI Device Path

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x02	Sub type – Expanded ACPI Device Path
0x02	0x02	0x10	Length – 0x10 bytes
0x04	0x04	0x1234, 0x5678	_HID-device specific
0x08	0x04	0x0000	_UID
0x0C	0x04	0x41D0, 0x0A03	_CID PNP0A03 – 0x41D0 represents a compressed string 'PNP' and is in the low order bytes.
0x10	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x11	0x01	0xFF	Sub type – End of Entire Device Path
0x12	0x02	0x04	Length – 0x04 bytes

13.3 PCI Driver Model

[Section 13.3](#) and [Section 13.4](#) describe the PCI Driver Model. This includes the behavior of PCI Bus Drivers, the behavior of a PCI Device Drivers, and a detailed description of the PCI I/O Protocol. The PCI Bus Driver manages PCI buses present in a system, and PCI Device Drivers manage PCI controllers present on PCI buses. The PCI Device Drivers produce an I/O abstraction that can be used to boot an EFI compliant operating system.

This document provides enough material to implement a PCI Bus Driver, and the tools required to design and implement a PCI Device Drivers. It does not provide any information on specific PCI devices.

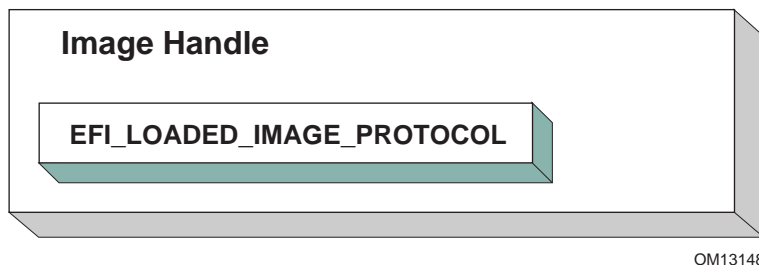
The material contained in this section is designed to extend this specification and the *UEFI Driver Model* in a way that supports PCI device drivers and PCI bus drivers. These extensions are provided in the form of PCI-specific protocols. This section provides the information required to implement a PCI Bus Driver in system firmware. The section also contains the information required by driver writers to design and implement PCI Device Drivers that a platform may need to boot a UEFI-compliant OS.

The PCI Driver Model described here is intended to be a foundation on which a PCI Bus Driver and a wide variety of PCI Device Drivers can be created.

13.3.1 PCI Driver Initialization

There are very few differences between a PCI Bus Driver and PCI Device Driver in the entry point of the driver. The file for a driver image must be loaded from some type of media. This could include ROM, FLASH, hard drives, floppy drives, CD-ROM, or even a network connection. Once a driver image has been found, it can be loaded into system memory with the Boot Service [LoadImage \(\)](#). **LoadImage ()** loads a PE/COFF formatted image into system memory. A handle is created for the driver, and a Loaded Image Protocol instance is placed on that handle. A handle that contains a Loaded Image Protocol instance is called an *Image Handle*. At this point, the

driver has not been started. It is just sitting in memory waiting to be started. [Figure 35](#) shows the state of an image handle for a driver after **LoadImage ()** has been called.



OM13148

Figure 35. Image Handle

After a driver has been loaded with the Boot Service [LoadImage \(\)](#), it must be started with the Boot Service [StartImage \(\)](#). This is true of all types of applications and drivers that can be loaded and started on an UEFI compliant system. The entry point for a driver that follows the UEFI Driver Model must follow some strict rules. First, it is not allowed to touch any hardware. Instead, it is only allowed to install protocol instances onto its own *Image Handle*. A driver that follows the UEFI Driver Model is *required* to install an instance of the Driver Binding Protocol onto its own *Image Handle*. It may optionally install the Driver Diagnostics Protocol or the Component Name Protocol. In addition, if a driver wishes to be unloadable it may optionally update the Loaded Image Protocol to provide its own [Unload \(\)](#) function. Finally, if a driver needs to perform any special operations when the Boot Service [EFI BOOT SERVICES](#) is called, it may optionally create an event with a notification function that is triggered when the Boot Service **ExitBootServices ()** is called. An *Image Handle* that contains a Driver Binding Protocol instance is known as a *Driver Image Handle*. [Figure 36](#) shows a possible configuration for the *Image Handle* from [Figure 35](#) after the Boot Service **StartImage ()** has been called.

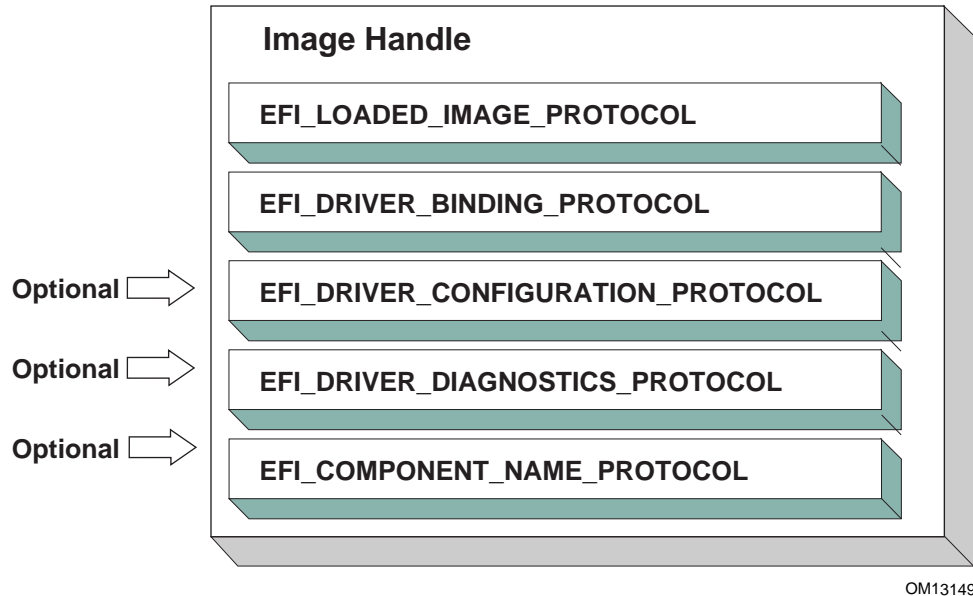


Figure 36. PCI Driver Image Handle

13.3.1.1 Driver Diagnostics Protocol

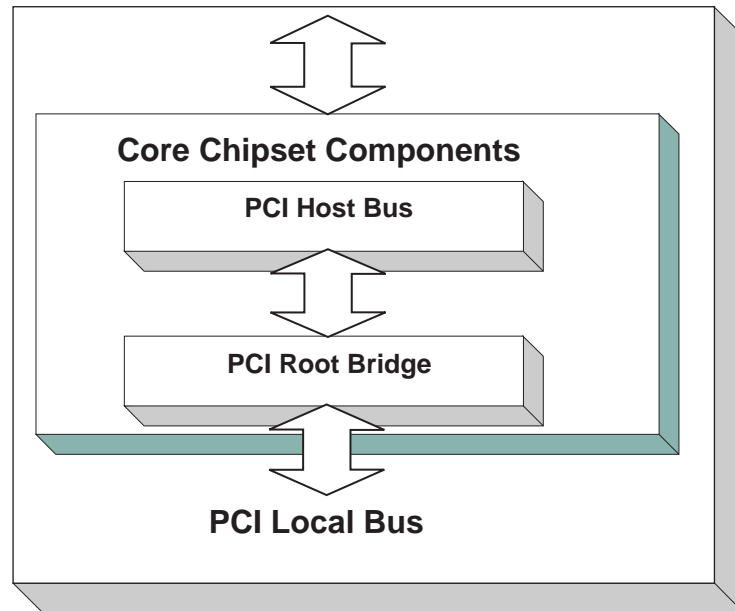
If a PCI Bus Driver or a PCI Device Driver requires diagnostics, then an [EFI DRIVER DIAGNOSTICS PROTOCOL](#) must be installed on the image handle in the entry point for the driver. This protocol contains functions to perform diagnostics on a controller. The [EFI DRIVER DIAGNOSTICS PROTOCOL](#) is not allowed to interact with the user. Instead, it must return status information through a buffer. The functions of this protocol will be invoked by a platform management utility. Please see the *EFI Driver Model Specification* for details on the [EFI_DRIVER_DIAGNOSTICS_PROTOCOL](#).

13.3.1.2 Component Name Protocol

Both a PCI Bus Driver and a PCI Device Driver are able to produce user readable names for the PCI drivers and/or the set of PCI controllers that the PCI drivers are managing. This is accomplished by installing an instance of the [EFI COMPONENT_NAME2 PROTOCOL](#) on the image handle of the driver. This protocol can produce driver and controller names in the form of a Unicode string in one of several languages. This protocol can be used by a platform management utility to display user readable names for the drivers and controllers present in a system. Please see the *EFI Driver Model Specification* for details on the [EFI_COMPONENT_NAME_PROTOCOL](#).

13.3.2 PCI Bus Drivers

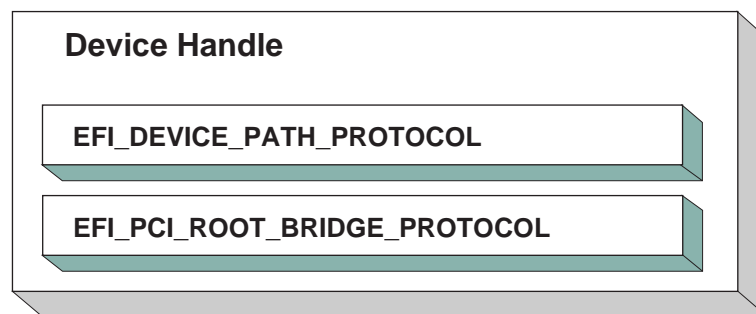
A PCI Bus Driver manages PCI Host Bus Controllers that can contain one or more PCI Root Bridges. [Figure 37](#) shows an example of a desktop system that has one PCI Host Bus Controller with one PCI Root Bridge.



OM13161

Figure 37. PCI Host Bus Controller

The PCI Host Bus Controller in [Figure 37](#) is abstracted in software with the PCI Root Bridge I/O Protocol. A PCI Bus Driver will manage handles that contain this protocol. [Figure 38](#) shows an example device handle for a PCI Host Bus Controller. It contains a Device Path Protocol instance and a PCI Root Bridge I/O Protocol Instance.



OM13151

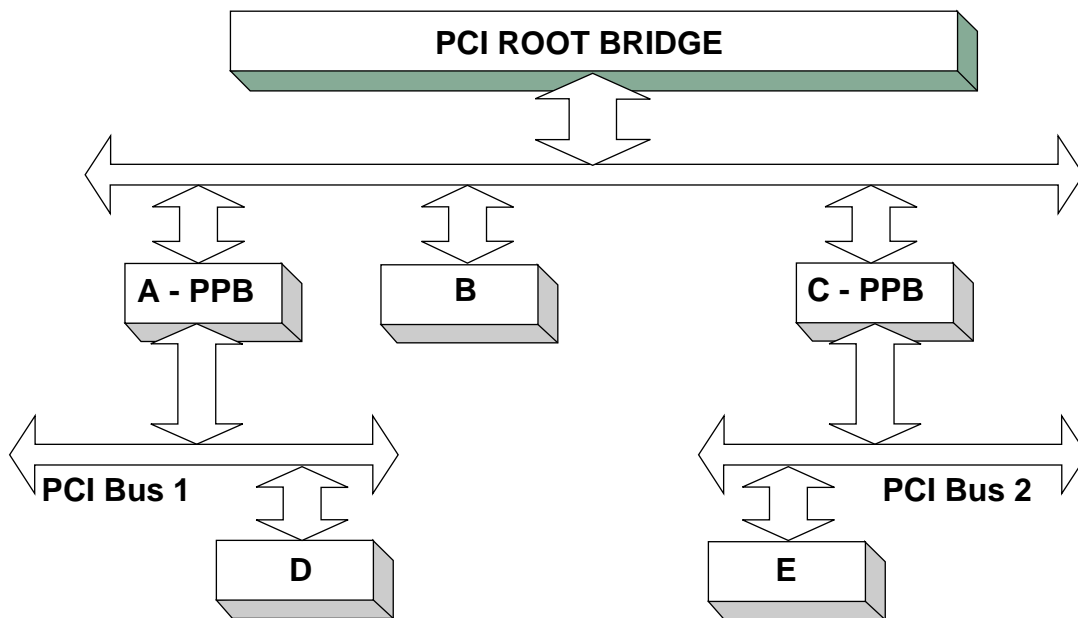
Figure 38. Device Handle for a PCI Host Bus Controller

13.3.2.1 Driver Binding Protocol for PCI Bus Drivers

The Driver Binding Protocol contains three services. These are [Supported\(\)](#), [Start\(\)](#), and [Stop\(\)](#). **Supported()** tests to see if the PCI Bus Driver can manage a device handle. A PCI Bus Driver can only manage device handles that contain the Device Path Protocol and the PCI Root

Bridge I/O Protocol, so a PCI Bus Driver must look for these two protocols on the device handle that is being tested.

The **Start()** function tells the PCI Bus Driver to start managing a device handle. The device handle should support the protocols shown in [Figure 38](#). The PCI Root Bridge I/O Protocols provides access to the PCI I/O, PCI Memory, PCI Prefetchable Memory, and PCI DMA functions. The PCI Controllers behind a PCI Root Bridge may exist on one or more PCI Buses. The standard mechanism for expanding the number of PCI Buses on a single PCI Root Bridge is to use PCI to PCI Bridges. Once a PCI Enumerator configures these bridges, they are invisible to software. As a result, the PCI Bus Driver flattens the PCI Bus hierarchy when it starts managing a device handle that represents a PCI Host Controller. [Figure 39](#) shows the physical tree structure for a set of PCI Device denoted by A, B, C, D, and E. Device A and C are PCI to PCI Bridges.



OM13166

Figure 39. Physical PCI Bus Structure

[Figure 40](#) shows the tree structure generated by a PCI Bus Driver before and after **Start()** is called. This is a logical view of set of PCI controller, and not a physical view. The physical tree is flattened, so any PCI to PCI bridge devices are invisible. In this example, the PCI Bus Driver finds the five child PCI Controllers on the PCI Bus from [Figure 39](#). A device handle is created for every PCI Controller including all the PCI to PCI Bridges. The arrow with the dashed line coming into the PCI Host Bus Controller represents a link to the PCI Host Bus Controller's parent. If the PCI Host Bus Controller is a Root Bus Controller, then it will not have a parent. The PCI Driver Model does not require that a PCI Host Bus Controller be a Root Bus Controller. A PCI Host Bus Controller can be present at any location in the tree, and the PCI Bus Driver should be able to manage the PCI Host Bus Controller.

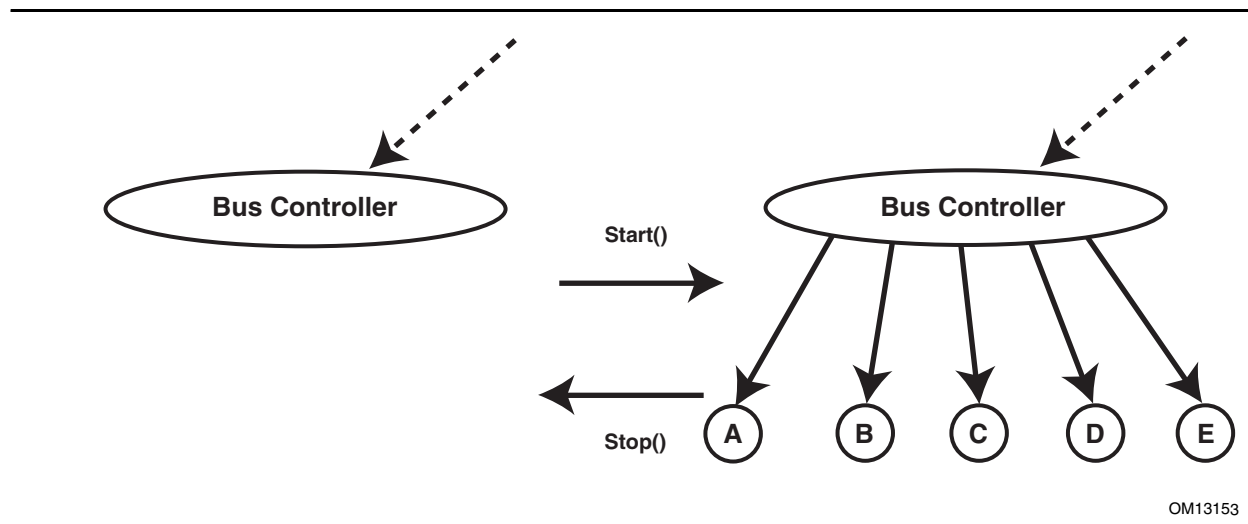


Figure 40. Connecting a PCI Bus Driver

The PCI Bus Driver has the option of creating all of its children in one call to [Start\(\)](#), or spreading it across several calls to **Start()**. In general, if it is possible to design a bus driver to create one child at a time, it should do so to support the rapid boot capability in the UEFI Driver Model. Each of the child device handles created in **Start()** must contain a Device Path Protocol instance, a PCI I/O protocol instance, and optionally a Bus Specific Driver Override Protocol instance. The PCI I/O Protocol is described in [Section 13.4](#). The format of device paths for PCI Controllers is described in Section 2.6, and details on the Bus Specific Driver Override Protocol can be found in the *EFI Driver Model Specification*. [Figure 41](#) shows an example child device handle that is created by a PCI Bus Driver for a PCI Controller.

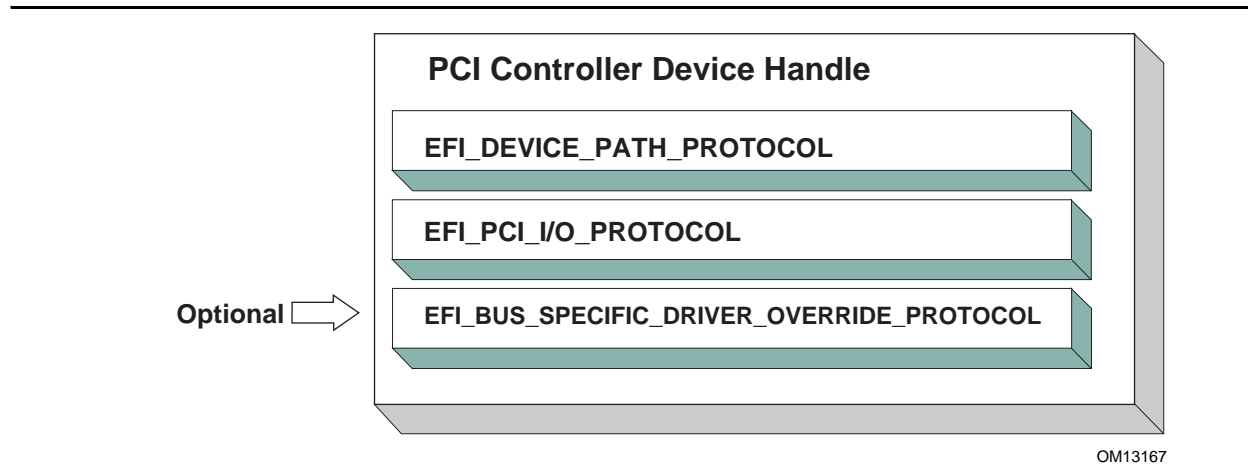


Figure 41. Child Handle Created by a PCI Bus Driver

A PCI Bus Driver must perform several steps to manage a PCI Host Bus Controller, as follows:

- Initialize the PCI Host Bus Controller.

- If the PCI buses have not been initialized by a previous agent, perform PCI Enumeration on all the PCI Root Bridges that the PCI Host Bus Controller contains. This involves assigning a PCI bus number, allocating PCI I/O resources, PCI Memory resources, and PCI Prefetchable Memory resources.
- Discover all the PCI Controllers on all the PCI Root Bridges. If a PCI Controller is a PCI to PCI Bridge, then the I/O, Memory, and Bus Master bits in the Control register of the PCI Configuration Header should be placed in the enabled state. The PCI Bus Driver should disable the I/O, Memory, and Bus Master bits for PCI Controllers that respond to legacy ISA resources (e.g. VGA). It is a PCI Device Driver's responsibility to enable the I/O, Memory, and Bus Master bits (if they are not already enabled by the PCI bus driver) of the Control register as required with a call to the [Attributes \(\)](#) service when the PCI Device Driver is started. A similar call to the [Attributes \(\)](#) service should be made when the PCI Device Driver is stopped to restore original [Attributes \(\)](#) state, including the I/O, Memory, and Bus Master bits of the Control register.
- Create a device handle for each PCI Controller found. If a request is being made to start only one PCI Controller, then only create one device handle.
- Install a Device Path Protocol instance and a PCI I/O Protocol instance on the device handle created for each PCI Controller.
- If the PCI Controller has a PCI Option ROM, then allocate a memory buffer that is the same size as the PCI Option ROM, and copy the PCI Option ROM contents to the memory buffer.
- If the PCI Option ROM contains any UEFI drivers, then attach a Bus Specific Driver Override Protocol to the device handle of the PCI Controller that is associated with the PCI Option ROM.

The [Stop \(\)](#) function tells the PCI Bus Driver to stop managing a PCI Host Bus Controller. The [Stop \(\)](#) function can destroy one or more of the device handles that were created on a previous call to [Start \(\)](#). If all of the child device handles have been destroyed, then [Stop \(\)](#) will place the PCI Host Bus Controller in a quiescent state. The functionality of [Stop \(\)](#) mirrors [Start \(\)](#), as follows:

1. Complete all outstanding transactions to the PCI Host Bus Controller.
2. If the PCI Host Bus Controller is being stopped, then place it in a quiescent state.
3. If one or more child handles are being destroyed, then:
 - a Uninstall all the protocols from the device handles for the PCI Controllers found in [Start \(\)](#).
 - b Free any memory buffers allocated for PCI Option ROMs.
 - c Destroy the device handles for the PCI controllers created in [Start \(\)](#).

13.3.2.2 PCI Enumeration

The PCI Enumeration process is a platform-specific operation that depends on the properties of the chipset that produces the PCI bus. As a result, details on PCI Enumeration are outside the scope of this document. A PCI Bus Driver requires that PCI Enumeration has been performed, so it either needs to have been done prior to the PCI Bus Driver starting, or it must be part of the PCI Bus Driver's implementation.

13.3.3 PCI Device Drivers

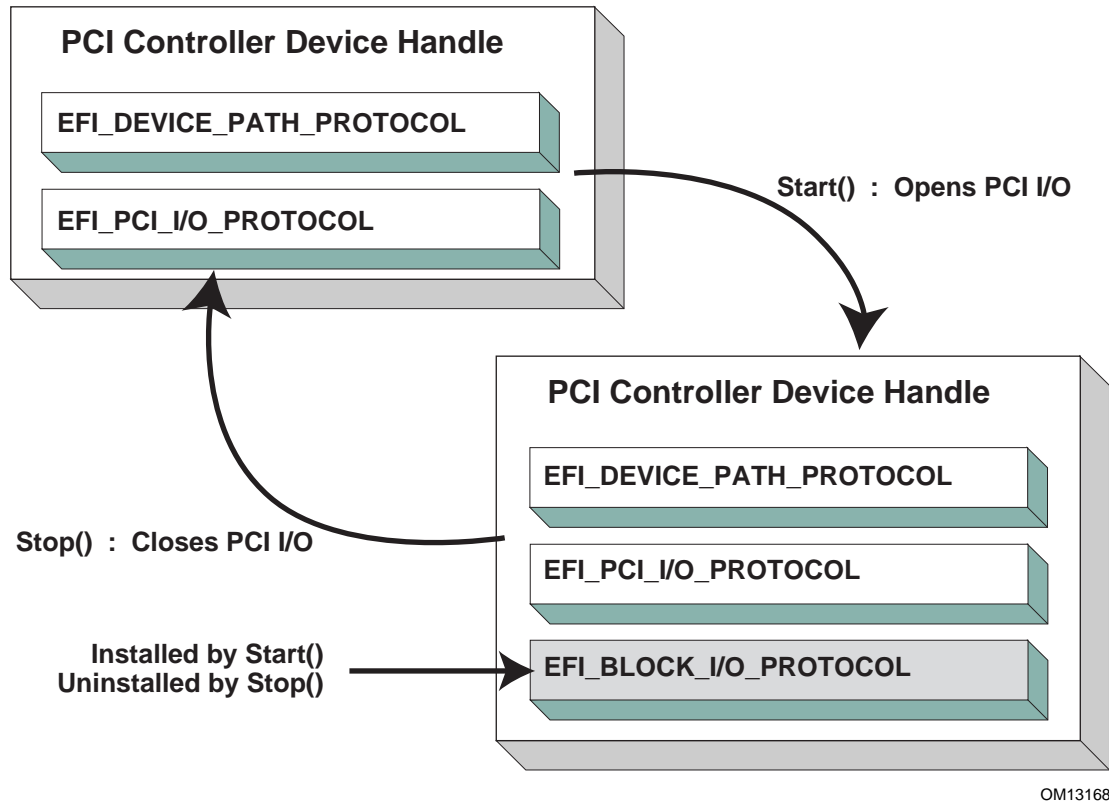
PCI Device Drivers manage PCI Controllers. Device handles for PCI Controllers are created by PCI Bus Drivers. A PCI Device Driver is not allowed to create any new device handles. Instead, it attaches protocol instance to the device handle of the PCI Controller. These protocol instances are I/O abstractions that allow the PCI Controller to be used in the preboot environment. The most common I/O abstractions are used to boot an EFI compliant OS.

13.3.3.1 Driver Binding Protocol for PCI Device Drivers

The Driver Binding Protocol contains three services. These are [Supported\(\)](#), [Start\(\)](#), and [Stop\(\)](#). **Supported()** tests to see if the PCI Device Driver can manage a device handle. A PCI Device Driver can only manage device handles that contain the Device Path Protocol and the PCI I/O Protocol, so a PCI Device Driver must look for these two protocols on the device handle that is being tested. In addition, it needs to check to see if the device handle represents a PCI Controller that the PCI Device Driver knows how to manage. This is typically done by using the services of the PCI I/O Protocol to read the PCI Configuration Header for the PCI Controller, and looking at the *VendorId*, *DeviceId*, and *SubsystemId* fields.

The **Start()** function tells the PCI Device Driver to start managing a PCI Controller. A PCI Device Driver is not allowed to create any new device handles. Instead, it installs one or more addition protocol instances on the device handle for the PCI Controller. A PCI Device Driver is not allowed to modify the resources allocated to a PCI Controller. These resource allocations are owned by the PCI Bus Driver or some other firmware component that initialized the PCI Bus prior to the execution of the PCI Bus Driver. This means that the PCI BARs (Base Address Registers) and the configuration of any PCI to PCI bridge controllers must not be modified by a PCI Device Driver. A PCI Bus Driver will leave a PCI Device in a disabled safe initial state. A PCI Device Driver should save the original **Attributes()** state. It is a PCI Device Driver's responsibility to call **Attributes()** to enable the I/O, Memory, and Bus Master decodes if they are not already enabled by the PCI bus driver.

The [Stop\(\)](#) function mirrors the [Start\(\)](#) function, so the **Stop()** function completes any outstanding transactions to the PCI Controller and removes the protocol interfaces that were installed in **Start()**. [Figure 42](#) shows the device handle for a PCI Controller before and after **Start()** is called. In this example, a PCI Device Driver is adding the Block I/O Protocol to the device handle for the PCI Controller. It is also a PCI Device Driver's responsibility to restore original **Attributes()** state, including the I/O, Memory, and Bus Master decodes by calling [Attributes\(\)](#).



OM13168

Figure 42. Connecting a PCI Device Driver

13.4 EFI PCI I/O Protocol

This section provides a detailed description of the [EFI PCI IO PROTOCOL](#). This protocol is used by code, typically drivers, running in the EFI boot services environment to access memory and I/O on a PCI controller. In particular, functions for managing devices on PCI buses are defined here.

The interfaces provided in the [EFI_PCI_IO_PROTOCOL](#) are for performing basic operations to memory, I/O, and PCI configuration space. The system provides abstracted access to basic system resources to allow a driver to have a programmatic method to access these basic system resources. The main goal of this protocol is to provide an abstraction that simplifies the writing of device drivers for PCI devices. This goal is accomplished by providing the following features:

- A driver model that does not require the driver to search the PCI busses for devices to manage. Instead, drivers are provided the location of the device to manage or have the capability to be notified when a PCI controller is discovered.
- A device driver model that abstracts the I/O addresses, Memory addresses, and PCI Configuration addresses from the PCI device driver. Instead, BAR (Base Address Register) relative addressing is used for I/O and Memory accesses, and device relative addressing is used for PCI Configuration accesses. The BAR relative addressing is specified in the PCI I/O services as a BAR index. A PCI controller may contain a combination of 32-bit and 64-bit

BARs. The BAR index represents the logical BAR number in the standard PCI configuration header starting from the first BAR. The BAR index does not represent an offset into the standard PCI Configuration Header because those offsets will vary depending on the combination and order of 32-bit and 64-bit BARs.

- The Device Path for the PCI device can be obtained from the same device handle that the **EFI_PCI_IO_PROTOCOL** resides.
- The PCI Segment, PCI Bus Number, PCI Device Number, and PCI Function Number of the PCI device if they are required. The general idea is to abstract these details away from the PCI device driver. However, if these details are required, then they are available.
- Details on any nonstandard address decoding that is not covered by the PCI device's Base Address Registers.
- Access to the PCI Root Bridge I/O Protocol for the PCI Host Bus for which the PCI device is a member.
- A copy of the PCI Option ROM if it is present in system memory.
- Functions to perform bus mastering DMA. This includes both packet based DMA and common buffer DMA.

EFI_PCI_IO_PROTOCOL

Summary

Provides the basic Memory, I/O, PCI configuration, and DMA interfaces that a driver uses to access its PCI controller.

GUID

```
#define EFI_PCI_IO_PROTOCOL_GUID \
    {0x4cf5b200, 0x68b8, 0x4ca5, 0x9e, 0xec, 0xb2, 0x3e, 0x3f, 0x50, \
     0x2, 0x9a}
```

Protocol Interface Structure

```
typedef struct _EFI_PCI_IO_PROTOCOL {
    EFI_PCI_IO_PROTOCOL_POLL_IO_MEM    PollMem;
    EFI_PCI_IO_PROTOCOL_POLL_IO_MEM    PollIo;
    EFI_PCI_IO_PROTOCOL_ACCESS         Mem;
    EFI_PCI_IO_PROTOCOL_ACCESS         Io;
    EFI_PCI_IO_PROTOCOL_CONFIG_ACCESS  Pci;
    EFI_PCI_IO_PROTOCOL_COPY_MEM       CopyMem;
    EFI_PCI_IO_PROTOCOL_MAP            Map;
    EFI_PCI_IO_PROTOCOL_UNMAP          Unmap;
    EFI_PCI_IO_PROTOCOL_ALLOCATE_BUFFER AllocateBuffer;
    EFI_PCI_IO_PROTOCOL_FREE_BUFFER    FreeBuffer;
    EFI_PCI_IO_PROTOCOL_FLUSH          Flush;
    EFI_PCI_IO_PROTOCOL_GET_LOCATION   GetLocation;
    EFI_PCI_IO_PROTOCOL_ATTRIBUTES     Attributes;
}
```

```

EFI_PCI_IO_PROTOCOL_GET_BAR_ATTRIBUTES  GetBarAttributes;
EFI_PCI_IO_PROTOCOL_SET_BAR_ATTRIBUTES  SetBarAttributes;
UINT64                                  RomSize;
VOID                                     *RomImage;
} EFI_PCI_IO_PROTOCOL;

```

Parameters

<i>PollMem</i>	Polls an address in PCI memory space until an exit condition is met, or a timeout occurs. See the PollMem() function description.
<i>PollIo</i>	Polls an address in PCI I/O space until an exit condition is met, or a timeout occurs. See the PollIo() function description.
<i>Mem.Read</i>	Allows BAR relative reads to PCI memory space. See the Mem.Read() function description.
<i>Mem.Write</i>	Allows BAR relative writes to PCI memory space. See the Mem.Write() function description.
<i>Io.Read</i>	Allows BAR relative reads to PCI I/O space. See the Io.Read() function description.
<i>Io.Write</i>	Allows BAR relative writes to PCI I/O space. See the Io.Write() function description.
<i>Pci.Read</i>	Allows PCI controller relative reads to PCI configuration space. See the Pci.Read() function description.
<i>Pci.Write</i>	Allows PCI controller relative writes to PCI configuration space. See the Pci.Write() function description.
<i>CopyMem</i>	Allows one region of PCI memory space to be copied to another region of PCI memory space. See the CopyMem() function description.
<i>Map</i>	Provides the PCI controller-specific address needed to access system memory for DMA. See the Map() function description.
<i>Unmap</i>	Releases any resources allocated by Map() . See the Unmap() function description.
<i>AllocateBuffer</i>	Allocates pages that are suitable for a common buffer mapping. See the AllocateBuffer() function description.
<i>FreeBuffer</i>	Frees pages that were allocated with AllocateBuffer() . See the FreeBuffer() function description.
<i>Flush</i>	Flushes all PCI posted write transactions to system memory. See the Flush() function description.
<i>GetLocation</i>	Retrieves this PCI controller's current PCI bus number, device number, and function number. See the GetLocation() function description.
<i>Attributes</i>	Performs an operation on the attributes that this PCI controller supports. The operations include getting the set of supported attributes, retrieving the current attributes, setting the current

<i>GetBarAttributes</i>	attributes, enabling attributes, and disabling attributes. See the Attributes () function description.
<i>SetBarAttributes</i>	Gets the attributes that this PCI controller supports setting on a BAR using SetBarAttributes () , and retrieves the list of resource descriptors for a BAR. See the GetBarAttributes () function description.
<i>RomSize</i>	Sets the attributes for a range of a BAR on a PCI controller. See the SetBarAttributes () function description.
<i>RomImage</i>	The size, in bytes, of the ROM image. A pointer to the in memory copy of the ROM image. The PCI Bus Driver is responsible for allocating memory for the ROM image, and copying the contents of the ROM to memory. The contents of this buffer are either from the PCI option ROM that can be accessed through the ROM BAR of the PCI controller, or it is from a platform-specific location. The Attributes () function can be used to determine from which of these two sources the <i>RomImage</i> buffer was initialized.

Related Definitions

```

//*****
// EFI_PCI_IO_PROTOCOL_WIDTH
//*****
typedef enum {
    EfiPciIoWidthUint8,
    EfiPciIoWidthUint16,
    EfiPciIoWidthUint32,
    EfiPciIoWidthUint64,
    EfiPciIoWidthFifoUint8,
    EfiPciIoWidthFifoUint16,
    EfiPciIoWidthFifoUint32,
    EfiPciIoWidthFifoUint64,
    EfiPciIoWidthFillUint8,
    EfiPciIoWidthFillUint16,
    EfiPciIoWidthFillUint32,
    EfiPciIoWidthFillUint64,
    EfiPciIoWidthMaximum
} EFI_PCI_IO_PROTOCOL_WIDTH;

#define EFI_PCI_IO_PASS_THROUGH_BAR    0xff

//*****
// EFI_PCI_IO_PROTOCOL_POLL_IO_MEM
//*****
typedef
EFI_STATUS

```

```

(EFIAPI *EFI_PCI_IO_PROTOCOL_POLL_IO_MEM) (
    IN  EFI_PCI_IO_PROTOCOL  *This,
    IN  EFI_PCI_IO_PROTOCOL_WIDTH  Width,
    IN  UINT8                BarIndex,
    IN  UINT64               Offset,
    IN  UINT64               Mask,
    IN  UINT64               Value,
    IN  UINT64               Delay,
    OUT UINT64               *Result
);
//*****
// EFI_PCI_IO_PROTOCOL_IO_MEM
//*****
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_IO_MEM) (
    IN  EFI_PCI_IO_PROTOCOL  *This,
    IN  EFI_PCI_IO_PROTOCOL_WIDTH  Width,
    IN  UINT8                BarIndex,
    IN  UINT64               Offset,
    IN  UINTN                Count,
    IN OUT VOID              *Buffer
);

//*****
// EFI_PCI_IO_PROTOCOL_ACCESS
//*****
typedef struct {
    EFI_PCI_IO_PROTOCOL_IO_MEM  Read;
    EFI_PCI_IO_PROTOCOL_IO_MEM  Write;
} EFI_PCI_IO_PROTOCOL_ACCESS;

//*****
// EFI_PCI_IO_PROTOCOL_CONFIG
//*****
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_CONFIG) (
    IN  EFI_PCI_IO_PROTOCOL  *This,
    IN  EFI_PCI_IO_PROTOCOL_WIDTH  Width,
    IN  UINT32               Offset,
    IN  UINTN                Count,
    IN OUT VOID              *Buffer
);

```

```

//*****
// EFI_PCI_IO_PROTOCOL_CONFIG_ACCESS
//*****
typedef struct {
    EFI_PCI_IO_PROTOCOL_CONFIG  Read;
    EFI_PCI_IO_PROTOCOL_CONFIG  Write;
} EFI_PCI_IO_PROTOCOL_CONFIG_ACCESS;
//*****
// EFI PCI I/O Protocol Attribute bits
//*****
#define EFI_PCI_IO_ATTRIBUTE_ISA_MOTHERBOARD_IO    0x0001
#define EFI_PCI_IO_ATTRIBUTE_ISA_IO                0x0002
#define EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO        0x0004
#define EFI_PCI_IO_ATTRIBUTE_VGA_MEMORY            0x0008
#define EFI_PCI_IO_ATTRIBUTE_VGA_IO                0x0010
#define EFI_PCI_IO_ATTRIBUTE_IDE_PRIMARY_IO        0x0020
#define EFI_PCI_IO_ATTRIBUTE_IDE_SECONDARY_IO      0x0040
#define EFI_PCI_IO_ATTRIBUTE_MEMORY_WRITE_COMBINE  0x0080
#define EFI_PCI_IO_ATTRIBUTE_IO                    0x0100
#define EFI_PCI_IO_ATTRIBUTE_MEMORY                0x0200
#define EFI_PCI_IO_ATTRIBUTE_BUS_MASTER            0x0400
#define EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED         0x0800
#define EFI_PCI_IO_ATTRIBUTE_MEMORY_DISABLE        0x1000
#define EFI_PCI_IO_ATTRIBUTE_EMBEDDED_DEVICE       0x2000
#define EFI_PCI_IO_ATTRIBUTE_EMBEDDED_ROM          0x4000
#define EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE    0x8000
#define EFI_PCI_IO_ATTRIBUTE_ISA_IO_16             0x10000
#define EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16     0x20000
#define EFI_PCI_IO_ATTRIBUTE_VGA_IO_16             0x40000

```

EFI_PCI_IO_ATTRIBUTE_ISA_IO_16

If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded to the PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles. This bit may not be combined with

EFI_PCI_IO_ATTRIBUTE_ISA_IO.

EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16

If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded to the PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers on a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the

PCI Controller are configured to forward these PCI I/O cycles. This bit may not be combined with **EFI_PCI_IO_ATTRIBUTE_VGA_IO** or **EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO**.

EFI_PCI_IO_ATTRIBUTE_VGA_IO_16

If this bit is set, then the PCI I/O cycles in the ranges 0x3B0–0x3BB and 0x3C0–0x3DF are forwarded to the PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles. This bit may not be combined with **EFI_PCI_IO_ATTRIBUTE_VGA_IO** or **EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO**. Because **EFI_PCI_IO_ATTRIBUTE_VGA_IO_16** also includes the I/O range described by **EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16**, the **EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16** bit is ignored if **EFI_PCI_IO_ATTRIBUTE_VGA_IO_16** is set.

EFI_PCI_IO_ATTRIBUTE_ISA_MOTHERBOARD_IO

If this bit is set, then the PCI I/O cycles between 0x00000000 and 0x000000FF are forwarded to the PCI controller. This bit is used to forward I/O cycles for ISA motherboard devices. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_ISA_IO

If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded to the PCI controller using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO

If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded to the PCI controller using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers on a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_VGA_MEMORY

If this bit is set, then the PCI memory cycles between 0xA0000 and 0xBFFFF are forwarded to the PCI controller. This bit is used to forward memory cycles for a VGA frame buffer on a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI Memory cycles.

EFI_PCI_IO_ATTRIBUTE_VGA_IO

If this bit is set, then the PCI I/O cycles in the ranges 0x3B0-0x3BB and 0x3C0-0x3DF are forwarded to the PCI controller using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and the address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles. Since **EFI_PCI_IO_ATTRIBUTE_VGA_IO** also includes the I/O range described by **EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO**, the **EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO** bit is ignored if **EFI_PCI_IO_ATTRIBUTE_VGA_IO** is set.

EFI_PCI_IO_ATTRIBUTE_IDE_PRIMARY_IO

If this bit is set, then the PCI I/O cycles in the ranges 0x1F0-0x1F7 and 0x3F6-0x3F7 are forwarded to a PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Primary IDE controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_IDE_SECONDARY_IO

If this bit is set, then the PCI I/O cycles in the ranges 0x170-0x177 and 0x376-0x377 are forwarded to a PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Secondary IDE controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_MEMORY_WRITE_COMBINE

If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a write combining mode. This bit is used to improve the write performance to a memory buffer on a PCI controller. By default, PCI memory ranges are not accessed in a write combining mode.

EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED

If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a cached mode. By default, PCI memory ranges are accessed noncached.

EFI_PCI_IO_ATTRIBUTE_IO

If this bit is set, then the PCI device will decode the PCI I/O cycles that the device is configured to decode.

EFI_PCI_IO_ATTRIBUTE_MEMORY

If this bit is set, then the PCI device will decode the PCI Memory cycles that the device is configured to decode.

EFI_PCI_IO_ATTRIBUTE_BUS_MASTER

If this bit is set, then the PCI device is allowed to act as a bus master on the PCI bus.

EFI_PCI_IO_ATTRIBUTE_MEMORY_DISABLE

If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is disabled, and can no longer be accessed. By default, all PCI memory ranges are enabled.

EFI_PCI_IO_ATTRIBUTE_EMBEDDED_DEVICE

If this bit is set, then the PCI controller is an embedded device that is typically a component on the system board. If this bit is clear, then this PCI controller is part of an adapter that is populating one of the systems PCI slots.

EFI_PCI_IO_ATTRIBUTE_EMBEDDED_ROM

If this bit is set, then the PCI option ROM described by the *RomImage* and *RomSize* fields is not from ROM BAR of the PCI controller. If this bit is clear, then the *RomImage* and *RomSize* fields were initialized based on the PCI option ROM found through the ROM BAR of the PCI controller.

EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE

If this bit is set, then the PCI controller is capable of producing PCI Dual Address Cycles, so it is able to access a 64-bit address space. If this bit is not set, then the PCI controller is not capable of producing PCI Dual Address Cycles, so it is only able to access a 32-bit address space.

```
//*****
// EFI_PCI_IO_PROTOCOL_OPERATION
//*****
typedef enum {
    EfiPciIoOperationBusMasterRead,
    EfiPciIoOperationBusMasterWrite,
    EfiPciIoOperationBusMasterCommonBuffer,
    EfiPciIoOperationMaximum
} EFI_PCI_IO_PROTOCOL_OPERATION;
```

EfiPciIoOperationBusMasterRead

A read operation from system memory by a bus master.

EfiPciIoOperationBusMasterWrite

A write operation to system memory by a bus master.

EfiPciIoOperationBusMasterCommonBuffer

Provides both read and write access to system memory by both the processor and a bus master. The buffer is coherent from both the processor's and the bus master's point of view.

Description

The **EFI_PCI_IO_PROTOCOL** provides the basic Memory, I/O, PCI configuration, and DMA interfaces that are used to abstract accesses to PCI controllers. There is one **EFI_PCI_IO_PROTOCOL** instance for each PCI controller on a PCI bus. A device driver that wishes to manage a PCI controller in a system will have to retrieve the **EFI_PCI_IO_PROTOCOL** instance that is associated with the PCI controller. A device handle for a PCI controller will

minimally contain an [EFI_DEVICE_PATH_PROTOCOL](#) instance and an [EFI_PCI_IO_PROTOCOL](#) instance.

Bus mastering PCI controllers can use the DMA services for DMA operations. There are three basic types of bus mastering DMA that is supported by this protocol. These are DMA reads by a bus master, DMA writes by a bus master, and common buffer DMA. The DMA read and write operations may need to be broken into smaller chunks. The caller of [Map\(\)](#) must pay attention to the number of bytes that were mapped, and if required, loop until the entire buffer has been transferred. The following is a list of the different bus mastering DMA operations that are supported, and the sequence of [EFI_PCI_IO_PROTOCOL](#) interfaces that are used for each DMA operation type.

DMA Bus Master Read Operation

Call [Map\(\)](#) for EfiPciIoOperationBusMasterRead.

Program the DMA Bus Master with the *DeviceAddress* returned by [Map\(\)](#).

Start the DMA Bus Master.

Wait for DMA Bus Master to complete the read operation.

Call [Unmap\(\)](#).

DMA Bus Master Write Operation

Call [Map\(\)](#) for EfiPciIoOperationBusMasterWrite.

Program the DMA Bus Master with the *DeviceAddress* returned by [Map\(\)](#).

Start the DMA Bus Master.

Wait for DMA Bus Master to complete the write operation.

Perform a PCI controller specific read transaction to flush all PCI write buffers (See *PCI Specification* Section 3.2.5.2).

Call [Flush\(\)](#).

Call [Unmap\(\)](#).

DMA Bus Master Common Buffer Operation

Call [AllocateBuffer\(\)](#) to allocate a common buffer.

Call [Map\(\)](#) for EfiPciIoOperationBusMasterCommonBuffer.

Program the DMA Bus Master with the *DeviceAddress* returned by [Map\(\)](#).

The common buffer can now be accessed equally by the processor and the DMA bus master.

Call [Unmap\(\)](#).

Call [FreeBuffer\(\)](#).

EFI_PCI_IO_PROTOCOL.PollMem()

Summary

Reads from the memory space of a PCI controller. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_POLL_IO_MEM) (
    IN  EFI_PCI_IO_PROTOCOL      *This,
    IN  EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN  UINT8                    BarIndex,
    IN  UINT64                   Offset,
    IN  UINT64                   Mask,
    IN  UINT64                   Value,
    IN  UINT64                   Delay,
    OUT UINT64                   *Result
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI IO PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH is defined in Section 13.4 .
<i>BarIndex</i>	The BAR index of the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass <i>Offset</i> to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in Section 13.4 .
<i>Offset</i>	The offset within the selected BAR to start the memory operation.
<i>Mask</i>	Mask used for the polling criteria. Bytes above <i>Width</i> in <i>Mask</i> are ignored. The bits in the bytes below <i>Width</i> which are zero in <i>Mask</i> are ignored when polling the memory address.
<i>Value</i>	The comparison value used for the polling exit criteria.
<i>Delay</i>	The number of 100 ns units to poll. Note that timer available may be of poorer granularity.
<i>Result</i>	Pointer to the last value read from the memory location.

Description

This function provides a standard way to poll a PCI memory location. A PCI memory read operation is performed at the PCI memory address specified by *BarIndex* and *Offset* for the width specified by *Width*. The result of this PCI memory read operation is stored in *Result*. This PCI memory read operation is repeated until either a timeout of *Delay* 100 ns units has expired, or (*Result & Mask*) is equal to *Value*.

This function will always perform at least one memory access no matter how small *Delay* may be. If *Delay* is 0, then *Result* will be returned with a status of **EFI_SUCCESS** even if *Result* does not match the exit criteria. If *Delay* expires, then **EFI_TIMEOUT** is returned.

If *Width* is not **EfiPciIoWidthUint8**, **EfiPciIoWidthUint16**, **EfiPciIoWidthUint32**, or **EfiPciIoWidthUint64**, then **EFI_INVALID_PARAMETER** is returned.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI controller on a platform might require. For example on some platforms, width requests of **EfiPciIoWidthUint64** do not work.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. However, if the memory mapped I/O region being accessed by this function has the **EFI_PCI_ATTRIBUTE_MEMORY_CACHED** attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

EFI_SUCCESS	The last data returned from the access matched the poll exit criteria.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Result</i> is NULL .
EFI_UNSUPPORTED	<i>BarIndex</i> not valid for this PCI controller.
EFI_UNSUPPORTED	<i>Offset</i> is not valid for the <i>BarIndex</i> of this PCI controller.
EFI_TIMEOUT	<i>Delay</i> expired before a match occurred.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL.PollIo()

Summary

Reads from the I/O space of a PCI controller. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_POLL_IO_MEM) (
    IN  EFI_PCI_IO_PROTOCOL      *This,
    IN  EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN  UINT8                    BarIndex,
    IN  UINT64                   Offset,
    IN  UINT64                   Mask,
    IN  UINT64                   Value,
    IN  UINT64                   Delay,
    OUT UINT64                   *Result
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Width</i>	Signifies the width of the I/O operations. Type EFI_PCI_IO_PROTOCOL_WIDTH is defined in Section 13.4 .
<i>BarIndex</i>	The BAR index of the standard PCI Configuration header to use as the base address for the I/O operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass <i>Offset</i> to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in Section 13.4 .
<i>Offset</i>	The offset within the selected BAR to start the I/O operation.
<i>Mask</i>	Mask used for the polling criteria. Bytes above <i>Width</i> in <i>Mask</i> are ignored. The bits in the bytes below <i>Width</i> which are zero in <i>Mask</i> are ignored when polling the I/O address.
<i>Value</i>	The comparison value used for the polling exit criteria.
<i>Delay</i>	The number of 100 ns units to poll. Note that timer available may be of poorer granularity.
<i>Result</i>	Pointer to the last value read from the memory location.

Description

This function provides a standard way to poll a PCI I/O location. A PCI I/O read operation is performed at the PCI I/O address specified by *BarIndex* and *Offset* for the width specified by *Width*. The result of this PCI I/O read operation is stored in *Result*. This PCI I/O read operation is repeated until either a timeout of *Delay* 100 ns units has expired, or (*Result & Mask*) is equal to *Value*.

This function will always perform at least one I/O access no matter how small *Delay* may be. If *Delay* is 0, then *Result* will be returned with a status of **EFI_SUCCESS** even if *Result* does not match the exit criteria. If *Delay* expires, then **EFI_TIMEOUT** is returned.

If *Width* is not **EfiPciIoWidthUint8**, **EfiPciIoWidthUint16**, **EfiPciIoWidthUint32**, or **EfiPciIoWidthUint64**, then **EFI_INVALID_PARAMETER** is returned.

The I/O operations are carried out exactly as requested. The caller is responsible satisfying any alignment and I/O width restrictions that the PCI controller on a platform might require. For example on some platforms, width requests of **EfiPciIoWidthUint64** do not work.

All the PCI read transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

EFI_SUCCESS	The last data returned from the access matched the poll exit criteria.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Result</i> is NULL .
EFI_UNSUPPORTED	<i>BarIndex</i> not valid for this PCI controller.
EFI_UNSUPPORTED	<i>Offset</i> is not valid for the PCI BAR specified by <i>BarIndex</i> .
EFI_TIMEOUT	<i>Delay</i> expired before a match occurred.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL.Mem.Read() EFI_PCI_IO_PROTOCOL.Mem.Write()

Summary

Enable a PCI driver to access PCI controller registers in the PCI memory space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_MEM) (
    IN      EFI_PCI_IO_PROTOCOL      *This,
    IN      EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN      UINT8                    BarIndex,
    IN      UINT64                   Offset,
    IN      UINTN                    Count,
    IN OUT VOID                      *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH is defined in Section 13.4 .
<i>BarIndex</i>	The BAR index of the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass <i>Offset</i> to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in Section 13.4 .
<i>Offset</i>	The offset within the selected BAR to start the memory operation.
<i>Count</i>	The number of memory operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>Offset</i> .
<i>Buffer</i>	For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The [Mem.Read\(\)](#), and [Mem.Write\(\)](#) functions enable a driver to access controller registers in the PCI memory space.

The I/O operations are carried out exactly as requested. The caller is responsible for any alignment and I/O width issues which the bus, device, platform, or type of I/O might require. For example on some platforms, width requests of **EfiPciIoWidthUint64** do not work.

If *Width* is **EfiPciIoWidthUint8**, **EfiPciIoWidthUint16**, **EfiPciIoWidthUint32**, or **EfiPciIoWidthUint64**, then both *Address* and *Buffer* are incremented for each of the *Count* operations performed.

If *Width* is **EfiPciIoWidthFifoUint8**, **EfiPciIoWidthFifoUint16**, **EfiPciIoWidthFifoUint32**, or **EfiPciIoWidthFifoUint64**, then only *Buffer* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times on the same *Address*.

If *Width* is **EfiPciIoWidthFillUint8**, **EfiPciIoWidthFillUint16**, **EfiPciIoWidthFillUint32**, or **EfiPciIoWidthFillUint64**, then only *Address* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times from the first element of *Buffer*.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the *PCI Specification*. However, if the memory-mapped I/O region being accessed by this function has the **EFI_PCI_ATTRIBUTE_MEMORY_CACHED** attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

EFI_SUCCESS	The data was read from or written to the PCI controller.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_UNSUPPORTED	<i>BarIndex</i> not valid for this PCI controller.
EFI_UNSUPPORTED	The address range specified by <i>Offset</i> , <i>Width</i> , and <i>Count</i> is not valid for the PCI BAR specified by <i>BarIndex</i> .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL Io.Read() EFI_PCI_IO_PROTOCOL Io.Write()

Summary

Enable a PCI driver to access PCI controller registers in the PCI I/O space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_MEM) (
    IN      EFI_PCI_IO_PROTOCOL      *This,
    IN      EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN      UINT8                    BarIndex,
    IN      UINT64                   Offset,
    IN      UINTN                    Count,
    IN OUT VOID                      *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH is defined in Section 13.4 .
<i>BarIndex</i>	The BAR index in the standard PCI Configuration header to use as the base address for the I/O operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass <i>Offset</i> to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in Section 13.4 .
<i>Offset</i>	The offset within the selected BAR to start the I/O operation.
<i>Count</i>	The number of I/O operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>Offset</i> .
<i>Buffer</i>	For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The `Io.Read()`, and `Io.Write()` functions enable a driver to access PCI controller registers in PCI I/O space.

The I/O operations are carried out exactly as requested. The caller is responsible for any alignment and I/O width issues which the bus, device, platform, or type of I/O might require. For example on some platforms, width requests of `EfiPciIoWidthUint64` do not work.

If *Width* is **EfiPciIoWidthUint8**, **EfiPciIoWidthUint16**, **EfiPciIoWidthUint32**, or **EfiPciIoWidthUint64**, then both *Address* and *Buffer* are incremented for each of the *Count* operations performed.

If *Width* is **EfiPciIoWidthFifoUint8**, **EfiPciIoWidthFifoUint16**, **EfiPciIoWidthFifoUint32**, or **EfiPciIoWidthFifoUint64**, then only *Buffer* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times on the same *Address*.

If *Width* is **EfiPciIoWidthFillUint8**, **EfiPciIoWidthFillUint16**, **EfiPciIoWidthFillUint32**, or **EfiPciIoWidthFillUint64**, then only *Address* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times from the first element of *Buffer*.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

EFI_SUCCESS	The data was read from or written to the PCI controller.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_UNSUPPORTED	<i>BarIndex</i> not valid for this PCI controller.
EFI_UNSUPPORTED	The address range specified by <i>Offset</i> , <i>Width</i> , and <i>Count</i> is not valid for the PCI BAR specified by <i>BarIndex</i> .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL.Pci.Read() EFI_PCI_IO_PROTOCOL.Pci.Write()

Summary

Enable a PCI driver to access PCI controller registers in PCI configuration space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_CONFIG) (
    IN      EFI_PCI_IO_PROTOCOL      *This,
    IN      EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN      UINT32                    Offset,
    IN      UINTN                     Count,
    IN OUT VOID                       *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH is defined in Section 13.4 .
<i>Offset</i>	The offset within the PCI configuration space for the PCI controller.
<i>Count</i>	The number of PCI configuration operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>Offset</i> .
<i>Buffer</i>	For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The **Pci.Read()** and **Pci.Write()** functions enable a driver to access PCI configuration registers for the PCI controller.

The PCI Configuration operations are carried out exactly as requested. The caller is responsible for any alignment and I/O width issues which the bus, device, platform, or type of I/O might require. For example on some platforms, width requests of **EfiPciIoWidthUint64** do not work.

If *Width* is **EfiPciIoWidthUint8**, **EfiPciIoWidthUint16**, **EfiPciIoWidthUint32**, or **EfiPciIoWidthUint64**, then both *Address* and *Buffer* are incremented for each of the *Count* operations performed.

If *Width* is **EfiPciIoWidthFifoUint8**, **EfiPciIoWidthFifoUint16**, **EfiPciIoWidthFifoUint32**, or **EfiPciIoWidthFifoUint64**, then only *Buffer* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times on the same *Address*.

If *Width* is **EfiPciIoWidthFillUint8**, **EfiPciIoWidthFillUint16**, **EfiPciIoWidthFillUint32**, or **EfiPciIoWidthFillUint64**, then only *Address* is incremented for each of the *Count* operations performed. The read or write operation is performed *Count* times from the first element of *Buffer*.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

EFI_SUCCESS	The data was read from or written to the PCI controller.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL .
EFI_UNSUPPORTED	The address range specified by <i>Offset</i> , <i>Width</i> , and <i>Count</i> is not valid for the PCI configuration header of the PCI controller.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL.CopyMem()

Summary

Enables a PCI driver to copy one region of PCI memory space to another region of PCI memory space.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_COPY_MEM) (
    IN      EFI_PCI_IO_PROTOCOL      *This,
    IN      EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN      UINT8                    DestBarIndex,
    IN      UINT64                   DestOffset,
    IN      UINT8                    SrcBarIndex,
    IN      UINT64                   SrcOffset,
    IN      UINTN                    Count
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI IO PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Width</i>	Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH is defined in Section 13.4 .
<i>DestBarIndex</i>	The BAR index in the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass <i>Offset</i> to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in Section 13.4 .
<i>DestOffset</i>	The destination offset within the BAR specified by <i>DestBarIndex</i> to start the memory writes for the copy operation. The caller is responsible for aligning the <i>DestOffset</i> if required.
<i>SrcBarIndex</i>	The BAR index in the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass <i>Offset</i> to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in Section 13.4 .

<i>SrcOffset</i>	The source offset within the BAR specified by <i>SrcBarIndex</i> to start the memory reads for the copy operation. The caller is responsible for aligning the <i>SrcOffset</i> if required.
<i>Count</i>	The number of memory operations to perform. Bytes moved is <i>Width</i> size * <i>Count</i> , starting at <i>DestOffset</i> and <i>SrcOffset</i> .

Description

The **CopyMem()** function enables a PCI driver to copy one region of PCI memory space to another region of PCI memory space on a PCI controller. This is especially useful for video scroll operations on a memory mapped video buffer.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI controller on a platform might require. For example on some platforms, width requests of **EfiPciIoWidthUint64** do not work.

If *Width* is **EfiPciWidthUint8**, **EfiPciWidthUint16**, **EfiPciWidthUint32**, or **EfiPciWidthUint64**, then *Count* read/write transactions are performed to move the contents of the *SrcOffset* buffer to the *DestOffset* buffer. The implementation must be reentrant, and it must handle overlapping *SrcOffset* and *DestOffset* buffers. This means that the implementation of **CopyMem()** must choose the correct direction of the copy operation based on the type of overlap that exists between the *SrcOffset* and *DestOffset* buffers. If either the *SrcOffset* buffer or the *DestOffset* buffer crosses the top of the processor's address space, then the result of the copy operation is unpredictable.

The contents of the *DestOffset* buffer on exit from this service must match the contents of the *SrcOffset* buffer on entry to this service. Due to potential overlaps, the contents of the *SrcOffset* buffer may be modified by this service. The following rules can be used to guarantee the correct behavior:

- If $DestOffset > SrcOffset$ and $DestOffset < (SrcOffset + Width\ size * Count)$, then the data should be copied from the *SrcOffset* buffer to the *DestOffset* buffer starting from the end of buffers and working toward the beginning of the buffers.
- Otherwise, the data should be copied from the *SrcOffset* buffer to the *DestOffset* buffer starting from the beginning of the buffers and working toward the end of the buffers.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the *PCI Specification*. However, if the memory-mapped I/O region being accessed by this function has the **EFI_PCI_ATTRIBUTE_MEMORY_CACHED** attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

EFI_SUCCESS	The data was copied from one memory region to another memory region.
EFI_INVALID_PARAMETER	<i>Width</i> is invalid.
EFI_UNSUPPORTED	<i>DestBarIndex</i> not valid for this PCI controller.

EFI_UNSUPPORTED	<i>SrcBarIndex</i> not valid for this PCI controller.
EFI_UNSUPPORTED	The address range specified by <i>DestOffset</i> , <i>Width</i> , and <i>Count</i> is not valid for the PCI BAR specified by <i>DestBarIndex</i> .
EFI_UNSUPPORTED	The address range specified by <i>SrcOffset</i> , <i>Width</i> , and <i>Count</i> is not valid for the PCI BAR specified by <i>SrcBarIndex</i> .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL.Map()

Summary

Provides the PCI controller–specific addresses needed to access system memory.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_MAP) (
    IN      EFI_PCI_IO_PROTOCOL      *This,
    IN      EFI_PCI_IO_PROTOCOL_OPERATION Operation,
    IN      VOID                      *HostAddress,
    IN OUT  UINTN                     *NumberOfBytes,
    OUT     EFI_PHYSICAL_ADDRESS      *DeviceAddress,
    OUT     VOID                      **Mapping
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Operation</i>	Indicates if the bus master is going to read or write to system memory. Type EFI_PCI_IO_PROTOCOL_OPERATION is defined in Section 13.4 .
<i>HostAddress</i>	The system memory address to map to the PCI controller.
<i>NumberOfBytes</i>	On input the number of bytes to map. On output the number of bytes that were mapped.
<i>DeviceAddress</i>	The resulting map address for the bus master PCI controller to use to access the hosts <i>HostAddress</i> . Type EFI_PHYSICAL_ADDRESS is defined in Section 6.2 . This address cannot be used by the processor to access the contents of the buffer specified by <i>HostAddress</i> .
<i>Mapping</i>	A resulting value to pass to Unmap() .

Description

The [Map\(\)](#) function provides the PCI controller–specific addresses needed to access system memory. This function is used to map system memory for PCI bus master DMA accesses.

All PCI bus master accesses must be performed through their mapped addresses and such mappings must be freed with [Unmap\(\)](#) when complete. If the bus master access is a single read or write data transfer, then [EfiPciIoOperationBusMasterRead](#) or [EfiPciIoOperation-BusMasterWrite](#) is used and the range is unmapped to complete the operation. If performing an [EfiPciIoOperationBusMasterRead](#) operation, all the data must be present in system memory before the [Map\(\)](#) is performed. Similarly, if performing an [EfiPciIoOperation-BusMasterWrite](#), the data cannot be properly accessed in system memory until [Unmap\(\)](#) is performed.

Bus master operations that require both read and write access or require multiple host device interactions within the same mapped region must use **EfiPciIoOperation-BusMasterCommonBuffer**. However, only memory allocated via the [AllocateBuffer\(\)](#) interface can be mapped for this operation type.

In all mapping requests the resulting *NumberOfBytes* actually mapped may be less than the requested amount. In this case, the DMA operation will have to be broken up into smaller chunks. The **Map()** function will map as much of the DMA operation as it can at one time. The caller may have to loop on **Map()** and **Unmap()** in order to complete a large DMA transfer.

Status Codes Returned

EFI_SUCCESS	The range was mapped for the returned <i>NumberOfBytes</i> .
EFI_INVALID_PARAMETER	<i>Operation</i> is invalid.
EFI_INVALID_PARAMETER	HostAddress is NULL .
EFI_INVALID_PARAMETER	NumberOfBytes is NULL .
EFI_INVALID_PARAMETER	DeviceAddress is NULL .
EFI_INVALID_PARAMETER	<i>Mapping</i> is NULL .
EFI_UNSUPPORTED	The <i>HostAddress</i> cannot be mapped as a common buffer.
EFI_DEVICE_ERROR	The system hardware could not map the requested address.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_PCI_IO_PROTOCOL.Unmap()

Summary

Completes the [Map \(\)](#) operation and releases any corresponding resources.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_UNMAP) (
    IN EFI_PCI_IO_PROTOCOL *This,
    IN VOID *Mapping
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Mapping</i>	The mapping value returned from Map () .

Description

The [Unmap \(\)](#) function completes the [Map \(\)](#) operation and releases any corresponding resources. If the operation was an [EfiPciIoOperationBusMasterWrite](#), the data is committed to the target system memory. Any resources used for the mapping are freed.

Status Codes Returned

EFI_SUCCESS	The range was unmapped.
EFI_DEVICE_ERROR	The data was not committed to the target system memory.

EFI_PCI_IO_PROTOCOL.AllocateBuffer()

Summary

Allocates pages that are suitable for an **EfiPciIoOperationBusMasterCommonBuffer** mapping.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_PCI_IO_PROTOCOL_ALLOCATE_BUFFER) (
    IN     EFI_PCI_IO_PROTOCOL  *This,
    IN     EFI_ALLOCATE_TYPE    Type,
    IN     EFI_MEMORY_TYPE      MemoryType,
    IN     UINTN                Pages,
    OUT    VOID                 **HostAddress,
    IN     UINT64               Attributes
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Type</i>	This parameter is not used and must be ignored.
<i>MemoryType</i>	The type of memory to allocate, EfiBootServicesData or EfiRuntimeServicesData . Type EFI_MEMORY_TYPE is defined in Chapter Section 6.2 .
<i>Pages</i>	The number of pages to allocate.
<i>HostAddress</i>	A pointer to store the base system memory address of the allocated range.
<i>Attributes</i>	The requested bit mask of attributes for the allocated range. Only the attributes EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE , and EFI_PCI_ATTRIBUTE_MEMORY_CACHED may be used with this function. If any other bits are set, then EFI_UNSUPPORTED is returned. This function may choose to ignore this bit mask. The EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE , and EFI_PCI_ATTRIBUTE_MEMORY_CACHED attributes provide a hint to the implementation that may improve the performance of the calling driver. The implementation may choose any default for the memory attributes including write combining, cached, both, or neither as long as the allocated buffer can be seen equally by both the processor and the PCI bus master.

Description

The **AllocateBuffer()** function allocates pages that are suitable for an **EfiPciIoOperationBusMasterCommonBuffer** mapping. This means that the buffer

allocated by this function must support simultaneous access by both the processor and a PCI Bus Master. The device address that the PCI Bus Master uses to access the buffer can be retrieved with a call to [Map\(\)](#).

If the current attributes of the PCI controller has the **EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE** bit set, then when the buffer allocated by this function is mapped with a call to **Map()**, the device address that is returned by **Map()** must be within the 64-bit device address space of the PCI Bus Master. The attributes for a PCI controller can be managed by calling [Attributes\(\)](#).

If the current attributes for the PCI controller has the **EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE** bit clear, then when the buffer allocated by this function is mapped with a call to **Map()**, the device address that is returned by **Map()** must be within the 32-bit device address space of the PCI Bus Master. The attributes for a PCI controller can be managed by calling **Attributes()**.

If the memory allocation specified by *MemoryType* and *Pages* cannot be satisfied, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The requested memory pages were allocated.
EFI_INVALID_PARAMETER	<i>MemoryType</i> is invalid.
EFI_INVALID_PARAMETER	HostAddress is NULL .
EFI_UNSUPPORTED	<i>Attributes</i> is unsupported. The only legal attribute bits are MEMORY_WRITE_COMBINE and MEMORY_CACHED .
EFI_OUT_OF_RESOURCES	The memory pages could not be allocated.

EFI_PCI_IO_PROTOCOL.FreeBuffer()

Summary

Frees memory that was allocated with [AllocateBuffer\(\)](#) .

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_FREE_BUFFER) (
    IN EFI_PCI_IO_PROTOCOL    *This,
    IN UINTN                  Pages,
    IN VOID                   *HostAddress
);
```

Parameters

<i>This</i>	A pointer to the EFI PCI IO PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Pages</i>	The number of pages to free.
<i>HostAddress</i>	The base system memory address of the allocated range.

Description

The **FreeBuffer()** function frees memory that was allocated with **AllocateBuffer()** .

Status Codes Returned

EFI_SUCCESS	The requested memory pages were freed.
EFI_INVALID_PARAMETER	The memory range specified by <i>HostAddress</i> and <i>Pages</i> was not allocated with AllocateBuffer() .

EFI_PCI_IO_PROTOCOL.Flush()

Summary

Flushes all PCI posted write transactions from a PCI host bridge to system memory.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_FLUSH) (
    IN EFI_PCI_IO_PROTOCOL *This
);
```

Parameters

This A pointer to the [EFI PCI IO PROTOCOL](#) instance. Type [EFI_PCI_IO_PROTOCOL](#) is defined in [Section 13.4](#).

Description

The **Flush()** function flushes any PCI posted write transactions from a PCI host bridge to system memory. Posted write transactions are generated by PCI bus masters when they perform write transactions to target addresses in system memory.

This function does not flush posted write transactions from any PCI bridges. A PCI controller specific action must be taken to guarantee that the posted write transactions have been flushed from the PCI controller and from all the PCI bridges into the PCI host bridge. This is typically done with a PCI read transaction from the PCI controller prior to calling **Flush()**.

If the PCI controller specific action required to flush the PCI posted write transactions has been performed, and this function returns **EFI_SUCCESS**, then the PCI bus master's view and the processor's view of system memory are guaranteed to be coherent. If the PCI posted write transactions cannot be flushed from the PCI host bridge, then the PCI bus master and processor are not guaranteed to have a coherent view of system memory, and **EFI_DEVICE_ERROR** is returned.

Status Codes Returned

EFI_SUCCESS	The PCI posted write transactions were flushed from the PCI host bridge to system memory.
EFI_DEVICE_ERROR	The PCI posted write transactions were not flushed from the PCI host bridge due to a hardware error.

EFI_PCI_IO_PROTOCOL.GetLocation()

Summary

Retrieves this PCI controller's current PCI bus number, device number, and function number.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_GET_LOCATION) (
    IN  EFI_PCI_IO_PROTOCOL  *This,
    OUT UINTN                 *SegmentNumber,
    OUT UINTN                 *BusNumber,
    OUT UINTN                 *DeviceNumber,
    OUT UINTN                 *FunctionNumber
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>SegmentNumber</i>	The PCI controller's current PCI segment number.
<i>BusNumber</i>	The PCI controller's current PCI bus number.
<i>DeviceNumber</i>	The PCI controller's current PCI device number.
<i>FunctionNumber</i>	The PCI controller's current PCI function number.

Description

The **GetLocation()** function retrieves a PCI controller's current location on a PCI Host Bridge. This is specified by a PCI segment number, PCI bus number, PCI device number, and PCI function number. These values can be used with the PCI Root Bridge I/O Protocol to perform PCI configuration cycles on the PCI controller, or any of its peer PCI controller's on the same PCI Host Bridge.

Status Codes Returned

EFI_SUCCESS	The PCI controller location was returned.
EFI_INVALID_PARAMETER	SegmentNumber is NULL .
EFI_INVALID_PARAMETER	BusNumber is NULL .
EFI_INVALID_PARAMETER	DeviceNumber is NULL .
EFI_INVALID_PARAMETER	FunctionNumber is NULL .

EFI_PCI_IO_PROTOCOL.Attributes()

Summary

Performs an operation on the attributes that this PCI controller supports. The operations include getting the set of supported attributes, retrieving the current attributes, setting the current attributes, enabling attributes, and disabling attributes.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_ATTRIBUTES) (
    IN  EFI_PCI_IO_PROTOCOL           *This,
    IN  EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION  Operation,
    IN  UINT64                        Attributes,
    OUT UINT64                        *Result  OPTIONAL
);
```

Parameters

- | | |
|-------------------|--|
| <i>This</i> | A pointer to the EFI PCI IO PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 . |
| <i>Operation</i> | The operation to perform on the attributes for this PCI controller. Type EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION is defined in “Related Definitions” below. |
| <i>Attributes</i> | The mask of attributes that are used for Set , Enable , and Disable operations. The available attributes are listed in Section 13.4 . |
| <i>Result</i> | A pointer to the result mask of attributes that are returned for the Get and Supported operations. This is an optional parameter that may be NULL for the Set , Enable , and Disable operations. The available attributes are listed in Section 13.4 . |

Related Definitions

```

//*****
// EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION
//*****
typedef enum {
    EfiPciIoAttributeOperationGet,
    EfiPciIoAttributeOperationSet,
    EfiPciIoAttributeOperationEnable,
    EfiPciIoAttributeOperationDisable,
    EfiPciIoAttributeOperationSupported,
    EfiPciIoAttributeOperationMaximum
} EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION;
```

EfiPciIoAttributeOperationGet

Retrieve the PCI controller's current attributes, and return them in *Result*. If *Result* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. For this operation, *Attributes* is ignored.

EfiPciIoAttributeOperationSet

Set the PCI controller's current attributes to *Attributes*. If a bit is set in *Attributes* that is not supported by this PCI controller or one of its parent bridges, then **EFI_UNSUPPORTED** is returned. For this operation, *Result* is an optional parameter that may be **NULL**.

EfiPciIoAttributeOperationEnable

Enable the attributes specified by the bits that are set in *Attributes* for this PCI controller. Bits in *Attributes* that are clear are ignored. If a bit is set in *Attributes* that is not supported by this PCI controller or one of its parent bridges, then **EFI_UNSUPPORTED** is returned. For this operation, *Result* is an optional parameter that may be **NULL**.

EfiPciIoAttributeOperationDisable

Disable the attributes specified by the bits that are set in *Attributes* for this PCI controller. Bits in *Attributes* that are clear are ignored. If a bit is set in *Attributes* that is not supported by this PCI controller or one of its parent bridges, then **EFI_UNSUPPORTED** is returned. For this operation, *Result* is an optional parameter that may be **NULL**.

EfiPciIoAttributeOperationSupported

Retrieve the PCI controller's supported attributes, and return them in *Result*. If *Result* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. For this operation, *Attributes* is ignored.

Description

The **Attributes ()** function performs an operation on the attributes associated with this PCI controller. If *Operation* is greater than or equal to the maximum operation value, then **EFI_INVALID_PARAMETER** is returned. If *Operation* is **Get** or **Supported**, and *Result* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If *Operation* is **Set**, **Enable**, or **Disable** for an attribute that is not supported by the PCI controller, then **EFI_UNSUPPORTED** is returned. Otherwise, the operation is performed as described in "Related Definitions" and **EFI_SUCCESS** is returned. It is possible for this function to return **EFI_UNSUPPORTED** even if the PCI controller supports the attribute. This can occur when the PCI root bridge does not support the attribute. For example, if VGA I/O and VGA Memory transactions cannot be forwarded onto PCI root bridge #2, then a request by a PCI VGA driver to enable the **VGA_IO** and **VGA_MEMORY** bits will fail even though a PCI VGA controller behind PCI root bridge #2 is able to decode these transactions.

This function will also return **EFI_UNSUPPORTED** if more than one PCI controller on the same PCI root bridge has already successfully requested one of the ISA addressing attributes. For example, if one PCI VGA controller had already requested the **VGA_IO** and **VGA_MEMORY** attributes, then a second PCI VGA controller on the same root bridge cannot succeed in requesting those same attributes. This restriction applies to the ISA-, VGA-, and IDE-related attributes.

Status Codes Returned

EFI_SUCCESS	The operation on the PCI controller's attributes was completed. If the operation was Get or Supported , then the attribute mask is returned in <i>Result</i> .
EFI_INVALID_PARAMETER	<i>Operation</i> is greater than or equal to EfiPciIoAttributeOperationMaximum .
EFI_INVALID_PARAMETER	<i>Operation</i> is Get and <i>Result</i> is NULL .
EFI_INVALID_PARAMETER	<i>Operation</i> is Supported and <i>Result</i> is NULL .
EFI_UNSUPPORTED	<i>Operation</i> is Set , and one or more of the bits set in <i>Attributes</i> are not supported by this PCI controller or one of its parent bridges.
EFI_UNSUPPORTED	<i>Operation</i> is Enable , and one or more of the bits set in <i>Attributes</i> are not supported by this PCI controller or one of its parent bridges.
EFI_UNSUPPORTED	<i>Operation</i> is Disable , and one or more of the bits set in <i>Attributes</i> are not supported by this PCI controller or one of its parent bridges.

EFI_PCI_IO_PROTOCOL.GetBarAttributes()

Summary

Gets the attributes that this PCI controller supports setting on a BAR using [SetBarAttributes\(\)](#), and retrieves the list of resource descriptors for a BAR.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_GET_BAR_ATTRIBUTES) (
    IN EFI_PCI_IO_PROTOCOL *This,
    IN UINT8 BarIndex,
    OUT UINT64 *Supports OPTIONAL,
    OUT VOID **Resources OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>BarIndex</i>	The BAR index of the standard PCI Configuration header to use as the base address for resource range. The legal range for this field is 0..5.
<i>Supports</i>	A pointer to the mask of attributes that this PCI controller supports setting for this BAR with SetBarAttributes() . The list of attributes is listed in Section 13.4 . This is an optional parameter that may be NULL .
<i>Resources</i>	A pointer to the ACPI 2.0 resource descriptors that describe the current configuration of this BAR of the PCI controller. This buffer is allocated for the caller with the Boot Service AllocatePool() . It is the caller's responsibility to free the buffer with the Boot Service FreePool() . See "Related Definitions" below for the ACPI 2.0 resource descriptors that may be used. This is an optional parameter that may be NULL .

Related Definitions

There are only two resource descriptor types from the *ACPI Specification* that may be used to describe the current resources allocated to BAR of a PCI Controller. These are the QWORD Address Space Descriptor (ACPI 2.0 Section 6.4.3.5.1), and the End Tag (ACPI 2.0 Section 6.4.2.8). The QWORD Address Space Descriptor can describe memory, I/O, and bus number ranges for dynamic or fixed resources. The configuration of a BAR of a PCI Controller is described with one or more QWORD Address Space Descriptors followed by an End Tag. [Table 96](#) and [Table 97](#) contain these two descriptor types. Please see the *ACPI Specification* for details on the field values.

Table 96. ACPI 2.0 QWORD Address Space Descriptor

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x8A	QWORD Address Space Descriptor
0x01	0x02	0x2B	Length of this descriptor in bytes not including the first two fields
0x03	0x01		Resource Type 0 – Memory Range 1 – I/O Range 2 – Bus Number Range
0x04	0x01		General Flags
0x05	0x01		Type Specific Flags
0x06	0x08		Address Space Granularity
0x0E	0x08		Address Range Minimum
0x16	0x08		Address Range Maximum
0x1E	0x08		Address Translation Offset
0x26	0x08		Address Length

Table 97. ACPI 2.0 End Tag

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x79	End Tag
0x01	0x01	0x00	Checksum. If 0, then checksum is assumed to be valid.

Description

The **GetBarAttributes ()** function returns in *Supports* the mask of attributes that the PCI controller supports setting for the BAR specified by *BarIndex*. It also returns in *Resources* a list of ACPI 2.0 resource descriptors for the BAR specified by *BarIndex*. Both *Supports* and *Resources* are optional parameters. If both *Supports* and *Resources* are **NULL**, then **EFI_INVALID_PARAMETER** is returned. It is the caller’s responsibility to free *Resources* with the Boot Service **FreePool ()** when the caller is done with the contents of *Resources*. If there are not enough resources to allocate *Resources*, then **EFI_OUT_OF_RESOURCES** is returned.

If a bit is set in *Supports*, then the PCI controller supports this attribute type for the BAR specified by *BarIndex*, and a call can be made to **SetBarAttributes ()** using that attribute type.

Status Codes Returned

EFI_SUCCESS	If <i>Supports</i> is not NULL , then the attributes that the PCI controller supports are returned in <i>Supports</i> . If <i>Resources</i> is not NULL , then the ACPI 2.0 resource descriptors that the PCI controller is currently using are returned in <i>Resources</i> .
-------------	--

EFI_OUT_OF_RESOURCES	There are not enough resources available to allocate <i>Resources</i> .
EFI_UNSUPPORTED	<i>BarIndex</i> not valid for this PCI controller.
EFI_INVALID_PARAMETER	Both <i>Supports</i> and <i>Attributes</i> are NULL .

EFI_PCI_IO_PROTOCOL.SetBarAttributes()

Summary

Sets the attributes for a range of a BAR on a PCI controller.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_SET_BAR_ATTRIBUTES) (
    IN      EFI_PCI_IO_PROTOCOL  *This,
    IN      UINT64                Attributes,
    IN      UINT8                 BarIndex,
    IN OUT  UINT64                *Offset,
    IN OUT  UINT64                *Length
);
```

Parameters

<i>This</i>	A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in Section 13.4 .
<i>Attributes</i>	The mask of attributes to set for the resource range specified by <i>BarIndex</i> , <i>Offset</i> , and <i>Length</i> .
<i>BarIndex</i>	The BAR index of the standard PCI Configuration header to use as the base address for the resource range. The legal range for this field is 0..5.
<i>Offset</i>	A pointer to the BAR relative base address of the resource range to be modified by the attributes specified by <i>Attributes</i> . On return, <i>*Offset</i> will be set to the actual base address of the resource range. Not all resources can be set to a byte boundary, so the actual base address may differ from the one passed in by the caller.
<i>Length</i>	A pointer to the length of the resource range to be modified by the attributes specified by <i>Attributes</i> . On return, <i>*Length</i> will be set to the actual length of the resource range. Not all resources can be set to a byte boundary, so the actual length may differ from the one passed in by the caller.

Description

The **SetBarAttributes()** function sets the attributes specified in *Attributes* for the PCI controller on the resource range specified by *BarIndex*, *Offset*, and *Length*. Since the granularity of setting these attributes may vary from resource type to resource type, and from platform to platform, the actual resource range and the one passed in by the caller may differ. As a result, this function may set the attributes specified by *Attributes* on a larger resource range than the caller requested. The actual range is returned in *Offset* and *Length*. The caller is responsible for verifying that the actual range for which the attributes were set is acceptable.

If the attributes are set on the PCI controller, then the actual resource range is returned in *Offset* and *Length*, and **EFI_SUCCESS** is returned. Many of the attribute types also require that the state of the PCI Host Bus Controller and the state of any PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller to be modified. This function will only return **EFI_SUCCESS** if all of these state changes are made. The PCI Controller may support a combination of attributes, but unless the PCI Host Bus Controller and the PCI to PCI bridges also support that same combination of attributes, then this call will return an error.

If the attributes specified by *Attributes*, or the resource range specified by *BarIndex*, *Offset*, and *Length* are not supported by the PCI controller, then **EFI_UNSUPPORTED** is returned. The set of supported attributes for the PCI controller can be found by calling [GetBarAttributes\(\)](#).

If either *Offset* or *Length* is **NULL** then **EFI_INVALID_PARAMETER** is returned.

If there are not enough resources available to set the attributes, then **EFI_OUT_OF_RESOURCES** is returned.

Status Codes Returned

EFI_SUCCESS	The set of attributes specified by <i>Attributes</i> for the resource range specified by <i>BarIndex</i> , <i>Offset</i> , and <i>Length</i> were set on the PCI controller, and the actual resource range is returned in <i>Offset</i> and <i>Length</i> .
EFI_UNSUPPORTED	The set of attributes specified by <i>Attributes</i> is not supported by the PCI controller for the resource range specified by <i>BarIndex</i> , <i>Offset</i> , and <i>Length</i> .
EFI_INVALID_PARAMETER	<i>Offset</i> is NULL .
EFI_INVALID_PARAMETER	<i>Length</i> is NULL .
EFI_OUT_OF_RESOURCES	There are not enough resources to set the attributes on the resource range specified by <i>BarIndex</i> , <i>Offset</i> , and <i>Length</i> .

13.4.1 PCI Device Paths

An [EFI PCI IO PROTOCOL](#) must be installed on a handle for its services to be available to PCI device drivers. In addition to the [EFI PCI IO PROTOCOL](#), an [EFI DEVICE PATH PROTOCOL](#) must also be installed on the same handle. See Chapter [Section 9](#) for a detailed description of the [EFI_DEVICE_PATH_PROTOCOL](#).

Typically, an ACPI Device Path Node is used to describe a PCI Root Bridge. Depending on the bus hierarchy in the system, additional device path nodes may precede this ACPI Device Path Node. A PCI device path is described with PCI Device Path Nodes. There will be one PCI Device Path node for the PCI controller itself, and one PCI Device Path Node for each PCI to PCI Bridge that is between the PCI controller and the PCI Root Bridge.

[Table 98](#) shows an example device path for a PCI controller that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node, a PCI Device Path Node, and a Device Path End Structure. The

_HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03 , 0) / PCI (7 , 0) .

Table 98. PCI Device 7, Function 0 on PCI Root Bridge 0

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x00	PCI Function
0x11	0x01	0x07	PCI Device
0x12	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x13	0x01	0xFF	Sub type – End of Entire Device Path
0x14	0x02	0x04	Length – 0x04 bytes

[Table 99](#) shows an example device path for a PCI controller that is located behind a PCI to PCI bridge at PCI device number 0x07 and PCI function 0x00. The PCI to PCI bridge is directly attached to a PCI root bridge, and it is at PCI device number 0x05 and PCI function 0x00. This device path consists of an ACPI Device Path Node, two PCI Device Path Nodes, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03 , 0) / PCI (5 , 0) / PCI (7 , 0) .

Table 99. PCI Device 7, Function 0 behind PCI to PCI bridge

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes

Byte Offset	Byte Length	Data	Description
0x10	0x01	0x00	PCI Function
0x11	0x01	0x05	PCI Device
0x12	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x13	0x01	0x01	Sub type – PCI
0x14	0x02	0x06	Length – 0x06 bytes
0x16	0x01	0x00	PCI Function
0x17	0x01	0x07	PCI Device
0x18	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x19	0x01	0xFF	Sub type – End of Entire Device Path
0x1A	0x02	0x04	Length – 0x04 bytes

13.4.2 PCI Option ROMs

EFI takes advantage of both the *PCI Specification* and the *PE/COFF Specification* to store EFI images in a PCI Option ROM. There are several rules that must be followed when constructing a PCI Option ROM:

- A PCI Option ROM can be no larger than 16 MB.
- A PCI Option ROM may contain one or more images.
- Each image must be on a 512-byte boundary.
- Each image must be an even multiple of 512 bytes in length. This means that images that are not an even multiple of 512 bytes in length must be padded to the next 512-byte boundary.
- Legacy Option ROM images begin with a Standard PCI Expansion ROM Header ([Table 100](#)).
- EFI Option ROM images begin with an EFI PCI Expansion ROM Header ([Table 104](#)).
- Each image must contain a PCIR data structure in the first 64 KB of the image ([Table 101](#)).
- The image data for an EFI Option ROM image must begin in the first 64 KB of the image.
- The image data for an EFI Option ROM image must be a PE/COFF image or a compressed PE/COFF image following the EFI 1.10 Compression Algorithm Specification, and referencing [Appendix H](#) for the Compression Source Code.
- The PCIR data structure must begin on a 4-byte boundary.
- If the PCI Option ROM contains a Legacy Option ROM image, it must be the first image.
- The images are placed in the PCI Option ROM in order from highest to lowest priority. This priority is used to build the ordered list of Driver Image Handles that are produced by the Bus Specific Driver Override Protocol for a PCI Controller.
- In the future EBC is the only way new processor bindings can be added.

There are several options available when building a PCI option ROM for a PCI adapter. A PCI Option ROM can choose to support only a legacy PC-AT platform, only an EFI compliant platform, or both. This flexibility allows a migration path from adapters that support only legacy PC-AT platforms, to adapters that support both PC-AT platforms and EFI compliant platforms, to adapters that support only EFI compliant platforms. The following is a list of the image combinations that

may be placed in a PCI option ROM. This is not an exhaustive list. Instead, it provides what will likely be the most common PCI option ROM layouts. EFI compliant system firmware must work with all of these PCI option ROM layouts, plus any other layouts that are possible within the *PCI Specification*. The format of a Legacy Option ROM image is defined in the *PCI Specification*.

- Legacy Option ROM image
- Legacy Option ROM image + IA-32 EFI driver
- Legacy Option ROM image + Itanium Processor Family EFI driver
- Legacy Option ROM image + IA-32 EFI driver + Itanium Processor Family EFI driver
- Legacy Option ROM image + IA-32 EFI driver + x64 EFI driver
- Legacy Option ROM image + EBC Driver
- IA-32 UEFI driver
- Itanium Processor Family EFI driver
- IA-32 UEFI driver + Itanium Processor Family EFI driver
- EBC Driver

It is also possible to place an application written to this specification in a PCI Option ROM. However, the PCI Bus Driver will ignore these images. The exact mechanism by which applications can be loaded and executed from a PCI Option ROM is outside the scope of this document.

Table 100. Standard PCI Expansion ROM Header

Offset	Byte Length	Value	Description
0x00	1	0x55	ROM Signature, byte 1
0x01	1	0xAA	ROM Signature, byte 2
0x02-0x17	22	XX	Reserved per processor architecture unique data
0x18-0x19	2	XX	Pointer to PCIR Data Structure

Table 101. PCIR Data Structure

Offset	Byte Length	Description
0x00	4	Signature, the string 'PCIR'
0x04	2	Vendor Identification
0x06	2	Device Identification
0x08	2	Pointer to Vital Product Data
0x0a	2	PCIR Data Structure Length
0x0c	1	PCIR Data Structure Revision
0x0d	3	Class Code
0x10	2	Image Length
0x12	2	Revision Level of Code/Data
0x14	1	Code Type
0x15	1	Indicator. Used to identify if this is the last image in the ROM
0x16	2	Reserved

Table 102. PCI Expansion ROM Code Types

Code Type	Description
0x00	IA-32, PC-AT compatible
0x01	Open Firmware standard for PCI
0x02	Hewlett-Packard PA RISC
0x03	EFI Image
0x04-0xFF	Reserved

Table 103. EFI PCI Expansion ROM Header

Offset	Byte Length	Value	Description
0x00	1	0x55	ROM Signature, byte 1
0x01	1	0xAA	ROM Signature, byte 2
0x02	2	XXXX	Initialization Size – size of this image in units of 512 bytes. The size includes this header.
0x04	4	0x0EF1	Signature from EFI image header
0x08	2	XX	Subsystem value for EFI image header
0x0a	2	XX	Machine type from EFI image header
0x0c	2	XX	Compression type 0x0000 - The image is uncompressed 0x0001 - The image is compressed. See the <i>EFI 1.1 Compression Algorithm Specification</i> and Appendix H . 0x0002 - 0xFFFF - Reserved
0x0e	8	0x00	Reserved
0x16	2	XX	Offset to EFI Image
0x18	2	XX	Offset to PCIR Data Structure

13.4.2.1 PCI Bus Driver Responsibilities

A PCI Bus Driver must scan a PCI Option ROM for PCI Device Drivers. If a PCI Option ROM is found during PCI Enumeration, then a copy of the PCI Option ROM is placed in a memory buffer. The PCI Bus Driver will use the memory copy of the PCI Option ROM to search for UEFI drivers after PCI Enumeration. The PCI Bus Driver will search the list of images in a PCI Option ROM for the ones that have a Code Type of 0x03 in the PCIR Data Structure, and a Signature of 0xEF1 in the EFI PCI Expansion ROM Header. Then, it will examine the Subsystem Type of the EFI PCI Expansion ROM Header. If the Subsystem Type is **IMAGE_SUBSYSTEM_EFI_BOOT_SERVICE_DRIVER**(11) or **IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER**(12), then the PCI Bus Driver can load the PCI Device Driver from the PCI Option ROM. The Offset to EFI Image Header field of the EFI PCI Expansion ROM Header is used to get a pointer to the beginning of the PE/COFF image in the PCI Option ROM. The PE/COFF image may have been compressed using the *EFI 1.10* Compression Algorithm. If it has been compressed, then the PCI Bus Driver must decompress the driver to a memory buffer. The Boot Service [LoadImage \(\)](#) can then be used to

load the driver. If the platform does not support the Machine Type of the driver, then **LoadImage ()** may fail.

It is the PCI Bus Driver's responsibility to verify that the Expansion ROM Header and PCIR Data Structure are valid. It is the responsibility of the Boot Service **LoadImage ()** to verify that the PE/COFF image is valid. The Boot Service **LoadImage ()** may fail for several reasons including a corrupt PE/COFF image or an unsupported Machine Type.

The PCI Option ROM search may produce one or more Driver Image Handles for the PCI Controller that is associated with the PCI Option ROM. The PCI Bus Driver is responsible for producing a Bus Specific Driver Override Protocol instance for every PCI Controller has a PCI Option ROM that contains one or more UEFI Drivers. The Bus Specific Driver Override Protocol produces an ordered list of Driver Image Handles. The order that the UEFI Drivers are placed in the PCI Option ROM is the order of Driver Image Handles that must be returned by the Bus Specific Driver Override Protocol. This gives the party that builds the PCI Option ROM control over the order that the drivers are used in the Boot Service [ConnectController \(\)](#).

13.4.2.2 PCI Device Driver Responsibilities

A PCI Device Driver should not be designed to care where it is stored. It can reside in a PCI Option ROM, the system's motherboard ROM, a hard drive, a CD-ROM drive, etc. All PCI Device Drivers are compiled and linked to generate a PE/COFF image. When a PE/COFF image is placed in a PCI Option ROM, it must follow the rules outlined in [Section 13.4.2](#). The recommended image layout is to insert an EFI PCI Expansion ROM Header and a PCIR Data Structure in front of the PE/COFF image, and pad the entire image up to the next 512-byte boundary. [Figure 43](#) shows the format of a single PCI Device Driver that can be added to a PCI Option ROM.

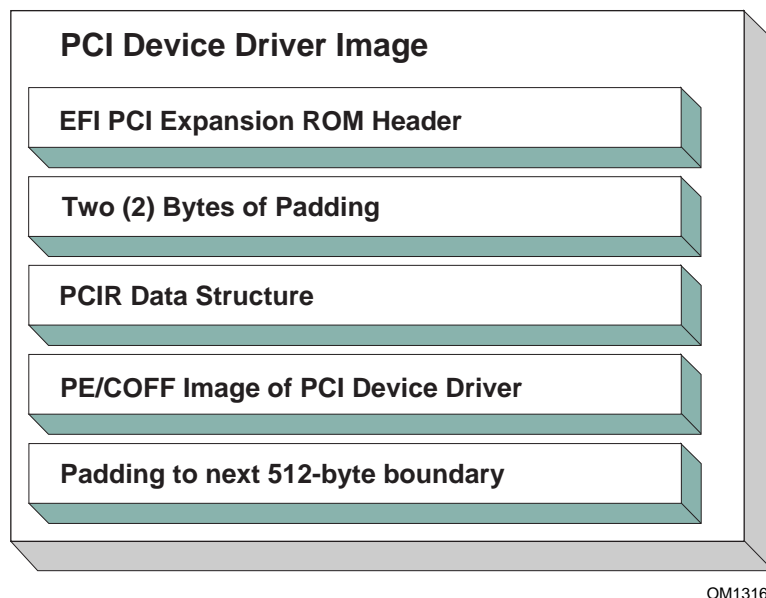


Figure 43. Recommended PCI Driver Image Layout

The field values for the EFI PCI Expansion ROM Header and the PCIR Data Structure would be as follows in this recommended PCI Driver image layout. An image must start at a 512-byte boundary, and the end of the image must be padded to the next 512-byte boundary.

Table 104. Recommended PCI Device Driver Layout

Offset	Byte Length	Value	Description
0x00	1	0x55	ROM Signature, byte 1
0x01	1	0xAA	ROM Signature, byte 2
0x02	2	XXXX	Initialization Size – size of this image in units of 512 bytes. The size includes this header
0x04	4	0x0EF1	Signature from EFI image header
0x08	2	XX 0x0B 0x0C	Subsystem Value from the PCI Driver's PE/COFF Image Header Subsystem Value for an EFI Boot Service Driver Subsystem Value for an EFI Runtime Driver
0x0a	2	XX 0x014C 0x0200 0x0EBC 0x8664	Machine type from the PCI Driver's PE/COFF Image Header IA-32 Machine Type Itanium processor type EFI Byte Code (EBC) Machine Type X64 Machine Type
0x0C	2	XXXX 0x0000 0x0001	Compression Type Uncompressed Compressed following the <i>EFI 1.10 Compression Algorithm Specification</i>
0x0E	8	0x00	Reserved
0x16	2	0x0034	Offset to EFI Image
0x18	2	0x001C	Offset to PCIR Data Structure
0x1A	2	0x0000	Padding to align PCIR Data Structure on a 4 byte boundary
0x1C	4	'PCIR'	PCIR Data Structure Signature
0x20	2	XXXX	Vendor ID from the PCI Controller's Configuration Header
0x22	2	XXXX	Device ID from the PCI Controller's Configuration Header
0x24	2	0x0000	Reserved
0x26	2	0x0018	The length of the PCIR Data Structure in bytes
0x28	1	0x00	PCIR Data Structure Revision. Value for PCI 2.2 Option ROM
0x29	3	XXXX	Class Code from the PCI Controller's Configuration Header
0x2C	2	XXXX	Code Image Length in units of 512 bytes. Same as Initialization Size
0x2E	2	XXXX	Revision Level of the Code/Data. This field is ignored
0x30	1	0x03	Code Type
0x31	1	XX	Indicator. Bit 7 clear means another image follows. Bit 7 set means that this image is the last image in the PCI Option ROM. Bits 0–6 are reserved.
		0x00 0x80	Additional images follow this image in the PCI Option ROM This image is the last image in the PCI Option ROM
0x32	2	0x0000	Reserved

Offset	Byte Length	Value	Description
0x34	X	XXXX	The beginning of the PCI Device Driver's PE/COFF Image

13.4.3 Nonvolatile Storage

A PCI adapter may contain some form of nonvolatile storage. Since there are no standard access mechanisms for nonvolatile storage on PCI adapters, the PCI I/O Protocol does not provide any services for nonvolatile storage. However, a PCI Device Driver may choose to implement its own access mechanisms. If there is a private channel between a PCI Controller and a nonvolatile storage device, a PCI Device Driver can use it for configuration options or vital product data.

Note: *The fields `RomImage` and `RomSize` in the PCI I/O Protocol do not provide direct access to the PCI Option ROM on a PCI adapter. Instead, they provide access to a copy of the PCI Option ROM in memory. If the contents of the `RomImage` are modified, only the memory copy is updated. If a vendor wishes to update the contents of a PCI Option ROM, they must provide their own utility or driver to perform this task. There is no guarantee that the BAR for the PCI Option ROM is valid at the time that the utility or driver may execute, so the utility or driver must provide the code required to gain write access to the PCI Option ROM contents. The algorithm for gaining write access to a PCI Option ROM is both platform specific and adapter specific, so it is outside the scope of this document.*

13.4.4 PCI Hot-Plug Events

It is possible to design a PCI Bus Driver to work with PCI Bus that conforms to the PCI Hot-Plug Specification. There are two levels of functionality that could be provided in the preboot environment. The first is to initialize the PCI Hot-Plug capable bus so it can be used by an operating system that also conforms to the PCI Hot-Plug Specification. This only affects the PCI Enumeration that is performed in either the PCI Bus Driver's initialization, or a firmware component that executes prior to the PCI Bus Driver's initialization. None of the PCI Device Drivers need to be aware of the fact that a PCI Controller may exist in a slot that is capable of a hot-plug event. Also, the addition, removal, and replacement of PCI adapters in the preboot environment would not be allowed.

The second level of functionality is to actually implement the full hot-plug capability in the PCI Bus Driver. This is not recommended because it adds a great deal of complexity to the PCI Bus Driver design with very little added value. However, there is nothing about the PCI Driver Model that would preclude this implementation. It would have to use an event based periodic timer to monitor the hot-plug capable slots, and take advantage of the [ConnectController\(\)](#) and [DisconnectController\(\)](#) Boot Services to dynamically start and stop the drivers that manage the PCI controller that is being added, removed, or replaced.

14

Protocols — SCSI Driver Models and Bus Support

The intent of this chapter is to specify a method of providing direct access to SCSI devices. These protocols provide services that allow a generic driver to produce the Block I/O protocol for SCSI disk devices, and allows an EFI utility to issue commands to any SCSI device. The main reason to provide such an access is to enable S.M.A.R.T. functionality during POST (i.e., issuing Mode Sense, Mode Select, and Log Sense to SCSI devices). This is accomplished by using a generic API such as SCSI Pass Thru. The use of this method will enable additional functionality in the future without modifying the EFI SCSI Pass Thru driver. SCSI Pass Thru is not limited to SCSI channels. It is applicable to all channel technologies that utilize SCSI commands such as SCSI, ATAPI, and Fibre Channel. This chapter describes the SCSI Driver Model. This includes the behavior of SCSI Bus Drivers, the behavior of SCSI Device Drivers, and a detailed description of the SCSI I/O Protocol. This chapter provides enough material to implement a SCSI Bus Driver, and the tools required to design and implement SCSI Device Drivers. It does not provide any information on specific SCSI devices.

14.1 SCSI Driver Model Overview

The EFI SCSI Driver Stack includes the SCSI Pass Thru Driver, SCSI Bus Driver and individual SCSI Device Drivers.

SCSI Pass Thru Driver: A SCSI Pass Through Driver manages a SCSI Host Controller that contains one or more SCSI Buses. It creates SCSI Bus Controller Handles for each SCSI Bus, and attaches SCSI Pass Thru Protocol and Device Path Protocol to each handle the driver produced. Please refer to *EFII.1 SCSI Pass Thru Protocol, Version 0.8* for details about the protocol.

SCSI Bus Driver: A SCSI Bus Driver manages a SCSI Bus Controller Handle that is created by SCSI Pass Thru Driver. It creates SCSI Device Handles for each SCSI Device Controller detected during SCSI Bus Enumeration, and attaches SCSI I/O Protocol and Device Path Protocol to each handle the driver produced.

SCSI Device Driver: A SCSI Device Driver manages one kind of SCSI Device. Device handles for SCSI Devices are created by SCSI Bus Drivers. A SCSI Device Driver could be a bus driver itself, and may create child handles. But most SCSI Device Drivers will be device drivers that do not create new handles. For the pure device driver, it attaches protocol instance to the device handle of the SCSI Device. These protocol instances are I/O abstractions that allow the SCSI Device to be used in the pre-boot environment. The most common I/O abstractions are used to boot an EFI compliant OS.

14.2 SCSI Bus Drivers

A SCSI Bus Driver manages a SCSI Bus Controller Handle. A SCSI Bus Controller Handle is created by a SCSI Pass Thru Driver and is abstracted in software with the SCSI Pass Thru Protocol. A SCSI Bus Driver will manage handles that contain this protocol. [Figure 44](#) shows an example device handle for a SCSI Bus handle. It contains a Device Path Protocol instance and a SCSI Pass Thru Protocol Instance.

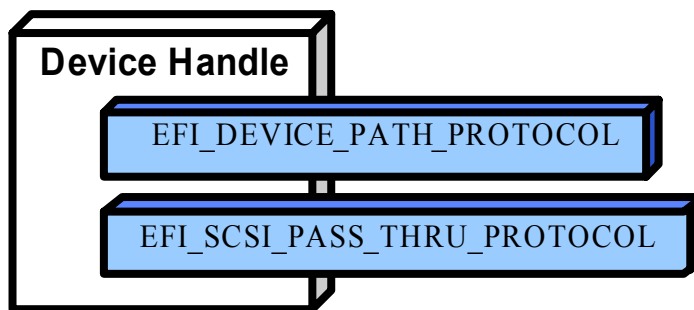


Figure 44. Device Handle for a SCSI Bus Controller

14.2.1 Driver Binding Protocol for SCSI Bus Drivers

The Driver Binding Protocol contains three services. These are **Supported()**, **Start()**, and **Stop()**. **Supported()** tests to see if the SCSI Bus Driver can manage a device handle. A SCSI Bus Driver can only manage device handle that contain the Device Path Protocol and the SCSI Pass Thru Protocol, so a SCSI Bus Driver must look for these two protocols on the device handle that is being tested.

The **Start()** function tells the SCSI Bus Driver to start managing a device handle. The device handle should support the protocols shown in [Figure 44](#). The SCSI Pass Thru Protocol provides information about a SCSI Channel and the ability to communicate with any SCSI devices attached to that SCSI Channel.

The SCSI Bus Driver has the option of creating all of its children in one call to **Start()**, or spreading it across several calls to **Start()**. In general, if it is possible to design a bus driver to create one child at a time, it should do so to support the rapid boot capability in the UEFI Driver Model. Each of the child device handles created in **Start()** must contain a Device Path Protocol instance, and a SCSI I/O protocol instance. The SCSI I/O Protocol is described in [Section 14.4](#) and [Section 13.4](#). The format of device paths for SCSI Devices is described in [Section 14.5](#). [Figure 45](#) shows an example child device handle that is created by a SCSI Bus Driver for a SCSI Device.

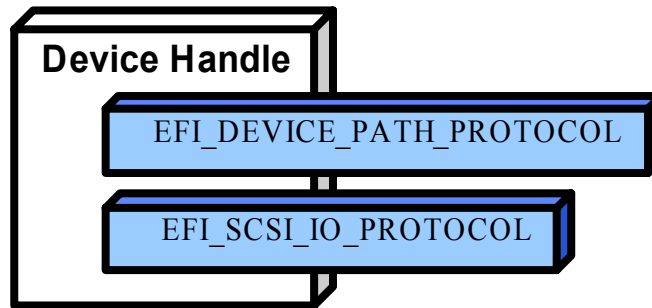


Figure 45. Child Handle Created by a SCSI Bus Driver

A SCSI Bus Driver must perform several steps to manage a SCSI Bus.

1. Scan for the SCSI Devices on the SCSI Channel that connected to the SCSI Bus Controller. If a request is being made to scan only one SCSI Device, then only looks for the one specified. Create a device handle for the SCSI Device found.
2. Install a Device Path Protocol instance and a SCSI I/O Protocol instance on the device handle created for each SCSI Device.

The **Stop()** function tells the SCSI Bus Driver to stop managing a SCSI Bus. The **Stop()** function can destroy one or more of the device handles that were created on a previous call to **Start()**. If all of the child device handles have been destroyed, then **Stop()** will place the SCSI Bus Controller in a quiescent state. The functionality of **Stop()** mirrors **Start()**.

14.2.2 SCSI Enumeration

The purpose of the SCSI Enumeration is only to scan for the SCSI Devices attached to the specific SCSI channel. The SCSI Bus driver need not allocate resources for SCSI Devices (like PCI Bus Drivers do), nor need it connect a SCSI Device with its Device Driver (like USB Bus Drivers do). The details of the SCSI Enumeration is implementation specific, thus is out of the scope of this document.

14.3 SCSI Device Drivers

SCSI Device Drivers manage SCSI Devices. Device handles for SCSI Devices are created by SCSI Bus Drivers. A SCSI Device Driver could be a bus driver itself, and may create child handles. But most SCSI Device Drivers will be device drivers that do not create new handles. For the pure device driver, it attaches protocol instance to the device handle of the SCSI Device. These protocol instances are I/O abstractions that allow the SCSI Device to be used in the pre-boot environment. The most common I/O abstractions are used to boot an EFI compliant OS.

14.3.1 Driver Binding Protocol for SCSI Device Drivers

The Driver Binding Protocol contains three services. These are **Supported()**, **Start()**, and **Stop()**. **Supported()** tests to see if the SCSI Device Driver can manage a device handle. A SCSI Device Driver can only manage device handle that contain the Device Path Protocol and the

SCSI I/O Protocol, so a SCSI Device Driver must look for these two protocols on the device handle that is being tested. In addition, it needs to check to see if the device handle represents a SCSI Device that SCSI Device Driver knows how to manage. This is typically done by using the services of the SCSI I/O Protocol to see whether the device information retrieved is supported by the device driver.

The **Start()** function tells the SCSI Device Driver to start managing a SCSI Device. A SCSI Device Driver could be a bus driver itself, and may create child handles. But most SCSI Device Drivers will be device drivers that do not create new handles. For the pure device driver, it installs one or more addition protocol instances on the device handle for the SCSI Device.

The **Stop()** function mirrors the **Start()** function, so the **Stop()** function completes any outstanding transactions to the SCSI Device and removes the protocol interfaces that were installed in **Start()**.

14.4 EFI SCSI I/O Protocol

This section defines the EFI SCSI I/O protocol. This protocol is used by code, typically drivers, running in the EFI boot services environment to access SCSI devices. In particular, functions for managing devices on SCSI buses are defined here.

The interfaces provided in the **EFI_SCSI_IO_PROTOCOL** are for performing basic operations to access SCSI devices.

EFI_SCSI_IO_PROTOCOL

This section provides a detailed description of the **EFI_SCSI_IO_PROTOCOL**.

Summary

Provides services to manage and communicate with SCSI devices.

GUID

```
#define EFI_SCSI_IO_PROTOCOL_GUID \
{0x932f47e6, 0x2362, 0x4002, 0x80, 0x3e, 0x3c, 0xd5, 0x4b, 0x13,
 0x8f, 0x85}
```

Protocol Interface Structure

```
typedef struct _EFI_SCSI_IO_PROTOCOL {
    EFI_SCSI_IO_PROTOCOL_GET_DEVICE_TYPE           GetDeviceType;
    EFI_SCSI_IO_PROTOCOL_GET_DEVICE_LOCATION      GetDeviceLocation;
    EFI_SCSI_IO_PROTOCOL_RESET_BUS                ResetBus;
    EFI_SCSI_IO_PROTOCOL_RESET_DEVICE            ResetDevice;
    EFI_SCSI_IO_PROTOCOL_EXECUTE_SCSI_COMMAND    ExecuteScsiCommand;
    UINT32                                         IoAlign;
} EFI_SCSI_IO_PROTOCOL;
```

Parameters

<i>IoAlign</i>	Supplies the alignment requirement for any buffer used in a data transfer. <i>IoAlign</i> values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, <i>IoAlign</i> must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by <i>IoAlign</i> with no remainder.
<i>GetDeviceType</i>	Retrieves the information of the device type which the SCSI device belongs to. See GetDeviceType() .
<i>GetDeviceLocation</i>	Retrieves the device location information in the SCSI bus. See GetDeviceLocation() .
<i>ResetBus</i>	Resets the entire SCSI bus the SCSI device attaches to. See ResetBus() .
<i>ResetDevice</i>	Resets the SCSI Device that is specified by the device handle the SCSI I/O protocol attaches. See ResetDevice() .
<i>ExecuteScsiCommand</i>	Sends a SCSI command to the SCSI device and waits for the execution completion until an exit condition is met, or a timeout occurs. See ExecuteScsiCommand() .

Description

The **EFI_SCSI_IO_PROTOCOL** provides the basic functionalities to access and manage a SCSI Device. There is one **EFI_SCSI_IO_PROTOCOL** instance for each SCSI Device on a SCSI Bus. A device driver that wishes to manage a SCSI Device in a system will have to retrieve the **EFI_SCSI_IO_PROTOCOL** instance that is associated with the SCSI Device. A device handle for a SCSI Device will minimally contain an **EFI_DEVICE_PATH_PROTOCOL** instance and an **EFI_SCSI_IO_PROTOCOL** instance.

EFI_SCSI_IO_PROTOCOL.GetDeviceType()

Summary

Retrieves the device type information of the SCSI Device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SCSI_IO_PROTOCOL_GET_DEVICE_TYPE) (
    IN  EFI_SCSI_IO_PROTOCOL    *This,
    OUT UINT8                   *DeviceType
);
```

Parameters

<i>This</i>	A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL .
<i>DeviceType</i>	A pointer to the device type information retrieved from the SCSI Device. See “Related Definitions” for the possible returned values of this parameter.

Description

This function is used to retrieve the SCSI device type information. This function is typically used for SCSI Device Drivers to quickly recognize whether the SCSI Device could be managed by it.

If *DeviceType* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. Otherwise, the device type is returned in *DeviceType* and **EFI_SUCCESS** is returned.

Related Definitions

```
//Defined in the SCSI Primary Commands standard (e.g., SPC-4)
//
#define EFI_SCSI_IO_TYPE_DISK           0x00 // Disk device
#define EFI_SCSI_IO_TYPE_TAPE          0x01 // Tape device
#define EFI_SCSI_IO_TYPE_PRINTER       0x02 // Printer
#define EFI_SCSI_IO_TYPE_PROCESSOR     0x03 // Processor
#define EFI_SCSI_IO_TYPE_WORM          0x04 // Write-once read-multiple
#define EFI_SCSI_IO_TYPE_CDROM         0x05 // CD or DVD device
#define EFI_SCSI_IO_TYPE_SCANNER       0x06 // Scanner device
#define EFI_SCSI_IO_TYPE_OPTICAL       0x07 // Optical memory device
#define EFI_SCSI_IO_TYPE_MEDIUMCHANGER 0x08 // Medium Changer device
#define EFI_SCSI_IO_TYPE_COMMUNICATION 0x09 // Communications device
#define MFI_SCSI_IO_TYPE_A             0x0A // Obsolete
#define MFI_SCSI_IO_TYPE_B             0x0B // Obsolete
#define MFI_SCSI_IO_TYPE_RAID          0x0C // Storage array controller
                                        // device (e.g., RAID)
#define MFI_SCSI_IO_TYPE_SES           0x0D // Enclosure services device
```

```

#define MFI_SCSI_IO_TYPE_RBC          0x0E // Simplified direct-access
                                         // device (e.g., magnetic
                                         // disk)
#define MFI_SCSI_IO_TYPE_OCRW        0x0F // Optical card reader/
                                         // writer device
#define MFI_SCSI_IO_TYPE_BRIDGE      0x10 // Bridge Controller
                                         // Commands
#define MFI_SCSI_IO_TYPE OSD         0x11 // Object-based Storage
                                         // Device
#define EFI_SCSI_IO_TYPE_RESERVED_LOW 0x12 // Reserved (low)
#define EFI_SCSI_IO_TYPE_RESERVED_HIGH 0x1E // Reserved (high)
#define EFI_SCSI_IO_TYPE_UNKNOWN     0x1F // Unknown no device type
    
```

Status Codes Returned

EFI_SUCCESS	Retrieves the device type information successfully.
EFI_INVALID_PARAMETER	The DeviceType is NULL .

EFI_SCSI_IO_PROTOCOL.GetDeviceLocation()

Summary

Retrieves the SCSI device location in the SCSI channel.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SCSI_IO_PROTOCOL_GET_DEVICE_LOCATION) (
    IN EFI_SCSI_IO_PROTOCOL *This,
    IN OUT UINT8             **Target,
    OUT  UINT64              *Lun
);
```

Parameters

<i>This</i>	A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL .
<i>Target</i>	A pointer to the Target Array which represents the ID of a SCSI device on the SCSI channel..
<i>Lun</i>	A pointer to the Logical Unit Number of the SCSI device on the SCSI channel.

Description

This function is used to retrieve the SCSI device location in the SCSI bus. The device location is determined by a (Target, Lun) pair. This function allows a SCSI Device Driver to retrieve its location on the SCSI channel, and may use the SCSI Pass Thru Protocol to access the SCSI device directly.

If *Target* or *Lun* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. Otherwise, the device location is returned in *Target* and *Lun*, and **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	Retrieves the device location successfully.
EFI_INVALID_PARAMETER	Target or Lun is NULL .

EFI_SCSI_IO_PROTOCOL.ResetBus()

Summary

Resets the SCSI Bus that the SCSI Device is attached to.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SCSI_IO_PROTOCOL_RESET_BUS) (
    IN EFI_SCSI_IO_PROTOCOL      *This
);
```

Parameters

This A pointer to the **EFI_SCSI_IO_PROTOCOL** instance. Type **EFI_SCSI_IO_PROTOCOL** is defined in [EFI_SCSI_IO_PROTOCOL](#).

Description

This function provides the mechanism to reset the whole SCSI bus that the specified SCSI Device is connected to. Some SCSI Host Controller may not support bus reset, if so, **EFI_UNSUPPORTED** is returned. If a device error occurs while executing that bus reset operation, then **EFI_DEVICE_ERROR** is returned. If a timeout occurs during the execution of the bus reset operation, then **EFI_TIMEOUT** is returned. If the bus reset operation is completed, then **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The SCSI bus is reset successfully.
EFI_DEVICE_ERROR	Errors encountered when resetting the SCSI bus.
EFI_UNSUPPORTED	The bus reset operation is not supported by the SCSI Host Controller.
EFI_TIMEOUT	A timeout occurred while attempting to reset the SCSI bus.

EFI_SCSI_IO_PROTOCOL.ResetDevice()

Summary

Resets the SCSI Device that is specified by the device handle that the SCSI I/O Protocol is attached.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SCSI_IO_PROTOCOL_RESET_DEVICE) (
    IN EFI_SCSI_IO_PROTOCOL      *This
);
```

Parameters

This

A pointer to the **EFI_SCSI_IO_PROTOCOL** instance. Type **EFI_SCSI_IO_PROTOCOL** is defined in [EFI_SCSI_IO_PROTOCOL](#).

Description

This function provides the mechanism to reset the SCSI Device. If the SCSI bus does not support a device reset operation, then **EFI_UNSUPPORTED** is returned. If a device error occurs while executing that device reset operation, then **EFI_DEVICE_ERROR** is returned. If a timeout occurs during the execution of the device reset operation, then **EFI_TIMEOUT** is returned. If the device reset operation is completed, then **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	Reset the SCSI Device successfully.
EFI_DEVICE_ERROR	Errors are encountered when resetting the SCSI Device.
EFI_UNSUPPORTED	The SCSI bus does not support a device reset operation.
EFI_TIMEOUT	A timeout occurred while attempting to reset the SCSI Device.

EFI_SCSI_IO_PROTOCOL.ExecuteScsiCommand()

Summary

Sends a SCSI Request Packet to the SCSI Device for execution.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_SCSI_IO_PROTOCOL_EXECUTE_SCSI_COMMAND) (
    IN      EFI_SCSI_IO_PROTOCOL          *This,
    IN OUT  EFI_SCSI_IO_SCSI_REQUEST_PACKET *Packet,
    IN      EFI_EVENT                     Event OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL .
<i>Packet</i>	The SCSI request packet to send to the SCSI Device specified by the device handle. See “Related Definitions” for a description of EFI_SCSI_IO_SCSI_REQUEST_PACKET .
<i>Event</i>	If the SCSI bus where the SCSI device is attached does not support non-blocking I/O, then <i>Event</i> is ignored, and blocking I/O is performed. If <i>Event</i> is NULL , then blocking I/O is performed. If <i>Event</i> is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and <i>Event</i> will be signaled when the SCSI Request Packet completes.

Related Definitions

```
typedef struct {
    UINT64      Timeout;
    VOID        *InDataBuffer;
    VOID        *OutDataBuffer;
    VOID        *SenseData;
    VOID        *Cdb;
    UINT32      InTransferLength;
    UINT32      OutTransferLength;
    UINT8       CdbLength;
    UINT8       DataDirection;
    UINT8       HostAdapterStatus;
    UINT8       TargetStatus;
    UINT8       SenseDataLength;
} EFI_SCSI_IO_SCSI_REQUEST_PACKET;
```

<i>Timeout</i>	The timeout, in 100 ns units, to use for the execution of this SCSI Request Packet. A <i>Timeout</i> value of 0 means that this function will wait indefinitely for the SCSI Request Packet to execute. If <i>Timeout</i> is greater than zero, then this function will return EFI_TIMEOUT if the time required to execute the SCSI Request Packet is greater than <i>Timeout</i> .
<i>DataBuffer</i>	A pointer to the data buffer to transfer from or to the SCSI device.
<i>InDataBuffer</i>	A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for SCSI READ command. For all SCSI WRITE Commands this must point to NULL .
<i>OutDataBuffer</i>	A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for SCSI WRITE command. For all SCSI READ commands this field must point to NULL .
<i>SenseData</i>	A pointer to the sense data that was generated by the execution of the SCSI Request Packet.
<i>Cdb</i>	A pointer to buffer that contains the Command Data Block to send to the SCSI device.
<i>InTransferLength</i>	On Input, the size, in bytes, of <i>InDataBuffer</i> . On output, the number of bytes transferred between the SCSI controller and the SCSI device. If <i>InTransferLength</i> is larger than the SCSI controller can handle, no data will be transferred, <i>InTransferLength</i> will be updated to contain the number of bytes that the SCSI controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.
<i>OutTransferLength</i>	On Input, the size, in bytes of <i>OutDataBuffer</i> . On Output, the Number of bytes transferred between SCSI Controller and the SCSI device. If <i>OutTransferLength</i> is larger than the SCSI controller can handle, no data will be transferred, <i>OutTransferLength</i> will be updated to contain the number of bytes that the SCSI controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.
<i>CdbLength</i>	The length, in bytes, of the buffer <i>Cdb</i> . The standard values are 6, 10, 12, and 16, but other values are possible if a variable length <i>CDB</i> is used.
<i>DataDirection</i>	The direction of the data transfer. 0 for reads, 1 for writes. A value of 2 is Reserved for Bi-Directional SCSI commands. For example XDREADWRITE. All other values are reserved, and must not be used.
<i>HostAdapterStatus</i>	The status of the SCSI Host Controller that produces the SCSI bus where the SCSI device attached when the SCSI Request Packet was executed on the SCSI Controller. See the possible values listed below.
<i>TargetStatus</i>	The status returned by the SCSI device when the SCSI Request Packet was executed. See the possible values listed below.
<i>SenseDataLength</i>	On input, the length in bytes of the <i>SenseData</i> buffer. On output, the number of bytes written to the <i>SenseData</i> buffer.

```

//
// DataDirection
//
#define EFI_SCSI_IO_DATA_DIRECTION_READ          0
#define EFI_SCSI_IO_DATA_DIRECTION_WRITE        1
#define EFI_SCSI_IO_DATA_DIRECTION_BIDIRECTIONAL 2

//
// HostAdapterStatus
//
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_OK          0x00
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_TIMEOUT_COMMAND 0x09
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_TIMEOUT      0x0b
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_MESSAGE_REJECT 0x0d
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_BUS_RESET    0x0e
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_PARITY_ERROR 0x0f
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_REQUEST_SENSE_FAILED 0x10
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_SELECTION_TIMEOUT 0x11
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_DATA_OVERRUN_UNDERRUN 0x12
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_BUS_FREE    0x13
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_PHASE_ERROR 0x14
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_OTHER      0x7f

//
// TargetStatus
//
#define EFI_SCSI_IO_STATUS_TARGET_GOOD              0x00
#define EFI_SCSI_IO_STATUS_TARGET_CHECK_CONDITION 0x02
#define EFI_SCSI_IO_STATUS_TARGET_CONDITION_MET    0x04
#define EFI_SCSI_IO_STATUS_TARGET_BUSY             0x08
#define EFI_SCSI_IO_STATUS_TARGET_INTERMEDIATE     0x10
#define EFI_SCSI_IO_STATUS_TARGET_INTERMEDIATE_CONDITION_MET 0x14
#define EFI_SCSI_IO_STATUS_TARGET_RESERVATION_CONFLICT 0x18
#define EFI_SCSI_IO_STATUS_TARGET_COMMAND_TERMINATED 0x22
#define EFI_SCSI_IO_STATUS_TARGET_QUEUE_FULL      0x28

```

Description

This function sends the SCSI Request Packet specified by *Packet* to the SCSI Device.

If the SCSI Bus supports non-blocking I/O and *Event* is not **NULL**, then this function will return immediately after the command is sent to the SCSI Device, and will later signal *Event* when the command has completed. If the SCSI Bus supports non-blocking I/O and *Event* is **NULL**, then this function will send the command to the SCSI Device and block until it is complete. If the SCSI Bus

does not support non-blocking I/O, the *Event* parameter is ignored, and the function will send the command to the SCSI Device and block until it is complete.

If *Packet* is successfully sent to the SCSI Device, then **EFI_SUCCESS** is returned.

If *Packet* cannot be sent because there are too many packets already queued up, then **EFI_NOT_READY** is returned. The caller may retry *Packet* at a later time.

If a device error occurs while sending the *Packet*, then **EFI_DEVICE_ERROR** is returned.

If a timeout occurs during the execution of *Packet*, then **EFI_TIMEOUT** is returned.

If any field of *Packet* is invalid, then **EFI_INVALID_PARAMETER** is returned.

If the data buffer described by *DataBuffer* and *TransferLength* is too big to be transferred in a single command, then **EFI_BAD_BUFFER_SIZE** is returned. The number of bytes actually transferred is returned in *TransferLength*.

If the command described in *Packet* is not supported by the SCSI Host Controller that produces the SCSI bus, then **EFI_UNSUPPORTED** is returned.

If **EFI_SUCCESS**, **EFI_BAD_BUFFER_SIZE**, **EFI_DEVICE_ERROR**, or **EFI_TIMEOUT** is returned, then the caller must examine the status fields in *Packet* in the following precedence order: *HostAdapterStatus* followed by *TargetStatus* followed by *SenseDataLength*, followed by *SenseData*. If non-blocking I/O is being used, then the status fields in *Packet* will not be valid until the *Event* associated with *Packet* is signaled.

If **EFI_NOT_READY**, **EFI_INVALID_PARAMETER** or **EFI_UNSUPPORTED** is returned, then *Packet* was never sent, so the status fields in *Packet* are not valid. If non-blocking I/O is being used, the *Event* associated with *Packet* will not be signaled.

Status Codes Returned

EFI_SUCCESS	The SCSI Request Packet was sent by the host. For read and bi-directional commands, <i>InTransferLength</i> bytes were transferred to <i>InDataBuffer</i> . For write and bi-directional commands, <i>OutTransferLength</i> bytes were transferred from <i>OutDataBuffer</i> . See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , <i>SenseDataLength</i> , and <i>SenseData</i> in that order for additional status information.
EFI_BAD_BUFFER_SIZE	The SCSI Request Packet was not executed. For read and bi-directional commands, the number of bytes that could be transferred is returned in <i>InTransferLength</i> . For write and bi-directional commands, the number of bytes that could be transferred is returned in <i>OutTransferLength</i> . See <i>HostAdapterStatus</i> and <i>TargetStatus</i> in that order for additional status information.
EFI_NOT_READY	The SCSI Request Packet could not be sent because there are too many SCSI Command Packets already queued. The caller may retry again later.

EFI_DEVICE_ERROR	A device error occurred while attempting to send the SCSI Request Packet. See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , <i>SenseDataLength</i> , and <i>SenseData</i> in that order for additional status information.
EFI_INVALID_PARAMETER	The contents of <i>CommandPacket</i> are invalid. The SCSI Request Packet was not sent, so no additional status information is available.
EFI_UNSUPPORTED	The command described by the SCSI Request Packet is not supported by the SCSI initiator (i.e., SCSI Host Controller). The SCSI Request Packet was not sent, so no additional status information is available.
EFI_TIMEOUT	A timeout occurred while waiting for the SCSI Request Packet to execute. See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , <i>SenseDataLength</i> , and <i>SenseData</i> in that order for additional status information.

14.5 SCSI Device Paths

An **EFI_SCSI_IO_PROTOCOL** must be installed on a handle for its services to be available to SCSI device drivers. In addition to the **EFI_SCSI_IO_PROTOCOL**, an **EFI_DEVICE_PATH_PROTOCOL** must also be installed on the same handle. See [Section 9](#) for detailed description of the **EFI_DEVICE_PATH_PROTOCOL**.

The SCSI Driver Model defined in this document can support the SCSI channel generated or emulated by multiple architectures, such as Parallel SCSI, ATAPI, Fibre Channel, InfiniBand, and other future channel types. In this section, there are four example device paths provided, including SCSI device path, ATAPI device path, Fibre Channel device path and InfiniBand device path.

14.5.1 SCSI Device Path Example

[Table 105](#) shows an example device path for a SCSI device controller on a desktop platform. This SCSI device controller is connected to a SCSI channel that is generated by a PCI SCSI host controller. The PCI SCSI host controller generates a single SCSI channel, it is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. The SCSI device controller is assigned SCSI Id 2, and its LUN is 0.

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, a SCSI Node, and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03, 0) / PCI (7, 0) / SCSI (2, 0) .

Table 105. SCSI Device Path Examples

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path

Byte Offset	Byte Length	Data	Description
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x07	PCI Function
0x11	0x01	0x00	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x13	0x01	0x02	Sub type – SCSI
0x14	0x02	0x08	Length – 0x08 bytes
0x16	0x02	0x0002	Target ID on the SCSI bus (PUN)
0x18	0x02	0x0000	Logical Unit Number (LUN)
0x1A	0x01	0xff	Generic Device Path Header – Type End of Hardware Device Path
0x1B	0x01	0xFF	Sub type – End of Entire Device Path
0x1C	0x02	0x04	Length – 0x04 bytes

14.5.2 ATAPI Device Path Example

[Table 106](#) shows an example device path for an ATAPI device on a desktop platform. This ATAPI device is connected to the IDE bus on Primary channel, and is configured as the Master device on the channel. The IDE bus is generated by the IDE controller that is a PCI device. It is located at PCI device number 0x1F and PCI function 0x01, and is directly attached to a PCI root bridge.

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, an ATAPI Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03, 0) / PCI (7, 0) / ATA (Primary, Master, 0) .

Table 106. ATAPI Device Path Examples

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes

Byte Offset	Byte Length	Data	Description
0x10	0x01	0x07	PCI Function
0x11	0x01	0x00	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x13	0x01	0x01	Sub type – ATAPI
0x14	0x02	0x08	Length – 0x08 bytes
0x16	0x01	0x00	PrimarySecondary – Set to zero for primary or one for secondary.
0x17	0x01	0x00	SlaveMaster – set to zero for master or one for slave.
0x18	0x02	0x0000	Logical Unit Number,LUN.
0x1A	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x1B	0x01	0xFF	Sub type – End of Entire Device Path
0x1C	0x02	0x04	Length – 0x04 bytes

14.5.3 Fibre Channel Device Path Example

[Table 107](#) shows an example device path for an SCSI device that is connected to a Fibre Channel Port on a desktop platform. The Fibre Channel Port is a PCI device that is located at PCI device number 0x08 and PCI function 0x00, and is directly attached to a PCI root bridge. The Fibre Channel Port is addressed by the World Wide Number, and is assigned as X (X is a 64bit value); the SCSI device’s Logical Unit Number is 0.

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, a Fibre Channel Device Path Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03, 0) / PCI (8, 0) / Fibre (X, 0) .

Table 107. Fibre Channel Device Path Examples

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x08	PCI Function
0x11	0x01	0x00	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x13	0x01	0x02	Sub type – Fibre Channel

Byte Offset	Byte Length	Data	Description
0x14	0x02	0x24	Length – 0x24 bytes
0x16	0x04	0x00	Reserved
0x1A	0x08	X	Fibre Channel World Wide Number
0x22	0x08	0x00	Fibre Channel Logical Unit Number (LUN).
0x2A	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x2B	0x01	0xFF	Sub type – End of Entire Device Path
0x2C	0x02	0x04	Length – 0x04 bytes

14.5.4 InfiniBand Device Path Example

[Table 108](#) shows an example device path for a SCSI device in an InfiniBand Network. This SCSI device is connected to a single SCSI channel generated by a SCSI Host Adapter, and the SCSI Host Adapter is an end node in the InfiniBand Network. The SCSI Host Adapter is a PCI device that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. The SCSI device is addressed by the (IOU X, IOC Y, DeviceId Z) in the InfiniBand Network. (X, Y, Z are EUI-64 compliant identifiers).

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, an InfiniBand Node, and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

`ACPI (PNP0A03, 0) / PCI (7, 0) / Infiniband (X, Y, Z) .`

Table 108. InfiniBand Device Path Examples

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID</code> PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes.
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x07	PCI Function
0x11	0x01	0x00	PCI Device
0x12	0x01	0x03	Generic Device Path Header – Type Message Device Path
0x13	0x01	0x09	Sub type – InfiniBand
0x14	0x02	0x20	Length – 0x20 bytes
0x16	0x04	0x00	Reserved
0x1A	0x08	X	64bit node GUID of the IOU
0x22	0x08	Y	64bit GUID of the IOC

Byte Offset	Byte Length	Data	Description
0x2A	0x08	Z	64bit persistent ID of the device.
0x32	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x33	0x01	0xFF	Sub type – End of Entire Device Path
0x34	0x02	0x04	Length – 0x04 bytes

14.6 SCSI Pass Thru Device Paths

An [EFI EXT SCSI PASS THRU PROTOCOL](#) must be installed on a handle for its services to be available to UEFI drivers and applications. In addition to the [EFI EXT SCSI PASS THRU PROTOCOL](#), an [EFI DEVICE PATH PROTOCOL](#) must also be installed on the same handle. See [Section 9](#) for a detailed description of the [EFI_DEVICE_PATH_PROTOCOL](#).

A device path describes the location of a hardware component in a system from the processor’s point of view. This includes the list of busses that lie between the processor and the SCSI controller. The *EFI Specification* takes advantage of the *ACPI Specification* to name system components. For the following set of examples, a PCI SCSI controller is assumed. The examples will show a SCSI controller on the root PCI bus, and a SCSI controller behind a PCI-PCI bridge. In addition, an example of a multichannel SCSI controller will be shown.

[Table 109](#) shows an example device path for a single channel PCI SCSI controller that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node, a PCI Device Path Node, and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03, 0) / PCI (7, 0) .

Table 109. Single Channel PCI SCSI Controller

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID</code> PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x00	PCI Function
0x11	0x01	0x07	PCI Device
0x12	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x13	0x01	0xFF	Sub type – End of Entire Device Path

Byte Offset	Byte Length	Data	Description
0x14	0x02	0x04	Length – 0x04 bytes

[Table 110](#) shows an example device path for a single channel PCI SCSI controller that is located behind a PCI to PCI bridge at PCI device number 0x07 and PCI function 0x00. The PCI to PCI bridge is directly attached to a PCI root bridge, and it is at PCI device number 0x05 and PCI function 0x00. This device path consists of an ACPI Device Path Node, two PCI Device Path Nodes, and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI (PNP0A03, 0) / PCI (5, 0) / PCI (7, 0) .

Table 110. Single Channel PCI SCSI Controller behind a PCI Bridge

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	<code>_HID</code> PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0000	<code>_UID</code>
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x00	PCI Function
0x11	0x01	0x05	PCI Device
0x12	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x13	0x01	0x01	Sub type – PCI
0x14	0x02	0x06	Length – 0x06 bytes
0x16	0x01	0x00	PCI Function
0x17	0x01	0x07	PCI Device
0x18	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x19	0x01	0xFF	Sub type – End of Entire Device Path
0x1A	0x02	0x04	Length – 0x04 bytes

[Table 111](#) shows an example device path for channel #3 of a four channel PCI SCSI controller that is located behind a PCI to PCI bridge at PCI device number 0x07 and PCI function 0x00. The PCI to PCI bridge is directly attached to a PCI root bridge, and it is at PCI device number 0x05 and PCI function 0x00. This device path consists of an ACPI Device Path Node, two PCI Device Path Nodes, a Controller Node, and a Device Path End Structure. The `_HID` and `_UID` must match the ACPI table description of the PCI Root Bridge. The shorthand notation of the device paths for all four of the SCSI channels are listed below. [Table 111](#) shows the last device path listed.

ACPI (PNP0A03, 0) / PCI (5, 0) / PCI (7, 0) / Ctrl (0)
 ACPI (PNP0A03, 0) / PCI (5, 0) / PCI (7, 0) / Ctrl (1)
 ACPI (PNP0A03, 0) / PCI (5, 0) / PCI (7, 0) / Ctrl (2)
 ACPI (PNP0A03, 0) / PCI (5, 0) / PCI (7, 0) / Ctrl (3)

Table 111. Channel #3 of a PCI SCSI Controller behind a PCI Bridge

Byte Offset	Byte Length	Data	Description
0x00	0x01	0x02	Generic Device Path Header – Type ACPI Device Path
0x01	0x01	0x01	Sub type – ACPI Device Path
0x02	0x02	0x0C	Length – 0x0C bytes
0x04	0x04	0x41D0, 0x0A03	_HID PNP0A03 – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
0x08	0x04	0x0000	_UID
0x0C	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x0D	0x01	0x01	Sub type – PCI
0x0E	0x02	0x06	Length – 0x06 bytes
0x10	0x01	0x00	PCI Function
0x11	0x01	0x05	PCI Device
0x12	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x13	0x01	0x01	Sub type – PCI
0x14	0x02	0x06	Length – 0x06 bytes
0x16	0x01	0x00	PCI Function
0x17	0x01	0x07	PCI Device
0x18	0x01	0x01	Generic Device Path Header – Type Hardware Device Path
0x19	0x01	0x05	Sub type – Controller
0x1A	0x02	0x08	Length – 0x08 bytes
0x1C	0x04	0x0003	Controller Number
0x20	0x01	0xFF	Generic Device Path Header – Type End of Hardware Device Path
0x21	0x01	0xFF	Sub type – End of Entire Device Path
0x22	0x02	0x04	Length – 0x04 bytes

14.7 Extended SCSI Pass Thru Protocol

This section defines the Extended SCSI Pass Thru Protocol. This protocol allows information about a SCSI channel to be collected, and allows SCSI Request Packets to be sent to any SCSI devices on a SCSI channel even if those devices are not boot devices. This protocol is attached to the device handle of each SCSI channel in a system that the protocol supports, and can be used for diagnostics. It may also be used to build a Block I/O driver for SCSI hard drives and SCSI CD-ROM or DVD drives to allow those devices to become boot devices.

EFI_EXT_SCSI_PASS_THRU_PROTOCOL

This section provides a detailed description of the [EFI_EXT_SCSI_PASS_THRU_PROTOCOL](#).

Summary

Provides services that allow SCSI Pass Thru commands to be sent to SCSI devices attached to a SCSI channel.

GUID

```
#define EFI_EXT_SCSI_PASS_THRU_PROTOCOL_GUID \
    {0x1d3de7f0, 0x807, 0x424f, 0xaa, 0x69, 0x11, 0xa5, 0x4e, 0x19, 0xa4, \
     0x6f}
```

Protocol Interface Structure

```
typedef struct _EFI_EXT_SCSI_PASS_THRU_PROTOCOL {
    EFI_EXT_SCSI_PASS_THRU_MODE           *Mode;
    EFI_EXT_SCSI_PASS_THRU_PASSTHRU      PassThru;
    EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET_LUN  GetNextTargetLun;
    EFI_EXT_SCSI_PASS_THRU_BUILD_DEVICE_PATH  BuildDevicePath;
    EFI_EXT_SCSI_PASS_THRU_GET_TARGET_LUN     GetTargetLun;
    EFI_EXT_SCSI_PASS_THRU_RESET_CHANNEL      ResetChannel;
    EFI_EXT_SCSI_PASS_THRU_RESET_TARGET_LUN  ResetTargetLun;
    EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET   GetNextTarget;}
EFI_EXT_SCSI_PASS_THRU_PROTOCOL;
```

Parameters

<i>Mode</i>	A pointer to the EFI_EXT_SCSI_PASS_THRU_MODE data for this SCSI channel. EFI_EXT_SCSI_PASS_THRU_MODE is defined in “Related Definitions” below.
<i>PassThru</i>	Sends a SCSI Request Packet to a SCSI device that is Connected to the SCSI channel. See the PassThru () function description.
<i>GetNextTargetLun</i>	Retrieves the list of legal Target IDs and LUNs for the SCSI devices on a SCSI channel. See the GetNextTargetLun () function description.
<i>BuildDevicePath</i>	Allocates and builds a device path node for a SCSI Device on a SCSI channel. See the BuildDevicePath () function description.
<i>GetTargetLun</i>	Translates a device path node to a Target ID and LUN. See the GetTargetLun () function description.
<i>ResetChannel</i>	Resets the SCSI channel. This operation resets all the SCSI devices connected to the SCSI channel. See the ResetChannel () function description.
<i>ResetTargetLun</i>	Resets a SCSI device that is connected to the SCSI channel. See the ResetTargetLun () function description.

GetNextTartget Retrieves the list of legal Target IDs for the SCSI devices on a SCSI channel. See the [GetNextTarget\(\)](#) function description.

The following data values in the **EFI_EXT_SCSI_PASS_THRU_MODE** interface are read-only.

AdapterId The Target ID of the host adapter on the SCSI channel.

Attributes Additional information on the attributes of the SCSI channel. See “Related Definitions” below for the list of possible attributes.

IoAlign Supplies the alignment requirement for any buffer used in a data transfer. *IoAlign* values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, *IoAlign* must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by *IoAlign* with no remainder.

Related Definitions

```
typedef struct {
    UINT32     AdapterId;
    UINT32     Attributes;
    UINT32     IoAlign;
} EFI_EXT_SCSI_PASS_THRU_MODE;
```

```
#define TARGET_MAX_BYTES0x10
#define EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL    0x0001
#define EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL     0x0002
#define EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_NONBLOCKIO 0x0004
```

EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL

If this bit is set, then the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interface is for physical devices on the SCSI channel.

EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL

If this bit is set, then the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interface is for logical devices on the SCSI channel.

EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_NONBLOCKIO

If this bit is set, then the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interface supports non blocking I/O. Every **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** must support blocking I/O. The support of nonblocking I/O is optional.

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** provides information about a SCSI channel and the ability to send SCI Request Packets to any SCSI device attached to that SCSI channel. The information includes the Target ID of the host controller on the SCSI channel and the attributes of the SCSI channel.

The printable name for the SCSI controller, and the printable name of the SCSI channel can be provided through the **EFI_COMPONENT_NAME_PROTOCOL** for multiple languages.

The *Attributes* field of the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interface tells if the interface is for physical SCSI devices or logical SCSI devices. Drivers for non-RAID SCSI controllers will set both the **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL**, and the **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL** bits.

Drivers for RAID controllers that allow access to the physical devices and logical devices will produce two **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interfaces: one with just the **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL** bit set and another with just the **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL** bit set. One interface can be used to access the physical devices attached to the RAID controller, and the other can be used to access the logical devices attached to the RAID controller for its current configuration.

Drivers for RAID controllers that do not allow access to the physical devices will produce one **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interface with just the **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL** bit set. The interface for logical devices can also be used by a file system driver to mount the RAID volumes. An **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** with neither **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL** nor **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL** set is an illegal configuration.

The *Attributes* field also contains the **EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_NONBLOCKIO** bit. All **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** interfaces must support blocking I/O. If this bit is set, then the interface support both blocking I/O and nonblocking I/O.

Each **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** instance must have an associated device path. Typically this will have an *ACPI* device path node and a *PCI* device path node, although variation will exist. For a SCSI controller that supports only one channel per PCI bus/device/function, it is recommended, but not required, that an additional *Controller* device path node (for controller 0) be appended to the device path.

For a SCSI controller that supports multiple channels per PCI bus/device/function, it is required that a *Controller* device path node be appended for each channel.

Additional information about the SCSI channel can be obtained from protocols attached to the same handle as the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL**, or one of its parent handles. This would include the device I/O abstraction used to access the internal registers and functions of the SCSI controller.

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.PassThru()

Summary

Sends a SCSI Request Packet to a SCSI device that is attached to the SCSI channel. This function supports both blocking I/O and nonblocking I/O. The blocking I/O functionality is required, and the nonblocking I/O functionality is optional.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_PASSTHRU) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL      *This,
    IN UINT8                                *Target,
    IN UINT64                               Lun,
    IN OUT EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET *Packet,
    IN EFI_EVENT                            Event OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Section 14.7 .
<i>Target</i>	The Target is an array of size TARGET_MAX_BYTES and it represents the id of the SCSI device to send the SCSI Request Packet. Each transport driver may chose to utilize a subset of this size to suit the needs of transport target representation. For example, a Fibre Channel driver may use only 8 bytes (WWN) to represent an FC target.
<i>Lun</i>	The LUN of the SCSI device to send the SCSI Request Packet.
<i>Packet</i>	A pointer to the SCSI Request Packet to send to the SCSI device specified by <i>Target</i> and <i>Lun</i> . See “Related Definitions” below for a description of EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET .
<i>Event</i>	If nonblocking I/O is not supported then <i>Event</i> is ignored, and blocking I/O is performed. If <i>Event</i> is NULL , then blocking I/O is performed. If <i>Event</i> is not NULL and non blocking I/O is supported, then nonblocking I/O is performed, and <i>Event</i> will be signaled when the SCSI Request Packet completes.

Related Definitions

```
typedef struct {
    UINT64    Timeout;
    VOID      *InDataBuffer;
    VOID      *OutDataBuffer;
```

```

VOID      *SenseData;
VOID      *Cdb;
UINT32    InTransferLength;
UINT32    OutTransferLength;
UINT8     CdbLength;
UINT8     DataDirection;
UINT8     HostAdapterStatus;
UINT8     TargetStatus;
UINT8     SenseDataLength;
} EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET;

```

Timeout The timeout, in 100 ns units, to use for the execution of this SCSI Request Packet. A *Timeout* value of 0 means that this function will wait indefinitely for the SCSI Request Packet to execute. If *Timeout* is greater than zero, then this function will return **EFI_TIMEOUT** if the time required to execute the SCSI Request Packet is greater than *Timeout*.

InDataBuffer A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for read and bidirectional commands. For all write and non data commands where *InTransferLength* is 0 this field is optional and may be **NULL**. If this field is not **NULL**, then it must be aligned on the boundary specified by the *IoAlign* field in the **EFI_EXT_SCSI_PASS_THRU_MODE** structure.

OutDataBuffer A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for write or bidirectional commands. For all read and non data commands where *OutTransferLength* is 0 this field is optional and may be **NULL**. If this field is not **NULL**, then it must be aligned on the boundary specified by the *IoAlign* field in the **EFI_EXT_SCSI_PASS_THRU_MODE** structure.

SenseData A pointer to the sense data that was generated by the execution of the SCSI Request Packet. If *SenseDataLength* is 0, then this field is optional and may be **NULL**. It is strongly recommended that a sense data buffer of at least 252 bytes be provided to guarantee the entire sense data buffer generated from the execution of the SCSI Request Packet can be returned. If this field is not **NULL**, then it must be aligned to the boundary specified in the *IoAlign* field in the **EFI_EXT_SCSI_PASS_THRU_MODE** structure.

Cdb A pointer to buffer that contains the Command Data Block to send to the SCSI device specified by *Target* and *Lun*.

InTransferLength On Input, the size, in bytes, of *InDataBuffer*. On output, the number of bytes transferred between the SCSI controller and the SCSI device. If *InTransferLength* is larger than the SCSI controller can handle, no data will be transferred, *InTransferLength* will be updated to contain the number

of bytes that the SCSI controller is able to transfer, and **EFI_BAD_BUFFER_SIZE** will be returned.

OutTransferLength On Input, the size, in bytes of *OutDataBuffer*. On Output, the Number of bytes transferred between SCSI Controller and the SCSI device. If *OutTransferLength* is larger than the SCSI controller can handle, no data will be transferred, *OutTransferLength* will be updated to contain the number of bytes that the SCSI controller is able to transfer, and **EFI_BAD_BUFFER_SIZE** will be returned.

CdbLength The length, in bytes, of the buffer *Cdb*. The standard values are 6, 10, 12, and 16, but other values are possible if a variable length *CDB* is used.

DataDirection The direction of the data transfer. 0 for reads, 1 for writes. A value of 2 is Reserved for Bi-Directional SCSI commands. For example XDREADWRITE. All other values are reserved, and must not be used.

HostAdapterStatus The status of the host adapter specified by *This* when the SCSI Request Packet was executed on the target device. See the possible values listed below. If bit 7 of this field is set, then *HostAdapterStatus* is a vendor defined error code.

TargetStatus The status returned by the device specified by *Target* and *Lun* when the SCSI Request Packet was executed. See the possible values listed below.

SenseDataLength On input, the length in bytes of the *SenseData* buffer. On output, the number of bytes written to the *SenseData* buffer.

```
//
// DataDirection
//
#define EFI_EXT_SCSI_DATA_DIRECTION_READ          0
#define EFI_EXT_SCSI_DATA_DIRECTION_WRITE        1
#define EFI_EXT_SCSI_DATA_DIRECTION_BIDIRECTIONAL 2
//
// HostAdapterStatus
//
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_OK          0x00
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_TIMEOUT_COMMAND 0x09
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_TIMEOUT    0x0b
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_MESSAGE_REJECT 0x0d
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_BUS_RESET   0x0e
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_PARITY_ERROR 0x0f
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_REQUEST_SENSE_FAILED 0x10
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_SELECTION_TIMEOUT 0x11
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_DATA_OVERRUN_UNDERRUN 0x12
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_BUS_FREE    0x13
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_PHASE_ERROR 0x14
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_OTHER      0x7f
```

```

//
// TargetStatus
//
#define EFI_EXT_SCSI_STATUS_TARGET_GOOD                0x00
#define EFI_EXT_SCSI_STATUS_TARGET_CHECK_CONDITION    0x02
#define EFI_EXT_SCSI_STATUS_TARGET_CONDITION_MET      0x04
#define EFI_EXT_SCSI_STATUS_TARGET_BUSY               0x08
#define EFI_EXT_SCSI_STATUS_TARGET_INTERMEDIATE      0x10
#define EFI_EXT_SCSI_STATUS_TARGET_INTERMEDIATE_CONDITION_MET 0x14
#define EFI_EXT_SCSI_STATUS_TARGET_RESERVATION_CONFLICT 0x18
#define EFI_EXT_SCSI_STATUS_TARGET_TASK_SET_FULL     0x28
#define EFI_EXT_SCSI_STATUS_TARGET_ACA_ACTIVE        0x30
#define EFI_EXT_SCSI_STATUS_TARGET_TASK_ABORTED     0x40

```

Description

The [PassThru\(\)](#) function sends the SCSI Request Packet specified by *Packet* to the SCSI device specified by *Target* and *Lun*. If the driver supports nonblocking I/O and *Event* is not **NULL**, then the driver will return immediately after the command is sent to the selected device, and will later signal *Event* when the command has completed.

If the driver supports nonblocking I/O and *Event* is NULL, then the driver will send the command to the selected device and block until it is complete.

If the driver does not support nonblocking I/O, then the *Event* parameter is ignored, and the driver will send the command to the selected device and block until it is complete.

If *Packet* is successfully sent to the SCSI device, then **EFI_SUCCESS** is returned.

If *Packet* cannot be sent because there are too many packets already queued up, then **EFI_NOT_READY** is returned. The caller may retry *Packet* at a later time.

If a device error occurs while sending the *Packet*, then **EFI_DEVICE_ERROR** is returned.

If a timeout occurs during the execution of *Packet*, then **EFI_TIMEOUT** is returned.

If *Target* or *Lun* are not in a valid range for the SCSI channel, then **EFI_INVALID_PARAMETER** is returned. If *InDataBuffer*, *OutDataBuffer* or *SenseData* do not meet the alignment requirement specified by the *IoAlign* field of the **EFI_EXT_SCSI_PASS_THRU_MODE** structure, then **EFI_INVALID_PARAMETER** is returned. If any of the other fields of *Packet* are invalid, then **EFI_INVALID_PARAMETER** is returned.

If the data buffer described by *InDataBuffer* and *InTransferLength* is too big to be transferred in a single command, then no data is transferred and **EFI_BAD_BUFFER_SIZE** is returned. The number of bytes that can be transferred in a single command are returned in *InTransferLength*..

If the data buffer described by *OutDataBuffer* and *OutTransferLength* is too big to be transferred in a single command, then no data is transferred and **EFI_BAD_BUFFER_SIZE** is returned. The number of bytes that can be transferred in a single command are returned in *OutTransferLength*..

If the command described in *Packet* is not supported by the host adapter, then **EFI_UNSUPPORTED** is returned.

If **EFI_SUCCESS**, **EFI_BAD_BUFFER_SIZE**, **EFI_DEVICE_ERROR**, or **EFI_TIMEOUT** is returned, then the caller must examine the status fields in *Packet* in the following precedence order: *HostAdapterStatus* followed by *TargetStatus* followed by *SenseDataLength*, followed by *SenseData*.

If nonblocking I/O is being used, then the status fields in *Packet* will not be valid until the *Event* associated with *Packet* is signaled.

If **EFI_NOT_READY**, **EFI_INVALID_PARAMETER** or **EFI_UNSUPPORTED** is returned, then *Packet* was never sent, so the status fields in *Packet* are not valid. If nonblocking I/O is being used, the *Event* associated with *Packet* will not be signaled.

Note: Some examples of SCSI read commands are READ, INQUIRY, and MODE_SENSE.

Note: Some examples of SCSI write commands are WRITE and MODE_SELECT.

Note: An example of a SCSI non data command is TEST_UNIT_READY.

Status Codes Returned

EFI_SUCCESS	The SCSI Request Packet was sent by the host. For bi-directional commands, <i>InTransferLength</i> bytes were transferred from <i>InDataBuffer</i> . For write and bi-directional commands, <i>OutTransferLength</i> bytes were transferred by <i>OutDataBuffer</i> . See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , <i>SenseDataLength</i> , and <i>SenseData</i> in that order for additional status information.
EFI_BAD_BUFFER_SIZE	The SCSI Request Packet was not executed. The number of bytes that could be transferred is returned in <i>InTransferLength</i> . For write and bi-directional commands, <i>OutTransferLength</i> bytes were transferred by <i>OutDataBuffer</i> . See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , and in that order for additional status information.
EFI_NOT_READY	The SCSI Request Packet could not be sent because there are too many SCSI Request Packets already queued. The caller may retry again later.
EFI_DEVICE_ERROR	A device error occurred while attempting to send the SCSI Request Packet. See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , <i>SenseDataLength</i> , and <i>SenseData</i> in that order for additional status information.
EFI_INVALID_PARAMETER	<i>Target</i> , <i>Lun</i> , or the contents of <i>ScsiRequestPacket</i> are invalid. The SCSI Request Packet was not sent, so no additional status information is available.

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EFI_UNSUPPORTED	The command described by the SCSI Request Packet is not supported by the host adapter. This includes the case of Bi-directional SCSI commands not supported by the implementation. The SCSI Request Packet was not sent, so no additional status information is available.
EFI_TIMEOUT	A timeout occurred while waiting for the SCSI Request Packet to execute. See <i>HostAdapterStatus</i> , <i>TargetStatus</i> , <i>SenseDataLength</i> , and <i>SenseData</i> in that order for additional status information.

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTargetLun()

Summary

Used to retrieve the list of legal Target IDs and LUNs for SCSI devices on a SCSI channel. These can either be the list SCSI devices that are actually present on the SCSI channel, or the list of legal Target IDs and LUNs for the SCSI channel. Regardless, the caller of this function must probe the Target ID and LUN returned to see if a SCSI device is actually present at that location on the SCSI channel.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET_LUN) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL  *This,
    IN OUT UINT8                        **Target,
    IN OUT UINT64                       *Lun
);
```

Parameters

<i>This</i>	A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Section 14.7 .
<i>Target</i>	On input, a pointer to the Target ID (an array of size TARGET_MAX_BYTES) of a SCSI device present on the SCSI channel. On output, a pointer to the Target ID (an array of TARGET_MAX_BYTES) of the next SCSI device present on a SCSI channel. An input value of 0xFF 's (all bytes in the array are 0xFF) in the Target array retrieves the Target ID of the first SCSI device present on a SCSI channel.
<i>Lun</i>	On input, a pointer to the LUN of a SCSI device present on the SCSI channel. On output, a pointer to the LUN of the next SCSI device present on a SCSI channel.

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTargetLun()** function retrieves the Target ID and LUN of a SCSI device present on a SCSI channel. If on input a *Target* is specified by all **0xFF** in the Target array, then the Target ID and LUN of the first SCSI device is returned in *Target* and *Lun* and **EFI_SUCCESS** is returned.

If *Target* and *Lun* is a Target ID and LUN value that was returned on a previous call to **GetNextTargetLun()**, then the Target ID and LUN of the next SCSI device on the SCSI channel is returned in *Target* and *Lun*, and **EFI_SUCCESS** is returned.

If *Target array* is not all **0xFF**'s and *Target* and *Lun* were not returned on a previous call to **GetNextTargetLun()**, then **EFI_INVALID_PARAMETER** is returned.

If *Target* and *Lun* are the Target ID and LUN of the last SCSI device on the SCSI channel, then **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	The Target ID and LUN of the next SCSI device on the SCSI channel was returned in <i>Target</i> and <i>Lun</i> .
EFI_NOT_FOUND	There are no more SCSI devices on this SCSI channel.
EFI_INVALID_PARAMETER	<i>Target array</i> is not all 0xFF 's, and <i>Target</i> and <i>Lun</i> were not returned on a previous call to GetNextTargetLun() .

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.BuildDevicePath()

Summary

Used to allocate and build a device path node for a SCSI device on a SCSI channel.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_EXT_SCSI_PASS_THRU_BUILD_DEVICE_PATH) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL    *This,
    IN UINT8                               *Target,
    IN UINT64                              Lun
    IN OUT EFI_DEVICE_PATH_PROTOCOL      **DevicePath
);
```

Parameters

<i>This</i>	A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Section 14.7 .
<i>Target</i>	The Target is an array of size TARGET_MAX_BYTES and it specifies the Target ID of the SCSI device for which a device path node is to be allocated and built. Transport drivers may chose to utilize a subset of this size to suit the representation of targets. For example, a Fibre Channel driver may use only 8 bytes (WWN) in the array to represent a FC target.
<i>Lun</i>	The LUN of the SCSI device for which a device path node is to be allocated and built.
<i>DevicePath</i>	A pointer to a single device path node that describes the SCSI device specified by <i>Target</i> and <i>Lun</i> . This function is responsible for allocating the buffer <i>DevicePath</i> with the boot service AllocatePool() . It is the caller's responsibility to free <i>DevicePath</i> when the caller is finished with <i>DevicePath</i> .

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL.BuildDevicePath()** function allocates and builds a single device path node for the SCSI device specified by *Target* and *Lun*. If the SCSI device specified by *Target* and *Lun* are not present on the SCSI channel, then **EFI_NOT_FOUND** is returned. If *DevicePath* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If there are not enough resources to allocate the device path node, then **EFI_OUT_OF_RESOURCES** is returned. Otherwise, *DevicePath* is allocated with the boot service **AllocatePool()**, the contents of *DevicePath* are initialized to describe the SCSI device specified by *Target* and *Lun*, and **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The device path node that describes the SCSI device specified by <i>Target</i> and <i>Lun</i> was allocated and returned in <i>DevicePath</i> .
EFI_NOT_FOUND	The SCSI devices specified by <i>Target</i> and <i>Lun</i> does not exist on the SCSI channel.
EFI_INVALID_PARAMETER	<i>DevicePath</i> is NULL .
EFI_OUT_OF_RESOURCES	There are not enough resources to allocate DevicePath.

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetTargetLun()

Summary

Used to translate a device path node to a Target ID and LUN.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_GET_TARGET_LUN) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,
    IN EFI_DEVICE_PATH_PROTOCOL       *DevicePath
    OUT UINT8                          **Target,
    OUT UINT64                         *Lun
);
```

Parameters

<i>This</i>	A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Section 14.7 .
<i>DevicePath</i>	A pointer to the device path node that describes a SCSI device on the SCSI channel.
<i>Target</i>	A pointer to the Target Array which represents the ID of a SCSI device on the SCSI channel.
<i>Lun</i>	A pointer to the LUN of a SCSI device on the SCSI channel.

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetTargetLun()** function determines the Target ID and LUN associated with the SCSI device described by *DevicePath*. If *DevicePath* is a device path node type that the SCSI Pass Thru driver supports, then the SCSI Pass Thru driver will attempt to translate the contents *DevicePath* into a Target ID and LUN. If this translation is successful, then that Target ID and LUN are returned in *Target* and *Lun*, and **EFI_SUCCESS** is returned.

If *DevicePath*, *Target*, or *Lun* are **NULL**, then **EFI_INVALID_PARAMETER** is returned.

If *DevicePath* is not a device path node type that the SCSI Pass Thru driver supports, then **EFI_UNSUPPORTED** is returned.

If *DevicePath* is a device path node type that the SCSI Pass Thru driver supports, but there is not a valid translation from *DevicePath* to a Target ID and LUN, then **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	<i>DevicePath</i> was successfully translated to a Target ID and LUN, and they were returned in Target and Lun.
-------------	---

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EFI_INVALID_PARAMETER	<i>DevicePath</i> is NULL .
EFI_INVALID_PARAMETER	<i>Target</i> is NULL
EFI_INVALID_PARAMETER	<i>Lun</i> is NULL
EFI_UNSUPPORTED	This driver does not support the device path node type in <i>DevicePath</i> .
EFI_NOT_FOUND	A valid translation from <i>DevicePath</i> to a Target ID and LUN does not exist.

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetChannel()

Summary

Resets a SCSI channel. This operation resets all the SCSI devices connected to the SCSI channel.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_RESET_CHANNEL) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL      *This
);
```

Parameters

This

A pointer to the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** instance. Type **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** is defined in [Section 14.7](#).

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetChannel()** function resets a SCSI channel. This operation resets all the SCSI devices connected to the SCSI channel. If this SCSI channel does not support a reset operation, then **EFI_UNSUPPORTED** is returned.

If a device error occurs while executing that channel reset operation, then **EFI_DEVICE_ERROR** is returned.

If a timeout occurs during the execution of the channel reset operation, then **EFI_TIMEOUT** is returned. If the channel reset operation is completed, then **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The SCSI channel was reset.
EFI_UNSUPPORTED	The SCSI channel does not support a channel reset operation.
EFI_DEVICE_ERROR	A device error occurred while attempting to reset the SCSI channel.
EFI_TIMEOUT	A timeout occurred while attempting to reset the SCSI channel.

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetTargetLun()

Summary

Resets a SCSI logical unit that is connected to a SCSI channel.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_EXT_SCSI_PASS_THRU_RESET_TARGET_LUN) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL    *This,
    IN UINT8                               *Target,
    IN UINT64                              Lun
);
```

Parameters

<i>This</i>	A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Section 14.7 .
<i>Target</i>	The Target is an array of size TARGET_MAX_BYTE and it represents the target port ID of the SCSI device containing the SCSI logical unit to reset. Transport drivers may chose to utilize a subset of this array to suit the representation of their targets. For example a Fibre Channel driver may use only 8 bytes in the array (WWN) to represent a FC target.
<i>Lun</i>	The LUN of the SCSI device to reset.

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetTargetLun()** function resets the SCSI logical unit specified by *Target* and *Lun*. If this SCSI channel does not support a target reset operation, then **EFI_UNSUPPORTED** is returned.

If *Target* or *Lun* are not in a valid range for this SCSI channel, then **EFI_INVALID_PARAMETER** is returned.

If a device error occurs while executing that logical unit reset operation, then **EFI_DEVICE_ERROR** is returned.

If a timeout occurs during the execution of the logical unit reset operation, then **EFI_TIMEOUT** is returned.

If the logical unit reset operation is completed, then **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The SCSI device specified by <i>Target</i> and <i>Lun</i> was reset
EFI_UNSUPPORTED	The SCSI channel does not support a target reset operation.
EFI_INVALID_PARAMETER	<i>Target</i> or <i>Lun</i> are invalid.

EFI_DEVICE_ERROR	A device error occurred while attempting to reset the SCSI device specified by <i>Target</i> and <i>Lun</i> .
EFI_TIMEOUT	A timeout occurred while attempting to reset the SCSI device specified by <i>Target</i> and <i>Lun</i> .

EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTarget()

Summary

Used to retrieve the list of legal Target IDs for SCSI devices on a SCSI channel. These can either be the list SCSI devices that are actually present on the SCSI channel, or the list of legal Target IDs for the SCSI channel. Regardless, the caller of this function must probe the Target ID returned to see if a SCSI device is actually present at that location on the SCSI channel.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET) (
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,
    IN OUT UINT8                        **Target,
);
```

Parameters

This A pointer to the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** instance. Type **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** is defined in [Section 14.7](#).

Target On input, a pointer to the Target ID (an array of size **TARGET_MAX_BYTES**) of a SCSI device present on the SCSI channel. On output, a pointer to the Target ID (an array of **TARGET_MAX_BYTES**) of the next SCSI device present on a SCSI channel. An input value of **0xF**'s (all bytes in the array are **0xF**) in the Target array retrieves the Target ID of the first SCSI device present on a SCSI channel.

Description

The **EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTarget()** function retrieves the Target ID of a SCSI device present on a SCSI channel. If on input a *Target* is specified by all 0xF in the Target array, then the Target ID of the first SCSI device is returned in *Target* and **EFI_SUCCESS** is returned.

If *Target* is a Target ID value that was returned on a previous call to **GetNextTarget()**, then the Target ID of the next SCSI device on the SCSI channel is returned in *Target*, and **EFI_SUCCESS** is returned.

If *Target* array is not all **0xF**'s and *Target* were not returned on a previous call to **GetNextTarget()**, then **EFI_INVALID_PARAMETER** is returned.

If *Target* is the Target ID of the last SCSI device on the SCSI channel, then **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	The Target ID of the next SCSI device on the SCSI channel was returned in <i>Target</i> .
EFI_NOT_FOUND	There are no more SCSI devices on this SCSI channel.
EFI_INVALID_PARAMETER	<i>Target array</i> is not all 0xF's , and <i>Target</i> were not returned on a previous call to GetNextTarget () .

15

Protocols - iSCSI Boot

15.1 Overview

The iSCSI protocol defines a transport for SCSI data over TCP/IP. It also provides an interoperable solution that takes advantage of existing internet infrastructure, management facilities, and addresses distance limitations. The iSCSI protocol specification was developed by the Internet Engineering Task Force (IETF) and is SCSI Architecture Model-2 (SAM-2) compliant. iSCSI encapsulates block-oriented SCSI commands into iSCSI Protocol Data Units (PDU) that traverse the network over TCP/IP. iSCSI defines a Session, the initiator and target nexus (I-T nexus), which could be a bundle of one or more TCP connections.

Similar to other existing mass storage protocols like Fibre Channel and parallel SCSI, boot over iSCSI is an important functionality. This document will attempt to capture the various cases for iSCSI boot and common up with generic EFI protocol changes to address them.

15.1.1 iSCSI UEFI Driver Layering

Case 1: iSCSI UEFI Driver on a NIC: The driver will be layered on top of the networking layers. It will use the DHCP, IP, and TCP and packet level interface protocols of the EFI networking stack.

Case 2: iSCSI UEFI Driver on a TOE (or any other TCP offload card): The driver will be layered on top of the TOE TCP interfaces. It will use the DHCP, IP, TCP protocols of the TOE.

15.2 EFI iSCSI Initiator Name Protocol

This protocol sets and obtains the iSCSI Initiator Name. The iSCSI Initiator Name protocol builds a default iSCSI name. The iSCSI name configures using the programming interfaces defined below. Successive configuration of the iSCSI initiator name overwrites the previously existing name. Once overwritten, the previous name will not be retrievable. Setting an iSCSI name string that is zero length is illegal. The maximum size of the iSCSI Initiator Name is 224 bytes (including the NULL terminator).

EFI_ISCSI_INITIATOR_NAME_PROTOCOL

Summary

iSCSI Initiator Name Protocol for setting and obtaining the iSCSI Initiator Name.

GUID

```
#define EFI_ISCSI_INITIATOR_NAME_PROTOCOL_GUID \
    {0x59324945, 0xec44, 0x4c0d, 0xb1, 0xcd, 0x9d, 0xb1, 0x39, \
     0xdf, 0x7, 0xc}
```

Protocol Interface Structure

```
typedef struct _EFI_ISCSI_INITIATOR_NAME_PROTOCOL {  
    EFI_ISCSI_INITIATOR_NAME_GET  Get;  
    EFI_ISCSI_INITIATOR_NAME_SET  Set;  
} EFI_ISCSI_INITIATOR_NAME_PROTOCOL;
```

Parameters

<i>Get</i>	Used to retrieve the iSCSI Initiator Name.
<i>Set</i>	Used to set the iSCSI Initiator Name.

Description

The **EFI_ISCSI_INIT_NAME_PROTOCOL** provides the ability to get and set the iSCSI Initiator Name.

EFI_ISCSI_INITIATOR_NAME_PROTOCOL. Get()

Summary

Retrieves the current set value of iSCSI Initiator Name.

Prototype

```
typedef EFI_STATUS
(EFI_API *EFI_ISCSI_INITIATOR_NAME_GET) (
    IN      EFI_ISCSI_INITIATOR_NAME_PROTOCOL  *This
    IN OUT UINTN                               *BufferSize
    OUT     VOID                               *Buffer
)
```

Parameters

<i>This</i>	Pointer to the EFI_ISCSI_INITIATOR_NAME_PROTOCOL instance.
<i>BufferSize</i>	Size of the buffer in bytes pointed to by Buffer / Actual size of the variable data buffer.
<i>Buffer</i>	Pointer to the buffer for data to be read.

Description

This function will retrieve the iSCSI Initiator Name from Non-volatile memory.

Status Codes Returned

EFI_SUCCESS	Data was successfully retrieved into the provided buffer and the <i>BufferSize</i> was sufficient to handle the iSCSI initiator name
EFI_BUFFER_TOO_SMALL	<i>BufferSize</i> is too small for the result. <i>BufferSize</i> will be updated with the size required to complete the request. <i>Buffer</i> will not be affected.
EFI_INVALID_PARAMETER	<i>BufferSize</i> is NULL . <i>BufferSize</i> and <i>Buffer</i> will not be affected.
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL . <i>BufferSize</i> and <i>Buffer</i> will not be affected.
EFI_DEVICE_ERROR	The iSCSI initiator name could not be retrieved due to a hardware error.

EFI_ISCSI_INITIATOR_NAME_PROTOCOL.Set()

Summary

Sets the iSCSI Initiator Name.

Prototype

```
typedef EFI_STATUS
(EFI_API *EFI_ISCSI_INITIATOR_NAME_SET) {
    IN     EFI_ISCSI_INITIATOR_NAME_PROTOCOL *This
    IN OUT UINTN                               *BufferSize
    IN     VOID                               *Buffer
}
```

Parameters

<i>This</i>	Pointer to the EFI_ISCSI_INITIATOR_NAME_PROTOCOL instance
<i>BufferSize</i>	Size of the buffer in bytes pointed to by Buffer.
<i>Buffer</i>	Pointer to the buffer for data to be written.

Description

This function will set the iSCSI Initiator Name into Non-volatile memory.

Status Codes Returned

EFI_SUCCESS	Data was successfully stored by the protocol
EFI_UNSUPPORTED	Platform policies do not allow for data to be written
EFI_INVALID_PARAMETER	<i>BufferSize</i> exceeds the maximum allowed limit. <i>BufferSize</i> will be updated with the maximum size required to complete the request.
EFI_INVALID_PARAMETER	<i>BufferSize</i> is NULL . <i>BufferSize</i> and <i>Buffer</i> will not be affected
EFI_INVALID_PARAMETER	<i>Buffer</i> is NULL . <i>BufferSize</i> and <i>Buffer</i> will not be affected.
EFI_DEVICE_ERROR	The data could not be stored due to a hardware error.
EFI_OUT_OF_RESOURCES	Not enough storage is available to hold the data
EFI_PROTOCOL_ERROR	Input iSCSI initiator name does not adhere to RFC 3720 (and other related protocols)

16

Protocols — USB Support

16.1 USB2 Host Controller Protocol

[Section 16.1](#) and [Section 16.1.1](#) describe the USB2 Host Controller Protocol. This protocol provides an I/O abstraction for a USB2 Host Controller. The USB2 Host Controller is a hardware component that interfaces to a Universal Serial Bus (USB). It moves data between system memory and devices on the USB by processing data structures and generating transactions on the USB. This protocol is used by a USB Bus Driver to perform all data transaction over the Universal Serial Bus. It also provides services to manage the USB root hub that is integrated into the USB Host Controller. USB device drivers do not use this protocol directly. Instead, they use the I/O abstraction produced by the USB Bus Driver. This protocol should only be used by drivers that require direct access to the USB bus.

16.1.1 USB Host Controller Protocol Overview

The USB Host Controller Protocol is used by code, typically USB bus drivers, running in the EFI boot services environment, to perform data transactions over a USB bus. In addition, it provides an abstraction for the root hub of the USB bus.

The interfaces provided in the [EFI_USB2_HC_PROTOCOL](#) are used to manage data transactions on a USB bus. It also provides control methods for the USB root hub. The [EFI_USB2_HC_PROTOCOL](#) is designed to support both USB 1.1 and USB 2.0 – compliant host controllers.

The [EFI_USB2_HC_PROTOCOL](#) abstracts basic functionality that is designed to operate with the EHCI, UHCI and OHCI standards. By using this protocol, a single USB bus driver can be implemented without knowing if the underlying USB host controller conforms to the EHCI, OHCI or the UHCI standards.

Each instance of the [EFI_USB2_HC_PROTOCOL](#) corresponds to a USB host controller in a platform. The protocol is attached to the device handle of a USB host controller that is created by a device driver for the USB host controller's parent bus type. For example, a USB host controller that is implemented as a PCI device would require a PCI device driver to produce an instance of the [EFI_USB2_HC_PROTOCOL](#).

EFI_USB2_HC_PROTOCOL

Summary

Provides basic USB host controller management, basic data transactions over USB bus, and USB root hub access.

GUID

```
#define EFI_USB2_HC_PROTOCOL_GUID \
```

```
{0x3e745226, 0x9818, 0x45b6, 0xa2, 0xac, 0xd7, 0xcd, 0xe, 0x8b,
 0xa2, 0xbc}
```

Protocol Interface Structure

```
typedef struct _EFI_USB2_HC_PROTOCOL {
    EFI_USB2_HC_PROTOCOL_GET_CAPABILITY      GetCapability;
    EFI_USB2_HC_PROTOCOL_RESET              Reset;
    EFI_USB2_HC_PROTOCOL_GET_STATE          GetState;
    EFI_USB2_HC_PROTOCOL_SET_STATE          SetState;
    EFI_USB2_HC_PROTOCOL_CONTROL_TRANSFER   ControlTransfer;
    EFI_USB2_HC_PROTOCOL_BULK_TRANSFER      BulkTransfer;
    EFI_USB2_HC_PROTOCOL_ASYNC_INTERRUPT_TRANSFER AsyncInterruptTransfer;
    EFI_USB2_HC_PROTOCOL_SYNC_INTERRUPT_TRANSFER SyncInterruptTransfer;
    EFI_USB2_HC_PROTOCOL_ISOCHRONOUS_TRANSFER IsochronousTransfer;
    EFI_USB2_HC_PROTOCOL_ASYNC_ISOCHRONOUS_TRANSFER AsyncIsochronousTransfer;
    EFI_USB2_HC_PROTOCOL_GET_ROOTHUB_PORT_STATUS GetRootHubPortStatus;
    EFI_USB2_HC_PROTOCOL_SET_ROOTHUB_PORT_FEATURE SetRootHubPortFeature;
    EFI_USB2_HC_PROTOCOL_CLEAR_ROOTHUB_PORT_FEATURE ClearRootHubPortFeature;

    UINT16      MajorRevision;
    UINT16      MinorRevision;
} EFI_USB2_HC_PROTOCOL;
```

Parameters

<i>GetCapability</i>	Retrieves the capabilities of the USB host controller. See the GetCapability() function description.
<i>Reset</i>	Software reset of USB. See the Reset() function description.
<i>GetState</i>	Retrieves the current state of the USB host controller. See the GetState() function description.
<i>SetState</i>	Sets the USB host controller to a specific state. See the SetState() function description.
<i>ControlTransfer</i>	Submits a control transfer to a target USB device. See the ControlTransfer() function description.
<i>BulkTransfer</i>	Submits a bulk transfer to a bulk endpoint of a USB device. See the BulkTransfer() function description.
<i>AsyncInterruptTransfer</i>	Submits an asynchronous interrupt transfer to an interrupt endpoint of a USB device. See the AsyncInterruptTransfer() function description.

- SyncInterruptTransfer* Submits a synchronous interrupt transfer to an interrupt endpoint of a USB device. See the [SyncInterruptTransfer \(\)](#) function description.
- IsochronousTransfer* Submits isochronous transfer to an isochronous endpoint of a USB device. See the [IsochronousTransfer \(\)](#) function description.
- AsyncIsochronousTransfer* Submits nonblocking USB isochronous transfer. See the [AsyncIsochronousTransfer \(\)](#) function description.
- GetRootHubPortStatus* Retrieves the status of the specified root hub port. See the [GetRootHubPortStatus \(\)](#) function description.
- SetRootHubPortFeature* Sets the feature for the specified root hub port. See the [SetRootHubPortFeature \(\)](#) function description.
- ClearRootHubPortFeature* Clears the feature for the specified root hub port. See the [ClearRootHubPortFeature \(\)](#) function description.
- MajorRevision* The major revision number of the USB host controller. The revision information indicates the release of the Universal Serial Bus Specification with which the host controller is compliant.
- MinorRevision* The minor revision number of the USB host controller. The revision information indicates the release of the Universal Serial Bus Specification with which the host controller is compliant.

Description

The **EFI_USB2_HC_PROTOCOL** provides USB host controller management, basic data transactions over a USB bus, and USB root hub access. A device driver that wishes to manage a USB bus in a system retrieves the **EFI_USB2_HC_PROTOCOL** instance that is associated with the USB bus to be managed. A device handle for a USB host controller will minimally contain an [EFI_DEVICE_PATH_PROTOCOL](#) instance, and an **EFI_USB2_HC_PROTOCOL** instance.

EFI_USB2_HC_PROTOCOL.GetCapability()

Summary

Retrieves the Host Controller capabilities.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_GET_CAPABILITY) (
    IN  EFI_USB2_HC_PROTOCOL  *This,
    OUT UINT8                 *MaxSpeed,
    OUT UINT8                 *PortNumber,
    OUT UINT8                 *Is64BitCapable
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>MaxSpeed</i>	Host controller data transfer speed; see “Related Definitions” below for a list of supported transfer speed values.
<i>PortNumber</i>	Number of the root hub ports.
<i>Is64BitCapable</i>	TRUE if controller supports 64-bit memory addressing, FALSE otherwise.

Related Definitions

```
#define EFI_USB_SPEED_FULL  0x0000
#define EFI_USB_SPEED_LOW   0x0001
#define EFI_USB_SPEED_HIGH  0x0002
```

EFI_USB_SPEED_LOW	Low speed USB device; data bandwidth is up to 1 Mb/s. Supported by USB 1.1 OHCI and UHCI host controllers.
EFI_USB_SPEED_FULL	Full speed USB device; data bandwidth is up to 12 Mb/s. Supported by USB 1.1 OHCI and UHCI host controllers.
EFI_USB_SPEED_HIGH	High speed USB device; data bandwidth is up to 480 Mb/s. Supported by USB 2.0 EHCI host controllers.

Description

This function is used to retrieve the host controller capabilities. *MaxSpeed* indicates the maximum data transfer speed the controller is capable of; this information is needed for the subsequent transfers. *PortNumber* is the number of root hub ports, it is required by the USB bus driver to perform bus enumeration. *Is64BitCapable* indicates that controller is capable of 64-bit memory access so that the host controller software can use memory blocks above 4 GB for the data transfers.

Status Codes Returned

EFI_SUCCESS	The host controller capabilities were retrieved successfully.
EFI_INVALID_PARAMETER	MaxSpeed or PortNumber or Is64BitCapable is NULL .
EFI_DEVICE_ERROR	An error was encountered while attempting to retrieve the capabilities.

EFI_USB2_HC_PROTOCOL.Reset()

Summary

Provides software reset for the USB host controller.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_RESET) (
    IN  EFI_USB2_HC_PROTOCOL  *This,
    IN  UINT16                 Attributes
);

```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>Attributes</i>	A bit mask of the reset operation to perform. See “Related Definitions” below for a list of the supported bit mask values.

Related Definitions

```

#define EFI_USB_HC_RESET_GLOBAL           0x0001
#define EFI_USB_HC_RESET_HOST_CONTROLLER 0x0002
#define EFI_USB_HC_RESET_GLOBAL_WITH_DEBUG 0x0004
#define EFI_USB_HC_RESET_HOST_WITH_DEBUG 0x0008

```

EFI_USB_HC_RESET_GLOBAL

If this bit is set, a global reset signal will be sent to the USB bus. This resets all of the USB bus logic, including the USB host controller hardware and all the devices attached on the USB bus.

EFI_USB_HC_RESET_HOST_CONTROLLER

If this bit is set, the USB host controller hardware will be reset. No reset signal will be sent to the USB bus.

EFI_USB_HC_RESET_GLOBAL_WITH_DEBUG

If this bit is set, then a global reset signal will be sent to the USB bus. This resets all of the USB bus logic, including the USB host controller and all of the devices attached on the USB bus. If this is an EHCI controller and the debug port has been configured, then this will still reset the host controller.

EFI_USB_HC_RESET_HOST_WITH_DEBUG

If this bit is set, the USB host controller hardware will be reset. If this is an EHCI controller and the debug port has been configured, then this will still reset the host controller.

Description

This function provides a software mechanism to reset a USB host controller. The type of reset is specified by the *Attributes* parameter. If the type of reset specified by *Attributes* is not valid, then **EFI_INVALID_PARAMETER** is returned. If the reset operation is completed, then **EFI_SUCCESS** is returned. If the type of reset specified by *Attributes* is not currently supported by the host controller hardware, **EFI_UNSUPPORTED** is returned. If a device error occurs during the reset operation, then **EFI_DEVICE_ERROR** is returned.

Note: For EHCI controllers, the **EFI_USB_HC_RESET_GLOBAL** and **EFI_USB_HC_RESET_HOST_CONTROLLER** types of reset do not actually reset the bus if the debug port has been configured. In these cases, the function will return **EFI_ACCESS_DENIED**.

Status Codes Returned

EFI_SUCCESS	The reset operation succeeded.
EFI_INVALID_PARAMETER	<i>Attributes</i> is not valid.
EFI_UNSUPPORTED	The type of reset specified by <i>Attributes</i> is not currently supported by the host controller hardware.
EFI_ACCESS_DENIED	Reset operation is rejected due to the debug port being configured and active; only EFI_USB_HC_RESET_GLOBAL_WITH_DEBUG or EFI_USB_HC_RESET_HOST_WITH_DEBUG reset <i>Attributes</i> can be used to perform reset operation for this host controller.
EFI_DEVICE_ERROR	An error was encountered while attempting to perform the reset operation.

EFI_USB2_HC_PROTOCOL.GetState()

Summary

Retrieves current state of the USB host controller.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_GET_STATE) (
    IN  EFI_USB2_HC_PROTOCOL  *This,
    OUT EFI_USB_HC_STATE      *State
);

```

Parameters

This

A pointer to the [EFI_USB2_HC_PROTOCOL](#) instance. Type [EFI_USB2_HC_PROTOCOL](#) is defined in [Section 16.1](#).

State

A pointer to the [EFI_USB_HC_STATE](#) data structure that indicates current state of the USB host controller. Type [EFI_USB_HC_STATE](#) is defined in “Related Definitions.”

Related Definitions

```

typedef enum {
    EfiUsbHcStateHalt,
    EfiUsbHcStateOperational,
    EfiUsbHcStateSuspend,
    EfiUsbHcStateMaximum
} EFI_USB_HC_STATE;
EfiUsbHcStateHalt

```

The host controller is in halt state. No USB transactions can occur while in this state. The host controller can enter this state for three reasons:

- After host controller hardware reset.
- Explicitly set by software.
- Triggered by a fatal error such as consistency check failure.

EfiUsbHcStateOperational

The host controller is in an operational state. When in this state, the host controller can execute bus traffic. This state must be explicitly set to enable the USB bus traffic.

EfiUsbHcStateSuspend

The host controller is in the suspend state. No USB transactions can occur while in this state. The host controller enters this state for the following reasons:

- Explicitly set by software.
- Triggered when there is no bus traffic for 3 microseconds.

Description

This function is used to retrieve the USB host controller’s current state. The USB Host Controller Protocol publishes three states for USB host controller, as defined in “Related Definitions” below. If *State* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If a device error occurs while attempting to retrieve the USB host controllers current state, then **EFI_DEVICE_ERROR** is returned. Otherwise, the USB host controller’s current state is returned in *State*, and **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The state information of the host controller was returned in <i>State</i> .
EFI_INVALID_PARAMETER	State is NULL .
EFI_DEVICE_ERROR	An error was encountered while attempting to retrieve the host controller’s current state.

EFI_USB2_HC_PROTOCOL.SetState()

Summary

Sets the USB host controller to a specific state.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_SET_STATE) (
    IN EFI_USB2_HC_PROTOCOL    *This,
    IN EFI_USB_HC_STATE        State
);
```

Parameters

This

A pointer to the [EFI_USB2_HC_PROTOCOL](#) instance. Type [EFI_USB2_HC_PROTOCOL](#) is defined in [Section 16.1](#).

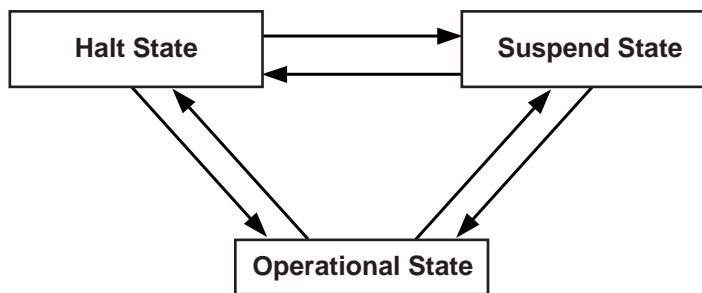
State

Indicates the state of the host controller that will be set. See the definition and description of the type [EFI_USB_HC_STATE](#) in the [GetState\(\)](#) function description.

Description

This function is used to explicitly set a USB host controller's state. There are three states defined for the USB host controller. These are the halt state, the operational state and the suspend state.

[Figure 46](#) illustrates the possible state transitions:



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Figure 46. Software Triggered State Transitions of a USB Host Controller

If the state specified by *State* is not valid, then **EFI_INVALID_PARAMETER** is returned. If a device error occurs while attempting to place the USB host controller into the state specified by *State*, then **EFI_DEVICE_ERROR** is returned. If the USB host controller is successfully placed in the state specified by *State*, then **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The USB host controller was successfully placed in the state specified by <i>State</i> .
EFI_INVALID_PARAMETER	<i>State</i> is invalid.
EFI_DEVICE_ERROR	Failed to set the state specified by <i>State</i> due to device error.

EFI_USB2_HC_PROTOCOL.ControlTransfer()

Summary

Submits control transfer to a target USB device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_CONTROL_TRANSFER) (
    IN      EFI_USB2_HC_PROTOCOL      *This,
    IN      UINT8                     DeviceAddress,
    IN      UINT8                     DeviceSpeed,
    IN      UINTN                     MaximumPacketLength,
    IN      EFI_USB_DEVICE_REQUEST    *Request,
    IN      EFI_USB_DATA_DIRECTION    TransferDirection,
    IN OUT VOID                       *Data      OPTIONAL,
    IN OUT UINTN                      *DataLength OPTIONAL,
    IN      UINTN                     TimeOut,
    IN      EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,
    OUT     UINT32                    *TransferResult
);
```

Related Definitions

```
typedef struct {
    UINT8    TranslatorHubAddress,
    UINT8    TranslatorPortNumber
} EFI_USB2_HC_TRANSACTION_TRANSLATOR;
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>DeviceAddress</i>	Represents the address of the target device on the USB, which is assigned during USB enumeration.
<i>DeviceSpeed</i>	Indicates device speed. See “Related Definitions” in GetCapability() for a list of the supported values.
<i>MaximumPacketLength</i>	Indicates the maximum packet size that the default control transfer endpoint is capable of sending or receiving.
<i>Request</i>	A pointer to the USB device request that will be sent to the USB device. Refer to Section 2.5.1 14.2 of EFI 1.1 USB Driver Model , version 0.7.
<i>TransferDirection</i>	Specifies the data direction for the transfer. There are three values available, EfiUsbDataIn , EfiUsbDataOut and

	EfiUsbNoData. Refer to Section 2.5.1 of <i>EFI 1.1 USB Driver Model, version 0.7 14.2</i> .
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	On input, indicates the size, in bytes, of the data buffer specified by <i>Data</i> . On output, indicates the amount of data actually transferred.
<i>Translator</i>	A pointer to the transaction translator data. See “Description” for the detailed information of this data structure.
<i>TimeOut</i>	Indicates the maximum time, in milliseconds, which the transfer is allowed to complete.
<i>TransferResult</i>	A pointer to the detailed result information generated by this control transfer. Refer to Section 2.5.1 of <i>EFI 1.1 USB Driver Model, version 0.7 14.2</i> .

Description

This function is used to submit a control transfer to a target USB device specified by *DeviceAddress*. Control transfers are intended to support configuration/command/status type communication flows between host and USB device.

There are three control transfer types according to the data phase. If the *TransferDirection* parameter is **EfiUsbNoData**, *Data* is **NULL**, and *DataLength* is 0, then no data phase is present in the control transfer. If the *TransferDirection* parameter is **EfiUsbDataOut**, then *Data* specifies the data to be transmitted to the device, and *DataLength* specifies the number of bytes to transfer to the device. In this case, there is an OUT DATA stage followed by a SETUP stage. If the *TransferDirection* parameter is **EfiUsbDataIn**, then *Data* specifies the data to be received from the device, and *DataLength* specifies the number of bytes to receive from the device. In this case there is an IN DATA stage followed by a SETUP stage.

Translator is necessary to perform split transactions on low-speed or full-speed devices connected to a high-speed hub. Such transaction require the device connection information: device address and the port number of the hub that device is connected to. This information is passed through the fields of **EFI_USB2_HC_TRANSACTION_TRANSLATOR** structure. See “Related Definitions” for the structure field names. Translator is passed as **NULL** for the USB1.1 host controllers transfers or when the transfer is requested for high-speed device connected to USB2.0 controller.

If the control transfer has completed successfully, then **EFI_SUCCESS** is returned. If the transfer cannot be completed within the timeout specified by *TimeOut*, then **EFI_TIMEOUT** is returned. If an error other than timeout occurs during the USB transfer, then **EFI_DEVICE_ERROR** is returned and the detailed error code will be returned in the *TransferResult* parameter.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- *TransferDirection* is invalid.
- *TransferDirection*, *Data*, and *DataLength* do not match one of the three control transfer types described above.
- *Request* pointer is **NULL**.

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- *MaximumPacketLength* is not valid. If *DeviceSpeed* is **EFI_USB_SPEED_LOW**, then *MaximumPacketLength* must be 8. If *IsSlowDevice* is **FALSE** **EFI_USB_SPEED_FULL** or **EFI_USB_SPEED_HIGH**, then *MaximumPacketLength* must be 8, 16, 32, or 64.
- *TransferResult* pointer is **NULL**.
- *Translator* is **NULL** while the requested transfer requires split transaction. The conditions of the split transactions are described above in “Description” section.

Status Codes Returned

EFI_SUCCESS	The control transfer was completed successfully.
EFI_OUT_OF_RESOURCES	The control transfer could not be completed due to a lack of resources.
EFI_INVALID_PARAMETER	Some parameters are invalid. The possible invalid parameters are described in “Description” above.
EFI_TIMEOUT	The control transfer failed due to timeout.
EFI_DEVICE_ERROR	The control transfer failed due to host controller or device error. Caller should check <i>TransferResult</i> for detailed error information.

EFI_USB2_HC_PROTOCOL.BulkTransfer()

Summary

Submits bulk transfer to a bulk endpoint of a USB device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_BULK_TRANSFER) (
    IN      EFI_USB2_HC_PROTOCOL  *This,
    IN      UINT8                 DeviceAddress,
    IN      UINT8                 EndPointAddress,
    IN      UINT8                 DeviceSpeed,
    IN      UINTN                 MaximumPacketLength,
    IN      UINT8                 DataBuffersNumber,
    IN OUT VOID                   *Data[EFI_USB_MAX_BULK_BUFFER_NUM],
    IN OUT UINTN                  *DataLength,
    IN OUT UINT8                  *DataToggle,
    IN      UINTN                 TimeOut,
    IN      EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,
    OUT     UINT32                 *TransferResult
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>DeviceAddress</i>	Represents the address of the target device on the USB, which is assigned during USB enumeration.
<i>EndPointAddress</i>	The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is 0). It is the caller's responsibility to make sure that the <i>EndPointAddress</i> represents a bulk endpoint.
<i>DeviceSpeed</i>	Indicates device speed. The supported values are EFI_USB_SPEED_FULL and EFI_USB_SPEED_HIGH .
<i>MaximumPacketLength</i>	Indicates the maximum packet size the target endpoint is capable of sending or receiving.
<i>DataBuffersNumber</i>	Number of data buffers prepared for the transfer.
<i>Data</i>	Array of pointers to the buffers of data that will be transmitted to USB device or received from USB device.

<i>DataLength</i>	When input, indicates the size, in bytes, of the data buffers specified by <i>Data</i> . When output, indicates the actually transferred data size.
<i>DataToggle</i>	A pointer to the data toggle value. On input, it indicates the initial data toggle value the bulk transfer should adopt; on output, it is updated to indicate the data toggle value of the subsequent bulk transfer.
<i>Translator</i>	A pointer to the transaction translator data. See <code>ControlTransfer()</code> “Description” for the detailed information of this data structure.
<i>TimeOut</i>	Indicates the maximum time, in milliseconds, which the transfer is allowed to complete.
<i>TransferResult</i>	A pointer to the detailed result information of the bulk transfer. Refer to Section 2.5.1 of EFI1.1 USB Driver Model, version 0.7 14.2.

Description

This function is used to submit bulk transfer to a target endpoint of a USB device. The target endpoint is specified by *DeviceAddress* and *EndpointAddress*. Bulk transfers are designed to support devices that need to communicate relatively large amounts of data at highly variable times where the transfer can use any available bandwidth. Bulk transfers can be used only by full-speed and high-speed devices.

High-speed bulk transfers can be performed using multiple data buffers. The number of buffers that are actually prepared for the transfer is specified by *DataBuffersNumber*. For full-speed bulk transfers this value is ignored.

Data represents a list of pointers to the data buffers. For full-speed bulk transfers only the data pointed by *Data[0]* shall be used. For high-speed transfers depending on *DataLength* there several data buffers can be used. The total number of buffers must not exceed

EFI_USB_MAX_BULK_BUFFER_NUM. See “Related Definitions” for the **EFI_USB_MAX_BULK_BUFFER_NUM** value.

The data transfer direction is determined by the endpoint direction that is encoded in the *EndPointAddress* parameter. Refer to *USB Specification, Revision 2.0* on the Endpoint Address encoding.

The *DataToggle* parameter is used to track target endpoint’s data sequence toggle bits. The USB provides a mechanism to guarantee data packet synchronization between data transmitter and receiver across multiple transactions. The data packet synchronization is achieved with the data sequence toggle bits and the DATA0/DATA1 PIDs. A bulk endpoint’s toggle sequence is initialized to DATA0 when the endpoint experiences a configuration event. It toggles between DATA0 and DATA1 in each successive data transfer. It is host’s responsibility to track the bulk endpoint’s data toggle sequence and set the correct value for each data packet. The input *DataToggle* value points to the data toggle value for the first data packet of this bulk transfer; the output *DataToggle* value points to the data toggle value for the last successfully transferred data packet of this bulk transfer. The caller should record the data toggle value for use in subsequent bulk transfers to the same endpoint.

If the bulk transfer is successful, then **EFI_SUCCESS** is returned. If USB transfer cannot be completed within the timeout specified by *Timeout*, then **EFI_TIMEOUT** is returned. If an error

other than timeout occurs during the USB transfer, then **EFI_DEVICE_ERROR** is returned and the detailed status code is returned in *TransferResult*.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- *Data* is **NULL**.
- *DataLength* is 0.
- *DeviceSpeed* is not valid; the legal values are **EFI_USB_SPEED_FULL** or **EFI_USB_SPEED_HIGH**.
- *MaximumPacketLength* is not valid. The legal value of this parameter is 64 or less for full-speed and 512 or less for high-speed transaction.
- *DataToggle* points to a value other than 0 and 1.
- *TransferResult* is **NULL**.

Status Codes Returned

EFI_SUCCESS	The bulk transfer was completed successfully.
EFI_OUT_OF_RESOURCES	The bulk transfer could not be submitted due to lack of resource.
EFI_INVALID_PARAMETER	Some parameters are invalid. The possible invalid parameters are described in “Description” above.
EFI_TIMEOUT	The bulk transfer failed due to timeout.
EFI_DEVICE_ERROR	The bulk transfer failed due to host controller or device error. Caller should check <i>TransferResult</i> for detailed error information.

EFI_USB2_HC_PROTOCOL.AsyncInterruptTransfer()

Summary

Submits an asynchronous interrupt transfer to an interrupt endpoint of a USB device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_ASYNC_INTERRUPT_TRANSFER) (
    IN  EFI_USB2_HC_PROTOCOL      *This,
    IN  UINT8                     DeviceAddress,
    IN  UINT8                     EndPointAddress,
    IN  UINT8                     DeviceSpeed,
    IN  UINTN                     MaximumPacketLength,
    IN  BOOLEAN                   IsNewTransfer,
    IN OUT UINT8                  *DataToggle,
    IN  UINTN                     PollingInterval OPTIONAL,
    IN  UINTN                     DataLength      OPTIONAL,
    IN  EFI_ASYNC_USB_TRANSFER_CALLBACK CallBackFunction OPTIONAL,
    IN  VOID                      *Context        OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>DeviceAddress</i>	Represents the address of the target device on the USB, which is assigned during USB enumeration.
<i>EndPointAddress</i>	The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is zero). It is the caller's responsibility to make sure that the <i>EndPointAddress</i> represents an interrupt endpoint.
<i>DeviceSpeed</i>	Indicates device speed. See "Related Definitions" in EFI_USB2_HC_PROTOCOL.ControlTransfer() for a list of the supported values.
<i>MaximumPacketLength</i>	Indicates the maximum packet size the target endpoint is capable of sending or receiving.
<i>IsNewTransfer</i>	If TRUE , an asynchronous interrupt pipe is built between the host and the target interrupt endpoint. If FALSE , the specified asynchronous interrupt pipe is canceled. If TRUE , and an interrupt transfer exists for the target end point, then EFI_INVALID_PARAMETER is returned.

<i>DataToggle</i>	A pointer to the data toggle value. On input, it is valid when <i>IsNewTransfer</i> is TRUE , and it indicates the initial data toggle value the asynchronous interrupt transfer should adopt. On output, it is valid when <i>IsNewTransfer</i> is FALSE , and it is updated to indicate the data toggle value of the subsequent asynchronous interrupt transfer.
<i>PollingInterval</i>	Indicates the interval, in milliseconds, that the asynchronous interrupt transfer is polled. This parameter is required when <i>IsNewTransfer</i> is TRUE .
<i>DataLength</i>	Indicates the length of data to be received at the rate specified by <i>PollingInterval</i> from the target asynchronous interrupt endpoint. This parameter is only required when <i>IsNewTransfer</i> is TRUE .
<i>CallbackFunction</i>	The Callback function. This function is called at the rate specified by <i>PollingInterval</i> . This parameter is only required when <i>IsNewTransfer</i> is TRUE . Refer to Section 2.5.3 of EFI 1.1 USB Driver Model, version 0.7,14.2 for the definition of this type.
<i>Context</i>	The context that is passed to the <i>CallbackFunction</i> . This is an optional parameter and may be NULL .

Description

This function is used to submit asynchronous interrupt transfer to a target endpoint of a USB device. The target endpoint is specified by *DeviceAddress* and *EndpointAddress*. In the USB Specification, Revision 2.0, interrupt transfer is one of the four USB transfer types. In the [EFI USB2 HC PROTOCOL](#), interrupt transfer is divided further into synchronous interrupt transfer and asynchronous interrupt transfer.

An asynchronous interrupt transfer is typically used to query a device’s status at a fixed rate. For example, keyboard, mouse, and hub devices use this type of transfer to query their interrupt endpoints at a fixed rate. The asynchronous interrupt transfer is intended to support the interrupt transfer type of “submit once, execute periodically.” Unless an explicit request is made, the asynchronous transfer will never retire.

If *IsNewTransfer* is **TRUE**, then an interrupt transfer is started at a fixed rate. The rate is specified by *PollingInterval*, the size of the receive buffer is specified by *DataLength*, and the callback function is specified by *CallbackFunction*. *Context* specifies an optional context that is passed to the *CallbackFunction* each time it is called. The *CallbackFunction* is intended to provide a means for the host to periodically process interrupt transfer data.

If *IsNewTransfer* is **TRUE**, and an interrupt transfer exists for the target end point, then **EFI_INVALID_PARAMETER** is returned.

If *IsNewTransfer* is **FALSE**, then the interrupt transfer is canceled.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- Data transfer direction indicated by *EndPointAddress* is other than **EfiUsbDataIn**.
- *IsNewTransfer* is **TRUE** and *DataLength* is 0.

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- *IsNewTransfer* is **TRUE** and *DataToggle* points to a value other than 0 and 1.
- *IsNewTransfer* is **TRUE** and *PollingInterval* is not in the range 1..255.
- *IsNewTransfer* requested where an interrupt transfer exists for the target end point.

Status Codes Returned

EFI_SUCCESS	The asynchronous interrupt transfer request has been successfully submitted or canceled.
EFI_INVALID_PARAMETER	Some parameters are invalid. The possible invalid parameters are described in “Description” above. When an interrupt transfer exists for the target end point and a new transfer is requested, EFI_INVALID_PARAMETER is returned.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.

EFI_USB2_HC_PROTOCOL.SyncInterruptTransfer()

Summary

Submits synchronous interrupt transfer to an interrupt endpoint of a USB device.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_USB2_HC_PROTOCOL_SYNC_INTERRUPT_TRANSFER) (
    IN      EFI_USB2_HC_PROTOCOL  *This,
    IN      UINT8                 DeviceAddress,
    IN      UINT8                 EndPointAddress,
    IN      UINT8                 DeviceSpeed,
    IN      UINTN                 MaximumPacketLength,
    IN OUT VOID                   *Data,
    IN OUT UINTN                 *DataLength,
    IN OUT UINT8                 *DataToggle,
    IN      UINTN                 TimeOut,
    OUT     UINT32                *TransferResult
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>DeviceAddress</i>	Represents the address of the target device on the USB, which is assigned during USB enumeration.
<i>EndPointAddress</i>	The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is zero). It is the caller's responsibility to make sure that the <i>EndPointAddress</i> represents an interrupt endpoint.
<i>DeviceSpeed</i>	Indicates device speed. See "Related Definitions" in ControlTransfer() for a list of the supported values.
<i>MaximumPacketLength</i>	Indicates the maximum packet size the target endpoint is capable of sending or receiving.
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	On input, the size, in bytes, of the data buffer specified by <i>Data</i> . On output, the number of bytes transferred.
<i>DataToggle</i>	A pointer to the data toggle value. On input, it indicates the initial data toggle value the synchronous interrupt transfer should adopt; on output, it is updated to indicate the data toggle value of the subsequent synchronous interrupt transfer.

- TimeOut* Indicates the maximum time, in milliseconds, which the transfer is allowed to complete.
- TransferResult* A pointer to the detailed result information from the synchronous interrupt transfer. Refer to Section 2.5.1 of EFI1.1 USB Driver Model, version 0.714.2.

Description

This function is used to submit a synchronous interrupt transfer to a target endpoint of a USB device. The target endpoint is specified by *DeviceAddress* and *EndpointAddress*. In the USB Specification, Revision2.0, interrupt transfer is one of the four USB transfer types. In the [EFI USB2 HC PROTOCOL](#), interrupt transfer is divided further into synchronous interrupt transfer and asynchronous interrupt transfer.

The synchronous interrupt transfer is designed to retrieve small amounts of data from a USB device through an interrupt endpoint. A synchronous interrupt transfer is only executed once for each request. This is the most significant difference from the asynchronous interrupt transfer.

If the synchronous interrupt transfer is successful, then **EFI_SUCCESS** is returned. If the USB transfer cannot be completed within the timeout specified by *Timeout*, then **EFI_TIMEOUT** is returned. If an error other than timeout occurs during the USB transfer, then **EFI_DEVICE_ERROR** is returned and the detailed status code is returned in *TransferResult*.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- Data transfer direction indicated by *EndPointAddress* is not **EfiUsbDataIn**.
- *Data* is **NULL**.
- *DataLength* is 0.
- *MaximumPacketLength* is not valid. The legal value of this parameter should be 3072 or less for high-speed device, 64 or less for a full-speed device; for a slow device, it is limited to 8 or less. For the full-speed device, it should be 8, 16, 32, or 64; for the slow device, it is limited to 8.
- *DataToggle* points to a value other than 0 and 1.
- *TransferResult* is **NULL**.

Status Codes Returned

EFI_SUCCESS	The synchronous interrupt transfer was completed successfully.
EFI_OUT_OF_RESOURCES	The synchronous interrupt transfer could not be submitted due to lack of resource.
EFI_INVALID_PARAMETER	Some parameters are invalid. The possible invalid parameters are described in “Description” above.
EFI_TIMEOUT	The synchronous interrupt transfer failed due to timeout.
EFI_DEVICE_ERROR	The synchronous interrupt transfer failed due to host controller or device error. Caller should check <i>TransferResult</i> for detailed error information.

EFI_USB2_HC_PROTOCOL.IsochronousTransfer()

Summary

Submits isochronous transfer to an isochronous endpoint of a USB device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_ISOCHRONOUS_TRANSFER) (
    IN      EFI_USB2_HC_PROTOCOL  *This,
    IN      UINT8                 DeviceAddress,
    IN      UINT8                 EndPointAddress,
    IN      UINT8                 DeviceSpeed,
    IN      UINTN                 MaximumPacketLength,
    IN      UINT8                 DataBuffersNumber,
    IN OUT VOID                   *Data[EFI_USB_MAX_ISO_BUFFER_NUM],
    IN      UINTN                 DataLength,
    IN      EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,
    OUT     UINT32                 *TransferResult
);
```

Related Definitions

```
#define EFI_USB_MAX_ISO_BUFFER_NUM7
#define EFI_USB_MAX_ISO_BUFFER_NUM12
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>DeviceAddress</i>	Represents the address of the target device on the USB, which is assigned during USB enumeration.
<i>EndPointAddress</i>	The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is 0). It is the caller's responsibility to make sure that the <i>EndPointAddress</i> represents an isochronous endpoint.
<i>DeviceSpeed</i>	Indicates device speed. The supported values are EFI_USB_SPEED_FULL and EFI_USB_SPEED_HIGH .
<i>MaximumPacketLength</i>	Indicates the maximum packet size the target endpoint is capable of sending or receiving. For isochronous endpoints, this value is used to reserve the bus time in the schedule, required for the per-frame data payloads. The pipe may, on an ongoing basis, actually use less bandwidth than that reserved.
<i>DataBuffersNumber</i>	Number of data buffers prepared for the transfer.

<i>Data</i>	Array of pointers to the buffers of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	Specifies the length, in bytes, of the data to be sent to or received from the USB device.
<i>Translator</i>	A pointer to the transaction translator data. See ControlTransfer() “Description” for the detailed information of this data structure.
<i>TransferResult</i>	A pointer to the detail result information of the isochronous transfer. Refer to Section 2.5.1 of EFI1.1 USB Driver Model, version 0.7.

Description

This function is used to submit isochronous transfer to a target endpoint of a USB device. The target endpoint is specified by *DeviceAddress* and *EndpointAddress*. Isochronous transfers are used when working with isochronous data. It provides periodic, continuous communication between the host and a device. Isochronous transfers can be used only by full-speed and high-speed devices.

High-speed isochronous transfers can be performed using multiple data buffers. The number of buffers that are actually prepared for the transfer is specified by *DataBuffersNumber*. For full-speed isochronous transfers this value is ignored.

Data represents a list of pointers to the data buffers. For full-speed isochronous transfers only the data pointed by *Data[0]* shall be used. For high-speed isochronous transfers and for the split transactions depending on *DataLength* there several data buffers can be used. For the high-speed isochronous transfers the total number of buffers must not exceed

EFI_USB_MAX_ISO_BUFFER_NUM. For split transactions performed on full-speed device by high-speed host controller the total number of buffers is limited to

EFI_USB_MAX_ISO_BUFFER_NUM1 See “Related Definitions” for the

EFI_USB_MAX_ISO_BUFFER_NUM and **EFI_USB_MAX_ISO_BUFFER_NUM1** values.

If the isochronous transfer is successful, then **EFI_SUCCESS** is returned. The isochronous transfer is designed to be completed within one USB frame time, if it cannot be completed, **EFI_TIMEOUT** is returned. If an error other than timeout occurs during the USB transfer, then

EFI_DEVICE_ERROR is returned and the detailed status code will be returned in *TransferResult*.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- *Data* is **NULL**.
- *DataLength* is 0.
- *MaximumPacketLength* is larger than 1023.
- *TransferResult* is **NULL**.

Status Codes Returned

EFI_SUCCESS	The isochronous transfer was completed successfully.
EFI_OUT_OF_RESOURCES	The isochronous transfer could not be submitted due to lack of resource.
EFI_INVALID_PARAMETER	Some parameters are invalid. The possible invalid parameters are described in “Description” above.

EFI_TIMEOUT	The isochronous transfer cannot be completed within the one USB frame time.
EFI_DEVICE_ERROR	The isochronous transfer failed due to host controller or device error. Caller should check <i>TransferResult</i> for detailed error information.
EFI_UNSUPPORTED	The implementation doesn't support an Isochronous transfer function.

EFI_USB2_HC_PROTOCOL.AsyncIsochronousTransfer()

Summary

Submits nonblocking isochronous transfer to an isochronous endpoint of a USB device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI * EFI_USB2_HC_PROTOCOL_ASYNC_ISOCHRONOUS_TRANSFER) (
    IN      EFI_USB2_HC_PROTOCOL      *This,
    IN      UINT8                     DeviceAddress,
    IN      UINT8                     EndPointAddress,
    IN      UINT8                     DeviceSpeed,
    IN      UINTN                     MaximumPacketLength,
    IN      UINT8                     DataBuffersNumber,
    IN OUT VOID                       *Data[EFI_USB_MAX_ISO_BUFFER_NUM],
    IN      UINTN                     DataLength,
    IN      EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,
    IN EFI_ASYNC_USB_TRANSFER_CALLBACK IsochronousCallBack,
    IN VOID                             *Context OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>DeviceAddress</i>	Represents the address of the target device on the USB, which is assigned during USB enumeration.
<i>EndPointAddress</i>	The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is zero). It is the caller's responsibility to make sure that the <i>EndPointAddress</i> represents an isochronous endpoint.
<i>DeviceSpeed</i>	Indicates device speed. The supported values are EFI_USB_SPEED_FULL and EFI_USB_SPEED_HIGH .
<i>MaximumPacketLength</i>	Indicates the maximum packet size the target endpoint is capable of sending or receiving. For isochronous endpoints, this value is used to reserve the bus time in the schedule, required for the per-frame data payloads. The pipe may, on an ongoing basis, actually use less bandwidth than that reserved.
<i>DataBuffersNumber</i>	Number of data buffers prepared for the transfer.
<i>Data</i>	Array of pointers to the buffers of data that will be transmitted to USB device or received from USB device.

<i>DataLength</i>	Specifies the length, in bytes, of the data to be sent to or received from the USB device.
<i>Translator</i>	A pointer to the transaction translator data. See ControlTransfer() “Description” for the detailed information of this data structure.
<i>IsochronousCallback</i>	The Callback function. This function is called if the requested isochronous transfer is completed. Refer to Section 2.5.3 of EFI1.1 USB Driver Model, version 0.7.
<i>Context</i>	Data passed to the <i>IsochronousCallback</i> function. This is an optional parameter and may be NULL .

Description

This is an asynchronous type of USB isochronous transfer. If the caller submits a USB isochronous transfer request through this function, this function will return immediately. When the isochronous transfer completes, the **IsochronousCallback** function will be triggered, the caller can know the transfer results. If the transfer is successful, the caller can get the data received or sent in this callback function.

The target endpoint is specified by *DeviceAddress* and *EndpointAddress*. Isochronous transfers are used when working with isochronous data. It provides periodic, continuous communication between the host and a device. Isochronous transfers can be used only by full-speed and high-speed devices.

High-speed isochronous transfers can be performed using multiple data buffers. The number of buffers that are actually prepared for the transfer is specified by *DataBuffersNumber*. For full-speed isochronous transfers this value is ignored.

Data represents a list of pointers to the data buffers. For full-speed isochronous transfers only the data pointed by *Data[0]* shall be used. For high-speed isochronous transfers and for the split transactions depending on *DataLength* there several data buffers can be used. For the high-speed isochronous transfers the total number of buffers must not exceed

EFI_USB_MAX_ISO_BUFFER_NUM. For split transactions performed on full-speed device by high-speed host controller the total number of buffers is limited to **EFI_USB_MAX_ISO_BUFFER_NUM1**. See “Related Definitions” in IsochronousTransfer() section for the **EFI_USB_MAX_ISO_BUFFER_NUM** and **EFI_USB_MAX_ISO_BUFFER_NUM1** values.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- *Data* is **NULL**.
- *DataLength* is 0.
- *MaximumPacketLength* is larger than 1023.

Status Codes Returned

EFI_SUCCESS	The asynchronous isochronous transfer was completed successfully.
EFI_OUT_OF_RESOURCES	The asynchronous isochronous transfer could not be submitted due to lack of resource.
EFI_INVALID_PARAMETER	Some parameters are invalid. The possible invalid parameters are described in “Description” above.

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EFI_UNSUPPORTED	The implementation doesn't support Isochronous transfer function
-----------------	--

EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus()

Summary

Retrieves the current status of a USB root hub port.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_GET_ROOTHUB_PORT_STATUS) (
    IN  EFI_USB2_HC_PROTOCOL  *This,
    IN  UINT8                 PortNumber,
    OUT EFI_USB_PORT_STATUS   *PortStatus
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>PortNumber</i>	Specifies the root hub port from which the status is to be retrieved. This value is zero based. For example, if a root hub has two ports, then the first port is numbered 0, and the second port is numbered 1.
<i>PortStatus</i>	A pointer to the current port status bits and port status change bits. The type EFI_USB_PORT_STATUS is defined in “Related Definitions” below.

Related Definitions

```
typedef struct{
    UINT16  PortStatus;
    UINT16  PortChangeStatus;
} EFI_USB_PORT_STATUS;

//*****
// EFI_USB_PORT_STATUS.PortStatus bit definition
//*****
#define USB_PORT_STAT_CONNECTION      0x0001
#define USB_PORT_STAT_ENABLE         0x0002
#define USB_PORT_STAT_SUSPEND        0x0004
#define USB_PORT_STAT_OVERCURRENT    0x0008
#define USB_PORT_STAT_RESET          0x0010
#define USB_PORT_STAT_POWER          0x0100
#define USB_PORT_STAT_LOW_SPEED      0x0200
#define USB_PORT_STAT_HIGH_SPEED     0x0400

//*****
```

```
// EFI_USB_PORT_STATUS.PortChangeStatus bit definition
//*****
#define USB_PORT_STAT_C_CONNECTION    0x0001
#define USB_PORT_STAT_C_ENABLE       0x0002
#define USB_PORT_STAT_C_SUSPEND      0x0004
#define USB_PORT_STAT_C_OVERCURRENT  0x0008
#define USB_PORT_STAT_C_RESET        0x0010
```

PortStatus Contains current port status bitmap. The root hub port status bitmap is unified with the USB hub port status bitmap. See [Table 112](#) for a reference, which is borrowed from *Chapter 11, Hub Specification, of USB Specification, Revision 1.1*.

PortChangeStatus Contains current port status change bitmap. The root hub port change status bitmap is unified with the USB hub port status bitmap. See [Table 113](#) for a reference, which is borrowed from *Chapter 11, Hub Specification, of USB Specification, Revision 1.1*.

Table 112. USB Hub Port Status Bitmap

Bit	Description
0	Current Connect Status: (USB_PORT_STAT_CONNECTION) This field reflects whether or not a device is currently connected to this port. 0 = No device is present 1 = A device is present on this port
1	Port Enable / Disabled: (USB_PORT_STAT_ENABLE) Ports can be enabled by software only. Ports can be disabled by either a fault condition (disconnect event or other fault condition) or by software. 0 = Port is disabled 1 = Port is enabled
2	Suspend: (USB_PORT_STAT_SUSPEND) This field indicates whether or not the device on this port is suspended. 0 = Not suspended 1 = Suspended
3	Over-current Indicator: (USB_PORT_STAT_OVERCURRENT) This field is used to indicate that the current drain on the port exceeds the specified maximum. 0 = All no over-current condition exists on this port 1 = An over-current condition exists on this port
4	Reset: (USB_PORT_STAT_RESET) Indicates whether port is in reset state. 0 = Port is not in reset state 1 = Port is in reset state
5-7	Reserved These bits return 0 when read.
8	Port Power: (USB_PORT_STAT_POWER) This field reflects a port's logical, power control state. 0 = This port is in the Powered-off state 1 = This port is not in the Powered-off state

Bit	Description
9	<p>Low Speed Device Attached: (USB_PORT_STAT_LOW_SPEED) This is relevant only if a device is attached.</p> <p>0 = Full-speed device attached to this port 1 = Low-speed device attached to this port</p>
10	<p>High Speed Device Attached: (USB_PORT_STAT_HIGH_SPEED) This field indicates whether the connected device is high-speed device</p> <p>0 = High-speed device is not attached to this port 1 = High-speed device attached to this port</p> <p>NOTE: this bit has precedence over Bit 9; if set, bit 9 must be ignored.</p>
11-15	<p>Reserved These bits return 0 when read.</p>

Table 113. Hub Port Change Status Bitmap

Bit	Description
0	<p>Connect Status Change: (USB_PORT_STAT_C_CONNECTION) Indicates a change has occurred in the port's Current Connect Status.</p> <p>0 = No change has occurred to Current Connect status 1 = Current Connect status has changed</p>
1	<p>Port Enable /Disable Change: (USB_PORT_STAT_C_ENABLE)</p> <p>0 = No change 1 = Port enabled/disabled status has changed</p>
2	<p>Suspend Change: (USB_PORT_STAT_C_SUSPEND) This field indicates a change in the host-visible suspend state of the attached device.</p> <p>0 = No change 1 = Resume complete</p>
3	<p>Over-Current Indicator Change: (USB_PORT_STAT_C_OVERCURRENT)</p> <p>0 = No change has occurred to Over-Current Indicator 1 = Over-Current Indicator has changed</p>
4	<p>Reset Change: (USB_PORT_STAT_C_RESET) This field is set when reset processing on this port is complete.</p> <p>0 = No change 1 = Reset complete</p>
5-15	<p>Reserved. These bits return 0 when read.</p>

Description

This function is used to retrieve the status of the root hub port specified by *PortNumber*.

[EFI_USB_PORT_STATUS](#) describes the port status of a specified USB port. This data structure is designed to be common to both a USB root hub port and a USB hub port.

The number of root hub ports attached to the USB host controller can be determined with the function [GetRootHubPortStatus\(\)](#). If *PortNumber* is greater than or equal to the number of ports returned by [GetRootHubPortNumber\(\)](#), then **EFI_INVALID_PARAMETER** is returned. Otherwise, the status of the USB root hub port is returned in *PortStatus*, and **EFI_SUCCESS** is returned.

Status Codes Returned

EFI_SUCCESS	The status of the USB root hub port specified by <i>PortNumber</i> was returned in <i>PortStatus</i> .
EFI_INVALID_PARAMETER	<i>PortNumber</i> is invalid.

EFI_USB2_HC_PROTOCOL.SetRootHubPortFeature()

Summary

Sets a feature for the specified root hub port.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_SET_ROOTHUB_PORT_FEATURE) (
    IN EFI_USB2_HC_PROTOCOL    *This,
    IN UINT8                   PortNumber,
    IN EFI_USB_PORT_FEATURE    PortFeature
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>PortNumber</i>	Specifies the root hub port whose feature is requested to be set. This value is zero based. For example, if a root hub has two ports, then the first port is number 0, and the second port is numbered 1.
<i>PortFeature</i>	Indicates the feature selector associated with the feature set request. The port feature indicator is defined in “Related Definitions” and Table 114 below.

Related Definitions

```
typedef enum {
    EfiUsbPortEnable           = 1,
    EfiUsbPortSuspend         = 2,
    EfiUsbPortReset           = 4,
    EfiUsbPortPower           = 8,
    EfiUsbPortOwner           = 13,
    EfiUsbPortConnectChange   = 16,
    EfiUsbPortEnableChange    = 17,
    EfiUsbPortSuspendChange   = 18,
    EfiUsbPortOverCurrentChange = 19,
    EfiUsbPortResetChange     = 20
} EFI_USB_PORT_FEATURE;
```

The feature values specified in the enumeration variable have special meaning. Each value indicates its bit index in the port status and status change bitmaps, if combines these two bitmaps into a 32-bit bitmap. The meaning of each port feature is listed in [Table 114](#).

Table 114. USB Port Features

Port Feature	For SetRootHubPortFeature	For ClearRootHubPortFeature
EfiUsbPortEnable	Enable the given port of the root hub.	Disable the given port of the root hub.
EfiUsbPortSuspend	Put the given port into suspend state.	Restore the given port from the previous suspend state.
EfiUsbPortReset	Reset the given port of the root hub.	Clear the RESET signal for the given port of the root hub.
EfiUsbPortPower	Power the given port.	Shutdown the power from the given port.
EfiUsbPortOwner	N/A.	Releases the port ownership of this port to companion host controller.
EfiUsbPortConnectChange	N/A.	Clear USB_PORT_STAT_C_CONNECTION bit of the given port of the root hub.
EfiUsbPortEnableChange	N/A.	Clear USB_PORT_STAT_C_ENABLE bit of the given port of the root hub.
EfiUsbPortSuspendChange	N/A.	Clear USB_PORT_STAT_C_SUSPEND bit of the given port of the root hub.
EfiUsbPortOverCurrentChange	N/A.	Clear USB_PORT_STAT_C_OVERCURRENT bit of the given port of the root hub.
EfiUsbPortResetChange	N/A.	Clear USB_PORT_STAT_C_RESET bit of the given port of the root hub.

Description

This function sets the feature specified by *PortFeature* for the USB root hub port specified by *PortNumber*. Setting a feature enables that feature or starts a process associated with that feature. For the meanings about the defined features, please refer to [Table 112](#) and [Table 113](#).

The number of root hub ports attached to the USB host controller can be determined with the function [GetRootHubPortStatus\(\)](#). If *PortNumber* is greater than or equal to the number of ports returned by [GetRootHubPortNumber\(\)](#), then **EFI_INVALID_PARAMETER** is returned. If *PortFeature* is not **EfiUsbPortEnable**, **EfiUsbPortSuspend**, **EfiUsbPortReset** nor **EfiUsbPortPower**, then **EFI_INVALID_PARAMETER** is returned.

Status Codes Returned

EFI_SUCCESS	The feature specified by <i>PortFeature</i> was set for the USB root hub port specified by <i>PortNumber</i> .
EFI_INVALID_PARAMETER	<i>PortNumber</i> is invalid or <i>PortFeature</i> is invalid for this function.

EFI_USB2_HC_PROTOCOL.ClearRootHubPortFeature()

Summary

Clears a feature for the specified root hub port.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_CLEAR_ROOTHUB_PORT_FEATURE) (
    IN EFI_USB2_HC_PROTOCOL    *This
    IN UINT8                   PortNumber,
    IN EFI_USB_PORT_FEATURE    PortFeature
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in Section 16.1 .
<i>PortNumber</i>	Specifies the root hub port whose feature is requested to be cleared. This value is zero-based. For example, if a root hub has two ports, then the first port is number 0, and the second port is numbered 1.
<i>PortFeature</i>	Indicates the feature selector associated with the feature clear request. The port feature indicator (EFI_USB_PORT_FEATURE) is defined in the “Related Definitions” section of the SetRootHubPortFeature() function description and in Table 114 .

Description

This function clears the feature specified by *PortFeature* for the USB root hub port specified by *PortNumber*. Clearing a feature disables that feature or stops a process associated with that feature. For the meanings about the defined features, refer to [Table 112](#) and [Table 113](#).

The number of root hub ports attached to the USB host controller can be determined with the function [GetRootHubPortStatus\(\)](#). If *PortNumber* is greater than or equal to the number of ports returned by [GetRootHubPortNumber\(\)](#), then [EFI_INVALID_PARAMETER](#) is returned. If *PortFeature* is not [EfiUsbPortEnable](#), [EfiUsbPortSuspend](#), [EfiUsbPortPower](#), [EfiUsbPortConnectChange](#), [EfiUsbPortResetChange](#), [EfiUsbPortEnableChange](#), [EfiUsbPortSuspendChange](#), or [EfiUsbPortOverCurrentChange](#), then [EFI_INVALID_PARAMETER](#) is returned.

Status Codes Returned

EFI_SUCCESS	The feature specified by <i>PortFeature</i> was cleared for the USB root hub port specified by <i>PortNumber</i> .
EFI_INVALID_PARAMETER	<i>PortNumber</i> is invalid or <i>PortFeature</i> is invalid.

16.2 USB Driver Model

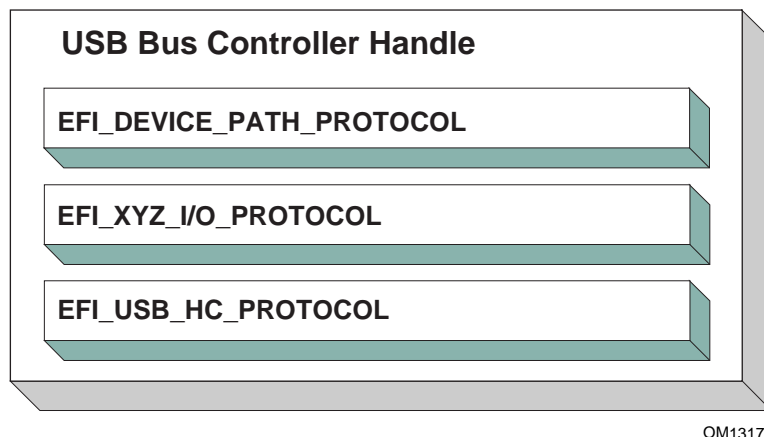
16.2.1 Scope

[Section 16.2](#) describes the USB Driver Model. This includes the behavior of USB Bus Drivers, the behavior of a USB Device Drivers, and a detailed description of the EFI USB I/O Protocol. This document provides enough material to implement a USB Bus Driver, and the tools required to design and implement USB Device Drivers. It does not provide any information on specific USB devices.

The material contained in this section is designed to extend this specification and the *UEFI Driver Model* in a way that supports USB device drivers and USB bus drivers. These extensions are provided in the form of USB specific protocols. This document provides the information required to implement a USB Bus Driver in system firmware. The document also contains the information required by driver writers to design and implement USB Device Drivers that a platform may need to boot a UEFI-compliant OS.

The USB Driver Model described here is intended to be a foundation on which a USB Bus Driver and a wide variety of USB Device Drivers can be created. USB Driver Model Overview

The USB Driver Stack includes the USB Bus Driver, USB Host Controller Driver, and individual USB device drivers.



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Figure 47. USB Bus Controller Handle

In the USB Bus Driver Design, the USB Bus Controller is managed by two drivers. One is USB Host Controller Driver, which consumes its parent bus **EFI_XYZ_IO_PROTOCOL**, and produces **EFI_USB2_HC_PROTOCOL** and attaches it to the Bus Controller Handle. The other one is USB Bus Driver, which consumes **EFI_USB2_HC_PROTOCOL**, and performs bus enumeration. [Figure 47](#) shows protocols that are attached to the USB Bus Controller Handle. Detailed descriptions are presented in the following sections.

16.2.2 USB Bus Driver

USB Bus Driver performs periodic Enumeration on the USB Bus. In USB bus enumeration, when a new USB controller is found, the bus driver does some standard configuration for that new controller, and creates a device handle for it. The [EFI_USB_IO_PROTOCOL](#) and the [EFI_DEVICE_PATH_PROTOCOL](#) are attached to the device handle so that the USB controller can be accessed. The USB Bus Driver is also responsible for connecting USB device drivers to USB controllers. When a USB device is detached from a USB bus, the USB bus driver will stop that USB controller, and uninstall the [EFI_USB_IO_PROTOCOL](#) and the [EFI_DEVICE_PATH_PROTOCOL](#) from that handle. A detailed description is given in [Section 16.2.2.3](#).

16.2.2.1 USB Bus Driver Entry Point

Like all other device drivers, the entry point for a USB Bus Driver attaches the [EFI_DRIVER_BINDING_PROTOCOL](#) to image handle of the USB Bus Driver.

16.2.2.2 Driver Binding Protocol for USB Bus Drivers

The Driver Binding Protocol contains three services. These are [Supported\(\)](#), [Start\(\)](#), and [Stop\(\)](#). [Supported\(\)](#) tests to see if the USB Bus Driver can manage a device handle. A USB Bus Driver can only manage a device handle that contains [EFI_USB2_HC_PROTOCOL](#).

The general idea is that the USB Bus Driver is a generic driver. Since there are several types of USB Host Controllers, an [EFI_USB2_HC_PROTOCOL](#) is used to abstract the host controller interface. Actually, a USB Bus Driver only requires an [EFI_USB2_HC_PROTOCOL](#).

The [Start\(\)](#) function tells the USB Bus Driver to start managing the USB Bus. In this function, the USB Bus Driver creates a device handle for the root hub, and creates a timer to monitor root hub connection changes.

The [Stop\(\)](#) function tells the USB Bus Driver to stop managing a USB Host Bus Controller. The [Stop\(\)](#) function simply deconfigures the devices attached to the root hub. The deconfiguration is a recursive process. If the device to be deconfigured is a USB hub, then all USB devices attached to its downstream ports will be deconfigured first, then itself. If all of the child devices handles have been destroyed then the [EFI_USB2_HC_PROTOCOL](#) is closed. Finally, the [Stop\(\)](#) function will then place the USB Host Bus Controller in a quiescent state.

16.2.2.3 USB Hot-Plug Event

Hot-Plug is one of the most important features provided by USB. A USB bus driver implements this feature through two methods. There are two types of hubs defined in the USB specification. One is the USB root hub, which is implemented in the USB Host controller. A timer event is created for the root hub. The other one is a USB Hub. An event is created for each hub that is correctly configured. All these events are associated with the same trigger which is USB bus numerator.

When USB bus enumeration is triggered, the USB Bus Driver checks the source of the event. This is required because the root hub differs from standard USB hub in checking the hub status. The status of a root hub is retrieved through the [EFI_USB2_HC_PROTOCOL](#), and that status of a standard USB hub is retrieved through a USB control transfer. A detailed description of the enumeration process is presented in the next section.

16.2.2.4 USB Bus Enumeration

When the periodic timer or the hubs notify event is signaled, the USB Bus Driver will perform bus enumeration.

1. Determine if the event is from the root hub or a standard USB hub.
2. Determine the port on which the connection change event occurred.
3. Determine if it is a connection change or a disconnection change.
4. If a connect change is detected, then a new device has been attached. Perform the following:
 - a Reset and enable that port.
 - b Configure the new device.
 - c Parse the device configuration descriptors; get all of its interface descriptors (i.e. all USB controllers), and configure each interface.
 - d Create a new handle for each interface (USB Controller) within the USB device. Attach the [EFI_DEVICE_PATH_PROTOCOL](#), and the [EFI_USB_IO_PROTOCOL](#) to each handle.
 - e Connect the USB Controller to a USB device driver with the Boot Service [ConnectController\(\)](#) if applicable.
 - f If the USB Controller is a USB hub, create a Hub notify event which is associated with the USB Bus Enumerator, and submit an Asynchronous Interrupt Transfer Request (See [Section 16.2.4](#)).
5. If a disconnect change, then a device has been detached from the USB Bus. Perform the following:
 - a If the device is not a USB Hub, then find and deconfigure the USB Controllers within the device. Then, stop each USB controller with [DisconnectController\(\)](#), and uninstall the [EFI_DEVICE_PATH_PROTOCOL](#) and the [EFI_USB_IO_PROTOCOL](#) from the controller's handle.
 - b If the USB controller is USB hub controller, first find and deconfigure all its downstream USB devices (this is a recursive process, since there may be additional USB hub controllers on the downstream ports), then deconfigure USB hub controller itself.

16.2.3 USB Device Driver

A USB Device Driver manages a USB Controller and produces a device abstraction for use by a preboot application.

16.2.3.1 USB Device Driver Entry Point

Like all other device drivers, the entry point for a USB Device Driver attaches [EFI_DRIVER_BINDING_PROTOCOL](#) to image handle of the USB Device Driver.

16.2.3.2 Driver Binding Protocol for USB Device Drivers

The Driver Binding Protocol contains three services. These are [Supported\(\)](#), [Start\(\)](#), and [Stop\(\)](#).

The [Supported\(\)](#) tests to see if the USB Device Driver can manage a device handle. This function checks to see if a controller can be managed by the USB Device Driver. This is done by

opening the [EFI_USB_IO_PROTOCOL](#) bus abstraction on the USB Controller handle, and using the [EFI_USB_IO_PROTOCOL](#) services to determine if this USB Controller matches the profile that the USB Device Driver is capable of managing.

The `Start()` function tells the USB Device Driver to start managing a USB Controller. It opens the [EFI_USB_IO_PROTOCOL](#) instance from the handle for the USB Controller. This protocol instance is used to perform USB packet transmission over the USB bus. For example, if the USB controller is USB keyboard, then the USB keyboard driver would produce and install the [EFI_SIMPLE_TEXT_INPUT_PROTOCOL](#) to the USB controller handle.

The `Stop()` function tells the USB Device Driver to stop managing a USB Controller. It removes the I/O abstraction protocol instance previously installed in `Start()` from the USB controller handle. It then closes the [EFI_USB_IO_PROTOCOL](#).

16.2.4 USB I/O Protocol

This section provides a detailed description of the [EFI_USB_IO_PROTOCOL](#). This protocol is used by code, typically drivers, running in the EFI boot services environment to access USB devices like USB keyboards, mice and mass storage devices. In particular, functions for managing devices on USB buses are defined here.

The interfaces provided in the [EFI_USB_IO_PROTOCOL](#) are for performing basic operations to access USB devices. Typically, USB devices are accessed through the four different transfers types:

<i>Controller Transfer</i>	Typically used to configure the USB device into an operation mode.
<i>Interrupt Transfer</i>	Typically used to get periodic small amount of data, like USB keyboard and mouse.
<i>Bulk Transfer</i>	Typically used to transfer large amounts of data like reading blocks from USB mass storage devices.
<i>Isochronous Transfer</i>	Typically used to transfer data at a fixed rate like voice data.

This protocol also provides mechanisms to manage and configure USB devices and controllers.

EFI_USB_IO_PROTOCOL

Summary

Provides services to manage and communicate with USB devices.

GUID

```
#define EFI_USB_IO_PROTOCOL_GUID \
    {0x2B2F68D6, 0x0CD2, 0x44cf, 0x8E, 0x8B, 0xBB, 0xA2, 0x0B, 0x1B, \
     0x5B, 0x75}
```

Protocol Interface Structure

```
typedef struct _EFI_USB_IO_PROTOCOL {
    EFI_USB_IO_CONTROL_TRANSFER        UsbControlTransfer;
    EFI_USB_IO_BULK_TRANSFER           UsbBulkTransfer;
```

```

EFI_USB_IO_ASYNC_INTERRUPT_TRANSFER           UsbAsyncInterruptTransfer;
EFI_USB_IO_SYNC_INTERRUPT_TRANSFER           UsbSyncInterruptTransfer
EFI_USB_IO_ISOCHRONOUS_TRANSFER             UsbIsochronousTransfer;
EFI_USB_IO_ASYNC_ISOCHRONOUS_TRANSFER       UsbAsyncIsochronousTransfer;
EFI_USB_IO_GET_DEVICE_DESCRIPTOR           UsbGetDeviceDescriptor;
EFI_USB_IO_GET_CONFIG_DESCRIPTOR           UsbGetConfigDescriptor;
EFI_USB_IO_GET_INTERFACE_DESCRIPTOR         UsbGetInterfaceDescriptor;
EFI_USB_IO_GET_ENDPOINT_DESCRIPTOR         UsbGetEndpointDescriptor;
EFI_USB_IO_GET_STRING_DESCRIPTOR           UsbGetStringDescriptor;
EFI_USB_IO_GET_SUPPORTED_LANGUAGES         UsbGetSupportedLanguages;
EFI_USB_IO_PORT_RESET                       UsbPortReset;
} EFI_USB_IO_PROTOCOL;

```

Parameters

- UsbControlTransfer* Accesses the USB Device through USB Control Transfer Pipe. See the [UsbControlTransfer \(\)](#) function description.
- UsbBulkTransfer* Accesses the USB Device through USB Bulk Transfer Pipe. See the [UsbBulkTransfer \(\)](#) function description.
- UsbAsyncInterruptTransfer* Non-block USB interrupt transfer. See the [UsbAsyncInterruptTransfer \(\)](#) function description.
- UsbSyncInterruptTransfer* Accesses the USB Device through USB Synchronous Interrupt Transfer Pipe. See the [UsbSyncInterruptTransfer \(\)](#) function description.
- UsbIsochronousTransfer* Accesses the USB Device through USB Isochronous Transfer Pipe. See the [UsbIsochronousTransfer \(\)](#) function description.
- UsbAsyncIsochronousTransfer* Nonblock USB isochronous transfer. See the [UsbAsyncIsochronousTransfer \(\)](#) function description.
- UsbGetDeviceDescriptor* Retrieves the device descriptor of a USB device. See the [UsbGetDeviceDescriptor \(\)](#) function description.
- UsbGetConfigDescriptor* Retrieves the activated configuration descriptor of a USB device. See the [UsbGetConfigDescriptor \(\)](#) function description.
- UsbGetInterfaceDescriptor* Retrieves the interface descriptor of a USB Controller. See the [UsbGetInterfaceDescriptor \(\)](#) function description.

UsbGetEndpointDescriptor

Retrieves the endpoint descriptor of a USB Controller. See the [UsbGetEndpointDescriptor \(\)](#) function description.

UsbGetStringDescriptor

Retrieves the string descriptor inside a USB Device. See the [UsbGetStringDescriptor \(\)](#) function description.

UsbGetSupportedLanguages

Retrieves the array of languages that the USB device supports. See the [UsbGetSupportedLanguages \(\)](#) function description.

UsbPortReset

Resets and reconfigures the USB controller. See the [UsbPortReset \(\)](#) function description.

Description

The **EFI_USB_IO_PROTOCOL** provides four basic transfers types described in the *USB 1.1 Specification*. These include control transfer, interrupt transfer, bulk transfer and isochronous transfer. The **EFI_USB_IO_PROTOCOL** also provides some basic USB device/controller management and configuration interfaces. A USB device driver uses the services of this protocol to manage USB devices.

EFI_USB_IO_PROTOCOL.UsbControlTransfer()

Summary

This function is used to manage a USB device with a control transfer pipe. A control transfer is typically used to perform device initialization and configuration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_CONTROL_TRANSFER) (
    IN     EFI_USB_IO_PROTOCOL    *This,
    IN     EFI_USB_DEVICE_REQUEST *Request,
    IN     EFI_USB_DATA_DIRECTION Direction,
    IN     UINT32                 Timeout,
    IN OUT VOID                  *Data      OPTIONAL,
    IN     UINTN                  DataLength OPTIONAL,
    OUT    UINT32                 *Status
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>Request</i>	A pointer to the USB device request that will be sent to the USB device. See “Related Definitions” below.
<i>Direction</i>	Indicates the data direction. See “Related Definitions” below for this type.
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>Timeout</i>	Indicating the transfer should be completed within this time frame. The units are in milliseconds. If <i>Timeout</i> is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.
<i>DataLength</i>	The size, in bytes, of the data buffer specified by <i>Data</i> .
<i>Status</i>	A pointer to the result of the USB transfer.

Related Definitions

```
typedef enum {
    EfiUsbDataIn,
    EfiUsbDataOut,
    EfiUsbNoData
} EFI_USB_DATA_DIRECTION;

//
// Error code for USB Transfer Results
```



```
//
#define EFI_USB_NOERROR           0x0000
#define EFI_USB_ERR_NOTEXECUTE    0x0001
#define EFI_USB_ERR_STALL        0x0002
#define EFI_USB_ERR_BUFFER       0x0004
#define EFI_USB_ERR_BABBLE       0x0008
#define EFI_USB_ERR_NAK          0x0010
#define EFI_USB_ERR_CRC          0x0020
#define EFI_USB_ERR_TIMEOUT      0x0040
#define EFI_USB_ERR_BITSTUFF     0x0080
#define EFI_USB_ERR_SYSTEM       0x0100

typedef struct {
    UINT8      RequestType;
    UINT8      Request;
    UINT16     Value;
    UINT16     Index;
    UINT16     Length;
} EFI_USB_DEVICE_REQUEST;
```

<i>RequestType</i>	The field identifies the characteristics of the specific request.
<i>Request</i>	This field specifies the particular request.
<i>Value</i>	This field is used to pass a parameter to USB device that is specific to the request.
<i>Index</i>	This field is also used to pass a parameter to USB device that is specific to the request.
<i>Length</i>	This field specifies the length of the data transferred during the second phase of the control transfer. If it is 0, then there is no data phase in this transfer.

Description

This function allows a USB device driver to communicate with the USB device through a Control Transfer. There are three control transfer types according to the data phase. If the *Direction* parameter is **EfiUsbNoData**, *Data* is **NULL**, and *DataLength* is 0, then no data phase exists for the control transfer. If the *Direction* parameter is **EfiUsbDataOut**, then *Data* specifies the data to be transmitted to the device, and *DataLength* specifies the number of bytes to transfer to the device. In this case there is an OUT DATA stage followed by a SETUP stage. If the *Direction* parameter is **EfiUsbDataIn**, then *Data* specifies the data that is received from the device, and *DataLength* specifies the number of bytes to receive from the device. In this case there is an IN DATA stage followed by a SETUP stage. After the USB transfer has completed successfully, **EFI_SUCCESS** is returned. If the transfer cannot be completed due to timeout, then **EFI_TIMEOUT** is returned. If an error other than timeout occurs during the USB transfer, then **EFI_DEVICE_ERROR** is returned and the detailed status code is returned in *Status*.

Status Code Returned

EFI_SUCCESS	The control transfer has been successfully executed.
EFI_INVALID_PARAMETER	The parameter <i>Direction</i> is not valid.
EFI_INVALID_PARAMETER	<i>Request</i> is NULL .
EFI_INVALID_PARAMETER	<i>Status</i> is NULL .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.
EFI_TIMEOUT	The control transfer fails due to timeout.
EFI_DEVICE_ERROR	The transfer failed. The transfer status is returned in <i>Status</i> .

EFI_USB_IO_PROTOCOL.UsbBulkTransfer()

Summary

This function is used to manage a USB device with the bulk transfer pipe. Bulk Transfers are typically used to transfer large amounts of data to/from USB devices.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_USB_IO_BULK_TRANSFER) (
    IN     EFI_USB_IO_PROTOCOL  *This,
    IN     UINT8                DeviceEndpoint,
    IN     OUT VOID             *Data,
    IN OUT UINTN               *DataLength,
    IN     UINTN                Timeout,
    OUT    UINT32               *Status
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>DeviceEndpoint</i>	The destination USB device endpoint to which the device request is being sent. <i>DeviceEndpoint</i> must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not a BULK endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	On input, the size, in bytes, of the data buffer specified by <i>Data</i> . On output, the number of bytes that were actually transferred.
<i>Timeout</i>	Indicating the transfer should be completed within this time frame. The units are in milliseconds. If <i>Timeout</i> is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.
<i>Status</i>	This parameter indicates the USB transfer status.

Description

This function allows a USB device driver to communicate with the USB device through Bulk Transfer. The transfer direction is determined by the endpoint direction. If the USB transfer is successful, then [EFI_SUCCESS](#) is returned. If USB transfer cannot be completed within the *Timeout* frame, [EFI_TIMEOUT](#) is returned. If an error other than timeout occurs during the USB

transfer, then **EFI_DEVICE_ERROR** is returned and the detailed status code will be returned in the *Status* parameter.

Status Code Returned

EFI_SUCCESS	The bulk transfer has been successfully executed.
EFI_INVALID_PARAMETER	If <i>DeviceEndpoint</i> is not valid.
EFI_INVALID_PARAMETER	<i>Data</i> is NULL .
EFI_INVALID_PARAMETER	<i>DataLength</i> is NULL .
EFI_INVALID_PARAMETER	<i>Status</i> is NULL .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.
EFI_TIMEOUT	The bulk transfer cannot be completed within <i>Timeout</i> timeframe.
EFI_DEVICE_ERROR	The transfer failed other than timeout, and the transfer status is returned in <i>Status</i> .

EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer()

Summary

This function is used to manage a USB device with an interrupt transfer pipe. An Asynchronous Interrupt Transfer is typically used to query a device’s status at a fixed rate. For example, keyboard, mouse, and hub devices use this type of transfer to query their interrupt endpoints at a fixed rate.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_ASYNC_INTERRUPT_TRANSFER) (
    IN EFI_USB_IO_PROTOCOL          *This,
    IN UINT8                        DeviceEndpoint,
    IN BOOLEAN                      IsNewTransfer,
    IN UINTN                        PollingInterval    OPTIONAL,
    IN UINTN                        DataLength         OPTIONAL,
    IN EFI_ASYNC_USB_TRANSFER_CALLBACK InterruptCallback OPTIONAL,
    IN VOID                          *Context         OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>DeviceEndpoint</i>	The destination USB device endpoint to which the device request is being sent. <i>DeviceEndpoint</i> must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not an INTERRUPT endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.
<i>IsNewTransfer</i>	If TRUE , a new transfer will be submitted to USB controller. If FALSE , the interrupt transfer is deleted from the device’s interrupt transfer queue. If TRUE , and an interrupt transfer exists for the target end point, then EFI_INVALID_PARAMETER is returned.
<i>PollingInterval</i>	Indicates the periodic rate, in milliseconds, that the transfer is to be executed. This parameter is required when <i>IsNewTransfer</i> is TRUE . The value must be between 1 to 255, otherwise EFI_INVALID_PARAMETER is returned. The units are in milliseconds.
<i>DataLength</i>	Specifies the length, in bytes, of the data to be received from the USB device. This parameter is only required when <i>IsNewTransfer</i> is TRUE .

<i>Context</i>	Data passed to the <i>InterruptCallback</i> function. This is an optional parameter and may be NULL .
<i>InterruptCallback</i>	The Callback function. This function is called if the asynchronous interrupt transfer is completed. This parameter is required when <i>IsNewTransfer</i> is TRUE . See “Related Definitions” for the definition of this type.

Related Definitions

```
typedef
EFI_STATUS
(EFI_API * EFI_ASYNC_USB_TRANSFER_CALLBACK) (
    IN VOID      *Data,
    IN UINTN     DataLength,
    IN VOID      *Context,
    IN UINT32    Status
);
```

<i>Data</i>	Data received or sent via the USB Asynchronous Transfer, if the transfer completed successfully.
<i>DataLength</i>	The length of <i>Data</i> received or sent via the Asynchronous Transfer, if transfer successfully completes.
<i>Context</i>	Data passed from UsbAsyncInterruptTransfer () request.
<i>Status</i>	Indicates the result of the asynchronous transfer.

Description

This function allows a USB device driver to communicate with a USB device with an Interrupt Transfer. Asynchronous Interrupt transfer is different than the other four transfer types because it is a nonblocking transfer. The interrupt endpoint is queried at a fixed rate, and the data transfer direction is always in the direction from the USB device towards the system.

If *IsNewTransfer* is **TRUE**, then an interrupt transfer is started at a fixed rate. The rate is specified by *PollingInterval*, the size of the receive buffer is specified by *DataLength*, and the callback function is specified by *InterruptCallback*. If *IsNewTransfer* is **TRUE**, and an interrupt transfer exists for the target end point, then **EFI_INVALID_PARAMETER** is returned.

If *IsNewTransfer* is **FALSE**, then the interrupt transfer is canceled.

Status Code Returned

EFI_SUCCESS	The asynchronous USB transfer request has been successfully executed.
EFI_DEVICE_ERROR	The asynchronous USB transfer request failed. When an interrupt transfer exists for the target end point and a new transfer is requested, EFI_INVALID_PARAMETER is returned.

Examples

Below is an example of how an asynchronous interrupt transfer is used. The example shows how a USB Keyboard Device Driver can periodically receive data from interrupt endpoint.

```

EFI_USB_IO_PROTOCOL      *UsbIo;
EFI_STATUS               Status;
USB_KEYBOARD_DEV         *UsbKeyboardDevice;
EFI_USB_INTERRUPT_CALLBACK KeyboardHandle;

. . .

Status = UsbIo->UsbAsyncInterruptTransfer(
    UsbIo,
    UsbKeyboardDevice->IntEndpointAddress,
    TRUE,
    UsbKeyboardDevice->IntPollingInterval,
    8,
    KeyboardHandler,
    UsbKeyboardDevice
);

. . .

//
// The following is the InterruptCallback function. If there is any results got /
// from Asynchronous Interrupt Transfer, this function will be called.
//
EFI_STATUS
KeyboardHandler(
    IN VOID          *Data,
    IN UINTN         DataLength,
    IN VOID          *Context,
    IN UINT32        Result
)
{
    USB_KEYBOARD_DEV *UsbKeyboardDevice;
    UINTN             I;

    if(EFI_ERROR(Result))
    {
        //
        // Something error during this transfer, just to some recovery work
        //
        . . .
        . . .
        return EFI_DEVICE_ERROR;
    }

    UsbKeyboardDevice = (USB_KEYBOARD_DEV *)Context;

    for(I = 0; I < DataLength; I++)
    {

```

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```
    ParsedData(Data[I]);  
    . . .  
}  
  
return EFI_SUCCESS;  
}
```


EFI_USB_IO_PROTOCOL.UsbSyncInterruptTransfer()

Summary

This function is used to manage a USB device with an interrupt transfer pipe. The difference between [UsbAsyncInterruptTransfer\(\)](#) and **UsbSyncInterruptTransfer()** is that the Synchronous interrupt transfer will only be executed one time. Once it returns, regardless of its status, the interrupt request will be deleted in the system.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_SYNC_INTERRUPT_TRANSFER) (
    IN      EFI_USB_IO_PROTOCOL  *This,
    IN      UINT8                DeviceEndpoint,
    IN OUT VOID                  *Data,
    IN OUT UINTN                 *DataLength,
    IN      UINTN                 Timeout,
    OUT     UINT32                *Status
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>DeviceEndpoint</i>	The destination USB device endpoint to which the device request is being sent. <i>DeviceEndpoint</i> must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not an INTERRUPT endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	On input, then size, in bytes, of the buffer <i>Data</i> . On output, the amount of data actually transferred.
<i>Timeout</i>	The time out, in seconds, for this transfer. If <i>Timeout</i> is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned. If the transfer is not completed in this time frame, then EFI_TIMEOUT is returned.
<i>Status</i>	This parameter indicates the USB transfer status.

Description

This function allows a USB device driver to communicate with a USB device through a synchronous interrupt transfer. The **UsbSyncInterruptTransfer()** differs from

[UsbAsyncInterruptTransfer\(\)](#) described in the previous section in that it is a blocking transfer request. The caller must wait for the function return, either successfully or unsuccessfully.

Status Code Returned

EFI_SUCCESS	The sync interrupt transfer has been successfully executed.
EFI_INVALID_PARAMETER	The parameter <i>DeviceEndpoint</i> is not valid.
EFI_INVALID_PARAMETER	<i>Data</i> is NULL .
EFI_INVALID_PARAMETER	<i>DataLength</i> is NULL .
EFI_INVALID_PARAMETER	<i>Status</i> is NULL .
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.
EFI_TIMEOUT	The transfer cannot be completed within <i>Timeout</i> timeframe.
EFI_DEVICE_ERROR	The transfer failed other than timeout, and the transfer status is returned in <i>Status</i> .

EFI_USB_IO_PROTOCOL.UsbIsochronousTransfer()

Summary

This function is used to manage a USB device with an isochronous transfer pipe. An Isochronous transfer is typically used to transfer streaming data.

Prototype

```
typedef
EFI_STATUS
(EFI_API * EFI_USB_IO_ISOCHRONOUS_TRANSFER) (
    IN      EFI_USB_IO_PROTOCOL  *This,
    IN      UINT8                DeviceEndpoint,
    IN OUT VOID                 *Data,
    IN      UINTN                DataLength,
    OUT     UINT32               *Status
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>DeviceEndpoint</i>	The destination USB device endpoint to which the device request is being sent. <i>DeviceEndpoint</i> must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not an ISOCHRONOUS endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	The size, in bytes, of the data buffer specified by <i>Data</i> .
<i>Status</i>	This parameter indicates the USB transfer status.

Description

This function allows a USB device driver to communicate with a USB device with an Isochronous Transfer. The type of transfer is different than the other types because the USB Bus Driver will not attempt to perform error recovery if transfer fails. If the USB transfer is completed successfully, then [EFI_SUCCESS](#) is returned. The isochronous transfer is designed to be completed within 1 USB frame time, if it cannot be completed, [EFI_TIMEOUT](#) is returned. If the transfer fails due to other reasons, then [EFI_DEVICE_ERROR](#) is returned and the detailed error status is returned in *Status*. If the data length exceeds the maximum payload per USB frame time, then it is this function’s responsibility to divide the data into a set of smaller packets that fit into a USB frame time. If all the packets are transferred successfully, then [EFI_SUCCESS](#) is returned.

Status Code Returned

EFI_SUCCESS	The isochronous transfer has been successfully executed.
EFI_INVALID_PARAMETER	The parameter <i>DeviceEndpoint</i> is not valid.
EFI_OUT_OF_RESOURCES	The request could not be completed due to a lack of resources.
EFI_TIMEOUT	The transfer cannot be completed within the 1 USB frame time.
EFI_DEVICE_ERROR	The transfer failed due to the reason other than timeout, The error status is returned in <i>Status</i> .
EFI_UNSUPPORTED	The implementation doesn't support an Isochronous transfer function.

EFI_USB_IO_PROTOCOL.UsbAsyncIsochronousTransfer()

Summary

This function is used to manage a USB device with an isochronous transfer pipe. An asynchronous Isochronous transfer is a nonblocking USB isochronous transfer.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_USB_IO_ASYNC_ISOCHRONOUS_TRANSFER) (
    IN EFI_USB_IO_PROTOCOL          *This,
    IN UINT8                        DeviceEndpoint,
    IN OUT VOID                     *Data,
    IN UINTN                        DataLength,
    IN EFI_ASYNC_USB_TRANSFER_CALLBACK IsochronousCallBack,
    IN VOID                          *Context          OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI USB IO PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>DeviceEndpoint</i>	The destination USB device endpoint to which the device request is being sent. <i>DeviceEndpoint</i> must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not an ISOCHRONOUS endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.
<i>Data</i>	A pointer to the buffer of data that will be transmitted to USB device or received from USB device.
<i>DataLength</i>	Specifies the length, in bytes, of the data to be sent to or received from the USB device.
<i>Context</i>	Data passed to the IsochronousCallback() function. This is an optional parameter and may be NULL.
<i>IsochronousCallBack</i>	The IsochronousCallback() function. This function is called if the requested isochronous transfer is completed. See the “Related Definitions” section of the UsbAsyncInterruptTransfer() function description.

Description

This is an asynchronous type of USB isochronous transfer. If the caller submits a USB isochronous transfer request through this function, this function will return immediately. When the isochronous transfer completes, the [IsochronousCallback\(\)](#) function will be triggered, the caller can

know the transfer results. If the transfer is successful, the caller can get the data received or sent in this callback function.

Status Code Returned

EFI_SUCCESS	The asynchronous isochronous transfer has been successfully submitted to the system.
EFI_INVALID_PARAMETER	The parameter <i>DeviceEndpoint</i> is not valid.
EFI_OUT_OF_RESOURCES	The request could not be submitted due to a lack of resources.
EFI_UNSUPPORTED	The implementation doesn't support an asynchronous Isochronous transfer function.

EFI_USB_IO_PROTOCOL.UsbGetDeviceDescriptor()

Summary

Retrieves the USB Device Descriptor.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_DEVICE_DESCRIPTOR) (
    IN  EFI_USB_IO_PROTOCOL      *This,
    OUT EFI_USB_DEVICE_DESCRIPTOR *DeviceDescriptor
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>DeviceDescriptor</i>	A pointer to the caller allocated USB Device Descriptor. See “Related Definitions” for a detailed description.

Related Definitions

```
//
// See USB1.1 for detail description.
//
typedef struct {
    UINT8    Length;
    UINT8    DescriptorType;
    UINT16   BcdUSB;
    UINT8    DeviceClass;
    UINT8    DeviceSubClass;
    UINT8    DeviceProtocol;
    UINT8    MaxPacketSize0;
    UINT16   IdVendor;
    UINT16   IdProduct;
    UINT16   BcdDevice;
    UINT8    StrManufacturer;
    UINT8    StrProduct;
    UINT8    StrSerialNumber;
    UINT8    NumConfigurations;
} EFI_USB_DEVICE_DESCRIPTOR;
```

Description

This function is used to retrieve information about USB devices. This information includes the device class, subclass, and the number of configurations the USB device supports. If *DeviceDescriptor* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If the USB

device descriptor is not found, then **EFI_NOT_FOUND** is returned. Otherwise, the device descriptor is returned in *DeviceDescriptor*, and **EFI_SUCCESS** is returned.

Status Code Returned

EFI_SUCCESS	The device descriptor was retrieved successfully.
EFI_INVALID_PARAMETER	DeviceDescriptor is NULL.
EFI_NOT_FOUND	The device descriptor was not found. The device may not be configured.

EFI_USB_IO_PROTOCOL.UsbGetConfigDescriptor()

Summary

Retrieves the USB Device Configuration Descriptor.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_USB_IO_GET_CONFIG_DESCRIPTOR) (
    IN  EFI_USB_IO_PROTOCOL      *This,
    OUT EFI_USB_CONFIG_DESCRIPTOR *ConfigurationDescriptor
);
```

Parameters

This A pointer to the [EFI_USB_IO_PROTOCOL](#) instance. Type [EFI_USB_IO_PROTOCOL](#) is defined in [Section 16.2.4](#).

ConfigurationDescriptor A pointer to the caller allocated USB Active Configuration Descriptor. See “Related Definitions” for a detailed description.

Related Definitions

```
//
// See USB1.1 for detail description.
//
typedef struct {
    UINT8    Length;
    UINT8    DescriptorType;
    UINT16   TotalLength;
    UINT8    NumInterfaces;
    UINT8    ConfigurationValue;
    UINT8    Configuration;
    UINT8    Attributes;
    UINT8    MaxPower;
} EFI_USB_CONFIG_DESCRIPTOR;
```

Description

This function is used to retrieve the active configuration that the USB device is currently using. If *ConfigurationDescriptor* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If the USB controller does not contain an active configuration, then **EFI_NOT_FOUND** is returned. Otherwise, the active configuration is returned in *ConfigurationDescriptor*, and **EFI_SUCCESS** is returned.

Status Code Returned

EFI_SUCCESS	The active configuration descriptor was retrieved successfully.
EFI_INVALID_PARAMETER	ConfigurationDescriptor is NULL.
EFI_NOT_FOUND	An active configuration descriptor cannot be found. The device may not be configured.

EFI_USB_IO_PROTOCOL.UsbGetInterfaceDescriptor()

Summary

Retrieves the Interface Descriptor for a USB Device Controller. As stated earlier, an interface within a USB device is equivalent to a USB Controller within the current configuration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_INTERFACE_DESCRIPTOR) (
    IN  EFI_USB_IO_PROTOCOL      *This,
    OUT EFI_USB_INTERFACE_DESCRIPTOR *InterfaceDescriptor
);
```

Parameters

This A pointer to the [EFI_USB_IO_PROTOCOL](#) instance. Type [EFI_USB_IO_PROTOCOL](#) is defined in [Section 16.2.4](#).

InterfaceDescriptor A pointer to the caller allocated USB Interface Descriptor within the configuration setting. See “Related Definitions” for a detailed description.

Related Definitions

```
//
// See USB1.1 for detail description.
//
typedef struct {
    UINT8 Length;
    UINT8 DescriptorType;
    UINT8 InterfaceNumber;
    UINT8 AlternateSetting;
    UINT8 NumEndpoints;
    UINT8 InterfaceClass;
    UINT8 InterfaceSubClass;
    UINT8 InterfaceProtocol;
    UINT8 Interface;
} EFI_USB_INTERFACE_DESCRIPTOR;
```

Description

This function is used to retrieve the interface descriptor for the USB controller. If *InterfaceDescriptor* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If the USB controller does not contain an interface descriptor, then **EFI_NOT_FOUND** is returned. Otherwise, the interface descriptor is returned in *InterfaceDescriptor*, and **EFI_SUCCESS** is returned.

Status Code Returned

EFI_SUCCESS	The interface descriptor retrieved successfully.
EFI_INVALID_PARAMETER	InterfaceDescriptor is NULL .
EFI_NOT_FOUND	The interface descriptor cannot be found. The device may not be correctly configured.

EFI_USB_IO_PROTOCOL.UsbGetEndpointDescriptor()

Summary

Retrieves an Endpoint Descriptor within a USB Controller.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_ENDPOINT_DESCRIPTOR) (
    IN  EFI_USB_IO_PROTOCOL      *This,
    IN  UINT8                    EndpointIndex,
    OUT EFI_USB_ENDPOINT_DESCRIPTOR *EndpointDescriptor
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>EndpointIndex</i>	Indicates which endpoint descriptor to retrieve. The valid range is 0..15.
<i>EndpointDescriptor</i>	A pointer to the caller allocated USB Endpoint Descriptor of a USB controller. See “Related Definitions” for a detailed description.

Related Definitions

```
//
// See USB1.1 for detail description.
//
typedef struct {
    UINT8    Length;
    UINT8    DescriptorType;
    UINT8    EndpointAddress;
    UINT8    Attributes;
    UINT16   MaxPacketSize;
    UINT8    Interval;
} EFI_USB_ENDPOINT_DESCRIPTOR;
```

Description

This function is used to retrieve an endpoint descriptor within a USB controller. If *EndpointIndex* is not in the range 0..15, then **EFI_INVALID_PARAMETER** is returned. If *EndpointDescriptor* is **NULL**, then **EFI_INVALID_PARAMETER** is returned. If the endpoint specified by *EndpointIndex* does not exist within the USB controller, then **EFI_NOT_FOUND** is returned. Otherwise, the endpoint descriptor is returned in *EndpointDescriptor*, and **EFI_SUCCESS** is returned.

Status Code Returned

EFI_SUCCESS	The endpoint descriptor was retrieved successfully.
EFI_INVALID_PARAMETER	<i>EndpointIndex</i> is not valid.
EFI_INVALID_PARAMETER	EndpointDescriptor is NULL .
EFI_NOT_FOUND	The endpoint descriptor cannot be found. The device may not be correctly configured.

Examples

The following code fragment shows how to retrieve all the endpoint descriptors from a USB controller.

```

EFI_USB_IO_PROTOCOL          *UsbIo;
EFI_USB_INTERFACE_DESCRIPTOR InterfaceDesc;
EFI_USB_ENDPOINT_DESCRIPTOR EndpointDesc;
UINTN                        Index;

Status = UsbIo->GetInterfaceDescriptor (
    UsbIo,
    &InterfaceDesc
);

. . .
for(Index = 0; Index < InterfaceDesc.NumEndpoints; Index++) {
    Status = UsbIo->GetEndpointDescriptor(
        UsbIo,
        Index,
        &EndpointDesc
    );

    . . .
}

```

EFI_USB_IO_PROTOCOL.UsbGetStringDescriptor()

Summary

Retrieves a Unicode string stored in a USB Device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_STRING_DESCRIPTOR) (
    IN  EFI_USB_IO_PROTOCOL  *This,
    IN  UINT16                LangID,
    IN  UINT8                 StringID,
    OUT CHAR16                **String
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>LangID</i>	The Language ID for the string being retrieved. See the UsbGetSupportedLanguages () function description for a more detailed description.
<i>StringID</i>	The ID of the string being retrieved.
<i>String</i>	A pointer to a buffer allocated by this function with AllocatePool () to store the string. If this function returns EFI_SUCCESS , it stores the string the caller wants to get. The caller should release the string buffer with FreePool () after the string is not used any more.

Description

This function is used to retrieve strings stored in a USB device. Strings are stored in a Unicode format. The string to retrieve is identified by a language and an identifier. The language is specified by *LangID*, and the identifier is specified by *StringID*. If the string is found, it is returned in *String*, and [EFI_SUCCESS](#) is returned. If the string cannot be found, then [EFI_NOT_FOUND](#) is returned. The string buffer is allocated by this function with [AllocatePool \(\)](#). The caller is responsible for calling [FreePool \(\)](#) for *String* when it is no longer required.

Status Code Returned

EFI_SUCCESS	The string was retrieved successfully.
EFI_NOT_FOUND	The string specified by <i>LangID</i> and <i>StringID</i> was not found.
EFI_OUT_OF_RESOURCES	There are not enough resources to allocate the return buffer <i>String</i> .

EFI_USB_IO_PROTOCOL.UsbGetSupportedLanguages()

Summary

Retrieves all the language ID codes that the USB device supports.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_SUPPORTED_LANGUAGES) (
    IN EFI_USB_IO_PROTOCOL *This,
    OUT UINT16              **LangIDTable,
    OUT UINT16              *TableSize
);
```

Parameters

<i>This</i>	A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in Section 16.2.4 .
<i>LangIDTable</i>	Language ID for the string the caller wants to get. This is a 16-bit ID defined by Microsoft. This buffer pointer is allocated and maintained by the USB Bus Driver, the caller should not modify its contents.
<i>TableSize</i>	The size, in bytes, of the table <i>LangIDTable</i> .

Description

Retrieves all the language ID codes that the USB device supports.

Status Code Returned

EFI_SUCCESS	The support languages were retrieved successfully.
-------------	--

EFI_USB_IO_PROTOCOL.UsbPortReset()

Summary

Resets and reconfigures the USB controller. This function will work for all USB devices except USB Hub Controllers.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_USB_IO_PORT_RESET) (
    IN EFI_USB_IO_PROTOCOL *This
);
```

Parameters

This

A pointer to the [EFI_USB_IO_PROTOCOL](#) instance. Type [EFI_USB_IO_PROTOCOL](#) is defined in [Section 16.2.4](#).

Description

This function provides a reset mechanism by sending a RESET signal from the parent hub port. A reconfiguration process will happen (that includes setting the address and setting the configuration). This reset function does not change the bus topology. A USB hub controller cannot be reset using this function, because it would impact the downstream USB devices. So if the controller is a USB hub controller, then [EFI_INVALID_PARAMETER](#) is returned.

Status Code Returned

EFI_SUCCESS	The USB controller was reset.
EFI_INVALID_PARAMETER	If the controller specified by <i>This</i> is a USB hub.
EFI_DEVICE_ERROR	An error occurred during the reconfiguration process.

Protocols - Debugger Support

This chapter describes a minimal set of protocols and associated data structures necessary to enable the creation of source level debuggers for EFI. It does not fully define a debugger design. Using the services described in this document, it should also be possible to implement a variety of debugger solutions.

17.1 Overview

Efficient UEFI driver and application development requires the availability of source level debugging facilities. Although completely on-target debuggers are clearly possible, UEFI debuggers are generally expected to be remotely hosted. That is to say, the debugger itself will be split between two machines, which are the host and target. A majority of debugger code runs on the host that is typically responsible for disassembly, symbol management, source display, and user interface. Similarly, a smaller piece of code runs on the target that establishes the communication to the host and proxies requests from the host. The on-target code is known as the “debug agent.”

The debug agent design is subdivided further into two parts, which are the processor/platform abstraction and the debugger host specific communication grammar. This specification describes architectural interfaces for the former only. Specific implementations for various debugger host communication grammars can be created that make use of the facilities described in this specification.

The processor/platform abstraction is presented as a pair of protocol interfaces, which are the Debug Support protocol and the Debug Port protocol.

The Debug Support protocol abstracts the processor’s debugging facilities, namely a mechanism to manage the processor’s context via caller-installable exception handlers.

The Debug Port protocol abstracts the device that is used for communication between the host and target. Typically this will be a 16550 serial port, 1394 device, or other device that is nominally a serial stream.

Furthermore, a table driven, quiescent, memory-only mechanism for determining the base address of PE32+ images is provided to enable the debugger host to determine where images are located in memory.

Aside from timing differences that occur because of running code associated with the debug agent and user initiated changes to the machine context, the operation of the on-target debugger component must be transparent to the rest of the system. In addition, no portion of the debug agent that runs in interrupt context may make any calls to EFI services or other protocol interfaces.

The services described in this document do not comprise a complete debugger, rather they provide a minimal abstraction required to implement a wide variety of debugger solutions.

17.2 EFI Debug Support Protocol

This section defines the EFI Debug Support protocol which is used by the debug agent.

17.2.1 EFI Debug Support Protocol Overview

The debug-agent needs to be able to gain control of the machine when certain types of events occur; i.e. breakpoints, processor exceptions, etc. Additionally, the debug agent must also be able to periodically gain control during operation of the machine to check for asynchronous commands from the host. The EFI Debug Support protocol services enable these capabilities.

The EFI Debug Support protocol interfaces produce callback registration mechanisms which are used by the debug agent to register functions that are invoked either periodically or when specific processor exceptions. When they are invoked by the Debug Support driver, these callback functions are passed the current machine context record. The debug agent may modify this context record to change the machine context which is restored to the machine after the callback function returns. The debug agent does not run in the same context as the rest of UEFI and all modifications to the machine context are deferred until after the callback function returns.

It is expected that there will typically be two instances of the EFI Debug Support protocol in the system. One associated with the native processor instruction set (IA-32, x64, or Itanium processor family), and one for the EFI virtual machine that implements EFI byte code (EBC).

While multiple instances of the EFI Debug Support protocol are expected, there must never be more than one for any given instruction set.

EFI_DEBUG_SUPPORT_PROTOCOL

Summary

This protocol provides the services to allow the debug agent to register callback functions that are called either periodically or when specific processor exceptions occur.

GUID

```
#define EFI_DEBUG_SUPPORT_PROTOCOL_GUID \
    { 0x275590C, 0x6F3C, 0x42FA, 0x9E, 0xA4, 0xA3, 0xBA, 0x54, 0x3C, \
      0xDA, 0x25 }
```

Protocol Interface Structure

```
typedef struct {
    EFI_INSTRUCTION_SET_ARCHITECTURE    Isa;
    EFI_GET_MAXIMUM_PROCESSOR_INDEX     GetMaximumProcessorIndex;
    EFI_REGISTER_PERIODIC_CALLBACK       RegisterPeriodicCallback;
    EFI_REGISTER_EXCEPTION_CALLBACK     RegisterExceptionCallback;
    EFI_INVALIDATE_INSTRUCTION_CACHE    InvalidateInstructionCache;
} EFI_DEBUG_SUPPORT_PROTOCOL;
```

Parameters

- Isa* Declares the processor architecture for this instance of the EFI Debug Support protocol.
- GetMaximumProcessorIndex* Returns the maximum processor index value that may be used with [EFI_DEBUG_SUPPORT_PROTOCOL.RegisterPeriodicCallback\(\)](#) and [EFI_DEBUG_SUPPORT_PROTOCOL.RegisterExceptionCallback\(\)](#). See the [EFI_DEBUG_SUPPORT_PROTOCOL.GetMaximumProcessorIndex\(\)](#) function description.
- RegisterPeriodicCallback* Registers a callback function that will be invoked periodically and asynchronously to the execution of EFI. See the [RegisterPeriodicCallback\(\)](#) function description.
- RegisterExceptionCallback* Registers a callback function that will be called each time the specified processor exception occurs. See the [RegisterExceptionCallback\(\)](#) function description.
- InvalidateInstructionCache* Invalidate the instruction cache of the processor. This is required by processor architectures where instruction and data caches are not coherent when instructions in the code under debug has been modified by the debug agent. See the [EFI_DEBUG_SUPPORT_PROTOCOL.InvalidateInstructionCache\(\)](#) function description.

Related Definitions

Refer to the Microsoft PE/COFF Specification revision 6.2 or later for `IMAGE_FILE_MACHINE` definitions.

Note: *At the time of publication of this specification, the latest revision of the PE/COFF specification was 6.2. The definition of `IMAGE_FILE_MACHINE_EBC` is not included in revision 6.2 of the PE/COFF specification. It will be added in a future revision of the PE/COFF specification.*

```
typedef enum {
    IsaIa32 = IMAGE_FILE_MACHINE_I386,    // 0x014C
    IsaX64  = IMAGE_FILE_MACHINE_X64,    // 0x8664
    IsaIpf  = IMAGE_FILE_MACHINE_IA64,   // 0x0200
    IsaEbc  = IMAGE_FILE_MACHINE_EBC     // 0x0EBC
} EFI_INSTRUCTION_SET_ARCHITECTURE
```

Description

The EFI Debug Support protocol provides the interfaces required to register debug agent callback functions and to manage the processor's instruction stream as required. Registered callback functions are invoked in interrupt context when the specified event occurs.

The driver that produces the EFI Debug Support protocol is also responsible for saving the machine context prior to invoking a registered callback function and restoring it after the callback function returns prior to returning to the code under debug. If the debug agent has modified the context record, the modified context must be used in the restore operation.

Furthermore, if the debug agent modifies any of the code under debug (to set a software breakpoint for example), it must call the **InvalidateInstructionCache()** function for the region of memory that has been modified.

EFI_DEBUG_SUPPORT_PROTOCOL.GetMaximumProcessorIndex()

Summary

Returns the maximum value that may be used for the *ProcessorIndex* parameter in [EFI_DEBUG_SUPPORT_PROTOCOL.RegisterPeriodicCallback\(\)](#) and [EFI_DEBUG_SUPPORT_PROTOCOL.RegisterExceptionCallback\(\)](#).

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_GET_MAXIMUM_PROCESSOR_INDEX) (
    IN EFI_DEBUG_SUPPORT_PROTOCOL *This,
    OUT UINTN *MaxProcessorIndex
);
```

Parameters

This A pointer to the [EFI_DEBUG_SUPPORT_PROTOCOL](#) instance. Type [EFI_DEBUG_SUPPORT_PROTOCOL](#) is defined in this section.

MaxProcessorIndex Pointer to a caller-allocated UINTN in which the maximum supported processor index is returned.

Description

The **GetMaximumProcessorIndex()** function returns the maximum processor index in the output parameter *MaxProcessorIndex*. This value is the largest value that may be used in the *ProcessorIndex* parameter for both **RegisterPeriodicCallback()** and **RegisterExceptionCallback()**. All values between 0 and *MaxProcessorIndex* must be supported by **RegisterPeriodicCallback()** and **RegisterExceptionCallback()**.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by **GetMaximumProcessorIndex()**. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
-------------	--------------------------------------

EFI_DEBUG_SUPPORT_PROTOCOL.RegisterPeriodicCallback()**Summary**

Registers a function to be called back periodically in interrupt context.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_REGISTER_PERIODIC_CALLBACK) (
    IN EFI_DEBUG_SUPPORT_PROTOCOL  *This,
    IN UINTN                       ProcessorIndex,
    IN EFI_PERIODIC_CALLBACK       PeriodicCallback
);
```

Parameters

<i>This</i>	A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in Section 17.2 .
<i>ProcessorIndex</i>	Specifies which processor the callback function applies to.
<i>PeriodicCallback</i>	A pointer to a function of type PERIODIC_CALLBACK that is the main periodic entry point of the debug agent. It receives as a parameter a pointer to the full context of the interrupted execution thread.

Related Definitions

```
typedef
VOID (*EFI_PERIODIC_CALLBACK) (
    IN OUT EFI_SYSTEM_CONTEXT  SystemContext
);

typedef union {
    EFI_SYSTEM_CONTEXT_EBC      *SystemContextEbc;
    EFI_SYSTEM_CONTEXT_IA32    *SystemContextIa32;
    EFI_SYSTEM_CONTEXT_X64     *SystemContextX64;
    EFI_SYSTEM_CONTEXT_IPF     *SystemContextIpf;
} EFI_SYSTEM_CONTEXT;

// System context for virtual EBC processors
typedef struct {
    UINT64    R0, R1, R2, R3, R4, R5, R6, R7;
    UINT64    Flags;
    UINT64    ControlFlags;
    UINT64    Ip;
} EFI_SYSTEM_CONTEXT_EBC;
```


Note: When the context record field is larger than the register being stored in it, the upper bits of the context record field are unused and ignored

```
// System context for IA-32 processors
typedef struct {
    UINT32 ExceptionData; // ExceptionData is
                        // additional data pushed
                        // on the stack by some
                        // types of IA-32
                        // exceptions

    EFI_FX_SAVE_STATE_IA32    FxSaveState;
    UINT32                    Dr0, Dr1, Dr2, Dr3, Dr6, Dr7;
    UINT32                    Cr0, Cr1 /* Reserved */, Cr2, Cr3, Cr4;
    UINT32                    Eflags;
    UINT32                    Ldtr, Tr;
    UINT32                    Gdtr[2], Idtr[2];
    UINT32                    Eip;
    UINT32                    Gs, Fs, Es, Ds, Cs, Ss;
    UINT32                    Edi, Esi, Ebp, Esp, Ebx, Edx, Ecx, Eax;
} EFI_SYSTEM_CONTEXT_IA32;

// FXSAVE_STATE - FP / MMX / XMM registers
typedef struct {
    UINT16    Fcw;
    UINT16    Fsw;
    UINT16    Ftw;
    UINT16    Opcode;
    UINT32    Eip;
    UINT16    Cs;
    UINT16    Reserved1;
    UINT32    DataOffset;
    UINT16    Ds;
    UINT8     Reserved2[10];
    UINT8     St0Mm0[10], Reserved3[6];
    UINT8     St1Mm1[10], Reserved4[6];
    UINT8     St2Mm2[10], Reserved5[6];
    UINT8     St3Mm3[10], Reserved6[6];
    UINT8     St4Mm4[10], Reserved7[6];
    UINT8     St5Mm5[10], Reserved8[6];
    UINT8     St6Mm6[10], Reserved9[6];
    UINT8     St7Mm7[10], Reserved10[6];
    UINT8     Xmm0[16];
    UINT8     Xmm1[16];
};
```

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```
    UINT8    Xmm2[16];
    UINT8    Xmm3[16];
    UINT8    Xmm4[16];
    UINT8    Xmm5[16];
    UINT8    Xmm6[16];
    UINT8    Xmm7[16];
    UINT8    Reserved11[14 * 16];
} EFI_FX_SAVE_STATE_IA32

// System context for x64 processors
typedef struct {
    UINT64    ExceptionData; // ExceptionData is
                          // additional data pushed
                          // on the stack by some
                          // types of x64 64-bit
                          // mode exceptions

    EFI_FX_SAVE_STATE_X64    FxSaveState;
    UINT64    Dr0, Dr1, Dr2, Dr3, Dr6, Dr7;
    UINT64    Cr0, Cr1 /* Reserved */, Cr2, Cr3, Cr4, Cr8;
    UINT64    Rflags;
    UINT64    Ldtr, Tr;
    UINT64    Gdtr[2], Idtr[2];
    UINT64    Rip;
    UINT64    Gs, Fs, Es, Ds, Cs, Ss;
    UINT64    Rdi, Rsi, Rbp, Rsp, Rbx, Rdx, Rcx, Rax;
    UINT64    R8, R9, R10, R11, R12, R13, R14, R15;
} EFI_SYSTEM_CONTEXT_X64;

// FXSAVE_STATE - FP / MMX / XMM registers
typedef struct {
    UINT16    Fcw;
    UINT16    Fsw;
    UINT16    Ftw;
    UINT16    Opcode;
    UINT64    Rip;
    UINT64    DataOffset;
    UINT8    Reserved1[8];
    UINT8    St0Mm0[10], Reserved2[6];
    UINT8    St1Mm1[10], Reserved3[6];
    UINT8    St2Mm2[10], Reserved4[6];
    UINT8    St3Mm3[10], Reserved5[6];
    UINT8    St4Mm4[10], Reserved6[6];
    UINT8    St5Mm5[10], Reserved7[6];
}
```

```

UINT8                St6Mm6[10], Reserved8[6];
UINT8                St7Mm7[10], Reserved9[6];
UINT8                Xmm0[16];
UINT8                Xmm1[16];
UINT8                Xmm2[16];
UINT8                Xmm3[16];
UINT8                Xmm4[16];
UINT8                Xmm5[16];
UINT8                Xmm6[16];
UINT8                Xmm7[16];
UINT8                Reserved11[14 * 16];
} EFI_FX_SAVE_STATE_X64;

// System context for Itanium processor family
typedef struct {
    UINT64 Reserved;

    UINT64 R1, R2, R3, R4, R5, R6, R7, R8, R9, R10,
        R11, R12, R13, R14, R15, R16, R17, R18, R19, R20,
        R21, R22, R23, R24, R25, R26, R27, R28, R29, R30,
        R31;

    UINT64 F2[2], F3[2], F4[2], F5[2], F6[2],
        F7[2], F8[2], F9[2], F10[2], F11[2],
        F12[2], F13[2], F14[2], F15[2], F16[2],
        F17[2], F18[2], F19[2], F20[2], F21[2],
        F22[2], F23[2], F24[2], F25[2], F26[2],
        F27[2], F28[2], F29[2], F30[2], F31[2];

    UINT64 Pr;

    UINT64 B0, B1, B2, B3, B4, B5, B6, B7;

    // application registers
    UINT64 ArRsc, ArBsp, ArBspstore, ArRnat;
    UINT64 ArFcr;
    UINT64 ArEflag, ArCsd, ArSsd, ArCflg;
    UINT64 ArFsr, ArFir, ArFdr;
    UINT64 ArCcv;
    UINT64 ArUnat;
    UINT64 ArFpsr;

```

```

UINT64 ArPfs, ArLc, ArEc;

// control registers
UINT64 CrDcr, CrItm, CrIva, CrPta, CrIpsr, CrIsr;
UINT64 CrIip, CrIfa, CrItir, CrIipa, CrIfs, CrIim;
UINT64 CrIha;

// debug registers
UINT64 Dbr0, Dbr1, Dbr2, Dbr3, Dbr4, Dbr5, Dbr6, Dbr7;
UINT64 Ibr0, Ibr1, Ibr2, Ibr3, Ibr4, Ibr5, Ibr6, Ibr7;

// virtual registers
UINT64 IntNat;// nat bits for R1-R31

} EFI_SYSTEM_CONTEXT_IPF;

```

Description

The **RegisterPeriodicCallback()** function registers and enables the on-target debug agent’s periodic entry point. To unregister and disable calling the debug agent’s periodic entry point, call **RegisterPeriodicCallback()** passing a **NULL** *PeriodicCallback* parameter.

The implementation must handle saving and restoring the processor context to/from the system context record around calls to the registered callback function.

If the interrupt is also used by the firmware for the EFI time base or some other use, two rules must be observed. First, the registered callback function must be called before any EFI processing takes place. Second, the Debug Support implementation must perform the necessary steps to pass control to the firmware’s corresponding interrupt handler in a transparent manner.

There is no quality of service requirement or specification regarding the frequency of calls to the registered *PeriodicCallback* function. This allows the implementation to mitigate a potential adverse impact to EFI timer based services due to the latency induced by the context save/restore and the associated callback function.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by **RegisterPeriodicCallback()**. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_ALREADY_STARTED	Non- NULL <i>PeriodicCallback</i> parameter when a callback function was previously registered.
EFI_OUT_OF_RESOURCES	System has insufficient memory resources to register new callback function.

EFI_DEBUG_SUPPORT_PROTOCOL.RegisterExceptionCallback()

Summary

Registers a function to be called when a given processor exception occurs.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *REGISTER_EXCEPTION_CALLBACK) (
    IN EFI_DEBUG_SUPPORT_PROTOCOL *This,
    IN UINTN ProcessorIndex,
    IN EFI_EXCEPTION_CALLBACK ExceptionCallback,
    IN EFI_EXCEPTION_TYPE ExceptionType
);
```

Parameters

<i>This</i>	A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in Section 17.2 .
<i>ProcessorIndex</i>	Specifies which processor the callback function applies to.
<i>ExceptionCallback</i>	A pointer to a function of type EXCEPTION_CALLBACK that is called when the processor exception specified by <i>ExceptionType</i> occurs. Passing NULL unregisters any previously registered function associated with <i>ExceptionType</i> .
<i>ExceptionType</i>	Specifies which processor exception to hook.

Related Definitions

```
typedef
VOID (*EFI_EXCEPTION_CALLBACK) (
    IN EFI_EXCEPTION_TYPE ExceptionType,
    IN OUT EFI_SYSTEM_CONTEXT SystemContext
);

typedef INTN EFI_EXCEPTION_TYPE;

// EBC Exception types
#define EXCEPT_EBC_UNDEFINED 0
#define EXCEPT_EBC_DIVIDE_ERROR 1
#define EXCEPT_EBC_DEBUG 2
#define EXCEPT_EBC_BREAKPOINT 3
#define EXCEPT_EBC_OVERFLOW 4
#define EXCEPT_EBC_INVALID_OPCODE 5
#define EXCEPT_EBC_STACK_FAULT 6
```

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```
#define EXCEPT_EBC_ALIGNMENT_CHECK 7
#define EXCEPT_EBC_INSTRUCTION_ENCODING 8
#define EXCEPT_EBC_BAD_BREAK 9
#define EXCEPT_EBC_SINGLE_STEP 10

// IA-32 Exception types
#define EXCEPT_IA32_DIVIDE_ERROR 0
#define EXCEPT_IA32_DEBUG 1
#define EXCEPT_IA32_NMI 2
#define EXCEPT_IA32_BREAKPOINT 3
#define EXCEPT_IA32_OVERFLOW 4
#define EXCEPT_IA32_BOUND 5
#define EXCEPT_IA32_INVALID_OPCODE 6
#define EXCEPT_IA32_DOUBLE_FAULT 8
#define EXCEPT_IA32_INVALID_TSS 10
#define EXCEPT_IA32_SEG_NOT_PRESENT 11
#define EXCEPT_IA32_STACK_FAULT 12
#define EXCEPT_IA32_GP_FAULT 13
#define EXCEPT_IA32_PAGE_FAULT 14
#define EXCEPT_IA32_FP_ERROR 16
#define EXCEPT_IA32_ALIGNMENT_CHECK 17
#define EXCEPT_IA32_MACHINE_CHECK 18
#define EXCEPT_IA32_SIMD 19

//
// X64 Exception types
//
#define EXCEPT_X64_DIVIDE_ERROR 0
#define EXCEPT_X64_DEBUG 1
#define EXCEPT_X64_NMI 2
#define EXCEPT_X64_BREAKPOINT 3
#define EXCEPT_X64_OVERFLOW 4
#define EXCEPT_X64_BOUND 5
#define EXCEPT_X64_INVALID_OPCODE 6
#define EXCEPT_X64_DOUBLE_FAULT 8
#define EXCEPT_X64_INVALID_TSS 10
#define EXCEPT_X64_SEG_NOT_PRESENT 11
#define EXCEPT_X64_STACK_FAULT 12
#define EXCEPT_X64_GP_FAULT 13
#define EXCEPT_X64_PAGE_FAULT 14
#define EXCEPT_X64_FP_ERROR 16
#define EXCEPT_X64_ALIGNMENT_CHECK 17
#define EXCEPT_X64_MACHINE_CHECK 18
```

```

#define EXCEPT_X64_SIMD 19

// Itanium Processor Family Exception types
#define EXCEPT_IPF_VHTP_TRANSLATION 0
#define EXCEPT_IPF_INSTRUCTION_TLB 1
#define EXCEPT_IPF_DATA_TLB 2
#define EXCEPT_IPF_ALT_INSTRUCTION_TLB 3
#define EXCEPT_IPF_ALT_DATA_TLB 4
#define EXCEPT_IPF_DATA_NESTED_TLB 5
#define EXCEPT_IPF_INSTRUCTION_KEY_MISSED 6
#define EXCEPT_IPF_DATA_KEY_MISSED 7
#define EXCEPT_IPF_DIRTY_BIT 8
#define EXCEPT_IPF_INSTRUCTION_ACCESS_BIT 9
#define EXCEPT_IPF_DATA_ACCESS_BIT 10
#define EXCEPT_IPF_BREAKPOINT 11
#define EXCEPT_IPF_EXTERNAL_INTERRUPT 12
// 13 - 19 reserved
#define EXCEPT_IPF_PAGE_NOT_PRESENT 20
#define EXCEPT_IPF_KEY_PERMISSION 21
#define EXCEPT_IPF_INSTRUCTION_ACCESS_RIGHTS 22
#define EXCEPT_IPF_DATA_ACCESS_RIGHTS 23
#define EXCEPT_IPF_GENERAL_EXCEPTION 24
#define EXCEPT_IPF_DISABLED_FP_REGISTER 25
#define EXCEPT_IPF_NAT_CONSUMPTION 26
#define EXCEPT_IPF_SPECULATION 27
// 28 reserved
#define EXCEPT_IPF_DEBUG 29
#define EXCEPT_IPF_UNALIGNED_REFERENCE 30
#define EXCEPT_IPF_UNSUPPORTED_DATA_REFERENCE 31
#define EXCEPT_IPF_FP_FAULT 32
#define EXCEPT_IPF_FP_TRAP 33
#define EXCEPT_IPF_LOWER_PRIVILEGE_TRANSFER_TRAP 34
#define EXCEPT_IPF_TAKEN_BRANCH 35
#define EXCEPT_IPF_SINGLE_STEP 36
// 37 - 44 reserved
#define EXCEPT_IPF_IA32_EXCEPTION 45
#define EXCEPT_IPF_IA32_INTERCEPT 46
#define EXCEPT_IPF_IA32_INTERRUPT 47

```

Description

The **RegisterExceptionCallback()** function registers and enables an exception callback function for the specified exception. The specified exception must be valid for the instruction set

architecture. To unregister the callback function and stop servicing the exception, call **RegisterExceptionCallback ()** passing a **NULL** *ExceptionCallback* parameter.

The implementation must handle saving and restoring the processor context to/from the system context record around calls to the registered callback function. No chaining of exception handlers is allowed.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by **RegisterExceptionCallback ()**. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_ALREADY_STARTED	Non- NULL <i>ExceptionCallback</i> parameter when a callback function was previously registered.
EFI_OUT_OF_RESOURCES	System has insufficient memory resources to register new callback function.

EFI_DEBUG_SUPPORT_PROTOCOL.InvalidateInstructionCache()

Summary

Invalidates processor instruction cache for a memory range. Subsequent execution in this range causes a fresh memory fetch to retrieve code to be executed.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_INVALIDATE_INSTRUCTION_CACHE) (
    IN EFI_DEBUG_SUPPORT_PROTOCOL  *This,
    IN UINTN                       ProcessorIndex,
    IN VOID                        *Start,
    IN UINT64                      Length
);
```

Parameters

<i>This</i>	A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in Section 17.2 .
<i>ProcessorIndex</i>	Specifies which processor's instruction cache is to be invalidated.
<i>Start</i>	Specifies the physical base of the memory range to be invalidated.
<i>Length</i>	Specifies the minimum number of bytes in the processor's instruction cache to invalidate.

Description

Typical operation of a debugger may require modifying the code image that is under debug. This can occur for many reasons, but is typically done to insert/remove software break instructions. Some processor architectures do not have coherent instruction and data caches so modifications to the code image require that the instruction cache be explicitly invalidated in that memory region.

The **InvalidateInstructionCache()** function abstracts this operation from the debug agent and provides a general purpose capability to invalidate the processor's instruction cache.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by

[EFI_DEBUG_SUPPORT_PROTOCOL.RegisterExceptionHandler\(\)](#). The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
-------------	--------------------------------------

17.3 EFI Debugport Protocol

This section defines the EFI Debugport protocol. This protocol is used by debug agent to communicate with the remote debug host.

17.3.1 EFI Debugport Overview

Historically, remote debugging has typically been done using a standard UART serial port to connect the host and target. This is obviously not possible in a legacy reduced system that does not have a UART. The Debugport protocol solves this problem by providing an abstraction that can support many different types of debugport hardware. The debug agent should use this abstraction to communicate with the host.

The interface is minimal with only reset, read, write, and poll abstractions. Since these functions are called in interrupt context, none of them may call any EFI services or other protocol interfaces.

Debugport selection and configuration is handled by setting defaults via an environment variable which contains a full device path to the debug port. This environment variable is used during the debugport driver's initialization to configure the debugport correctly. The variable contains a full device path to the debugport, with the last node (prior to the terminal node) being a debugport messaging node. See [Section 17.3.2](#) for details.

The driver must also produce an instance of the EFI Device Path protocol to indicate what hardware is being used for the debugport. This may be used by the OS to maintain the debugport across a call to [ExitBootServices\(\)](#).

EFI_DEBUGPORT_PROTOCOL

Summary

This protocol provides the communication link between the debug agent and the remote host.

GUID

```
#define EFI_DEBUGPORT_PROTOCOL_GUID \
  {0xEBA4E8D2, 0x3858, 0x41EC, 0xA2, 0x81, 0x26, 0x47, 0xBA, 0x96, \
   0x60, 0xD0}
```

Protocol Interface Structure

```
typedef struct {
  EFI_DEBUGPORT_RESET      Reset;
  EFI_DEBUGPORT_WRITE      Write;
  EFI_DEBUGPORT_READ       Read;
  EFI_DEBUGPORT_POLL       Poll;
} EFI_DEBUGPORT_PROTOCOL;
```

Parameters

<i>Reset</i>	Resets the debugport hardware.
<i>Write</i>	Send a buffer of characters to the debugport device.
<i>Read</i>	Receive a buffer of characters from the debugport device.
<i>Poll</i>	Determine if there is any data available to be read from the debugport device.

Description

The Debugport protocol is used for byte stream communication with a debugport device. The debugport can be a standard UART Serial port, a USB-based character device, or potentially any character-based I/O device.

The attributes for all UART-style debugport device interfaces are defined in the DEBUGPORT variable (see [Section 17.3.2](#)).

EFI_DEBUGPORT_PROTOCOL.Reset()

Summary

Resets the debugport.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DEBUGPORT_RESET) (
    IN EFI_DEBUGPORT_PROTOCOL      *This
);
```

Parameters

This

A pointer to the [EFI_DEBUGPORT_PROTOCOL](#) instance. Type [EFI_DEBUGPORT_PROTOCOL](#) is defined in [Section 17.3](#).

Description

The **Reset ()** function resets the debugport device.

It is the responsibility of the caller to insure all parameters are valid. There is no provision for parameter checking by **Reset ()**. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The debugport device was reset and is in usable state.
EFI_DEVICE_ERROR	The debugport device could not be reset and is unusable.

EFI_DEBUGPORT_PROTOCOL.Write()

Summary

Writes data to the debugport.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_DEBUGPORT_WRITE) (
    IN EFI_DEBUGPORT_PROTOCOL      *This,
    IN UINT32                       Timeout,
    IN OUT UINTN                    *BufferSize,
    IN VOID                         *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_DEBUGPORT_PROTOCOL instance. Type EFI_DEBUGPORT_PROTOCOL is defined in Section 17.3 .
<i>Timeout</i>	The number of microseconds to wait before timing out a write operation.
<i>BufferSize</i>	On input, the requested number of bytes of data to write. On output, the number of bytes of data actually written.
<i>Buffer</i>	A pointer to a buffer containing the data to write.

Description

The **Write()** function writes the specified number of bytes to a debugport device. If a timeout error occurs while data is being sent to the debugport, transmission of this buffer will terminate, and **EFI_TIMEOUT** will be returned. In all cases the number of bytes actually written to the debugport device is returned in *BufferSize*.

It is the responsibility of the caller to insure all parameters are valid. There is no provision for parameter checking by **Write()**. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The data was written.
EFI_DEVICE_ERROR	The device reported an error.
EFI_TIMEOUT	The data write was stopped due to a timeout.

EFI_DEBUGPORT_PROTOCOL.Read()

Summary

Reads data from the debugport.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DEBUGPORT_READ) (
    IN EFI_DEBUGPORT_PROTOCOL      *This,
    IN UINT32                       Timeout,
    IN OUT UINTN                    *BufferSize,
    OUT VOID                        *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI_DEBUGPORT_PROTOCOL instance. Type EFI_DEBUGPORT_PROTOCOL is defined in Section 17.3 .
<i>Timeout</i>	The number of microseconds to wait before timing out a read operation.
<i>BufferSize</i>	A pointer to an integer which, on input contains the requested number of bytes of data to read, and on output contains the actual number of bytes of data read and returned in <i>Buffer</i> .
<i>Buffer</i>	A pointer to a buffer into which the data read will be saved.

Description

The **Read()** function reads a specified number of bytes from a debugport. If a timeout error or an overrun error is detected while data is being read from the debugport, then no more characters will be read, and **EFI_TIMEOUT** will be returned. In all cases the number of bytes actually read is returned in **BufferSize*.

It is the responsibility of the caller to insure all parameters are valid. There is no provision for parameter checking by **Read()**. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

EFI_SUCCESS	The data was read.
EFI_DEVICE_ERROR	The debugport device reported an error.
EFI_TIMEOUT	The operation was stopped due to a timeout or overrun.

EFI_DEBUGPORT_PROTOCOL.Poll()

Summary

Checks to see if any data is available to be read from the debugport device.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_DEBUGPORT_POLL) (
    IN EFI_DEBUGPORT_PROTOCOL      *This
);
```

Parameters

This A pointer to the [EFI_DEBUGPORT_PROTOCOL](#) instance. Type [EFI_DEBUGPORT_PROTOCOL](#) is defined in [Section 17.3](#).

Description

The **Poll()** function checks if there is any data available to be read from the debugport device and returns the result. No data is actually removed from the input stream. This function enables simpler debugger design since buffering of reads is not necessary by the caller.

Status Codes Returned

EFI_SUCCESS	At least one byte of data is available to be read.
EFI_NOT_READY	No data is available to be read.
EFI_DEVICE_ERROR	The debugport device is not functioning correctly.

17.3.2 Debugport Device Path

The debugport driver must establish and maintain an instance of the EFI Device Path protocol for the debugport. A graceful handoff of debugport ownership between the EFI Debugport driver and an OS debugport driver requires that the OS debugport driver can determine the type, location, and configuration of the debugport device.

The Debugport Device Path is a vendor-defined messaging device path with no data, only a GUID. It is used at the end of a conventional device path to tag the device for use as the debugport. For example, a typical UART debugport would have the following fully qualified device path:

```
PciRoot(0)/Pci(0x1f,0)/ACPI(PNP0501,0)/UART(115200,N,8,1)/
DebugPort()
```

The Vendor_GUID that defines the debugport device path is the same as the debugport protocol GUID, as defined below.

```
#define DEVICE_PATH_MESSAGING_DEBUGPORT \
    EFI_DEBUGPORT_PROTOCOL_GUID
```

[Table 115](#) shows all fields of the debugport device path.

Table 115. Debugport Messaging Device Path

Mnemonic	Byte Offset	Byte Length	Description
Type	0	1	Type 3 – Messaging Device Path.
Sub Type	1	1	Sub Type 10 – Vendor.
Length	2	2	Length of this structure in bytes. Length is 20 bytes.
Vendor_GUID	4	16	DEVICE_PATH_MESSAGING_DEBUGPORT.

17.3.3 EFI Debugport Variable

Even though there may be more than one hardware device that could function as a debugport in a system, only one debugport may be active at a time. The DEBUGPORT variable is used to declare which hardware device will act as the debugport, and what communication parameters it should assume.

Like all EFI variables, the DEBUGPORT variable has both a name and a GUID. The name is “DEBUGPORT.” The GUID is the same as the **EFI_DEBUGPORT_PROTOCOL_GUID**:

```
#define EFI_DEBUGPORT_VARIABLE_NAME L"DEBUGPORT"
#define EFI_DEBUGPORT_VARIABLE_GUID EFI_DEBUGPORT_PROTOCOL_GUID
```

The data contained by the DEBUGPORT variable is a fully qualified debugport device path (see [Section 17.3.2](#)).

The desired communication parameters for the debugport are declared in the DEBUGPORT variable. The debugport driver must read this variable during initialization to determine how to configure the debug port.

To reduce the required complexity of the debugport driver, the debugport driver is not required to support all possible combinations of communication parameters. What combinations of parameters are possible is implementation specific.

Additionally debugport drivers implemented for PNP0501 devices, that is debugport devices with a PNP0501 ACPI node in the device path, must support the following defaults. These defaults must be used in the absence of a DEBUGPORT variable, or when the communication parameters specified in the DEBUGPORT variable are not supported by the driver.

- Baud : 115200
- 8 data bits
- No parity
- 1 stop bit
- No flow control (See Appendix A for flow control details)

In the absence of the DEBUGPORT variable, the selection of which port to use as the debug port is implementation specific.

Future revisions of this specification may define new defaults for other debugport types.

The debugport device path must be constructed to reflect the actual settings for the debugport. Any code needing to know the state of the debug port must reference the device path rather than the

DEBUGPORT variable, since the debugport may have assumed a default setting in spite of the existence of the DEBUGPORT variable.

If it is not possible to configure the debug port using either the settings declared in the DEBUGPORT variable or the default settings for the particular debugport type, the driver initialization must not install any protocol interfaces and must exit with an error.

17.4 EFI Debug Support Table

This chapter defines the EFI Debug Support Table which is used by the debug agent or an external debugger to determine loaded image information in a quiescent manner.

17.4.1 Overview

Every executable image loaded in EFI is represented by an EFI handle populated with an instance of the [EFI LOADED IMAGE PROTOCOL](#). This handle is known as an “image handle.” The associated Loaded Image protocol provides image information that is of interest to a source level debugger. Normal EFI executables can access this information by using EFI services to locate all instances of the Loaded Image protocol.

A debugger has two problems with this scenario. First, if it is an external hardware debugger, the location of the EFI system table is not known. Second, even if the location of the EFI system table is known, the services contained therein are generally unavailable to a debugger either because it is an on-target debugger that is running in interrupt context, or in the case of an external hardware debugger there is no debugger code running on the target at all.

Since a source level debugger must be capable of determining image information for all loaded images, an alternate mechanism that does not use EFI services must be provided. Two features are added to the EFI system software to enable this capability.

First, an alternate mechanism of locating the EFI system table is required. A check-summed structure containing the physical address of the EFI system table is created and located on a 4M aligned memory address. A hardware debugger can search memory for this structure to determine the location of the EFI system table.

Second, an [EFI_CONFIGURATION_TABLE](#) is published that leads to a database of pointers to all instances of the Loaded Image protocol. Several layers of indirection are used to allow dynamically managing the data as images are loaded and unloaded. Once the address of the EFI system table is known, it is possible to discover a complete and accurate list of EFI images. (Note that the EFI core itself must be represented by an instance of the Loaded Image protocol.)

[Figure 48](#) illustrates the table indirection and pointer usage.

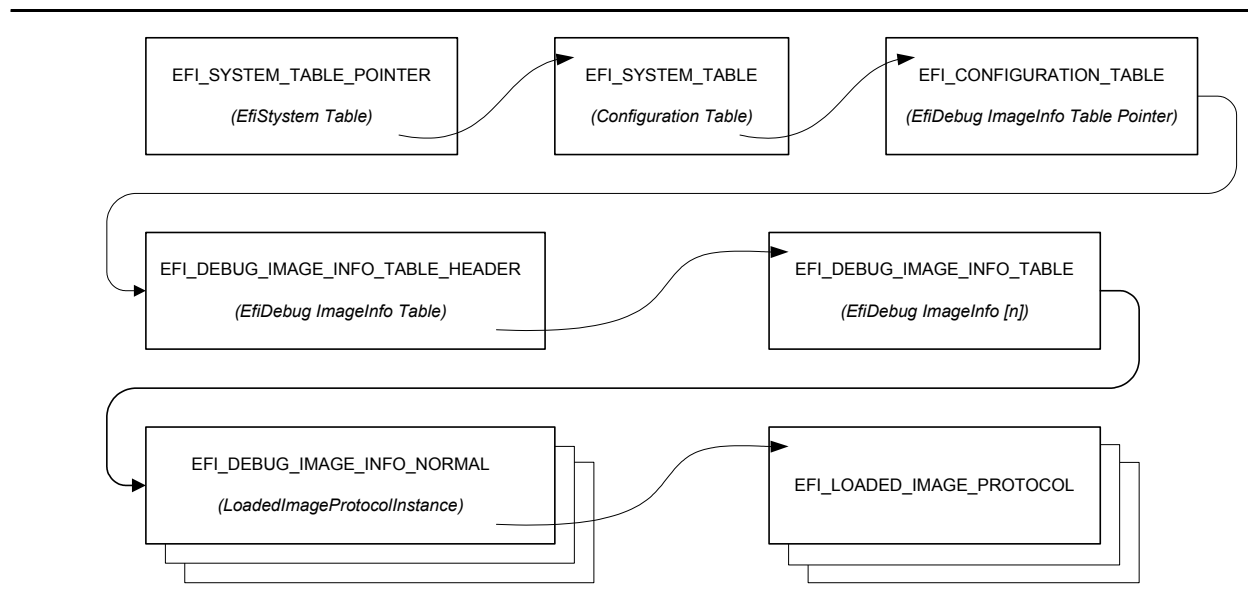


Figure 48. Debug Support Table Indirection and Pointer Usage

17.4.2 EFI System Table Location

The EFI system table can be located by an off-target hardware debugger by searching for the **EFI_SYSTEM_TABLE_POINTER** structure. The **EFI_SYSTEM_TABLE_POINTER** structure is located on a 4M boundary as close to the top of physical memory as feasible. It may be found searching for the **EFI_SYSTEM_TABLE_SIGNATURE** on each 4M boundary starting at the top of memory and scanning down. When the signature is found, the entire structure must be verified using the *Crc32* field. The 32-bit CRC of the entire structure is calculated assuming the *Crc32* field is zero. This value is then written to the *Crc32* field.

```
typedef struct _EFI_SYSTEM_TABLE_POINTER {
    UINT64          Signature;
    EFI_PHYSICAL_ADDRESS EfiSystemTableBase;
    UINT32          Crc32;
} EFI_SYSTEM_TABLE_POINTER;
```

- Signature* A constant **UINT64** that has the value **EFI_SYSTEM_TABLE_SIGNATURE** (see the EFI 1.0 specification).
- EfiSystemTableBase* The physical address of the EFI system table.
- Crc32* A 32-bit CRC value that is used to verify the **EFI_SYSTEM_TABLE_POINTER** structure is valid.

17.4.3 EFI Image Info

The **EFI_DEBUG_IMAGE_INFO_TABLE** is an array of pointers to **EFI_DEBUG_IMAGE_INFO** unions. Each member of an **EFI_DEBUG_IMAGE_INFO** union is a pointer to a data structure

representing a particular image type. For each image that has been loaded, there is an appropriate image data structure with a pointer to it stored in the **EFI_DEBUG_IMAGE_INFO_TABLE**. Data structures for normal images and SMM images are defined. All other image types are reserved for future use.

The process of locating the **EFI_DEBUG_IMAGE_INFO_TABLE** begins with an EFI configuration table.

```
//
// EFI_DEBUG_IMAGE_INFO_TABLE configuration table
// GUID declaration - {49152E77-1ADA-4764-B7A2-7AFEFED95E8B}
//
#define EFI_DEBUG_IMAGE_INFO_TABLE_GUID \
{0x49152E77, 0x1ADA, 0x4764, 0xB7, 0xA2, 0x7A, 0xFE, 0xFE, 0xD9, 0x5E,
 0x8B }
```

The configuration table leads to an **EFI_DEBUG_IMAGE_INFO_TABLE_HEADER** structure that contains a pointer to the **EFI_DEBUG_IMAGE_INFO_TABLE** and some status bits that are used to control access to the **EFI_DEBUG_IMAGE_INFO_TABLE** when it is being updated.

```
//
// UpdateStatus bits
//
#define EFI_DEBUG_IMAGE_INFO_UPDATE_IN_PROGRESS 0x01
#define EFI_DEBUG_IMAGE_INFO_TABLE_MODIFIED    0x02

typedef struct {
    volatile UINT32      UpdateStatus;
    UINT32               TableSize;
    EFI_DEBUG_IMAGE_INFO *EfiDebugImageInfoTable;
} EFI_DEBUG_IMAGE_INFO_TABLE_HEADER;
```

UpdateStatus *UpdateStatus* is used by the system to indicate the state of the debug image info table.

The **EFI_DEBUG_IMAGE_INFO_UPDATE_IN_PROGRESS** bit must be set when the table is being modified. Software consuming the table must qualify the access to the table with this bit.

The **EFI_DEBUG_IMAGE_INFO_TABLE_MODIFIED** bit is always set by software that modifies the table. It may be cleared by software that consumes the table once the entire table has been read. It is essentially a sticky version of the **EFI_DEBUG_IMAGE_INFO_UPDATE_IN_PROGRESS** bit and is intended to provide an efficient mechanism to minimize the number of times the table must be scanned by the consumer.

TableSize The number of **EFI_DEBUG_IMAGE_INFO** elements in the array pointed to by *EfiDebugImageInfoTable*.

EfiDebugImageInfoTable

A pointer to the first element of an array of **EFI_DEBUG_IMAGE_INFO** structures.

```
#define EFI_DEBUG_IMAGE_INFO_TYPE_NORMAL 0x01
```

```
typedef union {  
    UINT32 *ImageInfoType;  
    EFI_DEBUG_IMAGE_INFO_NORMAL *NormalImage;  
} EFI_DEBUG_IMAGE_INFO;
```

```
typedef struct {  
    UINT32 ImageInfoType;  
    EFI_LOADED_IMAGE_PROTOCOL *LoadedImageProtocolInstance;  
    EFI_HANDLE ImageHandle;  
} EFI_DEBUG_IMAGE_INFO_NORMAL;
```

ImageInfoType Indicates the type of image info structure. For PE32 EFI images, this is set to **EFI_DEBUG_IMAGE_INFO_TYPE_NORMAL**.

LoadedImageProtocolInstance A pointer to an instance of the loaded image protocol for the associated image.

ImageHandle Indicates the image handle of the associated image.

Protocols - Compression Algorithm Specification

In EFI firmware storage, binary codes/data are often compressed to save storage space. These compressed codes/data are extracted into memory for execution at boot time. This demands an efficient lossless compression/decompression algorithm. The compressor must produce small compressed images, and the decompressor must operate fast enough to avoid delays at boot time.

This chapter describes in detail the UEFI compression/decompression algorithm, as well as the EFI Decompress Protocol. The EFI Decompress Protocol provides a standard decompression interface for use at boot time.

18.1 Algorithm Overview

In this chapter the term “**character**” denotes a single byte and the term “**string**” denotes a series of concatenated characters.

The compression/decompression algorithm used in EFI firmware storage is a combination of the LZ77 algorithm and Huffman Coding. The LZ77 algorithm replaces a repeated string with a pointer to the previous occurrence of the string. Huffman Coding encodes symbols in a way that the more frequently a symbol appears in a text, the shorter the code that is assigned to it.

The compression process contains two steps:

- The first step is to find repeated strings (using LZ77 algorithm) and produce intermediate data. Beginning with the first character, the compressor scans the source data and determines if the characters starting at the current position can form a string previously appearing in the text. If a long enough matching string is found, the compressor will output a pointer to the string. If the pointer occupies more space than the string itself, the compressor will output the original character at the current position in the source data. Then the compressor advances to the next position and repeats the process. To speed up the compression process, the compressor dynamically maintains a **String Info Log** to record the positions and lengths of strings encountered, so that string comparisons are performed quickly by looking up the String Info Log.

Because a compressor cannot have unlimited resources, as the compression continues the compressor removes “old” string information. This prevents the String Info Log from becoming too large. As a result, the algorithm can only look up repeated strings within the range of a fixed-sized “sliding window” behind the current position.

In this way, a stream of intermediate data is produced which contains two types of symbols: the **Original Characters** (to be preserved in the decompressed data), and the **Pointers** (representing a previous string). A Pointer consists of two elements: the **String Position** and the **String Length**, representing the location and the length of the target string, respectively.

- To improve the compression ratio further, Huffman Coding is utilized as the second step. The intermediate data (consisting of original characters and pointers) is divided into **Blocks** so that the compressor can perform Huffman Coding on a Block immediately after it is generated;

eliminating the need for a second pass from the beginning after the intermediate data has been generated. Also, since symbol frequency distribution may differ in different parts of the intermediate data, Huffman Coding can be optimized for each specific Block. The compressor determines Block Size for each Block according to the specifications defined in [Section 18.2](#).

In each Block, two symbol sets are defined for Huffman Coding. The **Char&Len Set** consists of the Original Characters plus the String Lengths and the **Position Set** consists of String Positions (Note that the two elements of a Pointer belong to separate symbol sets). The Huffman Coding schemes applied on these two symbol sets are independent.

The algorithm uses “canonical” Huffman Coding so a Huffman tree can be represented as an array of code lengths in the order of the symbols in the symbol set. This code length array represents the Huffman Coding scheme for the symbol set. Both the Char&Len Set code length array and the Position Set code length array appear in the Block Header.

Huffman coding is used on the code length array of the Char&Len Set to define a third symbol set. The **Extra Set** is defined based on the code length values in the Char&Len Set code length array. The code length array for the Huffman Coding of Extra Set also appears in the Block Header together with the other two code length arrays. For exact format of the Block Header, see [Section 18.2.3.1](#).

The decompression process is straightforward given that the compression process is known. The decompressor scans the compressed data and decodes the symbols one by one, according to the Huffman code mapping tables generated from code length arrays. Along the process, if it encounters an original character, it outputs it; if it encounters a pointer, it looks it up in the already decompressed data and outputs the associated string.

18.2 Data Format

This section describes in detail the format of the compressed data produced by the compressor. The compressed data serves as input to the decompressor and can be fully extracted to the original source data.

18.2.1 Bit Order

In computer data representation, a byte is the minimum unit and there is no differentiation in the order of bits within a byte. However, the compressed data is a sequence of bits rather than a sequence of bytes and as a result the order of bits in a byte needs to be defined. In a compressed data stream, the higher bits are defined to precede the lower bits in a byte. [Figure 49](#) illustrates a compressed data sequence written as bytes from left to right. For each byte, the bits are written in an order with bit 7 (the highest bit) at the left and bit 0 (the lowest bit) at the right. Concatenating the bytes from left to right forms a bit sequence.

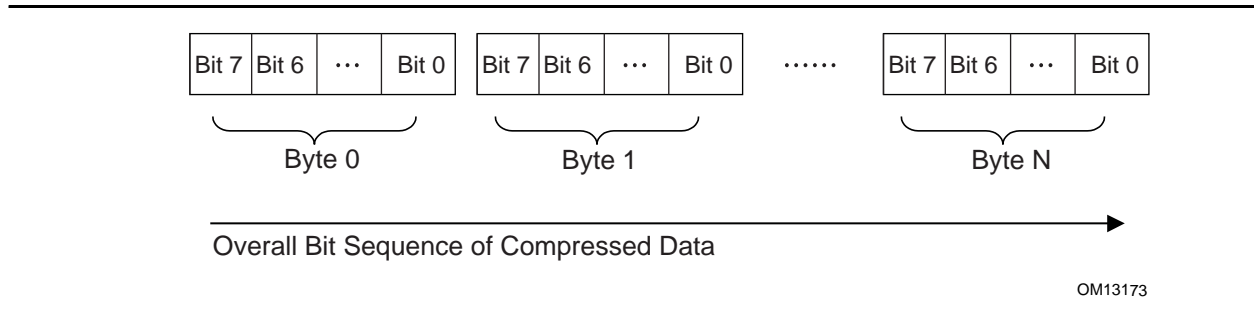


Figure 49. Bit Sequence of Compressed Data

The bits of the compressed data are actually formed by a sequence of data units. These data units have variable bit lengths. The bits of each data unit are arranged so that the higher bit of the data unit precedes the lower bit of the data unit.

18.2.2 Overall Structure

The compressed data begins with two 32-bit numerical fields: the compressed size and the original size. The compressed data following these two fields is composed of one or more Blocks. Each Block is a unit for Huffman Coding with a coding scheme independent of the other Blocks. Each Block is composed of a Block Header containing the Huffman code trees for this Block and a Block Body with the data encoded using the coding scheme defined by the Huffman trees. The compressed data is terminated by an additional byte of zero.

The overall structure of the compressed data is shown in [Figure 50](#).

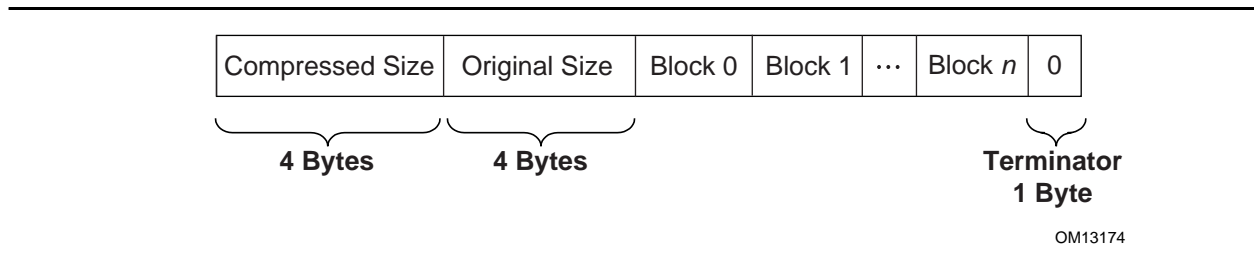


Figure 50. Compressed Data Structure

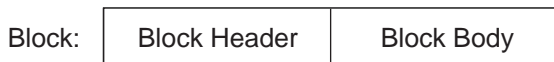
Note the following:

- Blocks are of variable lengths.
- Block lengths are counted by bits and not necessarily divisible by 8. Blocks are tightly packed (there are no padding bits between blocks). Neither the starting position nor ending position of a Block is necessarily at a byte boundary. However, if the last Block is not terminated at a byte boundary, there should be some bits of 0 to fill up the remaining bits of the last byte of the block, before the terminator byte of 0.
- Compressed Size =
Size in bytes of (Block 0 + Block 1 + ... + Block N + Filling Bits (if any) + Terminator).
- Original Size is the size in bytes of original data.

- Both Compressed Size and Original Size are “little endian” (starting from the least significant byte).

18.2.3 Block Structure

A Block is composed of a Block Header and a Block Body, as shown in [Figure 51](#). These two parts are packed tightly (there are no padding bits between them). The lengths in bits of Block Header and Block Body are not necessarily divisible by eight.



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Figure 51. Block Structure

18.2.3.1 Block Header

The Block Header contains the Huffman encoding information for this block. Since “canonical” Huffman Coding is being used, a Huffman tree is represented as an array of code lengths in increasing order of the symbols in the symbol set. Code lengths are limited to be less than or equal to 16 bits. This requires some extra handling of Huffman codes in the compressor, which is described in [Section 18.3](#).

There are three code length arrays for three different symbol sets in the Block Header: one for the Extra Set, one for the Char&Len Set, and one for the Position Set.

The Block Header is composed of the tightly packed (no padding bits) fields described in [Table 116](#).

Table 116. Block Header Fields

Field Name	Length (bits)	Description
Block Size	16	The size of this Block. Block Size is defined as the number of original characters plus the number of pointers that appear in the Block Body: Block Size = Number of Original Characters in the Block Body + Number of Pointers in the Block Body.
Extra Set Code Length Array Size	5	The number of code lengths in the Extra Set Code Length Array. The Extra Set Code Length Array contains code lengths of the Extra Set in increasing order of the symbols, and if all symbols greater than a certain symbol have zero code length, the Extra Set Code Length Array terminates at the last nonzero code length symbol. Since there are 19 symbols in the Extra Set (see the description of the Char&Len Set Code Length Array), the maximum Extra Set Code Length Array Size is 19.

Field Name	Length (bits)	Description
Extra Set Code Length Array	Variable	<p>If Extra Set Code Length Array Size is 0, then this field is a 5-bit value that represents the only Huffman code used.</p> <p>If Extra Set Code Length Array Size is not 0, then this field is an encoded form of a concatenation of code lengths in increasing order of the symbols.</p> <p>The concatenation of Code lengths are encoded as follows: If a code length is less than 7, then it is encoded as a 3-bit value; If a code length is equal to or greater than 7, then it is encoded as a series of "1"s followed by a terminating "0." The number of "1"s = Code length – 4. For example, code length "ten" is encoded as "1111110"; code length "seven" is encoded as "1110."</p> <p>After the third length of the code length concatenation, a 2-bit value is used to indicate the number of consecutive zero lengths immediately after the third length. (Note this 2-bit value only appears once after the third length, and does NOT appear multiple times after every 3rd length.) This 2-bit value ranges from 0 to 3. For example, if the 2-bit value is "00," then it means there are no zero lengths at the point, and following encoding starts from the fourth code length; if the 2-bit value is "10" then it means the fourth and fifth length are zero and following encoding starts from the sixth code length.</p>
Position Set Code Length Array Size	4	<p>The number of code lengths in the Position Set Code Length Array. The Position Set Code Length Array contains code lengths of Position Set in increasing order of the symbols in the Position Set, and if all symbols greater than a certain symbol have zero code length, the Position Set Code Length Array terminates at the last nonzero code length symbol. Since there are 14 symbols in the Position Set (see 3.3.2), the maximum Position Set Code Length Array Size is 14.</p>

Field Name	Length (bits)	Description
Char&Len Set Code Length Array	Variable	<p>If Char&Len Set Code Length Array Size is 0, then this field is a 9-bit value that represents the only Huffman code used.</p> <p>If Char&Len Set Code Length Array Size is not 0, then this field is an encoded form of a concatenation of code lengths in increasing order of the symbols.</p> <p>The concatenation of Code lengths are two-step encoded:</p> <p>Step 1:</p> <p>If a code length is not zero, then it is encoded as “code length + 2”;</p> <p>If a code length is zero, then the number of consecutive zero lengths starting from this code length is counted -- If the count is equal to or less than 2, then the code “0” is used for each zero length; if the count is greater than 2 and less than 19, then the code “1” followed by a 4-bit value of “count – 3” is used for these consecutive zero lengths; if the count is equal to 19, then it is treated as “1 + 18,” and a code “0” and a code “1” followed by a 4-bit value of “15” are used for these consecutive zero lengths; if the count is greater than 19, then the code “2” followed by a 9-bit value of “count – 20” is used for these consecutive zero lengths.</p> <p>Step 2:</p> <p>The second step encoding is a Huffman encoding of the codes produced by first step. (While encoding codes “1” and “2,” their appended values are not encoded and preserved in the resulting text). The code lengths of generated Huffman tree are just the contents of the Extra Set Code Length Array.</p>
Position Set Code Length Array Size	4	<p>The number of code lengths in the Position Set Code Length Array. The Position Set Code Length Array contains code lengths of Position Set in increasing order of the symbols in the Position Set, and if all symbols greater than a certain symbol have zero code length, the Position Set Code Length Array terminates at the last nonzero code length symbol. Since there are 14 symbols in the Position Set (see 3.3.2), the maximum Position Set Code Length Array Size is 14.</p>
Position Set Code Length Array	Variable	<p>If Position Set Code Length Array Size is 0, then this field is a 5-bit value that represents the only Huffman code used.</p> <p>If Position Set Code Length Array Size is not 0, then this field is an encoded form of a concatenation of code lengths in increasing order of the symbols.</p> <p>The concatenation of Code lengths are encoded as follows:</p> <p>If a code length is less than 7, then it is encoded as a normal 3-bit value;</p> <p>If a code length is equal to or greater than 7, then it is encoded as a series of “1”s followed by a terminating “0.” The number of “1”s = Code length – 4. For example, code length “10” is encoded as “111110”; code length “7” is encoded as “1110.”</p>

18.2.3.2 Block Body

The Block Body is simply a mixture of Original Characters and Pointers, while each Pointer has two elements: String Length preceding String Position. All these data units are tightly packed together.

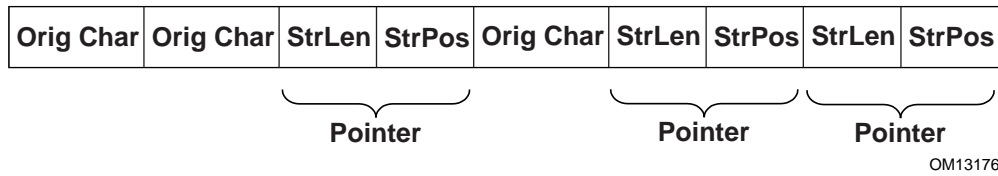


Figure 52. Block Body

The Original Characters, String Lengths and String Positions are all Huffman coded using the Huffman trees presented in the Block Header, with some additional variations. The exact format is described below:

An Original Character is a byte in the source data. A String Length is a value that is greater than 3 and less than 257 (this range should be ensured by the compressor). By calculating “(String Length – 3) | 0x100,” a value set is obtained that ranges from 256 to 509. By combining this value set with the value set of Original Characters (0 ~ 255), the Char&Len Set (ranging from 0 to 509) is generated for Huffman Coding.

A String Position is a value that indicates the distance between the current position and the target string. The String Position value is defined as “Current Position – Starting Position of the target string - 1.” The String Position value ranges from 0 to 8190 (so 8192 is the “sliding window” size, and this range should be ensured by the compressor). The lengths of the String Position values (in binary form) form a value set ranging from 0 to 13 (it is assumed that value 0 has length of 0). This value set is the Position Set for Huffman Coding. The full representation of a String Position value is composed of two consecutive parts: one is the Huffman code for the value length; the other is the actual String Position value of “length - 1” bits (excluding the highest bit since the highest bit is always “1”). For example, String Position value 18 is represented as: Huffman code for “5” followed by “0010.” If the value length is 0 or 1, then no value is appended to the Huffman code. This kind of representation favors small String Position values, which is a hint for compressor design.

18.3 Compressor Design

The compressor takes the source data as input and produces a compressed image. This section describes the design used in one possible implementation of a compressor that follows the EFI 1.10 Compression Algorithm. The source code that illustrates an implementation of this specific design is listed in Appendix H.

18.3.1 Overall Process

The compressor scans the source data from the beginning, character by character. As the scanning proceeds, the compressor generates Original Characters or Pointers and outputs the compressed data packed in a series of Blocks representing individual Huffman coding units.

The compressor maintains a String Info Log containing data that facilitates string comparison. Old data items are deleted and new data items are inserted regularly.

The compressor does not output a Pointer immediately after it sees a matching string for the current position. Instead, it delays its decision until it gets the matching string for the next position. The compressor has two criteria at hand: one is that the former match length should be no shorter than three characters; the other is that the former match length should be no shorter than the latter match length. Only when these two criteria are met does the compressor output a Pointer to the former matching string.

The overall process of compression can be described by following pseudo code:

```

Set the Current Position at the beginning of the source data;
Delete the outdated string info from the String Info Log;
Search the String Info Log for matching string;
Add the string info of the current position into the String Info Log;
WHILE not end of source data DO
    Remember the last match;
    Advance the Current Position by 1;
    Delete the outdated String Info from the String Info Log;
    Search the String Info Log for matching string;
    Add the string info of the Current Position into the String Info Log;
    IF the last match is shorter than 3 characters or this match is longer than
    the last match THEN
        Call Output()* to output the character at the previous position as an
        Original Character;
    ELSE
        Call Output()* to output a Pointer to the last matching string;
        WHILE (--last match length) > 0 DO
            Advance the Current Position by 1;
            Delete the outdated piece of string info from the String Info Log;
            Add the string info of the current position into the String Info Log;
        ENDWHILE
    ENDIF
ENDWHILE

```

The *Output()* is the function that is responsible for generating Huffman codes and Blocks. It accepts an Original Character or a Pointer as input and maintains a Block Buffer to temporarily store data units that are to be Huffman coded. The following pseudo code describes the function:

```

FUNCTION NAME: Output
INPUT: an Original Character or a Pointer

Put the Original Character or the Pointer into the Block Buffer;
Advance the Block Buffer position pointer by 1;
IF the Block Buffer is full THEN
    Encode the Char&Len Set in the Block buffer;
    Encode the Position Set in the Block buffer;
    Encode the Extra Set;
    Output the Block Header containing the code length arrays;
    Output the Block Body containing the Huffman encoded Original Characters and
    Pointers;
    Reset the Block Buffer position pointer to point to the beginning of the
    Block buffer;
ENDIF

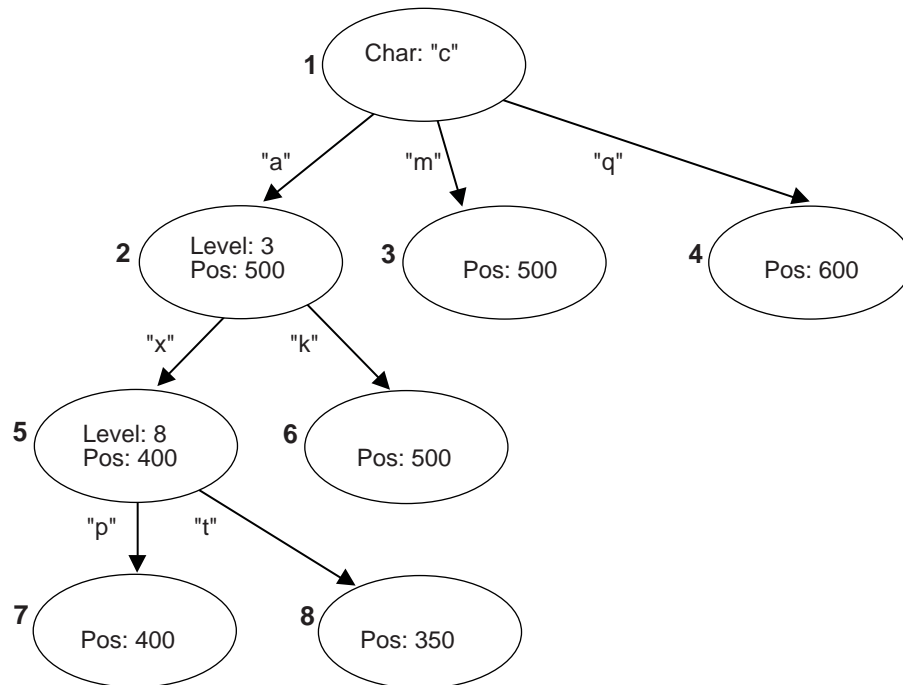
```

18.3.2 String Info Log

The provision of the String Info Log is to speed up the process of finding matching strings. The design of this has significant impact on the overall performance of the compressor. This section describes in detail how String Info Log is implemented and the typical operations on it.

18.3.2.1 Data Structures

The String Info Log is implemented as a set of search trees. These search trees are dynamically updated as the compression proceeds through the source data. The structure of a typical search tree is depicted in [Figure 53](#).



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Figure 53. String Info Log Search Tree

There are three types of nodes in a search tree: the root node, internal nodes, and leaves. The root node has a “character” attribute, which represents the starting character of a string. Each edge also has a “character” attribute, which represents the next character in the string. Each internal node has a “level” attribute, which indicates the character on any edge that leads to its child nodes is the “level + 1”th character in the string. Each internal node or leaf has a “position” attribute that indicates the string’s starting position in the source data.

To speed up the tree searching, a hash function is used. Given the parent node and the edge-character, the hash function will quickly find the expected child node.

18.3.2.2 Searching the Tree

Traversing the search tree is performed as follows:

The following example uses the search tree shown in [Figure 53](#) above. Assume that the current position in the source data contains the string “camxrspj...”

1. The starting character “c” is used to find the root of the tree. The next character “a” is used to follow the edge from node 1 to node 2. The “position” of node 2 is 500, so a string starting with

“ca” can be found at position 500. The string at the current position is compared with the string starting at position 500.

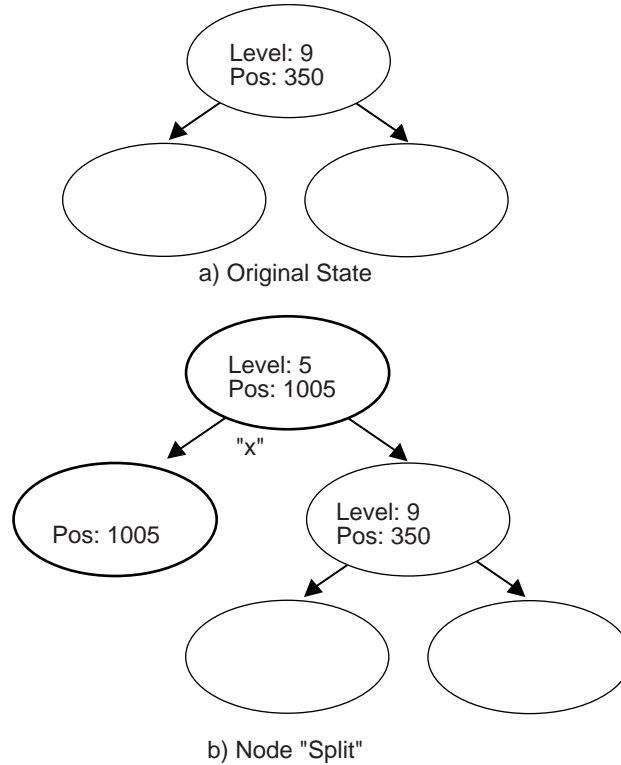
2. Node 2 is at Level 3; so at most three characters are compared. Assume that the three-character comparison passes.
3. The fourth character “x” is used to follow the edge from Node 2 to Node 5. The position value of node 5 is 400, which means there is a string located in position 400 that starts with “cam” and the character at position 403 is an “x.”
4. Node 5 is at Level 8, so the fifth to eighth characters of the source data are compared with the string starting at position 404. Assume the strings match.
5. At this point, the ninth character “p” has been reached. It is used to follow the edge from Node 5 to Node 7.
6. This process continues until a mismatch occurs, or the length of the matching strings exceeds the predefined `MAX_MATCH_LENGTH`. The most recent matching string (which is also the longest) is the desired matching string.

18.3.2.3 Adding String Info

String info needs to be added to the String Info Log for each position in the source data. Each time a search for a matching string is performed, the new string info is inserted for the current position. There are several cases that can be discussed:

1. No root is found for the first character. A new tree is created with the root node labeled with the starting character and a child leaf node with its edge to the root node labeled with the second character in the string. The “position” value of the child node is set to the current position.
2. One root node matches the first character, but the second character does not match any edge extending from the root node. A new child leaf node is created with its edge labeled with the second character. The “position” value of the new leaf child node is set to the current position.
3. A string comparison succeeds with an internal node, but a matching edge for the next character does not exist. This is similar to (2) above. A new child leaf node is created with its edge labeled with the character that does not exist. The “position” value of the new leaf child node is set to the current position.
4. A string comparison exceeds `MAX_MATCH_LENGTH`. Note: This only happens with leaf nodes. For this case, the “position” value in the leaf node is updated with the current position.
5. If a string comparison with an internal node or leaf node fails (mismatch occurs before the “Level + 1”th character is reached or `MAX_MATCH_LENGTH` is exceeded), then a “split” operation is performed as follows:

Suppose a comparison is being performed with a level 9 Node, at position 350, and the current position is 1005. If the sixth character at position 350 is an “x” and the sixth character at position 1005 is a “y,” then a mismatch will occur. In this case, a new internal node and a new child node are inserted into the tree, as depicted in [Figure 54](#).



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Figure 54. Node Split

The b) portion of [Figure 54](#) has two new inserted nodes, which reflects the new string information that was found at the current position. The process splits the old node into two child nodes, and that is why this operation is called a “split.”

18.3.2.4 Deleting String Info

The String Info Log will grow as more and more string information is logged. The size of the String Info Log must be limited, so outdated information must be removed on a regular basis. A sliding window is maintained behind the current position, and the searches are always limited within the range of the sliding window. Each time the current position is advanced, outdated string information that falls outside the sliding window should be removed from the tree. The search for outdated string information is simplified by always updating the nodes’ “position” attribute when searching for matching strings.

18.3.3 Huffman Code Generation

Another major component of the compressor design is generation of the Huffman Code.

Huffman Coding is applied to the Char&Len Set, the Position Set, and the Extra Set. The Huffman Coding used here has the following features:

- The Huffman tree is represented as an array of code lengths (“canonical” Huffman Coding);

- The maximum code length is limited to 16 bits.

The Huffman code generation process can be divided into three steps. These are the generation of Huffman tree, the adjustment of code lengths, and the code generation.

18.3.3.1 Huffman Tree Generation

This process generates a typical Huffman tree. First, the frequency of each symbol is counted, and a list of nodes is generated with each node containing a symbol and the symbol's frequency. The two nodes with the lowest frequency values are merged into a single node. This new node becomes the parent node of the two nodes that are merged. The frequency value of this new parent node is the sum of the two child nodes' frequency values. The node list is updated to include the new parent node but exclude the two child nodes that are merged. This process is repeated until there is a single node remaining that is the root of the generated tree.

18.3.3.2 Code Length Adjustment

The leaf nodes of the tree generated by the previous step represent all the symbols that were generated. Traditionally the code for each symbol is found by traversing the tree from the root node to the leaf node. Going down a left edge generates a "0," and going down a right edge generates a "1." However, a different approach is used here. The number of codes of each code length is counted. This generates a 16-element *LengthCount* array, with *LengthCount[i]* = Number Of Codes whose Code Length is *i*. Since a code length may be longer than 16 bits, the sixteenth entry of the *LengthCount* array is set to the Number Of Codes whose Code Length is greater than or equal to 16.

The *LengthCount* array goes through further adjustment described by following code:

```

INT32 i, k;
UINT32 cum;

cum = 0;
for (i = 16; i > 0; i--) {
    cum += LengthCount[i] << (16 - i);
}
while (cum != (1U << 16)) {
    LengthCount[16]--;
    for (i = 15; i > 0; i--) {
        if (LengthCount[i] != 0) {
            LengthCount[i]--;
            LengthCount[i+1] += 2;
            break;
        }
    }
    cum--;
}

```

18.3.3.3 Code Generation

In the previous step, the count of each length was obtained. Now, each symbol is going to be assigned a code. First, the length of the code for each symbol is determined. Naturally, the code lengths are assigned in such a way that shorter codes are assigned to more frequently appearing symbols. A *CodeLength* array is generated with *CodeLength[i]* = the code length of symbol *i*. Given this array, a code is assigned to each symbol using the algorithm described by the pseudo code below (the resulting codes are stored in array *Code* such that *Code[i]* = the code assigned to symbol *i*):


```

INT32    i;
UINT16   Start[18];

Start[1] = 0;

for (i = 1; i <= 16; i++) {
    Start[i + 1] = (UINT16)((Start[i] + LengthCount[i]) << 1);
}

for (i = 0; i < NumberOfSymbols; i++) {
    Code[i] = Start[CodeLength[i]]++;
}

```

The code length adjustment process ensures that no code longer than the designated length will be generated. As long as the decompressor has the *CodeLength* array at hand, it can regenerate the codes.

18.4 Decompressor Design

The decompressor takes the compressed data as input and produces the original source data. The main tasks for the decompressor are decoding Huffman codes and restoring Pointers to the strings to which they point.

The following pseudo code describes the algorithm used in the design of a decompressor. The source code that illustrates an implementation of this design is listed in Appendix I.

```

WHILE not end of data DO
    IF at block boundary THEN
        Read in the Extra Set Code Length Array;
        Generate the Huffman code mapping table for the Extra Set;
        Read in and decode the Char&Len Set Code Length Array;
        Generate the Huffman code mapping table for the Char&Len Set;
        Read in the Position Set Code Length Array;
        Generate the Huffman code mapping table for the Position Set;
    ENDIF
    Get next code;
    Look the code up in the Char&Len Set code mapping table.
    Store the result as C;
    IF C < 256 (it represents an Original Character) THEN
        Output this character;
    ELSE (it represents a String Length)
        Transform C to be the actual String Length value;
        Get next code and look it up in the Position Set code mapping table, and
        with some additional transformation, store the result as P;
        Output C characters starting from the position "Current Position - P";
    ENDIF
ENDWHILE

```

18.5 Decompress Protocol

This section provides a detailed description of the **EFI_DECOMPRESS_PROTOCOL**.

EFI_DECOMPRESS_PROTOCOL

Summary

Provides a decompression service.

GUID

```
#define EFI_DECOMPRESS_PROTOCOL_GUID \
    {0xd8117cfe, 0x94a6, 0x11d4, 0x9a, 0x3a, 0x0, 0x90, 0x27, 0x3f, \
     0xc1, 0x4d}
```

Protocol Interface Structure

```
typedef struct _EFI_DECOMPRESS_PROTOCOL {
    EFI_DECOMPRESS_GET_INFO    GetInfo;
    EFI_DECOMPRESS_DECOMPRESS Decompress;
} EFI_DECOMPRESS_PROTOCOL;
```

Parameters

GetInfo

Given the compressed source buffer, this function retrieves the size of the uncompressed destination buffer and the size of the scratch buffer required to perform the decompression. It is the caller's responsibility to allocate the destination buffer and the scratch buffer prior to calling [EFI_DECOMPRESS_PROTOCOL.Decompress\(\)](#). See the [EFI_DECOMPRESS_PROTOCOL.GetInfo\(\)](#) function description.

Decompress

Decompresses a compressed source buffer into an uncompressed destination buffer. It is the caller's responsibility to allocate the destination buffer and a scratch buffer prior to making this call. See the [Decompress\(\)](#) function description.

Description

The **EFI_DECOMPRESS_PROTOCOL** provides a decompression service that allows a compressed source buffer in memory to be decompressed into a destination buffer in memory. It also requires a temporary scratch buffer to perform the decompression. The **GetInfo()** function retrieves the size of the destination buffer and the size of the scratch buffer that the caller is required to allocate. The **Decompress()** function performs the decompression. The scratch buffer can be freed after the decompression is complete.

EFI_DECOMPRESS_PROTOCOL.GetInfo()

Summary

Given a compressed source buffer, this function retrieves the size of the uncompressed buffer and the size of the scratch buffer required to decompress the compressed source buffer.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DECOMPRESS_GET_INFO) (
    IN  EFI_DECOMPRESS_PROTOCOL  *This,
    IN  VOID                      *Source,
    IN  UINT32                    SourceSize,
    OUT UINT32                    *DestinationSize,
    OUT UINT32                    *ScratchSize
);
```

Parameters

<i>This</i>	A pointer to the EFI_DECOMPRESS_PROTOCOL instance. Type EFI_DECOMPRESS_PROTOCOL is defined in Section 18.5 .
<i>Source</i>	The source buffer containing the compressed data.
<i>SourceSize</i>	The size, in bytes, of the source buffer.
<i>DestinationSize</i>	A pointer to the size, in bytes, of the uncompressed buffer that will be generated when the compressed buffer specified by <i>Source</i> and <i>SourceSize</i> is decompressed.
<i>ScratchSize</i>	A pointer to the size, in bytes, of the scratch buffer that is required to decompress the compressed buffer specified by <i>Source</i> and <i>SourceSize</i> .

Description

The **GetInfo()** function retrieves the size of the uncompressed buffer and the temporary scratch buffer required to decompress the buffer specified by *Source* and *SourceSize*. If the size of the uncompressed buffer or the size of the scratch buffer cannot be determined from the compressed data specified by *Source* and *SourceData*, then **EFI_INVALID_PARAMETER** is returned. Otherwise, the size of the uncompressed buffer is returned in *DestinationSize*, the size of the scratch buffer is returned in *ScratchSize*, and **EFI_SUCCESS** is returned.

The **GetInfo()** function does not have scratch buffer available to perform a thorough checking of the validity of the source data. It just retrieves the “Original Size” field from the beginning bytes of the source data and output it as *DestinationSize*. And *ScratchSize* is specific to the decompression implementation.

Status Codes Returned

EFI_SUCCESS	The size of the uncompressed data was returned in <i>DestinationSize</i> and the size of the scratch buffer was returned in <i>ScratchSize</i> .
EFI_INVALID_PARAMETER	The size of the uncompressed data or the size of the scratch buffer cannot be determined from the compressed data specified by <i>Source</i> and <i>SourceSize</i> .

EFI_DECOMPRESS_PROTOCOL.Decompress()

Summary

Decompresses a compressed source buffer.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DECOMPRESS_DECOMPRESS) (
    IN  EFI_DECOMPRESS_PROTOCOL  *This,
    IN   VOID                    *Source,
    IN   UINT32                  SourceSize,
    IN OUT VOID                  *Destination,
    IN   UINT32                  DestinationSize,
    IN OUT VOID                  *Scratch,
    IN   UINT32                  ScratchSize
);
```

Parameters

<i>This</i>	A pointer to the EFI_DECOMPRESS_PROTOCOL instance. Type EFI_DECOMPRESS_PROTOCOL is defined in Section 18.5 .
<i>Source</i>	The source buffer containing the compressed data.
<i>SourceSize</i>	The size of source data.
<i>Destination</i>	On output, the destination buffer that contains the uncompressed data.
<i>DestinationSize</i>	The size of the destination buffer. The size of the destination buffer needed is obtained from EFI_DECOMPRESS_PROTOCOL.GetInfo() .
<i>Scratch</i>	A temporary scratch buffer that is used to perform the decompression.
<i>ScratchSize</i>	The size of scratch buffer. The size of the scratch buffer needed is obtained from GetInfo() .

Description

The **Decompress()** function extracts decompressed data to its original form.

This protocol is designed so that the decompression algorithm can be implemented without using any memory services. As a result, the **Decompress()** function is not allowed to call [AllocatePool\(\)](#) or [AllocatePages\(\)](#) in its implementation. It is the caller's responsibility to allocate and free the *Destination* and *Scratch* buffers.

If the compressed source data specified by *Source* and *SourceSize* is successfully decompressed into *Destination*, then **EFI_SUCCESS** is returned. If the compressed source data specified by

Source and *SourceSize* is not in a valid compressed data format, then **EFI_INVALID_PARAMETER** is returned.

Status Codes Returned

EFI_SUCCESS	Decompression completed successfully, and the uncompressed buffer is returned in <i>Destination</i> .
EFI_INVALID_PARAMETER	The source buffer specified by <i>Source</i> and <i>SourceSize</i> is corrupted (not in a valid compressed format).

Protocols - ACPI Protocols

EFI_ACPI_TABLE_PROTOCOL

Summary

This protocol may be used to install or remove an ACPI table from a platform.

GUID

```
#define EFI_ACPI_TABLE_PROTOCOL_GUID \
{0xffe06bdd, 0x6107, 0x46a6, 0xb27b, 0x9c5a, 0x7e, 0xc5, 0x27,
0x5c}
```

Protocol Interface Structure

```
typedef struct _EFI_ACPI_TABLE_PROTOCOL {
EFI_ACPI_TABLE_INSTALL_ACPI_TABLE    InstallAcpiTable;
EFI_ACPI_TABLE_UNINSTALL_ACPI_TABLE  UninstallAcpiTable;
} EFI_ACPI_TABLE_PROTOCOL;
```

Parameters

InstallAcpiTable Installs an ACPI table into the system.

UninstallAcpiTable Removes a previously installed ACPI table from the system.

Description

The **EFI_ACPI_TABLE_PROTOCOL** provides the ability for a component to install and uninstall ACPI tables from a platform.

EFI_ACPI_TABLE_PROTOCOL.InstallAcpiTable()

Summary

Installs an ACPI table into the RSDT/XSDT.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ACPI_TABLE_INSTALL_ACPI_TABLE) (
    IN EFI_ACPI_TABLE_PROTOCOL          *This,
    IN VOID                             *AcpiTableBuffer,
    IN UINTN                            AcpiTableBufferSize,
    OUT UINTN                            *TableKey,
);
```

Parameters

This A pointer to a [EFI ACPI TABLE PROTOCOL](#).

AcpiTableBuffer A pointer to a buffer containing the ACPI table to be installed.

AcpiTableBufferSize Specifies the size, in bytes, of the *AcpiTableBuffer* buffer.

TableKey Returns a key to refer to the ACPI table.

Description

The **InstallAcpiTable()** function allows a caller to install an ACPI table. When successful, the table will be linked by the RSDT/XSDT. *AcpiTableBuffer* specifies the table to be installed. **InstallAcpiTable()** will make a copy of the table and insert the copy into the RSDT/XSDT. **InstallAcpiTable()** must insert the new table at the end of the RSDT/XSDT.

To prevent namespace collision, ACPI tables may be created using UEFI ACPI table format. See [Appendix O](#).

On successful output, *TableKey* is initialized with a unique key. Its value may be used in a subsequent call to **UninstallAcpiTable** to remove an ACPI table.

If an EFI application is running at the time of this call, the relevant **EFI_CONFIGURATION_TABLE** pointer to the RSDT is no longer considered valid.

Status Codes Returned

EFI_SUCCESS	The table was successfully inserted
EFI_INVALID_PARAMETER	Either <i>AcpiTableBuffer</i> is NULL , <i>TableKey</i> is NULL , or <i>AcpiTableBufferSize</i> and the size field embedded in the ACPI table pointed to by <i>AcpiTableBuffer</i> are not in sync
EFI_OUT_OF_RESOURCES	Insufficient resources exist to complete the request.

EFI_ACPI_TABLE_PROTOCOL.UninstallAcpiTable()

Summary

Removes an ACPI table from the RSDT/XSDT.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ACPI_TABLE_UNINSTALL_ACPI_TABLE) (
    IN EFI_ACPI_TABLE_PROTOCOL    *This,
    IN UINTN                       TableKey,
);
```

Parameters

<i>This</i>	A pointer to a EFI ACPI TABLE PROTOCOL .
<i>TableKey</i>	Specifies the table to uninstall. The key was returned from InstallAcpiTable() .

Description

The **UninstallAcpiTable()** function allows a caller to remove an ACPI table. The routine will remove its reference from the RSDT/XSDT. A table is referenced by the TableKey parameter returned from a prior call to **InstallAcpiTable()**. If an EFI application is running at the time of this call, the relevant **EFI_CONFIGURATION_TABLE** pointer to the RSDT is no longer considered valid.

Status Codes Returned

EFI_SUCCESS	The table was successfully inserted
EFI_NOT_FOUND	TableKey does not refer to a valid key for a table entry.
EFI_OUT_OF_RESOURCES	Insufficient resources exist to complete the request.

EFI Byte Code Virtual Machine

This section defines an EFI Byte Code (EBC) Virtual Machine that can provide platform- and processor-independent mechanisms for loading and executing EFI device drivers.

20.1 Overview

The current design for option ROMs that are used in personal computer systems has been in place since 1981. Attempts to change the basic design requirements have failed for a variety of reasons. The EBC Virtual Machine described in this chapter is attempting to help achieve the following goals:

- Abstract and extensible design
- Processor independence
- OS independence
- Build upon existing specifications when possible
- Facilitate the removal of legacy infrastructure
- Exclusive use of EFI Services

One way to satisfy many of these goals is to define a pseudo or virtual machine that can interpret a predefined instruction set. This will allow the virtual machine to be ported across processor and system architectures without changing or recompiling the option ROM. This specification defines a set of machine level instructions that can be generated by a C compiler.

The following sections are a detailed description of the requirements placed on future option ROMs.

20.1.1 Processor Architecture Independence

Option ROM images shall be independent of supported 32-bit and supported 64-bit architectures. In order to abstract the architectural differences between processors option ROM images shall be EBC. This model is presented below:

- 64-bit C source code
- The EFI EBC image is the flashed image
- The system BIOS implements the EBC interpreter
- The interpreter handles 32 vs. 64 bit issues

Current Option ROM technology is processor dependent and heavily reliant upon the existence of the PC-AT infrastructure. These dependencies inhibit the evolution of both hardware and software under the veil of “backward compatibility.” A solution that isolates the hardware and support infrastructure through abstraction will facilitate the uninhibited progression of technology.

20.1.2 OS Independent

Option ROMs shall not require or assume the existence of a particular OS.

20.1.3 EFI Compliant

Option ROM compliance with EFI requires (but is not limited to) the following:

- Little endian layout
- Single-threaded model with interrupt polling if needed
- Where EFI provides required services, EFI is used exclusively. These include:
 - Console I/O
 - Memory Management
 - Timer services
 - Global variable access
- When an Option ROM provides EFI services, the EFI specification is strictly followed:
 - Service/protocol installation
 - Calling conventions
 - Data structure layouts
 - Guaranteed return on services

20.1.4 Coexistence of Legacy Option ROMs

The infrastructure shall support coexistent Legacy Option ROM and EBC Option ROM images. This case would occur, for example, when a Plug and Play Card has both Legacy and EBC Option ROM images flashed. The details of the mechanism used to select which image to load is beyond the scope of this document. Basically, a legacy System BIOS would not recognize an EBC Option ROM and therefore would never load it. Conversely, an EFI Firmware Boot Manager would only load images that it supports.

The EBC Option ROM format must utilize a legacy format to the extent that a Legacy System BIOS can:

- Determine the type of the image, in order to ignore the image. The type must be incompatible with currently defined types.
- Determine the size of the image, in order to skip to the next image.

20.1.5 Relocatable Image

An EBC option ROM image shall be eligible for placement in any system memory area large enough to accommodate it.

Current option ROM technology requires images to be shadowed in system memory address range 0xC0000 to 0xEFFFF on a 2048 byte boundary. This dependency not only limits the number of Option ROMs, it results in unused memory fragments up to 2 KB.

20.1.6 Size Restrictions Based on Memory Available

EBC option ROM images shall not be limited to a predetermined fixed maximum size.

Current option ROM technology limits the size of a preinitialization option ROM image to 128 KB (126 KB actual). Additionally, in the DDIM an image is not allowed to grow during initialization. It is inevitable that 64-bit solutions will increase in complexity and size. To avoid revisiting this issue, EBC option ROM size is only limited by available system memory. EFI memory allocation services allow device drivers to claim as much memory as they need, within limits of available system memory.

The PCI specification limits the size of an image stored in an option ROM to 16 MB. If the driver is stored on the hard drive then the 16MB option ROM limit does not apply. In addition, the PE/COFF object format limits the size of images to 2 GB.

20.2 Memory Ordering

The term memory ordering refers to the order in which a processor issues reads (loads) and writes (stores) out onto the bus to system memory. The EBC Virtual Machine enforces strong memory ordering, where reads and writes are issued on the system bus in the order they occur in the instruction stream under all circumstances.

20.3 Virtual Machine Registers

The EBC virtual machine utilizes a simple register set. There are two categories of VM registers: general purpose registers and dedicated registers. All registers are 64-bits wide. There are eight (8) general-purpose registers (**R0-R7**), which are used by most EBC instructions to manipulate or fetch data. [Table 117](#) lists the general-purpose registers in the VM and the conventions for their usage during execution.

Table 117. General Purpose VM Registers

Index	Register	Description
0	R0	Points to the top of the stack
1-3	R1-R3	Preserved across calls
4-7	R4-R7	Scratch, not preserved across calls

Register **R0** is used as a stack pointer and is used by the [CALL](#), [RET](#), [PUSH](#), and [POP](#) instructions. The VM initializes this register to point to the incoming arguments when an EBC image is started or entered. This register may be modified like any other general purpose VM register using EBC instructions. Register **R7** is used for function return values.

Unlike the general-purpose registers, the VM dedicated registers have specific purposes. There are two dedicated registers: the instruction pointer (**IP**), and the flags (**Flags**) register. Specialized instructions provide access to the dedicated registers. These instructions reference the particular dedicated register by its assigned index value. [Table 118](#) lists the dedicated registers and their corresponding index values.

Table 118. Dedicated VM Registers

Index	Register	Description	
0	FLAGS		
		Bit	Description
		0	C = Condition code
		1	SS = Single step
		2..63	Reserved
1	IP	Points to current instruction	
2..7	Reserved	Not defined	

The VM **Flags** register contains VM status and context flags. [Table 119](#) lists the descriptions of the bits in the **Flags** register.

Table 119. VM Flags Register

Bit	Flag	Description
0	C	Condition code. Set to 1 if the result of the last compare was true, or set to 0 if the last compare was false. Used by conditional JMP instructions.
1	S	Single-step. If set, causes the VM to generate a single-step exception after executing each instruction. The bit is not cleared by the VM following the exception.
2..63	-	Reserved

The VM **IP** register is used as an instruction pointer and holds the address of the currently executing EBC instruction. The virtual machine will update the **IP** to the address of the next instruction on completion of the current instruction, and will continue execution from the address indicated in **IP**. The **IP** register can be moved into any general-purpose register (**R0-R7**). Data manipulation and data movement instructions can then be used to manipulate the value. The only instructions that may modify the **IP** are the [JMP](#), [CALL](#), and [RET](#) instructions. Since the instruction set is designed to use words as the minimum instruction entity, the low order bit (bit 0) of **IP** is always cleared to 0. If a JMP, CALL, or RET instruction causes bit 0 of **IP** to be set to 1, then an alignment exception occurs.

20.4 Natural Indexing

The natural indexing mechanism is the critical functionality that enables EBC to be executed unchanged on 32- or 64-bit systems. Natural indexing is used to specify the offset of data relative to a base address. However, rather than specifying the offset as a fixed number of bytes, the offset is encoded in a form that specifies the actual offset in two parts: a constant offset, and an offset specified as a number of natural units (where one natural unit = sizeof(VOID *)). These two values are used to compute the actual offset to data at runtime. When the VM decodes an index during execution, the resultant offset is computed based on the natural processor size. The encoded

indexes themselves may be 16, 32, or 64 bits in size. [Table 120](#) describes the fields in a natural index encoding.

Table 120. Index Encoding

Bit #	Description
N	Sign bit (sign), most significant bit
N-3..N-1	Bits assigned to natural units (w)
A..N-4	Constant units (c)
0..A-1	Natural units (n)

As shown in [Table 120](#), for a given encoded index, the most significant bit (bit N) specifies the sign of the resultant offset after it has been calculated. The sign bit is followed by three bits (N-3..N-1) that are used to compute the width of the natural units field (n). The value (w) from this field is multiplied by the index size in bytes to determine the actual width (A) of the natural units field (n). Once the width of the natural units field has been determined, then the natural units (n) and constant units (c) can be extracted. The offset is then calculated at runtime according to the following equation:

$$\text{Offset} = (c + n * (\text{sizeof}(\text{VOID} *))) * \text{sign}$$

The following sections describe each of these fields in more detail.

20.4.1 Sign Bit

The sign bit determines the sign of the index once the offset calculation has been performed. All index computations using “n” and “c” are done with positive numbers, and the sign bit is only used to set the sign of the final offset computed.

20.4.2 Bits Assigned to Natural Units

This 3-bit field that is used to determine the width of the natural units field. The units vary based on the size of the index according to [Table 121](#). For example, for a 16-bit index, the value contained in this field would be multiplied by 2 to get the actual width of the natural-units field.

Table 121. Index Size in Index Encoding

Index Size	Units
16 bits	2 bits
32 bits	4 bits
64 bits	8 bits

20.4.3 Constant

The constant is the number of bytes in the index that do not scale with processor size. When the index is a 16-bit value, the maximum constant is 4095. This index is achieved when the bits assigned to natural units is 0.

20.4.4 Natural Units

Natural units are used when a structure has fields that can vary with the architecture of the processor. Fields that precipitate the use of natural units include pointers and EFI INTN and UINTN data types. The size of one pointer or INTN/UINTN equals one natural unit. The natural units field in an index encoding is a count of the number of natural fields whose sizes (in bytes) must be added to determine a field offset.

As an example, assume that a given EBC instruction specifies a 16-bit index of 0xA048. This breaks down into:

- Sign bit (bit 15) = 1 (negative offset)
- Bits assigned to natural units (w, bits 14-12) = 2. Multiply by index size in bytes = $2 \times 2 = 4$ (A)
- $c = \text{bits } 11-4 = 4$
- $n = \text{bits } 3-0 = 8$

On a 32-bit machine, the offset is then calculated to be:

- Offset = $(4 + 8 * 4) * -1 = -36$
- On a 64-bit machine, the offset is calculated to be:
- Offset = $(4 + 8 * 8) * -1 = -68$

20.5 EBC Instruction Operands

The VM supports an EBC instruction set that performs data movement, data manipulation, branching, and other miscellaneous operations typical of a simple processor. Most instructions operate on two operands, and have the general form:

INSTRUCTION Operand1, Operand2

Typically, instruction operands will be one of the following:

- Direct
- Indirect
- Indirect with index
- Immediate

The following subsections explain these operands.

20.5.1 Direct Operands

When a direct operand is specified for an instruction, the data to operate upon is contained in one of the VM general-purpose registers **R0-R7**. Syntactically, an example of direct operand mode could be the [ADD](#) instruction:

ADD64 R1, R2

This form of the instruction utilizes two direct operands. For this particular instruction, the VM would take the contents of register **R2**, add it to the contents of register **R1**, and store the result in register **R1**.

20.5.2 Indirect Operands

When an indirect operand is specified, a VM register contains the address of the operand data. This is sometimes referred to as register indirect, and is indicated by prefixing the register operand with “@.” Syntactically, an example of an indirect operand mode could be this form of the ADD instruction:

```
ADD32 R1, @R2
```

For this instruction, the VM would take the 32-bit value at the address specified in **R2**, add it to the contents of register **R1**, and store the result in register **R1**.

20.5.3 Indirect with Index Operands

When an indirect with index operand is specified, the address of the operand is computed by adding the contents of a register to a decoded natural index that is included in the instruction. Typically with indexed addressing, the base address will be loaded in the register and an index value will be used to indicate the offset relative to this base address. Indexed addressing takes the form

```
@R1 (+n, +c)
```

where:

- **R₁** is one of the general-purpose registers (**R0-R7**) which contains the base address
- **+n** is a count of the number of “natural” units offset. This portion of the total offset is computed at runtime as $(n * \text{sizeof}(\text{VOID} *))$
- **+c** is a byte offset to add to the natural offset to resolve the total offset

The values of **n** and **c** can be either positive or negative, though they must both have the same sign. These values get encoded in the indexes associated with EBC instructions as shown in [Table 120](#). Indexes can be 16-, 32-, or 64-bits wide depending on the instruction. An example of indirect with index syntax would be:

```
ADD32 R1, @R2 (+1, +8)
```

This instruction would take the address in register **R2**, add $(8 + 1 * \text{sizeof}(\text{VOID} *))$, read the 32-bit value at the address, add the contents of **R1** to the value, and store the result back to **R1**.

20.5.4 Immediate Operands

Some instructions support an immediate operand, which is simply a value included in the instruction encoding. The immediate value may or may not be sign extended, depending on the particular instruction. One instruction that supports an immediate operand is [MOVI](#). An example usage of this instruction is:

```
MOVIww R1, 0x1234
```

This instruction moves the immediate value 0x1234 directly into VM register **R1**. The immediate value is contained directly in the encoding for the MOVI instruction.

20.6 EBC Instruction Syntax

Most EBC instructions have one or more variations that modify the size of the instruction and/or the behavior of the instruction itself. These variations will typically modify an instruction in one or more of the following ways:

- The size of the data being operated upon
- The addressing mode for the operands
- The size of index or immediate data
- To represent these variations syntactically in this specification the following conventions are used:
 - Natural indexes are indicated with the “Index” keyword, and may take the form of “Index16,” “Index32,” or “Index64” to indicate the size of the index value supported. Sometimes the form Index16|32|64 is used here, which is simply a shorthand notation for Index16|Index32|Index64. A natural index is encoded per [Table 120](#) and is resolved at runtime.
 - Immediate values are indicated with the “Immed” keyword, and may take the form of “Immed16,” “Immed32,” or “Immed64” to indicate the size of the immediate value supported. The shorthand notation Immed16|32|64 is sometimes used when different size immediate values are supported.
 - Terms in brackets [] are required.
 - Terms in braces { } are optional.
 - Alternate terms are separated by a vertical bar |.
 - The form R₁ and R₂ represent Operand 1 register and Operand 2 register respectfully, and can typically be any VM general-purpose register **R0-R7**.
 - Within descriptions of the instructions, brackets [] enclosing a register and/or index indicate that the contents of the memory pointed to by the enclosed contents are used.

20.7 Instruction Encoding

Most EBC instructions take the form:

INSTRUCTION R₁, R₂ Index|Immed

For those instructions that adhere to this form, the binary encoding for the instruction will typically consist of an opcode byte, followed by an operands byte, followed by two or more bytes of immediate or index data. Thus the instruction stream will be:

(1 Byte Opcode) + (1 Byte Operands) + (Immediate data|Index data)

20.7.1 Instruction Opcode Byte Encoding

The first byte of an instruction is the opcode byte, and an instruction’s actual opcode value consumes 6 bits of this byte. The remaining two bits will typically be used to indicate operand sizes and/or presence or absence of index or immediate data. [Table 122](#) defines the bits in the opcode byte for most instructions, and their usage.

Table 122. Opcode Byte Encoding

Bit	Sym	Description
6..7	Modifiers	One or more of: Index or immediate data present/absent Operand size Index or immediate data size
0..5	Op	Instruction opcode

For those instructions that use bit 7 to indicate the presence of an index or immediate data and bit 6 to indicate the size of the index or immediate data, if bit 7 is 0 (no immediate data), then bit 6 is ignored by the VM. Otherwise, unless otherwise specified for a given instruction, setting unused bits in the opcode byte results in an instruction encoding exception when the instruction is executed. Setting the modifiers field in the opcode byte to reserved values will also result in an instruction encoding exception.

20.7.2 Instruction Operands Byte Encoding

The second byte of most encoded instructions is an operand byte, which encodes the registers for the instruction operands and whether the operands are direct or indirect. [Table 123](#) defines the encoding for the operand byte for these instructions. Unless otherwise specified for a given instruction, setting unused bits in the operand byte results in an instruction encoding exception when the instruction is executed. Setting fields in the operand byte to reserved values will also result in an instruction encoding exception.

Table 123. Operand Byte Encoding

Bit	Description
7	0 = Operand 2 is direct 1 = Operand 2 is indirect
4..6	Operand 2 register
3	0 = Operand 1 is direct 1 = Operand 1 is indirect
0..2	Operand 1 register

20.7.3 Index/Immediate Data Encoding

Following the operand bytes for most instructions is the instruction's immediate data. The immediate data is, depending on the instruction and instruction encoding, either an unsigned or signed literal value, or an index encoded using natural encoding. In either case, the size of the immediate data is specified in the instruction encoding.

For most instructions, the index/immediate value in the instruction stream is interpreted as a signed immediate value if the register operand is direct. This immediate value is then added to the contents of the register to compute the instruction operand. If the register is indirect, then the data is usually interpreted as a natural index (see [Section 20.4](#)) and the computed index value is added to the contents of the register to get the address of the operand.

20.8 EBC Instruction Set

The following sections describe each of the EBC instructions in detail. Information includes an assembly-language syntax, a description of the instruction functionality, binary encoding, and any limitations or unique behaviors of the instruction.

ADD

Syntax

ADD[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Adds two signed operands and stores the result to Operand 1. The operation can be performed on either 32-bit (ADD32) or 64-bit (ADD64) operands.

Operation

Operand 1 <= **Operand 1** + **Operand 2**

Table 124. ADD Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x0C
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index and the Operand 2 value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the R₂ register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is ADD32 and Operand 1 is direct, then the result is stored back to the Operand 1 register with the upper 32 bits cleared.

AND

Syntax

AND [32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Performs a logical AND operation on two operands and stores the result to Operand 1. The operation can be performed on either 32-bit (AND32) or 64-bit (AND64) operands.

Operation

Operand 1 <= **Operand 1** AND **Operand 2**

Table 125. AND Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x14
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is AND32 and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

ASHR

Syntax

ASHR[32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Performs an arithmetic right-shift of a signed 32-bit (ASHR32) or 64-bit (ASHR64) operand and stores the result back to Operand 1

Operation

Operand 1 <= **Operand 1** SHIFT-RIGHT **Operand 2**

Table 126. ASHR Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x19
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R₂+ Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is ASHR32, and Operand 1 is direct, then the result is stored back to the Operand 1 register with the upper 32 bits cleared.

BREAK

Syntax

BREAK [**break code**]

Description

The BREAK instruction is used to perform special processing by the VM. The break code specifies the functionality to perform.

BREAK 0 – Runaway program break. This indicates that the VM is likely executing code from cleared memory. This results in a bad break exception.

BREAK 1 – Get virtual machine version. This instruction returns the 64-bit virtual machine revision number in VM register **R7**. The encoding is shown in [Table 127](#) and [Table 128](#). A VM that conforms to this version of the specification should return a version number of 0x00010000.

Table 127. VM Version Format

Bits	Description
63-32	Reserved = 0
31..16	VM major version
15..0	VM minor version

BREAK 3 – Debug breakpoint. Executing this instruction results in a debug break exception. If a debugger is attached or available, then it may halt execution of the image.

BREAK 4 – System call. There are no system calls supported for use with this break code, so the VM will ignore the instruction and continue execution at the following instruction.

BREAK 5 – Create thunk. This causes the interpreter to create a thunk for the EBC entry point whose 32-bit IP-relative offset is stored at the 64-bit address in VM register **R7**. The interpreter then replaces the contents of the memory location pointed to by **R7** to point to the newly created thunk. Since all EBC IP-relative offsets are relative to the next instruction or data object, the original offset is off by 4, so must be incremented by 4 to get the actual address of the entry point.

BREAK 6 – Set compiler version. An EBC C compiler can insert this break instruction into an executable to set the compiler version used to build an EBC image. When the VM executes this instruction it takes the compiler version from register **R7** and may perform version compatibility checking. The compiler version number follows the same format as the VM version number returned by the BREAK 1 instruction.

Table 128. BREAK Instruction Encoding

Byte	Description
0	Opcode = 0x00

Byte	Description
1	0 = Runaway program break 1 = Get virtual machine version 3 = Debug breakpoint 4 = System call 5 = Create thunk 6 = Set compiler version

Behaviors and Restrictions

- Executing an undefined BREAK code results in a bad break exception.
- Executing BREAK 0 results in a bad break exception.

CALL

Syntax

```
CALL32{EX}{a}  {@}R1  {Immed32 | Index32}
CALL64{EX}{a}  Immed64
```

Description

The CALL instruction pushes the address of the following instruction on the stack and jumps to a subroutine. The subroutine may be either EBC or native code, and may be to an absolute or **IP**-relative address. CALL32 is used to jump directly to EBC code within a given application, whereas CALLEX is used to jump to external code (either native or EBC), which requires thinking. Functionally, the CALL does the following:

```
R0 = R0 - 8;
PUSH64 ReturnAddress
if (Opcode.ImmedData64Bit) {
  if (Operands.EbcCall) {
    IP = Immed64;
  } else {
    NativeCall (Immed64);
  }
} else {
  if (Operand1 != R0) {
    Addr = Operand1;
  } else {
    Addr = Immed32;
  }
  if (Operands.EbcCall) {
    if (Operands.RelativeAddress) {
      IP += Addr + SizeOfThisInstruction;
    } else {
      IP = Addr
    }
  } else {
    if (Operands.RelativeAddress) {
      NativeCall (IP + Addr)
    } else {
      NativeCall (Addr)
    }
  }
}
```

Operation

```
R0 <= R0 - 16
[R0] <= IP + SizeOfThisInstruction
IP <= IP + SizeOfThisInstruction + Operand 1 (relative CALL)
IP <= Operand 1 (absolute CALL)
```

Table 129. CALL Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index data absent 1 = Immediate/index data present
	6	0 = CALL32 with 32-bit immediate data/index if present 1 = CALL64 with 64-bit immediate data
	0..5	Opcode = 0x03
1	Bit	Description
	6..7	Reserved = 0
	5	0 = Call to EBC 1 = Call to native code
	4	0 = Absolute address 1 = Relative address
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..5	Optional 32-bit index/immediate for CALL32	
2..9	Required 64-bit immediate data for CALL64	

BEHAVIOR AND RESTRICTIONS

- For the CALL32 forms, if Operand 1 is indirect, then the immediate data is interpreted as an index, and the Operand 1 value is fetched from memory address $[R_1 + \text{Index}_{32}]$.
- For the CALL32 forms, if Operand 1 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 1 register contents such that $\text{Operand 1} = R_1 + \text{Immed}_{32}$.
- For the CALLEX forms, the VM must fix up the stack pointer and execute a call to native code in a manner compatible with the native code such that the callee is able to access arguments passed on the VM stack..
- For the CALLEX forms, the value returned by the callee should be returned in **R7**.
- For the CALL64 forms, the Operand 1 fields are ignored.
- If $\text{Byte7:Bit6} = 1$ (CALL64), then Byte1:Bit4 is assumed to be 0 (absolute address)
- For CALL32 forms, if Operand 1 register = **R0**, then the register operand is ignored and only the immediate data is used in the calculation of the call address.
- Prior to the call, the VM will decrement the stack pointer **R0** by 16 bytes, and store the 64-bit return address on the stack.
- Offsets for relative calls are relative to the address of the instruction following the CALL instruction.

CMP

Syntax

CMP[32|64][eq|lte|gte|ulte|ugte] R₁, {@}R₂ {Index16|Immed16}

Description

The CMP instruction is used to compare Operand 1 to Operand 2. Supported comparison modes are =, <=, >=, unsigned <=, and unsigned >=. The comparison size can be 32 bits (CMP32) or 64 bits (CMP64). The effect of this instruction is to set or clear the condition code bit in the **Flags** register per the comparison results. The operands are compared as signed values except for the CMPulte and CMPugte forms.

Operation

CMPEq: **Flags.C** <= (Operand 1 == Operand 2)
CMPlte: **Flags.C** <= (Operand 1 <= Operand 2)
CMPgte: **Flags.C** <= (Operand 1 >= Operand 2)
CMPulte: **Flags.C** <= (Operand 1 <= Operand 2) (unsigned)
CMPugte: **Flags.C** <= (Operand 1 >= Operand 2) (unsigned)

Table 130. CMP Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index data absent 1 = Immediate/index data present
	6	0 = 32-bit comparison 1 = 64-bit comparison
	0..5	Opcode 0x05 = CMPEq compare equal 0x06 = CMPlte compare signed less then/equal 0x07 = CMPgte compare signed greater than/equal 0x08 = CMPulte compare unsigned less than/equal 0x09 = CMPugte compare unsigned greater than/equal
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	Reserved = 0
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory address $[R_2 + \text{Index}16]$.
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the register contents such that $\text{Operand 2} = R_2 + \text{Immed}16$.
- Only register direct is supported for Operand 1.

CMPI

Syntax

CMPI [**32** | **64**] {**w** | **d**} [**eq** | **lte** | **gte** | **ulte** | **ugte**] {**@**}**R₁** {**Index16**} ,
Immed16 | **Immed32**

Description

Compares two operands, one of which is an immediate value, for =, <=, >=, unsigned <=, or unsigned >=, and sets or clears the condition flag bit in the **Flags** register accordingly. Comparisons can be performed on a 32-bit (CMPI32) or 64-bit (CMPI64) basis. The size of the immediate data can be either 16 bits (CMPIw) or 32 bits (CMPId).

Operation

CMPIeq: Flags.C <= (Operand 1 == Operand 2)
CMPIlte: Flags.C <= (Operand 1 <= Operand 2)
CMPIgte: Flags.C <= (Operand 1 >= Operand 2)
CMPIulte: Flags.C <= (Operand 1 <= Operand 2)
CMPIugte: Flags.C <= (Operand 1 >= Operand 2)

Table 131. CMPI Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = 16-bit immediate data 1 = 32-bit immediate data
	6	0 = 32-bit comparison 1 = 64-bit comparison
	0..5	Opcode 0x2D = CMPIeq compare equal 0x2E = CMPIlte compare signed less than/equal 0x2F = CMPIgte compare signed greater than/equal 0x30 = CMPIulte compare unsigned less than/equal 0x31 = CMPIugte compare unsigned greater than/equal
1	Bit	Description
	5..7	Reserved = 0
	4	0 = Operand 1 index absent 1 = Operand 1 index present
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit Operand 1 index	
2..3/4..5	16-bit immediate data	
2..5/4..7	32-bit immediate data	

Behaviors and Restrictions

- The immediate data is fetched as a signed value.
- If the immediate data is smaller than the comparison size, then the immediate data is sign-extended appropriately.
- If Operand 1 is direct, and an Operand 1 index is specified, then an instruction encoding exception is generated.

DIV

Syntax

DIV[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Performs a divide operation on two signed operands and stores the result to Operand 1. The operation can be performed on either 32-bit (DIV32) or 64-bit (DIV64) operands.

Operation

Operand 1 <= **Operand 1** / **Operand 2**

Table 132. DIV Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x10
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R₂+ Index16].
- If Operand 2 is direct, then the immediate data is considered a signed value and is added to the register contents such that Operand 2 = R₂ + Immed16
- If the instruction is DIV32 form, and Operand 1 is direct, then the upper 32 bits of the result are set to 0 before storing to the Operand 1 register.
- A divide-by-0 exception occurs if Operand 2 = 0.

DIVU

Syntax

DIVU[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Performs a divide operation on two unsigned operands and stores the result to Operand 1. The operation can be performed on either 32-bit (DIVU32) or 64-bit (DIVU64) operands.

Operation

Operand 1 <= **Operand 1** / **Operand 2**

Table 133. DIVU Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x11
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the value is fetched from memory as an unsigned value at address [R₂+ Index16].
- If Operand 2 is direct, then the immediate data is considered an unsigned value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16
- For the DIVU32 form, if Operand 1 is direct then the upper 32 bits of the result are set to 0 before storing back to the Operand 1 register.
- A divide-by-0 exception occurs if Operand 2 = 0.

EXTNDB

Syntax

EXTNDB[32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Sign-extend a byte value and store the result to Operand 1. The byte can be signed extended to 32 bits (EXTNDB32) or 64 bits (EXTNDB64).

Operation

Operand 1 <= (sign extended) **Operand 2**

Table 134. EXTNDB Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x1A
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the byte Operand 2 value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value, is added to the signed-extended byte from the Operand 2 register, and the byte result is sign extended to 32 or 64 bits.
- If the instruction is EXTNDB32 and Operand 1 is direct, then the 32-bit result is stored in the Operand 1 register with the upper 32 bits cleared.

EXTNDD

Syntax

EXTNDD [32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Sign-extend a 32-bit Operand 2 value and store the result to Operand 1. The Operand 2 value can be extended to 32 bits (EXTNDD32) or 64 bits (EXTNDD64).

Operation

Operand 1 <= (sign extended) **Operand 2**

Table 135. EXTNDD Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x1C
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the 32-bit value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value such that Operand 2 = R₂ + Immed16, and the value is sign extended to 32 or 64 bits accordingly.
- If the instruction is EXTNDD32 and Operand 1 is direct, then the result is stored in the Operand 1 register with the upper 32 bits cleared.

EXTNDW

Syntax

EXTNDW[32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Sign-extend a 16-bit Operand 2 value and store the result back to Operand 1. The value can be signed extended to 32 bits (EXTNDW32) or 64 bits (EXTNDW64).

Operation

Operand 1 <= (sign extended) **Operand 2**

Table 136. EXTNDW Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x1B
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the word value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value such that Operand 2 = R₂ + Immed16, and the value is sign extended to 32 or 64 bits accordingly.
- If the instruction is EXTNDW32 and Operand 1 is direct, then the 32-bit result is stored in the Operand 1 register with the upper 32 bits cleared.

JMP

Syntax

```
JMP32{cs|cc} {@}R1 {Immed32|Index32}
JMP64{cs|cc} Immed64
```

Description

The JMP instruction is used to conditionally or unconditionally jump to a relative or absolute address and continue executing EBC instructions. The condition test is done using the condition bit in the VM **Flags** register. The JMP64 form only supports an immediate value that can be used for either a relative or absolute jump. The JMP32 form adds support for indirect addressing of the JMP offset or address. The JMP is implemented as:

```
if (ConditionMet) {
    if (Operand.RelativeJump) {
        IP += Operand1 + SizeOfThisInstruction;
    } else {
        IP = Operand1;
    }
}
```

Operation

```
IP <= Operand 1 (absolute address)
IP <= IP + SizeOfThisInstruction + Operand 1 (relative address)
```

Table 137. JMP Instruction Encoding

Byte	Description	
0	Bit	Description
	7	0 = Immediate/index data absent 1 = Immediate/index data present
	6	0 = JMP32 1 = JMP64
	0..5	Opcode = 0x01
1	Bit	Description
	7	0 = Unconditional jump 1 = Conditional jump
	6	0 = Jump if Flags.C is clear (cc) 1 = Jump if Flags.C is set (cs)
	5	Reserved = 0
	4	0 = Absolute address 1 = Relative address
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1

Byte	Description
2..5	Optional 32-bit immediate data/index for JMP32
2..9	64-bit immediate data for JMP64

Behaviors and Restrictions

- Operand 1 fields are ignored for the JMP64 forms
- If the instruction is JMP32, and Operand 1 register = **R0**, then the register contents are assumed to be 0.
- If the instruction is JMP32, and Operand 1 is indirect, then the immediate data is interpreted as an index, and the jump offset or address is fetched as a 32-bit signed value from address $[R_1 + \text{Index32}]$
- If the instruction is JMP32, and Operand 1 is direct, then the immediate data is considered a signed immediate value such that $\text{Operand 1} = R_1 + \text{Immed32}$
- If the jump is unconditional, then Byte1:Bit6 (condition) is ignored
- If the instruction is JMP64, and Byte0:Bit7 is clear (no immediate data), then an instruction encoding exception is generated.
- If the instruction is JMP32, and Operand 2 is indirect, then the Operand 2 value is read as a natural value from memory address $[R_1 + \text{Index32}]$
- An alignment check exception is generated if the jump is taken and the target address is odd.

JMP8

Syntax

JMP8{cs|cc} **Immed8**

Description

Conditionally or unconditionally jump to a relative offset and continue execution. The offset is a signed one-byte offset specified in the number of words. The offset is relative to the start of the following instruction.

Operation

IP = IP + SizeOfThisInstruction + (Immed8 * 2)

Table 138. JMP8 Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Unconditional jump 1 = Conditional jump
	6	0 = Jump if Flags.C is clear (cc) 1 = Jump if Flags.C is set (cs)
	0..5	Opcode = 0x02
1	Immediate data (signed word offset)	

Behaviors and Restrictions

- If the jump is unconditional, then Byte0:Bit6 (condition) is ignored

LOADSP

Syntax

LOADSP [**Flags**], **R₂**

Description

This instruction loads a VM dedicated register with the contents of a VM general-purpose register **R0-R7**. The dedicated register is specified by its index as shown in [Table 118](#).

Operation

Operand 1 \leftarrow **R₂**

Table 139. LOADSP Instruction Encoding

BYTE	Description	
0	Bit	Description
	6..7	Reserved = 0
	0..5	Opcode = 0x29
1	7	Reserved
	4..6	Operand 2 general purpose register
	3	Reserved
	0..2	Operand 1 dedicated register index

Behaviors and Restrictions

- Attempting to load any register (Operand 1) other than the **Flags** register results in an instruction encoding exception.
- Specifying a reserved dedicated register index results in an instruction encoding exception.
- If Operand 1 is the **Flags** register, then reserved bits in the **Flags** register are not modified by this instruction.

MOD

Syntax

MOD [32|64] {@}R₁, {@}R₂ {Index16|Immed16}

Description

Perform a modulus on two signed 32-bit (MOD32) or 64-bit (MOD64) operands and store the result to Operand 1.

Operation

Operand 1 <= **Operand 1** MOD **Operand 2**

Table 140. MOD Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x12
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value such that Operand 2 = R₂ + Immed16, and the value is sign extended to 32 or 64 bits accordingly.
- If Operand 2 = 0, then a divide-by-zero exception is generated.

MODU

Syntax

MODU[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Perform a modulus on two unsigned 32-bit (MODU32) or 64-bit (MODU64) operands and store the result to Operand 1.

Operation

Operand 1 <= **Operand 1** MOD **Operand 2**

Table 141. MODU Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x13
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered an unsigned immediate value such that Operand 2 = R₂ + Immed16.
- If Operand 2 = 0, then a divide-by-zero exception is generated.

MOV

Syntax

```
MOV[b|w|d|q]{w|d} {@}R1 {Index16|32}, {@}R2 {Index16|32}
MOVqq {@}R1 {Index64}, {@}R2 {Index64}
```

Description

This instruction moves data from Operand 2 to Operand 1. Both operands can be indexed, though both indexes are the same size. In the instruction syntax for the first form, the first variable character indicates the size of the data move, which can be 8 bits (b), 16 bits (w), 32 bits (d), or 64 bits (q). The optional character indicates the presence and size of the index value(s), which may be 16 bits (w) or 32 bits (d). The MOVqq instruction adds support for 64-bit indexes.

Operation

```
Operand 1 <= Operand 2
```

Table 142. MOV Instruction Encoding

Byte	Description		
0	Bit	Description	
	7	0 = Operand 1 index absent 1 = Operand 1 index present	
	6	0 = Operand 2 index absent 1 = Operand 2 index present	
1	0..5	0x1D = MOVbw opcode 0x1E = MOVww opcode 0x1F = MOVdw opcode 0x20 = MOVqw opcode 0x21 = MOVbd opcode 0x22 = MOVwd opcode 0x23 = MOVdd opcode 0x24 = MOVqd opcode 0x28 = MOVqq opcode	
	Bit	Description	
	7	0 = Operand 2 direct 1 = Operand 2 indirect	
	4..6	Operand 2	
	3	0 = Operand 1 direct 1 = Operand 1 indirect	
	0..2	Operand 1	
	2..3	Optional Operand 1 16-bit index	
	2..3/4..5	Optional Operand 2 16-bit index	
	2..5	Optional Operand 1 32-bit index	
2..5/6..9	Optional Operand 2 32-bit index		

Byte	Description
2..9	Optional Operand 1 64-bit index (MOVqq)
2..9/10..17	Optional Operand 2 64-bit index (MOVqq)

Behaviors and Restrictions

- If an index is specified for Operand 1, and Operand 1 is direct, then an instruction encoding exception is generated.

MOVI

Syntax

MOVI [b|w|d|q] [w|d|q] {@}R₁ {Index16}, Immed16|32|64

Description

This instruction moves a signed immediate value to Operand 1. In the instruction syntax, the first variable character specifies the width of the move, which may be 8 bits (b), 16 bits (w), 32-bits (d), or 64 bits (q). The second variable character specifies the width of the immediate data, which may be 16 bits (w), 32 bits (d), or 64 bits (q).

Operation

Operand 1 <= **Operand 2**

Table 143. MOVI Instruction Encoding

BYTE	Description	
0	Bit	Description
	6..7	0 = Reserved 1 = Immediate data is 16 bits (w) 2 = Immediate data is 32 bits (d) 3 = Immediate data is 64 bits (q)
	0..5	Opcode = 0x37
1	Bit	Description
	7	Reserved = 0
	6	0 = Operand 1 index absent 1 = Operand 1 index present
	4..5	0 = 8 bit (b) move 1 = 16 bit (w) move 2 = 32 bit (d) move 3 = 64 bit (q) move
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit index	
2..3/4..5	16-bit immediate data	
2..5/4..7	32-bit immediate data	
2..9/4..11	64-bit immediate data	

Behaviors and Restrictions

- Specifying an index value with Operand 1 direct results in an instruction encoding exception.
- If the immediate data is smaller than the move size, then the value is sign-extended to the width of the move.

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- If Operand 1 is a register, then the value is stored to the register with bits beyond the move size cleared.

MOVIn

Syntax

MOVIn[w|d|q] {@}R₁ {Index16}, Index16|32|64

Description

This instruction moves an indexed value of form (+n,+c) to Operand 1. The index value is converted from (+n, +c) format to a signed offset per the encoding described in [Table 120](#). The size of the Operand 2 index data can be 16 (w), 32 (d), or 64 (q) bits.

Operation

Operand 1 <= Operand 2 (index value)

Table 144. MOVIn Instruction Encoding

BYTE	Description	
0	Bit	Description
	6..7	0 = Reserved 1 = Operand 2 index value is 16 bits (w) 2 = Operand 2 index value is 32 bits (d) 3 = Operand 2 index value is 64 bits (q)
	0..5	Opcode = 0x38
1	Bit	Description
	7	Reserved
	6	0 = Operand 1 index absent 1 = Operand 1 index present
	4..5	Reserved = 0
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit Operand 1 index	
2..3/4..5	16-bit Operand 2 index	
2..5/4..7	32-bit Operand 2 index	
2..9/4..11	64-bit Operand 2 index	

Behaviors and Restrictions

- Specifying an Operand 1 index when Operand 1 is direct results in an instruction encoding exception.
- The Operand 2 index is sign extended to the size of the move if necessary.
- If the Operand 2 index size is smaller than the move size, then the value is truncated.
- If Operand 1 is direct, then the Operand 2 value is sign extended to 64 bits and stored to the Operand 1 register.

MOVn

Syntax

MOVn{w|d} {@}R₁ {Index16|32}, {@}R₂ {Index16|32}

Description

This instruction loads an unsigned natural value from Operand 2 and stores the value to Operand 1. Both operands can be indexed, though both operand indexes are the same size. The operand index(s) can be 16 bits (w) or 32 bits (d).

Operation

Operand1 <= (UINTN)Operand2

Table 145. MOVn Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 1 index absent 1 = Operand 1 index present
	6	0 = Operand 2 index absent 1 = Operand 2 index present
	0..5	0x32 = MOVnw opcode 0x33 = MOVnd opcode
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional Operand 1 16-bit index	
2..3/4..5	Optional Operand 2 16-bit index	
2..5	Optional Operand 1 32-bit index	
2..5/6..9	Optional Operand 2 32-bit index	

Behaviors and Restrictions

- If an index is specified for Operand 2, and Operand 2 register is direct, then the Operand 2 index value is added to the register contents such that Operand 2 = (UINTN)(R₂ + Index).
- If an index is specified for Operand 1, and Operand 1 is direct, then an instruction encoding exception is generated.
- If Operand 1 is direct, then the Operand 2 value will be 0-extended to 64 bits on a 32-bit machine before storing to the Operand 1 register.

MOVREL

Syntax

MOVREL[w|d|q] {**@**}R₁ {**Index16**}, **Immed16|32|64**

Description

This instruction fetches data at an **IP**-relative immediate offset (Operand 2) and stores the result to Operand 1. The offset is a signed offset relative to the following instruction. The fetched data is unsigned and may be 16 (w), 32 (d), or 64 (q) bits in size.

Operation

Operand 1 <= [**IP** + **SizeOfThisInstruction** + **Immed**]

Table 146. MOVREL Instruction Encoding

BYTE	Description	
0	Bit	Description
	6..7	0 = Reserved 1 = Immediate data is 16 bits (w) 2 = Immediate data is 32 bits (d) 3 = Immediate data is 64 bits (q)
	0..5	Opcod = 0x39
1	Bit	Description
	7	Reserved = 0
	6	0 = Operand 1 index absent 1 = Operand 1 index present
	4..5	Reserved = 0
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit Operand 1 index	
2..3/4..5	16-bit immediate offset	
2..5/4..7	32-bit immediate offset	
2..9/4..11	64-bit immediate offset	

Behaviors and Restrictions

- If an Operand 1 index is specified and Operand 1 is direct, then an instruction encoding exception is generated.

MOVsn

Syntax

MOVsn{w} {@}R₁, {Index16}, {@}R₂ {Index16|Immed16}

MOVsn{d} {@}R₁ {Index32}, {@}R₂ {Index32|Immed32}

Description

Moves a signed natural value from Operand 2 to Operand 1. Both operands can be indexed, though the indexes are the same size. Indexes can be either 16 bits (MOVsnw) or 32 bits (MOVsnd) in size.

Operation

Operand 1 <= Operand 2

Table 147. MOVsn Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 1 index absent 1 = Operand 1 index present
	6	0 = Operand 2 index/immediate data absent 1 = Operand 2 index/immediate data present
	0..5	0x25 = MOVsnw opcode 0x26 = MOVsnd opcode
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit Operand 1 index (MOVsnw)	
2..3/4..5	Optional 16-bit Operand 2 index (MOVsnw)	
2..5	Optional 32-bit Operand 1 index/immediate data (MOVsnd)	
2..5/6..9	Optional 32-bit Operand 2 index/immediate data (MOVsnd)	

Behaviors and Restrictions

- If Operand 2 is direct, and Operand 2 index/immediate data is specified, then the immediate value is read as a signed immediate value and is added to the contents of Operand 2 register such that $\text{Operand 2} = R_2 + \text{Immed}$.
- If Operand 2 is indirect, and Operand 2 index/immediate data is specified, then the immediate data is interpreted as an index and the Operand 2 value is fetched from memory as a signed value at address $[R_2 + \text{Index16}]$.

- If an index is specified for Operand 1, and Operand 1 is direct, then an instruction encoding exception is generated.
- If Operand 1 is direct, then the Operand 2 value is sign-extended to 64-bits on 32-bit native machines.

MUL

Syntax

MUL[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Perform a signed multiply of two operands and store the result back to Operand 1. The operands can be either 32 bits (MUL32) or 64 bits (MUL64).

Operation

Operand 1 <= **Operand** * **Operand 2**

Table 148. MUL Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x0E
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit Operand 2 immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is MUL32, and Operand 1 is direct, then the result is stored to Operand 1 register with the upper 32 bits cleared.

MULU

Syntax

MULU[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Performs an unsigned multiply of two 32-bit (MULU32) or 64-bit (MULU64) operands, and stores the result back to Operand 1.

Operation

Operand 1 <= **Operand** * **Operand 2**

Table 149. MULU Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x0F
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is MULU32 and Operand 1 is direct, then the result is written to the Operand 1 register with the upper 32 bits cleared.

NEG

Syntax

NEG[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Multiply Operand 2 by negative 1, and store the result back to Operand 1. Operand 2 is a signed value and fetched as either a 32-bit (NEG32) or 64-bit (NEG64) value.

Operation

Operand 1 <= -1 * **Operand 2**

Table 150. NEG Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x0B
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is NEG32 and Operand 1 is direct, then the result is stored in Operand 1 register with the upper 32-bits cleared.

NOT

Syntax

NOT[32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Performs a logical NOT operation on Operand 2, an unsigned 32-bit (NOT32) or 64-bit (NOT64) value, and stores the result back to Operand 1.

Operation

Operand 1 <= **NOT** **Operand 2**

Table 151. NOT Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x0A
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is NOT32 and Operand 1 is a register, then the result is stored in the Operand 1 register with the upper 32 bits cleared.

OR

Syntax

OR[32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Performs a bit-wise OR of two 32-bit (OR32) or 64-bit (OR64) operands, and stores the result back to Operand 1.

Operation

Operand 1 <= **Operand 1** OR **Operand 2**

Table 152. OR Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x15
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is OR32 and Operand 1 is direct, then the result is stored to Operand 1 register with the upper 32 bits cleared.

POP

Syntax

POP [32 | 64] {**@**}**R**₁ {**Index16** | **Immed16**}

Description

This instruction pops a 32-bit (POP32) or 64-bit (POP64) value from the stack, stores the result to Operand 1, and adjusts the stack pointer **R0** accordingly.

Operation

Operand 1 <= [**R0**]
R0 <= **R0** + 4 (POP32)
R0 <= **R0** + 8 (POP64)

Table 153. POP Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x2C
1	Bit	Description
	7..4	Reserved = 0
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is read as a signed value and is added to the value popped from the stack, and the result stored to the Operand 1 register.
- If Operand 1 is indirect, then the immediate data is interpreted as an index, and the value popped from the stack is stored to address [**R**₁ + **Index16**].
- If the instruction is POP32, and Operand 1 is direct, then the popped value is sign-extended to 64 bits before storing to the Operand 1 register.

POPn

Syntax

```
POPn {@}R1 {Index16|Immed16}
```

Description

Read an unsigned natural value from memory pointed to by stack pointer **R0**, adjust the stack pointer accordingly, and store the value back to Operand 1.

Operation

```
Operand 1 <= (UINTN) [R0]
R0 <= R0 + sizeof (VOID *)
```

Table 154. POPn Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	Reserved = 0
	0..5	Opcode = 0x36
1	Bit	Description
	7..4	Reserved = 0
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is fetched as a signed value and is added to the value popped from the stack and the result is stored back to the Operand 1 register.
- If Operand 1 is indirect, and an index/immediate data is specified, then the immediate data is interpreted as a natural index and the value popped from the stack is stored at $[R_1 + \text{Index16}]$.
- If Operand 1 is direct, and the instruction is executed on a 32-bit machine, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

PUSH

Syntax

PUSH[32|64] {**@**}**R**₁ {**Index16|Immed16**}

Description

Adjust the stack pointer **R0** and store a 32-bit (PUSH32) or 64-bit (PUSH64) Operand 1 value on the stack.

Operation

R0 <= **R0** - 4 (PUSH32)

R0 <= **R0** - 8 (PUSH64)

[**R0**] <= **Operand 1**

Table 155. PUSH Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x2B
1	Bit	Description
	7..4	Reserved = 0
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is read as a signed value and is added to the Operand 1 register contents such that $\text{Operand 1} = R_1 + \text{Immed16}$.
- If Operand 1 is indirect, and an index/immediate data is specified, then the immediate data is interpreted as a natural index and the pushed value is read from $[R_1 + \text{Index16}]$.

PUSHn

Syntax

PUSHn {@}R₁ {Index16|Immed16}

Description

Adjust the stack pointer **R0**, and store a natural value on the stack.

Operation

R0 <= **R0** - sizeof (VOID *)
[R0] <= Operand 1

Table 156. PUSHn Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Immediate/index absent 1 = Immediate/index present
	6	Reserved = 0
	0..5	Opcode = 0x35
1	Bit	Description
	7..4	Reserved = 0
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is fetched as a signed value and is added to the Operand 1 register contents such that Operand 1 = R₁ + Immed16.
- If Operand 1 is indirect, and an index/immediate data is specified, then the immediate data is interpreted as a natural index and the Operand 1 value pushed is fetched from [R₁ + Index16].

RET

Syntax

RET

Description

This instruction fetches the return address from the stack, sets the **IP** to the value, adjusts the stack pointer register **R0**, and continues execution at the return address. If the RET is a final return from the EBC driver, then execution control returns to the caller, which may be EBC or native code.

Operation

IP <= [R0]
R0 <= R0 + 16

Table 157. RET Instruction Encoding

BYTE	Description	
0	Bit	Description
	6..7	Reserved = 0
	0..5	Opcode = 0x04
1	Reserved = 0	

Behaviors and Restrictions

- An alignment exception will be generated if the return address is not aligned on a 16-bit boundary.

SHL

Syntax

SHL[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Left-shifts Operand 1 by Operand 2 bit positions and stores the result back to Operand 1. The operand sizes may be either 32-bits (SHL32) or 64 bits (SHL64).

Operation

Operand 1 <= **Operand 1** << **Operand 2**

Table 158. SHL Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x17
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is SHL32, and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

SHR

Syntax

SHR[32|64] {**@**}R₁, {**@**}R₂ {**Index16|Immed16**}

Description

Right-shifts unsigned Operand 1 by Operand 2 bit positions and stores the result back to Operand 1. The operand sizes may be either 32-bits (SHR32) or 64 bits (SHR64).

Operation

Operand 1 <= **Operand 1** >> **Operand 2**

Table 159. SHR Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x18
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is SHR32, and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

STORESP

Syntax

STORESP R_1 , [IP|Flags]

Description

This instruction transfers the contents of a dedicated register to a general-purpose register. See [Table 118](#) for the VM dedicated registers and their corresponding index values.

Operation

Operand 1 \leftarrow **Operand 2**

Table 160. STORESP Instruction Encoding

BYTE	Description	
0	Bit	Description
	6..7	Reserved = 0
	0..5	Opcode = 0x2A
1	7	Reserved = 0
	4..6	Operand 2 dedicated register index
	3	Reserved = 0
	0..2	Operand 1 general purpose register

Behaviors and Restrictions

- Specifying an invalid dedicated register index results in an instruction encoding exception.

SUB

Syntax

SUB[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Subtracts a 32-bit (SUB32) or 64-bit (SUB64) signed Operand 2 value from a signed Operand 1 value of the same size, and stores the result to Operand 1.

Operation

Operand 1 <= **Operand 1** - **Operand 2**

Table 161. SUB Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x0D
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is SUB32 and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

XOR

Syntax

XOR[32|64] {**@**}R₁, {**@**}R₂ {**Index16**|**Immed16**}

Description

Performs a bit-wise exclusive OR of two 32-bit (XOR32) or 64-bit (XOR64) operands, and stores the result back to Operand 1.

Operation

Operand 1 <= **Operand 1 XOR Operand 2**

Table 162. XOR Instruction Encoding

BYTE	Description	
0	Bit	Description
	7	0 = Operand 2 immediate/index absent 1 = Operand 2 immediate/index present
	6	0 = 32-bit operation 1 = 64-bit operation
	0..5	Opcode = 0x16
1	Bit	Description
	7	0 = Operand 2 direct 1 = Operand 2 indirect
	4..6	Operand 2
	3	0 = Operand 1 direct 1 = Operand 1 indirect
	0..2	Operand 1
2..3	Optional 16-bit immediate data/index	

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R₂ + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R₂ + Immed16.
- If the instruction is XOR32 and Operand1 is direct, then the result is stored to the Operand 1 register with the upper 32-bits cleared.

20.9 Runtime and Software Conventions

20.9.1 Calling Outside VM

Calls can be made to routines in other modules that are native or in another VM. It is the responsibility of the calling VM to prepare the outgoing arguments correctly to make the call outside the VM. It is also the responsibility of the VM to prepare the incoming arguments correctly for the call from outside the VM. Calls outside the VM must use the [CALLEX](#) instruction.

20.9.2 Calling Inside VM

Calls inside VM can be made either directly using the [CALL](#) or [CALLEX](#) instructions. Using direct CALL instructions is an optimization.

20.9.3 Parameter Passing

Parameters are pushed on the VM stack per the CDECL calling convention. Per this convention, the last argument in the parameter list is pushed on the stack first, and the first argument in the parameter list is pushed on the stack last.

All parameters are stored or accessed as natural size (using naturally sized instruction) except 64-bit integers, which are pushed as 64-bit values. 32-bit integers are pushed as natural size (since they should be passed as 64-bit parameter values on 64-bit machines).

20.9.4 Return Values

Return values of 8 bytes or less in size are returned in general-purpose register **R7**. Return values larger than 8 bytes are not supported.

20.9.5 Binary Format

PE32+ format will be used for generating binaries for the VM. A VarBss section will be included in the binary image. All global and static variables will be placed in this section. The size of the section will be based on worst-case 64-bit pointers. Initialized data and pointers will also be placed in the VarBss section, with the compiler generating code to initialize the values at runtime.

20.10 Architectural Requirements

This section provides a high level overview of the architectural requirements that are necessary to support execution of EBC on a platform.

20.10.1 EBC Image Requirements

All EBC images will be PE32+ format. Some minor additions to the format will be required to support EBC images. See the *Microsoft Portable Executable and Common Object File Format Specification* pointed to in [Appendix Q](#) for details of this image file format.

A given EBC image must be executable on different platforms, independent of whether it is a 32- or 64-bit processor. All EBC images should be driver implementations.

20.10.2 EBC Execution Interfacing Requirements

EBC drivers will typically be designed to execute in an (usually preboot) EFI environment. As such, EBC drivers must be able to invoke protocols and expose protocols for use by other drivers or applications. The following execution transitions must be supported:

- EBC calling EBC
- EBC calling native code
- Native code calling EBC
- Native code calling native code
- Returning from all the above transitions

Obviously native code calling native code is available by default, so is not discussed in this document.

To maintain backward compatibility with existing native code, and minimize the overhead for non-EBC drivers calling EBC protocols, all four transitions must be seamless from the application perspective. Therefore, drivers, whether EBC or native, shall not be required to have any knowledge of whether or not the calling code, or the code being called, is native or EBC compiled code. The onus is put on the tools and interpreter to support this requirement.

20.10.3 Interfacing Function Parameters Requirements

To allow code execution across protocol boundaries, the interpreter must ensure that parameters passed across execution transitions are handled in the same manner as the standard parameter passing convention for the native processor.

20.10.4 Function Return Requirements

The interpreter must support standard function returns to resume execution to the caller of external protocols. The details of this requirement are specific to the native processor. The called function must not be required to have any knowledge of whether or not the caller is EBC or native code.

20.10.5 Function Return Values Requirements

The interpreter must support standard function return values from called protocols. The exact implementation of this functionality is dependent on the native processor. This requirement applies to return values of 64 bits or less. The called function must not be required to have any knowledge of whether or not the caller is EBC or native code. Note that returning of structures is not supported.

20.11 EBC Interpreter Protocol

The EFI EBC protocol provides services to execute EBC images, which will typically be loaded into option ROMs.

EFI_EBC_PROTOCOL

Summary

This protocol provides the services that allow execution of EBC images.

GUID

```
#define EFI_EBC_PROTOCOL_GUID \
{0x13AC6DD1, 0x73D0, 0x11D4, 0xB0, 0x6B, 0x00, 0xAA, 0x00, 0xBD, \
  0x6D, 0xE7}
```

Protocol Interface Structure

```
typedef struct _EFI_EBC_PROTOCOL {
    EFI_EBC_CREATE_THUNK           CreateThunk;
    EFI_EBC_UNLOAD_IMAGE           UnloadImage;
    EFI_EBC_REGISTER_ICACHE_FLUSH RegisterICacheFlush;
    EFI_EBC_GET_VERSION            GetVersion;
} EFI_EBC_PROTOCOL;
```

Parameters

<i>CreateThunk</i>	Creates a thunk for an EBC image entry point or protocol service, and returns a pointer to the thunk. See the CreateThunk () function description.
<i>UnloadImage</i>	Called when an EBC image is unloaded to allow the interpreter to perform any cleanup associated with the image's execution. See the UnloadImage () function description.
<i>RegisterICacheFlush</i>	Called to register a callback function that the EBC interpreter can call to flush the processor instruction cache after creating thunks. See the RegisterICacheFlush () function description.
<i>GetVersion</i>	Called to get the version of the associated EBC interpreter. See the GetVersion () function description.

Description

The EFI EBC protocol provides services to load and execute EBC images, which will typically be loaded into option ROMs. The image loader will load the EBC image, perform standard relocations, and invoke the [CreateThunk \(\)](#) service to create a thunk for the EBC image's entry point. The image can then be run using the standard EFI start image services.

EFI_EBC_PROTOCOL.CreateThunk()

Summary

Creates a thunk for an EBC entry point, returning the address of the thunk.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_EBC_CREATE_THUNK) (
    IN EFI_EBC_PROTOCOL      *This,
    IN EFI_HANDLE            ImageHandle,
    IN VOID                  *EbcEntryPoint,
    OUT VOID                  **Thunk
);
```

Parameters

<i>This</i>	A pointer to the EFI_EBC_PROTOCOL instance. This protocol is defined in Section 20.11 .
<i>ImageHandle</i>	Handle of image for which the thunk is being created.
<i>EbcEntryPoint</i>	Address of the actual EBC entry point or protocol service the thunk should call.
<i>Thunk</i>	Returned pointer to a thunk created.

Description

A PE32+ EBC image, like any other PE32+ image, contains an optional header that specifies the entry point for image execution. However for EBC images this is the entry point of EBC instructions, so is not directly executable by the native processor. Therefore when an EBC image is loaded, the loader must call this service to get a pointer to native code (thunk) that can be executed which will invoke the interpreter to begin execution at the original EBC entry point.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_INVALID_PARAMETER	Image entry point is not 2-byte aligned.
EFI_OUT_OF_RESOURCES	Memory could not be allocated for the thunk.

EFI_EBC_PROTOCOL.UnloadImage()

Summary

Called prior to unloading an EBC image from memory.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_EBC_UNLOAD_IMAGE) (
    IN EFI_EBC_PROTOCOL      *This,
    IN EFI_HANDLE            ImageHandle
);
```

Parameters

This

A pointer to the [EFI_EBC_PROTOCOL](#) instance. This protocol is defined in [Section 20.11](#).

ImageHandle

Image handle of the EBC image that is being unloaded from memory.

Description

This function is called after an EBC image has exited, but before the image is actually unloaded. It is intended to provide the interpreter with the opportunity to perform any cleanup that may be necessary as a result of loading and executing the image.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_INVALID_PARAMETER	Image handle is not recognized as belonging to an EBC image that has been executed.

EFI_EBC_PROTOCOL.RegisterICacheFlush()

Summary

Registers a callback function that the EBC interpreter calls to flush the processor instruction cache following creation of thunks.

Prototype

```
typedef
EFI_STATUS
(* EFI_EBC_REGISTER_ICACHE_FLUSH) (
    IN EFI_EBC_PROTOCOL           *This,
    IN EBC_ICACHE_FLUSH          Flush
);
```

Parameters

<i>This</i>	A pointer to the EFI_EBC_PROTOCOL instance. This protocol is defined in Section 20.11 .
<i>Flush</i>	Pointer to a function of type EBC_ICACH_FLUSH . See “Related Definitions” below for a detailed description of this type.

Related Definitions

```
typedef
EFI_STATUS
(* EBC_ICACHE_FLUSH) (
    IN EFI_PHYSICAL_ADDRESS      Start,
    IN UINT64                    Length
);
```

<i>Start</i>	The beginning physical address to flush from the processor’s instruction cache.
<i>Length</i>	The number of bytes to flush from the processor’s instruction cache.

This is the prototype for the *Flush* callback routine. A pointer to a routine of this type is passed to the EBC [EFI_EBC_REGISTER_ICACHE_FLUSH](#) protocol service.

Description

An EBC image’s original PE32+ entry point is not directly executable by the native processor. Therefore to execute an EBC image, a thunk (which invokes the EBC interpreter for the image’s original entry point) must be created for the entry point, and the thunk is executed when the EBC image is started. Since the thunks may be created on-the-fly in memory, the processor’s instruction cache may require to be flushed after thunks are created. The caller to this EBC service can provide a pointer to a function to flush the instruction cache for any thunks created after the [CreateThunk \(\)](#) service has been called. If an instruction-cache flush callback is not provided to

the interpreter, then the interpreter assumes the system has no instruction cache, or that flushing the cache is not required following creation of thunks.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
-------------	--------------------------------------

EFI_EBC_PROTOCOL.GetVersion()

Summary

Called to get the version of the interpreter.

Prototype

```
typedef
EFI_STATUS
(* EFI_EBC_GET_VERSION) (
    IN EFI_EBC_PROTOCOL      *This,
    OUT UINT64               *Version
);
```

Parameters

This

A pointer to the [EFI_EBC_PROTOCOL](#) instance. This protocol is defined in [Section 20.11](#).

Version

Pointer to where to store the returned version of the interpreter.

Description

This function is called to get the version of the loaded EBC interpreter. The value and format of the returned version is identical to that returned by the EBC [BREAK](#) 1 instruction.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_INVALID_PARAMETER	Version pointer is NULL .

20.12 EBC Tools

20.12.1 EBC C Compiler

This section describes the responsibilities of the EBC C compiler. To fully specify these responsibilities requires that the thunking mechanisms between EBC and native code be described.

20.12.2 C Coding Convention

The EBC C compiler supports only the C programming language. There is no support for C++, inline assembly, floating point types/operations, or C calling conventions other than CDECL.

Pointer type in C is supported only as 64-bit pointer. The code should be 64-bit pointer ready (not assign pointers to integers and vice versa).

The compiler does not support user-defined sections through pragmas.

Global variables containing pointers that are initialized will be put in the uninitialized VarBss section and the compiler will generate code to initialize these variables during load time. The code

will be placed in an init text section. This compiler-generated code will be executed before the actual image entry point is executed.

20.12.3 EBC Interface Assembly Instructions

The EBC instruction set includes two forms of a [CALL](#) instruction that can be used to invoke external protocols. Their assembly language formats are:

```
CALLEX Immed64
CALLEX32 {@}R1 {Immed32}
```

Both forms can be used to invoke external protocols at an absolute address specified by the immediate data and/or register operand. The second form also supports jumping to code at a relative address. When one of these instructions is executed, the interpreter is responsible for thunking arguments and then jumping to the destination address. When the called function returns, code begins execution at the EBC instruction following the CALL instruction. The process by which this happens is called thunking. Later sections describe this operation in detail.

20.12.4 Stack Maintenance and Argument Passing

There are several EBC assembly instructions that directly manipulate the stack contents and stack pointer. These instructions operate on the EBC stack, not the interpreter stack. The instructions include the EBC [PUSH](#), [POP](#), [PUSHn](#), and [POPn](#), and all forms of the [MOV](#) instructions.

These instructions must adjust the EBC stack pointer in the same manner as equivalent instructions of the native instruction set. With this implementation, parameters pushed on the stack by an EBC driver can be accessed normally for stack-based native code. If native code expects parameters in registers, then the interpreter thunking process must transfer the arguments from EBC stack to the appropriate processor registers. The process would need to be reversed when native code calls EBC.

20.12.5 Native to EBC Arguments Calling Convention

The calling convention for arguments passed to EBC functions follows the standard CDECL calling convention. The arguments must be pushed as their native size. After the function arguments have been pushed on the stack, execution is passed to the called EBC function. The overhead of thunking the function parameters depends on the standard parameter passing convention for the host processor. The implementation of this functionality is left to the interpreter.

20.12.6 EBC to Native Arguments Calling Convention

When EBC makes function calls via function pointers, the EBC C compiler cannot determine whether the calls are to native code or EBC. It therefore assumes that the calls are to native code, and emits the appropriate EBC [CALLEX](#) instructions. To be compatible with calls to native code, the calling convention of EBC calling native code must follow the parameter passing convention of the native processor. The EBC C compiler generates EBC instructions that push all arguments on the stack. The interpreter is then responsible for performing the necessary thunking. The exact implementation of this functionality is left to the interpreter.

20.12.7 EBC to EBC Arguments Calling Convention

If the EBC C compiler is able to determine that a function call is to a local function, it can emit a standard EBC [CALL](#) instruction. In this case, the function arguments are passed as described in the other sections of this specification.

20.12.8 Function Returns

When EBC calls an external function, the thinking process includes setting up the host processor stack or registers such that when the called function returns, execution is passed back to the EBC at the instruction following the call. The implementation is left to the interpreter, but it must follow the standard function return process of the host processor. Typically this will require the interpreter to push the return address on the stack or move it to a processor register prior to calling the external function.

20.12.9 Function Return Values

EBC function return values of 8 bytes or less are returned in VM general-purpose register **R7**. Returning values larger than 8 bytes on the stack is not supported. Instead, the caller or callee must allocate memory for the return value, and the caller can pass a pointer to the callee, or the callee can return a pointer to the value in the standard return register **R7**.

If an EBC function returns to native code, then the interpreter thinking process is responsible for transferring the contents of **R7** to an appropriate location such that the caller has access to the value using standard native code. Typically the value will be transferred to a processor register. Conversely, if a native function returns to an EBC function, the interpreter is responsible for transferring the return value from the native return memory or register location into VM register **R7**.

20.12.10 Thinking

Thinking is the process by which transitions between execution of native and EBC are handled. The major issues that must be addressed for thinking are the handling of function arguments, how the external function is invoked, and how return values and function returns are handled. The following sections describe the thinking process for the possible transitions.

20.12.10.1 Thinking EBC to Native Code

By definition, all external calls from within EBC are calls to native code. The EBC [CALLEX](#) instructions are used to make these calls. A typical application for EBC calling native code would be a simple “Hello World” driver. For a UEFI driver, the code could be written as shown below.

```

EFI_STATUS EfiMain (
    IN EFI_HANDLE          ImageHandle,
    IN EFI_SYSTEM_TABLE   *ST
)
{
    ST->ConOut->OutputString(ST->ConOut, L"Hello World!");
    return EFI_SUCCESS;
}

```

This C code, when compiled to EBC assembly, could result in two [PUSHn](#) instructions to push the parameters on the stack, some code to get the absolute address of the [OutputString\(\)](#) function, then a CALLEX instruction to jump to native code. Typical pseudo assembly code for the function call could be something like the following:

```
PUSHn    _HelloString
PUSHn    _ConOut
MOVnw    R1, _OutputString
CALLEX64R1
```

The interpreter is responsible for executing the PUSHn instructions to push the arguments on the EBC stack when interpreting the PUSHn instructions. When the CALLEX instruction is encountered, it must think to external native code. The exact thinking mechanism is native processor dependent. For example, a supported 32-bit thinking implementation could simply move the system stack pointer to point to the EBC stack, then perform a [CALL](#) to the absolute address specified in VM register **R1**. However, the function calling convention for the Itanium processor family calls for the first 8 function arguments being passed in registers. Therefore, the Itanium processor family thinking mechanism requires the arguments to be copied from the EBC stack into processor registers. Then a CALL can be performed to jump to the absolute address in VM register **R1**. Note that since the interpreter is not aware of the number of arguments to the function being called, the maximum amount of data may be copied from the EBC stack into processor registers.

20.12.10.2 Thunking Native Code to EBC

An EBC driver may install protocols for use by other EBC drivers, or UEFI drivers or applications. These protocols provide the mechanism by which external native code can call EBC. Typical C code to install a generic protocol is shown below.

```
EFI_STATUS Foo(UINT32 Arg1, UINT32 Arg2);

MyProtInterface->Service1= Foo;

Status = LibInstallProtocolInterfaces (&Handle, &MyProtGUID,
MyProtInterface, NULL);
```

To support thunking native code to EBC, the EBC compiler resolves all EBC function pointers using one level of indirection. In this way, the address of an EBC function actually becomes the address of a piece of native (thunk) code that invokes the interpreter to execute the actual EBC function. As a result of this implementation, any time the address of an EBC function is taken, the EBC C compiler must generate the following:

- A 64-bit function pointer data object that contains the actual address of the EBC function
- EBC initialization code that is executed before the image entry point that will execute EBC [BREAK](#) 5 instructions to create thunks for each function pointer data object
- Associated relocations for the above

So for the above code sample, the compiler must generate EBC initialization code similar to the following. This code is executed prior to execution of the actual EBC driver's entry point.

```
MOVqq R7, Foo_pointer; get address of Foo pointer
```

```
BREAK 5 ; create a thunk for the function
```

The BREAK instruction causes the interpreter to create native thunk code elsewhere in memory, and then modify the memory location pointed to by R7 to point to the newly created thunk code for EBC function Foo. From within EBC, when the address of Foo is taken, the address of the thunk is actually returned. So for the assignment of the protocol Service1 above, the EBC C compiler will generate something like the following:

```
MOVqq R7, Foo_pointer; get address of Foo function pointer
MOVqq R7, @R7 ; one level of indirection
MOVn R6, _MyProtInterface->Service1 ; get address of variable
MOVqq @R6, R7 ; address of thunk to ->Service1
```

20.12.10.3 Thunking EBC to EBC

EBC can call EBC via function pointers or protocols. These two mechanisms are treated identically by the EBC C compiler, and are performed using EBC [CALLEX](#) instructions. For EBC to call EBC, the EBC being called must have provided the address of the function. As described above, the address is actually the address of native thunk code for the actual EBC function. Therefore, when EBC calls EBC, the interpreter assumes native code is being called so prepares function arguments accordingly, and then makes the call. The native thunk code assumes native code is calling EBC, so will basically “undo” the preparation of function arguments, and then invoke the interpreter to execute the actual EBC function of interest.

20.12.11 EBC Linker

New constants must be defined for use by the linker in processing EBC images. For EBC images, the linker must set the machine type in the PE file header accordingly to indicate that the image contains EBC.

```
#define IMAGE_FILE_MACHINE_EBC0x0EBC
```

In addition, the linker must support EBC images with of the following subsystem types as set in a PE32+ optional header:

```
#define IMAGE_SUBSYSTEM_EFI_APPLICATION 10
#define IMAGE_SUBSYSTEM_EFI_BOOT_SERVICE_DRIVER 11
#define IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER 12
```

For EFI EBC images and object files, the following relocation types must be supported:

```
// No relocations required
#define IMAGE_REL_EBC_ABSOLUTE0x0000
// 32-bit address w/o image base
#define IMAGE_REL_EBC_ADDR32NB0x0001
// 32-bit relative address from byte following relocs
#define IMAGE_REL_EBC_REL320x0002
// Section table index
#define IMAGE_REL_EBC_SECTION0x0003
// Offset within section
#define IMAGE_REL_EBC_SECREL0x0004
```

The ADDR32NB relocation is used internally to the linker when RVAs are emitted. It also is used for version resources which probably will not be used. The REL32 relocation is for PC relative addressing on code. The SECTION and SECREL relocations are used for debug information.

20.12.12 Image Loader

The EFI image loader is responsible for loading an executable image into memory and applying relocation information so that an image can execute at the address in memory where it has been loaded prior to execution of the image. For EBC images, the image loader must also invoke the interpreter protocol to create a thunk for the image entry point and return the address of this thunk. After loading the image in this manner, the image can be executed in the standard manner. To implement this functionality, only minor changes will be made to EFI service [LoadImage\(\)](#), and no changes should be made to [StartImage\(\)](#).

After the image is unloaded, the EFI image load service must call the EBC [UnloadImage\(\)](#) service to perform any cleanup to complete unloading of the image. Typically this will include freeing up any memory allocated for thunks for the image during load and execution.

20.12.13 Debug Support

The interpreter must support debugging in an EFI environment per the EFI debug support protocol.

20.13 VM Exception Handling

This section lists the different types of exceptions that the VM may assert during execution of an EBC image. If a debugger is attached to the EBC driver via the EFI debug support protocol, then the debugger should be able to capture and identify the exception type. If a debugger is not attached, then depending on the severity of the exception, the interpreter may do one of the following:

- Invoke the EFI ASSERT() macro, which will typically display an error message and halt the system
- Sit in a while(1) loop to hang the system
- Ignore the exception and continue execution of the image (minor exceptions only)

It is a platform policy decision as to the action taken in response to EBC exceptions. The following sections describe the exceptions that may be generated by the VM.

20.13.1 Divide By 0 Exception

A divide-by-0 exception can occur for the EBC instructions [DIV](#), [DIVU](#), [MOD](#), and [MODU](#).

20.13.2 Debug Break Exception

A debug break exception occurs if the VM encounters a [BREAK](#) instruction with a break code of 3.

20.13.3 Invalid Opcode Exception

An invalid opcode exception will occur if the interpreter encounters a reserved opcode during execution.

20.13.4 Stack Fault Exception

A stack fault exception can occur if the interpreter detects that function nesting within the interpreter or system interrupts was sufficient to potentially corrupt the EBC image's stack contents. This exception could also occur if the EBC driver attempts to adjust the stack pointer outside the range allocated to the driver.

20.13.5 Alignment Exception

An alignment exception can occur if the particular implementation of the interpreter does not support unaligned accesses to data or code. It may also occur if the stack pointer or instruction pointer becomes misaligned.

20.13.6 Instruction Encoding Exception

An instruction encoding exception can occur for the following:

- For some instructions, if an Operand 1 index is specified and Operand 1 is direct
- If an instruction encoding has reserved bits set to values other than 0
- If an instruction encoding has a field set to a reserved value.

20.13.7 Bad Break Exception

A bad break exception occurs if the VM encounters a [BREAK](#) instruction with a break code of 0, or any other unrecognized or unsupported break code.

20.13.8 Undefined Exception

An undefined exception can occur for other conditions detected by the VM. The cause of such an exception is dependent on the VM implementation, but will most likely include internal VM faults.

20.14 Option ROM Formats

The new option ROM capability is designed to be a departure from the legacy method of formatting an option ROM. PCI local bus add-in cards are the primary targets for this design although support for future bus types will be added as necessary. EFI EBC drivers can be stored in option ROMs or on hard drives in an EFI system partition.

The new format defined for the UEFI specification is intended to coexist with legacy format PCI Expansion ROM images. This provides the ability for IHVs to make a single option ROM binary that contains both legacy and new format images at the same time. This is important for the ability to have single add-in card SKUs that can work in a variety of systems both with and without native support for UEFI. Support for multiple image types in this way provides a smooth migration path during the period before widespread adoption of UEFI drivers as the primary means of support for software needed to accomplish add-in card operation in the pre-OS boot timeframe.

20.14.1 EFI Drivers for PCI Add-in Cards

The location mechanism for UEFI drivers in PCI option ROM containers is described fully in [Section 10.3](#). Readers should refer to this section for complete details of the scheme and associated data structures.

20.14.2 Non-PCI Bus Support

EFI expansion ROMs are not supported on any other bus besides PCI local bus in the current revision of the UEFI specification.

This means that support for UEFI drivers in legacy ISA add-in card ROMs is explicitly excluded.

Support for UEFI drivers to be located on add-in card type devices for future bus designs other than PCI local bus will be added to future revisions of the uEFI specification. This support will depend upon the specifications that govern such new bus designs with respect to the mechanisms defined for support of driver code on devices.

Network Protocols - SNP, PXE and BIS

21.1 Simple Network Protocol

This section defines the Simple Network Protocol. This protocol provides a packet level interface to a network adapter.

EFI_SIMPLE_NETWORK_PROTOCOL

Summary

The **EFI_SIMPLE_NETWORK_PROTOCOL** provides services to initialize a network interface, transmit packets, receive packets, and close a network interface.

GUID

```
#define EFI_SIMPLE_NETWORK_PROTOCOL_GUID \
  {0xA19832B9, 0xAC25, 0x11D3, 0x9A, 0x2D, 0x00, 0x90, 0x27, 0x3f, 0xc1,
   0x4d}
```

Revision Number

```
#define EFI_SIMPLE_NETWORK_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```
typedef struct _EFI_SIMPLE_NETWORK_PROTOCOL_ {
    UINT64                Revision;
    EFI_SIMPLE_NETWORK_START Start;
    EFI_SIMPLE_NETWORK_STOP Stop;
    EFI_SIMPLE_NETWORK_INITIALIZE Initialize;
    EFI_SIMPLE_NETWORK_RESET Reset;
    EFI_SIMPLE_NETWORK_SHUTDOWN Shutdown;
    EFI_SIMPLE_NETWORK_RECEIVE_FILTERS ReceiveFilters;
    EFI_SIMPLE_NETWORK_STATION_ADDRESS StationAddress;
    EFI_SIMPLE_NETWORK_STATISTICS Statistics;
    EFI_SIMPLE_NETWORK_MCAST_IP_TO_MAC MCastIpToMac;
    EFI_SIMPLE_NETWORK_NVDATA NvData;
    EFI_SIMPLE_NETWORK_GET_STATUS GetStatus;
    EFI_SIMPLE_NETWORK_TRANSMIT Transmit;
    EFI_SIMPLE_NETWORK_RECEIVE Receive;
    EFI_EVENT              WaitForPacket;
    EFI_SIMPLE_NETWORK_MODE *Mode;
} EFI_SIMPLE_NETWORK_PROTOCOL;
```

Parameters

<i>Revision</i>	Revision of the EFI_SIMPLE_NETWORK_PROTOCOL . All future revisions must be backwards compatible. If a future version is not backwards compatible it is not the same GUID.
<i>Start</i>	Prepares the network interface for further command operations. No other EFI_SIMPLE_NETWORK_PROTOCOL interface functions will operate until this call is made. See the Start () function description.
<i>Stop</i>	Stops further network interface command processing. No other EFI_SIMPLE_NETWORK_PROTOCOL interface functions will operate after this call is made until another Start () call is made. See the Stop () function description.
<i>Initialize</i>	Resets the network adapter and allocates the transmit and receive buffers. See the Initialize () function description.
<i>Reset</i>	Resets the network adapter and reinitializes it with the parameters provided in the previous call to Initialize () . See the Reset () function description.
<i>Shutdown</i>	Resets the network adapter and leaves it in a state safe for another driver to initialize. The memory buffers assigned in the Initialize () call are released. After this call, only the Initialize () or Stop () calls may be used. See the Shutdown () function description.
<i>ReceiveFilters</i>	Enables and disables the receive filters for the network interface and, if supported, manages the filtered multicast HW MAC (Hardware Media Access Control) address list. See the ReceiveFilters () function description.
<i>StationAddress</i>	Modifies or resets the current station address, if supported. See the StationAddress () function description.
<i>Statistics</i>	Collects statistics from the network interface and allows the statistics to be reset. See the Statistics () function description.
<i>MCastIpToMac</i>	Maps a multicast IP address to a multicast HW MAC address. See the MCastIPToMAC () function description.
<i>NvData</i>	Reads and writes the contents of the NVRAM devices attached to the network interface. See the NvData () function description.
<i>GetStatus</i>	Reads the current interrupt status and the list of recycled transmit buffers from the network interface. See the GetStatus () function description.
<i>Transmit</i>	Places a packet in the transmit queue. See the Transmit () function description.
<i>Receive</i>	Retrieves a packet from the receive queue, along with the status flags that describe the packet type. See the Receive () function description.
<i>WaitForPacket</i>	Event used with WaitForEvent () to wait for a packet to be received.

Mode

Pointer to the [EFI_SIMPLE_NETWORK_MODE](#) data for the device. See “Related Definitions” below.

Related Definitions

```
//*****
// EFI_SIMPLE_NETWORK_MODE
//
// Note that the fields in this data structure are read-only and
// are updated by the code that produces the EFI_SIMPLE_NETWORK_PROTOCOL
// functions. All these fields must be discovered
// during driver initialization.
//*****
typedef struct {
    UINT32          State;
    UINT32          HwAddressSize;
    UINT32          MediaHeaderSize;
    UINT32          MaxPacketSize;
    UINT32          NvRamSize;
    UINT32          NvRamAccessSize;
    UINT32          ReceiveFilterMask;
    UINT32          ReceiveFilterSetting;
    UINT32          MaxMCastFilterCount;
    UINT32          MCastFilterCount;
    EFI_MAC_ADDRESS MCastFilter[MAX_MCAST_FILTER_CNT];
    EFI_MAC_ADDRESS CurrentAddress;
    EFI_MAC_ADDRESS BroadcastAddress;
    EFI_MAC_ADDRESS PermanentAddress;
    UINT8           IfType;
    BOOLEAN         MacAddressChangeable;
    BOOLEAN         MultipleTxSupported;
    BOOLEAN         MediaPresentSupported;
    BOOLEAN         MediaPresent;
} EFI_SIMPLE_NETWORK_MODE;
```

<i>State</i>	Reports the current state of the network interface (see EFI_SIMPLE_NETWORK_STATE below). When an EFI_SIMPLE_NETWORK_PROTOCOL driver initializes a network interface, the network interface is left in the EfiSimpleNetworkStopped state.
<i>HwAddressSize</i>	The size, in bytes, of the network interface’s HW address.
<i>MediaHeaderSize</i>	The size, in bytes, of the network interface’s media header.
<i>MaxPacketSize</i>	The maximum size, in bytes, of the packets supported by the network interface.

NvRamSize The size, in bytes, of the NVRAM device attached to the network interface. If an NVRAM device is not attached to the network interface, then this field will be zero. This value must be a multiple of *NvramAccessSize*.

NvRamAccessSize The size that must be used for all NVRAM reads and writes. The start address for NVRAM read and write operations and the total length of those operations, must be a multiple of this value. The legal values for this field are 0, 1, 2, 4, and 8. If the value is zero, then no NVRAM devices are attached to the network interface.

ReceiveFilterMask The multicast receive filter settings supported by the network interface.

ReceiveFilterSetting The current multicast receive filter settings. See “Bit Mask Values for *ReceiveFilterSetting*” below.

MaxMCastFilterCount The maximum number of multicast address receive filters supported by the driver. If this value is zero, then `ReceiveFilters()` cannot modify the multicast address receive filters. This field may be less than **MAX_MCAST_FILTER_CNT** (see below).

MCastFilterCount The current number of multicast address receive filters.

MCastFilter Array containing the addresses of the current multicast address receive filters.

CurrentAddress The current HW MAC address for the network interface.

BroadcastAddress The current HW MAC address for broadcast packets.

PermanentAddress The permanent HW MAC address for the network interface.

IfType The interface type of the network interface. See RFC 1700, section “Number Hardware Type.”

MacAddressChangeable **TRUE** if the HW MAC address can be changed.

MultipleTxSupported **TRUE** if the network interface can transmit more than one packet at a time.

MediaPresentSupported **TRUE** if the presence of media can be determined; otherwise **FALSE**. If **FALSE**, **MediaPresent** cannot be used.

MediaPresent **TRUE** if media are connected to the network interface; otherwise **FALSE**. This field is only valid immediately after calling [Initialize\(\)](#).

```

//*****
// EFI_SIMPLE_NETWORK_STATE
//*****
typedef enum {
    EfiSimpleNetworkStopped,
    EfiSimpleNetworkStarted,

```

```

        EfiSimpleNetworkInitialized,
        EfiSimpleNetworkMaxState
    } EFI_SIMPLE_NETWORK_STATE;

//*****
// MAX_MCAST_FILTER_CNT
//*****
#define MAX_MCAST_FILTER_CNT16

//*****
// Bit Mask Values for ReceiveFilterSetting.
//
// Note that all other bit values are reserved.
//*****
#define EFI_SIMPLE_NETWORK_RECEIVE_UNICAST          0x01
#define EFI_SIMPLE_NETWORK_RECEIVE_MULTICAST       0x02
#define EFI_SIMPLE_NETWORK_RECEIVE_BROADCAST       0x04
#define EFI_SIMPLE_NETWORK_RECEIVE_PROMISCUOUS     0x08
#define EFI_SIMPLE_NETWORK_RECEIVE_PROMISCUOUS_MULTICAST 0x10

```

Description

The **EFI_SIMPLE_NETWORK_PROTOCOL** protocol is used to initialize access to a network adapter. Once the network adapter initializes, the **EFI_SIMPLE_NETWORK_PROTOCOL** protocol provides services that allow packets to be transmitted and received. This provides a packet level interface that can then be used by higher level drivers to produce boot services like DHCP, TFTP, and MFTFTP. In addition, this protocol can be used as a building block in a full UDP and TCP/IP implementation that can produce a wide variety of application level network interfaces. See the *Preboot Execution Environment (PXE) Specification* for more information.

Note: *The underlying network hardware may only be able to access 4 GB (32-bits) of system memory. Any requests to transfer data to/from memory above 4 GB with 32-bit network hardware will be double-buffered (using intermediate buffers below 4 GB) and will reduce performance.*

EFI_SIMPLE_NETWORK.Start()

Summary

Changes the state of a network interface from “stopped” to “started.”

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_START) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL    *This
);
```

Parameters

This A pointer to the [EFI SIMPLE NETWORK PROTOCOL](#) instance.

Description

This function starts a network interface. If the network interface successfully starts, then **EFI_SUCCESS** will be returned.

Status Codes Returned

EFI_SUCCESS	The network interface was started.
EFI_ALREADY_STARTED	The network interface is already in the started state.
EFI_INVALID_PARAMETER	<i>This</i> parameter was NULL or did not point to a valid <code>EFI_SIMPLE_NETWORK_PROTOCOL</code> structure.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.
EFI_UNSUPPORTED	This function is not supported by the network interface.

EFI_SIMPLE_NETWORK.Stop()

Summary

Changes the state of a network interface from “started” to “stopped.”

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_STOP) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL    *This
);
```

Parameters

This A pointer to the [EFI SIMPLE NETWORK PROTOCOL](#) instance.

Description

This function stops a network interface. This call is only valid if the network interface is in the started state. If the network interface was successfully stopped, then **EFI_SUCCESS** will be returned.

Status Codes Returned

EFI_SUCCESS	The network interface was stopped.
EFI_NOT_STARTED	The network interface has not been started.
EFI_INVALID_PARAMETER	<i>This</i> parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.
EFI_UNSUPPORTED	This function is not supported by the network interface.

EFI_SIMPLE_NETWORK.Initialize()

Summary

Resets a network adapter and allocates the transmit and receive buffers required by the network interface; optionally, also requests allocation of additional transmit and receive buffers.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_INITIALIZE) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL      *This,
    IN UINTN                            ExtraRxBufferSize    OPTIONAL,
    IN UINTN                            ExtraTxBufferSize    OPTIONAL
);
```

Parameters

- This* A pointer to the [EFI_SIMPLE_NETWORK_PROTOCOL](#) instance.
- ExtraRxBufferSize* The size, in bytes, of the extra receive buffer space that the driver should allocate for the network interface. Some network interfaces will not be able to use the extra buffer, and the caller will not know if it is actually being used.
- ExtraTxBufferSize* The size, in bytes, of the extra transmit buffer space that the driver should allocate for the network interface. Some network interfaces will not be able to use the extra buffer, and the caller will not know if it is actually being used.

Description

This function allocates the transmit and receive buffers required by the network interface. If this allocation fails, then **EFI_OUT_OF_RESOURCES** is returned. If the allocation succeeds and the network interface is successfully initialized, then **EFI_SUCCESS** will be returned.

Status Codes Returned

EFI_SUCCESS	The network interface was initialized.
EFI_NOT_STARTED	The network interface has not been started.
EFI_OUT_OF_RESOURCES	There was not enough memory for the transmit and receive buffers.
EFI_INVALID_PARAMETER	<i>This</i> parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.
EFI_UNSUPPORTED	The increased buffer size feature is not supported.

EFI_SIMPLE_NETWORK.Reset()

Summary

Resets a network adapter and reinitializes it with the parameters that were provided in the previous call to [Initialize\(\)](#).

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_RESET) (
  IN EFI_SIMPLE_NETWORK_PROTOCOL      *This,
  IN BOOLEAN                          ExtendedVerification
);
```

Parameters

This A pointer to the [EFI_SIMPLE_NETWORK_PROTOCOL](#) instance.

ExtendedVerification Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

This function resets a network adapter and reinitializes it with the parameters that were provided in the previous call to [Initialize\(\)](#). The transmit and receive queues are emptied and all pending interrupts are cleared. Receive filters, the station address, the statistics, and the multicast-IP-to-HW MAC addresses are not reset by this call. If the network interface was successfully reset, then **EFI_SUCCESS** will be returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

Status Codes Returned

EFI_SUCCESS	The network interface was reset.
EFI_NOT_STARTED	The network interface has not been started.
EFI_INVALID_PARAMETER	One or more of the parameters has an unsupported value.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.
EFI_UNSUPPORTED	This function is not supported by the network interface.

EFI_SIMPLE_NETWORK.Shutdown()

Summary

Resets a network adapter and leaves it in a state that is safe for another driver to initialize.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_SHUTDOWN) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL      *This
);
```

Parameters

This A pointer to the [EFI SIMPLE NETWORK PROTOCOL](#) instance.

Description

This function releases the memory buffers assigned in the [Initialize\(\)](#) call. Pending transmits and receives are lost, and interrupts are cleared and disabled. After this call, only the [Initialize\(\)](#) and [Stop\(\)](#) calls may be used. If the network interface was successfully shutdown, then **EFI_SUCCESS** will be returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

Status Codes Returned

EFI_SUCCESS	The network interface was shutdown.
EFI_NOT_STARTED	The network interface has not been started.
EFI_INVALID_PARAMETER	<i>This</i> parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.

EFI_SIMPLE_NETWORK.ReceiveFilters()

Summary

Manages the multicast receive filters of a network interface.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_RECEIVE_FILTERS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL    *This,
    IN UINT32                          Enable,
    IN UINT32                          Disable,
    IN BOOLEAN                         ResetMCastFilter,
    IN UINTN                            MCastFilterCnt OPTIONAL,
    IN EFI_MAC_ADDRESS                 *MCastFilter OPTIONAL,
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.
<i>Enable</i>	A bit mask of receive filters to enable on the network interface.
<i>Disable</i>	A bit mask of receive filters to disable on the network interface. For backward compatibility with EFI 1.1 platforms, the EFI_SIMPLE_NETWORK_RECEIVE_MULTICAST bit must be set when the <i>ResetMCastFilter</i> parameter is TRUE .
<i>ResetMCastFilter</i>	Set to TRUE to reset the contents of the multicast receive filters on the network interface to their default values.
<i>MCastFilterCnt</i>	Number of multicast HW MAC addresses in the new <i>MCastFilter</i> list. This value must be less than or equal to the <i>MCastFilterCnt</i> field of EFI_SIMPLE_NETWORK_MODE . This field is optional if <i>ResetMCastFilter</i> is TRUE .
<i>MCastFilter</i>	A pointer to a list of new multicast receive filter HW MAC addresses. This list will replace any existing multicast HW MAC address list. This field is optional if <i>ResetMCastFilter</i> is TRUE .

Description

This function is used enable and disable the hardware and software receive filters for the underlying network device.

The receive filter change is broken down into three steps:

- The filter mask bits that are set (ON) in the Enable parameter are added to the current receive filter settings.
- The filter mask bits that are set (ON) in the Disable parameter are subtracted from the updated receive filter settings.

- If the resulting receive filter setting is not supported by the hardware a more liberal setting is selected.

If the same bits are set in the Enable and Disable parameters, then the bits in the Disable parameter takes precedence.

If the ResetMCastFilter parameter is TRUE, then the multicast address list filter is disabled (irregardless of what other multicast bits are set in the Enable and Disable parameters). The Snp->Mode->MCastFilterCount field is set to zero. The Snp->Mode->MCastFilter contents are undefined.

After enabling or disabling receive filter settings, software should verify the new settings by checking the Snp->Mode->ReceiveFilterSettings, Snp->Mode->MCastFilterCount and Snp->Mode->MCastFilter fields.

Note: Some network drivers and/or devices will automatically promote receive filter settings if the requested setting can not be honored. For example, if a request for four multicast addresses is made and the underlying hardware only supports two multicast addresses the driver might set the promiscuous or promiscuous multicast receive filters instead. The receiving software is responsible for discarding any extra packets that get through the hardware receive filters.

Note: *Note: To disable all receive filter hardware, the network driver must be Shutdown() and Stopped(). Calling ReceiveFilters() with Disable set to Snp->Mode->ReceiveFilterSettings will make it so no more packets are returned by the Receive() function, but the receive hardware may still be moving packets into system memory before inspecting and discarding them. Unexpected system errors, reboots and hangs can occur if an OS is loaded and the network devices are not Shutdown() and Stopped().*

If **ResetMCastFilter** is **TRUE**, then the multicast receive filter list on the network interface will be reset to the default multicast receive filter list. If **ResetMCastFilter** is **FALSE**, and this network interface allows the multicast receive filter list to be modified, then the **MCastFilterCnt** and **MCastFilter** are used to update the current multicast receive filter list. The modified receive filter list settings can be found in the **MCastFilter** field of [EFI_SIMPLE_NETWORK_MODE](#). If the network interface does not allow the multicast receive filter list to be modified, then **EFI_INVALID_PARAMETER** will be returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

If the receive filter mask and multicast receive filter list have been successfully updated on the network interface, **EFI_SUCCESS** will be returned.

Status Codes Returned

EFI_SUCCESS	The multicast receive filter list was updated.
EFI_NOT_STARTED	The network interface has not been started.

<p>EFI_INVALID_PARAMETER</p>	<ul style="list-style-type: none"> • One or more of the following conditions is TRUE: • <i>This</i> is NULL • There are bits set in Enable that are not set in Snp->Mode->ReceiveFilterMask • There are bits set in Disable that are not set in Snp->Mode->ReceiveFilterMask • Multicast is being enabled (the EFI_SIMPLE_NETWORK_RECEIVE_MULTICAST bit is set in Enable, it is not set in Disable, and ResetMCastFilter is FALSE) and MCastFilterCount is zero • Multicast is being enabled and MCastFilterCount is greater than Snp->Mode->MaxMCastFilterCount • Multicast is being enabled and MCastFilter is NULL • Multicast is being enabled and one or more of the addresses in the MCastFilter list are not valid multicast MAC addresses
<p>EFI_DEVICE_ERROR</p>	<ul style="list-style-type: none"> • One or more of the following conditions is TRUE: • The network interface has been started but has not been initialized • An unexpected error was returned by the underlying network driver or device
<p>EFI_UNSUPPORTED</p>	<p>This function is not supported by the network interface.</p>

EFI_SIMPLE_NETWORK.StationAddress()

Summary

Modifies or resets the current station address, if supported.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_STATION_ADDRESS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
    IN BOOLEAN                      Reset,
    IN EFI_MAC_ADDRESS              *New    OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.
<i>Reset</i>	Flag used to reset the station address to the network interface's permanent address.
<i>New</i>	New station address to be used for the network interface.

Description

This function modifies or resets the current station address of a network interface, if supported. If **Reset** is **TRUE**, then the current station address is set to the network interface's permanent address. If **Reset** is **FALSE**, and the network interface allows its station address to be modified, then the current station address is changed to the address specified by **New**. If the network interface does not allow its station address to be modified, then **EFI_INVALID_PARAMETER** will be returned. If the station address is successfully updated on the network interface, **EFI_SUCCESS** will be returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

Status Codes Returned

EFI_SUCCESS	The network interface's station address was updated.
EFI_NOT_STARTED	The Simple Network Protocol interface has not been started by calling Start() .
EFI_INVALID_PARAMETER	The <i>New</i> station address was not accepted by the NIC.
EFI_INVALID_PARAMETER	<i>Reset</i> is FALSE and <i>New</i> is NULL .
EFI_DEVICE_ERROR	The Simple Network Protocol interface has not been initialized by calling Initialize() .
EFI_DEVICE_ERROR	An error occurred attempting to set the new station address.
EFI_UNSUPPORTED	The NIC does not support changing the network interface's station address.

EFI_SIMPLE_NETWORK.Statistics()

Summary

Resets or collects the statistics on a network interface.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_STATISTICS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
    IN BOOLEAN                      Reset,
    IN OUT UINTN                    *StatisticsSize    OPTIONAL,
    OUT EFI_NETWORK_STATISTICS      *StatisticsTable  OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.
<i>Reset</i>	Set to TRUE to reset the statistics for the network interface.
<i>StatisticsSize</i>	On input the size, in bytes, of <i>StatisticsTable</i> . On output the size, in bytes, of the resulting table of statistics.
<i>StatisticsTable</i>	A pointer to the EFI_NETWORK_STATISTICS structure that contains the statistics. Type EFI_NETWORK_STATISTICS is defined in “Related Definitions” below.

Related Definitions

```
//*****
// EFI_NETWORK_STATISTICS
//
// Any statistic value that is -1 is not available
// on the device and is to be ignored.
//*****
typedef struct {
    UINT64    RxTotalFrames;
    UINT64    RxGoodFrames;
    UINT64    RxUndersizeFrames;
    UINT64    RxOversizeFrames;
    UINT64    RxDroppedFrames;
    UINT64    RxUnicastFrames;
    UINT64    RxBroadcastFrames;
    UINT64    RxMulticastFrames;
    UINT64    RxCrcErrorFrames;
    UINT64    RxTotalBytes;
```

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```
UINT64    TxTotalFrames;  
UINT64    TxGoodFrames;  
UINT64    TxUndersizeFrames;  
UINT64    TxOversizeFrames;  
UINT64    TxDroppedFrames;  
UINT64    TxUnicastFrames;  
UINT64    TxBroadcastFrames;  
UINT64    TxMulticastFrames;  
UINT64    TxCrcErrorFrames;  
UINT64    TxTotalBytes;  
UINT64    Collisions;  
UINT64    UnsupportedProtocol;  
} EFI_NETWORK_STATISTICS;
```

<i>RxTotalFrames</i>	Total number of frames received. Includes frames with errors and dropped frames.
<i>RxGoodFrames</i>	Number of valid frames received and copied into receive buffers.
<i>RxUndersizeFrames</i>	Number of frames below the minimum length for the communications device.
<i>RxOversizeFrames</i>	Number of frames longer than the maximum length for the communications device.
<i>RxDroppedFrames</i>	Valid frames that were dropped because receive buffers were full.
<i>RxUnicastFrames</i>	Number of valid unicast frames received and not dropped.
<i>RxBroadcastFrames</i>	Number of valid broadcast frames received and not dropped.
<i>RxMulticastFrames</i>	Number of valid multicast frames received and not dropped.
<i>RxCrcErrorFrames</i>	Number of frames with CRC or alignment errors.
<i>RxTotalBytes</i>	Total number of bytes received. Includes frames with errors and dropped frames.
<i>TxTotalFrames</i>	Total number of frames transmitted. Includes frames with errors and dropped frames.
<i>TxGoodFrames</i>	Number of valid frames transmitted and copied into receive buffers.
<i>TxUndersizeFrames</i>	Number of frames below the minimum length for the media. This would be less than 64 for Ethernet.
<i>TxOversizeFrames</i>	Number of frames longer than the maximum length for the media. This would be greater than 1500 for Ethernet.
<i>TxDroppedFrames</i>	Valid frames that were dropped because receive buffers were full.
<i>TxUnicastFrames</i>	Number of valid unicast frames transmitted and not dropped.
<i>TxBroadcastFrames</i>	Number of valid broadcast frames transmitted and not dropped.
<i>TxMulticastFrames</i>	Number of valid multicast frames transmitted and not dropped.
<i>TxCrcErrorFrames</i>	Number of frames with CRC or alignment errors.
<i>TxTotalBytes</i>	Total number of bytes transmitted. Includes frames with errors and dropped frames.

Collisions Number of collisions detected on this subnet.

UnsupportedProtocol Number of frames destined for unsupported protocol.

Description

This function resets or collects the statistics on a network interface. If the size of the statistics table specified by **StatisticsSize** is not big enough for all the statistics that are collected by the network interface, then a partial buffer of statistics is returned in **StatisticsTable**, **StatisticsSize** is set to the size required to collect all the available statistics, and **EFI_BUFFER_TOO_SMALL** is returned.

If **StatisticsSize** is big enough for all the statistics, then **StatisticsTable** will be filled, **StatisticsSize** will be set to the size of the returned **StatisticsTable** structure, and **EFI_SUCCESS** is returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

If **Reset** is **FALSE**, and both **StatisticsSize** and **StatisticsTable** are **NULL**, then no operations will be performed, and **EFI_SUCCESS** will be returned.

If **Reset** is **TRUE**, then all of the supported statistics counters on this network interface will be reset to zero.

Status Codes Returned

EFI_SUCCESS	The requested operation succeeded.
EFI_NOT_STARTED	The Simple Network Protocol interface has not been started by calling Start () .
EFI_BUFFER_TOO_SMALL	<i>StatisticsSize</i> is not NULL and <i>StatisticsTable</i> is NULL . The current buffer size that is needed to hold all the statistics is returned in <i>StatisticsSize</i> .
EFI_BUFFER_TOO_SMALL	<i>StatisticsSize</i> is not NULL and <i>StatisticsTable</i> is not NULL . The current buffer size that is needed to hold all the statistics is returned in <i>StatisticsSize</i> . A partial set of statistics is returned in <i>StatisticsTable</i> .
EFI_INVALID_PARAMETER	<i>StatisticsSize</i> is NULL and <i>StatisticsTable</i> is not NULL .
EFI_DEVICE_ERROR	The Simple Network Protocol interface has not been initialized by calling Initialize () .
EFI_DEVICE_ERROR	An error was encountered collecting statistics from the NIC.
EFI_UNSUPPORTED	The NIC does not support collecting statistics from the network interface.

EFI_SIMPLE_NETWORK.MCastIPtoMAC()

Summary

Converts a multicast IP address to a multicast HW MAC address.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_MCAST_IP_TO_MAC) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL    *This,
    IN BOOLEAN                        IPv6,
    IN EFI_IP_ADDRESS                 *IP,
    OUT EFI_MAC_ADDRESS               *MAC
);
```

Parameters

<i>This</i>	A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.
<i>IPv6</i>	Set to TRUE if the multicast IP address is IPv6 [RFC 2460]. Set to FALSE if the multicast IP address is IPv4 [RFC 791].
<i>IP</i>	The multicast IP address that is to be converted to a multicast HW MAC address.
<i>MAC</i>	The multicast HW MAC address that is to be generated from <i>IP</i> .

Description

This function converts a multicast IP address to a multicast HW MAC address for all packet transactions. If the mapping is accepted, then **EFI_SUCCESS** will be returned.

Status Codes Returned

EFI_SUCCESS	The multicast IP address was mapped to the multicast HW MAC address.
EFI_NOT_STARTED	The Simple Network Protocol interface has not been started by calling Start() .
EFI_INVALID_PARAMETER	<i>IP</i> is NULL .
EFI_INVALID_PARAMETER	<i>MAC</i> is NULL .
EFI_INVALID_PARAMETER	<i>IP</i> does not point to a valid IPv4 or IPv6 multicast address.
EFI_DEVICE_ERROR	The Simple Network Protocol interface has not been initialized by calling Initialize() .
EFI_UNSUPPORTED	<i>IPv6</i> is TRUE and the implementation does not support IPv6 multicast to MAC address conversion.

EFI_SIMPLE_NETWORK.NvData()

Summary

Performs read and write operations on the NVRAM device attached to a network interface.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_NVDATA) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This
    IN BOOLEAN                      ReadWrite,
    IN UINTN                        Offset,
    IN UINTN                        BufferSize,
    IN OUT VOID                     *Buffer
);
```

Parameters

<i>This</i>	A pointer to the EFI SIMPLE NETWORK PROTOCOL instance.
<i>ReadWrite</i>	TRUE for read operations, FALSE for write operations.
<i>Offset</i>	Byte offset in the NVRAM device at which to start the read or write operation. This must be a multiple of <i>NvRamAccessSize</i> and less than <i>NvRamSize</i> . (See EFI SIMPLE NETWORK MODE)
<i>BufferSize</i>	The number of bytes to read or write from the NVRAM device. This must also be a multiple of <i>NvramAccessSize</i> .
<i>Buffer</i>	A pointer to the data buffer.

Description

This function performs read and write operations on the NVRAM device attached to a network interface. If **ReadWrite** is **TRUE**, a read operation is performed. If **ReadWrite** is **FALSE**, a write operation is performed.

Offset specifies the byte offset at which to start either operation. **Offset** must be a multiple of **NvRamAccessSize**, and it must have a value between zero and **NvRamSize**.

BufferSize specifies the length of the read or write operation. **BufferSize** must also be a multiple of **NvRamAccessSize**, and **Offset** + **BufferSize** must not exceed **NvRamSize**.

If any of the above conditions is not met, then **EFI_INVALID_PARAMETER** will be returned.

If all the conditions are met and the operation is “read,” the NVRAM device attached to the network interface will be read into **Buffer** and **EFI_SUCCESS** will be returned. If this is a write operation, the contents of **Buffer** will be used to update the contents of the NVRAM device attached to the network interface and **EFI_SUCCESS** will be returned.

Status Codes Returned

EFI_SUCCESS	The NVRAM access was performed.
EFI_NOT_STARTED	The network interface has not been started.
EFI_INVALID_PARAMETER	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • The <i>This</i> parameter is NULL • The <i>This</i> parameter does not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure • The <i>Offset</i> parameter is not a multiple of EFI_SIMPLE_NETWORK_MODE.NvRamAccessSize • The <i>Offset</i> parameter is not less than EFI_SIMPLE_NETWORK_MODE.NvRamSize • The <i>BufferSize</i> parameter is not a multiple of EFI_SIMPLE_NETWORK_MODE.NvRamAccessSize <p>The <i>Buffer</i> parameter is NULL</p>
EFI_DEVICE_ERROR	The command could not be sent to the network interface.
EFI_UNSUPPORTED	This function is not supported by the network interface.

EFI_SIMPLE_NETWORK.GetStatus()

Summary

Reads the current interrupt status and recycled transmit buffer status from a network interface.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_GET_STATUS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL      *This,
    OUT UINT32                          *InterruptStatus    OPTIONAL,
    OUT VOID                             **TxBuf            OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI SIMPLE NETWORK PROTOCOL instance.
<i>InterruptStatus</i>	A pointer to the bit mask of the currently active interrupts (see “Related Definitions”). If this is NULL , the interrupt status will not be read from the device. If this is not NULL , the interrupt status will be read from the device. When the interrupt status is read, it will also be cleared. Clearing the transmit interrupt does not empty the recycled transmit buffer array.
<i>TxBuf</i>	Recycled transmit buffer address. The network interface will not transmit if its internal recycled transmit buffer array is full. Reading the transmit buffer does not clear the transmit interrupt. If this is NULL , then the transmit buffer status will not be read. If there are no transmit buffers to recycle and <i>TxBuf</i> is not NULL , * <i>TxBuf</i> will be set to NULL .

Related Definitions

```

//*****
// Interrupt Bit Mask Settings for InterruptStatus.
// Note that all other bit values are reserved.
//*****
#define EFI_SIMPLE_NETWORK_RECEIVE_INTERRUPT    0x01
#define EFI_SIMPLE_NETWORK_TRANSMIT_INTERRUPT  0x02
#define EFI_SIMPLE_NETWORK_COMMAND_INTERRUPT   0x04
#define EFI_SIMPLE_NETWORK_SOFTWARE_INTERRUPT  0x08
```

Description

This function gets the current interrupt and recycled transmit buffer status from the network interface. The interrupt status is returned as a bit mask in **InterruptStatus**. If **InterruptStatus** is **NULL**, the interrupt status will not be read. If **TxBuf** is not **NULL**, a

recycled transmit buffer address will be retrieved. If a recycled transmit buffer address is returned in **TxBuf**, then the buffer has been successfully transmitted, and the status for that buffer is cleared. If the status of the network interface is successfully collected, **EFI_SUCCESS** will be returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

Status Codes Returned

EFI_SUCCESS	The status of the network interface was retrieved.
EFI_NOT_STARTED	The network interface has not been started.
EFI_INVALID_PARAMETER	<i>This</i> parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.

EFI_SIMPLE_NETWORK.Transmit()

Summary

Places a packet in the transmit queue of a network interface.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_TRANSMIT) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This
    IN UINTN                        HeaderSize,
    IN UINTN                        BufferSize,
    IN VOID                        *Buffer,
    IN EFI_MAC_ADDRESS             *SrcAddr    OPTIONAL,
    IN EFI_MAC_ADDRESS             *DestAddr   OPTIONAL,
    IN UINT16                       *Protocol  OPTIONAL,
);
```

Parameters

<i>This</i>	A pointer to the EFI SIMPLE NETWORK PROTOCOL instance.
<i>HeaderSize</i>	The size, in bytes, of the media header to be filled in by the Transmit() function. If <i>HeaderSize</i> is nonzero, then it must be equal to <i>This->Mode->MediaHeaderSize</i> and the <i>DestAddr</i> and <i>Protocol</i> parameters must not be NULL .
<i>BufferSize</i>	The size, in bytes, of the entire packet (media header and data) to be transmitted through the network interface.
<i>Buffer</i>	A pointer to the packet (media header followed by data) to be transmitted. This parameter cannot be NULL . If <i>HeaderSize</i> is zero, then the media header in <i>Buffer</i> must already be filled in by the caller. If <i>HeaderSize</i> is nonzero, then the media header will be filled in by the Transmit() function.
<i>SrcAddr</i>	The source HW MAC address. If <i>HeaderSize</i> is zero, then this parameter is ignored. If <i>HeaderSize</i> is nonzero and <i>SrcAddr</i> is NULL , then <i>This->Mode->CurrentAddress</i> is used for the source HW MAC address.
<i>DestAddr</i>	The destination HW MAC address. If <i>HeaderSize</i> is zero, then this parameter is ignored.
<i>Protocol</i>	The type of header to build. If <i>HeaderSize</i> is zero, then this parameter is ignored. See RFC 1700, section "Ether Types," for examples.

Description

This function places the packet specified by **Header** and **Buffer** on the transmit queue. If **HeaderSize** is nonzero and **HeaderSize** is not equal to

This->Mode->MediaHeaderSize, then **EFI_INVALID_PARAMETER** will be returned. If **BufferSize** is less than **This->Mode->MediaHeaderSize**, then **EFI_BUFFER_TOO_SMALL** will be returned. If **Buffer** is **NULL**, then **EFI_INVALID_PARAMETER** will be returned. If **HeaderSize** is nonzero and **DestAddr** or **Protocol** is **NULL**, then **EFI_INVALID_PARAMETER** will be returned. If the transmit engine of the network interface is busy, then **EFI_NOT_READY** will be returned. If this packet can be accepted by the transmit engine of the network interface, the packet contents specified by **Buffer** will be placed on the transmit queue of the network interface, and **EFI_SUCCESS** will be returned. [GetStatus\(\)](#) can be used to determine when the packet has actually been transmitted. The contents of the *Buffer* must not be modified until the packet has actually been transmitted.

The **Transmit()** function performs nonblocking I/O. A caller who wants to perform blocking I/O, should call **Transmit()**, and then **GetStatus()** until the transmitted buffer shows up in the recycled transmit buffer.

If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

Status Codes Returned

EFI_SUCCESS	The packet was placed on the transmit queue.
EFI_NOT_STARTED	The network interface has not been started.
EFI_NOT_READY	The network interface is too busy to accept this transmit request.
EFI_BUFFER_TOO_SMALL	The <i>BufferSize</i> parameter is too small.
EFI_INVALID_PARAMETER	One or more of the parameters has an unsupported value.
EFI_DEVICE_ERROR	The command could not be sent to the network interface.
EFI_UNSUPPORTED	This function is not supported by the network interface.

EFI_SIMPLE_NETWORK.Receive()

Summary

Receives a packet from a network interface.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_RECEIVE) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL      *This
    OUT UINTN                           *HeaderSize    OPTIONAL,
    IN OUT UINTN                         *BufferSize,
    OUT VOID                             *Buffer,
    OUT EFI_MAC_ADDRESS                  *SrcAddr       OPTIONAL,
    OUT EFI_MAC_ADDRESS                  *DestAddr      OPTIONAL,
    OUT UINT16                           *Protocol     OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI SIMPLE NETWORK PROTOCOL instance.
<i>HeaderSize</i>	The size, in bytes, of the media header received on the network interface. If this parameter is NULL , then the media header size will not be returned.
<i>BufferSize</i>	On entry, the size, in bytes, of <i>Buffer</i> . On exit, the size, in bytes, of the packet that was received on the network interface.
<i>Buffer</i>	A pointer to the data buffer to receive both the media header and the data.
<i>SrcAddr</i>	The source HW MAC address. If this parameter is NULL , the HW MAC source address will not be extracted from the media header.
<i>DestAddr</i>	The destination HW MAC address. If this parameter is NULL , the HW MAC destination address will not be extracted from the media header.
<i>Protocol</i>	The media header type. If this parameter is NULL , then the protocol will not be extracted from the media header. See RFC 1700 section “Ether Types” for examples.

Description

This function retrieves one packet from the receive queue of a network interface. If there are no packets on the receive queue, then **EFI_NOT_READY** will be returned. If there is a packet on the receive queue, and the size of the packet is smaller than **BufferSize**, then the contents of the packet will be placed in **Buffer**, and **BufferSize** will be updated with the actual size of the packet. In addition, if **SrcAddr**, **DestAddr**, and **Protocol** are not **NULL**, then these values will be extracted from the media header and returned. **EFI_SUCCESS** will be returned if a packet was

successfully received. If **BufferSize** is smaller than the received packet, then the size of the receive packet will be placed in **BufferSize** and **EFI_BUFFER_TOO_SMALL** will be returned. If the driver has not been initialized, **EFI_DEVICE_ERROR** will be returned.

Status Codes Returned

EFI_SUCCESS	The received data was stored in <i>Buffer</i> , and <i>BufferSize</i> has been updated to the number of bytes received.
EFI_NOT_STARTED	The network interface has not been started.
EFI_NOT_READY	No packets have been received on the network interface.
EFI_BUFFER_TOO_SMALL	<i>BufferSize</i> is too small for the received packets. <i>BufferSize</i> has been updated to the required size.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> The <i>This</i> parameter is NULL The <i>This</i> parameter does not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure. The <i>BufferSize</i> parameter is NULL The <i>Buffer</i> parameter is NULL
EFI_DEVICE_ERROR	The command could not be sent to the network interface.

21.2 Network Interface Identifier Protocol

This is an optional protocol that is used to describe details about the software layer that is used to produce the Simple Network Protocol. This protocol is only required if the underlying network interface is 16-bit UNDI, 32/64-bit S/W UNDI, or H/W UNDI. It is used to obtain type and revision information about the underlying network interface.

An instance of the Network Interface Identifier protocol must be created for each physical external network interface that is controlled by the !PXE structure. The !PXE structure is defined in the 32/64-bit UNDI Specification in Appendix E.

EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL

Summary

An optional protocol that is used to describe details about the software layer that is used to produce the Simple Network Protocol.

GUID

```
#define EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_GUID \
{0xE18541CD, 0xF755, 0x4f73, 0x92, 0x8D, 0x64, 0x3C, 0x8A, 0x79, 0xB2, \
0x29}
```

Revision Number

```
#define EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_REVISION \
0x00010000
```

Protocol Interface Structure

```
typedef struct {
    UINT64    Revision;
    UINT64    Id;
    UINT64    ImageAddr;
    UINT32    ImageSize;
    CHAR8     StringId[4];
    UINT8     Type;
    UINT8     MajorVer;
    UINT8     MinorVer;
    BOOLEAN   Ipv6Supported;
    UINT8     IfNum;
} EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL;
```

Parameters

Revision

The revision of the **EFI_NETWORK_INTERFACE_IDENTIFIER** protocol.

Id

Address of the first byte of the identifying structure for this network interface. This is only valid when the network interface is started (see [Start\(\)](#)). When the network interface is not started, this field is set to zero.

16-bit UNDI and 32/64-bit S/W UNDI:

Id contains the address of the first byte of the copy of the **!PXE** structure in the relocated UNDI code segment. See the *Preboot Execution Environment (PXE) Specification* and Appendix E.

H/W UNDI:

Id contains the address of the **!PXE** structure.

ImageAddr

Address of the unrelocated network interface image.

16-bit UNDI:

ImageAddr is the address of the PXE option ROM image in upper memory.

32/64-bit S/W UNDI:

ImageAddr is the address of the unrelocated S/W UNDI image.

H/W UNDI:

ImageAddr contains zero.

ImageSize

Size of unrelocated network interface image.

16-bit UNDI:

ImageSize is the size of the PXE option ROM image in upper memory.

32/64-bit S/W UNDI:

ImageSize is the size of the unrelocated S/W UNDI image.

H/W UNDI:

<i>StringId</i>	ImageSize contains zero. A four-character ASCII string that is sent in the class identifier field of option 60 in DHCP. For a <i>Type</i> of EfiNetworkInterfaceUndi , this field is “UNDI.”
<i>Type</i>	Network interface type. This will be set to one of the values in EFI_NETWORK_INTERFACE_TYPE (see “Related Definitions” below).
<i>MajorVer</i>	Major version number. 16-bit UNDI: MajorVer comes from the third byte of the UNDIRev field in the UNDI ROM ID structure. Refer to the <i>Preboot Execution Environment (PXE) Specification</i> . 32/64-bit S/W UNDI and H/W UNDI: MajorVer comes from the Major field in the !PXE structure. See Appendix E.
<i>MinorVer</i>	Minor version number. 16-bit UNDI: MinorVer comes from the second byte of the UNDIRev field in the UNDI ROM ID structure. Refer to the <i>Preboot Execution Environment (PXE) Specification</i> . 32/64-bit S/W UNDI and H/W UNDI: MinorVer comes from the Minor field in the !PXE structure. See Appendix E.
Ipv6Supported	TRUE if the network interface supports IPv6; otherwise FALSE .
<i>IfNum</i>	The network interface number that is being identified by this Network Interface Identifier Protocol. This field must be less than or equal to the IFcnt field in the !PXE structure.

Related Definitions

```

//*****
// EFI_NETWORK_INTERFACE_TYPE
//*****
typedef enum {
    EfiNetworkInterfaceUndi = 1
} EFI_NETWORK_INTERFACE_TYPE;

```

Description

The **EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL** is used by [EFI PXE BASE CODE PROTOCOL](#) and OS loaders to identify the type of the underlying network interface and to locate its initial entry point.

21.3 PXE Base Code Protocol

This section defines the Preboot Execution Environment (PXE) Base Code protocol, which is used to access PXE-compatible devices for network access and network booting. More information about PXE can be found in the *Preboot Execution Environment (PXE) Specification* at: <ftp://download.intel.com/ial/wfm/pxespec.pdf>.

EFI_PXE_BASE_CODE_PROTOCOL

Summary

The **EFI_PXE_BASE_CODE_PROTOCOL** is used to control PXE-compatible devices. The features of these devices are defined in the *Preboot Execution Environment (PXE) Specification*. An **EFI_PXE_BASE_CODE_PROTOCOL** will be layered on top of an **EFI_MANAGED_NETWORK_PROTOCOL** protocol in order to perform packet level transactions. The **EFI_PXE_BASE_CODE_PROTOCOL** handle also supports the [EFI_LOAD_FILE_PROTOCOL](#) protocol. This provides a clean way to obtain control from the boot manager if the boot path is from the remote device.

GUID

```
#define EFI_PXE_BASE_CODE_PROTOCOL_GUID \
    {0x03C4E603, 0xAC28, 0x11d3, 0x9A, 0x2D, 0x00, 0x90, 0x27, 0x3F, 0xC1, 0x4D}
```

Revision Number

```
#define EFI_PXE_BASE_CODE_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```
typedef struct {
    UINT64                Revision;
    EFI_PXE_BASE_CODE_START Start;
    EFI_PXE_BASE_CODE_STOP Stop;
    EFI_PXE_BASE_CODE_DHCP Dhcp;
    EFI_PXE_BASE_CODE_DISCOVER Discover;
    EFI_PXE_BASE_CODE_MTFTP Mtftp;
    EFI_PXE_BASE_CODE_UDP_WRITE UdpWrite;
    EFI_PXE_BASE_CODE_UDP_READ UdpRead;
    EFI_PXE_BASE_CODE_SET_IP_FILTER SetIpFilter;
    EFI_PXE_BASE_CODE_ARP Arp;
    EFI_PXE_BASE_CODE_SET_PARAMETERS SetParameters;
    EFI_PXE_BASE_CODE_SET_STATION_IP SetStationIp;
    EFI_PXE_BASE_CODE_SET_PACKETS SetPackets;
    EFI_PXE_BASE_CODE_MODE *Mode;
} EFI_PXE_BASE_CODE_PROTOCOL;
```

Parameters

<i>Revision</i>	The revision of the EFI_PXE_BASE_CODE_PROTOCOL . All future revisions must be backwards compatible. If a future version is not backwards compatible it is not the same GUID.
<i>Start</i>	Starts the PXE Base Code Protocol. Mode structure information is not valid and no other Base Code Protocol functions will operate until the Base Code is started. See the Start() function description.
<i>Stop</i>	Stops the PXE Base Code Protocol. Mode structure information is unchanged by this function. No Base Code Protocol functions will operate until the Base Code is restarted. See the Stop() function description.
<i>Dhcp</i>	Attempts to complete a DHCPv4 D.O.R.A. (discover / offer / request / acknowledge) or DHCPv6 S.A.R.R (solicit / advertise / request / reply) sequence. See the Dhcp() function description.
<i>Discover</i>	Attempts to complete the PXE Boot Server and/or boot image discovery sequence. See the Discover() function description.
<i>Mtftp</i>	Performs TFTP and MTFTP services. See the Mtftp() function description.
<i>UdpWrite</i>	Writes a UDP packet to the network interface. See the UdpWrite() function description.
<i>UdpRead</i>	Reads a UDP packet from the network interface. See the UdpRead() function description.
<i>SetIpFilter</i>	Updates the IP receive filters of the network device. See the SetIpFilter() function description.
<i>Arp</i>	Uses the ARP protocol to resolve a MAC address. See the Arp() function description.
<i>SetParameters</i>	Updates the parameters that affect the operation of the PXE Base Code Protocol. See the SetParameters() function description.
<i>SetStationIp</i>	Updates the station IP address and subnet mask values. See the SetStationIp() function description.
<i>SetPackets</i>	Updates the contents of the cached DHCP and Discover packets. See the SetPackets() function description.
<i>Mode</i>	Pointer to the EFI_PXE_BASE_CODE_MODE data for this device. The EFI_PXE_BASE_CODE_MODE structure is defined in “Related Definitions” below.

Related Definitions

```

//*****
// Maximum ARP and Route Entries
//*****
#define EFI_PXE_BASE_CODE_MAX_ARP_ENTRIES      8
#define EFI_PXE_BASE_CODE_MAX_ROUTE_ENTRIES   8
    
```



```

//*****
// EFI_PXE_BASE_CODE_MODE
//
// The data values in this structure are read-only and
// are updated by the code that produces the
// EFI_PXE_BASE_CODE_PROTOCOLfunctions. //
//*****
typedef struct {
    BOOLEAN                Started;
    BOOLEAN                Ipv6Available;
    BOOLEAN                Ipv6Supported;
    BOOLEAN                UsingIpv6;
    BOOLEAN                BisSupported;
    BOOLEAN                BisDetected;
    BOOLEAN                AutoArp;
    BOOLEAN                SendGUID;
    BOOLEAN                DhcpDiscoverValid;
    BOOLEAN                DhcpAckReceived;
    BOOLEAN                ProxyOfferReceived;
    BOOLEAN                PxeDiscoverValid;
    BOOLEAN                PxeReplyReceived;
    BOOLEAN                PxeBisReplyReceived;
    BOOLEAN                IcmpErrorReceived;
    BOOLEAN                TftpErrorReceived;
    BOOLEAN                MakeCallbacks;
    UINT8                 TTL;
    UINT8                 ToS;
    EFI_IP_ADDRESS        StationIp;
    EFI_IP_ADDRESS        SubnetMask;
    EFI_PXE_BASE_CODE_PACKET DhcpDiscover;
    EFI_PXE_BASE_CODE_PACKET DhcpAck;
    EFI_PXE_BASE_CODE_PACKET ProxyOffer;
    EFI_PXE_BASE_CODE_PACKET PxeDiscover;
    EFI_PXE_BASE_CODE_PACKET PxeReply;
    EFI_PXE_BASE_CODE_PACKET PxeBisReply;
    EFI_PXE_BASE_CODE_IP_FILTER IpFilter;
    UINT32                 ArpCacheEntries;
    EFI_PXE_BASE_CODE_ARP_ENTRY
        ArpCache[EFI_PXE_BASE_CODE_MAX_ARP_ENTRIES];
    UINT32                 RouteTableEntries;
    EFI_PXE_BASE_CODE_ROUTE_ENTRY
        RouteTable[EFI_PXE_BASE_CODE_MAX_ROUTE_ENTRIES];
    EFI_PXE_BASE_CODE_ICMP_ERROR IcmpError;
    EFI_PXE_BASE_CODE_TFTP_ERROR TftpError;
} EFI_PXE_BASE_CODE_MODE;

```

<i>Started</i>	TRUE if this device has been started by calling Start() . This field is set to TRUE by the Start() function and to FALSE by the Stop() function.
<i>Ipv6Available</i>	TRUE if the Simple Network Protocol being used supports IPv6.
<i>Ipv6Supported</i>	TRUE if this PXE Base Code Protocol implementation supports IPv6.
<i>UsingIpv6</i>	TRUE if this device is currently using IPv6. This field is set by the Start() function.
<i>BisSupported</i>	TRUE if this PXE Base Code implementation supports Boot Integrity Services (BIS). This field is set by the Start() function.
<i>BisDetected</i>	TRUE if this device and the platform support Boot Integrity Services (BIS). This field is set by the Start() function.
<i>AutoArp</i>	TRUE for automatic ARP packet generation; FALSE otherwise. This field is initialized to TRUE by Start() and can be modified with the SetParameters() function.
<i>SendGUID</i>	This field is used to change the Client Hardware Address (chaddr) field in the DHCP and Discovery packets. Set to TRUE to send the SystemGuid (if one is available). Set to FALSE to send the client NIC MAC address. This field is initialized to FALSE by Start() and can be modified with the SetParameters() function.
<i>DhcpDiscoverValid</i>	This field is initialized to FALSE by the Start() function and set to TRUE when the Dhcp() function completes successfully. When TRUE , the DhcpDiscover field is valid. This field can also be changed by the SetPackets() function.
<i>DhcpAckReceived</i>	This field is initialized to FALSE by the Start() function and set to TRUE when the Dhcp() function completes successfully. When TRUE , the DhcpAck field is valid. This field can also be changed by the SetPackets() function.
<i>ProxyOfferReceived</i>	This field is initialized to FALSE by the Start() function and set to TRUE when the Dhcp() function completes successfully and a proxy DHCP offer packet was received. When TRUE , the ProxyOffer packet field is valid. This field can also be changed by the SetPackets() function.
<i>PxeDiscoverValid</i>	When TRUE , the PxeDiscover packet field is valid. This field is set to FALSE by the Start() and Dhcp() functions, and can be set to TRUE or FALSE by the Discover() and SetPackets() functions.
<i>PxeReplyReceived</i>	When TRUE , the PxeReply packet field is valid. This field is set to FALSE by the Start() and Dhcp() functions, and can be set to TRUE or FALSE by the Discover() and SetPackets() functions.
<i>PxeBisReplyReceived</i>	When TRUE , the PxeBisReply packet field is valid. This field is set to FALSE by the Start() and Dhcp() functions, and

	can be set to TRUE or FALSE by the Discover () and SetPackets () functions.
<i>IcmpErrorReceived</i>	Indicates whether the IcmpError field has been updated. This field is reset to FALSE by the Start () , Dhcp () , Discover () , Mtftp () , UdpRead () , UdpWrite () and Arp () functions. If an ICMP error is received, this field will be set to TRUE after the IcmpError field is updated.
<i>TftpErrorReceived</i>	Indicates whether the TftpError field has been updated. This field is reset to FALSE by the Start () and Mtftp () functions. If a TFTP error is received, this field will be set to TRUE after the TftpError field is updated.
<i>MakeCallbacks</i>	When FALSE , callbacks will not be made. When TRUE , make callbacks to the PXE Base Code Callback Protocol. This field is reset to FALSE by the Start () function if the PXE Base Code Callback Protocol is not available. It is reset to TRUE by the Start () function if the PXE Base Code Callback Protocol is available.
<i>TTL</i>	The “time to live” field of the IP header. This field is initialized to DEFAULT_TTL (See “Related Definitions”) by the Start () function and can be modified by the SetParameters () function.
<i>ToS</i>	The type of service field of the IP header. This field is initialized to DEFAULT_ToS (See “Related Definitions”) by Start () , and can be modified with the SetParameters () function.
<i>StationIp</i>	The device’s current IP address. This field is initialized to a zero address by Start () . This field is set when the Dhcp () function completes successfully. This field can also be set by the SetStationIp () function. This field must be set to a valid IP address by either Dhcp () or SetStationIp () before the Discover () , Mtftp () , UdpRead () , UdpWrite () and Arp () functions are called.
<i>SubnetMask</i>	The device’s current subnet mask. This field is initialized to a zero address by the Start () function. This field is set when the Dhcp () function completes successfully. This field can also be set by the SetStationIp () function. This field must be set to a valid subnet mask by either Dhcp () or SetStationIp () before the Discover () , Mtftp () , UdpRead () , UdpWrite () , or Arp () functions are called.
<i>DhcpDiscover</i>	Cached DHCP Discover packet. This field is zero-filled by the Start () function, and is set when the Dhcp () function completes successfully. The contents of this field can be replaced by the SetPackets () function.
<i>DhcpAck</i>	Cached DHCP Ack packet. This field is zero-filled by the Start () function, and is set when the Dhcp () function completes successfully. The contents of this field can be replaced by the SetPackets () function.

<i>ProxyOffer</i>	Cached Proxy Offer packet. This field is zero-filled by the Start() function, and is set when the Dhcp() function completes successfully. The contents of this field can be replaced by the SetPackets() function.
<i>PxeDiscover</i>	Cached PXE Discover packet. This field is zero-filled by the Start() function, and is set when the Discover() function completes successfully. The contents of this field can be replaced by the SetPackets() function.
<i>PxeReply</i>	Cached PXE Reply packet. This field is zero-filled by the Start() function, and is set when the Discover() function completes successfully. The contents of this field can be replaced by the SetPackets() function.
<i>PxeBisReply</i>	Cached PXE BIS Reply packet. This field is zero-filled by the Start() function, and is set when the Discover() function completes successfully. This field can be replaced by the SetPackets() function.
<i>IpFilter</i>	The current IP receive filter settings. The receive filter is disabled and the number of IP receive filters is set to zero by the <u>Start()</u> function, and is set by the <u>SetIpFilter()</u> function.
<i>ArpCacheEntries</i>	The number of valid entries in the ARP cache. This field is reset to zero by the Start() function.
<i>ArpCache</i>	Array of cached ARP entries.
<i>RouteTableEntries</i>	The number of valid entries in the current route table. This field is reset to zero by the Start() function.
<i>RouteTable</i>	Array of route table entries.
<i>IcmpError</i>	ICMP error packet. This field is updated when an ICMP error is received and is undefined until the first ICMP error is received. This field is zero-filled by the Start() function.
<i>TftpError</i>	TFTP error packet. This field is updated when a TFTP error is received and is undefined until the first TFTP error is received. This field is zero-filled by the Start() function.

```

//*****
// EFI_PXE_BASE_CODE_UDP_PORT
//*****
typedef UINT16 EFI_PXE_BASE_CODE_UDP_PORT;

//*****
// EFI_IPv4_ADDRESS and EFI_IPv6_ADDRESS
//*****
typedef struct {
    UINT8    Addr[4];
} EFI_IPv4_ADDRESS;

typedef struct {

```

```

    UINT8   Addr[16];
} EFI_IPv6_ADDRESS;

//*****
// EFI_IP_ADDRESS
//*****
typedef union {
    UINT32           Addr[4];
    EFI_IPv4_ADDRESS v4;
    EFI_IPv6_ADDRESS v6;
} EFI_IP_ADDRESS;

//*****
// EFI_MAC_ADDRESS
//*****
typedef struct {
    UINT8   Addr[32];
} EFI_MAC_ADDRESS;

```

DHCP Packet Data Types

This section defines the data types for DHCP packets, ICMP error packets, and TFTP error packets. All of these are byte-packed data structures.

Note: *All the multibyte fields in these structures are stored in network order.*

```

//*****
// EFI_PXE_BASE_CODE_DHCPV4_PACKET
//*****
typedef struct {
    UINT8           BootpOpcode;
    UINT8           BootpHwType;
    UINT8           BootpHwAddrLen;
    UINT8           BootpGateHops;
    UINT32          BootpIdent;
    UINT16          BootpSeconds;
    UINT16          BootpFlags;
    UINT8           BootpCiAddr[4];
    UINT8           BootpYiAddr[4];
    UINT8           BootpSiAddr[4];
    UINT8           BootpGiAddr[4];
    UINT8           BootpHwAddr[16];
    UINT8           BootpSrvName[64];
    UINT8           BootpBootFile[128];
}

```

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```
        UINT32      DhcpMagik;
        UINT8       DhcpOptions[56];
} EFI_PXE_BASE_CODE_DHCPV4_PACKET;

/*****
// EFI_PXE_BASE_CODE_PACKET
/*****
typedef union {
    UINT8                               Raw[1472];
    EFI_PXE_BASE_CODE_DHCPV4_PACKET     Dhcpv4;
    // EFI_PXE_BASE_CODE_DHCPV6_PACKET   Dhcpv6;
} EFI_PXE_BASE_CODE_PACKET;

/*****
// EFI_PXE_BASE_CODE_ICMP_ERROR
/*****
typedef struct {
    UINT8      Type;
    UINT8      Code;
    UINT16     Checksum;
    union {
        UINT32  reserved;
        UINT32  Mtu;
        UINT32  Pointer;
        struct {
            UINT16  Identifier;
            UINT16  Sequence;
        } Echo;
    } u;
    UINT8      Data[494];
} EFI_PXE_BASE_CODE_ICMP_ERROR;

/*****
// EFI_PXE_BASE_CODE_TFTP_ERROR
/*****
typedef struct {
    UINT8      ErrorCode;
    CHAR8      ErrorString[127];
} EFI_PXE_BASE_CODE_TFTP_ERROR;
```

IP Receive Filter Settings

This section defines the data types for IP receive filter settings.

```
#define EFI_PXE_BASE_CODE_MAX_IPCNT8
```

```

//*****
// EFI_PXE_BASE_CODE_IP_FILTER
//*****
typedef struct {
    UINT8           Filters;
    UINT8           IpCnt;
    UINT16          reserved;
    EFI_IP_ADDRESS  IpList[EFI_PXE_BASE_CODE_MAX_IPCNT];
} EFI_PXE_BASE_CODE_IP_FILTER;

#define EFI_PXE_BASE_CODE_IP_FILTER_STATION_IP      0x0001
#define EFI_PXE_BASE_CODE_IP_FILTER_BROADCAST     0x0002
#define EFI_PXE_BASE_CODE_IP_FILTER_PROMISCUOUS   0x0004
#define EFI_PXE_BASE_CODE_IP_FILTER_PROMISCUOUS_MULTICAST 0x0008

```

ARP Cache Entries

This section defines the data types for ARP cache entries, and route table entries.

```

//*****
// EFI_PXE_BASE_CODE_ARP_ENTRY
//*****
typedef struct {
    EFI_IP_ADDRESS  IpAddr;
    EFI_MAC_ADDRESS MacAddr;
} EFI_PXE_BASE_CODE_ARP_ENTRY;

//*****
// EFI_PXE_BASE_CODE_ROUTE_ENTRY
//*****
typedef struct {
    EFI_IP_ADDRESS  IpAddr;
    EFI_IP_ADDRESS  SubnetMask;
    EFI_IP_ADDRESS  GwAddr;
} EFI_PXE_BASE_CODE_ROUTE_ENTRY;

```

Filter Operations for UDP Read/Write Functions

This section defines the types of filter operations that can be used with the [UdpRead\(\)](#) and [UdpWrite\(\)](#) functions.

```

#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_SRC_IP      0x0001
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_SRC_PORT   0x0002
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_DEST_IP   0x0004
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_DEST_PORT 0x0008
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_USE_FILTER     0x0010

```

```
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_MAY_FRAGMENT 0x0020
#define DEFAULT_TTL 16
#define DEFAULT_ToS 0
```

The following table defines values for the PXE DHCP and Bootserver Discover packet tags that are specific to the UEFI environment. Complete definitions of all PXE tags are defined in [Table 163](#) “PXE DHCP Options (Full List),” in the *PXE Specification*.

Table 163. PXE Tag Definitions for EFI

Tag Name	Tag #	Length	Data Field
Client Network Interface Identifier	94 [0x5E]	3 [0x03]	Type (1), MajorVer (1), MinorVer (1) Type is a one byte field that identifies the network interface that will be used by the downloaded program. Type is followed by two one byte version number fields, MajorVer and MinorVer. Type UNDI (1) = 0x01 Versions WfM-1.1a 16-bit UNDI: MajorVer = 0x02, MinorVer = 0x00 PXE-2.0 16-bit UNDI: MajorVer = 0x02, MinorVer = 0x01 32/64-bit UNDI & H/W UNDI: MajorVer = 0x03, MinorVer = 0x00
Client System Architecture	93 [0x5D]	2 [0x02]	Type (2) Type is a two byte, network order, field that identifies the processor and programming environment of the client system. Types Legacy x86 PC = 0x00 0x00 Supported Itanium PC = 0x00 0x02 IA-32 PC = 0x00 0x06 X64 EFI PC=0x00 0x07
Class Identifier	60 [0x3C]	32 [0x20]	"PXEClient:Arch:xxxxx:UNDI:yyyzzz" "PXEClient:..." is used to identify communication between PXE clients and servers. Information from tags 93 & 94 is embedded in the Class Identifier string. (The strings defined in this tag are case sensitive and must not be NULL-terminated.) xxxxx = ASCII representation of Client System Architecture. yyyzzz = ASCII representation of Client Network Interface Identifier version numbers MajorVer(yyy) and MinorVer(zzz). Example "PXEClient:Arch:00002:UNDI:00300" identifies an IA64 PC w/ 32/64-bit UNDI

Description

The basic mechanisms and flow for remote booting in UEFI are identical to the remote boot functionality described in detail in the *PXE Specification*. However, the actual execution environment, linkage, and calling conventions are replaced and enhanced for the UEFI environment.

The DHCP Option for the Client System Architecture is used to inform the DHCP server if the client is a UEFI environment in supported systems. The server may use this information to provide default images if it does not have a specific boot profile for the client.

A handle that supports [EFI PXE BASE CODE PROTOCOL](#) is required to support [EFI LOAD FILE PROTOCOL](#). The [EFI_LOAD_FILE_PROTOCOL](#) function [LoadFile\(\)](#) is used by the firmware to load files from devices that do not support file system type accesses. Specifically, the firmware's boot manager invokes [LoadFile\(\)](#) with [BootPolicy](#) being [TRUE](#) when attempting to boot from the device. The firmware then loads and transfers control to the downloaded PXE boot image. Once the remote image is successfully loaded, it may utilize the [EFI_PXE_BASE_CODE_PROTOCOL](#) interfaces, or even the [EFI_SIMPLE_NETWORK_PROTOCOL](#) interfaces, to continue the remote process.

EFI_PXE_BASE_CODE_PROTOCOL.Start()

Summary

Enables the use of the PXE Base Code Protocol functions.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_START) (
    IN EFI_PXE_BASE_CODE_PROTOCOL    *This,
    IN BOOLEAN                       UseIpv6
);
```

Parameters

<i>This</i>	Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.
<i>UseIpv6</i>	Specifies the type of IP addresses that are to be used during the session that is being started. Set to TRUE for IPv6 addresses, and FALSE for IPv4 addresses.

Description

This function enables the use of the PXE Base Code Protocol functions. If the **Started** field of the [EFI_PXE_BASE_CODE_MODE](#) structure is already **TRUE**, then **EFI_ALREADY_STARTED** will be returned. If **UseIpv6** is **TRUE**, then IPv6 formatted addresses will be used in this session. If **UseIpv6** is **FALSE**, then IPv4 formatted addresses will be used in this session. If **UseIpv6** is **TRUE**, and the **Ipv6Supported** field of the [EFI_PXE_BASE_CODE_MODE](#) structure is **FALSE**, then **EFI_UNSUPPORTED** will be returned. If there is not enough memory or other resources to start the PXE Base Code Protocol, then **EFI_OUT_OF_RESOURCES** will be returned. Otherwise, the PXE Base Code Protocol will be started, and all of the fields of the [EFI_PXE_BASE_CODE_MODE](#) structure will be initialized as follows:

Started	Set to TRUE .
Ipv6Supported	Unchanged.
Ipv6Available	Unchanged.
UsingIpv6	Set to UseIpv6 .
BisSupported	Unchanged.
BisDetected	Unchanged.
AutoArp	Set to TRUE .
SendGUID	Set to FALSE .
TTL	Set to DEFAULT_TTL .
ToS	Set to DEFAULT_ToS .
DhcpCompleted	Set to FALSE .
ProxyOfferReceived	Set to FALSE .
StationIp	Set to an address of all zeros.

SubnetMask	Set to a subnet mask of all zeros.
DhcpDiscover	Zero-filled.
DhcpAck	Zero-filled.
ProxyOffer	Zero-filled.
PxeDiscoverValid	Set to FALSE .
PxeDiscover	Zero-filled.
PxeReplyValid	Set to FALSE .
PxeReply	Zero-filled.
PxeBisReplyValid	Set to FALSE .
PxeBisReply	Zero-filled.
IpFilter	Set the Filters field to 0 and the IpCnt field to 0.
ArpCacheEntries	Set to 0.
ArpCache	Zero-filled.
RouteTableEntries	Set to 0.
RouteTable	Zero-filled.
IcmpErrorReceived	Set to FALSE .
IcmpError	Zero-filled.
TftpErrorReceived	Set to FALSE .
TftpError	Zero-filled.
<i>MakeCallbacks</i>	Set to TRUE if the PXE Base Code Callback Protocol is available. Set to FALSE if the PXE Base Code Callback Protocol is not available.

Status Codes Returned

EFI_SUCCESS	The PXE Base Code Protocol was started.
EFI_INVALID_PARAMETER	The <i>This</i> parameter is NULL or does not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure.
EFI_UNSUPPORTED	<i>UseIpv6</i> is TRUE , but the <i>Ipv6Supported</i> field of the EFI_PXE_BASE_CODE_MODE structure is FALSE .
EFI_ALREADY_STARTED	The PXE Base Code Protocol is already in the started state.
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_OUT_OF_RESOURCES	Could not allocate enough memory or other resources to start the PXE Base Code Protocol.

EFI_PXE_BASE_CODE_PROTOCOL.Dhcp()

Summary

Attempts to complete a DHCPv4 D.O.R.A. (discover / offer / request / acknowledge) or DHCPv6 S.A.R.R (solicit / advertise / request / reply) sequence.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_DHCP) (
    IN EFI_PXE_BASE_CODE_PROTOCOL    *This,
    IN BOOLEAN                       SortOffers
);
```

Parameters

This Pointer to the [EFI_PXE_BASE_CODE_PROTOCOL](#) instance.

SortOffers **TRUE** if the offers received should be sorted. Set to **FALSE** to try the offers in the order that they are received.

Description

This function attempts to complete the DHCP sequence. If this sequence is completed, then **EFI_SUCCESS** is returned, and the **DhcpCompleted**, **ProxyOfferReceived**, **StationIp**, **SubnetMask**, **DhcpDiscover**, **DhcpAck**, and **ProxyOffer** fields of the [EFI_PXE_BASE_CODE_MODE](#) structure are filled in.

If **SortOffers** is **TRUE**, then the cached DHCP offer packets will be sorted before they are tried. If **SortOffers** is **FALSE**, then the cached DHCP offer packets will be tried in the order in which they are received. Please see the *Preboot Execution Environment (PXE) Specification* for additional details on the implementation of DHCP.

This function can take at least 31 seconds to timeout and return control to the caller. If the DHCP sequence does not complete, then **EFI_TIMEOUT** will be returned.

If the Callback Protocol does not return **EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE**, then the DHCP sequence will be stopped and **EFI_ABORTED** will be returned.

Status Codes Returned

EFI_SUCCESS	Valid DHCP has completed.
EFI_NOT_STARTED	The PXE Base Code Protocol is in the stopped state.
EFI_INVALID_PARAMETER	The <i>This</i> parameter is NULL or does not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure.
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_OUT_OF_RESOURCES	Could not allocate enough memory to complete the DHCP Protocol.
EFI_ABORTED	The callback function aborted the DHCP Protocol.

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EFI_TIMEOUT	The DHCP Protocol timed out.
EFI_ICMP_ERROR	An ICMP error packet was received during the DHCP session. The ICMP error packet has been cached in the EFI_PXE_BASE_CODE_MODE . <i>IcmpError</i> packet structure. Information about ICMP packet contents can be found in RFC 792.
EFI_NO_RESPONSE	Valid PXE offer was not received.

EFI_PXE_BASE_CODE_PROTOCOL.Discover()

Summary

Attempts to complete the PXE Boot Server and/or boot image discovery sequence.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_DISCOVER) (
    IN EFI_PXE_BASE_CODE_PROTOCOL      *This,
    IN UINT16                          Type,
    IN UINT16                          *Layer,
    IN BOOLEAN                          UseBis,
    IN EFI_PXE_BASE_CODE_DISCOVER_INFO *Info    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI PXE BASE CODE PROTOCOL instance.
<i>Type</i>	The type of bootstrap to perform. See “Related Definitions” below.
<i>Layer</i>	Pointer to the boot server layer number to discover, which must be PXE_BOOT_LAYER_INITIAL when a new server type is being discovered. This is the only layer type that will perform multicast and broadcast discovery. All other layer types will only perform unicast discovery. If the boot server changes Layer , then the new Layer will be returned.
<i>UseBis</i>	TRUE if Boot Integrity Services are to be used. FALSE otherwise.
<i>Info</i>	Pointer to a data structure that contains additional information on the type of discovery operation that is to be performed. If this field is NULL , then the contents of the cached DhcpAck and ProxyOffer packets will be used.

Related Definitions

```

//*****
// Bootstrap Types
//*****

#define EFI_PXE_BASE_CODE_BOOT_TYPE_BOOTSTRAP      0
#define EFI_PXE_BASE_CODE_BOOT_TYPE_MS_WINNT_RIS  1
#define EFI_PXE_BASE_CODE_BOOT_TYPE_INTEL_LCM     2
#define EFI_PXE_BASE_CODE_BOOT_TYPE_DOSUNDI      3
#define EFI_PXE_BASE_CODE_BOOT_TYPE_NEC_ESMPRO    4
#define EFI_PXE_BASE_CODE_BOOT_TYPE_IBM_WSOD     5
#define EFI_PXE_BASE_CODE_BOOT_TYPE_IBM_LCCM     6
#define EFI_PXE_BASE_CODE_BOOT_TYPE_CA_UNICENTER_TNG 7
```

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```
#define EFI_PXE_BASE_CODE_BOOT_TYPE_HP_OPENVIEW      8
#define EFI_PXE_BASE_CODE_BOOT_TYPE_ALTIRIS_9       9
#define EFI_PXE_BASE_CODE_BOOT_TYPE_ALTIRIS_10      10
#define EFI_PXE_BASE_CODE_BOOT_TYPE_ALTIRIS_11      11
#define EFI_PXE_BASE_CODE_BOOT_TYPE_NOT_USED_12      12
#define EFI_PXE_BASE_CODE_BOOT_TYPE_REDHAT_INSTALL  13
#define EFI_PXE_BASE_CODE_BOOT_TYPE_REDHAT_BOOT     14
#define EFI_PXE_BASE_CODE_BOOT_TYPE_REMBO          15
#define EFI_PXE_BASE_CODE_BOOT_TYPE_BEOBOOT         16
//
// Values 17 through 32767 are reserved.
// Values 32768 through 65279 are for vendor use.
// Values 65280 through 65534 are reserved.
//
#define EFI_PXE_BASE_CODE_BOOT_TYPE_PXETEST         65535

#define EFI_PXE_BASE_CODE_BOOT_LAYER_MASK           0x7FFF
#define EFI_PXE_BASE_CODE_BOOT_LAYER_INITIAL        0x0000

//*****
// EFI_PXE_BASE_CODE_DISCOVER_INFO
//*****
typedef struct {
    BOOLEAN                UseMCast;
    BOOLEAN                UseBCast;
    BOOLEAN                UseUCast;
    BOOLEAN                MustUseList;
    EFI_IP_ADDRESS         ServerMCastIp;
    UINT16                 IpCnt;
    EFI_PXE_BASE_CODE_SRVLIST SrvList[IpCnt];
} EFI_PXE_BASE_CODE_DISCOVER_INFO;

//*****
// EFI_PXE_BASE_CODE_SRVLIST
//*****
typedef struct {
    UINT16                 Type;
    BOOLEAN                AcceptAnyResponse;
    UINT8                 reserved;
    EFI_IP_ADDRESS         IpAddr;
} EFI_PXE_BASE_CODE_SRVLIST;
```


Description

This function attempts to complete the PXE Boot Server and/or boot image discovery sequence. If this sequence is completed, then **EFI_SUCCESS** is returned, and the **PxeDiscoverValid**, **PxeDiscover**, **PxeReplyReceived**, and **PxeReply** fields of the **EFI_PXE_BASE_CODE_MODE** structure are filled in. If **UseBis** is **TRUE**, then the **PxeBisReplyReceived** and **PxeBisReply** fields of the **EFI_PXE_BASE_CODE_MODE** structure will also be filled in. If **UseBis** is **FALSE**, then **PxeBisReplyValid** will be set to **FALSE**.

In the structure referenced by parameter **Info**, the PXE Boot Server list, **SrvList[]**, has two uses: It is the Boot Server IP address list used for unicast discovery (if the **UseUCast** field is **TRUE**), and it is the list used for Boot Server verification (if the **MustUseList** field is **TRUE**). Also, if the **MustUseList** field in that structure is **TRUE** and the **AcceptAnyResponse** field in the **SrvList[]** array is **TRUE**, any Boot Server reply of that type will be accepted. If the **AcceptAnyResponse** field is **FALSE**, only responses from Boot Servers with matching IP addresses will be accepted.

This function can take at least 10 seconds to timeout and return control to the caller. If the Discovery sequence does not complete, then **EFI_TIMEOUT** will be returned. Please see the *Preboot Execution Environment (PXE) Specification* for additional details on the implementation of the Discovery sequence.

If the Callback Protocol does not return

EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE, then the Discovery sequence is stopped and **EFI_ABORTED** will be returned.

Status Codes Returned

EFI_SUCCESS	The Discovery sequence has been completed.
EFI_NOT_STARTED	The PXE Base Code Protocol is in the stopped state.
EFI_INVALID_PARAMETER	One or more of the following conditions was TRUE : <ul style="list-style-type: none"> The <i>This</i> parameter was NULL The <i>This</i> parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure The <i>Layer</i> parameter was NULL The <i>Info->ServerMCastIp</i> parameter does not contain a valid multicast IP address The <i>Info->UseUCast</i> parameter is not FALSE and the <i>Info->IpCnt</i> parameter is zero One or more of the IP addresses in the <i>Info->SrvList[]</i> array is not a valid unicast IP address.
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_OUT_OF_RESOURCES	Could not allocate enough memory to complete Discovery.
EFI_ABORTED	The callback function aborted the Discovery sequence.
EFI_TIMEOUT	The Discovery sequence timed out.

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EFI_ICMP_ERROR	An ICMP error packet was received during the PXE discovery session. The ICMP error packet has been cached in the EFI_PXE_BASE_CODE_MODE . <i>IcmpError</i> packet structure. Information about ICMP packet contents can be found in RFC 792.
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EFI_PXE_BASE_CODE_PROTOCOL.Mtftp()

Summary

Used to perform TFTP and MTFTP services.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_PXE_BASE_CODE_MTFTP) (
    IN EFI_PXE_BASE_CODE_PROTOCOL      *This,
    IN EFI_PXE_BASE_CODE_TFTP_OPCODE  Operation,
    IN OUT VOID                        *BufferPtr, OPTIONAL
    IN BOOLEAN                         Overwrite,
    IN OUT UINT64                      *BufferSize,
    IN UINTN                           *BlockSize, OPTIONAL
    IN EFI_IP_ADDRESS                 *ServerIp,
    IN CHAR8                           *Filename, OPTIONAL
    IN EFI_PXE_BASE_CODE_MTFTP_INFO   *Info, OPTIONAL
    IN BOOLEAN                         DontUseBuffer
);
```

Parameters

<i>This</i>	Pointer to the EFI PXE BASE CODE PROTOCOL instance.
<i>Operation</i>	The type of operation to perform. See “Related Definitions” below for the list of operation types.
<i>BufferPtr</i>	A pointer to the data buffer. Ignored for read file if DontUseBuffer is TRUE .
<i>Overwrite</i>	Only used on write file operations. TRUE if a file on a remote server can be overwritten.
<i>BufferSize</i>	For get-file-size operations, <i>BufferSize</i> returns the size of the requested file. For read-file and write-file operations, this parameter is set to the size of the buffer specified by the <i>BufferPtr</i> parameter. For read-file operations, if EFI_BUFFER_TOO_SMALL is returned, <i>BufferSize</i> returns the size of the requested file.
<i>BlockSize</i>	The requested block size to be used during a TFTP transfer. This must be at least 512. If this field is NULL , then the largest block size supported by the implementation will be used.
<i>ServerIp</i>	The TFTP / MTFTP server IP address.
<i>Filename</i>	A Null-terminated ASCII string that specifies a directory name or a file name. This is ignored by MTFTP read directory.
<i>Info</i>	Pointer to the MTFTP information. This information is required to start or join a multicast TFTP session. It is also required to perform the “get file size” and “read directory” operations of

MTFTP. See “Related Definitions” below for the description of this data structure.

DontUseBuffer

Set to **FALSE** for normal TFTP and MTFTP read file operation. Setting this to **TRUE** will cause TFTP and MTFTP read file operations to function without a receive buffer, and all of the received packets are passed to the Callback Protocol which is responsible for storing them. This field is only used by TFTP and MTFTP read file.

Related Definitions

```

//*****
// EFI_PXE_BASE_CODE_TFTP_OPCODE
//*****
typedef enum {
    EFI_PXE_BASE_CODE_TFTP_FIRST,
    EFI_PXE_BASE_CODE_TFTP_GET_FILE_SIZE,
    EFI_PXE_BASE_CODE_TFTP_READ_FILE,
    EFI_PXE_BASE_CODE_TFTP_WRITE_FILE,
    EFI_PXE_BASE_CODE_TFTP_READ_DIRECTORY,
    EFI_PXE_BASE_CODE_MTFTP_GET_FILE_SIZE,
    EFI_PXE_BASE_CODE_MTFTP_READ_FILE,
    EFI_PXE_BASE_CODE_MTFTP_READ_DIRECTORY,
    EFI_PXE_BASE_CODE_MTFTP_LAST
} EFI_PXE_BASE_CODE_TFTP_OPCODE;

//*****
// EFI_PXE_BASE_CODE_MTFTP_INFO
//*****
typedef struct {
    EFI_IP_ADDRESS          MCastIp;
    EFI_PXE_BASE_CODE_UDP_PORT CPort;
    EFI_PXE_BASE_CODE_UDP_PORT SPort;
    UINT16                  ListenTimeout;
    UINT16                  TransmitTimeout;
} EFI_PXE_BASE_CODE_MTFTP_INFO;

```

MCastIp File multicast IP address. This is the IP address to which the server will send the requested file.

CPort Client multicast listening port. This is the UDP port to which the server will send the requested file.

SPort Server multicast listening port. This is the UDP port on which the server listens for multicast open requests and data acks.

ListenTimeout The number of seconds a client should listen for an active multicast session before requesting a new multicast session.

TransmitTimeout The number of seconds a client should wait for a packet from the server before retransmitting the previous open request or data ack packet.

Description

This function is used to perform TFTP and MFTFTP services. This includes the TFTP operations to get the size of a file, read a directory, read a file, and write a file. It also includes the MFTFTP operations to get the size of a file, read a directory, and read a file. The type of operation is specified by **Operation**. If the callback function that is invoked during the TFTP/MFTFTP operation does not return **EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE**, then **EFI_ABORTED** will be returned.

For read operations, the return data will be placed in the buffer specified by **BufferPtr**. If **BufferSize** is too small to contain the entire downloaded file, then **EFI_BUFFER_TOO_SMALL** will be returned and **BufferSize** will be set to zero or the size of the requested file (the size of the requested file is only returned if the TFTP server supports TFTP options). If **BufferSize** is large enough for the read operation, then **BufferSize** will be set to the size of the downloaded file, and **EFI_SUCCESS** will be returned. Applications using the **PxeBc.Mtftp()** services should use the **get-file-size** operations to determine the size of the downloaded file prior to using the **read-file** operations—especially when downloading large (greater than 64 MB) files—instead of making two calls to the **read-file** operation. Following this recommendation will save time if the file is larger than expected and the TFTP server does not support TFTP option extensions. Without TFTP option extension support, the client has to download the entire file, counting and discarding the received packets, to determine the file size.

For write operations, the data to be sent is in the buffer specified by **BufferPtr**. **BufferSize** specifies the number of bytes to send. If the write operation completes successfully, then **EFI_SUCCESS** will be returned.

For TFTP “get file size” operations, the size of the requested file or directory is returned in **BufferSize**, and **EFI_SUCCESS** will be returned. If the TFTP server does not support options, the file will be downloaded into a bit bucket and the length of the downloaded file will be returned. For MFTFTP “get file size” operations, if the MFTFTP server does not support the “get file size” option, **EFI_UNSUPPORTED** will be returned.

This function can take up to 10 seconds to timeout and return control to the caller. If the TFTP sequence does not complete, **EFI_TIMEOUT** will be returned.

If the Callback Protocol does not return **EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE**, then the TFTP sequence is stopped and **EFI_ABORTED** will be returned.

The format of the data returned from a TFTP read directory operation is a null-terminated filename followed by a null-terminated information string, of the form “size year-month-day hour:minute:second” (i.e. %d %d-%d-%d %d:%d:%f - note that the seconds field can be a decimal number), where the date and time are UTC. For an MFTFTP read directory command, there is additionally a null-terminated multicast IP address preceding the filename of the form %d.%d.%d.%d for IP v4. The final entry is itself null-terminated, so that the final information string is terminated with two null octets.

Status Codes Returned

EFI_SUCCESS	The TFTP/MTFTP operation was completed.
EFI_NOT_STARTED	The PXE Base Code Protocol is in the stopped state.
EFI_INVALID_PARAMETER	<p>One or more of the following conditions was TRUE:</p> <ul style="list-style-type: none"> • The <i>This</i> parameter was NULL • The <i>This</i> parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure • The Operation parameter was not one of the listed EFI_PXE_BASE_CODE_TFTP_OPCODE constants • The <i>BufferPtr</i> parameter was NULL and the DontUseBuffer parameter was FALSE • The <i>BufferSize</i> parameter was NULL • The BlockSize parameter was not NULL and *BlockSize was less than 512 • The ServerIp parameter was NULL or did not contain a valid unicast IP address • The Filename parameter was NULL for a file transfer or information request • The Info parameter was NULL for a multicast request <p>The Info->MCastIp parameter is not a valid multicast IP address</p>
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_BUFFER_TOO_SMALL	The buffer is not large enough to complete the read operation.
EFI_ABORTED	The callback function aborted the TFTP/MTFTP operation.
EFI_TIMEOUT	The TFTP/MTFTP operation timed out.
EFI_TFTP_ERROR	<p>A TFTP error packet was received during the MTFTP session. The TFTP error packet has been cached in the EFI_PXE_BASE_CODE_MODE.TftpError packet structure. Information about TFTP error packet contents can be found in RFC 1350.</p>
EFI_ICMP_ERROR	<p>An ICMP error packet was received during the MTFTP session. The ICMP error packet has been cached in the EFI_PXE_BASE_CODE_MODE.IcmpError packet structure. Information about ICMP packet contents can be found in RFC 792.</p>

EFI_PXE_BASE_CODE_PROTOCOL.UdpWrite()

Summary

Writes a UDP packet to the network interface.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_PXE_BASE_CODE_UDP_WRITE) (
    IN EFI_PXE_BASE_CODE_PROTOCOL      *This,
    IN UINT16                          OpFlags,
    IN EFI_IP_ADDRESS                  *DestIp,
    IN EFI_PXE_BASE_CODE_UDP_PORT      *DestPort,
    IN EFI_IP_ADDRESS                  *GatewayIp,    OPTIONAL
    IN EFI_IP_ADDRESS                  *SrcIp,        OPTIONAL
    IN OUT EFI_PXE_BASE_CODE_UDP_PORT *SrcPort,     OPTIONAL
    IN UINTN                            *HeaderSize,  OPTIONAL
    IN VOID                             *HeaderPtr,   OPTIONAL
    IN UINTN                            *BufferSize,
    IN VOID                             *BufferPtr
);
```

Parameters

<i>This</i>	Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.
<i>OpFlags</i>	The UDP operation flags. If MAY_FRAGMENT is set, then if required, this UDP write operation may be broken up across multiple packets.
<i>DestIp</i>	The destination IP address.
<i>DestPort</i>	The destination UDP port number.
<i>GatewayIp</i>	The gateway IP address. If <i>DestIp</i> is not in the same subnet as StationIp , then this gateway IP address will be used. If this field is NULL , and the DestIp is not in the same subnet as <i>StationIp</i> , then the RouteTable will be used.
<i>SrcIp</i>	The source IP address. If this field is NULL , then <i>StationIp</i> will be used as the source IP address.
<i>SrcPort</i>	The source UDP port number. If OpFlags has ANY_SRC_PORT set or <i>SrcPort</i> is NULL , then a source UDP port will be automatically selected. If a source UDP port was automatically selected, and SrcPort is not NULL , then it will be returned in <i>SrcPort</i> .
<i>HeaderSize</i>	An optional field which may be set to the length of a header at <i>HeaderPtr</i> to be prefixed to the data at <i>BufferPtr</i> .
<i>HeaderPtr</i>	If <i>HeaderSize</i> is not NULL , a pointer to a header to be prefixed to the data at <i>BufferPtr</i> .
<i>BufferSize</i>	A pointer to the size of the data at BufferPtr .

BufferPtr

A pointer to the data to be written.

Description

This function writes a UDP packet specified by the (optional **HeaderPtr** and) **BufferPtr** parameters to the network interface. The UDP header is automatically built by this routine. It uses the parameters **OpFlags**, **DestIp**, **DestPort**, **GatewayIp**, **SrcIp**, and **SrcPort** to build this header. If the packet is successfully built and transmitted through the network interface, then **EFI_SUCCESS** will be returned. If a timeout occurs during the transmission of the packet, then **EFI_TIMEOUT** will be returned. If an ICMP error occurs during the transmission of the packet, then the **IcmpErrorReceived** field is set to **TRUE**, the **IcmpError** field is filled in and **EFI_ICMP_ERROR** will be returned. If the Callback Protocol does not return **EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE**, then **EFI_ABORTED** will be returned.

Status Codes Returned

EFI_SUCCESS	The UDP Write operation was completed.
EFI_NOT_STARTED	The PXE Base Code Protocol is in the stopped state.
EFI_INVALID_PARAMETER	One or more of the following conditions was TRUE : <ul style="list-style-type: none"> • The <i>This</i> parameter was NULL • The <i>This</i> parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure • Reserved bits in the OpFlags parameter were not set to zero • The DestIp parameter was NULL • The DestPort parameter was NULL • The GatewayIp parameter was not NULL and did not contain a valid unicast IP address. • The HeaderSize parameter was not NULL and *HeaderSize is zero • The *HeaderSize parameter was not zero and the HeaderPtr parameter was NULL • The BufferSize parameter was NULL • The *BufferSize parameter was not zero and the BufferPtr parameter was NULL
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_BAD_BUFFER_SIZE	The buffer is too long to be transmitted.
EFI_ABORTED	The callback function aborted the UDP Write operation.
EFI_TIMEOUT	The UDP Write operation timed out.
EFI_ICMP_ERROR	An ICMP error packet was received during the UDP write session. The ICMP error packet has been cached in the EFI_PXE_BASE_CODE_MODE.IcmpError packet structure. Information about ICMP packet contents can be found in RFC 792.

EFI_PXE_BASE_CODE_PROTOCOL.UdpRead()

Summary

Reads a UDP packet from the network interface.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_UDP_READ) (
    IN EFI_PXE_BASE_CODE_PROTOCOL      *This
    IN UINT16                          OpFlags,
    IN OUT EFI_IP_ADDRESS              *DestIp,      OPTIONAL
    IN OUT EFI_PXE_BASE_CODE_UDP_PORT *DestPort,  OPTIONAL
    IN OUT EFI_IP_ADDRESS              *SrcIp,      OPTIONAL
    IN OUT EFI_PXE_BASE_CODE_UDP_PORT *SrcPort,  OPTIONAL
    IN UINTN                           *HeaderSize, OPTIONAL
    IN VOID                            *HeaderPtr,  OPTIONAL
    IN OUT UINTN                       *BufferSize,
    IN VOID                            *BufferPtr
);
```

Parameters

<i>This</i>	Pointer to the EFI PXE BASE CODE PROTOCOL instance.
<i>OpFlags</i>	The UDP operation flags.
<i>DestIp</i>	The destination IP address.
<i>DestPort</i>	The destination UDP port number.
<i>SrcIp</i>	The source IP address.
<i>SrcPort</i>	The source UDP port number.
<i>HeaderSize</i>	An optional field which may be set to the length of a header to be put in HeaderPtr .
<i>HeaderPtr</i>	If HeaderSize is not NULL , a pointer to a buffer to hold the HeaderSize bytes which follow the UDP header.
<i>BufferSize</i>	On input, a pointer to the size of the buffer at <i>BufferPtr</i> . On output, the size of the data written to <i>BufferPtr</i> .
<i>BufferPtr</i>	A pointer to the data to be read.

Description

This function reads a UDP packet from a network interface. The data contents are returned in (the optional **HeaderPtr** and) **BufferPtr**, and the size of the buffer received is returned in **BufferSize**. If the input **BufferSize** is smaller than the UDP packet received (less optional **HeaderSize**), it will be set to the required size, and **EFI_BUFFER_TOO_SMALL** will be returned. In this case, the contents of **BufferPtr** are undefined, and the packet is lost. If a UDP packet is successfully received, then **EFI_SUCCESS** will be returned, and the information from the UDP header will be returned in **DestIp**, **DestPort**, **SrcIp**, and **SrcPort** if they are not **NULL**.

Depending on the values of **OpFlags** and the **DestIp**, **DestPort**, **SrcIp**, and **SrcPort** input values, different types of UDP packet receive filtering will be performed. The following tables summarize these receive filter operations.

Table 164. Destination IP Filter Operation

OpFlags USE_FILTER	OpFlags ANY_DEST_IP	DestIp	Action
0	0	NULL	Receive a packet sent to <i>StationIp</i> .
0	1	NULL	Receive a packet sent to any IP address.
1	x	NULL	Receive a packet whose destination IP address passes the IP filter.
0	0	not NULL	Receive a packet whose destination IP address matches <i>DestIp</i> .
0	1	not NULL	Receive a packet sent to any IP address and, return the destination IP address in <i>DestIp</i> .
1	x	not NULL	Receive a packet whose destination IP address passes the IP filter, and return the destination IP address in <i>DestIp</i> .

Table 165. Destination UDP Port Filter Operation

OpFlags ANY_DEST_PORT	DestPort	Action
0	NULL	Return EFI_INVALID_PARAMETER .
1	NULL	Receive a packet sent to any UDP port.
0	not NULL	Receive a packet whose destination Port matches <i>DestPort</i> .
1	not NULL	Receive a packet sent to any UDP port, and return the destination port in <i>DestPort</i> .

Table 166. Source IP Filter Operation

OpFlags ANY_SRC_IP	SrcIp	Action
0	NULL	Return EFI_INVALID_PARAMETER .
1	NULL	Receive a packet sent from any IP address.
0	not NULL	Receive a packet whose source IP address matches <i>SrcIp</i> .
1	not NULL	Receive a packet sent from any IP address, and return the source IP address in <i>SrcIp</i> .

Table 167. Source UDP Port Filter Operation

OpFlags ANY_SRC_PORT	SrcPort	Action
0	NULL	Return EFI_INVALID_PARAMETER .

OpFlags	SrcPort	Action
ANY_SRC_PORT		
1	NULL	Receive a packet sent from any UDP port.
0	not NULL	Receive a packet whose source UDP port matches <i>SrcPort</i> .
1	not NULL	Receive a packet sent from any UDP port, and return the source UDP port in <i>SrcPort</i> .

Status Codes Returned

EFI_SUCCESS	The UDP Read operation was completed.
EFI_NOT_STARTED	The PXE Base Code Protocol is in the stopped state.
EFI_INVALID_PARAMETER	One or more of the following conditions was TRUE : <ul style="list-style-type: none"> The <i>This</i> parameter was NULL The <i>This</i> parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure Reserved bits in the OpFlags parameter were not set to zero The HeaderSize parameter is not NULL and *HeaderSize is zero The HeaderSize parameter is not NULL L and the HeaderPtr parameter is NULL The BufferSize parameter is NULL The BufferPtr parameter is NULL
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_BUFFER_TOO_SMALL	The packet is larger than <i>Buffer</i> can hold.
EFI_ABORTED	The callback function aborted the UDP Read operation.
EFI_TIMEOUT	The UDP Read operation timed out.

<p>EFI_INVALID_PARAMETER</p>	<ul style="list-style-type: none"> • One or more of the following conditions was TRUE: • The <i>This</i> parameter was NULL • The <i>This</i> parameter did not point to a valid <u>EFI PXE BASE CODE PROTOCOL</u> structure • The <i>NewFilter</i> parameter was NULL • The <i>NewFilter</i> -> <i>IPList</i> [] array contains one or more broadcast IP addresses
<p>EFI_NOT_STARTED</p>	<p>The PXE Base Code Protocol is not in the started state.</p>

EFI_PXE_BASE_CODE_PROTOCOL.Arp()

Summary

Uses the ARP protocol to resolve a MAC address.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_ARP) (
    IN EFI_PXE_BASE_CODE_PROTOCOL    *This,
    IN EFI_IP_ADDRESS                *IpAddr,
    IN EFI_MAC_ADDRESS               *MacAddr    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.
<i>IpAddr</i>	Pointer to the IP address that is used to resolve a MAC address. When the MAC address is resolved, the ArpCacheEntries and ArpCache fields of the EFI_PXE_BASE_CODE_MODE structure are updated.
<i>MacAddr</i>	If not NULL , a pointer to the MAC address that was resolved with the ARP protocol.

Description

This function uses the ARP protocol to resolve a MAC address. The **UsingIpv6** field of the **EFI_PXE_BASE_CODE_MODE** structure is used to determine if IPv4 or IPv6 addresses are being used. The IP address specified by **IpAddr** is used to resolve a MAC address. If the ARP protocol succeeds in resolving the specified address, then the **ArpCacheEntries** and **ArpCache** fields of the **EFI_PXE_BASE_CODE_MODE** structure are updated, and **EFI_SUCCESS** is returned. If **MacAddr** is not **NULL**, the resolved MAC address is placed there as well.

If the PXE Base Code protocol is in the stopped state, then **EFI_NOT_STARTED** is returned. If the ARP protocol encounters a timeout condition while attempting to resolve an address, then **EFI_TIMEOUT** is returned. If the Callback Protocol does not return **EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE**, then **EFI_ABORTED** is returned.

Status Codes Returned

EFI_SUCCESS	The IP or MAC address was resolved.
EFI_INVALID_PARAMETER	One or more of the following conditions was : <ul style="list-style-type: none"> • The <i>This</i> parameter was NULL • The <i>This</i> parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure • The IpAddr parameter was NULL
EFI_DEVICE_ERROR	The network device encountered an error during this operation.
EFI_NOT_STARTED	The PXE Base Code Protocol is in the stopped state.

EFI_TIMEOUT	The ARP Protocol encountered a timeout condition.
EFI_ABORTED	The callback function aborted the ARP Protocol.

EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()

Summary

Updates the parameters that affect the operation of the PXE Base Code Protocol.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_PXE_BASE_CODE_SET_PARAMETERS) (
    IN EFI_PXE_BASE_CODE_PROTOCOL *This,
    IN BOOLEAN                    *NewAutoArp,        OPTIONAL
    IN BOOLEAN                    *NewSendGUID,       OPTIONAL
    IN UINT8                      *NewTTL,            OPTIONAL
    IN UINT8                      *NewToS,            OPTIONAL
    IN BOOLEAN                    *NewMakeCallback   OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.
<i>NewAutoArp</i>	If not NULL , a pointer to a value that specifies whether to replace the current value of AutoARP . TRUE for automatic ARP packet generation, FALSE otherwise. If NULL , this parameter is ignored.
<i>NewSendGUID</i>	If not NULL , a pointer to a value that specifies whether to replace the current value of SendGUID . TRUE to send the SystemGUID (if there is one) as the client hardware address in DHCP; FALSE to send client NIC MAC address. If NULL , this parameter is ignored. If <i>NewSendGUID</i> is TRUE and there is no SystemGUID, then EFI_INVALID_PARAMETER is returned.
<i>NewTTL</i>	If not NULL , a pointer to be used in place of the current value of TTL , the “time to live” field of the IP header. If NULL , this parameter is ignored.
<i>NewToS</i>	If not NULL , a pointer to be used in place of the current value of ToS , the “type of service” field of the IP header. If NULL , this parameter is ignored.
<i>NewMakeCallback</i>	If not NULL , a pointer to a value that specifies whether to replace the current value of the MakeCallback field of the Mode structure. If NULL , this parameter is ignored. If the Callback Protocol is not available EFI_INVALID_PARAMETER is returned.

Description

This function sets parameters that affect the operation of the PXE Base Code Protocol. The parameter specified by *NewAutoArp* is used to control the generation of ARP protocol packets. If *NewAutoArp* is **TRUE**, then ARP Protocol packets will be generated as required by the PXE Base Code Protocol. If *NewAutoArp* is **FALSE**, then no ARP Protocol packets will be generated. In this case, the only mappings that are available are those stored in the **ArpCache** of the

[EFI_PXE_BASE_CODE_MODE](#) structure. If there are not enough mappings in the **ArpCache** to perform a PXE Base Code Protocol service, then the service will fail. This function updates the **AutoArp** field of the **EFI_PXE_BASE_CODE_MODE** structure to **NewAutoArp**.

The [SetParameters\(\)](#) call must be invoked after a Callback Protocol is installed to enable the use of callbacks.

Status Codes Returned

EFI_SUCCESS	The new parameters values were updated.
EFI_INVALID_PARAMETER	<ul style="list-style-type: none"> • One or more of the following conditions was TRUE : • The <i>This</i> parameter was NULL • The <i>This</i> parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure • The <i>NewSendGUID</i> parameter is not NULL and * <i>NewSendGUID</i> is TRUE and a system GUID could not be located • The <i>NewMakeCallback</i> parameter is not NULL and * <i>NewMakeCallback</i> is TRUE and an EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL could not be located on the network device handle.
EFI_NOT_STARTED	The PXE Base Code Protocol is not in the started state.

EFI_PXE_BASE_CODE_PROTOCOL.SetStationIp()

Summary

Updates the station IP address and/or subnet mask values of a network device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_SET_STATION_IP) (
    IN EFI_PXE_BASE_CODE_PROTOCOL      *This,
    IN EFI_IP_ADDRESS                  *NewStationIp,    OPTIONAL
    IN EFI_IP_ADDRESS                  *NewSubnetMask    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI PXE BASE CODE PROTOCOL instance.
<i>NewStationIp</i>	Pointer to the new IP address to be used by the network device. If this field is NULL , then the StationIp address will not be modified.
<i>NewSubnetMask</i>	Pointer to the new subnet mask to be used by the network device. If this field is NULL , then the SubnetMask will not be modified.

Description

This function updates the station IP address and/or subnet mask values of a network device.

The *NewStationIp* field is used to modify the network device’s current IP address. If *NewStationIp* is **NULL**, then the current IP address will not be modified. Otherwise, this function updates the *StationIp* field of the [EFI PXE BASE CODE MODE](#) structure with *NewStationIp*.

The *NewSubnetMask* field is used to modify the network device’s current subnet mask. If *NewSubnetMask* is **NULL**, then the current subnet mask will not be modified. Otherwise, this function updates the **SubnetMask** field of the [EFI_PXE_BASE_CODE_MODE](#) structure with *NewSubnetMask*.

Status Codes Returned

EFI_SUCCESS	The new station IP address and/or subnet mask were updated.
EFI_INVALID_PARAMETER	One or more of the following conditions was TRUE : <ul style="list-style-type: none"> • The <i>This</i> s parameter was NULL • The <i>This</i> parameter did not point to a valid EFI PXE BASE CODE PROTOCOL structure • The NewStationIp parameter is not NULL and * <i>NewStationIp</i> is not a valid unicast IP address • The <i>NewSubnetMask</i> parameter is not NULL and * <i>NewSubnetMask</i> does not contain a valid IP subnet mask

EFI_NOT_STARTED	The PXE Base Code Protocol is not in the started state.
-----------------	---

EFI_PXE_BASE_CODE_PROTOCOL.SetPackets()

Summary

Updates the contents of the cached DHCP and Discover packets.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_PXE_BASE_CODE_SET_PACKETS) (
    IN EFI_PXE_BASE_CODE_PROTOCOL      *This,
    IN BOOLEAN                        *NewDhcpDiscoverValid,    OPTIONAL
    IN BOOLEAN                        *NewDhcpAckReceived,      OPTIONAL
    IN BOOLEAN                        *NewProxyOfferReceived,   OPTIONAL
    IN BOOLEAN                        *NewPxeDiscoverValid,     OPTIONAL
    IN BOOLEAN                        *NewPxeReplyReceived,     OPTIONAL
    IN BOOLEAN                        *NewPxeBisReplyReceived,  OPTIONAL
    IN EFI_PXE_BASE_CODE_PACKET      *NewDhcpDiscover,    OPTIONAL
    IN EFI_PXE_BASE_CODE_PACKET      *NewDhcpAck,          OPTIONAL
    IN EFI_PXE_BASE_CODE_PACKET      *NewProxyOffer,       OPTIONAL
    IN EFI_PXE_BASE_CODE_PACKET      *NewPxeDiscover,      OPTIONAL
    IN EFI_PXE_BASE_CODE_PACKET      *NewPxeReply,         OPTIONAL
    IN EFI_PXE_BASE_CODE_PACKET      *NewPxeBisReply       OPTIONAL
);
```

Parameters

This Pointer to the [EFI PXE BASE CODE PROTOCOL](#) instance.

NewDhcpDiscoverValid Pointer to a value that will replace the current *DhcpDiscoverValid* field. If **NULL**, this parameter is ignored.

NewDhcpAckReceived Pointer to a value that will replace the current **DhcpAckReceived** field. If **NULL**, this parameter is ignored.

NewProxyOfferReceived Pointer to a value that will replace the current *ProxyOfferReceived* field. If **NULL**, this parameter is ignored.

NewPxeDiscoverValid Pointer to a value that will replace the current *ProxyOfferReceived* field. If **NULL**, this parameter is ignored.

NewPxeReplyReceived Pointer to a value that will replace the current *PxeReplyReceived* field. If **NULL**, this parameter is ignored.

NewPxeBisReplyReceived Pointer to a value that will replace the current *PxeBisReplyReceived* field. If **NULL**, this parameter is ignored.

NewDhcpDiscover Pointer to the new cached DHCP Discover packet contents. If **NULL**, this parameter is ignored.

<i>NewDhcpAck</i>	Pointer to the new cached DHCP Ack packet contents. If NULL , this parameter is ignored.
<i>NewProxyOffer</i>	Pointer to the new cached Proxy Offer packet contents. If NULL , this parameter is ignored.
<i>NewPxeDiscover</i>	Pointer to the new cached PXE Discover packet contents. If NULL , this parameter is ignored.
<i>NewPxeReply</i>	Pointer to the new cached PXE Reply packet contents. If NULL , this parameter is ignored.
<i>NewPxeBisReply</i>	Pointer to the new cached PXE BIS Reply packet contents. If NULL , this parameter is ignored.

Description

The pointers to the new packets are used to update the contents of the cached packets in the [EFI PXE BASE CODE MODE](#) structure.

Status Codes Returned

EFI_SUCCESS	The cached packet contents were updated.
EFI_INVALID_PARAMETER	<ul style="list-style-type: none"> One or more of the following conditions was TRUE: The <i>This</i> parameter was NULL The <i>This</i> parameter did not point to a valid EFI PXE BASE CODE PROTOCOL structure.
EFI_NOT_STARTED	The PXE Base Code Protocol is not in the started state.

21.4 PXE Base Code Callback Protocol

This protocol is a specific instance of the PXE Base Code Callback Protocol that is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet. The PXE Base Code Callback Protocol must be on the same handle as the PXE Base Code Protocol.

EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL

Summary

Protocol that is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet.

GUID

```
#define EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_GUID \
  {0x245DCA21, 0xFB7B, 0x11d3, 0x8F, 0x01, 0x00, 0xA0, 0xC9, 0x69, 0x72, \
  0x3B}
```

Revision Number

```
#define EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_REVISION \
  0x00010000
```

Protocol Interface Structure

```
typedef struct {  
    UINT64 Revision;  
    EFI_PXE_CALLBACK Callback;  
} EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL;
```

Parameters

Revision

The revision of the **EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL**. All future revisions must be backwards compatible. If a future revision is not backwards compatible, it is not the same GUID.

Callback

Callback routine used by the PXE Base Code [Dhcp\(\)](#), [Discover\(\)](#), [Mtftp\(\)](#), [UdpWrite\(\)](#), and [Arp\(\)](#) functions.

EFI_PXE_BASE_CODE_CALLBACK.Callback()

Summary

Callback function that is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet.

Prototype

```
typedef
EFI_PXE_BASE_CODE_CALLBACK_STATUS
(*EFI_PXE_CALLBACK) (
    IN EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL *This,
    IN EFI_PXE_BASE_CODE_FUNCTION        Function,
    IN BOOLEAN                            Received,
    IN UINT32                             PacketLen,
    IN EFI_PXE_BASE_CODE_PACKET           *Packet OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI PXE BASE CODE PROTOCOL instance.
<i>Function</i>	The PXE Base Code Protocol function that is waiting for an event.
<i>Received</i>	TRUE if the callback is being invoked due to a receive event. FALSE if the callback is being invoked due to a transmit event.
<i>PacketLen</i>	The length, in bytes, of Packet . This field will have a value of zero if this is a wait for receive event.
<i>Packet</i>	If <i>Received</i> is TRUE , a pointer to the packet that was just received; otherwise a pointer to the packet that is about to be transmitted. This field will be NULL if this is not a packet event.

Related Definitions

```

/*****
// EFI_PXE_BASE_CODE_CALLBACK_STATUS
/*****
typedef enum {
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_FIRST,
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE,
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_ABORT,
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_LAST
} EFI_PXE_BASE_CODE_CALLBACK_STATUS;

/*****
// EFI_PXE_BASE_CODE_FUNCTION
/*****
```

```

typedef enum {
    EFI_PXE_BASE_CODE_FUNCTION_FIRST,
    EFI_PXE_BASE_CODE_FUNCTION_DHCP,
    EFI_PXE_BASE_CODE_FUNCTION_DISCOVER,
    EFI_PXE_BASE_CODE_FUNCTION_MTFTP,
    EFI_PXE_BASE_CODE_FUNCTION_UDP_WRITE,
    EFI_PXE_BASE_CODE_FUNCTION_UDP_READ,
    EFI_PXE_BASE_CODE_FUNCTION_ARP,
    EFI_PXE_BASE_CODE_FUNCTION_IGMP,
    EFI_PXE_BASE_CODE_PXE_FUNCTION_LAST
} EFI_PXE_BASE_CODE_FUNCTION;

```

Description

This function is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet. Parameters **Function** and **Received** specify the type of event. Parameters **PacketLen** and **Packet** specify the packet that generated the event. If these fields are zero and **NULL** respectively, then this is a status update callback. If the operation specified by **Function** is to continue, then **CALLBACK_STATUS_CONTINUE** should be returned. If the operation specified by **Function** should be aborted, then **CALLBACK_STATUS_ABORT** should be returned. Due to the polling nature of UEFI device drivers, a callback function should not execute for more than 5 ms.

The [SetParameters \(\)](#) function must be called after a Callback Protocol is installed to enable the use of callbacks.

21.5 Boot Integrity Services Protocol

This section defines the Boot Integrity Services (BIS) protocol, which is used to check a digital signature of a data block against a digital certificate for the purpose of an integrity and authorization check. BIS is primarily used by the Preboot Execution Environment (PXE) Base Code protocol [EFI PXE BASE CODE PROTOCOL](#) to check downloaded network boot images before executing them. BIS is an UEFI Boot Services Driver, so its services are also available to applications written to this specification until the time of [ExitBootServices \(\)](#). More information about BIS can be found in the *Boot Integrity Services Application Programming Interface Version 1.0*.

This section defines the Boot Integrity Services Protocol. This protocol is used to check a digital signature of a data block against a digital certificate for the purpose of an integrity and authorization check.

EFI_BIS_PROTOCOL

Summary

The **EFI_BIS_PROTOCOL** is used to check a digital signature of a data block against a digital certificate for the purpose of an integrity and authorization check.

GUID

```
#define EFI_BIS_PROTOCOL_GUID \
    {0x0b64aab0, 0x5429, 0x11d4, 0x98, 0x16, 0x00, 0xa0, 0xc9, 0x1f,
    0xad, 0xcf}
```

Protocol Interface Structure

```
typedef struct _EFI_BIS_PROTOCOL {
    EFI_BIS_INITIALIZE    Initialize;
    EFI_BIS_SHUTDOWN     Shutdown;
    EFI_BIS_FREE         Free;
    EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CERTIFICATE
        GetBootObjectAuthorizationCertificate;
    EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CHECKFLAG
        GetBootObjectAuthorizationCheckFlag;
    EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_UPDATE_TOKEN
        GetBootObjectAuthorizationUpdateToken;
    EFI_BIS_GET_SIGNATURE_INFO
        GetSignatureInfo;
    EFI_BIS_UPDATE_BOOT_OBJECT_AUTHORIZATION
        UpdateBootObjectAuthorization;
    EFI_BIS_VERIFY_BOOT_OBJECT
        VerifyBootObject;
    EFI_BIS_VERIFY_OBJECT_WITH_CREDENTIAL
        VerifyObjectWithCredential;
} EFI_BIS_PROTOCOL;
```

Parameters

<i>Initialize</i>	Initializes an application instance of the EFI_BIS protocol, returning a handle for the application instance. Other functions in the EFI_BIS protocol require a valid application instance handle obtained from this function. See the Initialize() function description.
<i>Shutdown</i>	Ends the lifetime of an application instance of the EFI_BIS protocol, invalidating its application instance handle. The application instance handle may no longer be used in other functions in the EFI_BIS protocol. See the Shutdown() function description.
<i>Free</i>	Frees memory structures allocated and returned by other functions in the EFI_BIS protocol. See the Free() function description.
<i>GetBootObjectAuthorizationCertificate</i>	Retrieves the current digital certificate (if any) used by the EFI_BIS protocol as the source of authorization for verifying

boot objects and altering configuration parameters. See the [GetBootObjectAuthorizationCertificate\(\)](#) function description.

GetBootObjectAuthorizationCheckFlag

Retrieves the current setting of the authorization check flag that indicates whether or not authorization checks are required for boot objects. See the [GetBootObjectAuthorizationCheckFlag\(\)](#) function description.

GetBootObjectAuthorizationUpdateToken

Retrieves an uninterpreted token whose value gets included and signed in a subsequent request to alter the configuration parameters, to protect against attempts to “replay” such a request. See the [GetBootObjectAuthorizationUpdateToken\(\)](#) function description.

GetSignatureInfo

Retrieves information about the digital signature algorithms supported and the identity of the installed authorization certificate, if any. See the [GetSignatureInfo\(\)](#) function description.

UpdateBootObjectAuthorization

Requests that the configuration parameters be altered by installing or removing an authorization certificate or changing the setting of the check flag. See the [UpdateBootObjectAuthorization\(\)](#) function description.

VerifyBootObject

Verifies a boot object according to the supplied digital signature and the current authorization certificate and check flag setting. See the [VerifyBootObject\(\)](#) function description.

VerifyObjectWithCredential

Verifies a data object according to a supplied digital signature and a supplied digital certificate. See the [VerifyObjectWithCredential\(\)](#) function description.

Description

The **EFI_BIS_PROTOCOL** provides a set of functions as defined in this section. There is no physical device associated with these functions, however, in the context of UEFI every protocol operates on a device. Accordingly, BIS installs and operates on a single abstract device that has only a software representation.

EFI_BIS_PROTOCOL.Initialize()

Summary

Initializes the BIS service, checking that it is compatible with the version requested by the caller. After this call, other BIS functions may be invoked.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_INITIALIZE) (
    IN     EFI_BIS_PROTOCOL           *This,
    OUT    BIS_APPLICATION_HANDLE     *AppHandle,
    IN OUT EFI_BIS_VERSION           *InterfaceVersion,
    IN     EFI_BIS_DATA               *TargetAddress
);
```

Parameters

<i>This</i>	A pointer to the EFI_BIS_PROTOCOL object. The protocol implementation may rely on the actual pointer value and object location, so the caller must not copy the object to a new location.
<i>AppHandle</i>	The function writes the new BIS_APPLICATION_HANDLE if successful, otherwise it writes NULL . The caller must eventually destroy this handle by calling Shutdown() . Type BIS_APPLICATION_HANDLE is defined in “Related Definitions” below.
<i>InterfaceVersion</i>	On input, the caller supplies the major version number of the interface version desired. The minor version number supplied on input is ignored since interface compatibility is determined solely by the major version number. On output, both the major and minor version numbers are updated with the major and minor version numbers of the interface (and underlying implementation). This update is done whether or not the initialization was successful. Type EFI_BIS_VERSION is defined in “Related Definitions” below.
<i>TargetAddress</i>	Indicates a network or device address of the BIS platform to connect to. Local-platform BIS implementations require that the caller sets <i>TargetAddress.Data</i> to NULL , but otherwise ignores this parameter. BIS implementations that redirect calls to an agent at a remote address must define their own format and interpretation of this parameter outside the scope of this document. For all implementations, if the <i>TargetAddress</i> is an unsupported value, the function fails with the error EFI_UNSUPPORTED . Type EFI_BIS_DATA is defined in “Related Definitions” below.

Related Definitions

```

//*****
// BIS_APPLICATION_HANDLE
//*****
typedef VOID                *BIS_APPLICATION_HANDLE;

```

This type is an opaque handle representing an initialized instance of the BIS interface. A **BIS_APPLICATION_HANDLE** value is returned by the *Initialize()* function as an “out” parameter. Other BIS functions take a **BIS_APPLICATION_HANDLE** as an “in” parameter to identify the BIS instance.

```

//*****
// EFI_BIS_VERSION
//*****
typedef struct _EFI_BIS_VERSION {
    UINT32                Major;
    UINT32                Minor;
} EFI_BIS_VERSION;

```

Major

This describes the major BIS version number. The major version number defines version compatibility. That is, when a new version of the BIS interface is created with new capabilities that are not available in the previous interface version, the major version number is increased.

Minor

This describes a minor BIS version number. This version number is increased whenever a new BIS implementation is built that is fully interface compatible with the previous BIS implementation. This number may be reset when the major version number is increased.

This type represents a version number of the BIS interface. This is used as an “in out” parameter of the *Initialize()* function for a simple form of negotiation of the BIS interface version between the caller and the BIS implementation.

```

//*****
// EFI_BIS_VERSION predefined values
// Use these values to initialize EFI_BIS_VERSION.Major
// and to interpret results of Initialize.
//*****
#define BIS_CURRENT_VERSION_MAJOR    BIS_VERSION_1
#define BIS_VERSION_1                1

```

These C preprocessor macros supply values for the major version number of an **EFI_BIS_VERSION**. At the time of initialization, a caller supplies a value to request a BIS interface version. On return, the (IN OUT) parameter is over-written with the actual version of the interface.

```

//*****
// EFI_BIS_DATA
//
// EFI_BIS_DATA instances obtained from BIS must be freed by
// calling Free\(\).
//*****
typedef struct _EFI_BIS_DATA {
    UINT32      Length;
    UINT8       *Data;
} EFI_BIS_DATA;

    Length          The length of the data buffer in bytes.
    Data            A pointer to the raw data buffer.

```

This type defines a structure that describes a buffer. BIS uses this type to pass back and forth most large objects such as digital certificates, strings, etc.. Several of the BIS functions allocate a **EFI_BIS_DATA*** and return it as an “out” parameter. The caller must eventually free any allocated **EFI_BIS_DATA*** using the [Free\(\)](#) function.

Description

This function must be the first BIS function invoked by an application. It passes back a [BIS APPLICATION HANDLE](#) value that must be used in subsequent BIS functions. The handle must be eventually destroyed by a call to the [Shutdown\(\)](#) function, thus ending that handle’s lifetime. After the handle is destroyed, BIS functions may no longer be called with that handle value. Thus all other BIS functions may only be called between a pair of [Initialize\(\)](#) and **Shutdown()** functions.

There is no penalty for calling **Initialize()** multiple times. Each call passes back a distinct handle value. Each distinct handle must be destroyed by a distinct call to **Shutdown()**. The lifetimes of handles created and destroyed with these functions may be overlapped in any way.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_INCOMPATIBLE_VERSION	The <i>InterfaceVersion.Major</i> requested by the caller was not compatible with the interface version of the implementation. The <i>InterfaceVersion.Major</i> has been updated with the current interface version.
EFI_UNSUPPORTED	This is a local-platform implementation and <i>TargetAddress.Data</i> was not NULL , or <i>TargetAddress.Data</i> was any other value that was not supported by the implementation.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.

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EFI_DEVICE_ERROR	The function encountered an unexpected internal failure while initializing a cryptographic software module, or No cryptographic software module with compatible version was found, or A resource limitation was encountered while using a cryptographic software module.
EFI_INVALID_PARAMETER	The <i>This</i> parameter supplied by the caller is NULL or does not reference a valid EFI BIS PROTOCOL object, or The <i>AppHandle</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>InterfaceVersion</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>TargetAddress</i> parameter supplied by the caller is NULL or an invalid memory reference.

EFI_BIS_PROTOCOL.Shutdown()

Summary

Shuts down an application's instance of the BIS service, invalidating the application handle. After this call, other BIS functions may no longer be invoked using the application handle value.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_SHUTDOWN) (
    IN BIS_APPLICATION_HANDLE  AppHandle
);
```

Parameters

AppHandle An opaque handle that identifies the caller's instance of initialization of the BIS service. Type [BIS APPLICATION HANDLE](#) is defined in the [Initialize\(\)](#) function description.

Description

This function shuts down an application's instance of the BIS service, invalidating the application handle. After this call, other BIS functions may no longer be invoked using the application handle value.

This function must be paired with a preceding successful call to the **Initialize()** function. The lifetime of an application handle extends from the time the handle was returned from **Initialize()** until the time the handle is passed to **Shutdown()**. If there are other remaining handles whose lifetime is still active, they may still be used in calling BIS functions.

The caller must free all memory resources associated with this *AppHandle* that were allocated and returned from other BIS functions before calling **Shutdown()**. Memory resources are freed using the [Free\(\)](#) function. Failure to free such memory resources is a caller error, however, this function does not return an error code under this circumstance. Further attempts to access the outstanding memory resources cause unspecified results.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_DEVICE_ERROR	The function encountered an unexpected internal error while returning resources associated with a cryptographic software module, or The function encountered an internal error while trying to shut down a cryptographic software module.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.

EFI_BIS_PROTOCOL.Free()

Summary

Frees memory structures allocated and returned by other functions in the **EFI_BIS** protocol.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_BIS_FREE) (
    IN BIS_APPLICATION_HANDLE  AppHandle,
    IN EFI_BIS_DATA            *ToFree
);
```

Parameters

AppHandle

An opaque handle that identifies the caller's instance of initialization of the BIS service. Type [BIS_APPLICATION_HANDLE](#) is defined in the [Initialize\(\)](#) function description.

ToFree

An **EFI_BIS_DATA*** and associated memory block to be freed. This **EFI_BIS_DATA*** must have been allocated by one of the other BIS functions. Type [EFI_BIS_DATA](#) is defined in the [Initialize\(\)](#) function description.

Description

This function deallocates an **EFI_BIS_DATA*** and associated memory allocated by one of the other BIS functions.

Callers of other BIS functions that allocate memory in the form of an **EFI_BIS_DATA*** must eventually call this function to deallocate the memory before calling the [Shutdown\(\)](#) function for the application handle under which the memory was allocated. Failure to do so causes unspecified results, and the continued correct operation of the BIS service cannot be guaranteed.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_INVALID_PARAMETER	The <i>ToFree</i> parameter is not or is no longer a memory resource associated with this <i>AppHandle</i> .
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.

EFI_BIS_PROTOCOL.GetBootObjectAuthorizationCertificate()

Summary

Retrieves the certificate that has been configured as the identity of the organization designated as the source of authorization for signatures of boot objects.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CERTIFICATE) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    OUT EFI_BIS_DATA            **Certificate
);
```

Parameters

AppHandle

An opaque handle that identifies the caller's instance of initialization of the BIS service. Type [BIS_APPLICATION_HANDLE](#) is defined in the [Initialize\(\)](#) function description.

Certificate

The function writes an allocated **EFI_BIS_DATA*** containing the Boot Object Authorization Certificate object. The caller must eventually free the memory allocated by this function using the function [Free\(\)](#). Type [EFI_BIS_DATA](#) is defined in the [Initialize\(\)](#) function description.

Description

This function retrieves the certificate that has been configured as the identity of the organization designated as the source of authorization for signatures of boot objects.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_NOT_FOUND	There is no Boot Object Authorization Certificate currently installed.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.
EFI_INVALID_PARAMETER	The <i>Certificate</i> parameter supplied by the caller is NULL or an invalid memory reference.

EFI_BIS_PROTOCOL.GetBootObjectAuthorizationCheckFlag()

Summary

Retrieves the current status of the Boot Authorization Check Flag.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CHECKFLAG) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    OUT BOOLEAN                 *CheckIsRequired
);
```

Parameters

AppHandle

An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type [BIS_APPLICATION_HANDLE](#) is defined in the [Initialize\(\)](#) function description.

CheckIsRequired

The function writes the value **TRUE** if a Boot Authorization Check is currently required on this platform, otherwise the function writes **FALSE**.

Description

This function retrieves the current status of the Boot Authorization Check Flag (in other words, whether or not a Boot Authorization Check is currently required on this platform).

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.
EFI_INVALID_PARAMETER	The <i>CheckIsRequired</i> parameter supplied by the caller is NULL or an invalid memory reference.

EFI_BIS_PROTOCOL.GetBootObjectAuthorizationUpdateToken()

Summary

Retrieves a unique token value to be included in the request credential for the next update of any parameter in the Boot Object Authorization set (Boot Object Authorization Certificate and Boot Authorization Check Flag).

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_UPDATE_TOKEN) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    OUT EFI_BIS_DATA            **UpdateToken
);
```

Parameters

AppHandle

An opaque handle that identifies the caller's instance of initialization of the BIS service. Type [BIS_APPLICATION_HANDLE](#) is defined in the [Initialize\(\)](#) function description.

UpdateToken

The function writes an allocated **EFI_BIS_DATA*** containing the new unique update token value. The caller must eventually free the memory allocated by this function using the function [Free\(\)](#). Type [EFI_BIS_DATA](#) is defined in the [Initialize\(\)](#) function description.

Description

This function retrieves a unique token value to be included in the request credential for the next update of any parameter in the Boot Object Authorization set (Boot Object Authorization Certificate and Boot Authorization Check Flag). The token value is unique to this platform, parameter set, and instance of parameter values. In particular, the token changes to a new unique value whenever any parameter in this set is changed.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.
EFI_DEVICE_ERROR	The function encountered an unexpected internal error in a cryptographic software module.
EFI_INVALID_PARAMETER	The <i>UpdateToken</i> parameter supplied by the caller is NULL or an invalid memory reference.

EFI_BIS_PROTOCOL.GetSignatureInfo()

Summary

Retrieves a list of digital certificate identifier, digital signature algorithm, hash algorithm, and key-length combinations that the platform supports.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_GET_SIGNATURE_INFO) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    OUT EFI_BIS_DATA            **SignatureInfo
);
```

Parameters

AppHandle An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type [BIS_APPLICATION_HANDLE](#) is defined in the [Initialize\(\)](#) function description.

SignatureInfo The function writes an allocated **EFI_BIS_DATA*** containing the array of **EFI_BIS_SIGNATURE_INFO** structures representing the supported digital certificate identifier, algorithm, and key length combinations. The caller must eventually free the memory allocated by this function using the function [Free\(\)](#). Type [EFI_BIS_DATA](#) is defined in the [Initialize\(\)](#) function description. Type **EFI_BIS_SIGNATURE_INFO** is defined in “Related Definitions” below.

Related Definitions

```

//*****
// EFI_BIS_SIGNATURE_INFO
//*****
typedef struct _EFI_BIS_SIGNATURE_INFO {
    BIS_CERT_ID      CertificateID;
    BIS_ALG_ID       AlgorithmID;
    UINT16           KeyLength;
} EFI_BIS_SIGNATURE_INFO;
```

CertificateID A shortened value identifying the platform’s currently configured Boot Object Authorization Certificate, if one is currently configured. The shortened value is derived from the certificate as defined in the Related Definition for **BIS_CERT_ID** below. If there is no certificate currently configured, the value is one of the reserved **BIS_CERT_ID_XXX** values defined below. Type **BIS_CERT_ID** and its predefined reserved values are defined in “Related Definitions” below.

<i>AlgorithmID</i>	A predefined constant representing a particular digital signature algorithm. Often this represents a combination of hash algorithm and encryption algorithm, however, it may also represent a standalone digital signature algorithm. Type BIS_ALG_ID and its permitted values are defined in “Related Definitions” below.
<i>KeyLength</i>	The length of the public key, in bits, supported by this digital signature algorithm.

This type defines a digital certificate, digital signature algorithm, and key-length combination that may be supported by the BIS implementation. This type is returned by **GetSignatureInfo()** to describe the combination(s) supported by the implementation.

```

//*****
// BIS_GET_SIGINFO_COUNT macro
//   Tells how many EFI_BIS_SIGNATURE_INFO elements are contained
//   in a EFI_BIS_DATA struct pointed to by the provided
//   EFI_BIS_DATA*.
//*****
#define BIS_GET_SIGINFO_COUNT(BisDataPtr) \
    ((BisDataPtr)->Length/sizeof(EFI_BIS_SIGNATURE_INFO))

```

<i>BisDataPtr</i>	Supplies the pointer to the target EFI_BIS_DATA structure.
<i>(return value)</i>	The number of EFI_BIS_SIGNATURE_INFO elements contained in the array.

This macro computes how many **EFI_BIS_SIGNATURE_INFO** elements are contained in an **EFI_BIS_DATA** structure returned from **GetSignatureInfo()**. The number returned is the count of items in the list of supported digital certificate, digital signature algorithm, and key-length combinations.

```

//*****
// BIS_GET_SIGINFO_ARRAY macro
//   Produces a EFI_BIS_SIGNATURE_INFO* from a given
//   EFI_BIS_DATA*.
//*****
#define BIS_GET_SIGINFO_ARRAY(BisDataPtr) \
    ((EFI_BIS_SIGNATURE_INFO*) (BisDataPtr)->Data)

```

<i>BisDataPtr</i>	Supplies the pointer to the target EFI_BIS_DATA structure.
<i>(return value)</i>	The pointer to the EFI_BIS_SIGNATURE_INFO array, cast as an EFI_BIS_SIGNATURE_INFO* .

This macro returns a pointer to the **EFI_BIS_SIGNATURE_INFO** array contained in an **EFI_BIS_DATA** structure returned from **GetSignatureInfo()** representing the list of supported digital certificate, digital signature algorithm, and key-length combinations.

```

//*****
// BIS_CERT_ID
//*****
typedef UINT32          BIS_CERT_ID;

```

This type represents a shortened value that identifies the platform’s currently configured Boot Object Authorization Certificate. The value is the first four bytes, in “little-endian” order, of the SHA-1 hash of the certificate, except that the most-significant bits of the second and third bytes are reserved, and must be set to zero regardless of the outcome of the hash function. This type is included in the array of values returned from the *GetSignatureInfo()* function to indicate the required source of a signature for a boot object or a configuration update request. There are a few predefined reserved values with special meanings as described below.

```

//*****
// BIS_CERT_ID predefined values
// Currently defined values for EFI_BIS_SIGNATURE_INFO.
// CertificateId.
//*****
#define BIS_CERT_ID_DSA      BIS_ALG_DSA      //CSSM_ALGID_DSA
#define BIS_CERT_ID_RSA_MD5 BIS_ALG_RSA_MD5  //
CSSM_ALGID_MD5_WITH_RSA

```

These C preprocessor symbols provide values for the **BIS_CERT_ID** type. These values are used when the platform has no configured Boot Object Authorization Certificate. They indicate the signature algorithm that is supported by the platform. Users must be careful to avoid constructing Boot Object Authorization Certificates that transform to **BIS_CERT_ID** values that collide with these predefined values or with the **BIS_CERT_ID** values of other Boot Object Authorization Certificates they use.

```

//*****
// BIS_CERT_ID_MASK
// The following is a mask value that gets applied to the
// truncated hash of a platform Boot Object Authorization
// Certificate to create the CertificateId. A CertificateId
// must not have any bits set to the value 1 other than bits in
// this mask.
//*****
#define BIS_CERT_ID_MASK (0xFF7F7FFF)

```

This C preprocessor symbol may be used as a bit-wise “AND” value to transform the first four bytes (in little-endian order) of a SHA-1 hash of a certificate into a certificate ID with the “reserved” bits properly set to zero.

```

//*****
// BIS_ALG_ID
//*****
typedef UINT16          BIS_ALG_ID;

```

This type represents a digital signature algorithm. A digital signature algorithm is often composed of a particular combination of secure hash algorithm and encryption algorithm. This type also allows for digital signature algorithms that cannot be decomposed. Predefined values for this type are as defined below.

```

//*****
// BIS_ALG_ID predefined values
// Currently defined values for EFI_BIS_SIGNATURE_INFO.
// AlgorithmID. The exact numeric values come from "Common
// Data Security Architecture (CDSA) Specification."
//*****
#define BIS_ALG_DSA      (41)    //CSSM_ALGID_DSA
#define BIS_ALG_RSA_MD5 (42)    //CSSM_ALGID_MD5_WITH_RSA

```

These values represent the two digital signature algorithms predefined for BIS. Each implementation of BIS must support at least one of these digital signature algorithms. Values for the digital signature algorithms are chosen by an industry group known as The Open Group. Developers planning to support additional digital signature algorithms or define new digital signature algorithms should refer to The Open Group for interoperable values to use.

Description

This function retrieves a list of digital certificate identifier, digital signature algorithm, hash algorithm, and key-length combinations that the platform supports. The list is an array of (certificate id, algorithm id, key length) triples, where the certificate id is derived from the platform's Boot Object Authorization Certificate as described in the Related Definition for **BIS_CERT_ID** above, the algorithm id represents the combination of signature algorithm and hash algorithm, and the key length is expressed in bits. The number of array elements can be computed using the *Length* field of the retrieved **EFI_BIS_DATA***.

The retrieved list is in order of preference. A digital signature algorithm for which the platform has a currently configured Boot Object Authorization Certificate is preferred over any digital signature algorithm for which there is not a currently configured Boot Object Authorization Certificate. Thus the first element in the list has a *CertificateID* representing a Boot Object Authorization Certificate if the platform has one configured. Otherwise the *CertificateID* of the first element in the list is one of the reserved values representing a digital signature algorithm.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.

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EFI_DEVICE_ERROR	The function encountered an unexpected internal error in a cryptographic software module, or The function encountered an unexpected internal consistency check failure (possible corruption of stored Boot Object Authorization Certificate).
EFI_INVALID_PARAMETER	The <i>SignatureInfo</i> parameter supplied by the caller is NULL or an invalid memory reference.

EFI_BIS_PROTOCOL.UpdateBootObjectAuthorization()

Summary

Updates one of the configurable parameters of the Boot Object Authorization set (Boot Object Authorization Certificate or Boot Authorization Check Flag).

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_UPDATE_BOOT_OBJECT_AUTHORIZATION) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    IN  EFI_BIS_DATA             *RequestCredential,
    OUT EFI_BIS_DATA             **NewUpdateToken
);
```

Parameters

AppHandle

An opaque handle that identifies the caller's instance of initialization of the BIS service. Type [BIS_APPLICATION_HANDLE](#) is defined in the [Initialize\(\)](#) function description.

RequestCredential

This is a Signed Manifest with embedded attributes that carry the details of the requested update. The required syntax of the Signed Manifest is described in the Related Definition for Manifest Syntax below. The key used to sign the request credential must be the private key corresponding to the public key in the platform's configured Boot Object Authorization Certificate. Authority to update parameters in the Boot Object Authorization set cannot be delegated.

If there is no Boot Object Authorization Certificate, the request credential may be signed with any private key. In this case, this function interacts with the user in a platform-specific way to determine whether the operation should succeed. Type [EFI_BIS_DATA](#) is defined in the [Initialize\(\)](#) function description.

NewUpdateToken

The function writes an allocated [EFI_BIS_DATA*](#) containing the new unique update token value. The caller must eventually free the memory allocated by this function using the function [Free\(\)](#). Type [EFI_BIS_DATA](#) is defined in the [Initialize\(\)](#) function description.

Related Definitions

```

//*****
// Manifest Syntax

```

```

//*****

```

The Signed Manifest consists of three parts grouped together into an Electronic Shrink Wrap archive as described in [SM spec]: a manifest file, a signer’s information file, and a signature block file. These three parts, along with examples are described in the following sections. In these examples, text in parentheses is a description of the text that would appear in the signed manifest. Text outside of parentheses must appear exactly as shown. Also note that manifest files and signer’s information files must conform to a 72-byte line-length limit. Continuation lines (lines beginning with a single “space” character) are used for lines longer than 72 bytes. The examples given here follow this rule for continuation lines.

Note that the manifest file and signer’s information file parts of a Signed Manifest are ASCII (not Unicode) text files. In cases where these files contain a base-64 encoded string, the string is an ASCII (not Unicode) string before base-64 encoding.

```

//*****
// Manifest File Example
//*****

```

The manifest file must include a section referring to a memory-type data object with the reserved name as shown in the example below. This data object is a zero-length object whose sole purpose in the manifest is to serve as a named collection point for the attributes that carry the details of the requested update. The attributes are also contained in the manifest file. An example manifest file is shown below.

```

Manifest-Version: 2.0
ManifestPersistentId: (base-64 representation of a unique GUID)

Name: memory:UpdateRequestParameters
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of zero-length
buffer)
X-Intel-BIS-ParameterSet: (base-64 representation of
BootObjectAuthorizationSetGUID)
X-Intel-BIS-ParameterSetToken: (base-64 representation of the current
update token)
X-Intel-BIS-ParameterId: (base-64 representation of
"BootObjectAuthorizationCertificate" or
"BootAuthorizationCheckFlag")
X-Intel-BIS-ParameterValue: (base-64 representation of
certificate or
single-byte boolean flag)

```

A line-by-line description of this manifest file is as follows.

```

Manifest-Version: 2.0

```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```

ManifestPersistentId: (base-64 representation of a unique GUID)

```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every manifest file created. The Win32 function `UuidCreate()` can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

`Name: memory:UpdateRequestParameters`

This identifies the manifest section that carries a dummy zero-length data object serving as the collection point for the attribute values appearing later in this manifest section (lines prefixed with “**X-Intel-BIS-**”). The string “**memory:UpdateRequestParameters**” must appear exactly as shown.

`Digest-Algorithms: SHA-1`

This enumerates the digest algorithms for which integrity data is included for the data object. These are required even though the data object is zero-length. For systems with DSA signing, SHA-1 hash, and 1024-bit key length, the digest algorithm must be “**SHA-1**.” For systems with RSA signing, MD5 hash, and 512-bit key length, the digest algorithm must be “**MD5**.” Multiple algorithms can be specified as a whitespace-separated list. For every digest algorithm **XXX** listed, there must also be a corresponding **XXX-Digest** line.

`SHA-1-Digest: (base-64 representation of a SHA-1 digest of zero-length buffer)`

Gives the corresponding digest value for the dummy zero-length data object. The value is base-64 encoded. Note that for both MD5 and SHA-1, the digest value for a zero-length data object is not zero.

`X-Intel-BIS-ParameterSet: (base-64 representation of BootObjectAuthorizationSetGUID)`

A named attribute value that distinguishes updates of BIS parameters from updates of other parameters. The left-hand attribute-name keyword must appear exactly as shown. The GUID value for the right-hand side is always the same, and can be found under the preprocessor symbol **BOOT_OBJECT_AUTHORIZATION_PARMSET_GUIDVALUE**. The representation inserted into the manifest is base-64 encoded.

Note the “**X-Intel-BIS-**” prefix on this and the following attributes. The “**X-**” part of the prefix was chosen to avoid collisions with future reserved keywords defined by future versions of the signed manifest specification. The “**Intel-BIS-**” part of the prefix was chosen to avoid collisions with other user-defined attribute names within the user-defined attribute name space.

`X-Intel-BIS-ParameterSetToken: (base-64 representation of the current update token)`

A named attribute value that makes this update of BIS parameters different from any other on the same target platform. The left-hand attribute-name keyword must appear exactly as shown. The value for the right-hand side is generally different for each update-request manifest generated. The value to be base-64 encoded is retrieved through the functions

[`GetBootObjectAuthorizationUpdateToken\(\)`](#) or [`UpdateBootObjectAuthorization\(\)`](#).

`X-Intel-BIS-ParameterId: (base-64 representation of “BootObjectAuthorizationCertificate” or “BootAuthorizationCheckFlag”)`

A named attribute value that indicates which BIS parameter is to be updated. The left-hand attribute-name keyword must appear exactly as shown. The value for the right-hand side is the base-64 encoded representation of one of the two strings shown.

```
X-Intel-BIS-ParameterValue: (base-64 representation of
certificate or
single-byte boolean flag)
```

A named attribute value that indicates the new value to be set for the indicated parameter. The left-hand attribute-name keyword must appear exactly as shown. The value for the right-hand side is the appropriate base-64 encoded new value to be set. In the case of the Boot Object Authorization Certificate, the value is the new digital certificate raw data. A zero-length value removes the certificate altogether. In the case of the Boot Authorization Check Flag, the value is a single-byte Boolean value, where a nonzero value “turns on” the check and a zero value “turns off” the check.

```

//*****
// Signer's Information File Example
//*****

```

The signer’s information file must include a section whose name matches the reserved data object section name of the section in the Manifest file. This section in the signer’s information file carries the integrity data for the attributes in the corresponding section in the manifest file. An example signer’s information file is shown below.

```
Signature-Version: 2.0
SignerInformationPersistentId: (base-64 representation of a unique
GUID)
SignerInformationName: BIS_UpdateManifestSignerInfoName

Name: memory:UpdateRequestParameters
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
corresponding manifest section)
```

A line-by-line description of this signer’s information file is as follows.

```
Signature-Version: 2.0
```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```
SignerInformationPersistentId: (base-64 representation of a unique
GUID)
```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every signer’s information file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

```
SignerInformationName: BIS_UpdateManifestSignerInfoName
```

The left-hand string must appear exactly as shown. The right-hand string must appear exactly as shown.

```
Name: memory:UpdateRequestParameters
```

This identifies the section in the signer’s information file corresponding to the section with the same name in the manifest file described earlier. The string

“**memory:UpdateRequestParameters**” must appear exactly as shown.

```
Digest-Algorithms: SHA-1
```

This enumerates the digest algorithms for which integrity data is included for the corresponding manifest section. Strings identifying digest algorithms are the same as in the manifest file. The digest

algorithms specified here must match those specified in the manifest file. For every digest algorithm **XXX** listed, there must also be a corresponding **XXX-Digest** line.

```
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
corresponding manifest section)
```

Gives the corresponding digest value for the corresponding manifest section. The value is base-64 encoded. Note that for the purpose of computing the hash of the manifest section, the manifest section starts at the beginning of the opening “**Name:**” keyword and continues up to, but not including, the next section’s “**Name:**” keyword or the end-of-file. Thus the hash includes the blank line(s) at the end of a section and any newline(s) preceding the next “**Name:**” keyword or end-of-file.

```
//*****
// Signature Block File Example
//*****
```

A signature block file is a raw binary file (not base-64 encoded) that is a PKCS#7 defined format signature block. The signature block covers exactly the contents of the signer’s information file. There must be a correspondence between the name of the signer’s information file and the signature block file. The base name matches, and the three-character extension is modified to reflect the signature algorithm used according to the following rules:

- DSA signature algorithm (which uses SHA-1 hash): extension is DSA.
- RSA signature algorithm with MD5 hash: extension is RSA.

So for example with a signer’s information file name of “myinfo.SF,” the corresponding DSA signature block file name would be “myinfo.DSA.”

The format of a signature block file is defined in [PKCS].

```
//*****
// "X-Intel-BIS-ParameterSet" Attribute value
// Binary Value of "X-Intel-BIS-ParameterSet" Attribute.
// (Value is Base-64 encoded in actual signed manifest).
//*****
```

```
#define BOOT_OBJECT_AUTHORIZATION_PARMSET_GUID \
{0xedd35e31,0x7b9,0x11d2,0x83,0xa3,0x0,0xa0,0xc9,0x1f,0xad,0xcf}
```

This preprocessor symbol gives the value for an attribute inserted in signed manifests to distinguish updates of BIS parameters from updates of other parameters. The representation inserted into the manifest is base-64 encoded.

Description

This function updates one of the configurable parameters of the Boot Object Authorization set (Boot Object Authorization Certificate or Boot Authorization Check Flag). It passes back a new unique update token that must be included in the request credential for the next update of any parameter in the Boot Object Authorization set. The token value is unique to this platform, parameter set, and instance of parameter values. In particular, the token changes to a new unique value whenever any parameter in this set is changed.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.
EFI_DEVICE_ERROR	The function encountered an unexpected internal error in a cryptographic software module.
EFI_SECURITY_VIOLATION	<p>The signed manifest supplied as the <i>RequestCredential</i> parameter was invalid (could not be parsed),</p> <p>or</p> <p>The signed manifest supplied as the <i>RequestCredential</i> parameter failed to verify using the installed Boot Object Authorization Certificate or the signer's Certificate in <i>RequestCredential</i>,</p> <p>or</p> <p>Platform-specific authorization failed,</p> <p>or</p> <p>The signed manifest supplied as the <i>RequestCredential</i> parameter did not include the X-Intel-BIS-ParameterSet attribute value,</p> <p>or</p> <p>The X-Intel-BIS-ParameterSet attribute value supplied did not match the required GUID value,</p> <p>or</p> <p>The signed manifest supplied as the <i>RequestCredential</i> parameter did not include the X-Intel-BIS-ParameterSetToken attribute value,</p> <p>or</p> <p>The X-Intel-BIS-ParameterSetToken attribute value supplied did not match the platform's current update-token value,</p> <p>or</p>

<p>EFI_SECURITY_VIOLATION</p>	<p>The signed manifest supplied as the <i>RequestCredential</i> parameter did not include the X-Intel-BIS-ParameterId attribute value,</p> <p>or</p> <p>The X-Intel-BIS-ParameterId attribute value supplied did not match one of the permitted values,</p> <p>or</p> <p>The signed manifest supplied as the <i>RequestCredential</i> parameter did not include the X-Intel-BIS-ParameterValue attribute value,</p> <p>or</p> <p>Any other required attribute value was missing,</p> <p>or</p> <p>The new certificate supplied was too big to store,</p> <p>or</p> <p>The new certificate supplied was invalid (could not be parsed),</p> <p>or</p> <p>The new certificate supplied had an unsupported combination of key algorithm and key length,</p> <p>or</p> <p>The new check flag value supplied is the wrong length (1 byte),</p> <p>or</p> <p>The signed manifest supplied as the <i>RequestCredential</i> parameter did not include a signer certificate,</p> <p>or</p> <p>The signed manifest supplied as the <i>RequestCredential</i> parameter did not include the manifest section named "memory:UpdateRequestParameters,"</p> <p>or</p>
-------------------------------	---

<p>EFI_SECURITY_VIOLATION</p>	<p>The signed manifest supplied as the <i>RequestCredential</i> parameter had a signing certificate with an unsupported public-key algorithm, or The manifest section named “memory:UpdateRequestParameters” did not include a digest with a digest algorithm corresponding to the signing certificate’s public key algorithm, or The zero-length data object referenced by the manifest section named “memory:UpdateRequestParameters” did not verify with the digest supplied in that manifest section, or The signed manifest supplied as the <i>RequestCredential</i> parameter did not include a signer’s information file with the SignerInformationName identifying attribute value “BIS_UpdateManifestSignerInfoName,” or There were no signers associated with the identified signer’s information file, or There was more than one signer associated with the identified signer’s information file, or Any other unspecified security violation occurred.</p>
<p>EFI_DEVICE_ERROR</p>	<p>An unexpected internal error occurred while analyzing the new certificate’s key algorithm, or An unexpected internal error occurred while attempting to retrieve the public key algorithm of the manifest’s signer’s certificate, or An unexpected internal error occurred in a cryptographic software module.</p>
<p>EFI_INVALID_PARAMETER</p>	<p>The <i>RequestCredential</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>RequestCredential.Data</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>NewUpdateToken</i> parameter supplied by the caller is NULL or an invalid memory reference.</p>

EFI_BIS_PROTOCOL.VerifyBootObject()

Summary

Verifies the integrity and authorization of the indicated data object according to the indicated credentials.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_VERIFY_BOOT_OBJECT) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    IN  EFI_BIS_DATA            *Credentials,
    IN  EFI_BIS_DATA            *DataObject,
    OUT BOOLEAN                 *IsVerified
);
```

Parameters

<i>AppHandle</i>	An opaque handle that identifies the caller's instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the Initialize() function description.
<i>Credentials</i>	A Signed Manifest containing verification information for the indicated data object. The Manifest signature itself must meet the requirements described below. This parameter is optional if a Boot Authorization Check is currently not required on this platform (<i>Credentials.Data</i> may be NULL), otherwise this parameter is required. The required syntax of the Signed Manifest is described in the Related Definition for Manifest Syntax below. Type EFI_BIS_DATA is defined in the Initialize() function description.
<i>DataObject</i>	An in-memory copy of the raw data object to be verified. Type EFI_BIS_DATA is defined in the Initialize() function description.
<i>IsVerified</i>	The function writes TRUE if the verification succeeded, otherwise FALSE .

Related Definitions

```
/**
//*****
// Manifest Syntax
//*****
**/
```

The Signed Manifest consists of three parts grouped together into an Electronic Shrink Wrap archive as described in [SM spec]: a manifest file, a signer's information file, and a signature block file. These three parts along with examples are described in the following sections. In these examples, text in parentheses is a description of the text that would appear in the signed manifest. Text outside of parentheses must appear exactly as shown. Also note that manifest files and signer's information files must conform to a 72-byte line-length limit. Continuation lines (lines beginning with a single

“space” character) are used for lines longer than 72 bytes. The examples given here follow this rule for continuation lines.

Note that the manifest file and signer’s information file parts of a Signed Manifest are ASCII (not Unicode) text files. In cases where these files contain a base-64 encoded string, the string is an ASCII (not Unicode) string before base-64 encoding.

```

//*****
// Manifest File Example
//*****

```

The manifest file must include a section referring to a memory-type data object with the reserved name as shown in the example below. This data object is the Boot Object to be verified. An example manifest file is shown below.

```

Manifest-Version: 2.0
ManifestPersistentId: (base-64 representation of a unique GUID)

Name: memory:BootObject
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
boot object)

```

A line-by-line description of this manifest file is as follows.

```
Manifest-Version: 2.0
```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```
ManifestPersistentId: (base-64 representation of a unique GUID)
```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every manifest file created. The Win32 function `UuidCreate()` can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

```
Name: memory:BootObject
```

This identifies the section that carries the integrity data for the Boot Object. The string “**memory:BootObject**” must appear exactly as shown. Note that the Boot Object cannot be found directly from this manifest. A caller verifying the Boot Object integrity must load the Boot Object into memory and specify its memory location explicitly to this verification function through the *DataObject* parameter.

```
Digest-Algorithms: SHA-1
```

This enumerates the digest algorithms for which integrity data is included for the data object. For systems with DSA signing, SHA-1 hash, and 1024-bit key length, the digest algorithm must be “**SHA-1**.” For systems with RSA signing, MD5 hash, and 512-bit key length, the digest algorithm must be “**MD5**.” Multiple algorithms can be specified as a whitespace-separated list. For every digest algorithm **XXX** listed, there must also be a corresponding **XXX-Digest** line.

```
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the boot object)
```

Gives the corresponding digest value for the data object. The value is base-64 encoded.

```

//*****
// Signer's Information File Example
//*****

```

The signer's information file must include a section whose name matches the reserved data object section name of the section in the Manifest file. This section in the signer's information file carries the integrity data for the corresponding section in the manifest file. An example signer's information file is shown below.

```

Signature-Version: 2.0
SignerInformationPersistentId: (base-64 representation of a
    unique GUID)
SignerInformationName: BIS_VerifiableObjectSignerInfoName

Name: memory:BootObject
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
    corresponding manifest section)

```

A line-by-line description of this signer's information file is as follows.

```
Signature-Version: 2.0
```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```
SignerInformationPersistentId: (base-64 representation of a unique GUID)
```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every signer's information file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

```
SignerInformationName: BIS_VerifiableObjectSignerInfoName
```

The left-hand string must appear exactly as shown. The right-hand string must appear exactly as shown.

```
Name: memory:BootObject
```

This identifies the section in the signer's information file corresponding to the section with the same name in the manifest file described earlier. The string "**memory:BootObject**" must appear exactly as shown.

```
Digest-Algorithms: SHA-1
```

This enumerates the digest algorithms for which integrity data is included for the corresponding manifest section. Strings identifying digest algorithms are the same as in the manifest file. The digest algorithms specified here must match those specified in the manifest file. For every digest algorithm **XXX** listed, there must also be a corresponding **XXX-Digest** line.

```
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
    corresponding manifest section)
```

Gives the corresponding digest value for the corresponding manifest section. The value is base-64 encoded. Note that for the purpose of computing the hash of the manifest section, the manifest section starts at the beginning of the opening "**Name:**" keyword and continues up to, but not including, the next section's "**Name:**" keyword or the end-of-file. Thus the hash includes the blank line(s) at the end of a section and any newline(s) preceding the next "**Name:**" keyword or end-of-file.

```

//*****
// Signature Block File Example
//*****

```

A signature block file is a raw binary file (not base-64 encoded) that is a PKCS#7 defined format signature block. The signature block covers exactly the contents of the signer’s information file. There must be a correspondence between the name of the signer’s information file and the signature block file. The base name matches, and the three-character extension is modified to reflect the signature algorithm used according to the following rules:

- DSA signature algorithm (which uses SHA-1 hash): extension is DSA.
- RSA signature algorithm with MD5 hash: extension is RSA.

So for example with a signer’s information file name of “myinfo.SF,” the corresponding DSA signature block file name would be “myinfo.DSA.”

The format of a signature block file is defined in [PKCS].

Description

This function verifies the integrity and authorization of the indicated data object according to the indicated credentials. The rules for successful verification depend on whether or not a Boot Authorization Check is currently required on this platform.

If a Boot Authorization Check is *not* currently required on this platform, no authorization check is performed. However, the following rules are applied for an integrity check:

- In this case, the credentials are optional. If they are *not* supplied (*Credentials.Data* is **NULL**), no integrity check is performed, and the function returns immediately with a “success” indication and *IsVerified* is **TRUE**.
- If the credentials *are* supplied (*Credentials.Data* is other than **NULL**), integrity checks are performed as follows:
 - Verify the credentials – The credentials parameter is a valid signed Manifest, with a single signer. The signer’s identity is included in the credential as a certificate.
 - Verify the data object – The Manifest must contain a section named “**memory:BootObject**,” with associated verification information (in other words, hash value). The hash value from this Manifest section must match the hash value computed over the specified *DataObject* data.
 - If these checks succeed, the function returns with a “success” indication and *IsVerified* is **TRUE**. Otherwise, *IsVerified* is **FALSE** and the function returns with a “security violation” indication.

If a Boot Authorization Check *is* currently required on this platform, authorization and integrity checks are performed. The integrity check is the same as in the case above, except that it is required. The following rules are applied:

- Verify the credentials – The credentials parameter is required in this case (*Credentials.Data* must be other than **NULL**). The credentials parameter is a valid Signed Manifest, with a single signer. The signer’s identity is included in the credential as a certificate.
- Verify the data object – The Manifest must contain a section named “**memory:BootObject**,” with associated verification information (in other words, hash value). The hash value from this Manifest section must match the hash value computed over the specified *DataObject* data.

- Do Authorization check – This happens one of two ways depending on whether or not the platform currently has a Boot Object Authorization Certificate configured.
 - If a Boot Object Authorization Certificate is not currently configured, this function interacts with the user in a platform-specific way to determine whether the operation should succeed.
 - If a Boot Object Authorization Certificate *is* currently configured, this function uses the Boot Object Authorization Certificate to determine whether the operation should succeed. The public key certified by the signer’s certificate must match the public key in the Boot Object Authorization Certificate configured for this platform. The match must be direct, that is, the signature authority cannot be delegated along a certificate chain.
 - If these checks succeed, the function returns with a “success” indication and *IsVerified* is **TRUE**. Otherwise, *IsVerified* is **FALSE** and the function returns with a “security violation” indication.

Note that if a Boot Authorization Check is currently required on this platform this function *always* performs an authorization check, either through platform-specific user interaction or through a signature generated with the private key corresponding to the public key in the platform’s Boot Object Authorization Certificate.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_INVALID_PARAMETER	The <i>Credentials</i> parameter supplied by the caller is NULL or an invalid memory reference, or The Boot Authorization Check is currently required on this platform and the <i>Credentials.Data</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>DataObject</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>DataObject.Data</i> parameter supplied by the caller is NULL or an invalid memory reference, or The <i>IsVerified</i> parameter supplied by the caller is NULL or an invalid memory reference.
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.

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EFI_SECURITY_VIOLATION	The signed manifest supplied as the <i>Credentials</i> parameter was invalid (could not be parsed), or The signed manifest supplied as the <i>Credentials</i> parameter failed to verify using the installed Boot Object Authorization Certificate or the signer's Certificate in <i>Credentials</i> , or Platform-specific authorization failed, or Any other required attribute value was missing, or The signed manifest supplied as the <i>Credentials</i> parameter did not include a signer certificate, or
------------------------	--

EFI_SECURITY_VIOLATION	<p>The signed manifest supplied as the <i>Credentials</i> parameter did not include the manifest section named “memory:BootObject,”</p> <p>or</p> <p>The signed manifest supplied as the <i>Credentials</i> parameter had a signing certificate with an unsupported public-key algorithm,</p> <p>or</p> <p>The manifest section named “memory:BootObject” did not include a digest with a digest algorithm corresponding to the signing certificate’s public key algorithm,</p> <p>or</p> <p>The data object supplied as the <i>DataObject</i> parameter and referenced by the manifest section named “memory:BootObject” did not verify with the digest supplied in that manifest section,</p> <p>or</p> <p>The signed manifest supplied as the <i>Credentials</i> parameter did not include a signer’s information file with the SignerInformationName identifying attribute value “BIS_VerifiableObjectSignerInfoName,”</p> <p>or</p> <p>There were no signers associated with the identified signer’s information file,</p> <p>or</p> <p>There was more than one signer associated with the identified signer’s information file,</p> <p>or</p> <p>The platform’s check flag is “on” (requiring authorization checks) but the <i>Credentials.Data</i> supplied by the caller is NULL,</p> <p>or</p> <p>Any other unspecified security violation occurred.</p>
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EFI_DEVICE_ERROR	An unexpected internal error occurred while attempting to retrieve the public key algorithm of the manifest's signer's certificate, or An unexpected internal error occurred in a cryptographic software module.
------------------	--

EFI_BIS_PROTOCOL.VerifyObjectWithCredential()

Summary

Verifies the integrity and authorization of the indicated data object according to the indicated credentials and authority certificate.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BIS_VERIFY_OBJECT_WITH_CREDENTIAL) (
    IN  BIS_APPLICATION_HANDLE  AppHandle,
    IN  EFI_BIS_DATA            *Credentials,
    IN  EFI_BIS_DATA            *DataObject,
    IN  EFI_BIS_DATA            *SectionName,
    IN  EFI_BIS_DATA            *AuthorityCertificate,
    OUT BOOLEAN                 *IsVerified
);
```

Parameters

<i>AppHandle</i>	An opaque handle that identifies the caller's instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the Initialize() function description.
<i>Credentials</i>	A Signed Manifest containing verification information for the indicated data object. The Manifest signature itself must meet the requirements described below. The required syntax of the Signed Manifest is described in the Related Definition of Manifest Syntax below. Type EFI_BIS_DATA is defined in the Initialize() function description.
<i>DataObject</i>	An in-memory copy of the raw data object to be verified. Type EFI_BIS_DATA is defined in the Initialize() function description.
<i>SectionName</i>	An ASCII (not Unicode) string giving the section name in the manifest holding the verification information (in other words, hash value) that corresponds to <i>DataObject</i> . Type EFI_BIS_DATA is defined in the Initialize() function description.
<i>AuthorityCertificate</i>	A digital certificate whose public key must match the signer's public key which is found in the credentials. This parameter is optional (<i>AuthorityCertificate.Data</i> may be NULL). Type EFI_BIS_DATA is defined in the Initialize() function description.

IsVerified The function writes **TRUE** if the verification was successful. Otherwise, the function writes **FALSE**.

Related Definitions

```

//*****
// Manifest Syntax
//*****

```

The Signed Manifest consists of three parts grouped together into an Electronic Shrink Wrap archive as described in [SM spec]: a manifest file, a signer’s information file, and a signature block file. These three parts along with examples are described in the following sections. In these examples, text in parentheses is a description of the text that would appear in the signed manifest. Text outside of parentheses must appear exactly as shown. Also note that manifest files and signer’s information files must conform to a 72-byte line-length limit. Continuation lines (lines beginning with a single “space” character) are used for lines longer than 72 bytes. The examples given here follow this rule for continuation lines.

Note that the manifest file and signer’s information file parts of a Signed Manifest are ASCII (not Unicode) text files. In cases where these files contain a base-64 encoded string, the string is an ASCII (not Unicode) string before base-64 encoding.

```

//*****
// Manifest File Example
//*****

```

The manifest file must include a section referring to a memory-type data object with the caller-chosen name as shown in the example below. This data object is the Data Object to be verified. An example manifest file is shown below.

```

Manifest-Version: 2.0
ManifestPersistentId: (base-64 representation of a unique GUID)

Name: (a memory-type data object name)
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
data object)

```

A line-by-line description of this manifest file is as follows.

```
Manifest-Version: 2.0
```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```
ManifestPersistentId: (base-64 representation of a unique GUID)
```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every manifest file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

```
Name: (a memory-type data object name)
```

This identifies the section that carries the integrity data for the target Data Object. The right-hand string must obey the syntax for memory-type references, that is, it is of the form “**memory:SomeUniqueName.**” The “**memory:**” part of this string must appear exactly. The

“**SomeUniqueName**” part is chosen by the caller. It must be unique within the section names in this manifest file. The entire “**memory:SomeUniqueName**” string must match exactly the corresponding string in the signer’s information file described below. Furthermore, this entire string must match the value given for the *SectionName* parameter to this function. Note that the target Data Object cannot be found directly from this manifest. A caller verifying the Data Object integrity must load the Data Object into memory and specify its memory location explicitly to this verification function through the *DataObject* parameter.

```
Digest-Algorithms: SHA-1
```

This enumerates the digest algorithms for which integrity data is included for the data object. For systems with DSA signing, SHA-1 hash, and 1024-bit key length, the digest algorithm must be “**SHA-1**.” For systems with RSA signing, MD5 hash, and 512-bit key length, the digest algorithm must be “**MD5**.” Multiple algorithms can be specified as a whitespace-separated list. For every digest algorithm **XXX** listed, there must also be a corresponding **XXX-Digest** line.

```
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the data object)
```

Gives the corresponding digest value for the data object. The value is base-64 encoded.

```

//*****
// Signer's Information File Example
//*****

```

The signer’s information file must include a section whose name matches the reserved data object section name of the section in the Manifest file. This section in the signer’s information file carries the integrity data for the corresponding section in the manifest file. An example signer’s information file is shown below.

```

Signature-Version: 2.0
SignerInformationPersistentId: (base-64 representation of a
unique GUID)
SignerInformationName: BIS_VerifiableObjectSignerInfoName

Name: (a memory-type data object name)
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the
corresponding manifest section)

```

A line-by-line description of this signer’s information file is as follows.

```
Signature-Version: 2.0
```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```
SignerInformationPersistentId: (base-64 representation of a unique GUID)
```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every signer’s information file created. The Win32 function `UuidCreate()` can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

```
SignerInformationName: BIS_VerifiableObjectSignerInfoName
```

The left-hand string must appear exactly as shown. The right-hand string must appear exactly as shown.

```
Name: (a memory-type data object name)
```

This identifies the section in the signer’s information file corresponding to the section with the same name in the manifest file described earlier. The right-hand string must match exactly the corresponding string in the manifest file described above.

`Digest-Algorithms: SHA-1`

This enumerates the digest algorithms for which integrity data is included for the corresponding manifest section. Strings identifying digest algorithms are the same as in the manifest file. The digest algorithms specified here must match those specified in the manifest file. For every digest algorithm **XXX** listed, there must also be a corresponding **XXX-Digest** line.

`SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)`

Gives the corresponding digest value for the corresponding manifest section. The value is base-64 encoded. Note that for the purpose of computing the hash of the manifest section, the manifest section starts at the beginning of the opening “**Name:**” keyword and continues up to, but not including, the next section’s “**Name:**” keyword or the end-of-file. Thus the hash includes the blank line(s) at the end of a section and any newline(s) preceding the next “**Name:**” keyword or end-of-file.

```

//*****
// Signature Block File Example
//*****

```

A signature block file is a raw binary file (not base-64 encoded) that is a PKCS#7 defined format signature block. The signature block covers exactly the contents of the signer’s information file. There must be a correspondence between the name of the signer’s information file and the signature block file. The base name matches, and the three-character extension is modified to reflect the signature algorithm used according to the following rules:

- DSA signature algorithm (which uses SHA-1 hash): extension is DSA.
- RSA signature algorithm with MD5 hash: extension is RSA.

So for example with a signer’s information file name of “myinfo.SF,” the corresponding DSA signature block file name would be “myinfo.DSA.”

The format of a signature block file is defined in [PKCS].

Description

This function verifies the integrity and authorization of the indicated data object according to the indicated credentials and authority certificate.

Both an integrity check and an authorization check are performed. The rules for a successful integrity check are:

- Verify the credentials – The credentials parameter is a valid Signed Manifest, with a single signer. The signer’s identity is included in the credential as a certificate.
- Verify the data object – The Manifest must contain a section with the name as specified by the *SectionName* parameter, with associated verification information (in other words, hash value). The hash value from this Manifest section must match the hash value computed over the data specified by the *DataObject* parameter of this function.

The authorization check is optional. It is performed only if the *AuthorityCertificate.Data* parameter is other than **NULL**. If it is other than **NULL**, the rules for a successful authorization check are:

- The *AuthorityCertificate* parameter is a valid digital certificate. There is no requirement regarding the signer (issuer) of this certificate.
- The public key certified by the signer’s certificate must match the public key in the *AuthorityCertificate*. The match must be direct, that is, the signature authority cannot be delegated along a certificate chain.

If all of the integrity and authorization check rules are met, the function returns with a “success” indication and *IsVerified* is **TRUE**. Otherwise, it returns with a nonzero specific error code and *IsVerified* is **FALSE**.

Status Codes Returned

EFI_SUCCESS	The function completed successfully.
EFI_NO_MAPPING	The <i>AppHandle</i> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.
EFI_INVALID_PARAMETER	<p>The <i>Credentials</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p> <p>The <i>Credentials.Data</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p> <p>The <i>Credentials.Length</i> supplied by the caller is zero,</p> <p>or</p> <p>The <i>DataObject</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p> <p>The <i>DataObject.Data</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p>

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EFI_INVALID_PARAMETER	<p>The <i>SectionName</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p> <p>The <i>SectionName.Data</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p> <p>The <i>SectionName.Length</i> supplied by the caller is zero,</p> <p>or</p> <p>The <i>AuthorityCertificate</i> parameter supplied by the caller is NULL or an invalid memory reference,</p> <p>or</p> <p>The <i>IsVerified</i> parameter supplied by the caller is NULL or an invalid memory reference.</p>
EFI_OUT_OF_RESOURCES	The function failed due to lack of memory or other resources.

<p>EFI_SECURITY_VIOLATION</p>	<p>The <i>Credentials.Data</i> supplied by the caller is NULL, or The <i>AuthorityCertificate</i> supplied by the caller was invalid (could not be parsed), or The signed manifest supplied as <i>Credentials</i> failed to verify using the <i>AuthorityCertificate</i> supplied by the caller or the manifest's signer's certificate, or Any other required attribute value was missing, or The signed manifest supplied as the <i>Credentials</i> parameter did not include a signer certificate, or The signed manifest supplied as the <i>Credentials</i> parameter did not include the manifest section named according to <i>SectionName</i>, or The signed manifest supplied as the <i>Credentials</i> parameter had a signing certificate with an unsupported public-key algorithm, or The manifest section named according to <i>SectionName</i> did not include a digest with a digest algorithm corresponding to the signing certificate's public key algorithm, or The data object supplied as the <i>DataObject</i> parameter and referenced by the manifest section named according to <i>SectionName</i> did not verify with the digest supplied in that manifest section, or</p>
<p>EFI_SECURITY_VIOLATION</p>	<p>The signed manifest supplied as the <i>Credentials</i> parameter did not include a signer's information file with the SignerInformationName identifying attribute value "BIS_VerifiableObjectSignerInfoName," or There were no signers associated with the identified signer's information file, or There was more than one signer associated with the identified signer's information file, or Any other unspecified security violation occurred.</p>

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EFI_DEVICE_ERROR	An unexpected internal error occurred while attempting to retrieve the public key algorithm of the manifest's signer's certificate, or An unexpected internal error occurred in a cryptographic software module.
------------------	--

Network Protocols — Managed Network

22.1 EFI Managed Network Protocol

This chapter defines the EFI Managed Network Protocol. It is split into the following two main sections:

- Managed Network Service Binding Protocol (MNSBP)
- Managed Network Protocol (MNP)

The MNP provides raw (unformatted) asynchronous network packet I/O services. These services make it possible for multiple-event-driven drivers and applications to access and use the system network interfaces at the same time.

EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL

Summary

The MNSBP is used to locate communication devices that are supported by an MNP driver and to create and destroy instances of the MNP child protocol driver that can use the underlying communications device.

The EFI Service Binding Protocol in [Section 2.5.8](#) defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the MNP.

GUID

```
#define EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL_GUID \
{0xf36ff770,0xa7e1,0x42cf,0x9ed2,0x56,0xf0,0xf2,0x71,0xf4,0x4c}
```

Description

A network application (or driver) that requires shared network access can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an MNSBP GUID. Each device with a published MNSBP GUID supports MNP and may be available for use.

After a successful call to the

`EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the child MNP driver instance is in an unconfigured state; it is not ready to send and receive data packets.

Before a network application terminates execution, every successful call to the

`EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the

`EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

EFI_MANAGED_NETWORK_PROTOCOL

Summary

The MNP is used by network applications (and drivers) to perform raw (unformatted) asynchronous network packet I/O.

GUID

```
#define EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL_GUID \
  {0xf36ff770, 0xa7e1, 0x42cf, 0x9e, 0xd2, 0x56, 0xf0, 0xf2, 0x71, 0xf4, 0x4c}
```

Protocol Interface Structure

```
typedef struct _EFI_MANAGED_NETWORK_PROTOCOL {
  EFI_MANAGED_NETWORK_GET_MODE_DATA    GetModeData;
  EFI_MANAGED_NETWORK_CONFIGURE        Configure;
  EFI_MANAGED_NETWORK_MCAST_IP_TO_MAC  McastIpToMac;
  EFI_MANAGED_NETWORK_GROUPS           Groups;
  EFI_MANAGED_NETWORK_TRANSMIT         Transmit;
  EFI_MANAGED_NETWORK_RECEIVE          Receive;
  EFI_MANAGED_NETWORK_CANCEL           Cancel;
  EFI_MANAGED_NETWORK_POLL             Poll;
} EFI_MANAGED_NETWORK_PROTOCOL;
```

Parameters

<i>GetModeData</i>	Returns the current MNP child driver operational parameters. May also support returning underlying Simple Network Protocol (SNP) driver mode data. See the GetModeData () function description.
<i>Configure</i>	Sets and clears operational parameters for an MNP child driver. See the Configure () function description.
<i>McastIpToMac</i>	Translates a software (IP) multicast address to a hardware (MAC) multicast address. This function may be unsupported in some MNP implementations. See the McastIpToMac () function description.
<i>Groups</i>	Enables and disables receive filters for multicast addresses. This function may be unsupported in some MNP implementations. See the Groups () function description.
<i>Transmit</i>	Places asynchronous outgoing data packets into the transmit queue. See the Transmit () function description.
<i>Receive</i>	Places an asynchronous receiving request into the receiving queue. See the Receive () function description.
<i>Cancel</i>	Aborts a pending transmit or receive request. See the Cancel () function description.

Poll

Polls for incoming data packets and processes outgoing data packets. See the **Poll()** function description.

Description

The services that are provided by MNP child drivers make it possible for multiple drivers and applications to send and receive network traffic using the same network device.

Before any network traffic can be sent or received, the

EFI_MANAGED_NETWORK_PROTOCOL.Configure() function must initialize the operational parameters for the MNP child driver instance. Once configured, data packets can be received and sent using the following functions:

- **EFI_MANAGED_NETWORK_PROTOCOL.Transmit()**
- **EFI_MANAGED_NETWORK_PROTOCOL.Receive()**
- **EFI_MANAGED_NETWORK_PROTOCOL.Poll()**

EFI_MANAGED_NETWORK_PROTOCOL.GetModeData()

Summary

Returns the operational parameters for the current MNP child driver. May also support returning the underlying SNP driver mode data.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_GET_MODE_DATA) (
    IN EFI_MANAGED_NETWORK_PROTOCOL      *This,
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA  *MnpConfigData OPTIONAL,
    OUT EFI_SIMPLE_NETWORK_MODE          *SnpModeData  OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.
<i>MnpConfigData</i>	Pointer to storage for MNP operational parameters. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in “Related Definitions” below.
<i>SnpModeData</i>	Pointer to storage for SNP operational parameters. This feature may be unsupported. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL .

Description

The **GetModeData()** function is used to read the current mode data (operational parameters) from the MNP or the underlying SNP.

Related Definitions

```
/**
//*****
// EFI_MANAGED_NETWORK_CONFIG_DATA
//*****
typedef struct {
    UINT32      ReceivedQueueTimeoutValue;
    UINT32      TransmitQueueTimeoutValue;
    UINT16      ProtocolTypeFilter;
    BOOLEAN     EnableUnicastReceive;
    BOOLEAN     EnableMulticastReceive;
    BOOLEAN     EnableBroadcastReceive;
    BOOLEAN     EnablePromiscuousReceive;
    BOOLEAN     FlushQueuesOnReset;
    BOOLEAN     EnableReceiveTimestamps;
    BOOLEAN     DisableBackgroundPolling;
} EFI_MANAGED_NETWORK_CONFIG_DATA;
```

ReceivedQueueTimeoutValue

Timeout value for a UEFI one-shot timer event. A packet that has not been removed from the MNP receive queue by a call to **EFI_MANAGED_NETWORK_PROTOCOL.Poll()** will be dropped if its receive timeout expires. If this value is zero, then there is no receive queue timeout. If the receive queue fills up, then the device receive filters are disabled until there is room in the receive queue for more packets. The startup default value is 10,000,000 (10 seconds).

TransmitQueueTimeoutValue

Timeout value for a UEFI one-shot timer event. A packet that has not been removed from the MNP transmit queue by a call to **EFI_MANAGED_NETWORK_PROTOCOL.Poll()** will be dropped if its transmit timeout expires. If this value is zero, then there is no transmit queue timeout. If the transmit queue fills up, then the **EFI_MANAGED_NETWORK_PROTOCOL.Transmit()** function will return **EFI_NOT_READY** until there is room in the transmit queue for more packets. The startup default value is 10,000,000 (10 seconds).

ProtocolTypeFilter Ethernet type II 16-bit protocol type in host byte order. Valid values are zero and 1,500 to 65,535. Set to zero to receive packets with any protocol type. The startup default value is zero.

EnableUnicastReceive

Set to **TRUE** to receive packets that are sent to the network device MAC address. The startup default value is **FALSE**.

EnableMulticastReceive

Set to **TRUE** to receive packets that are sent to any of the active multicast groups. The startup default value is **FALSE**.

EnableBroadcastReceive

Set to **TRUE** to receive packets that are sent to the network device broadcast address. The startup default value is **FALSE**.

EnablePromiscuousReceive

Set to **TRUE** to receive packets that are sent to any MAC address. Note that setting this field to **TRUE** may cause packet loss and degrade system performance on busy networks. The startup default value is **FALSE**.

FlushQueuesOnReset

Set to **TRUE** to drop queued packets when the configuration is changed. The startup default value is **FALSE**.

EnableReceiveTimestamps

Set to **TRUE** to timestamp all packets when they are received

by the MNP. Note that timestamps may be unsupported in some MNP implementations. The startup default value is **FALSE**.

DisableBackgroundPolling

Set to **TRUE** to disable background polling in this MNP instance. Note that background polling may not be supported in all MNP implementations. The startup default value is **FALSE**, unless background polling is not supported.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_UNSUPPORTED	The requested feature is unsupported in this MNP implementation.
EFI_NOT_STARTED	This MNP child driver instance has not been configured. The default values are returned in <i>MnpConfigData</i> if it is not NULL .
Other	The mode data could not be read.

EFI_MANAGED_NETWORK_PROTOCOL.Configure()

Summary

Sets or clears the operational parameters for the MNP child driver.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_CONFIGURE) (
    IN EFI_MANAGED_NETWORK_PROTOCOL      *This,
    IN EFI_MANAGED_NETWORK_CONFIG_DATA   *MnpConfigData  OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.
<i>MnpConfigData</i>	Pointer to configuration data that will be assigned to the MNP child driver instance. If NULL , the MNP child driver instance is reset to startup defaults and all pending transmit and receive requests are flushed. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData() .

Description

The **Configure()** function is used to set, change, or reset the operational parameters for the MNP child driver instance. Until the operational parameters have been set, no network traffic can be sent or received by this MNP child driver instance. Once the operational parameters have been reset, no more traffic can be sent or received until the operational parameters have been set again.

Each MNP child driver instance can be started and stopped independently of each other by setting or resetting their receive filter settings with the **Configure()** function.

After any successful call to **Configure()**, the MNP child driver instance is started. The internal periodic timer (if supported) is enabled. Data can be transmitted and may be received if the receive filters have also been enabled.

Note: *If multiple MNP child driver instances will receive the same packet because of overlapping receive filter settings, then the first MNP child driver instance will receive the original packet and additional instances will receive copies of the original packet.*

Note: *Warning: Receive filter settings that overlap will consume extra processor and/or DMA resources and degrade system and network performance.*

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
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EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none">• <i>This</i> is NULL.• <i>MnpConfigData.ProtocolTypeFilter</i> is not valid. The operational data for the MNP child driver instance is unchanged.
EFI_OUT_OF_RESOURCES	Required system resources (usually memory) could not be allocated. The MNP child driver instance has been reset to startup defaults.
EFI_UNSUPPORTED	The requested feature is unsupported in this [MNP] implementation. The operational data for the MNP child driver instance is unchanged.
EFI_DEVICE_ERROR	An unexpected network or system error occurred. The MNP child driver instance has been reset to startup defaults.
Other	The MNP child driver instance has been reset to startup defaults.

EFI_MANAGED_NETWORK_PROTOCOL.McastIpToMac()

Summary

Translates an IP multicast address to a hardware (MAC) multicast address. This function may be unsupported in some MNP implementations.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_MANAGED_NETWORK_MCAST_IP_TO_MAC) (
    IN EFI_MANAGED_NETWORK_PROTOCOL *This,
    IN BOOLEAN                      Ipv6Flag,
    IN EFI_IP_ADDRESS                *IpAddress,
    OUT EFI_MAC_ADDRESS              *MacAddress
);
```

Parameters

<i>This</i>	Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.
<i>Ipv6Flag</i>	Set to TRUE to if <i>IpAddress</i> is an IPv6 multicast address. Set to FALSE if <i>IpAddress</i> is an IPv4 multicast address.
<i>IpAddress</i>	Pointer to the multicast IP address (in network byte order) to convert.
<i>MacAddress</i>	Pointer to the resulting multicast MAC address.

Description

The **McastIpToMac()** function translates an IP multicast address to a hardware (MAC) multicast address.

This function may be implemented by calling the underlying **EFI_SIMPLE_NETWORK.MCastIpToMac()** function, which may also be unsupported in some MNP implementations.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_INVALID_PARAMETER	One of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. <i>IpAddress</i> is NULL. <i>*IpAddress</i> is not a valid multicast IP address. <i>MacAddress</i> is NULL.
EFI_NOT_STARTED	This MNP child driver instance has not been configured.
EFI_UNSUPPORTED	The requested feature is unsupported in this MNP implementation.
EFI_DEVICE_ERROR	An unexpected network or system error occurred.
Other	The address could not be converted.

EFI_MANAGED_NETWORK_PROTOCOL.Groups()

Summary

Enables and disables receive filters for multicast address. This function may be unsupported in some MNP implementations.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_GROUPS) (
    IN EFI_MANAGED_NETWORK_PROTOCOL *This,
    IN BOOLEAN JoinFlag,
    IN EFI_MAC_ADDRESS *MacAddress OPTIONAL
);
```

Parameters

This Pointer to the **EFI_MANAGED_NETWORK_PROTOCOL** instance.

JoinFlag Set to **TRUE** to join this multicast group.
Set to **FALSE** to leave this multicast group.

MacAddress Pointer to the multicast MAC group (address) to join or leave.

Description

The **Groups ()** function only adds and removes multicast MAC addresses from the filter list. The MNP driver does not transmit or process Internet Group Management Protocol (IGMP) packets.

If *JoinFlag* is **FALSE** and *MacAddress* is **NULL**, then all joined groups are left.

Status Codes Returned

EFI_SUCCESS	The requested operation completed successfully.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. <i>JoinFlag</i> is TRUE and <i>MacAddress</i> is NULL. <i>*MacAddress</i> is not a valid multicast MAC address. The MNP multicast group settings are unchanged.
EFI_NOT_STARTED	This MNP child driver instance has not been configured.
EFI_ALREADY_STARTED	The supplied multicast group is already joined.
EFI_NOT_FOUND	The supplied multicast group is not joined.
EFI_DEVICE_ERROR	An unexpected network or system error occurred. The MNP child driver instance has been reset to startup defaults.
EFI_UNSUPPORTED	The requested feature is unsupported in this MNP implementation.
Other	The requested operation could not be completed. The MNP multicast group settings are unchanged.

EFI_MANAGED_NETWORK_PROTOCOL.Transmit()

Summary

Places asynchronous outgoing data packets into the transmit queue.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_TRANSMIT) (
    IN EFI_MANAGED_NETWORK_PROTOCOL      *This,
    IN EFI_MANAGED_NETWORK_COMPLETION_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.
<i>Token</i>	Pointer to a token associated with the transmit data descriptor. Type EFI_MANAGED_NETWORK_COMPLETION_TOKEN is defined in “Related Definitions” below.

Description

The **Transmit()** function places a completion token into the transmit packet queue. This function is always asynchronous.

The caller must fill in the *Token.Event* and *Token.TxData* fields in the completion token, and these fields cannot be **NULL**. When the transmit operation completes, the MNP updates the *Token.Status* field and the *Token.Event* is signaled.

Note: *There may be a performance penalty if the packet needs to be defragmented before it can be transmitted by the network device. Systems in which performance is critical should review the requirements and features of the underlying communications device and drivers.*

Related Definitions

```
/**
//*****
// EFI_MANAGED_NETWORK_COMPLETION_TOKEN
//*****
typedef struct {
    EFI_EVENT          Event;
    EFI_STATUS         Status;
    union {
        EFI_MANAGED_NETWORK_RECEIVE_DATA *RxData;
        EFI_MANAGED_NETWORK_TRANSMIT_DATA *TxData;
    } Packet;
} EFI_MANAGED_NETWORK_COMPLETION_TOKEN;
```

<i>Event</i>	This <i>Event</i> will be signaled after the <i>Status</i> field is updated by the MNP. The type of <i>Event</i> must be
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<i>Status</i>	<p>EVT_NOTIFY_SIGNAL. The Task Priority Level (TPL) of <i>Event</i> must be lower than or equal to TPL_CALLBACK.</p> <p>This field will be set to one of the following values:</p> <p>EFI_SUCCESS: The receive or transmit completed successfully.</p> <p>EFI_ABORTED: The receive or transmit was aborted.</p> <p>EFI_TIMEOUT: The transmit timeout expired.</p> <p>EFI_DEVICE_ERROR: There was an unexpected system or network error.</p>
<i>RxData</i>	<p>When this token is used for receiving, <i>RxData</i> is a pointer to the EFI_MANAGED_NETWORK_RECEIVE_DATA.</p>
<i>TxData</i>	<p>When this token is used for transmitting, <i>TxData</i> is a pointer to the EFI_MANAGED_NETWORK_TRANSMIT_DATA.</p>

The **EFI_MANAGED_NETWORK_COMPLETION_TOKEN** structure is used for both transmit and receive operations.

When it is used for transmitting, the *Event* and *TxData* fields must be filled in by the MNP client. After the transmit operation completes, the MNP updates the *Status* field and the *Event* is signaled.

When it is used for receiving, only the *Event* field must be filled in by the MNP client. After a packet is received, the MNP fills in the *RxData* and *Status* fields and the *Event* is signaled.

```

//*****
// EFI_MANAGED_NETWORK_RECEIVE_DATA
//*****
typedef struct {
    EFI_TIME      Timestamp;
    EFI_EVENT     RecycleEvent;
    UINT32        PacketLength;
    UINT32        HeaderLength;
    UINT32        AddressLength;
    UINT32        DataLength;
    BOOLEAN       BroadcastFlag;
    BOOLEAN       MulticastFlag;
    BOOLEAN       PromiscuousFlag;
    UINT16        ProtocolType;
    VOID          *DestinationAddress;
    VOID          *SourceAddress;
    VOID          *MediaHeader;
    VOID          *PacketData;
} EFI_MANAGED_NETWORK_RECEIVE_DATA;

```

<i>Timestamp</i>	System time when the MNP received the packet. <i>Timestamp</i> is zero filled if receive timestamps are disabled or unsupported.
<i>RecycleEvent</i>	MNP clients must signal this event after the received data has been processed so that the receive queue storage can be reclaimed. Once <i>RecycleEvent</i> is signaled, this structure and the received data that is pointed to by this structure must not be accessed by the client.
<i>PacketLength</i>	Length of the entire received packet (media header plus the data).
<i>HeaderLength</i>	Length of the media header in this packet.
<i>AddressLength</i>	Length of a MAC address in this packet.
<i>DataLength</i>	Length of the data in this packet.
<i>BroadcastFlag</i>	Set to TRUE if this packet was received through the broadcast filter. (The destination MAC address is the broadcast MAC address.)
<i>MulticastFlag</i>	Set to TRUE if this packet was received through the multicast filter. (The destination MAC address is in the multicast filter list.)
<i>PromiscuousFlag</i>	Set to TRUE if this packet was received through the promiscuous filter. (The destination address does not match any of the other hardware or software filter lists.)
<i>ProtocolType</i>	16-bit protocol type in host byte order. Zero if there is no protocol type field in the packet header.
<i>DestinationAddress</i>	Pointer to the destination address in the media header.
<i>SourceAddress</i>	Pointer to the source address in the media header.
<i>MediaHeader</i>	Pointer to the first byte of the media header.
<i>PacketData</i>	Pointer to the first byte of the packet data (immediately following media header).

An **EFI_MANAGED_NETWORK_RECEIVE_DATA** structure is filled in for each packet that is received by the MNP.

If multiple instances of this MNP driver can receive a packet, then the receive data structure and the received packet are duplicated for each instance of the MNP driver that can receive the packet.

```

//*****
// EFI_MANAGED_NETWORK_TRANSMIT_DATA
//*****
typedef struct {
    EFI_MAC_ADDRESS          *DestinationAddress  OPTIONAL;
    EFI_MAC_ADDRESS          *SourceAddress      OPTIONAL;
    UINT16                   ProtocolType       OPTIONAL;
    UINT32                   DataLength;
    UINT16                   HeaderLength       OPTIONAL;
    UINT16                   FragmentCount;
    EFI_MANAGED_NETWORK_FRAGMENT_DATA FragmentTable[1];
} EFI_MANAGED_NETWORK_TRANSMIT_DATA;

```

<i>DestinationAddress</i>	Pointer to the destination MAC address if the media header is not included in <i>FragmentTable[]</i> . If NULL , then the media header is already filled in <i>FragmentTable[]</i> .
<i>SourceAddress</i>	Pointer to the source MAC address if the media header is not included in <i>FragmentTable[]</i> . Ignored if <i>DestinationAddress</i> is NULL .
<i>ProtocolType</i>	The protocol type of the media header in host byte order. Ignored if <i>DestinationAddress</i> is NULL .
<i>DataLength</i>	Sum of all <i>FragmentLength</i> fields in <i>FragmentTable[]</i> minus the media header length.
<i>HeaderLength</i>	Length of the media header if it is included in the <i>FragmentTable</i> . Must be zero if <i>DestinationAddress</i> is not NULL .
<i>FragmentCount</i>	Number of data fragments in <i>FragmentTable[]</i> . This field cannot be zero.
<i>FragmentTable</i>	Table of data fragments to be transmitted. The first byte of the first entry in <i>FragmentTable[]</i> is also the first byte of the media header or, if there is no media header, the first byte of payload. Type EFI_MANAGED_NETWORK_FRAGMENT_DATA is defined below.

The **EFI_MANAGED_NETWORK_TRANSMIT_DATA** structure describes a (possibly fragmented) packet to be transmitted.

The *DataLength* field plus the *HeaderLength* field must be equal to the sum of all of the *FragmentLength* fields in the *FragmentTable*.

If the media header is included in *FragmentTable[]*, then it cannot be split between fragments.

```

//*****
// EFI_MANAGED_NETWORK_FRAGMENT_DATA
//*****
typedef struct {
    UINT32      FragmentLength;
    VOID        *FragmentBuffer;
} EFI_MANAGED_NETWORK_FRAGMENT_DATA;
    
```

FragmentLength Number of bytes in the *FragmentBuffer*. This field may not be set to zero.

FragmentBuffer Pointer to the fragment data. This field may not be set to **NULL**.

The **EFI_MANAGED_NETWORK_FRAGMENT_DATA** structure describes the location and length of a packet fragment to be transmitted.

Status Codes Returned

EFI_SUCCESS	The transmit completion token was cached.
EFI_NOT_STARTED	This MNP child driver instance has not been configured.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.Event</i> is NULL. • <i>Token.TxData</i> is NULL. • <i>Token.TxData.DestinationAddress</i> is not NULL and <i>Token.TxData.HeaderLength</i> is zero. • <i>Token.TxData.FragmentCount</i> is zero. • $(Token.TxData.HeaderLength + Token.TxData.DataLength)$ is not equal to the sum of the <i>Token.TxData.FragmentTable[].FragmentLength</i> fields. • One or more of the <i>Token.TxData.FragmentTable[].FragmentLength</i> fields is zero. • One or more of the <i>Token.TxData.FragmentTable[].FragmentBufferfields</i> is NULL. • <i>Token.TxData.DataLength</i> is greater than <i>MTU</i>
EFI_ACCESS_DENIED	The transmit completion token is already in the transmit queue.
EFI_OUT_OF_RESOURCES	The transmit data could not be queued due to a lack of system resources (usually memory).
EFI_DEVICE_ERROR	An unexpected system or network error occurred. The MNP child driver instance has been reset to startup defaults.

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EFI_NOT_READY	The transmit request could not be queued because the transmit queue is full.
---------------	--

EFI_MANAGED_NETWORK_PROTOCOL.Receive()

Summary

Places an asynchronous receiving request into the receiving queue.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_MANAGED_NETWORK_RECEIVE) (
    IN EFI_MANAGED_NETWORK_PROTOCOL      *This,
    IN EFI_MANAGED_NETWORK_COMPLETION_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.
<i>Token</i>	Pointer to a token associated with the receive data descriptor. Type EFI_MANAGED_NETWORK_COMPLETION_TOKEN is defined in EFI_MANAGED_NETWORK_PROTOCOL.Transmit() .

Description

The **Receive()** function places a completion token into the receive packet queue. This function is always asynchronous.

The caller must fill in the *Token.Event* field in the completion token, and this field cannot be **NULL**. When the receive operation completes, the MNP updates the *Token.Status* and *Token.RxData* fields and the *Token.Event* is signaled.

Status Codes Returned

EFI_SUCCESS	The receive completion token was cached.
EFI_NOT_STARTED	This MNP child driver instance has not been configured.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. <i>Token</i> is NULL. <i>Token.Event</i> is NULL
EFI_OUT_OF_RESOURCES	The transmit data could not be queued due to a lack of system resources (usually memory).
EFI_DEVICE_ERROR	An unexpected system or network error occurred. The MNP child driver instance has been reset to startup defaults.
EFI_ACCESS_DENIED	The receive completion token was already in the receive queue.
EFI_NOT_READY	The receive request could not be queued because the receive queue is full.

EFI_MANAGED_NETWORK_PROTOCOL.Cancel()

Summary

Aborts an asynchronous transmit or receive request.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_CANCEL) (
    IN EFI_MANAGED_NETWORK_PROTOCOL          *This,
    IN EFI_MANAGED_NETWORK_COMPLETION_TOKEN *Token OPTIONAL
);
```

Parameters

This Pointer to the **EFI_MANAGED_NETWORK_PROTOCOL** instance.

Token Pointer to a token that has been issued by **EFI_MANAGED_NETWORK_PROTOCOL.Transmit()** or **EFI_MANAGED_NETWORK_PROTOCOL.Receive()**. If **NULL**, all pending tokens are aborted. Type **EFI_MANAGED_NETWORK_COMPLETION_TOKEN** is defined in **EFI_MANAGED_NETWORK_PROTOCOL.Transmit()**.

Description

The **Cancel()** function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, *Token.Status* will be set to **EFI_ABORTED** and then *Token.Event* will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	The asynchronous I/O request was aborted and <i>Token.Event</i> was signaled. When <i>Token</i> is NULL , all pending requests were aborted and their events were signaled.
EFI_NOT_STARTED	This MNP child driver instance has not been configured.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_FOUND	When <i>Token</i> is not NULL , the asynchronous I/O request was not found in the transmit or receive queue. It has either completed or was not issued by Transmit() and Receive() .

EFI_MANAGED_NETWORK_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_POLL) (
    IN EFI_MANAGED_NETWORK_PROTOCOL    *This
);
```

Parameters

This Pointer to the **EFI_MANAGED_NETWORK_PROTOCOL** instance.

Description

The **Poll()** function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

Normally, a periodic timer event internally calls the **Poll()** function. But, in some systems, the periodic timer event may not call **Poll()** fast enough to transmit and/or receive all data packets without missing packets. Drivers and applications that are experiencing packet loss should try calling the **Poll()** function more often.

Status Codes Returned

EFI_SUCCESS	Incoming or outgoing data was processed.
EFI_NOT_STARTED	This MNP child driver instance has not been configured.
EFI_DEVICE_ERROR	An unexpected system or network error occurred. The MNP child driver instance has been reset to startup defaults.
EFI_NOT_READY	No incoming or outgoing data was processed. Consider increasing the polling rate.
EFI_TIMEOUT	Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.

Network Protocols - ARP and DHCPv4

23.1 ARP Protocol

This section defines the EFI Address Resolution Protocol (ARP) Protocol interface. It is split into the following two main sections:

- ARP Service Binding Protocol (ARPSBP)
- ARP Protocol (ARP)

ARP provides a generic implementation of the Address Resolution Protocol that is described in RFCs 826 and 1122. RFCs can be found at <http://www.ietf.org/>.

EFI_ARP_SERVICE_BINDING_PROTOCOL

Summary

The ARPSBP is used to locate communication devices that are supported by an ARP driver and to create and destroy instances of the ARP child protocol driver.

The EFI Service Binding Protocol in [Section 2.5.8](#) defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the ARP.

GUID

```
#define EFI_ARP_SERVICE_BINDING_PROTOCOL_GUID \
{0xf44c00ee,0x1f2c,0x4a00,0xaa,0x09,0x1c,0x9f,0x3e,0x08,0x00,0xa3}
```

Description

A network application (or driver) that requires network address resolution can use one of the protocol handler services, such as **BS->LocateHandleBuffer()**, to search for devices that publish a ARPSBP GUID. Each device with a published ARPSBP GUID supports ARP and may be available for use.

After a successful call to the **EFI_ARP_SERVICE_BINDING_PROTOCOL.CreateChild()** function, the child ARP driver instance is in an unconfigured state; it is not ready to resolve addresses.

All child ARP driver instances that are created by one **EFI_ARP_SERVICE_BINDING_PROTOCOL** instance will share an ARP cache to improve efficiency.

Before a network application terminates execution, every successful call to the **EFI_ARP_SERVICE_BINDING_PROTOCOL.CreateChild()** function must be matched with a call to the **EFI_ARP_SERVICE_BINDING_PROTOCOL.DestroyChild()** function.

Note: All the network addresses that are described in **EFI ARP PROTOCOL** are stored in network byte order. Both incoming and outgoing ARP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

EFI_arp_protocol

Summary

ARP is used to resolve local network protocol addresses into network hardware addresses.

GUID

```
#define EFI_arp_protocol_GUID \
{0xf4b427bb,0xba21,0x4f16,0xbc,0x4e,0x43,0xe4,0x16,0xab,0x61,0x9c}
```

Protocol Interface Structure

```
typedef struct _EFI_arp_protocol {
    EFI_arp_configure      Configure;
    EFI_arp_add            Add;
    EFI_arp_find           Find;
    EFI_arp_delete         Delete;
    EFI_arp_flush          Flush;
    EFI_arp_request        Request;
    EFI_arp_cancel         Cancel;
} EFI_arp_protocol;
```

Parameters

<i>Configure</i>	Adds a new station address (protocol type and network address) to the ARP cache. See the Configure () function description.
<i>Add</i>	Manually inserts an entry to the ARP cache for administrative purpose. See the Add () function description.
<i>Find</i>	Locates one or more entries in the ARP cache. See the Find () function description.
<i>Delete</i>	Removes an entry from the ARP cache. See the Delete () function description.
<i>Flush</i>	Removes all dynamic ARP cache entries of a specified protocol type. See the Flush () function description.
<i>Request</i>	Starts an ARP request session. See the Request () function description.
<i>Cancel</i>	Abort previous ARP request session. See the Cancel () function description.

Description

The **EFI_arp_protocol** defines a set of generic ARP services that can be used by any network protocol driver to resolve subnet local network addresses into hardware addresses. Normally, a

periodic timer event internally sends and receives packets for ARP. But in some systems where the periodic timer is not supported, drivers and applications that are experiencing packet loss should try calling the **Poll ()** function of the EFI Managed Network Protocol frequently.

Note: **Add ()** and **Delete ()** are typically used for administrative purposes, such as denying traffic to and from a specific remote machine, preventing ARP requests from coming too fast, and providing static address pairs to save time. **Find ()** is also used to update an existing ARP cache entry.

EFI_ARP_PROTOCOL.Configure()

Summary

Assigns a station address (protocol type and network address) to this instance of the ARP cache.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ARP_CONFIGURE) (
    IN EFI_ARP_PROTOCOL           *This,
    IN EFI_ARP_CONFIG_DATA       *ConfigData  OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_ARP_PROTOCOL instance.
<i>ConfigData</i>	A pointer to the EFI_ARP_CONFIG_DATA structure. Type EFI_ARP_CONFIG_DATA is defined in “Related Definitions” below.

Description

The **Configure()** function is used to assign a station address to the ARP cache for this instance of the ARP driver. Each ARP instance has one station address. The **EFI_ARP_PROTOCOL** driver will respond to ARP requests that match this registered station address. A call to **Configure()** with the *ConfigData* field set to **NULL** will reset this ARP instance.

Once a protocol type and station address have been assigned to this ARP instance, all the following ARP functions will use this information. Attempting to change the protocol type or station address to a configured ARP instance will result in errors.

Related Definitions

```

//*****
// EFI_ARP_CONFIG_DATA
//*****
typedef struct {
    UINT16           SwAddressType;
    UINT8           SwAddressLength;
    VOID            *StationAddress;
    UINT32          EntryTimeOut;
    UINT32          RetryCount;
    UINT32          RetryTimeOut;
} EFI_ARP_CONFIG_DATA;
```

<i>SwAddressType</i>	16-bit protocol type number in host byte order. More information can be found at http://www.iana.org/assignments/ethernet-numbers .
----------------------	--

<i>SwAddressLength</i>	Length in bytes of the station's protocol address to register.
<i>StationAddress</i>	Pointer to the first byte of the protocol address to register. For example, if <i>SwAddressType</i> is 0x0800 (IP), then <i>StationAddress</i> points to the first byte of this station's IP address stored in network byte order.
<i>EntryTimeout</i>	The timeout value in 100-ns units that is associated with each new dynamic ARP cache entry. If it is set to zero, the value is implementation-specific.
<i>RetryCount</i>	The number of retries before a MAC address is resolved. If it is set to zero, the value is implementation-specific.
<i>RetryTimeout</i>	The timeout value in 100-ns units that is used to wait for the ARP reply packet or the timeout value between two retries. Set to zero to use implementation-specific value.

Status Codes Returned

EFI_SUCCESS	The new station address was successfully registered.
EFI_INVALID_PARAMETER	<ul style="list-style-type: none"> One or more of the following conditions is TRUE: <i>This</i> is NULL. <i>SwAddressLength</i> is zero when <i>ConfigData</i> is not NULL. <i>StationAddress</i> is NULL when <i>ConfigData</i> is not NULL.
EFI_ACCESS_DENIED	The <i>SwAddressType</i> , <i>SwAddressLength</i> , or <i>StationAddress</i> is different from the one that is already registered.
EFI_OUT_OF_RESOURCES	Storage for the new <i>StationAddress</i> could not be allocated.

EFI_ARP_PROTOCOL.Add()

Summary

Inserts an entry to the ARP cache.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_ARP_ADD) (
    IN EFI_ARP_PROTOCOL  *This,
    IN BOOLEAN           DenyFlag,
    IN VOID              *TargetSwAddress  OPTIONAL,
    IN VOID              *TargetHwAddress  OPTIONAL,
    IN UINT32            TimeoutValue,
    IN BOOLEAN           Overwrite
);

```

Parameters

<i>This</i>	A pointer to the EFI_ARP_PROTOCOL instance..
<i>DenyFlag</i>	Set to TRUE if this entry is a “deny” entry. Set to FALSE if this entry is a “normal” entry.
<i>TargetSwAddress</i>	Pointer to a protocol address to add (or deny). May be set to NULL if <i>DenyFlag</i> is TRUE .
<i>TargetHwAddress</i>	Pointer to a hardware address to add (or deny). May be set to NULL if <i>DenyFlag</i> is TRUE .
<i>TimeoutValue</i>	Time in 100-ns units that this entry will remain in the ARP cache. A value of zero means that the entry is permanent. A nonzero value will override the one given by Configure() if the entry to be added is dynamic entry.
<i>Overwrite</i>	If TRUE , the matching cache entry will be overwritten with the supplied parameters. If FALSE , EFI_ACCESS_DENIED is returned if the corresponding cache entry already exists.

Description

The **Add()** function is used to insert entries into the ARP cache.

ARP cache entries are typically inserted and updated by network protocol drivers as network traffic is processed. Most ARP cache entries will time out and be deleted if the network traffic stops. ARP cache entries that were inserted by the **Add()** function may be static (will not time out) or dynamic (will time out).

Default ARP cache timeout values are not covered in most network protocol specifications (although RFC 1122 comes pretty close) and will only be discussed in general in this specification. The timeout values that are used in the EFI Sample Implementation should be used only as a guideline. Final product implementations of the EFI network stack should be tuned for their expected network environments.

The **Add ()** function can insert the following two types of entries into the ARP cache:

- “Normal” entries
- “Deny” entries

“Normal” entries must have both a *TargetSwAddress* and *TargetHwAddress* and are used to resolve network protocol addresses into network hardware addresses. Entries are keyed by *TargetSwAddress*. Each *TargetSwAddress* can have only one *TargetHwAddress*. A *TargetHwAddress* may be referenced by multiple *TargetSwAddress* entries.

“Deny” entries may have a *TargetSwAddress* or a *TargetHwAddress*, but not both. These entries tell the ARP driver to ignore any traffic to and from (and to) these addresses. If a request comes in from an address that is being denied, then the request is ignored.

If a normal entry to be added matches a deny entry of this driver, *Overwrite* decides whether to remove the matching deny entry. On the other hand, an existing normal entry can be removed based on the value of *Overwrite* if a deny entry to be added matches the existing normal entry. Two entries are matched only when they have the same addresses or when one of the normal entry addresses is the same as the address of a deny entry.

Status Codes Returned

EFI_SUCCESS	The entry has been added or updated.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <i>This</i> is NULL . <i>DenyFlag</i> is FALSE and <i>TargetHwAddress</i> is NULL . <i>DenyFlag</i> is FALSE and <i>TargetSwAddress</i> is NULL . <i>TargetHwAddress</i> is NULL and <i>TargetSwAddress</i> is NULL . Both <i>TargetSwAddress</i> and <i>TargetHwAddress</i> are not NULL when <i>DenyFlag</i> is TRUE .
EFI_OUT_OF_RESOURCES	The new ARP cache entry could not be allocated.
EFI_ACCESS_DENIED	The ARP cache entry already exists and <i>Overwrite</i> is not TRUE .
EFI_NOT_STARTED	The ARP driver instance has not been configured.

EFI_ARP_PROTOCOL.Find()

Summary

Locates one or more entries in the ARP cache.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_ARP_FIND) (
    IN EFI_ARP_PROTOCOL      *This,
    IN BOOLEAN               BySwAddress,
    IN VOID                  *AddressBuffer      OPTIONAL,
    OUT UINT32               *EntryLength       OPTIONAL,
    OUT UINT32               *EntryCount        OPTIONAL,
    OUT EFI_ARP_FIND_DATA    **Entries         OPTIONAL,
    IN BOOLEAN               Refresh
);
```

Parameters

<i>This</i>	A pointer to the EFI_ARP_PROTOCOL instance.
<i>BySwAddress</i>	Set to TRUE to look for matching software protocol addresses. Set to FALSE to look for matching hardware protocol addresses.
<i>AddressBuffer</i>	Pointer to address buffer. Set to NULL to match all addresses.
<i>EntryLength</i>	The size of an entry in the entries buffer. To keep the EFI_ARP_FIND_DATA structure properly aligned, this field may be longer than sizeof(EFI_ARP_FIND_DATA) plus the length of the software and hardware addresses.
<i>EntryCount</i>	The number of ARP cache entries that are found by the specified criteria.
<i>Entries</i>	Pointer to the buffer that will receive the ARP cache entries. Type EFI_ARP_FIND_DATA is defined in “Related Definitions” below.
<i>Refresh</i>	Set to TRUE to refresh the timeout value of the matching ARP cache entry.

Description

The **Find()** function searches the ARP cache for matching entries and allocates a buffer into which those entries are copied. The first part of the allocated buffer is **EFI_ARP_FIND_DATA**, following which are protocol address pairs and hardware address pairs.

When finding a specific protocol address (*BySwAddress* is **TRUE** and *AddressBuffer* is not **NULL**), the ARP cache timeout for the found entry is reset if *Refresh* is set to **TRUE**. If the found ARP cache entry is a permanent entry, it is not affected by *Refresh*.

Related Definitions

```

//*****
// EFI_ARP_FIND_DATA
//*****
typedef struct {
    UINT32          Size;
    BOOLEAN        DenyFlag;
    BOOLEAN        StaticFlag;
    UINT16         HwAddressType;
    UINT16         SwAddressType;
    UINT8          HwAddressLength;
    UINT8          SwAddressLength;
} EFI_ARP_FIND_DATA;
    
```

<i>Size</i>	Length in bytes of this entry.
<i>DenyFlag</i>	Set to TRUE if this entry is a “deny” entry. Set to FALSE if this entry is a “normal” entry.
<i>StaticFlag</i>	Set to TRUE if this entry will not time out. Set to FALSE if this entry will time out.
<i>HwAddressType</i>	16-bit ARP hardware identifier number.
<i>SwAddressType</i>	16-bit protocol type number.
<i>HwAddressLength</i>	Length of the hardware address.
<i>SwAddressLength</i>	Length of the protocol address.

Status Codes Returned

EFI_SUCCESS	The requested ARP cache entries were copied into the buffer.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. Both <i>EntryCount</i> and <i>EntryLength</i> are NULL, when <i>Refresh</i> is FALSE.
EFI_NOT_FOUND	No matching entries were found.
EFI_NOT_STARTED	The ARP driver instance has not been configured.

EFI_ARP_PROTOCOL.Delete()

Summary

Removes entries from the ARP cache.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ARP_DELETE) (
    IN EFI_ARP_PROTOCOL      *This,
    IN BOOLEAN               BySwAddress,
    IN VOID                  *AddressBuffer OPTIONAL
);
```

Parameters

<i>This</i>	A pointer to the EFI_ARP_PROTOCOL instance.
<i>BySwAddress</i>	Set to TRUE to delete matching protocol addresses. Set to FALSE to delete matching hardware addresses.
<i>AddressBuffer</i>	Pointer to the address buffer that is used as a key to look for the cache entry. Set to NULL to delete all entries.

Description

The **Delete()** function removes specified ARP cache entries.

Status Codes Returned

EFI_SUCCESS	The entry was removed from the ARP cache.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_FOUND	The specified deletion key was not found.
EFI_NOT_STARTED	The ARP driver instance has not been configured.

EFI_ARP_PROTOCOL.Flush()

Summary

Removes all dynamic ARP cache entries that were added by this interface.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ARP_FLUSH) (
    IN EFI_ARP_PROTOCOL *This
);
```

Parameters

This A pointer to the **EFI_ARP_PROTOCOL** instance.

Description

The **Flush()** function deletes all dynamic entries from the ARP cache that match the specified software protocol type.

Status Codes Returned

EFI_SUCCESS	The cache has been flushed.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_FOUND	There are no matching dynamic cache entries.
EFI_NOT_STARTED	The ARP driver instance has not been configured.

EFI_ARP_PROTOCOL.Request()

Summary

Starts an ARP request session.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ARP_REQUEST) (
    IN EFI_ARP_PROTOCOL *This,
    IN VOID *TargetSwAddress OPTIONAL,
    IN EFI_EVENT ResolvedEvent OPTIONAL,
    OUT VOID *TargetHwAddress
);
```

Parameters

<i>This</i>	A pointer to the EFI_ARP_PROTOCOL instance..
<i>TargetSwAddress</i>	Pointer to the protocol address to resolve.
<i>ResolvedEvent</i>	Pointer to the event that will be signaled when the address is resolved or some error occurs.
<i>TargetHwAddress</i>	Pointer to the buffer for the resolved hardware address in network byte order. The buffer must be large enough to hold the resulting hardware address. <i>TargetHwAddress</i> must not be NULL .

Description

The **Request()** function tries to resolve the *TargetSwAddress* and optionally returns a *TargetHwAddress* if it already exists in the ARP cache.

If the registered *SwAddressType* (see **EFI_ARP_PROTOCOL.Add()**) is IPv4 or IPv6 and the *TargetSwAddress* is a multicast address, then the *TargetSwAddress* is resolved using the underlying **EFI_MANAGED_NETWORK_PROTOCOL.McastIpToMac()** function.

If the *TargetSwAddress* is **NULL**, then the network interface hardware broadcast address is returned immediately in *TargetHwAddress*.

If the *ResolvedEvent* is not **NULL** and the address to be resolved is not in the ARP cache, then the event will be signaled when the address request completes and the requested hardware address is returned in the *TargetHwAddress*. If the timeout expires and the retry count is exceeded or an unexpected error occurs, the event will be signaled to notify the caller, which should check the *TargetHwAddress* to see if the requested hardware address is available. If it is not available, the *TargetHwAddress* is filled by zero.

If the address to be resolved is already in the ARP cache and resolved, then the event will be signaled immediately if it is not **NULL**, and the requested hardware address is also returned in *TargetHwAddress*.

Status Codes Returned

EFI_SUCCESS	The data was copied from the ARP cache into the <i>TargetHwAddress</i> buffer.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <i>This</i> is NULL <i>TargetHwAddress</i> is NULL
EFI_ACCESS_DENIED	The requested address is not present in the normal ARP cache but is present in the deny address list. Outgoing traffic to that address is forbidden.
EFI_NOT_STARTED	The ARP driver instance has not been configured.
EFI_NOT_READY	The request has been started and is not finished.
EFI_UNSUPPORTED	The requested conversion is not supported in this implementation or configuration.

EFI_ARP_PROTOCOL.Cancel()

Summary

Cancels an ARP request session.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_ARP_CANCEL) (
    IN EFI_ARP_PROTOCOL *This,
    IN VOID *TargetSwAddress OPTIONAL,
    IN EFI_EVENT ResolvedEvent OPTIONAL
);
```

Parameters

This A pointer to the **EFI_ARP_PROTOCOL** instance.

TargetSwAddress Pointer to the protocol address in previous request session.

ResolvedEvent Pointer to the event that is used as the notification event in previous request session.

Description

The **Cancel()** function aborts the previous ARP request (identified by *This*, *TargetSwAddress* and *ResolvedEvent*) that is issued by **EFI_ARP_PROTOCOL.Request()**. If the request is in the internal ARP request queue, the request is aborted immediately and its *ResolvedEvent* is signaled. Only an asynchronous address request needs to be canceled. If *TargetSwAddress* and *ResolveEvent* are both **NULL**, all the pending asynchronous requests that have been issued by *This* instance will be cancelled and their corresponding events will be signaled.

Status Codes Returned

EFI_SUCCESS	The pending request session(s) is/are aborted and corresponding event(s) is/are signaled.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. <i>TargetSwAddress</i> is not NULL and <i>ResolvedEvent</i> is NULL. <i>TargetSwAddress</i> is NULL and <i>ResolvedEvent</i> is not NULL.
EFI_NOT_STARTED	The ARP driver instance has not been configured.
EFI_NOT_FOUND	The request is not issued by EFI_ARP_PROTOCOL.Request() .

23.2 EFI DHCPv4 Protocol

This section provides a detailed description of the **EFI_DHCP4_PROTOCOL** and the **EFI_DHCP4_SERVICE_BINDING_PROTOCOL**. The EFI DHCPv4 Protocol is used to collect configuration information for the EFI IPv4 Protocol drivers and to provide DHCPv4 server and PXE boot server discovery services.

EFI_DHCP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI DHCPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI DHCPv4 Protocol driver and to create and destroy EFI DHCPv4 Protocol child driver instances that can use the underlying communications device.

GUID

```
#define EFI_DHCP4_SERVICE_BINDING_PROTOCOL_GUID \
{0x9d9a39d8,0xbd42,0x4a73,0xa4,0xd5,0x8e,0xe9,0x4b,0xe1,0x13,0x80}
```

Description

A network application or driver that requires basic DHCPv4 services can use one of the protocol handler services, such as **BS->LocateHandleBuffer()**, to search for devices that publish an EFI DHCPv4 Service Binding Protocol GUID. Each device with a published EFI DHCPv4 Service Binding Protocol GUID supports the EFI DHCPv4 Protocol and may be available for use.

After a successful call to the

EFI_DHCP4_SERVICE_BINDING_PROTOCOL.CreateChild() function, the newly created EFI DHCPv4 Protocol child driver instance is ready to be used by a network application or driver.

Before a network application or driver terminates execution, every successful call to the

EFI_DHCP4_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the **EFI_DHCP4_SERVICE_BINDING_PROTOCOL.DestroyChild()** function.

EFI_DHCP4_PROTOCOL

Summary

This protocol is used to collect configuration information for the EFI IPv4 Protocol drivers and to provide DHCPv4 server and PXE boot server discovery services.

GUID

```
#define EFI_DHCP4_PROTOCOL_GUID \
{0x8a219718,0x4ef5,0x4761,0x91,0xc8,0xc0,0xf0,0x4b,0xda,0x9e,
0x56}
```

Protocol Interface Structure

```
typedef struct _EFI_DHCP4_PROTOCOL {
    EFI_DHCP4_GET_MODE_DATA      GetModeData;
    EFI_DHCP4_CONFIGURE          Configure;
    EFI_DHCP4_START               Start;
    EFI_DHCP4_RENEW_REBIND       RenewRebind;
    EFI_DHCP4_RELEASE             Release;
    EFI_DHCP4_STOP                Stop;
    EFI_DHCP4_BUILD               Build;
    EFI_DHCP4_TRANSMIT_RECEIVE    TransmitReceive;
    EFI_DHCP4_PARSE               Parse;
} EFI_DHCP4_PROTOCOL;
```

Parameters

<i>GetModeData</i>	Gets the EFI DHCPv4 Protocol driver status and operational data. See the GetModeData () function description.
<i>Configure</i>	Initializes, changes, or resets operational settings for the EFI DHCPv4 Protocol driver. See the Configure () function description.
<i>Start</i>	Starts the DHCP configuration process. See the Start () function description.
<i>RenewRebind</i>	Tries to manually extend the lease time by sending a request packet. See the RenewRebind () function description.
<i>Release</i>	Releases the current configuration and returns the EFI DHCPv4 Protocol driver to the initial state. See the Release () function description.
<i>Stop</i>	Stops the DHCP configuration process no matter what state the driver is in. After being stopped, this driver will not automatically communicate with the DHCP server. See the Stop () function description.
<i>Build</i>	Puts together a DHCP or PXE packet. See the Build () function description.
<i>TransmitReceive</i>	Transmits a DHCP or PXE packet and waits for response packets. See the TransmitReceive () function description.
<i>Parse</i>	Parses the packed DHCP or PXE option data. See the Parse () function description.

Description

The **EFI_DHCP4_PROTOCOL** is used to collect configuration information for the EFI IPv4 Protocol driver and provide DHCP server and PXE boot server discovery services.

Byte Order Note

All the IPv4 addresses that are described in **EFI_DHCP4_PROTOCOL** are stored in network byte order. Both incoming and outgoing DHCP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order

EFI_DHCP4_PROTOCOL.GetModeData()

Summary

Returns the current operating mode and cached data packet for the EFI DHCPv4 Protocol driver.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_GET_MODE_DATA) (
    IN  EFI_DHCP4_PROTOCOL    *This,
    OUT EFI_DHCP4_MODE_DATA   *Dhcp4ModeData
);
```

Parameters

<i>This</i>	Pointer to the EFI_DHCP4_PROTOCOL instance.
<i>Dhcp4ModeData</i>	Pointer to storage for the EFI_DHCP4_MODE_DATA structure. Type EFI_DHCP4_MODE_DATA is defined in “Related Definitions” below.

Description

The **GetModeData ()** function returns the current operating mode and cached data packet for the EFI DHCPv4 Protocol driver.

Related Definitions

```

//*****
// EFI_DHCP4_MODE_DATA
//*****
typedef struct {
    EFI_DHCP4_STATE           State;
    EFI_DHCP4_CONFIG_DATA     ConfigData;
    EFI_IPv4_ADDRESS          ClientAddress;
    EFI_MAC_ADDRESS           ClientMacAddress;
    EFI_IPv4_ADDRESS           ServerAddress;
    EFI_IPv4_ADDRESS           RouterAddress;
    EFI_IPv4_ADDRESS           SubnetMask;
    UINT32                     LeaseTime;
    EFI_DHCP4_PACKET           *ReplyPacket;
} EFI_DHCP4_MODE_DATA;
```

<i>State</i>	The EFI DHCPv4 Protocol driver operating state. Type EFI_DHCP4_STATE is defined below.
--------------	---

<i>ConfigData</i>	The configuration data of the current EFI DHCPv4 Protocol driver instance. Type EFI_DHCP4_CONFIG_DATA is defined in EFI_DHCP4_PROTOCOL.Configure () .
-------------------	---

<i>ClientAddress</i>	The client IP address that was acquired from the DHCP server. If it is zero, the DHCP acquisition has not completed yet and the following fields in this structure are undefined.
<i>ClientMacAddress</i>	The local hardware address.
<i>ServerAddress</i>	The server IP address that is providing the DHCP service to this client.
<i>RouterAddress</i>	The router IP address that was acquired from the DHCP server. May be zero if the server does not offer this address.
<i>SubnetMask</i>	The subnet mask of the connected network that was acquired from the DHCP server.
<i>LeaseTime</i>	The lease time (in 1-second units) of the configured IP address. The value 0xFFFFFFFF means that the lease time is infinite. A default lease of 7 days is used if the DHCP server does not provide a value.
<i>ReplyPacket</i>	The cached latest DHCPACK or DHCPNAK or BOOTP REPLY packet. May be NULL if no packet is cached.

•

The **EFI_DHCP4_MODE_DATA** structure describes the operational data of the current DHCP procedure.

```

//*****
// EFI_DHCP4_STATE
//*****
typedef enum {
    Dhcp4Stopped           = 0x0,
    Dhcp4Init              = 0x1,
    Dhcp4Selecting         = 0x2,
    Dhcp4Requesting        = 0x3,
    Dhcp4Bound             = 0x4,
    Dhcp4Renewing          = 0x5,
    Dhcp4Rebinding         = 0x6,
    Dhcp4InitReboot        = 0x7,
    Dhcp4Rebooting         = 0x8
} EFI_DHCP4_STATE;

```

[Table 168](#) describes the fields in the above enumeration.

Table 168. DHCP4 Enumerations

<i>Dhcp4Stopped</i>	The EFI DHCPv4 Protocol driver is stopped and EFI_DHCP4_PROTOCOL.Configure() needs to be called. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.
---------------------	--

<i>Dhcp4Init</i>	The EFI DHCPv4 Protocol driver is inactive and EFI_DHCP4_PROTOCOL.Start() needs to be called. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.
<i>Dhcp4Selecting</i>	The EFI DHCPv4 Protocol driver is collecting DHCP offer packets from DHCP servers. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.
<i>Dhcp4Requesting</i>	The EFI DHCPv4 Protocol driver has sent the request to the DHCP server and is waiting for a response. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.
<i>Dhcp4Bound</i>	The DHCP configuration has completed. All of the fields in the EFI_DHCP4_MODE_DATA structure are defined.
<i>Dhcp4Renewing</i>	The DHCP configuration is being renewed and another request has been sent out, but it has not received a response from the server yet. All of the fields in the EFI_DHCP4_MODE_DATA structure are available but may change soon.
<i>Dhcp4Rebinding</i>	The DHCP configuration has timed out and the EFI DHCPv4 Protocol driver is trying to extend the lease time. The rest of the EFI_DHCP4_MODE structure is undefined in this state.
<i>Dhcp4InitReboot</i>	The EFI DHCPv4 Protocol driver is initialized with a previously allocated or known IP address. EFI_DHCP4_PROTOCOL.Start() needs to be called to start the configuration process. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.
<i>Dhcp4Rebooting</i>	The EFI DHCPv4 Protocol driver is seeking to reuse the previously allocated IP address by sending a request to the DHCP server. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.

EFI_DHCP4_STATE defines the DHCP operational states that are described in RFC 2131, which can be obtained from the following URL:

<http://www.ietf.org/rfc/rfc2131.txt>

A variable number of EFI DHCPv4 Protocol driver instances can coexist but they share the same state machine. More precisely, each communication device has a separate DHCP state machine if there are multiple communication devices. Each EFI DHCPv4 Protocol driver instance that is created by the same EFI DHCPv4 Service Binding Protocol driver instance shares the same state machine. In this document, when we refer to the state of EFI DHCPv4 Protocol driver, we actually refer to the state of the communication device from which the current EFI DHCPv4 Protocol Driver instance is created.


```

//*****
// EFI_DHCP4_PACKET
//*****
#pragma pack(1)
typedef struct {
    UINT32          Size;
    UINT32          Length;
    struct{
        EFI_DHCP4_HEADER  Header;
        UINT32            Magik;
        UINT8             Option[1];
    } Dhcp4;
} EFI_DHCP4_PACKET;
#pragma pack()

```

Size Size of the **EFI_DHCP4_PACKET** buffer.

Length Length of the **EFI_DHCP4_PACKET** from the first byte of the *Header* field to the last byte of the *Option[]* field.

Header DHCP packet header.

Magik DHCP magik cookie in network byte order.

Option Start of the DHCP packed option data.

EFI_DHCP4_PACKET defines the format of DHCPv4 packets. See RFC 2131 for more information.

Status Codes Returned

EFI_SUCCESS	The mode data was returned.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .

EFI_DHCP4_PROTOCOL.Configure()

Summary

Initializes, changes, or resets the operational settings for the EFI DHCPv4 Protocol driver.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_DHCP4_CONFIGURE) (
    IN EFI_DHCP4_PROTOCOL           *This,
    IN EFI_DHCP4_CONFIG_DATA       *Dhcp4CfgData OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_DHCP4_PROTOCOL instance.
<i>Dhcp4CfgData</i>	Pointer to the EFI_DHCP4_CONFIG_DATA . Type EFI_DHCP4_CONFIG_DATA is defined in “Related Definitions” below.

Description

The **Configure ()** function is used to initialize, change, or reset the operational settings of the EFI DHCPv4 Protocol driver for the communication device on which the EFI DHCPv4 Service Binding Protocol is installed. This function can be successfully called only if both of the following are true:

- This instance of the EFI DHCPv4 Protocol driver is in the *Dhcp4Stopped*, *Dhcp4Init*, *Dhcp4InitReboot*, or *Dhcp4Bound* states.
- No other EFI DHCPv4 Protocol driver instance that is controlled by this EFI DHCPv4 Service Binding Protocol driver instance has configured this EFI DHCPv4 Protocol driver.

When this driver is in the *Dhcp4Stopped* state, it can transfer into one of the following two possible initial states:

- *Dhcp4Init*
- *Dhcp4InitReboot*

The driver can transfer into these states by calling **Configure ()** with a non-**NULL** *Dhcp4CfgData*. It can transfer into *Dhcp4Init* when no IP address is provided in *Dhcp4CfgData* or into *Dhcp4InitReboot* state if there is a previously assigned IP address. Otherwise, the state of EFI DHCPv4 Protocol driver will not be changed.

When **Configure ()** is called successfully while *Dhcp4CfgData* is set to **NULL**, the default configuring data will be reset in the EFI DHCPv4 Protocol driver and the state of the EFI DHCPv4 Protocol driver will not be changed. If one instance wants to make it possible for another instance to configure the EFI DHCPv4 Protocol driver, it must call this function with *Dhcp4CfgData* set to **NULL**.

Related Definitions

```
//
*****
// EFI_DHCP4_CONFIG_DATA
//
*****
typedef struct {
    UINT32                DiscoverTryCount;
    UINT32                *DiscoverTimeout;
    UINT32                RequestTryCount;
    UINT32                *RequestTimeout;
    EFI_IPv4_ADDRESS      ClientAddress;
    EFI_DHCP4_CALLBACK    Dhcp4Callback;
    VOID                  *CallbackContext;
    UINT32                OptionCount;
    EFI_DHCP4_PACKET_OPTION **OptionList;
} EFI_DHCP4_CONFIG_DATA;
```

<i>DiscoverTryCount</i>	Number of times to try sending DHCPDISCOVER packets and waiting for DHCPOFFER packets before accepting failure. (This value is also the number of entries in the <i>DiscoverTimeout</i> array.) Set to zero to use the default try counts and timeout values.
<i>DiscoverTimeout</i>	Maximum amount of time (in seconds) to wait for DHCPOFFER packets in each of the retries. Timeout values of zero will default to a timeout value of one second. Set to NULL to use default timeout values.
<i>RequestTryCount</i>	Number of times to try sending DHCPREQUEST packets and waiting for DHCPACK packets before accepting failure. (This value is also the number of entries in the <i>RequestTimeout</i> array.) Set to zero to use the default try counts and timeout values.
<i>RequestTimeout</i>	Maximum amount of time (in seconds) to wait for DHCPACK packets in each of the retries. Timeout values of zero will default to a timeout value of one second. Set to NULL to use default timeout values.
<i>ClientAddress</i>	Setting this parameter to the previously allocated IP address will cause the EFI DHCPv4 Protocol driver to enter the <i>Dhcp4InitReboot</i> state. Set this field to 0.0.0.0 to enter the <i>Dhcp4Init</i> state.
<i>Dhcp4Callback</i>	The callback function to intercept various events that occurred in the DHCP configuration process. Set to NULL to ignore all those events. Type EFI_DHCP4_CALLBACK is defined below.

CallbackContext Pointer to the context that will be passed to *Dhcp4Callback* when it is called.

OptionCount Number of DHCP options in the *OptionList*.

OptionList List of DHCP options to be included in every DHCPDISCOVER packet and subsequent DHCPREQUEST packet that is generated from DHCPOFFER packets. Pad options are appended automatically by DHCP driver in outgoing DHCP packets. If *OptionList* itself contains pad option, they are ignored by driver. *OptionList* can be freed after **EFI_DHCP4_PROTOCOL.Configure()** returns. Ignored if *OptionCount* is zero. Type **EFI_DHCP4_PACKET_OPTION** is defined below.

```
//
*****
// EFI_DHCP4_CALLBACK
//
*****
typedef EFI_STATUS (*EFI_DHCP4_CALLBACK) (
    IN EFI_DHCP4_PROTOCOL      *This,
    IN VOID                    *Context,
    IN EFI_DHCP4_STATE         CurrentState,
    IN EFI_DHCP4_EVENT         Dhcp4Event,
    IN EFI_DHCP4_PACKET        *Packet,           OPTIONAL
    OUT EFI_DHCP4_PACKET       **NewPacket       OPTIONAL
);
```

This Pointer to the EFI DHCPv4 Protocol instance that is used to configure this callback function.

Context Pointer to the context that is initialized by **EFI_DHCP4_PROTOCOL.Configure()**.

CurrentState The current operational state of the EFI DHCPv4 Protocol driver. Type **EFI_DHCP4_STATE** is defined in **EFI_DHCP4_PROTOCOL.GetModeData()**.

Dhcp4Event The event that occurs in the current state, which usually means a state transition. Type **EFI_DHCP4_EVENT** is defined below.

Packet The DHCP packet that is going to be sent or already received. May be **NULL** if the event has no associated packet. Do not cache this packet except for copying it. Type **EFI_DHCP4_PACKET** is defined in **EFI_DHCP4_PROTOCOL.GetModeData()**.

NewPacket The packet that is used to replace the above *Packet*. Do not set this pointer exactly to the above *Packet* or a modified *Packet*. *NewPacket* can be **NULL** if the EFI DHCPv4 Protocol driver

does not expect a new packet to be returned. The user may set **NewPacket* to **NULL** if no replacement occurs.

EFI_DHCP4_CALLBACK is provided by the consumer of the EFI DHCPv4 Protocol driver to intercept events that occurred in the configuration process. This structure provides advanced control of each state transition of the DHCP process. The returned status code determines the behavior of the EFI DHCPv4 Protocol driver. There are three possible returned values, which are described in the following table.

EFI_SUCCESS	Tells the EFI DHCPv4 Protocol driver to continue the DHCP process. When it is in the <i>Dhcp4Selecting</i> state, it tells the EFI DHCPv4 Protocol driver to stop collecting more DHCPOFFER packets and go ahead to requesting the state after asking the user to provide a selected DHCPOFFER packet.
EFI_NOT_READY	Only used in the <i>Dhcp4Selecting</i> state. The EFI DHCPv4 Protocol driver will continue to wait for more DHCPOFFER packets until the retry timeout expires.
EFI_ABORTED	Tells the EFI DHCPv4 Protocol driver to abort the current process and return to the <i>Dhcp4Init</i> or <i>Dhcp4InitReboot</i> state.

```
//
*****
// EFI_DHCP4_EVENT
//
*****
typedef enum {
    Dhcp4SendDiscover          = 0x01,
    Dhcp4RcvdOffer             = 0x02,
    Dhcp4SelectOffer           = 0x03,
    Dhcp4SendRequest           = 0x04,
    Dhcp4RcvdAck               = 0x05,
    Dhcp4RcvdNak               = 0x06,
    Dhcp4SendDecline           = 0x07,
    Dhcp4BoundCompleted        = 0x08,
    Dhcp4EnterRenewing         = 0x09,
    Dhcp4EnterRebinding        = 0x0a,
    Dhcp4AddressLost           = 0x0b,
    Dhcp4Fail                   = 0x0c
} EFI_DHCP4_EVENT;
```

Following is a description of the fields in the above enumeration.

- Dhcp4SendDiscover* A DHCPDISCOVER packet is about to be sent. The packet is passed to *Dhcp4Callback* and can be modified or replaced in *Dhcp4Callback*.
- Dhcp4RcvdOffer* A DHCPOFFER packet was just received. This packet is passed to *Dhcp4Callback*, which may copy this packet and cache it

for selecting a task later. If the callback returns **EFI_SUCCESS**, this driver will finish the selecting state. If **EFI_NOT_READY** is returned, this driver will continue to wait for DHCPOFFER packets until the timer expires. In either case,

Dhcp4SelectOffer will occur for the user to select an offer.

Dhcp4SelectOffer It is time for *Dhcp4Callback* to select an offer. This driver passes the latest received DHCPOFFER packet to the callback. The *Dhcp4Callback* may store one packet in the *NewPacket* parameter of the function that was selected from previously received DHCPOFFER packets. If the latest packet is the selected one or if the user does not care about it, no extra overhead is needed. Simply skipping this event is enough.

Dhcp4SendRequest A request packet is about to be sent. The user can modify or replace this packet.

Dhcp4RcvdAck A DHCPACK packet was received and will be passed to *Dhcp4Callback*. The callback may decline this DHCPACK packet by returning **EFI_ABORTED**. In this case, the EFI DHCPv4 Protocol driver will send a DHCPDECLINE packet to the server and then return to the *Dhcp4Init* state.

Dhcp4RcvdNak A DHCPNAK packet was received and will be passed to *Dhcp4Callback*. The EFI DHCPv4 Protocol driver will then return to the *Dhcp4Init* state no matter what status code is returned from the callback function.

Dhcp4SendDecline A decline packet is about to be sent. *Dhcp4Callback* can modify or replace this packet.

Dhcp4BoundCompleted The DHCP configuration process has completed. No packet is associated with this event.

Dhcp4EnterRenewing It is time to enter the *Dhcp4Renewing* state and to contact the server that originally issued the network address. No packet is associated with this event.

Dhcp4EnterRebinding It is time to enter the *Dhcp4Rebinding* state and to contact any server. No packet is associated with this event.

Dhcp4AddressLost The configured IP address was lost either because the lease has expired, the user released the configuration, or a DHCPNAK packet was received in the *Dhcp4Renewing* or *Dhcp4Rebinding* state. No packet is associated with this event.

Dhcp4Fail The DHCP process failed because a DHCPNAK packet was received or the user aborted the DHCP process at a time when the configuration was not available yet. No packet is associated with this event.

```

//*****
// EFI_DHCP4_HEADER
//*****
#pragma pack(1)
typedef struct{
    UINT8           OpCode;
    UINT8           HwType;
    UINT8           HwAddrLen;
    UINT8           Hops;
    UINT32          Xid;
    UINT16          Seconds;
    UINT16          Reserved;
    EFI_IPv4_ADDRESS ClientAddr;
    EFI_IPv4_ADDRESS YourAddr;
    EFI_IPv4_ADDRESS ServerAddr;
    EFI_IPv4_ADDRESS GatewayAddr;
    UINT8           ClientHwAddr[16];
    CHAR8           ServerName[64];
    CHAR8           BootFileName[128];
} EFI_DHCP4_HEADER;
#pragma pack()

```

<i>OpCode</i>	Message type. 1 = BOOTREQUEST, 2 = BOOTREPLY.
<i>HwType</i>	Hardware address type.
<i>HwAddrLen</i>	Hardware address length.
<i>Hops</i>	Maximum number of hops (routers, gateways, or relay agents) that this DHCP packet can go through before it is dropped.
<i>Xid</i>	DHCP transaction ID.
<i>Seconds</i>	Number of seconds that have elapsed since the client began address acquisition or the renewal process.
<i>Reserved</i>	Reserved for future use.
<i>ClientAddr</i>	Client IP address from the client.
<i>YourAddr</i>	Client IP address from the server.
<i>ServerAddr</i>	IP address of the next server in bootstrap.
<i>GatewayAddr</i>	Relay agent IP address.
<i>ClientHwAddr</i>	Client hardware address.
<i>ServerName</i>	Optional server host name.
<i>BootFileName</i>	Boot file name.

EFI_DHCP4_HEADER describes the semantics of the DHCP packet header. This packet header is in network byte order.

```

//*****
// EFI_DHCP4_PACKET_OPTION
//*****
#pragma pack(1)
typedef struct {
    UINT8      OpCode;
    UINT8      Length;
    UINT8      Data[1];
} EFI_DHCP4_PACKET_OPTION;
#pragma pack()
    
```

OpCode DHCP option code.

Length Length of the DHCP option data. Not present if *OpCode* is 0 or 255.

Data Start of the DHCP option data. Not present if *OpCode* is 0 or 255 or if *Length* is zero.

The DHCP packet option data structure is used to reference option data that is packed in the DHCP packets. Use caution when accessing multibyte fields because the information in the DHCP packet may not be properly aligned for the machine architecture.

Status Codes Returned

EFI_SUCCESS	The EFI DHCPv4 Protocol driver is now in the <i>Dhcp4Init</i> or <i>Dhcp4InitReboot</i> state, if the original state of this driver was <i>Dhcp4Stopped</i> and the value of <i>Dhcp4CfgData</i> was not NULL . Otherwise, the state was left unchanged.
EFI_ACCESS_DENIED	This instance of the EFI DHCPv4 Protocol driver was not in the <i>Dhcp4Stopped</i> , <i>Dhcp4Init</i> , <i>Dhcp4InitReboot</i> , or <i>Dhcp4Bound</i> state.
EFI_ACCESS_DENIED	Another instance of this EFI DHCPv4 Protocol driver is already in a valid configured state.
EFI_INVALID_PARAMETER	<ul style="list-style-type: none"> • One or more following conditions are TRUE: • <i>This</i> is NULL. • <i>DiscoverTryCount</i> > 0 and <i>DiscoverTimeout</i> is NULL • <i>RequestTryCount</i> > 0 and <i>RequestTimeout</i> is NULL. • <i>OptionCount</i> >0 and <i>OptionList</i> is NULL. • <i>ClientAddress</i> is not a valid unicast address.
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_DEVICE_ERROR	An unexpected system or network error occurred.

EFI_DHCP4_PROTOCOL.Start()

Summary

Starts the DHCP configuration process.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_DHCP4_START) (
    IN EFI_DHCP4_PROTOCOL    *This,
    IN EFI_EVENT             CompletionEvent OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_DHCP4_PROTOCOL instance.
<i>CompletionEvent</i>	If not NULL , indicates the event that will be signaled when the EFI DHCPv4 Protocol driver is transferred into the <i>Dhcp4Bound</i> state or when the DHCP process is aborted. EFI_DHCP4_PROTOCOL.GetModeData() can be called to check the completion status. If NULL , EFI_DHCP4_PROTOCOL.Start() will wait until the driver is transferred into the <i>Dhcp4Bound</i> state or the process fails.

Description

The **Start()** function starts the DHCP configuration process. This function can be called only when the EFI DHCPv4 Protocol driver is in the *Dhcp4Init* or *Dhcp4InitReboot* state.

If the DHCP process completes successfully, the state of the EFI DHCPv4 Protocol driver will be transferred through *Dhcp4Selecting* and *Dhcp4Requesting* to the *Dhcp4Bound* state. The *CompletionEvent* will then be signaled if it is not **NULL**.

If the process aborts, either by the user or by some unexpected network error, the state is restored to the *Dhcp4Init* state. The **Start()** function can be called again to restart the process.

Refer to RFC 2131 for precise state transitions during this process. At the time when each event occurs in this process, the callback function that was set by **EFI_DHCP4_PROTOCOL.Configure()** will be called and the user can take this opportunity to control the process.

Status Codes Returned

EFI_SUCCESS	The DHCP configuration process has started, or it has completed when <i>CompletionEvent</i> is NULL .
EFI_NOT_STARTED	The EFI DHCPv4 Protocol driver is in the <i>Dhcp4Stopped</i> state. EFI_DHCP4_PROTOCOL.Configure() needs to be called.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .

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EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_TIMEOUT	The DHCP configuration process failed because no response was received from the server within the specified timeout value.
EFI_ABORTED	The user aborted the DHCP process.
EFI_ALREADY_STARTED	Some other EFI DHCPv4 Protocol instance already started the DHCP process.
EFI_DEVICE_ERROR	An unexpected network or system error occurred.

EFI_DHCP4_PROTOCOL.RenewRebind()

Summary

Extends the lease time by sending a request packet.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_RENEW_REBIND) (
    IN EFI_DHCP4_PROTOCOL    *This,
    IN BOOLEAN               RebindRequest,
    IN EFI_EVENT             CompletionEvent    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_DHCP4_PROTOCOL instance.
<i>RebindRequest</i>	If TRUE , this function broadcasts the request packets and enters the <i>Dhcp4Rebinding</i> state. Otherwise, it sends a unicast request packet and enters the <i>Dhcp4Renewing</i> state.
<i>CompletionEvent</i>	If not NULL , this event is signaled when the renew/rebind phase completes or some error occurs. EFI_DHCP4_PROTOCOL.GetModeData() can be called to check the completion status. If NULL , EFI_DHCP4_PROTOCOL.RenewRebind() will busy-wait until the DHCP process finishes.

Description

The **RenewRebind()** function is used to manually extend the lease time when the EFI DHCPv4 Protocol driver is in the *Dhcp4Bound* state and the lease time has not expired yet. This function will send a request packet to the previously found server (or to any server when *RebindRequest* is **TRUE**) and transfer the state into the *Dhcp4Renewing* state (or *Dhcp4Rebinding* when *RebindingRequest* is **TRUE**). When a response is received, the state is returned to *Dhcp4Bound*.

If no response is received before the try count is exceeded (the *RequestTryCount* field that is specified in **EFI_DHCP4_CONFIG_DATA**) but before the lease time that was issued by the previous server expires, the driver will return to the *Dhcp4Bound* state and the previous configuration is restored. The outgoing and incoming packets can be captured by the **EFI_DHCP4_CALLBACK** function.

Status Codes Returned

EFI_SUCCESS	The EFI DHCPv4 Protocol driver is now in the <i>Dhcp4Renewing</i> state or is back to the <i>Dhcp4Bound</i> state.
-------------	--

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EFI_NOT_STARTED	The EFI DHCPv4 Protocol driver is in the <i>Dhcp4Stopped</i> state. EFI_DHCP4_PROTOCOL.Configure() needs to be called.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_TIMEOUT	There was no response from the server when the try count was exceeded.
EFI_ACCESS_DENIED	The driver is not in the <i>Dhcp4Bound</i> state.
EFI_DEVICE_ERROR	An unexpected network or system error occurred.

EFI_DHCP4_PROTOCOL.Release()

Summary

Releases the current address configuration.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_RELEASE) (
    IN EFI_DHCP4_PROTOCOL *This
);
```

Parameters

This Pointer to the **EFI_DHCP4_PROTOCOL** instance.

Description

The **Release()** function releases the current configured IP address by doing either of the following:

- Sending a DHCPRELEASE packet when the EFI DHCPv4 Protocol driver is in the *Dhcp4Bound* state
- Setting the previously assigned IP address that was provided with the **EFI_DHCP4_PROTOCOL.Configure()** function to 0.0.0.0 when the driver is in *Dhcp4InitReboot* state

After a successful call to this function, the EFI DHCPv4 Protocol driver returns to the *Dhcp4Init* state and any subsequent incoming packets will be discarded silently.

Status Codes Returned

EFI_SUCCESS	The EFI DHCPv4 Protocol driver is now in the <i>Dhcp4Init</i> phase.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_ACCESS_DENIED	The EFI DHCPv4 Protocol driver is not in the <i>Dhcp4Bound</i> or <i>Dhcp4InitReboot</i> state.
EFI_DEVICE_ERROR	An unexpected network or system error occurred.

EFI_DHCP4_PROTOCOL.Stop()

Summary

Stops the DHCP configuration process.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_STOP) (
    IN EFI_DHCP4_PROTOCOL    *This
);
```

Parameters

This Pointer to the **EFI_DHCP4_PROTOCOL** instance.

Description

The **Stop()** function is used to stop the DHCP configuration process. After this function is called successfully, the EFI DHCPv4 Protocol driver is transferred into the *Dhcp4Stopped* state. **EFI_DHCP4_PROTOCOL.Configure()** needs to be called before DHCP configuration process can be started again. This function can be called when the EFI DHCPv4 Protocol driver is in any state.

Status Codes Returned

EFI_SUCCESS	The EFI DHCPv4 Protocol driver is now in the <i>Dhcp4Stopped</i> state.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .

EFI_DHCP4_PROTOCOL.Build()

Summary

Builds a DHCP packet, given the options to be appended or deleted or replaced.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_BUILD) (
    IN EFI_DHCP4_PROTOCOL           *This,
    IN EFI_DHCP4_PACKET             *SeedPacket,
    IN UINT32                       DeleteCount,
    IN UINT8                        *DeleteList           OPTIONAL,
    IN UINT32                       AppendCount,
    IN EFI_DHCP4_PACKET_OPTION      *AppendList[]        OPTIONAL,
    OUT EFI_DHCP4_PACKET             **NewPacket
);
```

Parameters

<i>This</i>	Pointer to the EFI_DHCP4_PROTOCOL instance.
<i>SeedPacket</i>	Initial packet to be used as a base for building new packet. Type EFI_DHCP4_PACKET is defined in EFI_DHCP4_PROTOCOL.GetModeData() .
<i>DeleteCount</i>	Number of opcodes in the <i>DeleteList</i> .
<i>DeleteList</i>	List of opcodes to be deleted from the seed packet. Ignored if <i>DeleteCount</i> is zero.
<i>AppendCount</i>	Number of entries in the <i>OptionList</i> .
<i>AppendList</i>	Pointer to a DHCP option list to be appended to <i>SeedPacket</i> . If <i>SeedPacket</i> also contains options in this list, they are replaced by new options (except pad option). Ignored if <i>AppendCount</i> is zero. Type EFI_DHCP4_PACKET_OPTION is defined in EFI_DHCP4_PROTOCOL.Configure() .
<i>NewPacket</i>	Pointer to storage for the pointer to the new allocated packet. Use the EFI Boot Service FreePool() on the resulting pointer when done with the packet.

Description

The **Build()** function is used to assemble a new packet from the original packet by replacing or deleting existing options or appending new options. This function does not change any state of the EFI DHCPv4 Protocol driver and can be used at any time.

Status Codes Returned

EFI_SUCCESS	The new packet was built.
-------------	---------------------------

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EFI_OUT_OF_RESOURCES	Storage for the new packet could not be allocated.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none">• <i>This</i> is NULL.• <i>SeedPacket</i> is NULL.• <i>SeedPacket</i> is not a well-formed DHCP packet.• <i>AppendCount</i> is not zero and <i>AppendList</i> is NULL.• <i>DeleteCount</i> is not zero and <i>DeleteList</i> is NULL.• <i>NewPacket</i> is NULL• Both <i>DeleteCount</i> and <i>AppendCount</i> are zero and <i>NewPacket</i> is not NULL.

EFI_DHCP4_PROTOCOL.TransmitReceive()

Summary

Transmits a DHCP formatted packet and optionally waits for responses.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_TRANSMIT_RECEIVE) (
    IN EFI_DHCP4_PROTOCOL           *This,
    IN EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_DHCP4_PROTOCOL instance.
<i>Token</i>	Pointer to the EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN structure. Type EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN is defined in “Related Definitions” below.

Description

The **TransmitReceive()** function is used to transmit a DHCP packet and optionally wait for the response from servers. This function does not change the state of the EFI DHCPv4 Protocol driver and thus can be used at any time.

Related Definitions

```

/*****
// EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN
*****/
typedef struct {
    OUT EFI_STATUS           Status;
    IN EFI_EVENT             CompletionEvent           OPTIONAL;
    IN EFI_IPv4_ADDRESS      RemoteAddress;
    IN UINT16                 RemotePort;
    IN EFI_IPv4_ADDRESS      GatewayAddress           OPTIONAL;
    IN UINT32                 ListenPointCount;
    IN EFI_DHCP4_LISTEN_POINT *ListenPoints           OPTIONAL;
    IN UINT32                 TimeoutValue;
    IN EFI_DHCP4_PACKET       *Packet;
    OUT UINT32                 ResponseCount           OPTIONAL;
    OUT EFI_DHCP4_PACKET       *ResponseList           OPTIONAL;
} EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN;
```

<i>Status</i>	The completion status of transmitting and receiving. Possible values are described in the “Status Codes Returned” table below.
---------------	--

When *CompletionEvent* is **NULL**, this status is the same as the one returned by the **TransmitReceive()** function.

CompletionEvent If not **NULL**, the event that will be signaled when the collection process completes. If **NULL**, this function will busy-wait until the collection process competes.

RemoteAddress Pointer to the server IP address. This address may be a unicast, multicast, or broadcast address.

RemotePort Server listening port number. If zero, the default server listening port number (67) will be used.

GatewayAddress Pointer to the gateway address to override the existing setting.

ListenPointCount The number of entries in *ListenPoints*. If zero, the default station address and port number 68 are used.

ListenPoints An array of station address and port number pairs that are used as receiving filters. The first entry is also used as the source address and source port of the outgoing packet. Type **EFI_DHCP4_LISTEN_POINT** is defined below.

TimeoutValue Number of seconds to collect responses. Zero is invalid.

Packet Pointer to the packet to be transmitted. Type **EFI_DHCP4_PACKET** is defined in **EFI_DHCP4_PROTOCOL.GetModeData()**.

ResponseCount Number of received packets.

ResponseList Pointer to the allocated list of received packets. The caller must use the EFI Boot Service **FreePool()** when done using the received packets.

```

//*****
// EFI_DHCP4_LISTEN_POINT
//*****
typedef struct {
    EFI_IPv4_ADDRESS    ListenAddress;
    EFI_IPv4_ADDRESS    SubnetMask;
    UINT16              ListenPort;
} EFI_DHCP4_LISTEN_POINT;

```

ListenAddress Alternate listening address. It can be a unicast, multicast, or broadcast address. The **TransmitReceive()** function will collect only those packets that are destined to this address.

SubnetMask The subnet mask of above listening unicast/broadcast IP address. Ignored if *ListenAddress* is a multicast address. If it is **0.0.0.0**, the subnet mask is automatically computed from unicast *ListenAddress*. Cannot be **0.0.0.0** if *ListenAddress* is direct broadcast address on subnet.

ListenPort

Alternate station source (or listening) port number. If zero, then the default station port number (68) will be used.

Status Codes Returned

EFI_SUCCESS	The packet was successfully queued for transmission.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token.RemoteAddress</i> is zero. • <i>Token.Packet</i> is NULL. • <i>Token.Packet</i> is not a well-formed DHCP packet. • The transaction ID in <i>Token.Packet</i> is in use by another DHCP process.
EFI_NOT_READY	The previous call to this function has not finished yet. Try to call this function after collection process completes.
EFI_NO_MAPPING	The default station address is not available yet.
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_UNSUPPORTED	The implementation doesn't support this function
Others	Some other unexpected error occurred.

EFI_DHCP4_PROTOCOL.Parse()

Summary

Parses the packed DHCP option data.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP4_PARSE) (
    IN EFI_DHCP4_PROTOCOL          *This,
    IN EFI_DHCP4_PACKET           *Packet
    IN OUT UINT32                  *OptionCount,
    IN OUT EFI_DHCP4_PACKET_OPTION *PacketOptionList[] OPTIONAL
);
```

Parameters

This Pointer to the **EFI_DHCP4_PROTOCOL** instance.

Packet Pointer to packet to be parsed. Type **EFI_DHCP4_PACKET** is defined in **EFI_DHCP4_PROTOCOL.GetModeData()**.

OptionCount On input, the number of entries in the *PacketOptionList*. On output, the number of entries that were written into the *PacketOptionList*.

PacketOptionList List of packet option entries to be filled in. End option or pad options are not included. Type **EFI_DHCP4_PACKET_OPTION** is defined in **EFI_DHCP4_PROTOCOL.Configure()**.

Description

The **Parse()** function is used to retrieve the option list from a DHCP packet. If ***OptionCount** isn't zero, and there is enough space for all the DHCP options in the **Packet**, each element of **PacketOptionList** is set to point to somewhere in the **Packet->Dhcp4.Option** where a new DHCP option begins. If RFC3396 is supported, the caller should reassemble the parsed DHCP options to get the final result. If ***OptionCount** is zero or there isn't enough space for all of them, the number of DHCP options in the **Packet** is returned in **OptionCount**.

Status Codes Returned

EFI_SUCCESS	The packet was successfully parsed.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Packet</i> is NULL. • <i>Packet</i> is not a well-formed DHCP packet. • <i>OptionCount</i> is NULL.

EFI_BUFFER_TOO_SMALL	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • <i>*OptionCount</i> is smaller than the number of options that were found in the <i>Packet</i>. • <i>PacketOptionList</i> is NULL.
EFI_OUT_OF_RESOURCE	The packet is failed to parse because of resource shortage.

Network Protocols —TCPv4, IPv4 and Configuration

24.1 EFI TCPv4 Protocol

This section defines the EFI TCPv4 (Transmission Control Protocol version 4) Protocol.

EFI_TCP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI TCPv4 Service Binding Protocol is used to locate EFI TCPv4 Protocol drivers to create and destroy child of the driver to communicate with other host using TCP protocol.

GUID

```
#define EFI_TCP4_SERVICE_BINDING_PROTOCOL_GUID \
{0x00720665,0x67EB,0x4a99,0xBA,0xF7,0xD3,0xC3,0x3A,0x1C,0x7C,0xC9}
```

Description

A network application that requires TCPv4 I/O services can call one of the protocol handler services, such as **BS->LocateHandleBuffer()**, to search devices that publish an EFI TCPv4 Service Binding Protocol GUID. Such device supports the EFI TCPv4 Protocol and may be available for use.

After a successful call to the **EFI_TCP4_SERVICE_BINDING_PROTOCOL.CreateChild()** function, the newly created child EFI TCPv4 Protocol driver is in an un-configured state; it is not ready to do any operation except **Poll()** send and receive data packets until configured as the purpose of the user and perhaps some other indispensable function belonged to TCPv4 Protocol driver is called properly.

Every successful call to the **EFI_TCP4_SERVICE_BINDING_PROTOCOL.CreateChild()** function must be matched with a call to the **EFI_TCP4_SERVICE_BINDING_PROTOCOL.DestroyChild()** function to release the protocol driver.

EFI TCP4 Variable

Summary

A list of all the IPv4 addresses and port numbers in use must be maintained for each communications device. This list is stored as volatile variable so it can be publicly read.

Vendor GUID

```
gEfiTcp4ServiceBindingProtocolGuid ;
```

Variable Name

```
CHAR16 *MacAddress;
```

Attribute

```
EFI_VARIABLE_BOOTSERVICE_ACCESS
```

Description

MacAddress is the string of printed hexadecimal value for each byte in hardware address (of type **EFI_MAC_ADDRESS**) of the communications device. No 0x or h is included in each hex value. The length of **MacAddress** is determined by the hardware address length. For example: if the hardware address is 00-07-E9-51-60-D7, and address length is 6 bytes, then **MacAddress** is **Çk"0007E95160D7"**.

Related Definitions

```

//*****
// EFI_TCP4_VARIABLE_DATA
//*****
typedef struct {
    EFI_HANDLE           DriverHandle;
    UINTN32              ServiceCount;
    EFI_TCP4_SERVICE_POINT Services[1];
} EFI_TCP4_VARIABLE_DATA;

```

<i>DriverHandle</i>	The handle of the driver that creates this entry.
<i>ServiceCount</i>	The number of address/port pairs following this data structure.
<i>Services</i>	List of address/port pairs that are currently in use. Type EFI_TCP4_SERVICE_POINT is defined below.

```

//*****
// EFI_TCP4_SERVICE_POINT
//*****
typedef struct{
    EFI_HANDLE           InstanceHandle;
    EFI_IPv4_ADDRESS     LocalAddress;
    UINT16               LocalPort;
    EFI_IPv4_ADDRESS     RemoteAddress;
    UINT16               RemotePort;
} EFI_TCP4_SERVICE_POINT;

```

<i>InstanceHandle</i>	The EFI TCPv4 Protocol instance handle that is using this service port.
-----------------------	---

<i>LocalAddress</i>	The local IPv4 address to which this TCPv4 protocol instance is bound.
<i>LocalPort</i>	The local port number in host byte order.
<i>RemoteAddress</i>	The remote IPv4 address. It may be 0.0.0.0 if it isn't connected to any remote host.
<i>RemotePort</i>	The remote port number in host byte order. It may be zero if it isn't connected to any remote host

EFI_TCP4_PROTOCOL

Summary

The EFI TCPv4 Protocol provides services to send and receive data stream.

GUID

```
#define EFI_TCP4_PROTOCOL_GUID \
{0x65530BC7,0xA359,0x410f,0xB0,0x10,0x5A,0xAD,0xC7,0xEC,0x2B,
0x62}
```

Protocol Interface Structure

```
typedef struct _EFI_TCP4_PROTOCOL {
EFI_TCP4_GET_MODE_DATA      GetModeData;
EFI_TCP4_CONFIGURE          Configure;
EFI_TCP4_ROUTES              Routes;
EFI_TCP4_CONNECT            Connect;
EFI_TCP4_ACCEPT              Accept;
EFI_TCP4_TRANSMIT            Transmit;
EFI_TCP4_RECEIVE             Receive;
EFI_TCP4_CLOSE               Close;
EFI_TCP4_CANCEL              Cancel;
EFI_TCP4_POLL                 Poll;
} EFI_TCP4_PROTOCOL;
```

Parameters

<i>GetModeData</i>	Get the current operational status. See the GetModeData () function description.
<i>Configure</i>	Initialize, change, or brutally reset operational settings of the EFI TCPv4 Protocol. See the Configure () function description.
<i>Routes</i>	Add or delete routing entries for this TCP4 instance. See the Routes () function description.
<i>Connect</i>	Initiate the TCP three-way handshake to connect to the remote peer configured in this TCP instance. The function is a nonblocking operation. See the Connect () function description.
<i>Accept</i>	Listen for incoming TCP connection request. This function is a nonblocking operation. See the Accept () function description.

<i>Transmit</i>	Queue outgoing data to the transmit queue. This function is a nonblocking operation. See the Transmit () function description.
<i>Receive</i>	Queue a receiving request token to the receive queue. This function is a nonblocking operation. See the Receive () function description.
<i>Close</i>	Gracefully disconnecting a TCP connection follow RFC 793 or reset a TCP connection. This function is a nonblocking operation. See the Close () function description.
<i>Cancel</i>	Abort a pending connect, listen, transmit or receive request. See the Cancel () function description.
<i>Poll</i>	Poll to receive incoming data and transmit outgoing TCP segments. See the Poll () function description.

Description

The **EFI_TCP4_PROTOCOL** defines the EFI TCPv4 Protocol child to be used by any network drivers or applications to send or receive data stream. It can either listen on a specified port as a service or actively connected to remote peer as a client. Each instance has its own independent settings, such as the routing table.

Note: *In this document, all IPv4 addresses and incoming/outgoing packets are stored in network byte order. All other parameters in the functions and data structures that are defined in this document are stored in host byte order unless explicitly specified.*

EFI_TCP4_PROTOCOL.GetModeData()

Summary

Get the current operational status.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_GET_MODE_DATA) (
    IN EFI_TCP4_PROTOCOL                *This,
    OUT EFI_TCP4_CONNECTION_STATE      *Tcp4State           OPTIONAL,
    OUT EFI_TCP4_CONFIG_DATA           *Tcp4ConfigData      OPTIONAL,
    OUT EFI_IPv4_MODE_DATA             *Ip4ModeData        OPTIONAL,
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData      OPTIONAL,
    OUT EFI_SIMPLE_NETWORK_MODE        *SnpModeData         OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>Tcp4State</i>	Pointer to the buffer to receive the current TCP state. Type EFI_TCP4_CONNECTION_STATE is defined in “Related Definitions” below.
<i>Tcp4ConfigData</i>	Pointer to the buffer to receive the current TCP configuration. Type EFI_TCP4_CONFIG_DATA is defined in “Related Definitions” below.
<i>Ip4ModeData</i>	Pointer to the buffer to receive the current IPv4 configuration data used by the TCPv4 instance. Type EFI_IP4_MODE_DATA is defined in EFI_IP4_PROTOCOL.GetModeData() .
<i>MnpConfigData</i>	Pointer to the buffer to receive the current MNP configuration data used indirectly by the TCPv4 instance. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData() .
<i>SnpModeData</i>	Pointer to the buffer to receive the current SNP configuration data used indirectly by the TCPv4 instance. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL .

Description

The **GetModeData()** function copies the current operational settings of this EFI TCPv4 Protocol instance into user-supplied buffers. This function can also be used to retrieve the operational setting of underlying drivers such as IPv4, MNP, or SNP.

Related Definition

```
typedef struct {
    BOOLEAN                UseDefaultAddress;
    EFI_IPv4_ADDRESS       StationAddress;
    EFI_IPv4_ADDRESS       SubnetMask;
    UINT16                 StationPort;
    EFI_IPv4_ADDRESS       RemoteAddress;
    UINT16                 RemotePort;
    BOOLEAN                ActiveFlag;
} EFI_TCP4_ACCESS_POINT;
```

<i>UseDefaultAddress</i>	Set to TRUE to use the default IP address and default routing table. If the default IP address is not available yet, then the underlying EFI IPv4 Protocol driver will use EFI_IP4_CONFIG_PROTOCOL to retrieve the IP address and subnet information.
<i>StationAddress</i>	The local IP address assigned to this EFI TCPv4 Protocol instance. The EFI TCPv4 and EFI IPv4 Protocol drivers will only deliver incoming packets whose destination addresses exactly match the IP address. Not used when <i>UseDefaultAddress</i> is TRUE .
<i>SubnetMask</i>	The subnet mask associated with the station address. Not used when <i>UseDefaultAddress</i> is TRUE .
<i>StationPort</i>	The local port number to which this EFI TCPv4 Protocol instance is bound. If the instance doesn't care the local port number, set <i>StationPort</i> to zero to use an ephemeral port.
<i>RemoteAddress</i>	The remote IP address to which this EFI TCPv4 Protocol instance is connected. If <i>ActiveFlag</i> is FALSE (i.e. a passive TCPv4 instance), the instance only accepts connections from the <i>RemoteAddress</i> . If <i>ActiveFlag</i> is TRUE the instance is connected to the <i>RemoteAddress</i> , i.e., outgoing segments will be sent to this address and only segments from this address will be delivered to the application. When <i>ActiveFlag</i> is FALSE it can be set to zero and means that incoming connection request from any address will be accepted.
<i>RemotePort</i>	The remote port to which this EFI TCPv4 Protocol instance connects or connection request from which is accepted by this EFI TCPv4 Protocol instance. If <i>ActiveFlag</i> is FALSE it can be zero and means that incoming connection request from any port will be accepted. Its value can not be zero when <i>ActiveFlag</i> is TRUE .
<i>ActiveFlag</i>	Set it to TRUE to initiate an active open. Set it to FALSE to initiate a passive open to act as a server.

```
typedef struct {
    UINTN32      ReceiveBufferSize;
    UINTN32      SendBufferSize;
    UINTN32      MaxSynBackLog;
    UINTN32      ConnectionTimeout;
    UINTN32      DataRetries;
    UINTN32      FinTimeout;
    UINTN32      TimeWaitTimeout;
    UINTN32      KeepAliveProbes;
    UINTN32      KeepAliveTime;
    UINTN32      KeepAliveInterval;
    BOOLEAN      EnableNagle;
    BOOLEAN      EnableTimeStamp;
    BOOLEAN      EnableWindowScaling;
    BOOLEAN      EnableSelectiveAck;
    BOOLEAN      EnablePathMtuDiscovery;
}EFI_TCP4_OPTION;
```

<i>ReceiveBufferSize</i>	The size of the TCP receive buffer.
<i>SendBufferSize</i>	The size of the TCP send buffer.
<i>MaxSynBackLog</i>	The length of incoming connect request queue for a passive instance. When set to zero, the value is implementation specific.
<i>ConnectionTimeout</i>	The maximum seconds a TCP instance will wait for before a TCP connection established. When set to zero, the value is implementation specific.
<i>DataRetries</i>	The number of times TCP will attempt to retransmit a packet on an established connection. When set to zero, the value is implementation specific.
<i>FinTimeout</i>	How many seconds to wait in the FIN_WAIT_2 states for a final FIN flag before the TCP instance is closed. This timeout is in effective only if the application has called Close() to disconnect the connection completely. It is also called FIN_WAIT_2 timer in other implementations. When set to zero, it should be disabled because the FIN_WAIT_2 timer itself is against the standard. The default value is 60.
<i>TimeWaitTimeout</i>	How many seconds to wait in TIME_WAIT state before the TCP instance is closed. The timer is disabled completely to provide a method to close the TCP connection quickly if it is set to zero. It is against the related RFC documents.
<i>KeepAliveProbes</i>	The maximum number of TCP keep-alive probes to send before giving up and resetting the connection if no response from the other end. Set to zero to disable keep-alive probe.
<i>KeepAliveTime</i>	The number of seconds a connection needs to be idle before TCP sends out periodical keep-alive probes. When set to zero, the

	value is implementation specific. It should be ignored if keep-alive probe is disabled.
<i>KeepAliveInterval</i>	The number of seconds between TCP keep-alive probes after the periodical keep-alive probe if no response. When set to zero, the value is implementation specific. It should be ignored if keep-alive probe is disabled.
<i>EnableNagle</i>	Set it to TRUE to enable the Nagle algorithm as defined in RFC896. Set it to FALSE to disable it.
<i>EnableTimeStamp</i>	Set it to TRUE to enable TCP timestamps option as defined in RFC1323. Set to FALSE to disable it.
<i>EnableWindowScaling</i>	Set it to TRUE to enable TCP window scale option as defined in RFC1323. Set it to FALSE to disable it.
<i>EnableSelectiveAck</i>	Set it to TRUE to enable selective acknowledge mechanism described in RFC 2018. Set it to FALSE to disable it. Implementation that supports SACK can optionally support DSAK as defined in RFC 2883.
<i>EnablePathMtuDiscovery</i>	Set it to TRUE to enable path MTU discovery as defined in RFC 1191. Set to FALSE to disable it.

Option setting with digital value will be modified by driver if it is set out of the implementation specific range and an implementation specific default value will be set accordingly.

```
//
*****
// EFI_TCP4_CONFIG_DATA
//
*****
typedef struct {
    // Receiving Filters
    // I/O parameters
    UINT8          TypeOfService;
    UINT8          TimeToLive;

    // Access Point
    EFI_TCP4_ACCESS_POINT AccessPoint;

    // TCP Control Options
    EFI_TCP4_OPTION      * ControlOption;
} EFI_TCP4_CONFIG_DATA;
```

TypeOfService *TypeOfService* field in transmitted IPv4 packets.
TimeToLive *TimeToLive* field in transmitted IPv4 packets.

```

AccessPoint           Used to specify TCP communication end settings for a TCP
                        instance.

ControlOption        Used to configure the advance TCP option for a connection. If set
                        to NULL, implementation specific options for TCP connection
                        will be used.

//
*****
// EFI_TCP4_CONNECTION_STATE
//
*****

typedef enum {
    Tcp4StateClosed           = 0,
    Tcp4StateListen           = 1,
    Tcp4StateSynSent          = 2,
    Tcp4StateSynReceived      = 3,
    Tcp4StateEstablished     = 4,
    Tcp4StateFinWait1        = 5,
    Tcp4StateFinWait2        = 6,
    Tcp4StateClosing         = 7,
    Tcp4StateTimeWait        = 8,
    Tcp4StateCloseWait       = 9,
    Tcp4StateLastAck         = 10
} EFI_TCP4_CONNECTION_STATE;

```

Status Codes Returned

EFI_SUCCESS	The mode data was read.
EFI_NOT_STARTED	No configuration data is available because this instance hasn't been started.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .

EFI_TCP4_PROTOCOL.Configure()

Summary

- Initialize or brutally reset the operational parameters for this EFI TCPv4 instance.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_CONFIGURE) (
    IN EFI_TCP4_PROTOCOL          *This,
    IN EFI_TCP4_CONFIG_DATA      *TcpConfigData OPTIONAL
);
```

Parameters

This Pointer to the **EFI_TCP4_PROTOCOL** instance.

TcpConfigData Pointer to the configure data to configure the instance.

Description

The **Configure()** function does the following:

- Initialize this EFI TCPv4 instance, i.e., initialize the communication end setting, specify active open or passive open for an instance.
- Reset this TCPv4 instance brutally, i.e., cancel all pending asynchronous tokens, flush transmission and receiving buffer directly without informing the communication peer.

No other TCPv4 Protocol operation can be executed by this instance until it is configured properly. For an active TCP4 instance, after a proper configuration it may call **Connect()** to initiates the three-way handshake. For a passive TCP4 instance, its state will transit to **Tcp4StateListen** after configuration, and **Accept()** may be called to listen the incoming TCP connection request. If *TcpConfigData* is set to **NULL**, the instance is reset. Resetting process will be done brutally, the state machine will be set to **Tcp4StateClosed** directly, the receive queue and transmit queue will be flushed, and no traffic is allowed through this instance.

Status Codes Returned

EFI_SUCCESS	The operational settings are set, changed, or reset successfully.
EFI_NO_MAPPING	When using a default address, configuration (through DHCP, BOOTP, RARP, etc.) is not finished yet.

<p>EFI_INVALID_PARAMETER</p>	<p>One or more following conditions are TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>TcpConfigData</i> -><i>AccessPoint.StationAddress</i> isn't a valid unicast IPv4 address when <i>TcpConfigData</i> -><i>AccessPoint.UseDefaultAddress</i> is FALSE. • <i>TcpConfigData</i> -><i>AccessPoint.SubnetMask</i> isn't a valid IPv4 address mask when <i>TcpConfigData</i> -> <i>AccessPoint.UseDefaultAddress</i> is FALSE. The subnet mask must be contiguous. • <i>TcpConfigData</i> -><i>AccessPoint.RemoteAddress</i> isn't a valid unicast IPv4 address. • <i>TcpConfigData</i> -><i>AccessPoint.RemoteAddress</i> is zero or <i>TcpConfigData</i> -><i>AccessPoint.RemotePort</i> is zero when <i>TcpConfigData</i> -><i>AccessPoint.ActiveFlag</i> is TRUE. • A same access point has been configured in other TCP instance properly.
<p>EFI_ACCESS_DENIED</p>	<p>Configuring TCP instance when it is configured without calling Configure () with NULL to reset it.</p>
<p>EFI_DEVICE_ERROR</p>	<p>An unexpected network or system error occurred.</p>
<p>EFI_UNSUPPORTED</p>	<p>One or more of the control options are not supported in the implementation.</p>
<p>EFI_OUT_OF_RESOURCES</p>	<p>Could not allocate enough system resources when executing Configure ().</p>

EFI_TCP4_PROTOCOL.Routes()

Summary

Add or delete routing entries.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_TCP4_ROUTES) (
    IN EFI_TCP4_PROTOCOL    *This,
    IN BOOLEAN              DeleteRoute,
    IN EFI_IPv4_ADDRESS     *SubnetAddress,
    IN EFI_IPv4_ADDRESS     *SubnetMask,
    IN EFI_IPv4_ADDRESS     *GatewayAddress
);
```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>DeleteRoute</i>	Set it to TRUE to delete this route from the routing table. Set it to FALSE to add this route to the routing table. <i>DestinationAddress</i> and <i>SubnetMask</i> are used as the keywords to search route entry.
<i>SubnetAddress</i>	The destination network.
<i>SubnetMask</i>	The subnet mask of the destination network.
<i>GatewayAddress</i>	The gateway address for this route. It must be on the same subnet with the station address unless a direct route is specified.

Description

The **Routes()** function adds or deletes a route from the instance's routing table.

The most specific route is selected by comparing the *SubnetAddress* with the destination IP address's arithmetical **AND** to the *SubnetMask*.

The default route is added with both *SubnetAddress* and *SubnetMask* set to 0.0.0.0. The default route matches all destination IP addresses if there is no more specific route.

Direct route is added with *GatewayAddress* set to 0.0.0.0. Packets are sent to the destination host if its address can be found in the Address Resolution Protocol (ARP) cache or it is on the local subnet. If the instance is configured to use default address, a direct route to the local network will be added automatically.

Each TCP instance has its own independent routing table. Instance that uses the default IP address will have a copy of the **EFI_IP4_CONFIG_PROTOCOL**'s routing table. The copy will be updated automatically whenever the IP driver reconfigures its instance. As a result, the previous modification to the instance's local copy will be lost.

The priority of checking the route table is specific with IP implementation and every IP implementation must comply with RFC 1122.

Note: *There is no way to set up routes to other network interface cards (NICs) because each NIC has its own independent network stack that shares information only through **EFI TCPv4 variable**.*

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_NOT_STARTED	The EFI TCPv4 Protocol instance has not been configured.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>SubnetAddress</i> is NULL. • <i>SubnetMask</i> is NULL. • <i>GatewayAddress</i> is NULL. • <i>*SubnetAddress</i> is not NULL a valid subnet address. • <i>*SubnetMask</i> is not a valid subnet mask. • <i>*GatewayAddress</i> is not a valid unicast IP address or it is not in the same subnet.
EFI_OUT_OF_RESOURCES	Could not allocate enough resources to add the entry to the routing table.
EFI_NOT_FOUND	This route is not in the routing table.
EFI_ACCESS_DENIED	The route is already defined in the routing table.
EFI_UNSUPPORTED	The TCP driver does not support this operation.

EFI_TCP4_PROTOCOL.Connect()

Summary

Initiate a nonblocking TCP connection request for an active TCP instance.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_CONNECT) (
    IN EFI_TCP4_PROTOCOL           *This,
    IN EFI_TCP4_CONNECTION_TOKEN *ConnectionToken,
);
```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>ConnectionToken</i>	Pointer to the connection token to return when the TCP three way handshake finishes. Type EFI_TCP4_CONNECTION_TOKEN is defined in “Related Definition” below.

Description

The **Connect()** function will initiate an active open to the remote peer configured in current TCP instance if it is configured active. If the connection succeeds or fails due to any error, the *ConnectionToken->CompletionToken.Event* will be signaled and *ConnectionToken->CompletionToken.Status* will be updated accordingly. This function can only be called for the TCP instance in **Tcp4StateClosed** state. The instance will transfer into **Tcp4StateSynSent** if the function returns **EFI_SUCCESS**. If TCP three way handshake succeeds, its state will become **Tcp4StateEstablished**, otherwise, the state will return to **Tcp4StateClosed**.

Related Definitions

```
//
*****
// EFI_TCP4_COMPLETION_TOKEN
//
*****
typedef struct {
    EFI_EVENT           Event;
    EFI_STATUS          Status;
} EFI_TCP4_COMPLETION_TOKEN;
```

<i>Event</i>	The <i>Event</i> to signal after request is finished and <i>Status</i> field is updated by the EFI TCPv4 Protocol driver. The type of <i>Event</i> must be EVT_NOTIFY_SIGNAL , and its Task Priority Level (TPL) must be lower than or equal to TPL_CALLBACK .
<i>Status</i>	The variable to receive the result of the completed operation.

The **EFI_TCP4_COMPLETION_TOKEN** is used as a common header for various asynchronous tokens.

```
//
*****
// EFI_TCP4_CONNECTION_TOKEN
//
*****
typedef struct {
    EFI_TCP4_COMPLETION_TOKEN      CompletionToken;
} EFI_TCP4_CONNECTION_TOKEN;
```

Status

The *Status* in the *CompletionToken* will be set to one of the following values if the active open succeeds or an unexpected error happens:

EFI_SUCCESS. The active open succeeds and the instance is in **Tcp4StateEstablished**.

EFI_CONNECTION_RESET. The connect fails because the connection is reset either by instance itself or communication peer.

EFI_ABORTED. The active open was aborted.

EFI_TIMEOUT. The connection establishment timer expired and no more specific information is available.

EFI_NETWORK_UNREACHABLE. The active open fails because an ICMP network unreachable error is received.

EFI_HOST_UNREACHABLE. The active open fails because an ICMP host unreachable error is received.

EFI_PROTOCOL_UNREACHABLE. The active open fails because an ICMP protocol unreachable error is received.

EFI_PORT_UNREACHABLE. The connection establishment timer times out and an ICMP port unreachable error is received.

EFI_ICMP_ERROR. The connection establishment timer timeout and some other ICMP error is received.

EFI_DEVICE_ERROR. An unexpected system or network error occurred.

Status Codes Returned

EFI_SUCCESS	The connection request is successfully initiated and the state of this TCPv4 instance has been changed to Tcp4StateSynSent .
EFI_NOT_STARTED	This EFI TCPv4 Protocol instance has not been configured.

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EFI_ACCESS_DENIED	One or more of the following conditions are TRUE : <ul style="list-style-type: none">• This instance is not configured as an active one.• This instance is not in <i>Tcp4StateClosed</i> state.
EFI_INVALID_PARAMETER	One or more of the following are TRUE : <ul style="list-style-type: none">• <i>This</i> is NULL.• <i>ConnectionToken</i> is NULL.• <i>ConnectionToken</i> -><i>CompletionToken.Event</i> is NULL.
EFI_OUT_OF_RESOURCES	The driver can't allocate enough resource to initiate the active open.
EFI_DEVICE_ERROR	An unexpected system or network error occurred.

EFI_TCP4_PROTOCOL.Accept()

Summary

Listen on the passive instance to accept an incoming connection request. This is a nonblocking operation.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_ACCEPT) (
    IN EFI_TCP4_PROTOCOL           *This,
    IN EFI_TCP4_LISTEN_TOKEN      *ListenToken
);

```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>ListenToken</i>	Pointer to the listen token to return when operation finishes. Type EFI_TCP4_LISTEN_TOKEN is defined in “Related Definition” below.

Related Definitions

```

//
*****
// EFI_TCP4_LISTEN_TOKEN
//
*****
typedef struct {
    EFI_TCP4_COMPLETION_TOKEN      CompletionToken;
    EFI_HANDLE                     NewChildHandle;
} EFI_TCP4_LISTEN_TOKEN;

```

<i>Status</i>	The <i>Status</i> in <i>CompletionToken</i> will be set to the following value if accept finishes: EFI_SUCCESS . A remote peer has successfully established a connection to <i>this</i> instance. A new TCP instance has also been created for the connection. EFI_CONNECTION_RESET . The accept fails because the connection is reset either by instance itself or communication peer. EFI_ABORTED . The accept request has been aborted.
<i>NewChildHandle</i>	The new TCP instance handle created for the established connection.

Description

The **Accept ()** function initiates an asynchronous accept request to wait for an incoming connection on the passive TCP instance. If a remote peer successfully establishes a connection with

this instance, a new TCP instance will be created and its handle will be returned in *ListenToken->NewChildHandle*. The newly created instance is configured by inheriting the passive instance's configuration and is ready for use upon return. The instance is in the **Tcp4StateEstablished** state.

The *ListenToken->CompletionToken.Event* will be signaled when a new connection is accepted, user aborts the listen or connection is reset.

This function only can be called when current TCP instance is in **Tcp4StateListen** state.

Status Codes Returned

EFI_SUCCESS	The listen token has been queued successfully.
EFI_NOT_STARTED	This EFI TCPv4 Protocol instance has not been configured.
EFI_ACCESS_DENIED	One or more of the following are TRUE : <ul style="list-style-type: none"> • This instance is not a passive instance. • This instance is not in <i>Tcp4StateListen</i> state. • The same listen token has already existed in the listen token queue of this TCP instance.
EFI_INVALID_PARAMETER	One or more of the following are TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>ListenToken</i> is NULL. • <i>ListenToken->CompletionToken.Event</i> is NULL.
EFI_OUT_OF_RESOURCES	Could not allocate enough resource to finish the operation.
EFI_DEVICE_ERROR	Any unexpected and not belonged to above category error.

EFI_TCP4_PROTOCOL.Transmit()

Summary

Queues outgoing data into the transmit queue.

Prototype

```

typedef
EFI_STATUS
(EFI_API *EFI_TCP4_TRANSMIT) (
    IN EFI_TCP4_PROTOCOL           *This,
    IN EFI_TCP4_IO_TOKEN          *Token
);

```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>Token</i>	Pointer to the completion token to queue to the transmit queue. Type EFI_TCP4_IO_TOKEN is defined in “Related Definitions” below.

Description

The **Transmit()** function queues a sending request to this TCPv4 instance along with the user data. The status of the token is updated and the event in the token will be signaled once the data is sent out or some error occurs.

Related Definitions

```

//
*****
// EFI_TCP4_IO_TOKEN
//
*****
typedef struct {
    EFI_TCP4_COMPLETION_TOKEN          CompletionToken;
    union {
        EFI_TCP4_RECEIVE_DATA          *RxData;
        EFI_TCP4_TRANSMIT_DATA         *TxData;
    } Packet;
} EFI_TCP4_IO_TOKEN;

```

Status When transmission finishes or meets any unexpected error it will be set to one of the following values:

EFI_SUCCESS. The receiving or transmission operation completes successfully.

EFI_CONNECTION_RESET. The receiving or transmission operation fails because this connection is reset either by instance itself or communication peer.

EFI_ABORTED. The receiving or transmission is aborted.

EFI_TIMEOUT. The transmission timer expires and no more specific information is available.

EFI_NETWORK_UNREACHABLE. The transmission fails because an ICMP network unreachable error is received.

EFI_HOST_UNREACHABLE. The transmission fails because an ICMP host unreachable error is received.

EFI_PROTOCOL_UNREACHABLE. The transmission fails because an ICMP protocol unreachable error is received.

EFI_PORT_UNREACHABLE. The transmission fails and an ICMP port unreachable error is received.

EFI_ICMP_ERROR. The transmission fails and some other ICMP error is received.

EFI_DEVICE_ERROR. An unexpected system or network error occurs.

RxData When this token is used for receiving, *RxData* is a pointer to **EFI_TCP4_RECEIVE_DATA**. Type **EFI_TCP4_RECEIVE_DATA** is defined below.

TxData When this token is used for transmitting, *TxData* is a pointer to **EFI_TCP4_TRANSMIT_DATA**. Type **EFI_TCP4_TRANSMIT_DATA** is defined below.

The **EFI_TCP4_IO_TOKEN** structures are used for both transmit and receive operations.

When used for transmitting, the *CompletionToken.Event* and *TxData* fields must be filled in by the user. After the transmit operation completes, the *CompletionToken.Status* field is updated by the instance and the *Event* is signaled.

- When used for receiving, the *CompletionToken.Event* and *RxData* fields must be filled in by the user. After a receive operation completes, *RxData* and *Status* are updated by the instance and the *Event* is signaled.

```

//
*****
// EFI_TCP4_RECEIVE_DATA
//
*****
typedef struct {
    BOOLEAN                UrgentFlag;
    UINTN32                DataLength;
    UINTN32                FragmentCount;
    EFI_TCP4_FRAGMENT_DATA FragmentTable[1];
} EFI_TCP4_RECEIVE_DATA;

```

UrgentFlag Whether those data are urgent. When this flag is set, the instance is in urgent mode. The implementations of this specification

should follow RFC793 to process urgent data, and should NOT mix the data across the urgent point in one token.

<i>DataLength</i>	When calling Receive () function, it is the byte counts of all <i>Fragmentbuffer</i> in <i>FragmentTable</i> allocated by user. When the token is signaled by TCPv4 driver it is the length of received data in the fragments.
<i>FragmentCount</i>	Number of fragments.
<i>FragmentTable</i>	An array of fragment descriptors. Type EFI_TCP4_FRAGMENT_DATA is defined below.

When TCPv4 driver wants to deliver received data to the application, it will pick up the first queued receiving token, update its *Token->Packet.RxData* then signal the *Token->CompletionToken.Event*.

- The *FragmentBuffers* in *FragmentTable* are allocated by the application when calling **Receive ()** function and received data will be copied to those buffers by the driver. *FragmentTable* may contain multiple buffers that are NOT in the continuous memory locations. The application should combine those buffers in the *FragmentTable* to process data if necessary.

```
//
*****
// EFI_TCP4_FRAGMENT_DATA
//
*****
typedef struct {
    UINT32N      FragmentLength;
    VOID         *FragmentBuffer;
} EFI_TCP4_FRAGMENT_DATA;
```

<i>FragmentLength</i>	Length of data buffer in the fragment.
<i>FragmentBuffer</i>	Pointer to the data buffer in the fragment.

EFI_TCP4_FRAGMENT_DATA allows multiple receive or transmit buffers to be specified. The purpose of this structure is to provide scattered read and write.

```

//*****
// EFI_TCP4_TRANSMIT_DATA
//*****
typedef struct {
    BOOLEAN          Push;
    BOOLEAN          Urgent;
    UINTN32          DataLength;
    UINTN32          FragmentCount;
    EFI_TCP4_FRAGMENT_DATA  FragmentTable[1];
} EFI_TCP4_TRANSMIT_DATA;
    
```

Push If **TRUE**, data must be transmitted promptly, and the PUSH bit in the last TCP segment created will be set. If **FALSE**, data transmission may be delay to combine with data from subsequent **Transmit()**s for efficiency.

Urgent The data in the fragment table are urgent and urgent point is in effect if **TRUE**. Otherwise those data are NOT considered urgent.

DataLength Length of the data in the fragments.

FragmentCount Number of fragments.

FragmentTable A array of fragment descriptors. Type **EFI_TCP4_FRAGMENT_DATA** is defined above.

The EFI TCPv4 Protocol user must fill this data structure before sending a packet. The packet may contain multiple buffers in non-continuous memory locations.

Status Codes Returned

EFI_SUCCESS	The data has been queued for transmission.
EFI_NOT_STARTED	This EFI TCPv4 Protocol instance has not been configured.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	One or more of the following are TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token->CompletionToken.Event</i> is NULL. • <i>Token->Packet.TxData</i> is NULL. • <i>Token->Packet.FragmentCount</i> is zero. • <i>Token->Packet.DataLength</i> is not equal to the sum of fragment lengths.

EFI_ACCESS_DENIED	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • A transmit completion token with the same <i>Token->CompletionToken.Event</i> was already in the transmission queue. • The current instance is in <i>Tcp4StateClosed</i> state. • The current instance is a passive one and it is in <i>Tcp4StateListen</i> state. • User has called Close () to disconnect this connection.
EFI_NOT_READY	<p>The completion token could not be queued because the transmit queue is full.</p>
EFI_OUT_OF_RESOURCES	<p>Could not queue the transmit data because of resource shortage.</p>
EFI_NETWORK_UNREACHABLE	<p>There is no route to the destination network or address.</p>

EFI_TCP4_PROTOCOL.Receive()

Summary

Places an asynchronous receive request into the receiving queue.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_RECEIVE) (
    IN EFI_TCP4_PROTOCOL *This,
    IN EFI_TCP4_IO_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>Token</i>	Pointer to a token that is associated with the receive data descriptor. Type EFI_TCP4_IO_TOKEN is defined in EFI_TCP4_PROTOCOL.Transmit() .

Description

The **Receive()** function places a completion token into the receive packet queue. This function is always asynchronous. The caller must allocate the *Token->CompletionToken.Event* and the *FragmentBuffer* used to receive data. He also must fill the *DataLength* which represents the whole length of all *FragmentBuffer*. When the receive operation completes, the EFI TCPv4 Protocol driver updates the *Token->CompletionToken.Status* and *Token->Packet.RxData* fields and the *Token->CompletionToken.Event* is signaled. If got data the data and its length will be copy into the *FragmentTable*, in the same time the full length of received data will be recorded in the *DataLength* fields. Providing a proper notification function and context for the event will enable the user to receive the notification and receiving status. That notification function is guaranteed to not be re-entered.

Status Codes Returned

EFI_SUCCESS	The receive completion token was cached.
EFI_NOT_STARTED	This EFI TCPv4 Protocol instance has not been configured.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.

EFI_INVALID_PARAMETER	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token->CompletionToken.Event</i> is NULL. • <i>Token->Packet.RxData</i> is NULL. • <i>Token->Packet.RxData->DataLength</i> is 0. • The <i>Token->Packet.RxData->DataLength</i> is not the sum of all <i>FragmentBuffer</i> length in <i>FragmentTable</i>.
EFI_OUT_OF_RESOURCES	<p>The receive completion token could not be queued due to a lack of system resources (usually memory).</p>
EFI_DEVICE_ERROR	<p>An unexpected system or network error occurred. The EFI TCPv4 Protocol instance has been reset to startup defaults.</p>
EFI_ACCESS_DENIED	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • A receive completion token with the same <i>Token->CompletionToken.Event</i> was already in the receive queue. • The current instance is in <i>Tcp4StateClosed</i> state. • The current instance is a passive one and it is in <i>Tcp4StateListen</i> state. • User has called Close () to disconnect this connection.
EFI_CONNECTION_FIN	<p>The communication peer has closed the connection and there is no buffered data in the receive buffer of this instance.</p>
EFI_NOT_READY	<p>The receive request could not be queued because the receive queue is full.</p>

EFI_TCP4_PROTOCOL.Close()

Summary

Disconnecting a TCP connection gracefully or reset a TCP connection. This function is a nonblocking operation.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_CLOSE) (
    IN EFI_TCP4_PROTOCOL           *This,
    IN EFI_TCP4_CLOSE_TOKEN       *CloseToken
);
```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>CloseToken</i>	Pointer to the close token to return when operation finishes. Type EFI_TCP4_CLOSE_TOKEN is defined in “Related Definition” below.

Related Definitions

```
//
*****
// EFI_TCP4_CLOSE_TOKEN
//
*****
typedef struct {
    EFI_TCP4_COMPLETION_TOKEN    CompletionToken;
    BOOLEAN                      AbortOnClose;
} EFI_TCP4_CLOSE_TOKEN;
```

<i>Status</i>	When close finishes or meets any unexpected error it will be set to one of the following values: EFI_SUCCESS . The close operation completes successfully. EFI_ABORTED . User called configure with NULL without close stopping.
<i>AbortOnClose</i>	Abort the TCP connection on close instead of the standard TCP close process when it is set to TRUE . This option can be used to satisfy a fast disconnect.

Description

Initiate an asynchronous close token to TCP driver. After **Close ()** is called, any buffered transmission data will be sent by TCP driver and the current instance will have a graceful close working flow described as RFC 793 if *AbortOnClose* is set to **FALSE**, otherwise, a reset packet will be sent by TCP driver to fast disconnect this connection. When the close operation completes

successfully the TCP instance is in **Tcp4StateClosed** state, all pending asynchronous operation is signaled and any buffers used for TCP network traffic is flushed.

Status Codes Returned

EFI_SUCCESS	The Close () is called successfully.
EFI_NOT_STARTED	This EFI TCPv4 Protocol instance has not been configured.
EFI_ACCESS_DENIED	One or more of the following are TRUE : <ul style="list-style-type: none"> • Configure () has been called with <i>TcpConfigData</i> set to NULL and this function has not returned. • Previous Close () call on this instance has not finished.
EFI_INVALID_PARAMETER	One or more of the following are TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>CloseToken</i> is NULL. • <i>CloseToken->CompletionToken.Event</i> is NULL.
EFI_OUT_OF_RESOURCES	Could not allocate enough resource to finish the operation.
EFI_DEVICE_ERROR	Any unexpected and not belonged to above category error.

EFI_TCP4_PROTOCOL.Cancel()

Summary

Abort an asynchronous connection, listen, transmission or receive request.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_TCP4_CANCEL) (
    IN EFI_TCP4_PROTOCOL          *This,
    IN EFI_TCP4_COMPLETION_TOKEN *Token    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_TCP4_PROTOCOL instance.
<i>Token</i>	Pointer to a token that has been issued by EFI_TCP4_PROTOCOL.Connect() , EFI_TCP4_PROTOCOL.Accept() , EFI_TCP4_PROTOCOL.Transmit() or EFI_TCP4_PROTOCOL.Receive() . If NULL , all pending tokens issued by above four functions will be aborted. Type EFI_TCP4_COMPLETION_TOKEN is defined in EFI_TCP4_PROTOCOL.Connect() .

Description

The **Cancel()** function aborts a pending connection, listen, transmit or receive request. If *Token* is not **NULL** and the token is in the connection, listen, transmission or receive queue when it is being cancelled, its *Token->Status* will be set to **EFI_ABORTED** and then *Token->Event* will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, **EFI_NOT_FOUND** is returned. If *Token* is **NULL** all asynchronous token issued by **Connect()**, **Accept()**, **Transmit()** and **Receive()** will be aborted.

Status Codes Returned

EFI_SUCCESS	The asynchronous I/O request is aborted and <i>Token->Event</i> is signaled.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_STARTED	This instance hasn't been configured.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) hasn't finished yet.
EFI_NOT_FOUND	The asynchronous I/O request isn't found in the transmission or receive queue. It has either completed or wasn't issued by Transmit() and Receive() .

EFI_TCP4_PROTOCOL.Poll()

Summary

Poll to receive incoming data and transmit outgoing segments.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_TCP4_POLL) (
    IN EFI_TCP4_PROTOCOL          *This
);
```

Parameters

This Pointer to the **EFI_TCP4_PROTOCOL** instance.

Description

The **Poll()** function increases the rate that data is moved between the network and application and can be called when the TCP instance is created successfully. Its use is optional.

In some implementations, the periodical timer in the MNP driver may not poll the underlying communications device fast enough to avoid drop packets. Drivers and applications that are experiencing packet loss should try calling the **Poll()** function in a high frequency.

Status Codes Returned

EFI_SUCCESS	Incoming or outgoing data was processed.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_DEVICE_ERROR	An unexpected system or network error occurred.
EFI_NOT_READY	No incoming or outgoing data is processed.
EFI_TIMEOUT	Data was dropped out of the transmission or receive queue. Consider increasing the polling rate.

24.2 EFI IPv4 Protocol

This section defines the EFI IPv4 (Internet Protocol version 4) Protocol interface. It is split into the following three main sections:

- EFI IPv4 Service Binding Protocol
- EFI IPv4 Variable
- EFI IPv4 Protocol

The EFI IPv4 Protocol provides basic network IPv4 packet I/O services, which includes support for a subset of the Internet Control Message Protocol (ICMP) and may include support for the Internet Group Management Protocol (IGMP).

EFI_IP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI IPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI IPv4 Protocol driver and to create and destroy instances of the EFI IPv4 Protocol child protocol driver that can use the underlying communications device.

GUID

```
#define EFI_IP4_SERVICE_BINDING_PROTOCOL_GUID \
{0xc51711e7, 0xb4bf, 0x404a, 0xbf, 0xb8, 0x0a, 0x04, 0x8e, 0xf1, 0xff, 0xe4}
```

Description

A network application that requires basic IPv4 I/O services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an EFI IPv4 Service Binding Protocol GUID. Each device with a published EFI IPv4 Service Binding Protocol GUID supports the EFI IPv4 Protocol and may be available for use.

After a successful call to the `EFI_IP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI IPv4 Protocol driver is in an unconfigured state; it is not ready to send and receive data packets.

Before a network application terminates execution, every successful call to the `EFI_IP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_IP4_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

EFI IPv4 Variable

Summary

An accurate list of all of the IPv4 addresses and subnet masks that are currently being used must be maintained for each communications device. This list is stored as a volatile variable so it can be publicly read.

Vendor GUID

```
gEfiIp4ServiceBindingProtocolGuid
```

Variable Name

```
CHAR16 *MacAddress;
```

Attribute

```
EFI_VARIABLE_BOOTSERVICE_ACCESS
```

Description

`MacAddress` is the string of printed hexadecimal value for each byte in hardware address (of type `EFI_MAC_ADDRESS`) of the communications device. No 0x or h is included in each hex value. The length of `MacAddress` is determined by the hardware address length. For example: if the

hardware address is 00-07-E9-51-60-D7, and address length is 6 bytes, then **MacAddress** is `Çk"0007E95160D7"`.

Related Definitions

```

//*****
// EFI_IP4_VARIABLE_DATA_
//*****
typedef struct {
    EFI_HANDLE          DriverHandle;
    UINT32              AddressCount;
    EFI_IP4_ADDRESS_PAIR AddressPairs[1];
} EFI_IP4_VARIABLE_DATA;

```

<i>DriverHandle</i>	The handle of the driver that creates this entry.
<i>AddressCount</i>	The number of IPv4 address and subnet mask pairs that follow this data structure.
<i>AddressPairs</i>	List of IPv4 address and subnet mask pairs that are currently in use. Type EFI_IP4_ADDRESS_PAIR is defined below.

```

//*****
// EFI_IP4_ADDRESS_PAIR
//*****
typedef struct{
    EFI_HANDLE          InstanceHandle;
    EFI_IPv4_ADDRESS    Ip4Address;
    EFI_IPv4_ADDRESS    SubnetMask;
} EFI_IP4_ADDRESS_PAIR;

```

<i>InstanceHandle;</i>	The EFI IPv4 Protocol instance handle that is using this address/subnetmask pair.
<i>Ip4Address</i>	IPv4 address in network byte order.
<i>SubnetMask</i>	Subnet mask in network byte order.

EFI_IP4_PROTOCOL

Summary

The EFI IPv4 Protocol implements a simple packet-oriented interface that can be used by drivers, daemons, and applications to transmit and receive network packets.

GUID

```
#define EFI_IP4_PROTOCOL_GUID \
{0x41d94cd2,0x35b6,0x455a,0x82,0x58,0xd4,0xe5,0x13,0x34,0xaa,
0xdd}
```

Protocol Interface Structure

```
typedef struct _EFI_IP4_PROTOCOL {
    EFI_IP4_GET_MODE_DATA    GetModeData;
    EFI_IP4_CONFIGURE        Configure;
    EFI_IP4_GROUPS            Groups;
    EFI_IP4_ROUTES            Routes;
    EFI_IP4_TRANSMIT          Transmit;
    EFI_IP4_RECEIVE           Receive;
    EFI_IP4_CANCEL            Cancel;
    EFI_IP4_POLL              Poll;
} EFI_IP4_PROTOCOL;
```

Parameters

<i>GetModeData</i>	Gets the current operational settings for this instance of the EFI IPv4 Protocol driver. See the GetModeData () function description.
<i>Configure</i>	Changes or resets the operational settings for the EFI IPv4 Protocol. See the Configure () function description.
<i>Groups</i>	Joins and leaves multicast groups. See the Groups () function description.
<i>Routes</i>	Adds and deletes routing table entries. See the Routes () function description.
<i>Transmit</i>	Places outgoing data packets into the transmit queue. See the Transmit () function description.
<i>Receive</i>	Places a receiving request into the receiving queue. See the Receive () function description.
<i>Cancel</i>	Aborts a pending transmit or receive request. See the Cancel () function description.
<i>Poll</i>	Polls for incoming data packets and processes outgoing data packets. See the Poll () function description.

Description

The **EFI_IP4_PROTOCOL** defines a set of simple IPv4, ICMPv4, and IGMPv4 services that can be used by any network protocol driver, daemon, or application to transmit and receive IPv4 data packets.

Note: All the IPv4 addresses that are described in **EFI_IP4_PROTOCOL** are stored in network byte order. Both incoming and outgoing IP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

EFI_IP4_PROTOCOL.GetModeData()

Summary

Gets the current operational settings for this instance of the EFI IPv4 Protocol driver.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_IP4_GET_MODE_DATA) (
    IN EFI_IP4_PROTOCOL                *This,
    OUT EFI_IP4_MODE_DATA              *Ip4ModeData    OPTIONAL,
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,
    OUT EFI_SIMPLE_NETWORK_MODE       *SnpModeData    OPTIONAL
);

```

Parameters

<i>This</i>	Pointer to the EFI_IP4_PROTOCOL instance.
<i>Ip4ModeData</i>	Pointer to the EFI IPv4 Protocol mode data structure. Type EFI_IP4_MODE_DATA is defined in “Related Definitions” below.
<i>MnpConfigData</i>	Pointer to the managed network configuration data structure. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData() .
<i>SnpData</i>	Pointer to the simple network mode data structure. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL .

Description

The **GetModeData()** function returns the current operational mode data for this driver instance. The data fields in **EFI_IP4_MODE_DATA** are read only. This function is used optionally to retrieve the operational mode data of underlying networks or drivers.

Related Definitions

```

//*****
// EFI_IP4_MODE_DATA
//*****
typedef struct {
    BOOLEAN                IsStarted;
    EFI_IP4_CONFIG_DATA    ConfigData;
    BOOLEAN                IsConfigured;
    UINT32                 GroupCount;
    EFI_IPv4_ADDRESS       *GroupTable;
    UINT32                 RouteCount;
    EFI_IP4_ROUTE_TABLE    *RouteTable;
    UINT32                 IcmpTypeCount;
    EFI_IP4_ICMP_TYPE       *IcmpTypeList;
} EFI_IP4_MODE_DATA;

```

<i>IsStarted</i>	Set to TRUE after this EFI IPv4 Protocol instance has been successfully configured with operational parameters by calling the Configure () interface when EFI IPv4 Protocol instance is stopped. All other fields in this structure are undefined until this field is TRUE . Set to FALSE when the instance's operational parameter has been reset.
<i>ConfigData</i>	Current configuration settings. Undefined until <i>IsStarted</i> is TRUE . Type EFI_IP4_CONFIG_DATA is defined below.
<i>IsConfigured</i>	Set to TRUE when the EFI IPv4 Protocol instance has a station address and subnet mask. If it is using the default address, the default address has been acquired. Set to FALSE when the EFI IPv4 Protocol driver is not configured.
<i>GroupCount</i>	Number of joined multicast groups. Undefined until <i>IsConfigured</i> is TRUE .
<i>GroupTable</i>	List of joined multicast group addresses. Undefined until <i>IsConfigured</i> is TRUE .
<i>RouteCount</i>	Number of entries in the routing table. Undefined until <i>IsConfigured</i> is TRUE .
<i>RouteTable</i>	Routing table entries. Undefined until <i>IsConfigured</i> is TRUE . Type EFI_IP4_ROUTE_TABLE is defined below.
<i>IcmpTypeCount</i>	Number of entries in the supported ICMP types list.
<i>IcmpTypeList</i>	Array of ICMP types and codes that are supported by this EFI IPv4 Protocol driver. Type EFI_IP4_ICMP_TYPE is defined below.

The **EFI_IP4_MODE_DATA** structure describes the operational state of this IPv4 interface.


```

//*****
// EFI_IP4_CONFIG_DATA
//*****
typedef struct {
    UINT8           DefaultProtocol;
    BOOLEAN         AcceptAnyProtocol;
    BOOLEAN         AcceptIcmpErrors;
    BOOLEAN         AcceptBroadcast;
    BOOLEAN         AcceptPromiscuous;
    BOOLEAN         UseDefaultAddress;
    EFI_IPv4_ADDRESS StationAddress;
    EFI_IPv4_ADDRESS SubnetMask;
    UINT8           TypeOfService;
    UINT8           TimeToLive;
    BOOLEAN         DoNotFragment;
    BOOLEAN         RawData;
    UINT32          ReceiveTimeout;
    UINT32          TransmitTimeout;
} EFI_IP4_CONFIG_DATA;

```

<i>DefaultProtocol</i>	The default IPv4 protocol packets to send and receive. Ignored when <i>AcceptPromiscuous</i> is TRUE . An updated list of protocol numbers can be found at http://www.iana.org/assignments/protocol-numbers .
<i>AcceptAnyProtocol</i>	Set to TRUE to receive all IPv4 packets that get through the receive filters. Set to FALSE to receive only the <i>DefaultProtocol</i> IPv4 packets that get through the receive filters. Ignored when <i>AcceptPromiscuous</i> is TRUE .
<i>AcceptIcmpErrors</i>	Set to TRUE to receive ICMP error report packets. Ignored when <i>AcceptPromiscuous</i> or <i>AcceptAnyProtocol</i> is TRUE .
<i>AcceptBroadcast</i>	Set to TRUE to receive broadcast IPv4 packets. Ignored when <i>AcceptPromiscuous</i> is TRUE . Set to FALSE to stop receiving broadcast IPv4 packets.
<i>AcceptPromiscuous</i>	Set to TRUE to receive all IPv4 packets that are sent to any hardware address or any protocol address. Set to FALSE to stop receiving all promiscuous IPv4 packets.
<i>UseDefaultAddress</i>	Set to TRUE to use the default IPv4 address and default routing table. If the default IPv4 address is not available yet, then the EFI IPv4 Protocol driver will use EFI_IP4_CONFIG_PROTOCOL to retrieve the IPv4 address and subnet information. (This field can be set and changed only when the EFI IPv4 driver is transitioning from the stopped to the started states.)
<i>StationAddress</i>	The station IPv4 address that will be assigned to this EFI IPv4Protocol instance. The EFI IPv4 Protocol driver will deliver

only incoming IPv4 packets whose destination matches this IPv4 address exactly. Address 0.0.0.0 is also accepted as a special case in which incoming packets destined to any station IP address are always delivered. When **EFI_IP4_CONFIG_DATA** is used in **Configure ()**, it is ignored if *UseDefaultAddress* is **TRUE**; When **EFI_IP4_CONFIG_DATA** is used in **GetModeData ()**, it contains the default address if *UseDefaultAddress* is **TRUE** and the default address has been acquired.

<i>SubnetMask</i>	The subnet address mask that is associated with the station address. When EFI_IP4_CONFIG_DATA is used in Configure () , it is ignored if <i>UseDefaultAddress</i> is TRUE ; When EFI_IP4_CONFIG_DATA is used in GetModeData () , it contains the default subnet mask if <i>UseDefaultAddress</i> is TRUE and the default address has been acquired.
<i>TypeOfService</i>	<i>TypeOfService</i> field in transmitted IPv4 packets.
<i>TimeToLive</i>	<i>TimeToLive</i> field in transmitted IPv4 packets.
<i>DoNotFragment</i>	State of the <i>DoNotFragment</i> bit in transmitted IPv4 packets.
<i>RawData</i>	Set to TRUE to send and receive unformatted packets. The other IPv4 receive filters are still applied. Fragmentation is disabled for <i>RawData</i> mode. NOTE: Unformatted packets include the IP header and payload. The media header is appended automatically for outgoing packets by underlying network drivers.
<i>ReceiveTimeout</i>	The timer timeout value (number of microseconds) for the receive timeout event to be associated with each assembled packet. Zero means do not drop assembled packets.
<i>TransmitTimeout</i>	The timer timeout value (number of microseconds) for the transmit timeout event to be associated with each outgoing packet. Zero means do not drop outgoing packets.

The **EFI_IP4_CONFIG_DATA** structure is used to report and change IPv4 session parameters.

```

//*****
// EFI_IP4_ROUTE_TABLE
//*****
typedef struct {
    EFI_IPv4_ADDRESS    SubnetAddress;
    EFI_IPv4_ADDRESS    SubnetMask;
    EFI_IPv4_ADDRESS    GatewayAddress;
} EFI_IP4_ROUTE_TABLE;
    
```

<i>SubnetAddress</i>	The subnet address to be routed.
<i>SubnetMask</i>	The subnet mask. If (<i>DestinationAddress & SubnetMask == SubnetAddress</i>), then the packet is to be directed to the <i>GatewayAddress</i> .

GatewayAddress The IPv4 address of the gateway that redirects packets to this subnet. If the IPv4 address is 0.0.0.0, then packets to this subnet are not redirected.

EFI_IP4_ROUTE_TABLE is the entry structure that is used in routing tables.

```

//*****
// EFI_IP4_ICMP_TYPE
//*****
typedef struct {
    UINT8          Type;
    UINT8          Code;
} EFI_IP4_ICMP_TYPE
    
```

Type The type of ICMP message. See RFC 792 and RFC 950.

Code The code of the ICMP message, which further describes the different ICMP message formats under the same *Type*. See RFC 792 and RFC 950.

EFI_IP4_ICMP_TYPE is used to describe those ICMP messages that are supported by this EFI IPv4 Protocol driver.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_OUT_OF_RESOURCES	The required mode data could not be allocated.

EFI_IP4_PROTOCOL.Configure()

Summary

Assigns an IPv4 address and subnet mask to this EFI IPv4 Protocol driver instance.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_CONFIGURE) (
    IN EFI_IP4_PROTOCOL           *This,
    IN EFI_IP4_CONFIG_DATA       *IpConfigData    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_PROTOCOL instance.
<i>IpConfigData</i>	Pointer to the EFI IPv4 Protocol configuration data structure. Type EFI_IP4_CONFIG_DATA is defined in EFI_IP4_PROTOCOL.GetModeData() .

Description

The **Configure()** function is used to set, change, or reset the operational parameters and filter settings for this EFI IPv4 Protocol instance. Until these parameters have been set, no network traffic can be sent or received by this instance. Once the parameters have been reset (by calling this function with *IpConfigData* set to **NULL**), no more traffic can be sent or received until these parameters have been set again. Each EFI IPv4 Protocol instance can be started and stopped independently of each other by enabling or disabling their receive filter settings with the **Configure()** function.

When *IpConfigData.UseDefaultAddress* is set to **FALSE**, the new station address will be appended as an alias address into the addresses list in the EFI IPv4 Protocol driver. While set to **TRUE**, **Configure()** will trigger the **EFI_IP4_CONFIG_PROTOCOL** to retrieve the default IPv4 address if it is not available yet. Clients could frequently call **GetModeData()** to check the status to ensure that the default IPv4 address is ready.

If operational parameters are reset or changed, any pending transmit and receive requests will be cancelled. Their completion token status will be set to **EFI_ABORTED** and their events will be signaled.

Status Codes Returned

EFI_SUCCESS	The driver instance was successfully opened.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.

EFI_INVALID_PARAMETER	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>IpConfigData.StationAddress</i> is not a unicast IPv4 address. • <i>IpConfigData.SubnetMask</i> is not a valid IPv4 subnet mask.
EFI_UNSUPPORTED	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • A configuration protocol (DHCP, BOOTP, RARP, etc.) could not be located when clients choose to use the default IPv4 address. This EFI IPv4 Protocol implementation does not support this requested filter or timeout setting.
EFI_OUT_OF_RESOURCES	<p>The EFI IPv4 Protocol driver instance data could not be allocated.</p>
EFI_ALREADY_STARTED	<p>The interface is already open and must be stopped before the IPv4 address or subnet mask can be changed. The interface must also be stopped when switching to/from raw packet mode.</p>
EFI_DEVICE_ERROR	<p>An unexpected system or network error occurred. The EFI IPv4 Protocol driver instance is not opened.</p>

EFI_IP4_PROTOCOL.Groups()

Summary

Joins and leaves multicast groups.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_GROUPS) (
    IN EFI_IP4_PROTOCOL *This,
    IN BOOLEAN          JoinFlag,
    IN EFI_IPv4_ADDRESS *GroupAddress OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_PROTOCOL instance.
<i>JoinFlag</i>	Set to TRUE to join the multicast group session and FALSE to leave.
<i>GroupAddress</i>	Pointer to the IPv4 multicast address.

Description

The **Groups ()** function is used to join and leave multicast group sessions. Joining a group will enable reception of matching multicast packets. Leaving a group will disable the multicast packet reception.

If *JoinFlag* is **FALSE** and *GroupAddress* is **NULL**, all joined groups will be left.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_INVALID_PARAMETER	One or more of the following is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>JoinFlag</i> is TRUE and <i>GroupAddress</i> is NULL. • <i>GroupAddress</i> is not NULL and * <i>GroupAddress</i> is not a multicast IPv4 address.
EFI_NOT_STARTED	This instance has not been started.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_OUT_OF_RESOURCES	System resources could not be allocated.
EFI_UNSUPPORTED	This EFI IPv4 Protocol implementation does not support multicast groups.
EFI_ALREADY_STARTED	The group address is already in the group table (when <i>JoinFlag</i> is TRUE).
EFI_NOT_FOUND	The group address is not in the group table (when <i>JoinFlag</i> is FALSE).

EFI_DEVICE_ERROR	An unexpected system or network error occurred.
------------------	---

EFI_IP4_PROTOCOL.Routes()

Summary

Adds and deletes routing table entries.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_ROUTES) (
    IN EFI_IP4_PROTOCOL    *This,
    IN BOOLEAN             DeleteRoute,
    IN EFI_IPv4_ADDRESS    *SubnetAddress,
    IN EFI_IPv4_ADDRESS    *SubnetMask,
    IN EFI_IPv4_ADDRESS    *GatewayAddress
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_PROTOCOL instance.
<i>DeleteRoute</i>	Set to TRUE to delete this route from the routing table. Set to FALSE to add this route to the routing table. <i>SubnetAddress</i> and <i>SubnetMask</i> are used as the key to each route entry.
<i>SubnetAddress</i>	The address of the subnet that needs to be routed.
<i>SubnetMask</i>	The subnet mask of <i>SubnetAddress</i> .
<i>GatewayAddress</i>	The unicast gateway IPv4 address for this route.

Description

The **Routes()** function adds a route to or deletes a route from the routing table.

Routes are determined by comparing the *SubnetAddress* with the destination IPv4 address arithmetically **AND**-ed with the *SubnetMask*. The gateway address must be on the same subnet as the configured station address.

The default route is added with *SubnetAddress* and *SubnetMask* both set to 0.0.0.0. The default route matches all destination IPv4 addresses that do not match any other routes.

A *GatewayAddress* that is zero is a nonroute. Packets are sent to the destination IP address if it can be found in the ARP cache or on the local subnet. One automatic nonroute entry will be inserted into the routing table for outgoing packets that are addressed to a local subnet (gateway address of 0.0.0.0).

Each EFI IPv4 Protocol instance has its own independent routing table. Those EFI IPv4 Protocol instances that use the default IPv4 address will also have copies of the routing table that was provided by the **EFI_IP4_CONFIG_PROTOCOL**, and these copies will be updated whenever the EIF IPv4 Protocol driver reconfigures its instances. As a result, client modification to the routing table will be lost.

Note: *There is no way to set up routes to other network interface cards because each network interface card has its own independent network stack that shares information only through **EFI IPv4 variable**.*

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_NOT_STARTED	The driver instance has not been started.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>SubnetAddress</i> is NULL. • <i>SubnetMask</i> is NULL. • <i>GatewayAddress</i> is NULL. • <i>*SubnetAddress</i> is not a valid subnet address. • <i>*SubnetMask</i> is not a valid subnet mask. • <i>*GatewayAddress</i> is not a valid unicast IPv4 address.
EFI_OUT_OF_RESOURCES	Could not add the entry to the routing table.
EFI_NOT_FOUND	This route is not in the routing table (when <i>DeleteRoute</i> is TRUE).
EFI_ACCESS_DENIED	The route is already defined in the routing table (when <i>DeleteRoute</i> is FALSE).

EFI_IP4_PROTOCOL.Transmit()

Summary

Places outgoing data packets into the transmit queue.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_IP4_TRANSMIT) (
    IN EFI_IP4_PROTOCOL          *This,
    IN EFI_IP4_COMPLETION_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_PROTOCOL instance.
<i>Token</i>	Pointer to the transmit token. Type EFI_IP4_COMPLETION_TOKEN is defined in “Related Definitions” below.

Description

The **Transmit()** function places a sending request in the transmit queue of this EFI IPv4 Protocol instance. Whenever the packet in the token is sent out or some errors occur, the event in the token will be signaled and the status is updated.

Related Definitions

```

//*****
// EFI_IP4_COMPLETION_TOKEN
//*****
typedef struct {
    EFI_EVENT          Event;
    EFI_STATUS        Status;
    union {
        EFI_IP4_RECEIVE_DATA *RxData;
        EFI_IP4_TRANSMIT_DATA *TxData;
    }
} EFI_IP4_COMPLETION_TOKEN;
```

<i>Event</i>	This <i>Event</i> will be signaled after the <i>Status</i> field is updated by the EFI IPv4 Protocol driver. The type of <i>Event</i> must be EFI_NOTIFY_SIGNAL . The Task Priority Level (TPL) of <i>Event</i> must be lower than or equal to TPL_CALLBACK .
<i>Status</i>	Will be set to one of the following values: EFI_SUCCESS . The receive or transmit completed successfully. EFI_ABORTED . The receive or transmit was aborted.

EFI_TIMEOUT. The transmit timeout expired.

EFI_ICMP_ERROR. An ICMP error packet was received.

EFI_DEVICE_ERROR. An unexpected system or network error occurred.

RxData When this token is used for receiving, *RxData* is a pointer to the **EFI_IP4_RECEIVE_DATA**. Type **EFI_IP4_RECEIVE_DATA** is defined below.

TxData When this token is used for transmitting, *TxData* is a pointer to the **EFI_IP4_TRANSMIT_DATA**. Type **EFI_IP4_TRANSMIT_DATA** is defined below.

EFI_IP4_COMPLETION_TOKEN structures are used for both transmit and receive operations.

When the structure is used for transmitting, the *Event* and *TxData* fields must be filled in by the EFI IPv4 Protocol client. After the transmit operation completes, EFI IPv4 Protocol updates the *Status* field and the *Event* is signaled.

When the structure is used for receiving, only the **Event** field must be filled in by the EFI IPv4 Protocol client. After a packet is received, the EFI IPv4 Protocol fills in the **RxData** and **Status** fields and the **Event** is signaled. If the packet is an ICMP error message, the **Status** is set to **EFI_ICMP_ERROR**, and the packet is delivered up as usual. The protocol from the IP head in the ICMP error message is used to de-multiplex the packet.

```

//*****
// EFI_IP4_RECEIVE_DATA
//*****
typedef struct {
    EFI_TIME                TimeStamp;
    EFI_EVENT               RecycleSignal;
    UINT32                  HeaderLength;
    EFI_IP4_HEADER          *Header;
    UINT32                  OptionsLength;
    VOID                    *Options;
    UINT32                  DataLength;
    UINT32                  FragmentCount;
    EFI_IP4_FRAGMENT_DATA  FragmentTable[1];
} EFI_IP4_RECEIVE_DATA;

```

TimeStamp Time when the EFI IPv4 Protocol driver accepted the packet.

RecycleSignal After this event is signaled, the receive data structure is released and must not be referenced.

HeaderLength Length of the IPv4 packet header. Zero if *ConfigData.RawData* is **TRUE**.

Header Pointer to the IPv4 packet header. If the IPv4 packet was fragmented, this argument is a pointer to the header in the first fragment. **NULL** if *ConfigData.RawData* is **TRUE**. Type **EFI_IP4_HEADER** is defined below.

<i>OptionsLength</i>	Length of the IPv4 packet header options. May be zero.
<i>Options</i>	Pointer to the IPv4 packet header options. If the IPv4 packet was fragmented, this argument is a pointer to the options in the first fragment. May be NULL .
<i>DataLength</i>	Sum of the lengths of IPv4 packet buffers in <i>FragmentTable</i> . May be zero.
<i>FragmentCount</i>	Number of IPv4 payload (or raw) fragments. If <i>ConfigData.RawData</i> is TRUE , this count is the number of raw IPv4 fragments received so far. May be zero.
<i>FragmentTable</i>	Array of payload (or raw) fragment lengths and buffer pointers. If <i>ConfigData.RawData</i> is TRUE , each buffer points to a raw IPv4 fragment and thus IPv4 header and options are included in each buffer. Otherwise, IPv4 headers and options are not included in these buffers. Type EFI_IP4_FRAGMENT_DATA is defined below.

The EFI IPv4 Protocol receive data structure is filled in when IPv4 packets have been assembled (or when raw packets have been received). In the case of IPv4 packet assembly, the individual packet fragments are only verified and are not reorganized into a single linear buffer.

The *FragmentTable* contains a sorted list of zero or more packet fragment descriptors. The referenced packet fragments may not be in contiguous memory locations.

```

//*****
// EFI_IP4_HEADER
//*****
#pragma pack(1)
typedef struct {
    UINT8           HeaderLength:4;
    UINT8           Version:4;
    UINT8           TypeOfService;
    UINT16          TotalLength;
    UINT16          Identification;
    UINT16          Fragmentation;
    UINT8           TimeToLive;
    UINT8           Protocol;
    UINT16          Checksum;
    EFI_IPv4_ADDRESS SourceAddress;
    EFI_IPv4_ADDRESS DestinationAddress;
} EFI_IP4_HEADER;
#pragma pack()

```

The fields in the IPv4 header structure are defined in the Internet Protocol version 4 specification, which can be found at: <ftp://ftp.rfc-editor.org/in-notes/rfc791.txt>.

```

//*****
// EFI_IP4_FRAGMENT_DATA
//*****
typedef struct {
    UINT32      FragmentLength;
    VOID        *FragmentBuffer;
} EFI_IP4_FRAGMENT_DATA;

```

FragmentLength Length of fragment data. This field may not be set to zero.

FragmentBuffer Pointer to fragment data. This field may not be set to **NULL**.

The **EFI_IP4_FRAGMENT_DATA** structure describes the location and length of the IPv4 packet fragment to transmit or that has been received.

```

//*****
// EFI_IP4_TRANSMIT_DATA
//*****
typedef struct {
    EFI_IPv4_ADDRESS      DestinationAddress;
    EFI_IP4_OVERRIDE_DATA *OverrideData;
    UINT32                OptionsLength;
    VOID                  *OptionsBuffer;
    UINT32                TotalDataLength;
    UINT32                FragmentCount;
    EFI_IP4_FRAGMENT_DATA FragmentTable[1];
} EFI_IP4_TRANSMIT_DATA;

```

DestinationAddress

The destination IPv4 address. Ignored if *RawData* is **TRUE**.

OverrideData

If not **NULL**, the IPv4 transmission control override data. Ignored if *RawData* is **TRUE**. Type **EFI_IP4_OVERRIDE_DATA** is defined below.

OptionsLength

Length of the IPv4 header options data. Must be zero if the IPv4 driver does not support IPv4 options. Ignored if *RawData* is **TRUE**.

OptionsBuffer

Pointer to the IPv4 header options data. Ignored if *OptionsLength* is zero. Ignored if *RawData* is **TRUE**.

TotalDataLength

Total length of the *FragmentTable* data to transmit.

FragmentCount

Number of entries in the fragment data table.

FragmentTable

Start of the fragment data table. Type **EFI_IP4_FRAGMENT_DATA** is defined above.

The **EFI_IP4_TRANSMIT_DATA** structure describes a possibly fragmented packet to be transmitted.

```

//*****
// EFI_IP4_OVERRIDE_DATA
//*****
typedef struct {
    EFI_IPv4_ADDRESS    SourceAddress;
    EFI_IPv4_ADDRESS    GatewayAddress;
    UINT8               Protocol;
    UINT8               TypeOfService;
    UINT8               TimeToLive;
    BOOLEAN              DoNotFragment;
} EFI_IP4_OVERRIDE_DATA;

```

SourceAddress Source address override.

GatewayAddress Gateway address to override the one selected from the routing table. This address must be on the same subnet as this station address. If set to 0.0.0.0, the gateway address selected from routing table will not be overridden.

Protocol Protocol type override.

TypeOfService Type-of-service override.

TimeToLive Time-to-live override.

DoNotFragment Do-not-fragment override.

The information and flags in the override data structure will override default parameters or settings for one **Transmit()** function call.

Status Codes Returned

EFI_SUCCESS	The data has been queued for transmission.
EFI_NOT_STARTED	This instance has not been started.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.

<p>EFI_INVALID_PARAMETER</p>	<p>One or more of the following is TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.Event</i> is NULL • <i>Token.Packet.TxData</i> is NULL. • <i>Token.Packet.TxData.OverrideData.GatewayAddress</i> in the override data structure is not a unicast IPv4 address if <i>OverrideData</i> is not NULL. • <i>Token.Packet.TxData.OverrideData.SourceAddress</i> is not a unicast IPv4 address if <i>OverrideData</i> is not NULL. • <i>Token.Packet.OptionsLength</i> is not zero and <i>Token.Packet.OptionsBuffer</i> is NULL. • <i>Token.Packet.FragmentCount</i> is zero. • One or more of the <i>Token.Packet.TxData.FragmentTable[] . FragmentLength</i> fields is zero. • One or more of the <i>Token.Packet.TxData.FragmentTable[] . FragmentBuffer</i> fields is NULL. • <i>Token.Packet.TxData.TotalDataLength</i> is zero or not equal to the sum of fragment lengths. • The IP header in <i>FragmentTable</i> is not a well-formed header when <i>RawData</i> is TRUE.
<p>EFI_ACCESS_DENIED</p>	<p>The transmit completion token with the same <i>Token.Event</i> was already in the transmit queue.</p>
<p>EFI_NOT_READY</p>	<p>The completion token could not be queued because the transmit queue is full.</p>
<p>EFI_NOT_FOUND</p>	<p>Not route is found to destination address.</p>
<p>EFI_OUT_OF_RESOURCES</p>	<p>Could not queue the transmit data.</p>
<p>EFI_BUFFER_TOO_SMALL</p>	<p><i>Token.Packet.TxData.TotalDataLength</i> is too short to transmit.</p>
<p>EFI_BAD_BUFFER_SIZE</p>	<p>The length of the IPv4 header + option length + total data length is greater than MTU (or greater than the maximum packet size if <i>Token.Packet.TxData.OverrideData.DoNotFragment</i> is TRUE.)</p>

EFI_IP4_PROTOCOL.Receive()

Summary

Places a receiving request into the receiving queue.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_RECEIVE) (
    IN EFI_IP4_PROTOCOL          *This,
    IN EFI_IP4_COMPLETION_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_PROTOCOL instance.
<i>Token</i>	Pointer to a token that is associated with the receive data descriptor. Type EFI_IP4_COMPLETION_TOKEN is defined in “Related Definitions” of above Transmit() .

Description

The **Receive()** function places a completion token into the receive packet queue. This function is always asynchronous.

The *Token.Event* field in the completion token must be filled in by the caller and cannot be **NULL**. When the receive operation completes, the EFI IPv4 Protocol driver updates the *Token.Status* and *Token.Packet.RxData* fields and the *Token.Event* is signaled.

Status Codes Returned

EFI_SUCCESS	The receive completion token was cached.
EFI_NOT_STARTED	This EFI IPv4 Protocol instance has not been started.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.Event</i> is NULL.
EFI_OUT_OF_RESOURCES	The receive completion token could not be queued due to a lack of system resources (usually memory).
EFI_DEVICE_ERROR	An unexpected system or network error occurred. The EFI IPv4 Protocol instance has been reset to startup defaults.
EFI_ACCESS_DENIED	The receive completion token with the same <i>Token.Event</i> was already in the receive queue.
EFI_NOT_READY	The receive request could not be queued because the receive queue is full.

EFI_ICMP_ERROR	An ICMP error packet was received.
----------------	------------------------------------

EFI_IP4_PROTOCOL.Cancel()

Summary

Abort an asynchronous transmit or receive request.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_IP4_CANCEL) (
    IN EFI_IP4_PROTOCOL           *This,
    IN EFI_IP4_COMPLETION_TOKEN  *Token    OPTIONAL
);
```

Parameters

This Pointer to the **EFI_IP4_PROTOCOL** instance.

Token Pointer to a token that has been issued by **EFI_IP4_PROTOCOL.Transmit()** or **EFI_IP4_PROTOCOL.Receive()**. If **NULL**, all pending tokens are aborted. Type **EFI_IP4_COMPLETION_TOKEN** is defined in **EFI_IP4_PROTOCOL.Transmit()**.

Description

The **Cancel()** function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, *Token->Status* will be set to **EFI_ABORTED** and then *Token->Event* will be signaled. If the token is not in one of the queues, which usually means the asynchronous operation has completed, this function will not signal the token and **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	The asynchronous I/O request was aborted and <i>Token->Event</i> was signaled. When <i>Token</i> is NULL , all pending requests were aborted and their events were signaled.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_STARTED	This instance has not been started.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_NOT_FOUND	When <i>Token</i> is not NULL , the asynchronous I/O request was not found in the transmit or receive queue. It has either completed or was not issued by Transmit() and Receive() .

EFI_IP4_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```

typedef
EFI_STATUS
(EFI_API *EFI_IP4_POLL) (
    IN EFI_IP4_PROTOCOL      *This
);

```

Parameters

This Pointer to the **EFI_IP4_PROTOCOL** instance.

Description

The **Poll()** function polls for incoming data packets and processes outgoing data packets. Network drivers and applications can call the **EFI_IP4_PROTOCOL.Poll()** function to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems the periodic timer event may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the **EFI_IP4_PROTOCOL.Poll()** function more often.

Status Codes Returned

EFI_SUCCESS	Incoming or outgoing data was processed.
EFI_NOT_STARTED	This EFI IPv4 Protocol instance has not been started.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_DEVICE_ERROR	An unexpected system or network error occurred.
EFI_NOT_READY	No incoming or outgoing data is processed.
EFI_TIMEOUT	Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.

24.3 EFI IPv4 Configuration Protocol

This section provides a detailed description of the EFI IPv4 Configuration Protocol.

EFI_IP4_CONFIG_PROTOCOL

Summary

The **EFI_IP4_CONFIG_PROTOCOL** driver performs platform- and policy-dependent configuration for the EFI IPv4 Protocol driver.

GUID

```
#define EFI_IP4_CONFIG_PROTOCOL_GUID \
{0x3b95aa31,0x3793,0x434b,0x86,0x67,0xc8,0x07,0x08,0x92,0xe0,
0x5e}
```

Protocol Interface Structure

```
typedef struct _EFI_IP4_CONFIG_PROTOCOL {
    EFI_IP4_CONFIG_START      Start;
    EFI_IP4_CONFIG_STOP      Stop;
    EFI_IP4_CONFIG_GET_DATA  GetData;
} EFI_IP4_CONFIG_PROTOCOL;
```

Parameters

<i>Start</i>	Starts running the configuration policy for the EFI IPv4 Protocol driver. See the Start() function description.
<i>Stop</i>	Stops running the configuration policy for the EFI IPv4 Protocol driver. See the Stop() function description.
<i>GetData</i>	Returns the default configuration data (if any) for the EFI IPv4 Protocol driver. See the GetData() function description.

Description

In an effort to keep platform policy code out of the EFI IPv4 Protocol driver, the **EFI_IP4_CONFIG_PROTOCOL** driver will be used as the central repository of any platform- and policy-specific configuration for the EFI IPv4 Protocol driver.

An EFI IPv4 Configuration Protocol interface will be installed on each communications device handle that is managed by the platform setup policy. The driver that is responsible for creating EFI IPv4 variable must open the EFI IPv4 Configuration Protocol driver interface

BY_DRIVER|EXCLUSIVE.

An example of a configuration policy decision for the EFI IPv4 Protocol driver would be to use a static IP address/subnet mask pair on the platform management network interface and then use dynamic IP addresses that are configured by DHCP on the remaining network interfaces.

EFI_IP4_CONFIG_PROTOCOL.Start()

Summary

Starts running the configuration policy for the EFI IPv4 Protocol driver.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_CONFIG_START) (
    IN EFI_IP4_CONFIG_PROTOCOL    *This,
    IN EFI_EVENT                  DoneEvent,
    IN EFI_EVENT                  ReconfigEvent
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_CONFIG_PROTOCOL instance.
<i>DoneEvent</i>	Event that will be signaled when the EFI IPv4 Protocol driver configuration policy completes execution. This event must be of type EVT_NOTIFY_SIGNAL .
<i>ReconfigEvent</i>	Event that will be signaled when the EFI IPv4 Protocol driver configuration needs to be updated. This event must be of type EVT_NOTIFY_SIGNAL .

Description

The **Start()** function is called to determine and to begin the platform configuration policy by the EFI IPv4 Protocol driver. This determination may be as simple as returning **EFI_UNSUPPORTED** if there is no EFI IPv4 Protocol driver configuration policy. It may be as involved as loading some defaults from nonvolatile storage, downloading dynamic data from a DHCP server, and checking permissions with a site policy server.

Starting the configuration policy is just the beginning. It may finish almost instantly or it may take several minutes before it fails to retrieve configuration information from one or more servers. Once the policy is started, drivers should use the *DoneEvent* parameter to determine when the configuration policy has completed. **EFI_IP4_CONFIG_PROTOCOL.GetData()** must then be called to determine if the configuration succeeded or failed.

Until the configuration completes successfully, EFI IPv4 Protocol driver instances that are attempting to use default configurations must return **EFI_NO_MAPPING**.

Once the configuration is complete, the EFI IPv4 Configuration Protocol driver signals *DoneEvent*. The configuration may need to be updated in the future, however; in this case, the EFI IPv4 Configuration Protocol driver must signal *ReconfigEvent*, and all EFI IPv4 Protocol driver instances that are using default configurations must return **EFI_NO_MAPPING** until the configuration policy has been rerun.

Status Codes Returned

EFI_SUCCESS	The configuration policy for the EFI IPv4 Protocol driver is now running.
EFI_INVALID_PARAMETER	One or more of the following parameters is NULL : <ul style="list-style-type: none"> • <i>This</i> • <i>DoneEvent</i> • <i>ReconfigEvent</i>
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_ALREADY_STARTED	The configuration policy for the EFI IPv4 Protocol driver was already started.
EFI_DEVICE_ERROR	An unexpected system error or network error occurred.
EFI_UNSUPPORTED	This interface does not support the EFI IPv4 Protocol driver configuration.

EFI_IP4_CONFIG_PROTOCOL.Stop()

Summary

Stops running the configuration policy for the EFI IPv4 Protocol driver.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_CONFIG_STOP) (
    IN EFI_IP4_CONFIG_PROTOCOL *This
);
```

Parameters

This Pointer to the **EFI_IP4_CONFIG_PROTOCOL** instance.

Description

The **Stop()** function stops the configuration policy for the EFI IPv4 Protocol driver. All configuration data will be lost after calling **Stop()**.

Status Codes Returned

EFI_SUCCESS	The configuration policy for the EFI IPv4 Protocol driver has been stopped.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_STARTED	The configuration policy for the EFI IPv4 Protocol driver was not started.

EFI_IP4_CONFIG_PROTOCOL.GetData()

Summary

Returns the default configuration data (if any) for the EFI IPv4 Protocol driver.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_IP4_CONFIG_GET_DATA) (
    IN EFI_IP4_CONFIG_PROTOCOL *This,
    IN OUT UINTN                *IpConfigDataSize,
    OUT EFI_IP4_IPCONFIG_DATA  *IpConfigData    OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_IP4_CONFIG_PROTOCOL instance.
<i>IpConfigDataSize</i>	On input, the size of the <i>IpConfigData</i> buffer. On output, the count of bytes that were written into the <i>IpConfigData</i> buffer.
<i>IpConfigData</i>	Pointer to the EFI IPv4 Configuration Protocol driver configuration data structure. Type EFI_IP4_IPCONFIG_DATA is defined in “Related Definitions” below.

Description

The **GetData()** function returns the current configuration data for the EFI IPv4 Protocol driver after the configuration policy has completed.

Related Definitions

```
/**
//*****
// EFI_IP4_IPCONFIG_DATA
//*****
typedef struct {
    EFI_IPv4_ADDRESS    StationAddress;
    EFI_IPv4_ADDRESS    SubnetMask;
    UINT32              RouteTableSize;
    EFI_IP4_ROUTE_TABLE *RouteTable    OPTIONAL;
} EFI_IP4_IPCONFIG_DATA;
```

<i>StationAddress</i>	Default station IP address, stored in network byte order.
<i>SubnetMask</i>	Default subnet mask, stored in network byte order.
<i>RouteTableSize</i>	Number of entries in the following <i>RouteTable</i> . May be zero.
<i>RouteTable</i>	Default routing table data (stored in network byte order). Ignored if <i>RouteTableSize</i> is zero. Type

EFI_IP4_ROUTE_TABLE is defined in
EFI_IP4_PROTOCOL.GetModeData().

EFI_IP4_IPCONFIG_DATA contains the minimum IPv4 configuration data that is needed to start basic network communication. The *StationAddress* and *SubnetMask* must be a valid unicast IP address and subnet mask.

If *RouteTableSize* is not zero, then *RouteTable* contains a properly formatted routing table for the *StationAddress/SubnetMask*, with the last entry in the table being the default route.

Status Codes Returned

EFI_SUCCESS	The EFI IPv4 Protocol driver configuration has been returned.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_STARTED	The configuration policy for the EFI IPv4 Protocol driver is not running.
EFI_NOT_READY	EFI IPv4 Protocol driver configuration is still running.
EFI_ABORTED	EFI IPv4 Protocol driver configuration could not complete.
EFI_BUFFER_TOO_SMALL	* <i>IpConfigDataSize</i> is smaller than the configuration data buffer or <i>IpConfigData</i> is NULL .

Network Protocols — UDPv4 and MTFTPv4

25.1 EFI UDPv4 Protocol

This section defines the EFI UDPv4 (User Datagram Protocol version 4) Protocol that interfaces over the EFI IPv4 Protocol.

EFI_UDP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI UDPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI UDPv4 Protocol driver and to create and destroy instances of the EFI UDPv4 Protocol child protocol driver that can use the underlying communications device.

GUID

```
#define EFI_UDP4_SERVICE_BINDING_PROTOCOL_GUID \
{0x83f01464, 0x99bd, 0x45e5, 0xb3, 0x83, 0xaf, 0x63, 0x05, 0xd8, 0xe9, 0xe6}
```

Description

A network application that requires basic UDPv4 I/O services can use one of the protocol handler services, such as **BS->LocateHandleBuffer()**, to search for devices that publish a EFI UDPv4 Service Binding Protocol GUID. Each device with a published EFI UDPv4 Service Binding Protocol GUID supports the EFI UDPv4 Protocol and may be available for use.

After a successful call to the **EFI_UDP4_SERVICE_BINDING_PROTOCOL.CreateChild()** function, the newly created child EFI UDPv4 Protocol driver is in an unconfigured state; it is not ready to send and receive data packets.

Before a network application terminates execution every successful call to the **EFI_UDP4_SERVICE_BINDING_PROTOCOL.CreateChild()** function must be matched with a call to the **EFI_UDP4_SERVICE_BINDING_PROTOCOL.DestroyChild()** function.

EFI UDP4 Variable

Summary

An accurate list of all of the IPv4 addresses and port number that are currently being used must be maintained for each communications device. This list is stored as a volatile EFI variable so it can be publicly read.

Vendor GUID

`gEfiUdp4ServiceBindingProtocolGuid`

Variable Name

`CHAR16 *MacAddress;`

Attribute

`EFI_VARIABLE_BOOTSERVICE_ACCESS`

Description

MacAddress is the string of printed hexadecimal value for each byte in hardware address (of type **EFI_MAC_ADDRESS**) of the communications device. No 0x or h is included in each hex value. The length of **MacAddress** is determined by the hardware address length. For example: if the hardware address is 00-07-E9-51-60-D7, and address length is 6 bytes, then the **MacAddress** is "0007E95160D7".

Related Definitions

```

//*****
// EFI_UDP4_VARIABLE_DATA
//*****
typedef struct {
    EFI_HANDLE           DriverHandle;
    UINT32               ServiceCount;
    EFI_UDP4_SERVICE_POINT Services[1];
} EFI_UDP4_VARIABLE_DATA;

```

<i>DriverHandle</i>	The handle of the driver that creates this entry.
<i>ServiceCount</i>	The number of address/port pairs that follow this data structure.
<i>Services</i>	List of address/port pairs that are currently in use. Type EFI_UDP4_SERVICE_POINT is defined below.

```

//*****
// EFI_UDP4_SERVICE_POINT
//*****
typedef struct{
    EFI_HANDLE           InstanceHandle;
    EFI_IPv4_ADDRESS     LocalAddress;
    UINT16               LocalPort;
    EFI_IPv4_ADDRESS     RemoteAddress;
    UINT16               RemotePort;
} EFI_UDP4_SERVICE_POINT;

```

<i>InstanceHandle</i>	The EFI UDPv4 Protocol instance handle that is using this address/port pair. May be NULL if no instance is associated with this service access point.
-----------------------	--

<i>LocalAddress</i>	The IPv4 address to which this instance of the EFI UDPv4 Protocol is bound.
<i>LocalPort</i>	The port number in host byte order on which the service is listening.
<i>RemoteAddress</i>	The IPv4 address of the remote host. May be 0.0.0.0 if it is not connected to any remote host.
<i>RemotePort</i>	The port number in host byte order on which the remote host is listening. May be zero if it is not connected to any remote host.

EFI_UDP4_PROTOCOL

Summary

The EFI UDPv4 Protocol provides simple packet-oriented services to transmit and receive UDP packets.

GUID

```
#define EFI_UDP4_PROTOCOL_GUID \
{0x3ad9df29,0x4501,0x478d,0xb1,0xf8,0x7f,0x7f,0xe7,0x0e,0x50,0xf3}
```

Protocol Interface Structure

```
typedef struct _EFI_UDP4_PROTOCOL {
EFI_UDP4_GET_MODE_DATA      GetModeData;
EFI_UDP4_CONFIGURE          Configure;
EFI_UDP4_GROUPS              Groups;
EFI_UDP4_ROUTES              Routes;
EFI_UDP4_TRANSMIT            Transmit;
EFI_UDP4_RECEIVE             Receive;
EFI_UDP4_CANCEL              Cancel;
EFI_UDP4_POLL                Poll;
} EFI_UDP4_PROTOCOL;
```

Parameters

<i>GetModeData</i>	Reads the current operational settings. See the GetModeData () function description.
<i>Configure</i>	Initializes, changes, or resets operational settings for the EFI UDPv4 Protocol. See the Configure () function description.
<i>Groups</i>	Joins and leaves multicast groups. See the Groups () function description.
<i>Routes</i>	Add and deletes routing table entries. See the Routes () function description.
<i>Transmit</i>	Queues outgoing data packets into the transmit queue. This function is a nonblocked operation. See the Transmit () function description.

<i>Receive</i>	Places a receiving request token into the receiving queue. This function is a nonblocked operation. See the Receive () function description.
<i>Cancel</i>	Aborts a pending transmit or receive request. See the Cancel () function description.
<i>Poll</i>	Polls for incoming data packets and processes outgoing data packets. See the Poll () function description.

Description

The **EFI_UDP4_PROTOCOL** defines an EFI UDPv4 Protocol session that can be used by any network drivers, applications, or daemons to transmit or receive UDP packets. This protocol instance can either be bound to a specified port as a service or connected to some remote peer as an active client. Each instance has its own settings, such as the routing table and group table, which are independent from each other.

Note: *In this document, all IPv4 addresses and incoming/outgoing packets are stored in network byte order. All other parameters in the functions and data structures that are defined in this document are stored in host byte order.*

EFI_UDP4_PROTOCOL.GetModeData()

Summary

Reads the current operational settings.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_UDP4_GET_MODE_DATA) (
    IN EFI_UDP4_PROTOCOL           *This,
    OUT EFI_UDP4_CONFIG_DATA       *Udp4ConfigData    OPTIONAL,
    OUT EFI_IP4_MODE_DATA          *Ip4ModeData        OPTIONAL,
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData  OPTIONAL,
    OUT EFI_SIMPLE_NETWORK_MODE    *SnpModeData        OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_UDP4_PROTOCOL instance.
<i>Udp4ConfigData</i>	Pointer to the buffer to receive the current configuration data. Type EFI_UDP4_CONFIG_DATA is defined in “Related Definitions” below.
<i>Ip4ModeData</i>	Pointer to the EFI IPv4 Protocol mode data structure. Type EFI_IP4_MODE_DATA is defined in EFI_IP4_PROTOCOL.GetModeData() .
<i>MnpConfigData</i>	Pointer to the managed network configuration data structure. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData() .
<i>SnpModeData</i>	Pointer to the simple network mode data structure. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL .

Description

The **GetModeData()** function copies the current operational settings of this EFI UDPv4 Protocol instance into user-supplied buffers. This function is used optionally to retrieve the operational mode data of underlying networks or drivers.

Related Definition

```
//
*****
// EFI_UDP4_CONFIG_DATA
//
*****
typedef struct {
    //Receiving Filters
    BOOLEAN          AcceptBroadcast;
    BOOLEAN          AcceptPromiscuous;
    BOOLEAN          AcceptAnyPort;
    BOOLEAN          AllowDuplicatePort;
    // I/O parameters
    UINT8            TypeOfService;
    UINT8            TimeToLive;
    BOOLEAN          DoNotFragment;
    UINT32           ReceiveTimeout;
    UINT32           TransmitTimeout;
    // Access Point
    BOOLEAN          UseDefaultAddress;
    EFI_IPv4_ADDRESS StationAddress;
    EFI_IPv4_ADDRESS SubnetMask;
    UINT16           StationPort;
    EFI_IPv4_ADDRESS RemoteAddress;
    UINT16           RemotePort;
} EFI_UDP4_CONFIG_DATA;
```

<i>AcceptBroadcast</i>	Set to TRUE to accept broadcast UDP packets.
<i>AcceptPromiscuous</i>	Set to TRUE to accept UDP packets that are sent to any address.
<i>AcceptAnyPort</i>	Set to TRUE to accept UDP packets that are sent to any port.
<i>AllowDuplicatePort</i>	Set to TRUE to allow this EFI UDPv4 Protocol child instance to open a port number that is already being used by another EFI UDPv4 Protocol child instance.
<i>TypeOfService</i>	<i>TypeOfService</i> field in transmitted IPv4 packets.
<i>TimeToLive</i>	<i>TimeToLive</i> field in transmitted IPv4 packets.
<i>DoNotFragment</i>	Set to TRUE to disable IP transmit fragmentation.
<i>ReceiveTimeout</i>	The receive timeout value (number of microseconds) to be associated with each incoming packet. Zero means do not drop incoming packets.
<i>TransmitTimeout</i>	The transmit timeout value (number of microseconds) to be associated with each outgoing packet. Zero means do not drop outgoing packets.
<i>UseDefaultAddress</i>	Set to TRUE to use the default IP address and default routing table. If the default IP address is not available yet, then the

underlying EFI IPv4 Protocol driver will use **EFI_IP4_CONFIG_PROTOCOL** to retrieve the IP address and subnet information. Ignored for incoming filtering if *AcceptPromiscuous* is set to **TRUE**.

StationAddress The station IP address that will be assigned to this EFI UDPv4 Protocol instance. The EFI UDPv4 and EFI IPv4 Protocol drivers will only deliver incoming packets whose destination matches this IP address exactly. Address 0.0.0.0 is also accepted as a special case in which incoming packets destined to any station IP address are always delivered. Not used when *UseDefaultAddress* is **TRUE**. Ignored for incoming filtering if *AcceptPromiscuous* is **TRUE**.

SubnetMask The subnet address mask that is associated with the station address. Not used when *UseDefaultAddress* is **TRUE**.

StationPort The port number to which this EFI UDPv4 Protocol instance is bound. If a client of the EFI UDPv4 Protocol does not care about the port number, set *StationPort* to zero. The EFI UDPv4 Protocol driver will assign a random port number to transmitted UDP packets. Ignored if *AcceptAnyPort* is set to **TRUE**.

RemoteAddress The IP address of remote host to which this EFI UDPv4 Protocol instance is connecting. If *RemoteAddress* is not 0.0.0.0, this EFI UDPv4 Protocol instance will be connected to *RemoteAddress*; i.e., outgoing packets of this EFI UDPv4 Protocol instance will be sent to this address by default and only incoming packets from this address will be delivered to client. Ignored for incoming filtering if *AcceptPromiscuous* is **TRUE**.

RemotePort The port number of the remote host to which this EFI UDPv4 Protocol instance is connecting. If it is not zero, outgoing packets of this EFI UDPv4 Protocol instance will be sent to this port number by default and only incoming packets from this port will be delivered to client. Ignored if *RemoteAddress* is 0.0.0.0 and ignored for incoming filtering if *AcceptPromiscuous* is **TRUE**.

Status Codes Returned

EFI_SUCCESS	The mode data was read.
EFI_NOT_STARTED	When <i>Udp4ConfigData</i> is queried, no configuration data is available because this instance has not been started.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .

EFI_ALREADY_STARTED	The EFI UDPv4 Protocol instance is already started/configured and must be stopped/reset before it can be reconfigured. Only <i>TypeOfService</i> , <i>TimeToLive</i> , <i>DoNotFragment</i> , <i>ReceiveTimeout</i> , and <i>TransmitTimeout</i> can be reconfigured without stopping the current instance of the EFI UDPv4 Protocol.
EFI_ACCESS_DENIED	<i>UdpConfigData.AllowDuplicatePort</i> is FALSE and <i>UdpConfigData.StationPort</i> is already used by other instance.
EFI_OUT_OF_RESOURCES	The EFI UDPv4 Protocol driver cannot allocate memory for this EFI UDPv4 Protocol instance.
EFI_DEVICE_ERROR	An unexpected network or system error occurred and this instance was not opened.

EFI_UDP4_PROTOCOL.Groups()

Summary

Joins and leaves multicast groups.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_UDP4_GROUPS) (
    IN EFI_UDP4_PROTOCOL *This,
    IN BOOLEAN JoinFlag,
    IN EFI_IPv4_ADDRESS *MulticastAddress OPTIONAL
);
```

Parameters

This Pointer to the **EFI_UDP4_PROTOCOL** instance.

JoinFlag Set to **TRUE** to join a multicast group. Set to **FALSE** to leave one or all multicast groups.

MulticastAddress Pointer to multicast group address to join or leave.

Description

The **Groups ()** function is used to enable and disable the multicast group filtering.

If the *JoinFlag* is **FALSE** and the *MulticastAddress* is **NULL**, then all currently joined groups are left.

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_NOT_STARTED	The EFI UDPv4 Protocol instance has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_OUT_OF_RESOURCES	Could not allocate resources to join the group.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. <i>JoinFlag</i> is TRUE and <i>MulticastAddress</i> is NULL. <i>JoinFlag</i> is TRUE and <i>*MulticastAddress</i> is not a valid multicast address.
EFI_ALREADY_STARTED	The group address is already in the group table (when <i>JoinFlag</i> is TRUE).
EFI_NOT_FOUND	The group address is not in the group table (when <i>JoinFlag</i> is FALSE).
EFI_DEVICE_ERROR	An unexpected system or network error occurred.

EFI_UDP4_PROTOCOL.Routes()

Summary

Adds and deletes routing table entries.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_UDP4_ROUTES) (
    IN EFI_UDP4_PROTOCOL    *This,
    IN BOOLEAN              DeleteRoute,
    IN EFI_IPv4_ADDRESS     *SubnetAddress,
    IN EFI_IPv4_ADDRESS     *SubnetMask,
    IN EFI_IPv4_ADDRESS     *GatewayAddress
);
```

Parameters

<i>This</i>	Pointer to the EFI_UDP4_PROTOCOL instance.
<i>DeleteRoute</i>	Set to TRUE to delete this route from the routing table. Set to FALSE to add this route to the routing table. <i>DestinationAddress</i> and <i>SubnetMask</i> are used as the key to each route entry.
<i>SubnetAddress</i>	The destination network address that needs to be routed.
<i>SubnetMask</i>	The subnet mask of <i>SubnetAddress</i> .
<i>GatewayAddress</i>	The gateway IP address for this route.

Description

The **Routes()** function adds a route to or deletes a route from the routing table.

Routes are determined by comparing the *SubnetAddress* with the destination IP address and arithmetically **AND**-ing it with the *SubnetMask*. The gateway address must be on the same subnet as the configured station address.

The default route is added with *SubnetAddress* and *SubnetMask* both set to 0.0.0.0. The default route matches all destination IP addresses that do not match any other routes.

A zero *GatewayAddress* is a nonroute. Packets are sent to the destination IP address if it can be found in the Address Resolution Protocol (ARP) cache or on the local subnet. One automatic nonroute entry will be inserted into the routing table for outgoing packets that are addressed to a local subnet (gateway address of 0.0.0.0).

Each instance of the EFI UDPv4 Protocol has its own independent routing table. Instances of the EFI UDPv4 Protocol that use the default IP address will also have copies of the routing table provided by the **EFI_IP4_CONFIG_PROTOCOL**. These copies will be updated automatically whenever the IP driver reconfigures its instances; as a result, the previous modification to these copies will be lost.

Note: *There is no way to set up routes to other network interface cards (NICs) because each NIC has its own independent network stack that shares information only through **EFI UDP4 Variable**.*

Status Codes Returned

EFI_SUCCESS	The operation completed successfully.
EFI_NOT_STARTED	The EFI UDPv4 Protocol instance has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>SubnetAddress</i> is NULL. • <i>SubnetMask</i> is NULL. • <i>GatewayAddress</i> is NULL. • <i>*SubnetAddress</i> is not a valid subnet address. • <i>*SubnetMask</i> is not a valid subnet mask. • <i>*GatewayAddress</i> is not a valid unicast IP address.
EFI_OUT_OF_RESOURCES	Could not add the entry to the routing table.
EFI_NOT_FOUND	This route is not in the routing table.
EFI_ACCESS_DENIED	The route is already defined in the routing table.

EFI_UDP4_PROTOCOL.Transmit()

Summary

Queues outgoing data packets into the transmit queue.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_UDP4_TRANSMIT) (
    IN EFI_UDP4_PROTOCOL           *This,
    IN EFI_UDP4_COMPLETION_TOKEN  *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_UDP4_PROTOCOL instance.
<i>Token</i>	Pointer to the completion token that will be placed into the transmit queue. Type EFI_UDP4_COMPLETION_TOKEN is defined in “Related Definitions” below.

Description

The **Transmit()** function places a sending request to this instance of the EFI UDPv4 Protocol, alongside the transmit data that was filled by the user. Whenever the packet in the token is sent out or some errors occur, the **Token.Event** will be signaled and **Token.Status** is updated. Providing a proper notification function and context for the event will enable the user to receive the notification and transmitting status.

Related Definitions

```
//
*****
// EFI_UDP4_COMPLETION_TOKEN
//
*****
typedef struct {
    EFI_EVENT           Event;
    EFI_STATUS         Status;
    union {
        EFI_UDP4_RECEIVE_DATA  *RxData;
        EFI_UDP4_TRANSMIT_DATA *TxData;
    } Packet;
} EFI_UDP4_COMPLETION_TOKEN;
```

<i>Event</i>	This <i>Event</i> will be signaled after the <i>Status</i> field is updated by the EFI UDPv4 Protocol driver. The type of <i>Event</i> must be EVT_NOTIFY_SIGNAL . The Task Priority Level (TPL) of <i>Event</i> must be lower than or equal to TPL_CALLBACK .
--------------	--

<i>Status</i>	<p>Will be set to one of the following values:</p> <p>EFI_SUCCESS. The receive or transmit operation completed successfully.</p> <p>EFI_ABORTED. The receive or transmit was aborted.</p> <p>EFI_TIMEOUT. The transmit timeout expired.</p> <p>EFI_NETWORK_UNREACHABLE. The destination network is unreachable. RxData is set to NULL in this situation.</p> <p>EFI_HOST_UNREACHABLE. The destination host is unreachable. RxData is set to NULL in this situation.</p> <p>EFI_PROTOCOL_UNREACHABLE. The UDP protocol is unsupported in the remote system. RxData is set to NULL in this situation.</p> <p>EFI_PORT_UNREACHABLE. No service is listening on the remote port. RxData is set to NULL in this situation.</p> <p>EFI_ICMP_ERROR. Some other Internet Control Message Protocol (ICMP) error report was received. For example, packets are being sent too fast for the destination to receive them and the destination sent an ICMP source quench report. RxData is set to NULL in this situation.</p> <p>EFI_DEVICE_ERROR. An unexpected system or network error occurred.</p>
<i>RxData</i>	<p>When this token is used for receiving, <i>RxData</i> is a pointer to EFI_UDP4_RECEIVE_DATA. Type EFI_UDP4_RECEIVE_DATA is defined below.</p>
<i>TxData</i>	<p>When this token is used for transmitting, <i>TxData</i> is a pointer to EFI_UDP4_TRANSMIT_DATA. Type EFI_UDP4_TRANSMIT_DATA is defined below.</p>

The **EFI_UDP4_COMPLETION_TOKEN** structures are used for both transmit and receive operations.

When used for transmitting, the *Event* and *TxData* fields must be filled in by the EFI UDPv4 Protocol client. After the transmit operation completes, the *Status* field is updated by the EFI UDPv4 Protocol and the *Event* is signaled.

- When used for receiving, only the *Event* field must be filled in by the EFI UDPv4 Protocol client. After a packet is received, *RxData* and *Status* are filled in by the EFI UDPv4 Protocol and the *Event* is signaled.
- The ICMP related status codes filled in *Status* are defined as follows:


```

//
*****
// UDP4 Token Status definition
//
*****
#define EFI_NETWORK_UNREACHABLE    EFIERR(100)
#define EFI_HOST_UNREACHABLE       EFIERR(101)
#define EFI_PROTOCOL_UNREACHABLE   EFIERR(102)
#define EFI_PORT_UNREACHABLE       EFIERR(103)

//
*****
// EFI_UDP4_RECEIVE_DATA
//
*****
typedef struct {
    EFI_TIME                TimeStamp;
    EFI_EVENT                RecycleSignal;
    EFI_UDP4_SESSION_DATA   UdpSession;
    UINT32                   DataLength;
    UINT32                   FragmentCount;
    EFI_UDP4_FRAGMENT_DATA  FragmentTable[1];
} EFI_UDP4_RECEIVE_DATA;

```

<i>TimeStamp</i>	Time when the EFI UDPv4 Protocol accepted the packet.
<i>RecycleSignal</i>	Indicates the event to signal when the received data has been processed.
<i>UdpSession</i>	The UDP session data including <i>SourceAddress</i> , <i>SourcePort</i> , <i>DestinationAddress</i> , and <i>DestinationPort</i> . Type EFI_UDP4_SESSION_DATA is defined below.
<i>DataLength</i>	The sum of the fragment data length.
<i>FragmentCount</i>	Number of fragments. May be zero.
<i>FragmentTable</i>	Array of fragment descriptors. IP and UDP headers are included in these buffers if <i>ConfigData.RawData</i> is TRUE . Otherwise they are stripped. May be zero. Type EFI_UDP4_FRAGMENT_DATA is defined below.

EFI_UDP4_RECEIVE_DATA is filled by the EFI UDPv4 Protocol driver when this EFI UDPv4 Protocol instance receives an incoming packet. If there is a waiting token for incoming packets, the *CompletionToken.Packet.RxData* field is updated to this incoming packet and the *CompletionToken.Event* is signaled. The EFI UDPv4 Protocol client must signal the *RecycleSignal* after processing the packet.

- *FragmentTable* could contain multiple buffers that are not in the continuous memory locations. The EFI UDPv4 Protocol client might need to combine two or more buffers in *FragmentTable* to form their own protocol header.

```
//
*****
// EFI_UDP4_SESSION_DATA
//
*****
typedef struct {
    EFI_IPv4_ADDRESS    SourceAddress;
    UINT16              SourcePort;
    EFI_IPv4_ADDRESS    DestinationAddress;
    UINT16              DestinationPort;
} EFI_UDP4_SESSION_DATA;
```

SourceAddress Address from which this packet is sent. If this field is set to zero when sending packets, the address that is assigned in **EFI_UDP4_PROTOCOL.Configure()** is used.

SourcePort Port from which this packet is sent. It is in host byte order. If this field is set to zero when sending packets, the port that is assigned in **EFI_UDP4_PROTOCOL.Configure()** is used. If this field is set to zero and unbound, a call to **EFI_UDP4_PROTOCOL.Transmit()** will fail.

DestinationAddress Address to which this packet is sent.

DestinationPort Port to which this packet is sent. It is in host byte order. If this field is set to zero and unconnected, the call to **EFI_UDP4_PROTOCOL.Transmit()** will fail.

The **EFI_UDP4_SESSION_DATA** is used to retrieve the settings when receiving packets or to override the existing settings of this EFI UDPv4 Protocol instance when sending packets.

```
//
*****
// EFI_UDP4_FRAGMENT_DATA
//
*****
typedef struct {
    UINT32              FragmentLength;
    VOID                *FragmentBuffer;
} EFI_UDP4_FRAGMENT_DATA;
```

FragmentLength Length of the fragment data buffer.

FragmentBuffer Pointer to the fragment data buffer.

EFI_UDP4_FRAGMENT_DATA allows multiple receive or transmit buffers to be specified. The purpose of this structure is to avoid copying the same packet multiple times.

```

//*****
// EFI_UDP4_TRANSMIT_DATA
//*****
typedef struct {
    EFI_UDP4_SESSION_DATA    *UdpSessionData;
    EFI_IPv4_ADDRESS         *GatewayAddress;
    UINT32                   DataLength;
    UINT32                   FragmentCount;
    EFI_UDP4_FRAGMENT_DATA   FragmentTable[1];
} EFI_UDP4_TRANSMIT_DATA;
    
```

- UdpSessionData* If not **NULL**, the data that is used to override the transmitting settings. Type **EFI_UDP4_SESSION_DATA** is defined above.
- GatewayAddress* The next-hop address to override the setting from the routing table.
- DataLength* Sum of the fragment data length. Must not exceed the maximum UDP packet size.
- FragmentCount* Number of fragments.
- FragmentTable* Array of fragment descriptors. Type **EFI_UDP4_FRAGMENT_DATA** is defined above.

The EFI UDPv4 Protocol client must fill this data structure before sending a packet. The packet may contain multiple buffers that may be not in a continuous memory location.

Status Codes Returned

EFI_SUCCESS	The data has been queued for transmission.
EFI_NOT_STARTED	This EFI UDPv4 Protocol instance has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.

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EFI_INVALID_PARAMETER	<p>One or more of the following are TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.Event</i> is NULL. • <i>Token.Packet.TxData</i> is NULL. • <i>Token.Packet.TxData.FragmentCount</i> is zero. • <i>Token.Packet.TxData.DataLength</i> is not equal to the sum of fragment lengths. • One or more of the <i>Token.Packet.TxData.FragmentTable[] . FragmentLength</i> fields is zero. • One or more of the <i>Token.Packet.TxData.FragmentTable[] . FragmentBuffer</i> fields is NULL. • <i>Token.Packet.TxData.GatewayAddress</i> is not a unicast IPv4 address if it is not NULL. • <i>Token.Packet.TxData.UdpSessionData.SourceAddress</i> is not a valid unicast IPv4 address or <i>Token.Packet.TxData.UdpSessionData.DestinationAddress</i> is zero if the <i>UdpSessionData</i> is not NULL.
EFI_ACCESS_DENIED	The transmit completion token with the same <i>Token.Event</i> was already in the transmit queue.
EFI_NOT_READY	The completion token could not be queued because the transmit queue is full.
EFI_OUT_OF_RESOURCES	Could not queue the transmit data.
EFI_NOT_FOUND	There is no route to the destination network or address.
EFI_BAD_BUFFER_SIZE	The data length is greater than the maximum UDP packet size. Or the length of the IP header + UDP header + data length is greater than MTU if <i>DoNotFragment</i> is TRUE .

EFI_UDP4_PROTOCOL.Receive()

Summary

Places an asynchronous receive request into the receiving queue.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_UDP4_RECEIVE) (
    IN EFI_UDP4_PROTOCOL          *This,
    IN EFI_UDP4_COMPLETION_TOKEN *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_UDP4_PROTOCOL instance.
<i>Token</i>	Pointer to a token that is associated with the receive data descriptor. Type EFI_UDP4_COMPLETION_TOKEN is defined in EFI_UDP4_PROTOCOL.Transmit() .

Description

The **Receive()** function places a completion token into the receive packet queue. This function is always asynchronous.

The caller must fill in the *Token.Event* field in the completion token, and this field cannot be **NULL**. When the receive operation completes, the EFI UDPv4 Protocol driver updates the *Token.Status* and *Token.Packet.RxData* fields and the *Token.Event* is signaled. Providing a proper notification function and context for the event will enable the user to receive the notification and receiving status. That notification function is guaranteed to not be re-entered.

Status Codes Returned

EFI_SUCCESS	The receive completion token was cached.
EFI_NOT_STARTED	This EFI UDPv4 Protocol instance has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> <i>This</i> is NULL. <i>Token</i> is NULL. <i>Token.Event</i> is NULL.
EFI_OUT_OF_RESOURCES	The receive completion token could not be queued due to a lack of system resources (usually memory).
EFI_DEVICE_ERROR	An unexpected system or network error occurred. The EFI UDPv4 Protocol instance has been reset to startup defaults.

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EFI_ACCESS_DENIED	A receive completion token with the same <i>Token.Event</i> was already in the receive queue.
EFI_NOT_READY	The receive request could not be queued because the receive queue is full.

EFI_UDP4_PROTOCOL.Cancel()

Summary

Aborts an asynchronous transmit or receive request.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_UDP4_CANCEL) (
    IN EFI_UDP4_PROTOCOL           *This,
    IN EFI_UDP4_COMPLETION_TOKEN  *Token    OPTIONAL
);
```

Parameters

This Pointer to the **EFI_UDP4_PROTOCOL** instance.

Token Pointer to a token that has been issued by **EFI_UDP4_PROTOCOL.Transmit()** or **EFI_UDP4_PROTOCOL.Receive()**. If **NULL**, all pending tokens are aborted. Type **EFI_UDP4_COMPLETION_TOKEN** is defined in **EFI_UDP4_PROTOCOL.Transmit()**.

Description

The **Cancel()** function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, *Token.Status* will be set to **EFI_ABORTED** and then *Token.Event* will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and **EFI_NOT_FOUND** is returned.

Status Codes Returned

EFI_SUCCESS	The asynchronous I/O request was aborted and <i>Token.Event</i> was signaled. When <i>Token</i> is NULL , all pending requests are aborted and their events are signaled.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_NOT_STARTED	This instance has not been started.
EFI_NO_MAPPING	When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_NOT_FOUND	When <i>Token</i> is not NULL , the asynchronous I/O request was not found in the transmit or receive queue. It has either completed or was not issued by Transmit() and Receive() .

EFI_UDP4_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_UDP4_POLL) (
    IN EFI_UDP4_PROTOCOL          *This
);
```

Parameters

This Pointer to the **EFI_UDP4_PROTOCOL** instance.

Description

The **Poll()** function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the **Poll()** function more often.

Status Codes Returned

EFI_SUCCESS	Incoming or outgoing data was processed.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_DEVICE_ERROR	An unexpected system or network error occurred.
EFI_TIMEOUT	Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.

25.2 EFI MTFTPv4 Protocol

This section defines the EFI MTFTPv4 Protocol interface that is built upon the EFI UDPv4 Protocol.

EFI_MTFTP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI MTFTPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI MTFTPv4 Protocol driver and to create and destroy instances of the EFI MTFTPv4 Protocol child protocol driver that can use the underlying communications device.

GUID

```
#define EFI_MTFTP4_SERVICE_BINDING_PROTOCOL_GUID \
{0x2E800BE, 0x8F01, 0x4aa6, 0x94, 0x6B, 0xD7, 0x13, 0x88, 0xE1, 0x83,
0x3F}
```

Description

A network application or driver that requires MTFTPv4 I/O services can use one of the protocol handler services, such as **BS->LocateHandleBuffer()**, to search for devices that publish an EFI MTFTPv4 Service Binding Protocol GUID. Each device with a published EFI MTFTPv4 Service Binding Protocol GUID supports the EFI MTFTPv4 Protocol service and may be available for use.

After a successful call to the

EFI_MTFTP4_SERVICE_BINDING_PROTOCOL.CreateChild() function, the newly created child EFI MTFTPv4 Protocol driver instance is in an unconfigured state; it is not ready to transfer data.

Before a network application terminates execution, every successful call to the

EFI_MTFTP4_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the **EFI_MTFTP4_SERVICE_BINDING_PROTOCOL.DestroyChild()** function.

Each instance of the EFI MTFTPv4 Protocol driver can support one file transfer operation at a time. To download two files at the same time, two instances of the EFI MTFTPv4 Protocol driver will need to be created.

EFI_MTFTP4_PROTOCOL

Summary

The EFI MTFTPv4 Protocol provides basic services for client-side unicast and/or multicast TFTP operations.

GUID

```
#define EFI_MTFTP4_PROTOCOL_GUID \
{0x78247c57,0x63db,0x4708,0x99,0xc2,0xa8,0xb4,0xa9,0xa6,0x1f,
0x6b}
```

Protocol Interface Structure

```
typedef struct _EFI_MTFTP4_PROTOCOL {
    EFI_MTFTP4_GET_MODE_DATA GetModeData;
    EFI_MTFTP4_CONFIGURE      Configure;
    EFI_MTFTP4_GET_INFO       GetInfo;
    EFI_MTFTP4_PARSE_OPTIONS  ParseOptions;
    EFI_MTFTP4_READ_FILE      ReadFile;
    EFI_MTFTP4_WRITE_FILE     WriteFile;
    EFI_MTFTP4_READ_DIRECTORY ReadDirectory;
    EFI_MTFTP4_POLL           Poll;
} EFI_MTFTP4_PROTOCOL;
```

Parameters

<i>GetModeData</i>	Reads the current operational settings. See the GetModeData () function description.
<i>Configure</i>	Initializes, changes, or resets the operational settings for this instance of the EFI MTFTPv4 Protocol driver. See the Configure () function description.
<i>GetInfo</i>	Retrieves information about a file from an MTFTPv4 server. See the GetInfo () function description.
<i>ParseOptions</i>	Parses the options in an MTFTPv4 OACK (options acknowledgement) packet. See the ParseOptions () function description.
<i>ReadFile</i>	Downloads a file from an MTFTPv4 server. See the ReadFile () function description.
<i>WriteFile</i>	Uploads a file to an MTFTPv4 server. This function may be unsupported in some EFI implementations. See the WriteFile () function description.
<i>ReadDirectory</i>	Downloads a related file “directory” from an MTFTPv4 server. This function may be unsupported in some EFI implementations. See the ReadDirectory () function description.
<i>Poll</i>	Polls for incoming data packets and processes outgoing data packets. See the Poll () function description.

Description

The **EFI_MTFTP4_PROTOCOL** is designed to be used by UEFI drivers and applications to transmit and receive data files. The EFI MTFTPv4 Protocol driver uses the underlying EFI UDPv4 Protocol driver and EFI IPv4 Protocol driver.

EFI_MTFTP4_PROTOCOL.GetModeData()

Summary

Reads the current operational settings.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_GET_MODE_DATA) (
    IN EFI_MTFTP4_PROTOCOL      *This,
    OUT EFI_MTFTP4_MODE_DATA    *ModeData
);
```

Parameters

<i>This</i>	Pointer to the EFI_MTFTP4_PROTOCOL instance.
<i>ModeData</i>	Pointer to storage for the EFI MTFTPv4 Protocol driver mode data. Type EFI_MTFTP4_MODE_DATA is defined in “Related Definitions” below.

Description

The **GetModeData ()** function reads the current operational settings of this EFI MTFTPv4 Protocol driver instance.

Related Definitions

```
/**
//*****
// EFI_MTFTP4_MODE_DATA
//*****
typedef struct {
    EFI_MTFTP4_CONFIG_DATA    ConfigData;
    UINT8                    SupportedOptionCount;
    UINT8                    **SupportedOptions;
    UINT8                    UnsupportedOptionCount;
    UINT8                    **UnsupportedOptions;
} EFI_MTFTP4_MODE_DATA;
```

<i>ConfigData</i>	The configuration data of this instance. Type EFI_MTFTP4_CONFIG_DATA is defined below.
<i>SupportedOptionCount</i>	The number of option strings in the following <i>SupportedOptions</i> array.
<i>SupportedOptions</i>	An array of option strings that are recognized and supported by this EFI MTFTPv4 Protocol driver implementation.
<i>UnsupportedOptionCount</i>	The number of option strings in the following <i>UnsupportedOptions</i> array.

UnsupportedOptions

An array of option strings that are recognized but are not supported by this EFI MTFTPv4 Protocol driver implementation.

The **EFI_MTFTP4_MODE_DATA** structure describes the operational state of this instance.

```

//*****
// EFI_MTFTP4_CONFIG_DATA
//*****
typedef struct {
    BOOLEAN                UseDefaultSetting;
    EFI_IPv4_ADDRESS       StationIp;
    EFI_IPv4_ADDRESS       SubnetMask;
    UINT16                 LocalPort;
    EFI_IPv4_ADDRESS       GatewayIp;
    EFI_IPv4_ADDRESS       ServerIp;
    UINT16                 InitialServerPort;
    UINT16                 TryCount;
    UINT16                 TimeoutValue;
} EFI_MTFTP4_CONFIG_DATA;

```

- UseDefaultSetting* Set to **TRUE** to use the default station address/subnet mask and the default route table information.
- StationIp* If *UseDefaultSetting* is **FALSE**, indicates the station address to use.
- SubnetMask* If *UseDefaultSetting* is **FALSE**, indicates the subnet mask to use.
- LocalPort* Local port number. Set to zero to use the automatically assigned port number.
- GatewayIp* if *UseDefaultSetting* is **FALSE**, indicates the gateway IP address to use.
- ServerIp* The IP address of the MTFTPv4 server.
- InitialServerPort* The initial MTFTPv4 server port number. Request packets are sent to this port. This number is almost always 69 and using zero defaults to 69.
- TryCount* The number of times to transmit MTFTPv4 request packets and wait for a response.
- TimeoutValue* The number of seconds to wait for a response after sending the MTFTPv4 request packet.

The **EFI_MTFTP4_CONFIG_DATA** structure is used to report and change MTFTPv4 session parameters.

Status Codes Returned

EFI_SUCCESS	The configuration data was successfully returned.
EFI_OUT_OF_RESOURCES	The required mode data could not be allocated.

EFI_INVALID_PARAMETER	<i>This</i> is NULL or <i>ModeData</i> is NULL .
-----------------------	--

EFI_MTFTP4_PROTOCOL.Configure()

Summary

Initializes, changes, or resets the default operational setting for this EFI MTFTPv4 Protocol driver instance.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_MTFTP4_CONFIGURE) (
    IN EFI_MTFTP4_PROTOCOL      *This,
    IN EFI_MTFTP4_CONFIG_DATA  *MtftpConfigData  OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_MTFTP4_PROTOCOL instance.
<i>MtftpConfigData</i>	Pointer to the configuration data structure. Type EFI_MTFTP4_CONFIG_DATA is defined in EFI_MTFTP4_PROTOCOL.GetModeData() .

Description

The **Configure()** function is used to set and change the configuration data for this EFI MTFTPv4 Protocol driver instance. The configuration data can be reset to startup defaults by calling **Configure()** with *MtftpConfigData* set to **NULL**. Whenever the instance is reset, any pending operation is aborted. By changing the EFI MTFTPv4 Protocol driver instance configuration data, the client can connect to different MTFTPv4 servers. The configuration parameters in *MtftpConfigData* are used as the default parameters in later MTFTPv4 operations and can be overridden in later operations.

Status Codes Returned

EFI_SUCCESS	The EFI MTFTPv4 Protocol driver was configured successfully.
EFI_INVALID_PARAMETER	One or more following conditions are TRUE : <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>MtftpConfigData.UseDefaultSetting</i> is FALSE and <i>MtftpConfigData.StationIp</i> is not a valid IPv4 unicast address. • <i>MtftpCofigData.UseDefaultSetting</i> is FALSE and <i>MtftpConfigData.SubnetMask</i> is invalid. • <i>MtftpCofigData.ServerIp</i> is not a valid IPv4 unicast address. • <i>MtftpConfigData.UseDefaultSetting</i> is FALSE and <i>MtftpConfigData.GatewayIp</i> is not a valid IPv4 unicast address or is not in the same subnet with station address.

EFI_ACCESS_DENIED	The EFI configuration could not be changed at this time because there is one MTFTP background operation in progress.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) has not finished yet.
EFI_UNSUPPORTED	A configuration protocol (DHCP, BOOTP, RARP, etc.) could not be located when clients choose to use the default address settings.
EFI_OUT_OF_RESOURCES	The EFI MTFTPv4 Protocol driver instance data could not be allocated.
EFI_DEVICE_ERROR	An unexpected system or network error occurred. The EFI MTFTPv4 Protocol driver instance is not configured.

EFI_MTFFTP4_PROTOCOL.GetInfo()

Summary

Gets information about a file from an MTFFTPv4 server.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MTFFTP4_GET_INFO) (
    IN EFI_MTFFTP4_PROTOCOL           *This,
    IN EFI_MTFFTP4_OVERRIDE_DATA     *OverrideData    OPTIONAL,
    IN UINT8                          *Filename,
    IN UINT8                          *ModeStr          OPTIONAL,
    IN UINT8                          *OptionCount,
    IN EFI_MTFFTP4_OPTION             *OptionList      OPTIONAL,
    OUT UINT32                         *PacketLength,
    OUT EFI_MTFFTP4_PACKET            **Packet          OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_MTFFTP4_PROTOCOL instance.
<i>OverrideData</i>	Data that is used to override the existing parameters. If NULL , the default parameters that were set in the EFI_MTFFTP4_PROTOCOL.Configure() function are used. Type EFI_MTFFTP4_OVERRIDE_DATA is defined in “Related Definitions” below.
<i>Filename</i>	Pointer to ASCIIZ file name string.
<i>ModeStr</i>	Pointer to ASCIIZ mode string. If NULL , “octet” will be used.
<i>OptionCount</i>	Number of option/value string pairs in <i>OptionList</i> .
<i>OptionList</i>	Pointer to array of option/value string pairs. Ignored if <i>OptionCount</i> is zero. Type EFI_MTFFTP4_OPTION is defined in “Related Definitions” below.
<i>PacketLength</i>	The number of bytes in the returned packet.
<i>Packet</i>	The pointer to the received packet. This buffer must be freed by the caller. Type EFI_MTFFTP4_PACKET is defined in “Related Definitions” below.

Description

The **GetInfo()** function assembles an MTFFTPv4 request packet with options; sends it to the MTFFTPv4 server; and may return an MTFFTPv4 OACK, MTFFTPv4 ERROR, or ICMP ERROR packet. Retries occur only if no response packets are received from the MTFFTPv4 server before the timeout expires.

Related Definitions

```
//
*****
// EFI_MFTFTP_OVERRIDE_DATA
//
*****
typedef struct {
    EFI_IPv4_ADDRESS GatewayIp;
    EFI_IPv4_ADDRESS ServerIp;
    UINT16           ServerPort;
    UINT16           TryCount;
    UINT16           TimeoutValue;
} EFI_MFTFTP4_OVERRIDE_DATA;
```

<i>GatewayIp</i>	IP address of the gateway. If set to 0.0.0.0, the default gateway address that was set by the EFI_MFTFTP4_PROTOCOL.Configure() function will not be overridden.
<i>ServerIp</i>	IP address of the MFTFTPv4 server. If set to 0.0.0.0, it will use the value that was set by the EFI_MFTFTP4_PROTOCOL.Configure() function.
<i>ServerPort</i>	MFTFTPv4 server port number. If set to zero, it will use the value that was set by the EFI_MFTFTP4_PROTOCOL.Configure() function.
<i>TryCount</i>	Number of times to transmit MFTFTPv4 request packets and wait for a response. If set to zero, it will use the value that was set by the EFI_MFTFTP4_PROTOCOL.Configure() function.
<i>TimeoutValue</i>	Number of seconds to wait for a response after sending the MFTFTPv4 request packet. If set to zero, it will use the value that was set by the EFI_MFTFTP4_PROTOCOL.Configure() function.

The **EFI_MFTFTP4_OVERRIDE_DATA** structure is used to override the existing parameters that were set by the **EFI_MFTFTP4_PROTOCOL.Configure()** function.

```
//
*****
// EFI_MFTFTP4_OPTION
//
*****
typedef struct {
    UINT8           *OptionStr;
    UINT8           *ValueStr;
} EFI_MFTFTP4_OPTION;
```

<i>OptionStr</i>	Pointer to the ASCIIZ MFTFTPv4 option string.
<i>ValueStr</i>	Pointer to the ASCIIZ MFTFTPv4 value string.

```

#pragma pack(1)

/*****
// EFI_MTFTP4_PACKET
*****/
typedef union {
    UINT16      OpCode;
    EFI_MTFTP4_REQ_HEADER    Rrq, Wrq;
    EFI_MTFTP4_OACK_HEADER   Oack;
    EFI_MTFTP4_DATA_HEADER   Data;
    EFI_MTFTP4_ACK_HEADER    Ack;
    EFI_MTFTP4_DATA8_HEADER  Data8;
    EFI_MTFTP4_ACK8_HEADER   Ack8;
    EFI_MTFTP4_ERROR_HEADER  Error;
} EFI_MTFTP4_PACKET;

/*****
// EFI_MTFTP4_REQ_HEADER
*****/
typedef struct {
    UINT16      OpCode;
    UINT8       Filename[1];
} EFI_MTFTP4_REQ_HEADER;

/*****
// EFI_MTFTP4_OACK_HEADER
*****/
typedef struct {
    UINT16      OpCode;
    UINT8       Data[1];
} EFI_MTFTP4_OACK_HEADER;

/*****
// EFI_MTFTP4_DATA_HEADER
*****/
typedef struct {
    UINT16      OpCode;
    UINT16      Block;
    UINT8       Data[1];
} EFI_MTFTP4_DATA_HEADER;

/*****
// EFI_MTFTP4_ACK_HEADER
*****/
typedef struct {
    UINT16      OpCode;
    UINT16      Block[1];
}

```

```

} EFI_MTFTP4_ACK_HEADER;

/*****
// EFI_MTFTP4_DATA8_HEADER
*****/
typedef struct {
    UINT16    OpCode;
    UINT64    Block;
    UINT8     Data[1];
} EFI_MTFTP4_DATA8_HEADER;

/*****
// EFI_MTFTP4_ACK8_HEADER
*****/
typedef struct {
    UINT16    OpCode;
    UINT64    Block[1];
} EFI_MTFTP4_ACK8_HEADER;

/*****
// EFI_MTFTP4_ERROR_HEADER
*****/
typedef struct {
    UINT16    OpCode;
    UINT16    ErrorCode;
    UINT8     ErrorMessage[1];
} EFI_MTFTP4_ERROR_HEADER;

#pragma pack()

```

[Table 169](#) below describes the parameters that are listed in the MTFTPv4 packet structure definitions above. All the above structures are byte packed. The pragmas may vary from compiler to compiler. The MTFTPv4 packet structures are also used by the following functions:

- `EFI_MTFTP4_PROTOCOL.ReadFile()`
- `EFI_MTFTP4_PROTOCOL.WriteFile()`
- `EFI_MTFTP4_PROTOCOL.ReadDirectory()`
- The EFI MTFTPv4 Protocol packet check callback functions

Note: *Both incoming and outgoing MTFTPv4 packets are in network byte order. All other parameters defined in functions or data structures are stored in host byte order.*

Table 169. Descriptions of Parameters in MTFTPv4 Packet Structures

Data Structure	Parameter	Description
EFI_MTFTP4_PACKET	OpCode	Type of packets as defined by the MTFTPv4 packet opcodes. Opcode values are defined below.
	Rrq, Wrq	Read request or write request packet header. See the description for EFI_MTFTP4_REQ_HEADER below in this table.
	Oack	Option acknowledge packet header. See the description for EFI_MTFTP4_OACK_HEADER below in this table.
	Data	Data packet header. See the description for EFI_MTFTP4_DATA_HEADER below in this table.
	Ack	Acknowledgement packet header. See the description for EFI_MTFTP4_ACK_HEADER below in this table.
	Data8	Data packet header with big block number. See the description for EFI_MTFTP4_DATA8_HEADER below in this table.
	Ack8	Acknowledgement header with big block number. See the description for EFI_MTFTP4_ACK8_HEADER below in this table.
	Error	Error packet header. See the description for EFI_MTFTP4_ERROR_HEADER below in this table.
EFI_MTFTP4_REQ_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_RRQ for a read request or <i>OpCode</i> = EFI_MTFTP4_OPCODE_WRQ for a write request.
	Filename	The file name to be downloaded or uploaded.
EFI_MTFTP4_OACK_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_OACK .
	Data	The option strings in the option acknowledgement packet.
EFI_MTFTP4_DATA_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_DATA .
	Block	Block number of this data packet.
	Data	The content of this data packet.

Data Structur	Parameter	Description
EFI_MTFTP4_ACK_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_ACK .
	Block	The block number of the data packet that is being acknowledged.
EFI_MTFTP4_DATA8_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_DATA8 .
	Block	The block number of data packet.
	Data	The content of this data packet.
EFI_MTFTP4_ACK8_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_ACK8 .
	Block	The block number of the data packet that is being acknowledged.
EFI_MTFTP4_ERROR_HEADER	OpCode	For this packet type, <i>OpCode</i> = EFI_MTFTP4_OPCODE_ERROR .
	ErrorCode	The error number as defined by the MTFTPv4 packet error codes. Values for <i>ErrorCode</i> are defined below.
	ErrorMessage	Error message string.

```
//
// MTFTP Packet OpCodes
//
#define EFI_MTFTP4_OPCODE_RRQ      1
#define EFI_MTFTP4_OPCODE_WRQ      2
#define EFI_MTFTP4_OPCODE_DATA     3
#define EFI_MTFTP4_OPCODE_ACK      4
#define EFI_MTFTP4_OPCODE_ERROR    5
#define EFI_MTFTP4_OPCODE_OACK     6
#define EFI_MTFTP4_OPCODE_DIR      7
#define EFI_MTFTP4_OPCODE_DATA8    8
#define EFI_MTFTP4_OPCODE_ACK8     9
```

Following is a description of the fields in the above definition.

<i>EFI_MTFTP4_OPCODE_RRQ</i>	The MTFTPv4 packet is a read request.
<i>EFI_MTFTP4_OPCODE_WRQ</i>	The MTFTPv4 packet is a write request.
<i>EFI_MTFTP4_OPCODE_DATA</i>	The MTFTPv4 packet is a data packet.
<i>EFI_MTFTP4_OPCODE_ACK</i>	The MTFTPv4 packet is an acknowledgement packet.
<i>EFI_MTFTP4_OPCODE_ERROR</i>	The MTFTPv4 packet is an error packet.

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<code>EFI_MTFTP4_OPCODE_OACK</code>	The MTFTPv4 packet is an option acknowledgement packet.
<code>EFI_MTFTP4_OPCODE_DIR</code>	The MTFTPv4 packet is a directory query packet.
<code>EFI_MTFTP4_OPCODE_DATA8</code>	The MTFTPv4 packet is a data packet with a big block number.
<code>EFI_MTFTP4_OPCODE_ACK8</code>	The MTFTPv4 packet is an acknowledgement packet with a big block number.

```
//
// MTFTP ERROR Packet ErrorCodes
//
#define EFI_MTFTP4_ERRORCODE_NOT_DEFINED           0
#define EFI_MTFTP4_ERRORCODE_FILE_NOT_FOUND       1
#define EFI_MTFTP4_ERRORCODE_ACCESS_VIOLATION     2
#define EFI_MTFTP4_ERRORCODE_DISK_FULL           3
#define EFI_MTFTP4_ERRORCODE_ILLEGAL_OPERATION    4
#define EFI_MTFTP4_ERRORCODE_UNKNOWN_TRANSFER_ID  5
#define EFI_MTFTP4_ERRORCODE_FILE_ALREADY_EXISTS  6
#define EFI_MTFTP4_ERRORCODE_NO_SUCH_USER         7
#define EFI_MTFTP4_ERRORCODE_REQUEST_DENIED       8
```

<code>EFI_MTFTP4_ERRORCODE_NOT_DEFINED</code>	The error code is not defined. See the error message in the packet (if any) for details.
<code>EFI_MTFTP4_ERRORCODE_FILE_NOT_FOUND</code>	The file was not found.
<code>EFI_MTFTP4_ERRORCODE_ACCESS_VIOLATION</code>	There was an access violation.
<code>EFI_MTFTP4_ERRORCODE_DISK_FULL</code>	The disk was full or its allocation was exceeded.
<code>EFI_MTFTP4_ERRORCODE_ILLEGAL_OPERATION</code>	The MTFTPv4 operation was illegal.
<code>EFI_MTFTP4_ERRORCODE_UNKNOWN_TRANSFER_ID</code>	The transfer ID is unknown.
<code>EFI_MTFTP4_ERRORCODE_FILE_ALREADY_EXISTS</code>	The file already exists.
<code>EFI_MTFTP4_ERRORCODE_NO_SUCH_USER</code>	There is no such user.
<code>EFI_MTFTP4_ERRORCODE_REQUEST_DENIED</code>	The request has been denied due to option negotiation.

Status Codes Returned

<code>EFI_SUCCESS</code>	An MTFTPv4 OACK packet was received and is in the <i>Buffer</i> .
--------------------------	---

EFI_INVALID_PARAMETER	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Filename</i> is NULL. • <i>OptionCount</i> is not zero and <i>OptionList</i> is NULL. • One or more options in <i>OptionList</i> have wrong format. • <i>PacketLength</i> is NULL. • One or more IPv4 addresses in <i>OverrideData</i> are not valid unicast IPv4 addresses if <i>OverrideData</i> is not NULL.
EFI_UNSUPPORTED	<ul style="list-style-type: none"> • One or more options in the <i>OptionList</i> are in the unsupported list of structure EFI_MTFTP4_MODE_DATA.
EFI_NOT_STARTED	The EFI MTFTPv4 Protocol driver has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) has not finished yet.
EFI_ACCESS_DENIED	The previous operation has not completed yet.
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_TFTP_ERROR	An MTFTPv4 ERROR packet was received and is in the <i>Buffer</i> .
EFI_ICMP_ERROR	An ICMP ERROR packet was received and the Packet is set to NULL .
EFI_PROTOCOL_ERROR	An unexpected MTFTPv4 packet was received and is in the <i>Buffer</i> .
EFI_TIMEOUT	No responses were received from the MTFTPv4 server.
EFI_DEVICE_ERROR	An unexpected network error or system error occurred.

EFI_MTFTP4_PROTOCOL.ParseOptions()

Summary

Parses the options in an MTFTPv4 OACK packet.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_PARSE_OPTIONS) (
    IN EFI_MTFTP4_PROTOCOL *This,
    IN UINT32 PacketLen,
    IN EFI_MTFTP4_PACKET *Packet,
    OUT UINT32 *OptionCount,
    OUT EFI_MTFTP4_OPTION **OptionList OPTIONAL
);
```

Parameters

<i>This</i>	Pointer to the EFI_MTFTP4_PROTOCOL instance.
<i>PacketLen</i>	Length of the OACK packet to be parsed.
<i>Packet</i>	Pointer to the OACK packet to be parsed. Type EFI_MTFTP4_PACKET is defined in EFI_MTFTP4_PROTOCOL.GetInfo() .
<i>OptionCount</i>	Pointer to the number of options in following <i>OptionList</i> .
<i>OptionList</i>	Pointer to EFI_MTFTP4_OPTION storage. Call the EFI Boot Service FreePool() to release each option if they are not needed any more. Type EFI_MTFTP4_OPTION is defined in EFI_MTFTP4_PROTOCOL.GetInfo() .

Description

The **ParseOptions()** function parses the option fields in an MTFTPv4 OACK packet and returns the number of options that were found and optionally a list of pointers to the options in the packet.

If one or more of the option fields are not valid, then **EFI_PROTOCOL_ERROR** is returned and **OptionCount* and **OptionList* stop at the last valid option.

Status Codes Returned

EFI_SUCCESS	The OACK packet was valid and the <i>OptionCount</i> and <i>OptionList</i> parameters have been updated.
EFI_INVALID_PARAMETER	One or more of the following conditions is TRUE : <ul style="list-style-type: none"> • <i>PacketLen</i> is 0. • <i>Packet</i> is NULL or <i>Packet</i> is not a valid MTFTPv4 packet. • <i>OptionCount</i> is NULL.
EFI_NOT_FOUND	No options were found in the OACK packet.

EFI_OUT_OF_RESOURCES	Storage for the <i>OptionList</i> array cannot be allocated.
EFI_PROTOCOL_ERROR	One or more of the option fields is invalid.

EFI_MTFFTP4_PROTOCOL.ReadFile()

Summary

Downloads a file from an MTFFTPv4 server.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_MTFFTP4_READ_FILE) (
    IN EFI_MTFFTP4_PROTOCOL          *This,
    IN EFI_MTFFTP4_TOKEN            *Token
);

```

Parameters

<i>This</i>	Pointer to the EFI_MTFFTP4_PROTOCOL instance.
<i>Token</i>	Pointer to the token structure to provide the parameters that are used in this operation. Type EFI_MTFFTP4_TOKEN is defined in “Related Definitions” below.

Description

The **ReadFile()** function is used to initialize and start an MTFFTPv4 download process and optionally wait for completion. When the download operation completes, whether successfully or not, the *Token.Status* field is updated by the EFI MTFFTPv4 Protocol driver and then *Token.Event* is signaled (if it is not **NULL**).

Data can be downloaded from the MTFFTPv4 server into either of the following locations:

- A fixed buffer that is pointed to by *Token.Buffer*
- A download service function that is pointed to by *Token.CheckPacket*

If both *Token.Buffer* and *Token.CheckPacket* are used, then *Token.CheckPacket* will be called first. If the call is successful, the packet will be stored in *Token.Buffer*.

Related Definitions

```
//
*****
// EFI_MFTFP4_TOKEN
//
*****
typedef struct {
    OUT EFI_STATUS                Status;
    IN EFI_EVENT                  Event;
    IN EFI_MFTFP4_OVERRIDE_DATA  *OverrideData;
    IN UINT8                      *Filename;
    IN UINT8                      *ModeStr;
    IN UINT32                     OptionCount;
    IN EFI_MFTFP4_OPTION          *OptionList;
    IN OUT UINT64                 BufferSize;
    IN OUT VOID                   *Buffer;
    IN EFI_MFTFP4_CHECK_PACKET    CheckPacket;
    IN EFI_MFTFP4_TIMEOUT_CALLBACK TimeoutCallback;
    IN EFI_MFTFP4_PACKET_NEEDED   PacketNeeded;
} EFI_MFTFP4_TOKEN;
```

<i>Status</i>	The status that is returned to the caller at the end of the operation to indicate whether this operation completed successfully. Defined <i>Status</i> values are listed below.
<i>Event</i>	The event that will be signaled when the operation completes. If set to NULL , the corresponding function will wait until the read or write operation finishes. The type of <i>Event</i> must be EVT_NOTIFY_SIGNAL . The Task Priority Level (TPL) of <i>Event</i> must be lower than or equal to TPL_CALLBACK .
<i>OverrideData</i>	If not NULL , the data that will be used to override the existing configure data. Type EFI_MFTFP4_OVERRIDE_DATA is defined in EFI_MFTFP4_PROTOCOL.GetInfo() .
<i>Filename</i>	Pointer to the ASCIIZ file name string.
<i>ModeStr</i>	Pointer to the ASCIIZ mode string. If NULL , “octet” is used.
<i>OptionCount</i>	Number of option/value string pairs.
<i>OptionList</i>	Pointer to an array of option/value string pairs. Ignored if <i>OptionCount</i> is zero. Both a remote server and this driver implementation should support these options. If one or more options are unrecognized by this implementation, it is sent to the remote server without being changed. Type EFI_MFTFP4_OPTION is defined in EFI_MFTFP4_PROTOCOL.GetInfo() .
<i>BufferSize</i>	Size of the data buffer.
<i>Buffer</i>	Pointer to the data buffer. Data that is downloaded from the MFTFPv4 server is stored here. Data that is uploaded to the

<i>CheckPacket</i>	MTFTPv4 server is read from here. Ignored if <i>BufferSize</i> is zero.
<i>TimeoutCallback</i>	Pointer to the callback function to check the contents of the received packet. Type EFI_MTFTP4_CHECK_PACKET is defined below.
<i>PacketNeeded</i>	Pointer to the function to be called when a timeout occurs. Type EFI_MTFTP4_TIMEOUT_CALLBACK is defined below.
<i>PacketNeeded</i>	Pointer to the function to provide the needed packet contents. Only used in WriteFile() operation. Type EFI_MTFTP4_PACKET_NEEDED is defined below.

The **EFI_MTFTP4_TOKEN** structure is used for both the MTFTPv4 reading and writing operations. The caller uses this structure to pass parameters and indicate the operation context. After the reading or writing operation completes, the EFI MTFTPv4 Protocol driver updates the *Status* parameter and the *Event* is signaled if it is not **NULL**. The following table lists the status codes that are returned in the *Status* parameter.

Status Codes Returned in the Status Parameter

EFI_SUCCESS	The data file has been transferred successfully.
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_BUFFER_TOO_SMALL	<i>BufferSize</i> is not large enough to hold the downloaded data in downloading process.
EFI_ABORTED	Current operation is aborted by user.
EFI_ICMP_ERROR	An ICMP ERROR packet was received.
EFI_TIMEOUT	No responses were received from the MTFTPv4 server.
EFI_TFTP_ERROR	An MTFTPv4 ERROR packet was received.
EFI_DEVICE_ERROR	An unexpected network error or system error occurred.

```
//
*****
// EFI_MTFTP4_CHECK_PACKET
//
*****
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_CHECK_PACKET) (
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token,
    IN UINT16 PacketLen,
    IN EFI_MTFTP4_PACKET *Packet
);
```

This Pointer to the **EFI_MTFTP4_PROTOCOL** instance.

Token The token that the caller provided in the `EFI_MTFTP4_PROTOCOL.ReadFile()`, `WriteFile()` or `ReadDirectory()` function. Type `EFI_MTFTP4_TOKEN` is defined in `EFI_MTFTP4_PROTOCOL.ReadFile()`.

PacketLen Indicates the length of the packet.

Packet Pointer to an MTFTPv4 packet. Type `EFI_MTFTP4_PACKET` is defined in `EFI_MTFTP4_PROTOCOL.GetInfo()`.

`EFI_MTFTP4_CHECK_PACKET` is a callback function that is provided by the caller to intercept the `EFI_MTFTP4_OPCODE_DATA` or `EFI_MTFTP4_OPCODE_DATA8` packets processed in the `EFI_MTFTP4_PROTOCOL.ReadFile()` function, and alternatively to intercept `EFI_MTFTP4_OPCODE_OACK` or `EFI_MTFTP4_OPCODE_ERROR` packets during a call to `EFI_MTFTP4_PROTOCOL.ReadFile()`, `WriteFile()` or `ReadDirectory()`. Whenever an MTFTPv4 packet with the type described above is received from a server, the EFI MTFTPv4 Protocol driver will call `EFI_MTFTP4_CHECK_PACKET` function to let the caller have an opportunity to process this packet. Any status code other than `EFI_SUCCESS` that is returned from this function will abort the transfer process.

```
//
*****
// EFI_MTFTP4_TIMEOUT_CALLBACK
//
*****
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_TIMEOUT_CALLBACK) (
    IN EFI_MTFTP4_PROTOCOL    *This,
    IN EFI_MTFTP4_TOKEN      *Token
);
```

This Pointer to the `EFI_MTFTP4_PROTOCOL` instance.

Token The token that is provided in the `EFI_MTFTP4_PROTOCOL.ReadFile()` or `EFI_MTFTP4_PROTOCOL.WriteFile()` or `EFI_MTFTP4_PROTOCOL.ReadDirectory()` functions by the caller. Type `EFI_MTFTP4_TOKEN` is defined in `EFI_MTFTP4_PROTOCOL.ReadFile()`.

`EFI_MTFTP4_TIMEOUT_CALLBACK` is a callback function that the caller provides to capture the timeout event in the `EFI_MTFTP4_PROTOCOL.ReadFile()`, `EFI_MTFTP4_PROTOCOL.WriteFile()` or `EFI_MTFTP4_PROTOCOL.ReadDirectory()` functions. Whenever a timeout occurs, the EFI MTFTPv4 Protocol driver will call the `EFI_MTFTP4_TIMEOUT_CALLBACK` function to notify the caller of the timeout event. Any status code other than `EFI_SUCCESS` that is returned from this function will abort the current download process.

```
//
*****
// EFI_MTFTP4_PACKET_NEEDED
//
*****
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_PACKET_NEEDED) (
    IN EFI_MTFTP4_PROTOCOL    *This,
    IN EFI_MTFTP4_TOKEN      *Token,
    IN OUT UINT16             *Length,
    OUT VOID                  **Buffer
);
```

This Pointer to the **EFI_MTFTP4_PROTOCOL** instance.

Token The token provided in the **EFI_MTFTP4_PROTOCOL.WriteFile()** by the caller.

Length Indicates the length of the raw data wanted on input, and the length the data available on output.

Buffer Pointer to the buffer where the data is stored.

EFI_MTFTP4_PACKET_NEEDED is a callback function that the caller provides to feed data to the **EFI_MTFTP4_PROTOCOL.WriteFile()** function. **EFI_MTFTP4_PACKET_NEEDED** provides another mechanism for the caller to provide data to upload other than a static buffer. The EFI MTFTP4 Protocol driver always calls **EFI_MTFTP4_PACKET_NEEDED** to get packet data from the caller if no static buffer was given in the initial call to **EFI_MTFTP4_PROTOCOL.WriteFile()** function. Setting **Length* to zero signals the end of the session. Returning a status code other than **EFI_SUCCESS** aborts the session.

Status Codes Returned

EFI_SUCCESS	The data file is being downloaded.
EFI_INVALID_PARAMETER	<p>One or more of the parameters is not valid.</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.FileName</i> is NULL. • <i>Token.OptionCount</i> is not zero and <i>Token.OptionList</i> is NULL. • One or more options in <i>Token.OptionList</i> have wrong format. • <i>Token.Buffer</i> and <i>Token.CheckPacket</i> are both NULL. • One or more IPv4 addresses in <i>Token.OverrideData</i> are not valid unicast IPv4 addresses if <i>Token.OverrideData</i> is not NULL.

EFI_UNSUPPORTED	<ul style="list-style-type: none"> One or more options in the <i>Token.OptionList</i> are in the unsupported list of structure EFI_MTFTP4_MODE_DATA.
EFI_NOT_STARTED	The EFI MTFTPv4 Protocol driver has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_ALREADY_STARTED	This <i>Token</i> is being used in another MTFTPv4 session.
EFI_ACCESS_DENIED	The previous operation has not completed yet.
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_DEVICE_ERROR	An unexpected network error or system error occurred.

EFI_MTFTP4_PROTOCOL.WriteFile()

Summary

Sends a data file to an MTFTPv4 server. May be unsupported in some EFI implementations.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_WRITE_FILE) (
    IN EFI_MTFTP4_PROTOCOL          *This,
    IN EFI_MTFTP4_TOKEN             *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_MTFTP4_PROTOCOL instance.
<i>Token</i>	Pointer to the token structure to provide the parameters that are used in this function. Type EFI_MTFTP4_TOKEN is defined in EFI_MTFTP4_PROTOCOL.ReadFile() .

Description

The **WriteFile()** function is used to initialize an uploading operation with the given option list and optionally wait for completion. If one or more of the options is not supported by the server, the unsupported options are ignored and a standard TFTP process starts instead. When the upload process completes, whether successfully or not, *Token.Event* is signaled, and the EFI MTFTPv4 Protocol driver updates *Token.Status*.

The caller can supply the data to be uploaded in the following two modes:

- Through the user-provided buffer
- Through a callback function

With the user-provided buffer, the *Token.BufferSize* field indicates the length of the buffer, and the driver will upload the data in the buffer. With an **EFI_MTFTP4_PACKET_NEEDED** callback function, the driver will call this callback function to get more data from the user to upload. See the definition of **EFI_MTFTP4_PACKET_NEEDED** for more information. These two modes cannot be used at the same time. The callback function will be ignored if the user provides the buffer.

Status Codes Returned

EFI_SUCCESS	The upload session has started.
EFI_UNSUPPORTED	The operation is not supported by this implementation.

<p>EFI_INVALID_PARAMETER</p>	<p>One or more of the following conditions is TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.FileName</i> is NULL. • <i>Token.OptionCount</i> is not zero and <i>Token.OptionList</i> is NULL. • One or more options in <i>Token.OptionList</i> have wrong format. • <i>Token.Buffer</i> and <i>Token.PacketNeeded</i> are both NULL. • One or more IPv4 addresses in <i>Token.OverrideData</i> are not valid unicast IPv4 addresses if <i>Token.OverrideData</i> is not NULL.
<p>EFI_UNSUPPORTED</p>	<ul style="list-style-type: none"> • One or more options in the <i>Token.OptionList</i> are in the unsupported list of structure EFI_MTFTP4_MODE_DATA.
<p>EFI_NOT_STARTED</p>	<p>The EFI MTFTPv4 Protocol driver has not been started.</p>
<p>EFI_NO_MAPPING</p>	<p>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</p>
<p>EFI_ALREADY_STARTED</p>	<p>This <i>Token</i> is already being used in another MTFTPv4 session.</p>
<p>EFI_OUT_OF_RESOURCES</p>	<p>Required system resources could not be allocated.</p>
<p>EFI_ACCESS_DENIED</p>	<p>The previous operation has not completed yet.</p>
<p>EFI_DEVICE_ERROR</p>	<p>An unexpected network error or system error occurred.</p>

EFI_MTFFTP4_PROTOCOL.ReadDirectory()

Summary

Downloads a data file “directory” from an MTFFTPv4 server. May be unsupported in some EFI implementations.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MTFFTP4_READ_DIRECTORY) (
    IN EFI_MTFFTP4_PROTOCOL          *This,
    IN EFI_MTFFTP4_TOKEN             *Token
);
```

Parameters

<i>This</i>	Pointer to the EFI_MTFFTP4_PROTOCOL instance.
<i>Token</i>	Pointer to the token structure to provide the parameters that are used in this function. Type EFI_MTFFTP4_TOKEN is defined in EFI_MTFFTP4_PROTOCOL.ReadFile() .

Description

The **ReadDirectory()** function is used to return a list of files on the MTFFTPv4 server that are logically (or operationally) related to *Token.FileName*. The directory request packet that is sent to the server is built with the option list that was provided by caller, if present.

The file information that the server returns is put into either of the following locations:

- A fixed buffer that is pointed to by *Token.Buffer*
- A download service function that is pointed to by *Token.CheckPacket*

If both *Token.Buffer* and *Token.CheckPacket* are used, then *Token.CheckPacket* will be called first. If the call is successful, the packet will be stored in *Token.Buffer*.

The returned directory listing in the *Token.Buffer* or **EFI_MTFFTP4_PACKET** consists of a list of two or three variable-length ASCII strings, each terminated by a null character, for each file in the directory. If the multicast option is involved, the first field of each directory entry is the static multicast IP address and UDP port number that is associated with the file name. The format of the field is **ip:ip:ip:ip:port**. If the multicast option is not involved, this field and its terminating null character are not present.

The next field of each directory entry is the file name and the last field is the file information string. The information string contains the file size and the create/modify timestamp. The format of the information string is **filesize yyyy-mm-dd hh:mm:ss:ffff**. The timestamp is Coordinated Universal Time (UTC; also known as Greenwich Mean Time [GMT]).

Status Codes Returned

EFI_SUCCESS	The MTFFTPv4 related file "directory" has been downloaded.
EFI_UNSUPPORTED	The EFI MTFFTPv4 Protocol driver does not support this function.

EFI_INVALID_PARAMETER	<p>One or more of these conditions is TRUE:</p> <ul style="list-style-type: none"> • <i>This</i> is NULL. • <i>Token</i> is NULL. • <i>Token.FileName</i> is NULL. • <i>Token.OptionCount</i> is not zero and <i>Token.OptionList</i> is NULL. • One or more options in <i>Token.OptionList</i> have wrong format. <p><i>Token.Buffer</i> and <i>Token.CheckPacket</i> are both NULL.</p> <ul style="list-style-type: none"> • One or more IPv4 addresses in <i>Token.OverrideData</i> are not valid unicast IPv4 addresses if <i>Token.OverrideData</i> is not NULL.
EFI_UNSUPPORTED	One or more options in the <i>Token.OptionList</i> are in the unsupported list of structure EFI_MTFTP4_MODE_DATA .
EFI_NOT_STARTED	The EFI MTFTPv4 Protocol driver has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_ALREADY_STARTED	This <i>Token</i> is already being used in another MTFTPv4 session.
EFI_OUT_OF_RESOURCES	Required system resources could not be allocated.
EFI_ACCESS_DENIED	The previous operation has not completed yet.
EFI_DEVICE_ERROR	An unexpected network error or system error occurred.

EFI_MTF4_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_MTF4_POLL) (
    IN EFI_MTF4_PROTOCOL          *This
);
```

Parameters

This Pointer to the **EFI_MTF4_PROTOCOL** instance.

Description

The **Poll()** function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the **Poll()** function more often.

Status Codes Returned

EFI_SUCCESS	Incoming or outgoing data was processed.
EFI_NOT_STARTED	This EFI MTF4 Protocol instance has not been started.
EFI_NO_MAPPING	When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.
EFI_INVALID_PARAMETER	<i>This</i> is NULL .
EFI_DEVICE_ERROR	An unexpected system or network error occurred.
EFI_TIMEOUT	Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.

Security - Secure Boot, Driver Signing and Hash

26.1 Secure Boot

This protocol is intended to provide access for generic authentication information associated with specific device paths. The authentication information is configurable using the defined interfaces. Successive configuration of the authentication information will overwrite the previously configured information. Once overwritten, the previous authentication information will not be retrievable.

EFI_AUTHENTICATION_INFO_PROTOCOL

Summary

This protocol is used on any device handle to obtain authentication information associated with the physical or logical device.

GUID

```
#define EFI_AUTHENTICATION_INFO_PROTOCOL_GUID \
    {0x7671d9d0, 0x53db, 0x4173, 0xaa, 0x69, 0x23, 0x27, 0xf2, 0x1f, \
     0xb, 0xc7}
```

Protocol Interface Structure

```
typedef struct _EFI_AUTHENTICATION_INFO_PROTOCOL {
    EFI_AUTHENTICATION_PROTOCOL_INFO_GET    Get;
    EFI_AUTHENTICATION_PROTOCOL_INFO_SET    Set;
} EFI_AUTHENTICATION_INFO_PROTOCOL;
```

Parameters

<i>Get</i>	Used to retrieve the Authentication Information associated with the controller handle
<i>Set</i>	Used to set the Authentication information associated with the controller handle

Description

The **EFI_AUTHENTICATION_INFO_PROTOCOL** provides the ability to get and set the authentication information associated with the controller handle.

EFI_AUTHENTICATION_INFO_PROTOCOL.Get()

Summary

Retrieves the Authentication information associated with a particular controller handle.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_AUTHENTICATION_INFO_PROTOCOL_GET) {
    IN  EFI_AUTHENTICATION_INFO_PROTOCOL  *This,
    IN  EFI_HANDLE                        *ControllerHandle,
    OUT VOID                             *Buffer
}
```

Parameters

<i>This</i>	Pointer to the EFI_AUTHENTICATION_INFO_PROTOCOL
<i>ControllerHandle</i>	Handle to the Controller
<i>Buffer</i>	Pointer to the authentication information. This function is responsible for allocating the buffer and it is the caller's responsibility to free buffer when the caller is finished with buffer.

Description

This function retrieves the Authentication Node for a given controller handle.

Status Codes Returned

EFI_SUCCESS	Successfully retrieved Authentication information for the given <i>ControllerHandle</i>
EFI_INVALID_PARAMETER	No matching Authentication information found for the given <i>ControllerHandle</i>
EFI_DEVICE_ERROR	The authentication information could not be retrieved due to a hardware error.

EFI_AUTHENTICATION_INFO_PROTOCOL.Set()

Summary

Set the Authentication information for a given controller handle.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_AUTHENTICATION_INFO_PROTOCOL_SET) {
    IN  EFI_AUTHENTICATION_INFO_PROTOCOL  *This,
    IN  EFI_HANDLE                        *ControllerHandle
    IN  VOID                              *Buffer
}
```

Parameters

<i>This</i>	Pointer to the EFI_AUTHENTICATION_INFO_PROTOCOL
<i>ControllerHandle</i>	Handle to the controller.
<i>Buffer</i>	Pointer to the authentication information.

Description

This function sets the authentication information for a given controller handle. If the authentication node exists corresponding to the given controller handle this function overwrites the previously present authentication information.

Status Codes Returned

EFI_SUCCESS	Successfully set the Authentication node information for the given <i>ControllerHandle</i> .
EFI_UNSUPPORTED	If the platform policies do not allow setting of the Authentication information.
EFI_DEVICE_ERROR	The authentication node information could not be configured due to a hardware error.
EFI_OUT_OF_RESOURCES	Not enough storage is available to hold the data.

Authentication Nodes

The authentication node is associated with specific controller paths. There can be various types of authentication nodes, each describing a particular authentication method and associated properties.

Generic Authentication Node Structures

An authentication node is a variable length binary structure that is made up of variable length authentication information. [Table 170](#) defines the generic structure. The Authentication type GUID defines the corresponding authentication node.

Table 170. Generic Authentication Node Structure

Mnemonic	Byte Offset	Byte Length	Description
Type GUID	0	16	Authentication Type GUID
Length	16	2	Length of this structure in bytes.
Specific Authentication Data	18	n	Specific Authentication Data. Type defines the authentication method and associated type of data. Size of the data is included in the length.

All Authentication Nodes are byte-packed data structures that may appear on any byte boundary. All code references to Authentication Nodes must assume all fields are UNALIGNED. Since every Authentication Node contains a length field in a known place, it is possible to traverse Authentication Node of unknown type.

CHAP (using RADIUS) Authentication Node

This Authentication Node type defines the CHAP authentication using RADIUS information.

GUID

```
#define EFI_AUTHENTICATION_CHAP_RADIUS_GUID \
{0xd6062b50, 0x15ca, 0x11da, 0x92, 0x19, 0x00, 0x10, 0x83, 0xff, 0xca, \
0x4d}
```

Node Definition

Table 171. CHAP Authentication Node Structure using RADIUS

Mnemonic	Byte Offset	Byte Length	Description
Type	0	16	EFI_AUTHENTICATION_CHAP_RADIUS_GUID
Length	1	2	Length of this structure in bytes.
RADIUS IP Address	1	16	Radius IPv4 or IPv6 Address
Reserved	3	2	Reserved
NAS IP Address	3	16	NAS IPv4 or IPv6 Address
NAS Secret Length	5	2	NAS Secret Length
NAS Secret	5	p	NAS Secret
CHAP Secret Length	5	2	CHAP Secret Length
CHAP Secret	5	q	CHAP Secret
CHAP Name Length	5	2	CHAP Name Length
CHAP Name	5	r	CHAP Name String

Summary

RADIUS IP Address	RADIUS Server IPv4 or IPv6 Address
NAS IP Address	Network Access Server IPv4 or IPv6 Address (OPTIONAL)
NAS Secret Length	Network Access Server Secret Length in bytes (OPTIONAL)

NAS Secret Network Access Server secret (OPTIONAL)
 CHAP Secret Length CHAP Initiator Secret length in bytes
 CHAP Secret CHAP Initiator Secret
 CHAP Name Length CHAP Initiator Name Length in bytes
 CHAP Name CHAP Initiator Name
 CHAP (using local database)Authentication Node
 This Authentication Node type defines CHAP using local
 database information.

GUID

```
#define EFI_AUTHENTICATION_CHAP_LOCAL_GUID \
{0xc280c73e, 0x15ca, 0x11da, 0xb0, 0xca, 0x00, 0x10, 0x83, 0xff, 0xca, \
0x4d}
```

Node Definition

Table 172. CHAP Authentication Node Structure using Local Database

Mnemonic	Byte Offset	Byte Length	Description
Type	0	16	EFI_AUTHENTICATION_CHAP_LOCAL_GUID
Length	16	2	Length of this structure in bytes.
Reserved	18	2	Reserved for future use
User Secret Length	20	2	User Secret Length
User Secret	22	p	User Secret
User Name Length	22+p	2	User Name Length
User Name	24+p	q	User Name
CHAP Secret Length	24+p+q	2	CHAP Secret Length
CHAP Secret	26+p+q	r	CHAP Secret
CHAP Name Length	26+p+q+r	2	CHAP Name Length
CHAP Name	28+p+q+r	s	CHAP Name String

Summary

User Secret Length User Secret Length in bytes
 User Secret User Secret
 User Name Length User Name Length in bytes
 User Name User Name
 CHAP Secret Length CHAP Initiator Secret length in bytes
 CHAP Secret CHAP Initiator Secret
 CHAP Name Length CHAP Initiator Name Length in bytes
 CHAP Name CHAP Initiator Name

26.2 UEFI Driver Signing Overview

This section describes a means of generating a digital signature for a UEFI executable, embedding that digital signature within the UEFI executable and verifying that the digital signature is from an authorized source.

The UEFI specification provides a standard format for executables. These executables may be located on un-secured media (such as a hard drive or unprotected flash device) or may be delivered via a un-secured transport layer (such as a network) or originate from a un-secured port (such as ExpressCard device or USB device). In each of these cases, the system provider may decide to authenticate either the origin of the executable or its integrity (i.e. it has not been tampered with). This section describes a means of doing so.

26.2.1 Digital Signatures

As a rule, digital signatures require two pieces: the data (often referred to as the *message*) and a public/private key pair. In order to create a digital signature, the message is processed by a hashing algorithm to create a hash value. This hash value is, in turn, encrypted using a signature algorithm and the private key to create the digital signature.

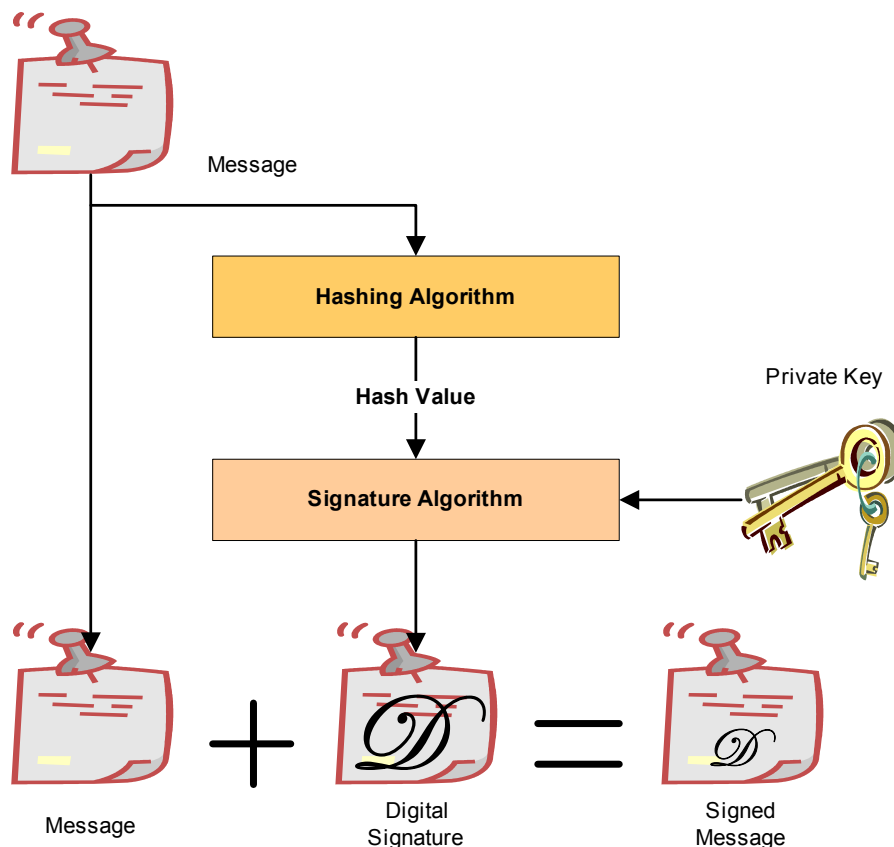


Figure 55. Creating A Digital Signature

In order to verify a signature, two pieces of data are required: the original message and the public key. First, the hash must be calculated exactly as it was calculated when the signature was created. Then the digital signature is decoded using the public key and the result is compared against the computed hash. If the two are identical, then you can be sure that message data is the one originally signed and it has not been tampered with.

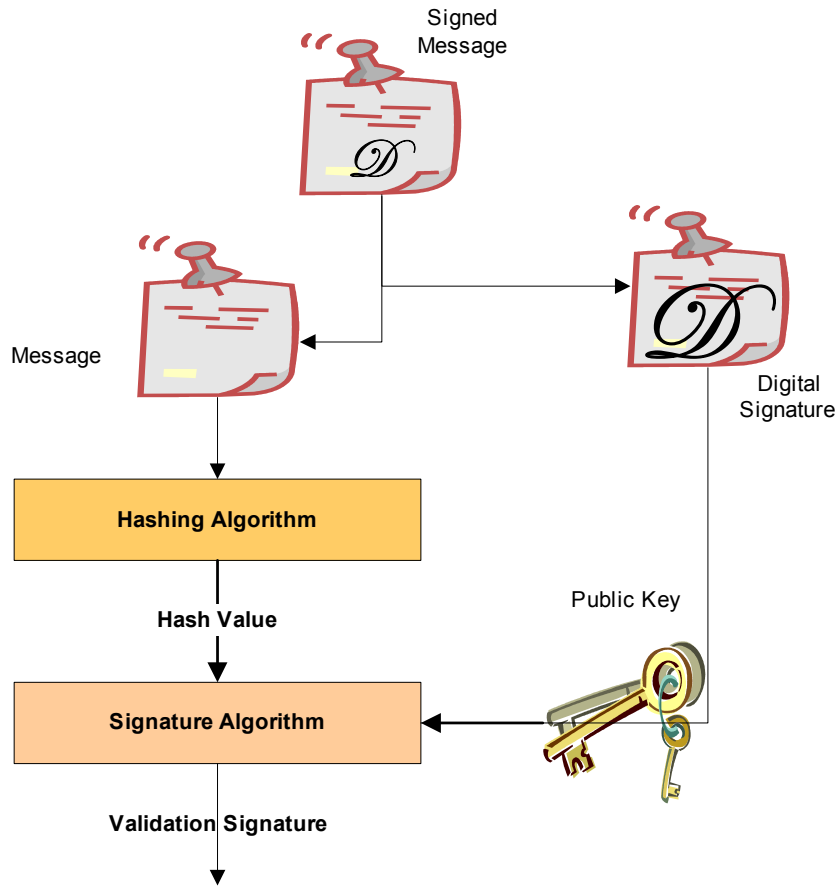


Figure 56. Verifying a Digital Signature

26.2.2 Embedded Signatures

The signatures used for digital signing of UEFI executables are embedded directly within the executable itself. Within the header is an array of directory entries. Each of these entries points to interesting places within the executable image. The fifth data directory entry contains a pointer to a list of certificates along with the length of the certificate areas. Each certificate may contain a digital signature used for validating the driver.

The following diagram illustrates how certificates are embedded in the PE/COFF file:

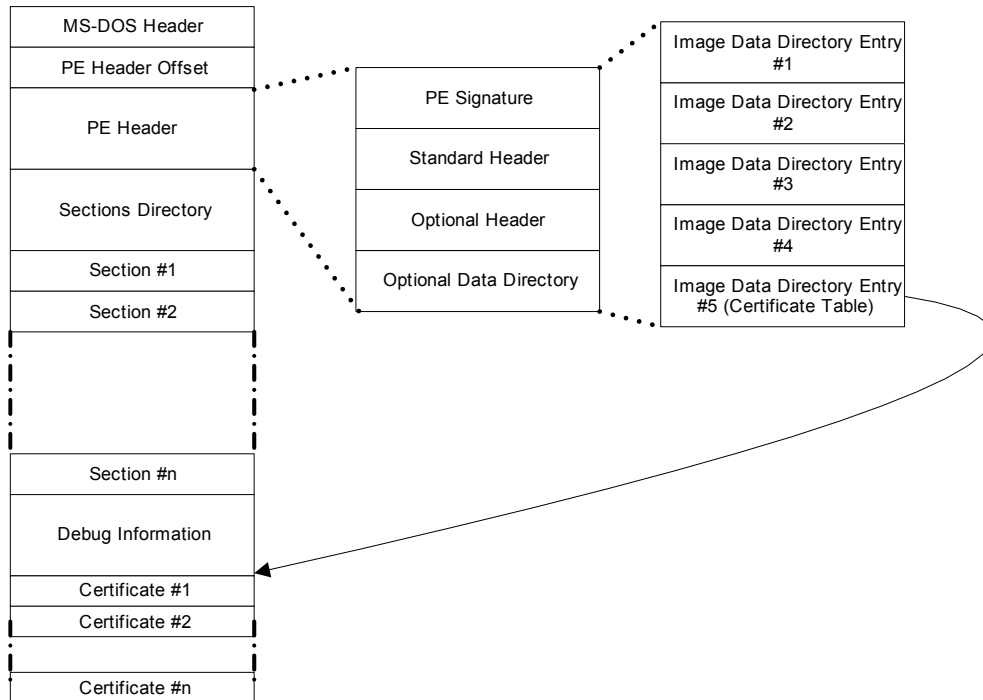


Figure 57. Embedded Digital Certificates

Within the PE/COFF optional header is a data directory. The 5th entry, if filled, points to a list of certificates. Normally, these certificates are appended to the end of the file.

26.2.3 Creating Message from Executables

One of the pieces required for creating a digital signature is the *message*. For a UEFI executable, the message is created from the PE/COFF image, starting at the first byte, but excluding the following portions:

- The checksum field in the PE/COFF header
- The certificate data directory structure (entry 5 in the data directory)
- The certificates themselves

26.2.4 Code Definitions

This section describes the new data structures used for signing UEFI executables.

WIN_CERTIFICATE

The **WIN_CERTIFICATE** structure is part of the PE/COFF specification and has the following definition:

```
typedef struct _WIN_CERTIFICATE {
    UINT32    dwLength;
    UINT16    wRevision;
    UINT16    wCertificateType;
    //UINT8    bCertificate[ANYSIZE_ARRAY];
} WIN_CERTIFICATE;
```

dwLength

The length of the entire certificate, including the length of the header, in bytes.

wRevision

The revision level of the **WIN_CERTIFICATE** structure. The current revision level is 0x0200.

wCertificateType

The certificate type. See **WIN_CERT_TYPE_XXX** for the UEFI certificate types. The UEFI specification reserves the range of certificate type values from 0x0EF0 to 0x0EFF.

bCertificate

The actual certificate. The format of the certificate depends on *wCertificateType*. The format of the UEFI certificates is defined below.

Prototype

```
typedef struct _WIN_CERTIFICATE_UEFI_GUID {
    WIN_CERTIFICATE    Hdr;
    EFI_GUID           CertType;
    UINT8              CertData[ANYSIZE_ARRAY];
} WIN_CERTIFICATE_UEFI_GUID;
```

Hdr

This is the standard **WIN_CERTIFICATE** header, where *wCertificateType* is set to **WIN_CERT_TYPE_UEFI_GUID**.

CertType

This is the unique id which determines the format of the *CertData*. In this case, the value is **EFI_CERT_TYPE_RSA2048_SHA256_GUID**.

CertData

This is the certificate data. The format of the data is determined by the *CertType*. In this case the value is **EFI_CERT_BLOCK_RSA_2048_SHA256**.

Information

The **WIN_CERTIFICATE_UEFI_GUID** certificate type allows new types of certificates to be developed for driver authentication without requiring a new certificate type. The *CertType* defines the format of the *CertData*, which length is defined by the size of the certificate less the fixed size of the **WIN_CERTIFICATE_UEFI_GUID** structure.

Related Definitions

```
#define WIN_CERT_TYPE_EFI_PKCS115    0x0EF0
#define WIN_CERT_TYPE_EFI_GUID       0x0EF1
#define EFI_CERT_TYPE_RSA2048_SHA256_GUID
{0xa7717414, 0xc616, 0x4977, {0x94, 0x20, 0x84, 0x47, 0x12,
0xa7, 0x35, 0xbf}}};

typedef struct _EFI_CERT_BLOCK_RSA_2048_SHA256 {
    UINT32                HashType;
    UINT8                 PublicKey[256];
    UINT8                 Signature[256];
} EFI_CERT_BLOCK_RSA_2048_SHA256;
```

WIN_CERTIFICATE_EFI_PKCS1_15

Description

Certificate which encapsulates the RSASSA_PKCS1-v1_5 digital signature.

Prototype

```
typedef struct _WIN_CERTIFICATE_EFI_PKCS1_15 {
    WIN_CERTIFICATE Hdr;
    EFI_GUID        HashAlgorithm;
    // UINT8        Signature[ANYSIZE_ARRAY];
} WIN_CERTIFICATE_EFI_PKCS1_15;
```

Hdr

This is the standard **WIN_CERTIFICATE** header, where *wCertificateType* is set to **WIN_CERT_TYPE_UEFI_PKCS1_15**.

HashAlgorithm

This is the hashing algorithm which was performed on the UEFI executable when creating the digital signature. It is one of the enumerated values pre-defined in [Section 26.4.1](#). See **EFI_HASH_ALGORITHM_x**.

Signature

This is the actual digital signature. The size of the signature is the same size as the key (1024-bit key is 128 bytes) and can be determined by subtracting the length of the other parts of this header from the total length of the certificate as found in *Hdr.dwLength*.

Information

The `WIN_CERTIFICATE_UEFI_PKCS1_15` structure is derived from `WIN_CERTIFICATE` and encapsulate the information needed to implement the RSASSA-PKCS1-v1_5 digital signature algorithm as specified in RFC2437.

26.2.5 WIN_CERTIFICATE_UEFI_GUID

Description

Certificate which encapsulates a GUID-specific digital signature.

Prototype

```
typedef struct WIN_CERTIFICATE_UEFI_GUID {
    WIN_CERTIFICATE    Hdr;
    EFI_GUID           CertType;
    UINT8              CertData[ANYSIZE_ARRAY];
} WIN_CERTIFICATE_UEFI_GUID;
```

<i>Hdr</i>	This is the standard <code>WIN_CERTIFICATE</code> header, where <i>wCertificateType</i> is set to <code>WIN_CERT_TYPE_UEFI_GUID</code> .
<i>CertType</i>	This is the unique id which determines the format of the <i>CertData</i> .
<i>CertData</i>	This is the certificate data. The format of the data is determined by the <i>CertType</i> .

Information

The UEFI GUID certificate type allows new types of certificates to be developed for driver authentication without requiring a new certificate type. The *CertType* defines the format of the *CertData*, which length is defined by the size of the certificate less the fixed size of the `WIN_CERTIFICATE_UEFI_GUID` structure.

26.3 Hash Overview

For the purposes of this specification, a hash function takes a variable length input and generates a fixed length hash value. In general, hash functions are *collision-resistant*, which means that it is infeasible to find two distinct inputs which produce the same hash value. Hash functions are generally *one-way* which means that it is infeasible to find an input based on the output hash value.

This specification describes a protocol which allows a driver to produce a protocol which supports zero or more hash functions.

26.3.1 Hash References

The following references define the standard means of creating the hashes used in this specification:

Secure Hash Signature Standard (SHS) (FIPS PUB 180-2), National Institute of Standards and Technology (August 1, 2002). See <http://csrc.nist.gov/publications/fips/fips180-2/fips180-2withchangenotice.pdf> (SHA-1, SHA-224, SHA-256, SHA-384, SHA-512)

MD5 Message-Digest Algorithm, R. Rivest (April 1992). See <http://www.ietf.org/rfc/rfc1321.txt>

26.4 EFI Hash Protocols

EFI_HASH_SERVICE_BINDING_PROTOCOL

Summary

The EFI Hash Service Binding Protocol is used to locate hashing services support provided by a driver and create and destroy instances of the EFI Hash Protocol so that a multiple drivers can use the underlying hashing services.

The EFI Service Binding Protocol that is defined in [Section 2.5.8](#) defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the EFI Hash Protocol.

GUID

```
#define EFI_HASH_SERVICE_BINDING_PROTOCOL \  
{0x42881c98, 0xa4f3, 0x44b0, 0xa3, 0x9d, 0xdf, 0xa1, 0x86, 0x67, \  
 0xd8, 0xcd};
```

Description

An application (or driver) that requires hashing services can use one of the protocol handler services, such as **BS->LocateHandleBuffer()**, to search for devices that publish an EFI Hash Service Binding Protocol. Each device with a published the EFI Hash Service Binding Protocol supports the EFI Hash Protocol and may be available for use.

After a successful call to the

EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild() function, the child EFI Hash Protocol driver instance is ready for use.

Before a network application terminates execution, every successful call to the

EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the **EFI_HASH_SERVICE_BINDING_PROTOCOL.DestroyChild()** function.

EFI_HASH_PROTOCOL

Summary

This protocol describes standard hashing functions.

GUID

```
#define EFI_HASH_PROTOCOL_GUID \
{0xc5184932,0xdba5,0x46db,0xa5,0xba,0xcc,0xb,0xda,0x9c,
0x14,0x35}
```

Protocol Interface Structure

```
typedef _EFI_HASH_PROTOCOL {
    EFI_HASH_GET_HASH_SIZE    GetHashSize;
    EFI_HASH_HASH              Hash;
} EFI_HASH_PROTOCOL;
```

Parameters

<i>GetHashSize</i>	Return the size of a specific type of resulting hash.
<i>Hash</i>	Create a hash for the specified message.

Description

This protocol allows creating a hash of an arbitrary message digest using one or more hash algorithms. The *GetHashSize* returns the expected size of the hash for a particular algorithm and whether or not that algorithm is, in fact, supported. The *Hash* actually creates a hash using the specified algorithm.

Related Definitions

None.

EFI_HASH_PROTOCOL.GetHashSize()

Summary

Returns the size of the hash which results from a specific algorithm.

Prototype

```

EFI_STATUS
EFIAPI
GetHashSize(
    IN CONST EFI_HASH_PROTOCOL  *This,
    IN CONST EFI_GUID           *HashAlgorithm,
    OUT UINTN                   *HashSize
);
    
```

Parameters

<i>This</i>	Points to this instance of EFI_HASH_PROTOCOL .
<i>HashAlgorithm</i>	Points to the EFI_GUID which identifies the algorithm to use. See Section 26.4.1.1 .
<i>HashSize</i>	Holds the returned size of the algorithm's hash.

Description

This function returns the size of the hash which will be produced by the specified algorithm.

Related Definitions

None

Status Codes Returned

EFI_SUCCESS	Hash size returned successfully.
EFI_INVALID_PARAMETER	<i>HashSize</i> is NULL
EFI_UNSUPPORTED	The algorithm specified by <i>HashAlgorithm</i> is not supported by this driver.

EFI_HASH_PROTOCOL.Hash()

Summary

Creates a hash for the specified message text.

Prototype

```

EFI_STATUS
EFIAPI
Hash (
    IN CONST EFI_HASH_PROTOCOL    *This,
    IN CONST EFI_GUID            *HashAlgorithm,
    IN BOOLEAN                   Extend,
    IN CONST UINT8               *Message,
    IN UINT64                    MessageSize,
    IN OUT EFI_HASH_OUTPUT      *Hash
);

```

Parameters

<i>This</i>	Points to this instance of EFI_HASH_PROTOCOL .
<i>HashAlgorithm</i>	Points to the EFI_GUID which identifies the algorithm to use. See Section 26.4.1.1 .
<i>Extend</i>	Specifies whether to create a new hash (FALSE) or extend the specified existing hash (TRUE).
<i>Message</i>	Points to the start of the message.
<i>MessageSize</i>	The size of <i>Message</i> , in bytes.
<i>Hash</i>	On input, if <i>Extend</i> is TRUE , then this holds the hash to extend. On output, holds the resulting hash computed from the message.

Description

This function creates the hash of the specified message text based on the specified algorithm *HashAlgorithm* and copies the result to the caller-provided buffer *Hash*. If *Extend* is **TRUE**, then the hash specified on input by *Hash* is extended. If *Extend* is **FALSE**, then the starting hash value will be that specified by the algorithm.

Related Definitions

EFI_HASH_OUTPUT

Status Codes Returned

EFI_SUCCESS	<i>Hash</i> returned successfully.
EFI_INVALID_PARAMETER	<i>Message</i> or <i>Hash</i> is NULL
EFI_UNSUPPORTED	The algorithm specified by <i>HashAlgorithm</i> is not supported by this driver.

EFI_UNSUPPORTED	<i>Extend</i> is TRUE and the algorithm doesn't support extending the hash.
-----------------	--

26.4.1 Other Code Definitions

EFI_SHA1_HASH, EFI_SHA224_HASH, EFI_SHA256_HASH, EFI_SHA384_HASH, EFI_SHA512HASH, EFI_MD5_HASH

Summary

Data structure which holds the result of the hash.

Prototype

```
typedef UINT8 EFI_MD5_HASH[16];
typedef UINT8 EFI_SHA1_HASH[20];
typedef UINT8 EFI_SHA224_HASH[28];
typedef UINT8 EFI_SHA256_HASH[32];
typedef UINT8 EFI_SHA384_HASH[48];
typedef UINT8 EFI_SHA512_HASH[64];
typedef union _EFI_HASH_OUTPUT {
    EFI_MD5_HASH      *Md5Hash;
    EFI_SHA1_HASH     *Sha1Hash;
    EFI_SHA224_HASH   *Sha224Hash;
    EFI_SHA256_HASH   *Sha256Hash;
    EFI_SHA384_HASH   *Sha384Hash;
    EFI_SHA512_HASH   *Sha512Hash;
} EFI_HASH_OUTPUT;
```

Description

These prototypes describe the expected hash output values from the *Hash* function of the **EFI_HASH_PROTOCOL**.

Related Definitions

None

26.4.1.1 EFI Hash Algorithms

The following table gives the **EFI_GUID** for standard hash algorithms and the corresponding ASN.1 OID (Object Identifier)

Table 173. EFI Hash Algorithms

Algorithm	EFI_GUID	OID
SHA-1	<pre>#define EFI_HASH_ALGORITHM_SHA1_GUID {0x2ae9d80f, 0x3fb2, 0x4095, { 0xb7, 0xb1, 0xe9, 0x31, 0x57, 0xb9, 0x46, 0xb6}}</pre>	<pre>id-sha1 OBJECT IDENTIFIER ::= { iso(1) identified- organization(3) oiw(14) secsig(3) algorithms(2) 26 }</pre>
SHA-224	<pre>#define EFI_HASH_ALGORITHM_SHA224_GUI D { 0x8df01a06, 0x9bd5, 0x4bf7, { 0xb0, 0x21, 0xdb, 0x4f, 0xd9, 0xcc, 0xf4, 0x5b } };</pre>	
SHA-256	<pre>#define EFI_HASH_ALGORITHM_SHA256_GUI D { 0x51aa59de, 0xfdf2, 0x4ea3, { 0xbc, 0x63, 0x87, 0x5f, 0xb7, 0x84, 0x2e, 0xe9 } };</pre>	<pre>id-sha256 OBJECT IDENTIFIER ::= { joint-iso-itu-t (2) country (16) us (840) organization (1) gov (101) csor (3) nistalgorithm (4) hashalgs (2) 1}</pre>
SHA-384	<pre>#define EFI_HASH_ALGORITHM_SHA384_GUI D { 0xefa96432, 0xde33, 0x4dd2, { 0xae, 0xe6, 0x32, 0x8c, 0x33, 0xdf, 0x77, 0x7a } };</pre>	<pre>id-sha384 OBJECT IDENTIFIER ::= { joint-iso-itu-t (2) country (16) us (840) organization (1) gov (101) csor (3) nistalgorithm (4) hashalgs (2) 2}</pre>
SHA-512	<pre>#define EFI_HASH_ALGORITHM_SHA512_GUI D { 0xcaa4381e, 0x750c, 0x4770, { 0xb8, 0x70, 0x7a, 0x23, 0xb4, 0xe4, 0x21, 0x30 } };</pre>	<pre>id-sha512 OBJECT IDENTIFIER ::= { joint-iso-itu-t (2) country (16) us (840) organization (1) gov (101) csor (3) nistalgorithm (4) hashalgs (2) 3}</pre>

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Algorithm	EFI_GUID	OID
MD5	<pre>#define EFI_HASH_ALGORTIHM_MD5_GUID { 0xaf7c79c, 0x65b5, 0x4319, { 0xb0, 0xae, 0x44, 0xec, 0x48, 0x4e, 0x4a, 0xd7 } };</pre>	<pre>id-md5 OBJECT IDENTIFIER ::= { iso (1) member-body (2) us (840) rsadsi (113549) digestAlgorithm (2) 5}</pre>

Human Interface Infrastructure Overview

This section defines the core code and services that are required for an implementation of the Human Interface Infrastructure (HII). This specification does the following:

- Describes the basic mechanisms to manage user input
- Provides code definitions for the HII-related protocols, functions, and type definitions that are architecturally required by the UEFI Specification

27.1 Goals

This chapter describes the mechanisms by which UEFI-compliant systems manage user input. The major areas described include the following:

- String and font management.
- User input abstractions (for keyboards and mice)
- Internal representations of the *forms* (in the HTML sense) that are used for running a preboot setup.
- External representations (and derivations) of the forms that are used to pass configuration information to runtime applications, and the mechanisms to allow the results of those applications to be driven back into the firmware.

General goals include:

- Simplified *localization*, the process by which the interface is adapted to a particular language.
- A "forms" representation mechanism that is rich enough to support the complex configuration issues encountered by platform developers, including stock keeping unit (SKU) management and interrelationships between questions in the forms.
- Definition of a mechanism to allow most or all the configuration of the system to be performed during boot, at runtime, and remotely. Where possible, the forms describing the configuration should be expressed using existing standards such as XML.
- Ability for the different drivers (including those from add-in cards) and applications to contribute forms, strings, and fonts in a uniform manner while still allowing innovation in the look and feel for Setup.

Support user-interface on a wide range of display devices:

- Local text display
- Local graphics display
- Remote text display
- Remote graphics display
- Web browser
- OS-present GUI

Support automated configuration without a display.

27.2 Design Discussion

This section describes the basic concepts behind the Human Interface Infrastructure. This is a set of protocols that allow a UEFI driver to provide the ability to register user interface and configuration content with the platform firmware. Unlike legacy option ROMs, the configuration of drivers and controllers is delayed until a platform management utility chooses to use the services of these protocols. UEFI drivers are not allowed to perform setup-like operations outside the context of these protocols. This means that a driver is not allowed to interact with the user outside the context of this protocol.

The following example shows a basic platform configuration or “setup” model. The drivers and applications install elements (such as fonts, strings, images and forms) into the HII Database, which acts as a central repository for the entire platform. The Forms Browser uses these elements to render the user interface on the display devices and receive information from the user via HID devices. When complete, the changes made by the user in the Forms Browser are saved, either to the UEFI global variable storage—(`GetVariable()` and `SetVariable()`)—or to variable storage provided by the individual drivers.

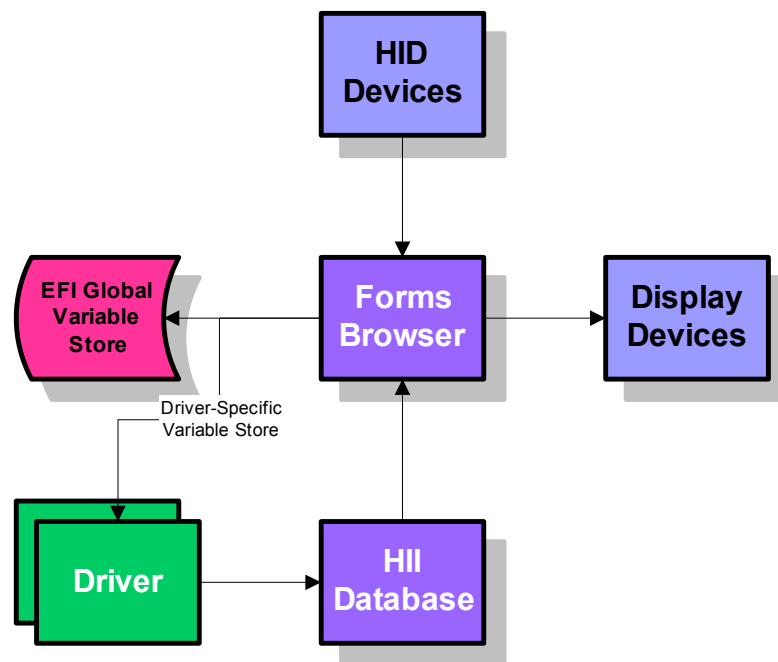


Figure 58. Platform Configuration Overview

27.2.1 Drivers And Applications

The user interface elements in the form of package lists are carried by the drivers and applications. Drivers and applications can create the package lists dynamically, or they can be pre-built and carried as resources in the driver/application image.

If they are stored as resources, then an editor can be used to modify the user interface elements without recompiling. For example, display elements can be modified or deleted, new languages added, and default values modified.

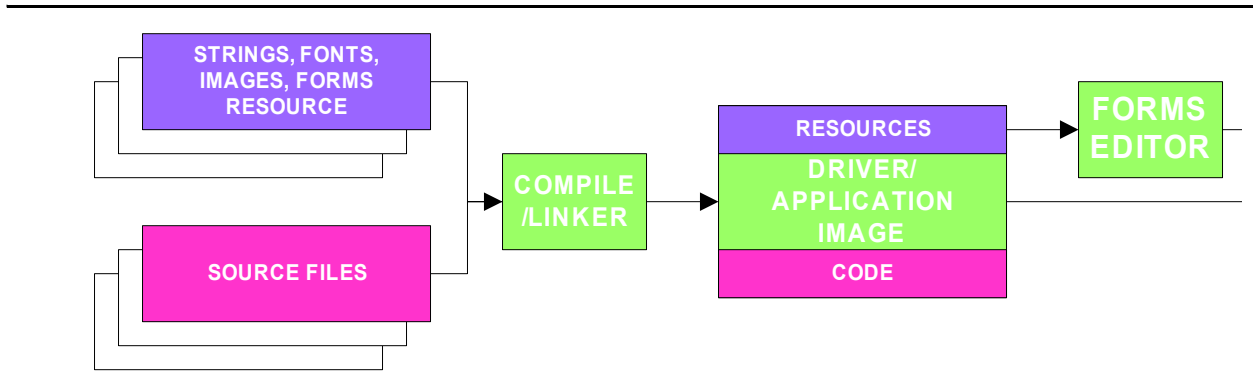


Figure 59. HII Resources In Drivers & Applications

The means by which the string, font, image and form resources are created is beyond the scope of this specification. The following diagram shows a few possible implementations. In both cases, the GUI design is an optional element and the user-interface elements are stored within a text-based resource file. Eventually, this source file is converted into a RES file (PE/COFF Resource Section) which can be linked with the main application.

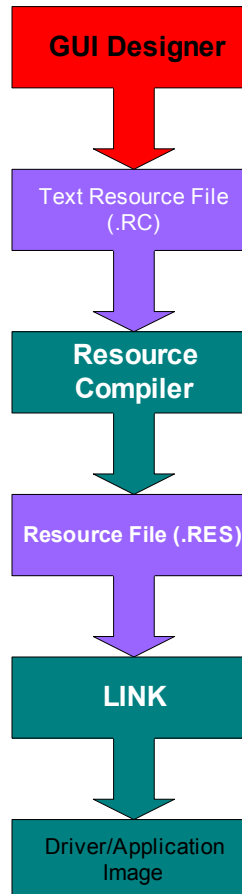


Figure 60. Creating UI Resources With Resource Files

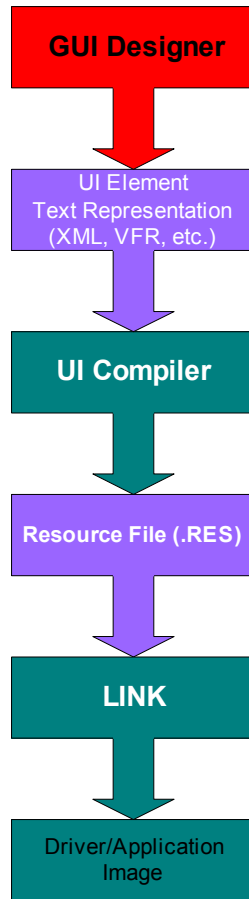


Figure 61. Creating UI Resources With Intermediate Source Representation

27.2.1.1 Platform and Driver Configuration

The intent is for this specification to enable the configuration of various target components in the system. The normally arduous task of managing user interface and configuration can be greatly simplified for the consumers of such functionality by enabling the platform to comprehend some standard user interactions.

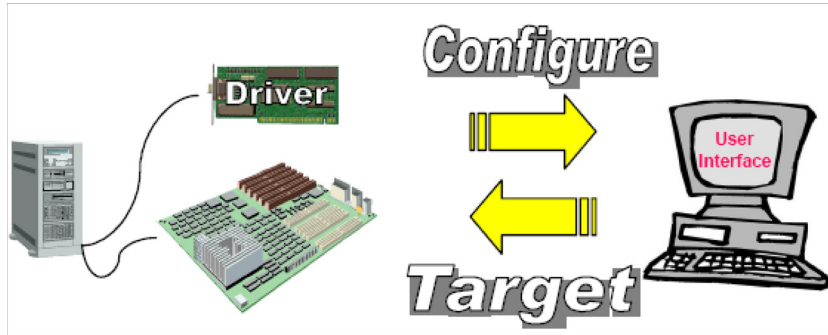


Figure 62. The Platform and Standard User Interactions

27.2.1.2 Pre-O/S applications

There are various scenarios where a platform component must interact in some fashion with the user. Examples of this are when presenting a user with several choices of information (e.g. boot menu) and sending information to the display (e.g. system status, logo, etc).

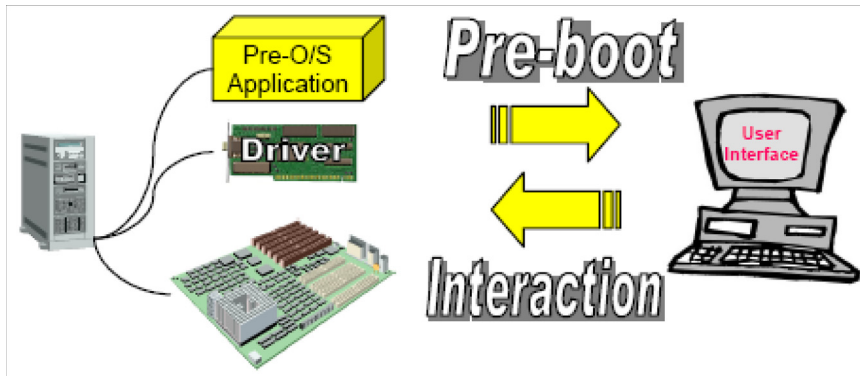


Figure 63. User and Platform Component Interaction

27.2.1.3 Description of User Interface Components

Various components listed in this specification are described in greater detail in their own sections. The user interface is composed of several distinct components illustrated below.

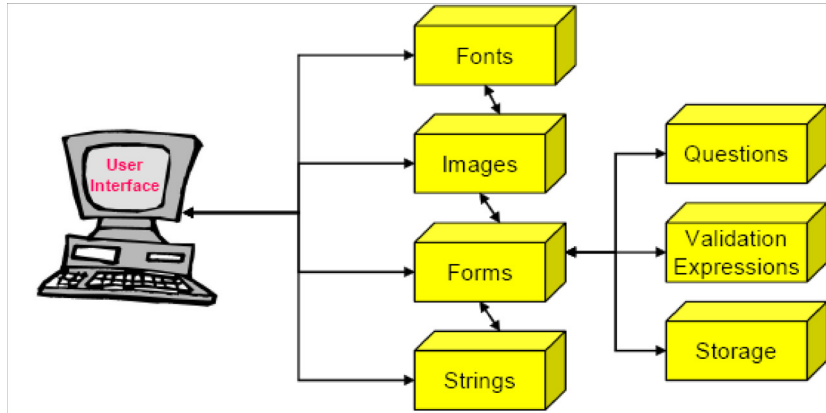


Figure 64. User Interface Components

27.2.1.4 Forms

This component describes what type of content needs to be displayed to the user by means of a binary encoding (i.e. Internal Forms Representation) and also has added context information such as how to validate certain input and further describes where to store such input if it is intended to be non-volatile. Applications such as a browser or script engine may use the information with the forms to validate configuration setting values with or without a user interface.

27.2.1.5 Strings

The strings are the text-based (UCS-2 encoded) representations of the information typically being referenced by the forms. The intent of this infrastructure is also to seamlessly enable multiple language support. To that end the strings have the appropriate language designators to differentiate one language from another.

27.2.1.6 Images/Fonts

Since most content is typically intended to have the ability to be rendered on the local system, the human interface infrastructure also supports the ability for images and fonts to be accepted and used by the underlying user interface components.

27.2.1.7 Consumers of the user interface data

The ultimate consumer of the user interface information will be some type of forms browser or forms processor. There are several usage scenarios which should be supported by this specification. These are illustrated below:

27.2.1.8 Connected forms browser/processor

The ability to have the forms processing engine render content when directly connected to the target platform should be apparent. From the forms processing engine perspective, this could be the local machine or a machine that is network attached. In either case, there is a constructed agent which feeds the material to the forms processor for purposes of rendering the user interface and interacting with the user. Note that a forms processor could simply act on the forms data without ever having to render the user interface and interact with the user. This situation is much more akin to script processing and should be a very supportable situation.

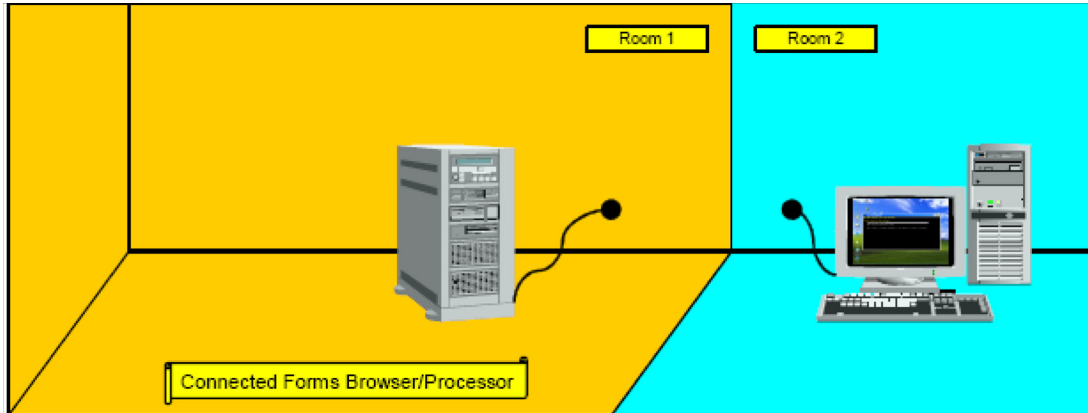


Figure 65. Connected Forms Browser/Processor

27.2.1.9 Disconnected Forms Browser/Processor

By enabling the ability to import and export a platform's settings, this infrastructure can also enable the ability for offline configuration. In this instance, a forms processor can interpret a given platform's form data and enable (either through user interaction or through automated scripting) the changing of configuration settings. These settings can then be applied to the target platform when a connection is established.

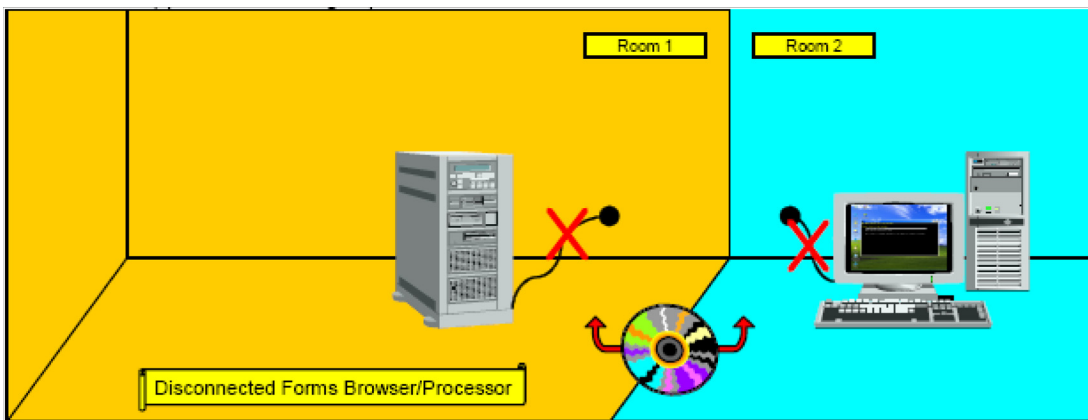


Figure 66. Disconnected Forms Browser/Processor

27.2.1.10 O/S-Present Forms Browser/Processor

When it is desired that the forms data be used in the presence of an O/S, this specification describes a means by which to support this capability. By being able to encapsulate the data and export it through standard means such that an O/S agent (e.g. forms browser/processor) can retrieve it, O/S-present usage models can be made available for further value-add implementations.

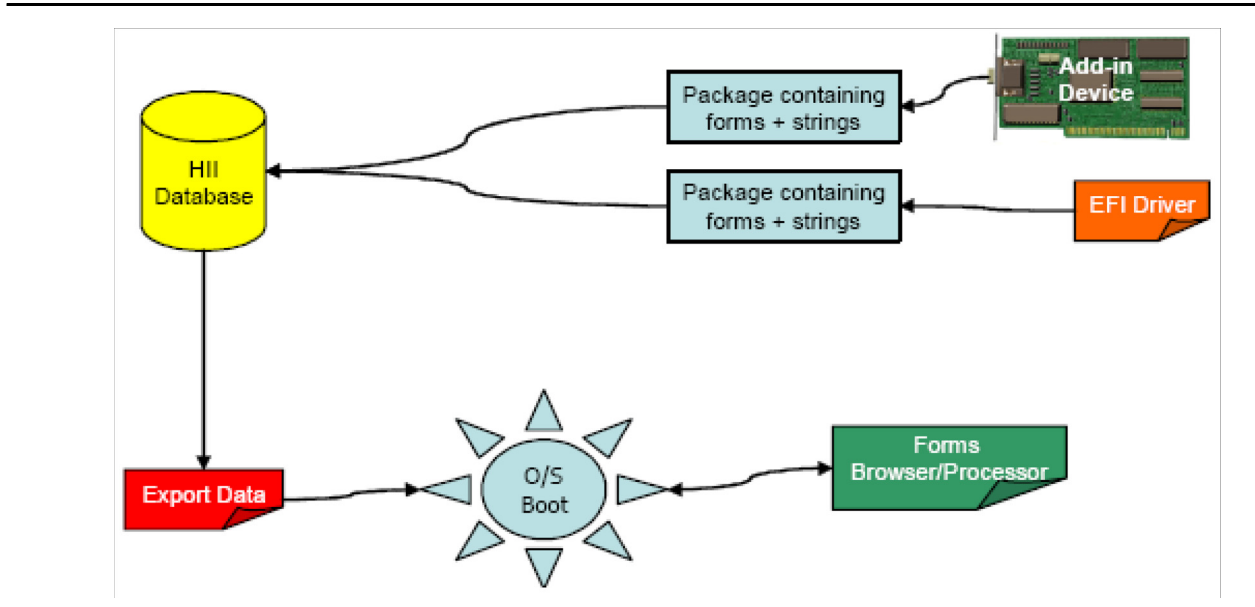


Figure 67. O/S-Present Forms Browser/Processor

27.2.1.11 Where are the Results Stored

The forms data encodes how to store the changes per configuration question. The ability to save data to the platform as well as to a proprietary on-board store is provided. The premise is that each of the target non-volatile store components (e.g. motherboard, add-in device, etc) would advertise an interface as described in this specification so that the forms browser/processor can route changes to the appropriate target.

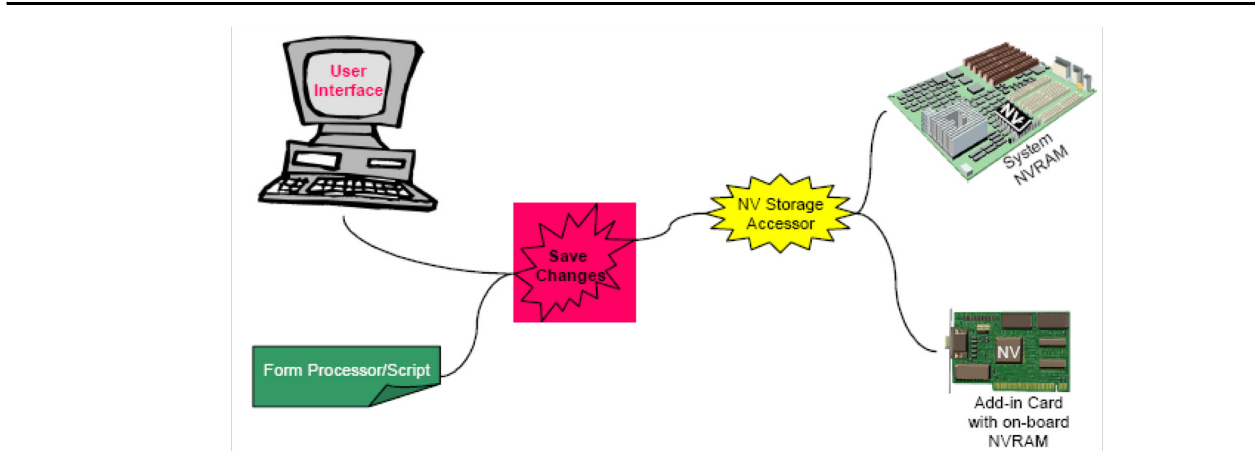


Figure 68. Platform Data Storage

27.2.2 Localization

Localization is the process by which the interface is adapted to a particular language. The table below discusses issues with localization and provides possible solutions.

Table 174. Localization Issues

Issue	Example	Solution	Comment
Directional display	Right to left printing for Hebrew.	Printing direction is a function of the language.	The display engine may or may not support all display techniques. If a language supports a display mechanism that the display engine does not, the language that uses the font must be selected.
Punctuation	Punctuation is directional. A comma in a right-to-left language is different from a comma in a left-to-right language.	Character choice is the choice of the author or translator.	
Line breakage	Rules vary from language to language.	The UEFI preboot GUI performs little or no formatting.	The runtime display depends on the runtime browser and is not defined here.
Date and time	Most Europeans would write July 4, 1776, as 4/7/1776 while the United States would write it 7/4/1776 and others would write 1776/7/4. The separator characters between the parts of both date and time vary as well.	Generally left to the creator of the user interface.	
Numbers	12,345.67 in one language is presented as 12.345,67 in another.	Print only integers and do not insert separator characters.	This solution is gaining acceptance around the world as more people use computers.

27.2.3 User Input

To limit the number of required glyphs, we must also limit the amount and type of user input.

User input generally comes from the following main types of devices:

- Keyboards
- Mouse-like pointing devices

Input from other devices, such as limited keys on a front panel, can be handled two ways:

- Treat the limited keys as special-purpose devices with completely unique interfaces.

- Programmatically make the limited keys mimic a keyboard or mouse-like pointing device.

Pointing devices require no localization. They are universally understood by the subset of the world population addressed in this specification. For example, if a person does not know how to use a mouse or other pointing device, it is probably not a good idea to allow that person to change a system's configuration.

On the other hand, keyboards are localized at the keycaps but not in the electronics. In other words, a French keyboard and a German keyboard might have very different keys but the software inside the keyboard—let alone the software in the system at the other end of the wire—cannot know which set of keycaps are installed.

This specification proposes to solve this issue by using the keys that are common between keyboards and ignoring language-specific keys. Keys that are available on USB keyboards in preboot mode include the following:

- Function keys (F1 – F12)
- Number keys (0-9)
- "Upside down T" cursor keys (the arrows, home, end, page up, page down)
- Numeric keypad keys
- The Enter, Space, Tab, and Esc keys
- Modifier keys (shifts, alts, controls, Windows*)
- Number lock

The scan codes for these keys do not vary from language to language. These keys are the standard keys used for browser navigation although most end-users are unaware of this fact. Help for form-entry-specific keys must be provided to enable a useful keys-only interface. The one case where other, language-specific keys may be used is to enter passwords. Because passwords are never displayed, there is no requirement to translate scan code to Unicode (keyboard localization) or scan code to font.

Additional data can be provided to enable a richer set of input characters. This input is necessary to support features such as arbitrary text input and passwords.

27.2.4 Keyboard Layout

27.2.4.1 Keyboard Mapping

UEFI's keyboard mapping loosely based definitions on ISO 9995. It bases the naming mechanism on the figure below. The keys highlighted in brown are the keys that nearly all keyboard layouts use for customizations. However, customization does not necessarily mean that all the keys are different. In fact, most of the keys are likely to be the same. When modifying the mapping, one can normally reference the keys in brown as the likely candidates (for whom to create modifications).

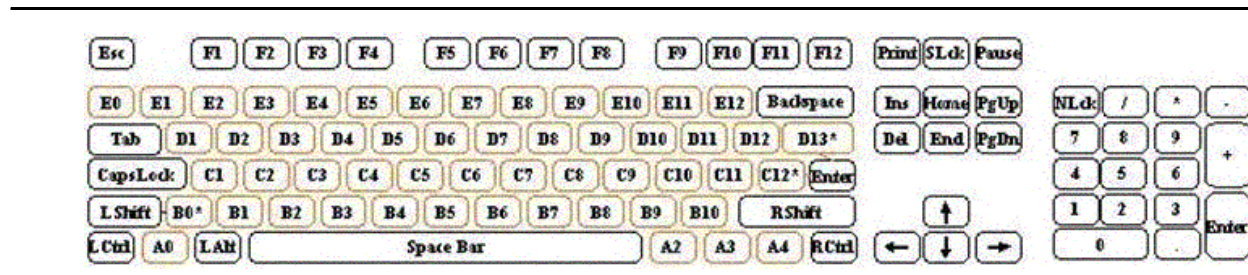


Figure 69. Keyboard Layout

Instead of referencing keys in hardware-specific ways such as scan codes, the HII specification defines an **EFI KEY** enumeration that allows for a simple method of referencing this hardware abstraction. Type **EFI_KEY** is defined in [EFI HII DATABASE PROTOCOL.GetKeyboardLayout\(\)](#). It also provides a way to update the keyboard layout with a great deal of flexibility. Any of the keys can be mapped to any Unicode value or control code value.

When defining the values for a particular key, there are six elements that are pertinent to the key:

Key name:

The EFI_KEY enumeration defines the names of the above keys.

Unicode value:

Defines the Unicode value (if any) of the named key.

Shifted Unicode value:

Defines the Unicode value (if any) of the named key while the shift modifier key is being pressed

Alt-GR Unicode value:

Defines the Unicode value (if any) of the named key while the Alt-GR modifier key (if any) is being pressed.

Shifted Alt-GR Unicode value:

Defines the Unicode value (if any) of the named key while the Shift and Alt-GR modifier key (if any) is being pressed.

Modifier key value:

Defines the nonprintable special function that this key has assigned to it.

Under normal circumstances, a key that has any Unicode definitions generally has a modifier key value of **EFI_NULL_MODIFIER**. This value means the key has no special function other than the printing of a character. An exception to the rule is if any of the Unicode values have a value of 0xFFFF. Although rarely used, this value is the one case in which a key might have both a printable character and an active control key value.

An example of this exception would be the numeric keypad’s insert key. The definition for this key on a standard US keyboard is as follows:

```
Key = EfiKeyZero
Unicode = 0x0030 (basically a '0')
```

```

ShiftedUnicode = 0xFFFF (the exception to the rule)
AltGrUnicode = 0x0000
ShiftedAltGrUnicode = 0x0000
Modifier = EFI_INSERT_MODIFIER

```

This key is one of the few keys that, under normal circumstances, prints something out but also has a special function. These special functions are generally limited to the numeric keypad; however, this general limitation does not prevent someone from having the flexibility of defining these types of variations.

27.2.4.2 Modifier Keys

The definitions of the modifier keys allow for special functionality that is not necessarily accomplished by a printable character. Many of these modifier keys are flags to toggle certain state bits on and off inside of a keyboard driver. An example is [EFI CAPS LOCK MODIFIER](#). This state being active could alter what the typing of a particular key produces. Other control keys, such as [EFI LEFT ARROW MODIFIER](#) and [EFI END MODIFIER](#), affect the position of the cursor. One modifier key is likely unfamiliar to most people who exclusively use US keyboards, and that key is the [EFI ALT GR MODIFIER](#) key. This key's primary purpose is to activate a secondary type of shift modifier that exposes additional printable characters on certain keys. In some keyboard layouts, this key does not exist and is normally the [EFI RIGHT ALT MODIFIER](#) key. None of the other modifier key functions should be a mystery to someone familiar with the usage of a standard computer keyboard.

An example of a few descriptor entries would be as follows:

```

Layout = {
  EfiKeyLCtrl,0,0,0,0,EFI_LEFT_CONTROL_MODIFIER, //Left control
                                                    // key
  EfiKeyA0,0,0,0,0,EFI_NULL_MODIFIER,           //Not defined
                                                    // windows key
  EfiKeySpaceBar,0x0020,0x0020,0x0020,0x0020,EFI_NULL_MODIFIER
                                                    //(Space Bar)
}

```

See Related Definitions in [EFI HII DATABASE PROTOCOL.GetKeyboardLayout\(\)](#) for the defined modifier values.

27.2.4.3 Non-spacing Keys

Non-spacing keys are a concept that provides the ability to **OR** together an accent key and another printable character. Non-spacing keys are defined as special types of modifier characters. They are typically accent keys that do not advance the cursor and in essence are a type of modifier key in that they maintain some level of state.

The way a person uses a non-spacing key is that the non-spacing key that maybe has the function of overlaying an umlaut (two dots) onto whatever the next character might be. The user presses the umlaut non-spacing key and follows it with a capital A, which yields an "Ä."

An example of a few descriptor entries would be as follows:

```

//
// If it's a dead key, we need to pass a list of physical key
// names, each with a unicode, shifted, altgr, shiftedaltgr
// value. Each key name will have a Modifier value of

```

```

// EFI_NS_KEY_MODIFIER for the first entry, and then the list of
// EFI_NS_KEY_DEPENDENCY_MODIFIER physical key descriptions.
// This eventually will lead to the next normal non-modifier key
// definition.
//
// This requires defining an additional Modifier value of
// EFI_NS_KEY_DEPENDENCY_MODIFIER to signify
// EFI_NS_KEY_MODIFIER children definitions.
//
// The keyboard driver (consumer of the layouts) will know that
// any key definitions with the EFI_NS_KEY_DEPENDENCY_MODIFIER
// modifier do not redefine the value of the specified EFI_KEY.
// They are simply used as a special case augmentation to the
// original EFI_NS_KEY_MODIFIER.
//
// It is an error condition to define a
// EFI_NS_KEY_MODIFIER without having all the
// EFI_NS_KEY_DEPENDENCY_MODIFIER keys defined serially.
//
Layout = {
  EfiKeyE0, 0, 0, 0, 0, EFI_NS_KEY_MODIFIER,
  EfiKeyC1, 0x00E2, 0x00C2, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
  EfiKeyD3, 0x00EA, 0x00CA, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
  EfiKeyD8, 0x00EC, 0x00CC, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
  EfiKeyD9, 0x00F4, 0x00D4, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
  EfiKeyD7, 0x00FB, 0x00CB, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
}

```

In the above example, a key located at E0 is designated as a dead key. Using a common German keyboard layout as the example, a circumflex accent "^" is defined as a dead key at the E0 location. The A, E, I, O, and U characters are valid keys that can be pressed after the dead key and will produce a valid printable character. These characters are located at C1, D3, D8, D9, and D7 respectively.

The results of the *Layout* definition provided above would allow for the production of the following characters: âÂÊËÎÔÛÛ.

27.2.5 Forms

This specification describes how a UEFI driver or application may present a forms (or dialogs) based interface. The forms-based interface assumes that each window or screen consists of some window dressing (title & buttons) and a list of questions. These questions represent individual configuration settings for the application or driver, although several GUI controls may be used for one question.

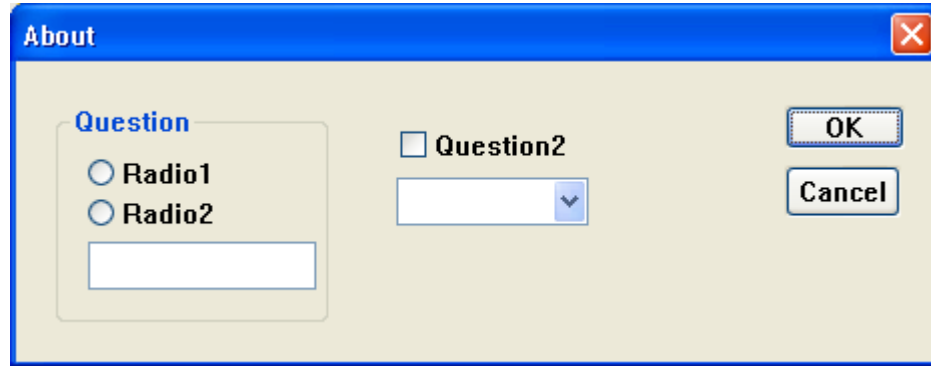


Figure 70. Forms-based Interface Example

The forms are stored in the HII database, along with the strings, fonts and images. The various attributes of the forms and questions are encoded in IFR (Internal Forms Representation)—with each object and attribute a byte stream.

Other applications (so-called “Forms Processors”) may use the information within the forms to validate configuration setting values without a user interface at all.

The Forms Browser provides a forms-based user interface which understands how to read the contents of the forms, interact with the user, and save the resulting values. The Forms Browser uses forms data installed by an application or driver during initialization in the HII database. The Forms Browser organizes the forms so that a user may navigate between the forms, select the individual questions and change the values using the HID and display devices. When the user has finished making modifications, the Forms Browser saves the values, either to the global EFI variable store or else to a private variable store provided by the driver or application.

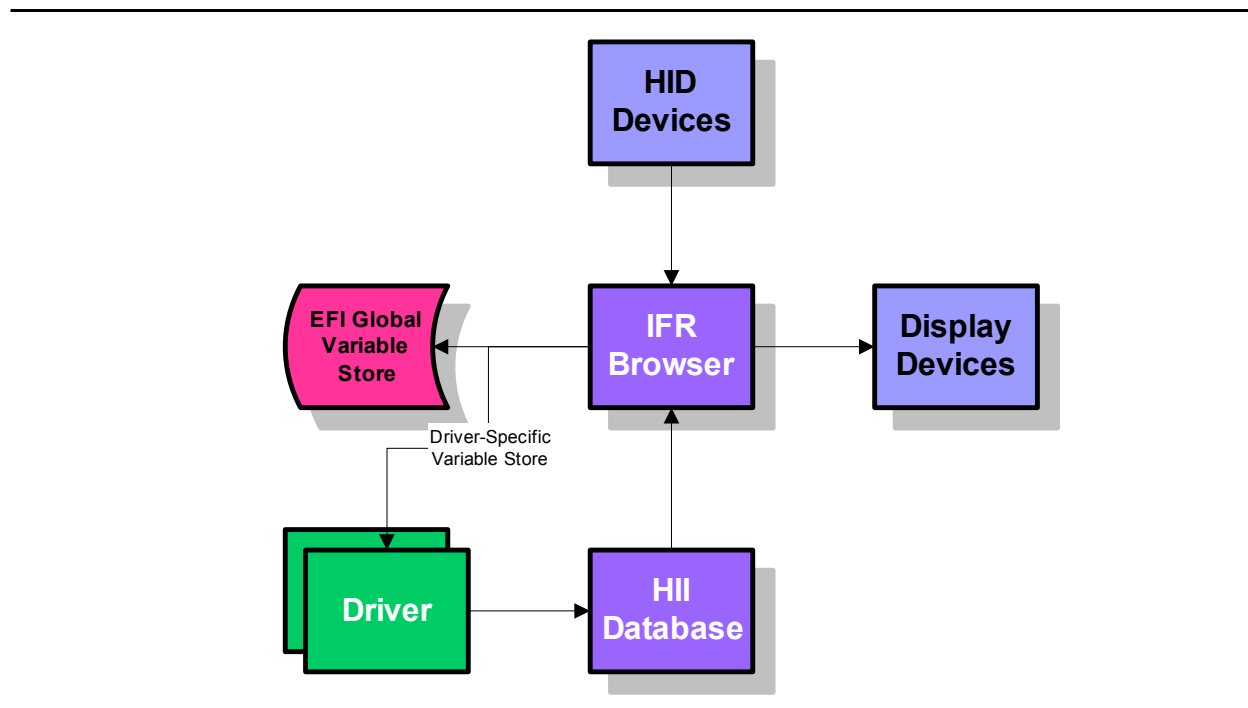


Figure 71. Platform Configuration Overview

27.2.5.1 Form Sets

Form sets are logically-related groups of forms. Each forms set has the following attributes:

- **Form Set Identifier.** Uniquely identifies the form set list using a GUID. The Form Set Identifier, along with a device path, uniquely identifies a form set in a system.
- **Title.** Title text for the form set.
- **Help.** Help text for the form set.
- **Image.** Title image for the form set.

Within a form set, there is one *parent* form and zero or more *child* forms. The parent form is the first enabled, visible form in the form set. The child forms are the second or later enabled, visible forms in the form set. In general, the Forms Browser will provide a means to navigate to the parent form. A cross-reference (see [Section 27.2.5.3.10](#)) is used to navigate between forms within a form set or between forms in different form sets.

Variable stores are declared within a form set. Variable stores describe the means for retrieval and storage of configuration settings, and location information within that variable store. For more information, see [Section 27.2.5.6](#).

Default stores are declared within a form set. Default stores group together different types of default settings (normal, manufacturing, etc.) and give them a name. See [Section 27.2.5.8](#) for more information.

The form set can control whether or not to process an individual form by nesting it inside of an **EFI_IFR_DISABLE_IF** expression. See [Section 27.2.5.2.3](#) for more information.

27.2.5.1.1 Syntax

The form set consists of an **EFI_IFR_FORM_SET** object, where the body consists of

```

form-set := EFI_IFR_FORM_SET form-set-list
form-set-list:=form form-set-list |
           EFI_IFR_IMAGE form-set-list |
           EFI_IFR_VARSTORE form-set-list |
           EFI_IFR_VARSTORE_EFI form-set-list |
           EFI_IFR_VARSTORE_NAME_VALUE form-set-list |
           EFI_IFR_DEFAULTSTORE |
           EFI_IFR_DISABLE_IF expression form-set-list |
<empty>

```

27.2.5.2 Forms

Forms are logically-related groups of statements (including questions) designed to be displayed together.

27.2.5.2.1 Attributes

Each form has the following attributes:

- Form Identifier

A 16-bit unsigned integer, which uniquely identifies the form within the form set. The Form Identifier, along with the device path and Form Set Identifier, uniquely identifies a form within a system.
- Title

Title text for the form. The Forms Browser may use this text to describe the nature and purpose of the form in a window title.
- Image

Title image for the form. The Forms Browser may use this image to display the nature and purpose of the form in a window title.

The form set can control whether or not to process a statement by nesting it inside of an **EFI_IFR_DISABLE_IF** expression. See [Section 27.2.5.3.4](#) for more information.

The form can control whether a particular statement is selectable by nesting it inside of an **EFI_IFR_GRAY_OUT_IF** expression. Statements that cannot be selected are displayed by Form Browsers, but cannot be selected by a user. **EFI_IFR_GRAY_OUT_IF** causes statements to be displayed with some visual indication. See [Section 27.2.5.3.6](#) for more information.

27.2.5.2.2 Syntax

The form consists of an **EFI_IFR_FORM** object, where the body consists of:

```

form := EFI_IFR_FORM form-tag-list
form-tag-list:=form-tag form-tag-list | <empty>
form-tag:=EFI_IFR_IMAGE |

```

EFI_IFR_LOCKED |
EFI_IFR_RULE |
default |
statement |
question |
cond-statement-list |
 <empty>

statement-list := *statement statement-list* |
 question statement-list |
 cond-statement-list |
 <empty>

cond-statement-list := **EFI_IFR_DISABLE_IF** *expression statement-list* |
 EFI_IFR_SUPPRESS_IF *expression statement-list* |
 EFI_IFR_GRAY_OUT_IF *expression statement-list* |
question-list := *question question-list* |
 <empty>

Other unknown opcodes are permitted, but will be ignored.

27.2.5.2.3 Enable/Disable

Disabled forms will not be processed at all by a Forms Processor. Forms are enabled unless:

- The form nests inside an **EFI_IFR_DISABLE_IF** expression which evaluated to false.
- The disabling of forms is evaluated during Forms Processor initialization and is not re-evaluated.

27.2.5.2.4 Modifiability

Forms can be locked so that a Forms Editor will not change it. Forms are unlocked unless:

- The form has an **EFI_IFR_LOCKED** in its scope.

The locking of statement is evaluated only during Forms Editor initialization.

27.2.5.3 Statements

All displayable items within the body of a form are statements. Statements provide information or capabilities to the user. Questions (see [Section 27.2.5.4](#)) are a specialized form of statement with a value. Statements are used only by Forms Browsers and are ignored by other Forms Processors.

27.2.5.3.1 Attributes

Statements have the following attributes:

- Prompt

The text that will be displayed with the statement.

- Help

The extended descriptive text that can be displayed with the statement.

- Image

The image that will be displayed with the statement.

Other than Questions, there are three types of statements:

- Static Text/Image
- Subtitle
- Cross-Reference

27.2.5.3.2 Syntax

statement := *subtitle* | *static-text* | *cross-reference*

statement-tag-list := *statement-tag* *statement-tag-list* |

<empty>

statement-tag := **EFI_IFR_IMAGE** |

EFI_IFR_LOCKED

27.2.5.3.3 Display

Statement display depends on the Forms Browser. Statements *do not* describe how the statement must be displayed but rather provide resources (such as text and images) for use by the Forms Browser. The Forms Browser uses this information to create the necessary user interface.

The Forms Browser may use the visibility (see [Section 27.2.5.3.5](#)) or selectability (see [Section 27.2.5.3.6](#)) of the statements to change the way the item is displayed. The **EFI_IFR_GRAY_OUT_IF** expression explicitly requires that nested statements have visual differentiation from normal statements.

27.2.5.3.4 Enable/Disable

Statements which have been disabled will not be processed at all by a Forms Processor. Statements are enabled unless:

- The parent statement or question is disabled.
- The statement is nested inside an **EFI_IFR_DISABLE_IF** expression which evaluated to false.
- The disabling of statements is evaluated during Forms Browser initialization and is not re-evaluated.

27.2.5.3.5 Visibility

Suppressed statements will not be displayed. Statements are displayed unless:

- The parent statement or question is suppressed.
- The statement is disabled (see [Section 27.2.5.3.4](#))
- The statement is nested inside an **EFI_IFR_SUPPRESS_IF** expression which evaluates to false.

The suppression of the statements is evaluated during Forms Browser initialization. Subsequently, the suppression of statements is reevaluated each time a value in any question on the selected form has changed.

27.2.5.3.6 Evaluation of Selectable Statements

A user in a Forms Browser can choose statements which are selectable. Statements are selectable unless:

- The parent statement or question is not selectable.
- The statement is suppressed (see [Section 27.2.5.3.4](#)).
- The statement is nested inside an **EFI_IFR_GRAY_OUT_IF** expression which evaluated to false.

The evaluation of selectable statements takes place during Forms Browser initialization. Subsequently, selectable statements are reevaluated each time a value in any question on the selected form has changed.

27.2.5.3.7 Modifiability

A statement can be locked so that a Forms Editor will not change it. Statements are unlocked unless:

- The parent form or parent statement/question is locked.
- The statement has an **EFI_IFR_LOCKED** in its scope.

The locking of a statement is evaluated only during Forms Editor initialization.

27.2.5.3.8 Static Text/Image

The Forms Browser displays the specified prompt, the specified text and (optionally) the image, but has no user interaction.

Syntax

static-text := **EFI_IFR_TEXT** *statement-tag-list*

27.2.5.3.9 Subtitle

The subtitle is a means of visually grouping questions by providing a separator, some optional separating text, and an optional image.

Syntax

subtitle := **EFI_IFR_SUBTITLE** *statement-tag-list*

27.2.5.3.10 Cross-Reference

The Forms Browser displays a means by which users navigate to other forms within the current form set, or within another installed form set. If the specified form or question does not exist, the button is not selectable, is grayed-out, or is suppressed.

Attributes

Cross references have the following attributes:

- Form Identifier
The identifier of the target form.
- Device Path

Optionally, the device path which contains the Form Identifier. Otherwise, the device path associated with the form set containing this cross-reference will be used.

- **Question Identifier**
The identifier of the target question on the target form. If specified then focus will be placed on the question identifier. Otherwise, the focus will be on the first question within the specified form.
- **Callback**
Specifies whether the call-back will be called when the button is pressed by the user.

Syntax

cross-reference:= **EFI_IFR_REF** *statement-tag-list*

27.2.5.3.11 Reset Button

The Forms Browser displays a means by which users can reset the current form to default values.

Attributes

Reset Buttons have the following attributes:

- **Default Id**
Specifies the default set to use when restoring defaults to the current form.
- **Callback**
Specifies whether the call-back will be called when the button is pressed by the user.

Syntax

cross-reference:= **EFI_IFR_RESET_BUTTON** *statement-tag-list*

27.2.5.4 Questions

Questions are statements which have a value. The value corresponds to a configuration setting for the platform or for a device. The question uniquely identifies the configuration setting, describes the possible values, the way the value is stored, and how the question should be displayed.

27.2.5.4.1 Attributes

Questions have the following attributes (in addition to those of statements):

- **Question Identifier**
A 16-bit unsigned integer which uniquely identifies the question within the form set in which it appears. The Question Identifier, along with the device path and Form Set Identifier, uniquely identifies a question within a system.
- **Default Value**
The value used when the user requests that defaults be loaded.
- **Manufacturing Value**
The value used when the user requests that manufacturing defaults are loaded.
- **Value**
Each question has a current value. See [Section 27.2.5.4.3](#) for more information.

- Value Format
The format used to store a question's value.
- Value Storage
The means by which values are stored. See [Section 27.2.5.4.4](#) for more information.
- Validation
New values assigned to questions can be validated, using validation expressions, or, if connected, using a callback. See [Section 27.2.5.9](#) for more information.
- Callback
If set, the callback will be called when the question's value is changed. In some cases, the presence of these callbacks prevents the question's value from being edited while disconnected.

The question can control whether a particular option can be displayed by nesting it inside of an **EFI_IFR_SUPPRESS_IF** expression. Form Browsers do not display Suppressed Options, but Suppressed Options may still be examined by Form Processors.

27.2.5.4.2 Syntax

```

question := boolean | date | number | ordered-list | string | time
question-tag-list:=question-tag question-tag-list |
<empty>
question-tag:=statement-tag |
    EFI_IFR_INCONSISTENT_IF expression |
    EFI_IFR_NO_SUBMIT_IF expression |
    EFI_IFR_DISABLE_IF expression |
    EFI_IFR_REFRESH |
    EFI_IFR_VARSTORE_DEVICE
question-option-tag :=EFI_IFR_SUPPRESS_IF expression question-option-list |
    EFI_IFR_VALUE optional-expression |
default |
    option
question-option-list :=question-tag question-option-list |
    question-option-tag question-option-list |
<empty>

```

Other unknown opcodes are permitted but are ignored.

27.2.5.4.3 Values

Question values are a data type listed in [Section 27.2.5.7.4](#). During initialization of the Forms Processor or Forms Browser, the values of all enabled questions are retrieved. If the value cannot be retrieved, then the question's value is Undefined.

A question with the value of type Undefined is suppressed. This suppression is reevaluated based on Value Refresh or when any question value on the selected form is changed.

When the form is submitted, the modified values are written to Value Storage. When the form is reset, the question value is set to the default question value. If there is no default question value, the question value is unchanged.

27.2.5.4.4 Storage Requirements

Question storage requirements describe the type and size of storage for the value. These storage requirements describe whether the question's value will be stored as an EFI global variable or using driver local storage. It also describes whether the value is packed together with other values in a buffer, or passed as a name-value pair. See [Section 27.2.5.6](#) for more information.

27.2.5.4.5 Display

Question display depends on the Forms Browser. Questions *do not* describe how the question must be displayed. Instead, questions provide resources (such as text and images) and information about visibility and the ability to edit the question. The Forms Browser uses these to create the necessary user interface.

Questions can have prompt text, help text and (optionally) an image. The prompt text usually describes the nature of the question. Help text is displayed either in a special display area or only at the request of the user. Questions can also have hints which describe how to visually organize the information

27.2.5.4.6 Action Button

Action buttons are buttons which cause a pre-defined configuration string to process immediately. There is no storage directly associated with the button.

Attributes

Action buttons have no additional attributes other than the common question attributes).

Storage

There is no storage associated with the action button.

Results

There are no results associated with the action button.

Syntax

boolean := **EFI_IFR_ACTION_BUTTON** *question-tag-list*

27.2.5.4.7 Boolean

Boolean questions are those that allow a choice between true and false. The question's value is Boolean. In general, construct questions so that the prompt text asks questions resulting in 'yes/enabled/on' is 'true' and 'no/disabled/off' is 'false'.

Boolean questions may be displayed as a check box, two radio buttons, a selection list, a list box, or a drop list box.

Attributes

Boolean questions have no additional attributes other than the common question attributes:

Storage

If the date question uses Buffer storage (see [Section 27.2.5.6](#)), then the size is exactly one byte, with the FALSE condition is zero and the TRUE value is 1.

Results

The results are represented as either 0 (FALSE) or 1 (TRUE).

Syntax

boolean := **EFI_IFR_CHECKBOX** *question-option-list*

27.2.5.4.8 Date

Date questions allow modification of part or all of a standard calendar date. The format of the date display depends on the Forms Browser and any localization.

Attributes

Date questions have the following attributes:

- Year Suppressed
The year will not be displayed or updated.
- Month Suppressed
The month will not be displayed or updated.
- Day Suppressed
The day will not be displayed or updated.
- UEFI Storage
In addition to normal question Value Storage, Date questions can optionally be instructed to save the date to either the system time or system wake-up time using the UEFI runtime services **SetTime ()** or **SetWakeuptime ()**. In this case, the date and time will be read first, the modifications made and changes will be written back.

Conversion to and from strings to a date depends on the system localization.

The date value is stored an **EFI_HII_TIME** structure. The **TimeZone** field is always set to **EFI_UNSPECIFIED_TIMEZONE**. The **Daylight** field is always set to zero. The contents of the other fields are undetermined.

Storage

If the date question uses Buffer storage (see [Section 27.2.5.6](#)), then the stored result will occupy exactly the size of **EFI_HII_DATE**.

Results

Results for date questions are represented as a hex dump of the **EFI_HII_DATE** structure.

Syntax

date := **EFI_IFR_DATE** *question-option-list*

27.2.5.4.9 Number

Number questions allow modification of an integer value up to 64-bits. Number questions can also specified pre-defined options.

Attributes

Number questions have the following attributes:

- **Radix**
Hint describes the output radix of numbers. The possible values are unsigned decimal, signed decimal or hexadecimal. Numbers displayed in hexadecimal will be prefixed by ‘0x’
- **Minimum Value**
The minimum unsigned value which can be accepted for this question.
- **Maximum Value**
The maximum unsigned value which can be accepted for this question.
- **Skip Value**
Defines the minimum increment between values.

Storage

If the number question uses Buffer storage (see [Section 27.2.5.6](#)), then the buffer size specified by must be 1, 2, 4 or 8. Also, the Forms Processor will do implicit error checking to make sure that the signed or unsigned value can be stored in the Buffer without lost of significant bits. For example, if the buffer size is 1 byte, then the largest unsigned integer value would be 255. Likewise, the largest signed integer value would be 127 and the smallest signed integer value would be -128. The Forms Processor will automatically detect this as an error and generate an appropriate error.

Results

The results are represented as Unicode unsigned hexadecimal values.

Syntax

```
number := EFI_IFR_NUMERIC question-option-list |
           EFI_IFR_ONE_OF question-option-list
```

27.2.5.4.10 Set

Sets are questions where n containers can be filled with any of m pre-defined choices. This supports both lists where a given value can only appear in one of the slots or where the same choice can appear many times.

Each of the containers takes the form of an option which a name, a value and (optionally) an image.

Attributes

Set questions have the following attributes:

- **Container Count**
Specifies the number of available selectable options.
- **Unique**
If set, then each choice may be used at most, once.
- **NoEmpty**
All slots must be filled with a non-zero value.

Storage

The set questions are stored as a Buffer with one byte for each Container.

Results

Each Container value is represented as two Unicode characters, one for each nibble. All hexadecimal characters (a-f) are in lower-case.

The results are represented as a series of Container values, starting with the lowest Container.

Syntax

ordered-list := **EFI_IFR_ORDERED_LIST** *question-option-list*

27.2.5.4.11 String

String questions allow modification of a string.

Attributes

String questions have the following attributes:

- Minimum Length
Hint describes the minimum length of the string, in characters.
- Maximum Length
Hint describes the maximum length of the string, in characters.
- Multi-Line
Hint describes that the string might contain multiple lines.
- Output Mask
If set, the text entered will not be displayed.

Storage

The string questions are stored as a NULL-terminated string. If the time question uses Buffer storage (see [Section 27.2.5.6](#)), then the buffer size must exceed the size of the NULL-terminated string. If the string is shorter than the length of the buffer, the remainder of the buffer is filled with NULL characters.

Results

Results for string questions are represented as hex dump of the string, including the terminating NULL character.

Syntax

string := **EFI_IFR_STRING** *question-option-list* |
EFI_IFR_PASSWORD *question-option-list*

27.2.5.4.12 Time

Time questions allow modification of part or all of a time. The format of the time display depends on the Forms Browser and any localization.

Attributes

Date questions have the following attributes:

- Hour Suppressed
The hour will not be displayed or updated.
- Minute Suppressed
The minute will not be displayed or updated.

- Second Suppressed
The second will not be displayed or updated.
- UEFI Storage
In addition to normal question Value Storage, time questions can be instructed to save the time to either the system time or system wake-up time using the UEFI runtime services **SetTime** or **SetWakeuptime**. In these instances, the date and time is read first, the modifications made and changes are then written back.

Conversion to and from strings to a time depends on the system localization.

The time value is stored as part of an **EFI_HII_TIME** structure. The contents of the other fields are undetermined.

Storage

If the time question uses Buffer storage (see [Section 27.2.5.6](#)), then the buffer size must be exactly the size of the **EFI_HII_TIME** structure..

Results

Results for time questions are represented as a hex dump of the **EFI_HII_TIME** structure.

Syntax

time := **EFI_IFR_TIME** question-option-list

27.2.5.5 Options

Use Options within questions to give text or graphic description of a particular question value. They may also describe the choices in the set data type.

Options have the following attributes:

- Text
The text for the option.
- Image
The image for the option.
- Value
The value for the option.
- Default
If set, this is the option selected when the user asks for the defaults. Only one visible option can have this bit set within a question's scope.
- Manufacturing Default
If set, this is the option selected when manufacturing defaults are set. Only one visible option can have this bit set within a question's scope.

27.2.5.5.1 Syntax

option := **EFI_IFR_ONE_OF_OPTION** option-tag-list
option-tag-list:=option-tag option-tag-list |
 <empty>

*option-tag:=***EFI_IFR_IMAGE**

27.2.5.5.2 Visibility

Options which have been suppressed will not be displayed. Options are displayed unless:

- The parent question is suppressed.
- The option is nested inside an **EFI_IFR_SUPPRESS_IF** expression which evaluated to false.

The suppression of the options is evaluated each time the option is displayed.

27.2.5.6 Storage

Question values are stored in *Variable Stores*, which are application, platform or device repositories for configuration settings. In many cases, this is non-volatile storage. In other cases, it holds only the current behavior of a driver or application.

Question values are retrieved from the variable store when the form is initialized. They are updated periodically based question settings and stored back in the variable store when the form is submitted.

There are four types of variable stores:

Buffer Storage.

With buffer storage, the application, platform or driver provides a buffer which contains the values for one or more questions. Each question provides the offset within the buffer and the size of the required storage. These variable stores are exposed by the app/driver using the **EFI_HII_CONFIG_ACCESS_PROTOCOL**, which is installed on the same handle as the package list.

Name/Value Storage .

With name/value storage, the application provides a string which contains the encoded values for a single question. These variable stores are exposed by the app/driver using the **EFI_HII_CONFIG_ACCESS_PROTOCOL**, which is installed on the same handle as the package list.

EFI Variable Storage.

This is a specialized form of Buffer Storage, which uses the EFI runtime services **GetVariable()** and **SetVariable()**.

EFI Date/Time Storage.

For date and time-related questions, the question values can be retrieved using the EFI runtime services **GetTime()** and **GetWakeuptime()** and stored using the EFI runtime services **SetTime()** and **SetWakeuptime()**.

The following table summarizes the types of information needed for each type of storage and where it is retrieved from.

Table 175. Information for Types of Storage

Storage Type	Information Type	Where It Comes From
Buffer Storage	Driver Handle	Handle specified with <code>NewPackageList()</code> or derived from <code>EFI_IFR_VARSTORE_DEVICE.DevicePath</code>
	Variable GUID	Variable store specified by <code>EFI_IFR_QUESTION_HEADER.VarStoreId</code>
	Variable Name	Variable store specified by <code>EFI_IFR_QUESTION_HEADER.VarStoreId</code>
	Variable Store Offset	Variable store offset specified by <code>EFI_IFR_QUESTION_HEADER.VarOffset</code>
Name/Value Storage	Driver Handle	Handle specified with <code>NewPackageList()</code> or derived from <code>EFI_IFR_VARSTORE_DEVICE.DevicePath</code>
	Variable GUID	Variable store specified by <code>EFI_IFR_QUESTION_HEADER.VarStoreId</code>
	Variable Name	Variable name specified by <code>EFI_IFR_QUESTION_HEADER.VarName</code>
EFI Variable Storage	Driver Handle	None
	Variable GUID	Variable store specified by <code>EFI_IFR_QUESTION_HEADER.VarStoreId</code>
	Variable Name	Variable name specified by <code>EFI_IFR_QUESTION_HEADER.VarName</code>
EFI Date/Time Storage	Driver Handle	None
	Variable GUID	None
	Variable Name	None

27.2.5.7 Expressions

This section describes the expressions used in various expressions in IFR. The expressions are encoded using normal IFR opcodes, but in RPN (Reverse Polish Notation) where the operands occur before the operator.

The opcodes fall into these categories:

Unary operators.

Functions taking a single sub-expression.

Binary operators.

Functions taking two sub-expressions.

Ternary operators.

Functions taking three sub-expressions.

Built-in functions.

Operators taking zero or more sub-expressions.

Constants.

Numeric and string constants.

Question Values.

Specified by their question identifier.

All integer operations are performed at 64-bit precision.

27.2.5.7.1 Expression Encoding

Expressions are usually encoded within the scope of another binary object. If the expression consists of more than a single opcode, the first opcode should open a scope (*Header.Scope* = 1) and use an **EFI_IFR_END** opcode to close the scope in order to make sure they can be skipped,

27.2.5.7.2 Expression Stack

When evaluating expressions, the Forms Processor uses a stack to hold intermediate values. Each operator either pushes a value on the stack, pops a value from the stack, or both. For example, the **EFI_IFR_ONE** operator pushes the integer value 1 on the expression stack. The **EFI_IFR_ADD** operator pops two integer values from the expression stack, adds them together, and pushes the result back on the stack.

After evaluating an expression, there should be only one value left on the expression stack.

27.2.5.7.3 Rules

Rules are pre-defined expressions attached to the form. These rules may be used in any expression within the form's scope. Each rule is given a unique identifier (0-255) when it is created by **EFI_IFR_RULE**. This same identifier is used when the rule is referred to in an expression with **EFI_IFR_RULE_REF**.

To save space, rules are intended to allow manual or automatic extraction of common sub-expressions from form expressions.

27.2.5.7.4 Data Types

The expressions use five basic data types:

Boolean

True or false.

Unsigned Integer

64-bit unsigned integer.

String

Unicode string.

Buffer

Fixed size array of unsigned 8-bit integers.

Undefined

Undetermined value. Used when the value cannot be calculated or for run-time errors.

Data conversion is not implicit. Explicit data conversion can be performed using the [EFI IFR TO STRING](#), [EFI IFR TO UINT](#), and [EFI IFR TO BOOLEAN](#) operators.

27.2.5.7.5 Syntax

The expressions have the following syntax:

```
expression      :=built-in-function |
constant |
expression unary-op |
expression expression binary-op |
expression expression expression ternary-op
```

```
optional-expression :=expression |
                    <empty>
```

```
built-in-function:=EFI_IFR_DUP |
EFI_IFR_EQ_ID_VAL |
EFI_IFR_EQ_ID_ID |
EFI_IFR_EQ_ID_LIST |
                    EFI_IFR_QUESTION_REF1 |
EFI_IFR_QUESTION_REF3 |
                    EFI_IFR_RULE_REF |
                    EFI_IFR_STRING_REF1 |
                    EFI_IFR_THIS
```

```
constant      :=EFI_IFR_FALSE |
EFI_IFR_ONE |
EFI_IFR_ONES |
EFI_IFR_TRUE |
EFI_IFR_UINT8 |
EFI_IFR_UINT16 |
EFI_IFR_UINT32 |
EFI_IFR_UINT64 |
EFI_IFR_UNDEFINED |
EFI_IFR_VERSION |
EFI_IFR_ZERO
binary-op      :=EFI_IFR_ADD |
```

```

EFI_IFR_AND |
EFI_IFR_BITWISE_AND |
EFI_IFR_BITWISE_NOT |
EFI_IFR_BITWISE_OR |
EFI_IFR_CATENATE |
EFI_IFR_DIVIDE |
EFI_IFR_EQUAL |
EFI_IFR_GREATER_EQUAL |
EFI_IFR_GREATER_THAN |
EFI_IFR_LESS_EQUAL |
EFI_IFR_LESS_THAN |
EFI_IFR_MATCH |
EFI_IFR_MODULO |
EFI_IFR_MULTIPLY |
EFI_IFR_NOT_EQUAL |
EFI_IFR_OR |
EFI_IFR_SHIFT_LEFT |
EFI_IFR_SHIFT_RIGHT |
EFI_IFR_SUBTRACT |
unary-op :=      EFI_IFR_LENGTH |
EFI_IFR_NOT |
EFI_IFR_QUESTION_REF2 |
EFI_IFR_STRING_REF2 |
EFI_IFR_TO_BOOLEAN |
EFI_IFR_TO_STRING |

EFI_IFR_TO_UINT
ternary-op:=EFI_IFR_CONDITIONAL |
                EFI_IFR_FIND |

EFI_IFR_MID |
                EFI_IFR_TOKEN |
                EFI_IFR_SPAN

```

27.2.5.8 Defaults

Defaults are pre-defined configuration setting values. There are three ways for defaults to be specified (highest priority listed first):

1. One or more **EFI_IFR_DEFAULT** opcodes appear within the scope of a question.
2. One of the Options (see [Section 27.2.5.5](#)) has its Standard Default or Manufacturing Default attribute set.

3. For Boolean questions, the Standard Default or Manufacturing Default values in the *Flags* field.

Questions can be reset to one of their default settings either by a Forms Processor-specific action or when the user presses a Reset button (see [Section 27.2.5.3.11](#)).

Defaults are grouped together into *default stores*. There are three standard default stores:

Standard Defaults

These are the defaults used to prepare the system/device for normal operation.

Manufacturing Defaults

These are the defaults used to prepare the system/device for manufacturing.

Safe Defaults

These are the defaults used to boot the system in a “safe” or low-risk mode.

The platform provider, the hardware provider or the firmware vendor can use other default stores.

When using a Forms Editor, new defaults should be added using the **EFI_IFR_DEFAULT** opcodes.

27.2.5.8.1 Attributes

Each default store has the following attributes:

- Default Identifier. A 16-bit unsigned integer which uniquely identifies the default store within the form set in which it appears.
- Default Name. A string which provides a name for the default store.

```
#define EFI_HII_DEFAULT_CLASS_STANDARD 0x0000
```

Default Class Assignment	Default ID Range
Specification Defined	0x0000 – 0x3FFF
Platform Defined	0x4000 – 0x7FFF
Hardware Vendor Defined	0x8000 – 0xBFFF
Firmware Vendor Defined	0xC000 – 0xFFFF

```
#define EFI_HII_DEFAULT_CLASS_MANUFACTURING 0x0001
#define EFI_HII_DEFAULT_CLASS_SAFE 0x0002
#define EFI_HII_DEFAULT_CLASS_PLATFORM_BEGIN 0x4000
#define EFI_HII_DEFAULT_CLASS_PLATFORM_END 0x7fff
#define EFI_HII_DEFAULT_CLASS_HARDWARE_BEGIN 0x8000
#define EFI_HII_DEFAULT_CLASS_HARDWARE_END 0xbfff
#define EFI_HII_DEFAULT_CLASS_FIRMWARE_BEGIN 0xc000
#define EFI_HII_DEFAULT_CLASS_FIRMWARE_END 0xffff
```

Users of these ranges are encouraged to use the specification defined ranges for maximum interoperability.

27.2.5.8.2 Syntax

```
default := EFI_IFR_DEFAULT default-tag
default-tag:=EFI_IFR_VALUE |
```

<empty>

27.2.5.9 Validation

Validation is the process of determining whether a value can be applied to a configuration setting. Validation takes place at three different points in the editing process: edit-level, question-level and form-level.

27.2.5.9.1 Edit-Level Validation

First, it takes place while the value is being edited with a Forms Browser. The Forms Browser may optionally reject values selected by the user which would fail Question-Level validation. For example, the Forms Browser may limit the length of strings entered so that they meet the Minimum and Maximum Length.

27.2.5.9.2 Question-Level Validation

Second, it takes place when the value has changed, normally when the user attempts to leave the control, navigate between the portions of the control or selects one of the option values. At this point, an error occurs if:

For a String (see [Section 27.2.5.4.11](#)), if the string length is less than the Minimum Length, then the Forms Processor generates an error.

For a String (see [Section 27.2.5.4.11](#)), if the string length is greater than the Maximum Length, then the Forms Processor generates an error.

For a Number (see [Section 27.2.5.4.9](#)), if the number cannot fit in the specified variable storage without loss of significant bits, then the Forms Processor generates an error.

For all questions, if an **EFI_IFR_INCONSISTENT_IF** evaluates to FALSE, then the Forms Processor will display the specified error text.

27.2.5.9.3 Form-Level Validation

Third, it takes place when exiting the form or when the values are submitted. The error occurs under two conditions:

- For all questions, if an **EFI_IFR_NO_SUBMIT_IF** evaluates to FALSE, then the Forms Processor will display the specified error text.
- If a Forms Processor such as a script processor performs Form-Level validation, where the concept of a form is not maintained, then the Form-Level validation must occur before processing question values from other forms or before completion of the configuration session.

27.2.5.10 Forms Processing

Forms Processors interpret the IFR in order to extract information about configuration settings. This section describes how the IFR should be interpreted and how errors should be handled.

27.2.5.10.1 Error Handling

The Forms Processor may encounter problems in interpreting the IFR. This section describes the standard ways of handling these issues:

Unknown Opcodes.

Unknown opcodes have a type which is not recognized by the Forms Processor. In general, the Forms Processor ignores the opcode, along with any nested opcodes.

Malformed Opcodes.

Malformed objects have a length which is less than the minimum length for that object type. In this case, the entire form is disabled.

Extended Opcodes.

Extended objects have a length longer than that expected by the Forms Processor. In this case, the Forms Processor interprets the object normally and ignores the extra data.

Malformed Forms Sets

Malformed forms sets occur when an object's length would cause it extend beyond the end of the forms set, or when the end of the forms set occurs while a scope is still open. In this case, the entire forms set is ignored.

Reserved Bits Set.

The Forms Processor should ignore all set reserved bits.

27.2.5.11 Forms Editing

This section describes considerations for Forms Editors, which are a specialized Forms Processor which can create and manipulate form lists, forms and questions in their binary form.

27.2.5.11.1 Locking

Locking indicates that a question or statement,--along with its related options, prompts, help text or images--should not be moved or edited. A statement or question is locked when the **IFR_LOCKED** opcode is found within its scope.

UEFI-compliant Forms Editors must allow statements or questions within an image to be locked, but should not allow them to be unlocked. UEFI-compliant Forms Editors must not allow modification of locked statements or questions or any of their associated data (including options, text or images).

Note: *This mechanism cannot prevent unauthorized modification. However, it does clearly state the intent of the driver creator that that they should not be modified.*

27.2.5.11.2 Moving Forms

When forms are moved between form sets, the related data (such as forms, variable stores and default stores) need to have their references renumbered to avoid conflicts with identifiers in the new form set. For forms, these include:

- **EFI_IFR_FORM** (and all references in **EFI_IFR_REF**)
- **EFI_IFR_DEFAULTSTORE** (and all references in **EFI_IFR_DEFAULT**)
- **EFI_IFR_VARSTORE_x** (and all references within question headers)

27.2.5.11.3 Moving Questions

When questions are moved between form sets, the related data (such as images and strings) need to be moved and references to results-processing and storage may need to be revised. For example:

- **String and Images.** If the question is being moved to another form set, then all strings and images associated with the question must be moved to the package list containing the form set and removed from the current one.

- **Form Set.** If the question is moved to a package list installed by a different driver, then the **EFI_IFR_VAR_STORAGE_DEVICE** (see [Section 27.3.8.3.82](#)) should be nested in the scope of the question, describing the driver installation device path.
- **Question References.** If a question value in another form set is referred to in any expressions (such as **EFI_IFR_INCONSISTENT_IF** or **EFI_IFR_NO_SUBMIT_IF**) using either **EFI_IFR_QUESTION_REF2** (see [Section 27.3.8.3.50](#)) or **EFI_IFR_QUESTION_REF1** (see [Section 27.3.8.3.49](#)) then these must be converted to a form of **EFI_IFR_QUESTION_REF3** (see [Section 27.3.8.3.51](#)), specifying the EFI_GUID of the form set and/or the device path of the package list containing the form set wherein the question referred to is defined.

When questions are moved between forms, whether in the same form list or another form list, question behavior reliant on the current form may need revision. One example is the use of **EFI_IFR_RULE_REF** in expressions. Here, rules are shortcuts for common expressions used in a form. If a question is moved to another form, the references to any rules in expressions must be replaced by the expression itself.

27.2.6 Strings

Strings in the UEFI environment are defined using UCS-2, which is a 16-bit-per-character representation. For user-interface purposes, strings are one of the types of resources which can be installed into the HII Database (see [Section 27.2.9](#)).

In order to facilitate localization, users reference strings by an identifier unique to the driver which installed it. Each identifier may have several translations associated with it, such as English, French, and Traditional Chinese. When displaying a string, the Forms Browser selects the actual text to display based on the current platform language setting.

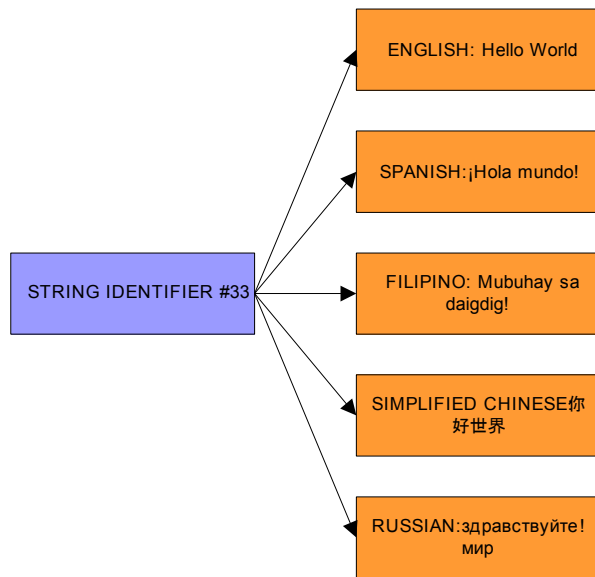


Figure 72. String Identifiers

The actual text for each language is stored separately (in a separate package), which makes it possible to add and remove language support just by including or excluding the appropriate package.

Each string may have font information, including the font family name, font size and font style, associated with it. Not all platforms or displays can support fonts and styles beyond the system default font (see [Section 27.2.7](#)), so the font information associated with the string should be viewed as a set of hints.

27.2.6.1 Configuration Language Paradigm

This specification uses the ISO 3066 language naming scheme to identify the language that a given string is associated with. Since the majority of strings discussed in this specification are associated with generating a user interface, the languages that are typically associated with strings have commonly defined languages such as en-US, zh-Hant, and it-IT. The ISO 3066 standard also reserves for private use languages prefixed with a value of “x”.

Note that this specification defines for its own purposes one of these private use areas as a special-purpose language that components can use for extracting information out of. Assume that any private-use languages encountered by a compliant implementation will likely consider those languages as configuration languages, and the associated behavior when referencing those languages will be platform specific. Section 2.12.2 describes an example of such a use.

27.2.6.2 Unicode Usage

This section describes how different aspects of the Unicode specification related to the strings within this specification.

27.2.6.2.1 Private Use Area

Unicode defines a *private use* area of 6500 characters that may be defined for local uses. Suggested uses include Egyptian Hieroglyphics; see *Developing International Software For Windows 95* and Windows NT** for more information. UEFI prohibits use of this area in a UEFI environment. This is because a centralized font database accumulated from the various drivers (a valid implementation) would end up with collisions in the private use area, and, generally, an XML browser could not display these characters.

27.2.6.2.2 Surrogate Area

The Unicode specification has two 16-bit character representations: UCS-2 and UTF-16. The UEFI specification uses UCS-2. The primary difference is that UTF-16 defines *surrogate areas* (see page 56 in *Professional XML*) that allow for expanded character representations of the 16-bit Unicode. These character representations are very similar to Double Byte Character Set (DBCS)—2048 Unicode values split into two groups (D000–DBFF and DC00–DFFF). They are defined as having 16 additional bits of value to make up the character, for a total of about one million extra characters. UEFI does not support surrogate characters.

27.2.6.2.3 Non-Spacing Characters

Unicode uses the concept of a *nonspacing* character. These glyphs are used to add accents, and so on, to other characters by what amounts to logically OR'ing the glyph over the previous glyph. There does not appear to be any predictable range in the Unicode encoding to determine nonspacing characters, yet these characters appear in many languages. Further, these characters enable spelling of several languages including many African languages and Vietnamese.

27.2.6.2.4 Common Control Codes

This specification allows the encoding of font display information within the strings using special control characters. These control codes are meant as display hints, and different platforms may ignore them, depending on display capabilities.

In single-byte encoding, these are in the form **0x7F 0xyy** or **0x7F 0x0y 0xzz**. Single-byte encoding is used only when coupled with the Standard Compression Scheme for Unicode, described in [Section 27.3.6.3](#).

In double-byte encoding, these are in the form **0xF6yy**, **0xF7zz** or **0xF8zz**. When converted to UCS-2, all control codes should use the **0xFxyy** form.

Table 176. Common Control Codes for Font Display Information

Value	Description	Single-Byte Encoding	Double-Byte Encoding
0x00	Font Family Select. The subsequent text will be displayed in the font specified by the following byte.	0x7F 0x00 0xzz	0xF7zz
0x01	Font Size Select. The subsequent text will be displayed in the point size, in half points, specified by the following byte.	0x7F 0x01 0xzz	0xF8zz
0x20	Bold On.	0x7F 0x20	0xF620
0x21	Bold Off	0x7F 0x21	0xF621
0x22	Italic On	0x7F 0x22	0xF622
0x23	Italic Off	0x7F 0x23	0xF623
0x24	Underline On	0x7F 0x24	0xF624
0x25	Underline Off	0x7F 0x25	0xF625

27.2.6.2.5 Line Breaks

This section describes the use of control characters to determine where break opportunities within strings. These guidelines are based on Unicode Technical Report #14, but are significantly simplified.

Spaces

In general, any of the following space characters is a line-break opportunity:

0020	SPACE
1680	OGHAM SPACE MARK

2000	EN QUAD
2001	EM QUAD
2002	EN SPACE
2003	EM SPACE
2004	THREE-PER-EM SPACE

2005	FOUR-PER-EM SPACE
2006	SIX-PER-EM SPACE
2008	PUNCTUATION SPACE
2009	THIN SPACE
200A	HAIR SPACE
205F	MEDIUM MATHEMATICAL SPACE

When a space is desired without a line-break opportunity, one of the following spaces should be used:

00A0	NO-BREAK SPACE (NBSP)
202F	NARROW NO-BREAK SPACE (NNBSP)

In-Word Break Opportunities

In some cases, allowing line-breaks in a word is desirable. These line break opportunities should be explicitly described using one of the characters from the following list:

200B	ZERO WIDTH SPACE (ZWSP)
------	-------------------------

Hyphens

The following characters are hyphens and other characters which describe line break opportunities after the character.

058A	ARMENIAN HYPHEN
2010	HYPHEN
2012	FIGURE DASH
2013	EN DASH
0F0B	TIBETAN MARK INTERSYLLABIC TSHEG
1361	ETHIOPIC WORDSPACE
17D5	KHMER SIGN BARIYOOSAN

The following characters describe line break opportunities before and after them, but not between a pair of them:

2014	EM DASH
------	---------

The following characters describe a hyphen which is not a line-breaking opportunity:

2011	NON-BREAKING HYPHEN (NBHY)
------	----------------------------

Mandatory Breaks

The following characters force a line-break:

000C	FORM FEED
000D	CARRIAGE RETURN
2028	LINE SEPARATOR
2029	PARAGRAPH SEPARATOR

27.2.7 Fonts

This section describes how fonts are used within the UEFI environment.

UEFI describes a standard font, which is required for all systems which support text display on bitmapped output devices. The standard font (named ‘system’) is a fixed pitch font, where all characters are either narrow (8x19) or wide (16x19). UEFI also allows for display of other fonts, both fixed-pitch and variable-pitch. Platform support for these fonts is optional.

UEFI fonts are described using either the Simplified Font Package ([Section 27.3.2](#)) or the normal Font Package ([Section 27.3.3](#)).

27.2.7.1 Font Attributes

Fonts have the following attributes:

Font Name. The font name describes, in broad terms, the visual style of the font. For example, “Arial” or “Times New Roman” The standard font always has the name “sysdefault”.

Font Size. The font size describes the maximum height of the character cell, in pixels. The standard font always has the font size of 19.

Font Style. The font style describes standard visual modifies to the base visual style of a font. Supported font styles include: bold, italic, underline, double-underline, embossed, outline and shadowed. Some font styles may also be simulated by the font rendering engine. The standard font always has no additional font styles.

27.2.7.2 Limiting Glyphs

Strings in the UEFI environment can be presented in environments with very different limitations. The most constrained environment is in the firmware phases prior to discovery of a boot device with a system partition. The main limitation in this environment is storage space. If unexpected strings could be displayed before system partition availability, the UEFI environment would have to store glyphs for all characters in a Unicode font. After system partition discovery, all glyphs could be made available.

Careful user interface design can limit to a manageable number, the quantity of unexpected characters that the system could be called on to display. Knowing what strings the firmware is going to display limits the number of glyphs it is required to carry.

In addition, carefully designed firmware can support a system where a limited number of strings are displayed before system partition availability. This may be done while enabling the input and display of large numbers of characters/glyphs using a full font file stored on the system partition. In such a situation, the designer must ensure that enough information can be displayed. The designer must also insure that the configuration can be changed using only information from firmware-based non-volatile storage to obtain access to a satisfactory system partition.

UEFI requires platform support of a font containing the basic Latin character set.

While the system firmware will carry this standard font, there might be times when a UEFI application or driver requires the printing of a character not contained within the platform firmware. In this case, a UEFI driver or application can carry this font data and add it to the font already present in the HII Database. New font glyphs are accepted when there is no font glyph definition for the Unicode character already in the specified font.

The figure below shows how fonts interact with the HII database and UEFI drivers, even if the font does not already exist in the database.

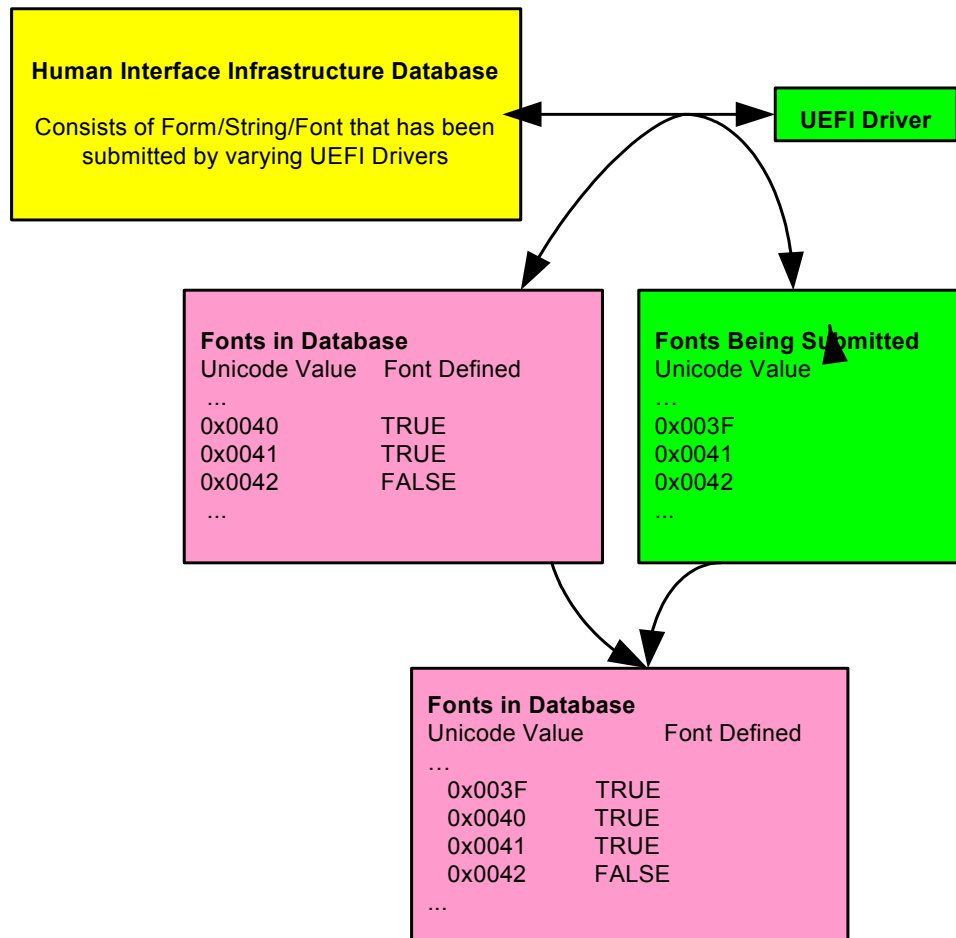


Figure 73. Fonts

27.2.7.3 Fixed Font Description

To allow a UEFI application or driver to extend the existing fonts with additional characters, the UEFI driver must be able to provide characters that fit aesthetically with the system font. For this reason the capability to define attributes of different fonts and to suggest a reasonable default target for these parameters is important.

Fonts can vary in width, style, baseline, height, size, and so on. The fixed font definition includes white space and the glyph data, as well as the positioning of the glyph data. This prevents characters of different fixed fonts from being adjusted at runtime to fit aesthetically together. To provide UEFI drivers with a basic description of how to design fixed font characters, a subset of industry standard font terms are defined below:

baseline

The distance from upper left corner of cell to the base of the Caps (A, B, C,...)

cap_height

The distance from the base of the Caps to the top of the Caps

x_height

The distance from the baseline to the top of the lower case 'x'

descender

The distance some characters extended below the baseline (g, j, p, q, y)

ascender

The distance from the top of the lower case 'x' to the tall lower case characters (b, d, f, h, k, l)

The following figure illustrates the font description terms:

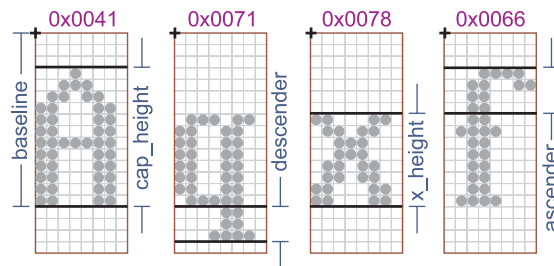


Figure 74. Font Description Terms

This 8x19 system font example (above), follows the original VGA 8x16 definition and creating double wide vertical lines, giving a *bold* look to the font (style = bold). Along with matching the 8x19 base system font, if a UEFI driver wants to extend the DBCS (Double Byte Character Set) font, it must be aware of the parameters that describe the 16x19 font, as shown below.

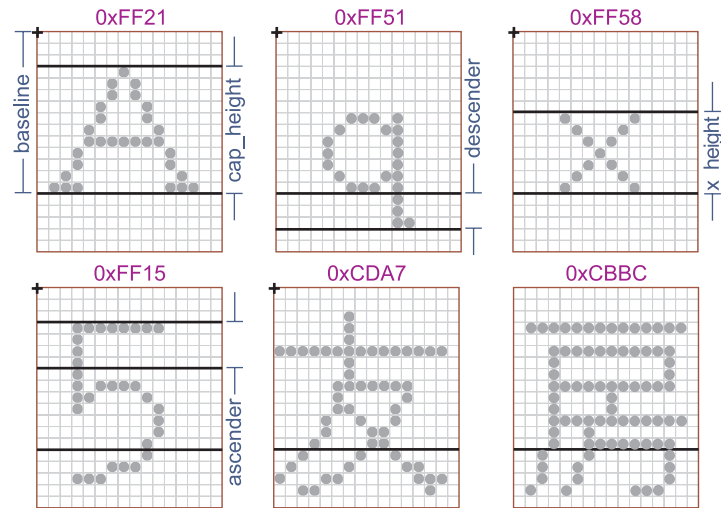


Figure 75. 16 x 19 Font Parameters

This 16x19 font example (above) has a style of *plain* (single width vertical lines) instead of *bold* like the 8x19 font, since there is not enough horizontal resolution to cleanly define the DBCS glyphs. The 16x19 ASCII characters have also been designed in a style matching the DBCS characters, allowing them to fit aesthetically together. Note that the default 16x19 fixed width characters are not stored like 1-bit images, one row after another; but instead stored with the left column (19 bytes) first, followed by the right column (19 bytes) of character data. The figure below shows how the characters of the previous figure would be laid out in the font structure.

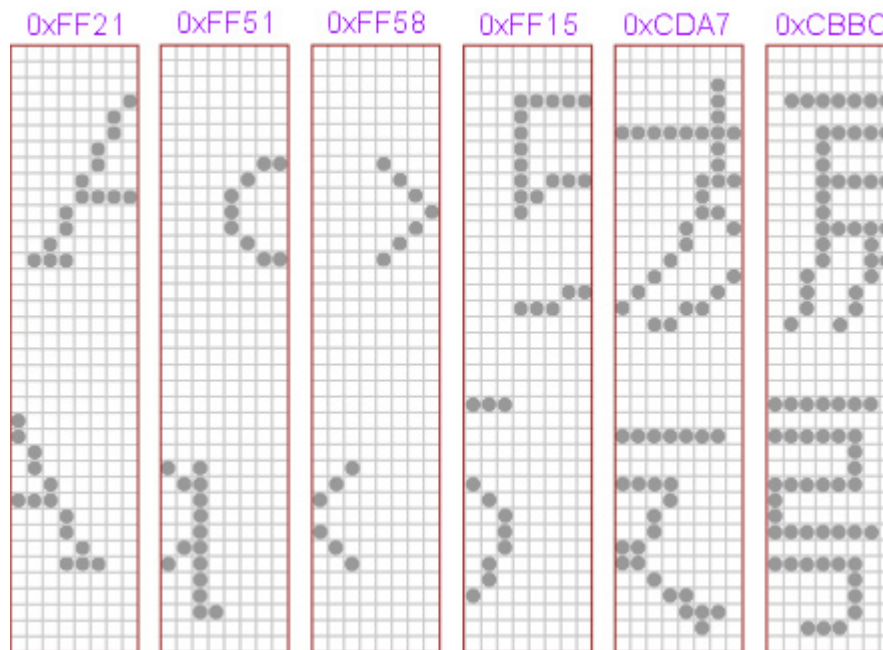


Figure 76. Font Structure Layout

27.2.7.3.1 System Fixed Font Design Guidelines

To allow a UEFI application or driver to extend the fixed font character set, the UEFI system fonts must adhere, at least roughly, to the design guidelines in the table below:

Table 177. Guidelines for UEFI System Fonts

Term	8 x 19 Font	16 x 19 Font
baseline	15 pixels	14 pixels
cap_height	12 pixels	11 pixels
x_height	8 pixels	7 pixels
descender	3 pixels	4 pixels
ascender	4 pixels	4 pixels

In the table above lists the terms in priority order. The most critical guideline to match is the *baseline*, followed by *cap_height* and *x_height*. The terms *descender* and *ascender* are not as critical to the aesthetic look of the font as are the other terms. These font design parameters are only guidelines. Failing to match them will not prevent reasonable operation of a UEFI driver that attempting to extend the system font.

27.2.7.4 Proportional Fonts Description

Unlike the fixed fonts, proportional fonts do not have a predefined character cell; instead the character cell is created based on the characters that are being displayed in the current line. In a proportional font only the glyph data is defined, no whitespace. Instead, the proportional font

defines five parameters (Width, Height, Offset_X, Offset_Y, & Advance), which allow the glyph data to be positioned in the character cell and calculate the origin of the next character.

In the figure below, you can see these parameters (in '[...]') for the characters shown, in addition you can see the actual byte storage (the padding to the nearest byte is shown shaded).

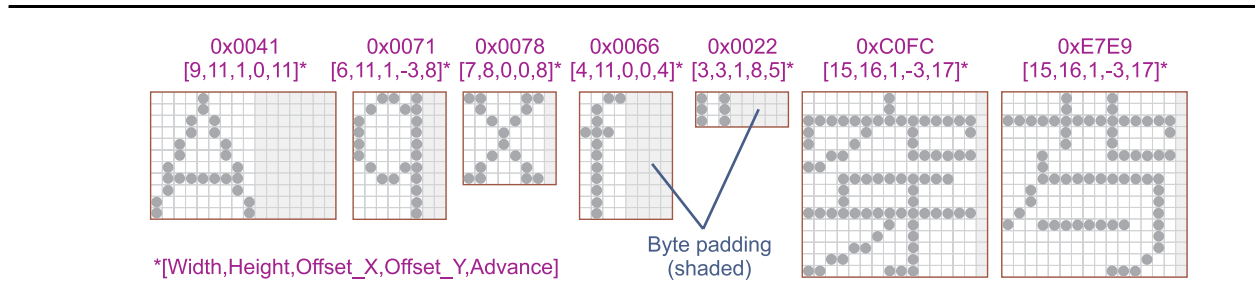


Figure 77. Proportional Font Parameters and Byte Padding

In addition to the individual glyph storage structures, a proportional font header contains the height of the font and the location of the baseline, which are required when combining glyphs from different fonts.

27.2.7.4.1 Aligning Glyphs to the Baseline

To display a line of proportional glyphs possibly from different fonts, scan characters to be displayed, saving the *baseline* value from the character with the highest font height, as well as the largest delta encountered below the baseline (*Offset_Y*). The *line height*, is this font height adjusted (if necessary) to include the largest delta before the baseline. As shown in the following figure, once the *baseline* value is found it is added to the starting position of the line to calculate the *Origin*. From the *Origin*, each and every glyph can be generated based on the individual glyph parameters, including the calculation of the next glyph's *Origin*.

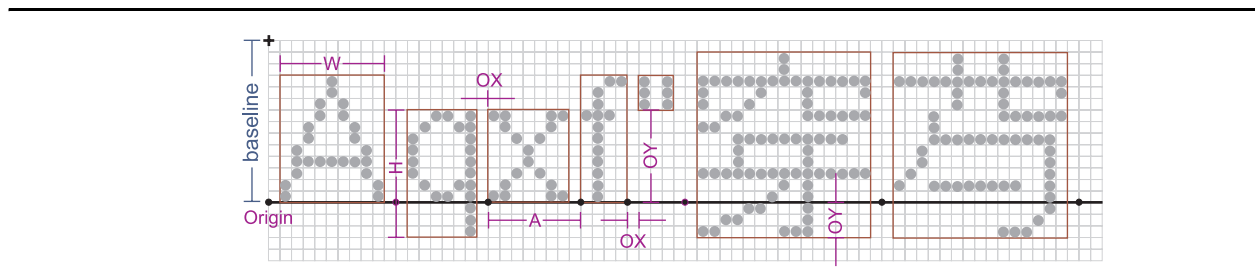


Figure 78. Aligning Glyphs

The starting position (upper left hand corner) of the glyph is defined by $(Origin_X + Offset_X)$, $(Origin_Y - (Offset_Y + Height))$. The Origin of the next glyph is defined by $(Origin_X + Advance)$, $(Origin_Y)$.

In addition to determining the *line height* and *baseline* values; the scan of the characters also calculates the *line width* by totaling up all of the *advance* values.

27.2.7.4.2 Proportional Font Design Guidelines

This method of aligning glyphs to a baseline allows one to place wildly different characters correctly position on a single line. However there still is a need for the system proportional fonts to roughly

adhere to overall font height (19 pixels high character cells) and the placement of the baseline at the bottom of the Caps (if applicable or about 5 pixels up from the bottom of the character cell). These guidelines are not as critical as the fixed font guidelines, since the character cell height are defined at runtime, based on what else is displayed with that character.

27.2.8 Images

The format of the images to be stored in the Human Interface Infrastructure (HII) database have been created to conform to the industry standard 1-bit, 4-bit, 8-bit, and 24-bit video memory layouts. The 24-bit and 32-bit display systems have the exact same display capabilities and the exact same pixel definition. The difference is that the 32-bit pixels are DWORD aligned for improve CPU efficiency when accessing video memory. The extra byte that is inserted from the 24-bit and the 32-bit layout has no bearing on the actual screen.

Video memory is arranged *left-to-right*, and then *top-to-bottom*. In a 1-bit or monochrome display, the most significant bit of the first byte defines the screen's upper left most pixel. In a 4-bit or 16 color, display the most significant nibble of the first byte defines the screen's upper left most pixel. In a 8-bit or 256 color display, the first byte defines the screen's upper left most pixel.

In both the 24-bit and 32-bit TrueColor displays, the first three bytes defines the screen's upper left most pixel. The first byte is the pixel's blue component value, the next byte is the pixel's green component value, and the third byte is the pixel's red component value (B,G,R). Each color component value can vary from 0x00 (color off) to 0xFF (color full on), allowing 16.8 millions colors that can be specified. In the 32-bit TrueColor display modes, the fourth byte is a *don't care*.

27.2.8.1 Converting to a 32-bit Display

The UEFI recommended video mode for computer-like devices uses a 32-bit Linear Frame Buffer video mode. All images stored in the HII database will need conversion to 32-bit before display.

To display a 24-bit image into 32-bit video memory, a pixel of the image is retrieved (read DWORD value advance pixel offset by 3) and then written to the video memory (write DWORD value advance pixel offset by 4).

To display any of the non-TrueColor images (1-bit, 4-bit, and 8-bit), there is an extra step of indirection through the palette definition to get the TrueColor pixel value. First retrieve the palette index value by isolating the corresponding bits, then index into the associated palette to retrieve the 24-bit (B,G,R) color entry (read DWORD value), then write it to the video memory (write DWORD value advance pixel offset by 4). For this reason, the palette color entry definition is defined exactly the same as the image color pixel (B,G,R).

27.2.8.2 Non-TrueColor Displays

It is possible to display the HII database images on non-TrueColor video modes. You cannot however, display images beyond the bit depth of the target screen resolution. For example you would be able to display 1-bit, 4-bit, and 8-bit images in a 256 color video mode. To do this you must create a global palette (256 entries), by merging all images color needs to a best fit palette and then programming the hardware palette with that data.

The hardware palette color definition (R,G,B) is backwards from the screen pixel definition (B,G,R), and will have to be swapped before programming. In addition, the hardware palette may only support 6-bit of magnitude per color component instead of the 8-bit defined in the palette information section; therefore the values will have to be shifted before writing.

27.2.9 HII Database

The Human Interface Infrastructure (HII) database is the resource that serves as the repository of all the form, string, image and font data for the system. Drivers that contain information that is appropriate for the database will export this data to the HII database.

For example, one driver might contain all the motherboard-specific data (the traditional “Setup” for the system). Additionally, add-in cards may contain their own drivers, which, in turn, have their own Setup-related data. All of the drivers that contain Setup-related data would export their information to the HII database, as shown in the figure below.

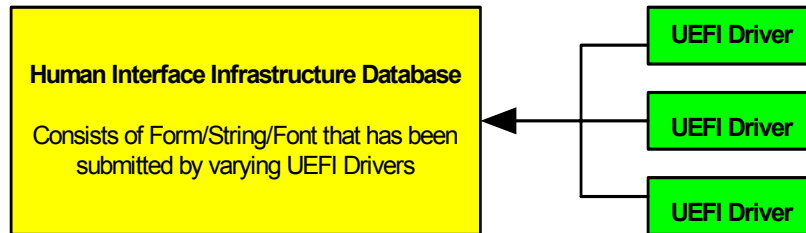


Figure 79. HII Database

27.2.10 Forms Browser

The UEFI Forms Browser is the application that reads the contents of the HII Database and interprets the data to present it to the user. A special Forms Browser gathers all setup-related data and presents it to the user. This program also takes the user input and provides for a mechanism to save the changes into non-volatile storage.

The figure below shows the relationship between the HII database, UEFI drivers, and the UEFI Forms Browser.

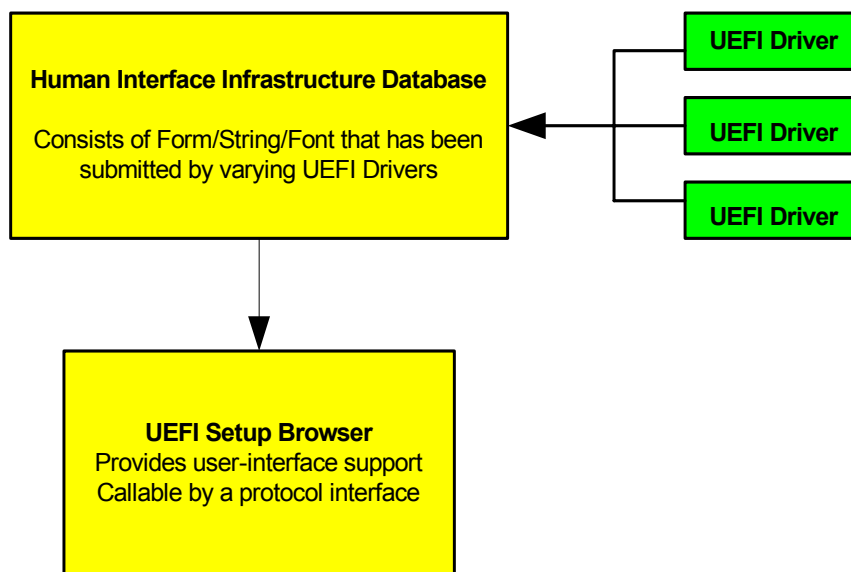


Figure 80. Setup Browser

27.2.11 Configuration Settings

In order to save user changes to configuration settings after the system reset or power-off, there must be some form of non-volatile storage available. There are two types of non-volatile storage: system non-volatile storage or add-in card non-volatile storage. Both types are supported.

In general, settings are not saved to non-volatile storage until the user specifically directs the Forms Browser to do so. There are exceptions, such as when operating in a batch or script mode, setting a system password, and updating the system date and time. The underlying platform support dictates whether or not hardware configuration changes are committed immediately.

As shown in the figure below, when a system reset occurs, the firmware’s initialization routines will launch the UEFI drivers (e.g. option ROMs). Drivers enabled to take direction from a non-volatile setting read the updated settings during their initialization..

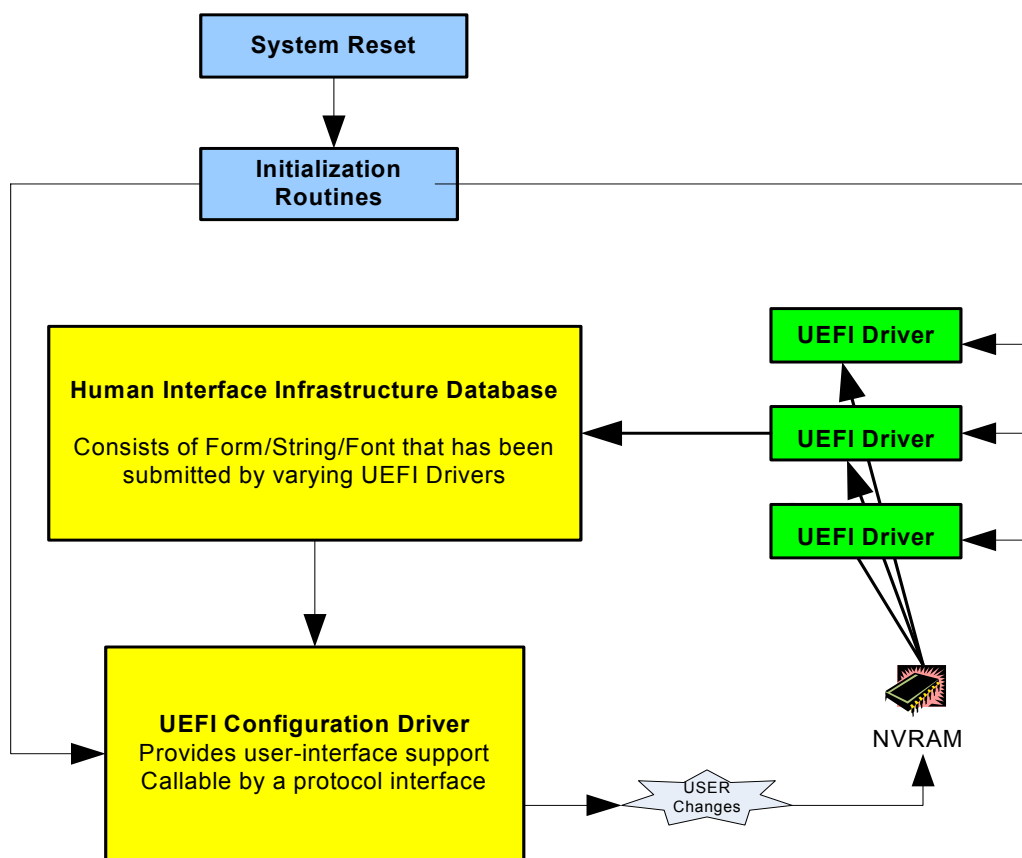


Figure 81. Storing Configuration Settings

27.2.11.1 OS Runtime Utilization

Due to the static nature of the data that is contained in the HII Database and the fact that certain classes of non-volatile storage can be updated during OS run-time, it is possible for an application

running under an OS to read the HII information, make configuration changes and even make changes.

The figure below shows how an OS makes use of the HII database during runtime. In this case, the contents of the HII Database is exported to a buffer. The pointer to the buffer is placed in the EFI System Configuration Table, where it can be retrieved by an OS application.

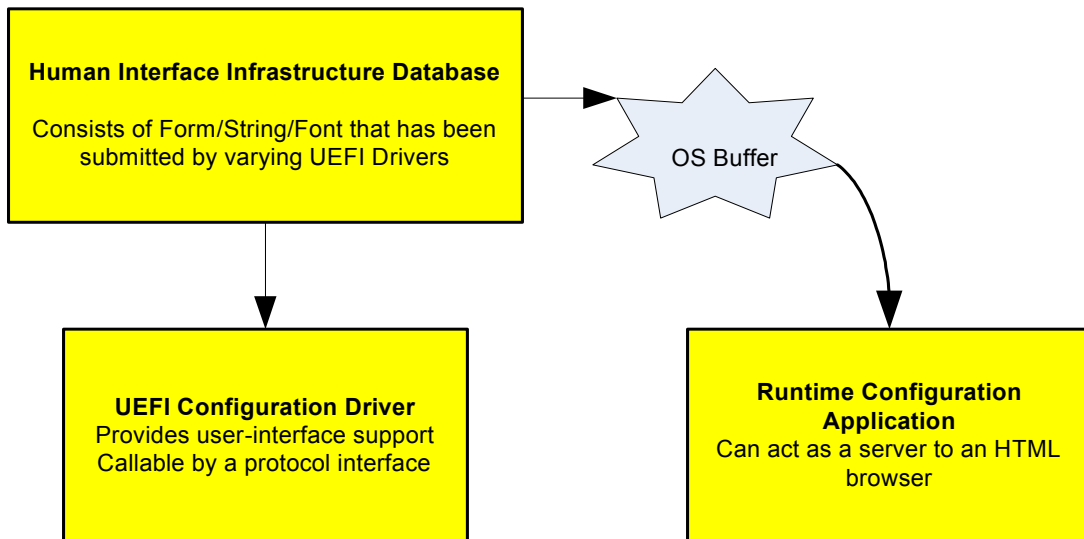


Figure 82. OS Runtime Utilization

The process used to allow an OS application to use this is as follows:

Drivers/applications in the system register user interface data into the HII Database

When the platform transitions from pre-boot to runtime phases of operation, the HII **ExportPackageLists()** is called to export the contents of the HII Database into a runtime buffer.

This runtime buffer is advertised in the UEFI Configuration Table using the HII Database Protocol's GUID so that an OS application can find the data.

The HII **ExportConfig()** is called to export the current configuration into a runtime buffer.

This runtime buffer is advertised in the UEFI Configuration Table using the HII Configuration Routing Protocol's GUID so that an OS application can find the data.

When an O/S application wants to display pre-boot configuration content, it searches the UEFI Configuration Table for the HII Database Protocol's GUID entry and renders the contents from the runtime buffer which it points to.

If the OS application needs to update the system configuration, the configuration information can be updated.

For those configuration settings which are stored in UEFI variables (i.e. using `GetVariable()` and `SetVariable()`), the application can update these using the abstraction provided by the operating system.

For those configuration settings which are not stored in UEFI variables, the OS application can use the UEFI UpdateCapsule runtime service to change the configuration.

27.2.11.2 Working with a UEFI Configuration Language

By defining the concept of a language that may provide hints to a consumer that the string payload may contain pre-defined standard keyword content, the user of this solution can export their configuration data for evaluation. This evaluation enables the consumer to determine if a particular platform supports a given configuration language, and in-turn be able to adjust known settings that are stored in a platform-specific manner. An example of this is illustrated below which uses various component described in this and the other HII chapters of this specification. In the example, a fictional technology called XYZ exists, and this particular platform supports it. The question is, how does a standard application which is not privy to the platform’s construction know how this setting is stored? To-date, this is not a reasonably solvable problem, but in the illustration below, this example shows how one might go about solving this issue.

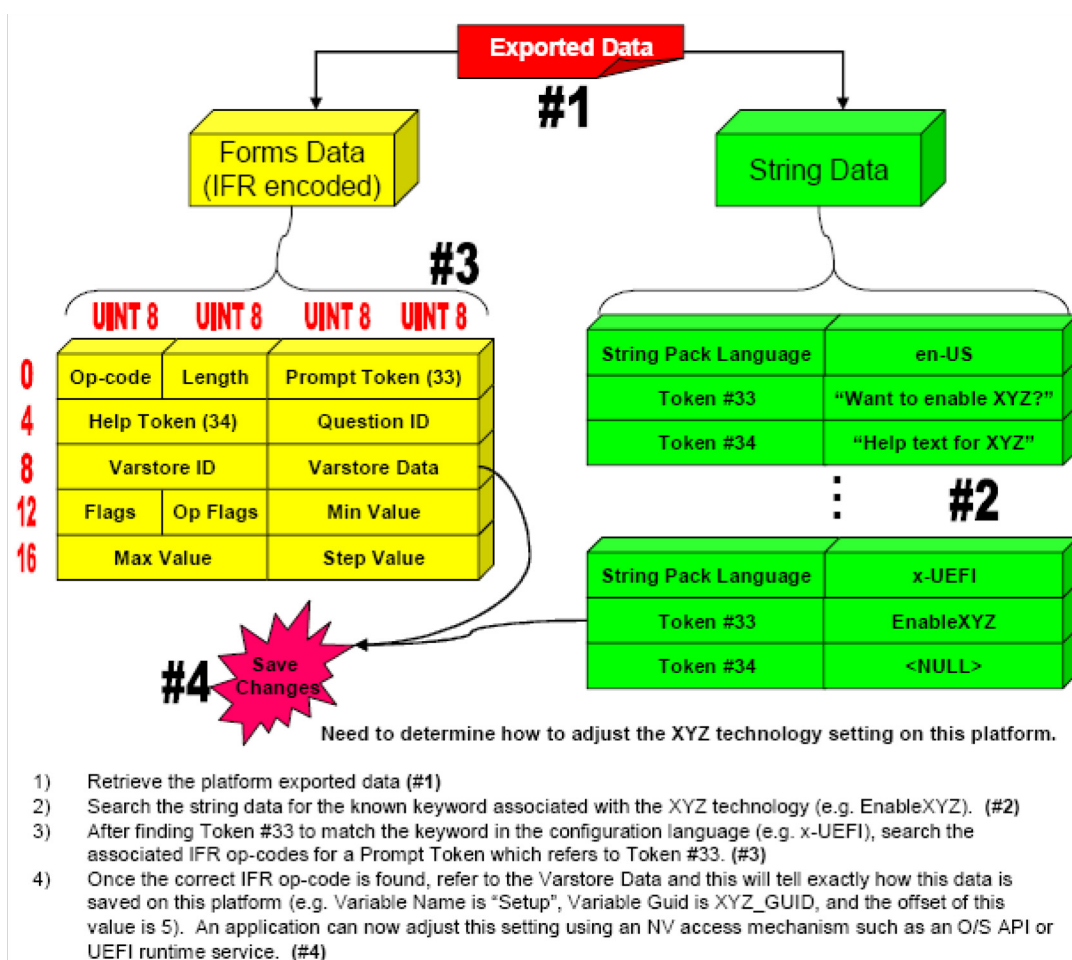


Figure 83. Standard Application Obtaining Setting Example

27.2.12 Form Callback Logic

Since it has been the design intent that the forms processor not need to understand the underlying hardware implementations or design paradigms of the platform, there were certain needs that could only be met by calling a more platform knowledgeable component. In this case, the component would typically be associated with some hardware device (e.g. motherboard, add-in card, etc). To facilitate this interaction, some formal interfaces were declared for more platform-specific components to advertise and the forms processor could then call.

Note that the need for the forms processor to call into an alternate component driver should be limited as much as possible. The two primary reasons for this are the cases where off-line or O/S-present configuration is important. Below is a flow chart which describes the typical decisions that a forms processor would make with regards to handling processes which necessitate a callback.

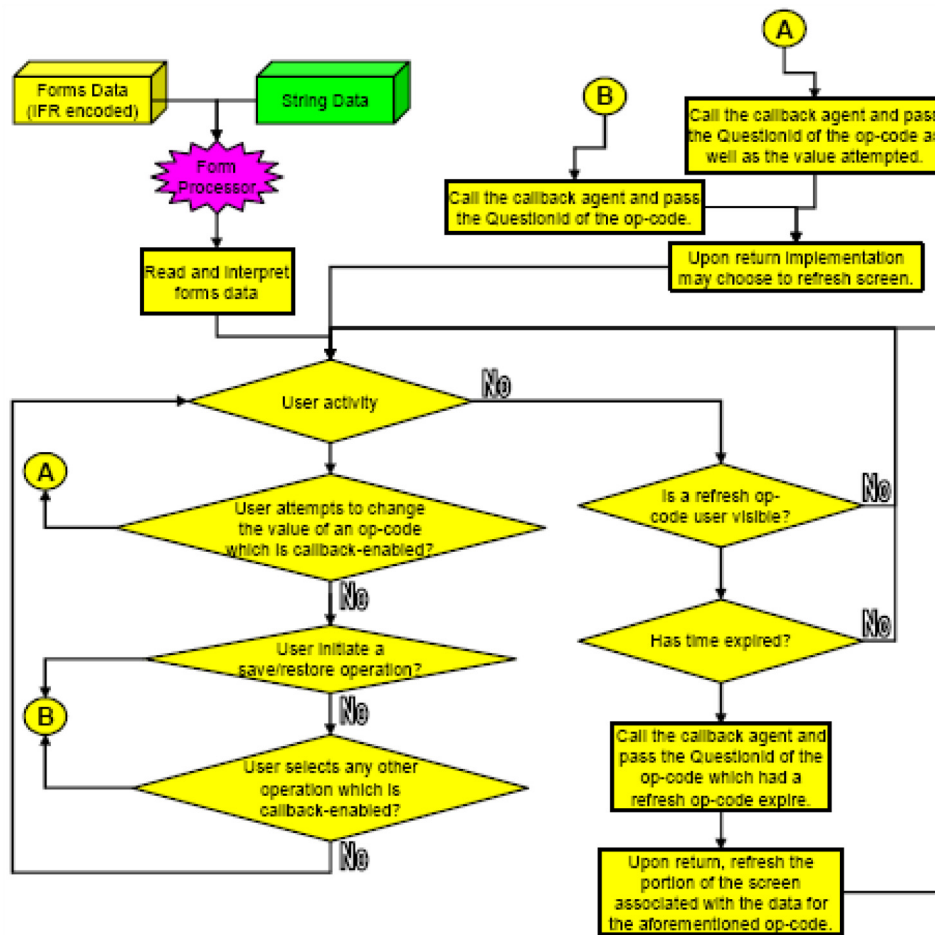


Figure 84. Typical Forms Processor Decisions Necessitating a Callback

27.2.13 Driver Model Interaction

The ability for a UEFI driver to interact with a target controller is abstracted through the Configuration Access Protocol. If a particular piece of hardware managed by a controller needs

configuration services, it is the responsibility of that controller to provide this configuration abstraction for the given device. Regardless of whether a device driver or bus driver is abstracting the hardware configuration, the interaction with a configured device is identical.

Note that the ability for a driver to provide these access protocols might be done fairly early in the initialization process. Depending on the hardware capabilities, one might be advantaged in providing configuration access very early so that being able to determine a given device's current settings can be done without a full enumeration of certain bus devices. Also note that the same recommendations that are made in the DriverBinding sections should still be maintained. These cover the Supported, Started, and Stopped functions.

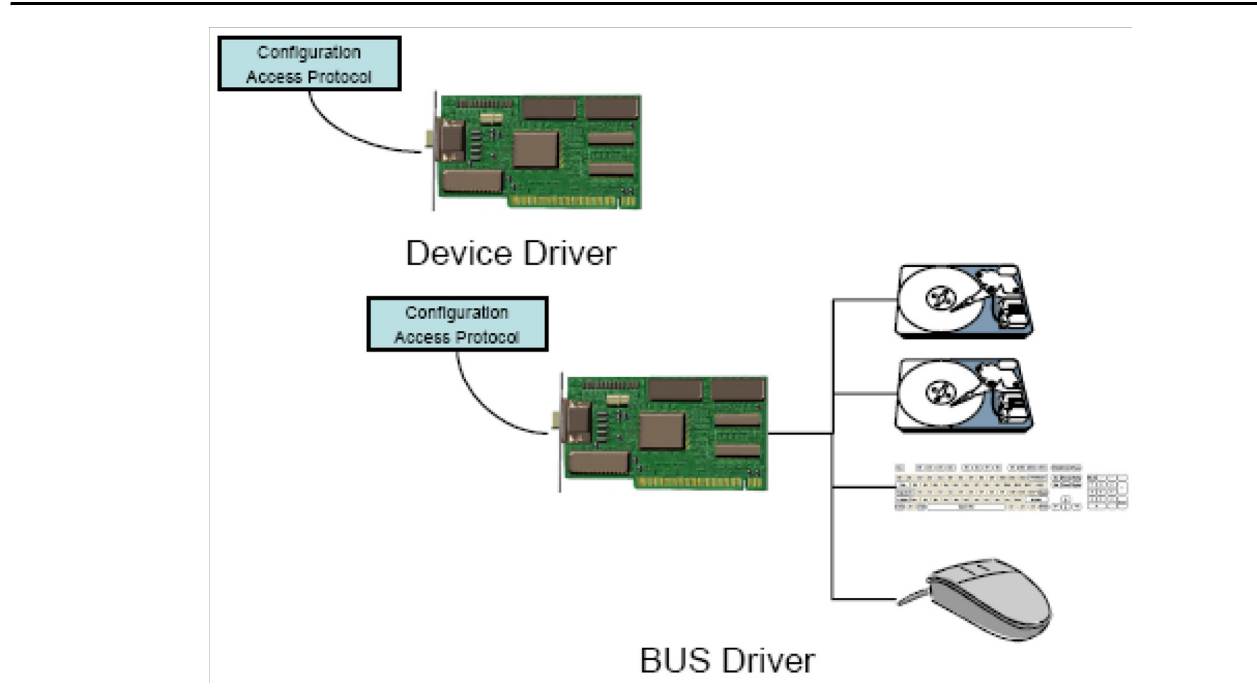


Figure 85. Driver Model Interactions

27.2.14 Human Interface Component Interactions

The figure below depicts the model used inside a common deployment of HII to manage human interface components.

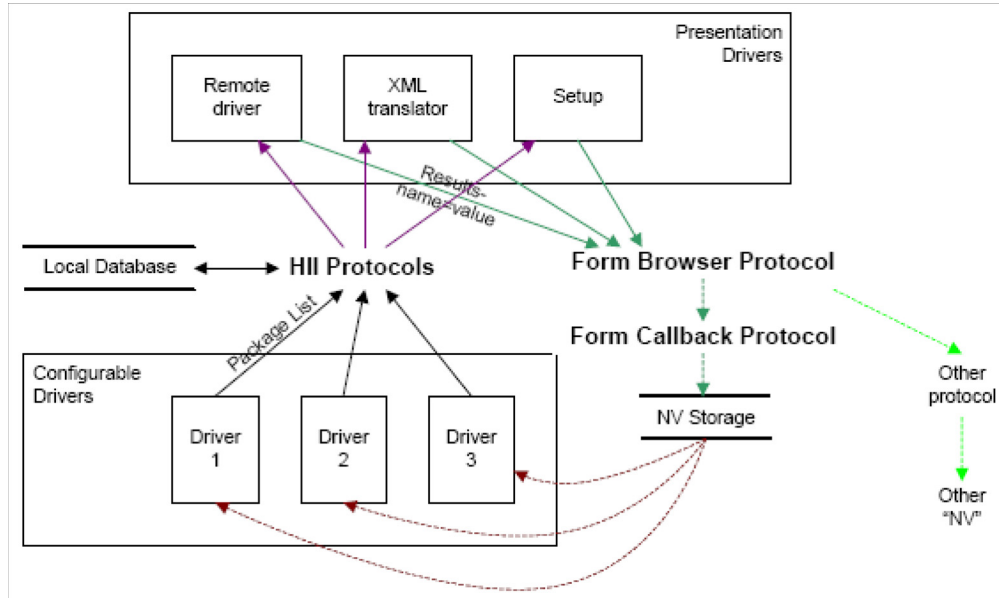


Figure 86. Managing Human Interface Components

27.3 Code Definitions

This chapter describes the binary encoding of the different package types:

- Font Package
- Simplified Font Package
- String Package
- Image Package
- Device Path Package
- Keyboard Layout Package
- GUID Package
- Device Path Package

27.3.1 Package Lists and Package Headers

EFI_HII_PACKAGE_HEADER

Summary

The header found at the start of each package.

Prototype

```
typedef struct {
    UINT32 Length:24;
```

```

    UINT32  Type:8;
    UINT8   Data[ ... ];
} EFI_HII_PACKAGE_HEADER;

```

Members

Length

The size of the package in bytes.

Type

The package type. See **EFI_HII_PACKAGE_TYPE_x**, below.

Data

The package data, the format of which is determined by *Type*.

Description

Each package starts with a header, as defined above, which indicates the size and type of the package. When added to a pointer pointing to the start of the header, *Length* points at the next package. The package lists form a package list when concatenated together and terminated with an **EFI_HII_PACKAGE_HEADER** with a *Type* of **EFI_HII_PACKAGE_END**.

The type **EFI_HII_PACKAGE_TYPE_GUID** is used for vendor-defined HII packages, whose contents are determined by the *Guid*.

The range of package types starting with **EFI_HII_PACKAGE_TYPE_SYSTEM_BEGIN** through **EFI_HII_PACKAGE_TYPE_SYSTEM_END** are reserved for system firmware implementers.

Related Definitions

```

#define EFI_HII_PACKAGE_TYPE_ALL           0x00
#define EFI_HII_PACKAGE_TYPE_GUID         0x01
#define EFI_HII_PACKAGE_FORM_CONFIG      0x02
#define EFI_HII_PACKAGE_FORM_APP         0x03
#define EFI_HII_PACKAGE_STRINGS           0x04
#define EFI_HII_PACKAGE_FONTS            0x05
#define EFI_HII_PACKAGE_IMAGES           0x06
#define EFI_HII_PACKAGE_SIMPLE_FONTS     0x07
#define EFI_HII_PACKAGE_DEVICE_PATH      0x08
#define EFI_HII_PACKAGE_END              0x09
#define EFI_HII_PACKAGE_TYPE_SYSTEM_BEGIN 0xE0
#define EFI_HII_PACKAGE_TYPE_SYSTEM_END  0xFF

```

Table 178. Package Types

Package Type	Description
EFI_HII_PACKAGE_TYPE_ALL	Pseudo-package type used when exporting package lists. See ExportPackageList() .

EFI_HII_PACKAGE_TYPE_GUID	Package type where the format of the data is specified using a GUID immediately following the package header.
EFI_HII_PACKAGE_TYPE_FORM_CONFIG	Forms package meant to be used by a system configuration utility such as setup.
EFI_HII_PACKAGE_TYPE_FORM_APP	Forms package meant to be invoked explicitly.
EFI_HII_PACKAGE_STRINGS	Strings package
EFI_HII_PACKAGE_FONTS	Fonts package.
EFI_HII_PACKAGE_IMAGES	Images package.
EFI_HII_PACKAGE_SIMPLE_FONTS	Simplified (8x19, 16x19) Fonts package
EFI_HII_PACKAGE_DEVICE_PATH	Binary-encoded device path.
EFI_HII_PACKAGE_END	Used to mark the end of a package list.
EFI_HII_PACKAGE_TYPE_SYSTEM_BEGIN... EFI_HII_PACKAGE_TYPE_SYSTEM_END	Package types reserved for use by platform firmware implementations.

27.3.1.1 EFI_HII_PACKAGE_LIST_HEADER

Summary

The header found at the start of each package list.

Prototype

```
typedef struct {
    EFI_GUID    PackageListGuid;
    UINT32     PackagLength;
} EFI_HII_PACKAGE_LIST_HEADER;
```

Members

PackageListGuid

The unique identifier applied to the list of packages which follows.

PackageLength

The size of the package list (in bytes), including the header.

Description

This header uniquely identifies the package list and is placed in front of a list of packages. Package lists with the same *PackageListGuid* value should contain the same data set. Updated versions should have updated GUIDs.

27.3.2 Simplified Font Package

The simplified font package describes the font glyphs for the standard 8x19 pixel (*narrow*) and 16x19 (*wide*) fonts. Other fonts should be described using the normal Font Package.

A simplified font package consists of a header and two types of glyph structures—standard-width (narrow) and wide glyphs.

27.3.2.1 EFI_HII_SIMPLE_FONT_PACKAGE_HDR

Summary

A simplified font package consists of a font header followed by a series of glyph structures.

Prototype

```
typedef struct _EFI_HII_SIMPLE_FONT_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER    Header;
    UINT16                    NumberOfNarrowGlyphs;
    UINT16                    NumberOfWideGlyphs;
    EFI_NARROW_GLYPH         NarrowGlyphs[];
    EFI_WIDE_GLYPH           WideGlyphs[];
} EFI_HII_SIMPLE_FONT_PACKAGE_HDR;
```

Members

Header

The header contains a *Length* and *Type* field. In the case of a font package, the type will be **EFI_HII_PACKAGE_SIMPLE_FONTS** and the length will be the total size of the font package including the size of the narrow and wide glyphs. See [EFI HII PACKAGE HEADER](#).

NumberOfNarrowGlyphs

The number of *NarrowGlyphs* that are included in the font package.

NumberOfWideGlyphs

The number of *WideGlyphs* that are included in the font package.

NarrowGlyphs

An array of **EFI_NARROW_GLYPH** entries. The number of entries is specified by *NumberOfNarrowGlyphs*.

WideGlyphs

An array of **EFI_WIDE_GLYPH** entries. The number of entries is specified by *NumberOfWideGlyphs*. To calculate the offset of *WideGlyphs*, use the offset of *NarrowGlyphs* and add the size of **EFI_NARROW_GLYPH** multiplied by the *NumberOfNarrowGlyphs*.

Description

The fonts must be presented in Unicode sort order. That is, the primary sort key is the UnicodeWeight and the secondary sort key is the SurrogateWeight.

It is up to developers who manage fonts to choose efficient mechanisms for accessing fonts. The contiguous presentation can easily be used because narrow and wide glyphs are not intermixed, so a binary search is possible (hence the requirement that the glyphs be sorted by weight).

27.3.2.2 EFI_NARROW_GLYPH

Summary

The **EFI_NARROW_GLYPH** has a preferred dimension (w x h) of 8 x 19 pixels.

Prototype

```
typedef struct {
    CHAR16      UnicodeWeight;
    UINT8       Attributes;
    UINT8       GlyphColl[19];
} EFI_NARROW_GLYPH;
```

Members

UnicodeWeight

The Unicode representation of the glyph. The term *weight* is the technical term for a character value.

Attributes

The data element containing the glyph definitions; see Related Definitions below.

GlyphColl

The column major glyph representation of the character. Bits with values of one indicate that the corresponding pixel is to be on when normally displayed; those with zero are off.

Description

Glyphs are represented by two structures, one each for the two sizes of glyphs. The narrow glyph (**EFI_NARROW_GLYPH**) is the normal glyph used for text display.

Related Definitions

```
// Contents of EFI_NARROW_GLYPH.Attributes
#define EFI_GLYPH_NON_SPACING  0x01
#define EFI_GLYPH_WIDE         0x02
```

Following is a description of the fields in the above definition:

EFI_GLYPH_NON_SPACING	This symbol is to be printed "on top of" (OR 'd with) the previous glyph before display.
EFI_GLYPH_WIDE	This symbol uses 16x19 formats rather than 8x19.

27.3.2.3 EFI_WIDE_GLYPH

Summary

The **EFI_WIDE_GLYPH** has a preferred dimension (w x h) of 16 x 19 pixels, which is large enough to accommodate logographic characters.

Prototype

```
typedef struct {
    CHAR16      UnicodeWeight;
    UINT8      Attributes;
    UINT8      GlyphCol1[GLYPH_HEIGHT];
    UINT8      GlyphCol2[GLYPH_HEIGHT];
    UINT8      Pad[3];
} EFI_WIDE_GLYPH;
```

Members

UnicodeWeight

The Unicode representation of the glyph. The term *weight* is the technical term for a character value.

Attributes

The data element containing the glyph definitions; see Related Definitions in **EFI_NARROW_GLYPH** for attribute values.

GlyphCol1 and GlyphCol2

The column major glyph representation of the character. Bits with values of one indicate that the corresponding pixel is to be on when normally displayed; those with zero are off.

Pad

Ensures that **sizeof(EFI_WIDE_GLYPH)** is twice the **sizeof(EFI_NARROW_GLYPH)**. The contents of *Pad* must be zero.

Description

Glyphs are represented via the two structures, one each for the two sizes of glyphs. The wide glyph (**EFI_WIDE_GLYPH**) is large enough to display logographic characters.

27.3.3 Font Package

The font package describes the glyphs for a single font with a single family, size and style. The package has two parts: a fixed header and the glyph blocks. All structures described here are byte packed.

27.3.3.1 Fixed Header

The fixed header consists of a standard record header and then the character values in this section, the flags (including the encoding method) and the offsets of the glyph information, the glyph bitmaps and the character map.

```
typedef struct _EFI_HII_FONT_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    UINT32                  HdrSize;
    UINT32                  GlyphBlockOffset;
    EFI_HII_GLYPH_INFO      Cell;
```



```

EFI_HII_FONT_STYLE      FontStyle;
CHAR16                  FontFamily[];
} EFI_HII_FONT_PACKAGE_HDR;

```

Header

The standard package header, where *Header.Size* = **EFI_HII_PACKAGE_FONTS**.

HdrSize

Size of this header.

GlyphInfoOffset

The offset, relative to the start of this header, of a series of variable-length glyph blocks, each describing information about the bitmap associated with a glyph.

Cell

This contains the measurement of the widest and tallest characters in the font (*Cell.Width* and *Cell.Height*). It also contains the offset to the horizontal and vertical origin point of the character cell (*Cell.OffsetX* and *Cell.OffsetY*). Finally, it contains the default *AdvanceX*. The individual glyph's *OffsetX* and *OffsetY* value is added to this position to determine where to draw the top-left pixel of the character's glyph. The character glyph's *AdvanceX* is added to this position to determine the origin point for the next character.

FontStyle

The design style of the font, 1 bit per style. See **EFI_HII_FONT_STYLE**.

FontFamily

The null-terminated string with the name of the font family to which the font belongs.

Related Definitions

```

typedef UINT32 EFI_HII_FONT_STYLE;
#define EFI_HII_FONT_STYLE_BOLD          0x00000001
#define EFI_HII_FONT_STYLE_ITALIC       0x00000002
#define EFI_HII_FONT_STYLE_EMBOSS      0x00010000
#define EFI_HII_FONT_STYLE_OUTLINE     0x00020000
#define EFI_HII_FONT_STYLE_SHADOW      0x00040000
#define EFI_HII_FONT_STYLE_UNDERLINE   0x00080000
#define EFI_HII_FONT_STYLE_DBL_UNDER  0x00100000

```

27.3.3.2 Glyph Information

For each Unicode character value, the glyph information gives the glyph bitmap, the character size and the position of the bitmap relative to the origin of the character cell. The glyph information is encoded as a series of blocks, each with a single byte header. The blocks must be processed in order. Each block begins with a single byte, which contains the block type.

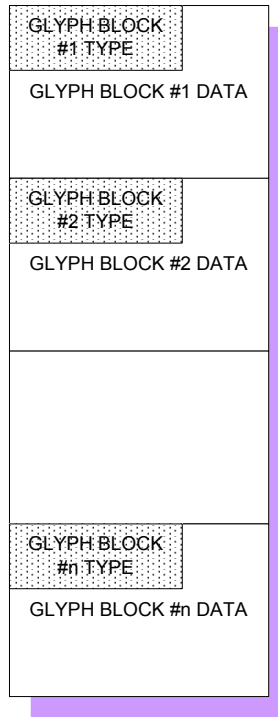


Figure 87. Glyph Information Encoded in Blocks

Prototype

```
typedef struct _EFI_HII_GLYPH_BLOCK {
    UINT8 BlockType;
    UINT8 BlockBody[];
} EFI_HII_GLYPH_BLOCK;
```

Members

The following table describes the different block types:

Name	Value	Description
EFI_HII_GIBT_END	0x00	The end of the glyph information.
EFI_HII_GIBT_GLYPH	0x10	Glyph information for a single character value, bit-packed.
EFI_HII_GIBT_GLYPHS	0x11	Glyph information for multiple character values.
EFI_HII_GIBT_GLYPH_DEFAULT	0x12	Glyph information for a single character value, using the default character cell information.
EFI_HII_GIBT_GLYPHS_DEFAULT	0x13	Glyph information for multiple character values, using the default character cell information.
EFI_HII_GIBT_DUPLICATE	0x20	Create a duplicate of an existing glyph but with a new character value.
EFI_HII_GIBT_SKIP2	0x21	Skip a number (1-65535) character values.

Name	Value	Description
EFI_HII_GIBT_SKIP1	0x22	Skip a number (1-255) character values.
EFI_HII_GIBT_DEFAULTS	0x23	Set default glyph information for subsequent glyph blocks.
EFI_HII_GIBT_EXT1	0x30	For future expansion (one byte length field)
EFI_HII_GIBT_EXT2	0x31	For future expansion (two byte length field)
EFI_HII_GIBT_EXT4	0x32	For future expansion (four byte length field)

Description

In order to recreate all glyphs, start at the first block and process them all until a **EFI_HII_GIBT_END** block is found. When processing the glyph blocks, each block refers to the current character value (*CharValueCurrent*), which is initially set to one (1).

Glyph blocks of an unknown type should be skipped. If they cannot be skipped, then processing halts.

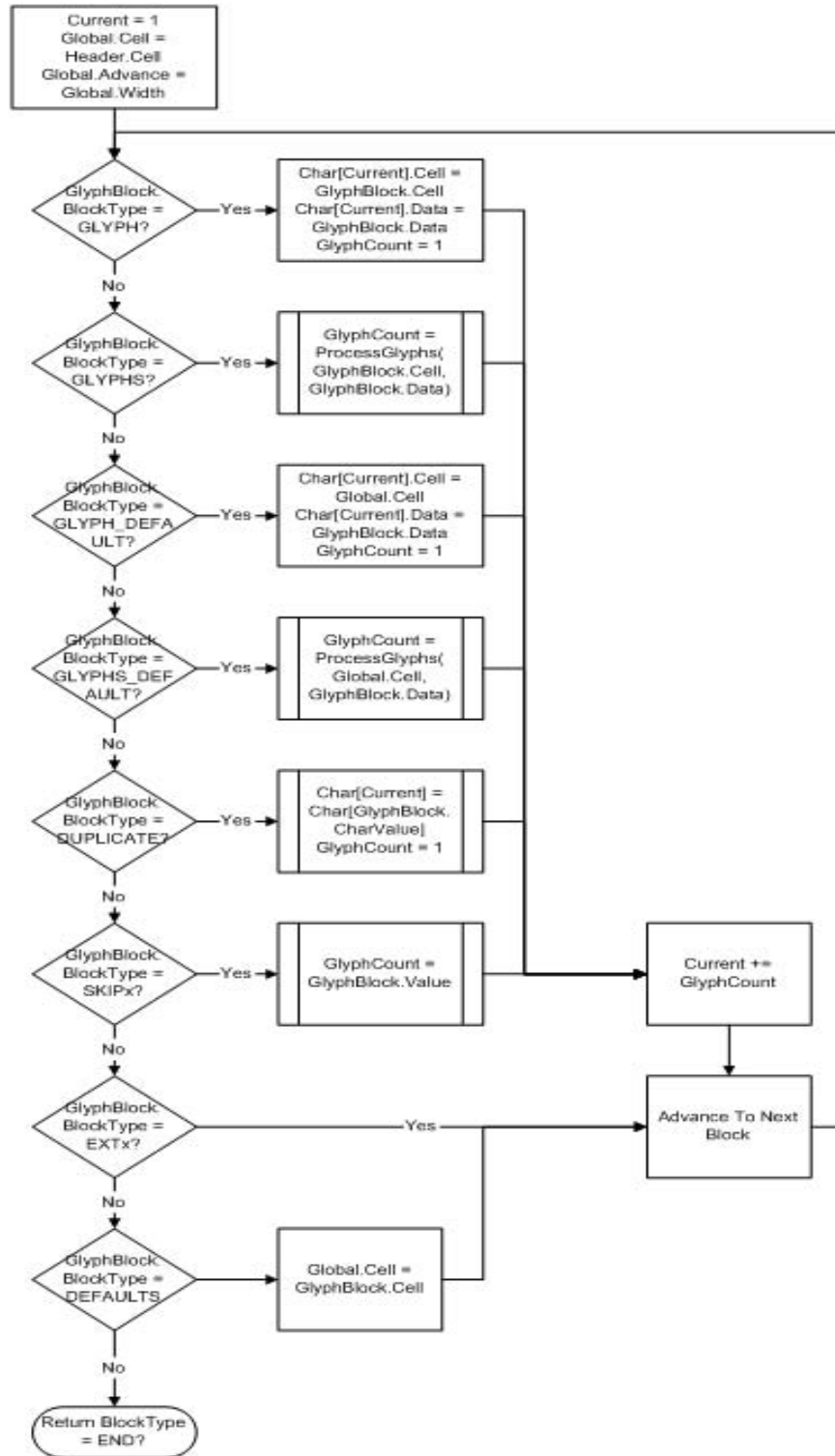


Figure 88. Glyph Block Processing

Related Definitions

```
typedef struct _EFI_HII_GLYPH_INFO {
    UINT16 Width;
    UINT16 Height;
    INT16  OffsetX;
    INT16  OffsetY;
    INT16  AdvanceX;
} EFI_HII_GLYPH_INFO;
```

Width

Width of the character or character cell, in pixels. For fixed-pitch fonts, this is the same as the advance.

Height

Height of the character or character cell, in pixels.

OffsetX

Offset to the horizontal edge of the character cell.

OffsetY

Offset to the vertical edge of the character cell.

AdvanceX

Number of pixels to advance to the right when moving from the origin of the current glyph to the origin of the next glyph.

27.3.3.2.1 EFI_HII_GIBT_DEFAULTS

Summary

Changes the default character cell information.

Prototype

```
typedef struct _EFI_HII_GIBT_DEFAULTS_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    EFI_HII_GLYPH_INFO Cell;
} EFI_HII_GIBT_DEFAULTS_BLOCK;
```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_DEFAULTS**.

Cell

The new default cell information which will be applied to all subsequent **GLYPH_DEFAULT** and **GLYPHS_DEFAULT** blocks.

Description

Changes the default cell information used for subsequent **EFI_HII_GIBT_GLYPH_DEFAULT** and **EFI_HII_GIBT_GLYPHS_DEFAULT** glyph blocks. The cell information described by *Cell* remains in effect until the next **EFI_HII_GIBT_DEFAULTS** is found. Prior to the first **EFI_HII_GIBT_DEFAULTS** block, the cell information in the fixed header are used.

27.3.3.2.2 EFI_HII_GIBT_DUPLICATE

Summary

Assigns a new character value to a previously defined glyph.

Prototype

```
typedef struct _EFI_HII_GIBT_DUPLICATE_BLOCK {
    EFI_HII_GLYPH_BLOCK      Header;
    CHAR16                   CharValue;
} EFI_HII_GIBT_DUPLICATE_BLOCK;
```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_DUPLICATE**.

CharValue

The previously defined character value with the exact same glyph.

Description

Indicates that the glyph with character value *CharValueCurrent* has the same glyph as a previously defined character value and increments *CharValueCurrent* by one.

27.3.3.2.3 EFI_HII_GIBT_END

Summary

Marks the end of the glyph information.

Prototype

```
typedef struct _EFI_GLYPH_GIBT_END_BLOCK {
    EFI_HII_GLYPH_BLOCK      Header;
} EFI_GLYPH_GIBT_END_BLOCK;
```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_END**.

Description

Any glyphs with a character value greater than or equal to *CharValueCurrent* are empty.

27.3.3.2.4 EFI_HII_GIBT_EXT1, EFI_HII_GIBT_EXT2, EFI_HII_GIBT_EXT4

Summary

Future expansion block types which have a length byte.

Prototype

```
typedef struct _EFI_HII_GIBT_EXT1_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    UINT8                BlockType2;
    UINT8                Length;
} EFI_HII_GIBT_EXT1_BLOCK;

typedef struct _EFI_HII_GIBT_EXT2_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    UINT8                BlockType2;
    UINT16               Length;
} EFI_HII_GIBT_EXT2_BLOCK;

typedef struct _EFI_HII_GIBT_EXT4_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    UINT8                BlockType2;
    UINT32               Length;
} EFI_HII_GIBT_EXT4_BLOCK;
```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_EXT1**, **EFI_HII_GIBT_EXT2** or **EFI_HII_GIBT_EXT4**.

Length

Size of the glyph block, in bytes.

Description

These are reserved for future expansion, with length bytes included so that they can be easily skipped.

27.3.3.2.5 EFI_HII_GIBT_GLYPH

Summary

Provide the bitmap for a single glyph.

Prototype

```
typedef struct _EFI_HII_GIBT_GLYPH_BLOCK {
```

```

EFI_HII_GLYPH_BLOCK Header;
EFI_HII_GLYPH_INFO Cell;
UINT16 GlyphCount;
UINT8 BitmapData[];
} EFI_HII_GIBT_GLYPH_BLOCK;

```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_GLYPH**.

Cell

Contains the width and height of the encoded bitmap (*Cell.Width* and *Cell.Height*), the number of pixels (signed) right of the character cell origin where the left edge of the bitmap should be placed (*Cell.OffsetX*), the number of pixels above the character cell origin where the top edge of the bitmap should be placed (*Cell.OffsetY*) and the number of pixels (signed) to move right to find the origin for the next character cell (*Cell.AdvanceX*).

GlyphCount

The number of glyph bitmaps.

BitmapData

The bitmap data specifies a series of pixels, one bit per pixel, *left-to-right, top-to-bottom*. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box, but the entire glyph is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: $((Cell.Width + 7) / 8) * Cell.Height$.

Description

This block provides the bitmap for the character with the value *CharValueCurrent* and increments *CharValueCurrent* by one. Each glyph contains a glyph width and height, a drawing offset, number of pixels to advance after drawing and then the encoded bitmap.

27.3.3.2.6 EFI_HII_GIBT_GLYPHS

Summary

Provide the bitmaps for multiple glyphs with the same cell information

Prototype

```

typedef struct _EFI_HII_GIBT_GLYPHS_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    EFI_HII_GLYPH_INFO Cell;
    UINT8 BitmapData[];
} EFI_HII_GIBT_GLYPHS_BLOCK;

```


Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_GLYPHS**.

Cell

Contains the width and height of the encoded bitmap (*Cell.Width* and *Cell.Height*), the number of pixels (signed) right of the character cell origin where the left edge of the bitmap should be placed (*Cell.OffsetX*), the number of pixels above the character cell origin where the top edge of the bitmap should be placed (*Cell.OffsetY*) and the number of pixels (signed) to move right to find the origin for the next character cell (*Cell.AdvanceX*).

BitmapData

The bitmap data specifies a series of pixels, one bit per pixel, *left-to-right, top-to-bottom*, for each glyph. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box. The number of bytes per bitmap can be calculated as: $((Cell.Width + 7) / 8) * Cell.Height$.

Description

Provides the bitmaps for the characters with the values *CharValueCurrent* through *CharValueCurrent + Count - 1* and increments *CharValueCurrent* by *Count*. These glyphs have identical cell information and the encoded bitmaps are exactly the same number of bytes.

27.3.3.2.7 EFI_HII_GIBT_GLYPH_DEFAULT

Summary

Provide the bitmap for a single glyph, using the default cell information.

Prototype

```
typedef struct _EFI_HII_GIBT_GLYPH_DEFAULT {
    EFI_HII_GLYPH_BLOCK  Header;
    UINT8                BitmapData[];
} EFI_HII_GIBT_GLYPH_DEFAULT;
```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_GLYPH_DEFAULT**.

BitmapData

The bitmap data specifies a series of pixels, one bit per pixel, *left-to-right, top-to-bottom*. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box. The number of bytes per bitmap can be calculated as: $((Global.Cell.Width + 7) / 8) * Global.Cell.Height$.

Description

Provides the bitmap for the character with the value *CharValueCurrent* and increments *CharValueCurrent* by 1. This glyph uses the default cell information. The default cell information is found in the font header or the most recently processed **EFI_HII_GIBT_DEFAULTS**.

27.3.3.2.8 EFI_HII_GIBT_GLYPHS_DEFAULT

Summary

Provide the bitmaps for multiple glyphs with the default cell information

Prototype

```
typedef struct _EFI_HII_GIBT_GLYPHS_DEFAULT_BLOCK {
    EFI_HII_GLYPH_BLOCK  Header;
    UINT16                Count;
    UINT8                BitmapData[];
} EFI_HII_GIBT_GLYPHS_DEFAULT_BLOCK;
```

Members

Header

Standard glyph block header, where *Header.BlockType* = **EFI_HII_GIBT_GLYPHS_DEFAULT**.

Count

Number of glyphs in the glyph block.

BitmapData

The bitmap data specifies a series of pixels, one bit per pixel, *left-to-right, top-to-bottom*, for each glyph. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box. The number of bytes per bitmap can be calculated as: $((Global.Cell.Width + 7) / 8) * Global.Cell.Height$.

Description

Provides the bitmaps for the characters with the values *CharValueCurrent* through *CharValueCurrent + Count - 1* and increments *CharValueCurrent* by *Count*. These glyphs use the default cell information and the encoded bitmaps have exactly the same number of bytes.

27.3.3.2.9 EFI_HII_GIBT_SKIPx

Summary

Increments the current character value *CharValueCurrent* by the number specified.

Prototype

```
typedef struct _EFI_HII_GIBT_SKIP2_BLOCK {
    EFI_HII_GLYPH_BLOCK  Header;
    UINT16                SkipCount;
} EFI_HII_GIBT_SKIP2_BLOCK;
```

```
typedef struct _EFI_HII_GIBT_SKIP1_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    UINT8 SkipCount;
} EFI_HII_GIBT_SKIP1_BLOCK;
```

Members

Header

Standard glyph block header, where *BlockType* = **EFI_HII_GIBT_SKIP1** or **EFI_HII_GIBT_SKIP2**.

SkipCount

The unsigned 8- or 16-bit value to add to *CharValueCurrent*.

Description

Increments the current character value *CharValueCurrent* by the number specified.

27.3.4 Device Path Package

Summary

The device path package is used to carry a device path associated with the package list.

Prototype

```
typedef struct EFI_DEVICE_PATH_PROTOCOL
EFI_HII_DEVICE_PATH_PACKAGE_HDR;
```

Description

This package is created by **NewPackageList()** when the package list is first added to the HII database by locating the **EFI_DEVICE_PATH_PROTOCOL** attached to the driver handle passed in to that function.

27.3.5 GUID Package

The GUID package is used to carry data where the format is defined by a GUID.

Prototype

```
typedef struct _EFI_HII_GUID_PACKAGE_HDR {
    EFI_GUID Guid;
} EFI_HII_GUID_PACKAGE_HDR;
```

Members

Guid

Identifier which describes the remaining data within the package.

Description

This is a free-form package type designed to allow extensibility by allowing the format to be specified using *Guid*.

27.3.6 String Package

The Strings package record describes the mapping between string identifiers and the actual text of the strings themselves. The package consists of three parts: a fixed header, the string information and the font information.

27.3.6.1 Fixed Header

The fixed header consists of a standard record header and then the string identifiers contained in this section and the offsets of the string and language information.

Prototype

```
typedef struct _EFI_HII_STRING_PACKAGE_HDR {
  EFI_HII_PACKAGE_HEADER  Header;
  UINT32                  HdrSize;
  UINT32                  StringInfoOffset;
  CHAR16                  LanguageWindow[16];
  EFI_STRING_ID           LanguageName;
  CHAR8                   Language[ ... ];
} EFI_HII_STRING_PACKAGE_HDR;
```

Members

Header

The standard package header, where *Header.Type* = **EFI_HII_PACKAGE_STRINGS**.

HdrSize

Size of this header.

StringInfoOffset

Offset, relative to the start of this header, of the string information.

LanguageWindow

Specifies the default values placed in the static and dynamic windows before processing each SCSU-encoded strings.

LanguageName

String identifier within the current string package of the full name of the language specified by *Language*.

Language

Language of the strings, as specified by RFC 3066.

Related Definition

```
#define UEFI_CONFIG_LANG L"x-UEFI"
#define UEFI_CONFIG_LANG L"x-i-UEFI"
```

27.3.6.2 String Information

For each string identifier, the string information gives the Unicode text and font. The string information is encoded as a series of blocks, each with a single byte header. The blocks must be processed in order, using the current string identifier (*StringIdCurrent*), which is set initially to one (1). Processing continues until an **SIBT_END** block is found.

There are three types of blocks: string blocks, duplicate blocks and skip blocks. String blocks specify the text and font for the current string identifier and increment to the next string identifier. Duplicate blocks copy the text of a previous string identifier and increment to the next string identifier. Skip blocks skip string identifiers, leaving them blank.

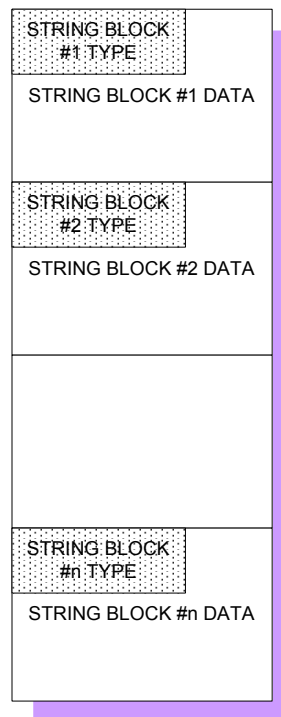


Figure 89. String Information Encoded in Blocks

Each block begins with a single byte, which contains the block type.

```
typedef struct {
    UINT8 BlockType;
    UINT8 BlockBody[];
} EFI_HII_STRING_BLOCK;
```

The following table describes the different block types:

Name	Value	Description
------	-------	-------------

Unified Extensible Firmware Interface Specification

EFI_HII_SIBT_END	0x00	The end of the string information.
EFI_HII_SIBT_STRING_SCSU	0x10	Single string using default font information.
EFI_HII_SIBT_STRING_SCSU_FONT	0x11	Single string with font information.
EFI_HII_SIBT_STRINGS_SCSU	0x12	Multiple strings using default font information.
EFI_HII_SIBT_STRINGS_SCSU_FONT	0x13	Multiple strings with font information.
EFI_HII_SIBT_STRING_UCS2	0x14	Single UCS-2 string using default font information.
EFI_HII_SIBT_STRING_UCS2_FONT	0x15	Single UCS-2 string with font information.
EFI_HII_SIBT_STRINGS_UCS2	0x16	Multiple UCS-2 strings using default font information.
EFI_HII_SIBT_STRINGS_UCS2_FONT	0x17	Multiple UCS-2 strings with font information.
EFI_HII_SIBT_DUPLICATE	0x20	Create a duplicate of an existing string.
EFI_HII_SIBT_SKIP2	0x21	Skip a certain number of string identifiers.
EFI_HII_SIBT_SKIP1	0x22	Skip a certain number of string identifiers.
EFI_HII_SIBT_EXT1	0x30	For future expansion (one byte length field)
EFI_HII_SIBT_EXT2	0x31	For future expansion (two byte length field)
EFI_HII_SIBT_EXT4	0x32	For future expansion (four byte length field)
EFI_HII_SIBT_FONT	0x40	Font information.

When processing the string blocks, each block type refers and modifies the current string identifier(*StringIdCurrent*).

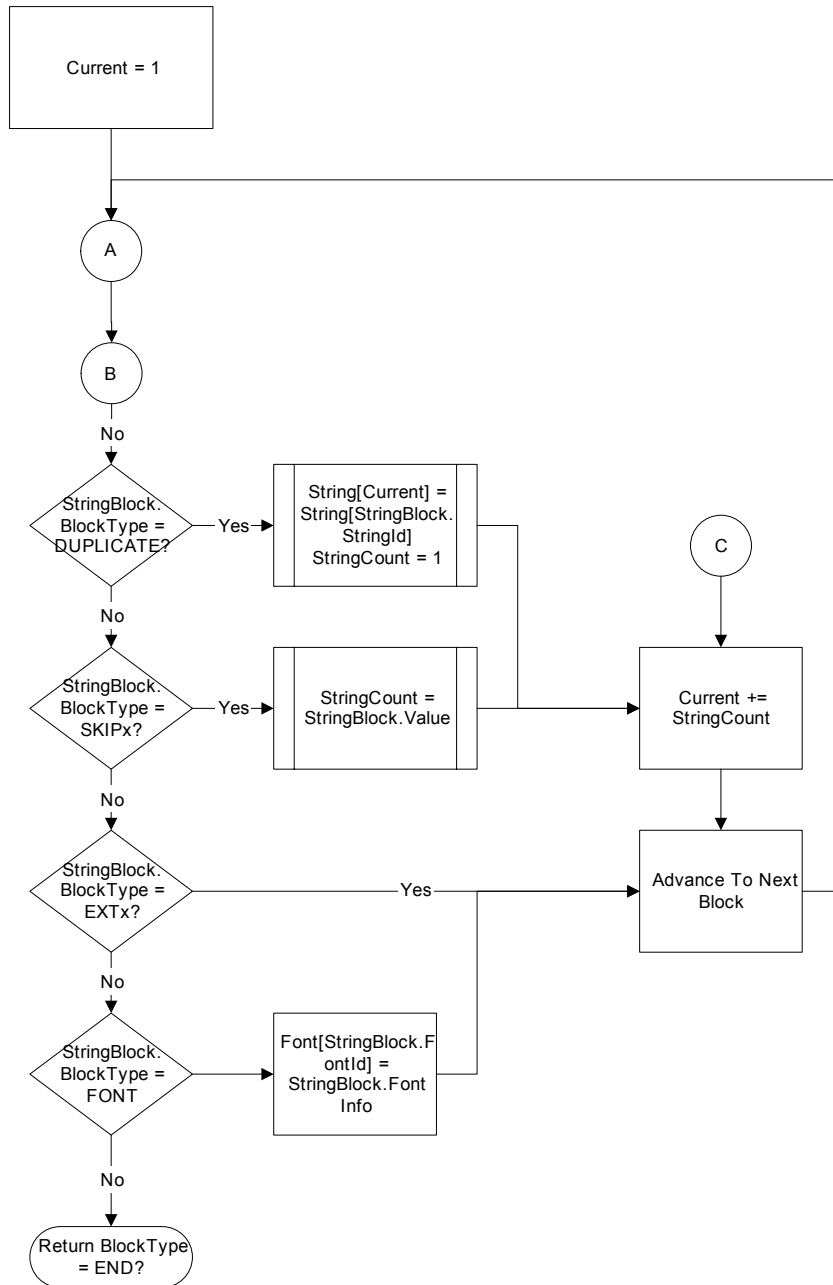


Figure 90. String Block Processing: Base Processing

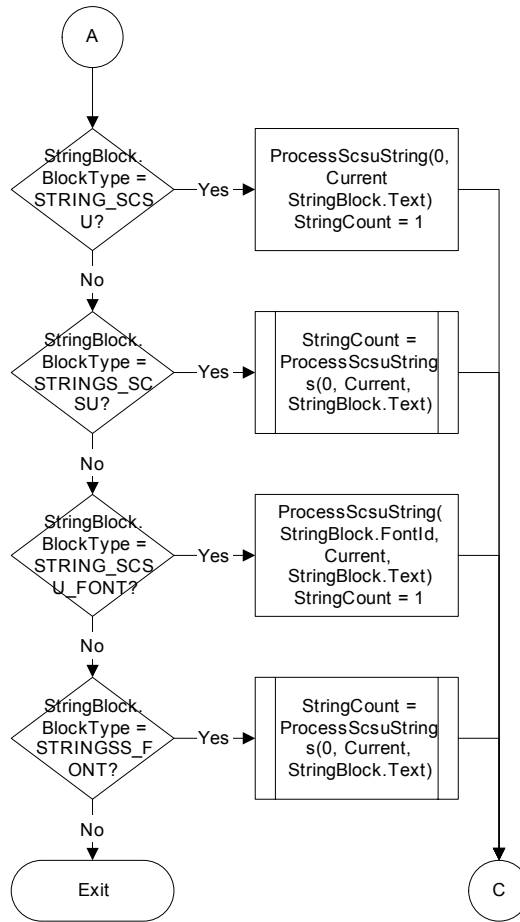


Figure 91. String Block Processing: SCSU Processing

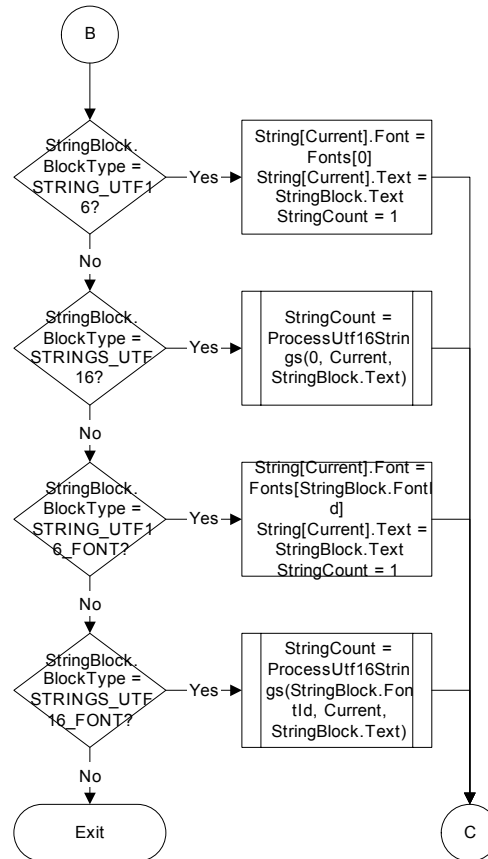


Figure 92. String Block Processing: UTF Processing

27.3.6.2.1 EFI_HII_SIBT_DUPLICATE

Summary

Creates a duplicate of a previously defined string.

Prototype

```

typedef struct _EFI_HII_SIBT_DUPLICATE_BLOCK {
    EFI_HII_STRING_BLOCK    Header;
    EFI_STRING_ID           StringId;
} EFI_HII_SIBT_DUPLICATE_BLOCK;
  
```

Members

Header

Standard string block header, where **Header.BlockType = EFI_HII_SIBT_DUPLICATE**.

StringId

The string identifier of a previously defined string with the exact same string text.

Description

Indicates that the string with string identifier *StringIdCurrent* is the same as a previously defined string and increments *StringIdCurrent* by one.

27.3.6.2.2 EFI_HII_SIBT_END

Summary

Marks the end of the string information.

Prototype

```
typedef struct _EFI_HII_SIBT_END_BLOCK {
    EFI_HII_STRING_BLOCK Header;
} EFI_HII_SIBT_END_BLOCK;
```

Members

Header

Standard string block header, where `Header.BlockType = EFI_HII_SIBT_END`.

Description

Any strings with a string identifier greater than or equal to *StringIdCurrent* are empty.

27.3.6.2.3 EFI_HII_SIBT_EXT1, EFI_HII_SIBT_EXT2, EFI_HII_SIBT_EXT4

Summary

Future expansion block types which have a length byte.

Prototype

```
typedef struct _EFI_HII_SIBT_EXT1_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 BlockType2;
    UINT8 Length;
} EFI_HII_SIBT_EXT1_BLOCK;
```

```
typedef struct _EFI_HII_SIBT_EXT2_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 BlockType2;
    UINT16 Length;
} EFI_HII_SIBT_EXT2_BLOCK;
```

```
typedef struct _EFI_HII_SIBT_EXT4_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 BlockType2;
    UINT32 Length;
} EFI_HII_SIBT_EXT4_BLOCK;
```

Members

Header

Standard string block header, where *Header.BlockType* = **EFI_HII_SIBT_EXT1**, **EFI_HII_SIBT_EXT2** or **EFI_HII_SIBT_EXT4**.

Length

Size of the string block, in bytes.

Description

These are reserved for future expansion, with length bytes included so that they can be easily skipped.

27.3.6.2.4 EFI_HII_SIBT_FONT

Summary

Provide information about a single font.

Prototype

```
typedef struct _EFI_HII_SIBT_FONT_BLOCK {
    EFI_HII_SIBT_EXT2  Header;
    UINT8              FontId;
    UINT16             FontSize;
    EFI_HII_FONT_STYLE FontStyle;
    CHAR16             FontName[...];
} EFI_HII_SIBT_FONT_BLOCK;
```

Members

Header

Standard extended header, where *Header.BlockType* = **EFI_HII_SIBT_FONT**.

FontId

Font identifier, which must be unique within the font package.

FontSize

Character cell size, in pixels, of the font.

FontStyle

Font style. Type **EFI_HII_FONT_STYLE** is defined in “Related Definitions” in **EFI_HII_FONT_PACKAGE_HDR**.

FontName

Null-terminated font family name.

Description

Associates a font identifier *FontId* with a font name *FontName*, size *FontSize* and style *FontStyle*. This font identifier may be used with the string blocks. The font identifier 0 is the default font for those string blocks which do not specify a font identifier.

27.3.6.2.5 EFI_HII_SIBT_SKIP1

Summary

Skips string identifiers.

Prototype

```
typedef struct _EFI_HII_SIBT_SKIP1_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8                SkipCount;
} EFI_HII_SIBT_SKIP1_BLOCK;
```

Members

Header

Standard string block header, where *Header.BlockType* = **EFI_HII_SIBT_SKIP1**.

SkipCount

The unsigned 8-bit value to add to *StringIdCurrent*.

Description

Increments the current string identifier *StringIdCurrent* by the number specified.

27.3.6.2.6 EFI_HII_SIBT_SKIP2

Summary

Skips string ids.

Prototype

```
typedef struct _EFI_HII_SIBT_SKIP2_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT16               SkipCount;
} EFI_HII_SIBT_SKIP2_BLOCK;
```

Members

Header

Standard string block header, where *Header.BlockType* = **EFI_HII_SIBT_SKIP2**.

SkipCount

The unsigned 16-bit value to add to *StringIdCurrent*.

Description

Increments the current string identifier *StringIdCurrent* by the number specified.

27.3.6.2.7 EFI_HII_SIBT_STRING_SCSU

Summary

Describe a string encoded using SCSU, in the default font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRING_SCSU_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    UINT8                 StringText[];
} EFI_HII_SIBT_STRING_SCSU_BLOCK;
```

Members

Header

Standard header where *Header.BlockType* =
EFI_HII_SIBT_STRING_SCSU.

StringText

The string text is a null-terminated string, which is assigned to the string identifier *StringIdCurrent*.

Description

This string block provides the SCSU-encoded text for the string in the default font with string identifier *StringIdCurrent* and increments *StringIdCurrent* by one.

27.3.6.2.8 EFI_HII_SIBT_STRING_SCSU_FONT

Summary

Describe a string in the specified font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRING_SCSU_FONT_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    UINT8                 FontIdentifier;
    UINT8                 StringText[];
} EFI_HII_SIBT_STRING_SCSU_FONT_BLOCK;
```

Members

Header

Standard string block header, where *Header.BlockType* =
EFI_HII_SIBT_STRING_SCSU_FONT.

FontIdentifier

The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an **EFI_HII_SIBT_FONT** block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See [Section 27.2.6.2.4](#).

StringText

The string text is a null-terminated encoded string, which is assigned to the string identifier *StringIdCurrent*.

Description

This string block provides the SCSU-encoded text for the string in the font specified by *FontIdentifier* with string identifier *StringIdCurrent* and increments *StringIdCurrent* by one.

27.3.6.2.9 EFI_HII_SIBT_STRINGS_SCSU**Summary**

Describe strings in the default font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRINGS_SCSU_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    UINT16                StringCount;
    UINT8                 StringText[];
} EFI_HII_SIBT_STRINGS_SCSU_BLOCK;
```

Members*Header*

Standard header where *Header.BlockType* = **EFI_HII_SIBT_STRINGS_SCSU**

StringCount

Number of strings in *StringText*.

StringText

The strings, where each string is a null-terminated encoded string.

Description

This string block provides the SCSU-encoded text for *StringCount* strings which have the default font and which have sequential string identifiers. The strings are assigned the identifiers, starting with *StringIdCurrent* and continuing through *StringIdCurrent + StringCount - 1*. *StringIdCurrent* is incremented by *StringCount*.

27.3.6.2.10 EFI_HII_SIBT_STRINGS_SCSU_FONT

Summary

Describe strings in the specified font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRINGS_SCSU_FONT_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    UINT8                 FontIdentifier;
    UINT16                 StringCount;
    UINT8                 StringText[];
} EFI_HII_SIBT_STRINGS_SCSU_FONT_BLOCK;
```

Members

Header

Standard header where *Header.BlockType* = **EFI_HII_SIBT_STRINGS_SCSU_FONT**.

StringCount

Number of strings in *StringText*.

FontIdentifier

The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an **EFI_HII_SIBT_FONT** block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See [Section 27.2.6.2.4](#).

StringText

The strings, where each string is a null-terminated encoded string.

Description

This string block provides the SCSU-encoded text for *StringCount* strings which have the font specified by *FontIdentifier* and which have sequential string identifiers. The strings are assigned the identifiers, starting with *StringIdCurrent* and continuing through *StringIdCurrent* + *StringCount* - 1. *StringIdCurrent* is incremented by *StringCount*.

27.3.6.2.11 EFI_HII_SIBT_STRING_UCS2

Summary

Describe a string in the default font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRING_UCS2_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    CHAR16                 StringText[];
} EFI_HII_SIBT_STRING_UCS2_BLOCK;
```

Members

Header

Standard header where *Header.BlockType* = **EFI_HII_SIBT_STRING_UCS2**.

StringText

The string text is a null-terminated UCS-2 string, which is assigned to the string identifier *StringIdCurrent*.

Description

This string block provides the UCS-2 encoded text for the string in the default font with string identifier *StringIdCurrent* and increments *StringIdCurrent* by one.

27.3.6.2.12 EFI_HII_SIBT_STRING_UCS2_FONT

Summary

Describe a string in the specified font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRING_UCS2_FONT_BLOCK {
    EFI_HII_STRING_BLOCK      Header;
    UINT8                     FontIdentifier;
    CHAR16                    StringText[];
} EFI_HII_SIBT_STRING_UCS2_FONT_BLOCK;
```

Members

Header

Standard header where *Header.BlockType* = **EFI_HII_SIBT_STRING_UCS2_FONT**.

FontIdentifier

The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an **EFI_HII_SIBT_FONT** block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See [Section 27.2.6.2.4](#).

StringText

The string text is a null-terminated UCS-2 string, which is assigned to the string identifier *StringIdCurrent*.

Description

This string block provides the UCS-2 encoded text for the string in the font specified by *FontIdentifier* with string identifier *StringIdCurrent* and increments *StringIdCurrent* by one.

27.3.6.2.13 EFI_HII_SIBT_STRINGS_UCS2

Summary

Describes strings in the default font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRINGS_UCS2_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    UINT16                StringCount;
    CHAR16               StringText[];
} EFI_HII_SIBT_STRINGS_UCS2_BLOCK;
```

Members

Header

Standard header where *Header.BlockType* = **EFI_HII_SIBT_STRINGS_UCS2**.

StringCount

Number of strings in *StringText*.

StringText

The string text is a series of null-terminated UCS-2 strings, which are assigned to the string identifiers *StringIdCurrent*.to *StringIdCurrent* + *StringCount* - 1.

Description

This string block provides the UCS-2 encoded text for the strings in the default font with string identifiers *StringIdCurrent* to *StringIdCurrent* + *StringCount* - 1 and increments *StringIdCurrent* by *StringCount*.

27.3.6.2.14 EFI_HII_SIBT_STRINGS_UCS2_FONT

Summary

Describes strings in the specified font.

Prototype

```
typedef struct _EFI_HII_SIBT_STRINGS_UCS2_FONT_BLOCK {
    EFI_HII_STRING_BLOCK  Header;
    UINT8                FontIdentifier;
    UINT16               StringCount;
    CHAR16               StringText[];
} EFI_HII_SIBT_STRING_UCS2_FONT_BLOCK;
```

Members

Header

Standard header where *Header.BlockType* = **EFI_HII_SIBT_STRINGS_UCS2_FONT**.

FontIdentifier

The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an **EFI_HII_SIBT_FONT** block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See [Section 27.2.6.2.4](#).

StringCount

Number of strings in *StringText*.

StringText

The string text is a series of null-terminated UCS-2 strings, which are assigned to the string identifiers *StringIdCurrent*.through *StringIdCurrent* + *StringCount* - 1.

Description

This string block provides the UCS-2 encoded text for the strings in the font specified by *FontIdentifier* with string identifiers *StringIdCurrent* to *StringIdCurrent* + *StringCount* - 1 and increments *StringIdCurrent* by *StringCount*.

27.3.6.3 String Encoding

Each of the following sections describes part of how string text is encoded.

27.3.6.3.1 Standard Compression Scheme for Unicode (SCSU)

The Unicode consortium provides a standard text compression algorithm, which minimizes the amount of storage required for multiple-language strings. For more information, see <http://www.unicode.org/unicode/reports/tr6>.

This specification extends the technique described in the following ways:

- The strings use the control code 0x7F to introduce the control codes described in [Section 27.2.6.2.4](#). The following byte is the control code. The character value 0x7F will be encoded as 0x01 (*SQ0*) 0x7F.
- The language information contains default static and dynamic code windows, whereas SCSU provides fixed values for these.
- Characters between 0xF000 and 0xFCFF should be rejected.

27.3.6.3.2 Unicode 2-Byte Encoding (UCS-2)

The Unicode consortium provides a standard encoding algorithm, which takes two bytes per character. See <http://www.unicode.org/> for more information.

Characters between 0xF000 and 0xFCFF should be rejected.

27.3.7 Image Package

The Image package record describes the mapping between image identifiers and the pixels of the image themselves. The package consists of three parts: a fixed header, image information and the palette information.

27.3.7.1 Fixed Header

Summary

The fixed header consists of a standard record header and the offsets of the image and palette information.

Prototype

```
typedef struct _EFI_HII_IMAGE_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    UINT32 ImageInfoOffset;
    UINT32 PaletteInfoOffset;
} EFI_HII_IMAGE_PACKAGE_HDR;
```

Members

Header

Standard package header, where *Header.Type* = **EFI_HII_PACKAGE_IMAGES**.

ImageInfoOffset

Offset, relative to this header, of the image information. If this is zero, then there are no images in the package.

PaletteInfoOffset

Offset, relative to this header, of the palette information. If this is zero, then there are no palettes in the image package.

27.3.7.2 Image Information

For each image identifier, the image information gives the bitmap and the relevant palette. The image information is encoded as a series of blocks, each with a single byte header. The blocks must be processed in order.

Each block begins with a single byte, which contains the block type.

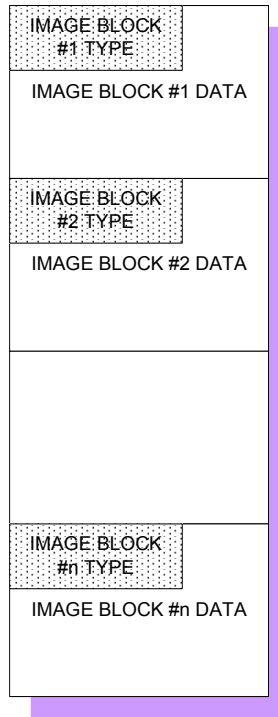


Figure 93. Image Information Encoded in Blocks

Prototype

```
typedef struct _EFI_HII_IMAGE_BLOCK {
    UINT8 BlockType;
    UINT8 BlockBody[];
} EFI_HII_IMAGE_BLOCK;
```

The following table describes the different block types:

Name	Value	Description
EFI_HII_IIBT_END	0x00	The end of the string information.
EFI_HII_IIBT_IMAGE_1BIT	0x10	1-bit w/palette
EFI_HII_IIBT_IMAGE_1BIT_TRANS	0x11	1-bit w/palette & transparency
EFI_HII_IIBT_IMAGE_4BIT	0x12	4-bit w/palette
EFI_HII_IIBT_IMAGE_4BIT_TRANS	0x13	4-bit w/palette & transparency
EFI_HII_IIBT_IMAGE_8BIT	0x14	8-bit w/palette
EFI_HII_IIBT_IMAGE_8BIT_TRANS	0x15	8-bit w/palette & transparency
EFI_HII_IIBT_IMAGE_24BIT	0x16	24-bit RGB
EFI_HII_IIBT_IMAGE_24BIT_TRANS	0x17	24-bit RGB w/transparency
EFI_HII_IIBT_IMAGE_JPEG	0x18	JPEG encoded image

EFI_HII_IIBT_DUPLICATE	0x20	Duplicate an existing image identifier
EFI_HII_IIBT_SKIP2	0x21	Skip a certain number of image identifiers.
EFI_HII_IIBT_SKIP1	0x22	Skip a certain number of image identifiers.
EFI_HII_IIBT_EXT1	0x30	For future expansion (one byte length field)
EFI_HII_IIBT_EXT2	0x31	For future expansion (two byte length field)
EFI_HII_IIBT_EXT4	0x32	For future expansion (four byte length field)

In order to recreate all images, start at the first block and process them all until an **EFI_HII_IIBT_END** block is found. When processing the image blocks, each block refers to the current image identifier (*ImageIdCurrent*), which is initially set to one (1).

Image blocks of an unknown type should be skipped. If they cannot be skipped, then processing halts.

27.3.7.2.1 EFI_HII_IIBT_END

Summary

Marks the end of the image information.

Prototype

```
typedef struct _EFI_HII_IIBT_END {
    EFI_HII_IMAGE_BLOCK Header;
} EFI_HII_IIBT_END;
```

Members

Header

Standard image block header, where *Header.BlockType* = **EFI_HII_IIBT_END**.

Description

Any images with an image identifier greater than or equal to *ImageIdCurrent* are empty.

27.3.7.2.2 EFI_HII_IIBT_EXT1, EFI_HII_IIBT_EXT2, EFI_HII_IIBT_EXT4

Summary

Generic prefix for image information with a 1-byte length.

Prototype

```
typedef struct _EFI_HII_IIBT_EXT1 {
    EFI_HII_IMAGE_BLOCK Header;
    UINT8 BlockType2;
    UINT8 Length;
} EFI_HII_IIBT_EXT1;

typedef struct _EFI_HII_IIBT_EXT2 {
```

```

        EFI_HII_IMAGE_BLOCK    Header;
        UINT8                  BlockType2;
        UINT16                  Length;
    } EFI_HII_IIBT_EXT2;

typedef struct _EFI_HII_IIBT_EXT4 {
    EFI_HII_IMAGE_BLOCK    Header;
    UINT8                  BlockType2;
    UINT32                  Length;
} EFI_HII_IIBT_EXT4;

```

Members

Header

Standard image block header, where *Header.BlockType* = **EFI_HII_IIBT_EXT1**, **EFI_HII_IIBT_EXT2** or **EFI_HII_IIBT_EXT4**.

Length

Size of the image block, in bytes, including the image block header.

Description

Future extensions for image records which need a length-byte length use this prefix.

27.3.7.2.3 EFI_HII_IIBT_IMAGE_1BIT

Summary

One bit-per-pixel graphics image with palette information.

Prototype

```

typedef struct _EFI_HII_IIBT_IMAGE_1BIT_BASE {
    UINT16                Width;
    UINT16                Height;
    UINT8                  Data[ ... ];
} EFI_HII_IIBT_IMAGE_1BIT_BASE;

typedef struct _EFI_HII_IBIT_IMAGE_1BIT {
    EFI_HII_IMAGE_BLOCK    Header;
    UINT8                  PaletteIndex;
    EFI_HII_IMAGE_1BIT_BASE Bitmap;
} EFI_HII_IBIT_IMAGE_1BIT;

```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_1BIT**.

Width

Width of the bitmap in pixels.

Height

Height of the bitmap in pixels.

Bitmap

The bitmap specifies a series of pixels, one bit per pixel, *left-to-right, top-to-bottom*, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: $((Width + 7)/8) * Height$.

PaletteIndex

Index of the palette in the palette information.

Description

This record assigns the 1-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier and increment *ImageIdCurrent* by one. The image's upper left hand corner pixel is the most significant bit of the first bitmap byte. An example of a **EFI_HII_IMAGE_1BIT** structure is shown below:

```

0x01           ; Palette Index
0x000B        ; Width
0x0013        ; Height
10000000b,00000000b ; Bitmap
11000000b,00000000b
11100000b,00000000b
11110000b,00000000b
11111000b,00000000b
11111100b,00000000b
11111110b,00000000b
11111111b,00000000b
11111111b,10000000b
11111111b,11000000b
11111111b,11100000b
11111110b,00000000b
11101111b,00000000b
11001111b,00000000b
10000111b,10000000b
00000111b,10000000b
00000011b,11000000b
00000011b,11000000b
00000001b,10000000b
0x0006       ; Palette Size
0x00,0x00,0x00 ; Entry 0 (black)
0xFF,0xFF,0xFF ; Entry 1 (white)

```

27.3.7.2.4 EFI_HII_IIBT_IMAGE_1BIT_TRANS

Summary

One bit-per-pixel graphics image with palette information and transparency.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_1BIT_TRANS {
    EFI_HII_IMAGE_BLOCK      Header;
    UINT8                    PaletteIndex;
    EFI_HII_IIBT_IMAGE_1BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_1BIT_TRANS;
```

Members*Header*

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_1BIT_TRANS**.

PaletteIndex

Index of the palette in the palette information.

Bitmap

The bitmap specifies a series of pixels, one bit per pixel, *left-to-right, top-to-bottom*, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: $((Width + 7)/8) * Height$.

Description

This record assigns the 1-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier and increment *ImageIdCurrent* by one. The data in the **EFI_HII_IIBT_IMAGE_1BIT_TRANS** structure is exactly the same as the **EFI_HII_IMAGE_1BIT** structure, the difference is how the data is treated.

The bitmap pixel value 0 is the ‘transparency’ value and will not be written to the screen. The bitmap pixel value 1 will be translated to the color specified by *Palette*.

27.3.7.2.5 EFI_HII_IIBT_IMAGE_24BIT

Summary

A 24 bit-per-pixel graphics image.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_24BIT_BASE {
    UINT16      Width;
    UINT16      Height;
    EFI_HII_RGB_PIXEL Bitmap[ ... ];
} EFI_HII_IIBT_IMAGE_24BIT_BASE;
```


Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_24BIT**.

Bitmap

The bitmap specifies a series of pixels, 24 bits per pixel, *left-to-right, top-to-bottom*. The number of bytes per bitmap can be calculated as: (Width * 3) * Height. Type **EFI_HII_RGB_PIXEL** is defined in “Related Definitions” below.

Description

This record assigns the 24-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier and increment *ImageIdCurrent* by one. The image’s upper left hand corner pixel is composed of the first three bitmap bytes. The first byte is the pixel’s blue component value, the next byte is the pixel’s green component value, and the third byte is the pixel’s red component value (B,G,R). Each color component value can vary from 0x00 (color off) to 0xFF (color full on), allowing 16.8 millions colors that can be specified.

Related Definitions

```
typedef struct _EFI_HII_RGB_PIXEL {
    UINT8    b;
    UINT8    g;
    UINT8    r;
} EFI_HII_RGB_PIXEL;
```

b

The relative intensity of blue in the pixel’s color, from off (0x00) to full-on (0xFF).

g

The relative intensity of green in the pixel’s color, from off (0x00) to full-on (0xFF).

r

The relative intensity of red in the pixel’s color, from off (0x00) to full-on (0xFF).

27.3.7.2.6 EFI_HII_IIBT_IMAGE_24BIT_TRANS

Summary

A 24 bit-per-pixel graphics image with transparency.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_24BIT_BASE {
    UINT16 Width;
    UINT16 Height;
    UINT8  Data[ ... ];
} EFI_HII_IIBT_IMAGE_24BIT_BASE;
```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_24BIT_TRANS**.

Bitmap

The bitmap specifies a series of pixels, 24 bits per pixel, *left-to-right, top-to-bottom*. The number of bytes per bitmap can be calculated as: (Width * 3) * Height.

Description

This record assigns the 24-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier and increment *ImageIdCurrent* by one. The data in the **EFI_HII_IMAGE_24BIT_TRANS** structure is exactly the same as the **EFI_HII_IMAGE_24BIT** structure, the difference is how the data is treated.

The bitmap pixel value 0x00, 0x00, 0x00 is the ‘transparency’ value and will not be written to the screen. All other bitmap pixel values will be written as defined to the screen. Since the ‘transparency’ value replaces *true* black, for image to display black they should use the color 0x00, 0x00, 0x01 (very dark red)

27.3.7.2.7 EFI_HII_IIBT_IMAGE_4BIT

Summary

Four bits-per-pixel graphics image with palette information.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_4BIT_BASE {
    UINT16    Width;
    UINT16    Height;
    UINT8     Data[ ... ];
} EFI_HII_IIBT_IMAGE_4BIT_BASE;

typedef struct _EFI_HII_IIBT_IMAGE_4BIT {
    EFI_HII_IMAGE_BLOCK    Header;
    UINT8                  PaletteIndex;
    EFI_HII_IMAGE_4BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_4BIT;
```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_4BIT**.

PaletteIndex

Index of the palette in the palette information.

Bitmap

The bitmap specifies a series of pixels, four bits per pixel, *left-to-right, top-to-bottom*, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: $((Width + 1)/2) * Height$.

Description

This record assigns the 4-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier using the specified palette and increment *ImageIdCurrent* by one. The image's upper left hand corner pixel is the most significant nibble of the first bitmap byte.

27.3.7.2.8 EFI_HII_IIBT_IMAGE_4BIT_TRANS**Summary**

Four bits-per-pixel graphics image with palette information and transparency.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_4BIT_BASE {
    UINT16    Width;
    UINT16    Height;
    UINT8     Data[ ... ];
} EFI_HII_IIBT_IMAGE_4BIT_BASE;

typedef struct _EFI_HII_IIBT_IMAGE_4BIT_TRANS {
    EFI_HII_IMAGE_BLOCK          Header;
    UINT8                        PaletteIndex;
    EFI_HII_IIBT_IMAGE_4BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_4BIT_TRANS;
```

Members*Header*

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_4BIT_TRANS**.

PaletteIndex

Index of the palette in the palette information.

Bitmap

The bitmap specifies a series of pixels, four bits per pixel, *left-to-right, top-to-bottom*, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: $((Width + 1)/2) * Height$.

Description

This record assigns the 4-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier using the specified palette and increment *ImageIdCurrent* by one. The data in the **EFI_HII_IIBT_IMAGE_4BIT_TRANS** structure is exactly the same as the **EFI_HII_IMAGE_4BIT** structure, the difference is how the data is treated.

The bitmap pixel value 0 is the ‘transparency’ value and will not be written to the screen. All the other bitmap pixel values will be translated to the color specified by *Palette*.

27.3.7.2.9 EFI_HII_IIBT_IMAGE_8BIT

Summary

Eight bits-per-pixel graphics image with palette information.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_8BIT_BASE {
    UINT16    Width;
    UINT16    Height;
    UINT8     Data[ ... ];
} EFI_HII_IIBT_IMAGE_8BIT_BASE;

typedef struct _EFI_HII_IIBT_IMAGE_8BIT_PALETTE {
    EFI_HII_IMAGE_BLOCK      Header;
    UINT8                    PaletteIndex;
    EFI_HII_IIBT_IMAGE_8BIT_BASE    Bitmap;
} EFI_HII_IIBT_IMAGE_8BIT_PALETTE;
```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_8BIT**.

PaletteIndex

Index of the palette in the palette information.

Bitmap

The bitmap specifies a series of pixels, eight bits per pixel, *left-to-right*, *top-to-bottom*. The number of bytes per bitmap can be calculated as: *Width* * *Height*.

Description

This record assigns the 8-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier using the specified palette and increment *ImageIdCurrent* by one. The image’s upper left hand corner pixel is the first bitmap byte.

27.3.7.2.10 EFI_HII_IIBT_IMAGE_8BIT_TRANS

Summary

Eight bits-per-pixel graphics image with palette information and transparency.

Prototype

```
typedef struct _EFI_HII_IIBT_IMAGE_8BIT_BASE {
    UINT16    Width;
    UINT16    Height;
```

```

    UINT8    Data[ ... ];
} EFI_HII_IIBT_IMAGE_8BIT_BASE;

typedef struct _EFI_HII_IIBT_IMAGE_8BIT_TRANS {
    EFI_HII_IMAGE_BLOCK    Header;
    UINT8                  PaletteIndex;
    EFI_HII_IMAGE_8BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_8BIT_TRANS;

```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_8BIT_TRANS**.

PaletteIndex

Index of the palette in the palette information.

Bitmap

The bitmap specifies a series of pixels, eight bits per pixel, *left-to-right, top-to-bottom*. The number of bytes per bitmap can be calculated as: *Width * Height*.

Description

This record assigns the 8-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier using the specified palette and increment *ImageIdCurrent* by one. The data in the **EFI_HII_IMAGE_8BIT_TRANS** structure is exactly the same as the **EFI_HII_IMAGE_8BIT** structure, the difference is how the data is treated.

The bitmap pixel value 0 is the ‘transparency’ value and will not be written to the screen. All the other bitmap pixel values will be translated to the color specified by *Palette*.

27.3.7.2.11 EFI_HII_IIBT_DUPLICATE

Summary

Assigns a new character value to a previously defined image.

Prototype

```

typedef struct _EFI_HII_IIBT_DUPLICATE_BLOCK {
    EFI_HII_IMAGE_BLOCK    Header;
    EFI_IMAGE_ID           ImageId;
} EFI_HII_IIBT_DUPLICATE_BLOCK;

```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_DUPLICATE**.

ImageId

The previously defined image ID with the exact same image.

Description

Indicates that the image with image ID *ImageValueCurrent* has the same image as a previously defined image ID and increments *ImageValueCurrent* by one.

27.3.7.2.12 EFI_HII_IIBT_IMAGE_JPEG

Summary

A true-color bitmap is encoded with JPEG image compression.

Prototype

```
typedef struct _EFI_HII_IIBT_JPEG {
EFI_HII_IMAGE_BLOCK  Header;
    UINT32              Size;
    UINT8               Data[ ... ];
} EFI_HII_IIBT_JPEG;
```

Members

Header

Standard image header, where *Header.BlockType* = **EFI_HII_IIBT_IMAGE_JPEG**.

Size

Specifies the size of the JPEG encoded data.

Data

JPEG encoded data with ‘JFIF’ signature at offset 6 in the data block. The JPEG encoded data, specifies type of encoding and final size of true-color image.

Description

This record assigns the JPEG image data to the *ImageIdCurrent* identifier and increment *ImageIdCurrent* by one. The JPEG decoder is only required to cover the basic JPEG encoding types, which are produced by standard available paint packages (for example: MSPaint under Windows from Microsoft). This would include JPEG encoding of high (1:1:1) and medium (4:1:1) quality with only three components (R,G,B) – no support for the special gray component encoding.

27.3.7.2.13 EFI_HII_IIBT_SKIP1

Summary

Skips image IDs.

Prototype

```
typedef struct _EFI_HII_IIBT_SKIP1_BLOCK {
```

```

EFI_HII_IMAGE_BLOCK  Header;
UINT8                SkipCount;
} EFI_HII_IIBT_SKIP1_BLOCK;

```

Members

Header

Standard image header, where *Header.BlockType* = `EFI_HII_IIBT_SKIP1`.

SkipCount

The unsigned 8-bit value to add to *ImageIdCurrent*.

Description

Increments the current image ID *ImageIdCurrent* by the number specified.

27.3.7.2.14 EFI_HII_IIBT_SKIP2

Summary

Skips image IDs.

Prototype

```

typedef struct _EFI_HII_IIBT_SKIP2_BLOCK {
    EFI_HII_IMAGE_BLOCK  Header;
    UINT16                SkipCount;
} EFI_HII_IIBT_SKIP2_BLOCK;

```

Members

Header

Standard image header, where *Header.BlockType* = `EFI_HII_IIBT_SKIP2`.

SkipCount

The unsigned 16-bit value to add to *ImageIdCurrent*.

Description

Increments the current image ID *ImageIdCurrent* by the number specified.

27.3.7.3 Palette Information

Summary

This section describes the palette information within an image package.

Prototype

```

typedef struct _EFI_HII_IMAGE_PALETTE_INFO_HEADER {
    UINT16 PaletteCount;
} EFI_HII_IMAGE_PALETTE_INFO_HEADER;

```

Members

PaletteCount

Number of palettes.

Description

This fixed header is followed by zero or more variable-length palette information records. The structures are assigned a number 1 to n.

27.3.7.3.1 Palette Information Records

Summary

A single palette

Prototype

```
typedef struct _EFI_HII_IMAGE_PALETTE_INFO {
    UINT16          PaletteSize;
    EFI_HII_RGB_PIXEL PaletteValue[...];
} EFI_HII_IMAGE_PALETTE_INFO;
```

Members

PaletteSize

Size of the palette information.

PaletteValue

Array of color values. Type **EFI_HII_RGB_PIXEL** is described in Related Definitions in **EFI_HII_IIBT_IMAGE_24BIT**.

Description

Each palette information record is an array of 24-bit color structures. The first entry (**PaletteValue[0]**) corresponds to color 0 in the source image; the second entry (**PaletteValue[1]**) corresponds to color 1, etc. Each palette entry is a three byte entry, with the first byte equal to the blue component of the color, followed by green, and finally red (B,G,R). Each color component value can vary from 0x00 (color off) to 0xFF (color full on), allowing 16.8 millions colors that can be specified.

A black & white 1-bit image would have the following palette structure:

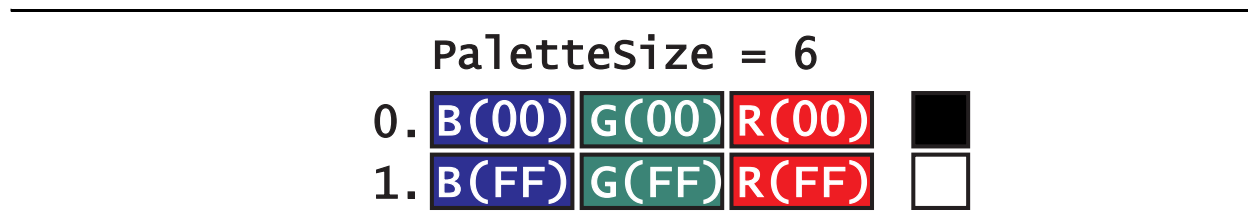


Figure 94. Palette Structure of a Black & White, One-Bit Image

A 4-bit image would have the following palette structure:

PaletteSize = 48

0.	B(00)	G(00)	R(00)	█
1.	B(00)	G(00)	R(80)	█
2.	B(00)	G(80)	R(00)	█
3.	B(00)	G(80)	R(80)	█
4.	B(80)	G(00)	R(00)	█
5.	B(80)	G(00)	R(80)	█
6.	B(80)	G(80)	R(00)	█
7.	B(C0)	G(C0)	R(C0)	█
8.	B(80)	G(80)	R(80)	█
9.	B(00)	G(00)	R(FF)	█
A.	B(00)	G(FF)	R(00)	█
B.	B(00)	G(FF)	R(FF)	█
C.	B(FF)	G(00)	R(00)	█
D.	B(FF)	G(00)	R(FF)	█
E.	B(FF)	G(0C)	R(00)	█
F.	B(FF)	G(FF)	R(FF)	█

Figure 95. Palette Structure of a Four-Bit Image

The image palette must only contain the palette entries specified in the bitmap. The bitmap should allocate each color index starting from 0x00, so the palette information can be as small as possible. The following is an example of a palette structure of a 4-bit image that only uses 6 colors:

PaletteSize = 18

0.	B(00)	G(00)	R(00)	█
1.	B(99)	G(00)	R(33)	█
2.	B(CC)	G(00)	R(33)	█
3.	B(FF)	G(33)	R(66)	█
4.	B(FF)	G(66)	R(66)	█
5.	B(FF)	G(99)	R(66)	█
6.	B(FF)	G(FF)	R(FF)	█

Figure 96. Palette Structure of a Four-Bit, Six-Color Image

Each palette entry specifies each unique color in the image. The above figure would be typical of light blue logo on a black background, with several shades of blue for anti-aliasing the blue logo on the black background.

27.3.8 Forms Package

This section describes all of the opcodes used to represent binary objects in IFR.

27.3.8.1 Binary Encoding

The IFR is a binary encoding for HII-related objects. Every object has (at least) three attributes:

Opcode. The enumeration of all of the different HII-related objects.

Length. The length of the opcode itself (2-127 bytes).

Scope. If set, this opens up a new scope. Certain objects describe attributes or capabilities which only apply to the current scope rather than the entire form. The scope extends up to the special END opcode, which marks the end of the current scope.

The binary objects are encoded as byte stream. Every object begins with a standard header (**EFI_IFR_OP_HEADER**), which describes the opcode type, length and scope.

The simple binary object consists of a standard header, which contains a single 8-bit opcode, a 7-bit length and a 1-bit nesting indicator. The length specifies the number of bytes in the opcode, including the header. The simple binary object may also have zero or more bytes of fixed, object-specific, data.

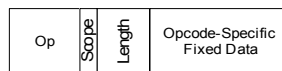


Figure 97. Simple Binary Object

When the *Scope* bit is set, it marks the beginning of a new scope which applies to all subsequent opcodes until the matching **EFI_IFR_END** opcode is found to close the scope. Those opcodes may, in turn, open new scopes as well, creating nested scopes.

27.3.8.2 Standard Headers

27.3.8.2.1 EFI_IFR_OP_HEADER

Summary

Standard opcode header

Prototype

```
typedef struct _EFI_IFR_OP_HEADER {
    UINT8                OpCode;
    UINT8                Length:7;
    UINT8                Scope:1;
} EFI_IFR_OP_HEADER;
```

Members

OpCode

Defines which type of operation is being described by this header. See [Section 27.3.8.3](#) for a list of IFR opcodes.

Length

Defines the number of bytes in the opcode, including this header.

Scope

If this bit is set, the opcode begins a new scope, which is ended by an **EFI_IFR_END** opcode.

Description

Forms are represented in a binary format roughly similar to processor instructions.

Each header contains an opcode, a length and a scope indicator.

If *Scope* indicator is set, the scope exists until it reaches a corresponding **EFI_IFR_END** opcode. Scopes may be nested within other scopes.

Related Definitions

```
typedef UINT16 EFI_QUESTION_ID;
typedef UINT16 EFI_IMAGE_ID;
typedef UINT16 EFI_STRING_ID;
typedef UINT16 EFI_FORM_ID;
typedef UINT16 EFI_VARSTORE_ID;
```

27.3.8.2.2 EFI_IFR_QUESTION_HEADER**Summary**

Standard question header.

Prototype

```
typedef struct _EFI_IFR_QUESTION_HEADER {
    EFI_IFR_STATEMENT_HEADER Header;
    EFI_QUESTION_ID           QuestionId;
    EFI_VARSTORE_ID           VarStoreId;
    union {
        EFI_STRING_ID         VarName;
        UINT16                 VarOffset;
    }                          VarStoreInfo;
    UINT8                     Flags;
} EFI_IFR_QUESTION_HEADER;
```

Members*Header*

The standard statement header.

QuestionId

The unique value that identifies the particular question being defined by the opcode. The value of zero is reserved.

Flags

A bit-mask that determines which unique settings are active for this question. See “Related Definitions” below for the meanings of the individual bits.

VarStoreId

Specifies the identifier of a previously declared variable store to use when storing the question’s value. A value of zero indicates no variable storage.

VarStoreInfo

Depending on the type of variable store selected, this contains either a 16-bit Buffer Storage offset (*VarOffset*) or a Name/Value or EFI Variable name (*VarName*).

Description

This is the standard header for questions.

Related Definitions

```

//*****
// Flags values
//*****
#define EFI_IFR_FLAG_READ_ONLY          0x01
#define EFI_IFR_FLAG_CALLBACK          0x04
#define EFI_IFR_FLAG_RESET_REQUIRED    0x10
#define EFI_IFR_FLAG_OPTIONS_ONLY      0x80
    
```

EFI_IFR_FLAG_READ_ONLY	The question is read-only
EFI_IFR_FLAG_CALLBACK	Designates if a particular opcode is to be treated as something that will initiate a callback to a registered driver.
EFI_IFR_FLAG_RESET_REQUIRED	If a particular choice is modified, designates that a return flag will be activated upon exiting of the browser, which indicates that the changes that the user requested require a reset to enact.
EFI_IFR_FLAG_OPTIONS_ONLY	For questions with options, this indicates that only the options will be available for user choice.

27.3.8.2.3 EFI_IFR_STATEMENT_HEADER

Summary

Standard statement header.

Prototype

```

typedef struct _EFI_IFR_STATEMENT_HEADER {
    EFI_STRING_ID  Prompt;
    EFI_STRING_ID  Help;
} EFI_IFR_STATEMENT_HEADER;
    
```

Members

Prompt

The string identifier of the prompt string for this particular statement. The value 0 indicates no prompt string.

Help

The string identifier of the help string for this particular statement. The value 0 indicates no help string.

Description

This is the standard header for statements, including questions.

27.3.8.3 Opcode Reference

This section describes each of the IFR opcode encodings in detail. The table below lists the opcodes in numeric order while the reference section lists them in alphabetic order.

Table 179. IFR Opcodes

Opcode	Value	Description
EFI_IFR_FORM	0x01	Form
EFI_IFR_SUBTITLE	0x02	Subtitle statement
EFI_IFR_TEXT	0x03	Static text/image statement
EFI_IFR_IMAGE	0x04	Static image.
EFI_IFR_ONE_OF	0x05	One-of question
EFI_IFR_CHECKBOX	0x06	Boolean question
EFI_IFR_NUMERIC	0x07	Numeric question
EFI_IFR_PASSWORD	0x08	Password string question
EFI_IFR_ONE_OF_OPTION	0x09	Option
EFI_IFR_SUPPRESS_IF	0x0A	Suppress if conditional
EFI_IFR_LOCKED	0x0B	Marks statement/question as locked
EFI_IFR_ACTION	0x0C	Button question
EFI_IFR_RESET_BUTTON	0x0D	Reset button statement
EFI_IFR_FORM_SET	0x0E	Form set
EFI_IFR_REF	0x0F	Cross-reference statement
EFI_IFR_NO_SUBMIT_IF	0x10	Error checking conditional
EFI_IFR_INCONSISTENT_IF	0x11	Error checking conditional
EFI_IFR_EQ_ID_VAL	0x12	Return true if question value equals UINT16
EFI_IFR_EQ_ID_ID	0x13	Return true if question value equals another question value

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Opcode	Value	Description
EFI_IFR_EQ_ID_VAL_LIST	0x14	Return true if question value is found in list of UINT16s
EFI_IFR_AND	0x15	Push true if both sub-expressions returns true.
EFI_IFR_OR	0x16	Push true if either sub-expressions returns true.
EFI_IFR_NOT	0x17	Push false if sub-expression returns true, otherwise return true.
EFI_IFR_RULE	0x18	Create rule in current form.
EFI_IFR_GRAY_OUT_IF	0x19	Nested statements, questions or options will not be selectable if expression returns true.
EFI_IFR_DATE	0x1A	Date question.
EFI_IFR_TIME	0x1B	Time question.
EFI_IFR_STRING	0x1C	String question
EFI_IFR_REFRESH	0x1D	Interval for refreshing a question
EFI_IFR_DISABLE_IF	0x1E	Nested statements, questions or options will not be processed if expression returns true.
	0x1E-0x19	Reserved
EFI_IFR_TO_LOWER_OP	0x20	Convert a string on the expression stack to lower case.
EFI_IFR_TO_UPPER_OP	0x21	Convert a string on the expression stack to upper case.
	0x22	Reserved
EFI_IFR_ORDERED_LIST	0x23	Set question
EFI_IFR_VARSTORE	0x24	Define a buffer-style variable storage.
EFI_IFR_VARSTORE_NAME_VALUE	0x25	Define a name/value style variable storage.
EFI_IFR_VARSTORE_EFI	0x26	Define a UEFI variable style variable storage.
EFI_IFR_VARSTORE_DEVICE	0x27	Specify the device path to use for variable storage.
EFI_IFR_VERSION	0x28	Push the revision level of the UEFI Specification to which this Forms Processor is compliant.
EFI_IFR_END	0x29	Marks end of scope.
EFI_IFR_MATCH	0x2a	Push TRUE if string matches a pattern.
EFI_IFR_EQUAL	0x30	Push TRUE if two expressions are equal.
EFI_IFR_NOT_EQUAL	0x31	Push TRUE if two expressions are not equal.

Opcode	Value	Description
EFI_IFR_GREATER_THAN	0x32	Push TRUE if one expression is greater than another expression.
EFI_IFR_GREATER_EQUAL	0x33	Push TRUE if one expression is greater than or equal to another expression.
EFI_IFR_LESS_THAN	0x33	Push TRUE if one expression is less than another expression.
EFI_IFR_LESS_EQUAL	0x34	Push TRUE if one expression is less than or equal to another expression.
EFI_IFR_BITWISE_AND	0x35	Bitwise-AND two unsigned integers and push the result.
EFI_IFR_BITWISE_OR	0x36	Bitwise-OR two unsigned integers and push the result.
EFI_IFR_BITWISE_NOT	0x37	Bitwise-NOT an unsigned integer and push the result.
EFI_IFR_SHIFT_LEFT	0x38	Shift an unsigned integer left by a number of bits and push the result.
EFI_IFR_SHIFT_RIGHT	0x39	Shift an unsigned integer right by a number of bits and push the result.
EFI_IFR_ADD	0x3A	Add two unsigned integers and push the result.
EFI_IFR_SUBTRACT	0x3B	Subtract two unsigned integers and push the result.
EFI_IFR_MULTIPLY	0x3C	Multiply two unsigned integers and push the result.
EFI_IFR_DIVIDE	0x3D	Divide one unsigned integer by another and push the result.
EFI_IFR_MODULO	0x3E	Divide one unsigned integer by another and push the remainder.
EFI_IFR_RULE_REF	0x3F	Evaluate a rule
EFI_IFR_QUESTION_REF1	0x40	Push a question's value
EFI_IFR_QUESTION_REF2	0x41	Push a question's value
EFI_IFR_UINT8	0x42	Push an 8-bit unsigned integer
EFI_IFR_UINT16	0x43	Push a 16-bit unsigned integer.
EFI_IFR_UINT32	0x44	Push a 32-bit unsigned integer
EFI_IFR_UINT64	0x45	Push a 64-bit unsigned integer.
EFI_IFR_TRUE	0x46	Push a boolean TRUE.
EFI_IFR_FALSE	0x47	Push a boolean FALSE
EFI_IFR_TO_UINT	0x48	Convert expression to an unsigned integer
EFI_IFR_TO_STRING	0x49	Convert expression to a string
EFI_IFR_TO_BOOLEAN	0x4A	Convert expression to a boolean.

Opcode	Value	Description
EFI_IFR_MID	0x4B	Extract portion of string or buffer
EFI_IFR_FIND	0x4C	Find a string in a string.
EFI_IFR_TOKEN	0x4D	Extract a delimited byte or character string from buffer or string.
EFI_IFR_STRING_REF1	0x4E	Push a string
EFI_IFR_STRING_REF2	0x4F	Push a string
EFI_IFR_CONDITIONAL	0x50	Duplicate one of two expressions depending on result of the first expression.
EFI_IFR_QUESTION_REF3	0x51	Push a question's value from a different form.
EFI_IFR_ZERO	0x52	Push a zero
EFI_IFR_ONE	0x53	Push a one
EFI_IFR_ONES	0x54	Push a 0xFFFFFFFFFFFFFFFF.
EFI_IFR_UNDEFINED	0x55	Push Undefined
EFI_IFR_LENGTH	0x56	Push length of buffer or string.
EFI_IFR_DUP	0x57	Duplicate top of expression stack
EFI_IFR_THIS	0x58	Push the current question's value
EFI_IFR_SPAN	0x59	Return first matching/non-matching character in a string
EFI_IFR_VALUE	0x5A	Provide a value for a question
EFI_IFR_DEFAULT	0x5B	Provide a default value for a question.
EFI_IFR_DEFAULTSTORE	0x5D	Define a Default Type Declaration
EFI_IFR_CATENATE	0x5E	Push concatenated buffers or strings.

Each of the following sections gives a detailed description of the opcodes' behavior.

27.3.8.3.1 EFI_IFR_ACTION

Summary

Create an action button.

Prototype

```
#define EFI_IFR_ACTION_OP 0x0C
typedef struct _EFI_IFR_ACTION {
    EFI_IFR_OP_HEADER           Header;
    EFI_IFR_QUESTION_HEADER    Question;
    EFI_STRING_ID               QuestionConfig;
} EFI_IFR_ACTION;
```


Members

Header

The standard opcode header, where *Header.OpCode* = **EFI_IFR_ACTION_OP**.

Question

The standard question header. See **EFI_IFR_QUESTION_HEADER** ([Section 27.3.8.2.2](#)) for more information.

QuestionConfig

The results string which will be processed when the button is selected by the user.

Description

Creates an action question. When the question is selected, the configuration string specified by *QuestionConfig* will be processed.

If the question is marked read-only (see **EFI_IFR_QUESTION_HEADER**) then the action question cannot be selected.

27.3.8.3.2 EFI_IFR_ADD

Summary

Add two unsigned integers and push the result.

Prototype

```
#define EFI_IFR_ADD 0x3a
typedef struct _EFI_IFR_ADD {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_ADD;
```

Members

Header

Standard opcode header, where *Header.OpCode* = **EFI_IFR_ADD_OP**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined.

Zero-extend the expressions. Then, add the *left-hand* expression to *right-hand* expression and push the lower 64-bits of the result.

27.3.8.3.3 EFI_IFR_AND

Summary

Return TRUE if both sub-expressions return TRUE. Otherwise return FALSE.

Prototype

```
#define EFI_IFR_AND_OP0x15
typedef struct _EFI_IFR_AND {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_AND;
```

Members

Header

The standard opcode header, where *Header.OpCode* = **EFI_IFR_AND_OP**.

Description

Pop two expressions from the expression stack. If the two expressions cannot be evaluated as boolean, push Undefined. If both expressions evaluate to TRUE, then push TRUE. Otherwise, push FALSE.

27.3.8.3.4 EFI_IFR_BITWISE_AND

Summary

Push the bitwise-AND of two expressions.

Prototype

```
#define EFI_IFR_BITWISE_AND0x35
typedef struct _EFI_IFR_BITWISE_AND {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_BITWISE_AND;
```

Members

Header

The standard opcode header, where *Header.OpCode* = **EFI_IFR_BITWISE_AND_OP**.

Description

Pop two expressions from the expression stack. If the two expressions cannot be evaluated as unsigned integers, push Undefined. Otherwise, zero-extend the unsigned integers to 64-bits, bitwise-AND them and push the result.

27.3.8.3.5 EFI_IFR_BITWISE_NOT

Summary

Push the bitwise-NOT of an expressions.

Prototype

```
#define EFI_IFR_BITWISE_NOT0x37
typedef struct _EFI_IFR_BITWISE_NOT {
    EFI_IFR_OP_HEADER Header;
```

```
} EFI_IFR_BITWISE_NOT;
```

Members

Header

The standard opcode header, where *Header.OpCode* = **EFI_IFR_BITWISE_NOT_OP**.

Description

Pop an expression from the expression stack. If the expression cannot be evaluated as an unsigned integer, push Undefined. Otherwise, zero-extend the unsigned integer to 64-bits, bitwise-NOT it and push the result.

27.3.8.3.6 EFI_IFR_BITWISE_OR

Summary

Push the bitwise-OR of two expressions.

Prototype

```
#define EFI_IFR_BITWISE_OR0x36
typedef struct _EFI_IFR_BITWISE_OR {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_BITWISE_OR;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_BITWISE_OR_OP**.

Description

Pop two expressions from the expression stack. If the two expressions cannot be evaluated as unsigned integers, push Undefined. Otherwise, zero-extend the unsigned integers to 64-bits, bitwise-OR them and push the result.

27.3.8.3.7 EFI_IFR_CATENATE

Summary

Concatenate two strings or buffers.

Prototype

```
#define EFI_IFR_CATENATE0x5e
typedef struct _EFI_IFR_CATENATE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_CATENATE;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_CATENATE_OP**.

Description

Pop two expressions from the expression stack. The first expression popped is the *second* expression and the second expression popped is the *first* expression.

If the *first* or *second* expression cannot be evaluated as a string or a buffer, push Undefined. If the *first* or *second* expressions are of different types, the push Undefined.

If the *first* and *second* expressions are strings, push a new string which contains the contents of the first string (without the NULL terminator) followed by the contents of the second string on to the expression stack.

If the *first* and *second* expressions are buffers, push a new buffer which contains the contents of the first buffer followed by the contents of the second buffer on to the expression stack.

27.3.8.3.8 EFI_IFR_CHECKBOX

Summary

Creates a boolean checkbox.

Prototype

```
#define EFI_IFR_CHECKBOX_OP0x06
typedef struct _EFI_IFR_CHECKBOX {
    EFI_IFR_OP_HEADER      Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8                  Flags;
} EFI_IFR_CHECKBOX;
```

Members

Header

The standard question header, where *Header.OpCode* = **EFI_IFR_CHECKBOX_OP**.

Question

The standard question header. See **EFI_IFR_QUESTION_HEADER** ([Section 27.3.8.2.2](#)) for more information.

Flags

Flags that describe the behavior of the question. All undefined bits should be zero. See **EFI_IFR_CHECKBOX_x** in Related Definitions for more information.

Description

Creates a Boolean checkbox question and adds it to the current form. The checkbox has two values: FALSE if the box is not checked and TRUE if it is.

There are three ways to specify defaults for this question: the *Flags* field (lowest priority), one or more nested `EFI_IFR_ONE_OF_OPTION`, or nested `EFI_IFR_DEFAULT` (highest priority).

An image may be associated with the question using a nested `EFI_IFR_IMAGE`.

Related Definitions

```
#define EFI_IFR_CHECKBOX_DEFAULT      0x01
#define EFI_IFR_CHECKBOX_DEFAULT_MFG 0x02
```

27.3.8.3.9 EFI_IFR_CONDITIONAL

Summary

Push one of two expressions, depending on a Boolean.

Prototype

```
#define EFI_IFR_CONDITIONAL0x50
typedef struct _EFI_IFR_CONDITIONAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_CONDITIONAL;
```

Members

Header

Standard opcode header, where *OpCode* is `EFI_IFR_CONDITIONAL_OP`.

Description

Pop three expressions from the expression stack. The first expression popped is the *third* expression and the second expression popped is the *second* expression and the last expression popped is the *first* expression.

If the *first* expression cannot be evaluated as a boolean, push Undefined.

If the *first* expression evaluates to TRUE, push the *third* expression. Otherwise, push the *second* expression.

27.3.8.3.10 EFI_IFR_DATE

Summary

Create a date question.

Prototype

```
#define EFI_IFR_DATE_OP0x1A
typedef struct _EFI_IFR_DATE {
    EFI_IFR_OP_HEADER      Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8                  Flags;
} EFI_IFR_DATE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_DATE_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

Flags

Flags that describe the behavior of the question. All undefined bits should be zero.

```
#define EFI_QF_DATE_YEAR_SUPPRESS    0x01
#define EFI_QF_DATE_MONTH_SUPPRESS  0x02
#define EFI_QF_DATE_DAY_SUPPRESS     0x04
#define EFI_QF_DATE_STORAGE          0x30
```

For **QF_DATE_STORAGE**, there are currently three valid values:

```
#define QF_DATE_STORAGE_NORMAL      0x00
#define QF_DATE_STORAGE_TIME        0x10
#define QF_DATE_STORAGE_WAKEUP     0x20
```

Description

Create a Date question (see [Section 27.2.5.4.8](#)) and add it to the current form.

There are two ways to specify defaults for this question: one or more nested **EFI_IFR_ONE_OF_OPTION** (lowest priority) or nested **EFI_IFR_DEFAULT** (highest priority).

An image may be associated with the option using a nested **EFI_IFR_IMAGE**.

27.3.8.3.11 EFI_IFR_DEFAULT

Summary

Provides a default value for the current question

Prototype

```
#define EFI_IFR_DEFAULT_OP 0x5b
typedef struct _EFI_IFR_DEFAULT {
    EFI_IFR_OP_HEADER  Header;
    UINT16             DefaultId;
    UINT8              Type;
    EFI_IFR_TYPE_VALUE Value;
} EFI_IFR_DEFAULT;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_DEFAULT_OP**.

DefaultId

Identifies the default store for this value. The default store must have previously been created using **EFI_IFR_DEFAULTSTORE**.

Type

The type of data in the *Value* field. See **EFI_IFR_TYPE_x** in **EFI_IFR_ONE_OF_OPTION**.

Value

The default value. The actual size of this field depends on *Type*. If *Type* is **EFI_IFR_TYPE_OTHER**, then the default value is provided by a nested **EFI_IFR_VALUE**.

Description

Creates a default value for the current question. The default value is either provided in the opcode itself (*Value*) or using a nested **EFI_IFR_VALUE**.

27.3.8.3.12 EFI_IFR_DEFAULTSTORE

Summary

Provides a declaration for the type of default values that a question can be associated with.

Prototype

```
#define EFI_IFR_DEFAULTSTORE_OP 0x5c
typedef struct _EFI_IFR_DEFAULTSTORE {
    EFI_IFR_OP_HEADER Header;
    EFI_STRING_ID      DefaultName;
    UINT16             DefaultId;
} EFI_IFR_DEFAULTSTORE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_DEFAULTSTORE_OP**

DefaultName

A string token reference for the human readable string associated with the type of default being declared.

DefaultId

The default identifier, which is unique within the current form set. The default identifier creates a group of defaults. See [Section 27.2.5.8.1](#) for the default identifier ranges.

Description

Declares a class of default which can then have question default values associated with.

An **EFI_IFR_DEFAULTSTORE** with a specified *DefaultId* must appear in the IFR before it can be referenced by an **EFI_IFR_DEFAULT**.

27.3.8.3.13 EFI_IFR_DISABLE_IF**Summary**

Disable all nested questions and expressions if the expression evaluates to **TRUE**.

Prototype

```
#define EFI_IFR_DISABLE_IF          0x1e
typedef struct _EFI_IFR_DISABLE_IF {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_DISABLE_IF;
```

Members*Header*

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_DISABLE_IF_OP**.

Description

All nested statements, questions, options or expressions will not be processed if the expression appearing as the first nested object evaluates to TRUE. If the expression consists of more than a single opcode, then the first opcode in the expression must have the Scope bit set and the expression must end with **EFI_IFR_END**.

The expression should only rely on constants, such as **EFI_IFR_VERSION**, since the Forms Processor may not have access to question values.

27.3.8.3.14 EFI_IFR_DIVIDE**Summary**

Divide one unsigned integer by another and push the result.

Prototype

```
#define EFI_IFR_DIVIDE0x3d
typedef struct _EFI_IFR_DIVIDE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_DIVIDE;
```


Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_DIVIDE**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined. If the *right-hand* expression is equal to zero, push Undefined.

Zero-extend the expressions to 64-bits. Then, divide the *left-hand* expression by the *right-hand* expression.

27.3.8.3.15 EFI_IFR_DUP

Summary

Duplicate the top value on the expression stack.

Prototype

```
#define EFI_IFR_DUP0x57
typedef struct _EFI_IFR_DUP {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_DUP;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_DIVIDE**.

Description

Duplicate the top expression on the expression stack.

NOTE: This opcode is usually used as an optimization by the tools to help eliminate common sub-expression calculation and make smaller expressions.

27.3.8.3.16 EFI_IFR_END

Summary

End of the current scope.

Prototype

```
#define EFI_IFR_END_OP0x28
typedef struct _EFI_IFR_END {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_END;
```

Members

Header

Standard opcode header, where *OpCode* is `EFI_IFR_END_OP`.

Description

Marks the end of the current scope.

27.3.8.3.17 EFI_IFR_EQUAL

Summary

Return TRUE if the two sub-expressions are equal.

Prototype

```
#define EFI_IFR_EQUAL0x30
typedef struct _EFI_IFR_EQUAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_EQUAL;
```

Members

Header

Standard opcode header, where *OpCode* is `EFI_IFR_EQUAL_OP`.

Description

Pop two expressions from the expression stack. If the two expressions are not strings, Booleans or unsigned integers, push Undefined. If the two expressions are of different types, push Undefined. Strings are compared lexicographically. If the two expressions are equal then push TRUE on the expression stack. If they are not equal, push FALSE.

27.3.8.3.18 EFI_IFR_EQ_ID_ID

Summary

Push TRUE if the two questions have the same value or FALSE if they are not equal.

Prototype

```
#define EFI_IFR_EQ_ID_ID_OP 0x13
typedef struct _EFI_IFR_EQ_ID_ID {
    EFI_IFR_OP_HEADER Header;
    EFI_QUESTION_ID QuestionId1;
    EFI_QUESTION_ID QuestionId2;
} EFI_IFR_EQ_ID_ID;
```

Members

Header

Standard opcode header, where *OpCode* is `EFI_IFR_EQ_ID_ID_OP`.

QuestionId1, QuestionId2

Specifies the identifier of the questions whose values will be compared.

Description

Evaluate the values of the specified questions (*QuestionId1, QuestionId2*). If the two values cannot be evaluated or cannot be converted to comparable types, then push Undefined. If they are equal, push TRUE. Otherwise push FALSE.

27.3.8.3.19 EFI_IFR_EQ_ID_LIST

Summary

Push TRUE if the question's value appears in a list of unsigned integers.

Prototype

```
#define EFI_IFR_EQ_ID_LIST_OP0x14
typedef struct _EFI_IFR_EQ_ID_LIST {
    EFI_IFR_OP_HEADER Header;
    EFI_QUESTION_ID QuestionId;
    UINT16 ListLength;
    UINT16 ValueList[1];
} EFI_IFR_EQ_ID_LIST;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_EQ_ID_LIST_OP**.

QuestionId

Specifies the identifier of the question whose value will be compared.

ListLength

Number of entries in *ValueList*.

ValueList

Zero or more unsigned integer values to compare against.

Description

Evaluate the value of the specified question (*QuestionId*). If the specified question cannot be evaluated as an unsigned integer, then push Undefined. If the value can be found in *ValueList*, then push TRUE. Otherwise push FALSE.

27.3.8.3.20 EFI_IFR_EQ_ID_VAL

Summary

Push TRUE if a question's value is equal to a 16-bit unsigned integer, otherwise FALSE.

Prototype

```
#define EFI_IFR_EQ_ID_VAL_OP0x12
```

```
typedef struct _EFI_IFR_EQ_ID_VAL {
    EFI_IFR_OP_HEADER Header;
    EFI_QUESTION_ID QuestionId;
    UINT16 Value;
} EFI_IFR_EQ_ID_VAL;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_EQ_ID_VAL_OP**.

QuestionId

Specifies the identifier of the question whose value will be compared.

Value

Unsigned integer value to compare against.

Description

Evaluate the value of the specified question (*QuestionId*). If the specified question cannot be evaluated as an unsigned integer, then push Undefined. If they are equal, push TRUE. Otherwise push FALSE.

27.3.8.3.21 EFI_IFR_FALSE

Summary

Push a FALSE on to the expression stack.

Prototype

```
#define EFI_IFR_FALSE_OP0x47
typedef struct _EFI_IFR_FALSE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_FALSE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_FALSE_OP**

Description

Push a FALSE on to the expression stack.

27.3.8.3.22 EFI_IFR_FIND

Summary

Return the index of a found sub-string within a string.

Prototype

```
#define EFI_IFR_FIND0x4c
typedef struct _EFI_IFR_FIND {
    EFI_IFR_OP_HEADER  Header;
    UINT8              Format;
} EFI_IFR_FIND;
```

Members

Header

Standard opcode header, where *OpCode* is `EFI_IFR_FIND_OP`.

Format

The following flags govern the matching criteria:

Related Definitions

```
#define EFI_IFR_FF_CASE_SENSITIVE      0x00
#define EFI_IFR_FF_CASE_INSENSITIVE   0x01
```

Description

Pop three expressions from the expression stack. The first expression popped is the *third* expression and the second expression popped is the *second* expression and the last expression popped is the *first* expression.

If the *first* or *second* expressions cannot be evaluated as a string, push Undefined. If the *third* expression cannot be evaluated as an unsigned integer, push Undefined.

The *first* expression is the string to search. The *second* expression is the string to compare with. The *third* expression is the zero-based index of the search. If the string is found, push the zero-based index of the found string. Otherwise, if the string is not found or the *third* expression specifies a value which is greater-than or equal to the length of the *first* expression's string, push 0xFFFFFFFFFFFFFFFF.

27.3.8.3.23 EFI_IFR_FORM

Summary

Creates a form.

Prototype

```
#define EFI_IFR_FORM_OP 0x01
typedef struct _EFI_IFR_FORM {
    EFI_IFR_OP_HEADER  Header;
    UINT16             FormId;
    EFI_STRING_ID      FormTitle;
} EFI_IFR_FORM;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_FORM_OP**.

FormId

The unique identification for this particular form.

FormTitle

The string token reference to the title of this particular form.

Description

A form is the encapsulation of what amounts to a browser page. The header defines a *FormId*, which is referenced by the form set, among others. It also defines a *FormTitle*, which is a string to be used as the title for the form.

27.3.8.3.24 EFI_IFR_FORM_SET

Summary

The form set is a collection of forms that are intended to describe the pages that will be displayed to the user.

Prototype

```
#define EFI_IFR_FORM_SET_OP0x0E

typedef struct _EFI_IFR_FORM_SET {
    EFI_IFR_OP_HEADER Header;
    EFI_GUID           Guid;
    EFI_STRING_ID     FormSetTitle;
    EFI_STRING_ID     Help;
} EFI_IFR_FORM_SET;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_FORM_SET_OP**.

Guid

The unique GUID value associated with this particular form set. Type **EFI_GUID** is defined in **InstallProtocolInterface()** in the *EFI 1.10 Specification*.

FormSetTitle

The string token reference to the title of this particular form set.

Help

The string token reference to the help of this particular form set.

Description

The form set consists of a header and zero or more forms.

27.3.8.3.25 EFI_IFR_GRAY_OUT_IF

Summary

Creates a group of statements or questions which are conditionally grayed-out.

Prototype

```
#define EFI_IFR_GRAYOUT_IF_OP0x19
typedef struct _EFI_IFR_GRAY_OUT_IF {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_GRAY_OUT_IF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_GRAY_OUT_IF_OP**.

Description

All nested statements or questions will be grayed out (not selectable and visually distinct) if the expression appearing as the first nested object evaluates to TRUE. If the expression consists of more than a single opcode, then the first opcode in the expression must have the Scope bit set and the expression must end with **EFI_IFR_END**.

Different browsers may support this option to varying degrees. For example, HTML has no similar construct so it may not support this facility.

27.3.8.3.26 EFI_IFR_GREATER_EQUAL

Summary

Push TRUE if one expression is greater or equal to another.

Prototype

```
#define EFI_IFR_GREATER_EQUAL0x33
typedef struct _EFI_IFR_GREATER_EQUAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_GREATER_EQUAL;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_GREATER_EQUAL**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to string, boolean or unsigned integer, push Undefined. If the two expressions do not evaluate to the same type, push Undefined. Strings are compared lexicographically.

If the *left-hand* expression is greater than or equal to the *right-hand* expression, push TRUE. Otherwise push FALSE.

27.3.8.3.27 EFI_IFR_GREATER_THAN

Summary

Push TRUE if one expression is greater than another.

Prototype

```
#define EFI_IFR_GREATER_THAN0x32
typedef struct _EFI_IFR_GREATER_THAN {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_GREATER_THAN;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_GREATER_THAN**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to string, boolean or unsigned integer, push Undefined. If the two expressions do not evaluate to the same type, push Undefined. Strings are compared lexicographically.

If the *left-hand* expression is greater than the *right-hand* expression, push TRUE. Otherwise push FALSE.

27.3.8.3.28 EFI_IFR_IMAGE

Summary

Creates an image for a statement or question.

Prototype

```
#define EFI_IFR_IMAGE_OP0x04
typedef struct _EFI_IFR_IMAGE {
    EFI_IMAGE_ID Id;
} EFI_IFR_IMAGE;
```

Members

Id

Image identifier in the HII database.

Description

Specifies the image within the HII database. If the specified image does not exist in the HII database, then return Undefined.

27.3.8.3.29 EFI_IFR_INCONSISTENT_IF

Summary

Creates a validation expression and error message for a question.

Prototype

```
#define EFI_IFR_INCONSISTENT_IF_OP0x011
typedef struct _EFI_IFR_INCONSISTENT_IF {
    EFI_IFR_OP_HEADER Header;
    EFI_STRING_ID      Error;
} EFI_IFR_INCONSISTENT_IF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_INCONSISTENT_IF_OP**.

Error

The string token reference to the string that will be used for the consistency check message.

Description

This tag uses a Boolean expression to allow the IFR creator to check options in a richer manner than provided by the question tags themselves. For example, this tag might be used to validate that two options are not using the same address or that the numbers that were entered align to some pattern (such as leap years and February in a date input field). The tag provides a string to be used in a error display to alert the user to the issue. Inconsistency tags will be evaluated when the user traverses from tag to tag. The user should not be allowed to submit the results of a form inconsistency.

27.3.8.3.30 EFI_IFR_LENGTH

Summary

Push the length of a buffer or string.

Prototype

```
#define EFI_IFR_LENGTH0x56
typedef struct _EFI_IFR_LENGTH {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LENGTH;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_LENGTH_OP**.

Description

Pop an expression from the expression stack. If the expression cannot be evaluated as a buffer or string, then push Undefined.

If the expression can be evaluated as a buffer, push the length of the buffer, in bytes.

If the expression can be evaluated as a string, push the length of the string, in characters.

27.3.8.3.31 EFI_IFR_LESS_EQUAL

Summary

Push TRUE if one expression is less than or equal to another.

Prototype

```

#define EFI_IFR_LESS_EQUAL0x35
typedef struct _EFI_IFR_LESS_EQUAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LESS_EQUAL;

```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_LESS_EQUAL**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to string, boolean or unsigned integer, push Undefined. If the two expressions do not evaluate to the same type, push Undefined. Strings are compared lexicographically.

If the *left-hand* expression is less than or equal to the *right-hand* expression, push TRUE. Otherwise push FALSE.

27.3.8.3.32 EFI_IFR_LESS_THAN

Summary

Push TRUE if one expression is less than another.

Prototype

```

#define EFI_IFR_LESS_THAN0x34
typedef struct _EFI_IFR_LESS_THAN {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LESS_THAN;

```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_LESS_THAN**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to string, boolean or unsigned integer, push Undefined. If the two expressions do not evaluate to the same type, push Undefined. Strings are compared lexicographically.

If the *left-hand* expression is less than the *right-hand* expression, push TRUE. Otherwise push FALSE.

27.3.8.3.33 EFI_IFR_LOCKED

Summary

Specifies that the statement or question is locked.

Prototype

```
#define EFI_IFR_LOCKED_OP0x2e
```

Members

None

Description

The presence of **EFI_IFR_LOCKED** indicates that the statement or question should not be modified by a Forms Editor.

27.3.8.3.34 EFI_IFR_MATCH

Summary

Returns whether a string matches a pattern.

Prototype

```
#define EFI_IFR_MATCH_OP 0x2a
typedef struct _EFI_IFR_MATCH {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_MATCH;
```

Members

Header

Standard opcode header, where *Header.Opcode* is **EFI_IFR_MATCH_OP**.

Description

Pop two expressions from the expression stack. The first expression popped is the *string* and the second expression popped is the *pattern*. If the *string* or the *pattern* cannot be evaluated as a string, then push Undefined.

The two strings are processed using the **MetaMatch** function of the **EFI_UNICODE_COLLATION2_PROTOCOL**. If the result is TRUE, then TRUE is pushed. If the result is FALSE, then FALSE is pushed.

27.3.8.3.35 EFI_IFR_MID

Summary

Extract a portion of a buffer or string.

Prototype

```
#define EFI_IFR_MID_OP0x4b
typedef struct _EFI_IFR_MID {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_MID;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_MID_OP**.

Description

Pop three expressions from the expression stack. The first expression popped is the *third* expression and the second expression popped is the *second* expression and the last expression popped is the *first* expression.

If the *first* expression cannot be evaluated as a string or a buffer, push Undefined. If the *second* or *third* expression cannot be evaluated as unsigned integers, push Undefined.

If the *first* expression is a string, then the *second* expression is the 0-based index of the first character in the string to extract and the *third* expression is the length of the string to extract. If the *third* expression is zero or the *second* expression is greater than or equal the string's length, then push an Empty string. Push the extracted string on the expression stack. If the *third* expression would cause extraction to extend beyond the end of the string, then only the characters up to and include the last character of the string are in the pushed result.

If the *first* expression is a buffer, then the *second* expression is the 0-based index of the first byte in the buffer to extract and the *third* expression is the length of the buffer to extract. If the *third* expression is zero or the *second* expression is greater than the buffer's length, then push an empty buffer. Push the extracted buffer on the expression stack. If the *third* expression would cause extraction to extend beyond the end of the buffer, then only the bytes up to and include the last byte of the buffer are in the pushed result.

27.3.8.3.36 EFI_IFR_MODULO

Summary

Divide one unsigned integer by another and push the remainder.

Prototype

```
#define EFI_IFR_MODULO_OP0x3e
typedef struct _EFI_IFR_MODULO {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_MODULO;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_MODULO**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined. If *right-hand* evaluates to 0, push Undefined.

Zero-extend the expressions to 64-bits. Then, divide the *left-hand* expression by the *right-hand* expression. Push the difference between the *left-hand* expression and the product of the *right-hand* expression and the calculated quotient.

27.3.8.3.37 EFI_IFR_MULTIPLY

Summary

Multiply one unsigned integer by another and push the result.

Prototype

```
#define EFI_IFR_MULTIPLY_OP0x3c
typedef struct _EFI_IFR_MULTIPLY {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_MULTIPLY;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_MULTIPLY**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined.

Zero-extend the expressions to 64-bits. Then, multiply the *right-hand* expression by the *left-hand* expression. Push the lower 64-bits of the result.

27.3.8.3.38 EFI_IFR_NOT

Summary

Return TRUE if the sub-expression returns FALSE. Otherwise return FALSE.

Prototype

```

#define EFI_IFR_NOT_OP0x17
typedef struct _EFI_IFR_NOT {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_NOT;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_NOT_OP**.

Description

Pop one expression from the expression stack and evaluates it as Boolean. If the expression is Undefined or cannot be evaluated as Boolean, push Undefined on the expression stack. If the expression evaluates to TRUE, then push FALSE. Otherwise, push TRUE.

27.3.8.3.39 EFI_IFR_NOT_EQUAL

Summary

Return TRUE if the two sub-expressions are not equal.

Prototype

```

#define EFI_IFR_NOT_EQUAL_OP0x31
typedef struct _EFI_IFR_NOT_EQUAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_NOT_EQUAL;

```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_NOT_EQUAL_OP**.

Description

Pop two expressions from the expression stack. If the two expressions are not strings, Booleans or unsigned integers, push Undefined. If the two expressions are of different types, push Undefined. Strings are compared lexicographically. If the two expressions are not equal then push TRUE on the expression stack. If they are equal, push FALSE.

27.3.8.3.40 EFI_IFR_NO_SUBMIT_IF

Summary

Creates a validation expression and error message for a question.

Prototype

```
#define EFI_IFR_NO_SUBMIT_IF_OP0x010
typedef struct _EFI_IFR_NO_SUBMIT_IF {
    EFI_IFR_OP_HEADER      Header;
    EFI_STRING_ID          Error;
} EFI_IFR_NO_SUBMIT_IF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_NO_SUBMIT_IF_OP**.

Error

The string token reference to the string that will be used for the consistency check message.

Description

Creates a conditional expression which will be evaluated when the form is submitted. If the conditional evaluates to FALSE, then the error message Error will be displayed to the user and the user will be prevented from submitting the form.

27.3.8.3.41 EFI_IFR_NUMERIC

Summary

Creates a number question.

Prototype

```
#define EFI_IFR_NUMERIC_OP0x07
typedef struct _EFI_IFR_NUMERIC {
    EFI_IFR_OP_HEADER      Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8                  Flags;

    union {
        struct {
            UINT8          MinValue;
            UINT8          MaxValue;
            UINT8          Step;
        } u8;
        struct {
            UINT16         MinValue;
        } u16;
    };
};
```

```

        UINT16          MaxValue;
        UINT16          Step;
    } u16;
    struct {
        UINT32          MinValue;
        UINT32          MaxValue;
        UINT32          Step;
    } u32;
    struct {
        UINT64          MinValue;
        UINT64          MaxValue;
        UINT64          Step;
    } u64;
} data;
} EFI_IFR_NUMERIC;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_NUMERIC_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

Flags

Specifies flags related to the numeric question. See “Related Definitions”

MinValue

The minimum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits.

MaxValue

The maximum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits.

Step

Defines the amount to increment or decrement the value each time a user requests a value change. If the step value is 0, then the input mechanism for the numeric value is to be free-form and require the user to type in the actual value. The size of the data field may vary from 8 to 64 bits.

Description

Creates a number question on the current form, with built-in error checking and default information. The storage size depends on the **EFI_IFR_NUMERIC_SIZE** portion of the *Flags* field.

There are two ways to specify defaults for this question: one or more nested **EFI_IFR_ONE_OF_OPTION** (lowest priority) or nested **EFI_IFR_DEFAULT** (highest priority).

An image may be associated with the option using a nested `EFI_IFR_IMAGE`.

Related Definitions

```
#define EFI_IFR_NUMERIC_SIZE      0x03
#define EFI_IFR_NUMERIC_SIZE_1   0x00
#define EFI_IFR_NUMERIC_SIZE_2   0x01
#define EFI_IFR_NUMERIC_SIZE_4   0x02
#define EFI_IFR_NUMERIC_SIZE_8   0x03

#define EFI_IFR_DISPLAY           0x30
#define EFI_IFR_DISPLAY_INT_DEC  0x00
#define EFI_IFR_DISPLAY_UINT_DEC 0x01
#define EFI_IFR_DISPLAY_UINT_HEX 0x02
```

EFI_IFR_NUMERIC_SIZE	Specifies the size of the numeric value, the storage required and the size of the <i>MinValue</i> , <i>MaxValue</i> and <i>Step</i> values in the opcode header.
EFI_IFR_DISPLAY_HEX	The value will be displayed in signed decimal, unsigned decimal or unsigned hexadecimal. Input is still allowed in any form.

27.3.8.3.42 EFI_IFR_ONE

Summary

Push a one on to the expression stack.

Prototype

```
#define EFI_IFR_ONE_OP0x53
typedef struct _EFI_IFR_ONE {
    EFI_IFR_OP_HEADER  Header;
} EFI_IFR_ONE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = `EFI_IFR_ONE_OP`

Description

Push a one on to the expression stack.

27.3.8.3.43 EFI_IFR_ONES

Summary

Push 0xFFFFFFFFFFFFFFFF on to the expression stack.

Prototype

```
#define EFI_IFR_ONES_OP0x54
typedef struct _EFI_IFR_ONES {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_ONES;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_ONES_OP**

Description

Push 0xFFFFFFFFFFFFFFFF on to the expression stack.

27.3.8.3.44 EFI_IFR_ONE_OF

Summary

Creates a select-one-of question.

Prototype

```
#define EFI_IFR_ONE_OF_OP0x05

typedef struct _EFI_IFR_ONE_OF {
    EFI_IFR_OP_HEADER    Header;
    EFI_IFR_QUESTION_HEADER    Question;
    UINT8                Flags;

    union {
        struct {
            UINT8        MinValue;
            UINT8        MaxValue;
            UINT8        Step;
        } u8;
        struct {
            UINT16       MinValue;
            UINT16       MaxValue;
            UINT16       Step;
        } u16;
        struct {
            UINT32       MinValue;
        } u32;
    };
};
```

```

        UINT32          MaxValue;
        UINT32          Step;
    } u32;
    struct {
        UINT64          MinValue;
        UINT64          MaxValue;
        UINT64          Step;
    } u64;
} data;
} EFI_IFR_ONE_OF;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_ONE_OF_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

Flags

Specifies flags related to the numeric question. See “Related Definitions” in **EFI_IFR_NUMERIC**.

MinValue

The minimum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits, depending on the size specified in *Flags*

MaxValue

The maximum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits, depending on the size specified in *Flags*

Step

Defines the amount to increment or decrement the value each time a user requests a value change. If the step value is 0, then the input mechanism for the numeric value is to be free-form and require the user to type in the actual value. The size of the data field may vary from 8 to 64 bits, depending on the size specified in **Flags**

Description

This opcode creates a select-on-of object, where the user must select from one of the nested options. This is identical to **EFI_IFR_NUMERIC**.

There are two ways to specify defaults for this question: one or more nested **EFI_IFR_ONE_OF_OPTION** (lowest priority) or nested **EFI_IFR_DEFAULT** (highest priority). An image may be associated with the option using a nested **EFI_IFR_IMAGE**.

27.3.8.3.45 EFI_IFR_ONE_OF_OPTION

Summary

Creates a pre-defined option for a question.

Prototype

```
#define EFI_IFR_ONE_OF_OPTION_OP0x09
typedef struct _EFI_IFR_ONE_OF_OPTION {
    EFI_IFR_OP_HEADER      Header;
    EFI_STRING_ID          Option;
    UINT8                  Flags;
    UINT8                  Type;
    EFI_IFR_TYPE_VALUE     Value;
} EFI_IFR_ONE_OF_OPTION;
```

Members*Header*

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_ONE_OF_OPTION_OP**.

Option

The string token reference to the option description string for this particular opcode.

Flags

Specifies the flags associated with the current option. See **EFI_IFR_OPTION_x**.

Type

Specifies the type of the option's value. See **EFI_IFR_TYPE**.

Value

The union of all of the different possible values. The actual contents (and size) of the field depends on *Type*.

Related Definitions

```
typedef union {
    UINT8      u8;      // EFI_IFR_TYPE_NUM_SIZE_8
    UINT16     u16;     // EFI_IFR_TYPE_NUM_SIZE_16
    UINT32     u32;     // EFI_IFR_TYPE_NUM_SIZE_32
    UINT64     u64;     // EFI_IFR_TYPE_NUM_SIZE_64
    BOOLEAN    b;       // EFI_IFR_TYPE_BOOLEAN
    EFI_HII_TIME time;  // EFI_IFR_TYPE_TIME
    EFI_HII_DATE date;  // EFI_IFR_TYPE_DATE
    EFI_STRING_ID string; // EFI_IFR_TYPE_STRING
} EFI_IFR_TYPE_VALUE;

#define EFI_IFR_TYPE_NUM_SIZE_8  0x00
#define EFI_IFR_TYPE_NUM_SIZE_16 0x01
```

```

#define EFI_IFR_TYPE_NUM_SIZE_32 0x02
#define EFI_IFR_TYPE_NUM_SIZE_64 0x03
#define EFI_IFR_TYPE_BOOLEAN     0x04
#define EFI_IFR_TYPE_TIME        0x05
#define EFI_IFR_TYPE_DATE        0x06
#define EFI_IFR_TYPE_STRING      0x07
#define EFI_IFR_TYPE_OTHER       0x08

#define EFI_IFR_OPTION_DEFAULT    0x10
#define EFI_IFR_OPTION_DEFAULT_MFG 0x20

```

Description

Create a selection for use in any of the questions.

The value is encoded within the opcode itself, unless `EFI_IFR_TYPE_OTHER` is specified, in which case the value is determined by a nested `EFI_IFR_VALUE`.

An image may be associated with the option using a nested `EFI_IFR_IMAGE`.

27.3.8.3.46 EFI_IFR_OR

Summary

Return TRUE if both sub-expressions return TRUE. Otherwise return FALSE.

Prototype

```

#define EFI_IFR_OR_OP0x16
typedef struct _EFI_IFR_OR {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_OR;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = `EFI_IFR_AND_OR`.

Description

Pop two expressions from the expression stack and evaluates them as Boolean. If either expression is Undefined or cannot be evaluated as Boolean, push Undefined on the expression stack. If either expression evaluates to TRUE, then push TRUE. Otherwise, push FALSE.

27.3.8.3.47 EFI_IFR_ORDERED_LIST

Summary

Creates a set question using an ordered list.

Prototype

```

#define EFI_IFR_ORDERED_LIST_OP0x23

```

```
typedef struct _EFI_IFR_ORDERED_LIST {
    EFI_IFR_OP_HEADER      Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8                  MaxContainers;
    UINT8                  Flags;
} EFI_IFR_ORDERED_LIST;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_ORDERED_LIST_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

MaxContainers

The maximum number of entries for which this tag will maintain an order. This value also identifies the size of the storage associated with this tag's ordering array.

Flags

A bit-mask that determines which unique settings are active for this opcode.

Description

Create an ordered list question in the current form. One thing to note is that valid values for the options in ordered lists should never be a 0. The value of 0 is used to determine if a particular "slot" in the array is empty. Therefore, if in the previous example 3 was followed by a 4 and then followed by a 0, the valid options to be displayed would be 3 and 4 only.

An image may be associated with the option using a nested **EFI_IFR_IMAGE**.

Related Definitions

```
#define EFI_IFR_UNIQUE_SET      0x01
#define EFI_IFR_NO_EMPTY_SET   0x02
```

These flags determine whether all entries in the list must be unique (**EFI_IFR_UNIQUE_SET**) and whether there can be any empty items in the ordered list (**EFI_IFR_NO_EMPTY_SET**).

27.3.8.3.48 EFI_IFR_PASSWORD

Summary

Creates a password question

Prototype

```
#define EFI_IFR_PASSWORD_OP0x08
typedef struct _EFI_IFR_PASSWORD {
    EFI_IFR_OP_HEADER      Header;
```

```

EFI_IFR_QUESTION_HEADER    Question;
UINT16                     MinSize;
UINT16                     MaxSize;
} EFI_IFR_PASSWORD;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_PASSWORD_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

MinSize

The minimum number of characters that can be accepted for this opcode.

MaxSize

The maximum number of characters that can be accepted for this opcode.

Description

Creates a password question in the current form.

An image may be associated with the option using a nested **EFI_IFR_IMAGE**.

27.3.8.3.49 EFI_IFR_QUESTION_REF1

Summary

Push a question's value on the expression stack.

Prototype

```

#define EFI_IFR_QUESTION_REF1_OP0x40
typedef struct _EFI_IFR_QUESTION_REF1 {
    EFI_IFR_OP_HEADER    Header;
    EFI_QUESTION_ID      QuestionId;
} EFI_IFR_QUESTION_REF1;

```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_QUESTION_REF1_OP**.

QuestionId

The question's identifier, which must be unique within the form set.

Description

Push the value of the question specified by *QuestionId* on to the expression stack. If the question's value cannot be determined or the question does not exist, then push Undefined.

27.3.8.3.50 EFI_IFR_QUESTION_REF2

Summary

Push a question's value on the expression stack.

Prototype

```
#define EFI_IFR_QUESTION_REF2_OP0x41
typedef struct _EFI_IFR_QUESTION_REF2 {
    EFI_IFR_OP_HEADER          Header;
} EFI_IFR_QUESTION_REF2;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_QUESTION_REF2_OP**.

Description

Pop an expression from the expression stack. If the expression cannot be evaluated as an unsigned integer or the value of the unsigned integer is greater than 0xFFFF, push Undefined. If the value of the question specified by the unsigned integer (converted to a question id) cannot be determined or the question does not exist, push Undefined. Otherwise, push the questions' value on to the expression stack.

27.3.8.3.51 EFI_IFR_QUESTION_REF3

Summary

Push a question's value on the expression stack.

Prototype

```
#define EFI_IFR_QUESTION_REF3_OP0x51
typedef struct _EFI_IFR_QUESTION_REF3 {
    EFI_IFR_OP_HEADER          Header;
} EFI_IFR_QUESTION_REF3;

typedef struct _EFI_IFR_QUESTION_REF3_2 {
    EFI_IFR_OP_HEADER          Header;
    EFI_STRING_ID              DevicePath;
} EFI_IFR_QUESTION_REF3_2;

typedef struct _EFI_IFR_QUESTION_REF3_3 {
    EFI_IFR_OP_HEADER          Header;
    EFI_STRING_ID              DevicePath;
    EFI_GUID                   Guid;
} EFI_IFR_QUESTION_REF3_3;
```


Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_QUESTION_REF3_OP**.

DevicePath

Specifies the text representation of the device path containing the form set where the question is defined. If this is not present or the value is 0 then the device path installed on the **EFI_HANDLE** which was registered with the form set containing the current question is used.

Guid

Specifies the GUID of the form set where the question is defined. If the value is Nil or this field is not present, then the current form set is used (if *DevicePath* is 0) or the only form set attached to the device path specified by *DevicePath* is used. If the value is Nil and there is more than one form set on the specified device path, then the value Undefined will be pushed.

Description

Pop an expression from the expression stack. If the expression cannot be evaluated as an unsigned integer or the value of the unsigned integer is greater than 0xFFFF, push Undefined. If the value of the question specified by the unsigned integer (converted to a question id) cannot be determined or the question does not exist, push Undefined. Otherwise, push the questions' value on to the expression stack.

This version allows question values from other forms to be referenced in expressions.

27.3.8.3.52 EFI_IFR_REF

Summary

Creates a cross-reference statement.

Prototype

```
#define EFI_IFR_REF_OP0x0F
typedef struct _EFI_IFR_REF {
    EFI_IFR_OP_HEADER           Header;
    EFI_IFR_STATEMENT_HEADER    Statement;
    EFI_FORM_ID                 FormId;
} EFI_IFR_REF;

typedef struct _EFI_IFR_REF2 {
    EFI_IFR_OP_HEADER           Header;
    EFI_IFR_STATEMENT_HEADER    Statement;
    EFI_FORM_ID                 FormId;
    EFI_QUESTION_ID             QuestionId;
} EFI_IFR_REF2;

typedef struct _EFI_IFR_REF3 {
```

```

EFI_IFR_OP_HEADER           Header;
EFI_IFR_STATEMENT_HEADER   Statement;
EFI_FORM_ID                 FormId;
EFI_QUESTION_ID            QuestionId;
EFI_STRING_ID              DevicePath;
} EFI_IFR_REF3;

```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_REF_OP**.

Statement

Standard statement header.

FormId

The form to which this link is referring. If this is zero, then the link is on the current form.

QuestionId

The question on the form to which this link is referring. If this field is not present (determined by the length of the opcode) or the value is zero, then the link refers to the top of the form.

DevicePath

The string form of the device path to which the form set containing the form specified by *FormId*. If this field is not present (determined by the opcode's length) or the value is zero, then the link refers to the current page.

Description

Creates a user-selectable link to a form or a question on a form. There are several forms of this opcode which are distinguished by the length of the opcode.

An image may be associated with the statement using a nested **EFI_IFR_IMAGE**.

27.3.8.3.53 EFI_IFR_REFRESH

Summary

Mark a question for periodic refresh.

Prototype

```

#define EFI_IFR_REFRESH_OP0x1d
typedef struct _EFI_IFR_REFRESH {
    EFI_IFR_OP_HEADER Header;
    UINT8             RefreshInterval;
} EFI_IFR_REFRESH;

```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_REFRESH_OP**.

RefreshInterval

Minimum number of seconds before the question value should be refreshed.

Description

When placed within the scope of a question or statement, it will force the question's value to be refreshed at least every *RefreshInterval* seconds. The value may be refreshed less often, depending on browser policy or capabilities.

27.3.8.3.54 EFI_IFR_RESET_BUTTON

Summary

Create a reset or submit button on the current form.

Prototype

```
#define EFI_IFR_RESET_BUTTON_OP0x0d
typedef struct _EFI_IFR_RESET_BUTTON {
    EFI_IFR_OP_HEADER           Header;
    EFI_IFR_QUESTION_HEADER    Question;
    EFI_DEFAULT_ID              DefaultId;
} EFI_IFR_RESET_BUTTON;
```

Members

Header

The standard header, where *Header.OpCode* = **EFI_IFR_RESET_BUTTON_OP**.

Question

Standard question header, including the prompt and help text The *QuestionId* is ignored.

DefaultId

Specifies the set of default store to use when restoring the defaults to the questions on this form. See **EFI_IFR_DEFAULTSTORE** ([Section 27.3.8.3.12](#)) for more information.

Description

This opcode creates a user-selectable button that resets the question values for all questions on the current form to the default values specified by *DefaultId*. If **EFI_IFR_FLAGS_CALLBACK** is set in the question header, then the callback associated with the form set will be called.

27.3.8.3.55 EFI_IFR_RULE

Summary

Create a rule for use in a form and associate it with an identifier.

Prototype

```
#define EFI_IFR_RULE_OP 0x18
typedef struct _EFI_IFR_RULE {
    EFI_IFR_OP_HEADER  Header;
    UINT8              RuleId;
} EFI_IFR_RULE;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_RULE_OP**.

RuleId

Unique identifier for the rule. There can only one rule within a form with the specified *RuleId*. If another already exists, then the form is marked as invalid.

Description

Create a rule, which associates an expression with an identifier and attaches it to the currently opened form. These rules allow common sub-expressions to be re-used within a form.

27.3.8.3.56 EFI_IFR_RULE_REF

Summary

Evaluate a form rule and push its result on the expression stack.

Prototype

```
#define EFI_IFR_RULE_REF_OP 0x3f
typedef struct _EFI_IFR_RULE_REF {
    EFI_IFR_OP_HEADER  Header;
    UINT8              RuleId;
} EFI_IFR_RULE_REF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_RULE_REF_OP**.

RuleId

The rule's identifier, which must be unique within the form.

Description

Look up the rule specified by *RuleId* and push the evaluated result on the expression stack. If the specified rule does not exist, then push Undefined.

27.3.8.3.57 EFI_IFR_SHIFT_LEFT

Summary

Shift left an unsigned integer and push the result.

Prototype

```
#define EFI_IFR_SHIFT_LEFT 0x38
typedef struct _EFI_IFR_SHIFT_LEFT {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_SHIFT_RIGHT;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_SHIFT_LEFT**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined.

Shift the *left-hand* expression left by the number of bits specified by the *right-hand* expression and push the result.

27.3.8.3.58 EFI_IFR_SHIFT_RIGHT

Summary

Shift right an unsigned integer and push the result.

Prototype

```
#define EFI_IFR_SHIFT_RIGHT 0x39
typedef struct _EFI_IFR_SHIFT_RIGHT {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_SHIFT_RIGHT;
```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_SHIFT_RIGHT**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined.

Shift the *left-hand* expression right by the number of bits specified by the *right-hand* expression and push the result.

27.3.8.3.59 EFI_IFR_SPAN

Summary

Push index of first character in string after certain characters

Prototype

```
#define EFI_IFR_SPAN_OP0x59
typedef struct _EFI_IFR_SPAN {
    EFI_IFR_OP_HEADER  Header;
    UINT8              Flags;
} EFI_IFR_SPAN;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_SPAN_OP**.

Flags

Specifies whether to find the first matching string (**EFI_IFR_FLAGS_LAST_NON_MATCHING**) or the first non-matching string (**EFI_IFR_FLAGS_FIRST_NON_MATCHING**).

Description

Pop three expressions from the expression stack. The first expression popped is the *third* expression and the second expression popped is the *second* expression and the last expression popped is the *first* expression.

If the *first* or *second* expressions cannot be evaluated as a string, push Undefined. If the *third* expression cannot be evaluated as an unsigned integer, push Undefined.

The *first* string is the string to scan. The *second* string consists of character pairs representing the low-end of a range and the high-end of a range of characters. The *third* unsigned integer represents the starting location for the scan.

The operation will push the zero-based index of the first character after the third expression which does not fall into any one of the ranges (**EFI_IFR_FLAGS_NON_MATCHING**) or push the zero-based index of the last character before the third expression which does not fall into any of the ranges (**EFI_IFR_FLAGS_FIRST_NON_MATCHING**).

Related Definitions

```
#define EFI_IFR_FLAGS_LAST_NON_MATCHING    0x00
#define EFI_IFR_FLAGS_FIRST_NON_MATCHING   0x01
```

27.3.8.3.60 EFI_IFR_STRING

Summary

Defines the string question.

Prototype

```
#define EFI_IFR_STRING_OP0x1C
typedef struct _EFI_IFR_STRING {
    EFI_IFR_OP_HEADER           Header;
    EFI_IFR_QUESTION_HEADER     Question;
    UINT8                       MinSize;
    UINT8                       MaxSize;
    UINT8                       Flags;
} EFI_IFR_STRING;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_STRING_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

MinSize

The minimum number of characters that can be accepted for this opcode.

MaxSize

The maximum number of characters that can be accepted for this opcode.

Flags

Flags which control the string editing behavior. See “Related Definitions” below.

Description

This creates a string question. The minimum length is *MinSize* and the maximum length is *MaxSize* characters.

An image may be associated with the question using a nested **EFI_IFR_IMAGE**.

There are two ways to specify defaults for this question: one or more nested **EFI_IFR_ONE_OF_OPTION** (lowest priority) or nested **EFI_IFR_DEFAULT** (highest priority).

If **EFI_IFR_STRING_MULTI_LINE** is set, it is a hint to the Forms Browser that multi-line text can be allowed. If it is clear, then multi-line editing should not be allowed.

Related Definitions

```
#define EFI_IFR_STRING_MULTI_LINE0x01
```

27.3.8.3.61 EFI_IFR_STRING_REF1

Summary

Push a string on the expression stack.

Prototype

```
#define EFI_IFR_STRING_REF1_OP0x4e
typedef struct _EFI_IFR_STRING_REF1 {
    EFI_IFR_OP_HEADER           Header;
    EFI_STRING_ID               StringId;
} EFI_IFR_STRING_REF1;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_STRING_REF1_OP**.

StringId

The string's identifier, which must be unique within the package list.

Description

Push the string specified by *StringId* on to the expression stack. If the string does not exist, then push an empty string.

27.3.8.3.62 EFI_IFR_STRING_REF2

Summary

Push a string on the expression stack.

Prototype

```
#define EFI_IFR_STRING_REF2_OP0x4f
typedef struct _EFI_IFR_STRING_REF2 {
    EFI_IFR_OP_HEADER           Header;
} EFI_IFR_STRING_REF2;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_STRING_REF2_OP**.

Description

Pop an expression from the expression stack. If the expression cannot be evaluated as an unsigned integer or the value of the unsigned integer is greater than 0xFFFF, push Undefined. If the string specified by the unsigned integer (converted to a string id) cannot be determined or the string does not exist, push an empty string. Otherwise, push the string on to the expression stack.

27.3.8.3.63 EFI_IFR_SUBTITLE

Summary

Creates a sub-title in the current form.

Prototype

```
#define EFI_IFR_SUBTITLE_OP0x02
typedef struct _EFI_IFR_SUBTITLE {
    EFI_IFR_OP_HEADER      Header;
    EFI_IFR_STATEMENT_HEADER Statement;
    UINT8                  Flags;
} EFI_IFR_SUBTITLE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_SUBTITLE_OP**.

Flags

Identifies specific behavior for the sub-title.

Description

Subtitle strings are intended to be used by authors to separate sections of questions into semantic groups. If *Header.Scope* is set, then the Forms Browser may further distinguish the end of the semantic group as including only those statements and questions which are nested.

If **EFI_IFR_FLAGS_HORIZONTAL** is set, then this provides a hint that the nested statements or questions should be horizontally arranged. Otherwise, they are assumed to be vertically arranged.

An image may be associated with the statement using a nested **EFI_IFR_IMAGE**.

Related Definitions

```
#define EFI_IFR_FLAGS_HORIZONTAL 0x01
```

27.3.8.3.64 EFI_IFR_SUBTRACT

Summary

Subtract one unsigned integer from another and push the result.

Prototype

```
#define EFI_IFR_SUBTRACT_OP0x3b
typedef struct _EFI_IFR_SUBTRACT {
    EFI_IFR_OP_HEADER      Header;
} EFI_IFR_SUBTRACT;
```

Members

Header

Standard opcode header, where *Header.OpCode* is **EFI_IFR_SUBTRACT**.

Description

Pop two expressions from the expression stack. The first expression popped is the *right-hand* expression and the second expression popped is the *left-hand* expression.

If the two expressions do not evaluate to unsigned integers, push Undefined.

Zero-extend the expressions to 64-bits. Then, subtract the *right-hand* expression from the *left-hand* expression. Push the lower 64-bits of the result.

27.3.8.3.65 EFI_IFR_SUPPRESS_IF

Summary

Creates a group of statements or questions which are conditionally invisible.

Prototype

```
#define EFI_IFR_SUPPRESS_IF_OP0x0a
typedef struct _EFI_IFR_SUPPRESS_IF {
    EFI_IFR_OP_HEADER          Header;
} EFI_IFR_SUPPRESS_IF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = **EFI_IFR_SUPPRESS_IF_OP**.

Description

The suppress tag causes the nested objects to be hidden from the user if the expression appearing as the first nested object evaluates to TRUE. If the expression consists of more than a single opcode, then the first opcode in the expression must have the Scope bit set and the expression must end with **EFI_IFR_END**.

This display form is maintained until the scope for this opcode is closed.

27.3.8.3.66 EFI_IFR_TEXT

Summary

Creates a static text and image.

Prototype

```
#define EFI_IFR_TEXT_OP0x03
typedef struct _EFI_IFR_TEXT {
    EFI_IFR_OP_HEADER          Header;
    EFI_IFR_STATEMENT_HEADER  Statement;
    EFI_STRING_ID              TextTwo;
```

```
} EFI_IFR_TEXT;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TEXT_OP**.

Statement

Standard statement header.

TextTwo

The string token reference to the secondary string for this opcode.

Description

This is a static text/image statement.

An image may be associated with the statement using a nested **EFI_IFR_IMAGE**.

27.3.8.3.67 EFI_IFR_THIS

Summary

Push current question's value.

Prototype

```
#define EFI_IFR_THIS_OP0x58
typedef struct _EFI_IFR_THIS {
    EFI_IFR_OP_HEADER  Header;
} EFI_IFR_THIS;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_THIS_OP**.

Description

Push the current question's value.

27.3.8.3.68 EFI_IFR_TIME

Summary

Create a Time question.

Prototype

```
#define EFI_IFR_TIME_OP0x1b
typedef struct _EFI_IFR_TIME {
    EFI_IFR_OP_HEADER           Header;
    EFI_IFR_QUESTION_HEADER    Question;
```

```

    UINT8                               Flags;
} EFI_IFR_TIME;

```

Members

Header

Basic question information. *Header.Opcode* = **EFI_IFR_TIME_OP**.

Question

The standard question header. See [Section 27.3.8.2.2](#) for more information.

Flags

A bit-mask that determines which unique settings are active for this opcode.

QF_TIME_HOUR_SUPPRESS	0x01
QF_TIME_MINUTE_SUPPRESS	0x02
QF_TIME_SECOND_SUPPRESS	0x04
QF_TIME_STORAGE	0x30

For **QF_TIME_STORAGE**, there are currently three valid values:

QF_TIME_STORAGE_NORMAL	0x00
QF_TIME_STORAGE_TIME	0x10
QF_TIME_STORAGE_WAKEUP	0x20

Description

Create a Time question (see [Section 27.2.5.4.12](#)) and add it to the current form.

An image may be associated with the question using a nested **EFI_IFR_IMAGE**.

27.3.8.3.69 EFI_IFR_TOKEN

Summary

Extract a delimited string from a string.

Prototype

```

#define EFI_IFR_TOKEN_OP0x4d
typedef struct _EFI_IFR_TOKEN {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_TOKEN;

```

Members

Header

Standard opcode header, where *OpCode* is **EFI_IFR_TOEKN_OP**.

Description

Pop three expressions from the expression stack. The first expression popped is the *third* expression and the second expression popped is the *second* expression and the last expression popped is the *first* expression.

If the *first* or *second* expressions cannot be evaluated as a string, push Undefined. If the *third* expression cannot be evaluated as an unsigned integer, push Undefined.

The *first* expression is the string. The *second* expression is a string, where each character is a valid delimiter. The *third* expression is the zero-based index. Push the nth delimited sub-string on to the expression stack (0 = left of the first delimiter). The end of the string always acts as the final delimiter. The no such string exists, an empty string is pushed.

27.3.8.3.70 EFI_IFR_TO_BOOLEAN

Summary

Convert an expression to a Boolean.

Prototype

```
#define EFI_IFR_TO_BOOLEAN_OP 0x4A
typedef struct _EFI_IFR_TO_BOOLEAN {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_TO_BOOLEAN;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TO_BOOLEAN_OP**

Description

Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as a Boolean, push Undefined. Otherwise push the Boolean on the expression stack.

When converting from an unsigned integer, zero will be converted to FALSE and any other value will be converted to TRUE.

When converting from a string, if case-insensitive compare with “true” is True, then push True. If a case-insensitive compare with “false” is True, then push False. Otherwise, push Undefined.

When converting from a buffer, if the buffer is all zeroes, then push False. Otherwise push True.

27.3.8.3.71 EFI_IFR_TO_LOWER

Summary

Convert a string on the expression stack to lower case.

Prototype

```
#define EFI_IFR_TO_LOWER_OP 0x20
typedef struct _EFI_IFR_TO_LOWER {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_TO_LOWER;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TO_LOWER_OP**

Description

Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as a string, push Undefined. Otherwise, convert the string to all lower case using the **StrLwr** function of the **EFI_UNICODE_COLLATION2_PROTOCOL** and push the string on the expression stack.

27.3.8.3.72 EFI_IFR_TO_STRING

Summary

Convert an expression to a string.

Prototype

```
#define EFI_IFR_TO_STRING_OP0x49
typedef struct _EFI_IFR_TO_STRING{
    EFI_IFR_OP_HEADER    Header;
    UINT8                Format;
} EFI_IFR_TO_STRING;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TO_STRING_OP**

Format

When converting from unsigned integers, these flags control the format:

- 0 = unsigned decimal
- 1 = signed decimal
- 2 = hexadecimal (lower-case alpha)
- 3 = hexadecimal (upper-case alpha)

When converting from a buffer, these flags control the format:

- 0 = ASCII
- 8 = Unicode

Description

Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as a string, push Undefined. Otherwise push the string on the expression stack.

When converting from an unsigned integer, the number will be converted to a unsigned decimal string (Format = 0), signed decimal string (Format = 1) or a hexadecimal string (Format = 2 or 3).

When converting from a boolean, the boolean will be converted to “True” (True) or “False” (False).
 When converting from a buffer, each 8-bit (Format = 0) or 16-bit (Format = 8) value will be converted into a character and appended to the string, up until the end of the buffer or a NULL character.

27.3.8.3.73 EFI_IFR_TO_UINT

Summary

Convert an expression to an unsigned integer.

Prototype

```
#define EFI_IFR_TO_UINT_OP 0x48
typedef struct _EFI_IFR_TO_UINT {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_TO_UINT;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TO_UINT_OP**

Description

Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as an unsigned integer, push Undefined. Otherwise push the unsigned integer on the expression stack.

When converting from a boolean, if True, push 1 and if False, push 0.

When converting from a string, whitespace is skipped. The prefix ‘0x’ or ‘0X’ indicates to convert from a hexadecimal string while the prefix ‘-’ indicates conversion from a signed integer string.

When converting from a buffer, if the buffer is greater than 8 bytes in length, push Undefined. Otherwise, zero-extend the contents of the buffer to 64-bits and push the unsigned integer.

27.3.8.3.74 EFI_IFR_TO_UPPER

Summary

Convert a string on the expression stack to upper case.

Prototype

```
#define EFI_IFR_TO_UPPER_OP 0x21
typedef struct _EFI_IFR_TO_UPPER {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_TO_UPPER;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TO_UPPER_OP**

Description

Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as a string, push Undefined. Otherwise, convert the string to all upper case using the **StrUpr** function of the **EFI_UNICODE_COLLATION2_PROTOCOL** and push the string on the expression stack.

27.3.8.3.75 EFI_IFR_TRUE

Summary

Push a TRUE on to the expression stack.

Prototype

```
#define EFI_IFR_TRUE_OP0x46
typedef struct _EFI_IFR_TRUE {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_TRUE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_TRUE_OP**

Description

Push a TRUE on to the expression stack.

27.3.8.3.76 EFI_IFR_UINT8, EFI_IFR_UINT16, EFI_IFR_UINT32, EFI_IFR_UINT64

Summary

Push an unsigned integer on to the expression stack.

Prototype

```
#define EFI_IFR_UINT8_OP0x42
typedef struct _EFI_IFR_UINT8 {
    EFI_IFR_OP_HEADER    Header;
    UINT8                Value;
} EFI_IFR_UINT8;

#define EFI_IFR_UINT8_OP0x43
typedef struct _EFI_IFR_UINT16 {
    EFI_IFR_OP_HEADER    Header;
```



```

    UINT16          Value;
} EFI_IFR_UINT16;

#define EFI_IFR_UINT8_OP0x44
typedef struct _EFI_IFR_UINT32 {
    EFI_IFR_OP_HEADER  Header;
    UINT32             Value;
} EFI_IFR_UINT32;

#define EFI_IFR_UINT8_OP0x45
typedef struct _EFI_IFR_UINT64 {
    EFI_IFR_OP_HEADER  Header;
    UINT64             Value;
} EFI_IFR_UINT64;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_UINT8_OP**, **EFI_IFR_UINT16_OP**, **EFI_IFR_UINT32_OP** or **EFI_IFR_UINT64_OP**.

Value

The unsigned integer.

Description

Push the specified unsigned integer, zero-extended to 64-bits, on to the expression stack.

27.3.8.3.77 EFI_IFR_UNDEFINED

Summary

Push an Undefined to the expression stack.

Prototype

```

#define EFI_IFR_UNDEFINED_OP0x55
typedef struct _EFI_IFR_UNDEFINED {
    EFI_IFR_OP_HEADER  Header;
} EFI_IFR_UNDEFINED;

```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_UNDEFINED_OP**

Description

Push Undefined on to the expression stack.

27.3.8.3.78 EFI_IFR_VALUE

Summary

Provides a value for the current question or default.

Prototype

```
#define EFI_IFR_VALUE_OP 0x5a
typedef struct _EFI_IFR_VALUE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_VALUE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_VALUE_OP**

Description

Creates a value for the current question or default with no storage. The value is the result of the expression nested in the scope.

If used for a question, then the question will be read-only.

27.3.8.3.79 EFI_IFR_VARSTORE

Summary

Creates a variable storage short-cut for linear buffer storage.

Prototype

```
#define EFI_IFR_VARSTORE_OP 0x24
typedef struct {
    EFI_IFR_OP_HEADER Header;
    EFI_GUID Guid;
    UINT16 VarStoreId;
    UINT16 Size;
    //UINT8 Name[];
} EFI_IFR_VARSTORE;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_VARSTORE_OP**.

Guid

The variable's GUID definition. This field comprises one half of the variable name, with the other half being the human-readable aspect of the name, which is represented by the string immediately following the Size field. Type **EFI_GUID** is defined in **InstallProtocolInterface ()** in the EFI 1.10 Specification.

VarStoreId

The variable store identifier, which is unique within the current form set.. This field is the value that uniquely identify this instance from others. Question headers refer to this value to designate which is the active variable that is being used. A value of zero is invalid.

Size

The size of the variable store.

Name

This field is actually not defined in the structure but is included here to illustrate the content of the encoding for this opcode. Because this field is variable in length, the string is a NULL-terminated string and the overall size will be reflected in the opcode's Header field.

Description

This opcode describes a Buffer Storage Variable Store within a form set. A question can select this variable store by setting the *VarStoreId* field in its opcode header.

An **EFI_IFR_VARSTORE** with a specified *VarStoreId* must appear in the IFR before it can be referenced by a question.

27.3.8.3.80 EFI_IFR_VARSTORE_NAME_VALUE

Summary

Creates a variable storage short-cut for name/value storage.

Prototype

```
#define EFI_IFR_VARSTORE_NAME_VALUE_OP0x25
typedef struct _EFI_IFR_VARSTORE_NAME_VALUE {
    EFI_IFR_OP_HEADER    Header;
    UINT16               VarStoreId;
    EFI_GUID             Guid;
} EFI_IFR_VARSTORE_NAME_VALUE;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_VARSTORE_NAME_VALUE_OP**.

Guid

The variable's GUID definition. This field comprises one half of the variable name, with the other half being the human-readable aspect of the name, which is specified in the *VariableName* field in the question's header (see **EFI_IFR_QUESTION_HEADER**). Type **EFI_GUID** is defined in **InstallProtocolInterface ()** in the UEFI 2.0 Specification.

VarStoreId

The variable store identifier, which is unique within the current form set.. This field is the value that uniquely identifies this variable store definition instance from others. Question headers refer to this value to designate which is the active variable that is being used. A value of zero is invalid.

Description

This opcode describes a Name/ValueVariable Store within a form set. A question can select this variable store by setting the *VarStoreId* field in its question header.

An **EFI_IFR_VARSTORE_NAME_VALUE** with a specified *VarStoreId* must appear in the IFR before it can be referenced by a question.

27.3.8.3.81 EFI_IFR_VARSTORE_EFI**Summary**

Creates a variable storage short-cut for EFI variable storage.

Prototype

```
#define EFI_IFR_VARSTORE_EFI_OP0x26
typedef struct _EFI_IFR_VARSTORE_EFI {
    EFI_IFR_OP_HEADER  Header;
    UINT16             VarStoreId;
    EFI_GUID           Guid;
} EFI_IFR_VARSTORE_EFI;
```

Members*Header*

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_VARSTORE_EFI_OP**.

VarStoreId

The variable store identifier, which is unique within the current form set.. This field is the value that uniquely identifies this variable store definition instance from others. Question headers refer to this value to designate which is the active variable that is being used. A value of zero is invalid.

Guid

The variable's GUID definition. This field comprises one half of the variable name, with the other half being the human-readable aspect of the name, which is specified in the *VariableName* field in the question's header (see

EFI_IFR_QUESTION_HEADER). Type **EFI_GUID** is defined in **InstallProtocolInterface ()** in the UEFI 2.0 Specification.

Flags

Specifies the flags to use for the variable.

Description

This opcode describes an EFI Variable Variable Store within a form set. The *Guid* specified here and the name specified by *VariableName* in the question's header will be used with **GetVariable ()** and **SetVariable ()**. A question can select this variable store by setting the *VarStoreId* field in its question header.

An **EFI_IFR_VARSTORE_EFI** with a specified *VarStoreId* must appear in the IFR before it can be referenced by a question.

27.3.8.3.82 EFI_IFR_VARSTORE_DEVICE

Summary

Select the device which contains the variable store.

Prototype

```
#define EFI_IFR_VARSTORE_DEVICE_OP0x27
typedef struct _EFI_IFR_VARSTORE_DEVICE {
    EFI_IFR_OP_HEADER           Header;
    EFI_STRING_ID               DevicePath;
} EFI_IFR_VARSTORE_DEVICE;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* =

EFI_IFR_VARSTORE_DEVICE_OP.

DevicePath

Specifies the string which contains the device path of the device where the variable store resides.

Description

This opcode describes the device path where a variable store resides. Normally, the Forms Processor finds the variable store on the handle specified when the HII database function **InstallPackageList ()** was called. However, if this opcode is found in the scope of a question, the handle specified by the text device path *DevicePath* is used instead.

27.3.8.3.83 EFI_IFR_VERSION

Summary

Push the version of the UEFI specification to which the Forms Processor conforms.

Prototype

```
#define EFI_IFR_VERSION_OP0x28
typedef struct _EFI_IFR_VERSION {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_VERSION;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_VERSION_OP**.

Description

Returns the revision level of the UEFI specification with which the Forms Processor is compliant as a 16-bit unsigned integer, with the form:

[15:8]	Major revision
[7:4]	Minor revision
[3:0]	Errata revision

27.3.8.3.84 EFI_IFR_ZERO

Summary

Push a zero on to the expression stack.

Prototype

```
#define EFI_IFR_ZERO_OP0x52
typedef struct _EFI_IFR_ZERO {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_ZERO;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode* = **EFI_IFR_ZERO_OP**

Description

Push a zero on to the expression stack.

28

HII Protocols

This section provides code definitions for the HII-related protocols, functions, and type definitions, which are the required architectural mechanisms by which UEFI-compliant systems manage user input. The major areas described include the following:

- Font management.
- String management.
- Image management.
- Database management.

28.1 Font Protocol

EFI_HII_FONT_PROTOCOL

Summary

Interfaces which retrieve font information.

GUID

```
#define EFI_HII_FONT_PROTOCOL_GUID \
    { 0xe9ca4775, 0x8657, 0x47fc, 0x97, 0xe7, 0x7e, 0xd6, \
      0x5a, 0x8, 0x43, 0x24 }
```

Protocol

```
typedef struct _EFI_HII_FONT_PROTOCOL {
    EFI_HII_STRING_TO_IMAGE      StringToImage;
    EFI_HII_STRING_ID_TO_IMAGE  StringIdToImage;
    EFI_HII_GET_GLYPH           GetGlyph;
    EFI_HII_GET_FONT_INFO       GetFontInfo;
} EFI_HII_FONT_PROTOCOL;
```

Members

StringToImage, StringIdToImage

Render a string to a bitmap or to the display.

GetGlyph

Return a specific glyph in a specific font.

GetFontInfo

Return font information for a specific font.

EFI_HII_FONT_PROTOCOL.StringToImage()

Summary

Renders a string to a bitmap or to the display.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_STRING_TO_IMAGE) (
    IN CONST EFI_HII_FONT_PROTOCOL *This,
    IN EFI_HII_OUT_FLAGS           Flags,
    IN CONST EFI_STRING           String,
    IN CONST EFI_FONT_DISPLAY_INFO *StringInfo,
    IN OUT EFI_IMAGE_OUTPUT       **Blt,
    IN UINTN                      BltX,
    IN UINTN                      BltY,
    OUT EFI_HII_ROW_INFO          **RowInfoArray OPTIONAL,
    OUT UINTN                     *RowInfoArraySize OPTIONAL,
    OUT UINTN                     *ColumnInfoArray OPTIONAL
);
```

Parameters

This

A pointer to the **EFI_HII_FONT_PROTOCOL** instance.

Flags

Describes how the string is to be drawn. **EFI_HII_OUT_FLAGS** is defined in Related Definitions, below.

String

Points to the null-terminated string to be displayed.

StringInfo

Points to the string output information, including the color and font. If NULL, then the string will be output in the default system font and color.

Blt

If this points to a non-NULL on entry, this points to the image, which is *Width* pixels wide and *Height* pixels high. The string will be drawn onto this image and **EFI_HII_OUT_FLAG_CLIP** is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller's responsibility to free this buffer.

BltX, BltY

Specifies the offset from the left and top edge of the image of the first character cell in the image.

RowInfoArray

If this is non-NULL on entry, then on exit, this will point to an allocated buffer containing row information and *RowInfoArraySize* will be updated to contain the number of elements. This array describes the characters which were at least partially drawn and the heights of the rows. It is the caller's responsibility to free this buffer.

RowInfoArraySize

If this is non-NULL on entry, then on exit it contains the number of elements in *RowInfoArray*.

ColumnInfoArray

If this is non-NULL, then on return it will be filled with the horizontal offset for each character in the string on the row where it is displayed. Non-printing characters will have the offset ~0. The caller is responsible to allocate a buffer large enough so that there is one entry for each character in the string, not including the null-terminator. It is possible when character display is normalized that some character cells overlap.

Description

This function renders a string to a bitmap or the screen using the specified font, color and options. It either draws the string and glyphs on an existing bitmap, allocates a new bitmap or uses the screen. The strings can be clipped or wrapped. Optionally, the function also returns the information about each row and the character position on that row.

If **EFI_HII_OUT_FLAG_CLIP** is set, then text will be formatted only based on explicit line breaks and all pixels which would lie outside the bounding box specified by *Width* and *Height* are ignored. The information in the *RowInfoArray* only describes characters which are at least partially displayed. For the final row, the *LineHeight* and *BaseLine* may describe pixels which are outside the limit specified by *Height* (unless **EFI_HII_OUT_FLAG_CLIP_CLEAN_Y** is specified) even though those pixels were not drawn. The *LineWidth* may describe pixels which are outside the limit specified by *Width* (unless **EFI_HII_OUT_FLAG_CLIP_CLEAN_X** is specified) even though those pixels were not drawn.

If **EFI_HII_OUT_FLAG_CLIP_CLEAN_X** is set, then it modifies the behavior of **EFI_HII_OUT_FLAG_CLIP** so that if a character's right-most on pixel cannot fit, then it will not be drawn at all. This flag requires that **EFI_HII_OUT_FLAG_CLIP** be set.

If **EFI_HII_OUT_FLAG_CLIP_CLEAN_Y** is set, then it modifies the behavior of **EFI_HII_OUT_FLAG_CLIP** so that if a row's bottom-most pixel cannot fit, then it will not be drawn at all. This flag requires that **EFI_HII_OUT_FLAG_CLIP** be set.

If **EFI_HII_OUT_FLAG_WRAP** is set, then text will be wrapped at the right-most line-break opportunity prior to a character whose right-most extent would exceed *Width*. If no line-break opportunity can be found, then the text will behave as if **EFI_HII_OUT_FLAG_CLIP_CLEAN_X** is set. This flag cannot be used with **EFI_HII_OUT_FLAG_CLIP_CLEAN_X**.

If **EFI_HII_OUT_FLAG_TRANSPARENT** is set, then *BackgroundColor* is ignored and all "off" pixels in the character's drawn will use the pixel value from *Blt*. This flag cannot be used if *Blt* is NULL upon entry.

If **EFI_HII_IGNORE_IF_NO_GLYPH** is set, then characters which have no glyphs are not drawn. Otherwise, they are replaced with Unicode character 0xFFFFD (REPLACEMENT CHARACTER).

If `EFI_HII_IGNORE_LINE_BREAK` is set, then explicit line break characters will be ignored.

If `EFI_HII_DIRECT_TO_SCREEN` is set, then the string will be written directly to the output device specified by *Screen*. Otherwise the string will be rendered to the bitmap specified by *Bitmap*.

Related Definitions

```
typedef UINT32 EFI_HII_OUT_FLAGS;

#define EFI_HII_OUT_FLAG_CLIP           0x00000001
#define EFI_HII_OUT_FLAG_WRAP         0x00000002
#define EFI_HII_OUT_FLAG_CLEAN_Y     0x00000004
#define EFI_HII_OUT_FLAG_CLEAN_X     0x00000008
#define EFI_HII_OUT_FLAG_TRANSPARENT 0x00000010
#define EFI_HII_IGNORE_IF_NO_GLYPH   0x00000020
#define EFI_HII_IGNORE_LINE_BREAK     0x00000040
#define EFI_HII_DIRECT_TO_SCREEN      0x00000080
```

```
typedef struct _EFI_HII_ROW_INFO {
    UINTN  StartIndex;
    UINTN  EndIndex;
    UINTN  LineHeight;
    UINTN  LineWidth;
    UINTN  BaselineOffset;
} EFI_HII_ROW_INFO;
```

StartIndex

The index of the first character in the string which is displayed on the line.

EndIndex

The index of the last character in the string which is displayed on the line. If this is the same as *StartIndex*, then no characters are displayed.

LineHeight

The height of the line, in pixels.

LineWidth

The width of the text on the line, in pixels.

BaselineOffset

The number of pixels above the bottom of the row of the font baseline or 0 if none.

Status Codes Returned

EFI_SUCCESS	The string was successfully updated.
EFI_OUT_OF_RESOURCES	Unable to allocate an output buffer for <i>RowInfoArray</i> or <i>Blt</i> .
EFI_INVALID_PARAMETER	The <i>String</i> or <i>Blt</i> or <i>Height</i> or <i>Width</i> was NULL.

EFI_HII_FONT_PROTOCOL.StringIdToImage()

Summary

Render a string to a bitmap or the screen containing the contents of the specified string.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_STRING_ID_TO_IMAGE) (
    IN      CONST EFI_HII_FONT_PROTOCOL *This,
    IN      EFI_HII_OUT_FLAGS           Flags,
    IN      EFI_HII_HANDLE              PackageList,
    IN      EFI_STRING_ID               StringId,
    IN      CONST CHAR8*                Language,
    IN      CONST EFI_FONT_DISPLAY_INFO *StringInfo OPTIONAL,
    IN OUT  EFI_IMAGE_OUTPUT            **Blt,
    IN      UINTN                       BltX,
    IN      UINTN                       BltY,
    OUT     EFI_HII_ROW_INFO            **RowInfoArray OPTIONAL,
    OUT     UINTN                       *RowInfoArraySize OPTIONAL,
    OUT     UINTN                       *ColumnInfoArray OPTIONAL
);
```

Parameters

This

A pointer to the **EFI_HII_FONT_PROTOCOL** instance.

Flags

Describes how the string is to be drawn. **EFI_HII_OUT_FLAGS** is defined in Related Definitions, below.

PackageList

The package list in the HII database to search for the specified string.

StringId

The string's id, which is unique within *PackageList*.

Language

Points to the language for the retrieved string. If NULL, then the current system language is used.

StringInfo

Points to the string output information, including the color and font. If NULL, then the string will be output in the default system font and color.

Blt

If this points to a non-NULL on entry, this points to the image, which is *Width* pixels wide and *Height* pixels high. The string will be drawn onto this image and **EFI_HII_OUT_FLAG_CLIP** is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller's responsibility to free this buffer.

BltX, BltY

Specifies the offset from the left and top edge of the output image of the first character cell in the image.

RowInfoArray

If this is non-NULL on entry, then on exit, this will point to an allocated buffer containing row information and *RowInfoArraySize* will be updated to contain the number of elements. This array describes the characters which were at least partially drawn and the heights of the rows. It is the caller's responsibility to free this buffer.

RowInfoArraySize

If this is non-NULL on entry, then on exit it contains the number of elements in *RowInfoArray*.

ColumnInfoArray

If non-NULL, on return it is filled with the horizontal offset for each character in the string on the row where it is displayed. Non-printing characters will have the offset ~0. The caller is responsible to allocate a buffer large enough so that there is one entry for each character in the string, not including the null-terminator. It is possible when character display is normalized that some character cells overlap.

Description

This function renders a string as a bitmap or to the screen and can clip or wrap the string. The bitmap is either supplied by the caller or else is allocated by the function. The strings are drawn with the font, size and style specified and can be drawn transparently or opaquely. The function can also return information about each row and each character's position on the row.

If **EFI_HII_OUT_FLAG_CLIP** is set, then text will be formatted only based on explicit line breaks and all pixels which would lie outside the bounding box specified by *Width* and *Height* are ignored. The information in the *RowInfoArray* only describes characters which are at least partially displayed. For the final row, the LineHeight and BaseLine may describe pixels which are outside the limit specified by *Height* (unless **EFI_HII_OUT_FLAG_CLIP_CLEAN_Y** is specified) even though those pixels were not drawn.

If **EFI_HII_OUT_FLAG_CLIP_CLEAN_X** is set, then it modifies the behavior of **EFI_HII_OUT_FLAG_CLIP** so that if a character's right-most on pixel cannot fit, then it will not be drawn at all. This flag requires that **EFI_HII_OUT_FLAG_CLIP** be set.

If **EFI_HII_OUT_FLAG_CLIP_CLEAN_Y** is set, then it modifies the behavior of **EFI_HII_OUT_FLAG_CLIP** so that if a row's bottom most pixel cannot fit, then it will not be drawn at all. This flag requires that **EFI_HII_OUT_FLAG_CLIP** be set.

If **EFI_HII_OUT_FLAG_WRAP** is set, then text will be wrapped at the right-most line-break opportunity prior to a character whose right-most extent would exceed *Width*. If no line-break opportunity can be found, then the text will behave as if **EFI_HII_OUT_FLAG_CLIP_CLEAN_X** is set. This flag cannot be used with **EFI_HII_OUT_FLAG_CLIP_CLEAN_X**.

If **EFI_HII_OUT_FLAG_TRANSPARENT** is set, then *BackgroundColor* is ignored and all “off” pixels in the character’s glyph will use the pixel value from *Blit*. This flag cannot be used if *Blit* is NULL upon entry.

If **EFI_HII_IGNORE_IF_NO_GLYPH** is set, then characters which have no glyphs are not drawn. Otherwise, they are replaced with Unicode character 0xFFFFD (REPLACEMENT CHARACTER).

If **EFI_HII_IGNORE_LINE_BREAK** is set, then explicit line break characters will be ignored.

If **EFI_HII_DIRECT_TO_SCREEN** is set, then the string will be written directly to the output device specified by *Screen*. Otherwise the string will be rendered to the bitmap specified by *Bitmap*.

Status Codes Returned

EFI_SUCCESS	The string was successfully updated.
EFI_OUT_OF_RESOURCES	Unable to allocate an output buffer for <i>RowInfoArray</i> or <i>Blit</i> .
EFI_INVALID_PARAMETER	The <i>String</i> or <i>Blit</i> or <i>Height</i> or <i>Width</i> was NULL.

EFI_HII_FONT_PROTOCOL.GetGlyph()

Summary

Return information about a single glyph.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_GET_GLYPH) (
    IN CONST EFI_HII_FONT_PROTOCOL *This,
    IN CHAR16 Char,
    IN CONST EFI_FONT_DISPLAY_INFO *StringInfo,
    OUT EFI_IMAGE_OUTPUT **Blt;
    OUT UINTN *Baseline OPTIONAL;
);
```

Parameters

This

A pointer to the **EFI_HII_FONT_PROTOCOL** instance.

Char

Character to retrieve.

StringInfo

Points to the string font and color information or NULL if the string should use the default system font and color.

Blt

Thus must point to a NULL on entry. A buffer will be allocated to hold the output and the pointer updated on exit. It is the caller's responsibility to free this buffer.

Baseline

Number of pixels from the bottom of the bitmap to the baseline.

Description

Convert the glyph for a single character into a bitmap.

Status Codes Returned

EFI_SUCCESS	Glyph bitmap created.
EFI_OUT_OF_RESOURCES	Unable to allocate the output buffer <i>Blt</i> .
EFI_WARN_UNKNOWN_GLYPH	The glyph was unknown and was replaced with the glyph for Unicode character 0xFFFFD.
EFI_INVALID_PARAMETER	<i>Blt</i> is NULL or <i>Width</i> is NULL or <i>Height</i> is NULL

EFI_HII_FONT_PROTOCOL.GetFontInfo()

Summary

Return information about a particular font.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_HII_GET_FONT_INFO) (
    IN      CONST EFI_HII_FONT_PROTOCOL  *This,
    IN OUT  EFI_FONT_HANDLE              *FontHandle,
    IN      CONST EFI_FONT_DISPLAY_INFO *StringInfoIn,
    OUT     EFI_FONT_DISPLAY_INFO       *StringInfoOut,
    IN      CONST EFI_STRING             *String OPTIONAL
);
```

Parameters

This

A pointer to the **EFI_HII_FONT_PROTOCOL** instance.

FontHandle

On entry, points to the font handle returned by a previous call to **GetFontInfo()** or NULL to start with the first font. On return, points to the returned font handle or points to NULL if there are no more matching fonts.

StringInfoIn

Upon entry, points to the font to return information about.

StringInfoOut

Upon return, contains the matching font's information. If NULL, then no information is returned.

String

Points to the string which will be tested to determine if all characters are available. If NULL, then any font is acceptable.

Description

This function iterates through fonts which match the specified font, using the specified criteria. If *String* is non-NULL, then all of the characters in the string must exist in order for a candidate font to be returned.

Status Codes Returned

EFI_SUCCESS	Matching font returned successfully.
EFI_NOT_FOUND	No matching font was found.
EFI_INVALID_PARAMETER	<i>FontHandle</i> is NULL or <i>StringInfoIn</i> is NULL

28.1.1 Code Definitions

EFI_FONT_DISPLAY_INFO

Summary

Describes font output-related information.

Prototype

```
typedef struct _EFI_FONT_DISPLAY_INFO {
    EFI_FONT_INFO           FontInfo;
    EFI_GRAPHICS_OUTPUT_BLT_PIXEL ForegroundColor;
    EFI_GRAPHICS_OUTPUT_BLT_PIXEL BackgroundColor;
    EFI_FONT_INFO_MASK      FontInfoMask;
} EFI_FONT_DISPLAY_INFO;
```

Members

FontInfo

Points to the font information or NULL if the string should use the default system font.

ForegroundColor

The color of the “on” pixels in the glyph in the bitmap.

BackgroundColor

The color of the “off” pixels in the glyph in the bitmap.

FontInfoMask

The font information mask determines which portion of the font information will be used and what to do if the specific font is not available.

Description

This structure is used for describing the way in which a string should be rendered in a particular font. *FontInfo* specifies the basic font information and *ForegroundColor* and *BackgroundColor* specify the color in which they should be displayed. The flags in *FontInfoMask* describe where the system default should be supplied instead of the specified

information. The flags also describe what options can be used to make a match between the font requested and the font available.

If **EFI_FONT_INFO_SYS_FONT** is specified, then the font name in *FontInfo* is ignored and the system font name is used. This flag cannot be used with **EFI_FONT_INFO_ANY_FONT**.

If **EFI_FONT_INFO_SYS_SIZE** is specified, then the font height specified in *FontInfo* is ignored and the system font height is used instead. This flag cannot be used with **EFI_FONT_INFO_ANY_SIZE**.

If **EFI_FONT_INFO_SYS_STYLE** is specified, then the font style in *FontInfo* is ignored and the system font style is used. This flag cannot be used with **EFI_FONT_INFO_ANY_STYLE**.

If **EFI_FONT_INFO_SYS_FORE_COLOR** is specified, then *ForegroundColor* is ignored and the system foreground color is used.

If **EFI_FONT_INFO_SYS_BACK_COLOR** is specified, then *BackgroundColor* is ignored and the system background color is used.

If **EFI_FONT_INFO_RESIZE** is specified, then the system may attempt to stretch or shrink a font to meet the size requested. This flag cannot be used with **EFI_FONT_INFO_ANY_SIZE**.

If **EFI_FONT_INFO_RESTYLE** is specified, then the system may attempt to remove some of the specified styles in order to meet the style requested. This flag cannot be used with **EFI_FONT_INFO_ANY_STYLE**.

If **EFI_FONT_INFO_ANY_FONT** is specified, then the system may attempt to match with any font. This flag cannot be used with **EFI_FONT_INFO_SYS_FONT**.

If **EFI_FONT_INFO_ANY_SIZE** is specified, then the system may attempt to match with any font size. This flag cannot be used with **EFI_FONT_INFO_SYS_SIZE** or **EFI_FONT_INFO_RESIZE**.

If **EFI_FONT_INFO_ANY_STYLE** is specified, then the system may attempt to match with any font style. This flag cannot be used with **EFI_FONT_INFO_SYS_STYLE** or **EFI_FONT_INFO_RESTYLE**.

Related Definitions

```

typedef UINT32 EFI_FONT_INFO_MASK;

#define EFI_FONT_INFO_SYS_FONT           0x00000001
#define EFI_FONT_INFO_SYS_SIZE          0x00000002
#define EFI_FONT_INFO_SYS_STYLE         0x00000004
#define EFI_FONT_INFO_SYS_FORE_COLOR    0x00000010
#define EFI_FONT_INFO_SYS_BACK_COLOR    0x00000020
#define EFI_FONT_INFO_RESIZE            0x00001000
#define EFI_FONT_INFO_RESTYLE           0x00002000
#define EFI_FONT_INFO_ANY_FONT          0x00010000
#define EFI_FONT_INFO_ANY_SIZE          0x00020000
#define EFI_FONT_INFO_ANY_STYLE         0x00040000

```

EFI_IMAGE_OUTPUT

Summary

Describes information about either a bitmap or a graphical output device.

Prototype

```

typedef struct _EFI_IMAGE_OUTPUT {
    UINT16                               Width;
    UINT16                               Height;
    union {
        EFI_GRAPHICS_OUTPUT_BLT_PIXEL    *Bitmap;
        EFI_GRAPHICS_OUTPUT_PROTOCOL     *Screen;
    } Image;
} EFI_IMAGE_OUTPUT;

```

Members

Width

Width of the output image.

Height

Height of the output image.

Bitmap

Points to the output bitmap.

Screen

Points to the **EFI_GRAPHICS_OUTPUT_PROTOCOL** which describes the screen on which to draw the specified string.

28.2 String Protocol

EFI_HII_STRING_PROTOCOL

Summary

Interfaces which manipulate string data.

GUID

```
#define EFI_HII_STRING_PROTOCOL_GUID \
    { 0xfd96974, 0x23aa, 0x4cdc, 0xb9, 0xcb, 0x98, 0xd1, \
      0x77, 0x50, 0x32, 0x2a }
```

Protocol

```
typedef struct _EFI_HII_STRING_PROTOCOL {
    EFI_HII_NEW_STRING           NewString;
    EFI_HII_GET_STRING           GetString;
    EFI_HII_SET_STRING           SetString;
    EFI_HII_GET_LANGUAGES        GetLanguages;
    EFI_HII_GET_2ND_LANGUAGES    GetSecondaryLanguages;
} EFI_HII_STRING_PROTOCOL;
```

Members

NewString

Add a new string.

GetString

Retrieve a string and related string information.

SetString

Change a string.

GetLanguages

List the languages for a particular package list.

GetSecondaryLanguages

List supported secondary languages for a particular primary language.

EFI_HII_STRING_PROTOCOL.NewString()

Summary

Creates a new string in a specific language and add it to strings from a specific package list.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_NEW_STRING) (
    IN  CONST EFI_HII_STRING_PROTOCOL  *This,
    IN  EFI_HII_HANDLE                 PackageList,
    OUT EFI_STRING_ID                  *StringId
    IN  CONST CHAR8                    *Language,
    IN  CONST EFI_STRING                String,
    IN  CONST EFI_FONT_INFO            *StringFontInfo OPTIONAL,
);
```

Parameters

This

A pointer to the **EFI_HII_STRING_PROTOCOL** instance.

PackageList

Handle of the package list where this string will be added.

Language

Points to the language for the new string. The language information is in the format described by [Appendix M](#) of the UEFI 2.0 specification.

String

Points to the new null-terminated string.

StringFontInfo

Points to the new string's font information or NULL if the string should have the default system font, size and style.

StringId

On return, contains the new strings id, which is unique within *PackageList*. Type **EFI_STRING_ID** is defined in TBD (14.2)

Description

This function adds the string *String* to the group of strings owned by *PackageList*, with the specified font information *StringFontInfo* and returns a new string id.

Related Definitions

```
typedef struct {
    UINT32  FontStyle;
    UINT16  FontSize; // character cell size in pixels
    CHAR16  FontName[...];
} EFI_FONT_INFO;
```

Status Codes Returns

EFI_SUCCESS	The new string was added successfully
EFI_OUT_OF_RESOURCES	Could not add the string.
EFI_INVALID_PARAMETER	<i>String</i> is NULL or <i>StringId</i> is NULL or <i>Language</i> is NULL.

EFI_HII_STRING_PROTOCOL.GetString()

Summary

Returns information about a string in a specific language, associated with a package list.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_HII_GET_STRING) (
    IN      CONST EFI_HII_STRING_PROTOCOL *This,
    IN      CONST CHAR8                  *Language,
    IN      EFI_HII_HANDLE                PackageList,
    IN      EFI_STRING_ID                 StringId,
    OUT     EFI_STRING                     String,
    IN OUT  UINTN                          StringSize,
    OUT     EFI_FONT_INFO                  *StringFontInfo OPTIONAL
);
```

Parameters

This

A pointer to the `EFI_HII_STRING_PROTOCOL` instance.

PackageList

The package list in the HII database to search for the specified string.

Language

Points to the language for the retrieved string.

StringId

The string's id, which is unique within *PackageList*.

String

Points to the new null-terminated string.

StringSize

On entry, points to the size of the buffer pointed to by *String*, in bytes. On return, points to the length of the string, in bytes.

StringFontInfo

Points to the string's font information or NULL if the string font information is not desired.

Description

This function retrieves the string specified by *StringId* which is associated with the specified *PackageList* in the language *Language* and copies it into the buffer specified by *String*.

If the string specified by *StringId* is not present in the specified *PackageList*, then **EFI_NOT_FOUND** is returned. If the string specified by *StringId* is present, but not in the specified language then **EFI_INVALID_LANGUAGE** is returned.

If the buffer specified by *StringSize* is too small to hold the string, then **EFI_BUFFER_TOO_SMALL** will be returned. *StringSize* will be updated to the size of buffer actually required to hold the string.

Status Codes Returned

EFI_SUCCESS	The string was returned successfully.
EFI_NOT_FOUND	The string specified by <i>StringId</i> is not available.
EFI_INVALID_LANGUAGE	The string specified by <i>StringId</i> is available but not in the specified language.
EFI_BUFFER_TOO_SMALL	The buffer specified by <i>StringLength</i> is too small to hold the string.
EFI_INVALID_PARAMETER	The <i>String</i> or <i>Language</i> was NULL.

EFI_HII_STRING_PROTOCOL.SetString()

Summary

Change information about the string.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_HII_SET_STRING) (
    IN CONST EFI_HII_STRING_PROTOCOL *This,
    IN EFI_HII_HANDLE                PackageList,
    IN EFI_STRING_ID                 StringId,
    IN CONST CHAR8                   *Language,
    IN CONST EFI_STRING               String,
    IN CONST EFI_FONT_INFO           *StringFontInfo OPTIONAL
);
```

Parameters

This

A pointer to the **EFI_HII_STRING_PROTOCOL** instance.

PackageList

The package list containing the strings.

Language

Points to the language for the updated string.

StringId

The string id, which is unique within *PackageList*.

String

Points to the new null-terminated string.

StringFontInfo

Points to the string's font information or NULL if the string font information is not changed.

Description

This function updates the string specified by *StringId* in the specified *PackageList* to the text specified by *String* and, optionally, the font information specified by *StringFontInfo*. There is no way to change the font information without changing the string text.

Status Codes Returned

EFI_SUCCESS	The string was successfully updated.
EFI_NOT_FOUND	The string specified by <i>StringId</i> is not in the database.
EFI_INVALID_PARAMETER	The <i>String</i> or <i>Language</i> was NULL.

EFI_OUT_OF_RESOURCES	The system is out of resources to accomplish the task.
----------------------	--

EFI_HII_STRING_PROTOCOL.GetLanguages()

Summary

Returns a list of the languages present in strings in a package list.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_GET_LANGUAGES) (
    IN      CONST EFI_HII_DATABASE_PROTOCOL *This,
    IN      EFI_HII_HANDLE                 PackageList,
    IN OUT CHAR8                           *Languages,
    IN OUT UINTN                           LanguageSize
);
```

Parameters

This

A pointer to the **EFI_HII_STRING_PROTOCOL** instance.

PackageList

The package list to examine.

Languages

Points to the buffer to hold the returned string.

LanguageSize

On entry, points to the size of the buffer pointed to by *Languages*, in bytes. On return, points to the length of *Languages*, in bytes.

Description

This function returns the list of supported languages, in the format specified in [Appendix M](#).

Status Codes Returned

EFI_SUCCESS	The languages were returned successfully.
EFI_BUFFER_TOO_SMALL	The <i>LanguageSize</i> is too small to hold the list of supported languages. <i>LanguageSize</i> is updated to contain the required size.
EFI_INVALID_PARAMETER	<i>Languages</i> is NULL.

EFI_HII_STRING_PROTOCOL.GetSecondaryLanguages()

Summary

Given a primary language, returns the secondary languages supported in a package list.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_GET_2ND_LANGUAGES) (
    IN      CONST EFI_HII_DATABASE_PROTOCOL *This,
    IN      EFI_HII_HANDLE                 PackageList,
    IN      CONST CHAR8*                   FirstLanguage;
    IN OUT  CHAR8                           *SecondLanguages,
    IN OUT  UINTN                           SecondLanguagesSize,
);
```

Parameters

This

A pointer to the **EFI_HII_STRING_PROTOCOL** instance.

PackageList

The package list to examine.

FirstLanguage

Points to the primary language. Languages are specified in the format specified in [Appendix M](#) of the UEFI 2.0 specification.

SecondaryLanguages

Points to the buffer to hold the returned list of secondary languages for the specified *FirstLanguage*. If there are no secondary languages, the function returns successfully, but this is set to NULL.

SecondaryLanguageSize

On entry, points to the size of the buffer pointed to by *Languages*, in bytes. On return, points to the length of *Languages* in bytes.

Description

Each string package has associated with it a single primary language and zero or more secondary languages. This routine returns the secondary languages associated with a package list.

Status Codes Returned

EFI_SUCCESS	Secondary languages correctly returned
EFI_BUFFER_TOO_SMALL	The buffer specified by <i>SecondLanguagesSize</i> is too small to hold the returned information. <i>SecondLanguageSize</i> is updated to hold the size of the buffer required.

EFI_INVALID_LANGUAGE	The language specified by <i>FirstLanguage</i> is not present in the specified package list.
EFI_INVALID_PARAMETER	<i>FirstLanguage</i> is NULL or <i>SecondLanguage</i> is NULL.

28.3 Image Protocol

EFI_HII_IMAGE_PROTOCOL

Summary

Protocol which allow access to images in the images database.

GUID

```
#define EFI_HII_IMAGE_PROTOCOL_GUID \
    { 0x31a6406a, 0x6bdf, 0x4e46, 0xb2, 0xa2, 0xeb, 0xaa, \
      0x89, 0xc4, 0x9, 0x20 }
```

Protocol

```
typedef struct _EFI_HII_IMAGE_PROTOCOL {
    EFI_HII_NEW_IMAGE           NewImage;
    EFI_HII_GET_IMAGE           GetImage;
    EFI_HII_SET_IMAGE           SetImage;
    EFI_HII_DRAW_IMAGE          DrawImage;
    EFI_HII_DRAW_IMAGE_ID       DrawImageId;
} EFI_HII_IMAGE_PROTOCOL;
```

Members

NewImage

Add a new image.

GetImage

Retrieve an image and related font information.

SetImage

Change an image.

EFI_HII_IMAGE_PROTOCOL.NewImage()

Summary

Creates a new image and add it to images from a specific package list.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_NEW_IMAGE) (
    IN  CONST EFI_HII_IMAGE_PROTOCOL *This,
    IN  EFI_HII_HANDLE               PackageList,
    OUT EFI_IMAGE_ID                 *ImageId
    IN  CONST EFI_IMAGE_INPUT        *Image
);
```

Parameters

This

A pointer to the **EFI_HII_IMAGE_PROTOCOL** instance.

PackageList

Handle of the package list where this image will be added.

ImageId

On return, contains the new image id, which is unique within *PackageList*.

Image

Points to the image.

Description

This function adds the image *Image* to the group of images owned by *PackageList*, and returns a new image identifier (*ImageId*).

Related Definitions

```
typedef UINT16 EFI_IMAGE_ID;

typedef struct _EFI_IMAGE_INPUT {
    UINT16                Width;
    UINT16                Height;
    EFI_GRAPHICS_OUTPUT_BLT_PIXEL *Bitmap;
} EFI_IMAGE_INPUT;
```

Status Codes Returns

EFI_SUCCESS	The new image was added successfully
EFI_OUT_OF_RESOURCES	Could not add the image.

Unified Extensible Firmware Interface Specification

EFI_INVALID_PARAMETER	<i>Image</i> is NULL or <i>ImageId</i> is NULL.
-----------------------	---

EFI_HII_IMAGE_PROTOCOL.GetImage()

Summary

Returns information about an image, associated with a package list.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_GET_IMAGE) (
    IN CONST EFI_HII_IMAGE_PROTOCOL *This,
    IN EFI_HII_HANDLE PackageList,
    IN EFI_IMAGE_ID ImageId,
    OUT EFI_IMAGE_INPUT *Image,
    OUT UINTN *ImageSize,
);
```

Parameters

This

A pointer to the **EFI_HII_IMAGE_PROTOCOL** instance.

PackageList

The package list in the HII database to search for the specified image.

ImageId

The image's id, which is unique within *PackageList*.

Image

Points to the new image.

ImageSize

On entry, points to the size of the buffer pointed to by *Image*, in bytes. On return, points to the length of the image, in bytes.

Description

This function retrieves the image specified by *ImageId* which is associated with the specified *PackageList* and copies it into the buffer specified by *Image*.

If the image specified by *ImageId* is not present in the specified *PackageList*, then **EFI_NOT_FOUND** is returned.

If the buffer specified by *ImageSize* is too small to hold the image, then **EFI_BUFFER_TOO_SMALL** will be returned. *ImageSize* will be updated to the size of buffer actually required to hold the image.

Status Codes Returned

EFI_SUCCESS	The image was returned successfully.
EFI_NOT_FOUND	The image specified by <i>ImageId</i> is not available.

Unified Extensible Firmware Interface Specification

EFI_BUFFER_TOO_SMALL	The buffer specified by <i>ImageLength</i> is too small to hold the image.
EFI_INVALID_PARAMETER	The <i>Image</i> or <i>Language</i> was NULL.

EFI_HII_IMAGE_PROTOCOL.SetImage()

Summary

Change information about the image.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_SET_IMAGE) (
    IN CONST EFI_HII_IMAGE_PROTOCOL *This,
    IN EFI_HII_HANDLE                PackageList,
    IN EFI_IMAGE_ID                  ImageId,
    IN CONST EFI_IMAGE_INPUT         Image,
);
```

Parameters

This

A pointer to the **EFI_HII_IMAGE_PROTOCOL** instance.

PackageList

The package list containing the images.

ImageId

The image id, which is unique within *PackageList*.

Image

Points to the image.

Description

This function updates the image specified by *ImageId* in the specified *PackageListHandle* to the image specified by *Image*.

Status Codes Returned

EFI_SUCCESS	The image was successfully updated.
EFI_NOT_FOUND	The image specified by <i>ImageId</i> is not in the database.
EFI_INVALID_PARAMETER	The <i>Image</i> or <i>Language</i> was NULL.

EFI_HII_IMAGE_PROTOCOL.DrawImage()

Summary

Renders an image to a bitmap or to the display.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_HII_DRAW_IMAGE) (
    IN CONST EFI_HII_IMAGE_PROTOCOL *This,
    IN EFI_HII_DRAW_FLAGS           Flags,
    IN CONST EFI_IMAGE_INPUT       Image,
    IN OUT EFI_IMAGE_OUTPUT        **Blt,
    IN UINTN                       BltX,
    IN UINTN                       BltY,
);

```

Parameters

This

A pointer to the **EFI_HII_IMAGE_PROTOCOL** instance.

Flags

Describes how the image is to be drawn. **EFI_HII_DRAW_FLAGS** is defined in Related Definitions, below.

Image

Points to the image to be displayed.

Blt

If this points to a non-NULL on entry, this points to the image, which is *Width* pixels wide and *Height* pixels high. The image will be drawn onto this image and **EFI_HII_DRAW_FLAG_CLIP** is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller's responsibility to free this buffer.

BltX, BltY

Specifies the offset from the left and top edge of the image of the first pixel in the image.

Description

This function renders an image to a bitmap or the screen using the specified color and options. It draws the image on an existing bitmap, allocates a new bitmap or uses the screen. The images can be clipped.

If **EFI_HII_DRAW_FLAG_CLIP** is set, then all pixels drawn outside the bounding box specified by *Width* and *Height* are ignored.

If **EFI_HII_DRAW_FLAG_TRANSPARENT** is set, then all “off” pixels in the images drawn will use the pixel value from *Blt*. This flag cannot be used if *Blt* is NULL upon entry.

If **EFI_HII_DIRECT_TO_SCREEN** is set, then the image will be written directly to the output device specified by *Screen*. Otherwise the image will be rendered to the bitmap specified by *Bitmap*.

Related Definitions

```
typedef UINT32 EFI_HII_DRAW_FLAGS;

#define EFI_HII_DRAW_FLAG_CLIP          0x00000001
#define EFI_HII_DRAW_FLAG_TRANSPARENT  0x00000010
#define EFI_HII_DIRECT_TO_SCREEN       0x00000080

typedef struct _EFI_IMAGE_OUTPUT {
    UINT16          Width;
    UINT16          Height;
    union {
        EFI_GRAPHICS_OUTPUT_BLT_PIXEL *Bitmap;
        EFI_GRAPHICS_OUTPUT_PROTOCOL *Screen;
    } Image;
} EFI_IMAGE_OUTPUT;
```

Width

Width of the output image.

Height

Height of the output image.

Bitmap

Points to the output bitmap.

Screen

Points to the **EFI_GRAPHICS_OUTPUT_PROTOCOL** which describes the screen on which to draw the specified image.

Status Codes Returned

EFI_SUCCESS	The image was successfully updated.
EFI_OUT_OF_RESOURCES	Unable to allocate an output buffer for <i>RowInfoArray</i> or <i>Blt</i> .
EFI_INVALID_PARAMETER	The <i>Image</i> or <i>Blt</i> or <i>Height</i> or <i>Width</i> was NULL.

EFI_HII_IMAGE_PROTOCOL.DrawImageId()

Summary

Render an image to a bitmap or the screen containing the contents of the specified image.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_DRAW_IMAGE_ID) (
    IN CONST EFI_HII_IMAGE_PROTOCOL    *This,
    IN EFI_HII_DRAW_FLAGS              Flags,
    IN EFI_HII_HANDLE                  PackageList,
    IN EFI_IMAGE_ID                    ImageId,
    IN OUT EFI_IMAGE_OUTPUT            **Blt,
    IN UINTN                            BltX,
    IN UINTN                            BltY,
);
```

Parameters

This

A pointer to the **EFI_HII_IMAGE_PROTOCOL** instance.

Flags

Describes how the image is to be drawn. **EFI_HII_DRAW_FLAGS** is defined in Related Definitions, below.

PackageList

The package list in the HII database to search for the specified image.

ImageId

The image's id, which is unique within *PackageList*.

Blt

If this points to a non-NULL on entry, this points to the image, which is *Width* pixels wide and *Height* pixels high. The image will be drawn onto this image and **EFI_HII_DRAW_FLAG_CLIP** is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller's responsibility to free this buffer.

BltX, BltY

Specifies the offset from the left and top edge of the output image of the first pixel in the image.

Description

This function renders an image as a bitmap or to the screen and can clip the image. The bitmap is either supplied by the caller or else is allocated by the function. The images can be drawn transparently or opaquely.

If **EFI_HII_DRAW_FLAG_CLIP** is set, then all pixels drawn outside the bounding box specified by *Width* and *Height* are ignored.

If **EFI_HII_DRAW_FLAG_TRANSPARENT** is set, then all “off” pixels in the character’s glyph will use the pixel value from *Blt*. This flag cannot be used if *Blt* is NULL upon entry.

If **EFI_HII_DIRECT_TO_SCREEN** is set, then the image will be written directly to the output device specified by *Screen*. Otherwise the image will be rendered to the bitmap specified by *Bitmap*.

Related Definitions

```
typedef UINT16 EFI_IMAGE_ID;
typedef struct _EFI_IMAGE_INPUT {
    UINT32                Flags;
    UINT16                Width;
    UINT16                Height;
    EFI_GRAPHICS_OUTPUT_BLT_PIXEL *Bitmap;
} EFI_IMAGE_INPUT;
```

Flags

Describe image characteristics. If **EFI_IMAGE_TRANSPARENT** is set, then the image was designed for transparent display.

```
#define EFI_IMAGE_TRANSPARENT    0x00000001
```

Width

Image width, in pixels.

Height

Image height, in pixels.

Bitmap

The actual bitmap, organized left-to-right, top-to-bottom. The size of the bitmap is *Width* * *Height* * **sizeof(EFI_GRAPHICS_OUTPUT_BLT_PIXEL)**.

Description

This function renders an image to a bitmap or the screen using the specified color and options. It draws the image on an existing bitmap, allocates a new bitmap or uses the screen. The images can be clipped.

If **EFI_HII_DRAW_FLAG_CLIP** is set, then all pixels drawn outside the bounding box specified by *Width* and *Height* are ignored.

The **EFI_HII_DRAW_FLAG_TRANSPARENT** flag determines whether the image will be drawn transparent or opaque. If **EFI_HII_DRAW_FLAG_FORCE_TRANS** is set, then the image will be drawn so that all “off” pixels in the image will be drawn using the pixel value from *Blt* and all other

pixels will be copied. If `EFI_HII_DRAW_FLAG_FORCE_OPAQUE` is set, then the image's pixels will be copied directly to the destination. If `EFI_HII_DRAW_FLAG_DEFAULT` is set, then the image will be drawn transparently or opaque, depending on the image's transparency setting (see `EFI_IMAGE_TRANSPARENT`). Images cannot be drawn transparently if `Blit` is NULL.

If `EFI_HII_DIRECT_TO_SCREEN` is set, then the image will be written directly to the output device specified by `Screen`. Otherwise the image will be rendered to the bitmap specified by `Bitmap`.

Related Definitions

```
typedef UINT32 EFI_HII_DRAW_FLAGS;
#define EFI_HII_DRAW_FLAG_CLIP          0x00000001
#define EFI_HII_DRAW_FLAG_TRANSPARENT  0x00000030
#define EFI_HII_DRAW_FLAG_DEFAULT      0x00000000
#define EFI_HII_DRAW_FLAG_FORCE_TRANS  0x00000001
#define EFI_HII_DRAW_FLAG_FORCE_OPAQUE 0x00000002
#define EFI_HII_DIRECT_TO_SCREEN       0x00000080
```

Status Codes Returned

EFI_SUCCESS	The image was successfully updated.
EFI_OUT_OF_RESOURCES	Unable to allocate an output buffer for <code>RowInfoArray</code> or <code>Blit</code> .
EFI_INVALID_PARAMETER	The <code>Image</code> or <code>Blit</code> or <code>Height</code> or <code>Width</code> was NULL.

28.4 Database Protocol

EFI_HII_DATABASE_PROTOCOL

Summary

Database manager for HII-related data structures.

GUID

```
#define EFI_HII_DATABASE_PROTOCOL_GUID \
{ 0xef9fc172, 0xa1b2, 0x4693, 0xb3, 0x27, 0x6d, 0x32, \
  0xfc, 0x41, 0x60, 0x42 }
```

Protocol

```
typedef struct _EFI_HII_DATABASE_PROTOCOL {
    EFI_HII_DATABASE_NEW_PACK           NewPackageList;
    EFI_HII_DATABASE_REMOVE_PACK        RemovePackageList;
    EFI_HII_DATABASE_UPDATE_PACK        UpdatePackageList;
    EFI_HII_DATABASE_LIST_PACKS         ListPackageLists;
    EFI_HII_DATABASE_EXPORT_PACKS       ExportPackageLists;
    EFI_HII_DATABASE_REGISTER_NOTIFY    RegisterPackageNotify;
    EFI_HII_DATABASE_UNREGISTER_NOTIFY  UnregisterPackageNotify;
    EFI_HII_FIND_KEYBOARD_LAYOUTS       FindKeyboardLayouts;
    EFI_HII_GET_KEYBOARD_LAYOUT         GetKeyboardLayout;
    EFI_HII_SET_KEYBOARD_LAYOUT         SetKeyboardLayout;
    EFI_HII_DATABASE_GET_PACK_HANDLE    GetPackageHandle;
} EFI_HII_DATABASE_PROTOCOL;
```

Members

NewPackageList

Add a new package list to the HII database.

RemovePackageList

Remove a package list from the HII database.

UpdatePackageList

Update a package list in the HII database.

ListPackageLists

List the handles of the package lists within the HII database.

ExportPackageLists

Export package lists from the HII database.

RegisterPackageNotify

Register notification when packages of a certain type are installed.

UnregisterPackageNotify

Unregister notification of packages.

FindKeyboardLayouts

Retrieves a list of the keyboard layouts in the system.

GetKeyboardLayout

Allows a program to extract the current keyboard layout. See the **GetKeyboardLayout ()** function description.

SetKeyboardLayout

Changes the current keyboard layout. See the **SetKeyboardLayout ()** function description.

EFI_HII_DATABASE_PROTOCOL.NewPackageList()

Summary

Adds the packages in the package list to the HII database.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_HII_NEW_PACK) (
    IN CONST EFI_HII_DATABASE_PROTOCOL *This,
    IN CONST EFI_HII_PACKAGE_LIST_HEADER *PackageList,
    IN CONST EFI_HANDLE DriverHandle,
    OUT EFI_HII_HANDLE *Handle
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

PackageList

A pointer to an **EFI_HII_PACKAGE_LIST_HEADER** structure.

DriverHandle

Associate the package list with this EFI handle

Handle

A pointer to the **EFI_HII_HANDLE** instance. Type **EFI_HII_HANDLE** is defined in Related Definitions below.

Description

This function adds the packages in the package list to the database and returns a handle. If there is a **EFI_DEVICE_PATH_PROTOCOL** associated with the *DriverHandle*, then this function will create a package of type **EFI_PACKAGE_TYPE_DEVICE_PATH** and add it to the package list.

For each package in the package list, registered functions with the notification type **NEW_PACK** and having the same package type will be called.

For each call to **NewPackageList()**, there should be a corresponding call to [EFI_HII_DATABASE_PROTOCOL.RemovePackageList\(\)](#).

Related Definitions

```
typedef VOID *EFI_HII_HANDLE;
```

Status Codes Returns

EFI_SUCCESS	The package list associated with the <i>Handle</i> was added to the HII database.
-------------	---

EFI_OUT_OF_RESOURCES	Unable to allocate necessary resources for the new database contents.
EFI_INVALID_PARAMETER	<i>PackageList</i> is NULL or <i>Handle</i> is NULL.

EFI_HII_DATABASE_PROTOCOL.RemovePackageList()

Summary

Removes a package list from the HII database.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_REMOVE_PACK) (
    IN CONST EFI_HII_DATABASE_PROTOCOL *This,
    IN EFI_HII_HANDLE Handle
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

Handle

The handle that was registered to the data that is requested for removal. Type **EFI_HII_HANDLE** is defined in **EFI_HII_DATABASE_PROTOCOL.NewPackageList()** in the Packages section.

Description

This function removes the package list that is associated with a handle *Handle* from the HII database. Before removing the package, any registered functions with the notification type **REMOVE_PACK** and the same package type will be called.

For each call to [EFI_HII_DATABASE_PROTOCOL.NewPackageList\(\)](#), there should be a corresponding call to RemovePackageList.

Status Codes Returned

EFI_SUCCESS	The data associated with the <i>Handle</i> was removed from the HII database.
EFI_INVALID_PARAMETER	The <i>Handle</i> was not valid.

EFI_HII_DATABASE_PROTOCOL.UpdatePackageList()

Summary

Update a package list in the HII database.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_REMOVE_PACK) (
    IN CONST EFI_HII_DATABASE_PROTOCOL  *This,
    IN EFI_HII_HANDLE                   Handle,
    IN CONST EFI_HII_PACKAGE_LIST      *PackageList,
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

Handle

The handle that was registered to the data that is requested for removal. Type **EFI_HII_HANDLE** is defined in **EFI_HII_DATABASE_PROTOCOL.NewPackageList()** in the Packages section.

PackageList

A pointer to an **EFI_HII_PACKAGE_LIST** package.

Description

This function updates the existing package list (which has the specified *Handle*) in the HII databases, using the new package list specified by *PackageList*. The update process has the following steps:

Collect all the package types in the package list specified by *PackageList*. A package type consists of the *Type* field of **EFI_HII_PACKAGE_HEADER** and, if the *Type* is **EFI_HII_PACKAGE_TYPE_GUID**, the *Guid* field, as defined in **EFI_HII_PACKAGE_GUID_HEADER**.

Iterate through the packages within the existing package list in the HII database specified by *Handle*. If a package's type matches one of the types collected in step 1, then perform the following steps:

- Call any functions registered with the notification type **REMOVE_PACK**.
- Remove the package from the package list and the HII database.

Add all of the packages within the new package list specified by *PackageList*, using the following steps:

- Add the package to the package list and the HII database.
- Call any functions registered with the notification type **ADD_PACK**.

Status Codes Returned

EFI_SUCCESS	The HII database was successfully updated.
EFI_OUT_OF_RESOURCES	Unable to allocate enough memory for the updated database.
EFI_INVALID_PARAMETER	The <i>Handle</i> was not valid.

EFI_HII_DATABASE_PROTOCOL.ListPackageLists()

Summary

Determines the handles that are currently active in the database.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_DATABASE_LIST_PACKS) (
    IN CONST EFI_HII_DATABASE_PROTOCOL  *This,
    IN UINT8                             PackageType,
    IN CONST EFI_GUID                    *PackageGuid,
    IN OUT UINTN                          *HandleBufferLength,
    OUT EFI_HII_HANDLE                   *Handle
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

PackageType

Specifies the package type of the packages to list or

EFI_HII_PACKAGE_TYPE_ALL for all packages to be listed.

PackageGuid

If *PackageType* is **EFI_HII_PACKAGE_TYPE_GUID**, then this is the pointer to the GUID which must match the *Guid* field of

EFI_HII_PACKAGE_GUID_HEADER. Otherwise, it must be NULL.

HandleBufferLength

On input, a pointer to the length of the handle buffer. On output, the length of the handle buffer that is required for the handles found.

Handle

An array of **EFI_HII_HANDLE** instances returned. Type **EFI_HII_HANDLE** is defined in **EFI_HII_DATABASE_PROTOCOL.NewPackageList()** in the Packages section.

Description

This function returns a list of the package handles of the specified type that are currently active in the database. The pseudo-type **EFI_HII_PACKAGE_TYPE_ALL** will cause all package handles to be listed.

Status Codes Returned

EFI_SUCCESS	<i>Handle</i> was updated successfully.
-------------	---

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EFI_BUFFER_TOO_SMALL	The <i>HandleBufferLength</i> parameter indicates that <i>Handle</i> is too small to support the number of handles. <i>HandleBufferLength</i> is updated with a value that will enable the data to fit.
----------------------	---

EFI_HII_DATABASE_PROTOCOL.ExportPackageLists()

Summary

Exports the contents of one or all package lists in the HII database into a buffer.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_HII_EXPORT_PACKS) (
    IN CONST EFI_HII_DATABASE_PROTOCOL    *This,
    IN EFI_HII_HANDLE                     Handle,
    IN OUT UINTN                           *BufferSize,
    OUT EFI_HII_PACKAGE_HEADER            *Buffer
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

Handle

An **EFI_HII_HANDLE** that corresponds to the desired package list in the HII database to export or NULL to indicate all package lists should be exported.

BufferSize

On input, a pointer to the length of the buffer. On output, the length of the buffer that is required for the exported data.

Buffer

A pointer to a buffer that will contain the results of the export function.

Description

This function will export one or all package lists in the database to a buffer. For each package list exported, this function will call functions registered with **EXPORT_PACK** and then copy the package list to the buffer. The registered functions may call

[EFI_HII_DATABASE_PROTOCOL.UpdatePackageList\(\)](#) to modify the package list before it is copied to the buffer.

If the specified *BufferSize* is too small, then the status **EFI_OUT_OF_RESOURCES** will be returned and the actual package size will be returned in *BufferSize*.

Status Codes Returned

EFI_SUCCESS	Package exported.
EFI_OUT_OF_RESOURCES	<i>BufferSize</i> is too small to hold the package.

EFI_HII_DATABASE_PROTOCOL.RegisterPackageNotify()

Summary

Registers a notification function for HII database-related events.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_DATABASE_REGISTER_NOTIFY) (
    IN  CONST EFI_HII_DATABASE_PROTOCOL  *This,
    IN  UINT8                            PackageType,
    IN  CONST EFI_GUID                   *PackageGuid,
    IN  CONST EFI_HII_DATABASE_NOTIFY    PackageNotifyFn,
    IN  EFI_HII_DATABASE_NOTIFY_TYPE     NotifyType,
    OUT EFI_HANDLE                        *NotifyHandle
);
```

Parameters

This

A pointer to the `EFI_HII_DATABASE_PROTOCOL` instance.

PackageType

The package type. See `EFI_HII_PACKAGE_TYPE_x` in [EFI HII PACKAGE HEADER](#).

PackageGuid

If *PackageType* is `EFI_HII_PACKAGE_TYPE_GUID`, then this is the pointer to the GUID which must match the *Guid* field of [EFI_HII_PACKAGE_GUID_HEADER](#). Otherwise, it must be NULL.

PackageNotifyFn

Points to the function to be called when the event specified by *NotificationType* occurs. See [EFI HII DATABASE NOTIFY](#).

NotifyType

Describes the types of notification which this function will be receiving. See [EFI HII DATABASE NOTIFY TYPE](#) for more a list of types.

NotifyHandle

Points to the unique handle assigned to the registered notification. Can be used in [EFI_HII_DATABASE_PROTOCOL.UnregisterPackageNotify\(\)](#) to stop notifications.

Description

This function registers a function which will be called when specified actions related to packages of the specified type occur in the HII database. By registering a function, other HII-related drivers are notified when specific package types are added, removed or updated in the HII database.

Each driver or application which registers a notification should use

[EFI_HII_DATABASE_PROTOCOL.UnregisterPackageNotify\(\)](#) before exiting.

Related Definitions

EFI_HII_PACKAGE_HEADER is defined in [EFI_HII_PACKAGE_HEADER](#).

EFI_HII_DATABASE_NOTIFY is defined in [EFI_HII_DATABASE_NOTIFY](#).

EFI_HII_DATABASE_NOTIFY_TYPE is defined in [EFI_HII_DATABASE_NOTIFY_TYPE](#).

Returned Status Codes

EFI_SUCCESS	Notification registered successfully.
EFI_OUT_OF_RESOURCES	Unable to allocate necessary data structures.
EFI_INVALID_PARAMETER	<i>PackageGuid</i> is not NULL when <i>PackageType</i> is not EFI_HII_PACKAGE_TYPE_GUID .

EFI_HII_DATABASE_PROTOCOL.UnregisterPackageNotify()

Summary

Removes the specified HII database package-related notification.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_DATABASE_UNREGISTER_NOTIFY) (
    IN CONST EFI_HII_DATABASE_PROTOCOL  *This,
    IN EFI_HANDLE                        NotificationHandle
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

NotificationHandle

The handle of the notification function being unregistered.

Returned Status Codes

EFI_SUCCESS	Invalidated
EFI_INVALID_PARAMETER	The <i>Handle</i> is invalid.

EFI_HII_DATABASE_PROTOCOL.FindKeyboardLayouts()

Summary

Retrieves a list of the keyboard layouts in the system.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_FIND_KEYBOARD_LAYOUTS) (
    IN     EFI_HII_DATABASE_PROTOCOL  *This,
    IN OUT UINT16                      *KeyGuidBufferLength,
    OUT    EFI_GUID                    *KeyGuidBuffer
);
```

Parameters

This

A pointer to the **EFI_HII_PROTOCOL** instance.

KeyGuidBufferLength

On input, a pointer to the length of the keyboard GUID buffer. On output, the length of the handle buffer that is required for the handles found.

KeyGuidBuffer

An array of keyboard layout GUID instances returned.

Description

This routine retrieves an array of GUID values for each keyboard layout that was previously registered in the system.

Status Codes Returned

EFI_SUCCESS	<i>KeyGuidBuffer</i> was updated successfully.
EFI_BUFFER_TOO_SMALL	The <i>KeyGuidBufferLength</i> parameter indicates that <i>KeyGuidBuffer</i> is too small to support the number of GUIDs. <i>KeyGuidBufferLength</i> is updated with a value that will enable the data to fit.

EFI_HII_DATABASE_PROTOCOL.GetKeyboardLayout()

Summary

Retrieves the requested keyboard layout.

Prototype

```

typedef
EFI_STATUS
(EFIAPI *EFI_HII_GET_KEYBOARD_LAYOUT) (
    IN      EFI_HII_DATABASE_PROTOCOL  *This,
    IN      EFI_GUID                   *KeyGuid,
    OUT     EFI_HII_KEYBOARD_LAYOUT    *KeyboardLayout
);

```

Parameters

This

A pointer to the **EFI_HII_PROTOCOL** instance.

KeyGuid

A pointer to the unique ID associated with a given keyboard layout. If *KeyGuid* is NULL then the current layout will be retrieved.

KeyboardLayout

A pointer to a buffer containing the retrieved keyboard layout. below.

Description

This routine retrieves the requested keyboard layout. The layout is a physical description of the keys on a keyboard and the character(s) that are associated with a particular set of key strokes.

Related Definitions

```

//*****
// EFI_HII_KEYBOARD_PACK
//*****
typedef struct {
    EFI_HII_PACK_HEADER    Header;
    UINT16                 LayoutCount;
    EFI_HII_KEYBOARD_LAYOUT Layout[];
} EFI_HII_KEYBOARD_PACK;

```

Header

The general pack header which defines both the type of pack and the length of the entire pack.

LayoutCount

The number of keyboard layouts contained in the entire keyboard pack.

Layout

An array of *LayoutCount* number of keyboard layouts.

```

//*****
// EFI_HII_KEYBOARD_LAYOUT
//*****
typedef struct {
    UINT16          LayoutLength;
    EFI_GUID        Guid;
    RELOFST        LayoutDescriptorString;
    UINT8          DescriptorCount;
    EFI_KEY_DESCRIPTOR Descriptors[];
} EFI_HII_KEYBOARD_LAYOUT;

```

LayoutLength

The length of the current keyboard layout.

Guid

The unique ID associated with this keyboard layout.

LayoutDescriptorString

An offset location (0 is the beginning of the **EFI_KEYBOARD_LAYOUT** instance) of the string which describes this keyboard layout. The data that is being referenced is in **EFI_DESCRIPTION_STRING_BUNDLE** format.

DescriptorCount

The number of Descriptor entries in this layout.

Descriptors

An array of key descriptors.

```

//*****
// EFI_DESCRIPTOR_STRING
//*****
typedef struct {
    CHAR16  Language[3];
    CHAR16  Space;
    CHAR16  DescriptionString[];
} EFI_DESCRIPTOR_STRING;

```

Language

The language to associate with *DescriptionString*.

Space

A space (U-0x0020) character to force as a separator between the *Language* field and the formal description string.

DescriptionString

A null-terminated description string.

```

//*****
// EFI_DESCRIPTOR_STRING_BUNDLE
//
// Example: 2ENG English Keyboard<null>SPA Keyboard en ingles<null>
//          <null> = U-0000
//*****
typedef struct {
    UINT16                DescriptionCount;
    EFI_DESCRIPTION_STRING DescriptionString[];
} EFI_DESCRIPTOR_STRING_BUNDLE;

```

DescriptionCount

The number of description strings.

DescriptionString

An array of language-specific description strings.

```

//*****
// EFI_KEY_DESCRIPTOR
//*****
typedef struct {
    EFI_KEY                Key;
    CHAR16                 Unicode;
    CHAR16                 ShiftedUnicode;
    CHAR16                 AltGrUnicode;
    CHAR16                 ShiftedAltGrUnicode;
    UINT16                 Modifier;
} EFI_KEY_DESCRIPTOR;

```

Key

Used to describe a physical key on a keyboard. Type **EFI_KEY** is defined below.

Unicode

Unicode value for the *Key*.

ShiftedUnicode

Unicode value for the key with the shift key being held down.

AltGrUnicode

Unicode value for the key with the Alt-GR being held down.

ShiftedAltGrUnicode

Unicode value for the key with the Alt-GR and shift keys being held down.

Modifier

Modifier keys are defined to allow for special functionality that is not necessarily accomplished by a printable character. Many of these modifier keys are flags to toggle certain state bits on and off inside of a keyboard driver. Values for *Modifier* are defined below.

```

//*****
// EFI_KEY
//*****
typedef enum {
    EfiKeyLCtrl, EfiKeyA0, EfiKeyLAlt, EfiKeySpaceBar,
    EfiKeyA2, EfiKeyA3, EfiKeyA4, EfiKeyRCtrl, EfiKeyLeftArrow,
    EfiKeyDownArrow, EfiKeyRightArrow, EfiKeyZero,
    EfiKeyPeriod, EfiKeyEnter, EfiKeyLShift, EfiKeyB0,
    EfiKeyB1, EfiKeyB2, EfiKeyB3, EfiKeyB4, EfiKeyB5, EfiKeyB6,
    EfiKeyB7, EfiKeyB8, EfiKeyB9, EfiKeyB10, EfiKeyRshift,
    EfiKeyUpArrow, EfiKeyOne, EfiKeyTwo, EfiKeyThree,
    EfiKeyCapsLock, EfiKeyC1, EfiKeyC2, EfiKeyC3, EfiKeyC4,
    EfiKeyC5, EfiKeyC6, EfiKeyC7, EfiKeyC8, EfiKeyC9,
    EfiKeyC10, EfiKeyC11, EfiKeyC12, EfiKeyFour, EfiKeyFive,
    EfiKeySix, EfiKeyPlus, EfiKeyTab, EfiKeyD1, EfiKeyD2,
    EfiKeyD3, EfiKeyD4, EfiKeyD5, EfiKeyD6, EfiKeyD7, EfiKeyD8,
    EfiKeyD9, EfiKeyD10, EfiKeyD11, EfiKeyD12, EfiKeyD13,
    EfiKeyDel, EfiKeyEnd, EfiKeyPgDn, EfiKeySeven, EfiKeyEight,
    EfiKeyNine, EfiKeyE0, EfiKeyE1, EfiKeyE2, EfiKeyE3,
    EfiKeyE4, EfiKeyE5, EfiKeyE6, EfiKeyE7, EfiKeyE8, EfiKeyE9,
    EfiKeyE10, EfiKeyE11, EfiKeyE12, EfiKeyBackSpace,
    EfiKeyIns, EfiKeyHome, EfiKeyPgUp, EfiKeyNLck, EfiKeySlash,
    EfiKeyAsterisk, EfiKeyMinus, EfiKeyEsc, EfiKeyF1, EfiKeyF2,
    EfiKeyF3, EfiKeyF4, EfiKeyF5, EfiKeyF6, EfiKeyF7, EfiKeyF8,
    EfiKeyF9, EfiKeyF10, EfiKeyF11, EfiKeyF12, EfiKeyPrint,
    EfiKeySLck, EfiKeyPause
} EFI_KEY;

```

See the figure below for which key corresponds to the values in the enumeration above. For example, **EfiKeyLCtrl** corresponds to the left control key in the lower-left corner of the keyboard, **EfiKeyFour** corresponds to the 4 key on the numeric keypad, and **EfiKeySLck** corresponds to the Scroll Lock key in the upper-right corner of the keyboard.

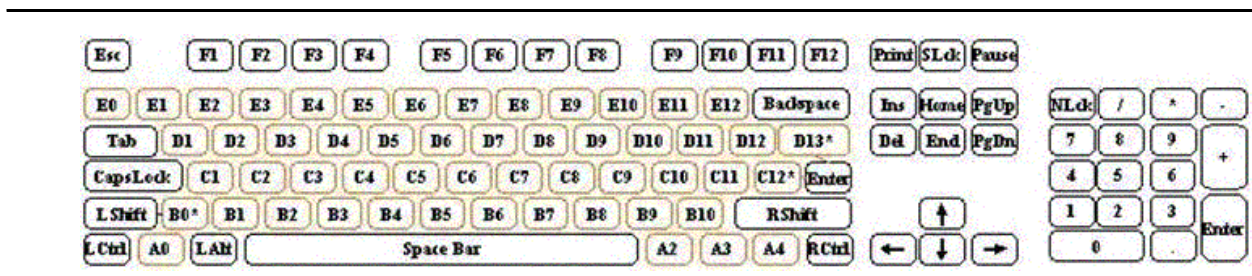


Figure 98. Keyboard Layout

```

//*****
// Modifier values
//*****
#define EFI_NULL_MODIFIER                0x0000
#define EFI_LEFT_CONTROL_MODIFIER        0x0001
#define EFI_RIGHT_CONTROL_MODIFIER       0x0002
#define EFI_LEFT_ALT_MODIFIER            0x0003
#define EFI_RIGHT_ALT_MODIFIER           0x0004
#define EFI_ALT_GR_MODIFIER              0x0005
#define EFI_INSERT_MODIFIER              0x0006
#define EFI_DELETE_MODIFIER              0x0007
#define EFI_PAGE_DOWN_MODIFIER           0x0008
#define EFI_PAGE_UP_MODIFIER             0x0009
#define EFI_HOME_MODIFIER                0x000A
#define EFI_END_MODIFIER                 0x000B
#define EFI_LEFT_SHIFT_MODIFIER          0x000C
#define EFI_RIGHT_SHIFT_MODIFIER         0x000D
#define EFI_CAPS_LOCK_MODIFIER           0x000E
#define EFI_NUM_LOCK_MODIFIER            0x000F
#define EFI_LEFT_ARROW_MODIFIER          0x0010
#define EFI_RIGHT_ARROW_MODIFIER         0x0011
#define EFI_DOWN_ARROW_MODIFIER          0x0012
#define EFI_UP_ARROW_MODIFIER            0x0013
#define EFI_NS_KEY_MODIFIER              0x0014
#define EFI_NS_KEY_DEPENDENCY_MODIFIER   0x0015
#define EFI_FUNCTION_KEY_ONE_MODIFIER     0x0016
#define EFI_FUNCTION_KEY_TWO_MODIFIER     0x0017
#define EFI_FUNCTION_KEY_THREE_MODIFIER   0x0018
#define EFI_FUNCTION_KEY_FOUR_MODIFIER    0x0019
#define EFI_FUNCTION_KEY_FIVE_MODIFIER    0x001A
#define EFI_FUNCTION_KEY_SIX_MODIFIER     0x001B
#define EFI_FUNCTION_KEY_SEVEN_MODIFIER   0x001C
#define EFI_FUNCTION_KEY_EIGHT_MODIFIER   0x001D
#define EFI_FUNCTION_KEY_NINE_MODIFIER    0x001E
#define EFI_FUNCTION_KEY_TEN_MODIFIER     0x001F
#define EFI_FUNCTION_KEY_ELEVEN_MODIFIER  0x0020
#define EFI_FUNCTION_KEY_TWELVE_MODIFIER  0x0021
//
// Keys that have multiple control functions based on modifier
// settings are handled in the keyboard driver implementation.
// For instance PRINT_KEY might have a modifier held down and
// is still a nonprinting character, but might have an alternate
// control function like SYSREQUEST
//
#define EFI_PRINT_MODIFIER                0x0022
#define EFI_SYS_REQUEST_MODIFIER          0x0023
#define EFI_SCROLL_LOCK_MODIFIER          0x0024

```



```
#define EFI_PAUSE_MODIFIER          0x0025
#define EFI_BREAK_MODIFIER         0x0026
```

Status Codes Returned

EFI_SUCCESS	The keyboard layout was retrieved successfully.
EFI_NOT_FOUND	The requested keyboard layout was not found.

EFI_HII_DATABASE_PROTOCOL.SetKeyboardLayout()

Summary

Sets the currently active keyboard layout.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_SET_KEYBOARD_LAYOUT) (
    IN      EFI_HII_DATABASE_PROTOCOL  *This,
    IN      EFI_GUID                   *KeyGuid
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

KeyGuid

A pointer to the unique ID associated with a given keyboard layout.

Description

This routine sets the default keyboard layout to the one referenced by *KeyGuid*. When this routine is called, an event will be signaled of the **EFI_HII_SET_KEYBOARD_LAYOUT_EVENT_GUID** group type. This is so that agents which are sensitive to the current keyboard layout being changed can be notified of this change.

Related Definitions

GUID

```
#define EFI_HII_SET_KEYBOARD_LAYOUT_EVENT_GUID \
    { 0x14982a4f, 0xb0ed, 0x45b8, 0xa8, 0x11, 0x5a, 0x7a, \
      0x9b, 0xc2, 0x32, 0xdf }
```

Status Codes Returned

EFI_SUCCESS	The current keyboard layout was successfully set.
EFI_NOT_FOUND	The referenced keyboard layout was not found, so action was taken.

EFI_HII_DATABASE_PROTOCOL.GetPackageListHandle()

Summary

Return the EFI handle associated with a package list.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_GET_PACK_HANDLE) (
    IN      EFI_HII_DATABASE_PROTOCOL      *This,
    IN      EFI_HII_HANDLE                 PackageListHandle,
    OUT     EFI_HANDLE                     *DriverHandle
);
```

Parameters

This

A pointer to the **EFI_HII_DATABASE_PROTOCOL** instance.

PackageListHandle

An **EFI_HII_HANDLE** that corresponds to the desired package list in the HII database.

DriverHandle

On return, contains the **EFI_HANDLE** which was registered with the package list in **NewPackageList()**.

Status Codes Returned

EFI_SUCCESS	The <i>DriverHandle</i> was returned successfully.
EFI_INVALID_PARAMETER	The <i>PackageListHandle</i> was not valid.

28.4.1 Database Structures

EFI_HII_DATABASE_NOTIFY

Summary

Handle a registered notification for a package change to the database.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_DATABASE_NOTIFY) (
    IN UINT8                               PackageType,
    IN CONST EFI_GUID                       *PackageGuid,
    IN CONST EFI_HII_PACKAGE_HEADER *Package,
    IN EFI_HII_HANDLE                       Handle,
    IN EFI_HII_DATABASE_NOTIFY_TYPE NotifyType
);
```

Parameters

PackageType

Package type of the notification.

PackageGuid

If *PackageType* is **EFI_HII_PACKAGE_TYPE_GUID**, then this is the pointer to the GUID from the *Guid* field of **EFI_HII_PACKAGE_GUID_HEADER**. Otherwise, it must be NULL.

Package

Points to the package referred to by the notification

Handle

The handle of the package list which contains the specified package.

NotifyType

The type of change concerning the database. See [EFI HII DATABASE NOTIFY TYPE](#).

Description

Functions which are registered to receive notification of database events have this prototype. The actual event is encoded in *NotifyType*. The following table describes how *PackageType*, *PackageGuid*, *Handle*, and *Package* are used for each of the notification types.

Notification Type	Parameter Description
NEW_PACK	<i>PackageType</i> and <i>PackageGuid</i> are the type of the new package. <i>Package</i> points to the new package. <i>Handle</i> is the handle of the package list which is being added to the database.
REMOVE_PACK	<i>PackageType</i> and <i>PackageGuid</i> are the type of the package which is being removed. <i>Package</i> points to the package being removed. <i>Handle</i> is the package list from which the package is being removed.

EXPORT_PACK	<i>PackageType</i> and <i>PackageGuid</i> are the type of the package being exported. <i>Package</i> points to the existing package in the database. <i>Handle</i> is the package list being exported.
ADD_PACK	<i>PackageType</i> and <i>PackageGuid</i> are the type of the package being added. <i>Package</i> points to the package being added. <i>Handle</i> is the package list to which the package is being added.

EFI_HII_DATABASE_NOTIFY_TYPE

```
typedef UINTN EFI_HII_DATABASE_NOTIFY_TYPE;
```

```
#define EFI_HII_DATABASE_NOTIFY_NEW_PACK      0x00000001
#define EFI_HII_DATABASE_NOTIFY_REMOVE_PACK  0x00000002
#define EFI_HII_DATABASE_NOTIFY_EXPORT_PACK  0x00000004
#define EFI_HII_DATABASE_NOTIFY_ADD_PACK     0x00000008
```


HII Configuration Processing and Browser Protocol

29.1 Introduction

This section describes the data and APIs used to manage the system's configuration: the actual data that describes the knobs and settings.

29.1.1 Common Configuration Data Format

The configuration data is stored as UNICODE name / value pairs. As in e.g. HTML, the name and value are separated by '=' and the pairs are separated one from the next by '&'. The configuration data structures are thus variable length UNICODE (UCS-2) strings.

Certain names and values have limitations on their syntax to manage routing and to enable extended support for common storage mechanisms.

29.1.2 Data Flow

There is a two-way flow through the hierarchy of drivers and protocols that parallels the flow in other parts of HII. Initially, the flow is from the drivers up to the HII database and on to configuration applications. When changes to configuration are accepted, the flow reverses itself, going from the configuration applications through the HII database protocols back to the drivers through separate protocols.

The flow from driver up consists of the current and alternative (default) configurations. The flow down from the configuration applications consists of changed configurations.

The protocol managed by the HII Database is known as the EFI HII Configuration Routing Protocol, while the one presented by the drivers themselves is known as the EFI HII Configuration Access Protocol. The HII Configuration Routing Protocol is the only one that outside callers should invoke.

29.2 Configuration Strings

The configuration strings follow the same general format as HTTP argument strings, which is to say '&' separated name / value pairs. The name and value are separated by '='. The strings are a subset of full HTML argument strings and do not require quoting, the '%' character sequences used to insert spaces, ampersands, equal signs, and the like into HTTP argument strings.

29.2.1 String Syntax

Assumptions are typical for BNF with the following extensions

Characters in single quotes, e.g. 'a', indicate terminals.

Square brackets immediately followed by a number *n* indicate that the contents are to be repeated *n* times, so [‘a’]4 would be “aaaa”.

An italicized non-terminal, e. g. *<All Printable ASCII Characters>* is used to indicate a set of terminals whose definition is outside the scope of this document. (Rest assured, Tim, this example is not used in the actual syntax.)

The syntax for configuration strings is as follows.

Basic forms:

```

<Dec19> ::= '1' | '2' | ... | '9'
<DecCh> ::= '0' | <Dec19>
<HexAf> ::= 'a' | 'b' | 'c' | 'd' | 'e' | 'f'
<Hex1f> ::= <Dec19> | <HexAf>
<HexCh> ::= <DecCh> | <HexAf>
<Number> ::= <HexCh>+
<Alpha> ::= 'a' | ... | 'z' | 'A' | ... | 'Z'
    
```

Types

```

<Guid> ::= <HexCh>32
<LabelStart> ::= <Alpha> | "_"
<LabelBody> ::= <LabelStart> | <DecCh>
<Name> ::= <LabelStart> [<LabelBody>]*
<Char> ::= <HexCh>4
<String> ::= [<Char>]+
<AltCfgId> ::= <HexCh>4
    
```

Routing elements

```

<GuidHdr> ::= 'GUID=' <Guid>
<NameHdr> ::= 'NAME=' <String>
<PathHdr> ::= 'PATH=' <UEFI binary Device Path represented as hex number>
<DescHdr> ::= 'ALTCFG=' <AltCfgId>
<ConfigHdr> ::= <GuidHdr>' '<NameHdr>' '<PathHdr>
<AltConfigHdr> ::= <ConfigHdr> '<DescHdr>
    
```

Body elements

```

<ConfigBody> ::= <ConfigElement>*
<ConfigElement> ::= '<BlockConfig> | '<NvConfig>
<BlockName> ::= 'OFFSET=' <Number>' &WIDTH=' <Number>
<BlockConfig> ::= <BlockName>' &VALUE=' <Number>
<RequestElement> ::= '<BlockName> | '<Label>
<NvConfig> ::= <Label>'=' <String> | <Label>'=' <Number>
    
```

Configuration strings


```

<ConfigRequest> ::= <ConfigHdr><ConfigRequest>*
<MultiConfigRequest> ::= <ConfigRequest>['&' <ConfigRequest>]*
<ConfigResp> ::= <ConfigHdr><ConfigBody>
<AltResp> ::= <AltConfigHdr><ConfigBody>
<ConfigAltResp> ::= <ConfigResp> ['&' <AltResp>]*
<MultiConfigAltResp> ::= <ConfigAltResp> ['&' <ConfigAltResp>]*
<MultiConfigResp> ::= <ConfigResp> ['&'<ConfigResp>]*

```

Notes:

The syntax for a **<Number>** is the C “%x” format, which is to say lower-case hexadecimal numbers except that leading zeroes are accepted.

The syntax for a **<Label>** is the C label (e.g. Variable) syntax.

The **<ConfigHdr>** provides routing information. The name field is required even if non-block storage is targeted. In these cases, it may be used as a way to distinguish like storages from one another when a driver is being used

The **<BlockName>** provides addressing information for managing block (e.g. UEFI Variable) storage. The first number provides the byte offset into the block while the second provides the length of bytes.

The **<PathHdr>** presents a hex encoding of a UEFI device path. This is not the printable path since the printable path is optional in UEFI and to enable simpler comparisons. The data is encoded as UNICODE %02x bytes in the same order as the device path resides in RAM memory.

The **<ConfigRequestString>** provides a mechanism to request the current configuration for one or more elements.

The **<AltCfgId>** is the identifier of a configuration declared in the corresponding IFR.

The name ‘GUID’ is also used to separate **<ConfigString>** or **<ConfigRequestString>** elements in the equivalent **Multi** version. That is:

```
GUID=...&NAME=...&...&fred=12&GUID=...&NAME=...&...&goyle=11
```

Indicates two **<ConfigStrings>**, with one ending with **fred=12**.

The following are reserved **<name>**s and cannot be used as names in a **<ConfigElement>**:

```

GUID
NAME
PATH
ALTCFG
OFFSET
WIDTH
VALUE

```

29.2.2 String Types

There are six string types. As can be seen from the BNF, the syntax of all is quite similar. The first three are used in communications between drivers and HII. The last three are used for analogous communication between external applications and HII.

<ConfigRequest>: This string is used by HII to request the current and any alternative configurations from a driver. It consists of routing information and only ampersand separated names.

<ConfigAltResp>: A string in this format is returned by the driver in response to a request to fill in a **<ConfigRequest>** string. The string consists of the current configuration followed by possibly several alternative configurations. The alternative configurations have the *ALTCFG* name / value pair in addition to the usual *GUID*, *NAME*, and *PATH* entries in the routing prefix. The *ALTCFG* value is a string token which is used to describe the alternative configuration.

<ConfigResp>: A string in this format is handed by the HII to the driver to cause the driver to change its configuration. It consists of routing information and name / value pairs which correspond to the questions in the driver's IFR. Only **<ConfigResp>** strings which refer to a driver in question may be handed to that driver. The driver shall reject all others.

<MultiConfigRequest>: A string in this format is handed to HII by an external application in order to request the current and alternate configurations of the system's drivers. The format of this string is a series of **<ConfigRequest>** strings separated by ampersands. The HII's job is to separate the requests and hand them off to the appropriate drivers (as indicated by the routing headers).

<MultiConfigAltResp>: A string in this format is handed back to an external application which has requested the current and alternate configurations of the system's drivers. The format of this string is a series of **<ConfigAltResp>** strings separated by ampersands. The HII creates this string by concatenating the current and alternate configuration strings provided by each driver.

<MultiConfigResp>: A string in this format is handed to the HII in order to update the system's configuration. Analogous to the other "Multi" string formats, its syntax is a series of ampersand separated **<ConfigResp>** strings. Upon receipt, the HII routes the **<ConfigResp>** strings to the corresponding drivers.

29.3 EFI HII Configuration Routing Protocol

EFI_HII_CONFIG_ROUTING_PROTOCOL

Summary

The EFI HII Configuration Routing Protocol manages the movement of configuration data from drivers to configuration applications. It then serves as the single point to receive configuration information from configuration applications, routing the results to the appropriate drivers.

GUID

```
#define EFI_HII_CONFIG_ROUTING_PROTOCOL_GUID \
    { 0x587e72d7, 0xcc50, 0x4f79, 0x82, 0x09, 0xca, 0x29, \
      0x1f, 0xc1, 0xa1, 0x0f }
```

Protocol Interface Structure

```
typedef struct {
    EFI_HII_EXTRACT_CONFIG    ExtractConfig;
    EFI_HII_EXPORT_CONFIG     ExportConfig;
    EFI_HII_ROUTE_CONFIG      RouteConfig;
}
```

```
EFI_HII_BLOCK_TO_CONFIG    BlockToConfig;  
EFI_HII_CONFIG_TO_BLOCK    ConfigToBlock;  
} EFI_HII_CONFIG_ROUTING_PROTOCOL;
```

Related Definitions

None

Parameters

Description

This protocol defines the configuration routing interfaces between external applications and the HII. There may only be one instance of this protocol in the system.

EFI_HII_CONFIG_ROUTING_PROTOCOL.ExtractConfig()

Summary

This function processes the results of processing forms and routes it to the appropriate handlers or storage.

Prototype

```
EFI_STATUS
(EFI_API * EFI_HII_EXTRACT_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This,
    IN CONST STRING      *Request,
    OUT STRING           *Progress,
    OUT STRING           *Results
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ROUTING_PROTOCOL** instance.

Request

A null-terminated Unicode string in **<MultiConfigRequest>** format.

Progress

On return, points to a character in the Request string. Points to the string's null terminator if request was successful. Points to the most recent '&' before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) if the request was not successful

Results

Null-terminated Unicode string in **<MultiConfigAltResp>** format which has all values filled in for the names in the Request string. String to be allocated by the called function.

Discussion

This function allows the caller to request the current configuration for one or more named elements from one or more drivers. The resulting string is in the standard HII configuration string format. If Successful **Results** contains an equivalent string with "=" and the values associated with all names added in.

The expected implementation is for each **<ConfigRequest>** substring in the Request, call the HII Configuration Routing Protocol **ExtractProtocol** function for the driver corresponding to the **<ConfigHdr>** at the start of the **<ConfigRequest>** substring. The request fails if no driver matches the **<ConfigRequest>** substring.

Note: Alternative configuration strings may also be appended to the end of the current configuration string. If they are, they must appear after the current configuration. They must contain the same routing (GUID, NAME, PATH) as the current configuration string. They must have an additional description indicating the type of alternative configuration the string represents,

“**ALTCFG=<StringToken>**”. That **<StringToken>** (when converted from Hex UNICODE to binary) is a reference to a string in the associated string pack.

As an example, assume that the Request string is:

GUID=...&NAME=00480050&PATH=...&Fred&George&Ron&Neville

A result might be:

GUID=...&NAME=00480050&PATH=...&Fred=16&George=16&Ron=12&Neville=11&

GUID=...&NAME=00480050&PATH=...&ALTCFG=0037&Fred=12&Neville=7

Status Codes Returned

EFI_SUCCESS	The <i>Results</i> string is filled with the values corresponding to all requested names.
EFI_OUT_OF_MEMORY	Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.
EFI_INVALID_PARAMETER	For example, passing in a NULL for the <i>Request</i> parameter would result in this type of error. The <i>Progress</i> parameter is set to NULL.
EFI_NOT_FOUND	Routing data doesn't match any known driver. Progress set to the "G" in "GUID" of the routing header that doesn't match. Note: There is no requirement that all routing data be validated before any configuration extraction.
EFI_INVALID_PARAMETER	Illegal syntax. Progress set to most recent & before the error or the beginning of the string.
EFI_INVALID_PARAMETER	Unknown name. Progress points to the & before the name in question.

EFI_HII_CONFIG_ROUTING_PROTOCOL.ExportConfig()

Summary

This function processes the results of processing forms and routes it to the appropriate handlers or storage.

Prototype

```
EFI_STATUS
(EFI_API * EFI_HII_EXPORT_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This,
    OUT STRING                               *Results
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ROUTING_PROTOCOL** instance.

Results

A null-terminated Unicode string in **<MultiConfigAltResp>** format which has all values filled in for the names in the Request string. String to be allocated by this function. De-allocation is up to the caller.

Discussion

This function allows the caller to request the current configuration for all of the current HII database. The results include both the current and alternate configurations as described in **ExtractConfig()** above.

Implementation note: This call has deceptively few inputs but the implementation is likely to be somewhat complex. The requirement is to scan all IFR in the HII database to determine the list of names and then request the configuration using the corresponding drivers’

EFI_HII_CONFIG_ACCESS_PROTOCOL.ExtractConfig() interfaces below.

Status Codes Returned

EFI_SUCCESS	The <i>Results</i> string is filled with the values corresponding to all requested names.
EFI_OUT_OF_MEMORY	Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.
EFI_INVALID_PARAMETERS	For example, passing in a NULL for the <i>Results</i> parameter would result in this type of error.

EFI_HII_CONFIG_ROUTING_PROTOCOL.RouteConfig()

Summary

This function processes the results of processing forms and routes it to the appropriate handlers or storage.

Prototype

```
EFI_STATUS
(EFI_API * EFI_HII_ROUTE_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This,
    IN CONST STRING Configuration,
    OUT STRING *Progress
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ROUTING_PROTOCOL** instance.

Configuration

A null-terminated Unicode string in **<MultiConfigResp>** format.

Progress

A pointer to a string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Discussion

This function routes the results of processing forms to the appropriate targets. It scans for **<ConfigHdr>** within the string and passes the header and subsequent body to the driver whose location is described in the **<ConfigHdr>**. Many **<ConfigHdr>**s may appear as a single request.

The expected implementation is to hand off the various **<ConfigResp>** substrings to the Configuration Access Protocol **RouteConfig** routine corresponding to the driver whose routing information is defined by the **<ConfigHdr>** in turn.

Status Codes Returned

EFI_SUCCESS	The results have been distributed or are awaiting distribution.
EFI_OUT_OF_MEMORY	Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.
EFI_INVALID_PARAMETERS	Passing in a NULL for the <i>Results</i> parameter would result in this type of error.
EFI_NOT_FOUND	Target for the specified routing data was not found

EFI_HII_CONFIG_ROUTING_PROTOCOL.BlockToConfig()

Summary

This helper function is to be called by drivers to map configuration data stored in byte array (“block”) formats such as UEFI Variables into current configuration strings.

Prototype

```

EFI_STATUS
(EFI_API * EFI_HII_BLOCK_TO_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This,
    IN CONST STRING                          ConfigRequest,
    IN CONST UINT8                            *Block,
    IN CONST UINTN                            BlockSize,
    OUT STRING                                **Config,
    OUT STRING                                *Progress
);

```

Parameters

This

Points to the **EFI_HII_CONFIG_ROUTING_PROTOCOL** instance.

ConfigRequest

A null-terminated Unicode string in **<ConfigRequest>** format.

Block

Array of bytes defining the block’s configuration.

BlockSize

Length in bytes of **Block**.

Config

Filled-in configuration string. String allocated by the function. Returned only if call is successful.

Progress

A pointer to a string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Discussion

This function extracts the current configuration from a block of bytes. To do so, it requires that the *ConfigRequest* string consists of a list of **<BlockName>** formatted names. It uses the offset in the name to determine the index into the Block to start the extraction and the width of each name to determine the number of bytes to extract. These are mapped to a UNICODE value using the equivalent of the C “%x” format (with optional leading spaces).

The call fails if, for any (offset, width) pair in *ConfigRequest*, $\text{offset} + \text{width} \geq \text{BlockSize}$.

Status Codes Returned

EFI_SUCCESS	The request succeeded. Progress points to the null terminator at the end of the <i>ConfigRequest</i> string.
EFI_OUT_OF_MEMORY	Not enough memory to allocate <i>Config</i> . Progress points to the first character of <i>ConfigRequest</i> .
EFI_INVALID_PARAMETERS	Passing in a NULL for the <i>ConfigRequest</i> or Block parameter would result in this type of error. Progress points to the first character of <i>ConfigRequest</i> .
EFI_NOT_FOUND	Target for the specified routing data was not found. <i>Progress</i> points to the “G” in “GUID” of the errant routing data.
EFI_DEVICE_ERROR	Block not large enough. <i>Progress</i> undefined.
EFI_INVALID_PARAMETER	Encountered non <BlockName> formatted string. Block is left updated and Progress points at the ‘&’ preceding the first non-<BlockName>.

EFI_HII_CONFIG_ROUTING_PROTOCOL.ConfigToBlock()

Summary

This helper function is to be called by drivers to map configuration strings to configurations stored in byte array (“block”) formats such as UEFI Variables.

Prototype

```
EFI_STATUS
(EFI_API * EFI_HII_CONFIG_TO_BLOCK ) (
    IN      CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This,
    IN      CONST STRING                          *ConfigResp,
    IN      CONST UINT8                           *Block,
    IN OUT  UINTN                                 *BlockSize,
    OUT     STRING                                *Progress
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ROUTING_PROTOCOL** instance.

ConfigResp

A null-terminated Unicode string in **<ConfigResp>** format.

CurrentBlock

A possibly null array of bytes representing the current block. Only bytes referenced in the *ConfigResp* string in the block are modified. If this parameter is null or if the **BlockLength* parameter is (on input) shorter than required by the **Configuration** string, only the *BlockSize* parameter is updated and an appropriate status (see below) is returned.

BlockSize

The length of the *Block* in units of UINT8. On input, this is the size of the *Block*. On output, if successful, contains the index of the last modified byte in the *Block*.

Progress

On return, points to an element of the *ConfigResp* string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Discussion

This function maps a configuration containing a series of **<BlockConfig>** formatted name value pairs in *ConfigResp* into a *Block* so it may be stored in a linear mapped storage such as a UEFI Variable. If present, the function skips **GUID, NAME, and PATH** in **<ConfigResp>**. It stops when it finds a non-**<BlockConfig>** name / value pair (after skipping the routing header) or when it reaches the end of the string.

Example

Assume an existing block containing:

```
00 01 02 03 04 05
```

And the ConfigResp string is:

```
OFFSET=4&WIDTH=1&VALUE=7&OFFSET=0&WIDTH=2&VALUE=AA55
```

The results are

```
55 AA 02 07 04 05
```

Status Codes Returned

EFI_SUCCESS	The request succeeded. Progress points to the null terminator at the end of the <i>ConfigRequest</i> string.
EFI_OUT_OF_MEMORY	Not enough memory to allocate <i>Config</i> . Progress points to the first character of <i>ConfigRequest</i> .
EFI_INVALID_PARAMETER	Passing in a NULL for the <i>ConfigRequest</i> or <i>Block</i> parameter would result in this type of error. Progress points to the first character of <i>ConfigRequest</i> .
EFI_NOT_FOUND	Target for the specified routing data was not found. <i>Progress</i> points to the "G" in "GUID" of the errant routing data.
EFI_DEVICE_ERROR	Block not large enough. <i>Progress</i> undefined.
EFI_INVALID_PARAMETER	Encountered non <BlockName> formatted name / value pair. <i>Block</i> is left updated and <i>Progress</i> points at the '&' preceding the first non-<BlockName>.

29.4 EFI HII Configuration Access Protocol

EFI_HII_CONFIGURATION_ACCESS_PROTOCOL

Summary

The EFI HII results processing protocol invokes this type of protocol when it needs to forward results to PCOL-based handler. This protocol is published by drivers requesting configuration from HII. It may only be invoked by HII.

GUID

```
// {330D4706-F2A0-4e4f-A369-B66FA8D54385}
#define EFI_HII_CONFIGURATION_ACCESS_PROTOCOL_GUID \
{ 0x330d4706, 0xf2a0, 0x4e4f, 0xa3, 0x69, 0xb6, 0x6f, \
  0xa8, 0xd5, 0x43, 0x85 }
```

Protocol Interface Structure

```
typedef struct {  
    EFI_HII_SET_RESULTS      ExtractConfig;  
    EFI_HII_GET_RESULTS     RouteConfig;  
    EFI_HII_CALLBACK        Callback;  
} EFI_HII_CONFIG_ACCESS_PROTOCOL;
```

Related Definitions

None

Parameters

ExtractConfig

This function breaks apart the UNICODE request strings routing them to the appropriate drivers. This function is analogous to the similarly named function in the HII Routing Protocol.

RouteConfig

This function breaks apart the UNICODE results strings and returns configuration information as specified by the request.

Callback

This function is called from the configuration browser to communicate certain activities that were initiated by a user.

Description

This protocol provides a callable interface between the HII and drivers. Only drivers which provide IFR data to HII are required to publish this protocol.

EFI_HII_CONFIG_ACCESS_PROTOCOL.ExtractConfig()

Summary

This function processes the results of processing forms and routes it to the appropriate handlers or storage.

Prototype

```
EFI_STATUS
(EFI_API * EFI_HII_EXTRACT_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ACCESS_PROTOCOL *This,
    IN CONST STRING                         *Request,
    OUT STRING                              *Progress,
    OUT STRING                              *Results
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ACCESS_PROTOCOL**.

Request

A null-terminated Unicode string in **<ConfigRequest>** format. Note that this includes the routing information as well as the configurable name / value pairs. It is invalid for this string to be in **<MultiConfigRequest>** format.

Progress

On return, points to a character in the *Request* string. Points to the string's null terminator if request was successful. Points to the most recent '&' before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) if the request was not successful

Results

A null-terminated Unicode string in **<ConfigAltResp>** format which has all values filled in for the names in the Request string. String to be allocated by the called function.

Discussion

This function allows the caller to request the current configuration for one or more named elements. The resulting string is in **<ConfigAltResp>** format.

Any and all alternative configuration strings shall also be appended to the end of the current configuration string. If they are, they must appear after the current configuration. They must contain the same routing (GUID, NAME, PATH) as the current configuration string. They must have an additional description indicating the type of alternative configuration the string represents, "**ALTCFG=<StringToken>**". That **<StringToken>** (when converted from Hex UNICODE to binary) is a reference to a string in the associated string pack.

As an example, assume that the Request string is:

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GUID=...&NAME=00480050&PATH=...&Fred&George&Ron&Neville

A result might be:

GUID=...&NAME=00480050&PATH=...&Fred=16&George=16&Ron=12&Neville=11&

GUID=...&NAME=00480050&PATH=...&ALTCFG=0037&Fred=12&Neville=7

Status Codes Returned

EFI_SUCCESS	The <i>Results</i> string is filled with the values corresponding to all requested names.
EFI_OUT_OF_MEMORY	Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.
EFI_INVALID_PARAMETER	For example, passing in a NULL for the <i>Request</i> parameter would result in this type of error. In this case, the <i>Progress</i> parameter would be set to NULL.
EFI_NOT_FOUND	Routing data doesn't match any known driver. Progress set to the first character in the routing header. Note: There is no requirement that the driver validate the routing data. It must skip the <ConfigHdr> in order to process the names.
EFI_INVALID_PARAMETER	Illegal syntax. Progress set to most recent & before the error or the beginning of the string.
EFI_INVALID_PARAMETER	Unknown name. <i>Progress</i> points to the & before the name in question.

EFI_HII_CONFIG_ACCESS_PROTOCOL.RouteConfig()

Summary

This function processes the results of changes in configuration for the driver that published this protocol.

Prototype

```
EFI_STATUS
(EFI_API * EFI_HII_ROUTE_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ACCESS_PROTOCOL *This,
    IN CONST STRING                        Configuration,
    OUT STRING                             *Progress
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ACCESS_PROTOCOL**.

Configuration

A null-terminated Unicode string in **<ConfigString>** format.

Progress

a pointer to a string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Discussion

This function applies changes in a driver’s configuration. Input is a *Configuration*, which has the routing data for this driver followed by name / value configuration pairs. The driver must apply those pairs to its configurable storage. If the driver’s configuration is stored in a linear block of data and the driver’s name / value pairs are in **<BlockConfig>** format, it may use the **ConfigToBlock** helper function (above) to simplify the job.

Status Codes Returned

EFI_SUCCESS	The results have been distributed or are awaiting distribution.
EFI_OUT_OF_MEMORY	Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.
EFI_INVALID_PARAMETERS	Passing in a NULL for the <i>Results</i> parameter would result in this type of error.
EFI_NOT_FOUND	Target for the specified routing data was not found

EFI_HII_CONFIG_ACCESS_PROTOCOL.Callback()

Summary

This function is called to provide results data to the driver.

Prototype

```
typedef
EFI_STATUS
(EFI_API *EFI_FORM_CALLBACK) (
    IN CONST EFI_HII_CONFIG_ACCESS_PROTOCOL *This,
    IN UINT16                               KeyValue,
    IN CONST VOID                           *Data,
);
```

Parameters

This

Points to the **EFI_HII_CONFIG_ACCESS_PROTOCOL**.

KeyValue

A unique value which is sent to the original exporting driver so that it can identify the type of data to expect. The format of the data tends to vary based on the opcode that generated the callback.

Data

A pointer to the data being sent to the original exporting driver. The format of the data should be the same as that of the question invoking the callback and will be known to the recipient.

Description

This function is called to provide results data to the driver. This data consists of a unique key that is used to identify which data is either being passed back or being asked for.

Status Codes Returned

EFI_SUCCESS	The firmware has successfully stored the variable and its data as defined by the <i>Attributes</i> .
EFI_INVALID_PARAMETER	An invalid combination of <i>Attributes</i> bits was supplied, or the <i>DataSize</i> exceeds the maximum allowed.
EFI_OUT_OF_RESOURCES	Not enough storage is available to hold the variable and its data.
EFI_DEVICE_ERROR	The variable could not be saved due to a hardware failure.

29.5 Browser Protocol

29.5.1 Form Browser Protocol

The **EFI_FORM_BROWSER_PROTOCOL** is the interface to call for drivers to leverage the EFI configuration driver interface.

EFI_FORM_BROWSER_PROTOCOL

Summary

The **EFI_FORM_BROWSER_PROTOCOL** is the interface to the EFI configuration driver. This interface will allow the caller to direct the configuration driver to use either the HII database or use the passed-in packet of data.

GUID

```
#define EFI_FORM_BROWSER_PROTOCOL_GUID \
    { 0xe5a1333e, 0xe1b4, 0x4e55, 0xce, 0xeb, 0x35, 0xc3, \
      0xef, 0x13, 0x34, 0x43 }
```

Protocol Interface Structure

```
typedef struct _EFI_FORM_BROWSER_PROTOCOL {
    EFI_SEND_FORM                SendForm;
    EFI_BROWSER_CALLBACK         BrowserCallback;
} EFI_FORM_BROWSER_PROTOCOL;
```

Parameters

SendForm

Provides direction to the configuration driver whether to use the HII database or to use a passed-in set of data. This function also establishes a pointer to the calling driver's callback interface. See the **SendForm()** function description.

BrowserCallback

Routine used to expose internal configuration state of the browser. This is primarily used by callback handler routines which were called by the browser and in-turn need to get additional information from the browser itself. See the **BrowserCallback()** function description.

Description

This protocol is the interface to call for drivers to leverage the EFI configuration driver interface.

EFI_FORM_BROWSER_PROTOCOL.SendForm()

Summary

Provides direction to the configuration driver whether to use the HII database or a passed-in set of data. This function also establishes a pointer to the calling driver's callback interface.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_SEND_FORM) (
    IN CONST EFI_FORM_BROWSER_PROTOCOL *This,
    IN EFI_HII_HANDLE *Handle,
    IN UINTN HandleCount,
    IN BOOLEAN SingleUse,
    IN CONST EFI_SCREEN_DESCRIPTOR *ScreenDimensions, OPTIONAL
    OUT BOOLEAN *ResetRequired OPTIONAL
);
```

Parameters

This

A pointer to the **EFI_FORM_BROWSER_PROTOCOL** instance.

Handle

A pointer to an array of HII handles to display. This value should correspond to the value of the HII form package that is required to be displayed. Type **EFI_HII_HANDLE** is defined in **EFI_HII_PROTOCOL.NewPackageList()** in the Packages section.

HandleCount

The number of handles in the array specified by *Handle*.

SingleUse

If FALSE, the browser operates as a standard forms processor and exits only when explicitly requested by the user. If TRUE, the browser will return immediately after processing the first user-generated selection.

ScreenDimensions

Allows the browser to be called so that it occupies a portion of the physical screen instead of dynamically determining the screen dimensions. If the input values violate the platform policy then the dimensions will be dynamically adjusted to comply. Type **EFI_SCREEN_DESCRIPTOR** is defined in "Related Definitions" below.

ResetRequired

This **BOOLEAN** value will tell the caller if a reset is required based on the data that might have been changed. The *ResetRequired* parameter is primarily applicable for configuration applications, and is an optional parameter.

Description

This function is the primary interface to the internal forms-based browser. By calling this routine, one is directing the browser to use a variety of passed-in information or primarily use the HII database as the source of information.

Related Definitions

```

/*****
// EFI_SCREEN_DESCRIPTOR
/*****
typedef struct {
    UINTN      LeftColumn;
    UINTN      RightColumn;
    UINTN      TopRow;
    UINTN      BottomRow;
} EFI_SCREEN_DESCRIPTOR;
    
```

LeftColumn

Value that designates the text column where the browser window will begin from the left-hand side of the screen

RightColumn

Value that designates the text column where the browser window will end on the right-hand side of the screen.

TopRow

Value that designates the text row from the top of the screen where the browser window will start.

BottomRow

Value that designates the text row from the bottom of the screen where the browser window will end.

Status Codes Returned

EFI_SUCCESS	The function completed successfully
EFI_NOT_FOUND	The variable was not found.
EFI_BUFFER_TOO_SMALL	The <i>DataSize</i> is too small for the result. <i>DataSize</i> has been updated with the size needed to complete the request.
EFI_INVALID_PARAMETER	One of the parameters has an invalid value.
EFI_DEVICE_ERROR	The variable could not be saved due to a hardware failure.

EFI_FORM_BROWSER_PROTOCOL.BrowserCallback()

Summary

This function is called by a callback handler to retrieve uncommitted state data from the browser.

Prototype

```

EFI_STATUS
(EFI_API *EFI_BROWSER_CALLBACK ) (
    IN     CONST EFI_FORM_BROWSER_PROTOCOL *This,
    IN OUT UINTN                          *ResultsDataSize,
    IN OUT STRING                          ResultsData,
    IN     BOOLEAN                          RetrieveData,
    IN     CONST EFI_GUID                   *VariableGuid, OPTIONAL
    IN     CONST CHAR16                     *VariableName  OPTIONAL
);
    
```

Parameters

This

A pointer to the **EFI_FORM_BROWSER_PROTOCOL** instance.

ResultsDataSize

A pointer to the size of the buffer associated with ResultsData.

ResultsData

A string returned from an IFR browser or equivalent. The results string will have no routing information in them.

RetrieveData

A BOOLEAN field which allows an agent to retrieve (if RetrieveData = TRUE) data from the uncommitted browser state information or set (if RetrieveData = FALSE) data in the uncommitted browser state information.

VariableGuid

An optional field to indicate the target variable GUID name to use.

VariableName

An optional field to indicate the target human-readable variable name.

Discussion

This routine is called by a routine which was called by the browser. This routine called this service in the browser to retrieve or set certain uncommitted state information.

Status Codes Returned

EFI_SUCCESS	The results have been distributed or are awaiting distribution.
EFI_OUT_OF_RESOURCES	The <i>ResultsDataSize</i> specified was too small to contain the results data.

Appendix A

GUID and Time Formats

All EFI GUIDs (Globally Unique Identifiers) have the format described in RFC 4122 and comply with the referenced algorithms for generating GUIDs. It should also be noted that TimeLow, TimeMid, TimeHighAndVersion fields in the EFI are encoded as little endian. The following table defines the format of an EFI GUID (128 bits).

Table 180. EFI GUID Format

Mnemonic	Byte Offset	Byte Length	Description
TimeLow	0	4	The low field of the timestamp.
TimeMid	4	2	The middle field of the timestamp.
TimeHighAndVersion	6	2	The high field of the timestamp multiplexed with the version number.
ClockSeqHighAndReserved	8	1	The high field of the clock sequence multiplexed with the variant.
ClockSeqLow	9	1	The low field of the clock sequence.
Node	10	6	The spatially unique node identifier. This can be based on any IEEE 802 address obtained from a network card. If no network card exists in the system, a cryptographic-quality random number can be used.

This appendix for GUID defines a 60-bit timestamp format that is used to generate the GUID. All EFI time information is stored in 64-bit structures that contain the following format: The timestamp is a 60-bit value that is represented by Coordinated Universal Time (UTC) as a count of 100-nanosecond intervals since 00:00:00.00, 15 October 1582 (the date of Gregorian reform to the Christian calendar). This time value will not roll over until the year 3400 AD. It is assumed that a future version of the EFI specification can deal with the year-3400 issue by extending this format if necessary.

Appendix B

Console

The EFI console was designed to allow input from a wide variety of devices. This appendix provides examples of the mapping of keyboard input from various types of devices to EFI scan codes. While representative of common console devices in use today, it is not intended to be a comprehensive list. EFI application programmers can use this table to identify the EFI Scan Code generated by a specific key press. The description of the example device input data that generates a EFI Scan Code may be useful to EFI driver writers, as well as showing the limitations on which EFI Scan codes can be generated by different types of console input devices.

The EFI console was designed so that it could map to common console devices. This appendix explains how an EFI console could map to a VGA with PC AT 101/102, PC ANSI, or ANSI X3.64 consoles.

B.1 Simple _Input and Simple_Input_Ex Protocols

[Table 181](#) and [Table 182](#) give examples of how input from a set of common input devices is mapped to EFI scan codes. Terminals and terminal emulators generally report function and editing keys as escape or control sequences. These sequences are formed by a control character followed by one or more additional graphic characters that indicate what the sequence means. ANSI X3.64 terminals generally require an ANSI parser to determine how to interpret a sequence and how to determine that the sequence is complete. These terminals can generate sequences using either 8-bit controls or 7-bit control sequences. Older terminal types, such as the VT100+ have a simpler set of sequences that can be interpreted using simple case statements. These terminals usually generate only 7-bit data, and 7-bit control sequences.

In the tables below, the CSI character is the 8-bit control character 0x9B, and is equivalent to the 7-bit control sequence "ESC [" (the 0x1B control ESC followed by the left bracket character 0x5B). The sequences are shown with spaces for readability, but do not contain the space character.

The VT100+ column represents a common class of terminal emulation that is a superset of the Digital Equipment Corporation (DEC) VT100 terminal. This includes VT-UTF8 (Hyperterm) and PC_ANSI terminal types. The ANSI X3.64 column shows the sequences generated by the DEC VT200 through VT500 terminals, which are an ANSI X3.64 / ISO 6429 compliant.

The USB HID and AT 101/102 columns show the scan codes generated by two common directly attached keyboards. These keyboards are generally used in combination with a VGA text display to form a "VGA Console".

In the table below, the cells with N/A contained in them are simply intended to reflect that the key may be defined for that terminal or keyboard, but there is no industry standard or consistent mapping for the key. Some input devices might not implement all of these keys.

Table 181. EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL

EFI Scan Code	Description	ANSI X3.64 / DEC VT200- 500 (8-bit mode)	VT100+ (7-bit mode)	USB Keyboard HID Values	AT 101/102 Keyboard Scan Codes
0x00	Null scan code	N/A	N/A	0x00	N/A
0x01	UP ARROW	CSI A	ESC [A	0x52	0xe0, 0x48
0x02	DOWN ARROW	CSI B	ESC [B	0x51	0xe0, 0x50
0x03	RIGHT ARROW	CSI C	ESC [C	0x4F	0xe0, 0x4d
0x04	LEFT ARROW	CSI D	ESC [D	0x50	0xe0, 0x4b
0x05	Home	CSI 1 ~	ESC h	0x4A	0xe0, 0x47
0x06	End	CSI 4 ~	ESC k	0x4D	0xe0, 0x4f
0x07	Insert	CSI 2 ~	ESC +	0x49	0xe0, 0x52
0x08	Delete	CSI 3 ~	ESC -	0x4C	0xe0, 0x53
0x09	Page Up	CSI 5 ~	ESC ?	0x4B	0xe0, 0x49
0x0a	Page Down	CSI 6 ~	ESC /	0x4E	0xe0, 0x51
0x0b	Function 1	CSI 1 1 ~	ESC 1	0x3A	0x3b
0x0c	Function 2	CSI 1 2 ~	ESC 2	0x3B	0x3c
0x0d	Function 3	CSI 1 3 ~	ESC 3	0x3C	0x3d
0x0e	Function 4	CSI 1 4 ~	ESC 4	0x3D	0x3e
0x0f	Function 5	CSI 1 5 ~	ESC 5	0x3E	0x3f
0x10	Function 6	CSI 1 7 ~	ESC 6	0x3F	0x40
0x11	Function 7	CSI 1 8 ~	ESC 7	0x40	0x41
0x12	Function 8	CSI 1 9 ~	ESC 8	0x41	0x42
0x13	Function 9	CSI 2 0 ~	ESC 9	0x42	0x43
0x14	Function 10	CSI 2 1 ~	ESC 0	0x43	0x44
0x17	Escape	ESC	ESC	0x29	0x01

Table 182. EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL

EFI Scan Code	Description	ANSI X3.64 / DEC VT200- 500 (8-bit mode)	VT100+ (7-bit mode)	USB Keyboard HID Values	AT 101/102 Keyboard Scan Codes
0x15	Function 11	CSI 2 3 ~	ESC !	0x44	0x57
0x16	Function 12	CSI 2 4 ~	ESC @	0x45	0x58
0x68	Function 13	CSI 2 5 ~	N/A	0x68	N/A
0x69	Function 14	CSI 2 6 ~	N/A	0x69	N/A
0x6A	Function 15	CSI 2 7 ~	N/A	0x6A	N/A
0x6B	Function 16	CSI 2 8 ~	N/A	0x6B	N/A

EFI Scan Code	Description	ANSI X3.64 / DEC VT200- 500 (8-bit mode)	VT100+ (7-bit mode)	USB Keyboard HID Values	AT 101/102 Keyboard Scan Codes
0x6C	Function 17	CSI 2 9 ~	N/A	0x6C	N/A
0x6D	Function 18	CSI 3 0 ~	N/A	0x6D	N/A
0x6E	Function 19	CSI 3 1 ~	N/A	0x6E	N/A
0x6F	Function 20	CSI 3 2 ~	N/A	0x6F	N/A
0x70	Function 21	N/A	N/A	0x70	N/A
0x71	Function 22	N/A	N/A	0x71	N/A
0x72	Function 23	N/A	N/A	0x72	N/A
0x73	Function 24	N/A	N/A	0x73	N/A
0x7F	Mute	N/A	N/A	0x7F	N/A
0x80	Volume Up	N/A	N/A	0x80	N/A
0x81	Volume Down	N/A	N/A	0x81	N/A
0x100	Brightness Up	N/A	N/A	N/A	N/A
0x101	Brightness Down	N/A	N/A	N/A	N/A
0x102	Suspend	N/A	N/A	N/A	N/A
0x103	Hibernate	N/A	N/A	N/A	N/A
0x104	Toggle Display	N/A	N/A	N/A	N/A
0x105	Recovery	N/A	N/A	N/A	N/A
0x106	Eject	N/A	N/A	N/A	N/A
0x8000-0xFFFF	OEM Reserved	N/A	N/A	N/A	N/A

B.2 SIMPLE_TEXT_OUTPUT

[Table 183](#) defines how the programmatic methods of the [EFI SIMPLE TEXT OUTPUT PROTOCOL](#) could be implemented as PC ANSI or ANSI X3.64 terminals. Detailed descriptions of PC ANSI and ANSI X3.64 escape sequences are as follows. The same type of operations can be supported via a PC AT type INT 10h interface.

Table 183. Control Sequences to Implement [EFI_SIMPLE_TEXT_INPUT_PROTOCOL](#)

PC ANSI Codes	ANSI X3.64 Codes	Description
ESC [2 J	CSI 2 J	Clear Display Screen.
ESC [0 m	CSI 0 m	Normal Text.
ESC [1 m	CSI 1 m	Bright Text.

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PC ANSI Codes	ANSI X3.64 Codes	Description
ESC [7 m	CSI 7 m	Reversed Text.
ESC [30 m	CSI 30 m	Black foreground, compliant with ISO Standard 6429.
ESC [31 m	CSI 31 m	Red foreground, compliant with ISO Standard 6429.
ESC [32 m	CSI 32 m	Green foreground, compliant with ISO Standard 6429.
ESC [33 m	CSI 33 m	Yellow foreground, compliant with ISO Standard 6429.
ESC [34 m	CSI 34 m	Blue foreground, compliant with ISO Standard 6429.
ESC [35 m	CSI 35 m	Magenta foreground, compliant with ISO Standard 6429.
ESC [36 m	CSI 36 m	Cyan foreground, compliant with ISO Standard 6429.
ESC [37 m	CSI 37 m	White foreground, compliant with ISO Standard 6429.
ESC [40 m	CSI 40 m	Black background, compliant with ISO Standard 6429.
ESC [41 m	CSI 41 m	Red background, compliant with ISO Standard 6429.
ESC [42 m	CSI 42 m	Green background, compliant with ISO Standard 6429.
ESC [43 m	CSI 43 m	Yellow background, compliant with ISO Standard 6429.
ESC [44 m	CSI 44 m	Blue background, compliant with ISO Standard 6429.
ESC [45 m	CSI 45 m	Magenta background, compliant with ISO Standard 6429.
ESC [46 m	CSI 46 m	Cyan background, compliant with ISO Standard 6429.
ESC [47 m	CSI 47 m	White background, compliant with ISO Standard 6429.
ESC [= 3 h	CSI = 3 h	Set Mode 80x25 color.
ESC [<i>row</i> ; <i>col</i> H	CSI <i>row</i> ; <i>col</i> H	Set cursor position to <i>row</i> ; <i>col</i> . <i>Row</i> and <i>col</i> are strings of ASCII digits.

Appendix C

Device Path Examples

This appendix presents an example EFI Device Path and explains its relationship to the ACPI name space. An example system design is presented along with its corresponding ACPI name space. These physical examples are mapped back to EFI Device Paths.

C.1 Example Computer System

[Figure 99](#) represents a hypothetical computer system architecture that will be used to discuss the construction of EFI Device Paths. The system consists of a memory controller that connects directly to the processors' front side bus. The memory controller is only part of a larger chipset, and it connects to a root PCI host bridge chip, and a secondary root PCI host bridge chip. The secondary PCI host bridge chip produces a PCI bus that contains a PCI to PCI bridge. The root PCI host bridge produces a PCI bus, and also contains USB, ATA66, and AC '97 controllers. The root PCI host bridge also contains an LPC bus that is used to connect a SIO (Super IO) device. The SIO contains a PC-AT-compatible floppy disk controller, and other PC-AT-compatible devices like a keyboard controller.

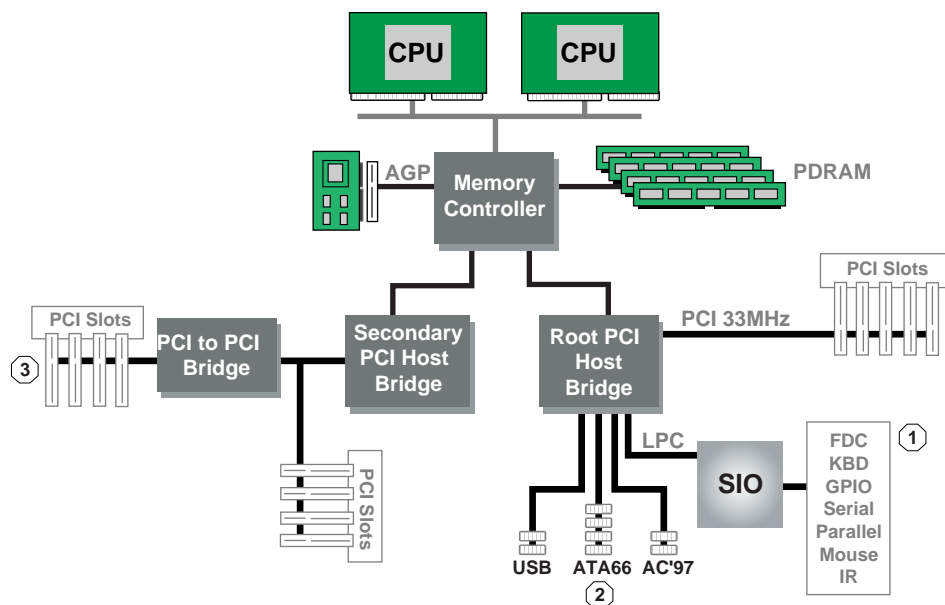


Figure 99. Example Computer System

The remainder of this appendix describes how to construct a device path for three example devices from the system in [Figure 99](#). The following is a list of the examples used:

- Legacy floppy

- IDE Disk
- Secondary root PCI bus with PCI to PCI bridge

Figure 100 is a partial ACPI name space for the system in Figure 99. Figure 100 is based on Figure 5-3 in the *Advanced Configuration and Power Interface Specification*.

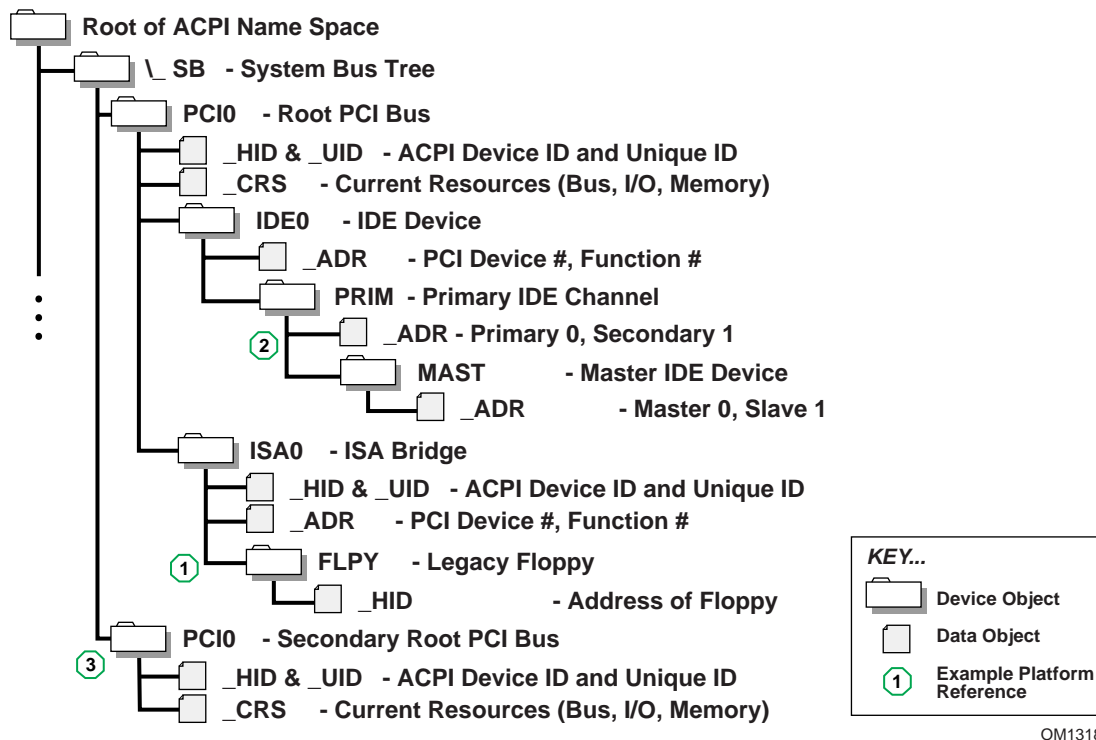


Figure 100. Partial ACPI Name Space for Example System

C.2 Legacy Floppy

The legacy floppy controller is contained in the SIO chip that is connected root PCI bus host bridge chip. The root PCI host bridge chip produces PCI bus 0, and other resources that appear directly to the processors in the system.

In ACPI this configuration is represented in the `_SB`, system bus tree, of the ACPI name space. `PCI0` is a child of `_SB` and it represents the root PCI host bridge. The SIO appears to the system to be a set of ISA devices, so it is represented as a child of `PCI0` with the name `ISA0`. The floppy controller is represented by `FLPY` as a child of the `ISA0` bus.

The EFI Device Path for the legacy floppy is defined in Table 184. It would contain entries for the following things:

- Root PCI Bridge. ACPI Device Path `_HID PNP0A03, _UID 0`. ACPI name space `_SB\PCI0`
- PCI to ISA Bridge. PCI Device Path with device and function of the PCI to ISA bridge. ACPI name space `_SB\PCI0\ISA0`

- Floppy Plug and Play ID. ACPI Device Path `_HID PNP0303, _UID 0`. ACPI name space `_SB\PCI0\ISA0\FLPY`
- End Device Path

Table 184. Legacy Floppy Device Path

Byte Offset	Byte Length	Data	Description
0	1	0x02	Generic Device Path Header – Type ACPI Device Path
1	1	0x01	Sub type – ACPI Device Path
2	2	0x0C	Length
4	4	0x41D0, 0x0A03	<code>_HID PNP0A03</code> – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
8	4	0x0000	<code>_UID</code>
C	1	0x01	Generic Device Path Header – Type Hardware Device Path
D	1	0x01	Sub type PCI Device Path
E	2	0x06	Length
10	1	0x00	PCI Function
11	1	0x10	PCI Device
12	1	0x02	Generic Device Path Header – Type ACPI Device Path
13	1	0x01	Sub type – ACPI Device Path
14	2	0x0C	Length
16	4	0x41D0, 0x0303	<code>_HID PNP0303</code>
1A	4	0x0000	<code>_UID</code>
1E	1	0xFF	Generic Device Path Header – Type End Device Path
1F	1	0xFF	Sub type – End Device Path
20	2	0x04	Length

C.3 IDE Disk

The IDE Disk controller is a PCI device that is contained in a function of the root PCI host bridge. The root PCI host bridge is a multi function device and has a separate function for chipset registers, USB, and IDE. The disk connected to the IDE ATA bus is defined as being on the primary or secondary ATA bus, and of being the master or slave device on that bus.

In ACPI this configuration is represented in the `_SB`, system bus tree, of the ACPI name space. `PCI0` is a child of `_SB` and it represents the root PCI host bridge. The IDE controller appears to the system to be a PCI device with some legacy properties, so it is represented as a child of `PCI0` with the name `IDE0`. `PRIM` is a child of `IDE0` and it represents the primary ATA bus of the IDE controller. `MAST` is a child of `PRIM` and it represents that this device is the ATA master device on this primary ATA bus.

The EFI Device Path for the PCI IDE controller is defined in [Table 185](#). It would contain entries for the following things:

- Root PCI Bridge. ACPI Device Path `_HID PNP0A03, _UID 0`. ACPI name space `_SB\PCI0`
- PCI IDE controller. PCI Device Path with device and function of the IDE controller. ACPI name space `_SB\PCI0\IDE0`
- ATA Address. ATA Messaging Device Path for Primary bus and Master device. ACPI name space `_SB\PCI0\IDE0\PRIM\MAST`
- End Device Path

Table 185. IDE Disk Device Path

Byte Offset	Byte Length	Data	Description
0	1	0x02	Generic Device Path Header – Type ACPI Device Path
1	1	0x01	Sub type – ACPI Device Path
2	2	0x0C	Length
4	4	0x41D0, 0x0A03	<code>_HID PNP0A03</code> – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
8	4	0x0000	<code>_UID</code>
C	1	0x01	Generic Device Path Header – Type Hardware Device Path
D	1	0x01	Sub type PCI Device Path
E	2	0x06	Length
10	1	0x01	PCI Function
11	1	0x10	PCI Device
12	1	0x03	Generic Device Path Header – Messaging Device Path
13	1	0x01	Sub type – ATAPI Device Path
14	2	0x06	Length
16	1	0x00	Primary =0, Secondary = 1
17	1	0x00	Master = 0, Slave = 1
18	2	0x0000	LUN
1A	1	0xFF	Generic Device Path Header – Type End Device Path
1B	1	0xFF	Sub type – End Device Path
1C	2	0x04	Length

C.4 Secondary Root PCI Bus with PCI to PCI Bridge

The secondary PCI host bridge materializes a second set of PCI buses into the system. The PCI buses on the secondary PCI host bridge are totally independent of the PCI buses on the root PCI host bridge. The only relationship between the two is they must be configured to not consume the same resources. The primary PCI bus of the secondary PCI host bridge also contains a PCI to PCI bridge. There is some arbitrary PCI device plugged in behind the PCI to PCI bridge in a PCI slot.

In ACPI this configuration is represented in the `_SB`, system bus tree, of the ACPI name space. `PCI1` is a child of `_SB` and it represents the secondary PCI host bridge. The PCI to PCI bridge and

the device plugged into the slot on its primary bus are not described in the ACPI name space. These devices can be fully configured by following the applicable PCI specification.

The EFI Device Path for the secondary root PCI bridge with a PCI to PCI bridge is defined in [Table 186](#). It would contain entries for the following things:

- Root PCI Bridge. ACPI Device Path `_HID PNP0A03, _UID 1`. ACPI name space `_SB\PCI1`
- PCI to PCI Bridge. PCI Device Path with device and function of the PCI Bridge. ACPI name space `_SB\PCI1`, PCI to PCI bridges are defined by PCI specification and not ACPI.
- PCI Device. PCI Device Path with the device and function of the PCI device. ACPI name space `_SB\PCI1`, PCI devices are defined by PCI specification and not ACPI.
- End Device Path.

Table 186. Secondary Root PCI Bus with PCI to PCI Bridge Device Path

Byte Offset	Byte Length	Data	Description
0	1	0x02	Generic Device Path Header – Type ACPI Device Path
1	1	0x01	Sub type – ACPI Device Path
2	2	0x0C	Length
4	4	0x41D0, 0x0A03	<code>_HID PNP0A03</code> – 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes
8	4	0x0001	<code>_UID</code>
C	1	0x01	Generic Device Path Header – Type Hardware Device Path
D	1	0x01	Sub type PCI Device Path
E	2	0x06	Length
10	1	0x00	PCI Function for PCI to PCI bridge
11	1	0x0c	PCI Device for PCI to PCI bridge
12	1	0x01	Generic Device Path Header – Type Hardware Device Path
13	1	0x01	Sub type PCI Device Path
14	2	0x08	Length
16	1	0x00	PCI Function for PCI Device
17	1	0x00	PCI Device for PCI Device
18	1	0xFF	Generic Device Path Header – Type End Device Path
19	1	0xFF	Sub type – End Device Path
1A	2	0x04	Length

C.5 ACPI Terms

Names in the ACPI name space that start with an underscore (“_”) are reserved by the ACPI specification and have architectural meaning. All ACPI names in the name space are four characters in length. The following four ACPI names are used in this specification.

`_ADR`. The Address on a bus that has standard enumeration. An example would be `PCI`, where the enumeration method is described in the PCI Local Bus specification.

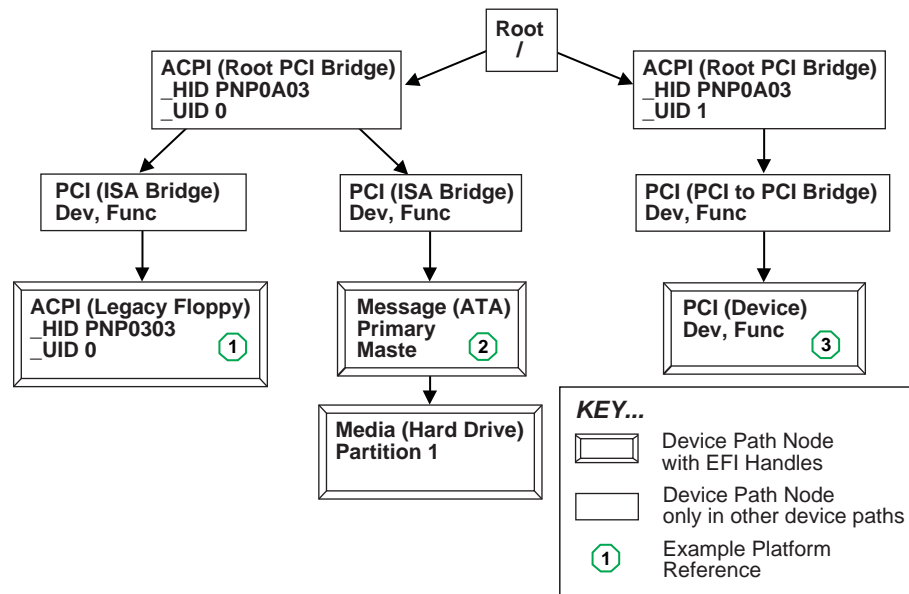
_CRS. The current resource setting of a device. A **_CRS** is required for devices that are not enumerated in a standard fashion. **_CRS** is how ACPI converts nonstandard devices into Plug and Play devices.

_HID. Represents a device’s Plug and Play hardware ID, stored as a 32-bit compressed EISA ID. **_HID** objects are optional in ACPI. However, a **_HID** object must be used to describe any device that will be enumerated by the ACPI driver in the OS. This is how ACPI deals with non-Plug and Play devices.

_UID. Is a serial number style ID that does not change across reboots. If a system contains more than one device that reports the same **_HID**, each device must have a unique **_UID**. The **_UID** only needs to be unique for device that have the exact same **_HID** value.

C.6 EFI Device Path as a Name Space

Figure 101 shows the EFI Device Path for the example system represented as a name space. The Device Path can be represented as a name space, but EFI does support manipulating the Device Path as a name space. You can only access Device Path information by locating the **DEVICE_PATH_INTERFACE** from a handle. Not all the nodes in a Device Path will have a handle.



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Figure 101. EFI Device Path Displayed As a Name Space

Appendix D

Status Codes

EFI interfaces return an **EFI_STATUS** code. [Table 188](#), [Table 189](#), and [Table 190](#) list these codes for success, errors, and warnings, respectively. Error codes also have their highest bit set, so all error codes have negative values. The range of status codes that have the highest bit set and the next to highest bit clear are reserved for use by EFI. The range of status codes that have both the highest bit set and the next to highest bit set are reserved for use by OEMs. Success and warning codes have their highest bit clear, so all success and warning codes have positive values. The range of status codes that have both the highest bit clear and the next to highest bit clear are reserved for use by EFI. The range of status code that have the highest bit clear and the next to highest bit set are reserved for use by OEMs. [Table 187](#) lists the status code ranges described above.

Table 187. EFI_STATUS Code Ranges

Supported 32-bit Range	Supported 64-bit Architecture Ranges	Description
0x00000000-0x1fffffff	0x0000000000000000-0x1fffffffffffffff	Success and warning codes reserved for use by UEFI main specification.
0x20000000-0x3fffffff	0x2000000000000000-0x3fffffffffffffff	Success and warning codes reserved for use by the Platform Initialization Architecture Specification.
0x80000000-0x9fffffff	0x8000000000000000-0x9fffffffffffffff	Error codes reserved for use by UEFI main spec.
0xa0000000-0xbfffffff	0xa000000000000000-0xbfffffffffffffff	Error codes reserved for use by the Platform Initialization Architecture Specification.

Table 188. EFI_STATUS Success Codes (High Bit Clear)

Mnemonic	Value	Description
EFI_SUCCESS	0	The operation completed successfully.

Table 189. EFI_STATUS Error Codes (High Bit Set)

Mnemonic	Value	Description
EFI_LOAD_ERROR	1	The image failed to load.
EFI_INVALID_PARAMETER	2	A parameter was incorrect.
EFI_UNSUPPORTED	3	The operation is not supported.
EFI_BAD_BUFFER_SIZE	4	The buffer was not the proper size for the request.

Mnemonic	Value	Description
EFI_BUFFER_TOO_SMALL	5	The buffer is not large enough to hold the requested data. The required buffer size is returned in the appropriate parameter when this error occurs.
EFI_NOT_READY	6	There is no data pending upon return.
EFI_DEVICE_ERROR	7	The physical device reported an error while attempting the operation.
EFI_WRITE_PROTECTED	8	The device cannot be written to.
EFI_OUT_OF_RESOURCES	9	A resource has run out.
EFI_VOLUME_CORRUPTED	10	An inconsistency was detected on the file system causing the operating to fail.
EFI_VOLUME_FULL	11	There is no more space on the file system.
EFI_NO_MEDIA	12	The device does not contain any medium to perform the operation.
EFI_MEDIA_CHANGED	13	The medium in the device has changed since the last access.
EFI_NOT_FOUND	14	The item was not found.
EFI_ACCESS_DENIED	15	Access was denied.
EFI_NO_RESPONSE	16	The server was not found or did not respond to the request.
EFI_NO_MAPPING	17	A mapping to a device does not exist.
EFI_TIMEOUT	18	The timeout time expired.
EFI_NOT_STARTED	19	The protocol has not been started.
EFI_ALREADY_STARTED	20	The protocol has already been started.
EFI_ABORTED	21	The operation was aborted.
EFI_ICMP_ERROR	22	An ICMP error occurred during the network operation.
EFI_TFTP_ERROR	23	A TFTP error occurred during the network operation.
EFI_PROTOCOL_ERROR	24	A protocol error occurred during the network operation.
EFI_INCOMPATIBLE_VERSION	25	The function encountered an internal version that was incompatible with a version requested by the caller.
EFI_SECURITY_VIOLATION	26	The function was not performed due to a security violation.
EFI_CRC_ERROR	27	A CRC error was detected.
EFI_END_OF_MEDIA	28	Beginning or end of media was reached
EFI_END_OF_FILE	31	The end of the file was reached.

Table 190. EFI_STATUS Warning Codes (High Bit Clear)

Mnemonic	Value	Description
EFI_WARN_UNKOWN_GLYPH	1	The Unicode string contained one or more characters that the device could not render and were skipped.
EFI_WARN_DELETE_FAILURE	2	The handle was closed, but the file was not deleted.
EFI_WARN_WRITE_FAILURE	3	The handle was closed, but the data to the file was not flushed properly.

Mnemonic	Value	Description
EFI_WARN_BUFFER_TOO_SMALL	4	The resulting buffer was too small, and the data was truncated to the buffer size.

Appendix E

Universal Network Driver Interfaces

E.1 Introduction

This appendix defines the 32/64-bit H/W and S/W Universal Network Driver Interfaces (UNDIs). These interfaces provide one method for writing a network driver; other implementations are possible.

E.1.1 Definitions

Table 191. Definitions

Term	Definition
BC	BaseCode The PXE BaseCode, included as a core protocol in EFI, is comprised of a simple network stack (UDP/IP) and a few common network protocols (DHCP, Bootserver Discovery, TFTP) that are useful for remote booting machines.
LOM	LAN On Motherboard This is a network device that is built onto the motherboard (or baseboard) of the machine.
NBP	Network Bootstrap Program This is the first program that is downloaded into a machine that has selected a PXE capable device for remote boot services. A typical NBP examines the machine it is running on to try to determine if the machine is capable of running the next layer (OS or application). If the machine is not capable of running the next layer, control is returned to the EFI boot manager and the next boot device is selected. If the machine is capable, the next layer is downloaded and control can then be passed to the downloaded program. Though most NBPs are OS loaders, NBPs can be written to be standalone applications such as diagnostics, backup/restore, remote management agents, browsers, etc.
NIC	Network Interface Card Technically, this is a network device that is inserted into a bus on the motherboard or in an expansion board. For the purposes of this document, the term NIC will be used in a generic sense, meaning any device that enables a network connection (including LOMs and network devices on external busses (USB, 1394, etc.)).
ROM	Read-Only Memory When used in this specification, ROM refers to a nonvolatile memory storage device on a NIC.

Term	Definition
PXE	<p>Preboot Execution Environment</p> <p>The complete PXE specification covers three areas; the client, the network and the server.</p> <p>Client</p> <ul style="list-style-type: none"> • Makes network devices into bootable devices. • Provides APIs for PXE protocol modules in EFI and for universal drivers in the OS. <p>Network</p> <ul style="list-style-type: none"> • Uses existing technology: DHCP, TFTP, etc. • Adds “vendor specific” tags to DHCP to define PXE specific operation within DHCP. • Adds multicast TFTP for high bandwidth remote boot applications. • Defines Bootserver discovery based on DHCP packet format. • <p>Server</p> <ul style="list-style-type: none"> • Bootserver: Responds to Bootserver discovery requests and serves up remote boot images. • proxyDHCP: Used to ease the transition of PXE clients and servers into existing network infrastructure. proxyDHCP provides the additional DHCP information that is needed by PXE clients and Bootservers without making changes to existing DHCP servers. • MTFTP: Adds multicast support to a TFTP server. • Plug-In Modules: Example proxyDHCP and Bootservers provided in the PXE SDK (software development kit) have the ability to take plug-in modules (PIMs). These PIMs are used to change/enhance the capabilities of the proxyDHCP and Bootservers.
UNDI	<p>Universal Network Device Interface</p> <p>UNDI is an architectural interface to NICs. Traditionally NICs have had custom interfaces and custom drivers (each NIC had a driver for each OS on each platform architecture). Two variations of UNDI are defined in this specification: H/W UNDI and S/W UNDI. H/W UNDI is an architectural hardware interface to a NIC. S/W UNDI is a software implementation of the H/W UNDI.</p>

E.1.2 Referenced Specifications

When implementing PXE services, protocols, ROMs or drivers, it is a good idea to understand the related network protocols and BIOS specifications. [Table 192](#) below includes all of the specifications referenced in this document.

Table 192. Referenced Specifications

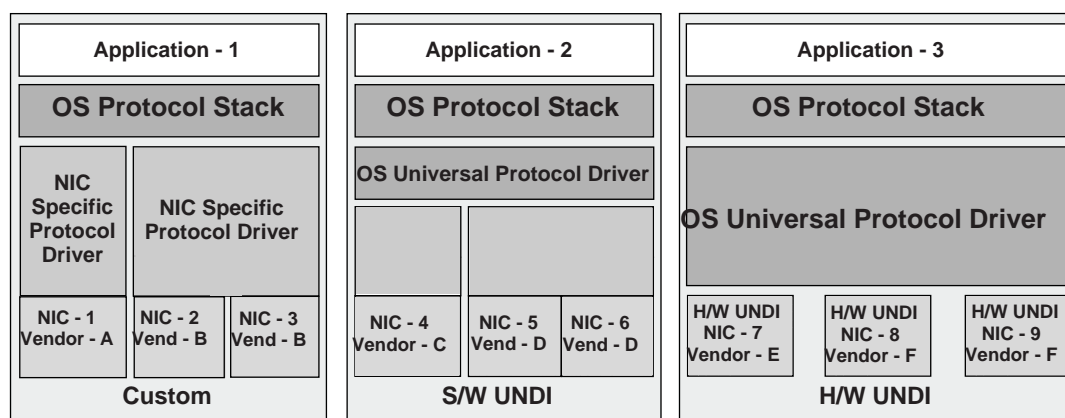
Acronym	Protocol/Specification
ARP	Address Resolution Protocol – http://www.ietf.org/rfc/rfc0826.txt . Required reading for those implementing the PXE Base Code Protocol.
Assigned Numbers	Lists the reserved numbers used in the RFCs and in this specification - http://www.ietf.org/rfc/rfc3232.txt
BIOS	Basic Input/Output System – Contact your BIOS manufacturer for reference and programming manuals.
BOOTP	Bootstrap Protocol – http://www.ietf.org/rfc/rfc0951.txt , http://www.ietf.org/rfc/rfc1542.txt , and http://www.ietf.org/rfc/rfc1534.txt . - These references are included for backward compatibility. BC protocol supports DHCP and BOOTP. Required reading for those implementing the PXE Base Code Protocol BC protocol or PXE Bootservers.

Acronym	Protocol/Specification
DHCP	Dynamic Host Configuration Protocol DHCP for Ipv4 (protocol: http://www.ietf.org/rfc/rfc2131.txt , options: http://www.ietf.org/rfc/rfc2132.txt , http://www.ietf.org/rfc/rfc3203.txt , http://www.ietf.org/rfc/rfc3396.txt , http://www.ietf.org/rfc/rfc1534.txt) Required reading for those implementing the PXE Base Code Protocol or PXE Bootservers.
EFI	Extensible Firmware Interface – http://developer.intel.com/technology/efi/index.htm Required reading for those implementing NBPs, OS loaders and preboot applications for machines with the EFI preboot environment.
ICMP	Internet Control Message Protocol ICMP for Ipv4: http://www.ietf.org/rfc/rfc0792.txt ICMP for Ipv6: http://www.ietf.org/rfc/rfc2463.txt Required reading for those implementing the BC protocol.
IETF	Internet Engineering Task Force – http://www.ietf.org/ This is a good starting point for obtaining electronic copies of Internet standards, drafts, and RFCs.
IGMP	Internet Group Management Protocol – http://www.ietf.org/rfc/rfc3376.txt . Required reading for those implementing the PXE Base Code Protocol.
IP	Internet Protocol Ipv4: http://www.ietf.org/rfc/rfc0791.txt Ipv6: http://www.ietf.org/rfc/rfc2460.txt and http://www.ipv6.org Required reading for those implementing the BC protocol.
MTFTP	Multicast TFTP – Defined in the 16-bit PXE specification. Required reading for those implementing the PXE Base Code Protocol.
PCI	Peripheral Component Interface – http://www.pcisig.com/ - Source for PCI specifications. Required reading for those implementing S/W or H/W UNDI on a PCI NIC or LOM.
PnP	Plug-and-Play – http://www.phoenix.com/en/support/white+papers-specs/ Source for PnP specifications.
PXE	Preboot eXecution Environment 16-bit PXE v2.1: ftp://download.intel.com/labs/manage/wfm/download/pxespec.pdf Required reading.
RFC	Request For Comments – http://www.ietf.org/rfc.html and http://www.keywave.ad.jp/RFC/index.html
TCP	Transmission Control Protocol TCPv4: http://www.ietf.org/rfc/rfc0793.txt TCPv6: ftp://ftp.ipv6.org/pub/rfc/rfc2147.txt Required reading for those implementing the PXE Base Code Protocol .
TFTP	Trivial File Transfer Protocol TFTP (protocol: http://www.ietf.org/rfc/rfc1350.txt , options: http://www.ietf.org/rfc/rfc2347.txt , http://www.ietf.org/rfc/rfc2348.txt , and http://www.ietf.org/rfc/rfc2349.txt). Required reading for those implementing the PXE Base Code Protocol.
UDP	User Datagram Protocol UDP over IPv4: http://www.ietf.org/rfc/rfc0768.txt UDP over IPv6: http://www.ietf.org/rfc/rfc2454.txt Required reading for those implementing the PXE Base Code Protocol.

Acronym	Protocol/Specification
WfM	Wired for Management http://www.intel.com/labs/manage/wfm/wfmspecs.htm Recommended reading for those implementing the PXE Base Code Protocol or PXE Bootservers.

E.1.3 OS Network Stacks

This is a simplified overview of three OS network stacks that contain three types of network drivers: Custom, S/W UNDI and H/W UNDI. [Figure 102](#) depicts an application bound to an OS protocol stack, which is in turn bound to a protocol driver that is bound to three NICs. [Table 193](#) below gives a brief list of pros and cons about each type of driver implementation.



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Figure 102. Network Stacks with Three Classes of Drivers

Table 193. Driver Types: Pros and Cons

Driver	Pro	Con
Custom	<ul style="list-style-type: none"> Can be very fast and efficient. NIC vendor tunes driver to OS & device. OS vendor does not have to write NIC driver. 	<ul style="list-style-type: none"> New driver for each OS/architecture must be maintained by NIC vendor. OS vendor must trust code supplied by third-party. OS vendor cannot test all possible driver/NIC versions. Driver must be installed before NIC can be used. Possible performance sink if driver is poorly written. Possible security risk if driver has back door.
S/W UNDI	<ul style="list-style-type: none"> S/W UNDI driver is simpler than a Custom driver. Easier to test outside of the OS environment. OS vendor can tune the universal protocol driver for best OS performance. NIC vendor only has to write one driver per processor architecture. 	<ul style="list-style-type: none"> Slightly slower than Custom or H/W UNDI because of extra call layer between protocol stack and NIC. S/W UNDI driver must be loaded before NIC can be used. OS vendor has to write the universal driver. Possible performance sink if driver is poorly written. Possible security risk if driver has back door.

Driver	Pro	Con
H/W UNDI	<ul style="list-style-type: none"> H/W UNDI provides a common architectural interface to all network devices. OS vendor controls all security and performance issues in network stack. NIC vendor does not have to write any drivers. NIC can be used without an OS or driver installed (preboot management). 	<ul style="list-style-type: none"> OS vendor has to write the universal driver (this might also be a Pro, depending on your point of view).

E.2 Overview

There are three major design changes between this specification and the 16-bit UNDI in version 2.1 of the PXE Specification:

- A new architectural hardware interface has been added.
- All UNDI commands use the same command format.
- BC is no longer part of the UNDI ROM.

E.2.1 32/64-bit UNDI Interface

The !PXE structures are used locate and identify the type of 32/64-bit UNDI interface (H/W or S/W), as shown in [Figure 103](#). These structures are normally only used by the system BIOS and universal network drivers.

!PXE H/W UNDI					!PXE S/W UNDI				
Offset	0x00	0x01	0x02	0x03	Offset	0x00	0x01	0x02	0x03
0x00	Signature				0x00	Signature			
0x04	Len	Fudge	Rev	IFcnt	0x04	Len	Fudge	Rev	IFcnt
0x08	Major	Minor	reserved		0x08	Major	Minor	reserved	
0x0C	Implementation				0x0C	Implementation			
0x10	reserved				0x10	Entry Point			
Len	Status								
Len + 0x04	Command				0x14				
Len + 0x08	CDBaddr				0x18	reserved	#bus		
Len + 0x0C									0x1C
					0x20	More BusTypes(s)			

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Figure 103. !PXE Structures for H/W and S/W UNDI

The !PXE structures used for H/W and S/W UNDI are similar but not identical. The difference in the format is tied directly to the differences required by the implementation. The !PXE structures for 32/64-bit UNDI are not compatible with the !PXE structure for 16-bit UNDI.

The !PXE structure for H/W UNDI is built into the NIC hardware. The first nine fields (from offsets 0x00 to 0x0F) are implemented as read-only memory (or ports). The last three fields (from Len to Len + 0x0F) are implemented as read/write memory (or ports). The optional reserved field at 0x10 is not defined in this specification and may be used for vendor data. How the location of the !PXE structure is found in system memory, or in I/O space is outlined in [Section E.5](#).

The !PXE structure for S/W UNDI can be loaded into system memory from one of three places; ROM on a NIC, system nonvolatile storage, or external storage. Since there are no direct memory or I/O ports available in the S/W UNDI !PXE structure, an indirect callable entry point is provided. S/W UNDI developers are free to make their internal designs as simple or complex as they desire, as long as all of the UNDI commands in this specification are implemented.

Descriptions of the fields in the !PXE structures is given in [Table 194](#).

Table 194. !PXE Structure Field Definitions

Identifier	Value	Description
Signature	"!PXE"	!PXE structure signature. This field is used to locate an UNDI hardware or software interface in system memory (or I/O) space. '!' is in the first (lowest address) byte, 'P' is in the second byte, 'X' in the third and 'E' in the last. This field must be aligned on a 16-byte boundary (the last address byte must be zero).
Len	Varies	Number of !PXE structure bytes to checksum. When computing the checksum of this structure the Len field MUST be used as the number of bytes to checksum. The !PXE structure checksum is computed by adding all of the bytes in the structure, starting with the first byte of the structure Signature: '!'. If the 8-bit sum of all of the unsigned bytes in this structure is not zero, this is not a valid !PXE structure.
Fudge	Varies	This field is used to make the 8-bit checksum of this structure equal zero.
Rev	0x02	Revision of this structure.
IFcnt	Varies	This field reports the number (minus one) of physical external network connections that are controlled by this !PXE interface. (If there is one network connector, this field is zero. If there are two network connectors, this field is one.)
Major	Varies	UNDI command interface. Minor revision number. 0x00 (Alpha): This version of UNDI does not operate as a runtime driver. The callback interface defined in the UNDI Start command is required. 0x10 (Beta): This version of UNDI can operate as an OS runtime driver. The callback interface defined in the UNDI Start command is required
Minor	Varies	UNDI command interface. Minor revision number. 0x00 (Alpha): This version of UNDI does not operate as a runtime driver. The callback interface defined in the UNDI Start command is required. 0x10 (Beta): This version of UNDI can operate as an OS runtime driver. The callback interface defined in the UNDI Start command is required.
reserved	0x0000	This field is reserved and must be set to zero.
Implementation	Varies	Identifies type of UNDI

Identifier	Value	Description
		<p>(S/W or H/W, 32 bit or 64 bit) and what features have been implemented. The implementation bits are defined below. Undefined bits must be set to zero by UNDI implementers. Applications/drivers must not rely on the contents of undefined bits (they may change later revisions).</p> <p>Bit 0x00: Command completion interrupts supported (1) or not supported (0) Bit 0x01: Packet received interrupts supported (1) or not supported (0) Bit 0x02: Transmit complete interrupts supported (1) or not supported (0) Bit 0x03: Software interrupt supported (1) or not supported (0) Bit 0x04: Filtered multicast receives supported (1) or not supported (0) Bit 0x05: Broadcast receives supported (1) or not supported (0) Bit 0x06: Promiscuous receives supported (1) or not supported (0) Bit 0x07: Promiscuous multicast receives supported (1) or not supported (0) Bit 0x08: Station MAC address settable (1) or not settable (0) Bit 0x09: Statistics supported (1) or not supported (0) Bit 0x0A,0x0B: NvData not available (0), read only (1), sparse write supported (2), bulk write supported (3) Bit 0x0C: Multiple frames per command supported (1) or not supported (0) Bit 0x0D: Command queuing supported (1) or not supported (0) Bit 0x0E: Command linking supported (1) or not supported (0) Bit 0x0F: Packet fragmenting supported (1) or not supported (0) Bit 0x10: Device can address 64 bits (1) or only 32 bits (0) Bit 0x1E: S/W UNDI: Entry point is virtual address (1) or unsigned offset from start of !PXE structure (0). Bit 0x1F: Interface type: H/W UNDI (1) or S/W UNDI (0)</p>
H/W UNDI Fields		
Reserved	Varies	<p>This field is optional and may be used for OEM & vendor unique data. If this field is present its length must be a multiple of 16 bytes and must be included in the !PXE structure checksum. This field, if present, will always start on a 16-byte boundary.</p> <p>Note: The size/contents of the !PXE structure may change in future revisions of this specification. Do not rely on OEM & vendor data starting at the same offset from the beginning of the !PXE structure. It is recommended that the OEM & vendor data include a signature that drivers/applications can search for.</p>

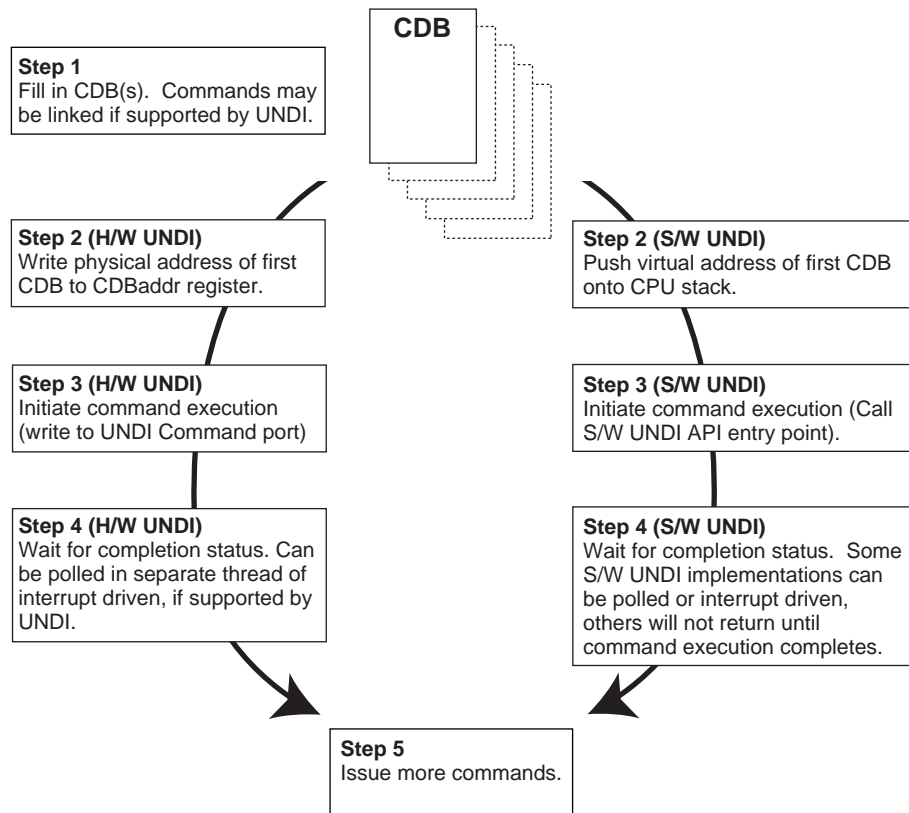
Unified Extensible Firmware Interface Specification

Identifier	Value	Description
Status	Varies	<p>UNDI operation, command and interrupt status flags.</p> <p>This is a read-only port. Undefined status bits must be set to zero. Reading this port does NOT clear the status.</p> <p>Bit 0x00: Command completion interrupt pending (1) or not pending (0)</p> <p>Bit 0x01: Packet received interrupt pending (1) or not pending (0)</p> <p>Bit 0x02: Transmit complete interrupt pending (1) or not pending (0)</p> <p>Bit 0x03: Software interrupt pending (1) or not pending (0)</p> <p>Bit 0x04: Command completion interrupts enabled (1) or disabled (0)</p> <p>Bit 0x05: Packet receive interrupts enabled (1) or disabled (0)</p> <p>Bit 0x06: Transmit complete interrupts enabled (1) or disabled (0)</p> <p>Bit 0x07: Software interrupts enabled (1) or disabled (0)</p> <p>Bit 0x08: Unicast receive enabled (1) or disabled (0)</p> <p>Bit 0x09: Filtered multicast receive enabled (1) or disabled (0)</p> <p>Bit 0x0A: Broadcast receive enabled (1) or disabled (0)</p> <p>Bit 0x0B: Promiscuous receive enabled (1) or disabled (0)</p> <p>Bit 0x0C: Promiscuous multicast receive enabled (1) or disabled (0)</p> <p>Bit 0x1D: Command failed (1) or command succeeded (0)</p> <p>Bits 0x1F:0x1E: UNDI state: Stopped (0), Started (1), Initialized (2), Busy (3)</p>
Command	Varies	<p>Use to execute commands, clear interrupt status and enable/disable receive levels. This is a read/write port. Read reflects the last write.</p> <p>Bit 0x00: Clear command completion interrupt (1) or NOP (0)</p> <p>Bit 0x01: Clear packet received interrupt (1) or NOP (0)</p> <p>Bit 0x02: Clear transmit complete interrupt (1) or NOP (0)</p> <p>Bit 0x03: Clear software interrupt (1) or NOP (0)</p> <p>Bit 0x04: Command completion interrupt enable (1) or disable (0)</p> <p>Bit 0x05: Packet receive interrupt enable (1) or disable (0)</p> <p>Bit 0x06: Transmit complete interrupt enable (1) or disable (0)</p> <p>Bit 0x07: Software interrupt enable (1) or disable (0). Setting this bit to (1) also generates a software interrupt.</p> <p>Bit 0x08: Unicast receive enable (1) or disable (0)</p> <p>Bit 0x09: Filtered multicast receive enable (1) or disable (0)</p> <p>Bit 0x0A: Broadcast receive enable (1) or disable (0)</p> <p>Bit 0x0B: Promiscuous receive enable (1) or disable (0)</p> <p>Bit 0x0C: Promiscuous multicast receive enable (1) or disable (0)</p> <p>Bit 0x1F: Operation type: Clear interrupt and/or filter (0), Issue command (1)</p>
CDBaddr	Varies	<p>Write the physical address of a CDB to this port. (Done with one 64-bit or two 32-bit writes, depending on processor architecture.) When done, use one 32-bit write to the command port to send this address into the command queue. Unused upper address bits must be set to zero.</p>
S/W UNDI Fields		
EntryPoint	Varies	<p>S/W UNDI API entry point address. This is either a virtual address or an offset from the start of the !PXE structure. Protocol drivers will push the 64-bit virtual address of a CDB on the stack and then call the UNDI API entry point. When control is returned to the protocol driver, the protocol driver must remove the address of the CDB from the stack.</p>
reserved	Zero	Reserved for future use.
BusTypeCnt	Varies	This field is the count of 4-byte BusType entries in the next field.

Identifier	Value	Description
BusType	Varies	This field defines the type of bus S/W UNDI is written to support: "PCIR," "PCCR," "USB" or "1394." This field is formatted like the Signature field. If the S/W UNDI supports more than one BusType there will be more than one BusType identifier in this field.

E.2.1.1 Issuing UNDI Commands

How commands are written and status is checked varies a little depending on the type of UNDI (H/W or S/W) implementation being used. The command flowchart shown in [Figure 104](#) is a high-level diagram on how commands are written to both H/W and S/W UNDI.



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Figure 104. Issuing UNDI Commands

E.2.2 UNDI Command Format

The format of the CDB is the same for all UNDI commands. [Figure 105](#) shows the structure of the CDB. Some of the commands do not use or always require the use of all of the fields in the CDB. When fields are not used they must be initialized to zero or the UNDI will return an error. The StatCode and StatFlags fields must always be initialized to zero or the UNDI will return an error. All reserved fields (and bit fields) must be initialized to zero or the UNDI will return an error.

Basically, the rule is: Do it right, or don't do it at all.

CDB Command Descriptor Block				
Offset	0x00	0x01	0x02	0x03
0x00	OpCode		OpFlags	
0x04	CPBsize		DBsize	
0x08	CPBaddr			
0x0C				
0x10	DBaddr			
0x14				
0x18	StatCode		StatFlags	
0x1C	IFnum		Control	

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Figure 105. UNDI Command Descriptor Block (CDB)

Descriptions of the CDB fields are given in [Table 195](#).

Table 195. UNDI CDB Field Definitions

Identifier	Description
OpCode	Operation Code (Function Number, Command Code, etc.) This field is used to identify the command being sent to the UNDI. The meanings of some of the bits in the OpFlags and StatFlags fields, and the format of the CPB and DB structures depends on the value in the OpCode field. Commands sent with an OpCode value that is not defined in this specification will not be executed and will return a StatCode of PXE_STATCODE_INVALID_CDB .
OpFlags	Operation Flags This bit field is used to enable/disable different features in a specific command operation. It is also used to change the format/contents of the CPB and DB structures. Commands sent with reserved bits set in the OpFlags field will not be executed and will return a StatCode of PXE_STATCODE_INVALID_CDB .
CPBsize	Command Parameter Block Size This field should be set to a number that is equal to the number of bytes that will be read from CPB structure during command execution. Setting this field to a number that is too small will cause the command to not be executed and a StatCode of PXE_STATCODE_INVALID_CDB will be returned. The contents of the CPB structure will not be modified.
DBsize	Data Block Size This field should be set to a number that is equal to the number of bytes that will be written into the DB structure during command execution. Setting this field to a number that is smaller than required will cause an error. It may be zero in some cases where the information is not needed.

Identifier	Description
CPBAddr	Command Parameter Block Address For H/W UNDI, this field must be the physical address of the CPB structure. For S/W UNDI, this field must be the virtual address of the CPB structure. If the operation does not have/use a CPB, this field must be initialized to PXE_CPADDR_NOT_USED . Setting up this field incorrectly will cause command execution to fail and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.
DBAddr	Data Block Address For H/W UNDI, this field must be the physical address of the DB structure. For S/W UNDI, this field must be the virtual address of the DB structure. If the operation does not have/use a CPB, this field must be initialized to PXE_DBADDR_NOT_USED . Setting up this field incorrectly will cause command execution to fail and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.
StatCode	Status Code This field is used to report the type of command completion: success or failure (and the type of failure). This field must be initialized to zero before the command is issued. The contents of this field is not valid until the PXE_STATFLAGS_COMMAND_COMPLETE status flag is set. If this field is not initialized to PXE_STATCODE_INITIALIZE the UNDI command will not execute and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.
StatFlags	Status Flags This bit field is used to report command completion and identify the format, if any, of the DB structure. This field must be initialized to zero before the command is issued. Until the command state changes to error or complete, all other CDB fields must not be changed. If this field is not initialized to PXE_STATFLAGS_INITIALIZE the UNDI command will not execute and a StatCode of PXE_STATCODE_INVALID_CDB will be returned. Bits 0x0F & 0x0E: Command state: Not started (0), Queued (1), Error (2), Complete (3).
IFnum	Interface Number This field is used to identify which network adapter (S/W UNDI) or network connector (H/W UNDI) this command is being sent to. If an invalid interface number is given, the command will not execute and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.
Control	Process Control This bit field is used to control command UNDI inter-command processing. Setting control bits that are not supported by the UNDI will cause the command execution to fail with a StatCode of PXE_STATCODE_INVALID_CDB . Bit 0x00: Another CDB follows this one (1) or this is the last or only CDB in the list (0). Bit 0x01: Queue command if busy (1), fail if busy (0).

E.3 UNDI C Definitions

The definitions in this section are used to aid in the portability and readability of the example 32/64-bit S/W UNDI source code and the rest of this specification.

E.3.1 Portability Macros

These macros are used for storage and communication portability.

E.3.1.1 PXE_INTEL_ORDER or PXE_NETWORK_ORDER

This macro is used to control conditional compilation in the S/W UNDI source code. One of these definitions needs to be uncommented in a common PXE header file.

```

// #define PXE_INTEL_ORDER    1 // little-endian
// #define PXE_NETWORK_ORDER  1 // big-endian

```

E.3.1.2 PXE_UINT64_SUPPORT or PXE_NO_UINT64_SUPPORT

This macro is used to control conditional compilation in the PXE source code. One of these definitions must be uncommented in the common PXE header file.

```

// #define PXE_UINT64_SUPPORT    1 // UINT64 supported
// #define PXE_NO_UINT64_SUPPORT 1 // UINT64 not supported

```

E.3.1.3 PXE_BUSTYPE

Used to convert a 4-character ASCII identifier to a 32-bit unsigned integer.

```

#ifdef PXE_INTEL_ORDER
#define PXE_BUSTYPE(a,b,c,d) \
(((PXE_UINT32)(d) & 0xFF) << 24) | \
(((PXE_UINT32)(c) & 0xFF) << 16) | \
(((PXE_UINT32)(b) & 0xFF) << 8) | \
(PXE_UINT32)(a) & 0xFF)
#else
#define PXE_BUSTYPE(a,b,c,d) \
(((PXE_UINT32)(a) & 0xFF) << 24) | \
(((PXE_UINT32)(b) & 0xFF) << 16) | \
(((PXE_UINT32)(c) & 0xFF) << 8) | \
(PXE_UINT32)(d) & 0xFF)
#endif

// *****
// UNDI ROM ID and device ID signature
// *****
#define PXE_BUSTYPE_PXE    PXE_BUSTYPE('!', 'P', 'X', 'E')

// *****
// BUS ROM ID signatures
// *****
#define PXE_BUSTYPE_PCI          PXE_BUSTYPE('P', 'C', 'I', 'R')
#define PXE_BUSTYPE_PC_CARD     PXE_BUSTYPE('P', 'C', 'C', 'R')
#define PXE_BUSTYPE_USB        PXE_BUSTYPE('U', 'S', 'B', 'R')
#define PXE_BUSTYPE_1394       PXE_BUSTYPE('1', '3', '9', '4')

```

E.3.1.4 PXE_SWAP_UINT16

This macro swaps bytes in a 16-bit word.

```

#ifdef PXE_INTEL_ORDER
#define PXE_SWAP_UINT16(n) \
(((PXE_UINT16)(n) & 0x00FF) << 8) | \

```



```

    (((PXE_UINT16) (n) & 0xFF00) >> 8)
#else
#define PXE_SWAP_UINT16(n)    (n)
#endif

```

E.3.1.5 PXE_SWAP_UINT32

This macro swaps bytes in a 32-bit word.

```

#ifdef PXE_INTEL_ORDER
#define PXE_SWAP_UINT32(n)    \
    (((PXE_UINT32) (n) & 0x000000FF) << 24) | \
    (((PXE_UINT32) (n) & 0x0000FF00) << 8) | \
    (((PXE_UINT32) (n) & 0x00FF0000) >> 8) | \
    (((PXE_UINT32) (n) & 0xFF000000) >> 24)
#else
#define PXE_SWAP_UINT32(n)    (n)
#endif

```

E.3.1.6 PXE_SWAP_UINT64

This macro swaps bytes in a 64-bit word for compilers that support 64-bit words.

```

#if PXE_UINT64_SUPPORT != 0
#ifdef PXE_INTEL_ORDER
#define PXE_SWAP_UINT64(n)    \
    (((PXE_UINT64) (n) & 0x00000000000000FF) << 56) | \
    (((PXE_UINT64) (n) & 0x000000000000FF00) << 40) | \
    (((PXE_UINT64) (n) & 0x0000000000FF0000) << 24) | \
    (((PXE_UINT64) (n) & 0x00000000FF000000) << 8) | \
    (((PXE_UINT64) (n) & 0x000000FF00000000) >> 8) | \
    (((PXE_UINT64) (n) & 0x0000FF0000000000) >> 24) | \
    (((PXE_UINT64) (n) & 0x00FF000000000000) >> 40) | \
    (((PXE_UINT64) (n) & 0xFF00000000000000) >> 56)
#else
#define PXE_SWAP_UINT64(n)    (n)
#endif
#endif // PXE_UINT64_SUPPORT

```

This macro swaps bytes in a 64-bit word, in place, for compilers that do not support 64-bit words.

This version of the 64-bit swap macro cannot be used in expressions.

```

#if PXE_NO_UINT64_SUPPORT != 0
#ifdef PXE_INTEL_ORDER
#define PXE_SWAP_UINT64(n)    \
{ \
    PXE_UINT32 tmp = (PXE_UINT64) (n) [1]; \
    (PXE_UINT64) (n) [1] = PXE_SWAP_UINT32 ((PXE_UINT64) (n) [0]); \
    (PXE_UINT64) (n) [0] = PXE_SWAP_UINT32 (tmp); \
}
#else
#define PXE_SWAP_UINT64(n)    (n)

```

```
#endif
#endif // PXE_NO_UINT64_SUPPORT
```

E.3.2 Miscellaneous Macros

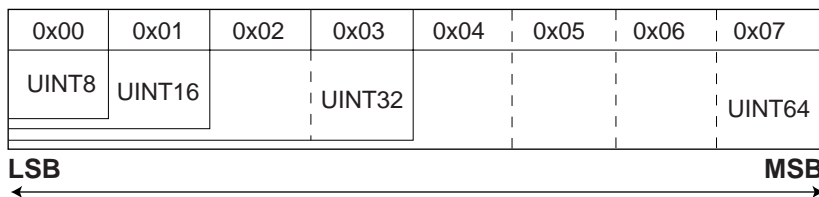
E.3.2.1 Miscellaneous

```
#define PXE_CPBSIZE_NOT_USED 0 // zero
#define PXE_DBSIZE_NOT_USED 0 // zero
#define PXE_CPADDR_NOT_USED (PXE_UINT64)0 // zero
#define PXE_DBADDR_NOT_USED (PXE_UINT64)0 // zero
```

E.3.3 Portability Types

The examples given below are just that, examples. The actual typedef instructions used in a new implementation may vary depending on the compiler and processor architecture.

The storage sizes defined in this section are critical for PXE module inter-operation. All of the portability typedefs define little endian (Intel® format) storage. The least significant byte is stored in the lowest memory address and the most significant byte is stored in the highest memory address, as shown in [Figure 106](#).



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Figure 106. Storage Types

E.3.3.1 PXE_CONST

The const type does not allocate storage. This type is a modifier that is used to help the compiler optimize parameters that do not change across function calls.

```
#define PXE_CONST const
```

E.3.3.2 PXE_VOLATILE

The volatile type does not allocate storage. This type is a modifier that is used to help the compiler deal with variables that can be changed by external procedures or hardware events.

```
#define PXE_VOLATILE volatile
```

E.3.3.3 PXE_VOID

The void type does not allocate storage. This type is used only to prototype functions that do not return any information and/or do not take any parameters.

```
typedef void PXE_VOID;
```

E.3.3.4 PXE_UINT8

Unsigned 8-bit integer.

```
typedef unsigned char    PXE_UINT8;
```

E.3.3.5 PXE_UINT16

Unsigned 16-bit integer.

```
typedef unsigned short   PXE_UINT16;
```

E.3.3.6 PXE_UINT32

Unsigned 32-bit integer.

```
typedef unsigned         PXE_UINT32;
```

E.3.3.7 PXE_UINT64

Unsigned 64-bit integer.

```
#if PXE_UINT64_SUPPORT != 0
typedef unsigned long    PXE_UINT64;
#endif // PXE_UINT64_SUPPORT
```

If a 64-bit integer type is not available in the compiler being used, use this definition:

```
#if PXE_NO_UINT64_SUPPORT != 0
typedef PXE_UINT32       PXE_UINT64[2];
#endif // PXE_NO_UINT64_SUPPORT
```

E.3.3.8 PXE_UINTN

Unsigned integer that is the default word size used by the compiler. This needs to be at least a 32-bit unsigned integer.

```
typedef unsigned        PXE_UINTN;
```

E.3.4 Simple Types

The PXE simple types are defined using one of the portability types from the previous section.

E.3.4.1 PXE_BOOL

Boolean (true/false) data type. For PXE zero is always false and nonzero is always true.

```
typedef PXE_UINT8       PXE_BOOL;
#define PXE_FALSE       0 // zero
#define PXE_TRUE        (!PXE_FALSE)
```

E.3.4.2 PXE_OPCODE

UNDI OpCode (command) descriptions are given in the next chapter. There are no BC OpCodes, BC protocol functions are discussed later in this document.

```
typedef PXE_UINT16      PXE_OPCODE;

// Return UNDI operational state.
#define PXE_OPCODE_GET_STATE      0x0000
```

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```
// Change UNDI operational state from Stopped to Started.
#define PXE_OPCODE_START          0x0001

// Change UNDI operational state from Started to Stopped.
#define PXE_OPCODE_STOP           0x0002

// Get UNDI initialization information.
#define PXE_OPCODE_GET_INIT_INFO  0x0003

// Get NIC configuration information.
#define PXE_OPCODE_GET_CONFIG_INFO 0x0004

// Changed UNDI operational state from Started to Initialized.
#define PXE_OPCODE_INITIALIZE     0x0005

// Reinitialize the NIC H/W.
#define PXE_OPCODE_RESET          0x0006

// Change the UNDI operational state from Initialized to Started.
#define PXE_OPCODE_SHUTDOWN       0x0007

// Read & change state of external interrupt enables.
#define PXE_OPCODE_INTERRUPT_ENABLES 0x0008

// Read & change state of packet receive filters.
#define PXE_OPCODE_RECEIVE_FILTERS  0x0009

// Read & change station MAC address.
#define PXE_OPCODE_STATION_ADDRESS  0x000A

// Read traffic statistics.
#define PXE_OPCODE_STATISTICS       0x000B

// Convert multicast IP address to multicast MAC address.
#define PXE_OPCODE_MCAST_IP_TO_MAC  0x000C

// Read or change nonvolatile storage on the NIC.
#define PXE_OPCODE_NVDATA           0x000D

// Get & clear interrupt status.
#define PXE_OPCODE_GET_STATUS       0x000E

// Fill media header in packet for transmit.
#define PXE_OPCODE_FILL_HEADER      0x000F

// Transmit packet(s).
```

```

#define PXE_OPCODE_TRANSMIT          0x0010

// Receive packet.
#define PXE_OPCODE_RECEIVE          0x0011

// Last valid PXE UNDI OpCode number.
#define PXE_OPCODE_LAST_VALID      0x0011

```

E.3.4.3 PXE_OPFLAGS

```

typedef PXE_UINT16 PXE_OPFLAGS;

#define PXE_OPFLAGS_NOT_USED        0x0000

//*****
// UNDI Get State
//*****

// No OpFlags

//*****
// UNDI Start
//*****

// No OpFlags

//*****
// UNDI Stop
//*****

// No OpFlags

//*****
// UNDI Get Init Info
//*****

// No Opflags

//*****
// UNDI Get Config Info
//*****

// No Opflags

//*****
// UNDI Initialize
//*****

```

```

#define PXE_OPFLAGS_INITIALIZE_CABLE_DETECT_MASK    0x0001
#define PXE_OPFLAGS_INITIALIZE_DETECT_CABLE        0x0000
#define PXE_OPFLAGS_INITIALIZE_DO_NOT_DETECT_CABLE  0x0001

//*****
// UNDI Reset
//*****

#define PXE_OPFLAGS_RESET_DISABLE_INTERRUPTS       0x0001
#define PXE_OPFLAGS_RESET_DISABLE_FILTERS         0x0002

//*****
// UNDI Shutdown
//*****

// No OpFlags

//*****
// UNDI Interrupt Enables
//*****

// Select whether to enable or disable external interrupt
// signals. Setting both enable and disable will return
// PXE_STATCODE_INVALID_OPFLAGS.

#define PXE_OPFLAGS_INTERRUPT_OPMASK               0xC000
#define PXE_OPFLAGS_INTERRUPT_ENABLE              0x8000
#define PXE_OPFLAGS_INTERRUPT_DISABLE            0x4000
#define PXE_OPFLAGS_INTERRUPT_READ               0x0000

// Enable receive interrupts. An external interrupt will be
// generated after a complete non-error packet has been received.

#define PXE_OPFLAGS_INTERRUPT_RECEIVE              0x0001

// Enable transmit interrupts. An external interrupt will be
// generated after a complete non-error packet has been
// transmitted.

#define PXE_OPFLAGS_INTERRUPT_TRANSMIT            0x0002

// Enable command interrupts. An external interrupt will be
// generated when command execution stops.

#define PXE_OPFLAGS_INTERRUPT_COMMAND             0x0004

```

```

// Generate software interrupt.  Setting this bit generates an
// externalinterrupt, if it is supported by the hardware.

#define PXE_OPFLAGS_INTERRUPT_SOFTWARE      0x0008

//*****
// UNDI Receive Filters
//*****

// Select whether to enable or disable receive filters.
// Setting both enable and disable will return
// PXE_STATCODE_INVALID_OPCODE.

#define PXE_OPFLAGS_RECEIVE_FILTER_OPMASK   0xC000
#define PXE_OPFLAGS_RECEIVE_FILTER_ENABLE  0x8000
#define PXE_OPFLAGS_RECEIVE_FILTER_DISABLE 0x4000
#define PXE_OPFLAGS_RECEIVE_FILTER_READ    0x0000

// To reset the contents of the multicast MAC address filter
// list,set this OpFlag:

#define PXE_OPFLAGS_RECEIVE_FILTERS_RESET_MCAST_LIST 0x2000

// Enable unicast packet receiving.  Packets sent to the
// current station MAC address will be received.

#define PXE_OPFLAGS_RECEIVE_FILTER_UNICAST    0x0001

// Enable broadcast packet receiving.  Packets sent to the
// broadcast MAC address will be received.

#define PXE_OPFLAGS_RECEIVE_FILTER_BROADCAST  0x0002

// Enable filtered multicast packet receiving.  Packets sent to
// anyof the multicast MAC addresses in the multicast MAC address
// filter list will be received.  If the filter list is empty, no
// multicast

#define PXE_OPFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST 0x0004

// Enable promiscuous packet receiving.  All packets will be
// received.

#define PXE_OPFLAGS_RECEIVE_FILTER_PROMISCUOUS 0x0008

// Enable promiscuous multicast packet receiving.  All multicast
// packets will be received.

```

```

#define PXE_OPFLAGS_RECEIVE_FILTER_ALL_MULTICAST    0x0010

//*****
// UNDI Station Address
//*****

#define PXE_OPFLAGS_STATION_ADDRESS_READ          0x0000
#define PXE_OPFLAGS_STATION_ADDRESS_WRITE        0x0000
#define PXE_OPFLAGS_STATION_ADDRESS_RESET        0x0001

//*****
// UNDI Statistics
//*****

#define PXE_OPFLAGS_STATISTICS_READ              0x0000
#define PXE_OPFLAGS_STATISTICS_RESET            0x0001

//*****
// UNDI MCast IP to MAC
//*****

// Identify the type of IP address in the CPB.

#define PXE_OPFLAGS_MCAST_IP_TO_MAC_OPMASK       0x0003
#define PXE_OPFLAGS_MCAST_IPV4_TO_MAC           0x0000
#define PXE_OPFLAGS_MCAST_IPV6_TO_MAC           0x0001

//*****
// UNDI NvData
//*****

// Select the type of nonvolatile data operation.

#define PXE_OPFLAGS_NVDATA_OPMASK                0x0001
#define PXE_OPFLAGS_NVDATA_READ                  0x0000
#define PXE_OPFLAGS_NVDATA_WRITE                0x0001

//*****
// UNDI Get Status
//*****

// Return current interrupt status. This will also clear any
// interrupts that are currently set. This can be used in a
// polling routine. The interrupt flags are still set and
// cleared even when the interrupts are disabled.

```



```

#define PXE_OPFLAGS_GET_INTERRUPT_STATUS      0x0001

// Return list of transmitted buffers for recycling. Transmit
// buffers must not be changed or unallocated until they have
// recycled. After issuing a transmit command, wait for a
// transmit complete interrupt. When a transmit complete
// interrupt is received, read the transmitted buffers. Do not
// plan on getting one buffer per interrupt. Some NICs and UNDIS
// may transmit multiple buffers per interrupt.

#define PXE_OPFLAGS_GET_TRANSMITTED_BUFFERS   0x0002

//*****
// UNDI Fill Header
//*****

#define PXE_OPFLAGS_FILL_HEADER_OPMASK       0x0001
#define PXE_OPFLAGS_FILL_HEADER_FRAGMENTED  0x0001
#define PXE_OPFLAGS_FILL_HEADER_WHOLE       0x0000

//*****
// UNDI Transmit
//*****

// S/W UNDI only. Return after the packet has been transmitted.
// A transmit complete interrupt will still be generated and the
// transmit buffer will have to be recycled.

#define PXE_OPFLAGS_SWUNDI_TRANSMIT_OPMASK   0x0001
#define PXE_OPFLAGS_TRANSMIT_BLOCK          0x0001
#define PXE_OPFLAGS_TRANSMIT_DONT_BLOCK     0x0000

#define PXE_OPFLAGS_TRANSMIT_OPMASK         0x0002
#define PXE_OPFLAGS_TRANSMIT_FRAGMENTED    0x0002
#define PXE_OPFLAGS_TRANSMIT_WHOLE         0x0000

//*****
// UNDI Receive
//*****

// No OpFlags

```

E.3.4.4 PXE_STATFLAGS

```

typedef PXE_UINT16 PXE_STATFLAGS;

#define PXE_STATFLAGS_INITIALIZE            0x0000

```

```

//*****
// Common StatFlags that can be returned by all commands.
//*****

// The COMMAND_COMPLETE and COMMAND_FAILED status flags must be
// implemented by all UNDIs. COMMAND_QUEUED is only needed by
// UNDIs that support command queuing.

#define PXE_STATFLAGS_STATUS_MASK          0xC000
#define PXE_STATFLAGS_COMMAND_COMPLETE    0xC000
#define PXE_STATFLAGS_COMMAND_FAILED      0x8000
#define PXE_STATFLAGS_COMMAND_QUEUED      0x4000

//*****
// UNDI Get State
//*****

#define PXE_STATFLAGS_GET_STATE_MASK       0x0003
#define PXE_STATFLAGS_GET_STATE_INITIALIZED 0x0002
#define PXE_STATFLAGS_GET_STATE_STARTED   0x0001
#define PXE_STATFLAGS_GET_STATE_STOPPED    0x0000

//*****
// UNDI Start
//*****

// No additional StatFlags

//*****
// UNDI Get Init Info
//*****

#define PXE_STATFLAGS_CABLE_DETECT_MASK    0x0001
#define PXE_STATFLAGS_CABLE_DETECT_NOT_SUPPORTED 0x0000
#define PXE_STATFLAGS_CABLE_DETECT_SUPPORTED 0x0001

//*****
// UNDI Initialize
//*****

#define PXE_STATFLAGS_INITIALIZED_NO_MEDIA 0x0001

//*****
// UNDI Reset
//*****

```

```

#define PXE_STATFLAGS_RESET_NO_MEDIA          0x0001

//*****
// UNDI Shutdown
//*****

// No additional StatFlags

//*****
// UNDI Interrupt Enables
//*****

// If set, receive interrupts are enabled.
#define PXE_STATFLAGS_INTERRUPT_RECEIVE      0x0001

// If set, transmit interrupts are enabled.
#define PXE_STATFLAGS_INTERRUPT_TRANSMIT     0x0002

// If set, command interrupts are enabled.
#define PXE_STATFLAGS_INTERRUPT_COMMAND      0x0004

//*****
// UNDI Receive Filters
//*****

// If set, unicast packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_UNICAST 0x0001

// If set, broadcast packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_BROADCAST 0x0002

// If set, multicast packets that match up with the multicast
// address filter list will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST 0x0004

// If set, all packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_PROMISCUOUS 0x0008

// If set, all multicast packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_ALL_MULTICAST 0x0010

//*****
// UNDI Station Address
//*****

// No additional StatFlags

```

```

//*****
// UNDI Statistics
//*****

// No additional StatFlags

//*****
// UNDI MCast IP to MAC
//*****

// No additional StatFlags

//*****
// UNDI NvData
//*****

// No additional StatFlags

//*****
// UNDI Get Status
//*****

// Use to determine if an interrupt has occurred.
#define PXE_STATFLAGS_GET_STATUS_INTERRUPT_MASK    0x000F
#define PXE_STATFLAGS_GET_STATUS_NO_INTERRUPTS    0x0000

// If set, at least one receive interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_RECEIVE          0x0001

// If set, at least one transmit interrupt occurred.

#define PXE_STATFLAGS_GET_STATUS_TRANSMIT        0x0002

// If set, at least one command interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_COMMAND          0x0004

// If set, at least one software interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_SOFTWARE        0x0008

// This flag is set if the transmitted buffer queue is empty.
// This flag will be set if all transmitted buffer addresses
// get written into the DB.
#define PXE_STATFLAGS_GET_STATUS_TXBUF_QUEUE_EMPTY 0x0010

// This flag is set if no transmitted buffer addresses were
// written into the DB. (This could be because DBsize was
// too small.)

```

```

#define PXE_STATFLAGS_GET_STATUS_NO_TXBUFS_WRITTEN 0x0020

//*****
// UNDI Fill Header
//*****

// No additional StatFlags

//*****
// UNDI Transmit
//*****

// No additional StatFlags.

//*****
// UNDI Receive
//*****

// No additional StatFlags.

```

E.3.4.5 PXE_STATCODE

```

typedef PXE_UINT16 PXE_STATCODE;

#define PXE_STATCODE_INITIALIZE 0x0000

//*****
// Common StatCodes returned by all UNDI commands, UNDI protocol
// functions and BC protocol functions.
//*****

#define PXE_STATCODE_SUCCESS 0x0000
#define PXE_STATCODE_INVALID_CDB 0x0001
#define PXE_STATCODE_INVALID_CPB 0x0002
#define PXE_STATCODE_BUSY 0x0003
#define PXE_STATCODE_QUEUE_FULL 0x0004
#define PXE_STATCODE_ALREADY_STARTED 0x0005
#define PXE_STATCODE_NOT_STARTED 0x0006
#define PXE_STATCODE_NOT_SHUTDOWN 0x0007
#define PXE_STATCODE_ALREADY_INITIALIZED 0x0008
#define PXE_STATCODE_NOT_INITIALIZED 0x0009
#define PXE_STATCODE_DEVICE_FAILURE 0x000A
#define PXE_STATCODE_NVDATA_FAILURE 0x000B
#define PXE_STATCODE_UNSUPPORTED 0x000C
#define PXE_STATCODE_BUFFER_FULL 0x000D
#define PXE_STATCODE_INVALID_PARAMETER 0x000E
#define PXE_STATCODE_INVALID_UNDI 0x000F
#define PXE_STATCODE_IPV4_NOT_SUPPORTED 0x0010

```

```

#define PXE_STATCODE_IPV6_NOT_SUPPORTED    0x0011
#define PXE_STATCODE_NOT_ENOUGH_MEMORY    0x0012
#define PXE_STATCODE_NO_DATA              0x0013

```

E.3.4.6 PXE_IFNUM

```

typedef PXE_UINT16 PXE_IFNUM;

// This interface number must be passed to the S/W UNDI Start
// command.

#define PXE_IFNUM_START                    0x0000

// This interface number is returned by the S/W UNDI Get State
// and Start commands if information in the CDB, CPB or DB is
// invalid.

#define PXE_IFNUM_INVALID                  0x0000

```

E.3.4.7 PXE_CONTROL

```

typedef PXE_UINT16 PXE_CONTROL;

// Setting this flag directs the UNDI to queue this command for
// later execution if the UNDI is busy and it supports command
// queuing.  If queuing is not supported, a
// PXE_STATCODE_INVALID_CONTROL error is returned.  If the queue
// is full, a PXE_STATCODE_CDB_QUEUE_FULL error is returned.

#define PXE_CONTROL_QUEUE_IF_BUSY          0x0002

// These two bit values are used to determine if there are more
// UNDI CDB structures following this one.  If the link bit is
// set, there must be a CDB structure following this one.
// Execution will start on the next CDB structure as soon as this
// one completes successfully.  If an error is generated by this
// command, execution will stop.

#define PXE_CONTROL_LINK                   0x0001
#define PXE_CONTROL_LAST_CDB_IN_LIST      0x0000

```

E.3.4.8 PXE_FRAME_TYPE

```

typedef PXE_UINT8 PXE_FRAME_TYPE;

#define PXE_FRAME_TYPE_NONE                0x00
#define PXE_FRAME_TYPE_UNICAST             0x01
#define PXE_FRAME_TYPE_BROADCAST           0x02
#define PXE_FRAME_TYPE_FILTERED_MULTICAST  0x03
#define PXE_FRAME_TYPE_PROMISCUOUS         0x04
#define PXE_FRAME_TYPE_PROMISCUOUS_MULTICAST 0x05

```

E.3.4.9 PXE_IPV4

This storage type is always big endian, not little endian.

```
typedef PXE_UINT32 PXE_IPV4;
```

E.3.4.10 PXE_IPV6

This storage type is always big endian, not little endian.

```
typedef struct s_PXE_IPV6 {
    PXE_UINT32 num[4];
} PXE_IPV6;
```

E.3.4.11 PXE_MAC_ADDR

This storage type is always big endian, not little endian.

```
typedef struct {
    PXE_UINT8 num[32];
} PXE_MAC_ADDR;
```

E.3.4.12 PXE_IFTYPE

The interface type is returned by the Get Initialization Information command and is used by the BC DHCP protocol function. This field is also used for the low order 8-bits of the H/W type field in ARP packets. The high order 8-bits of the H/W type field in ARP packets will always be set to 0x00 by the BC.

```
typedef PXE_UINT8 PXE_IFTYPE;

// This information is from the ARP section of RFC 3232.

//      1 Ethernet (10Mb)
//      2 Experimental Ethernet (3Mb)
//      3 Amateur Radio AX.25
//      4 Proteon ProNET Token Ring
//      5 Chaos
//      6 IEEE 802 Networks
//      7 ARCNET
//      8 Hyperchannel
//      9 Lanstar
//     10 Autonet Short Address
//     11 LocalTalk
//     12 LocalNet (IBM PCNet or SYTEK LocalNET)
//     13 Ultra link
//     14 SMDS
//     15 Frame Relay
//     16 Asynchronous Transmission Mode (ATM)
//     17 HDLC
//     18 Fibre Channel
//     19 Asynchronous Transmission Mode (ATM)
//     20 Serial Line
//     21 Asynchronous Transmission Mode (ATM)
```

```

#define PXE_IFTYPE_ETHERNET          0x01
#define PXE_IFTYPE_TOKENRING        0x04
#define PXE_IFTYPE_FIBRE_CHANNEL    0x12

```

E.3.4.13 PXE_MEDIA_PROTOCOL

Protocol type. This will be copied into the media header without doing byte swapping. Protocol type numbers can be obtained from the assigned numbers RFC 1700.

```

typedef UINT16      PXE_MEDIA_PROTOCOL;

```

E.3.5 Compound Types

All PXE structures must be byte packed.

E.3.5.1 PXE_HW_UNDI

This section defines the C structures and #defines for the !PXE H/W UNDI interface.

```

#pragma pack(1)
typedef struct s_pxe_hw_undi {
    PXE_UINT32  Signature;           // PXE_ROMID_SIGNATURE
    PXE_UINT8   Len;                // sizeof(PXE_HW_UNDI)
    PXE_UINT8   Fudge;              // makes 8-bit cksum equal zero
    PXE_UINT8   Rev;                // PXE_ROMID_REV
    PXE_UINT8   IFcnt;              // physical connector count
    PXE_UINT8   MajorVer;           // PXE_ROMID_MAJORVER
    PXE_UINT8   MinorVer;           // PXE_ROMID_MINORVER
    PXE_UINT16  reserved;           // zero, not used
    PXE_UINT32  Implementation;     // implementation flags
} PXE_HW_UNDI;
#pragma pack()

// Status port bit definitions

// UNDI operation state

#define PXE_HWSTAT_STATE_MASK          0xC0000000
#define PXE_HWSTAT_BUSY                0xC0000000
#define PXE_HWSTAT_INITIALIZED         0x80000000
#define PXE_HWSTAT_STARTED             0x40000000
#define PXE_HWSTAT_STOPPED             0x00000000

// If set, last command failed

#define PXE_HWSTAT_COMMAND_FAILED      0x20000000

// If set, identifies enabled receive filters

#define PXE_HWSTAT_PROMISCUOUS_MULTICAST_RX_ENABLED 0x00001000

```



```

#define PXE_HWSTAT_PROMISCUOUS_RX_ENABLED    0x00000800
#define PXE_HWSTAT_BROADCAST_RX_ENABLED    0x00000400
#define PXE_HWSTAT_MULTICAST_RX_ENABLED    0x00000200
#define PXE_HWSTAT_UNICAST_RX_ENABLED      0x00000100

// If set, identifies enabled external interrupts

#define PXE_HWSTAT_SOFTWARE_INT_ENABLED     0x00000080
#define PXE_HWSTAT_TX_COMPLETE_INT_ENABLED 0x00000040
#define PXE_HWSTAT_PACKET_RX_INT_ENABLED   0x00000020
#define PXE_HWSTAT_CMD_COMPLETE_INT_ENABLED 0x00000010

// If set, identifies pending interrupts

#define PXE_HWSTAT_SOFTWARE_INT_PENDING     0x00000008
#define PXE_HWSTAT_TX_COMPLETE_INT_PENDING 0x00000004
#define PXE_HWSTAT_PACKET_RX_INT_PENDING   0x00000002
#define PXE_HWSTAT_CMD_COMPLETE_INT_PENDING 0x00000001

// Command port definitions

// If set, CDB identified in CDBaddr port is given to UNDI.
// If not set, other bits in this word will be processed.

#define PXE_HWCMD_ISSUE_COMMAND              0x80000000
#define PXE_HWCMD_INTS_AND_FILTERS          0x00000000

// Use these to enable/disable receive filters.

#define PXE_HWCMD_PROMISCUOUS_MULTICAST_RX_ENABLE 0x00001000
#define PXE_HWCMD_PROMISCUOUS_RX_ENABLE          0x00000800
#define PXE_HWCMD_BROADCAST_RX_ENABLE            0x00000400
#define PXE_HWCMD_MULTICAST_RX_ENABLE            0x00000200
#define PXE_HWCMD_UNICAST_RX_ENABLE              0x00000100

// Use these to enable/disable external interrupts

#define PXE_HWCMD_SOFTWARE_INT_ENABLE           0x00000080
#define PXE_HWCMD_TX_COMPLETE_INT_ENABLE       0x00000040
#define PXE_HWCMD_PACKET_RX_INT_ENABLE         0x00000020
#define PXE_HWCMD_CMD_COMPLETE_INT_ENABLE      0x00000010

// Use these to clear pending external interrupts

#define PXE_HWCMD_CLEAR_SOFTWARE_INT           0x00000008
#define PXE_HWCMD_CLEAR_TX_COMPLETE_INT       0x00000004
#define PXE_HWCMD_CLEAR_PACKET_RX_INT         0x00000002

```

```
#define PXE_HWCMD_CLEAR_CMD_COMPLETE_INT    0x00000001
```

E.3.5.2 PXE_SW_UNDI

This section defines the C structures and #defines for the !PXE S/W UNDI interface.

```
#pragma pack(1)
typedef struct s_pxe_sw_undi {
    PXE_UINT32    Signature;           // PXE_ROMID_SIGNATURE
    PXE_UINT8     Len;                // sizeof(PXE_SW_UNDI)
    PXE_UINT8     Fudge;              // makes 8-bit cksum zero
    PXE_UINT8     Rev;                // PXE_ROMID_REV
    PXE_UINT8     IFcnt;              // physical connector count
    PXE_UINT8     MajorVer;           // PXE_ROMID_MAJORVER
    PXE_UINT8     MinorVer;           // PXE_ROMID_MINORVER
    PXE_UINT16    reserved1;          // zero, not used
    PXE_UINT32    Implementation;     // Implementation flags
    PXE_UINT64    EntryPoint;         // API entry point
    PXE_UINT8     reserved2[3];       // zero, not used
    PXE_UINT8     BusCnt;             // number of bustypes supported
    PXE_UINT32    BusType[1];        // list of supported bustypes
} PXE_SW_UNDI;
#pragma pack()
```

E.3.5.3 PXE_UNDI

PXE_UNDI combines both the H/W and S/W UNDI types into one typedef and has #defines for common fields in both H/W and S/W UNDI types.

```
#pragma pack(1)
typedef union u_pxe_undi {
    PXE_HW_UNDI  hw;
    PXE_SW_UNDI  sw;
} PXE_UNDI;
#pragma pack()

// Signature of !PXE structure

#define PXE_ROMID_SIGNATURE    PXE_BUSTYPE('!', 'P', 'X', 'E')

// !PXE structure format revision

#define PXE_ROMID_REV          0x02

// UNDI command interface revision.  These are the values that
// get sent in option 94 (Client Network Interface Identifier) in
// the DHCP Discover and PXE Boot Server Request packets.

#define PXE_ROMID_MAJORVER     0x03
#define PXE_ROMID_MINORVER     0x01
```

```

// Implementation flags

#define PXE_ROMID_IMP_HW_UNDI 0x80000000
#define PXE_ROMID_IMP_SW_VIRT_ADDR 0x40000000
#define PXE_ROMID_IMP_64BIT_DEVICE 0x00010000
#define PXE_ROMID_IMP_FRAG_SUPPORTED 0x00008000
#define PXE_ROMID_IMP_CMD_LINK_SUPPORTED 0x00004000
#define PXE_ROMID_IMP_CMD_QUEUE_SUPPORTED 0x00002000
#define PXE_ROMID_IMP_MULTI_FRAME_SUPPORTED 0x00001000
#define PXE_ROMID_IMP_NVDATA_SUPPORT_MASK 0x00000C00
#define PXE_ROMID_IMP_NVDATA_BULK_WRITABLE 0x00000C00
#define PXE_ROMID_IMP_NVDATA_SPARSE_WRITABLE 0x00000800
#define PXE_ROMID_IMP_NVDATA_READ_ONLY 0x00000400
#define PXE_ROMID_IMP_NVDATA_NOT_AVAILABLE 0x00000000
#define PXE_ROMID_IMP_STATISTICS_SUPPORTED 0x00000200
#define PXE_ROMID_IMP_STATION_ADDR_SETTABLE 0x00000100
#define PXE_ROMID_IMP_PROMISCUOUS_MULTICAST_RX_SUPPORTED 0x00000080
#define PXE_ROMID_IMP_PROMISCUOUS_RX_SUPPORTED 0x00000040
#define PXE_ROMID_IMP_BROADCAST_RX_SUPPORTED 0x00000020
#define PXE_ROMID_IMP_FILTERED_MULTICAST_RX_SUPPORTED 0x00000010
#define PXE_ROMID_IMP_SOFTWARE_INT_SUPPORTED 0x00000008
#define PXE_ROMID_IMP_TX_COMPLETE_INT_SUPPORTED 0x00000004
#define PXE_ROMID_IMP_PACKET_RX_INT_SUPPORTED 0x00000002
#define PXE_ROMID_IMP_CMD_COMPLETE_INT_SUPPORTED 0x00000001

```

E.3.5.4 PXE_CDB

PXE UNDI command descriptor block.

```

#pragma pack(1)
typedef struct s_pxe_cdb {
    PXE_OPCODE      OpCode;
    PXE_OPFLAGS     OpFlags;
    PXE_UINT16      CPBsize;
    PXE_UINT16      DBsize;
    PXE_UINT64      CPBaddr;
    PXE_UINT64      DBaddr;
    PXE_STATCODE    StatCode;
    PXE_STATFLAGS   StatFlags;
    PXE_UINT16      IFnum;
    PXE_CONTROL     Control;
} PXE_CDB;
#pragma pack()

```

E.3.5.5 PXE_IP_ADDR

This storage type is always big endian, not little endian.

```

#pragma pack(1)
typedef union u_pxe_ip_addr {

```

```

    PXE_IPV6    IPv6;
    PXE_IPV4    IPv4;
} PXE_IP_ADDR;
#pragma pack()

```

E.3.5.6 PXE_DEVICE

This typedef is used to identify the network device that is being used by the UNDI. This information is returned by the Get Config Info command.

```

#pragma pack(1)
typedef union pxe_device {

    // PCI and PC Card NICs are both identified using bus, device
    // and function numbers. For PC Card, this may require PC
    // Card services to be loaded in the BIOS or preboot
    // environment.
    struct {
        // See S/W UNDI ROMID structure definition for PCI and
        // PCC BusType definitions.
        PXE_UINT32    BusType;

        // Bus, device & function numbers that locate this device.
        PXE_UINT16    Bus;
        PXE_UINT8     Device;
        PXE_UINT8     Function;
    } PCI, PCC;

} PXE_DEVICE;
#pragma pack()

```

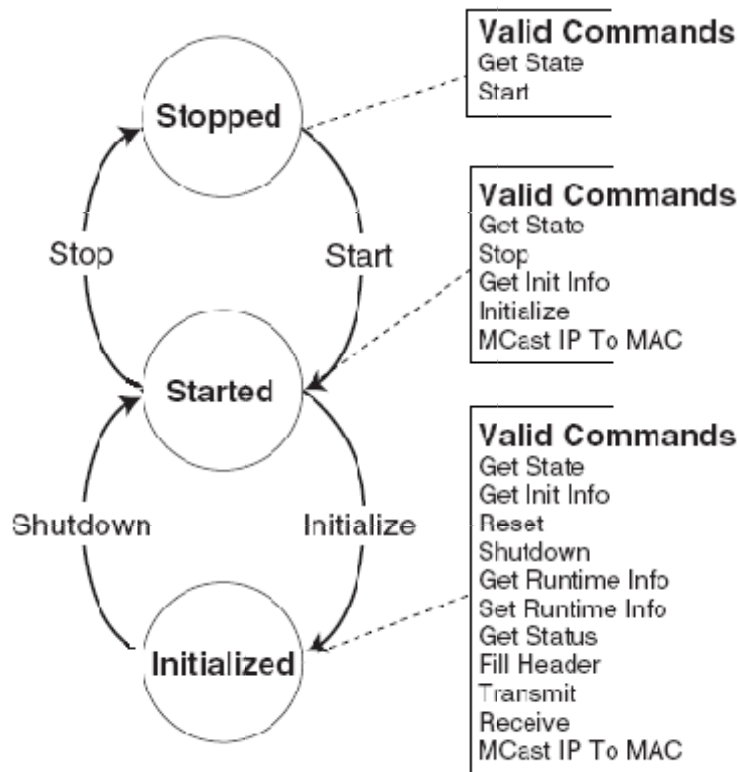
E.4 UNDI Commands

All 32/64-bit UNDI commands use the same basic command format, the CDB (Command Descriptor Block). CDB fields that are not used by a particular command must be initialized to zero by the application/driver that is issuing the command.

All UNDI implementations must set the command completion status (**PXE_STATFLAGS_COMMAND_COMPLETE**) after command execution completes. Applications and drivers must not alter or rely on the contents of any of the CDB, CPB or DB fields until the command completion status is set.

All commands return status codes for invalid CDB contents and, if used, invalid CPB contents. Commands with invalid parameters will not execute. Fix the error and submit the command again.

[Figure 107](#) describes the different UNDI states (Stopped, Started and Initialized), shows the transitions between the states and which UNDI commands are valid in each state.



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Figure 107. UNDI States, Transitions & Valid Commands

Note: All memory addresses including the CDB address, CPB address, and the DB address submitted to the S/W UNDI by the protocol drivers must be processor-based addresses. All memory addresses submitted to the H/W UNDI must be device based addresses.

Note: Additional requirements for S/W UNDI implementations: Processor register contents must be unchanged by S/W UNDI command execution (the application/driver does not have to save processor registers when calling S/W UNDI). Processor arithmetic flags are undefined (application/driver must save processor arithmetic flags if needed). Application/driver must remove CDB address from stack after control returns from S/W UNDI.

Note: Additional requirements for 32-bit network devices: All addresses given to the S/W UNDI must be 32-bit addresses. Any address that exceeds 32 bits (4 GB) will result in a return of one of the following status codes: PXE_STATCODE_INVALID_PARAMETER, PXE_STATCODE_INVALID_CDB or PXE_STATCODE_INVALID_CPB.

When executing linked commands, command execution will stop at the end of the CDB list (when the **PXE_CONTROL_LINK** bit is not set) or when a command returns an error status code.

E.4.1 Command Linking and Queuing

When linking commands, the CDBs must be stored consecutively in system memory without any gaps in between. Do not set the Link bit in the last CDB in the list. As shown in [Figure 108](#), the Link bit must be set in all other CDBs in the list.

Linked CDBs	
0x00	CDB
	Set Link bit.
0x1F	
0x20	CDB
	Set Link bit.
0x3F	
0x40	CDB
	Do not set Link bit.
0x5F	

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Figure 108. Linked CDBs

When the H/W UNDI is executing commands, the State bits in the Status field in the !PXE structure will be set to Busy (3).

When H/W or S/W UNDI is executing commands and a new command is issued, a StatCode of **PXE_STATCODE_BUSY** and a StatFlag of **PXE_STATFLAG_COMMAND_FAILURE** is set in the CDB. For linked commands, only the first CDB will be set to Busy, all other CDBs will be unchanged. When a linked command fails, execution on the list stops. Commands after the failing command will not be run.

As shown in [Figure 109](#), when queuing commands, only the first CDB needs to have the Queue Control flag set. If queuing is supported and the UNDI is busy and there is room in the command queue, the command (or list of commands) will be queued.

Queued CDBs	
0x00	CDB
0x1F	Set Queue bit. Set Link bit.
0x20	CDB
0x3F	Set Queue bit. Set Link bit.
0x40	CDB
0x5F	Set Queue bit. Set Link bit.

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Figure 109. Queued CDBs

When a command is queued a StatFlag of **PXE_STATFLAG_COMMAND_QUEUED** is set (if linked commands are queued only the StatFlag of the first CDB gets set). This signals that the command was added to the queue. Commands in the queue will be run on a first-in, first-out, basis. When a command fails, the next command in the queue is run. When a linked command in the queue fails, execution on the list stops. The next command, or list of commands, that was added to the command queue will be run.

E.4.2 Get State

This command is used to determine the operational state of the UNDI. An UNDI has three possible operational states:

- **Stopped.** A stopped UNDI is free for the taking. When all interface numbers (IFnum) for a particular S/W UNDI are stopped, that S/W UNDI image can be relocated or removed. A stopped UNDI will accept Get State and Start commands.
- **Started.** A started UNDI is in use. A started UNDI will accept Get State, Stop, Get Init Info, and Initialize commands.
- **Initialized.** An initialized UNDI is in used. An initialized UNDI will accept all commands except: Start, Stop, and Initialize.

Drivers and applications must not start using UNDI's that have been placed into the Started or Initialized states by another driver or application.

3.0 and 3.1 S/W UNDI: No callbacks are performed by this UNDI command.

E.4.2.1 Issuing the Command

To issue a Get State command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Get State command
OpCode	PXE_OPCODE_GET_STATE
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	PXE_DBADDR_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt
Control	Set as needed

E.4.2.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. StatFlags contain operational state.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued. All other fields are unchanged.
INITIALIZE	Command has not been executed or queued.

E.4.2.3 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. StatFlags contain operational state.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.

If the command completes successfully, use **PXE_STATFLAGS_GET_STATE_MASK** to check the state of the UNDI.

StatFlags	Reason
STOPPED	The UNDI is stopped.
STARTED	The UNDI is started, but not initialized.
INITIALIZED	The UNDI is initialized.

E.4.3 Start

This command is used to change the UNDI operational state from stopped to started. No other operational checks are made by this command. Protocol driver makes this call for each network interface supported by the UNDI with a set of call back routines and a unique identifier to identify the particular interface. UNDI does not interpret the unique identifier in any way except that it is a 64-bit value and it will pass it back to the protocol driver as a parameter to all the call back routines for any particular interface. If this is a S/W UNDI, the callback functions Delay(), Virt2Phys(), Map_Mem(), UnMap_Mem(), and Sync_Mem() functions will not be called by this command.

E.4.3.1 Issuing the Command

To issue a Start command for H/W UNDI, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a H/W UNDI Start command
OpCode	PXE_OPCODE_START
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	PXE_DBADDR_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt
Control	Set as needed

To issue a Start command for S/W UNDI, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a S/W UNDI Start command
OpCode	PXE_OPCODE_START
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	sizeof(PXE_CPB_START)
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	Address of a PXE_CPB_START structure.
DBaddr	PXE_DBADDR_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt
Control	Set as needed

E.4.3.2 Preparing the CPB

For the 3.1 S/W UNDI Start command, the CPB structure shown below must be filled in and the CDB must be set to **sizeof(struct s_pxe_cpb_start_31)**.

```
#pragma pack(1)
```

```

typedef struct s_pxe_cpb_start_31 {
    UINT64    Delay;
    //
    // Address of the Delay() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Delay(
    //     IN  UINT64    UniqueId,
    //     IN  UINT64    Microseconds);
    //
    // UNDI will never request a delay smaller than 10 microseconds

    // and will always request delays in increments of 10
    // microseconds. The Delay() callback routine must delay
    // between n and n + 10 microseconds before returning control
    // to the UNDI.
    //

    UINT64    Block;
    //
    // Address of the Block() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Block(
    //     IN  UINT64    UniqueId,
    //     IN  UINT32    Enable);
    //
    // UNDI may need to block multithreaded/multiprocessor access
    // to critical code sections when programming or accessing the
    // network device.  When UNDI needs a block, it will call the
    // Block()callback service with Enable set to a non-zero value.

    // When UNDI no longer needs the block, it will call Block()
    // with Enable set to zero.
    //

    UINT64    Virt2Phys;
    //
    // Convert a virtual address to a physical address.
    // This field can be set to zero if virtual and physical
    // addresses are identical.
    //
    // VOID
    // Virt2Phys(
    //     IN  UINT64    UniqueId,

```

```

// IN  UINT64    Virtual,
// OUT UINT64    PhysicalPtr);
//
// UNDI will pass in a virtual address and a pointer to storage
// for a physical address.  The Virt2Phys() service converts
// the virtual address to a physical address and stores the
// resulting physical address in the supplied buffer.  If no
// conversion is needed, the virtual address must be copied
// into the supplied physical address buffer.
//

UINT64    MemIo;
//
// Read/Write network device memory and/or I/O register space.
// This field cannot be set to zero.
//
// VOID
// MemIo(
//   IN    UINT64    UniqueId,
//   IN    UINT8     AccessType,
//   IN    UINT8     Length,
//   IN    UINT64    Port,
//   IN OUT UINT64    BufferPtr);
//
// UNDI uses the MemIo() service to access the network device
// memory and/or I/O registers.  The AccessType is one of the
// PXE_IO_XXX or PXE_MEM_XXX constants defined at the end of
// this section.  The Length is 1, 2, 4 or 8.  The Port number
// is relative to the base memory or I/O address space for this
// device.BufferPtr points to the data to be written to the
// Port or will contain the data that is read from the Port.
//

UINT64    MapMem;
//
// Map virtual memory address for DMA.
// This field can be set to zero if there is no mapping
// service.
//
// VOID
// MapMem(
//   IN  UINT64    UniqueId,
//   IN  UINT64    Virtual,
//   IN  UINT32    Size,
//   IN  UINT32    Direction,

```

```

// OUT UINT64 PhysicalPtr);
//
// When UNDI needs to perform a DMA transfer it will request a
// virtual-to-physical mapping using the MapMem() service. The
// Virtual parameter contains the virtual address to be mapped.
// The minimum Size of the virtual memory buffer to be mapped.
// Direction is one of the TO_DEVICE, FROM_DEVICE or
// TO_AND_FROM_DEVICE constants defined at the end of this
// section. PhysicalPtr contains the mapped physical address or
// a copy of the Virtual address if no mapping is required.
//
UINT64 UnMapMem;
//
// Un-map previously mapped virtual memory address.
// This field can be set to zero only if the MapMem() service
// is also set to zero.
//
// VOID
// UnMapMem(
// IN UINT64 UniqueId,
// IN UINT64 Virtual,
// IN UINT32 Size,
// IN UINT32 Direction,
// IN UINT64 PhysicalPtr);
//
// When UNDI is done with the mapped memory, it will use the
// UnMapMem() service to release the mapped memory.
//

UINT64 SyncMem;
//
// Synchronise mapped memory.
// This field can be set to zero only if the MapMem() service
// is also set to zero.
//
// VOID
// SyncMem(
// IN UINT64 UniqueId,
// IN UINT64 Virtual,
// IN UINT32 Size,
// IN UINT32 Direction,
// IN UINT64 PhysicalPtr);
//
// When the virtual and physical buffers need to be
// synchronized, UNDI will call the SyncMem() service.
//

```

```

    UINT64    UniqueId;
    //
    // UNDI will pass this value to each of the callback services.
    // A unique ID number should be generated for each instance of
    // the UNDI driver that will be using these callback services.
    //
} PXE_CPB_START_31;
#pragma pack()

```

For the 3.0 S/W UNDI Start command, the CPB structure shown below must be filled in and the CDB must be set to `sizeof(struct s_pxe_cpb_start_30)`.

```

#pragma pack(1)
typedef struct s_pxe_cpb_start_30 {
    UINT64    Delay;
    //
    // Address of the Delay() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Delay(
    //     IN  UINT64    Microseconds);
    //
    // UNDI will never request a delay smaller than 10 microseconds

    // and will always request delays in increments of 10.
    // microseconds The Delay() callback routine must delay between

    // n and n + 10 microseconds before returning control to the
    // UNDI.
    //

    UINT64    Block;
    //
    // Address of the Block() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Block(
    //     IN  UINT32    Enable);
    //
    // UNDI may need to block multithreaded/multiprocessor access
    // to critical code sections when programming or accessing the
    // network device.  When UNDI needs a block, it will call the
    // Block() callback service with Enable set to a non-zero value.

    // When UNDI no longer needs the block, it will call Block()

```

```

// with Enable set to zero.
//

UINT64    Virt2Phys;
//
// Convert a virtual address to a physical address.
// This field can be set to zero if virtual and physical
// addresses are identical.
//
// VOID
// Virt2Phys(
//   IN  UINT64    Virtual,
//   OUT UINT64    PhysicalPtr);
//
// UNDI will pass in a virtual address and a pointer to storage
// for a physical address.  The Virt2Phys() service converts
// the virtual address to a physical address and stores the
// resulting physical address in the supplied buffer.  If no
// conversion is needed, the virtual address must be copied
// into the supplied physical address buffer.
//

UINT64    MemIo;
//
// Read/Write network device memory and/or I/O register space.
// This field cannot be set to zero.
//
// VOID
// MemIo(
//   IN    UINT8    AccessType,
//   IN    UINT8    Length,
//   IN    UINT64   Port,
//   IN OUT UINT64   BufferPtr);
//
// UNDI uses the MemIo() service to access the network device
// memory and/or I/O registers.  The AccessType is one of the
// PXE_IO_XXX or PXE_MEM_XXX constants defined at the end of
// this section.  The Length is 1, 2, 4 or 8.  The Port number
// is relative to the base memory or I/O address space for this
// device. BufferPtr points to the data to be written to the
// Port or will contain the data that is read from the Port.
//
} PXE_CPB_START_30;
#pragma pack()

```

E.4.3.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. UNDI is now started.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.3.4 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. UNDI is now started.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
ALREADY_STARTED	The UNDI is already started.

E.4.4 Stop

This command is used to change the UNDI operational state from started to stopped.

E.4.4.1 Issuing the Command

To issue a Stop command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a Stop command
OpCode	PXE_OPCODE_STOP
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	PXE_DBADDR_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt
Control	Set as needed

E.4.4.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. UNDI is now stopped.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has not been executed or queued.

E.4.4.3 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. UNDI is now stopped.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_SHUTDOWN	The UNDI is initialized and must be shutdown before it can be stopped.

E.4.5 Get Init Info

This command is used to retrieve initialization information that is needed by drivers and applications to initialize UNDI.

E.4.5.1 Issuing the Command

To issue a Get Init Info command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a Get Init Info command
OpCode	PXE_OPCODE_GET_INIT_INFO
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	sizeof(PXE_DB_INIT_INFO)
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	Address of a PXE_DB_INIT_INFO structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.5.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. DB can be used.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.5.3 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. DB can be used.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.

E.4.5.4 StatFlags

To determine if cable detection is supported by this UNDI/NIC, use these macros with the value returned in the CDB.StatFlags field:

```
PXE_STATFLAGS_CABLE_DETECT_MASK  
PXE_STATFLAGS_CABLE_DETECT_NOT_SUPPORTED  
PXE_STATFLAGS_CABLE_DETECT_SUPPORTED
```

E.4.5.5 DB

```
#pragma pack(1)  
typedef struct s_pxe_db_get_init_info {  
  
    // Minimum length of locked memory buffer that must be given to  
    // the Initialize command. Giving UNDI more memory will  
    // generally give better performance.  
  
    // If MemoryRequired is zero, the UNDI does not need and will  
    // not use system memory to receive and transmit packets.  
  
    PXE_UINT32    MemoryRequired;  
  
    // Maximum frame data length for Tx/Rx excluding the media  
    // header.
```

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```
//
PXE_UINT32  FrameDataLen;

// Supported link speeds are in units of mega bits. Common
// ethernet values are 10, 100 and 1000. Unused LinkSpeeds[]
// entries are zero filled.

PXE_UINT32  LinkSpeeds[4];

// Number of nonvolatile storage items.

PXE_UINT32  NvCount;

// Width of nonvolatile storage item in bytes. 0, 1, 2 or 4

PXE_UINT16  NvWidth;

// Media header length. This is the typical media header
// length for this UNDI. This information is needed when
// allocating receive and transmit buffers.

PXE_UINT16  MediaHeaderLen;

// Number of bytes in the NIC hardware (MAC) address.

PXE_UINT16  HWaddrLen;

// Maximum number of multicast MAC addresses in the multicast
// MAC address filter list.

PXE_UINT16  MCastFilterCnt;

// Default number and size of transmit and receive buffers that
// will be allocated by the UNDI. If MemoryRequired is
// nonzero, this allocation will come out of the memory buffer
// given to the Initialize command. If MemoryRequired is zero,
// this allocation will come out of memory on the NIC.

PXE_UINT16  TxBufCnt;
PXE_UINT16  TxBufSize;
PXE_UINT16  RxBufCnt;
PXE_UINT16  RxBufSize;

// Hardware interface types defined in the Assigned Numbers RFC
// and used in DHCP and ARP packets.
// See the PXE_IFTYPE typedef and PXE_IFTYPE_xxx macros.

PXE_UINT8   IFType;
```

```

// Supported duplex options. This can be one or a combination
// of more than one constants defined as PXE_DUPLEX_XXXXX
// below. This value indicates the ability of UNDI to
// change/control the duplex modes of the NIC.

PXE_UINT8 SupportedDuplexModes;

// Supported loopback options. This field can be one or a
// combination of more than one constants defined as
// PXE_LOOPBACK_XXXXX #defines below. This value indicates
// the ability of UNDI to change/control the loopback modes
// of the NIC

PXE_UINT8 SupportedLoopBackModes;
} PXE_DB_GET_INIT_INFO;
#pragma pack()

#define PXE_MAX_TXRX_UNIT_ETHER 1500
#define PXE_HWADDR_LEN_ETHER 0x0006

#define PXE_DUPLEX_DEFAULT 0
#define PXE_DUPLEX_ENABLE_FULL_SUPPORTED 1
#define PXE_DUPLEX_FORCE_FULL_SUPPORTED 2

#define PXE_LOOPBACK_INTERNAL_SUPPORTED 1
#define PXE_LOOPBACK_EXTERNAL_SUPPORTED 2

```

E.4.6 Get Config Info

This command is used to retrieve configuration information about the NIC being controlled by the UNDI.

E.4.6.1 Issuing the Command

To issue a Get Config Info command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Get Config Info command
OpCode	PXE_OPCODE_GET_CONFIG_INFO
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	sizeof(PXE_DB_CONFIG_INFO)
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	Address of a PXE_DB_CONFIG_INFO structure
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt

CDB Field	How to initialize the CDB structure for a Get Config Info command
Control	Set as needed

E.4.6.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. DB has been written.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.6.3 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. DB has been written.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.

E.4.6.4 DB

```
#pragma pack(1)
typedef struct s_pxe_pci_config_info {

    // This is the flag field for the PXE_DB_GET_CONFIG_INFO union.
    // For PCI bus devices, this field is set to PXE_BUSTYPE_PCI.

    PXE_UINT32    BusType;

    // This identifies the PCI network device that this UNDI
    // interface is bound to.

    PXE_UINT16    Bus;
    PXE_UINT8     Device;
    PXE_UINT8     Function;

    // This is a copy of the PCI configuration space for this
    // network device.
```

```

union {
    PXE_UINT8    Byte[256];
    PXE_UINT16   Word[128];
    PXE_UINT32   Dword[64];
} Config;
} PXE_PCI_CONFIG_INFO;
#pragma pack()
#pragma pack(1)
typedef struct s_pxe_pcc_config_info {

    // This is the flag field for the PXE_DB_GET_CONFIG_INFO union.
    // For PCC bus devices, this field is set to PXE_BUSTYPE_PCC.

    PXE_UINT32   BusType;

    // This identifies the PCC network device that this UNDI
    // interface is bound to.

    PXE_UINT16   Bus;
    PXE_UINT8    Device;
    PXE_UINT8    Function;

    // This is a copy of the PCC configuration space for this
    // network device.

    union {
        PXE_UINT8    Byte[256];
        PXE_UINT16   Word[128];
        PXE_UINT32   Dword[64];
    } Config;
} PXE_PCC_CONFIG_INFO;
#pragma pack()

#pragma pack(1)
typedef union u_pxe_db_get_config_info {
    PXE_PCI_CONFIG_INFO   pci;
    PXE_PCC_CONFIG_INFO   pcc;
} PXE_DB_GET_CONFIG_INFO;
#pragma pack()

```

E.4.7 Initialize

This command resets the network adapter and initializes UNDI using the parameters supplied in the CPB. The Initialize command must be issued before the network adapter can be setup to transmit and receive packets. This command will not enable the receive unit or external interrupts.

Once the memory requirements of the UNDI are obtained by using the Get Init Info command, a block of kernel (nonswappable) memory may need to be allocated by the protocol driver. The

address of this kernel memory must be passed to UNDI using the Initialize command CPB. This memory is used for transmit and receive buffers and internal processing.

Initializing the network device will take up to four seconds for most network devices and in some extreme cases (usually poor cables) up to twenty seconds. Control will not be returned to the caller and the **COMMAND_COMPLETE** status flag will not be set until the NIC is ready to transmit.

E.4.7.1 Issuing the Command

To issue an Initialize command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for an Initialize command
OpCode	PXE_OPCODE_INITIALIZE
OpFlags	Set as needed.
CPBsize	sizeof(PXE_CPB_INITIALIZE)
DBsize	sizeof(PXE_DB_INITIALIZE)
CPBaddr	Address of a PXE_CPB_INITIALIZE structure.
Dbaddr	Address of a PXE_DB_INITIALIZE structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
lfnun	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.7.2 OpFlags

Cable detection can be enabled or disabled by setting one of the following OpFlags:

```
PXE_OPFLAGS_INITIALIZE_CABLE_DETECT
PXE_OPFLAGS_INITIALIZE_DO_NOT_DETECT_CABLE
```

E.4.7.3 Preparing the CPB

If the **MemoryRequired** field returned in the **PXE_DB_GET_INIT_INFO** structure is zero, the Initialize command does not need to be given a memory buffer or even a CPB structure. If the **MemoryRequired** field is nonzero, the Initialize command does need a memory buffer.

```
#pragma pack(1)
typedef struct s_pxe_cpb_initialize {

    // Address of first (lowest) byte of the memory buffer.
    // This buffer must be in contiguous physical memory and cannot
    // be swapped out. The UNDI will be using this for transmit
    // and receive buffering. This address must be a processor-
    // based address for S/W UNDI and a device-based address for
    // H/W UNDI.

    PXE_UINT64 MemoryAddr;

    // MemoryLength must be greater than or equal to MemoryRequired
    // returned by the Get Init Info command.
};
```

```

PXE_UINT32    MemoryLength;

// Desired link speed in Mbit/sec.  Common ethernet values are
// 10, 100 and 1000.  Setting a value of zero will auto-detect
// and/or use the default link speed (operation depends on
// UNDI/NIC functionality).

PXE_UINT32    LinkSpeed;

// Suggested number and size of receive and transmit buffers to
// allocate.  If MemoryAddr and MemoryLength are nonzero, this
// allocation comes out of the supplied memory buffer.  If
// MemoryAddr and MemoryLength are zero, this allocation comes
// out of memory on the NIC.

// If these fields are set to zero, the UNDI will allocate
// buffer counts and sizes as it sees fit.

PXE_UINT16    TxBufCnt;
PXE_UINT16    TxBufSize;
PXE_UINT16    RxBufCnt;
PXE_UINT16    RxBufSize;

// The following configuration parameters are optional and must
// be zero to use the default values.
// The possible values for these parameters are defined below.

PXE_UINT8     DuplexMode;

PXE_UINT8     LoopBackMode;
} PXE_CPB_INITIALIZE;
#pragma pack()

#define PXE_DUPLEX_AUTO_DETECT    0x00
#define PXE_FORCE_FULL_DUPLEX    0x01

#define PXE_FORCE_HALF_DUPLEX    0x02

#define PXE_LOOPBACK_NORMAL      0
#define PXE_LOOPBACK_INTERNAL    1
#define PXE_LOOPBACK_EXTERNAL    2

```

E.4.7.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. UNDI and network device is now initialized. DB has been written.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.7.5 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. UNDI and network device is now initialized. DB has been written. Check StatFlags.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
ALREADY_INITIALIZED	The UNDI is already initialized.
DEVICE_FAILURE	The network device could not be initialized.
NVDATA_FAILURE	The nonvolatile storage could not be read.

E.4.7.6 StatFlags

Check the StatFlags to see if there is an active connection to this network device. If the no media StatFlag is set, the UNDI and network device are still initialized.

PXE_STATFLAGS_INITIALIZED_NO_MEDIA

E.4.7.7 Before Using the DB

```
#pragma pack(1)
typedef struct s_pxe_db_initialize {

    // Actual amount of memory used from the supplied memory
    // buffer. This may be less than the amount of memory
    // supplied and may be zero if the UNDI and network device
    // do not use external memory buffers. Memory used by the
    // UNDI and network device is allocated from the lowest
    // memory buffer address.
```



```

PXE_UINT32    MemoryUsed;

// Actual number and size of receive and transmit buffers that
// were allocated.

PXE_UINT16    TxBufCnt;
PXE_UINT16    TxBufSize;
PXE_UINT16    RxBufCnt;
PXE_UINT16    RxBufSize
} PXE_DB_INITIALIZE;
#pragma pack()

```

E.4.8 Reset

This command resets the network adapter and reinitializes the UNDI with the same parameters provided in the Initialize command. The transmit and receive queues are emptied and any pending interrupts are cleared. Depending on the state of the OpFlags, the receive filters and external interrupt enables may also be reset.

Resetting the network device may take up to four seconds and in some extreme cases (usually poor cables) up to twenty seconds. Control will not be returned to the caller and the **COMMAND_COMPLETE** status flag will not be set until the NIC is ready to transmit.

E.4.8.1 Issuing the Command

To issue a Reset command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a Reset command
OpCode	PXE_OPCODE_RESET
OpFlags	Set as needed.
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	PXE_CPBSIZE_NOT_USED
DBaddr	PXE_DBSIZE_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt.
Control	Set as needed.

E.4.8.2 OpFlags

Normally the settings of the receive filters and external interrupt enables are unchanged by the Reset command. These two OpFlags will alter the operation of the Reset command.

```

PXE_OPFLAGS_RESET_DISABLE_INTERRUPTS
PXE_OPFLAGS_RESET_DISABLE_FILTERS

```

E.4.8.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. UNDI and network device have been reset. Check StatFlags.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.8.4 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. UNDI and network device have been reset. Check StatFlags.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.
DEVICE_FAILURE	The network device could not be initialized.
NVDATA_FAILURE	The nonvolatile storage is not valid.

E.4.8.5 StatFlags

Check the StatFlags to see if there is an active connection to this network device. If the no media StatFlag is set, the UNDI and network device are still reset.

PXE_STATFLAGS_RESET_NO_MEDIA

E.4.9 Shutdown

The Shutdown command resets the network adapter and leaves it in a safe state for another driver to initialize. Any pending transmits or receives are lost. Receive filters and external interrupt enables are reset (disabled). The memory buffer assigned in the Initialize command can be released or reassigned.

Once UNDI has been shutdown, it can then be stopped or initialized again. The Shutdown command changes the UNDI operational state from initialized to started.

E.4.9.1 Issuing the Command

To issue a Shutdown command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Shutdown command
OpCode	PXE_OPCODE_SHUTDOWN
OpFlags	PXE_OPFLAGS_NOT_USED
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	PXE_CPBSIZE_NOT_USED
DBaddr	PXE_DBSIZE_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.9.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. UNDI and network device are shutdown.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.9.3 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. UNDI and network device are shutdown.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.10 Interrupt Enables

The Interrupt Enables command can be used to read and/or change the current external interrupt enable settings. Disabling an external interrupt enable prevents an external (hardware) interrupt

from being signaled by the network device, internally the interrupt events can still be polled by using the Get Status command.

E.4.10.1 Issuing the Command

To issue an Interrupt Enables command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for an Interrupt Enables command
OpCode	PXE_OPCODE_INTERRUPT_ENABLES
OpFlags	Set as needed.
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	PXE_DBADDR_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt.
Control	Set as needed.

E.4.10.2 OpFlags

To read the current external interrupt enables settings set **CDB.OpFlags** to:

PXE_OPFLAGS_INTERRUPT_READ

To enable or disable external interrupts set one of these OpFlags:

PXE_OPFLAGS_INTERRUPT_DISABLE

PXE_OPFLAGS_INTERRUPT_ENABLE

When enabling or disabling interrupt settings, the following additional OpFlag bits are used to specify which types of external interrupts are to be enabled or disabled:

PXE_OPFLAGS_INTERRUPT_RECEIVE

PXE_OPFLAGS_INTERRUPT_TRANSMIT

PXE_OPFLAGS_INTERRUPT_COMMAND

PXE_OPFLAGS_INTERRUPT_SOFTWARE

Setting **PXE_OPFLAGS_INTERRUPT_SOFTWARE** does not enable an external interrupt type, it generates an external interrupt.

E.4.10.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. Check StatFlags.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.10.4 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. Check StatFlags.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.10.5 StatFlags

If the command was successful, the **CDB.StatFlags** field reports which external interrupt enable types are currently set. Possible **CDB.StatFlags** bit settings are:

- **PXE_STATFLAGS_INTERRUPT_RECEIVE**
- **PXE_STATFLAGS_INTERRUPT_TRANSMIT**
- **PXE_STATFLAGS_INTERRUPT_COMMAND**

The bits set in **CDB.StatFlags** may be different than those that were requested in **CDB.OpFlags**. For example: If transmit and receive share an external interrupt line, setting either the transmit or receive interrupt will always enable both transmit and receive interrupts. In this case both transmit and receive interrupts will be reported in **CDB.StatFlags**. Always expect to get more than you ask for!

E.4.11 Receive Filters

This command is used to read and change receive filters and, if supported, read and change the multicast MAC address filter list. Control will not be returned to the caller and the **COMMAND_COMPLETE** status flag will not be set until the NIC is ready to receive.

E.4.11.1 Issuing the Command

To issue a Receive Filters command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a Receive Filters command
OpCode	PXE_OPCODE_RECEIVE_FILTERS
OpFlags	Set as needed.
CPBsize	sizeof(PXE_CPB_RECEIVE_FILTERS)
DBsize	sizeof(PXE_DB_RECEIVE_FILTERS)
CPBaddr	Address of PXE_CPB_RECEIVE_FILTERS structure.
DBaddr	Address of PXE_DB_RECEIVE_FILTERS structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .

CDB Field	How to initialize the CDB structure for a Receive Filters command
Control	Set as needed.

E.4.11.2 OpFlags

To read the current receive filter settings set the **CDB.OpFlags** field to:

- **PXE_OPFLAGS_RECEIVE_FILTER_READ**

To change the current receive filter settings set one of these OpFlag bits:

- **PXE_OPFLAGS_RECEIVE_FILTER_ENABLE**
- **PXE_OPFLAGS_RECEIVE_FILTER_DISABLE**

When changing the receive filter settings, at least one of the OpFlag bits in this list must be selected:

- **PXE_OPFLAGS_RECEIVE_FILTER_UNICAST**
- **PXE_OPFLAGS_RECEIVE_FILTER_BROADCAST**
- **PXE_OPFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST**
- **PXE_OPFLAGS_RECEIVE_FILTER_PROMISCUOUS**
- **PXE_OPFLAGS_RECEIVE_FILTER_ALL_MULTICAST**

To clear the contents of the multicast MAC address filter list, set this OpFlag:

- **PXE_OPFLAGS_RECEIVE_FILTER_RESET_MCAST_LIST**

E.4.11.3 Preparing the CPB

The receive filter CPB is used to change the contents multicast MAC address filter list. To leave the multicast MAC address filter list unchanged, set the **CDB.CPBsize** field to **PXE_CPBSIZE_NOT_USED** and **CDB.CPBaddr** to **PXE_CPBADDR_NOT_USED**.

To change the multicast MAC address filter list, set **CDB.CPBsize** to the size, in bytes, of the multicast MAC address filter list and set **CDB.CPBaddr** to the address of the first entry in the multicast MAC address filter list.

```
typedef struct s_pxe_cpb_receive_filters {

    // List of multicast MAC addresses. This list, if present,
    // will replace the existing multicast MAC address filter list.

    PXE_MAC_ADDR MCastList[n];
} PXE_CPB_RECEIVE_FILTERS;
```

E.4.11.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. Check StatFlags. DB is written.
COMMAND_FAILED	Command failed. StatCode field contains error code.

StatFlags	Reason
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.11.5 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. Check StatFlags. DB is written.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.11.6 StatFlags

The receive filter settings in CDB.StatFlags are:

- **PXE_STATFLAGS_RECEIVE_FILTER_UNICAST**
- **PXE_STATFLAGS_RECEIVE_FILTER_BROADCAST**
- **PXE_STATFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST**
- **PXE_STATFLAGS_RECEIVE_FILTER_PROMISCUOUS**
- **PXE_STATFLAGS_RECEIVE_FILTER_ALL_MULTICAST**

Unsupported receive filter settings in OpFlags are promoted to the next more liberal receive filter setting. For example: If broadcast or filtered multicast are requested and are not supported by the network device, but promiscuous is; the promiscuous status flag will be set.

E.4.11.7 DB

The DB is used to read the current multicast MAC address filter list. The CDB.DBsize and CDB.DBaddr fields can be set to PXE_DBSIZE_NOT_USED and PXE_DBADDR_NOT_USED if the multicast MAC address filter list does not need to be read. When reading the multicast MAC address filter list extra entries in the DB will be filled with zero.

```
typedef struct s_pxe_db_receive_filters {

    // Filtered multicast MAC address list.

    PXE_MAC_ADDR MCastList[n];
} PXE_DB_RECEIVE_FILTERS;
```

E.4.12 Station Address

This command is used to get current station and broadcast MAC addresses and, if supported, to change the current station MAC address.

E.4.12.1 Issuing the Command

To issue a Station Address command, create a CDB and fill it in as shows in the table below:

CDB Field	How to initialize the CDB structure for a Station Address command
OpCode	PXE_OPCODE_STATION_ADDRESS
OpFlags	Set as needed.
CPBsize	sizeof(PXE_CPB_STATION_ADDRESS)
DBsize	sizeof(PXE_DB_STATION_ADDRESS)
CPBaddr	Address of <code>PXE_CPB_STATION_ADDRESS</code> structure.
DBaddr	Address of <code>PXE_DB_STATION_ADDRESS</code> structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to <code>!PXE.IFcnt</code> .
Control	Set as needed.

E.4.12.2 OpFlags

To read current station and broadcast MAC addresses set the OpFlags field to:

- `PXE_OPFLAGS_STATION_ADDRESS_READ`

To change the current station to the address given in the CPB set the OpFlags field to:

- `PXE_OPFLAGS_STATION_ADDRESS_WRITE`

To reset the current station address back to the power on default, set the OpFlags field to:

- `PXE_OPFLAGS_STATION_ADDRESS_RESET`

E.4.12.3 Preparing the CPB

To change the current station MAC address the `CDB.CPBsize` and `CDB.CPBaddr` fields must be set.

```
typedef struct s_pxe_cpb_station_address {

    // If supplied and supported, the current station MAC address
    // will be changed.

    PXE_MAC_ADDR    StationAddr;
} PXE_CPB_STATION_ADDRESS;
```


E.4.12.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. DB is written.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.12.5 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.
UNSUPPORTED	The requested operation is not supported.

E.4.12.6 Before Using the DB

The DB is used to read the current station, broadcast and permanent station MAC addresses. The **CDB.DBsize** and **CDB.DBaddr** fields can be set to **PXE_DBSIZE_NOT_USED** and **PXE_DBADDR_NOT_USED** if these addresses do not need to be read.

```
typedef struct s_pxe_db_station_address {  
  
    // Current station MAC address.  
    PXE_MAC_ADDR    StationAddr;  
  
    // Station broadcast MAC address.  
    PXE_MAC_ADDR    BroadcastAddr;  
  
    // Permanent station MAC address.  
    PXE_MAC_ADDR    PermanentAddr;  
} PXE_DB_STATION_ADDRESS;
```

E.4.13 Statistics

This command is used to read and clear the NIC traffic statistics. Before using this command check to see if statistics is supported in the **!PXE.Implementation** flags.

E.4.13.1 Issuing the Command

To issue a Statistics command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Statistics command
OpCode	PXE_OPCODE_STATISTICS
OpFlags	Set as needed.
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	sizeof(PXE_DB_STATISTICS)
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	Address of PXE_DB_STATISTICS structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.13.2 OpFlags

To read the current statistics counters set the OpFlags field to:

PXE_OPFLAGS_STATISTICS_READ

To reset the current statistics counters set the OpFlags field to:

PXE_OPFLAGS_STATISTICS_RESET

E.4.13.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. DB is written.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.13.4 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. DB is written.
INVALID_CDB	One of the CDB fields was not set correctly.

StatCode	Reason
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.
UNSUPPORTED	This command is not supported.

E.4.13.5 DB

Unsupported statistics counters will be zero filled by UNDI.

```

typedef struct s_pxe_db_statistics {

    // Bit field identifying what statistic data is collected by
    // the UNDI/NIC.
    // If bit 0x00 is set, Data[0x00] is collected.
    // If bit 0x01 is set, Data[0x01] is collected.
    // If bit 0x20 is set, Data[0x20] is collected.
    // If bit 0x21 is set, Data[0x21] is collected.
    // Etc.
    PXE_UINT64    Supported;

    // Statistic data.

    PXE_UINT64    Data[64];
} PXE_DB_STATISTICS;

// Total number of frames received.  Includes frames with errors
// and dropped frames.
#define PXE_STATISTICS_RX_TOTAL_FRAMES        0x00

// Number of valid frames received and copied into receive
// buffers.
#define PXE_STATISTICS_RX_GOOD_FRAMES        0x01

// Number of frames below the minimum length for the media.
// This would be <64 for ethernet.
#define PXE_STATISTICS_RX_UNDERSIZE_FRAMES    0x02

// Number of frames longer than the maximum length for the
// media.  This would be >1500 for ethernet.
#define PXE_STATISTICS_RX_OVERSIZE_FRAMES    0x03

// Valid frames that were dropped because receive buffers
// were full.
#define PXE_STATISTICS_RX_DROPPED_FRAMES    0x04

// Number of valid unicast frames received and not dropped.

```

```

#define PXE_STATISTICS_RX_UNICAST_FRAMES      0x05

// Number of valid broadcast frames received and not dropped.
#define PXE_STATISTICS_RX_BROADCAST_FRAMES    0x06

// Number of valid mutlicast frames received and not dropped.
#define PXE_STATISTICS_RX_MULTICAST_FRAMES    0x07

// Number of frames w/ CRC or alignment errors.
#define PXE_STATISTICS_RX_CRC_ERROR_FRAMES    0x08

// Total number of bytes received.  Includes frames with errors
// and dropped frames.
#define PXE_STATISTICS_RX_TOTAL_BYTES        0x09

// Transmit statistics.
#define PXE_STATISTICS_TX_TOTAL_FRAMES       0x0A
#define PXE_STATISTICS_TX_GOOD_FRAMES       0x0B
#define PXE_STATISTICS_TX_UNDERSIZE_FRAMES   0x0C
#define PXE_STATISTICS_TX_OVERSIZE_FRAMES   0x0D
#define PXE_STATISTICS_TX_DROPPED_FRAMES    0x0E
#define PXE_STATISTICS_TX_UNICAST_FRAMES    0x0F
#define PXE_STATISTICS_TX_BROADCAST_FRAMES  0x10
#define PXE_STATISTICS_TX_MULTICAST_FRAMES  0x11
#define PXE_STATISTICS_TX_CRC_ERROR_FRAMES  0x12
#define PXE_STATISTICS_TX_TOTAL_BYTES       0x13

// Number of collisions detection on this subnet.
#define PXE_STATISTICS_COLLISIONS           0x14

// Number of frames destined for unsupported protocol.
#define PXE_STATISTICS_UNSUPPORTED_PROTOCOL  0x15

```

E.4.14 MCast IP To MAC

Translate a multicast IPv4 or IPv6 address to a multicast MAC address.

E.4.14.1 Issuing the Command

To issue a MCast IP To MAC command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a MCast IP To MAC command
OpCode	PXE_OPCODE_MCAST_IP_TO_MAC
OpFlags	Set as needed.
CPBsize	sizeof(PXE_CPB_MCAST_IP_TO_MAC)
DBsize	sizeof(PXE_DB_MCAST_IP_TO_MAC)
CPBaddr	Address of <code>PXE_CPB_MCAST_IP_TO_MAC</code> structure.
Dbaddr	Address of <code>PXE_DB_MCAST_IP_TO_MAC</code> structure.

CDB Field	How to initialize the CDB structure for a MCast IP To MAC command
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
lfnm	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.14.2 OpFlags

To convert a multicast IP address to a multicast MAC address the UNDI needs to know the format of the IP address. Set one of these OpFlags to identify the format of the IP addresses in the CPB:

```
PXE_OPFLAGS_MCAST_IPV4_TO_MAC
PXE_OPFLAGS_MCAST_IPV6_TO_MAC
```

E.4.14.3 Preparing the CPB

Fill in an array of one or more multicast IP addresses. Be sure to set the **CDB.CPBsize** and **CDB.CPBaddr** fields accordingly.

```
typedef struct s_pxe_cpb_mcast_ip_to_mac {

    // Multicast IP address to be converted to multicast
    // MAC address.
    PXE_IP_ADDR    IP[n];
} PXE_CPB_MCAST_IP_TO_MAC;
```

E.4.14.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. DB is written.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.14.5 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. DB is written.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.

StatCode	Reason
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.14.6 Before Using the DB

The DB is where the multicast MAC addresses will be written.

```
typedef struct s_pxe_db_mcast_ip_to_mac {

    // Multicast MAC address.

    PXE_MAC_ADDR  MAC[n];
} PXE_DB_MCAST_IP_TO_MAC;
```

E.4.15 NvData

This command is used to read and write (if supported by NIC H/W) nonvolatile storage on the NIC. Nonvolatile storage could be EEPROM, FLASH or battery backed RAM.

E.4.15.1 Issuing the Command

To issue a NvData command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a NvData command
OpCode	PXE_OPCODE_NVDATA
OpFlags	Set as needed.
CPBsize	sizeof(PXE_CPB_NVDATA)
DBsize	sizeof(PXE_DB_NVDATA)
CPBaddr	Address of PXE_CPB_NVDATA structure.
Dbaddr	Address of PXE_DB_NVDATA structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
lfnm	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.15.2 Preparing the CPB

There are two types of nonvolatile data CPBs, one for sparse updates and one for bulk updates. Sparse updates allow updating of single nonvolatile storage items. Bulk updates always update all nonvolatile storage items. Check the **!PXE.Implementation** flags to see which type of nonvolatile update is supported by this UNDI and network device.

If you do not need to update the nonvolatile storage set the **CDB.CPBsize** and **CDB.CPBaddr** fields to **PXE_CPBSIZE_NOT_USED** and **PXE_CPBADDR_NOT_USED**.

E.4.15.2.1 Sparse NvData CPB

```
typedef struct s_pxe_cpb_nvdata_sparse {
```

```

// NvData item list. Only items in this list will be updated.

struct {

    // Nonvolatile storage address to be changed.
    PXE_UINT32    Addr;

    // Data item to write into above storage address.
    union {
        PXE_UINT8    Byte;
        PXE_UINT16   Word;
        PXE_UINT32   Dword;
    } Data;
} Item[n];
} PXE_CPB_NVDATA_SPARSE;

```

E.4.15.2.2 Bulk NvData CPB

```

// When using bulk update, the size of the CPB structure must be
// the same size as the nonvolatile NIC storage.

```

```

typedef union u_pxe_cpb_nvdata_bulk {

    // Array of byte-wide data items.
    PXE_UINT8    Byte[n];

    // Array of word-wide data items.
    PXE_UINT16   Word[n];

    // Array of dword-wide data items.
    PXE_UINT32   Dword[n];
} PXE_CPB_NVDATA_BULK;

```

E.4.15.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. Nonvolatile data is updated from CPB and/or written to DB.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.15.4 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. Nonvolatile data is updated from CPB and/or written to DB.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.
UNSUPPORTED	Requested operation is unsupported.

E.4.15.4.1 DB

Check the width and number of nonvolatile storage items. This information is returned by the Get Init Info command.

```
typedef struct s_pxe_db_nvdata {

    // Arrays of data items from nonvolatile storage.
    union {

        // Array of byte-wide data items.
        PXE_UINT8  Byte[n];

        // Array of word-wide data items.
        PXE_UINT16 Word[n];

        // Array of dword-wide data items.
        PXE_UINT32 Dword[n];

    } Data;
} PXE_DB_NVDATA;
```

E.4.16 Get Status

This command returns the current interrupt status and/or the transmitted buffer addresses. If the current interrupt status is returned, pending interrupts will be acknowledged by this command. Transmitted buffer addresses that are written to the DB are removed from the transmitted buffer queue.

This command may be used in a polled fashion with external interrupts disabled.

E.4.16.1 Issuing the Command

To issue a Get Status command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Get Status command
OpCode	PXE_OPCODE_GET_STATUS
OpFlags	Set as needed.
CPBsize	PXE_CPBSIZE_NOT_USED
DBsize	Sizeof(PXE_DB_GET_STATUS)
CPBaddr	PXE_CPBADDR_NOT_USED
DBaddr	Address of PXE_DB_GET_STATUS structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.16.1.1 Setting OpFlags

Set one or both of the OpFlags below to return the interrupt status and/or the transmitted buffer addresses.

PXE_OPFLAGS_GET_INTERRUPT_STATUS
PXE_OPFLAGS_GET_TRANSMITTED_BUFFERS

E.4.16.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. StatFlags and/or DB are updated.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.16.3 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. StatFlags and/or DB are updated.
INVALID_CDB	One of the CDB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.16.4 StatFlags

If the command completes successfully and the `PXE_OPFLAGS_GET_INTERRUPT_STATUS` OpFlag was set in the CDB, the current interrupt status is returned in the `CDB.StatFlags` field and any pending interrupts will have been cleared.

```
PXE_STATFLAGS_GET_STATUS_RECEIVE
PXE_STATFLAGS_GET_STATUS_TRANSMIT
PXE_STATFLAGS_GET_STATUS_COMMAND
PXE_STATFLAGS_GET_STATUS_SOFTWARE
```

The StatFlags above may not map directly to external interrupt signals. For example: Some NICs may combine both the receive and transmit interrupts to one external interrupt line. When a receive and/or transmit interrupt occurs, use the Get Status to determine which type(s) of interrupt(s) occurred.

This flag is set if the transmitted buffer queue is empty. This flag will be set if all transmitted buffer addresses get written into the DB.

```
PXE_STATFLAGS_GET_STATUS_TXBUF_QUEUE_EMPTY
```

This flag is set if no transmitted buffer addresses were written into the DB.

```
PXE_STATFLAGS_GET_STATUS_NO_TXBUFS_WRITTEN
```

E.4.16.5 Using the DB

When reading the transmitted buffer addresses there should be room for at least one 64-bit address in the DB. Once a complete transmitted buffer address is written into the DB, the address is removed from the transmitted buffer queue. If the transmitted buffer queue is full, attempts to use the Transmit command will fail.

```
#pragma pack(1)
typedef struct s_pxe_db_get_status {

    // Length of next receive frame (header + data). If this is
    // zero, there is no next receive frame available.

    PXE_UINT32    RxFrameLen;

    // Reserved, set to zero.

    PXE_UINT32    reserved;

    // Addresses of transmitted buffers that need to be recycled.

    PXE_UINT64    xBuffer[n];
} PXE_DB_GET_STATUS;
#pragma pack()
```

E.4.17 Fill Header

This command is used to fill the media header(s) in transmit packet(s).

E.4.17.1 Issuing the Command

To issue a Fill Header command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Fill Header command
OpCode	PXE_OPCODE_FILL_HEADER
OpFlags	Set as needed.
CPBsize	PXE_CPB_FILL_HEADER
DBsize	PXE_DBSIZE_NOT_USED
CPBaddr	Address of a PXE_CPB_FILL_HEADER structure.
DBaddr	PXE_DBADDR_NOT_USED
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.17.2 OpFlags

Select one of the OpFlags below so the UNDI knows what type of CPB is being used.

PXE_OPFLAGS_FILL_HEADER_WHOLE

PXE_OPFLAGS_FILL_HEADER_FRAGMENTED

E.4.17.3 Preparing the CPB

If multiple frames per command are supported (see **!PXE.Implementation** flags), multiple CPBs can be packed together. The **CDB.CPBsize** field lets the UNDI know how many CPBs are packed together.

E.4.17.4 Nonfragmented Frame

```
#pragma pack(1)
typedef struct s_pxe_cpb_fill_header {

    // Source and destination MAC addresses. These will be copied
    // into the media header without doing byte swapping.
    PXE_MAC_ADDR SrcAddr;
    PXE_MAC_ADDR DestAddr;

    // Address of first byte of media header. The first byte of
    // packet data follows the last byte of the media header.
    PXE_UINT64 MediaHeader;

    // Length of packet data in bytes (not including the media
    // header).
    PXE_UINT32 PacketLen;

    // Protocol type. This will be copied into the media header
    // without doing byte swapping. Protocol type numbers can be
    // obtained from the Assigned Numbers RFC 1700.
```

```

    PXE_UINT16    Protocol;

    // Length of the media header in bytes.
    PXE_UINT16    MediaHeaderLen;
} PXE_CPB_FILL_HEADER;
#pragma pack()

#define PXE_PROTOCOL_ETHERNET_IP        0x0800
#define PXE_PROTOCOL_ETHERNET_ARP      0x0806

```

E.4.17.5 Fragmented Frame

```

#pragma pack(1)
typedef struct s_pxe_cpb_fill_header_fragmented {

    // Source and destination MAC addresses.  These will be copied
    // into the media header without doing byte swapping.
    PXE_MAC_ADDR    SrcAddr;
    PXE_MAC_ADDR    DestAddr;

    // Length of packet data in bytes (not including the media
    // header).

    PXE_UINT32    PacketLen;
    // Protocol type.  This will be copied into the media header
    // without doing byte swapping.  Protocol type numbers can be
    // obtained from the Assigned Numbers RFC 1700.
    PXE_MEDIA_PROTOCOL    Protocol;

    // Length of the media header in bytes.
    PXE_UINT16    MediaHeaderLen;

    // Number of packet fragment descriptors.
    PXE_UINT16    FragCnt;

    // Reserved, must be set to zero.
    PXE_UINT16    reserved;

    // Array of packet fragment descriptors.  The first byte of the
    // media header is the first byte of the first fragment.

    struct {

        // Address of this packet fragment.
        PXE_UINT64    FragAddr;

        // Length of this packet fragment.
        PXE_UINT32    FragLen;
    }
}

```

```

        // Reserved, must be set to zero.
        PXE_UINT32 reserved;
    } FragDesc[n];
} PXE_CPB_FILL_HEADER_FRAGMENTED;
#pragma pack()

```

E.4.17.6 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. Frame is ready to transmit.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.17.7 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. Frame is ready to transmit.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Try again later.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.18 Transmit

The Transmit command is used to place a packet into the transmit queue. The data buffers given to this command are to be considered locked and the application or universal network driver loses the ownership of those buffers and must not free or relocate them until the ownership returns.

When the packets are transmitted, a transmit complete interrupt is generated (if interrupts are disabled, the transmit interrupt status is still set and can be checked using the Get Status command).

Some UNDI implementations and network adapters support transmitting multiple packets with one transmit command. If this feature is supported, multiple transmit CPBs can be linked in one transmit command.

Though all UNDI support fragmented frames, the same cannot be said for all network devices or protocols. If a fragmented frame CPB is given to UNDI and the network device does not support fragmented frames (see **!PXE.Implementation** flags), the UNDI will have to copy the fragments into a local buffer before transmitting.

E.4.18.1 Issuing the Command

To issue a Transmit command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Transmit command
OpCode	PXE_OPCODE_TRANSMIT
OpFlags	Set as needed.
CPBsize	<code>sizeof(PXE_CPB_TRANSMIT)</code>
DBsize	<code>PXE_DBSIZE_NOT_USED</code>
CPBaddr	Address of a <code>PXE_CPB_TRANSMIT</code> structure.
DBaddr	<code>PXE_DBADDR_NOT_USED</code>
StatCode	<code>PXE_STATCODE_INITIALIZE</code>
StatFlags	<code>PXE_STATFLAGS_INITIALIZE</code>
IFnum	A valid interface number from zero to <code>!PXE.IFcnt</code> .
Control	Set as needed.

E.4.18.2 OpFlags

Check the `!PXE.Implementation` flags to see if the network device support fragmented packets. Select one of the OpFlags below so the UNDI knows what type of CPB is being used.

`PXE_OPFLAGS_TRANSMIT_WHOLE`

`PXE_OPFLAGS_TRANSMIT_FRAGMENTED`

In addition to selecting whether or not fragmented packets are being given, S/W UNDI needs to know if it should block until the packets are transmitted. H/W UNDI cannot block, these two OpFlag settings have no affect when used with H/W UNDI.

`PXE_OPFLAGS_TRANSMIT_BLOCK`

`PXE_OPFLAGS_TRANSMIT_DONT_BLOCK`

E.4.18.3 Preparing the CPB

If multiple frames per command are supported (see `!PXE.Implementation` flags), multiple CPBs can be packed together. The `CDB.CPBsize` field lets the UNDI know how may frames are to be transmitted.

E.4.18.4 Nonfragmented Frame

```
#pragma pack(1)
```

```
typedef struct s_pxe_cpb_transmit {
```

```
    // Address of first byte of frame buffer. This is also the
    // first byte of the media header. This address must be a
    // processor-based address for S/W UNDI and a device-based
    // address for H/W UNDI.
```

```
    PXE_UINT64    FrameAddr;
```

```
    // Length of the data portion of the frame buffer in bytes. Do
    // not include the length of the media header.
```

```

PXE_UINT32  DataLen;

// Length of the media header in bytes.
PXE_UINT16  MediaheaderLen;

// Reserved, must be zero.
PXE_UINT16  reserved;
} PXE_CPB_TRANSMIT;
#pragma pack()

```

E.4.18.5 Fragmented Frame

```

#pragma pack(1)
typedef struct s_pxe_cpb_transmit_fragments {

// Length of packet data in bytes (not including the media
// header).
PXE_UINT32  FrameLen;

// Length of the media header in bytes.
PXE_UINT16  MediaheaderLen;

// Number of packet fragment descriptors.
PXE_UINT16  FragCnt;

// Array of frame fragment descriptors. The first byte of the
// first fragment is also the first byte of the media header.
struct {
// Address of this frame fragment. This address must be a
// processor-based address for S/W UNDI and a device-based
// address for H/W UNDI.
PXE_UINT64  FragAddr;

// Length of this frame fragment.
PXE_UINT32  FragLen;

// Reserved, must be set to zero.
PXE_UINT32  reserved;
} FragDesc[n];
} PXE_CPB_TRANSMIT_FRAGMENTS;
#pragma pack()

```

E.4.18.6 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
-----------	--------

COMMAND_COMPLETE	Command completed successfully. Use the Get Status command to see when frame buffers can be reused.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.18.7 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. Use the Get Status command to see when frame buffers can be reused.
INVALID_CDB	One of the CDB fields was not set correctly.
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Wait for queued commands to complete. Try again later.
BUFFER_FULL	Transmit buffer is full. Call Get Status command to empty buffer.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.19 Receive

When the network adapter has received a frame, this command is used to copy the frame into driver/application storage. Once a frame has been copied, it is removed from the receive queue.

E.4.19.1 Issuing the Command

To issue a Receive command, create a CDB and fill it in as shown in the table below:

CDB Field	How to initialize the CDB structure for a Receive command
OpCode	PXE_OPCODE_RECEIVE
OpFlags	Set as needed.
CPBsize	sizeof(PXE_CPB_RECEIVE)
DBsize	sizeof(PXE_DB_RECEIVE)
CPBaddr	Address of a PXE_CPB_RECEIVE structure.
DBaddr	Address of a PXE_DB_RECEIVE structure.
StatCode	PXE_STATCODE_INITIALIZE
StatFlags	PXE_STATFLAGS_INITIALIZE
IFnum	A valid interface number from zero to !PXE.IFcnt .
Control	Set as needed.

E.4.19.2 Preparing the CPB

If multiple frames per command are supported (see **!PXE.Implementation** flags), multiple CPBs can be packed together. For each complete received frame, a receive buffer large enough to contain the entire unfragmented frame needs to be described in the CPB. Note that if a smaller than required buffer is provided, only a portion of the packet is received into the buffer, and the remainder of the packet is lost. Subsequent attempts to receive the same packet with a corrected (larger) buffer will be unsuccessful, because the packet will have been flushed from the queue.

```
#pragma pack(1)
typedef struct s_pxe_cpb_receive {

    // Address of first byte of receive buffer. This is also the
    // first byte of the frame header. This address must be a
    // processor-based address for S/W UNDI and a device-based
    // address for H/W UNDI.

    PXE_UINT64    BufferAddr;

    // Length of receive buffer. This must be large enough to hold
    // the received frame (media header + data). If the length of
    // smaller than the received frame, data will be lost.
    PXE_UINT32    BufferLen;

    // Reserved, must be set to zero.
    PXE_UINT32    reserved;
} PXE_CPB_RECEIVE;
#pragma pack()
```

E.4.19.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the **CDB.StatFlags** field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

StatFlags	Reason
COMMAND_COMPLETE	Command completed successfully. Frames received and DB is written.
COMMAND_FAILED	Command failed. StatCode field contains error code.
COMMAND_QUEUED	Command has been queued.
INITIALIZE	Command has been not executed or queued.

E.4.19.4 Checking Command Execution Results

After command execution completes, either successfully or not, the **CDB.StatCode** field contains the result of the command execution.

StatCode	Reason
SUCCESS	Command completed successfully. Frames received and DB is written.
INVALID_CDB	One of the CDB fields was not set correctly.

StatCode	Reason
INVALID_CPB	One of the CPB fields was not set correctly.
BUSY	UNDI is already processing commands. Try again later.
QUEUE_FULL	Command queue is full. Wait for queued commands to complete. Try again later.
NO_DATA	Receive buffers are empty.
NOT_STARTED	The UNDI is not started.
NOT_INITIALIZED	The UNDI is not initialized.

E.4.19.5 Using the DB

If multiple frames per command are supported (see **!PXE.Implementation** flags), multiple DBs can be packed together.

```
#pragma pack(1)
typedef struct s_pxe_db_receive {

    // Source and destination MAC addresses from media header.
    PXE_MAC_ADDR    SrcAddr;
    PXE_MAC_ADDR    DestAddr;

    // Length of received frame. May be larger than receive buffer
    // size. The receive buffer will not be overwritten. This is
    // how to tell if data was lost because the receive buffer was
    // too small.
    PXE_UINT32    FrameLen;

    // Protocol type from media header.
    PXE_PROTOCOL    Protocol;

    // Length of media header in received frame.
    PXE_UINT16    MediaHeaderLen;

    // Type of receive frame.
    PXE_FRAME_TYPE    Type;

    // Reserved, must be zero.
    PXE_UINT8    reserved[7];
} PXE_DB_RECEIVE;
#pragma pack()
```

E.5 UNDI as an EFI Runtime Driver

This section defines the interface between UNDI and EFI and how UNDI must be initialized as an EFI runtime driver.

In the EFI environment, UNDI must implement the Network Interface Identifier (NII) protocol and install an interface pointer of the type NII protocol with EFI. It must also install a device path protocol with a device path that includes the hardware device path (such as PCI) appended with the

NIC's MAC address. If the UNDI drives more than one NIC device, it must install one set of NII and device path protocols for each device it controls.

UNDI must be compiled as a runtime driver so that when the operating system loads, a universal protocol driver can use the UNDI driver to access the NIC hardware.

For the universal driver to be able to find UNDI, UNDI must install a configuration table (using the EFI boot service [InstallConfigurationTable\(\)](#)) for the GUID [EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL](#). The format of the configuration table for UNDI is defined as follows.

```
struct undiconfig_table {
    UINT32 NumberOfInterfaces;    //The number of NIC devices
                                // that this UNDI controls.

    UINT32 reserved;

    struct undiconfigtable *nextlink;
                                // A pointer to the next UNDI
                                // configuration table.

    struct {
        VOID *NII_InterfacePointer;
                                // Pointer to the NII interface structure.
        VOID *DevicePathPointer;
                                // pointer to the device path for this NIC
    } NII_entry[n];             // The length of this array is given in
                                // the NumberOfInterfaces field.
} UNDI_CONFIG_TABLE;
```

Since there can only be one configuration table associated with any GUID and there can be more than one UNDI loaded, every instance of UNDI must check for any previous installations of the configuration tables and if there are any, it must traverse through the list of all UNDI configuration tables using the nextlink and install itself as the nextlink of the last table in the list.

The universal protocol driver is responsible for converting all the pointers in the UNDI_CONFIGURATION_TABLE to virtual addresses before accessing them. However, UNDI must install an event handler for the SET_VIRTUAL_ADDRESS event and convert all its internal pointers into virtual addresses when the event occurs for the universal protocol driver to be able to use UNDI.

Appendix F

Using the Simple Pointer Protocol

The Simple Pointer Protocol is intended to provide a simple mechanism for an application to interact with the user with some type of pointer device. To keep this interface simple, many of the custom controls that are typically present in an OS-present environment were left out. This includes the ability to adjust the double-click speed and the ability to adjust the pointer speed. Instead, the recommendations for how the Simple Pointer Protocol should be used are listed here.

X-Axis Movement:

If the Simple Pointer Protocol is being used to move a pointer or cursor around on an output display, the movement along the x-axis should move the pointer or cursor horizontally.

Y-Axis Movement:

If the Simple Pointer Protocol is being used to move a pointer or cursor around on an output display, the movement along the y-axis should move the pointer or cursor vertically.

Z-Axis Movement:

If the Simple Pointer Protocol is being used to move a pointer or cursor around on an output display, and the application that is using the Simple Pointer Protocol supports scrolling, then the movement along the z-axis should scroll the output display.

Double Click Speed:

If two clicks of the same button on a pointer occur in less than 0.5 seconds, then a double-click event has occurred. If a the same button is pressed with more than 0.5 seconds between clicks, then this is interpreted as two single-click events.

Pointer Speed:

The Simple Pointer Protocol returns the movement of the pointer device along an axis in counts. The Simple Pointer Protocol also contains a set of resolution fields that define the number of counts that will be received for each millimeter of movement of the pointer device along an axis. From these two values, the consumer of this protocol can determine the distance the pointer device has been moved in millimeters along an axis. For most applications, movement of a pointer device will result in the movement of a pointer on the screen. For each millimeter of motion by the pointer device in the x-axis, the pointer on the screen will be moved 2 percent of the screen width. For each millimeter of motion by the pointer device in the y-axis, the pointer on the screen will be moved 2 percent of the screen height.

Appendix G

Using the EFI SCSI Pass Thru Protocol

This appendix describes how an EFI utility might gain access to the EFI SCSI Pass Thru interfaces. The basic concept is to use the [LocateHandle\(\)](#) boot service to retrieve the list of handles that support the [EFI_EXT_SCSI_PASS_THRU_PROTOCOL](#). Each of these handles represents a different SCSI channel present in the system. Each of these handles can then be used to retrieve the [EFI_EXT_SCSI_PASS_THRU_PROTOCOL](#) interface with the [HandleProtocol\(\)](#) boot service. The [EFI_EXT_SCSI_PASS_THRU_PROTOCOL](#) interface provides the services required to access any of the SCSI devices attached to a SCSI channel. The services of the [EFI_EXT_SCSI_PASS_THRU_PROTOCOL](#) are then to loop through the Target IDs of all the SCSI devices on the SCSI channel.

```
#include "efi.h"
#include "efilib.h"

#include EFI_PROTOCOL_DEFINITION(ScsiPassThru)

EFI_GUID gEfiScsiPassThruProtocolGuid = EFI_SCSI_PASS_THRU_PROTOCOL_GUID;

EFI_STATUS
UtilityEntryPoint(
    EFI_HANDLE      ImageHandle,
    EFI_SYSTEM_TABLE SystemTable
)
{
    EFI_STATUS      Status;
    UINTN           NoHandles;
    EFI_HANDLE      *HandleBuffer;
    UINTN           Index;
    EFI_SCSI_PASS_THRU_PROTOCOL *ScsiPassThruProtocol;

    //
    // Initialize EFI Library
    //
    InitializeLib (ImageHandle, SystemTable);

    //
    // Get list of handles that support the
    // EFI_SCSI_PASS_THRU_PROTOCOL
    //
    NoHandles = 0;
    HandleBuffer = NULL;
    Status = LibLocateHandle(
        ByProtocol,
        &gEfiScsiPassThruProtocolGuid,
        NULL,
        &NoHandles,
        &HandleBuffer
    );

    if (EFI_ERROR(Status)) {
        BS->Exit(ImageHandle, EFI_SUCCESS, 0, NULL);
    }
}
```

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```
//
// Loop through all the handles that support
// EFI_SCSI_PASS_THRU
//
for (Index = 0; Index < NoHandles; Index++) {

    //
    // Get the EFI_SCSI_PASS_THRU_PROTOCOL Interface
    // on each handle
    //
    BS->HandleProtocol(
        HandleBuffer[Index],
        &gEfiScsiPassThruProtocolGuid,
        (VOID **)&ScsiPassThruProtocol
    );

    if (!EFI_ERROR(Status)) {

        //
        // Use the EFI_SCSI_PASS_THRU Interface to
        // perform tests
        //
        Status = DoScsiTests(ScsiPassThruProtocol);
    }
}
return EFI_SUCCESS;
}

EFI_STATUS
DoScsiTests(
    EFI_SCSI_PASS_THRU_PROTOCOL *ScsiPassThruProtocol
)
{
    EFI_STATUS                Status;
    UINT32                    Target;
    UINT64                    Lun;
    EFI_SCSI_PASS_THRU_SCSI_REQUEST_PACKET Packet;
    EFI_EVENT                 Event;

    //
    // Get first Target ID and LUN on the SCSI channel
    //
    Target = 0xffffffff;
    Lun    = 0;
    Status = ScsiPassThruProtocol->GetNextDevice(
        ScsiPassThruProtocol,
        &Target,
        &Lun
    );

    //
    // Loop through all the SCSI devices on the SCSI channel
    //
    while (!EFI_ERROR (Status)) {

        //
        // Blocking I/O example.
        // Fill in Packet before calling PassThru()
        //
    }
}
```



```

Status = ScsiPassThruProtocol->PassThru(
    ScsiPassThruProtocol,
    Target,
    Lun,
    &Packet,
    NULL
);

//
// Non Blocking I/O
// Fill in Packet and create Event before calling PassThru()
//
Status = ScsiPassThruProtocol->PassThru(
    ScsiPassThruProtocol,
    Target,
    Lun,
    &Packet,
    &Event
);

//
// Get next Target ID and LUN on the SCSI channel
//
Status = ScsiPassThruProtocol->GetNextDevice(
    ScsiPassThruProtocol,
    &Target,
    &Lun
);
}

return EFI_SUCCESS;
}

```


Appendix H

Compression Source Code

```
/**+
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Module Name:

    Compress.c

Abstract:

    Compression routine. The compression algorithm is a mixture of
    LZ77 and Huffman Coding. LZ77 transforms the source data into a
    sequence of Original Characters and Pointers to repeated strings.
    This sequence is further divided into Blocks and Huffman codings
    are applied to each Block.

Revision History:
--*/

#include <string.h>
#include <stdlib.h>
#include "eficommon.h"

//
// Macro Definitions
//

typedef INT16          NODE;
#define  UINT8_MAX     0xff
#define  UINT8_BIT     8
#define  THRESHOLD    3
#define  INIT_CRC     0
#define  WNDBIT       13
#define  WNDSIZ       (1U << WNDBIT)
#define  MAXMATCH     256
#define  PERC_FLAG    0x8000U
#define  CODE_BIT     16
#define  NIL          0
#define  MAX_HASH_VAL (3 * WNDSIZ + (WNDSIZ / 512 + 1) * UINT8_MAX)
#define  HASH(p, c)   ((p) + ((c) << (WNDBIT - 9)) + WNDSIZ * 2)
#define  CRCPOLY     0xA001
#define  UPDATE_CRC(c) mCrc = mCrcTable[(mCrc ^ (c)) & 0xFF] ^ (mCrc >>
UINT8_BIT)

//
// C: the Char&Len Set; P: the Position Set; T: the exTra Set
//

#define  NC          (UINT8_MAX + MAXMATCH + 2 - THRESHOLD)
#define  CBIT       9
#define  NP         (WNDBIT + 1)
#define  PBIT       4
#define  NT         (CODE_BIT + 3)
```

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```
#define TBIT                5
#if NT > NP
    #define                NPT NT
#else
    #define                NPT NP
#endif

//
// Function Prototypes
//

STATIC
VOID
PutDword(
    IN UINT32 Data
    );

STATIC
EFI_STATUS
AllocateMemory (
    );

STATIC
VOID
FreeMemory (
    );

STATIC
VOID
InitSlide (
    );

STATIC
NODE
Child (
    IN NODE q,
    IN UINT8 c
    );

STATIC
VOID
MakeChild (
    IN NODE q,
    IN UINT8 c,
    IN NODE r
    );

STATIC
VOID
Split (
    IN NODE Old
    );

STATIC
VOID
InsertNode (
    );

STATIC
VOID
DeleteNode (
```

```

    );

    STATIC
    VOID
    GetNextMatch (
    );

    STATIC
    EFI_STATUS
    Encode (
    );

    STATIC
    VOID
    CountTFreq (
    );

    STATIC
    VOID
    WritePTLen (
        IN INT32 n,
        IN INT32 nbit,
        IN INT32 Special
    );

    STATIC
    VOID
    WriteCLen (
    );

    STATIC
    VOID
    EncodeC (
        IN INT32 c
    );

    STATIC
    VOID
    EncodeP (
        IN UINT32 p
    );

    STATIC
    VOID
    SendBlock (
    );

    STATIC
    VOID
    Output (
        IN UINT32 c,
        IN UINT32 p
    );

    STATIC
    VOID
    HufEncodeStart (
    );

    STATIC
    VOID

```

Unified Extensible Firmware Interface Specification

```
HufEncodeEnd (
    );

STATIC
VOID
MakeCrcTable (
    );

STATIC
VOID
PutBits (
    IN INT32 n,
    IN UINT32 x
    );

STATIC
INT32
FreadCrc (
    OUT UINT8 *p,
    IN INT32 n
    );

STATIC
VOID
InitPutBits (
    );

STATIC
VOID
CountLen (
    IN INT32 i
    );

STATIC
VOID
MakeLen (
    IN INT32 Root
    );

STATIC
VOID
DownHeap (
    IN INT32 i
    );

STATIC
VOID
MakeCode (
    IN INT32 n,
    IN UINT8 Len[],
    OUT UINT16 Code[]
    );

STATIC
INT32
MakeTree (
    IN INT32 NParm,
    IN UINT16 FreqParm[],
    OUT UINT8 LenParm[],
    OUT UINT16 CodeParm[]
    );
```

```

//
// Global Variables
//

STATIC UINT8 *mSrc, *mDst, *mSrcUpperLimit, *mDstUpperLimit;

STATIC UINT8 *mLevel, *mText, *mChildCount, *mBuf, mCLen[NC], mPTLen[NPT],
*mLen;
STATIC INT16 mHeap[NC + 1];
STATIC INT32 mRemainder, mMatchLen, mBitCount, mHeapSize, mN;
STATIC UINT32 mBufSiz = 0, mOutputPos, mOutputMask, mSubBitBuf, mCrc;
STATIC UINT32 mCompSize, mOrigSize;

STATIC UINT16 *mFreq, *mSortPtr, mLenCnt[17], mLeft[2 * NC - 1], mRight[2 * NC -
1],
mCrcTable[UINT8_MAX + 1], mCFreq[2 * NC - 1], mCTable[4096],
mCCode[NC],
mPFreq[2 * NP - 1], mPTCode[NPT], mTFreq[2 * NT - 1];

STATIC NODE mPos, mMatchPos, mAvail, *mPosition, *mParent, *mPrev, *mNext =
NULL;

//
// functions
//

EFI_STATUS
Compress (
    IN      UINT8   *SrcBuffer,
    IN      UINT32  SrcSize,
    IN      UINT8   *DstBuffer,
    IN OUT  UINT32  *DstSize
)
/**+

Routine Description:

    The main compression routine.

Arguments:

    SrcBuffer    - The buffer storing the source data
    SrcSize      - The size of the source data
    DstBuffer    - The buffer to store the compressed data
    DstSize      - On input, the size of DstBuffer; On output,
                  the size of the actual compressed data.

Returns:

    EFI_BUFFER_TOO_SMALL - The DstBuffer is too small. In this case,
                          DstSize contains the size needed.
    EFI_SUCCESS          - Compression is successful.

--*/
{
    EFI_STATUS Status = EFI_SUCCESS;

    //

```

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```
// Initializations
//

mBufSiz = 0;
mBuf = NULL;
mText      = NULL;
mLevel     = NULL;
mChildCount = NULL;
mPosition  = NULL;
mParent    = NULL;
mPrev     = NULL;
mNext     = NULL;

mSrc = SrcBuffer;
mSrcUpperLimit = mSrc + SrcSize;
mDst = DstBuffer;
mDstUpperLimit = mDst + *DstSize;

PutDword(0L);
PutDword(0L);

MakeCrcTable ();

mOrigSize = mCompSize = 0;
mCrc = INIT_CRC;

//
// Compress it
//

Status = Encode();
if (EFI_ERROR (Status)) {
    return EFI_OUT_OF_RESOURCES;
}

//
// Null terminate the compressed data
//
if (mDst < mDstUpperLimit) {
    *mDst++ = 0;
}

//
// Fill in compressed size and original size
//
mDst = DstBuffer;
PutDword(mCompSize+1);
PutDword(mOrigSize);

//
// Return
//

if (mCompSize + 1 + 8 > *DstSize) {
    *DstSize = mCompSize + 1 + 8;
    return EFI_BUFFER_TOO_SMALL;
} else {
    *DstSize = mCompSize + 1 + 8;
    return EFI_SUCCESS;
}
```



```

}

STATIC
VOID
PutDword(
    IN UINT32 Data
)
/**++

Routine Description:

    Put a dword to output stream

Arguments:

    Data    - the dword to put

Returns: (VOID)

--*/
{
    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)((UINT8)(Data          ) & 0xff);
    }

    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)((UINT8)(Data >> 0x08) & 0xff);
    }

    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)((UINT8)(Data >> 0x10) & 0xff);
    }

    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)((UINT8)(Data >> 0x18) & 0xff);
    }
}

```

```

STATIC
EFI_STATUS
AllocateMemory ()
/**++

```

Routine Description:

Allocate memory spaces for data structures used in compression process

Arguments: (VOID)

Returns:

```

    EFI_SUCCESS          - Memory is allocated successfully
    EFI_OUT_OF_RESOURCES - Allocation fails

```

```

--*/
{
    UINT32    i;

    mText = malloc (WNDSIZ * 2 + MAXMATCH);
    for (i = 0; i < WNDSIZ * 2 + MAXMATCH; i++) {

```

Unified Extensible Firmware Interface Specification

```
        mText[i] = 0;
    }
    mLevel      = malloc ((WNDSIZ + UINT8_MAX + 1) * sizeof(*mLevel));
    mChildCount = malloc ((WNDSIZ + UINT8_MAX + 1) * sizeof(*mChildCount));
    mPosition   = malloc ((WNDSIZ + UINT8_MAX + 1) * sizeof(*mPosition));
    mParent     = malloc (WNDSIZ * 2 * sizeof(*mParent));
    mPrev       = malloc (WNDSIZ * 2 * sizeof(*mPrev));
    mNext       = malloc ((MAX_HASH_VAL + 1) * sizeof(*mNext));

    mBufSiz = 16 * 1024U;
    while ((mBuf = malloc(mBufSiz)) == NULL) {
        mBufSiz = (mBufSiz / 10U) * 9U;
        if (mBufSiz < 4 * 1024U) {
            return EFI_OUT_OF_RESOURCES;
        }
    }
    mBuf[0] = 0;

    return EFI_SUCCESS;
}
```

```
VOID
FreeMemory ()
/**++
```

Routine Description:

Called when compression is completed to free memory previously allocated.

Arguments: (VOID)

Returns: (VOID)

```
--*/
{
    if (mText) {
        free (mText);
    }

    if (mLevel) {
        free (mLevel);
    }

    if (mChildCount) {
        free (mChildCount);
    }

    if (mPosition) {
        free (mPosition);
    }

    if (mParent) {
        free (mParent);
    }

    if (mPrev) {
        free (mPrev);
    }

    if (mNext) {
        free (mNext);
    }
}
```

```

    }

    if (mBuf) {
        free (mBuf);
    }

    return;
}

```

```

STATIC
VOID
InitSlide ()
/*++

```

Routine Description:

Initialize String Info Log data structures

Arguments: (VOID)

Returns: (VOID)

```

--*/
{
    NODE i;

    for (i = WNDSIZ; i <= WNDSIZ + UINT8_MAX; i++) {
        mLevel[i] = 1;
        mPosition[i] = NIL; /* sentinel */
    }
    for (i = WNDSIZ; i < WNDSIZ * 2; i++) {
        mParent[i] = NIL;
    }
    mAvail = 1;
    for (i = 1; i < WNDSIZ - 1; i++) {
        mNext[i] = (NODE)(i + 1);
    }

    mNext[WNDSIZ - 1] = NIL;
    for (i = WNDSIZ * 2; i <= MAX_HASH_VAL; i++) {
        mNext[i] = NIL;
    }
}

```

```

STATIC
NODE
Child (
    IN NODE q,
    IN UINT8 c
)
/*++

```

Routine Description:

Find child node given the parent node and the edge character

Arguments:

q - the parent node

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```
    c          - the edge character

Returns:

    The child node (NIL if not found)

--*/
{
    NODE r;

    r = mNext[HASH(q, c)];
    mParent[NIL] = q; /* sentinel */
    while (mParent[r] != q) {
        r = mNext[r];
    }

    return r;
}

STATIC
VOID
MakeChild (
    IN NODE q,
    IN UINT8 c,
    IN NODE r
)
/*++
```

Routine Description:

Create a new child for a given parent node.

Arguments:

```
    q          - the parent node
    c          - the edge character
    r          - the child node
```

Returns: (VOID)

```
--*/
{
    NODE h, t;

    h = (NODE)HASH(q, c);
    t = mNext[h];
    mNext[h] = r;
    mNext[r] = t;
    mPrev[t] = r;
    mPrev[r] = h;
    mParent[r] = q;
    mChildCount[q]++;
}

STATIC
VOID
Split (
    NODE Old
)
/*++
```

Routine Description:

Split a node.

Arguments:

Old - the node to split

Returns: (VOID)

```
--*/
{
    NODE New, t;

    New = mAvail;
    mAvail = mNext[New];
    mChildCount[New] = 0;
    t = mPrev[Old];
    mPrev[New] = t;
    mNext[t] = New;
    t = mNext[Old];
    mNext[New] = t;
    mPrev[t] = New;
    mParent[New] = mParent[Old];
    mLevel[New] = (UINT8)mMatchLen;
    mPosition[New] = mPos;
    MakeChild(New, mText[mMatchPos + mMatchLen], Old);
    MakeChild(New, mText[mPos + mMatchLen], mPos);
}

```

```
STATIC
VOID
InsertNode ()
/*++

```

Routine Description:

Insert string info for current position into the String Info Log

Arguments: (VOID)

Returns: (VOID)

```
--*/
{
    NODE q, r, j, t;
    UINT8 c, *t1, *t2;

    if (mMatchLen >= 4) {

        //
        // We have just got a long match, the target tree
        // can be located by MatchPos + 1. Traverse the tree
        // from bottom up to get to a proper starting point.
        // The usage of PERC_FLAG ensures proper node deletion
        // in DeleteNode() later.
        //

        mMatchLen--;
        r = (INT16)((mMatchPos + 1) | WNDSIZ);
        while ((q = mParent[r]) == NIL) {

```

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```
    r = mNext[r];
}
while (mLevel[q] >= mMatchLen) {
    r = q; q = mParent[q];
}
t = q;
while (mPosition[t] < 0) {
    mPosition[t] = mPos;
    t = mParent[t];
}
if (t < WNDSIZ) {
    mPosition[t] = (NODE) (mPos | PERC_FLAG);
}
} else {

    //
    // Locate the target tree
    //

    q = (INT16) (mText[mPos] + WNDSIZ);
    c = mText[mPos + 1];
    if ((r = Child(q, c)) == NIL) {
        MakeChild(q, c, mPos);
        mMatchLen = 1;
        return;
    }
    mMatchLen = 2;
}

//
// Traverse down the tree to find a match.
// Update Position value along the route.
// Node split or creation is involved.
//

for ( ; ; ) {
    if (r >= WNDSIZ) {
        j = MAXMATCH;
        mMatchPos = r;
    } else {
        j = mLevel[r];
        mMatchPos = (NODE) (mPosition[r] & ~PERC_FLAG);
    }
    if (mMatchPos >= mPos) {
        mMatchPos -= WNDSIZ;
    }
    t1 = &mText[mPos + mMatchLen];
    t2 = &mText[mMatchPos + mMatchLen];
    while (mMatchLen < j) {
        if (*t1 != *t2) {
            Split(r);
            return;
        }
        mMatchLen++;
        t1++;
        t2++;
    }
    if (mMatchLen >= MAXMATCH) {
        break;
    }
    mPosition[r] = mPos;
}
```

```

    q = r;
    if ((r = Child(q, *t1)) == NIL) {
        MakeChild(q, *t1, mPos);
        return;
    }
    mMatchLen++;
}
t = mPrev[r];
mPrev[mPos] = t;
mNext[t] = mPos;
t = mNext[r];
mNext[mPos] = t;
mPrev[t] = mPos;
mParent[mPos] = q;
mParent[r] = NIL;

//
// Special usage of 'next'
//
mNext[r] = mPos;
}

```

```

STATIC
VOID
DeleteNode ()
/*++

```

Routine Description:

Delete outdated string info. (The Usage of PERC_FLAG ensures a clean deletion)

Arguments: (VOID)

Returns: (VOID)

```

--*/
{
    NODE q, r, s, t, u;

    if (mParent[mPos] == NIL) {
        return;
    }

    r = mPrev[mPos];
    s = mNext[mPos];
    mNext[r] = s;
    mPrev[s] = r;
    r = mParent[mPos];
    mParent[mPos] = NIL;
    if (r >= WNDISIZ || --mChildCount[r] > 1) {
        return;
    }
    t = (NODE)(mPosition[r] & ~PERC_FLAG);
    if (t >= mPos) {
        t -= WNDISIZ;
    }
    s = t;
    q = mParent[r];
    while ((u = mPosition[q]) & PERC_FLAG) {

```

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```
    u &= ~PERC_FLAG;
    if (u >= mPos) {
        u -= WNDSIZ;
    }
    if (u > s) {
        s = u;
    }
    mPosition[q] = (INT16)(s | WNDSIZ);
    q = mParent[q];
}
if (q < WNDSIZ) {
    if (u >= mPos) {
        u -= WNDSIZ;
    }
    if (u > s) {
        s = u;
    }
    mPosition[q] = (INT16)(s | WNDSIZ | PERC_FLAG);
}
s = Child(r, mText[t + mLevel[r]]);
t = mPrev[s];
u = mNext[s];
mNext[t] = u;
mPrev[u] = t;
t = mPrev[r];
mNext[t] = s;
mPrev[s] = t;
t = mNext[r];
mPrev[t] = s;
mNext[s] = t;
mParent[s] = mParent[r];
mParent[r] = NIL;
mNext[r] = mAvail;
mAvail = r;
}
```

```
STATIC
VOID
GetNextMatch ()
/**+
```

Routine Description:

Advance the current position (read in new data if needed).
Delete outdated string info. Find a match string for current position.

Arguments: (VOID)

Returns: (VOID)

```
--*/
{
    INT32 n;

    mRemainder--;
    if (++mPos == WNDSIZ * 2) {
        memmove(&mText[0], &mText[WNDSIZ], WNDSIZ + MAXMATCH);
        n = FreadCrc(&mText[WNDSIZ + MAXMATCH], WNDSIZ);
        mRemainder += n;
        mPos = WNDSIZ;
    }
}
```



```

    DeleteNode();
    InsertNode();
}

STATIC
EFI_STATUS
Encode ()
/**+

Routine Description:

    The main controlling routine for compression process.

Arguments: (VOID)

Returns:

    EFI_SUCCESS          - The compression is successful
    EFI_OUT_OF_RESOURCES - Not enough memory for compression process

--*/
{
    EFI_STATUS  Status;
    INT32      LastMatchLen;
    NODE       LastMatchPos;

    Status = AllocateMemory();
    if (EFI_ERROR(Status)) {
        FreeMemory();
        return Status;
    }

    InitSlide();

    HufEncodeStart();

    mRemainder = FreadCrc(&mText[WNDSIZ], WNDSIZ + MAXMATCH);

    mMatchLen = 0;
    mPos = WNDSIZ;
    InsertNode();
    if (mMatchLen > mRemainder) {
        mMatchLen = mRemainder;
    }
    while (mRemainder > 0) {
        LastMatchLen = mMatchLen;
        LastMatchPos = mMatchPos;
        GetNextMatch();
        if (mMatchLen > mRemainder) {
            mMatchLen = mRemainder;
        }

        if (mMatchLen > LastMatchLen || LastMatchLen < THRESHOLD) {
            //
            // Not enough benefits are gained by outputting a pointer,
            // so just output the original character
            //

            Output(mText[mPos - 1], 0);
        } else {

```

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```
//
// Outputting a pointer is beneficial enough, do it.
//

Output>LastMatchLen + (UINT8_MAX + 1 - THRESHOLD),
      (mPos - LastMatchPos - 2) & (WNDSIZ - 1));
while (--LastMatchLen > 0) {
    GetNextMatch();
}
if (mMatchLen > mRemainder) {
    mMatchLen = mRemainder;
}
}
}

HufEncodeEnd();
FreeMemory();
return EFI_SUCCESS;
}

```

```
STATIC
VOID
CountTFreq ()
/**+

```

Routine Description:

Count the frequencies for the Extra Set

Arguments: (VOID)

Returns: (VOID)

```
--*/
{
    INT32 i, k, n, Count;

    for (i = 0; i < NT; i++) {
        mTFreq[i] = 0;
    }
    n = NC;
    while (n > 0 && mCLen[n - 1] == 0) {
        n--;
    }
    i = 0;
    while (i < n) {
        k = mCLen[i++];
        if (k == 0) {
            Count = 1;
            while (i < n && mCLen[i] == 0) {
                i++;
                Count++;
            }
            if (Count <= 2) {
                mTFreq[0] = (UINT16)(mTFreq[0] + Count);
            } else if (Count <= 18) {
                mTFreq[1]++;
            } else if (Count == 19) {
                mTFreq[0]++;
                mTFreq[1]++;
            }
        }
    }
}

```

```

        } else {
            mTFreq[2]++;
        }
    } else {
        mTFreq[k + 2]++;
    }
}
}

```

```

STATIC
VOID
WritePTLen (
    IN INT32 n,
    IN INT32 nbit,
    IN INT32 Special
)
/+++

```

Routine Description:

Outputs the code length array for the Extra Set or the Position Set.

Arguments:

n - the number of symbols
nbit - the number of bits needed to represent 'n'
Special - the special symbol that needs to be take care of

Returns: (VOID)

```

--*/
{
    INT32 i, k;

    while (n > 0 && mPTLen[n - 1] == 0) {
        n--;
    }
    PutBits(nbit, n);
    i = 0;
    while (i < n) {
        k = mPTLen[i++];
        if (k <= 6) {
            PutBits(3, k);
        } else {
            PutBits(k - 3, (1U << (k - 3)) - 2);
        }
        if (i == Special) {
            while (i < 6 && mPTLen[i] == 0) {
                i++;
            }
            PutBits(2, (i - 3) & 3);
        }
    }
}
}

```

```

STATIC
VOID
WriteCLen ()
/+++

```

Routine Description:

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Outputs the code length array for Char&Length Set

Arguments: (VOID)

Returns: (VOID)

```
--*/
{
    INT32 i, k, n, Count;

    n = NC;
    while (n > 0 && mCLen[n - 1] == 0) {
        n--;
    }
    PutBits(CBIT, n);
    i = 0;
    while (i < n) {
        k = mCLen[i++];
        if (k == 0) {
            Count = 1;
            while (i < n && mCLen[i] == 0) {
                i++;
                Count++;
            }
            if (Count <= 2) {
                for (k = 0; k < Count; k++) {
                    PutBits(mPTLen[0], mPTCode[0]);
                }
            } else if (Count <= 18) {
                PutBits(mPTLen[1], mPTCode[1]);
                PutBits(4, Count - 3);
            } else if (Count == 19) {
                PutBits(mPTLen[0], mPTCode[0]);
                PutBits(mPTLen[1], mPTCode[1]);
                PutBits(4, 15);
            } else {
                PutBits(mPTLen[2], mPTCode[2]);
                PutBits(CBIT, Count - 20);
            }
        } else {
            PutBits(mPTLen[k + 2], mPTCode[k + 2]);
        }
    }
}

STATIC
VOID
EncodeC (
    IN INT32 c
)
{
    PutBits(mCLen[c], mCCode[c]);
}

STATIC
VOID
EncodeP (
    IN UINT32 p
)
{
```

```

UINT32 c, q;

c = 0;
q = p;
while (q) {
    q >>= 1;
    c++;
}
PutBits(mPTLen[c], mPTCode[c]);
if (c > 1) {
    PutBits(c - 1, p & (0xFFFFU >> (17 - c)));
}
}

```

```

STATIC
VOID
SendBlock ()
/*++

```

Routine Description:

Huffman code the block and output it.

Argument: (VOID)

Returns: (VOID)

```

--*/
{
    UINT32 i, k, Flags, Root, Pos, Size;
    Flags = 0;

    Root = MakeTree(NC, mCFreq, mCLen, mCCode);
    Size = mCFreq[Root];
    PutBits(16, Size);
    if (Root >= NC) {
        CountTFreq();
        Root = MakeTree(NT, mTFreq, mPTLen, mPTCode);
        if (Root >= NT) {
            WritePTLen(NT, TBIT, 3);
        } else {
            PutBits(TBIT, 0);
            PutBits(TBIT, Root);
        }
        WriteCLen();
    } else {
        PutBits(TBIT, 0);
        PutBits(TBIT, 0);
        PutBits(CBIT, 0);
        PutBits(CBIT, Root);
    }
    Root = MakeTree(NP, mPFreq, mPTLen, mPTCode);
    if (Root >= NP) {
        WritePTLen(NP, PBIT, -1);
    } else {
        PutBits(PBIT, 0);
        PutBits(PBIT, Root);
    }
    Pos = 0;
    for (i = 0; i < Size; i++) {
        if (i % UINT8_BIT == 0) {

```

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```
        Flags = mBuf[Pos++];
    } else {
        Flags <<= 1;
    }
    if (Flags & (1U << (UINT8_BIT - 1))) {
        EncodeC(mBuf[Pos++] + (1U << UINT8_BIT));
        k = mBuf[Pos++] << UINT8_BIT;
        k += mBuf[Pos++];
        EncodeP(k);
    } else {
        EncodeC(mBuf[Pos++]);
    }
}
for (i = 0; i < NC; i++) {
    mCFreq[i] = 0;
}
for (i = 0; i < NP; i++) {
    mPFreq[i] = 0;
}
}
```

```
STATIC
VOID
Output (
    IN UINT32 c,
    IN UINT32 p
)
/**+
```

Routine Description:

Outputs an Original Character or a Pointer

Arguments:

c - The original character or the 'String Length' element of a Pointer
p - The 'Position' field of a Pointer

Returns: (VOID)

```
--*/
{
    STATIC UINT32 CPos;

    if ((mOutputMask >>= 1) == 0) {
        mOutputMask = 1U << (UINT8_BIT - 1);
        if (mOutputPos >= mBufSiz - 3 * UINT8_BIT) {
            SendBlock();
            mOutputPos = 0;
        }
        CPos = mOutputPos++;
        mBuf[CPos] = 0;
    }
    mBuf[mOutputPos++] = (UINT8) c;
    mCFreq[c]++;
    if (c >= (1U << UINT8_BIT)) {
        mBuf[CPos] |= mOutputMask;
        mBuf[mOutputPos++] = (UINT8) (p >> UINT8_BIT);
        mBuf[mOutputPos++] = (UINT8) p;
        c = 0;
    }
}
```

```

        while (p) {
            p >>= 1;
            c++;
        }
        mPFreq[c]++;
    }
}

STATIC
VOID
HufEncodeStart ()
{
    INT32 i;

    for (i = 0; i < NC; i++) {
        mCFreq[i] = 0;
    }
    for (i = 0; i < NP; i++) {
        mPFreq[i] = 0;
    }
    mOutputPos = mOutputMask = 0;
    InitPutBits();
    return;
}

STATIC
VOID
HufEncodeEnd ()
{
    SendBlock();

    //
    // Flush remaining bits
    //
    PutBits(UINT8_BIT - 1, 0);

    return;
}

STATIC
VOID
MakeCrcTable ()
{
    UINT32 i, j, r;

    for (i = 0; i <= UINT8_MAX; i++) {
        r = i;
        for (j = 0; j < UINT8_BIT; j++) {
            if (r & 1) {
                r = (r >> 1) ^ CRCPOLY;
            } else {
                r >>= 1;
            }
        }
        mCrcTable[i] = (UINT16)r;
    }
}

STATIC
VOID

```

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```
PutBits (  
    IN INT32 n,  
    IN UINT32 x  
)  
/*++
```

Routine Description:

Outputs rightmost n bits of x

Arguments:

n - the rightmost n bits of the data is used
x - the data

Returns: (VOID)

```
--*/  
{  
    UINT8 Temp;  
  
    if (n < mBitCount) {  
        mSubBitBuf |= x << (mBitCount - n);  
    } else {  
  
        Temp = (UINT8)(mSubBitBuf | (x >> (n - mBitCount)));  
        if (mDst < mDstUpperLimit) {  
            *mDst++ = Temp;  
        }  
        mCompSize++;  
  
        if (n < UINT8_BIT) {  
            mSubBitBuf = x << (mBitCount - UINT8_BIT - n);  
        } else {  
  
            Temp = (UINT8)(x >> (n - UINT8_BIT));  
            if (mDst < mDstUpperLimit) {  
                *mDst++ = Temp;  
            }  
            mCompSize++;  
  
            mSubBitBuf = x << (mBitCount - 2 * UINT8_BIT - n);  
        }  
    }  
}
```

```
STATIC  
INT32  
FreadCrc (  
    OUT UINT8 *p,  
    IN INT32 n  
)  
/*++
```

Routine Description:

Read in source data

Arguments:

p - the buffer to hold the data


```

    n    - number of bytes to read

Returns:

    number of bytes actually read

--*/
{
    INT32 i;

    for (i = 0; mSrc < mSrcUpperLimit && i < n; i++) {
        *p++ = *mSrc++;
    }
    n = i;

    p -= n;
    mOrigSize += n;
    while (--i >= 0) {
        UPDATE_CRC(*p++);
    }
    return n;
}

```

```

STATIC
VOID
InitPutBits ()
{
    mBitCount = UINT8_BIT;
    mSubBitBuf = 0;
}

```

```

STATIC
VOID
CountLen (
    IN INT32 i
)
/*++

```

Routine Description:

Count the number of each code length for a Huffman tree.

Arguments:

i - the top node

Returns: (VOID)

```

--*/
{
    STATIC INT32 Depth = 0;

    if (i < mN) {
        mLenCnt[(Depth < 16) ? Depth : 16]++;
    } else {
        Depth++;
        CountLen(mLeft [i]);
        CountLen(mRight[i]);
        Depth--;
    }
}

```

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```
    }

    STATIC
    VOID
    MakeLen (
        IN INT32 Root
    )
    /*++

    Routine Description:

        Create code length array for a Huffman tree

    Arguments:

        Root    - the root of the tree

--*/
{
    INT32 i, k;
    UINT32 Cum;

    for (i = 0; i <= 16; i++) {
        mLenCnt[i] = 0;
    }
    CountLen(Root);

    //
    // Adjust the length count array so that
    // no code will be generated longer than the designated length
    //

    Cum = 0;
    for (i = 16; i > 0; i--) {
        Cum += mLenCnt[i] << (16 - i);
    }
    while (Cum != (1U << 16)) {
        mLenCnt[16]--;
        for (i = 15; i > 0; i--) {
            if (mLenCnt[i] != 0) {
                mLenCnt[i]--;
                mLenCnt[i+1] += 2;
                break;
            }
        }
        Cum--;
    }
    for (i = 16; i > 0; i--) {
        k = mLenCnt[i];
        while (--k >= 0) {
            mLen[*mSortPtr++] = (UINT8)i;
        }
    }
}

    STATIC
    VOID
    DownHeap (
        IN INT32 i
    )
    {
```

```

INT32 j, k;

//
// priority queue: send i-th entry down heap
//

k = mHeap[i];
while ((j = 2 * i) <= mHeapSize) {
    if (j < mHeapSize && mFreq[mHeap[j]] > mFreq[mHeap[j + 1]]) {
        j++;
    }
    if (mFreq[k] <= mFreq[mHeap[j]]) {
        break;
    }
    mHeap[i] = mHeap[j];
    i = j;
}
mHeap[i] = (INT16)k;
}

```

```

STATIC
VOID
MakeCode (
    IN  INT32 n,
    IN  UINT8 Len[],
    OUT UINT16 Code[]
)
/**+

```

Routine Description:

Assign code to each symbol based on the code length array

Arguments:

n - number of symbols
Len - the code length array
Code - stores codes for each symbol

Returns: (VOID)

```

--*/
{
    INT32 i;
    UINT16 Start[18];

    Start[1] = 0;
    for (i = 1; i <= 16; i++) {
        Start[i + 1] = (UINT16)((Start[i] + mLenCnt[i]) << 1);
    }
    for (i = 0; i < n; i++) {
        Code[i] = Start[Len[i]]++;
    }
}

```

```

STATIC
INT32
MakeTree (
    IN  INT32  NParm,
    IN  UINT16 FreqParm[],
    OUT UINT8  LenParm[],

```

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```
    OUT UINT16 CodeParm[]
  )
/*++
```

Routine Description:

Generates Huffman codes given a frequency distribution of symbols

Arguments:

NParm - number of symbols
FreqParm - frequency of each symbol
LenParm - code length for each symbol
CodeParm - code for each symbol

Returns:

Root of the Huffman tree.

```
--*/
{
    INT32 i, j, k, Avail;

    //
    // make tree, calculate len[], return root
    //

    mN = NParm;
    mFreq = FreqParm;
    mLen = LenParm;
    Avail = mN;
    mHeapSize = 0;
    mHeap[1] = 0;
    for (i = 0; i < mN; i++) {
        mLen[i] = 0;
        if (mFreq[i]) {
            mHeap[++mHeapSize] = (INT16)i;
        }
    }
    if (mHeapSize < 2) {
        CodeParm[mHeap[1]] = 0;
        return mHeap[1];
    }
    for (i = mHeapSize / 2; i >= 1; i--) {

        //
        // make priority queue
        //
        DownHeap(i);
    }
    mSortPtr = CodeParm;
    do {
        i = mHeap[1];
        if (i < mN) {
            *mSortPtr++ = (UINT16)i;
        }
        mHeap[1] = mHeap[mHeapSize--];
        DownHeap(1);
        j = mHeap[1];
        if (j < mN) {
            *mSortPtr++ = (UINT16)j;
        }
    } while (mHeapSize > 0);
}

```

```
    }
    k = Avail++;
    mFreq[k] = (UINT16)(mFreq[i] + mFreq[j]);
    mHeap[1] = (INT16)k;
    DownHeap(1);
    mLeft[k] = (UINT16)i;
    mRight[k] = (UINT16)j;
} while (mHeapSize > 1);

mSortPtr = CodeParm;
MakeLen(k);
MakeCode(NParm, LenParm, CodeParm);

//
// return root
//
return k;
}
```


Appendix I

Decompression Source Code

```

=/*++

Copyright (c) 2001-2002 Intel Corporation

Module Name:

    Decompress.c

Abstract:

    Decompressor.

--*/

#include "EfiCommon.h"

#define BITBUFSIZ      16
#define WNDBIT        13
#define WNSIZ         (1U << WNDBIT)
#define MAXMATCH      256
#define THRESHOLD     3
#define CODE_BIT      16
#define UINT8_MAX     0xff
#define BAD_TABLE     -1

//
// C: Char&Len Set; P: Position Set; T: exTra Set
//

#define NC              (0xff + MAXMATCH + 2 - THRESHOLD)
#define CBIT           9
#define NP              (WNDBIT + 1)
#define NT              (CODE_BIT + 3)
#define PBIT           4
#define TBIT           5
#if NT > NP
    #define NPT        NT
#else
    #define NPT        NP
#endif

typedef struct {
    UINT8      *mSrcBase;      //Starting address of compressed data
    UINT8      *mDstBase;     //Starting address of decompressed data

    UINT16     mBytesRemain;
    UINT16     mBitCount;
    UINT16     mBitBuf;
    UINT16     mSubBitBuf;
    UINT16     mBufSiz;
    UINT16     mBlockSize;

```

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```
UINT32      mDataIdx;
UINT32      mCompSize;
UINT32      mOrigSize;
UINT32      mOutBuf;
UINT32      mInBuf;

UINT16      mBadTableFlag;

UINT8       mBuffer[WNDSIZ];
UINT16      mLeft[2 * NC - 1];
UINT16      mRight[2 * NC - 1];
UINT32      mBuf;
UINT8       mCLen[NC];
UINT8       mPTLen[NPT];
UINT16      mCTable[4096];
UINT16      mPTTable[256];
} SCRATCH_DATA;

//
// Function Prototypes
//

STATIC
VOID
FillBuf (
    IN  SCRATCH_DATA *Sd,
    IN  UINT16      NumOfBits
);

STATIC
VOID
Decode (
    SCRATCH_DATA *Sd,
    UINT16      NumOfBytes
);

//
// Functions
//

EFI_STATUS
EFI_API
GetInfo (
    IN      EFI_DECOMPRESS_PROTOCOL *This,
    IN      VOID                    *Source,
    IN      UINT32                   SrcSize,
    OUT     UINT32                   *DstSize,
    OUT     UINT32                   *ScratchSize
)
/**+
```

Routine Description:

The implementation of `EFI_DECOMPRESS_PROTOCOL.GetInfo()`.

Arguments:

This - Protocol instance pointer.
Source - The source buffer containing the compressed data.


```

SrcSize      - The size of source buffer
DstSize      - The size of destination buffer.
ScratchSize  - The size of scratch buffer.

Returns:

EFI_SUCCESS      - The size of destination buffer and the size of scratch
buffer are successull retrieved.
EFI_INVALID_PARAMETER - The source data is corrupted

--*/
{
    UINT8 *Src;

    *ScratchSize = sizeof (SCRATCH_DATA);

    Src = Source;
    if (SrcSize < 8) {
        return EFI_INVALID_PARAMETER;
    }

    *DstSize = Src[4] + (Src[5] << 8) + (Src[6] << 16) + (Src[7] << 24);
    return EFI_SUCCESS;
}

```

```

EFI_STATUS
EFIAPI
Decompress (
    IN      EFI_DECOMPRESS_PROTOCOL *This,
    IN      VOID *Source,
    IN      UINT32 SrcSize,
    IN OUT  VOID *Destination,
    IN      UINT32 DstSize,
    IN OUT  VOID *Scratch,
    IN      UINT32 ScratchSize
)
/*++

```

Routine Description:

The implementation of `EFI_DECOMPRESS_PROTOCOL.Decompress()`.

Arguments:

This - The protocol instance.
Source - The source buffer containing the compressed data.
SrcSize - The size of the source buffer
Destination - The destination buffer to store the decompressed data
DstSize - The size of the destination buffer.
Scratch - The buffer used internally by the decompress routine. This buffer is needed to store intermediate data.
ScratchSize - The size of scratch buffer.

Returns:

```

EFI_SUCCESS      - Decompression is successfull
EFI_INVALID_PARAMETER - The source data is corrupted

--*/
{

```

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```
UINT32      Index;
UINT16      Count;
UINT32      CompSize;
UINT32      OrigSize;
UINT8       *Dst1;
EFI_STATUS  Status;
SCRATCH_DATA *Sd;
UINT8       *Src;
UINT8       *Dst;

Status = EFI_SUCCESS;
Src = Source;
Dst = Destination;
Dst1 = Dst;

if (ScratchSize < sizeof (SCRATCH_DATA)) {
    return EFI_INVALID_PARAMETER;
}

Sd = (SCRATCH_DATA *)Scratch;

if (SrcSize < 8) {
    return EFI_INVALID_PARAMETER;
}

CompSize = Src[0] + (Src[1] << 8) + (Src[2] << 16) + (Src[3] << 24);
OrigSize = Src[4] + (Src[5] << 8) + (Src[6] << 16) + (Src[7] << 24);

if (SrcSize < CompSize + 8) {
    return EFI_INVALID_PARAMETER;
}

Src = Src + 8;

for (Index = 0; Index < sizeof(SCRATCH_DATA); Index++) {
    ((UINT8*)Sd)[Index] = 0;
}

Sd->mBytesRemain = (UINT16)(-1);
Sd->mSrcBase = Src;
Sd->mDstBase = Dst;
Sd->mCompSize = CompSize;
Sd->mOrigSize = OrigSize;

//
// Fill the first two bytes
//
FillBuf(Sd, BITBUFSIZ);

while (Sd->mOrigSize > 0) {

    Count = (UINT16) (WNDSIZ < Sd->mOrigSize? WNDSIZ: Sd->mOrigSize);
    Decode (Sd, Count);

    if (Sd->mBadTableFlag != 0) {
        //
        // Something wrong with the source
        //
        return EFI_INVALID_PARAMETER;
    }
}
```

```

    for (Index = 0; Index < Count; Index ++) {
        if (Dst1 < Dst + DstSize) {
            *Dst1++ = Sd->mBuffer[Index];
        } else {
            return EFI_INVALID_PARAMETER;
        }
    }

    Sd->mOrigSize -= Count;
}

if (Sd->mBadTableFlag != 0) {
    Status = EFI_INVALID_PARAMETER;
} else {
    Status = EFI_SUCCESS;
}

return Status;
}

STATIC
VOID
FillBuf (
    IN SCRATCH_DATA *Sd,
    IN UINT16 NumOfBits
)
/**+

Routine Description:

    Shift mBitBuf NumOfBits left. Read in NumOfBits of bits from source.

Arguments:

    Sd          - The global scratch data
    NumOfBit    - The number of bits to shift and read.

Returns: (VOID)

--*/
{
    Sd->mBitBuf = (UINT16)(Sd->mBitBuf << NumOfBits);

    while (NumOfBits > Sd->mBitCount) {

        Sd->mBitBuf |= (UINT16)(Sd->mSubBitBuf <<
            (NumOfBits - (UINT16)(NumOfBits - Sd->mBitCount)));

        if (Sd->mCompSize > 0) {

            //
            // Get 1 byte into SubBitBuf
            //
            Sd->mCompSize--;
            Sd->mSubBitBuf = 0;
            Sd->mSubBitBuf = Sd->mSrcBase[Sd->mInBuf++];
            Sd->mBitCount = 8;

        } else {

```

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```
        Sd->mSubBitBuf = 0;
        Sd->mBitCount = 8;

    }
}

Sd->mBitCount = (UINT16)(Sd->mBitCount - NumOfBits);
Sd->mBitBuf |= Sd->mSubBitBuf >> Sd->mBitCount;
}
```

```
STATIC
UINT16
GetBits(
    IN  SCRATCH_DATA *Sd,
    IN  UINT16      NumOfBits
)
/*++
```

Routine Description:

Get NumOfBits of bits out from mBitBuf. Fill mBitBuf with subsequent NumOfBits of bits from source. Returns NumOfBits of bits that are popped out.

Arguments:

Sd - The global scratch data.
NumOfBits - The number of bits to pop and read.

Returns:

The bits that are popped out.

```
--*/
{
    UINT16  OutBits;

    OutBits = (UINT16)(Sd->mBitBuf >> (BITBUFSIZ - NumOfBits));

    FillBuf (Sd, NumOfBits);

    return  OutBits;
}
```

```
STATIC
UINT16
MakeTable (
    IN  SCRATCH_DATA *Sd,
    IN  UINT16      NumOfChar,
    IN  UINT8       *BitLen,
    IN  UINT16      TableBits,
    OUT UINT16      *Table
)
/*++
```

Routine Description:

Creates Huffman Code mapping table according to code length array.

Arguments:

Sd - The global scratch data
NumOfChar - Number of symbols in the symbol set
BitLen - Code length array
TableBits - The width of the mapping table
Table - The table

Returns:

0 - OK.
BAD_TABLE - The table is corrupted.

```
--*/  
{  
    UINT16 Count[17];  
    UINT16 Weight[17];  
    UINT16 Start[18];  
    UINT16 *p;  
    UINT16 k;  
    UINT16 i;  
    UINT16 Len;  
    UINT16 Char;  
    UINT16 JuBits;  
    UINT16 Avail;  
    UINT16 NextCode;  
    UINT16 Mask;  
  
    for (i = 1; i <= 16; i ++ ) {  
        Count[i] = 0;  
    }  
  
    for (i = 0; i < NumOfChar; i++) {  
        Count[BitLen[i]]++;  
    }  
  
    Start[1] = 0;  
  
    for (i = 1; i <= 16; i ++ ) {  
        Start[i + 1] = (UINT16) (Start[i] + (Count[i] << (16 - i)));  
    }  
  
    if (Start[17] != 0) { /*(1U << 16)*/  
        return (UINT16)BAD_TABLE;  
    }  
  
    JuBits = (UINT16) (16 - TableBits);  
  
    for (i = 1; i <= TableBits; i ++ ) {  
        Start[i] >>= JuBits;  
        Weight[i] = (UINT16) (1U << (TableBits - i));  
    }  
  
    while (i <= 16) {  
        Weight[i++] = (UINT16) (1U << (16 - i));  
    }  
  
    i = (UINT16) (Start[TableBits + 1] >> JuBits);  
  
    if (i != 0) {
```

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```
    k = (UINT16)(1U << TableBits);
    while (i != k) {
        Table[i++] = 0;
    }
}

Avail = NumOfChar;
Mask = (UINT16)(1U << (15 - TableBits));

for (Char = 0; Char < NumOfChar; Char++) {

    Len = BitLen[Char];
    if (Len == 0) {
        continue;
    }

    NextCode = (UINT16)(Start[Len] + Weight[Len]);

    if (Len <= TableBits) {

        for (i = Start[Len]; i < NextCode; i++) {
            Table[i] = Char;
        }

    } else {

        k = Start[Len];
        p = &Table[k >> JuBits];
        i = (UINT16)(Len - TableBits);

        while (i != 0) {
            if (*p == 0) {
                Sd->mRight[Avail] = Sd->mLeft[Avail] = 0;
                *p = Avail++;
            }

            if (k & Mask) {
                p = &Sd->mRight[*p];
            } else {
                p = &Sd->mLeft[*p];
            }

            k <<= 1;
            i--;
        }

        *p = Char;

    }

    Start[Len] = NextCode;
}

//
// Succeeds
//
return 0;
}
```

STATIC

```

UINT16
DecodeP (
    IN SCRATCH_DATA *Sd
)
/*++

Routine description:

    Decodes a position value.

Arguments:

    Sd        - the global scratch data

Returns:

    The position value decoded.

--*/
{
    UINT16 Val;
    UINT16 Mask;

    Val = Sd->mPTTable[Sd->mBitBuf >> (BITBUFSIZ - 8)];

    if (Val >= NP) {
        Mask = 1U << (BITBUFSIZ - 1 - 8);

        do {

            if (Sd->mBitBuf & Mask) {
                Val = Sd->mRight[Val];
            } else {
                Val = Sd->mLeft[Val];
            }

            Mask >>= 1;
        } while (Val >= NP);
    }

    //
    // Advance what we have read
    //
    FillBuf (Sd, Sd->mPTLen[Val]);

    if (Val) {
        Val = (UINT16)((1U << (Val - 1)) + GetBits (Sd, (UINT16)(Val - 1)));
    }

    return Val;
}

STATIC
UINT16
ReadPTLen (
    IN SCRATCH_DATA *Sd,
    IN UINT16 nn,
    IN UINT16 nbit,
    IN UINT16 Special
)

```

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```
/**+
```

```
Routine Description:
```

```
    Reads code lengths for the Extra Set or the Position Set
```

```
Arguments:
```

```
    Sd          - The global scratch data  
    nn          - Number of symbols  
    nbit        - Number of bits needed to represent nn  
    Special     - The special symbol that needs to be taken care of
```

```
Returns:
```

```
    0           - OK.  
    BAD_TABLE  - Table is corrupted.
```

```
--*/
```

```
{  
    UINT16      n;  
    UINT16      c;  
    UINT16      i;  
    UINT16      Mask;  
  
    n = GetBits (Sd, nbit);  
  
    if (n == 0) {  
        c = GetBits (Sd, nbit);  
  
        for ( i = 0; i < 256; i ++ ) {  
            Sd->mPTTable[i] = c;  
        }  
  
        for ( i = 0; i < nn; i++) {  
            Sd->mPTLen[i] = 0;  
        }  
  
        return 0;  
    }  
  
    i = 0;  
  
    while (i < n) {  
  
        c = (UINT16) (Sd->mBitBuf >> (BITBUFSIZ - 3));  
  
        if (c == 7) {  
            Mask = 1U << (BITBUFSIZ - 1 - 3);  
            while (Mask & Sd->mBitBuf) {  
                Mask >>= 1;  
                c += 1;  
            }  
        }  
  
        FillBuf (Sd, (UINT16) ((c < 7) ? 3 : c - 3));  
  
        Sd->mPTLen [i++] = (UINT8)c;  
  
        if (i == Special) {  
            c = GetBits (Sd, 2);  
        }  
    }  
}
```



```

        while ((INT16)(--c) >= 0) {
            Sd->mPTLen[i++] = 0;
        }
    }
}

while (i < nn) {
    Sd->mPTLen [i++] = 0;
}

return ( MakeTable (Sd, nn, Sd->mPTLen, 8, Sd->mPTTable) );
}

```

```

STATIC
VOID
ReadCLen (
    SCRATCH_DATA *Sd
)
/*++

```

Routine Description:

Reads code lengths for Char&Len Set.

Arguments:

Sd - the global scratch data

Returns: (VOID)

```

--*/
{
    UINT16    n;
    UINT16    c;
    UINT16    i;
    UINT16    Mask;

    n = GetBits(Sd, CBIT);

    if (n == 0) {
        c = GetBits(Sd, CBIT);

        for (i = 0; i < NC; i ++) {
            Sd->mCLen[i] = 0;
        }

        for (i = 0; i < 4096; i ++) {
            Sd->mCTable[i] = c;
        }

        return;
    }

    i = 0;
    while (i < n) {

        c = Sd->mPTTable[Sd->mBitBuf >> (BITBUFSIZ - 8)];
        if (c >= NT) {
            Mask = 1U << (BITBUFSIZ - 1 - 8);

```

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```
do {
    if (Mask & Sd->mBitBuf) {
        c = Sd->mRight [c];
    } else {
        c = Sd->mLeft [c];
    }

    Mask >>= 1;

}while (c >= NT);
}

//
// Advance what we have read
//
FillBuf (Sd, Sd->mPTLen[c]);

if (c <= 2) {

    if (c == 0) {
        c = 1;
    } else if (c == 1) {
        c = (UINT16)(GetBits (Sd, 4) + 3);
    } else if (c == 2) {
        c = (UINT16)(GetBits (Sd, CBIT) + 20);
    }

    while ((INT16)(--c) >= 0) {
        Sd->mCLen[i++] = 0;
    }

} else {

    Sd->mCLen[i++] = (UINT8)(c - 2);

}

}

while (i < NC) {
    Sd->mCLen[i++] = 0;
}

MakeTable (Sd, NC, Sd->mCLen, 12, Sd->mCTable);

return;
}
```

```
STATIC
UINT16
DecodeC (
    SCRATCH_DATA *Sd
)
/**+
```

Routine Description:

Decode a character/length value.

Arguments:

```

    Sd    - The global scratch data.

Returns:

    The value decoded.

--*/
{
    UINT16    j;
    UINT16    Mask;

    if (Sd->mBlockSize == 0) {

        //
        // Starting a new block
        //

        Sd->mBlockSize = GetBits(Sd, 16);
        Sd->mBadTableFlag = ReadPTLen (Sd, NT, TBIT, 3);
        if (Sd->mBadTableFlag != 0) {
            return 0;
        }

        ReadCLen (Sd);

        Sd->mBadTableFlag = ReadPTLen (Sd, NP, PBIT, (UINT16)(-1));
        if (Sd->mBadTableFlag != 0) {
            return 0;
        }
    }

    Sd->mBlockSize --;
    j = Sd->mCTable[Sd->mBitBuf >> (BITBUFSIZ - 12)];

    if (j >= NC) {
        Mask = 1U << (BITBUFSIZ - 1 - 12);

        do {
            if (Sd->mBitBuf & Mask) {
                j = Sd->mRight[j];
            } else {
                j = Sd->mLeft[j];
            }

            Mask >>= 1;
        } while (j >= NC);
    }

    //
    // Advance what we have read
    //
    FillBuf(Sd, Sd->mCLen[j]);

    return j;
}

STATIC
VOID
Decode (

```

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```
    SCRATCH_DATA *Sd,  
    UINT16      NumOfBytes  
    )  
    /*++
```

Routine Description:

Decode NumOfBytes and put the resulting data at starting point of mBuffer.
The buffer is circular.

Arguments:

Sd - The global scratch data
NumOfBytes - Number of bytes to decode

Returns: (VOID)

```
--*/  
{  
    UINT16      di;  
    UINT16      r;  
    UINT16      c;  
  
    r = 0;  
    di = 0;  
  
    Sd->mBytesRemain --;  
    while ((INT16) (Sd->mBytesRemain) >= 0) {  
        Sd->mBuffer[di++] = Sd->mBuffer[Sd->mDataIdx++];  
  
        if (Sd->mDataIdx >= WNDSIZ) {  
            Sd->mDataIdx -= WNDSIZ;  
        }  
  
        r ++;  
        if (r >= NumOfBytes) {  
            return;  
        }  
        Sd->mBytesRemain --;  
    }  
  
    for (;;) {  
        c = DecodeC (Sd);  
        if (Sd->mBadTableFlag != 0) {  
            return;  
        }  
  
        if (c < 256) {  
  
            //  
            // Process an Original character  
            //  
  
            Sd->mBuffer[di++] = (UINT8)c;  
            r ++;  
            if (di >= WNDSIZ) {  
                return;  
            }  
  
        } else {
```

```

//
// Process a Pointer
//

c = (UINT16)(c - (UINT8_MAX + 1 - THRESHOLD));
Sd->mBytesRemain = c;

Sd->mDataIdx = (r - DecodeP(Sd) - 1) & (WNDSIZ - 1); //Make circular

di = r;

Sd->mBytesRemain --;
while ((INT16)(Sd->mBytesRemain) >= 0) {
    Sd->mBuffer[di++] = Sd->mBuffer[Sd->mDataIdx++];
    if (Sd->mDataIdx >= WNDSIZ) {
        Sd->mDataIdx -= WNDSIZ;
    }

    r ++;
    if (di >= WNDSIZ) {
        return;
    }
    Sd->mBytesRemain --;
}
}
return;
}

```


Appendix J

EFI Byte Code Virtual Machine Opcode List

The following table lists the opcodes for EBC instructions. Note that opcodes only require 6 bits of the opcode byte of EBC instructions. The other two bits are used for other encodings that are dependent on the particular instruction.

Table 196. EBC Virtual Machine Opcode Summary

Opcode	Description
0x00	<u>BREAK</u> [break code]
0x01	<u>JMP</u> _{32{cs cc}} {@}R ₁ {Immed32 Index32} <u>JMP</u> _{64{cs cc}} Immed64
0x02	<u>JMP8</u> {cs cc} Immed8
0x03	<u>CALL</u> _{32{EX}{a}} {@}R ₁ {Immed32 Index32} <u>CALL</u> _{64{EX}{a}} Immed64
0x04	<u>RET</u>
0x05	<u>CMP</u> _{[32 64]eq} R ₁ , {@}R ₂ {Index16 Immed16}
0x06	<u>CMP</u> _{[32 64]lte} R ₁ , {@}R ₂ {Index16 Immed16}
0x07	<u>CMP</u> _{[32 64]gte} R ₁ , {@}R ₂ {Index16 Immed16}
0x08	<u>CMP</u> _{[32 64]ulte} R ₁ , {@}R ₂ {Index16 Immed16}
0x09	<u>CMP</u> _{[32 64]ugte} R ₁ , {@}R ₂ {Index16 Immed16}
0x0A	<u>NOT</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x0B	<u>NEG</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x0C	<u>ADD</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x0D	<u>SUB</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x0E	<u>MUL</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x0F	<u>MULU</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x10	<u>DIV</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x11	<u>DIVU</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x12	<u>MOD</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x13	<u>MODU</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x14	<u>AND</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x15	<u>OR</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x16	<u>XOR</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x17	<u>SHL</u> _[32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}

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Opcode	Description
0x18	SHR [32 64] {@}R ₁ ,{@}R ₂ {Index16 Immed16}
0x19	ASHR [32 64] {@}R ₁ ,{@}R ₂ {Index16 Immed16}
0x1A	EXTNDB [32 64] {@}R ₁ , {@}R ₂ {Index16 Immed16}
0x1B	EXTNDW [32 64] {@}R ₁ ,{@}R ₂ {Index16 Immed16}
0x1C	EXTNDD [32 64] {@}R ₁ ,{@}R ₂ {Index16 Immed16}
0x1D	MOV bw {@}R ₁ {Index16}, {@}R ₂ {Index16}
0x1E	MOV ww {@}R ₁ {Index16}, {@}R ₂ {Index16}
0x1F	MOV dw {@}R ₁ {Index16}, {@}R ₂ {Index16}
0x20	MOV qw {@}R ₁ {Index16}, {@}R ₂ {Index16}
0x21	MOV bd {@}R ₁ {Index32}, {@}R ₂ {Index32}
0x22	MOV wd {@}R ₁ {Index32}, {@}R ₂ {Index32}
0x23	MOV dd {@}R ₁ {Index32}, {@}R ₂ {Index32}
0x24	MOV qd {@}R ₁ {Index32}, {@}R ₂ {Index32}
0x25	MOV snw {@}R ₁ {Index16}, {@}R ₂ {Index16 Immed16}
0x26	MOV snd {@}R ₁ {Index32}, {@}R ₂ {Index32 Immed32}
0x27	Reserved
0x28	MOV qq {@}R ₁ {Index64}, {@}R ₂ {Index64}
0x29	LOADSP [Flags], R ₂
0x2A	STORESP R ₁ , [IP Flags]
0x2B	PUSH [32 64] {@}R ₁ {Index16 Immed16}
0x2C	POP [32 64] {@}R ₁ {Index16 Immed16}
0x2D	CMP I[32 64][w d]eq {@}R ₁ {Index16}, Immed16 Immed32
0x2E	CMP I[32 64][w d]lte {@}R ₁ {Index16}, Immed16 Immed32
0x2F	CMP I[32 64][w d]gte {@}R ₁ {Index16}, Immed16 Immed32
0x30	CMP I[32 64][w d]ulte {@}R ₁ {Index16}, Immed16 Immed32
0x31	CMP I[32 64][w d]ugte {@}R ₁ {Index16}, Immed16 Immed32
0x32	MOV nw {@}R ₁ {Index16}, {@}R ₂ {Index16}
0x33	MOV nd {@}R ₁ {Index32}, {@}R ₂ {Index32}
0x34	Reserved
0x35	PUSH n {@}R ₁ {Index16 Immed16}
0x36	POP n {@}R ₁ {Index16 Immed16}
0x37	MOV I[b w d q][w d q] {@}R ₁ {Index16}, Immed16 32 64
0x38	MOV In[w d q] {@}R ₁ {Index16}, Index16 32 64

Opcode	Description
0x39	MOVREL [w d q] {@}R ₁ {Index16}, Immed16 32 64
0x3A	Reserved
0x3B	Reserved
0x3C	Reserved
0x3D	Reserved
0x3E	Reserved
0x3F	Reserved

Appendix K

Alphabetic Function Lists

This appendix contains two tables that list all EFI functions alphabetically. [Table 197](#) lists the functions in pure alphabetic order. Functions that have the same name can be distinguished by the associated service or protocol (column 2). For example, there are **Flush()** functions from the EFI PCI I/O Protocol, the File System Protocol, and the PCI Root Bridge I/O Protocol. [Table 198](#) orders the functions alphabetically within a service or protocol. That is, column one names the service or protocol, and column two lists the functions in the service or protocol.

Table 197. Functions Listed in Alphabetic Order

Function Name	Service or Protocol	Subservice	Function Description
Accept()	EFI_TCP4_PROTOCOL		Listen on the passive instance to accept an incoming connection request. This is a nonblocking operation.
Add()	EFI_ARP_PROTOCOL		Inserts an entry to the ARP cache.
AllocateBuffer()	EFI PCI I/O Protocol		Allocates pages that are suitable for a common buffer mapping.
AllocateBuffer()	PCI Root Bridge I/O Protocol		Allocates pages that are suitable for a common buffer mapping.
AllocatePages()	Boot Services	Memory Allocation Services	Allocates memory pages of a particular type.
AllocatePool()	Boot Services	Memory Allocation Services	Allocates pool of a particular type.
AppendDeviceNode()	Device Path Utilities Protocol		Appends the device node to the specified device path.
AppendDevicePath()	Device Path Utilities Protocol		Appends the device path to the specified device path.
AppendDevicePathInstance()	Device Path Utilities Protocol		Appends a device path instance to another device path.
Arp()	PXE Base Code Protocol		Uses the ARP protocol to resolve a MAC address.

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Function Name	Service or Protocol	Subservice	Function Description
<u>AsyncInterruptTransfer()</u>	<u>USB2 Host Controller Protocol</u>		Submits an asynchronous interrupt transfer to an interrupt endpoint of a USB device.
<u>AsyncIsochronousTransfer()</u>	<u>USB2 Host Controller Protocol</u>		Submits nonblocking USB isochronous transfer.
<u>Attributes()</u>	<u>EFI PCI I/O Protocol</u>		Performs an operation on the attributes that this PCI controller supports.
BlockToConfig()	EFI_HII_CONFIG_ROUTING_PROTOCOL		This helper function is to be called by drivers to map configuration data stored in byte array ("block") formats such as UEFI Variables into current configuration strings.
<u>Blit()</u>	<u>Graphics Output Protocol</u>		Blit a rectangle of pixels on the graphics screen. Blit stands for BLock Transfer.
BrowserCallback()	EFI_FORM_BROWSER_PROTOCOL		This function is called by a callback handler to retrieve uncommitted state data from the browser.
Build()	EFI_DHCP4_PROTOCOL		Builds a DHCP packet, given the options to be appended or deleted or replaced.
<u>BuildDevicePath()</u>	<u>Extended SCSI Pass Thru Protocol</u>		Used to allocate and build a device path node for a SCSI device on a SCSI channel.
<u>BulkTransfer()</u>	<u>USB2 Host Controller Protocol</u>		Submits a bulk transfer to a bulk endpoint of a USB device.
<u>CalculateCrc32()</u>	<u>Boot Services</u>	<u>Miscellaneous Boot Services</u>	Computes and returns a 32-bit CRC for a data buffer.

Function Name	Service or Protocol	Subservice	Function Description
<u>Callback ()</u>	<u>PXE Base Code Callback Protocol</u>		Callback routine used by the PXE Base Code <u>Dhcp ()</u> , <u>Discover ()</u> , <u>Mtftp ()</u> , <u>UdpWrite ()</u> , and <u>Arp ()</u> functions.
CallBack()	EFI_HII_CONFIG_ACCESS_PROTOCOL.		This function is called to provide results data to the driver.
Cancel()	EFI_IP4_PROTOCOL.		Abort an asynchronous transmit or receive request.
Cancel()	EFI_MANAGED_NETWORK_PROTOCOL		Aborts an asynchronous transmit or receive request.
Cancel()	EFI_TCP4_PROTOCOL		Abort an asynchronous connection, listen, transmission or receive request.
Cancel()	EFI_UDP4_PROTOCOL		Aborts an asynchronous transmit or receive request.
<u>CheckEvent ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Checks whether an event is in the signaled state.
<u>ClearRootHubPortFeature ()</u>	<u>USB2 Host Controller Protocol</u>		Clears the feature for the specified root hub port.
<u>ClearScreen ()</u>	<u>Simple Text Output Protocol</u>		Clears the screen with the currently set background color.
<u>Close ()</u>	<u>EFI File Protocol</u>		Closes the current file handle.
Close()	EFI_TCP4_PROTOCOL		Disconnecting a TCP connection gracefully or reset a TCP connection. This function is a nonblocking operation.
<u>CloseEvent ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Closes and frees an event structure.

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Function Name	Service or Protocol	Subservice	Function Description
<u>CloseProtocol()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Removes elements from the list of agents consuming a protocol interface.
ConfigToBlock()	EFI_HII_CONFIG_ROUTING_PROTOCOL		This helper function is to be called by drivers to map configuration strings to configurations stored in byte array ("block") formats such as UEFI Variables.
<u>Configuration()</u>	<u>PCI Root Bridge I/O Protocol</u>		Gets the current resource settings for this PCI root bridge
Configure()	EFI_ARP_PROTOCOL		Assigns a station address (protocol type and network address) to this instance of the ARP cache.
Configure()	EFI_DHCP4_PROTOCOL		Initializes, changes, or resets the operational settings for the EFI DHCPv4 Protocol driver.
Configure()	EFI_IP4_PROTOCOL.		Assigns an IPv4 address and subnet mask to this EFI IPv4 Protocol driver instance.
Configure()	EFI_MANAGED_NETWORK_PROTOCOL		Sets or clears the operational parameters for the MNP child driver.
Configure()	EFI_MTFTP4_PROTOCOL		Initializes, changes, or resets the default operational setting for this EFI MTFTPv4 Protocol driver instance.
Configure()	EFI_TCP4_PROTOCOL		Initialize or brutally reset the operational parameters for this EFI TCPv4 instance.
Configure()	EFI_UDP4_PROTOCOL		Initializes, changes, or resets the operational parameters for this instance of the EFI UDPv4 Protocol.

Function Name	Service or Protocol	Subservice	Function Description
Connect()	EFI_TCP4_PROTOCOL		Initiate a nonblocking TCP connection request for an active TCP instance.
ConnectController ()	Boot Services	Protocol Handler Services	Uses a set of precedence rules to find the best set of drivers to manage a controller.
ControlTransfer ()	USB2 Host Controller Protocol		Submits a control transfer to a target USB device.
ConvertDeviceNodeToText ()	Device Path to Text Protocol		Converts a device node to text.
ConvertDevicePathToText ()	Device Path to Text Protocol		Converts a device path to text.
ConvertPointer ()	Runtime Services	Virtual Memory Services	Converts internal pointers when switching to virtual addressing.
ConvertTextToDeviceNode ()	Device Path from Text Protocol		Converts text to a device node.
ConvertTextToDevicePath ()	Device Path from Text Protocol		Converts text to a device path.
CopyMem ()	Boot Services	Miscellaneous Boot Services	Copies the contents of one buffer to another buffer.
CopyMem ()	EFI PCI I/O Protocol		Allows one region of PCI memory space to be copied to another region of PCI memory space
CopyMem ()	PCI Root Bridge I/O Protocol		Allows one region of PCI root bridge memory space to be copied to another region of PCI root bridge memory space.
CreateChild ()	EFI Service Binding Protocol		Creates a child handle and installs a protocol.
CreateDeviceNode ()	Device Path Utilities Protocol		Allocates memory for a device node with the specified type and sub-type.
CreateEvent ()	Boot Services	Event, Timer, and Task Priority Services	Creates a general-purpose event structure.

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Function Name	Service or Protocol	Subservice	Function Description
<u>CreateEventEx ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Create an event structure as part of an event group.
<u>CreateThunk ()</u>	<u>EBC Interpreter Protocol</u>		Creates a thunk for an EBC image entry point or protocol service, and returns a pointer to the thunk.
<u>Decompress ()</u>	<u>Decompress Protocol</u>		Decompresses a compressed source buffer into an uncompressed destination buffer.
Delete()	EFI_ARP_PROTOCOL		Removes entries from the ARP cache.
<u>Delete ()</u>	<u>EFI File Protocol</u>		Deletes a file.
<u>DestroyChild ()</u>	<u>EFI Service Binding Protocol</u>		Destroys a child handle with a protocol installed on it.
<u>Dhcp ()</u>	<u>PXE Base Code Protocol</u>		Attempts to complete a DHCPv4 D.O.R.A. (discover / offer / request / acknowledge) or DHCPv6 S.A.R.R (solicit / advertise / request / reply) sequence.
<u>DisconnectController ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Informs a set of drivers to stop managing a controller.
<u>Discover ()</u>	<u>PXE Base Code Protocol</u>		Attempts to complete the PXE Boot Server and/or boot image discovery sequence.
DrawImage()	EFI_HII_IMAGE_PROTOCOL		Renders an image to a bitmap or to the display.
DrawImageId()	EFI_HII_IMAGE_PROTOCOL		Renders an image to a bitmap or to the display.
<u>DriverLoaded ()</u>	<u>EFI Platform Driver Override Protocol</u>		Used to associate a driver image handle with a device path returned on a prior call.
<u>DuplicateDevicePath ()</u>	<u>Device Path Utilities Protocol</u>		Duplicates a device path structure.

Function Name	Service or Protocol	Subservice	Function Description
<u>EFI_IMAGE_ENTRY_POINT</u>	<u>Boot Services</u>	<u>Image Services</u>	Prototype of an EFI Image's entry point.
<u>EnableCursor()</u>	<u>Simple Text Output Protocol</u>		Turns the visibility of the cursor on/off.
<u>ExecuteScsiCommand()</u>	<u>EFI SCSI I/O Protocol</u>		Sends a SCSI Request Packet to the SCSI Device for execution.
<u>Exit()</u>	<u>Boot Services</u>	<u>Image Services</u>	Exits the image's entry point.
<u>ExitBootServices()</u>	<u>Boot Services</u>	<u>Image Services</u>	Terminates boot services.
ExportConfig()	EFI_HII_CONFIG_ROUTING_PROTOCOL		This function processes the results of processing forms and routes it to the appropriate handlers or storage.
ExportPackageLists()	EFI_HII_DATABASE_PROTOCOL		Exports the contents of one or all package lists in the HII database into a buffer.
ExtractConfig()	EFI_HII_CONFIG_ACCESS_PROTOCOL		This function processes the results of processing forms and routes it to the appropriate handlers or storage.
ExtractConfig()	EFI_HII_CONFIG_ROUTING_PROTOCOL		This function processes the results of processing forms and routes it to the appropriate handlers or storage.
<u>FatToStr()</u>	<u>Unicode Collation Protocol</u>		Converts an 8.3 FAT file name in an OEM character set to a Null-terminated Unicode string.
<u>Fill Header</u>	<u>UNDI Commands</u>		This command is used to fill the media header(s) in transmit packet(s).
Find()	EFI_ARP_PROTOCOL		Locates one or more entries in the ARP cache.
FindKeyboardLayouts()	EFI_HII_DATABASE_PROTOCOL		Retrieves a list of the keyboard layouts in the system.

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Function Name	Service or Protocol	Subservice	Function Description
Flush()	EFI_ARP_PROTOCOL		Removes all dynamic ARP cache entries that were added by this interface.
Flush ()	EFI File Protocol		Flushes all modified data associated with the file to the device.
Flush ()	EFI PCI I/O Protocol		Flushes all PCI posted write transactions to system memory.
Flush ()	PCI Root Bridge I/O Protocol		Flushes all PCI posted write transactions to system memory.
FlushBlocks ()	Block I/O Protocol		Flushes any cached blocks.
Free ()	Boot Integrity Services Protocol		Frees memory structures allocated and returned by other functions in the EFI BIS PROTOCOL .
FreeBuffer ()	EFI PCI I/O Protocol		Frees pages that were allocated with AllocateBuffer () .
FreeBuffer ()	PCI Root Bridge I/O Protocol		Free pages that were allocated with AllocateBuffer () .
FreePages ()	Boot Services	Memory Allocation Services	Frees memory pages.
FreePool ()	Boot Services	Memory Allocation Services	Frees allocated pool.
Get()	EFI_AUTHENTICATION_INFO_PROTOCOL		Retrieves the Authentication information associated with a particular controller handle.
Get()	EFI_ISCSI_INITIATOR_NAME_PROTOCOL		Retrieves the current set value of iSCSI Initiator Name.

Function Name	Service or Protocol	Subservice	Function Description
<u>Get Config Info</u>	<u>UNDI Commands</u>		This command is used to retrieve configuration information about the NIC being controlled by the UNDI.
<u>Get Init Info</u>	<u>UNDI Commands</u>		This command is used to retrieve initialization information that is needed by drivers and applications to initialize UNDI.
<u>Get State</u>	<u>UNDI Commands</u>		This command is used to determine the operational state of the UNDI.
<u>Get Status</u>	<u>UNDI Commands</u>		This command returns the current interrupt status and/or the transmitted buffer addresses.
<u>GetAttributes ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Gets the attributes that a PCI root bridge supports setting with <u>SetAttributes ()</u> , and the attributes that a PCI root bridge is currently using.
<u>GetBarAttributes ()</u>	<u>EFI PCI I/O Protocol</u>		Gets the attributes that this PCI controller supports setting on a BAR using <u>SetBarAttributes ()</u> , and retrieves the list of resource descriptors for a BAR.
<u>GetBootObjectAuthorizationCertificate ()</u>	<u>Boot Integrity Services Protocol</u>		Retrieves the current digital certificate (if any) used by the <u>EFI BIS PROTOCOL</u> as the source of authorization for verifying boot objects and altering configuration parameters

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Function Name	Service or Protocol	Subservice	Function Description
<u>GetBootObjectAuthorizationCheckFlag()</u>	<u>Boot Integrity Services Protocol</u>		Retrieves the current setting of the authorization check flag that indicates whether or not authorization checks are required for boot objects.
<u>GetBootObjectAuthorizationUpdateToken()</u>	<u>Boot Integrity Services Protocol</u>		Retrieves an uninterpreted token whose value gets included and signed in a subsequent request to alter the configuration parameters, to protect against attempts to “replay” such a request.
<u>GetCapability()</u>	<u>USB2 Host Controller Protocol</u>		Retrieves the capabilities of the USB host controller.
<u>GetControl()</u>	<u>Serial I/O Protocol</u>		Reads the status of the control bits on a serial device.
<u>GetControllerName()</u>	<u>EFI Component Name Protocol</u>		Retrieves a Unicode string that is the user readable name of the controller that is being managed by a UEFI driver.
GetData()	EFI_IP4_CONFIG_PROTOCOL		Returns the default configuration data (if any) for the EFI IPv4 Protocol driver.
<u>GetDevicePathSize()</u>	<u>Device Path Utilities Protocol</u>		Returns the size of the specified device path, in bytes.
<u>GetDeviceLocation()</u>	<u>EFI SCSI I/O Protocol</u>		Retrieves the device location in the SCSI channel.
<u>GetDeviceType()</u>	<u>EFI SCSI I/O Protocol</u>		Retrieves the type of SCSI device.
<u>GetDriver()</u>	<u>EFI Bus Specific Driver Override Protocol</u>		Uses a bus-specific algorithm to retrieve a driver image handle for a controller.

Function Name	Service or Protocol	Subservice	Function Description
<u>GetDriver ()</u>	<u>EFI Platform Driver Override Protocol</u>		Retrieves the image handle of the platform override driver for a controller in the system.
<u>GetDriverName ()</u>	<u>EFI Component Name Protocol</u>		Retrieves a Unicode string that is the user readable name of the UEFI driver.
<u>GetDriverPath ()</u>	<u>EFI Platform Driver Override Protocol</u>		Retrieves the device path of the platform override driver for a controller in the system.
GetEdid()	EFI_EDID_OVERRIDE_PROTOCOL		Returns policy information and potentially a replacement EDID for the specified video output device.
GetFontInfo()	EFI_HII_FONT_PROTOCOL		Return information about a particular font.
GetGlyph()	EFI_HII_FONT_PROTOCOL		Return information about a single glyph.
GetHashSize()	EFI_HASH_PROTOCOL		Returns the size of the hash which results from a specific algorithm.
GetImage()	EFI_HII_IMAGE_PROTOCOL		Returns information about an image, associated with a package list.
<u>GetInfo ()</u>	<u>Decompress Protocol</u>		Given the compressed source buffer, this function retrieves the size of the uncompressed destination buffer and the size of the scratch buffer required to perform the decompression.
<u>GetInfo ()</u>	<u>EFI File Protocol</u>		Gets the requested file or volume information.
GetInfo()	EFI_MTFPT4_PROTOCOL		Gets information about a file from an MTFPTv4 server.
GetKeyboardLayout()	EFI_HII_DATABASE_PROTOCOL		Retrieves the requested keyboard layout.

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Function Name	Service or Protocol	Subservice	Function Description
GetLanguages()	EFI_HII_STRING_PROTOCOL		Returns a list of the languages present in strings in a package list.
<u>GetLocation()</u>	<u>EFI PCI I/O Protocol</u>		Retrieves this PCI controller's current PCI bus number, device number, and function number.
<u>GetMaximumProcessorIndex()</u>	<u>EFI Debug Support Protocol</u>		Returns the maximum processor index value that may be used with <u>RegisterPeriodicCallback()</u> and <u>RegisterExceptionCallback()</u>
<u>GetMemoryMap()</u>	<u>Boot Services</u>	<u>Memory Allocation Services</u>	Returns the current boot services memory map and memory map key.
GetModeData()	EFI_DHCP4_PROTOCOL		Returns the current operating mode and cached data packet for the EFI DHCPv4 Protocol driver.
GetModeData()	EFI_IP4_PROTOCOL.		Gets the current operational settings for this instance of the EFI IPv4 Protocol driver.
GetModeData()	EFI_MANAGED_NETWORK_PROTOCOL		Returns the operational parameters for the current MNP child driver. May also support returning the underlying SNP driver mode data.
GetModeData()	EFI_MTFTP4_PROTOCOL		Reads the current operational settings.
GetModeData()	EFI_TCP4_PROTOCOL		Get the current operational status.
GetModeData()	EFI_UDP4_PROTOCOL		Reads the current operational settings.
<u>GetNextDevicePathInstance()</u>	<u>Device Path Utilities Protocol</u>		Retrieves the next device path instance from a device path data structure.
<u>GetNextHighMonotonicCount()</u>	<u>Runtime Services</u>	<u>Miscellaneous Runtime Services</u>	Returns the next high 32 bits of a platform's monotonic counter.

Function Name	Service or Protocol	Subservice	Function Description
<u>GetNextMonotonicCount()</u>	<u>Boot Services</u>	<u>Miscellaneous Boot Services</u>	Returns a monotonically increasing count for the platform.
<u>GetNextTarget()</u>	<u>Extended SCSI Pass Thru Protocol</u>		Retrieves the list of legal Target IDs for the SCSI devices on a SCSI channel.
<u>GetNextTargetLun()</u>	<u>Extended SCSI Pass Thru Protocol</u>		Retrieves the list of legal Target IDs and LUNs for the SCSI devices on a SCSI channel.
<u>GetNextVariableName()</u>	<u>Runtime Services</u>	<u>Variable Services</u>	Enumerates the current variable names.
GetPackageListHandle()	EFI_HII_DATABASE_PROTOCOL		Return the EFI handle associated with a package list.
<u>GetPosition()</u>	<u>EFI File Protocol</u>		Returns the current file position.
<u>GetRootHubPortStatus()</u>	<u>USB2 Host Controller Protocol</u>		Retrieves the status of the specified root hub port.
GetSecondaryLanguages()	EFI_HII_STRING_PROTOCOL		Given a primary language, returns the secondary languages supported in a package list.
<u>GetSignatureInfo()</u>	<u>Boot Integrity Services Protocol</u>		Retrieves information about the digital signature algorithms supported and the identity of the installed authorization certificate, if any.
GetState()	EFI_ABSOLUTE_POINTER_PROTOCOL		Retrieves the current state of a pointer device.
<u>GetState()</u>	<u>Simple Pointer Protocol</u>		Retrieves the current state of a pointer device.
<u>GetState()</u>	<u>USB2 Host Controller Protocol</u>		Retrieves the current state of the USB host controller.
<u>GetStatus()</u>	<u>Simple Network Protocol</u>		Reads the current interrupt status and recycled transmit buffer status from the network interface.

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Function Name	Service or Protocol	Subservice	Function Description
GetString()	EFI_HII_STRING_PROTOCOL		Returns information about a string in a specific language, associated with a package list.
GetTargetLun ()	Extended SCSI Pass Thru Protocol		Used to translate a device path node to a Target ID and LUN.
GetTime ()	Runtime Services	Time Services	Returns the current time and date, and the time-keeping capabilities of the platform.
GetVariable ()	Runtime Services	Variable Services	Returns the value of the specific variable.
GetVersion ()	EBC Interpreter Protocol		Gets the version of the associated EBC interpreter.
GetWakeupTime ()	Runtime Services	Time Services	Returns the current wakeup alarm clock setting.
Groups()	EFI_IP4_PROTOCOL.		Joins and leaves multicast groups.
Groups()	EFI_MANAGED_NETWORK_PROTOCOL		Enables and disables receive filters for multicast address. This function may be unsupported in some MNP implementations.
Groups()	EFI_UDP4_PROTOCOL		Joins and leaves multicast groups.
HandleProtocol ()	Boot Services	Protocol Handler Services	Queries the list of protocol handlers on a device handle for the requested Protocol Interface.
Hash()	EFI_HASH_PROTOCOL		Creates a hash for the specified message text.
Initialize ()	Boot Integrity Services Protocol		Initializes an application instance of the EFI BIS PROTOCOL , returning a handle for the application instance.

Function Name	Service or Protocol	Subservice	Function Description
<u>Initialize ()</u>	<u>Simple Network Protocol</u>		Resets the network adapter and allocates the transmit and receive buffers required by the network interface; also optionally allows space for additional transmit and receive buffers to be allocated
<u>Initialize</u>	<u>UNDI Commands</u>		This command resets the network adapter and initializes UNDI using the parameters supplied in the CPB.
InstallAcpiTable()	EFI_ACPI_TABLE_PROTOCOL		Installs an ACPI table into the RSDT/XSDT.
<u>InstallConfiguration Table ()</u>	<u>Boot Services</u>	<u>Miscellaneous Boot Services</u>	Adds, updates, or removes a configuration table from the EFI System Table.
<u>InstallMultipleProtocolInterfaces ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Installs one or more protocol interfaces onto a handle.
<u>InstallProtocolInterface ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Adds a protocol interface to an existing or new device handle.
<u>Interrupt Enables</u>	<u>UNDI Commands</u>		The Interrupt Enables command can be used to read and/or change the current external interrupt enable settings.
<u>InvalidateInstructionCache ()</u>	<u>EFI Debug Support Protocol</u>		Invalidate the instruction cache of the processor.
<u>Io.Read ()</u>	<u>EFI PCI I/O Protocol</u>		Allows BAR relative reads to PCI I/O space.
<u>Io.Read ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Allows reads from I/O space.
<u>Io.Write ()</u>	<u>EFI PCI I/O Protocol</u>		Allows BAR relative writes to PCI I/O space.
<u>Io.Write ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Allows writes to I/O space.
<u>IsDevicePathMultiInstance ()</u>	<u>Device Path Utilities Protocol</u>		Returns TRUE if this is a multi-instance device path.

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Function Name	Service or Protocol	Subservice	Function Description
<u>IsynchronousTransfer ()</u>	<u>USB2 Host Controller Protocol</u>		Submits isochronous transfer to an isochronous endpoint of a USB device.
ListPackageLists()	EFI_HII_DATABASE_P ROTOCOL		Determines the handles that are currently active in the database.
<u>LoadFile ()</u>	<u>Load File Protocol</u>		Causes the driver to load the requested file.
<u>LoadImage ()</u>	<u>Boot Services</u>	<u>Image Services</u>	Function to dynamically load another EFI Image.
<u>LocateDevicePath ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Locates the closest handle that supports the specified protocol on the specified device path.
<u>LocateHandle ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Locates the handle(s) that support the specified protocol.
<u>LocateHandleBuffer ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Retrieves the list of handles from the handle database that meet the search criteria. The return buffer is automatically allocated.
<u>LocateProtocol ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Finds the first handle in the handle database that supports the requested protocol.
<u>Map ()</u>	<u>EFI PCI I/O Protocol</u>		Provides the PCI controller specific address needed to access system memory for DMA.
<u>Map ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Provides the PCI controller specific addresses needed to access system memory for DMA.
<u>MCast IP To MAC</u>	<u>UNDI Commands</u>		Translate a multicast IPv4 or IPv6 address to a multicast MAC address.

Function Name	Service or Protocol	Subservice	Function Description
McastIpToMac()	EFI_MANAGED_NETWORK_PROTOCOL		Translates an IP multicast address to a hardware (MAC) multicast address. This function may be unsupported in some MNP implementations.
MCastIPtoMAC ()	Simple Network Protocol		Allows a multicast IP address to be mapped to a multicast HW MAC address.
Mem. Read ()	EFI PCI I/O Protocol		Allows BAR relative reads to PCI memory space.
Mem. Read ()	PCI Root Bridge I/O Protocol		Allows reads from memory mapped I/O space.
Mem. Write ()	EFI PCI I/O Protocol		Allows BAR relative writes to PCI memory space.
Mem. Write ()	PCI Root Bridge I/O Protocol		Allows writes to memory mapped I/O space.
MetaMatch ()	Unicode Collation Protocol		Performs a case insensitive comparison between a Unicode pattern string and a Unicode string.
Mtftp ()	PXE Base Code Protocol		Is used to perform TFTP and MTFTP services.
No associated function	EFI Device Path Protocol		Can be used on any device handle to obtain generic path/location information concerning the physical device or logical device.
No associated function	EFI Driver Entry Point		The main entry point for a UEFI driver.
NewImage()	EFI_HII_IMAGE_PROTOCOL		Creates a new image and add it to images from a specific package list.
NewPackageList()	EFI_HII_DATABASE_PROTOCOL		Adds the packages in the package list to the HII database.

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Function Name	Service or Protocol	Subservice	Function Description
NewString()	EFI_HII_STRING_PROTOCOL		Creates a new string in a specific language and add it to strings from a specific package list.
NvData ()	Simple Network Protocol		Allows read and writes to the NVRAM device attached to a network interface.
NvData	UNDI Commands		This command is used to read and write (if supported by NIC hardware) nonvolatile storage on the NIC.
Open ()	EFI File Protocol		Opens or creates a new file.
OpenProtocol ()	Boot Services	Protocol Handler Services	Adds elements to the list of agents consuming a protocol interface.
OpenProtocolInformation ()	Boot Services	Protocol Handler Services	Retrieve the list of agents that are currently consuming a protocol interface.
OpenVolume ()	Simple File System Protocol		Opens the volume for file I/O access.
OutputString ()	Simple Text Output Protocol		Displays the Unicode string on the device at the current cursor location.
Parse()	EFI_DHCP4_PROTOCOL		Parses the packed DHCP option data.
ParseOptions()	EFI_MTFTP4_PROTOCOL		Parses the options in an MTFTPv4 OACK packet.
PassThru ()	Extended SCSI Pass Thru Protocol		Sends a SCSI Request Packet to a SCSI device that is connected to the SCSI channel.
Pci.Read ()	EFI PCI I/O Protocol		Allows PCI controller relative reads to PCI configuration space.
Pci.Read ()	PCI Root Bridge I/O Protocol		Allows reads from PCI configuration space.
Pci.Write ()	EFI PCI I/O Protocol		Allows PCI controller relative writes to PCI configuration space.

Function Name	Service or Protocol	Subservice	Function Description
<u>Pci.Write ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Allows writes to PCI configuration space
<u>Poll ()</u>	<u>EFI Debugport Protocol</u>		Determine if there is any data available to be read from the debugport device.
Poll()	EFI_IP4_PROTOCOL.		Polls for incoming data packets and processes outgoing data packets.
Poll()	EFI_MANAGED_NETWORK_PROTOCOL		Polls for incoming data packets and processes outgoing data packets.
Poll()	EFI_MTFTP4_PROTOCOL		Polls for incoming data packets and processes outgoing data packets.
Poll()	EFI_TCP4_PROTOCOL		Poll to receive incoming data and transmit outgoing segments.
Poll()	EFI_UDP4_PROTOCOL		Polls for incoming data packets and processes outgoing data packets.
<u>PollIo ()</u>	<u>EFI PCI I/O Protocol</u>		Polls an address in PCI I/O space until an exit condition is met, or a timeout occurs.
<u>PollIo ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Polls an address in I/O space until an exit condition is met, or a timeout occurs.
<u>PollMem ()</u>	<u>EFI PCI I/O Protocol</u>		Polls an address in PCI memory space until an exit condition is met, or a timeout occurs
<u>PollMem ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Polls an address in memory mapped I/O space until an exit condition is met, or a timeout occurs.
<u>ProtocolsPerHandle ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Retrieves the list of protocols installed on a handle. The return buffer is automatically allocated.

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Function Name	Service or Protocol	Subservice	Function Description
<u>Query ()</u>	<u>EFI Platform to Driver Configuration Protocol</u>		Called by the UEFI Driver Start () function to get configuration information from the platform.
<u>QueryCapsuleCapabilities ()</u>	<u>Runtime Services</u>		Returns whether a capsule can be updated by calling <u>UpdateCapsule ()</u> .
<u>QueryMode ()</u>	<u>Graphics Output Protocol</u>		Returns information for an available graphics mode that the graphics device and the set of active video output devices supports.
<u>QueryMode ()</u>	<u>Simple Text Output Protocol</u>		Queries information about the output device's supported text mode.
<u>QueryVariableInfo ()</u>	<u>Runtime Services</u>	<u>Variable Services</u>	Returns information about variables.
<u>RaiseTPL ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Raises the task priority level.
Release()	EFI_DHCP4_PROTOCOL		Releases the current address configuration.
RenewRebind()	EFI_DHCP4_PROTOCOL		Extends the lease time by sending a request packet.
<u>Read ()</u>	<u>EFI Debugport Protocol</u>		Receive a buffer of characters from the debugport device.
<u>Read ()</u>	<u>EFI File Protocol</u>		Reads bytes from a file.
<u>Read ()</u>	<u>Serial I/O Protocol</u>		Receives a buffer of characters from a serial device.
<u>ReadBlocks ()</u>	<u>Block I/O Protocol</u>		Reads the requested number of blocks from the device.

Function Name	Service or Protocol	Subservice	Function Description
ReadDirectory()	EFI_MTFTP4_PROTOCOL		Downloads a data file "directory" from an MTFTPv4 server. May be unsupported in some EFI implementations.
ReadFile()	EFI_MTFTP4_PROTOCOL		Downloads a file from an MTFTPv4 server.
ReadKeyStrokeEx()	EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL		Reads the next keystroke from the input device.
RegisterKeyNotify()	EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL		Register a notification function for a particular keystroke for the input device.
<u>ReadDisk ()</u>	<u>Disk I/O Protocol</u>		Reads data from the disk.
<u>ReadKeyStroke ()</u>	<u>Simple Text Input Protocol</u>		Reads a keystroke from a simple input device.
Receive()	EFI_IP4_PROTOCOL.		Places a receiving request into the receiving queue.
Receive()	EFI_MANAGED_NETWORK_PROTOCOL		Places an asynchronous receiving request into the receiving queue.
<u>Receive ()</u>	<u>Simple Network Protocol</u>		Receives a packet from the network interface.
Receive()	EFI_TCP4_PROTOCOL		Places an asynchronous receive request into the receiving queue.
Receive()	EFI_UDP4_PROTOCOL		Places an asynchronous receive request into the receiving queue.
<u>Receive</u>	<u>UNDI Commands</u>		When the network adapter has received a frame, this command is used to copy the frame into driver/application storage.
<u>Receive Filters</u>	<u>UNDI Commands</u>		This command is used to read and change receive filters and, if supported, read and change the multicast MAC address filter list.

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Function Name	Service or Protocol	Subservice	Function Description
<u>ReceiveFilters ()</u>	<u>Simple Network Protocol</u>		Enables and disables the receive filters for the network interface and, if supported, manages the filtered multicast HW MAC address list.
<u>RegisterICacheFlush ()</u>	<u>EBC Interpreter Protocol</u>		Called to register a callback function that the EBC interpreter can call to flush the processor instruction cache after creating thunks.
<u>RegisterExceptionCallback ()</u>	<u>EFI Debug Support Protocol</u>		Registers a callback function that will be called each time the specified processor exception occurs.
RegisterPackageNotify()	EFI_HII_DATABASE_PROTOCOL		Registers a notification function for HII database-related events.
<u>RegisterPeriodicCallback ()</u>	<u>EFI Debug Support Protocol</u>		Registers a callback function that will be invoked periodically and asynchronously to the execution of EFI.
<u>RegisterProtocolNotify ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Registers for protocol interface installation notifications.
<u>ReinstallProtocolInterface ()</u>	<u>Boot Services</u>	<u>Protocol Handler Services</u>	Replaces a protocol interface.
RemovePackageList()	EFI_HII_DATABASE_PROTOCOL		Removes a package list from the HII database.
Request()	EFI_ARP_PROTOCOL		Starts an ARP request session.
Reset()	EFI_ABSOLUTE_POINTER_PROTOCOL		Resets the pointer device hardware.
<u>Reset ()</u>	<u>Block I/O Protocol</u>		Resets the block device hardware.
<u>Reset ()</u>	<u>EFI Debugport Protocol</u>		Resets the debugport hardware.
<u>Reset ()</u>	<u>Serial I/O Protocol</u>		Resets the hardware device.

Function Name	Service or Protocol	Subservice	Function Description
Reset ()	Simple Text Input Protocol		Resets a simple input device.
Reset()	EFI_SIMPLE_TEXT_IN PUT_EX_PROTOCOL		Resets the input device hardware.
Reset ()	Simple Network Protocol		Resets the network adapter, and reinitializes it with the parameters that were provided in the previous call to Initialize () .
Reset ()	Simple Pointer Protocol		Resets the pointer device hardware.
Reset ()	Simple Text Output Protocol		Resets the ConsoleOut device.
Reset	UNDI Commands		This command resets the network adapter and reinitializes the UNDI with the same parameters provided in the Initialize command.
Reset ()	USB2 Host Controller Protocol		Software reset of USB.
ResetBus ()	EFI SCSI I/O Protocol		Resets the bus the SCSI device is attached to.
ResetChannel ()	Extended SCSI Pass Thru Protocol		Resets the SCSI channel.
ResetDevice ()	EFI SCSI I/O Protocol		Resets the SCSI device.
ResetSystem ()	Runtime Services	Miscellaneous Runtime Services	Resets the entire platform.
ResetTargetLun ()	Extended SCSI Pass Thru Protocol		Resets a SCSI device that is connected to the SCSI channel.
Response ()	EFI Platform to Driver Configuration Protocol		Called by the UEFI Driver Start () function to let the platform know how UEFI driver processed the data return from Query () .
RestoreTPL ()	Boot Services	Event, Timer, and Task Priority Services	Restores/lowers the task priority level.
Routes()	EFI_IP4_PROTOCOL.		Adds and deletes routing table entries.

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Function Name	Service or Protocol	Subservice	Function Description
Routes()	EFI_TCP4_PROTOCOL		Add or delete routing entries
Routes()	EFI_UDP4_PROTOCOL		Adds and deletes routing table entries.
RouteConfig()	EFI_HII_CONFIG_ACCESS_PROTOCOL.		This function processes the results of changes in configuration for the driver that published this protocol.
RouteConfig()	EFI_HII_CONFIG_ROUTING_PROTOCOL		This function processes the results of processing forms and routes it to the appropriate handlers or storage.
<u>RunDiagnostics ()</u>	<u>EFI Driver Diagnostics Protocol</u>		Runs diagnostics on a controller.
SendForm()	EFI_FORM_BROWSER_PROTOCOL		Provides direction to the configuration driver whether to use the HII database or a passed-in set of data. This function also establishes a pointer to the calling driver's callback interface.
Set()	EFI_AUTHENTICATION_INFO_PROTOCOL		Set the Authentication information for a given controller handle.
Set()	EFI_ISCSI_INITIATOR_NAME_PROTOCOL		Sets the iSCSI Initiator Name.
<u>SetAttribute ()</u>	<u>Simple Text Output Protocol</u>		Sets the foreground and background color of the text that is output.
<u>SetAttributes ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Sets attributes for a resource range on a PCI root bridge.
<u>SetAttributes ()</u>	<u>Serial I/O Protocol</u>		Sets communication parameters for a serial device.
<u>SetBarAttributes ()</u>	<u>EFI PCI I/O Protocol</u>		Sets the attributes for a range of a BAR on a PCI controller.
<u>SetControl ()</u>	<u>Serial I/O Protocol</u>		Sets the control bits on a serial device.
<u>SetCursorPosition ()</u>	<u>Simple Text Output Protocol</u>		Sets the current cursor position.

Function Name	Service or Protocol	Subservice	Function Description
SetImage()	EFI_HII_IMAGE_PROTOCOL		Change information about the image.
<u>SetInfo ()</u>	<u>EFI File Protocol</u>		Sets the requested file information.
<u>SetIpFilter ()</u>	<u>PXE Base Code Protocol</u>		Updates the IP receive filters of a network device and enables software filtering.
SetKeyboardLayout()	EFI_HII_DATABASE_PROTOCOL		Sets the currently active keyboard layout.
<u>SetMem ()</u>	<u>Boot Services</u>	<u>Miscellaneous Boot Services</u>	Fills a buffer with a specified value.
<u>SetMode ()</u>	<u>Simple Text Output Protocol</u>		Sets the current mode of the output device.
<u>SetMode ()</u>	<u>Graphics Output Protocol</u>		Set the video device into the specified mode and clears the output display to black.
<u>SetPackets ()</u>	<u>PXE Base Code Protocol</u>		Updates the contents of the cached DHCP and Discover packets.
<u>SetParameters ()</u>	<u>PXE Base Code Protocol</u>		Updates the parameters that affect the operation of the PXE Base Code Protocol.
<u>SetPosition ()</u>	<u>EFI File Protocol</u>		Sets the current file position.
<u>SetRootHubPortFeature ()</u>	<u>USB2 Host Controller Protocol</u>		Sets the feature for the specified root hub port.
SetState()	EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL		Set certain state for the input device.
<u>SetState ()</u>	<u>USB2 Host Controller Protocol</u>		Sets the USB host controller to a specific state.
<u>SetStationIp ()</u>	<u>PXE Base Code Protocol</u>		Updates the station IP address and/or subnet mask values.
SetString()	EFI_HII_STRING_PROTOCOL		Change information about the string.
<u>SetTime ()</u>	<u>Runtime Services</u>	<u>Time Services</u>	Sets the current local time and date information.
<u>SetTimer ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Sets an event to be signaled at a particular time.

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Function Name	Service or Protocol	Subservice	Function Description
<u>SetVariable ()</u>	<u>Runtime Services</u>	<u>Variable Services</u>	Sets the value of the specified variable.
<u>SetVirtualAddressMap ()</u>	<u>Runtime Services</u>	<u>Virtual Memory Services</u>	Used by an OS loader to convert from physical addressing to virtual addressing.
<u>SetWakeupTime ()</u>	<u>Runtime Services</u>	<u>Time Services</u>	Sets the system wakeup alarm clock time.
<u>SetWatchdogTimer ()</u>	<u>Boot Services</u>	<u>Miscellaneous Boot Services</u>	Resets and sets the system's watchdog timer.
<u>Shutdown ()</u>	<u>Boot Integrity Services Protocol</u>		Ends the lifetime of an application instance of the <u>EFI BIS PROTOCOL</u> , invalidating its application instance handle.
<u>Shutdown ()</u>	<u>Simple Network Protocol</u>		Resets the network adapter and leaves it in a state safe for another driver to initialize.
<u>Shutdown</u>	<u>UNDI Commands</u>		Resets the network adapter and leaves it in a safe state for another driver to initialize.
<u>SignalEvent ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Signals an event.
<u>Stall ()</u>	<u>Boot Services</u>	<u>Miscellaneous Boot Services</u>	Stalls the processor.
Start()	EFI_DHCP4_PROTOCOL		Starts the DHCP configuration process.
<u>Start ()</u>	<u>EFI Driver Binding Protocol</u>		Starts a device controller or a bus controller.
Start()	EFI_IP4_CONFIG_PROTOCOL		Starts running the configuration policy for the EFI IPv4 Protocol driver.
<u>Start ()</u>	<u>PXE Base Code Protocol</u>		Enables the use of PXE Base Code Protocol functions.

Function Name	Service or Protocol	Subservice	Function Description
<u>Start ()</u>	<u>Simple Network Protocol</u>		Changes the network interface from the stopped state to the started state.
<u>Start</u>	<u>UNDI Commands</u>		This command is used to change the UNDI operational state from stopped to started.
<u>StartImage ()</u>	<u>Boot Services</u>	<u>Image Services</u>	Function to transfer control to the Image's entry point.
<u>Station Address</u>	<u>UNDI Commands</u>		This command is used to get current station and broadcast MAC addresses and, if supported, to change the current station MAC address.
<u>StationAddress ()</u>	<u>Simple Network Protocol</u>		Allows the station address of the network interface to be modified.
<u>Statistics ()</u>	<u>Simple Network Protocol</u>		Allows the statistics on the network interface to be reset and/or collected.
<u>Statistics</u>	<u>UNDI Commands</u>		This command is used to read and clear the NIC traffic statistics.
<u>Stop ()</u>	<u>EFI Driver Binding Protocol</u>		Stops a device controller or a bus controller.
Stop()	EFI_DHCP4_PROTOCOL		Stops the DHCP configuration process.
Stop()	EFI_IP4_CONFIG_PROTOCOL		Stops running the configuration policy for the EFI IPv4 Protocol driver.
<u>Stop ()</u>	<u>PXE Base Code Protocol</u>		Disables the use of PXE Base Code Protocol functions.
<u>Stop ()</u>	<u>Simple Network Protocol</u>		Changes the network interface from the started state to the stopped state.

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Function Name	Service or Protocol	Subservice	Function Description
<u>Stop</u>	<u>UNDI Commands</u>		This command is used to change the UNDI operational state from started to stopped.
<u>StriColl ()</u>	<u>Unicode Collation Protocol</u>		Performs a case-insensitive comparison between two Unicode strings.
StringIdToImage()	EFI_HII_FONT_PROTOCOL		Render a string to a bitmap or the screen containing the contents of the specified string.
StringToImage()	EFI_HII_FONT_PROTOCOL		Renders a string to a bitmap or to the display.
<u>StrLwr ()</u>	<u>Unicode Collation Protocol</u>		Converts all the Unicode characters in a Null-terminated Unicode string to lower case Unicode characters.
<u>StrToFat ()</u>	<u>Unicode Collation Protocol</u>		Converts a Null-terminated Unicode string to legal characters in a FAT filename using an OEM character set.
<u>StrUpr ()</u>	<u>Unicode Collation Protocol</u>		Converts all the Unicode characters in a Null-terminated Unicode string to upper case Unicode characters.
<u>Supported ()</u>	<u>EFI Driver Binding Protocol</u>		Tests to see if driver supports a given controller, and further tests to see if driver supports creating a handle for a specified child device.
<u>SyncInterruptTransfer ()</u>	<u>USB2 Host Controller Protocol</u>		Submits a synchronous interrupt transfer to an interrupt endpoint of a USB device.
<u>TapeRead ()</u>	<u>Tape I/O Protocol</u>		Reads a block of data from the tape.
<u>TapeReset ()</u>	<u>Tape I/O Protocol</u>		Resets the tape device or its parent bus.
<u>TapeRewind ()</u>	<u>Tape I/O Protocol</u>		Rewinds the tape.
<u>TapeSpace ()</u>	<u>Tape I/O Protocol</u>		Positions the tape.

Function Name	Service or Protocol	Subservice	Function Description
TapeWrite ()	Tape I/O Protocol		Writes a block of data to the tape.
TapeWriteFM ()	Tape I/O Protocol		Write filemarks to the tape.
TestString ()	Simple Text Output Protocol		Tests to see if the ConsoleOut device supports this Unicode string.
Transmit()	EFI_IP4_PROTOCOL.		Places outgoing data packets into the transmit queue.
Transmit()	EFI_MANAGED_NETWORK_PROTOCOL		Places asynchronous outgoing data packets into the transmit queue.
Transmit()	EFI_UDP4_PROTOCOL		Queues outgoing data packets into the transmit queue.
Transmit ()	Simple Network Protocol		Places a packet in the transmit queue of the network interface.
Transmit()	EFI_TCP4_PROTOCOL		Queues outgoing data into the transmit queue.
Transmit	UNDI Commands		The Transmit command is used to place a packet into the transmit queue.
TransmitReceive()	EFI_DHCP4_PROTOCOL		Transmits a DHCP formatted packet and optionally waits for responses.
UdpRead ()	PXE Base Code Protocol		Reads a UDP packet from a network interface.
UdpWrite ()	PXE Base Code Protocol		Writes a UDP packet to a network interface.
UninstallAcpiTable()	EFI_ACPI_TABLE_PROTOCOL		Removes an ACPI table from the RSDT/XSDT.
UninstallMultipleProtocolInterfaces ()	Boot Services	Protocol Handler Services	Uninstalls one or more protocol interfaces from a handle.
UninstallProtocolInterface ()	Boot Services	Protocol Handler Services	Removes a protocol interface from a device handle.
Unload ()	Loaded Image Protocol		Requests an image to unload.
UnloadImage ()	Boot Services	Image Services	Unloads an image.

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Function Name	Service or Protocol	Subservice	Function Description
<u>UnloadImage ()</u>	<u>EBC Interpreter Protocol</u>		Called when an EBC image is unloaded to allow the interpreter to perform any cleanup associated with the image's execution.
<u>Unmap ()</u>	<u>EFI PCI I/O Protocol</u>		Releases any resources allocated by <u>Map ()</u> .
<u>Unmap ()</u>	<u>PCI Root Bridge I/O Protocol</u>		Releases any resources allocated by <u>Map ()</u> .
UnregisterPackageNotify()	EFI_HII_DATABASE_PROTOCOL		Removes the specified HII database package-related notification.
<u>UpdateBootObjectAuthorization ()</u>	<u>Boot Integrity Services Protocol</u>		Requests that the configuration parameters be altered by installing or removing an authorization certificate or changing the setting of the check flag.
<u>UpdateCapsule ()</u>	<u>Runtime Services</u>	<u>Miscellaneous Runtime Services</u>	Passes capsules to the firmware with both virtual and physical mapping.
UpdatePackageList()	EFI_HII_DATABASE_PROTOCOL		Update a package list in the HII database.
UnregisterKeyNotify()	EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL		Set certain state for the input device.
<u>UsbAsyncInterruptTransfer ()</u>	<u>USB I/O Protocol</u>		Nonblock USB interrupt transfer.
<u>UsbAsyncIsochronousTransfer ()</u>	<u>USB I/O Protocol</u>		Nonblock USB isochronous transfer.
<u>UsbBulkTransfer ()</u>	<u>USB I/O Protocol</u>		Accesses the USB Device through USB Bulk Transfer Pipe.
<u>UsbControlTransfer ()</u>	<u>USB I/O Protocol</u>		Accesses the USB Device through USB Control Transfer Pipe.
<u>UsbGetConfigDescriptor ()</u>	<u>USB I/O Protocol</u>		Retrieves the activated configuration descriptor of a USB device.
<u>UsbGetDeviceDescriptor ()</u>	<u>USB I/O Protocol</u>		Retrieves the device descriptor of a USB device.

Function Name	Service or Protocol	Subservice	Function Description
<u>UsbGetEndpointDescriptor ()</u>	<u>USB I/O Protocol</u>		Retrieves the endpoint descriptor of a USB Controller.
<u>UsbGetInterfaceDescriptor ()</u>	<u>USB I/O Protocol</u>		Retrieves the interface descriptor of a USB Controller.
<u>UsbGetStringDescriptor ()</u>	<u>USB I/O Protocol</u>		Retrieves the string descriptor inside a USB Device.
<u>UsbGetSupportedLanguages ()</u>	<u>USB I/O Protocol</u>		Retrieves the array of languages that the USB device supports.
<u>UsbIsochronousTransfer ()</u>	<u>USB I/O Protocol</u>		Accesses the USB Device through USB Isochronous Transfer Pipe.
<u>UsbPortReset ()</u>	<u>USB I/O Protocol</u>		Resets and reconfigures the USB controller.
<u>UsbSyncInterruptTransfer ()</u>	<u>USB I/O Protocol</u>		Accesses the USB Device through USB Synchronous Interrupt Transfer Pipe.
<u>VerifyBootObject ()</u>	<u>Boot Integrity Services Protocol</u>		Verifies a boot object according to the supplied digital signature and the current authorization certificate and check flag setting.
<u>VerifyObjectWithCredential ()</u>	<u>Boot Integrity Services Protocol</u>		Verifies a data object according to a supplied digital signature and a supplied digital certificate.
<u>WaitForEvent ()</u>	<u>Boot Services</u>	<u>Event, Timer, and Task Priority Services</u>	Stops execution until an event is signaled.
<u>Write ()</u>	<u>EFI Debugport Protocol</u>		Send a buffer of characters to the debugport device.
<u>Write ()</u>	<u>EFI File Protocol</u>		Writes bytes to a file.
<u>Write ()</u>	<u>Serial I/O Protocol</u>		Sends a buffer of characters to a serial device.

Function Name	Service or Protocol	Subservice	Function Description
WriteBlocks ()	Block I/O Protocol		Writes the requested number of blocks to the device.
WriteDisk ()	Disk I/O Protocol		Writes data to the disk.
WriteFile()	EFI_MTFPV4_PROTOCOL		Sends a data file to an MTFPV4 server. May be unsupported in some EFI implementations.

Table 198. Functions Listed Alphabetically within a Service or Protocol

Service or Protocol	Function	Function Description
Block I/O Protocol	FlushBlocks ()	Flushes any cached blocks.
	ReadBlocks ()	Reads the requested number of blocks from the device.
	Reset ()	Resets the block device hardware.
	WriteBlocks ()	Writes the requested number of blocks to the device.

Service or Protocol	Function	Function Description
Boot Integrity Services Protocol	Free ()	Frees memory structures allocated and returned by other functions in the EFI BIS PROTOCOL .
	GetBootObjectAuthorizationCertificate ()	Retrieves the current digital certificate (if any) used by the EFI BIS PROTOCOL as the source of authorization for verifying boot objects and altering configuration parameters.
	GetBootObjectAuthorizationCheckFlag ()	Retrieves the current setting of the authorization check flag that indicates whether or not authorization checks are required for boot objects.
	GetBootObjectAuthorizationUpdateToken ()	Retrieves an uninterpreted token whose value gets included and signed in a subsequent request to alter the configuration parameters, to protect against attempts to “replay” such a request.
	GetSignatureInfo ()	Retrieves information about the digital signature algorithms supported and the identity of the installed authorization certificate, if any.
	Initialize ()	Initializes an application instance of the EFI_BIS protocol, returning a handle for the application instance.
	Shutdown ()	Ends the lifetime of an application instance of the EFI_BIS protocol, invalidating its application instance handle.
	UpdateBootObjectAuthorization ()	Requests that the configuration parameters be altered by installing or removing an authorization certificate or changing the setting of the check flag.
	VerifyBootObject ()	Verifies a boot object according to the supplied digital signature and the current authorization certificate and check flag setting.
	VerifyObjectWithCredential ()	Verifies a data object according to a supplied digital signature and a supplied digital certificate.
Boot Services	AllocatePages ()	Allocates memory pages of a particular type.
	AllocatePool ()	Allocates pool of a particular type.
	CalculateCrc32 ()	Computes and returns a 32-bit CRC for a data buffer.
	CheckEvent ()	Checks whether an event is in the signaled state.
	CloseEvent ()	Closes and frees an event structure.
	CloseProtocol ()	Removes elements from the list of agents consuming a protocol interface.
	ConnectController ()	Uses a set of precedence rules to find the best set of drivers to manage a controller.
	CopyMem ()	Copies the contents of one buffer to another buffer.
	CreateEvent ()	Creates a general-purpose event structure.

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Service or Protocol	Function	Function Description
Boot Services	CreateEventEx ()	Creates an event in a group.
	DisconnectController ()	Informs a set of drivers to stop managing a controller.
	EFI_IMAGE_ENTRY_POINT	Prototype of an EFI Image's entry point.
	Exit ()	Exits the image's entry point.
	ExitBootServices ()	Terminates boot services.
	FreePages ()	Frees memory pages.
	FreePool ()	Frees allocated pool.
	GetMemoryMap ()	Returns the current boot services memory map and memory map key.
	GetNextMonotonicCount ()	Returns a monotonically increasing count for the platform.
	HandleProtocol ()	Queries the list of protocol handlers on a device handle for the requested Protocol Interface.
	InstallConfigurationTable ()	Adds, updates, or removes a configuration table from the EFI System Table
	InstallMultipleProtocolInterfaces ()	Installs one or more protocol interfaces onto a handle.
	InstallProtocolInterface ()	Adds a protocol interface to an existing or new device handle.
	LoadImage ()	Function to dynamically load another EFI Image.
	LocateDevicePath ()	Locates the closest handle that supports the specified protocol on the specified device path.
	LocateHandle ()	Locates the handle(s) that support the specified protocol.
	LocateHandleBuffer ()	Retrieves the list of handles from the handle database that meet the search criteria. The return buffer is automatically allocated.

Service or Protocol	Function	Function Description
Boot Services	LocateProtocol ()	Finds the first handle in the handle database the supports the requested protocol.
	OpenProtocol ()	Adds elements to the list of agents consuming a protocol interface.
	OpenProtocolInformation ()	Retrieve the list of agents that are currently consuming a protocol interface.
	ProtocolsPerHandle ()	Retrieves the list of protocols installed on a handle. The return buffer is automatically allocated.
	RaiseTPL ()	Raises the task priority level.
	RegisterProtocolNotify ()	Registers for protocol interface installation notifications
	ReinstallProtocolInterface ()	Replaces a protocol interface.
	RestoreTPL ()	Restores/lowers the task priority level.
	SetMem ()	Fills a buffer with a specified value.
	SetTimer ()	Sets an event to be signaled at a particular time.
	SetWatchdogTimer ()	Resets and sets the system's watchdog timer.
	SignalEvent ()	Signals an event.
	Stall ()	Stalls the processor.
	StartImage ()	Function to transfer control to the Image's entry point.
	UninstallMultipleProtocolInterfaces ()	Uninstalls one or more protocol interfaces from a handle.
	UninstallProtocolInterface ()	Removes a protocol interface from a device handle.
	UnloadImage ()	Unloads an image.
	WaitForEvent ()	Stops execution until an event is signaled.
	EFI_ABSOLUTE_POINTER_PROTOCOL	GetState()
	Reset()	
EFI Debugport Protocol	Poll ()	Determine if there is any data available to be read from the debugport device.
	Read ()	Receive a buffer of characters from the debugport device.
	Reset ()	Resets the debugport hardware.
	Write ()	Send a buffer of characters to the debugport device.

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Service or Protocol	Function	Function Description
EFI Debug Support Protocol	GetMaximumProcessorIndex ()	Returns the maximum processor index value that may be used with RegisterPeriodicCallback () and RegisterExceptionCallback () .
	InvalidateInstructionCache ()	Invalidate the instruction cache of the processor.
	RegisterExceptionCallback ()	Registers a callback function that will be called each time the specified processor exception occurs.
	RegisterPeriodicCallback ()	Registers a callback function that will be invoked periodically and asynchronously to the execution of EFI.
Decompress Protocol	Decompress ()	Decompresses a compressed source buffer into an uncompressed destination buffer.
	GetInfo ()	Given the compressed source buffer, this function retrieves the size of the uncompressed destination buffer and the size of the scratch buffer required to perform the decompression.
Device Path from Text Protocol	ConvertTextToDeviceNode ()	Converts text to a device node.
	ConvertTextToDevicePath ()	Converts text to a device path.
Device Path to Text Protocol	ConvertDeviceNodeToText ()	Converts a device node to text.
	ConvertDevicePathToText ()	Converts a device path to text.

Service or Protocol	Function	Function Description
Device Path Utilities Protocol	AppendDeviceNode()	Appends the device node to the specified device path.
	AppendDevicePath()	Appends the device path to the specified device path.
	AppendDevicePathInstance()	Appends a device path instance to another device path.
	CreateDeviceNode()	Allocates memory for a device node with the specified type and sub-type.
	DuplicateDevicePath()	Duplicates a device path structure.
	GetDevicePathSize()	Returns the size of the specified device path, in bytes.
	GetNextDevicePathInstance()	Retrieves the next device path instance from a device path data structure.
	IsDevicePathMultiInstance()	Returns TRUE if this is a multi-instance device path.
Disk I/O Protocol	ReadDisk()	Reads data from the disk.
	WriteDisk()	Writes data to the disk.
EFI_ABSOLUTE_POINTER_PROTOCOL	GetState()	Retrieves the current state of a pointer device.
	Reset()	Retrieves the current state of a pointer device.
EFI_ACPI_TABLE_PROTOCOL	InstallAcpiTable()	Installs an ACPI table into the RSDT/XSDT.
	UninstallAcpiTable()	Removes an ACPI table from the RSDT/XSDT.
EFI_ARP_PROTOCOL	Add()	Inserts an entry to the ARP cache.
	Cancel()	Cancels an ARP request session.
	Configure()	Assigns a station address (protocol type and network address) to this instance of the ARP cache.
	Delete()	Removes entries from the ARP cache.
	Find()	Locates one or more entries in the ARP cache.
	Flush()	Removes all dynamic ARP cache entries that were added by this interface.
	Request()	Starts an ARP request session.
EFI_AUTHENTICATION_INFO_PROTOCOL	Get()	Retrieves the Authentication information associated with a particular controller handle.
	Set()	Set the Authentication information for a given controller handle.

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Service or Protocol	Function	Function Description
EFI Bus Specific Driver Override Protocol	GetDriver ()	Uses a bus specific algorithm to retrieve a driver image handle for a controller.
EBC Interpreter Protocol	CreateThunk ()	Creates a thunk for an EBC image entry point or protocol service, and returns a pointer to the thunk.
	RegisterICacheFlush ()	Called to register a callback function that the EBC interpreter can call to flush the processor instruction cache after creating thunks.
	UnloadImage ()	Called when an EBC image is unloaded to allow the interpreter to perform any cleanup associated with the image's execution.
	GetVersion ()	Gets the version of the associated EBC interpreter.
EFI Component Name Protocol	GetControllerName ()	Retrieves a Unicode string that is the user readable name of the controller that is being managed by a UEFI driver.
	GetDriverName ()	Retrieves a Unicode string that is the user readable name of the UEFI driver.
EFI Device Path Protocol	No associated function	Can be used on any device handle to obtain generic path/location information concerning the physical device or logical device.
EFI_DHCP4_PROTOCOL	Build()	Builds a DHCP packet, given the options to be appended or deleted or replaced.
	Configure()	Initializes, changes, or resets the operational settings for the EFI DHCPv4 Protocol driver.
	GetModeData()	Returns the current operating mode and cached data packet for the EFI DHCPv4 Protocol driver.
	Parse()	Parses the packed DHCP option data.
	Release()	Releases the current address configuration.
	RenewRebind()	Extends the lease time by sending a request packet.
	Start()	Starts the DHCP configuration process.
	Stop()	Stops the DHCP configuration process.
	TransmitReceive()	Transmits a DHCP formatted packet and optionally waits for responses.
	EFI Driver Binding Protocol	Start ()
Stop ()		Stops a device controller or a bus controller.
Supported ()		Tests to see if driver supports a given controller, and further tests to see if driver supports creating a handle for a specified child device.
EFI Driver Diagnostics Protocol	RunDiagnostics ()	Runs diagnostics on a controller.
EFI Driver Entry Point	No associated function	The main entry point for a UEFI Driver.

Service or Protocol	Function	Function Description
EFI_EDID_OVERRIDE_PROTOCOL	GetEdid()	Returns policy information and potentially a replacement EDID for the specified video output device.
EFI File Protocol	Close ()	Closes the current file handle.
	Delete ()	Deletes a file.
	Flush ()	Flushes all modified data associated with the file to the device.
	GetInfo ()	Gets the requested file or volume information.
	GetPosition ()	Returns the current file position.
	Open ()	Opens or creates a new file.
	Read ()	Reads bytes from a file.
	SetInfo ()	Sets the requested file information.
	SetPosition ()	Sets the current file position.
Write ()	Writes bytes to a file.	
EFI_FORM_BROWSER_PROTOCOL	BrowserCallback() 1	This function is called by a callback handler to retrieve uncommitted state data from the browser.
	SendForm()	Provides direction to the configuration driver whether to use the HII database or a passed-in set of data. This function also establishes a pointer to the calling driver's callback interface.
EFI_HASH_PROTOCOL	GetHashSize()	Returns the size of the hash which results from a specific algorithm.
	Hash()	Creates a hash for the specified message text.
EFI_HII_CONFIG_ACCESS_PROTOCOL	CallBack()	This function is called to provide results data to the driver.
	ExtractConfig()	This function processes the results of processing forms and routes it to the appropriate handlers or storage.
	RouteConfig()	This function processes the results of changes in configuration for the driver that published this protocol.
EFI_HII_CONFIG_ROUTING_PROTOCOL	.BlockToConfig()	This helper function is to be called by drivers to map configuration data stored in byte array ("block") formats such as UEFI Variables into current configuration strings.
	ConfigToBlock()	This helper function is to be called by drivers to map configuration strings to configurations stored in byte array ("block") formats such as UEFI Variables.
	ExportConfig()	This function processes the results of processing forms and routes it to the appropriate handlers or storage.

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Service or Protocol	Function	Function Description
	ExtractConfig()	This function processes the results of processing forms and routes it to the appropriate handlers or storage.
	RouteConfig()	This function processes the results of processing forms and routes it to the appropriate handlers or storage.
EFI_HII_DATABASE_PROTOCOL	ExportPackageLists()	Exports the contents of one or all package lists in the HII database into a buffer.
	FindKeyboardLayouts()	Retrieves a list of the keyboard layouts in the system.
	GetKeyboardLayout()	Retrieves the requested keyboard layout.
	GetPackageListHandle()	Return the EFI handle associated with a package list.
	ListPackageLists()	Determines the handles that are currently active in the database.
	NewPackageList()	Adds the packages in the package list to the HII database.
	RegisterPackageNotify()	Registers a notification function for HII database-related events.
	RemovePackageList()	Removes a package list from the HII database.
	SetKeyboardLayout()	Sets the currently active keyboard layout.
	UnregisterPackageNotify()	Removes the specified HII database package-related notification.
	UpdatePackageList()	Update a package list in the HII database.
EFI_HII_FONT_PROTOCOL	GetFontInfo()	Return information about a particular font.
	GetGlyph()	Return information about a single glyph.
	StringIdToImage()	Render a string to a bitmap or the screen containing the contents of the specified string.
	StringToImage()	Renders a string to a bitmap or to the display.
EFI_HII_IMAGE_PROTOCOL	DrawImage()	Renders an image to a bitmap or to the display.
	DrawImageId()	Renders an image to a bitmap or to the display.
	GetImage()	Returns information about an image, associated with a package list.
	NewImage()	Creates a new image and add it to images from a specific package list.
	SetImage()	Change information about the image.
EFI_HII_STRING_PROTOCOL	GetLanguages()	Returns a list of the languages present in strings in a package list.
	GetSecondaryLanguages()	Given a primary language, returns the secondary languages supported in a package list.

Service or Protocol	Function	Function Description
	GetString()	Returns information about a string in a specific language, associated with a package list.
	NewString()	Creates a new string in a specific language and add it to strings from a specific package list.
	SetString()	Change information about the string.
EFI_IP4_CONFIG_PROTOCOL	GetData()	Returns the default configuration data (if any) for the EFI IPv4 Protocol driver.
	Start()	Starts running the configuration policy for the EFI IPv4 Protocol driver.
	Stop()	Stops running the configuration policy for the EFI IPv4 Protocol driver.
EFI_IP4_PROTOCOL	Cancel()	Abort an asynchronous transmit or receive request.
	Configure()	Assigns an IPv4 address and subnet mask to this EFI IPv4 Protocol driver instance.
	GetModeData()	Gets the current operational settings for this instance of the EFI IPv4 Protocol driver.
	Groups()	Joins and leaves multicast groups.
	Poll()	Polls for incoming data packets and processes outgoing data packets.
	Receive()	Places a receiving request into the receiving queue.
	Routes()	Adds and deletes routing table entries.
	Transmit()	Places outgoing data packets into the transmit queue.
EFI_ISCSI_INITIATOR_NAME_PROTOCOL	Get()	Retrieves the current set value of iSCSI Initiator Name.
	Set()	Sets the iSCSI Initiator Name.
EFI_MANAGED_NETWORK_PROTOCOL	Cancel()	Aborts an asynchronous transmit or receive request.
	Configure()	Sets or clears the operational parameters for the MNP child driver.
	GetModeData()	Returns the operational parameters for the current MNP child driver. May also support returning the underlying SNP driver mode data.
	Groups()	Enables and disables receive filters for multicast address. This function may be unsupported in some MNP implementations.
	McastIpToMac()	Translates an IP multicast address to a hardware (MAC) multicast address. This function may be unsupported in some MNP implementations.
	Poll()	Polls for incoming data packets and processes outgoing data packets.
	Receive()	Places an asynchronous receiving request into the receiving queue.

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Service or Protocol	Function	Function Description
	Transmit()	Places asynchronous outgoing data packets into the transmit queue.
EFI_MTFTP4_PROTOCOL	Configure()	Initializes, changes, or resets the default operational setting for this EFI MTFTPv4 Protocol driver instance.
	GetInfo()	Gets information about a file from an MTFTPv4 server.
	GetModeData()	Reads the current operational settings.
	ParseOptions()	Parses the options in an MTFTPv4 OACK packet.
	Poll()	Polls for incoming data packets and processes outgoing data packets.
	ReadDirectory()	Downloads a data file “directory” from an MTFTPv4 server. May be unsupported in some EFI implementations.
	ReadFile()	Downloads a file from an MTFTPv4 server.
	WriteFile()	Sends a data file to an MTFTPv4 server. May be unsupported in some EFI implementations.
EFI Platform Driver Override Protocol	<u>DriverLoaded ()</u>	Used to associate a driver image handle with a device path returned on a prior call.
	<u>GetDriver ()</u>	Retrieves the image handle of the platform override driver for a controller in the system.
	<u>GetDriverPath ()</u>	Retrieves the device path of the platform override driver for a controller in the system.
EFI Platform to Driver Configuration Protocol	<u>Query ()</u>	Called by the UEFI Driver Start () function to get configuration information from the platform.
	<u>Response ()</u>	Called by the UEFI Driver Start () function to let the platform know how UEFI driver processed the data return from <u>Query ()</u> .
EFI SCSI I/O Protocol	<u>GetDeviceType ()</u>	Retrieves the type of SCSI device.
	<u>GetDeviceLocation ()</u>	Retrieves the device location in the SCSI channel.
	<u>ResetBus ()</u>	Resets the bus the SCSI device is attached to.
	<u>ResetDevice ()</u>	Resets the SCSI device.
	<u>ExecuteScsiCommand ()</u>	Sends a SCSI Request Packet to the SCSI Device for execution.
EFI Service Binding Protocol	<u>CreateChild ()</u>	Creates a child handle and installs a protocol.
	<u>DestroyChild ()</u>	Destroys a child handle with a protocol installed on it.

Service or Protocol	Function	Function Description
EFI PCI I/O Protocol	AllocateBuffer ()	Allocates pages that are suitable for a common buffer mapping.
	Attributes ()	Performs an operation on the attributes that this PCI controller supports.
	CopyMem ()	Allows one region of PCI memory space to be copied to another region of PCI memory space
	Flush ()	Flushes all PCI posted write transactions to system memory.
	FreeBuffer ()	Frees pages that were allocated with AllocateBuffer () .
	GetBarAttributes ()	Gets the attributes that this PCI controller supports setting on a BAR using SetBarAttributes () , and retrieves the list of resource descriptors for a BAR.
	GetLocation ()	Retrieves this PCI controller's current PCI bus number, device number, and function number.
	Io.Read ()	Allows BAR relative reads to PCI I/O space.
	Io.Write ()	Allows BAR relative writes to PCI I/O space.
	Map ()	Provides the PCI controller specific address needed to access system memory for DMA.
	Mem.Read ()	Allows BAR relative reads to PCI memory space.
	Mem.Write ()	Allows BAR relative writes to PCI memory space.
	Pci.Read ()	Allows PCI controller relative reads to PCI configuration space.
	Pci.Write ()	Allows PCI controller relative writes to PCI configuration space.
	PollIo ()	Polls an address in PCI I/O space until an exit condition is met, or a timeout occurs.
	PollMem ()	Polls an address in PCI memory space until an exit condition is met, or a timeout occurs
	SetBarAttributes ()	Sets the attributes for a range of a BAR on a PCI controller.
Unmap ()	Releases any resources allocated by Map () .	
EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL	ReadKeyStrokeEx()	Reads the next keystroke from the input device.
	RegisterKeyNotify()	Register a notification function for a particular keystroke for the input device.
	Reset()	Resets the input device hardware.
	SetState()	Set certain state for the input device.
	UnregisterKeyNotify()	Set certain state for the input device.

Unified Extensible Firmware Interface Specification

Service or Protocol	Function	Function Description	
EFI_TCP4_PROTOCOL	Accept()	Listen on the passive instance to accept an incoming connection request. This is a nonblocking operation.	
	Cancel()	Abort an asynchronous connection, listen, transmission or receive request.	
	Close()	Disconnecting a TCP connection gracefully or reset a TCP connection. This function is a nonblocking operation.	
	Configure()	Initialize or brutally reset the operational parameters for this EFI TCPv4 instance.	
	Connect()	Initiate a nonblocking TCP connection request for an active TCP instance.	
	GetModeData()	Get the current operational status.	
	Poll()	Poll to receive incoming data and transmit outgoing segments.	
	Receive()	Places an asynchronous receive request into the receiving queue.	
	Routes()	Add or delete routing entries	
	Transmit()	Queues outgoing data into the transmit queue.	
	EFI_UDP4_PROTOCOL	Cancel()	Aborts an asynchronous transmit or receive request.
		Configure()	Initializes, changes, or resets the operational parameters for this instance of the EFI UDPv4 Protocol.
		GetModeData()	Reads the current operational settings.
Groups()		Joins and leaves multicast groups.	
Poll()		Polls for incoming data packets and processes outgoing data packets.	
Receive()		Places an asynchronous receive request into the receiving queue.	
Routes()		Adds and deletes routing table entries.	
Transmit()		Queues outgoing data packets into the transmit queue.	

Service or Protocol	Function	Function Description
Extended SCSI Pass Thru Protocol	BuildDevicePath ()	Allocates and builds a device path node for a SCSI Device on a SCSI channel.
	GetNextTarget ()	Retrieves the list of legal Target IDs for the SCSI devices on a SCSI channel.
	GetNextTargetLun ()	Retrieves the list of legal Target IDs and LUNs for the SCSI devices on a SCSI channel.
	GetTargetLun ()	Translates a device path node to a Target ID and LUN.
	PassThru ()	Sends a SCSI Request Packet to a SCSI device that is connected to the SCSI channel.
	ResetChannel ()	Resets the SCSI channel.
	ResetTargetLun ()	Resets a SCSI device that is connected to the SCSI channel.
EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL	ReadKeyStrokeEx()	Reads the next keystroke from the input device.
	RegisterKeyNotify()	Register a notification function for a particular keystroke for the input device.
	Reset()	Resets the input device hardware.
	SetState()	Set certain state for the input device.
	UnregisterKeyNotify()	Set certain state for the input device.
Graphics Output Protocol	Blt ()	Blt a rectangle of pixels on the graphics screen. Blt stands for BLock Transfer.
	QueryMode ()	Returns information for an available graphics mode that the graphics device and the set of active video output devices supports.
	SetMode ()	Set the video device into the specified mode and clears the visible portions of the output display to black.
Load File Protocol	LoadFile ()	Causes the driver to load the requested file.
Loaded Image Protocol	Unload ()	Requests an image to unload.

Unified Extensible Firmware Interface Specification

Service or Protocol	Function	Function Description
PCI Root Bridge I/O Protocol	AllocateBuffer ()	Allocates pages that are suitable for a common buffer mapping.
	Configuration ()	Gets the current resource settings for this PCI root bridge
	CopyMem ()	Allows one region of PCI root bridge memory space to be copied to another region of PCI root bridge memory space.
	Flush ()	Flushes all PCI posted write transactions to system memory.
	FreeBuffer ()	Free pages that were allocated with AllocateBuffer () .
	GetAttributes ()	Gets the attributes that a PCI root bridge supports setting with SetAttributes () , and the attributes that a PCI root bridge is currently using.
	Io.Read ()	Allows reads from I/O space.
	Io.Write ()	Allows writes to I/O space.
	Map ()	Provides the PCI controller specific addresses needed to access system memory for DMA.
	Mem.Read ()	Allows reads from memory mapped I/O space.
	Mem.Write ()	Allows writes to memory mapped I/O space.
	Pci.Read ()	Allows reads from PCI configuration space.
	Pci.Write ()	Allows writes to PCI configuration space
	PollIo ()	Polls an address in I/O space until an exit condition is met, or a timeout occurs.
	PollMem ()	Polls an address in memory mapped I/O space until an exit condition is met, or a timeout occurs.
	SetAttributes ()	Sets attributes for a resource range on a PCI root bridge.
Unmap ()	Releases any resources allocated by Map () .	
PXE Base Code Callback Protocol	Callback ()	Callback routine used by the PXE Base Code Dhcp () , Discover () , Mtftp () , UdpWrite () , and Arp () functions.

Service or Protocol	Function	Function Description
PXE Base Code Protocol	Arp ()	Uses the ARP protocol to resolve a MAC address.
	Dhcp ()	Attempts to complete a DHCPv4 D.O.R.A. (discover / offer / request / acknowledge) or DHCPv6 S.A.R.R (solicit / advertise / request / reply) sequence.
	Callback ()	Callback function that is invoked when the PXE Base Code Protocol is waiting for an event.
	Discover ()	Attempts to complete the PXE Boot Server and/or boot image discovery sequence.
	Mtftp ()	Is used to perform TFTP and MTFTP services.
	SetIpFilter ()	Updates the IP receive filters of a network device and enables software filtering.
	SetPackets ()	Updates the contents of the cached DHCP and Discover packets.
	SetParameters ()	Updates the parameters that affect the operation of the PXE Base Code Protocol.
	SetStationIp ()	Updates the station IP address and/or subnet mask values.
	Start ()	Enables the use of PXE Base Code Protocol functions.
	Stop ()	Disables the use of PXE Base Code Protocol functions.
	UdpRead ()	Reads a UDP packet from a network interface.
	UdpWrite ()	Writes a UDP packet to a network interface.
Runtime Services	ConvertPointer ()	Used by EFI components to convert internal pointers when switching to virtual addressing.
	GetNextHighMonotonicCount ()	Returns the next high 32 bits of a platform's monotonic counter.
	GetNextVariableName ()	Enumerates the current variable names.
	GetTime ()	Returns the current time and date, and the time-keeping capabilities of the platform.
	GetVariable ()	Returns the value of the specific variable.
	GetWakeupTime ()	Returns the current wakeup alarm clock setting.
	QueryCapsuleCapabilities ()	Returns whether a capsule can be updated by calling UpdateCapsule () .
	QueryVariableInfo ()	Returns information about variables.
	ResetSystem ()	Resets the entire platform.
	SetTime ()	Sets the current local time and date information.

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Service or Protocol	Function	Function Description
Runtime Services	<u>SetVariable ()</u>	Sets the value of the specified variable.
	<u>SetVirtualAddress Map ()</u>	Used by an OS loader to convert from physical addressing to virtual addressing.
	<u>SetWakeupTime ()</u>	Sets the system wakeup alarm clock time.
	<u>UpdateCapsule ()</u>	Passes capsules to the firmware with both virtual and physical mapping.
Serial I/O Protocol	<u>GetControl ()</u>	Reads the status of the control bits on a serial device.
	<u>Read ()</u>	Receives a buffer of characters from a serial device.
	<u>Reset ()</u>	Resets the hardware device.
	<u>SetAttributes ()</u>	Sets communication parameters for a serial device.
	<u>SetControl ()</u>	Sets the control bits on a serial device.
	<u>Write ()</u>	Sends a buffer of characters to a serial device.
Simple File System Protocol	<u>OpenVolume ()</u>	Opens the volume for file I/O access.
Simple Text Input Protocol	<u>ReadKeyStroke ()</u>	Reads a keystroke from a simple input device.
	<u>Reset ()</u>	Resets a simple input device.
Simple Network Protocol	<u>GetStatus ()</u>	Reads the current interrupt status and recycled transmit buffer status from the network interface.
	<u>Initialize ()</u>	Resets the network adapter and allocates the transmit and receive buffers required by the network interface; also optionally allows space for additional transmit and receive buffers to be allocated
	<u>MCastIPtoMAC ()</u>	Allows a multicast IP address to be mapped to a multicast HW MAC address.
	<u>NvData ()</u>	Allows read and writes to the NVRAM device attached to a network interface.
	<u>Receive ()</u>	Receives a packet from the network interface.
	<u>ReceiveFilters ()</u>	Enables and disables the receive filters for the network interface and, if supported, manages the filtered multicast HW MAC address list
	<u>Reset ()</u>	Resets the network adapter, and reinitializes it with the parameters that were provided in the previous call to <u>Initialize ()</u> .

Service or Protocol	Function	Function Description
Simple Network Protocol	<u>Shutdown ()</u>	Resets the network adapter and leaves it in a state safe for another driver to initialize.
	<u>Start ()</u>	Changes the network interface from the stopped state to the started state.
	<u>StationAddress ()</u>	Allows the station address of the network interface to be modified.
	<u>Statistics ()</u>	Allows the statistics on the network interface to be reset and/or collected.
	<u>Stop ()</u>	Changes the network interface from the started state to the stopped state.
	<u>Transmit ()</u>	Places a packet in the transmit queue of the network interface.
Simple Pointer Protocol	<u>GetState ()</u>	Retrieves the current state of a pointer device.
	<u>Reset ()</u>	Resets the pointer device hardware.
Simple Text Output Protocol	<u>ClearScreen ()</u>	Clears the screen with the currently set background color.
	<u>EnableCursor ()</u>	Turns the visibility of the cursor on/off.
	<u>OutputString ()</u>	Displays the Unicode string on the device at the current cursor location.
	<u>QueryMode ()</u>	Queries information concerning the output device's supported text mode.
	<u>Reset ()</u>	Resets the ConsoleOut device.
	<u>SetAttribute ()</u>	Sets the foreground and background color of the text that is output.
	<u>SetCursorPosition ()</u>	Sets the current cursor position.
	<u>SetMode ()</u>	Sets the current mode of the output device.
	<u>TestString ()</u>	Tests to see if the ConsoleOut device supports this Unicode string.
Tape I/O Protocol	<u>TapeRead ()</u>	Reads a block of data from the tape.
	<u>TapeReset ()</u>	Resets the tape device or its parent bus.
	<u>TapeRewind ()</u>	Rewinds the tape.
	<u>TapeSpace ()</u>	Positions the tape.
	<u>TapeWrite ()</u>	Writes a block of data to the tape.
	<u>TapeWriteFM ()</u>	Write filemarks to the tape.

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Service or Protocol	Function	Function Description
UNDI Commands	Fill Header	This command is used to fill the media header(s) in transmit packet(s).
	Get Config Info	This command is used to retrieve configuration information about the NIC being controlled by the UNDI.
	Get Init Info	This command is used to retrieve initialization information that is needed by drivers and applications to initialize UNDI.
	Get State	This command is used to determine the operational state of the UNDI.
	Get Status	This command returns the current interrupt status and/or the transmitted buffer addresses.
	Initialize	This command resets the network adapter and initializes UNDI using the parameters supplied in the CPB.
	Interrupt Enables	The Interrupt Enables command can be used to read and/or change the current external interrupt enable settings.
	MCast IP To MAC	Translate a multicast IPv4 or IPv6 address to a multicast MAC address.
	NvData	This command is used to read and write (if supported by NIC H/W) nonvolatile storage on the NIC.
	Receive	When the network adapter has received a frame, this command is used to copy the frame into driver/application storage.
	Receive Filters	This command is used to read and change receive filters and, if supported, read and change the multicast MAC address filter list.
	Reset	This command resets the network adapter and reinitializes the UNDI with the same parameters provided in the Initialize command.
	Shutdown	The Shutdown command resets the network adapter and leaves it in a safe state for another driver to initialize.

Service or Protocol	Function	Function Description
UNDI Commands	<u>Start</u>	This command is used to change the UNDI operational state from stopped to started.
	<u>Station Address</u>	This command is used to get current station and broadcast MAC addresses and, if supported, to change the current station MAC address.
	<u>Statistics</u>	This command is used to read and clear the NIC traffic statistics.
	<u>Stop</u>	This command is used to change the UNDI operational state from started to stopped.
	<u>Transmit</u>	The Transmit command is used to place a packet into the transmit queue.
Unicode Collation Protocol	<u>FatToStr ()</u>	Converts an 8.3 FAT file name in an OEM character set to a Null-terminated Unicode string.
	<u>MetaiMatch ()</u>	Performs a case insensitive comparison between a Unicode pattern string and a Unicode string.
	<u>StriColl ()</u>	Performs a case-insensitive comparison between two Unicode strings.
	<u>StrLwr ()</u>	Converts all the Unicode characters in a Null-terminated Unicode string to lower case Unicode characters.
	<u>StrToFat ()</u>	Converts a Null-terminated Unicode string to legal characters in a FAT filename using an OEM character set.
	<u>StrUpr ()</u>	Converts all the Unicode characters in a Null-terminated Unicode string to upper case Unicode characters.
USB2 Host Controller Protocol	<u>AsyncInterruptTransfer ()</u>	Submits an asynchronous interrupt transfer to an interrupt endpoint of a USB device.
	<u>AsyncIsochronousTransfer ()</u>	Submits nonblocking USB isochronous transfer.
	<u>BulkTransfer ()</u>	Submits a bulk transfer to a bulk endpoint of a USB device.
	<u>ClearRootHubPortFeature ()</u>	Clears the feature for the specified root hub port.
	<u>ControlTransfer ()</u>	Submits a control transfer to a target USB device.
	<u>GetCapability ()</u>	Retrieves the capabilities of the USB host controller.
	<u>GetRootHubPortStatus ()</u>	Retrieves the status of the specified root hub port.
	<u>GetState ()</u>	Retrieves the current state of the USB host controller.

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Service or Protocol	Function	Function Description
USB2 Host Controller Protocol	IsochronousTransfer ()	Submits isochronous transfer to an isochronous endpoint of a USB device.
	Reset ()	Software reset of USB.
	SetRootHubPortFeature ()	Sets the feature for the specified root hub port.
	SetState ()	Sets the USB host controller to a specific state.
	SyncInterruptTransfer ()	Submits a synchronous interrupt transfer to an interrupt endpoint of a USB device.
USB I/O Protocol	UsbAsyncInterruptTransfer ()	Nonblock USB interrupt transfer.
	UsbAsyncIsochronousTransfer ()	Nonblock USB isochronous transfer.
	UsbBulkTransfer ()	Accesses the USB Device through USB Bulk Transfer Pipe.
	UsbControlTransfer ()	Accesses the USB Device through USB Control Transfer Pipe.
	UsbGetConfigDescriptor ()	Retrieves the activated configuration descriptor of a USB device.
	UsbGetDeviceDescriptor ()	Retrieves the device descriptor of a USB device.
	UsbGetEndpointDescriptor ()	Retrieves the endpoint descriptor of a USB Controller.
	UsbGetInterfaceDescriptor ()	Retrieves the interface descriptor of a USB Controller.
	UsbGetStringDescriptor ()	Retrieves the string descriptor inside a USB Device.
	UsbGetSupportedLanguages ()	Retrieves the array of languages that the USB device supports.
	UsbIsochronousTransfer ()	Accesses the USB Device through USB Isochronous Transfer Pipe.
	UsbPortReset ()	Resets and reconfigures the USB controller.
	UsbSyncInterruptTransfer ()	Accesses the USB Device through USB Synchronous Interrupt Transfer Pipe.

Appendix L

EFI 1.10 Protocol Changes and Deprecation List

L.1 Protocol and GUID Name Changes from EFI 1.10

This appendix lists the Protocol, GUID, and revision identifier name changes and the deprecated protocols compared to the *EFI Specification 1.10*. The protocols listed are not Runtime, Reentrant or MP Safe. Protocols are listed by EFI 1.10 name.

For protocols in the table whose TPL is not <= TPL_NOTIFY:

This function must be called at a TPL level less than or equal to %%%.

%%% is TPL_CALLBACK or TPL_APPLICATION. The <= is done via text.

Table 199. Protocol Name changes

EFI 11.0 Protocol Name	UEFI 2.0 Protocol Name
EFI_LOADED_IMAGE	EFI_LOADED_IMAGE_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_LOADED_IMAGE_PROTOCOL_GUID
EFI_DEVICE_PATH	EFI_DEVICE_PATH_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_DEVICE_PATH_PROTOCOL_GUID
SIMPLE_INPUT_INTERFACE	EFI_SIMPLE_INPUT_PROTOCOL
TPL	<= TPL_APPLICATION
New GUID name	EFI_SIMPLE_INPUT_PROTOCOL_GUID
SIMPLE_TEXT_OUTPUT_INTERFACE	EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL
TPL	<=TPL_CALLBACK
New GUID name	EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL_GUID
SERIAL_IO_INTERFACE	EFI_SERIAL_IO_PROTOCOL
TPL	<=TPL_CALLBACK
New GUID name	EFI_SERIAL_IO_PROTOCOL_GUID
EFI_LOAD_FILE_INTERFACE	EFI_LOAD_FILE_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_LOAD_FILE_PROTOCOL_GUID
EFI_FILE_IO_INTERFACE	EFI_SIMPLE_FILE_SYSTEM_PROTOCOL
TPL	<=TPL_CALLBACK
New GUID name	EFI_FILE_SYSTEM_PROTOCOL_GUID
EFI_FILE	EFI_FILE_PROTOCOL
TPL	<= TPL_CALLBACK
New GUID name	EFI_FILE_PROTOCOL_GUID
EFI_DISK_IO	EFI_DISK_IO_PROTOCOL

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EFI 11.0 Protocol Name	UEFI 2.0 Protocol Name
TPL	<=TPL_CALLBACK
New GUID name	EFI_DISK_IO_PROTOCOL_GUID
EFI_BLOCK_IO	EFI_BLOCK_IO_PROTOCOL
TPL	<=TPL_CALLBACK
New GUID name	EFI_BLOCK_IO_PROTOCOL_GUID
UNICODE_COLLATION_INTERFACE	EFI_UNICODE_COLLATION_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_UNICODE_COLLATION_PROTOCOL_GUID
EFI_SIMPLE_NETWORK	EFI_SIMPLE_NETWORK_PROTOCOL
TPL	<=TPL_CALLBACK
New GUID name	EFI_SIMPLE_NETWORK_PROTOCOL_GUID
EFI_NETWORK_INTERFACE_IDENTIFIER_INTERFACE	EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_GUID
EFI_PXE_BASE_CODE	EFI_PXE_BASE_CODE_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_PXE_BASE_CODE_PROTOCOL_GUID
EFI_PXE_BASE_CODE_CALLBACK	EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_GUID
EFI_DEVICE_IO_INTERFACE	EFI_DEVICE_IO_PROTOCOL
TPL	<= TPL_NOTIFY
New GUID name	EFI_DEVICE_IO_PROTOCOL_GUID

Table 200. Revision Identifier Name Changes

EFI 11.0 Revision Identifier Name	UEFI 2.0 Revision Identifier Name
EFI_LOADED_IMAGE_INFORMATION_REVISION	EFI_LOADED_IMAGE_PROTOCOL_REVISION
SERIAL_IO_INTERFACE_REVISION	EFI_SERIAL_IO_PROTOCOL_REVISION
EFI_FILE_IO_INTERFACE_REVISION	EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_REVISION
EFI_FILE_REVISION	EFI_FILE_PROTOCOL_REVISION
EFI_DISK_IO_INTERFACE_REVISION	EFI_DISK_IO_PROTOCOL_REVISION
EFI_BLOCK_IO_INTERFACE_REVISION	EFI_BLOCK_IO_PROTOCOL_REVISION
EFI_SIMPLE_NETWORK_INTERFACE_REVISION	EFI_SIMPLE_NETWORK_PROTOCOL_REVISION
EFI_NETWORK_INTERFACE_IDENTIFIER_INTERFACE_REVISION	EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_REVISION

EFI 11.0 Revision Identifier Name	UEFI 2.0 Revision Identifier Name
EFI_PXE_BASE_CODE_INTERFACE_REVISION	EFI_PXE_BASE_CODE_PROTOCOL_REVISION
EFI_PXE_BASE_CODE_CALLBACK_INTERFACE_REVISION	EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_REVISION

L.2 Deprecated Protocols

Device I/O Protocol – The support of the Device I/O Protocol (see EFI 1.1 Chapter 18) has been replaced by the use of the **PCI Root Bridge I/O** protocols which are described in [Section 13.2](#) of the UEFI 2.0 specification. Note: certain “legacy” EFI applications such as some of the ones that reside in the EFI Toolkit assume the presence of Device I/O.

UGA I/O + UGA Draw Protocol – The support of the UGA * Protocols (see EFI 1.1 Section 10.7) have been replaced by the use of the **EFI Graphics Output Protocol** described in [Section 11](#) of the UEFI 2.0 specification.

USB Host Controller Protocol (version that existed for EFI 1.1) – The support of the USB Host Controller Protocol (see EFI 1.1 Section 14.1) has been replaced by the use of a UEFI 2.0 instance that covers both USB 1.1 and USB 2.0 support, and is described in [Section 16](#) of the UEFI 2.0 specification. It replaces the pre-existing protocol definition.

SCSI Passthru Protocol – The support of the SCSI Passthru Protocol (see EFI 1.1 Section 13.1) has been replaced by the use of the **Extended SCSI Passthru Protocol** which is described in Chapter [Section 14.7](#) of the UEFI 2.0 specification.

BIS Protocol – Remains as an optional protocol.

Driver Configuration Protocol - the **EFI_DRIVER_CONFIGURATION_PROTOCOL** has been removed.

Appendix M

Formats--Language Codes and Language Code Arrays

This appendix lists the formats for language codes and language code arrays.

Specifying individual language codes

The preferred representation of a language code is done via an RFC 3066 language code identifier*.

*The following alias codes are also supported in addition to RFC 3066:

RFC string Supported Alias String

zh-Hans zh-chs

zh-Hant zh-cht

An RFC 3066 language code is represented as a NULL terminated char8 string.

An RFC 3066 language string must be constructed according to the tag creation rules in section 2.3 of RFC 3066. For example, when constructing the primary language tag for a locale identifier, if a 2 character ISO 639-1 language code exists along with a 3 character ISO 639-2 language code, then the ISO 639-1 language code must be used. Further, if an ISO 639-1 tag does not exist, then the ISO 639-2/T (Terminology) tag must be for the primary locale before an ISO 639-2/B (Bibliographic) tag may be used. See RFC 3066 for a complete discussion of this topic.

To provide backwards compatibility with preexisting EFI 1.10 drivers, a UEFI platforms may support deprecated protocols which represent languages in the ISO 639-2 format. This includes the following protocols: `UNICODE_COLLATION_INTERFACE`, `EFI_DRIVER_CONFIGURATION_PROTOCOL`,

`EFI_DRIVER_DIAGNOSTICS_PROTOCOL`, and `EFI_COMPONENT_NAME_PROTOCOL`.

The deprecated `LangCodes` and `Lang` global variables may also be supported by a platform for backwards compatibility.

Specifying language code arrays:

Native RFC 3066 format array:

An array of RFC 3066 character codes is represented as a NULL terminated char8 array of RFC 3066 language code strings. Each of these strings is delimited by a semicolon (;) character. For example, an array of US English and Traditional Chinese would be represented as the NULL-terminated string "en-us;zh-Hant".

Appendix N

Common Platform Error Record

N.1 Introduction

This appendix describes the common platform error record format for representing platform hardware errors.

N.2 Format

The general format of the common platform error record is illustrated in [Figure 110](#). The record consists of a header; followed by one or more section descriptors; and for each descriptor, an associated section which may contain either error or informational data.

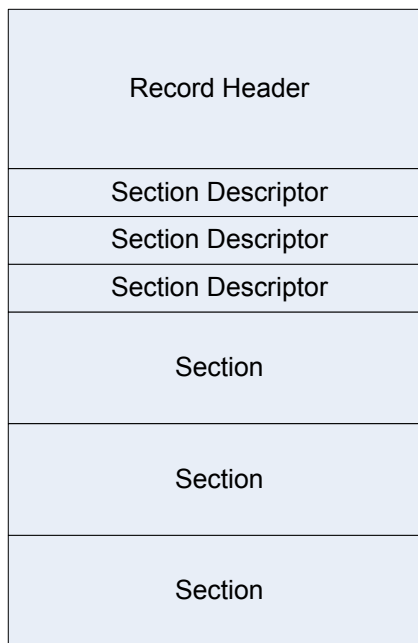


Figure 110. Error Record Format

N.2.1 Record Header

The record header includes information which uniquely identifies a hardware error record on a given system. The contents of the record header are described in [Table 201](#). The header is immediately followed by an array of one or more section descriptors. Sections may be either error sections, which contain error information retrieved from hardware, or they may be informational sections, which contain contextual information relevant to the error. An error record must contain at least one section.

Table 201. Error record header

Mnemonic	Byte Offset	Byte Length	Description
Signature Start	0	4	'REPC' Identifies this structure as a hardware error record
Revision	4	2	This is a 2-byte field representing a major and minor version number for the error record definition in BCD format. The interpretation of the major and minor version number is as follows: <ul style="list-style-type: none"> • Byte 0 – Minor (00): An increase in this revision indicates that changes to the headers and sections are backward compatible with software that use earlier revisions. Addition of new GUID types, errata fixes or clarifications are covered by a bump up. • Byte 1 – Major (01): An increase in this revision indicates that the changes are not backward compatible from a software perspective.
Signature End	6	4	Must be 0xFFFFFFFF
Section Count	10	2	This field indicates the number of valid sections associated with the record, corresponding to each of the following section descriptors.
Error Severity	12	4	Indicates the severity of the error condition. The severity of the error record corresponds to the most severe error section. <ul style="list-style-type: none"> 0 - Recoverable (also called non-fatal uncorrected) 1 - Fatal 2 - Corrected 3 - Informational All other values are reserved.
Validation Bits	16	4	This field indicates the validity of the following fields: <ul style="list-style-type: none"> • Bit 0 – If 1, the PlatformID field contains valid information • Bit 1 – If 1, the TimeStamp field contains valid information • Bit2: If 1, the PartitionID field contains valid information • Bits 3-31: Reserved, must be zero.
Record Length	20	4	Indicates the size of the actual error record, including the size of the record header, all section descriptors, and section bodies. The size may include extra buffer space to allow for the dynamic addition of error sections descriptors and bodies.

Mnemonic	Byte Offset	Byte Length	Description
Timestamp	24	8	<p>The timestamp correlates to the time when the error information was collected by the system software and may not necessarily represent the time of the error event. The timestamp contains the local time in BCD format.</p> <ul style="list-style-type: none"> • Byte 7 – Byte 0: • Byte 0: Seconds • Byte 1: Minutes • Byte 2: Hours • Byte 3: • Bit 0 – Timestamp is precise if this bit • is set and correlates to the time of the • error event. • Bit 7:1 – Reserved • Byte 4: Day • Byte 5: Month • Byte 6: Year • Byte 7: Century
Platform ID	32	16	<p>This field uniquely identifies the platform with a GUID. The platform's SMBIOS UUID should be used to populate this field. Error analysis software may use this value to uniquely identify a platform.</p>
Partition ID	48	16	<p>If the platform has multiple software partitions, system software may associate a GUID with the partition on which the error occurred.</p>
Creator ID	64	16	<p>This field contains a GUID indicating the creator of the error record. This value may be overwritten by subsequent owners of the record.</p>

Mnemonic	Byte Offset	Byte Length	Description
Notification Type	80	16	<p>This field holds a pre-assigned GUID value indicating the record association with an error event notification type. The defined types are:</p> <p>CMC {0x2DCE8BB1, 0xBDD7, 0x450e, {0xB9, 0xAD, 0x9C, 0xF4, 0xEB, 0xD4, 0xF8, 0x90}}</p> <p>CPE {0x4E292F96, 0xD843, 0x4a55, {0xA8, 0xC2, 0xD4, 0x81, 0xF2, 0x7E, 0xBE, 0xEE}}</p> <p>MCE {0xE8F56FFE, 0x919C, 0x4cc5, {0xBA, 0x88, 0x65, 0xAB, 0xE1, 0x49, 0x13, 0xBB}}</p> <p>PCIe {0xCF93C01F, 0x1A16, 0x4dfc, {0xB8, 0xBC, 0x9C, 0x4D, 0xAF, 0x67, 0xC1, 0x04}}</p> <p>INIT {0xCC5263E8, 0x9308, 0x454a, {0x89, 0xD0, 0x34, 0x0B, 0xD3, 0x9B, 0xC9, 0x8E}}</p> <p>NMI {0x5BAD89FF, 0xB7E6, 0x42c9, {0x81, 0x4A, 0xCF, 0x24, 0x85, 0xD6, 0xE9, 0x8A}}</p> <p>Boot {0x3D61A466, 0xAB40, 0x409a, {0xA6, 0x98, 0xF3, 0x62, 0xD4, 0x64, 0xB3, 0x8F}}</p>
Record ID	96	8	A platform generated record ID, which uniquely identifies each record. This is a monotonically increasing value which is unique across all record types.
Flags	104	4	Flags field contains information that describes the error record. See Table 2 for defined flags.
OS Reserved	108	8	Field for use by OS.
Reserved	116	12	Reserved. Must be zero.
Section Descriptor	128	Nx72	An array of <i>SectionCount</i> descriptors for the associated sections. The number of valid sections is equivalent to the <i>SectionCount</i> . The buffer size of the record may include more space to dynamically add additional Section Descriptors to the error record.

[Table 202](#) lists the flags that may be used to qualify an error record in the Error Record Header's Flags field.

Table 202. Error Record Header Flags

Value	Description
1	HW_ERROR_FLAGS_RECOVERED: Qualifies an error condition as one that has been recovered by system software.
2	HW_ERROR_FLAGS_PREVERR: Qualifies an error condition as one that occurred during a previous session. For instance, if the OS detects an error and determines that the system must be reset; it will save the error record before stopping the system. Upon restarting the OS marks the error record with this flag to know that the error is not live.
4	HW_ERROR_FLAGS_SIMULATED: Qualifies an error condition as one that was intentionally caused. This allows system software to recognize errors that are injected as a means of validating or testing error handling mechanisms.

N.2.1.1 Notification Type

A notification type identifies the mechanism by which an error event is reported to system software. This information helps consumers of error information (e.g. management applications or humans) by identifying the source of the error information. This allows, for instance, all CMC error log entries to be filtered from an error event log.

Listed below are the standard notification types. Each standard notification type is identified by a GUID. For error notification types that do not conform to one of the standard types, a platform-specific GUID may be defined to identify the notification type.

- Machine Check Exception (MCE): {0xE8F56FFE, 0x919C, 0x4cc5, {0xBA, 0x88, 0x65, 0xAB, 0xE1, 0x49, 0x13, 0xBB}}

A Machine Check Exception is a processor-generated exception class interrupt used to system software of the presence of a fatal or recoverable error condition.
- Corrected Machine Check (CMC): {0x2DCE8BB1, 0xBDD7, 0x450e, {0xB9, 0xAD, 0x9C, 0xF4, 0xEB, 0xD4, 0xF8, 0x90}}

Corrected Machine Checks identify error conditions that have been corrected by hardware or system firmware. CMCs are reported by the processor and may be reported via interrupt or by polling error status registers.
- Corrected Platform Error (CPE): {0x4E292F96, 0xD843, 0x4a55, {0xA8, 0xC2, 0xD4, 0x81, 0xF2, 0x7E, 0xBE, 0xEE}}

Corrected Platform Errors identify corrected errors from the platform (i.e. external memory controller, system bus, etc.). CPEs can be reported via interrupt or by polling error status registers.
- Non-Maskable Interrupt (NMI): {0x5BAD89FF, 0xB7E6, 0x42c9, {0x81, 0x4A, 0xCF, 0x24, 0x85, 0xD6, 0xE9, 0x8A}}

Non-Maskable Interrupts are used on X64 platforms to report fatal or recoverable platform error conditions. NMIs are reported via interrupt vector 2 on IA32 and X64 processor architecture platforms.
- PCI Express Error (PCIe): {0xCF93C01F, 0x1A16, 0x4dfc, {0xB8, 0xBC, 0x9C, 0x4D, 0xAF, 0x67, 0xC1, 0x04}}

See the PCI Express standard v1.1 for details regarding PCI Express Error Reporting. This notification type identifies errors that were reported to the system via an interrupt on a PCI Express root port.

- INIT Record (INIT): {0xCC5263E8, 0x9308, 0x454a, {0x89, 0xD0, 0x34, 0x0B, 0xD3, 0x9B, 0xC9, 0x8E}}

IPF Platforms optionally implement a mechanism (switch or button on the chassis) by which an operator may reset a system and have the system generate an INIT error record. This error record is documented in the IPF SAL specification. System software retrieves an INIT error record by querying the SAL for existing INIT records.

- BOOT Error Record (BOOT): {0x3D61A466, 0xAB40, 0x409a, {0xA6, 0x98, 0xF3, 0x62, 0xD4, 0x64, 0xB3, 0x8F}}

The BOOT Notification Type represents error conditions which are unhandled by system software and which result in a system shutdown/reset. System software retrieves a BOOT error record during boot by querying the platform for existing BOOT records. As an example, consider an x64 platform which implements a service processor. In some scenarios, the service processor may detect that the system is either hung or is in such a state that it cannot safely proceed without risking data corruption. In such a scenario the service processor may record some minimal error information in its system event log (SEL) and unilaterally reset the machine without notifying the OS or other system software. In such scenarios, system software is unaware of the condition that caused the system reset. A BOOT error record would contain information that describes the error condition that led to the reset so system software can log the information and use it for health monitoring.

N.2.2 Section Descriptor

Table 203. Section Descriptor

Mnemonic	Byte Offset	Byte Length	Description
Section Offset	0	4	Offset in bytes of the section body from the base of the record header.
Section Length	4	4	The length in bytes of the error section.
Revision	8	2	This is a 2-byte field representing a major and minor version number for the error record definition in BCD format. The interpretation of the major and minor version number is as follows: <ul style="list-style-type: none"> • Byte 0 – Minor (00): An increase in this revision indicates that changes to the headers and sections are backward compatible with software that uses earlier revisions. Addition of new GUID types, errata fixes or clarifications are covered by a bump up. • Byte 1 – Major (01): An increase in this revision indicates that the changes are not backward compatible from a software perspective
Validation Bits	10	1	This field indicates the validity of the following fields: <ul style="list-style-type: none"> • Bit 0 - If 1, the FRUId field contains valid information • Bit 1 - If 1, the FRUString field contains valid information Bits 7:2 – Reserved, must be zero.
Reserved	11	1	Must be zero.

Mnemonic	Byte Offset	Byte Length	Description
Flags	12	4	<p>Flag field contains information that describes the error section as follows:</p> <p>Bit 0 – Primary: If set, identifies the section as the section to be associated with the error condition. This allows for FRU determination and for error recovery operations. By identifying a primary section, the consumer of an error record can determine which section to focus on. It is not always possible to identify a primary section so this flag should be taken as a hint.</p> <p>Bit 1 – Containment Warning: If set, the error was not contained within the processor or memory hierarchy and the error may have propagated to persistent storage or network.</p> <p>Bit 2 – Reset: If set, the component must be re-initialized or re-enabled by the operating system prior to use.</p> <p>Bit 3 – Error threshold exceeded: If set, OS may choose to discontinue use of this resource.</p> <p>Bit 4 – Resource not accessible: If set, the resource could not be queried for error information due to conflicts with other system software or resources. Some fields of the section will be invalid.</p> <p>Bit 5 – Latent error: If set this flag indicates that action has been taken to ensure error containment (such a poisoning data), but the error has not been fully corrected and the data has not been consumed. System software may choose to take further corrective action before the data is consumed.</p> <p>Bit 6 through 31 – Reserved.</p>

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Mnemonic	Byte Offset	Byte Length	Description
Section Type	16	16	<p>This field holds a pre-assigned GUID value indicating that it is a section of a particular error. The different error section types are as defined below:</p> <p>Processor Generic</p> <ul style="list-style-type: none"> {0x9876CCAD, 0x47B4, 0x4bdb, {0xB6, 0x5E, 0x16, 0xF1, 0x93, 0xC4, 0xF3, 0xDB}} <p>Processor Specific</p> <ul style="list-style-type: none"> IA32/X64: {0xDC3EA0B0, 0xA144, 0x4797, {0xB9, 0x5B, 0x53, 0xFA, 0x24, 0x2B, 0x6E, 0x1D}} IPF: {0xe429faf1, 0x3cb7, 0x11d4, {0xb, 0xca, 0x7, 0x00, 0x80, 0xc7, 0x3c, 0x88, 0x81}}¹ <p>Platform Memory</p> <ul style="list-style-type: none"> {0xA5BC1114, 0x6F64, 0x4EDE, {0xB8, 0x63, 0x3E, 0x83, 0xED, 0x7C, 0x83, 0xB1}} <p>PCIe}}</p> <ul style="list-style-type: none"> {0xD995E954, 0xBBC1, 0x430F, {0xAD, 0x91, 0xB4, 0x4D, 0xCB, 0x3C, 0x6F, 0x35}} <p>Firmware Error Record Reference</p> <ul style="list-style-type: none"> {0x81212A96, 0x09ED, 0x4996, {0x94, 0x71, 0x8D, 0x72, 0x9C, 0x8E, 0x69, 0xED}} <p>PCI/PCI-X Bus</p> <ul style="list-style-type: none"> {0xC5753963, 0x3B84, 0x4095, {0xBF, 0x78, 0xED, 0xDA, 0xD3, 0xF9, 0xC9, 0xDD}} <p>PCI Component/Device</p> <ul style="list-style-type: none"> {0xEB5E4685, 0xCA66, 0x4769, {0xB6, 0xA2, 0x26, 0x06, 0x8B, 0x00, 0x13, 0x26}}
FRU Id	32	16	<p>GUID representing the FRU ID, if it exists, for the section reporting the error. The default value is zero indicating an invalid FRU ID. System software can use this to uniquely identify a physical device for tracking purposes. Association of a GUID to a physical device is done by the platform in an implementation-specific way (i.e. PCIe Device can lock a GUID to a PCIe Device ID).</p>
Section Severity	48	4	<p>This field indicates the severity associated with the error section.</p> <p>Byte 1: Error Severity</p> <p>0 – Recoverable (also called non-fatal uncorrected)</p> <p>1 – Fatal</p> <p>2 – Corrected</p> <p>3 – None</p> <p>Bytes 2-3: Reserved. Must be zero.</p> <p>Note that severity of non indicates that the section contains extra information that can be safely ignored by error handling software.</p>
FRU Text	52	20	<p>ASCII string identifying the FRU hardware.</p>

1. For an IPF processor-specific error section, the GUID listed is the value from section B.2.3 of the SAL specification. The format of the data for this section is same as the Processor Device Error Info in the SAL specification.

N.2.3 Non-standard Section Body

Information that does not conform to one the standard formats (i.e. those defined in sections 2.4 through 2.9 of this document) may be recorded in the error record in a non-standard section. The type (e.g. format) of a non-standard section is identified by the GUID populated in the *Section Descriptor's Section Type* field. This allows the information to be decoded by consumers if the format is externally documented. Examples of information that might be placed in a non-standard section include the IPF raw SAL error record, Error information recorded in implementation-specific PCI configuration space, and IPMI error information recorded in an IPMI SEL.

N.2.4 Processor Error Sections

The processor error sections are divided into two different components as described below:

1. Processor Generic Error Section: This section holds information about processor errors in a generic form and will be common across all processor architectures. An example of error information provided is the generic information of cache, tlb, etc., errors.
2. Processor Specific Error Section: This section consists of error information, which is specific to a processor architecture. In addition, certain processor architecture state at the time of error may also be captured in this section. This section is unique to each processor architecture (Itanium Processor Family, IA32/X64).

N.2.4.1 Generic Processor Error Section

The Generic Processor Error Section describes processor reported hardware errors for logical processors in the system.

Section Type: {0x9876CCAD, 0x47B4, 0x4bdb, {0xB6, 0x5E, 0x16, 0xF1, 0x93, 0xC4, 0xF3, 0xDB}}

Table 204. Processor Generic Error Section

Name	Byte Offset	Byte Length	Description
Validation Bits	0	8	The validation bit mask indicates whether or not each of the following fields is valid in this section. Bit 0 – Processor Type Valid Bit 1 – Processor ISA Valid Bit 2 – Processor Error Type Valid Bit 3 – Operation Valid Bit 4 – Flags Valid Bit 5 – Level Valid Bit 6 – CPU Version Valid Bit 7 – CPU Brand Info Valid Bit 8 – CPU Id Valid Bit 9 – Target Address Valid Bit 10 – Requester Identifier Valid Bit 11 – Responder Identifier Valid Bit 12 – Instruction IP Valid All other bits are reserved and must be zero.
Processor Type	8	1	Identifies the type of the processor architecture. 0: IA32/X64 1: IA64 All other values reserved.
Processor ISA	9	1	Identifies the type of the instruction set executing when the error occurred: 0: IA32 1: IA64 2: X64 All other values are reserved.
Processor Error Type	10	1	Indicates the type of error that occurred: 0x00: Unknown 0x01: Cache Error 0x02: TLB Error 0x04: Bus Error 0x08: Micro-Architectural Error All other values reserved.
Operation	11	1	Indicates the type of operation: 0: Unknown or generic 1: Data Read 2: Data Write 3: Instruction Execution All other values reserved.

Name	Byte Offset	Byte Length	Description
Flags	12	1	Indicates additional information about the error: Bit 0: Restartable – If 1, program execution can be restarted reliably after the error. Bit 1: Precise IP – If 1, the instruction IP captured is directly associated with the error. Bit 2: Overflow – If 1, a machine check overflow occurred (a second error occurred while the results of a previous error were still in the error reporting resources). Bit 3: Corrected – If 1, the error was corrected by hardware and/or firmware. All other bits are reserved and must be zero.
Level	13	1	Level of the structure where the error occurred, with 0 being the lowest level of cache.
Reserved	14	2	Must be zero.
CPU Version Info	16	8	This field represents the CPU Version Information and returns Family, Model, and stepping information (e.g. As provided by CPUID instruction with EAX=1 input with output values from EAX on the IA32/X64 processor or as provided by CPUID Register 3 register – Version Information on IA64 processors).
CPU Brand String	24	128	This field represents the Processor Brand String (e.g. As provided by the CPUID instruction with EAX=0x80000002 and ECX=0x80000003 for IA32/X64 processors or the return from PAL_BRAND_INFO for IA64 processors).
Processor ID	152	8	This value uniquely identifies the logical processor (e.g. As programmed into the local APIC ID register on IA32/X64 processors or programmed into the LID register on IA64 processors).
Target Address	160	8	Identifies the target address associated with the error.
Requestor Identifier	168	8	Identifies the requestor associated with the error.
Responder Identifier	176	8	Identifies the responder associated with the error.
Instruction IP	184	8	Identifies the instruction pointer when the error occurred.

N.2.4.2 IA32/X64 Processor Error Section

Type: {0xDC3EA0B0, 0xA144, 0x4797, {0xB9, 0x5B, 0x53, 0xFA, 0x24, 0x2B, 0x6E, 0x1D}}

Table 205. Processor Error Record

Mnemonic	Byte Offset	Byte Length	Description
Validation Bits	0	8	The validation bit mask indicates each of the following field is valid in this section: Bit0 – LocalAPIC_ID Valid Bit1 – CPUID Info Valid Bits 2-7 – Number of Processor Error Information Structure (PROC_ERR_INFO_NUM) Bit 8– 13 Number of Processor Context Information Structure (PROC_CONTEXT_INFO_NUM) Bits 14-63 – Reserved
Local APIC_ID	8	8	This is the processor APIC ID programmed into the APIC ID registers.
CPUID Info	16	48	This field represents the CPU ID structure of 48 bytes and returns Model, Family, and stepping information as provided by the CPUID instruction with EAX=1 input and output values from EAX, EBX, ECX, and EDX null extended to 64-bits.
Processor Error Info	64	Nx64	This is a variable-length structure consisting of N different 64 byte structures, each representing a single processor error information structure. The value of N ranges from 0-63 and is as indicated by PROC_ERR_INFO_NUM.
Processor Context	64+Nx64	NxX	This is a variable size field providing the information for the processor context state such as MC Bank MSRs and general registers. The value of N ranges from 0-63 and is as indicated by PROC_CONTEXT_INFO_NUM. Each processor context information structure is padded with zeros if the size is not a multiple of 16 bytes.

N.2.4.2.1 IA32/X64 Processor Error Information Structure

As described above, the processor error section contains a collection of structures called *Processor Error Information Structures* that contain processor structure specific error information. This section

details the layout of the *Processor Error Information Structure* and the detailed check information which is contained within.

Table 206. IA32/X64 Processor Error Information Structure

Mnemonic	Byte Offset	Byte Length	Description
Error Structure Type	0	16	This field holds a pre-assigned GUID indicating the type of Processor Error Information structure. The following Processor Error Information Structure Types have pre-defined GUID. <ul style="list-style-type: none"> • Cache Error Information (Cache Check) • TLB Error Information (TLB Check) • Bus Error Information (Bus Check) • Micro-architecture Specific Error Information (MS Check)
Validation Bits	16	8	Bit 0 – Check Info Valid Bit 1 – Target Address Identifier Valid Bit 2 – Requestor Identifier Valid Bit 3 – Responder Identifier Valid Bit 4 – Instruction Pointer Valid Bits 5-63 – Reserved
Check Information	24	8	StructureErrorType specific error check structure.
Target Identifier	32	8	Identifies the target associated with the error.
Requestor Identifier	40	8	Identifies the requestor associated with the error.
Responder Identifier	48	8	Identifies the responder associated with the error.
Instruction Pointer	56	8	Identifies the instruction executing when the error occurred.

IA32/X64 Cache Check Structure

Type: {0xA55701F5, 0xE3EF, 0x43de, {0xAC, 0x72, 0x24, 0x9B, 0x57, 0x3F, 0xAD, 0x2C}}

Table 207. IA32/X64 Cache Check Structure

Field Name	Bits	Description
ValidationBits	15:0	Indicates which fields in the Cache Check structure are valid: Bit 0 – Transaction Type Valid Bit 1 – Operation Valid Bit 2 – Level Valid Bit 3 – Processor Context Corrupt Valid Bit 4 – Uncorrected Valid Bit 5 – Precise IP Valid Bit 6 – Restartable Valid Bit 7– Overflow Valid Bits 8 – 15 Reserved
TransactionType	17:16	Type of cache error: 0 – Instruction 1 – Data Access 2 – Generic All other values are reserved

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Field Name	Bits	Description
Operation	21:18	Type of cache operation that caused the error: 0 – generic error (type of error cannot be determined) 1 – generic read (type of instruction or data request cannot be determined) 2 – generic write (type of instruction or data request cannot be determined) 3 – data read 4 – data write 5 – instruction fetch 6 – prefetch 7 – eviction 8 – snoop All other values are reserved.
Level	24:22	Cache Level
Processor Context Corrupt	25	This field indicates that the processor context might have been corrupted.
Uncorrected	26	This field indicates whether the error was corrected or uncorrected: 0: Corrected 1: Uncorrected
Precise IP	27	This field indicates that the instruction pointer pushed onto the stack is directly associated with the error
Restartable IP	28	This field indicates that program execution can be restarted reliably at the instruction pointer pushed onto the stack
Overflow	29	This field indicates an error overflow occurred
	63:30	Reserved

IA32/X64 TLB Check Structure

Type: {0xFC06B535, 0x5E1F, 0x4562, {0x9F, 0x25, 0x0A, 0x3B, 0x9A, 0xDB, 0x63, 0xC3}}

Table 208. IA32/X64 TLB Check Structure

Field Name	Bits	Description
Validation Bits	15:0	Indicate which fields in the Cache_Check structure are valid Bit 0 – Transaction Type Valid Bit 1 – Operation Valid Bit 2 – Level Valid Bit 3 – Processor Context Corrupt Valid Bit 4 – Uncorrected Valid Bit 5 – Precise IP Valid Bit 6 – Restartable IP Valid Bit 7 – Overflow Valid Bit 8 – 15 Reserved

Field Name	Bits	Description
Transaction Type	17:16	Type of TLB error 0 – Instruction 1 – Data Access 2 – Generic All other values are reserved
Operation	21:18	Type of TLB access operation that caused the machine check: 0 – generic error (type of error cannot be determined) 1 – generic read (type of instruction or data request cannot be determined) 2 – generic write (type of instruction or data request cannot be determined) 3 – data read 4 – data write 5 – instruction fetch 6 – prefetch All other values are reserved.
Level	24:22	TLB Level
Processor Context Corrupt	25	This field indicates that the processor context might have been corrupted.
Uncorrected	26	This field indicates whether the error was corrected or uncorrected: 0: Corrected 1: Uncorrected
PreciseIP	27	This field indicates that the instruction pointer pushed onto the stack is directly associated with the error.
Restartable IP	28	This field indicates the program execution can be restarted reliably at the instruction pointer pushed onto the stack.
Overflow	29	This field indicates an error overflow occurred
	63:30	Reserved

IA32/X64 Bus Check Structure

Type: {0x1CF3F8B3, 0xC5B1, 0x49a2, {0xAA, 0x59, 0x5E, 0xEF, 0x92, 0xFF, 0xA6, 0x3C}}

Table 209. IA32/X64 Bus Check Structure

Field Name	Bits	Description
Validation Bits	15:0	Indicate which fields in the Cache_Check structure are valid Bit 0 – Transaction Type Valid Bit 1 – Operation Valid Bit 2 – Level Valid Bit 3 – Processor Context Corrupt Valid Bit 4 – Uncorrected Valid Bit 5 – Precise IP Valid Bit 6 – Restartable IP Valid Bit 7 – Overflow Valid Bit 8 – Participation Type Valid Bit 9 – Time Out Valid Bit 10 – Address Space Valid Bit 11 – 15 Reserved
Transaction Type	17:16	Type of Bus error 0 – Instruction 1 – Data Access 2 – Generic All other values are reserved
Operation	21:18	Type of bus access operation that caused the machine check: 0 – generic error (type of error cannot be determined) 1 – generic read (type of instruction or data request cannot be determined) 2 – generic write (type of instruction or data request cannot be determined) 3 – data read 4 – data write 5 – instruction fetch 6 – prefetch All other values are reserved.
Level	24:22	Indicate which level of the bus hierarchy the error occurred in.
Processor Context Corrupt	25	This field indicates that the processor context might have been corrupted.
Uncorrected	26	This field indicates whether the error was corrected or uncorrected: 0: Corrected 1: Uncorrected
PreciseIP	27	This field indicates that the instruction pointer pushed onto the stack is directly associated with the error.
Restartable IP	28	This field indicates the program execution can be restarted reliably at the instruction pointer pushed onto the stack.

Field Name	Bits	Description
Overflow	29	This field indicates an error overflow occurred
Participation Type	31:30	Type of Participation 0 – Local Processor originated request 1 – Local processor Responded to request 2 – Local processor Observed 3 - Generic
Time Out	32	This field indicates that the request timed out.
Address Space	34:33	0 – Memory Access 1 – Reserved 2 – I/O 3 – Other Transaction
	63:35	Reserved

IA32/X64 MS Check Field Description

Type: {0x48AB7F57, 0xDC34, 0x4f6c, {0xA7, 0xD3, 0xB0, 0xB5, 0xB0, 0xA7, 0x43, 0x14}}

Table 210. IA32/X64 MS Check Field Description

Field Name	Bits	Description
Validation Bits	15:0	Indicate which fields in the Cache_Check structure are valid Bit 0 – Error Type Valid Bit 1 – Processor Context Corrupt Valid Bit 2 – Uncorrected Valid Bit 3 – Precise IP Valid Bit 4 – Restartable IP Valid Bit 5 – Overflow Valid Bit 6 – 15 Reserved
Error Type	18:16	Identifies the operation that caused the error: 0 – No Error 1 – Unclassified 2 – Microcode ROM Parity Error 3 – External Error 4 – FRC Error 5 – Internal Unclassified All other value are processor specific.
Processor Context Corrupt	19	This field indicates that the processor context might have been corrupted.
Uncorrected	20	This field indicates whether the error was corrected or uncorrected: 0: Corrected 1: Uncorrected
Precise IP	21	This field indicates that the instruction pointer pushed onto the stack is directly associated with the error.
Restartable IP	22	This field indicates the program execution can be restarted reliably at the instruction pointer pushed onto the stack.
Overflow	23	This field indicates an error overflow occurred

Field Name	Bits	Description
	63:24	Reserved

N.2.4.2.2 IA32/X64 Processor Context Information Structure

As described above, the processor error section contains a collection of structures called *Processor Context Information* that contain processor context state specific to the IA32/X64 processor architecture. This section details the layout of the *Processor Context Information Structure* and the detailed processor context type information.

Table 211. IA32/X64 Processor Context Information

Mnemonic	Byte Offset	Byte Length	Description
Register Context Type	0	2 bytes	Value indicating the type of processor context state being reported: 0 – Unclassified Data 1 – MSR Registers (Machine Check and other MSRs) 2 – 32-bit Mode Execution Context 3 – 64-bit Mode Execution Context 4 – FXSAVE Context 5 – 32-bit Mode Debug Registers (DR0-DR7) 6 – 64-bit Mode Debug Registers (DR0-DR7) 7 – Memory Mapped Registers Others - Reserved
Register Array Size	2	2 bytes	Represents the total size of the array for the Data Type being reported in bytes.
MSR Address	4	4 bytes	This field contains the starting MSR address for the type 1 register context.
MM Register Address	8	8 bytes	This field contains the starting memory address for the type 7 register context.
Register Array	16	N bytes	This field will provide the contents of the actual registers or raw data. The number of Registers or size of the raw data reported is determined by (Array Size / 8) or otherwise specified by the context structure type definition.

Table 212. IA32 Register State

Offset	Length	Field
0	4 bytes	EAX
4	4 bytes	EBX
8	4 bytes	ECX
12	4 bytes	EDX
16	4 bytes	ESI
20	4 bytes	EDI
24	4 bytes	EBP
28	4 bytes	ESP

Offset	Length	Field
32	2 bytes	CS
34	2 bytes	DS
36	2 bytes	SS
38	2 bytes	ES
40	2 bytes	FS
42	2 bytes	GS
44	4 bytes	EFLAGS
48	4 bytes	EIP
52	4 bytes	CR0
56	4 bytes	CR1
60	4 bytes	CR2
64	4 bytes	CR3
68	4 bytes	CR4
72	8 bytes	GDTR
80	8 bytes	IDTR
88	2 bytes	LDTR
90	2 bytes	TR

Table 213. X64 Register State

Offset	Length	Field
0	8 bytes	RAX
8	8 bytes	RBX
16	8 bytes	RCX
24	8 bytes	RDX
32	8 bytes	RSI
40	8 bytes	RDI
48	8 bytes	RBP
56	8 bytes	RSP
64	8 bytes	R8
72	8 bytes	R9
80	8 bytes	R10
88	8 bytes	R11
96	8 bytes	R12
104	8 bytes	R13
112	8 bytes	R14
120	8 bytes	R15
128	2 bytes	CS
130	2 bytes	DS
132	2 bytes	SS

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Offset	Length	Field
134	2 bytes	ES
136	2 bytes	FS
138	2 bytes	GS
140	2 bytes	Reserved
144	8 bytes	RFLAGS
152	8 bytes	EIP
160	8 bytes	CR0
168	8 bytes	CR1
176	8 bytes	CR2
184	8 bytes	CR3
192	8 bytes	CR4
200	8 bytes	CR8
208	16 bytes	GDTR
224	16 bytes	IDTR
240	2 bytes	LDTR
242	2 bytes	TR

N.2.4.3 IA64 Processor Error Section

Refer to the Intel Itanium Processor Family System Abstraction Layer specification for finding the IA64 specific error section body definition.

N.2.5 Platform Memory Error Section

Type: {0xA5BC1114, 0x6F64, 0x4EDE, {0xB8, 0x63, 0x3E, 0x83, 0xED, 0x7C, 0x83, 0xB1}}

Table 214. Memory Error Record

Mnemonic	Byte Offset	Byte Length	Description
Validation Bits	0	8	Indicates which fields in the memory error record are valid. Bit 0 – Error Status Valid Bit 1 – Physical Address Valid Bit 2 – Physical Address Mask Valid Bit 3 – Node Valid Bit 4 – Card Valid Bit 5 – Module Valid Bit 6 – Bank Valid Bit 7 – Device Valid Bit 8 – Row Valid Bit 9 – Column Valid Bit 10 – Bit Position Valid Bit 11 – Platform Requestor Id Valid Bit 12 – Platform Responder Id Valid Bit 13 – Memory Platform Target Valid Bit 14 – Memory Error Type Valid Bit 15-63 Reserved
Error Status	8	8	Memory error status information. See section 0 for error status details.
Physical Address	16	8	The physical address at which the memory error occurred.
Physical Address Mask	24	8	Defines the valid address bits in the <i>Physical Address</i> field. The mask specifies the granularity of the physical address which is dependent on the hw/ implementation factors such as interleaving.
Node	32	2	In a multi-node system, this value identifies the node containing the memory in error.
Card	34	2	The card number of the memory error location.
Module	36	2	The module or rank number of the memory error location. (NODE, CARD, and MODULE should provide the information necessary to identify the failing FRU).
Bank	38	2	The bank number of the memory associated with the error.
Device	40	2	The device number of the memory associated with the error.
Row	42	2	The row number of the memory error location.
Column	44	2	The column number of the memory error location.
Bit Position	46	2	The bit position(s) at which the memory error occurred.
Requestor ID	48	8	Hardware address of the device that initiated the transaction that took the error.
Responder ID	56	8	Hardware address of the device that responded to the transaction.
Target ID	64	8	Hardware address of the intended target of the transaction.

Mnemonic	Byte Offset	Byte Length	Description
Memory Error Type	72	1	Identifies the type of error that occurred: 0 – Unknown 1 – No error 2 – Single-bit ECC 3 – Multi-bit ECC 4 – Single-symbol ChipKill ECC 5 – Multi-symbol ChipKill ECC 6 – Master abort 7 – Target abort 8 – Parity Error 9 – Watchdog timeout 10 – Invalid address 11 – Mirror Broken 12 – Memory Sparing All other values reserved.

N.2.6 PCI Express Error Section

Type: {0xD995E954, 0xBBC1, 0x430F, {0xAD, 0x91, 0xB4, 0x4D, 0xCB, 0x3C, 0x6F, 0x35}}

Table 215. PCI Express Error Record

Mnemonic	Byte Offset	Byte Length	Description
Validation Bits	0	8	Indicates which of the following fields is valid: Bit 0 –Port Type Valid Bit 1 – Version Valid Bit 2 – Command Status Valid Bit 3 – Device ID Valid Bit 4 – Device Serial Number Valid Bit 5 – Bridge Control Status Valid Bit 6 – Capability Structure Status Valid Bit 7 – AER Info Valid Bit 8-63 – Reserved
Port Type	8	4	PCIe Device/Port Type as defined in the PCI Express capabilities register: 0: PCI Express End Point 1: Legacy PCI End Point Device 4: Root Port 5: Upstream Switch Port 6: Downstream Switch Port 7: PCI Express to PCI/PCI-X Bridge 8: PCI/PCI-X to PCI Express Bridge 9: Root Complex Integrated Endpoint Device 10: Root Complex Event Collector

Mnemonic	Byte Offset	Byte Length	Description
Version	12	4	PCIe Spec. version supported by the platform: Byte 0-1: PCIe Spec. Version Number <ul style="list-style-type: none"> • Byte0: Minor Version in BCD • Byte1: Major Version in BCD Byte2-3: Reserved
Command Status	16	4	Byte0-1: PCI Command Register Byte2-3: PCI Status Register
Reserved	20	4	Must be zero
Device ID	24	16	PCIe Root Port PCI/bridge PCI compatible device number and bus number information to uniquely identify the root port or bridge. Default values for both the bus numbers is zero. Byte 0-1: Vendor ID Byte 2-3: Device ID Byte 4-6: Class Code Byte 7: Function Number Byte 8: Device Number Byte 9-10: Segment Number Byte 11: Root Port/Bridge Primary Bus Number or device bus number Byte 12: Root Port/Bridge Secondary Bus Number Byte 13-14: Bit0:2: Reserved Bit3:15 Slot Number Byte 15 Reserved
Device Serial Number	40	8	Byte 0-3: PCIe Device Serial Number Lower DW Byte 4-7: PCIe Device Serial Number Upper DW
Bridge Control Status	48	4	This field is valid for bridges only. Byte 0-1: Bridge Secondary Status Register Byte 2-3: Bridge Control Register
Capability Structure	52	60	PCIe Capability Structure as defined in PCIe rev 1.1.
AER Info	112	96	PCIe Advanced Error Reporting Extended Capability Structure.

N.2.7 PCI/PCI-X Bus Error Section

Type: {0xC5753963, 0x3B84, 0x4095, {0xBF, 0x78, 0xED, 0xDA, 0xD3, 0xF9, 0xC9, 0xDD}}

Table 216. PCI/PCI-X Bus Error Section

Mnemonic	Byte Offset	Byte Length	Description
Validation Bits	0	8	Indicates which of the following fields is valid: Bit 0 –Error Status Valid Bit 1 – Error Type Valid Bit 2 – Bus Id Valid Bit 3 – Bus Address Valid Bit 4 – Bus Data Valid Bit 5 – Command Valid Bit 6 – Requestor Id Valid Bit 7 – Completer Id Valid Bit 8 – Target Id Valid Bit 9-63 Reserved
Error Status	8	8	PCI Bus Error Status. See section 0 for details.
Error Type	16	2	PCI Bus error Type Byte 0: 0 – Unknown or OEM system specific error 1 – Data Parity Error 2 – System Error 3 – Master Abort 4 – Bus Timeout or No Device Present (No DEVSEL#) 5 – Master Data Parity Error 6 – Address Parity Error 7 – Command Parity Error Others – Reserved Byte 1: Reserved
Bus Id	18	2	Bits 0:7 – Bus Number Bits 8:15 – Segment Number
Reserved	20	4	
Bus Address	24	8	Memory or I/O address on the bus at the time of the error.
Bus Data	32	8	Data on the PCI bus at the time of the error.
Bus Command	40	8	Bus command or operation at the time of the error. Byte 7: Bits 7-1: Reserved (should be zero) Byte 7: Bit 0: If 0, then the command is a PCI command. If 1, the command is a PCI-X command.
Bus Requestor Id	48	8	PCI Bus Requestor Id.
Bus Completer Id	56	8	PCI Bus Responder Id.
Target Id	64	8	PCI Bus intended target identifier.

N.2.8 PCI/PCI-X Component Error Section

Type: {0xEB5E4685, 0xCA66, 0x4769, {0xB6, 0xA2, 0x26, 0x06, 0x8B, 0x00, 0x13, 0x26}}

Table 217. PCI/PCI-X Component Error Section

Mnemonic	Byte Offset	Byte Length	Description
Validation Bits	0	8	Indicate which fields are valid: Bit 0 – Error Status Valid Bit 1 – Id Info Valid Bit 2 – Memory Number Valid Bit 3 – IO Number Valid Bit 4 – Register Data Pair Valid Bit 5-63 Reserved
Error Status	8	8	PCI Component Error Status. See section 0 for details.
Id Info	16	16	Identification Information: Bytes 0-1: Vendor Id Bytes 1-2: Device Id Bytes 4-6: Class Code Byte 7: Function Number Byte 8: Device Number Byte 9: Bus Number Byte 10: Segment Number Bytes 11-15: Reserved
Memory Number	32	4	Number of PCI Component Memory Mapped register address/data pair values present in this structure.
IO Number	36	4	Number of PCI Component Programmed IO register address/data pair values present in this structure.
Register Data Pairs	40	2x8xN	An array of address/data pair values. The address and data information may be from 2 to 8 bytes of actual data represented in the 8 byte array locations.

N.2.9 Firmware Error Record Reference

Type: {0x81212A96, 0x09ED, 0x4996, {0x94, 0x71, 0x8D, 0x72, 0x9C, 0x8E, 0x69, 0xED}}

Table 218. Firmware Error Record Reference

Mnemonic	Byte Offset	Byte Length	Description
Firmware Error Record Type	0	1	Identifies the type of firmware error record that is referenced by this section: 0: IPF SAL Error Record All other values reserved
Reserved	1	7	Must be zero.

Mnemonic	Byte Offset	Byte Length	Description
Record Identifier	8	8	This value uniquely identifies the firmware error record referenced by this section. This value may be used to retrieve the referenced firmware error record using means appropriate for the error record type.

N.2.10 Error Status

The error status definition provides the capability to abstract information from implementation-specific error registers into generic error codes.

Table 219. Error Status Fields

Bit Position	Description
7:0	Reserved
15:8	Encoded value for the Error_Type. See Table 20 Error Types for details.
16	Address: Error was detected on the address signals or on the address portion of the transaction.
17	Control: Error was detected on the control signals or in the control portion of the transaction.
18	Data: Error was detected on the data signals or in the data portion of the transaction.
19	Responder: Error was detected by the responder of the transaction.
20	Requester: Error was detected by the requester of the transaction.
21	First Error: If multiple errors are logged for a section type, this is the first error in the chronological sequence. Setting of this bit is optional.
22	Overflow: Additional errors occurred and were not logged due to lack of logging resources.
63:23	Reserved.

Table 220. Error Types

Encoding	Description
1	ERR_INTERNAL Error detected internal to the component.
16	ERR_BUS Error detected in the bus.
Detailed Internal Errors	
4	ERR_MEM Storage error in memory (DRAM).
5	ERR_TLB Storage error in TLB.
6	ERR_CACHE Storage error in cache.
7	ERR_FUNCTION Error in one or more functional units.
8	ERR_SELFTEST component failed self test.
9	ERR_FLOW Overflow or undervalue of internal queue.
Detailed Bus Errors	
17	ERR_MAP Virtual address not found on IO-TLB or IO-PDIR.
18	ERR_IMPROPER Improper access error.

Encoding	Description
19	ERR_UNIMPL Access to a memory address which is not mapped to any component
20	ERR_LOL Loss of Lockstep
21	ERR_RESPONSE Response not associated with a request
22	ERR_PARITY Bus parity error (must also set the A, C, or D Bits).
23	ERR_PROTOCOL Detection of a protocol error.
24	ERR_ERROR Detection of a PATH_ERROR
25	ERR_TIMEOUT Bus operation timeout.
26	ERR_POISONED A read was issued to data that has been poisoned.
All Others	Reserved.

Appendix O

UEFI ACPI Table

To prevent ACPI namespace collision, a UEFI ACPI table format is defined. This allows creation of ACPI tables without colliding with tables reserved in the namespace.

Table 221. UEFI Table Structure

Field	Byte Length	Byte Offset	Description
Header			
Signature	4	0	'UEFI'. Signature for the Boot Optimization Options Table.
Length	4	4	Length, in bytes, of the entire BOOT Table
Revision	1	8	1
Checksum	1	9	Entire table must sum to zero.
OEMID	6	10	OEM ID.
OEM Table ID	8	16	For the UEFI Table, the table ID is the manufacture model ID.
OEM Revision	4	24	OEM revision of UEFI table for supplied OEM Table ID.
Creator ID	4	28	Vendor ID of utility that created the table.
Creator Revision	4	32	Revision of utility that created the table.
Identifier	16	36	This value contains a UUID which identifies the remaining table contents.
DataOffset	2	52	Specifies the byte offset to the remaining data in the UEFI table.
Data	X	DataOffset	Contains the rest of the UEFI table contents

Appendix P

Hardware Error Record Persistence Usage

The OS determines if a platform implements support for *Hardware Error Record Persistence* by reading the *HwErrRecSupport* globally defined variable. If the attempt to read this variable returns `EFI_NOT_FOUND` (14), then the OS will infer that the platform does not implement *Hardware Error Record Persistence*. If the attempt to read this variable succeeds, then the OS uses the returned value to determine whether the platform supports *Hardware Error Record Persistence*. A non-zero value indicates that the platform supports *Hardware Error Record Persistence*.

P.1 Determining space

To determine the amount of space (in bytes) guaranteed by the platform for saving hardware error records, the OS invokes `QueryVariableInfo`, setting the HR bit in the `Attributes` bitmask.

P.2 Saving Hardware error records

To save a hardware error record, the OS invokes `SetVariable`, supplying `EFI_HARDWARE_ERROR_VARIABLE` as the *VendorGuid* and setting the HR bit in the *Attributes* bitmask. The *VariableName* will be constructed by the OS by concatenating an index to the string “HwErrRec” (i.e. HwErrRec0001). The index portion of the variable name is determined by reading all of the hardware error record variables currently stored on the platform and choosing an appropriate index value based on the names of the existing variables. The platform saves the supplied *Data*. If insufficient space is present to store the record, the platform will return `EFI_OUT_OF_RESOURCES`, in which case, the OS may clear an existing record and retry. A retry attempt may continue to fail with status `EFI_OUT_OF_RESOURCES` if a reboot is required to coalesce resources after deletion. The OS may only save error records after *ExitBootServices* is called. Firmware may also use the *Hardware Error Record Persistence* interface to write error records, but it may only do so before *ExitBootServices* is called. If firmware uses this interface to write an error record, it must use the *VariableName* format used by the OS as described above and the error records it creates must contain the firmware’s *CreatorId*. Firmware may overwrite error records whose *CreatorId* matches the firmware’s *CreatorId*. Firmware may overwrite error records that have been cleared by other components.

During OS initialization, the OS discovers the names of all persisted error record variables by enumerating the current variable names using `GetNextVariableName`. Having identified the names of all error record variables, the OS will then read and process all of the error records from the store. After the OS processes an error record, it clears the variable if it was the creator of the variable (determined by checking the *CreatorId* field of the error record).

P.3 Clearing error record variables

To clear error record variables, the OS invokes `SetVariable`, supplying `EFI_HARDWARE_ERROR_VARIABLE` as the *VendorGuid* and setting the HR bit in the *Attributes* bitmask. The supplied *DataSize*, and *Data* parameters will all be set to zero to indicate that the variable is to be cleared. The supplied *VariableName* identifies which error record variable

is to be cleared. The OS may only clear error records after *ExitBootServices* has been called. The OS itself may only clear error records which it created (e.g. error records whose *CreatorId* matches that of the OS). However, a management application running on the OS may clear error records created by other components. This enables error records created by firmware or other OSes to be cleared by the currently running OS.

Appendix Q

References

Q.1 Related Information

The following publications and sources of information may be useful to you or are referred to by this specification:

- [BASE64] *RFC 1521: MIME (Multipurpose Internet Mail Extensions) Part One: Mechanisms for Specifying and Describing the Format of Internet Message Bodies*. Section 5.2: Base64 Content-Transfer-Encoding. <ftp://ftp.isi.edu/in-notes/rfc1521.txt>
- [PKCS] *The Public-Key Cryptography Standards*, RSA Laboratories, Redwood City, CA: RSA Data Security, Inc.
- [RFC 1700] J. Reynolds, J. Postel: Assigned Numbers | ISI, October 1994
- [RFC 2460] *Internet Protocol, Version 6 (IPv6) Specification*, <http://www.faqs.org/rfcs/rfc2460.html>
- [RFC 791] *Internet Protocol DARPA Internet Program Protocol (IPv4) Specification*, September 1981, <http://www.faqs.org/rfcs/rfc791.html>
- [SM spec] *Common Security: CDSA and CSSM*, Version 2 (with corrigenda), was *Signed Manifest Specification*, The Open Group, May 2000. <http://www.opengroup.org/pubs/catalog/c914.htm>
- “*El Torito*” *Bootable CD-ROM Format Specification*, Version 1.0, Phoenix Technologies, Ltd., IBM Corporation, 1994, <http://www.phoenix.com/en/support/white+papers-specs/>
- *Advanced Configuration and Power Interface Specification*, Intel, Microsoft, Toshiba, Compaq, and Phoenix, Revision 2.0, July 27, 2000, <http://acpi.info/index.html>
- **Address Resolution Protocol** – <http://www.ietf.org/rfc/rfc0826.txt>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *Advanced Configuration and Power Interface Specification*, Revision 2.0, July 27, 2000, <http://www.acpi.info/spec.htm>
- **Assigned Numbers** – Lists the reserved numbers used in the RFCs and in this specification - <http://www.ietf.org/rfc/rfc1700.txt>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *BIOS Boot Specification Version 1.01*, Compaq Computer Corporation, Phoenix Technologies Ltd., Intel Corporation, 1996, <http://www.phoenix.com/en/support/white+papers-specs/>
- **Bootstrap Protocol** – <http://www.ietf.org/rfc/rfc0951.txt> - This reference is included for backward compatibility. BC protocol supports DHCP and BOOTP. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *CAE Specification [UUID], DCE 1.1:Remote Procedure Call*, Document Number C706, *Universal Unique Identifier Appendix*, Copyright © 1997, The Open Group, <http://www.opengroup.org/onlinepubs/9629399/toc.htm>

- *Clarification to Plug and Play BIOS Specification Version 1.0*, <http://www.microsoft.com/hwdev/tech/pnp/>
- *Developing International Software For Windows 95* and Windows NT**, Nadine Kano, Microsoft Press, 1995, ISBN: 1-55615-840-8.
- [DIS] Markup Languages
- **Dynamic Host Configuration Protocol** – DHCP for Ipv4 (protocol: <http://www.ietf.org/rfc/rfc2131.txt>, options: <http://www.ietf.org/rfc/rfc2132.txt>). Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *Envisioning Information*, Edward R. Tufte, Graphics Press, 1990.
- *EFI Specification Version 1.02*, Intel Corporation, 2000, <http://developer.intel.com/technology/efi>.
- *File Verification Using CRC*, Mark R. Nelson, Dr. Dobbs, May 1994
- *Hardware Design Guide Version 3.0 for Microsoft Windows 2000 Server*, Intel Corporation, Microsoft Corporation, 2000, <http://developer.intel.com/design/servers/desguide/hdgv3.htm>
- *HTML: The Definitive Guide, 2nd Edition*, Chuck Musciano and Bill Kennedy, O’Reilly and Associates, Inc., 1997, ISBN: 1-56592-235-2.
- *IA-32 Intel Architecture Software Developer’s Manual*, Intel Corporation, 2001, <http://www.intel.com/design/pentium4/manuals/>
- *Information Technology — BIOS Enhanced Disk Drive Services (EDD)*, working draft T13/1386D, Revision 5a, September 28, 2000, <http://t13.org/project/d1386r5a.pdf>
- ISO Standard 9995, *Keyboard layouts for text and office systems*, http://www.iso.ch/iso/en/ISOOnline.frontpage*.
- *Itanium® Architecture Software Developer’s Manual, Volume 1: Application Architecture, Rev. 1.0*, Order number 245317, Intel Corporation, January, 2000. Also available at <http://developer.intel.com/design/itanium/family/>
- *Itanium® Architecture Software Developer’s Manual, Volume 2: System Architecture, Rev. 1.0*, Order number 245318, Intel Corporation, January, 2000. Also available at <http://developer.intel.com/design/itanium/family/>
- *Itanium® Architecture Software Developer’s Manual, Volume 3: Instruction Set Reference, Rev. 1.0*, Order number 245319, Intel Corporation, January, 2000. Also available at <http://developer.intel.com/design/itanium/family/>
- *Itanium® Architecture Software Developer’s Manual, Volume 4: Itanium Processor Programmer’s Guide, Rev. 1.0*, Order number 245320, Intel Corporation, January 2000. Also available at <http://developer.intel.com/design/itanium/family/>
- *Itanium® Software Conventions and Runtime Architecture Guide*, Order number 245358, Intel Corporation, January, 2000. Also available at <http://developer.intel.com/design/itanium/family/>
- *Itanium® System Abstraction Layer Specification*, Available at <http://developer.intel.com/design/itanium/family/>
- *IEEE 1394 Specification*, <http://www.1394ta.org/Technology/Specifications/specifications.htm>

- **Internet Control Message Protocol** – ICMP for Ipv4: <http://www.ietf.org/rfc/rfc0792.txt>. ICMP for Ipv6: <http://www.ietf.org/rfc/rfc2463.txt>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- **Internet Engineering Task Force** – <http://www.ietf.org/>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- **Internet Group Management Protocol** – <http://www.ietf.org/rfc/rfc2236.txt> . Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- **Internet Protocol** - Ipv4: <http://www.ietf.org/rfc/rfc0791.txt>. Ipv6: <http://www.ietf.org/rfc/rfc2460.txt> & <http://www.ipv6.org>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *ISO 639-2:1998*. Codes for the Representation of Names of Languages – Part2: Alpha-3 code, <http://www.iso.ch/>
- ISO/IEC 3309:1991(E), *Information Technology - Telecommunications and information exchange between systems - High-level data link control (HDLC) procedures - Frame structure*, International Organization For Standardization, Fourth edition 1991-06-01
- ITU-T Rec. V.42, *Error-Correcting Procedures for DCEs using asynchronous-to-synchronous conversion*, October, 1996
- [DBCS] Japanese Language DBCS (Double Byte Character Set): MS-DOS Version, Sizuoka Information Industry, AX Conference, 1991.
- *JavaScript: The Definitive Guide, 3rd Edition*, David Flanagan, O’Reilly and Associates, Inc., 1998, ISBN: 1-56592-392-8.
- *JavaScript: The Complete Reference*, Thomas Powell & Fritz Schneider (McGraw-Hill/Osborne, Emeryville California, 2004)
- *Microsoft Extensible Firmware Initiative FAT32 File System Specification*, Version 1.03, Microsoft Corporation, December 6, 2000, <http://www.microsoft.com/hwdev/specs/>
- *Microsoft Portable Executable and Common Object File Format Specification*, Version 6.0, <http://www.microsoft.com/hwdev/specs/>, Microsoft Corporation, May 25, 2000
- *OSTA Universal Disk Format Specification*, Revision 2.00, Optical Storage Technology Association, 1998, <http://www.osta.org/specs/>
- *PCI BIOS Specification*, Revision 2.1, PCI Special Interest Group, Hillsboro, OR, <http://www.pcisig.com/specifications>
- *PCI Hot-Plug Specification* Revision 1.0, PCI Special Interest Group, Hillsboro, OR, <http://www.pcisig.com/specifications>
- *PCI Local Bus Specification* Revision 2.2, PCI Special Interest Group, Hillsboro, OR, <http://www.pcisig.com/specifications>
- *Plug and Play BIOS Specification*, Version 1.0A, Compaq Computer Corporation, Phoenix Technologies, Ltd., Intel Corporation, 1994, <http://www.microsoft.com/hwdev/tech/pnp/>
- **Plug and Play** – <http://www.phoenix.com/en/support/white+papers-specs/> Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *Portable Executable and Common Object File Format Specification*. See <http://www.microsoft.com/hwdev/hardware/PECOFF.asp>

Unified Extensible Firmware Interface Specification

- *POST Memory Manager Specification*, Version 1.01, Phoenix Technologies Ltd., Intel Corporation, 1997, <http://www.phoenix.com/en/support/white+papers-specs/>
- *Preboot Execution Environment (PXE) Specification*, Version 2.1. Intel Corporation, 1999. Available at <ftp://download.intel.com/labs/manage/wfm/download/pxespec.pdf>.
- *Professional XML*, Didier Martin, Mark Birbeck, et. al., Wrox Press, April, 2000, ISBN: 1-861003-11-0.
- [PUI] *Programming the User Interface: Principles and Examples*, Judith R. Brown, Steve Cunningham, John Wiley & Sons, 1989, ISBN: 0-471-63843-9.
- **Request For Comments** – <http://www.ietf.org/rfc.html> and <http://www.keywave.ad.jp/RFC/index.html>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *Super VGA Graphics Programming Secrets*, Steve Rimmer, Windcrest / McGraw-Hill, 1993, ISBN: 0-8306-4428-8.
- *SYSID BIOS Support Interface Requirements*, Version 1.2, Intel Corporation, 1997, <http://www.intel.com/labs/manage/wfm/wfmspecs.htm>
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- *The Visual Display of Quantitative Information*, Edward R. Tufte, Graphics Press, 1983.
- **Transmission Control Protocol** – TCPv4: <http://www.ietf.org/rfc/rfc0793.txt>. TCPv6: <ftp://ftp.ipv6.org/pub/rfc/rfc2147.txt>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- **Trivial File Transfer Protocol** – TFTP (protocol: <http://www.ietf.org/rfc/rfc1350.txt>, options: <http://www.ietf.org/rfc/rfc2347.txt>, <http://www.ietf.org/rfc/rfc2348.txt> and <http://www.ietf.org/rfc/rfc2349.txt>). Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- **User Datagram Protocol** – UDP over IPv4: <http://www.ietf.org/rfc/rfc0768.txt>. UDP over IPv6: <http://www.ietf.org/rfc/rfc2454.txt>. Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
- *The Unicode Standard*, Version 2.1, Unicode Consortium, <http://www.unicode.org/>
- More information on EFI 1.10 UGA ROM usage under an OS can be found at www.microsoft.com/hwdev/uga.
- *Universal Serial Bus PC Legacy Compatibility Specification*, Version 0.9, <http://www.usb.org/developers/docs.html>

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Q.2 Prerequisite Specifications

In general, this specification requires that functionality defined in a number of other existing specifications be present on a system that implements this specification. This specification requires that those specifications be implemented at least to the extent that all the required elements are present.

This specification prescribes the use and extension of previously established industry specification tables whenever possible. The trend to remove runtime call-based interfaces is well documented. The ACPI (Advanced Configuration and Power Interface) specification and the SAL (System Access Layer) specification are two examples of new and innovative firmware technologies that were designed on the premise that OS developers prefer to minimize runtime calls into firmware. ACPI focuses on no runtime calls to the BIOS, and the SAL specification only supports runtime services that make the OS more portable.

Q.2.1 ACPI Specification

The interface defined by the *Advanced Configuration and Power Interface (ACPI) Specification* is the current state-of-the-art in the platform-to-OS interface. ACPI fully defines the methodology that allows the OS to discover and configure all platform resources. ACPI allows the description of non-Plug and Play motherboard devices in a plug and play manner. ACPI also is capable of describing power management and hot plug events to the OS. (For more information on ACPI, refer to the ACPI web site at <http://www.acpi.info/spec.htm>).

Q.2.2 WfM Specification

The *Wired for Management (WfM) Specification* defines a baseline for manageability that can be used to lower the total cost of ownership of a computer system. WfM includes the System Management BIOS (SMBIOS) table-based interface that is used by the platform to relate platform-specific management information to the OS or an OS-based management agent. The format of the data is defined in the *System Management BIOS Reference Specification*, and it is up to higher level software to map the information provided by the platform into the appropriate schema. Examples of schema would include CIM (Common Information Model) and DMI (Desktop Management Interface). For more information on WfM or to obtain a copy of the WfM Specification, visit <http://www.intel.com/labs/manage/wfm/wfmspecs.htm>. To obtain the *System Management BIOS Reference Specification*, visit <http://www.phoenix.com/en/support/white+papers-specs/>.

Q.2.3 Additional Considerations for Itanium-Based Platforms

Any information or service that is available in Itanium architecture firmware specifications supersedes any requirement in the common supported 32-bit and Itanium architecture specifications listed above. The Itanium architecture firmware specifications (currently the *Itanium® System Abstraction Layer Specification* and portions of the *Intel® Itanium® Architecture Software Developer's Manual*, volumes 1–4) define the baseline functionality required for all Itanium

Unified Extensible Firmware Interface Specification

architecture platforms. The major addition that UEFI makes to these Itanium architecture firmware specifications is that it defines a boot infrastructure and a set of services that constitute a common platform definition for high-volume Itanium architecture-based systems to implement based on the more generalized Itanium architecture firmware specifications.

The following specifications are the required Intel Itanium architecture specifications for all Itanium architecture-based platforms:

- *Itanium® Processor Family System Abstraction Layer Specification*
- *Intel® Itanium® Architecture Software Developer's Manual*, volumes 1–4

Both documents are available at <http://developer.intel.com/design/itanium/family/>.

Appendix R

Glossary

_ADR

A reserved name in [ACPI](#) name space. It refers to an address on a bus that has standard enumeration. An example would be PCI, where the enumeration method is described in the PCI Local Bus specification.

_CRS

A reserved name in [ACPI](#) name space. It refers to the current resource setting of a device. A _CRS is required for devices that are not enumerated in a standard fashion. _CRS is how ACPI converts nonstandard devices into Plug and Play devices.

_HID

A reserved name in [ACPI](#) name space. It represents a device's plug and play hardware ID and is stored as a 32-bit compressed EISA ID. _HID objects are optional in ACPI. However, a _HID object must be used to describe any device that will be enumerated by the ACPI driver in the OS. This is how ACPI deals with non-Plug and Play devices.

_UID

A reserved name in [ACPI](#) name space. It is a serial number style ID that does not change across reboots. If a system contains more than one device that reports the same [_HID](#), each device must have a unique _UID. The _UID only needs to be unique for device that have the exact same [_HIDD](#) value.

ACPI Device Path

A [Device Path](#) that is used to describe devices whose enumeration is not described in an industry-standard fashion. These devices must be described using ACPI AML in the [ACPI](#) name space; this type of node provides linkage to the ACPI name space.

ACPI

Refers to the *Advanced Configuration and Power Interface Specification* and to the concepts and technology it discusses. The specification defines a new interface to the system board that enables the operating system to implement operating system-directed power management and system configuration.

Alt-GR Unicode

Represents the Unicode value of a key when the Alt-GR modifier key is held down. This key (A2) in some keyboard layouts is defined as the right alternate key and serves the same function as the left alternate key. However, in many other layouts it is a secondary modifier key similar to shift. For instance, key C1 is equated to the letter *a* and its Unicode value in the typical U.K. keyboard is a non-shifted value of 0x0061. When holding down the Alt-GR key in conjunction with the pressing of key C1, , the value on the same keyboard often produces an *á*, which is a Unicode 0x00E1.

Base Code (BC)

The [PXE](#) Base Code, included as a core protocol in [EFI](#), is comprised of a simple network stack (UDP/IP) and a few common network protocols ([DHCP](#), Bootserver Discovery, [TFTP](#)) that are useful for remote booting machines.

BC

See [Base Code \(BC\)](#)

Big Endian

A memory architecture in which the low-order byte of a multibyte datum is at the highest address, while the high-order byte is at the lowest address. See [Little Endian](#).

BIOS Boot Specification Device Path

A [Device Path](#) that is used to point to boot legacy operating systems; it is based on the *BIOS Boot Specification*, Version 1.01.

BIOS Parameter Block (BPB)

The first block (sector) of a partition. It defines the type and location of the [FAT File System](#) on a drive.

BIOS

Basic Input/Output System. A collection of low-level I/O service routines.

Block I/O Protocol

A protocol that is used during boot services to abstract mass storage devices. It allows boot services code to perform block I/O without knowing the type of a device or its controller.

Block Size

The fundamental allocation unit for devices that support the [Block I/O Protocol](#). Not less than 512 bytes. This is commonly referred to as sector size on hard disk drives.

Boot Device

The [Device Handle](#) that corresponds to the device from which the currently executing image was loaded.

Boot Manager

The part of the firmware implementation that is responsible for implementing system boot policy. Although a particular boot manager implementation is not specified in this document, such code is generally expected to be able to enumerate and handle transfers of control to the available OS loaders as well as UEFI applications and drivers on a given system. The boot manager would typically be responsible for interacting with the system user, where applicable, to determine what to load during system startup. In cases where user interaction is not indicated, the boot manager would determine what to load and, if multiple items are to be loaded, what the sequencing of such loads would be.

Boot Services Driver

A program that is loaded into boot services memory and stays resident until boot services terminates.

Boot Services Table

A table that contains the firmware entry points for accessing boot services functions such as [Task Priority Services](#) and [Memory Allocation Services](#). The table is accessed through a pointer in the [System Table](#).

Boot Services Time

The period of time between platform initialization and the call to [ExitBootServices \(\)](#). During this time, [EFI Drivers](#) and applications are loaded iteratively and the system boots from an ordered list of EFI OS loaders.

Boot Services

The collection of interfaces and protocols that are present in the boot environment. The services minimally provide an OS loader with access to platform capabilities required to complete OS boot. Services are also available to drivers and applications that need access to platform capability. Boot services are terminated once the operating system takes control of the platform.

BPB

See [BIOS Parameter Block \(BPB\)](#).

Callback

Target function which augments the Forms Processor's ability to evaluate or process configuration settings. Callbacks are not available when the Forms Processor is operating in a Disconnected state.

CIM

See [Common Information Model \(CIM\)](#).

Cluster

A collection of disk sectors. Clusters are the basic storage units for disk files. See [File Allocation Table \(FAT\)](#).

COFF

Common Object File Format, a standard file format for binary images.

Coherency Domain

- (1) The global set of resources that is visible to at least one processor in a platform.
- (2) The address resources of a system as seen by a processor. It consists of both system memory and I/O space.

Common Information Model (CIM)

An object-oriented schema defined by the [DMTF](#). CIM is an information model that provides a common way to describe and share management information enterprise-wide.

Console I/O Protocol

A protocol that is used during [Boot Services](#) to handle input and output of text-based information intended for the system administrator. It has two parts, a [Simple Input Protocol](#) that is used to obtain input from the [ConsoleIn](#) device and a [Simple Text Output Protocol](#) that is used to control text-based output devices. The [Console I/O Protocol](#) is also known as the EFI Console I/O Protocol.

ConsoleIn

The device handle that corresponds to the device used for user input in the boot services environment. Typically the system keyboard.

ConsoleOut

The device handle that corresponds to the device used to display messages to the user from the boot services environment. Typically a display screen.

DBCS

Double Byte Character Set.

Desktop Management Interface (DMI)

A platform management information framework, built by the [DMTF](#) and designed to provide manageability for desktop and server computing platforms by providing an interface that is:

- (1) independent of any specific desktop operating system, network operating system, network protocol, management protocol, processor, or hardware platform;
- (2) easy for vendors to implement; and
- (3) easily mapped to higher-level protocols.

Desktop Management Task Force (DMTF)

The DMTF is a standards organization comprised of companies from all areas of the computer industry. Its purpose is to create the standards and infrastructure for cost-effective management of PC systems.

Device Handle

A handle points to a list of one or more protocols that can respond to requests for services for a given device referred to by the handle.

Device I/O Protocol

A protocol that is used during boot services to access memory and I/O. Also called the EFI Device I/O Protocol.

Device Path Instance

When an environment variable represents multiple devices, it is possible for a device path to contain multiple device paths. An example of this would be the [ConsoleOut](#) environment variable that consists of both a VGA console and a serial output console. This environment variable would describe a console output stream that would send output to both devices and therefore has a Device Path that consists of two complete device paths. Each of these paths is a device path instance.

Device Path Node

A variable-length generic data structure that is used to build a device path. Nodes are distinguished by type, subtype, length, and path-specific data. See [Device Path](#).

Device Path Protocol

A protocol that is used during boot services to provide the information needed to construct and manage Device Paths. Also called the EFI Device Path Protocol.

Device Path

A variable-length binary data structure that is composed of variable-length generic device path nodes and is used to define the programmatic path to a logical or physical device. There are six major types of device paths: [Hardware Device Path](#), [ACPI Device Path](#), [Messaging Device Path](#), [Media Device Path](#), [BIOS Boot Specification Device Path](#), and [End of Hardware Device Path](#).

DHCP

See [Dynamic Host Configuration Protocol \(DHCP\)](#).

Disconnected

The state when a Forms Processor is manipulating a form set without being connected to the Target's pre-OS environment. For example, after booting an OS, a Forms Processor cannot execute call-backs or read the configuration settings. For example, when running a Forms Browser while on a remote machine that is not connected to the Target. In these cases, the Forms Processor has limited knowledge of the Target's current configuration settings and limited or no ability to use call-backs.

Disk I/O Protocol

A protocol that is used during boot services to abstract Block I/O devices to allow non-block-sized I/O operations. Also called the EFI Disk I/O Protocol.

DMI

See [DBCS](#).

DMTF

See [Desktop Management Task Force \(DMTF\)](#).

Dynamic Host Configuration Protocol (DHCP)

A protocol that is used to get information from a configuration server. DHCP is defined by the [Desktop Management Task Force \(DMTF\)](#), not [EFI](#).

EBC Image

Executable EBC image following the PE32 file format.

EBC

See [EFI Byte Code \(EBC\)](#).

EFI

Extensible Firmware Interface. An interface between the operating system (OS) and the platform firmware.

EFI Application

Modular code that may be loaded in the boot services environment to accomplish platform specific tasks within that environment. Examples of possible applications might include diagnostics or disaster recovery tools shipped with a platform that run outside the OS environment. Applications may be loaded in accordance with policy implemented by the platform firmware to accomplish a specific task. Control is then returned from the application to the platform firmware.

EFI Byte Code (EBC)

The binary encoding of instructions as output by the EBC C compiler and linker. The [EBC Image](#) is executed by the interpreter.

EFI Drivers

A module of code typically inserted into the firmware via protocol interfaces. Drivers may provide device support during the boot process or they may provide platform services. It is important not to confuse drivers in this specification with OS drivers that load to provide device support once the OS takes control of the platform.

EFI File

A container consisting of a number of blocks that holds an image or a data file within a file system that complies with this specification.

EFI Hard Disk

A hard disk that supports the new EFI partitioning scheme ([GUID Partition](#)).

EFI OS Loader

The first piece of operating system code loaded by the firmware to initiate the OS boot process. This code is loaded at a fixed address and then executed. The OS takes control of the system prior to completing the OS boot process by calling the interface that terminates all boot services.

EFI-compliant

Refers to a platform that complies with this specification.

EFI-conformant

See [EFI-compliant](#).

End of Hardware Device Path

A Device Path which, depending on the subtype, is used to indicate the end of the Device Path instance or Device Path structure.

Enhanced Mode (EM)

The 64-bit architecture extension that makes up part of the Intel® Itanium® architecture.

Event Services

The set of functions used to manage events. Includes [CheckEvent\(\)](#), [CreateEvent\(\)](#), [CloseEvent\(\)](#), [SignalEvent\(\)](#), and [WaitForEvent\(\)](#).

Event

An EFI data structure that describes an “event”—for example, the expiration of a timer.

Event Services

The set of functions used to manage events. Includes [CheckEvent\(\)](#), [CreateEvent\(\)](#), [CloseEvent\(\)](#), [SignalEvent\(\)](#), and [WaitForEvent\(\)](#).

FAT File System

The file system on which the [EFI File](#) system is based. See [File Allocation Table \(FAT\)](#) and [System Partition](#).

FAT

See [File Allocation Table \(FAT\)](#).

File Allocation Table (FAT)

A table that is used to identify the clusters that make up a disk file. File allocation tables come in three flavors: FAT12, which uses 12 bits for cluster numbers; FAT16, which uses 16 bits; and FAT32, which allots 32 bits but only uses 28 (the other 4 bits are reserved for future use).

File Handle Protocol

A component of the [File System Protocol](#). It provides access to a file or directory. Also called the EFI File Handle Protocol.

File System Protocol

A protocol that is used during boot services to obtain file-based access to a device. It has two parts, a [Simple File System Protocol](#) that provides a minimal interface for file-type access to a device, and a [File Handle Protocol](#) that provides access to a file or directory.

Firmware

Any software that is included in read-only memory (ROM).

Font

A graphical representation corresponding to a character set, in this case Unicode. The following are the same Latin letter in three fonts using the same size (14):

A
A
A

Font glyph

The individual elements of a font corresponding to single characters are called *font glyphs* or simply *glyphs*. The first character in each of the above three lines is a *glyph* for the letter "A" in three different fonts.

Form

Logical grouping of questions with a unique identifier.

Form Set

An HII database package describing a group of forms, including one parent form and zero or more child forms.

Forms Browser

A Forms Processor capable of displaying the user-interface information a display and interacting with a user.

Forms Processor

An application capable of reading and processing the forms data within a forms set.

Globally Unique Identifier (GUID)

A 128-bit value used to differentiate services and structures in the boot services environment. The format of a **GUID** is defined in Appendix A. See [Protocol](#).

Glyph

The individual elements of a font corresponding to single characters. May also be called *font* keyboard layout *glyphs*. Also see *font glyph* above.

GUID Partition Entry

A data structure that characterizes a [GUID Partition](#). Among other things, it specifies the starting and ending LBA of the partition.

GUID Partition Table Header

The header in a [GUID Partition Table](#). Among other things, it contains the number of partition entries in the table and the first and last blocks that can be used for the entries.

GUID Partition Table

A data structure that describes a [GUID Partition](#). It consists of an [GUID Partition Table Header](#) and, typically, at least one [GUID Partition Entry](#). There are two partition tables on an [EFI Hard Disk](#): the Primary Partition Table (located in block 1 of the disk) and a Backup Partition Table (located in the last block of the disk). The Backup Table is a copy of the Primary Table.

GUID Partition

A contiguous group of sectors on an [EFI Hard Disk](#).

Handle

See [Device Handle](#).

Hardware Device Path

A Device Path that defines how a hardware device is attached to the resource domain of a system (the resource domain is simply the shared memory, memory mapped I/O, and I/O space of the system).

HII

Human Interface Infrastructure.

HII Database

The centralized repository for HII-related information, organized as package lists.

HTML

Hypertext Markup Language. A particular implementation of SGML focused on hypertext applications. HTML is a fairly simple language that enables the description of pages (generally Internet pages) that include links to other pages and other data types (such as graphics). When applied to a larger world, HTML has many shortcomings, including localization (q.v.) and formatting issues. The HTML *form* concept is of particular interest to this application.

IA-32

See [Intel® Architecture-32 \(IA-32\)](#).

IFR

Internal Form Representation. Used to represent forms in EFI so that it can be interpreted as is or expanded easily into XHTML.

Image Handle

A handle for a loaded image; image handles support the loaded image protocol.

Image Handoff State

The information handed off to a loaded image as it begins execution; it consists of the image's handle and a pointer to the image's system table.

Image Header

The initial set of bytes in a loaded image. They define the image's encoding.

Image Services

The set of functions used to manage EFI images. Includes [LoadImage \(\)](#), [StartImage \(\)](#), [UnloadImage \(\)](#), [Exit \(\)](#), [ExitBootServices \(\)](#), and [EFI_IMAGE_ENTRY_POINT](#).

Image

- (1) An executable file stored in a file system that complies with this specification. Images may be drivers, applications or OS loaders. Also called an EFI Image.
- (2) Executable binary file containing [EBC](#) and data. Output by the EBC linker.

IME

Input Method Editor. A program or subprogram that is used to map keystrokes to logographic characters. For example, IMEs are used (possibly with user intervention) to map the Kana (Hirigana or Katakana) characters on Japanese keyboards to Kanji.

Intel® Architecture-32 (IA-32)

The 32-bit and 16-bit architecture described in the *Intel Architecture Software Developer's Manual*. IA-32 is the architecture of the Intel® P6 family of processors, which includes the Intel® Pentium® Pro, Pentium II, Pentium III, and Pentium 4 processors.

Intel® Itanium® Architecture

The Intel architecture that has 64-bit instruction capabilities, new performance-enhancing features, and support for the IA-32 instruction set. This architecture is described in the *Itanium™ Architecture Software Developer's Manual*.

internationalization

In this context, is the process of making a system usable across languages and cultures by using universally understood symbols. Internationalization is difficult due to the differences in cultures and the difficulty of creating obvious symbols; for example, why does a red octagon mean "Stop"?

Interpreter

The software implementation that decodes [EBC](#) binary instructions and executes them on a VM. Also called EBC interpreter.

Keyboard layout

The physical representation of a user's keyboard. The usage of this is in conjunction to a structure that equates the physical key(s) and the associated action it represents. For instance, key C1 is equated to the letter *a* and its Unicode value in the typical U.K. keyboard is a non-shifted value of 0x0061.

LAN On Motherboard (LOM)

This is a network device that is built onto the motherboard (or baseboard) of the machine.

Legacy Platform

A platform which, in the interests of providing backward-compatibility, retains obsolete technology.

LFN

See [Long File Names \(LFN\)](#).

Little Endian

A memory architecture in which the low-order byte of a multibyte datum is at the lowest address, while the high-order byte is at the highest address. See [Big Endian](#).

Load File Protocol

A protocol that is used during boot services to find and load other modules of code.

Loaded Image Protocol

A protocol that is used during boot services to obtain information about a loaded image. Also called the EFI Loaded Image Protocol.

Loaded Image

A file containing executable code. When started, a loaded image is given its image handle and can use it to obtain relevant image data.

ILocalization

The process of focusing a system in so that it works using the symbols of a language/culture. To a major extent the following design is influenced by the requirements of localization.

Logographic

A character set that uses characters to represent words or parts of words rather than syllables or sounds. Kanji is logographic but Kana characters are not.

LOM

See [LAN On Motherboard \(LOM\)](#).

Long File Names (LFN)

Refers to an extension to the [FAT File System](#) that allows file names to be longer than the original standard (eight characters plus a three-character extension).

Machine Check Abort (MCA)

The system management and error correction facilities built into the Intel Itanium processors.

Master Boot Record (MBR)

The data structure that resides on the first sector of a hard disk and defines the partitions on the disk.

MBR

See [Master Boot Record \(MBR\)](#).

MCA

See [Machine Check Abort \(MCA\)](#).

Media Device Path

A Device Path that is used to describe the portion of a medium that is being abstracted by a boot service. For example, a Media Device Path could define which partition on a hard drive was being used.

Memory Allocation Services

The set of functions used to allocate and free memory, and to retrieve the memory map. Includes [AllocatePages \(\)](#), [FreePages \(\)](#), [AllocatePool \(\)](#), [FreePool \(\)](#), and [GetMemoryMap \(\)](#).

Memory Map

A collection of structures that defines the layout and allocation of system memory during the boot process. Drivers and applications that run during the boot process prior to OS control may require memory. The boot services implementation is required to ensure that an appropriate representation of available and allocated memory is communicated to the OS as part of the hand-off of control.

Memory Type

One of the memory types defined by UEFI for use by the firmware and UEFI applications. Among others, there are types for boot services code, boot services data, [Runtime Services](#) code, and runtime services data. Some of the types are used for one purpose before [ExitBootServices \(\)](#) is called and another purpose after.

Messaging Device Path

A Device Path that is used to describe the connection of devices outside the [Coherency Domain](#) of the system. This type of node can describe physical messaging information (e.g., a SCSI ID) or abstract information (e.g., networking protocol IP addresses).

Miscellaneous Service

Various functions that are needed to support the [EFI](#) environment. Includes [InstallConfigurationTable \(\)](#), [ResetSystem \(\)](#), [Stall \(\)](#), [SetWatchdogTimer \(\)](#), [GetNextMonotonicCount \(\)](#), and [GetNextHighMonotonicCount \(\)](#).

MTFTP

See [Multicast Trivial File Transfer Protocol \(MTFTP\)](#).

Multicast Trivial File Transfer Protocol (MTFTP)

A **protocol** used to download a [Network Boot Program](#) to many clients simultaneously from a [TFTP](#) server.

Name Space

In general, a collection of device paths; in an EFI Device Path.

Native Code

Low level instructions that are native to the host processor. As such, the processor executes them directly with no overhead of interpretation. Contrast this with [EBC](#), which must be interpreted by native code to operate on a [VM](#).

NBP

See [Network Bootstrap Program \(NBP\)](#) or [Network Boot Program](#).

Network Boot Program

A remote boot image downloaded by a [PXE](#) client using the [Trivial File Transport Protocol \(TFTP\)](#) or the [Multicast Trivial File Transfer Protocol \(MTFTP\)](#). See [Network Bootstrap Program \(NBP\)](#).

Network Bootstrap Program (NBP)

This is the first program that is downloaded into a machine that has selected a PXE capable device for remote boot services.

A typical NBP examines the machine it is running on to try to determine if the machine is capable of running the next layer (OS or application). If the machine is not capable of running the next layer, control is returned to the [EFI](#) boot manager and the next boot device is selected. If the machine is capable, the next layer is downloaded

and control can then be passed to the downloaded program.

Though most NBPs are OS loaders, NBPs can be written to be standalone applications such as diagnostics, backup/restore, remote management agents, browsers, etc.

Network Interface Card (NIC)

Technically, this is a network device that is inserted into a bus on the motherboard or in an expansion board. For the purposes of this document, the term NIC will be used in a generic sense, meaning any device that enables a network connection (including [LOMs](#) and network devices on external buses (USB, 1394, etc.)).

NIC

See [Network Interface Card \(NIC\)](#).

Non-spacing key

Typically an accent key that does not advance the cursor and is used to create special characters similar to ÅäÊê. This function is provided only on certain keyboard layouts.

NV

Nonvolatile.

Package

III information with a unique type, such as strings, fonts, images or forms.

Package List

Group of packages identified by a GUID.

Page Memory

A set of contiguous pages. Page memory is allocated by [AllocatePages \(\)](#) and returned by [FreePages \(\)](#).

Partition Discovery

The process of scanning a block device to determine whether it contains a [Partition](#).

Partition

See [System Partition](#).

PC-AT

Refers to a PC platform that uses the AT form factor for their motherboards.

PCI Bus Driver

Software that creates a handle for every [PCI Controller](#) on a [PCI Host Bus Controller](#) and installs both the [PCI I/O Protocol](#) and the [Device Path Protocol](#) onto that handle. It may optionally perform [PCI Enumeration](#) if resources have not already been allocated to all the PCI Controllers on a PCI Host Bus Controller. It also loads and starts any UEFI drivers found in any PCI Option ROMs discovered during PCI Enumeration. If a driver is found in a [PCI Option ROM](#), the [PCI Bus Driver](#) will also attach the Bus Specific Driver Override Protocol to the handle for the PCI Controller that is associated with the PCI Option ROM that the driver was loaded from.

PCI Bus

A collection of up to 32 physical [PCI Devices](#) that share the same physical PCI bus. All devices on a PCI Bus share the same [PCI Configuration Space](#).

PCI Configuration Space

The configuration channel defined by PCI to configure [PCI Devices](#) into the resource domain of the system. Each PCI device must produce a standard set of registers in the form of a PCI Configuration Header, and can optionally produce device specific registers. The registers are addressed via Type 0 or Type 1 PCI Configuration Cycles as described by the *PCI Specification*. The PCI Configuration Space can be shared across multiple [PCI Buses](#). On most [PC-AT](#) architecture systems and typical Intel® chipsets, the PCI Configuration Space is accessed via I/O ports 0xCF8 and 0xCFC. Many other implementations are possible.

PCI Controller

A hardware components that is discovered by a [PCI Bus Driver](#), and is managed by a [PCI Device Driver](#). [PCI Functions](#) and [PCI Controller](#) are used equivalently in this document.

PCI Device Driver

Software that manages one or more PCI Controllers of a specific type. A driver will use the [PCI I/O Protocol](#) to produce a device I/O abstraction in the form of another protocol (i.e. Block I/O, Simple Network, Simple Input, Simple Text Output, Serial I/O, Load File).

PCI Devices

A collection of up to 8 [PCI Functions](#) that share the same [PCI Configuration Space](#). A PCI Device is physically connected to a [PCI Buses](#).

PCI Enumeration

The process of assigning resources to all the PCI Controllers on a given [PCI Host Bus Controller](#). This includes PCI Bus Number assignments, PCI Interrupt assignments, PCI I/O resource allocation, the PCI Memory resource allocation, the PCI Prefetchable Memory resource allocation, and miscellaneous PCI DMA settings.

PCI Functions

A controller that provides some type of I/O services. It consumes some combination of PCI I/O, PCI Memory, and PCI Prefetchable Memory regions, and up to 256 bytes of the [PCI Configuration Space](#). The PCI Function is the basic unit of configuration for PCI.

PCI Host Bus Controller

A chipset component that produces PCI I/O, PCI Memory, and PCI Prefetchable Memory regions in a single Coherency Domain. A PCI Host Bus Controller is composed of one or more [PCI Root Bridges](#).

PCI I/O Protocol

A software interface that provides access to PCI Memory, PCI I/O, and PCI Configuration spaces for a PCI Controller. It also provides an abstraction for PCI Bus Master DMA.

PCI Option ROM

A ROM device that is accessed through a PCI Controller, and is described in the PCI Controller's Configuration Header. It may contain one or more [PCI Device Drivers](#) that are used to manage the PCI Controller.

PCI Root Bridge I/O Protocol

A software abstraction that provides access to the PCI I/O, PCI Memory, and PCI Prefetchable Memory regions in a single Coherency Domain.

PCI Root Bridge

A chipset component(s) that produces a physical PCI Local Bus.

PCI Segment

A collection of up to 256 [PCI Buses](#) that share the same [PCI Configuration Space](#). PCI Segment is defined in Section 6.5.6 of the *ACPI 2.0 Specification* as the `_SEG` object. The `SAL_PCI_CONFIG_READ` and `SAL_PCI_CONFIG_WRITE` procedures defined in chapter 9 of the *SAL Specification* define how to access the PCI Configuration Space in a system that supports multiple PCI Segments. If a system only supports a single PCI Segment the PCI Segment number is defined to be zero. The existence of PCI Segments enables the construction of systems with greater than 256 PCI buses.

Pool Memory

A set of contiguous bytes. A pool begins on, but need not end on, an "8-byte" boundary. Pool memory is allocated in pages—that is, firmware allocates enough contiguous pages to contain the number of bytes specified in the allocation request. Hence, a pool can be contained within a single page or extend across multiple pages. Pool memory is allocated by [AllocatePool \(\)](#) and returned by [FreePool \(\)](#).

Preboot Execution Environment (PXE)

A means by which agents can be loaded remotely onto systems to perform management tasks in the absence of a running OS. To enable the interoperability of clients and downloaded bootstrap programs, the client preboot code must provide a set of services for use by a downloaded bootstrap. It also must ensure certain aspects of the client state at the point in time when the bootstrap begins executing.

The complete PXE specification covers three areas; the client, the network and the server.

Client

- Makes network devices into bootable devices.
- Provides APIs for PXE protocol modules in **EFI** and for universal drivers in the OS.

Network

- Uses existing technology: [DHCP](#), [TFTP](#), etc.
- Adds “vendor-specific” tags to DHCP to define PXE-specific operation within DHCP.
- Adds multicast TFTP for high bandwidth remote boot applications.
- Defines Bootserver discovery based on DHCP packet format.

Server

- **Bootserver:** Responds to Bootserver discovery requests and serves up remote boot images.
- **proxyDHCP:** Used to ease the transition of PXE clients and servers into existing network infrastructure. proxyDHCP provides the additional [DHCP](#) information that is needed by PXE clients and Bootservers without making changes to existing DHCP servers.
- **MTFTP:** Adds multicast support to a [TFTP](#) server.
- **Plug-In Modules:** Example proxyDHCP and Bootservers provided in the [PXE](#) SDK (software development kit) have the ability to take plug-in modules (PIMs). These PIMs are used to change/enhance the capabilities of the proxyDHCP and Bootservers.

Protocol Handler Services

The set of functions used to manipulate handles, protocols, and protocol interfaces. Includes [InstallProtocolInterface\(\)](#), [UninstallProtocolInterface\(\)](#), [ReinstallProtocolInterface\(\)](#), [HandleProtocol\(\)](#), [RegisterProtocolNotify\(\)](#), [LocateHandle\(\)](#), and [LocateDevicePath\(\)](#).

Protocol Handler

A function that responds to a call to a `HandleProtocol` request for a given handle. A protocol handler returns a protocol interface structure.

Protocol Interface Structure

The set of data definitions and functions used to access a particular type of device. For example, `BLOCK_IO` is a protocol that encompasses interfaces to read and write blocks from mass storage devices. See [Protocol](#).

Protocol Revision Number

The revision number associated with a protocol. See [Protocol](#).

Protocol

The information that defines how to access a certain type of device during boot services. A protocol consists of a [Globally Unique Identifier \(GUID\)](#), a protocol revision number, and a protocol interface structure. The interface structure contains data definitions and a set of functions for accessing the device. A device can have multiple protocols. Each protocol is accessible through the device’s handle.

PXE Base Code Protocol

A protocol that is used to control PXE-compatible devices. It may be used by the firmware's boot manager to support booting from remote locations. Also called the EFI PXE Base Code Protocol.

PXE

See [Preboot Execution Environment \(PXE\)](#).

Question

IFR which describes how a single configuration setting should be presented, stored, and validated.

Read-Only Memory (ROM)

When used with reference to the [UNDI](#) specification, ROM refers to a nonvolatile memory storage device on a [NIC](#).

Reset

The action which forces question values to be reset to their defaults.

ROM

See [Question](#).

Runtime Services Driver

A program that is loaded into runtime services memory and stays resident during runtime.

Runtime Services Table

A table that contains the firmware entry points for accessing runtime services functions such as [Time Services](#) and [Virtual Memory Services](#). The table is accessed through a pointer in the [System Table](#).

Runtime Services

Interfaces that provide access to underlying platform specific hardware that may be useful during OS runtime, such as timers. These services are available during the boot process but also persist after the OS loader terminates boot services.

SAL

See [System Abstraction Layer \(SAL\)](#).

scan code

A value representing the *location* of a key on a keyboard. Scan codes may also encode make (key press) and break (key release) and auto-repeat information.

Serial I/O Protocol

SGML

Standard Generalized Markup Language. A markup language for defining markup languages.

shifted Unicode

Represents the Unicode value of a key when the shift modifier key is held down. For instance, key C1 is equated to the letter *a* and its Unicode value in the typical U.K. keyboard is a non-shifted value of 0x0061. When the shift key is held down in conjunction with the pressing of key C1, however, the value on the same keyboard often produces an *A*, which is a Unicode 0x0041.

A [Protocol](#) that is used during boot services to abstract byte stream devices—that is, to communicate with character-based I/O devices.

Simple File System Protocol

A component of the [File System Protocol](#). It provides a minimal interface for file-type access to a device.

Simple Input Protocol

A **protocol** that is used to obtain input from the ConsoleIn device. It is one of two protocols that make up the [Console I/O Protocol](#).

Simple Network Protocol

A protocol that is used to provide a packet-level interface to a network adapter. Also called the EFI Simple Network Protocol.

Simple Text Output Protocol

A protocol that is used to control text-based output devices. It is one of two protocols that make up the [Console I/O Protocol](#).

SKU

Stock keeping unit. An acronym commonly used to reference a “version” of a particular platform. An example might be “We have three different SKUs of this platform.”

SMBIOS

See [System Management BIOS \(SMBIOS\)](#).

StandardError

The device handle that corresponds to the device used to display error messages to the user from the boot services environment.

Status Codes

Success, error, and warning codes returned by boot services and runtime services functions.

string

A null-terminated ordered list of 16-bit Unicode characters. All strings in this specification are implemented in [Unicode](#).

Submit

The action which forces modified question values to be written back to storage.

System Abstraction Layer (SAL)

Firmware that abstracts platform implementation differences, and provides the basic platform software interface to all higher level software.

System Management BIOS (SMBIOS)

A table-based interface that is required by the *Wired for Management Baseline Specification*. It is used to relate platform-specific management information to the OS or to an OS-based management agent.

System Partition

A section of a block device that is treated as a logical whole. For a hard disk with a legacy partitioning scheme, it is a contiguous grouping of sectors whose starting sector and size are defined by the [Master Boot Record \(MBR\)](#). For an [EFI Hard Disk](#), it is a contiguous grouping of sectors whose starting sector and size are defined by the [GUID Partition Table Header](#) and the associated [GUID Partition Entry](#). For “El Torito” devices, it is a logical device volume. For a diskette (floppy) drive, it is defined to be the entire medium (the term “diskette” includes legacy 3.5” diskette drives as well as newer media such as the Iomega Zip drive). System Partitions can reside on any medium that is supported by EFI boot services. System Partitions support backward compatibility with legacy Intel architecture systems by reserving the first block (sector) of the partition for compatibility code.

System Table

Table that contains the standard input and output handles for a UEFI application, as well as pointers to the boot services and runtime services tables. It may also contain pointers to other standard tables such as the [ACPI](#), [SMBIOS](#), and [SAL](#) System tables. A loaded image receives a pointer to its system table when it begins execution. Also called the EFI System Table.

Target

The system being configured.

Task Priority Level (TPL)

The boot services environment exposes three task priority levels: “normal,” “callback,” and “notify.”

Task Priority Services

The set of functions used to manipulate task priority levels. Includes [RaiseTPL\(\)](#) and [RestoreTPL\(\)](#).

TFTP

See [Trivial File Transport Protocol \(TFTP\)](#).

Time Format

The format for expressing time in an [EFI-compliant](#) platform. For more information, see Appendix A.

Time Services

The set of functions used to manage time. Includes [GetTime\(\)](#), [SetTime\(\)](#), [GetWakeuptime\(\)](#), and [SetWakeuptime\(\)](#).

Timer Services

The set of functions used to manipulate timers. Contains a single function, [SetTimer\(\)](#).

TPL

See [Target](#).

Trivial File Transport Protocol (TFTP)

A protocol used to download a [Network Boot Program](#) from a TFTP server.

UNDI

See [Universal Network Device Interface \(UNDI\)](#).

Unicode Collation Protocol

A protocol that is used during boot services to perform case-insensitive comparisons of Unicode strings.

Unicode

An industry standard internationalized character set used for human readable message display.

Universal Network Device Interface (UNDI)

UNDI is an architectural interface to [NICs](#). Traditionally NICs have had custom interfaces and custom drivers (each NIC had a driver for each OS on each platform architecture). Two variations of UNDI are defined in this specification: H/W UNDI and S/W UNDI. H/W UNDI is an architectural hardware interface to a NIC. S/W UNDI is a software implementation of the H/W UNDI.

Universal Serial Bus (USB)

A bi-directional, isochronous, dynamically attachable serial interface for adding peripheral devices such as serial ports, parallel ports, and input devices on a single bus.

USB Bus Driver

Software that enumerates and creates a handle for each newly attached USB Controller and installs both the [USB I/O Protocol](#) and the Device Path Protocol onto that handle, starts that device driver if applicable. For each newly detached USB Controller, the device driver is stopped, the USB I/O Protocol and the Device Path Protocol are uninstalled from the device handle, and the device handle is destroyed.

USB Bus

A collection of up to 127 physical [USB Devices](#) that share the same physical USB bus. All devices on a USB Bus share the bandwidth of the USB Bus.

USB Controller

A hardware component that is discovered by a [USB Bus Driver](#), and is managed by a [USB Device Driver](#). [USB Interface](#) and [USB Controller](#) are used equivalently in this document.

USB Device Driver

Software that manages one or more [USB Controller](#) of a specific type. A driver will use the [USB I/O Protocol](#) to produce a device I/O abstraction in the form of another protocol (i.e. Block I/O, Simple Network, Simple Input, Simple Text Output, Serial I/O, Load File).

USB Device

A USB peripheral that is physically attached to the [USB Bus](#).

USB Enumeration

A periodical process to search the [USB Bus](#) to detect if there have been any [USB Controller](#) attached or detached. If an attach event is detected, then the USB Controller's device address is assigned, and a child handle is created. If a detach event is detected, then the child handle is destroyed.

USB Host Controller

Moves data between system memory and devices on the [USB Bus](#) by processing data structures and generating the USB transactions. For USB 1.1, there are currently two types of USB Host Controllers: UHCI and OHCI.

USB Hub

A special [USB Device](#) through which more USB devices can be attached to the [USB Bus](#).

USB I/O Protocol

A software interface that provides services to manage a [USB Controller](#), and services to move data between a USB Controller and system memory.

USB Interface

The USB Interface is the basic unit of a physical [USB Device](#).

USB

See [Universal Serial Bus \(USB\)](#).

Variable Services

The set of functions used to manage variables. Includes [GetVariable\(\)](#), [SetVariable\(\)](#), and [GetNextVariableName\(\)](#).

Virtual Memory Services

The set of functions used to manage virtual memory. Includes [SetVirtualAddressMap\(\)](#) and [ConvertPointer\(\)](#).

VM

The Virtual Machine, a pseudo processor implementation consisting of registers which are manipulated by the interpreter when executing [EBC](#) instructions.

Watchdog Time

An alarm timer that may be set to go off. This can be used to regain control in cases where a code path in the boot services environment fails to or is unable to return control by the expected path.

WfM

See [Wired for Management \(WfM\)](#).

Wired for Management (WfM)

Refers to the *Wired for Management Baseline Specification*. The Specification defines a baseline for system manageability issues; its intent is to help lower the cost of computer ownership.

x64

Processors that are compatible with instruction sets and operation modes as exemplified by the AMD64 or Intel® Extended Memory 64 Technology (Intel® EM64T) architecture.

XHTML

Extensible HTML. XHTML "will obey all of the grammar rules of XML (properly nested elements, quoted attributes, and so on), while conforming to the vocabulary of HTML (the elements and attributes that are available for use and their relationships to one another)." [[PXML, pg. 153](#)]. Although not completely defined, XHTML is basically the intersection of XML and HTML and *does* support forms.

XML

Extensible Markup Language. A subset of SGML. Addresses many of the problems with HTML but does not currently (1.0) support forms in any specified way.

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 - 000004600000090000000636831302e646f6300f
 - fffadde000000000000000000000000000000000000
 - 0000000001600000010000000030063006800
 - 310030002e0064006f0063 1359

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 0450078006900740042006f006f00
 7400530065007200760069006300
 650073000000ExitBootServices()
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